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## MACX MCR-EX-T-UI-UP...

Temperature transducers with intrinsically safe input for temperature sensors, voltage signals, resistance-type sensors and potentiometers

Data sheet 104601 en 04

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## 1 Description

The configurable and programmable MACX

MCR-EX-T-UI-UP... temperature transducer is used for the intrinsically safe (Ex i) operation of all standard temperature sensors (RTDs and thermocouples), voltage signals, remote resistance-type sensors and potentiometers. The temperature input signals are output in a linearized format at the output. In addition to an analog current and voltage output, the module also has a switching output. The power supply has been designed as a wide range power supply.

The devices can be installed in zone 2 in the protection type "n" (EN 60079-15).

The temperature transducer can be configured with the standard configuration (see example: "Order key" on page 6) or order-specific according to the order key and is delivered calibrated and ready for operation. Possible settings for the modules configured according to the order (MACX MCR...-C) can be found in the order key on page page 6.

The set configuration is shown on the label on the side of the housing.

Features such as sensor type, connection method, measuring range, measuring unit, filter, alarm signal and output range can be configured using the IFS-CONF software and a device-specific DTM (Device Type Manager).

#### **Features**

- Input for all standard temperature sensors (RTDs and thermocouples), voltage signals, remote resistancetype sensors and potentiometers.
- With intrinsically safe inputs [Ex ia] IIC
- Current and voltage output
- Switching output (1 PDT relay)
- Configuration via software (FDT/DTM) or operator interface (IFS-OP-UNIT)
- Up to SIL 2 according to EN 61508 on output 4 ... 20 mA
- 3-way electrical isolation
- Installation in zone 2 permitted
- Wide range power supply 19.2 ... 253 V AC/DC
- With screw or spring-cage connection



#### **WARNING: Explosion hazard**

The device is an item of associated electrical equipment for intrinsically safe circuits. It is designed for use in zone 2, if specific conditions are observed.

When installing and operating the device, the applicable safety directives (including national safety directives), accident prevention regulations, as well as general technical regulations must be observed.



#### **WARNING: Explosion hazard**

Please observe the safety regulations and installation notes on page 11.



Make sure you always use the latest documentation. It can be downloaded at <a href="https://www.phoenixcontact.net/catalog">www.phoenixcontact.net/catalog</a>.



This data sheet is valid for the products listed in Section 3 "Ordering data".



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## 3 Ordering data

## Temperature transducer, Ex i

Description	Туре	Order No.	Pcs. / Pkt.
Standard configuration/in-stock article, with screw connection	MACX MCR-EX-T-UI-UP	2865654	1
Standard configuration/in-stock article, with spring-cage connection	MACX MCR-EX-T-UI-UP-SP	2924689	1
Order configuration/KMAT, with screw connection	MACX MCR-EX-T-UI-UP-C	2811763	1
Order configuration/KMAT, with spring-cage connection	MACX MCR-EX-T-UI-UP-SP-C	2924692	1

### Accessories

Description	Туре	Order No.	Pcs. / Pkt.
Operator interface for the configuration of compatible MACX modules.	IFS-OP-UNIT	2811899	1
Cradle unit, for snapping the operating and display unit onto the DIN rail	IFS-OP-CRADLE	2811886	1
Programming adapter for MACX MCR devices. With USB interface for programming with the IFS-CONF software	IFS-USB-PROG-ADAPTER	2811271	1
Cold junction compensation connector for thermocouples	MACX MCR-EX-CJC	2925002	1



For additional accessories, please refer to the INTERFACE catalog from Phoenix Contact.

