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FEATURES:

- Guaranteed Low Skew < 40ps (max)
- Very low duty cycle distortion < 125ps (max)
- High speed propagation delay < 1.75ns (max)
- Additive phase jitter, RMS 0.159ps (typical) @ 125MHz
- Up to 1GHz operation
- Selectable inputs
- Hot insertable and over-voltage tolerant inputs
- 3.3V / 2.5V LVTTTL, HSTL, eHSTL, LVEPECL (2.5V), LVPECL (3.3V), CML, or LVDS input interface
- Selectable differential inputs to six LVDS outputs
- Power-down mode
- 2.5V V_{DD}
- Available in VFQFPN package

APPLICATIONS:

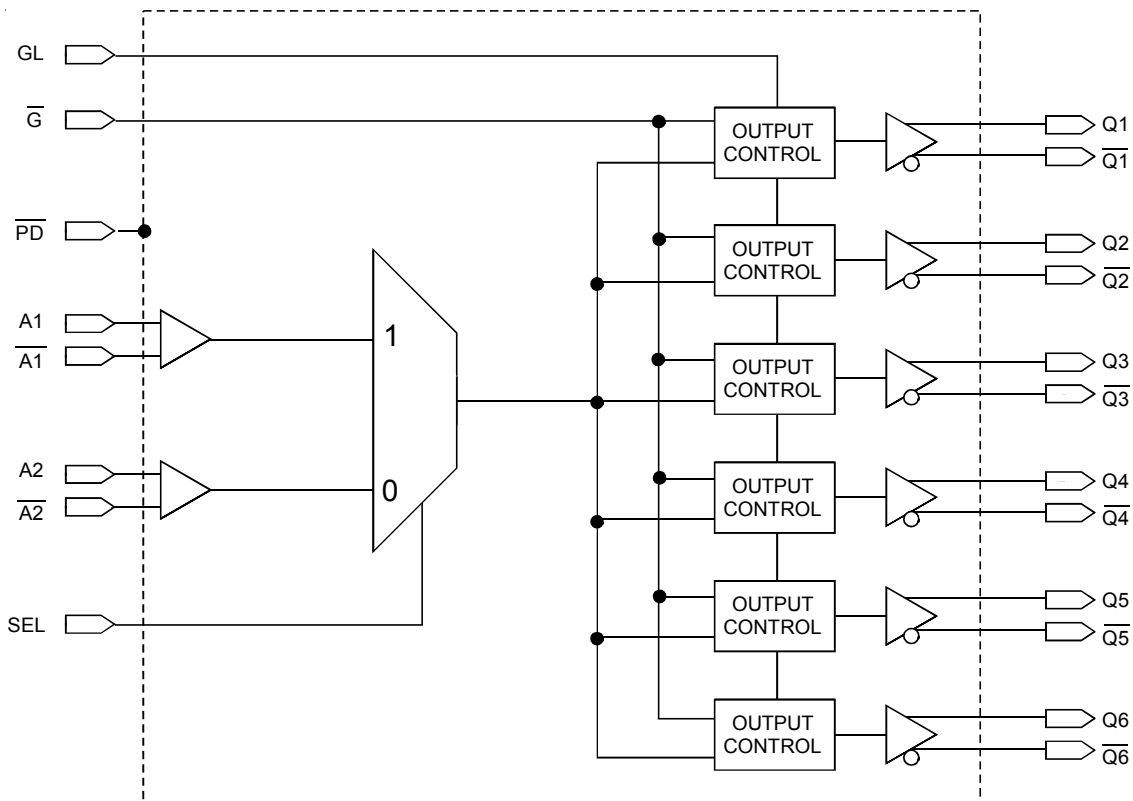
- Clock distribution

DESCRIPTION:

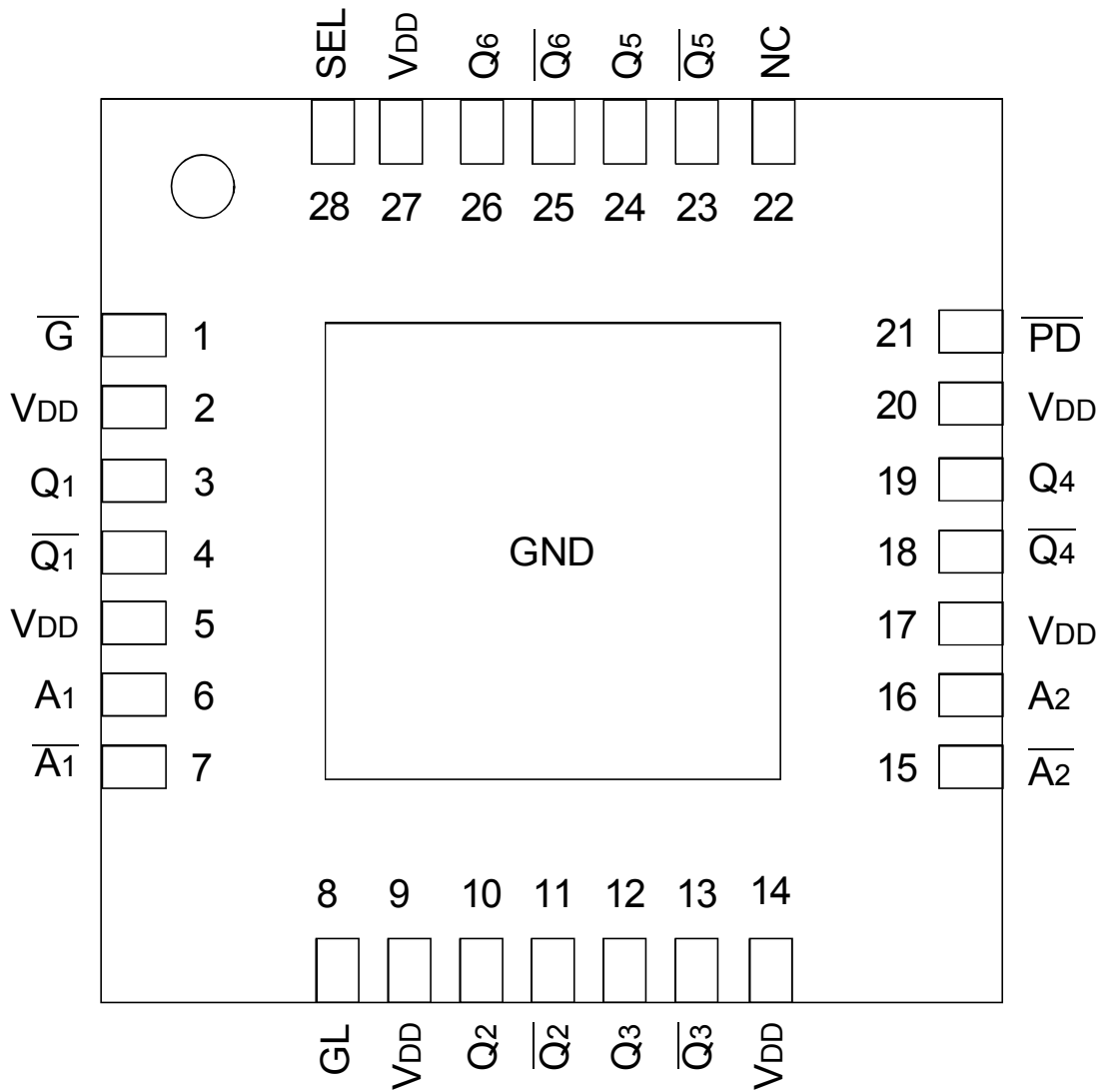
The IDT5T9306 2.5V differential clock buffer is a user-selectable differential input to six LVDS outputs. The fanout from a differential input to six LVDS outputs reduces loading on the preceding driver and provides an efficient clock distribution network. The IDT5T9306 can act as a translator from a differential HSTL, eHSTL, LVEPECL (2.5V), LVPECL (3.3V), CML, or LVDS input to LVDS outputs. A single-ended 3.3V / 2.5V LVTTTL input can also be used to translate to LVDS outputs. The redundant input capability allows for an asynchronous change-over from a primary clock source to a secondary clock source. Selectable reference inputs are controlled by SEL.

The IDT5T9306 outputs can be asynchronously enabled/disabled. When disabled, the outputs will drive to the value selected by the GL pin. Multiple power and grounds reduce noise.

FUNCTIONAL BLOCK DIAGRAM



PIN CONFIGURATION



VFQFPN
TOP VIEW

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

| Symbol | Description | Max | Unit |
|------------------|-------------------------------|------------------------------|------|
| V _{DD} | Power Supply Voltage | -0.5 to +3.6 | V |
| V _I | Input Voltage | -0.5 to +3.6 | V |
| V _O | Output Voltage ⁽²⁾ | -0.5 to V _{DD} +0.5 | V |
| T _{STG} | Storage Temperature | -65 to +150 | °C |
| T _J | Junction Temperature | 150 | °C |

NOTES:

- Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- Not to exceed 3.6V.

CAPACITANCE⁽¹⁾ (T_A = +25°C, F = 1.0MHz)

| Symbol | Parameter | Min | Typ. | Max. | Unit |
|-----------------|-------------------|-----|------|------|------|
| C _{IN} | Input Capacitance | — | — | 3 | pF |

NOTE:

- This parameter is measured at characterization but not tested

RECOMMENDED OPERATING RANGE

| Symbol | Description | Min. | Typ. | Max. | Unit |
|-----------------|-------------------------------|------|------|------|------|
| T _A | Ambient Operating Temperature | -40 | +25 | +85 | °C |
| V _{DD} | Internal Power Supply Voltage | 2.3 | 2.5 | 2.7 | V |

PIN DESCRIPTION

| Symbol | I/O | Type | Description |
|----------------------------|-----|-----------------------------|---|
| A _[1:2] | I | Adjustable ^(1,4) | Clock input. A _[1:2] is the "true" side of the differential clock input. |
| \bar{A} _[1:2] | I | Adjustable ^(1,4) | Complementary clock inputs. \bar{A} _[1:2] is the complementary side of A _[1:2] . For LVTTTL single-ended operation, \bar{A} _[1:2] should be set to the desired toggle voltage for A _[1:2] : 3.3V LVTTTL V _{REF} = 1650mV 2.5V LVTTTL V _{REF} = 1250mV |
| \bar{G} | I | LVTTTL | Gate control for differential outputs Q ₁ and \bar{Q} ₁ through Q ₆ and \bar{Q} ₆ . When \bar{G} is LOW, the differential outputs are active. When \bar{G} is HIGH, the differential outputs are asynchronously driven to the level designated by GL ⁽²⁾ . |
| GL | I | LVTTTL | Specifies output disable level. If HIGH, "true" outputs disable HIGH and "complementary" outputs disable LOW. If LOW, "true" outputs disable LOW and "complementary" outputs disable HIGH. |
| Q _n | O | LVDS | Clock outputs |
| \bar{Q} _n | O | LVDS | Complementary clock outputs |
| SEL | I | LVTTTL | Reference clock select. When LOW, selects A ₂ and \bar{A} ₂ . When HIGH, selects A ₁ and \bar{A} ₁ . |
| \bar{P} _D | I | LVTTTL | Power-down control. Shuts off entire chip. If LOW, the device goes into low power mode. Inputs and outputs are disabled. Both "true" and "complementary" outputs will pull to V _{DD} . Set HIGH for normal operation. ⁽³⁾ |
| V _{DD} | | PWR | Power supply for the device core and inputs |
| GND | | PWR | Power supply return for all power |
| NC | | | No connect; recommended to connect to GND |

NOTES:

- Inputs are capable of translating the following interface standards:
 - Single-ended 3.3V and 2.5V LVTTTL levels
 - Differential HSTL and eHSTL levels
 - Differential LVEPECL (2.5V) and LVPECL (3.3V) levels
 - Differential LVDS levels
 - Differential CML levels
- Because the gate controls are asynchronous, runt pulses are possible. It is the user's responsibility to either time the gate control signals to minimize the possibility of runt pulses or be able to tolerate them in down stream circuitry.
- It is recommended that the outputs be disabled before entering power-down mode. It is also recommended that the outputs remain disabled until the device completes power-up after asserting \bar{P} _D.
- The user must take precautions with any differential input interface standard being used in order to prevent instability when there is no input signal.

DC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE FOR LVTTTL⁽¹⁾

| Symbol | Parameter | Test Conditions | Min. | Typ. ⁽²⁾ | Max | Unit |
|------------------------------|---|---|------|---------------------|------|------|
| Input Characteristics | | | | | | |
| I _{IH} | Input HIGH Current | V _{DD} = 2.7V | — | — | ±5 | μA |
| I _{IL} | Input LOW Current | V _{DD} = 2.7V | — | — | ±5 | |
| V _{IK} | Clamp Diode Voltage | V _{DD} = 2.3V, I _{IN} = -18mA | — | -0.7 | -1.2 | V |
| V _{IN} | DC Input Voltage | | -0.3 | — | +3.6 | V |
| V _{IH} | DC Input HIGH | | 1.7 | — | — | V |
| V _{IL} | DC Input LOW | | — | — | 0.7 | V |
| V _{THI} | DC Input Threshold Crossing Voltage | | — | V _{DD} /2 | — | V |
| V _{REF} | Single-Ended Reference Voltage ⁽³⁾ | 3.3V LVTTTL | — | 1.65 | — | V |
| | | 2.5V LVTTTL | — | 1.25 | — | V |

NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. Typical values are at V_{DD} = 2.5V, +25°C ambient.
3. For A_[1:2] single-ended operation, $\bar{A}_{[1:2]}$ is tied to a DC reference voltage.