## 4 Order key

Order key for temperature transducer MACX-MCR-EX-T-UI-UP(-SP)-C (standard configuration entered as an example) Factory calibration certificate = FCC Order No. Safety Integrity Level (SIL) Measuring Output range Sensor type Connection Cold junction Measuring range: method compensation End unit Start 2811763 NONE ON PT100 OUT02 -50 150 С 2811763 ≘ 0 = off, e.g. with RTD, R,See °C OUT15 ≘ 0 5 mA ON ≘active See below 2 = 2-wire Sec C ≘ NONE ≘ without FCC MACX MCR-EX-T-UI-UP-C OUT16 = 0...10 mA NONE ≘ not active potentiometer 0 OUT01 = 0...20 mA m۷ ≘ 3 ≘ 3-wire YES ≘ with FCC (a fee is 2924692 ≘ MACX MCR-EX-T-UI-UP-SP-C V ≘ mV OUT25 â 1...5 mA charged) OUT26 = 2...10 mA ON only with output 1 a on, e.g. with TC range = OUT02 OUT05 ≘ 0 5 V YESPLUS ≘ Factory calibration certificate with 5 measuring points OUT03 = 0...10 V (a fee is charged) OUT13 = -5...+5 V OUT14 = -10...+10 V others freely configurable in the software Other setting options can be configured with the IFS-CONF software. Smallest measuring °C Resistance thermometers RTD PT100 -200 850 20 K Freely configurable user characteristic with Others can be selected or are freely Pt 200 acc. to IEC/EN 60751 30 interpolation points PT200 -200 850 20 K configured in the software. PT500 Pt 500 acc. to IEC/EN 60751 -200 850 20 K Output behavior in the event of a short circuit. Pt 1000 acc. to IEC/EN 60751 PT1000 -200 850 20 K sensor break, or overrange/underrange is freely configurable or can be set according to NE43 (standard configuration: NE43 upscale) PT100S Pt 100 acc. to Sama RC21-4-1966 -200 850 20 K Pt 1000 acc. to Sama RC21-4-1966 PT1000S -200 20 K PT100G Pt 100 acc, to GOST 6651 -200 850 20 K PT1000G Pt 1000 acc. to GOST 6651 Pt 100 acc. to JIS C1604/1997 -200 850 20 K Filter setting (standard configuration: 1) PT100.J -200 850 20 K PT1000J NI100 Pt 1000 acc. to JIS C1604/1997 Ni 100 acc. to DIN 43760/DIN IEC 60751 -200 -60 20 K 20 K Restart after failsafe (standard configuration: ON) 250 NI1000 NI100S Ni 1000 acc, to DIN 43760/DIN IEC 60751 Ni 100 acc. to Sama RC21-4-1966 -60 -60 20 K 250 Switching behavior: Switching output ? 180 Ni 1000 acc. to Sama RC21-4-1966 Ni 1000 (Landis & Gyr) (limit values, times, etc.) (standard configuration: OFF) NITOOOS -60 180 20 K -50 NI1000L 160 20 K CU10 CU50 Cu 10 acc. to Sama RC21-4-1966 Cu 50/Cu 100 acc. to GOST 6651 (α = 1.428) -70 500 100 K -50 200 100 K CUS3 Cu 53 acc. to GOST 6651 (α = 1.426) -50 180 100 K KTY81 KTY81-110 (Philips) -55 150 20 K KTY84 -40 300 20 K Thermocouples TC
Others can be selected in the software. acc. to IEC/EN 60584 (Pt30Rh-Pt6Rh) 500 acc. to IEC/EN 60584 (NiCr-CuNi) -230 1000 50 K acc. to IEC/EN 60584 (Fe-CuNi) -210 1200 50 K acc. to IEC/EN 60584 (NiCr-Ni) -250 1372 50 K acc. to IEC/EN 60584 (NiCrSi-NiSi) acc. to IEC/EN 60584 (Pt13Rh-Pt) -250 1300 50 K -50 1768 50 K acc. to IEC/EN 60584 (Pt10Rh-Pt) acc. to IEC/EN 60584 (Cu-CuNi) -50 1768 50 K S -200 400 50 K acc. to DIN 43760 (Fe-CuNi) acc. to DIN 43760 (Cu-CuNi) -200 900 50 K 600  $\mathring{\circ} \mathring{\circ} \mathring{\circ} \mathring{\circ} \mathring{\circ} \mathring{\circ} \mathring{\circ} \mathring{\circ}$ -200 50 K C ASTM JE988 (2002) D ASTM JE988 (2002) CA 0 2315 50 K DA 2315 50 K A1G A-1 GOST 8.585-2001 ٥ 2500 50 K A-2 GOST 8.585-2001 1800 A2G A3G A-3 GOST 8.585-2001 M GOST 8.585-2001 0 1800 50 K -200 100 LG -200 800 50 K RES03 Ω Resistance 0...150 Ω 150 Remote resistance-type sensors R 0 (2-, 3-, 4-wire)
Others can be selected in the software RES05 Resistance 0...600 Ω 600 Ω 10% of the selected Resistance 0...1200 € RES06 0 1200 Resistance 0...6250 Ω 6250 Ω measuring range 0 Resistance 0...12,500 Ω RES10 12500 RES12 ≘ Resistance 0...50,000 Ω 0 50000 Ω POT03 Potentiometer 0...150 Ω 0 100 Potentiometers POT05 Potentiometer 0...600 Ω ٥ 100 Others can be selected in the software Potentiometer 0...1200 Ω POT06 % 10% of the selected 0 100 % % % POT09 Potentiometer 0...6250  $\Omega$ Potentiometer 0...12,500  $\Omega$ 100 measuring range 100 POT12 0 100 Voltage signals mV
Others can be selected in the software. -1000 +1000 10% of nominal

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Temperature conversion guide for °C to °F:

 $T [°F] = \frac{9}{5} T [°C] + 32$ 

## 5 Technical data

5 i ecnnicai data	
Input	
Resistance thermometer	Pt, Ni, Cu sensors: 2-, 3-, 4-wire
Thermocouple sensor	B, E, J, K, N, R, S, T, L, U, CA, DA, A1G, A2G, A3G, MG, LG (see example, "Order key" on page 6)
Resistor	$0~\Omega~~50~k\Omega$
Potentiometer	0 Ω 50 kΩ
Voltage	-1000 mV 1000 mV
Output	
Output signal	4 mA 20 mA with SIL ON (further output signals can be configured with SIL OFF)
Maximum output signal	
Voltage output	±11 V
Current output	22 mA
Load	
Voltage output	≥ 10 kΩ
Current output	$\leq$ 600 $\Omega$ (at 20 mA)
Behavior in the event of a sensor error	According to NE 43 (or freely definable)
Switching output	
Contact type	1 PDT contact
Contact material	AgSnO2, hard gold-plated
Maximum switching voltage	30 V AC (30 V DC)
Maximum switching current	0.5 A (30 V AC) / 1 A (30 V DC)
Cycles	
With ohmic load	1 x 10 <sup>5</sup>
General data	
Supply voltage range	24 V 230 V AC/DC (-20%/+10%, 50/60 Hz)
Current consumption	< 50 mA (24 V DC)
Power consumption	< 1.5 W
Temperature coefficient	0.01 %/K, maximum
Step response (0 99 %)	
With SIL	Typ. 1000 ms
Without SIL	Typ. 700 ms
Transmission error, total	< 0.1% (e.g., for PT100, 300 K span, 4 20 mA)
Electrical isolation	4-way, between input/output/power supply/switching output
Input/output	375 V P (according to EN 60079-11)
Input/power supply	375 V P (according to EN 60079-11)
Input/switching output	375 V P (according to EN 60079-11)
Output/power supply	300 V rms reinforced insulation (according to EN 61010/50178)
Power supply/switching output	300 V rms reinforced insulation (according to EN 61010/50178)
Ambient temperature	coo v into touriored inculation (according to Envertere)
Operation	-20 °C +65°C
Storage/transport	-40 °C +85°C
Permissible humidity (operation)	5% 95% (no condensation)
Shock	15g, IEC 60068-2-27
Vibration	5g, IEC 60068-2-6
Status indicators	Green LED (supply voltage, PWR)
	Red LED, flashing (cable error, sensor error, ERR)
	Red LED (module error, ERR)
	Yellow LED (switching output)
	Tollow LLD (officially output)

General data []		
Housing material	PA 66-FR	
Color	Green	
Degree of protection	IP20	
Pollution degree	2	
Dimensions (width x height x depth)	17.5 x 99 x 114.5 mm	
Inflammability class according to UL 94	V0	
Design	Terminal housing for mounting on DIN rails	

### Conformance

EMC directive 2004/108/EC EN 61326-1; EN 61000-6-2<sup>1</sup>; EN 61000-6-4
Ex directive (ATEX) EN 60079-0, EN 60079-11, EN 60079-15, EN 61241-0, EN 61241-11

<sup>&</sup>lt;sup>1</sup> During the interference, there can possibly be small deviations.

Safety data according to ATEX for intrinsically safe circuits						
Maximum voltage (Uo)	6 V					
Maximum current (Io)		7.4 mA				
Maximum power (Po)	11 mW					
Gas group	Ex ia IIC			Ex ia IIB		
Maximum external inductance (Lo)	100 mH	10 mH	1 mH	100 mH	10 mH	1 mH
Maximum external capacity (Co)	1.3 μF	1.7 μF	2.6 μF	6.8 μF	9.2 μF	15 μF
Maximum internal inductance (Ci)	44 nF	44 nF	44 nF	44 nF	44 nF	44 nF
Maximum internal inductance (Li)	Negligible					
Maximum voltage U <sub>m</sub>	253 V AC	(125 V DC)				

Approvals			
ATEX		IBExU 10 ATEX 1044	
		IBExU 10 ATEX 1044	
IECEx approval	[Ex ia] IIC; [Ex iaD]; Ex nAC ic IIC T4	IECEx IBE 10.0004X	
UL, USA/Canada	Applied for		
Functional safety (SIL)	Can be used up to SIL 2		

Connection data MACX MCR-EX-T-UI-UP	
Conductor cross section	

Solid (minimum/maximum)
Stranded (minimum/maximum)
0.2 mm²/2.5 mm²
0.2 mm²/2.5 mm²
AWG/kcmil (minimum/maximum)
24/14
Stripping length
7 mm
Connection method
Plug-in screw connection
Tightening torque
Minimum 0.5 Nm/maximum 0.6 Nm

### Connection data MACX MCR-EX-T-UI-UP-SP

Conductor cross section

Solid (minimum/maximum)

Stranded (minimum/maximum)

0.2 mm²/1.5 mm²

0.2 mm²/1.5 mm²

AWG/kcmil (minimum/maximum) 24/16 Stripping length 8 mm

Connection method Spring-cage connection

## 6 Minimum span and measuring accuracies

#### 6.1 Pt and Ni-RTD inputs

Minimum measuring span:

With  $10 \Omega \le R0 < 100 \Omega$ : 100 KWith  $100 \Omega \le R0 \le 10 k\Omega$ : 20 K

### Measuring accuracy:

For  $10 \Omega \le R0 < 100 \Omega$ : **0.2 K x 100 \Omega / R0** = 0.1% x (100  $\Omega$ /R0) x (200 K/measuring span)

For  $100 \Omega \le R0 \le 1 \text{ k}\Omega$ : **0.2 K** = 0.1% x (200 K/measuring span) For  $1 \text{ k}\Omega < R0 \le 10 \text{ k}\Omega$ : **0.4 K** = 0.1% x (400 K/measuring span)

#### 6.2 Cu-RTD inputs

Minimum measuring span:

For  $10 \Omega \le R0 < 100 \Omega$ : 100 KFor  $100 \Omega \le R0 \le 10 k\Omega$ : 20 K

### Measuring accuracy:

For 10  $\Omega \le R0 < 100 \Omega$ : **0.5 K x 100 \Omega/R0** = 0.1% x (100  $\Omega$ /R0) x (500 K/measuring span)

For  $100 \Omega \le R0 \le 1 \text{ k}\Omega$ : **0.5 K** = 0.1% x (500 K/measuring span) For  $1 \text{ k}\Omega < R0 \le 10 \text{ k}\Omega$ : **1.0 K** = 0.1% x (1000 K/measuring span)

## 6.3 NI1000 input (Landis & Gyr), KTY 81-110, KTY 84-130 (Philips)

Minimum measuring span: 20 K Measuring accuracy: 0.2 K

#### 6.4 Thermocouple input

Minimum measuring span with TC: 50 K

Measuring accuracy of the input with TC signals:

TC type E, J, K, N, T, L, U, M, Lr Without cold junction error: 0.30 K TC types B, R, S, C, D, A1, A2, A3 Without cold junction error: 0.50 K

## 6.5 Cold junction error

Cold junction error: ± 1 K, maximum (with internal cold junction compensation).

With external compensation it depends on the quality of the cold junction and the sensor used.

#### 6.6 Voltage signal input

Minimum measuring span:

10% of the nominal span of the respective range.

#### Measuring accuracy:

```
-1000 ... 1000 mV : 0.01% (of measuring range)
-500 ... 500 mV : 0.01% (of measuring range)
-250 ... 250 mV : 0.01% (of measuring range)
-125 ... 125 mV : 0.01% (of measuring range)
-60 ... 60 mV : 0.01% (of measuring range)
-30 ... 30 mV : 0.01% (of measuring range)
-15 ... 15 mV : 0.01% (of measuring range)
```

#### 6.7 R transducers and resistors

50% of measuring range ≤ (nominal value of R transducer + lead resistance) ≤ measuring range

Minimum measuring span: 10% of the selected measuring range

#### Measuring accuracy:

0	$75 \Omega : 0.10\%$	(of measuring range)
0	150 $\Omega$ : 0.05%	(of measuring range)
0	$300~\Omega~:0.02\%$	(of measuring range)
0	$600~\Omega~:0.01\%$	(of measuring range)
0	1200 $\Omega : 0.01\%$	(of measuring range)
0	$2400~\Omega~:0.01\%$	(of measuring range)
0	$4800~\Omega~:0.01\%$	(of measuring range)
0	6250 $\Omega$ : 0.02%	(of measuring range)
0	12500 $\Omega$ : 0.02%	(of measuring range)
0	$25000 \ \Omega : 0.02\%$	(of measuring range)
0	$50000 \Omega : 0.02\%$	(of measuring range)