DC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE FOR DIFFERENTIAL INPUTS⁽¹⁾

| Symbol | Parameter | Test Conditions | Min. | Typ. ⁽²⁾ | Max | Unit |
|------------------------------|---|---|------|---------------------|-----------------|------|
| Input Characteristics | | | | | | |
| I _{IH} | Input HIGH Current | V _{DD} = 2.7V | — | — | ±5 | μA |
| I _{IL} | Input LOW Current | V _{DD} = 2.7V | — | — | ±5 | |
| V _{IK} | Clamp Diode Voltage | V _{DD} = 2.3V, I _{IN} = -18mA | — | -0.7 | -1.2 | V |
| V _{IN} | DC Input Voltage | | -0.3 | — | +3.6 | V |
| V _{DIF} | DC Differential Voltage ⁽³⁾ | | 0.1 | — | — | V |
| V _{CM} | DC Common Mode Input Voltage ⁽⁴⁾ | | 0.05 | — | V _{DD} | V |

NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. Typical values are at V_{DD} = 2.5V, +25°C ambient.
3. V_{DIF} specifies the minimum input differential voltage (V_{TR} - V_{CP}) required for switching where V_{TR} is the "true" input level and V_{CP} is the "complement" input level. The DC differential voltage must be maintained to guarantee retaining the existing HIGH or LOW input. The AC differential voltage must be achieved to guarantee switching to a new state.
4. V_{CM} specifies the maximum allowable range of (V_{TR} + V_{CP}) /2.

DC ELECTRICAL CHARACTERISTICS OVER RECOMMENDED OPERATING RANGE FOR LVDS⁽¹⁾

| Symbol | Parameter | Test Conditions | Min. | Typ. ⁽²⁾ | Max | Unit |
|-------------------------------|---|--|-------|---------------------|-------|------|
| Output Characteristics | | | | | | |
| V _{OT(+)} | Differential Output Voltage for the True Binary State | | 247 | — | 454 | mV |
| V _{OT(-)} | Differential Output Voltage for the False Binary State | | 247 | — | 454 | mV |
| ΔV _{OT} | Change in V _{OT} Between Complementary Output States | | — | — | 50 | mV |
| V _{OS} | Output Common Mode Voltage (Offset Voltage) | | 1.125 | 1.2 | 1.375 | V |
| ΔV _{OS} | Change in V _{OS} Between Complementary Output States | | — | — | 50 | mV |
| I _{OS} | Outputs Short Circuit Current | V _{OUT+} and V _{OUT-} = 0V | — | 12 | 24 | mA |
| I _{OSD} | Differential Outputs Short Circuit Current | V _{OUT+} = V _{OUT-} | — | 6 | 12 | mA |

NOTES:

1. See RECOMMENDED OPERATING RANGE table.
2. Typical values are at V_{DD} = 2.5V, T_A = +25°C ambient.

DIFFERENTIAL INPUT AC TEST CONDITIONS FOR HSTL

| Symbol | Parameter | Value | Units |
|---------------------------------|---|----------------|-------|
| V _{DIF} | Input Signal Swing ⁽¹⁾ | 1 | V |
| V _X | Differential Input Signal Crossing Point ⁽²⁾ | 750 | mV |
| D _H | Duty Cycle | 50 | % |
| V _{THI} | Input Timing Measurement Reference Level ⁽³⁾ | Crossing Point | V |
| t _R , t _F | Input Signal Edge Rate ⁽⁴⁾ | 2 | V/ns |

NOTES:

1. The 1V peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_{DIF} (AC) specification under actual use conditions.
2. A 750mV crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_X specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

DIFFERENTIAL INPUT AC TEST CONDITIONS FOR eHSTL

| Symbol | Parameter | Value | Units |
|---------------------------------|---|----------------|-------|
| V _{DIF} | Input Signal Swing ⁽¹⁾ | 1 | V |
| V _X | Differential Input Signal Crossing Point ⁽²⁾ | 900 | mV |
| D _H | Duty Cycle | 50 | % |
| V _{THI} | Input Timing Measurement Reference Level ⁽³⁾ | Crossing Point | V |
| t _R , t _F | Input Signal Edge Rate ⁽⁴⁾ | 2 | V/ns |

NOTES:

1. The 1V peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_{DIF} (AC) specification under actual use conditions.
2. A 900mV crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_X specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

DIFFERENTIAL INPUT AC TEST CONDITIONS FOR LVEPECL (2.5V) AND LVPECL (3.3V)

| Symbol | Parameter | Value | Units |
|---------------------------------|---|----------------|-------|
| V _{DIF} | Input Signal Swing ⁽¹⁾ | 732 | mV |
| V _X | Differential Input Signal Crossing Point ⁽²⁾ | LVEPECL | 1082 |
| | | LVPECL | 1880 |
| D _H | Duty Cycle | 50 | % |
| V _{THI} | Input Timing Measurement Reference Level ⁽³⁾ | Crossing Point | V |
| t _R , t _F | Input Signal Edge Rate ⁽⁴⁾ | 2 | V/ns |

NOTES:

1. The 732mV peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_{DIF} (AC) specification under actual use conditions.
2. 1082mV LVEPECL (2.5V) and 1880mV LVPECL (3.3V) crossing point levels are specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_X specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

DIFFERENTIAL INPUT AC TEST CONDITIONS FOR LVDS

| Symbol | Parameter | Value | Units |
|---------------------------------|---|----------------|-------|
| V _{DIF} | Input Signal Swing ⁽¹⁾ | 400 | mV |
| V _X | Differential Input Signal Crossing Point ⁽²⁾ | 1.2 | V |
| D _H | Duty Cycle | 50 | % |
| V _{THI} | Input Timing Measurement Reference Level ⁽³⁾ | Crossing Point | V |
| t _R , t _F | Input Signal Edge Rate ⁽⁴⁾ | 2 | V/ns |

NOTES:

1. The 400mV peak-to-peak input pulse level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_{DIF} (AC) specification under actual use conditions.
2. A 1.2V crossing point level is specified to allow consistent, repeatable results in an automatic test equipment (ATE) environment. This device meets the V_X specification under actual use conditions.
3. In all cases, input waveform timing is marked at the differential cross-point of the input signals.
4. The input signal edge rate of 2V/ns or greater is to be maintained in the 20% to 80% range of the input waveform.

AC DIFFERENTIAL INPUT SPECIFICATIONS⁽¹⁾

| Symbol | Parameter | Min. | Typ. | Max | Unit |
|------------------|--|------|------|-----------------|------|
| V _{DIF} | AC Differential Voltage ⁽²⁾ | 0.1 | — | 3.6 | V |
| V _{IX} | Differential Input Crosspoint Voltage | 0.05 | — | V _{DD} | V |
| V _{CM} | Common Mode Input Voltage Range ⁽³⁾ | 0.05 | — | V _{DD} | V |
| V _{IN} | Input Voltage | -0.3 | | +3.6 | V |

NOTES:

1. The output will not change state until the inputs have crossed and the minimum differential voltage range defined by V_{DIF} has been met or exceeded.
2. V_{DIF} specifies the minimum input voltage (V_{TR} - V_{CP}) required for switching where V_{TR} is the "true" input level and V_{CP} is the "complement" input level. The AC differential voltage must be achieved to guarantee switching to a new state.
3. V_{CM} specifies the maximum allowable range of (V_{TR} + V_{CP}) / 2.