#### Example:

R transducer with nominal value: 1000  $\Omega$  Measuring range to be selected: 0 ... 1200  $\Omega$ 

Minimum measuring span: 10% of the selected measuring

range =  $120 \Omega$ 

Measuring accuracy: 0.01% of the selected measuring

range =  $120 \text{ m}\Omega$ 

#### 6.8 Potentiometer

50% of measuring range ≤ (nominal value of potentiometer + lead resistance) ≤ measuring range

Minimum measuring span: 10% of the selected measuring range

#### Measuring accuracy:

```
0 ...
          75 \Omega : 0.10\%
                          (of measuring range)
0 ...
         150 \Omega : 0.05\%
                          (of measuring range)
0 ...
         300 \Omega : 0.02\%
                          (of measuring range)
0 ...
         600 \Omega : 0.02\% (of measuring range)
       1200 Ω: 0.02% (of measuring range)
0 ...
0 ...
       2400 \Omega: 0.02\% (of measuring range)
       4800 \Omega: 0.02\% (of measuring range)
0 ...
       6250 \Omega : 0.10\% (of measuring range)
0 \dots 12500 \Omega : 0.10\%
                          (of measuring range)
0 ... 25000 Ω: 0.10%
                          (of measuring range)
0 \dots 50000 \Omega : 0.10\%
                          (of measuring range)
```

#### Example:

Potentiometer with nominal value: 1000  $\Omega$  Measuring range to be selected: 0 ... 1200  $\Omega$ 

Minimum measuring span: 10% of the selected measuring

range =  $120 \Omega$ 

Measuring accuracy: 0.02% of the selected measuring

range = 240 m $\Omega$ 

#### 6.9 Output signals

## Analog output error

## 7 Safety regulations and installation notes

## 7.1 Installation and operation



## WARNING: Sensor does not conform to the specification

Make sure that the connected sensors are only used in the specified area (see "Order key" on page 6).



#### **WARNING: Sensor wiring**

Check the structure for functionally correct wiring (see "Basic circuit diagrams" on page 13).

Follow the installation instructions.



**NOTE:** Installation, operation, and maintenance may only be carried out by qualified specialist personnel.

When installing and operating the device, the applicable safety directives (including national safety directives), accident prevention regulations, as well as general technical regulations must be observed.



### NOTE:

Do not open the device or making changes to it. Do not repair the device yourself; replace it with an equivalent device. Repairs may only be performed by the manufacturer. The manufacturer is not liable for damage resulting from violation.



**NOTE:** The IP20 degree of protection (IEC 60529/EN 60529) of the device is intended for use in a clean and dry environment. Do not subject the device to mechanical and/or thermal loads that exceed the specified limits.



NOTE: Only specified devices from Phoenix Contact may be connected to the 12-pos. S-PORT interface.

For safety data, please refer to this data sheet and the certificates (EC-type examination certificate, and other approvals, if necessary).

## 7.2 Safety regulations for installation in potentially explosive areas

Regulations for intrinsically safe circuits



#### **WARNING: Explosion hazard**

The devices are approved for intrinsically safe (Ex i) circuits up to zone 0 (gas) and Ex zone 20 (dust). The technical safety values of the intrinsically safe field devices have to match the specifications of this package slip or otherwise the EC-type examination certificate.



## **WARNING: Explosion hazard**

If the device has been used in non-intrinsically safe circuits, it must not be used again in intrinsically safe circuits. Label the device clearly as being not intrinsically safe.



#### **WARNING: Explosion hazard**

If the device has been used in non-intrinsically safe circuits, it must not be used again in intrinsically safe circuits. Label the device clearly as being not intrinsically safe.

### Installation in zone 2



#### **WARNING: Explosion hazard**

The device is associated equipment of the Exiprotection type and is suitable for installation in zone 2.

Observe the specified conditions for use in potentially explosive areas.



#### WARNING: Explosion hazard

Install the device in a suitable, approved **housing** with a minimum of IP54 degree of protection. At the same time, observe IEC 60079-14/EN 60079-14 requirements.



#### **WARNING: Explosion hazard**

Disconnect the block power supply **before**:

 Connecting or disconnecting cables of nonintrinsically safe circuits.



## WARNING: Explosion hazard

Use only category 3G modules (ATEX 94/9/EC).



#### **WARNING: Explosion hazard**

The device must be stopped and immediately removed from the Ex area if it is damaged, was subjected to an impermissible load, stored incorrectly or if it malfunctions.

## Installation in areas with a danger of dust explosions



#### WARNING: Explosion hazard

The device is **not** designed for installation in areas with a danger of dust explosions.

Connection to the intrinsically safe circuit in areas with a danger of dust explosions (zones 20, 21 and 22) is only permitted if the equipment connected to this circuit is approved for this zone (e.g., category 1D, 2D or 3D).



## **WARNING: Explosion hazard**

If, however, you wish to use the device in zone 22, it must be installed in a housing that complies with IEC/EN 61241-1. In doing so, observe the maximum surface temperatures. Observe the requirements of IEC/EN 61241-14.



**NOTE:** Install the device in a suitable housing with IP54 protection.

#### 7.3 Use in safety-related applications (SIL 2)

When using the MACX MCR-EX-T-UI-UP... in safety-related applications, observe the instructions in the appendix, as the requirements differ for safety-related functions.



The switching output is not intended for safety-related applications.

### 8 Installation



### **NOTE: Electrostatic discharge!**

The device contains components that can be damaged or destroyed by electrostatic discharge. When handling the device, observe the necessary safety precautions against electrostatic discharge (ESD) according to EN 61340-5-1 and EN 61340-5-2.

Take precautions against electrostatic discharge before opening the front cover.