POWER SUPPLY CHARACTERISTICS FOR LVDS OUTPUTS⁽¹⁾

| Symbol | Parameter | Test Conditions | Typ. | Max | Unit |
|------------------|--|--|------|-----|------|
| I _{DDQ} | Quiescent V _{DD} Power Supply Current | V _{DD} = Max., All Input Clocks = LOW ⁽²⁾ Outputs enabled | — | 240 | mA |
| I _{TOT} | Total Power V _{DD} Supply Current | V _{DD} = 2.7V., F _{REFERENCE CLOCK} = 1GHz | — | 250 | mA |
| I _{PD} | Total Power Down Supply Current | \overline{PD} = LOW | — | 5 | mA |

NOTES:

1. These power consumption characteristics are for all the valid input interfaces and cover the worst case conditions.
2. The true input is held LOW and the complementary input is held HIGH.

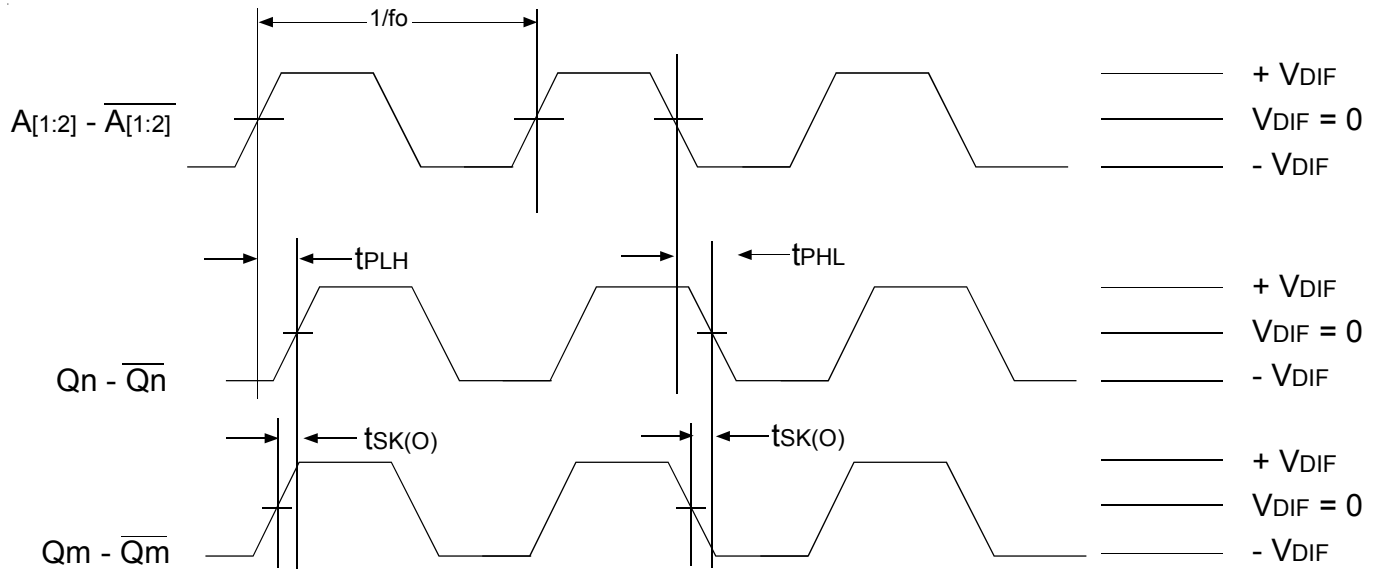
AC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE^(1,5)

| Symbol | Parameter | Min. | Typ. | Max | Unit |
|---|--|------|-------|------|------|
| Skew Parameters | | | | | |
| t _{SK(O)} | Same Device Output Pin-to-Pin Skew ⁽²⁾ | — | — | 40 | ps |
| t _{SK(P)} | Pulse Skew ⁽³⁾ | — | — | 125 | ps |
| t _{SK(PP)} | Part-to-Part Skew ⁽⁴⁾ | — | — | 300 | ps |
| Propagation Delay | | | | | |
| t _{PLH} | Propagation Delay A, \bar{A} Crosspoint to Q _n , \bar{Q}_n Crosspoint | — | 1.25 | 1.75 | ns |
| t _{PHL} | | | | | |
| f _O | Frequency Range ⁽⁶⁾ | — | — | 1 | GHz |
| Output Gate Enable/Disable Delay | | | | | |
| t _{PGE} | Output Gate Enable Crossing V _{THI} to Q _n / \bar{Q}_n Crosspoint | — | — | 3.5 | ns |
| t _{PGD} | Output Gate Disable Crossing V _{THI} to Q _n / \bar{Q}_n Crosspoint Driven to GL Designated Level | — | — | 3.5 | ns |
| Power Down Timing | | | | | |
| t _{PWRDN} | $\bar{P}\bar{D}$ Crossing V _{THI} to Q _n = V _{DD} , \bar{Q}_n = V _{DD} | — | — | 100 | μS |
| t _{PWRUP} | Output Gate Disable Crossing V _{THI} to Q _n / \bar{Q}_n Driven to GL Designated Level | — | — | 100 | μS |
| RMS Additive Phase Jitter | | | | | |
| t _{JIT} | RMS Additive Phase Jitter @ 25MHz (12kHz – 10MHz Integration Range) | | 0.541 | | ps |
| | RMS Additive Phase Jitter @ 125MHz (12kHz – 20MHz Integration Range) | | 0.159 | | ps |
| | RMS Additive Phase Jitter @ 156.25MHz (12kHz – 20MHz Integration Range) | | 0.185 | | ps |
| Output Rise/Fall Time | | | | | |
| t _R /t _F | Output Rise/Fall Time ⁽⁶⁾ , (20% - 80%) | 125 | | 600 | ps |

NOTES:

1. AC propagation measurements should not be taken within the first 100 cycles of startup.
2. Skew measured between crosspoints of all differential output pairs under identical input and output interfaces, transitions and load conditions on any one device.
3. Skew measured is the difference between propagation delay times t_{PHL} and t_{PLH} of any differential output pair under identical input and output interfaces, transitions and load conditions on any one device.
4. Skew measured is the magnitude of the difference in propagation times between any single differential output pair of two devices, given identical transitions and load conditions at identical V_{DD} levels and temperature.
5. All parameters are tested with a 50% input duty cycle.
6. Guaranteed by design but not production tested.

DIFFERENTIAL AC TIMING WAVEFORMS



Output Propagation and Skew Waveforms

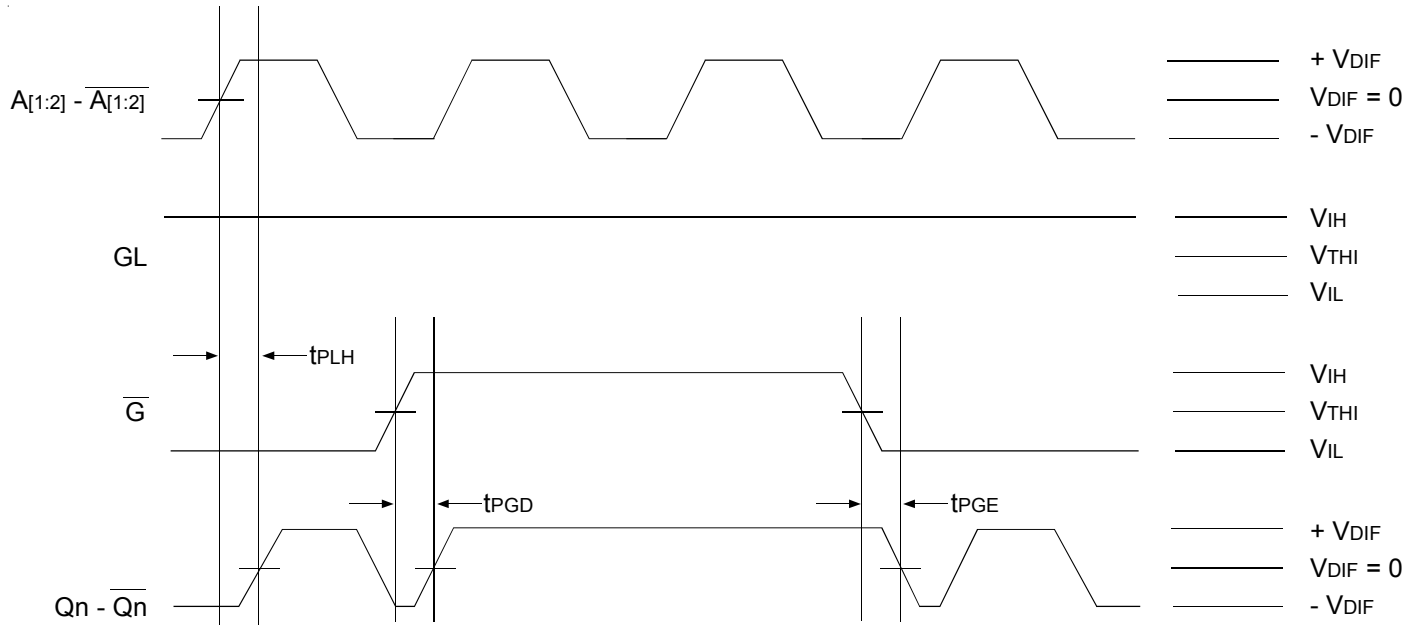
NOTES:

1. Pulse skew is calculated using the following expression:

$$t_{SK(P)} = |t_{PHL} - t_{PLH}|$$

Note that the t_{PHL} and t_{PLH} shown above are not valid measurements for this calculation because they are not taken from the same pulse.

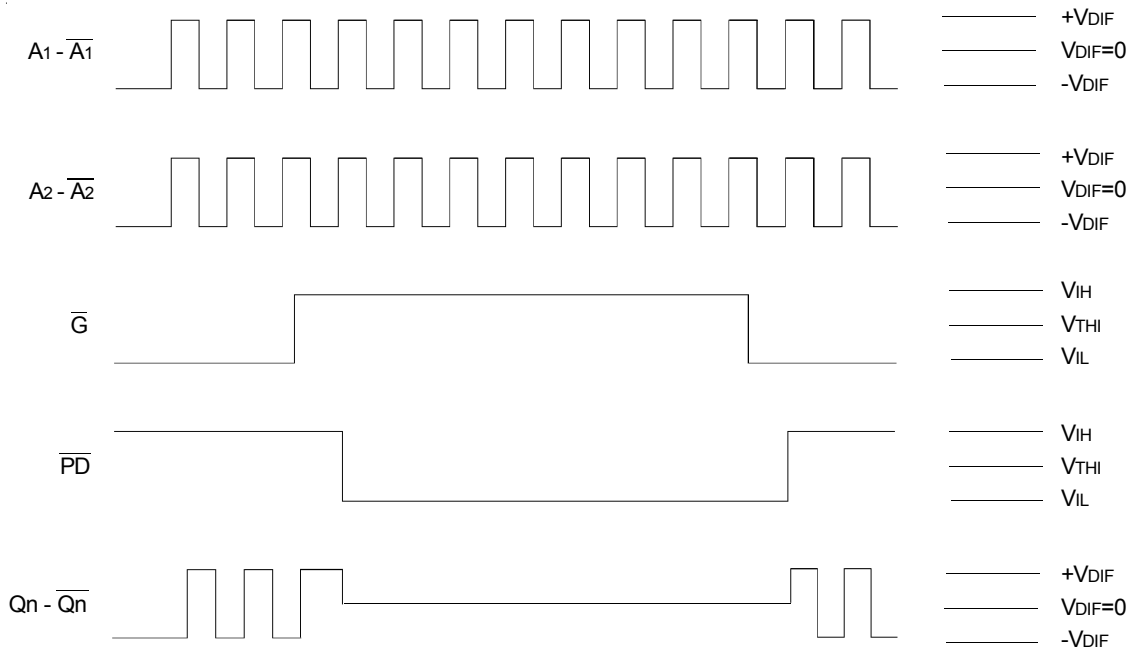
2. AC propagation measurements should not be taken within the first 100 cycles of startup.



Differential Gate Disable/Enable Showing Runt Pulse Generation

NOTE:

1. As shown, it is possible to generate runt pulses on gate disable and enable of the outputs. It is the user's responsibility to time the \bar{G} signal to avoid this problem.