## 8.1 Basic circuit diagrams

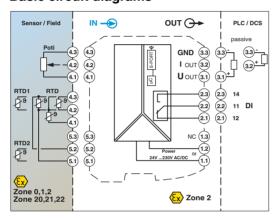


Figure 1 Sensor connection - resistance thermometers and potentiometers

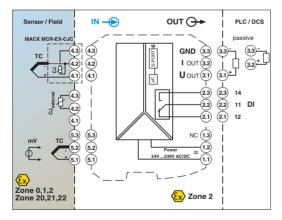


Figure 2 Sensor connection - thermocouples and mV sources

#### 8.2 Structure

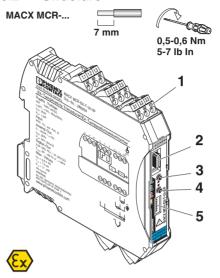


Figure 3 Structure MACX MCR-EX-T-UI-UP MACX MCR-...-SP

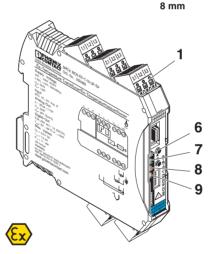


Figure 4 Structure MACX MCR-EX-T-UI-UP-SP

- 1 Plug-in COMBICON connectors
- **2** S-PORT (12-pos. programming interface)
- 3 Button S3 (UP), adjustment and reset functions
- 4 Button S2 (DOWN), adjustment and reset functions
- 5 DIP switch S1 for service mode
- 6 PWR LED, green, power supply
- 7 DAT LED, green, no function at present
- **8** LED ERR, red, module, cable and sensor error, underrange or overrange, service mode
- 9 DO LED, yellow, status of switching output

#### 8.3 Dimensions

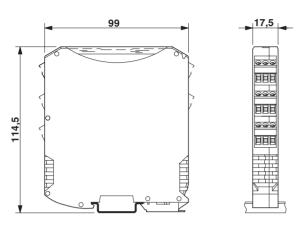


Figure 5 Dimensions (in mm)

### 8.4 Mounting



#### **WARNING: Explosion hazard**

If the module has been used in non-intrinsically safe circuits, it must not be used again in intrinsically safe circuits.

The module must be clearly labeled as non-intrinsically safe.

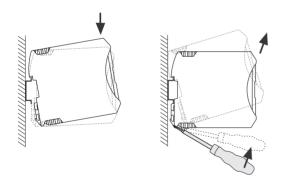


Figure 6 Mounting and removal

- Mount the module on a 35 mm DIN rail according to EN 60715.
- Install the module in a suitable housing to meet the requirements for the protection class.
- Before startup, check for correct function and wiring of the MACX MCR-EX-T-UI-UP..., in particular the wiring and marking of the intrinsically safe circuits.

#### 8.5 Connecting the cables

- Screw terminal blocks (for MACX MCR-EX-T-UI-UP);
   litz wires provided with ferrules.
  - Permissible cable cross section: 0.2 mm<sup>2</sup> to 2.5 mm<sup>2</sup>
- Spring-cage terminal blocks (for MACX MCR-EX-T-UI-UP-SP); litz wires provided with ferrules.
  - Permissible cable cross section: 0.2 mm<sup>2</sup> to 1.5 mm<sup>2</sup>
- Install intrinsically safe and non-intrinsically safe cables separately.

#### - Screw connection:

- Insert the conductor into the corresponding connection terminal block.
- Use a screwdriver to tighten the screw in the opening above the connection terminal block.

#### Spring-cage connection:

- Insert a screwdriver into the opening above the connection terminal block.
- Insert the conductor into the corresponding connection terminal block.

#### 8.6 Power supply

The power supply has been designed as a wide range power supply (19.2 ... 253 V AC/DC). The module is supplied with voltage via connection terminal blocks 1.1 and 1.2.

#### 8.7 Sensor types

The sensor types that can be used and their specific properties can be found in Section "Order key" on page 6

Depending on the connection method, the following terminal points are to be connected for temperature measurement (see Figure 1 on page 13).

## 8.7.1 Thermocouple (TC) with internal cold junction compensation

Thermocouple connection: Terminals 4.1 "+", 4.2 "-"



Use the MACX MCR-EX-CJC cold junction compensation connector provided (Order No. 2925002).



TC+CJ: Use the cold junction compensation connector provided at connection terminal blocks 4.1, 4.2 and 4.3.

## 8.7.2 Thermocouple (TC) with external or without cold junction compensation

- Thermocouple connection: Terminals 5.1 "+", 5.2 "-"



TC+CJ external: Use the external cold junction compensation sensor (e.g., PT100) at connection terminal blocks 4.2 and 4.3.

#### 8.7.3 Voltage input

Connection: Terminals 5.1 "+", 5.2 "-"

#### 8.7.4 Potentiometer

Connection: Terminals 4.1, 4.2, 4.3

#### 8.7.5 Resistance thermometer (RTD)



RL  $\leq$  25  $\Omega$  for each lead.

- 2-wire connection method: Terminals 4.2, 4.3
   The cable resistance can be compensated with the help of the IFS-CONF PC program, the IFS-OP-UNIT operator interface or in service mode (DIP switch).
- 3-wire connection method: Terminals 4.1, 4.2, 4.3
   In the case of the 3-wire connection method, ensure that all three cable resistances are the same.
- 4-wire connection method: Terminals 4.2, 4.3, 5.1, 5.2
- 2 x 2-wire connection method

Terminals RTD 1: 4.2, 4.3 Terminals RTD 2: 5.1, 5.2

#### 8.7.6 Measuring resistances



Up to 75  $\Omega$ : RL  $\leq$  2.5  $\Omega$  for each lead. Up to 150  $\Omega$ : RL  $\leq$  5  $\Omega$  for each lead. Up to 300  $\Omega$ : RL  $\leq$  10  $\Omega$  for each lead.

The terminal points 4.2 and 4.3 are used for measuring differing resistances.

#### 8.8 Current output

The current output can be freely configured between 0 and 20 mA. The minimum span is 4 mA. In safety-related applications (SIL = ON), the output is fixed at 4 ... 20 mA.