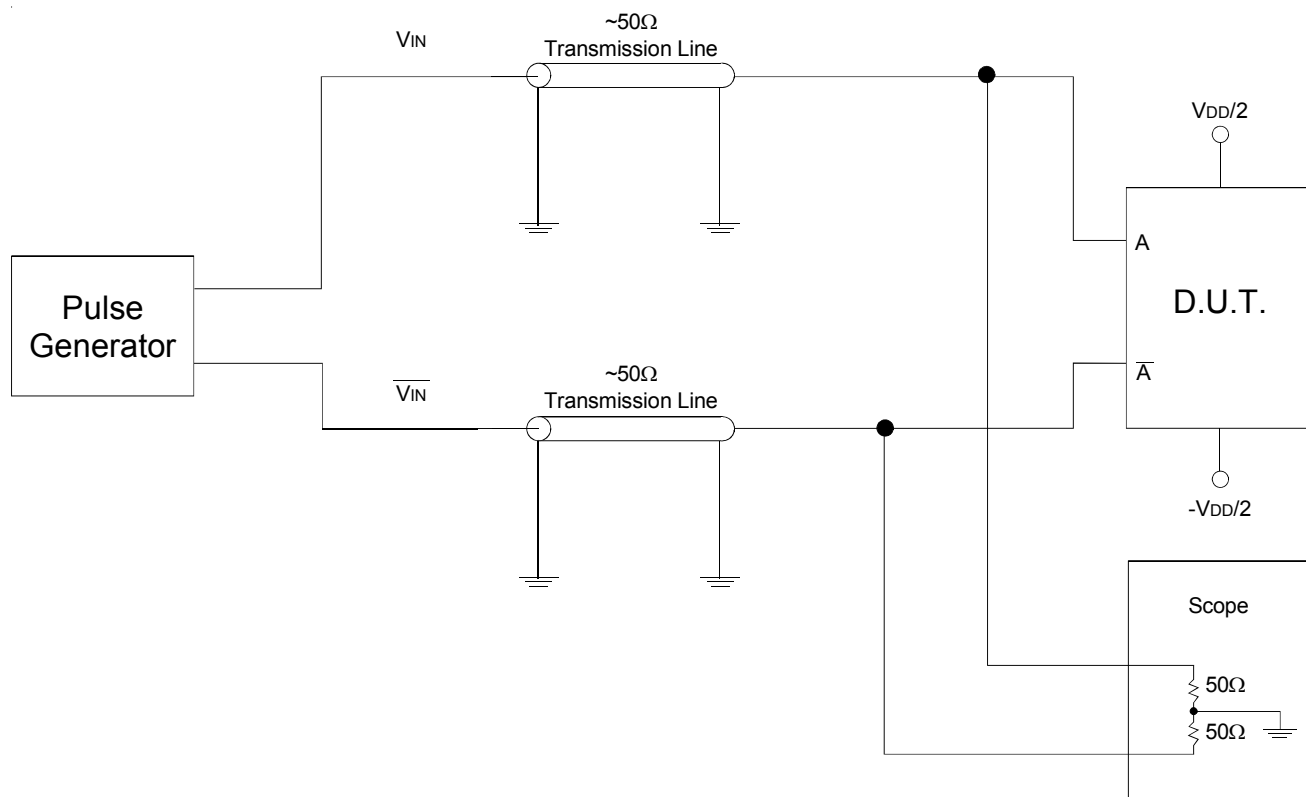


Power Down Timing

NOTES:

1. It is recommended that outputs be disabled before entering power-down mode. It is also recommended that the outputs remain disabled until the device completes power-up after asserting \bar{PD} .
2. The POWER DOWN TIMING diagram assumes that GL is HIGH.
3. It should be noted that during power-down mode, the outputs are both pulled to V_{DD} . In the POWER DOWN TIMING diagram this is shown when $Q_n - \bar{Q}_n$ goes to $V_{DIF} = 0$.

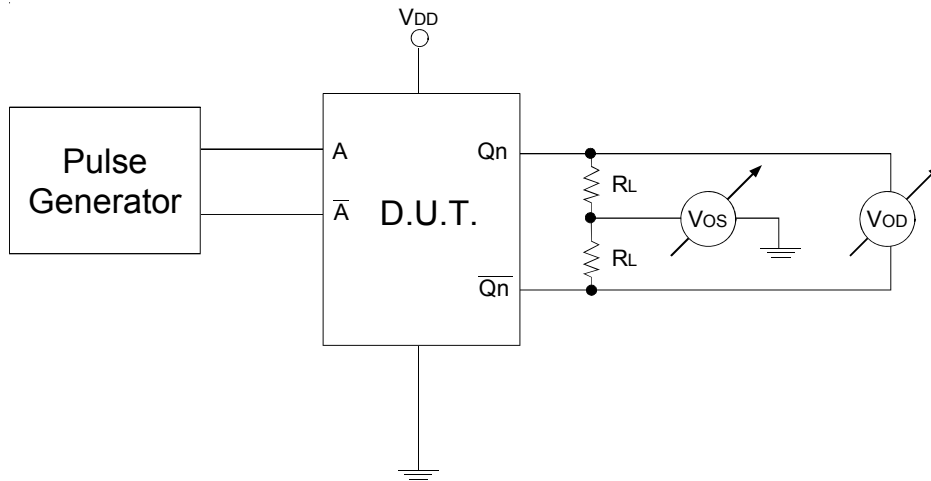
TEST CIRCUITS AND CONDITIONS



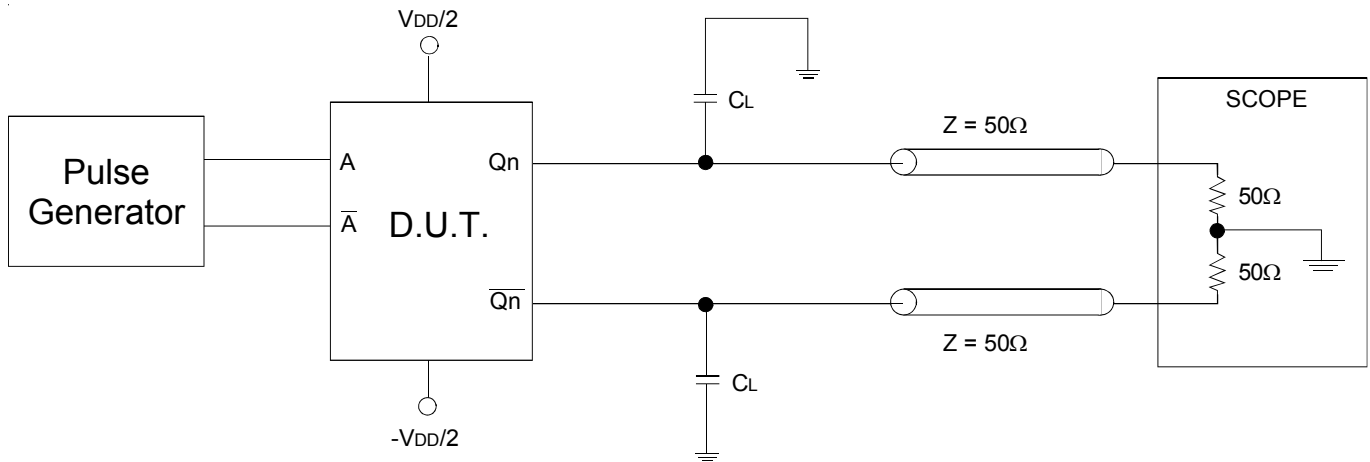
Test Circuit for Differential Input

DIFFERENTIAL INPUT TEST CONDITIONS

| Symbol | $V_{DD} = 2.5V \pm 0.2V$ | Unit |
|-----------|----------------------------------|------|
| V_{THI} | Crossing of A and \overline{A} | V |



Test Circuit for DC Outputs and Power Down Tests



Test Circuit for Propagation, Skew, and Gate Enable/Disable Timing

LVDS OUTPUT TEST CONDITION

| Symbol | $V_{DD} = 2.5V \pm 0.2V$ | Unit |
|--------|--------------------------|----------|
| CL | 0 ⁽¹⁾ | pF |
| | 8 ^(1,2) | |
| RL | 50 | Ω |

NOTES:

1. Specifications only apply to "Normal Operations" test condition. The T_{IA}/E_{IA} specification load is for reference only.
2. The scope inputs are assumed to have a 2pF load to ground. T_{IA}/E_{IA} - 644 specifies 5pF between the output pair. With $C_L = 8pF$, this gives the test circuit appropriate 5pF equivalent load.

VFQFPN EPAD THERMAL RELEASE PATH

In order to maximize both the removal of heat from the package and the electrical performance, a land pattern must be incorporated on the Printed Circuit Board (PCB) within the footprint of the package corresponding to the exposed metal pad or exposed heat slug on the package, as shown in *Figure 1*. The solderable area on the PCB, as defined by the solder mask, should be at least the same size/shape as the exposed pad/slug area on the package to maximize the thermal/electrical performance. Sufficient clearance should be designed on the PCB between the outer edges of the land pattern and the inner edges of pad pattern for the leads to avoid any shorts.

While the land pattern on the PCB provides a means of heat transfer and electrical grounding from the package to the board through a solder joint, thermal vias are necessary to effectively conduct from the surface of the PCB to the ground plane(s). The land pattern must be connected to ground

through these vias. The vias act as “heat pipes”. The number of vias (i.e. “heat pipes”) are application specific and dependent upon the package power dissipation as well as electrical conductivity requirements. Thus, thermal and electrical analysis and/or testing are recommended to determine the minimum number needed. Maximum thermal and electrical performance is achieved when an array of vias is incorporated in the land pattern. It is recommended to use as many vias connected to ground as possible. It is also recommended that the via diameter should be 12 to 13mils (0.30 to 0.33mm) with 1oz copper via barrel plating. This is desirable to avoid any solder wicking inside the via during the soldering process which may result in voids in solder between the exposed pad/slug and the thermal land. Precautions should be taken to eliminate any solder voids between the exposed heat slug and the land pattern. Note: These recommendations are to be used as a guideline only. For further information, refer to the Application Note on the *Surface Mount Assembly* of Amkor’s Thermally/Electrically Enhance Leadframe Base Package, Amkor Technology.

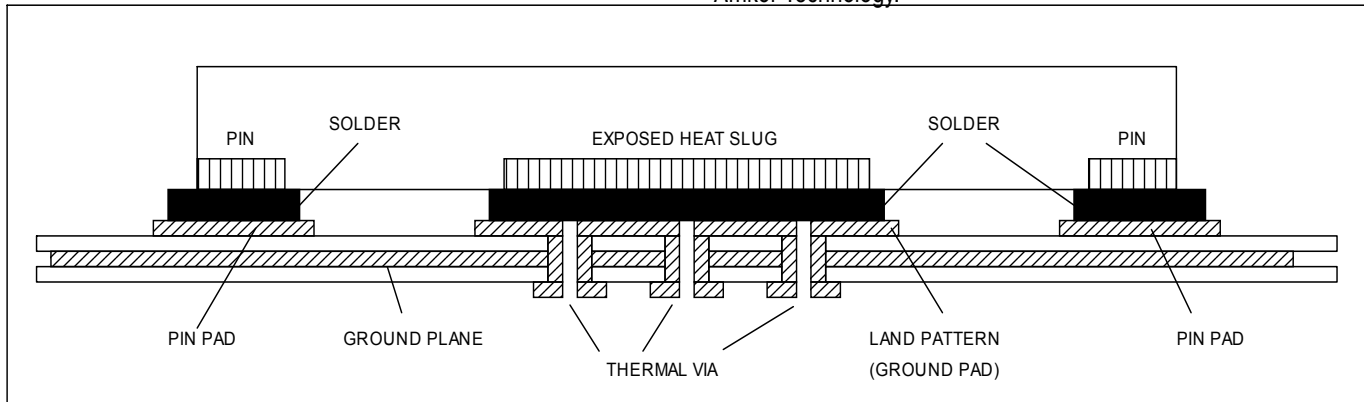


FIGURE 1. P.C.ASSEMBLY FOR EXPOSED PAD THERMAL RELEASE PATH –SIDE VIEW (DRAWING NOT TO SCALE)

SCHEMATIC LAYOUT

Figure 2 shows an example of IDT5T9306 schematic. In this example, the device is operated at $V_{DD} = 2.5V$. As with any high speed analog circuitry, the power supply pins are vulnerable to random noise. To achieve optimum jitter performance, power supply isolation is required.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1µF capacitor in each power pin filter should be placed on the device side of the PCB and the other components can be placed on the opposite side.

Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the

devices. The filter performance is designed for a wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10kHz. If a specific frequency noise component is known, such as switching power supplies frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitance in the local area of all devices.

The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure that the logic control inputs are properly set.

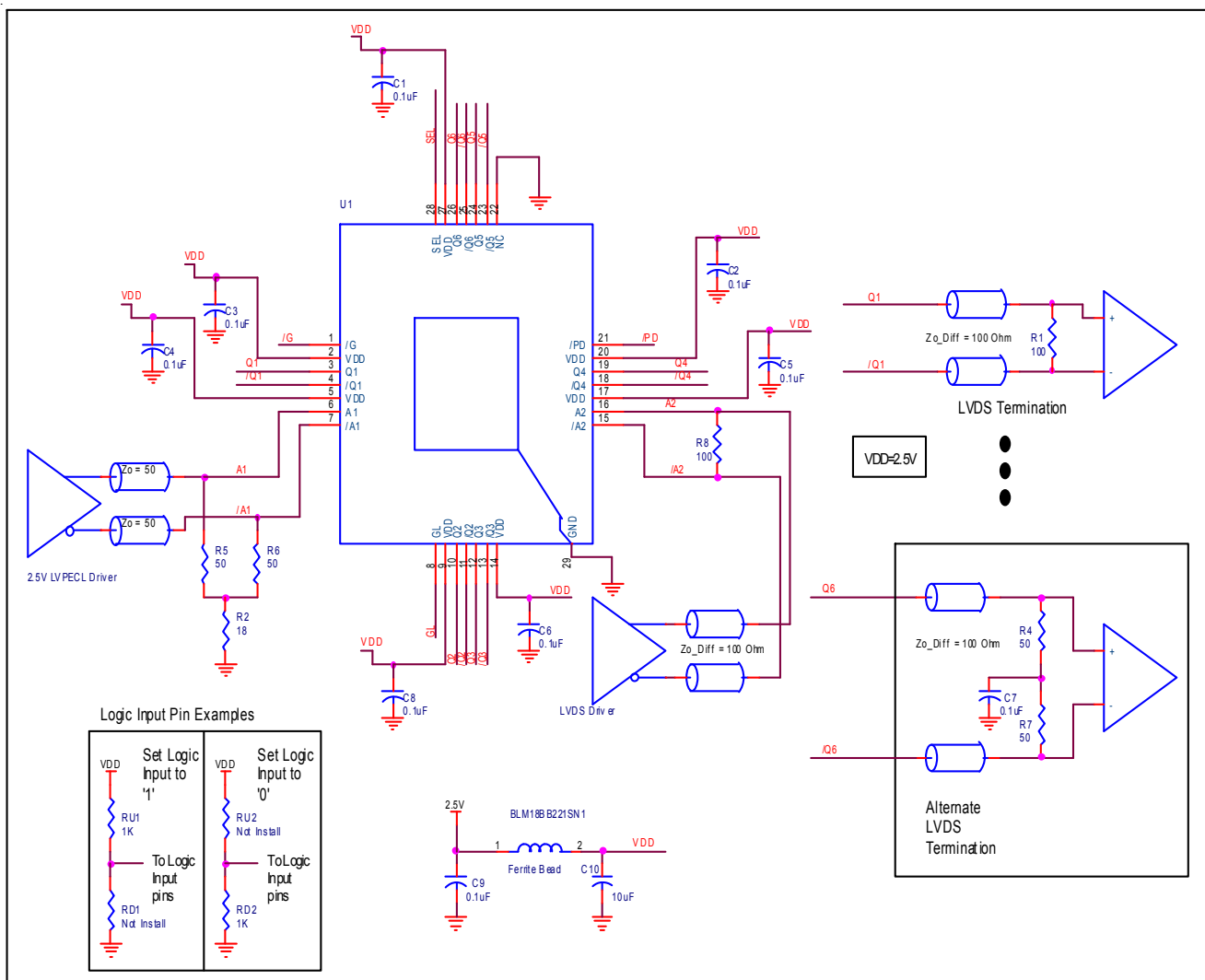
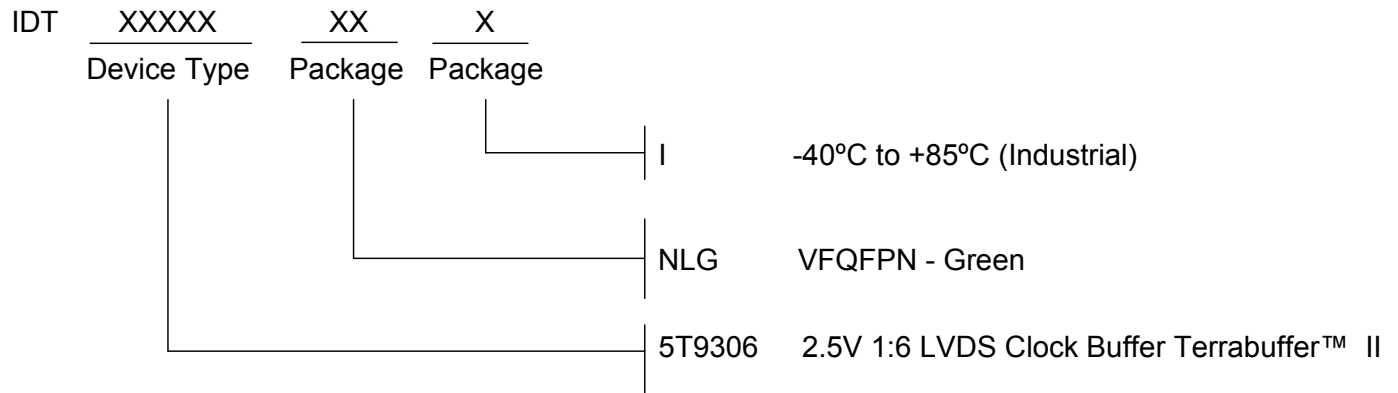