- Connection: Terminals 3.2 "+", 3.3 "-"

## 8.9 Voltage output



The voltage output cannot be used for safety-related applications (SIL = ON).

The voltage output can be freely configured between -10 and +10 V. The minimum span is 2 V.

Connection: Terminals 3.1 "+". 3.3 "-"

#### 8.10 Switching output

Switching output 1 has one PDT. The behavior of the switching output can be selected. The switching points SPL<sup>1</sup> and SPH<sup>2</sup> can be configured across the entire sensor range:

## Switching behavior of the switching output

#### Switching behavior 0



Switching output is permanently dropped.

#### Switching behavior 1



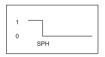
Switching output is permanently picked up.

#### Switching behavior 2



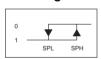
Switching output picks up when SPH<sup>2</sup> is exceeded.

#### **Switching behavior 3**



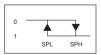
Switching output drops out when  $SPH^2$  is underrange.

### Switching behavior 4



Switching output picks up when SPL<sup>2</sup> is exceeded and drops out when SPH<sup>1</sup> is underrange (hysteresis).

#### Switching behavior 5



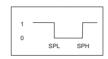
Switching output drops out when SPL<sup>2</sup> is exceeded and picks up when SPH<sup>1</sup> is underrange (hysteresis).

### Switching behavior 6



Switching output picks up between SPL<sup>1</sup> and SPH<sup>2</sup>.

#### Switching behavior 7



Switching output drops out between SPL<sup>1</sup> and SPH<sup>2</sup>.

- <sup>1</sup> SPL = Set Point Low (lower switching point)
- <sup>2</sup> SPH = Set Point High (upper switching point)



The switching output is not intended for safety-related applications.



If only the switching output is to be used, the current output (connection terminal blocks 3.2 and 3.3) must be short circuited or subjected to a load.

## 8.11 Switching output behavior with manual acknowledgement (latching)



Latching: No automatic restart after exceeding limit value (SPH: SET Point High) or falling below limit value (SPL: Set Point Low).

Disable the option "Restart after fail safe" in the configuration software.

## 8.11.1 Switching behavior (2): Undertemperature limit (≤ SPH)



#### Normal operating state > SPH

riorman operating ettator et it				
Step	Measure			
1	Measured	> SPH and module are acti-		
	value	vated		
2	Relay	ON		
3	Measured	≤SPH		
	value			
4	Relay	OFF		
5	Measured value	> SPH		
6	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.		

### Critical operating state ≤ SPH

Step	Measure	
1	Measured	≤ SPH and module are acti-
	value	vated
2	Relay	OFF
3	Measured	> SPH
	value	
4	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally
	<b>]</b>   ti	Acknowledgement is only possible when here is no critical state anymore and the deay time has passed.

## 8.11.2 (Switching behavior (3): Overtemperature limit (≥ SPH)



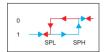
#### Normal operating state < SPH

	Tromai sporating state vol. ii				
Step	Measure				
1	Measured	< SPH and module are acti-			
	value	vated			
2	Relay	ON			
3	Measured	≥SPH			
	value				
4	Relay	OFF			
5	Measured value	< SPH			
6	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally			
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

## Critical operating state ≥ SPH

	- p			
Step	Measure			
1	Measured	≥ SPH and module are acti-		
	value	vated		
2	Relay	OFF		
3	Measured	< SPH		
	value			
4	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	there is	ledgement is only possible when no critical state anymore and the dehas passed.		

## 8.11.3 Switching behavior (4): Undertemperature limit with hysteresis (≤ SPL)



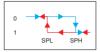
### Normal operating state > SPL

to man operating states of 2					
Step	Measure				
1	Measured	> SPL and module are acti-			
	value	vated			
2	Relay	ON			
3	Measured value	≤SPL			
4	Relay	OFF			
5	Measured value	> SPH			
6	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally			
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

## Critical operating state ≤ SPL

Step	Measure				
1	Measured value	d	≤ SPL and module are activated		
2	Relay		OFF		
3	Measured value	k	> SPH		
4	Relay		Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	i	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

## 8.11.4 Switching behavior (5): Overtemperature limit with hysteresis (≥ SPH)



### Normal operating state < SPH

	Tromai operating state ver m				
Step	Measure				
1	Measured	< SPH and module are acti-			
	value	vated			
2	Relay	ON			
3	Measured	≥ SPH			
	value				
4	Relay	OFF			
5	Measured value	< SPL			
6	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally			
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

## Critical operating state ≥ SPH

Step	Measure			
1	Measured value	≥ SPH and module are activated		
_				
2	Relay	OFF		
3	Measured	< SPL		
	value			
4	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	there is n	edgement is only possible when o critical state anymore and the de- as passed.		

## 8.11.5 Switching behavior (6): Temperature range limit (≤ SPL and ≥ SPH)



#### Normal operating state > SPL and < SPH

rtormar operating state > or 2 and < or ri				
Step	Measure			
1	Measured	> SPL and < SPH module		
	value	are activated		
2	Relay	ON		
3	Measured value	≤ SPL or ≥ SPH		
4	Relay	OFF		
5	Measured value	> SPL or < SPH		
6	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.		

## Critical operating state ≤ SPL and ≥ SPH

1	Measured value		≤ SPL and module are activated		
		b)	≥ SPH and module are activated		
2	Relay		OFF		
3	Measured		> SPL and < SPH		
	value b)		< SPH and > SPL		
4	Relay		Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	i	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

## 8.11.6 Switching behavior (7): Temperature range limit (≥ SPL and ≤ SPH)



## Normal operating state < SPL and > SPH

Step	Measure			
1	l	< SPL and module are acti-		
	value	vated		
	b,	> SPH and module are acti-		
		vated		
2	Relay	ON		
3	Measured a	≥ SPL and ≤ SPH		
	value b	≤ SPH and ≥ SPL		
4	Relay	OFF		
5	Measured value	< SPL or > SPH		
6	Relay	Remains OFF (latches) until		
		delay time has passed and		
		then acknowledged manu-		
		ally		
	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.			