FIGURE 2. IDT5T9306 SCHEMATIC EXAMPLE

REVISION HISTORY SHEET

| | |
|-------------------|---|
| July 23, 2002 | Datasheet creation |
| October 8, 2002 | Page 1, entire page changed; page 2, both diagrams; page 3, Pin Description and notes; page 4, DC Cha. for LVPECL and Differential Input tables; page 6, DC Cha. and Power Supply tables; page 7, entire page; page 9, added note 3; page 10, entire page; page 11, entire page; page 12, Ordering Info; added 3 new pages (10 thru 12) of diagrams. |
| October 10, 2002 | Page 1, entire page changed; page 2, both diagrams; page 3, Pin Description and notes; page 7, AC Cha. table; page 8, added new LVPECL table; page 10, removed Input Clock Switching diagram; page 11, deleted entire page; page 12, changed Power Down Timing; page 15, Ordering Info. |
| October 24, 2002 | Page 2, added note 1 to TQFP TOP VIEW text; page 3, added note 4 to Pin Description; page 4, replaced "Compliant devices must meet" with the text "This device meets" in four instances; page 5, Differential Input table, note 1, changed 1V to 732mV and replaced "Compliant devices must meet" with the text "This device meets"; page 6, DC Electrical table, Vdif row, changed Min. value to 0.1, and under Differential Input table replaced "Compliant devices must meet" with the text "This device meets" page 7, Power Supply table, replaced ((TBD)) with 800MHz, and under AC Electrical table, replaced ((TBD)) with 500; page 8, completely altered AC Differential table; page 12, LVDS Output table, replaced ((TBD)) with 3. |
| November 1, 2002 | Radical changes to entire document. |
| December 12, 2002 | Radical changes to entire document, using 5T9316 as a base. |
| December 16, 2002 | Throughout document, removed "Differential" from title; page 7, Power Supply table, changed Max values, changed REFERENCE value; page 10, note 1, changed \bar{G}_x to \bar{G} . |
| May 8, 2003 | Page 2, corrected pinout diagram. |
| August 7, 2003 | Page 1, Features text, 3rd bullet, changed 2ns to 1.75ns, 4th bullet, changed 800MHz to 1GHz, and 7th bullet, added CML, on Description, 3rd line, added CML to list; page 4, Pin Descr., note 1, added "Differential CML levels", for Description of PD row, replaced 2nd sentence with "Both 'true' and 'complementary' output will pull to Vdd"; page 5, DC... for Differential Inputs table, removed note 5 and changed Vcm Max. from 3.5 to Vdd; page 7, Power Supply table, changed 800MHz to 1GHz; page 8, AC Differential table, changed Vix and Vcm Max specs from 3.5V to Vdd, removed notes 4 and 5, and placed entire table on page 7, for AC Elect. table, added notes 5 and 6, changed ((TBD)) to 300ps, tplh Type to 1.25ns, and Max from 2ns to 1.75ns, and changed fo Max from 800MHz to 1GHz. |
| October 2, 2003 | Page 1, Features, 7th bullet, added "3.3V / 2.5V LVTTTL" to front, Description, added to 1st paragraph "A single-ended 3.3V/2.5V LVTTTL input can also be used to translate to LVDS outputs."; page 4, Pin Description table, added large block of text to 2nd row, added "Single-ended 3.3V and 2.5V LVTTTL levels" to note 1; page 5, DC for LVTTTL table, added Vref row and note 3, for DC for LVDS table, changed los ratings from 5 Typ, 7.5 Max to 12 Typ, 24 Max, and changed losd ratings from 5 Typ, 7.5 Max to 6 Typ, 12 Max; page 7, Power Supply table, changed Ipd from 3 to 5. |
| March 26, 2004 | Page 2, changed pin 22 to NC; page 3, changed pin 25 to NC; page 4, added NC row to Pin Description. |
| June 22, 2004 | Removed TQFP package. |
| October 26, 2004 | Inserted a page before Ordering Info and added Landing Pattern. |
| October 27, 2004 | Added note to Landing Pattern. |
| October 29, 2004 | Changed landing pattern diagram. |
| March 9, 2005 | Page 6, switched Iddq and Itot values. |
| October 23, 2007 | Page 7, added Additive Phase Jitter, RMS specs to the AC Electrical Characterisitcs Table. |
| April 15, 2008 | Page 7, added Rise/Fall Time spec. to the AC Electrical Characteristics Table. |
| January 31, 2011 | Page 12, added VFQFPN Thermal Release Path application note. Updated to header/footer to new format. |
| March 13, 2012 | Page 13, added schematic layout. Page 16, corrected ordering information table. |
| May 30, 2012 | Page 1, Features Section - changed Low Skew spec to <40ps (max) from <25ps. Page 7, AC Charastics Table - tsk(o) Max from 25ps to 40ps. |
| November 29, 2012 | Page 16, Removed leaded parts from Ordering Information |

ORDERING INFORMATION



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