#### Critical operating state ≥ SPL and ≤ SPH

ormour operating state 2 or 2 and 2 or 1				
Step	Measure			
1	Measured value	≥ SPL and ≤ SPH and mod- ule are activated		
	value	ule are activated		
2	Relay	OFF		
3	Measured	< SPL or > SPH		
	value			
4	Relay	Remains OFF (latches) until delay time has passed and then acknowledged manu- ally		
	there is no	Acknowledgement is only possible when there is no critical state anymore and the delay time has passed.		

#### 8.12 Monitoring function

The temperature transducer is equipped with monitoring functions for the input and output range.

#### Input monitoring function

The input monitoring function for line break and short circuit refers to the sensor connected to the input. When an error is detected, the output signal is set to the configured error value. In the case of RTD sensors and resistance-type sensors, short-circuit failures are detected resistance values < 1  $\Omega$ .

Short circuits of thermocouples and mV sources cannot be detected, since 0 V can be a valid signal.

On RTD sensors, resistance-type sensors and potentiometers, a line break is detected when the current flow through the sensor is faulty.

As soon as the fault has been eliminated, the temperature transducer continues to perform its normal functions. (see "LED status indicators" on page 22, Line faults)

#### **Output monitoring function**

The current output can be monitored for line breaks and maximum load. This is activated via the configuration. In safety-related applications (SIL = ON), the output monitoring is always active. The voltage output is not monitored. As soon as the fault has been eliminated, the temperature transducer continues to perform its normal functions. (see "LED status indicators" on page 22, Line faults)

### 8.13 Operating modes



If the configuration is modified using the IFS-OP-UNIT operator interface and PC-based software (e.g., IFS-CONF) or via DIP switch, the changes made must always be checked again and released before transfer to the temperature transducer.

After the transfer, the new data in the temperature transducer is applied by means of activation and a warm start.

#### 8.13.1 SIL ON/SIL OFF

The temperature transducer can either be operated in SIL ON or SIL OFF. The standard configuration is SIL ON with DIP switch S1 set to the OFF position. With the order configuration, customer-specific configurations can be selected in the order key (see "Order key" on page 6).

#### 8.13.2 Service mode

Service mode can be selected at any time via the IFS-OP-UNIT operator interface and the configuration software, e.g., IFS-CONF or via DIP switch S1.

If settings are changed during service mode and service mode is then exited, the temperature transducer performs a warm start in order to apply the newly set values. If no changes are made, the transducer starts up in normal measuring mode without a warm start. The switching output switches according to its configuration.

In service mode, it is also possible to simulate the output signal independently of the input signal (force). In this case, in safety-related applications the safety function of the device is deactivated and the initial value for the analog output signal is 2 mA, which allows subsequent devices to detect the deviation from normal operation as a result of the measured value being underrange.

During service mode, the switching output is deactivated and remains in its idle position.

## 9 Configuration



#### **WARNING: Explosion hazard**

When configuring in zone 2, the PC used must be approved for use in zone 2.

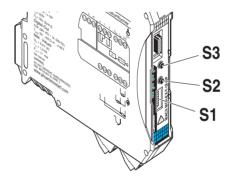


Figure 7 Position of the DIP switch and buttons



When a DIP switch from S1-2 ... S1-8 (ON) is switched on, the device is switched to service mode. The red ERR LED flashes (1.2 Hz) and a diagnostic I/O fault is displayed in the start screen.

## 9.1 Delivered state/standard configuration

Switch position DIP-S1								
1	1 2 3 4 5 6 7 8							
OFF	OFF OFF OFF OFF OFF OFF							

## 9.2 Zero adjust, adjustment via buttons S2 and S3 (only possible with SIL OFF)

- Set the adjustment by setting DIP switch S1-2 to ON.
- Observe the analog output and set it with button S2 (descending value) or S3 (ascending value) or

press the buttons S2 and S3 simultaneously time for > 3 seconds to reset the cable compensation.

 Save the set value by setting DIP switch S1-2 back to OFF.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF

## 9.3 Span adjust, adjustment via buttons 2 and 4 (only possible with SIL OFF)

- Set the adjustment by setting DIP switch S1-3 to ON.
- Observe the analog output and set it with button S2 (descending value) or S3 (ascending value)

press the buttons S2 and S3 simultaneously time for > 3 seconds to reset the cable compensation.

- Save the set value by setting DIP switch S1-3 back to OFF.
- Pressing buttons S2 and S3 simultaneously for > 3 seconds resets the adjustment.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF

### 9.4 Force output



When SIL is activated, the analog output starts at 2 mA and the switching output is deactivated.

- Set the adjustment by setting DIP switch S1-4 to ON.
- Observe the analog output and set with the S2 (descending value) or S3 (ascending value) button.
- The specification/simulation is reset and ended by setting DIP switch S1-4 back to OFF.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	OFF	OFF	ON	OFF	OFF	OFF	OFF

## 9.5 Cable compensation, 2-wire RTD or RTD 1 with 2 x RTD

- Set the cable compensation RTD 1 via DIP switches S1-1 to OFF and S1-5 to ON.
- Short circuit the sensor.
- Apply the current measured value as the cable resistance by pressing the S2 button.
- Save the set value by setting DIP switch S1-5 back to OFF.

Pressing buttons S2 and S3 simultaneously for > 3 seconds resets the cable compensation.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	OFF	OFF	OFF	ON	OFF	OFF	OFF

# 9.6 Cable compensation RTD 2 with 2 x RTD or TC with external cold junction compensation (TC + CJ external)

- Set the cable compensation RTD 2 via DIP switches S1-1 to ON and S1-5 to ON.
- · Short circuit the sensor.
- Apply the current measured value as the cable resistance by pressing the S2 button.
- Save the set value by setting DIP switches S1-1 and S1-5 back to OFF.

Pressing buttons S2 and S3 simultaneously for > 3 seconds resets the cable compensation.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
ON	OFF	OFF	OFF	ON	OFF	OFF	OFF

## 9.7 Automatic potentiometer adjustment (teach-in)

- Set the teach-in by setting DIP switch S1-6 to ON.
- Set potentiometer to start of range.
- Press the S2 button.
- Set potentiometer to end of range.
- Press the S3 button.
- Save the new measuring range by setting DIP switch S1-6 back to OFF.

Pressing buttons S2 and S3 simultaneously for > 3 seconds resets both values.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	OFF	OFF	OFF	OFF	ON	OFF	OFF

## 9.8 Manual acknowledgement of switching outputs (latch function)

- Set manual acknowledgment by setting DIP switch S1-7 to ON.
- Press buttons S2 and S3 simultaneously for > 3 seconds.
- Reset DIP switch S1-7 to OFF.

Switch position DIP-S1							
1	2	3	4	5	6	7	8
OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF

### 9.9 LED status indicators

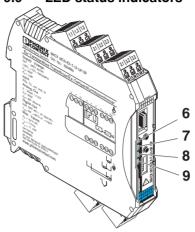


Figure 8 LED status indicators

No.	LED	Color	Description
6	PWR	Green	Supply voltage
		ON	Indicates the readiness for opera-
			tion of the temperature trans-
			ducer if supply voltage is available.
			The temperature transducer is
			configured without device supply
			via programming adapter IFS- USB-PROG-ADAPTER.
7	DAT	Cuasa	
7	DAT	Green	No function at present
8	ERR	Red	Error
		ON	Module error
		Flashing	Service mode active
		(1.2 Hz)	
		flashing	Line fault
		(2.4 Hz)	
9	DO	Yellow	Switching output 1
		ON	Switching output active

## 10 Password

The device is protected by means of a four-digit password set in the factory in order to prevent impermissible changes to the configuration.

Default setting: 1111



For safety-related applications, the password set in the factory must always be changed.

If the password is lost, it is not possible to reset it. In this case, please contact Phoenix Contact.

If, however, only data from the device is to be displayed or the device is to be used in non-safety-related applications, the password can be deactivated.

Setting: 0000

The device can be accessed either via the IFS-OP-UNIT (Order No.: 2811899) or via a service PC with connected programming adapter IFS-USB-PROG-ADAPTER (Order No.: 2811271) and the IFS-CONF configuration software.



Further information on configuration with the IFS-OP-UNIT or the IFS-CONF configuration software can be found in the relevant user manual.



**WARNING:** If *Functional Safety* is activated by a reconfiguration or changes are made to the active *Functional Safety* configuration, the rules under Installation and startup must be observed.



## WARNING: Limitations on safety-related applications

Only 4 ... 20 mA, limited programming of output current in the event of line faults (2 mA  $\leq$  I<sub>Out</sub>  $\leq$  3.6 mA or I<sub>Out</sub>  $\geq$  21 mA)



**WARNING:** Once new configuration data has been written, the device performs a warm start that changes the properties of the device. The following control device must be adapted to these modifications.



**NOTE:** Transfer and activate the configuration after the password has been changed.

## 11 Flow chart, operator interface

#### Configuration with the IFS-OP-UNIT

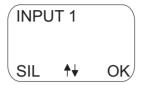
If you wish to use the MACX MCR-EX-T-UI-UP in combination with the IFS-OP-UNIT and with the IFS-OP-CRADLE,

the various operating functions that can be selected are shown in the display.

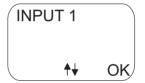


When active, the SIL functionality is displayed in the start screen.

**Example: Display of SIL ON** 



**Example: Display of SIL OFF** 





For safety reasons, the SIL function cannot be switched on again via the IFS-OP-UNIT operator interface.



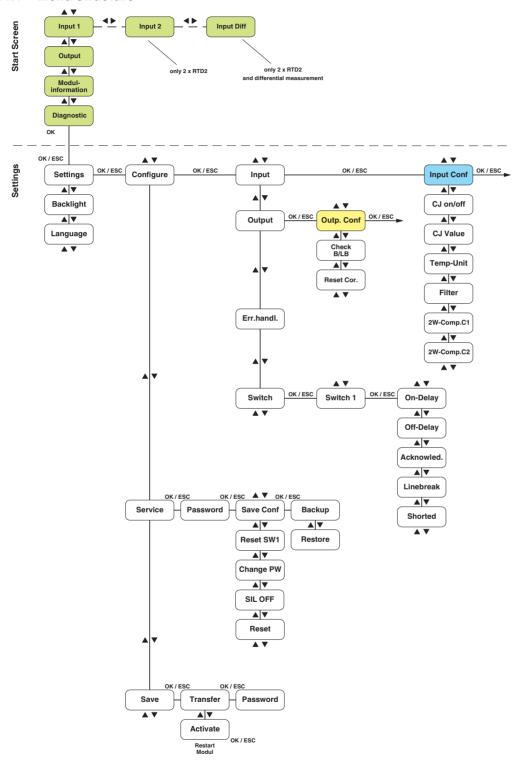
SIL can be switched off/deactivated via the SIL OFF menu item.

To reactivate/switch on the SIL function, PC-based configuration software, e.g., IFS-CONF is required.



If no input is entered for five minutes during configuration, the configuration is ended and any unsaved data will be lost.

### 11.1 Menu structure



### 11.2 Key for start screen

**Input Diff** 

Modul-

information

Diagnostic

Settings

Display of input and output signals, module and diagnostic information.

Input 1 Display of the actual value of input 1

Display of the actual value of input 2, only if a second RTD is configured with the 2-wire connection

Display of the actual value of the differential measurement with 2 x RTD with the 2-wire connection method.

Output Display of the actual value of the analog output

Display of module information (order designation, firmware version, config version)

Module diagnostics (simulation, module error, I/O error)

## 11.3 Key for SETTINGS - MENU

The active configuration is read out from the module.

Backlight Setting for the background illumination (on, off, autodim)

Language Setting for the menu language (English, German)

### 11.4 Key for SETTINGS - Configure

**Configure** Configuration of input, output, fault behavior and switching outputs