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Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



emPower

Evaluation and prototyping platform for SEGGER software User Guide & Reference Manual

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Contact address

SEGGER Microcontroller GmbH & Co. KG

In den Weiden 11 D-40721 Hilden

Germany

 Tel.
 +49 2103-2878-0

 Fax.
 +49 2103-2878-28

 E-mail:
 support@segger.com

 Internet:
 www.segger.com

Manual versions

This manual describes the current hardware version. If you find an error in the manual or a problem in the hardware, please inform us and we will try to assist you as soon as possible. Contact us for further information on topics or functions that are not yet documented.

Print date: April 18, 2016

| Revision | Date | Ву | Description | | |
|----------|--------|----|---|--|--|
| 2 | 160418 | RH | Chapter "Ethernet connector" added. Minor improvements & corrections. | | |
| 1 | 160108 | RH | Schematics added. | | |
| 0 | 151015 | DA | Initial Release. | | |

About this document

Assumptions

This document assumes that you already have a solid knowledge of the following:

- The software tools used for building your application (assembler, linker, C compiler).
- The C programming language.
- The target processor.
- DOS command line.

If you feel that your knowledge of C is not sufficient, we recommend *The C Programming Language* by Kernighan and Richie (ISBN 0–13–1103628), which describes the standard in C programming and, in newer editions, also covers the ANSI C standard.

How to use this manual

This manual explains all the functions and macros that the product offers. It assumes you have a working knowledge of the C language. Knowledge of assembly programming is not required.

Typographic conventions for syntax

This manual uses the following typographic conventions:

| Style | Used for | | | | |
|----------------|--|--|--|--|--|
| Body | Body text. | | | | |
| Keyword | Text that you enter at the command prompt or that appears on the display (that is system functions, file- or pathnames). | | | | |
| Parameter | Parameters in API functions. | | | | |
| Sample | Sample code in program examples. | | | | |
| Sample comment | Comments in program examples. | | | | |
| Reference | Reference to chapters, sections, tables and figures or other documents. | | | | |
| GUIElement | Buttons, dialog boxes, menu names, menu commands. | | | | |
| Emphasis | Very important sections. | | | | |

Table of contents

| 1 | Intro | duction to emPower | 8 |
|---|-------|--|------|
| | 1.1 | Overview on Hardware features and specifications | 9 |
| 2 | Fund | ctional Description | 11 |
| | 2.1 | Freescale Kinetis K66 MCU (MK66FN2M0VMD18) | .12 |
| | 2.2 | USB Connectors | . 13 |
| | | 2.2.1 Hi-Speed USB (HS USB) | . 13 |
| | | 2.2.2 USB HOST | .13 |
| | | 2.2.3 J-Link OB and alternative Debug Access | .13 |
| | 2.3 | Ethernet connector | .14 |
| | 2.4 | Storage Devices | .15 |
| | | 2.4.1 Macronix NAND Flash (MX30LF1GE8ABTI) | 15 |
| | | 2.4.2 Micro SD card | .15 |
| | 2.5 | Display adapter connector (J504) | .16 |
| | 2.6 | Expansion IF Module Connectors (J500-502) | 17 |
| | 2.7 | Pin Headers (J505-506) | . 19 |
| | 2.8 | Joystick, user/reset buttons, rotary input, LEDs | . 20 |
| | 2.9 | Power Supply | 21 |
| 3 | Sche | ematics | .23 |
| | 31 | MCU | 24 |
| | 3.2 | FTH HS USB Host | 25 |
| | 3.3 | IO. NAND Flash | 26 |
| | 3.4 | J-Link OB, Power Supply | .27 |
| | | | |

Chapter 1 Introduction to emPower

This section presents an overview of emPower, its structure, and its capabilities.

emPower is a dedicated demonstrator board providing the means for customers to evaluate and experience SEGGER's superior embedded middleware products. The board has a NXP Kinetis K66 microcontroller. It is designed without jumpers and configuration switches to easily illustrate the extensive capabilities of SEGGER's high-performance, feature rich software such as emFile (file system), embOS (RTOS), embOS/IP (IP stack), emModbus (Modbus stack), emWin (graphic library with GUI), or emUSB Device + Host (USB stacks).

The software evaluation package including these products is available for download here: https://www.segger.com/empower.html

This document is designed to give a quick overview on the features and specifications of the emPower board. If you are looking for a detailed description of SEGGER's middleware products, please refer to the individual product sites at https://www.segger.com



9

1.1 **Overview on Hardware features and specifications**

- NXP Kinetis K66 microcontroller (MK66FN2M0VMD18)
- Macronix SLC 1 GBit NAND Flash (MX30LF1GE8ABTI) •
- On-board debug probe J-Link-OB with Drag & Drop (STM32F072, Mini A/B-type • connector); SWD/SWO only, CDC/VCOM port support
- External debug interface (19-pin Cortex-M); incl. trace
- Fast Ethernet
- Micro SD card connector
- Display adapter connector (5 V/3.3 V, SPI, PWM for backlight control) .
- USB device: High speed, B-type connector (as on J-Link)
- USB host: Full speed, providing USB supply to device, A-Type receptacle (for directly . plugging in A-Type devices/modules)
- 3 expansion interfaces providing I2C, SPI buses, UART, GPIO/timer, analog input, power; compatible to 3.3 V SExI modules (comp. http://soldercore.com/data/SenseCore/ SenseCore.pdf)
- Joystick 4(+1)-way, 1x "FIRE" button, 1x RESET button •
- Rotary input (potentiometer to ADC)
- LEDs: 4x BiColor red/green •
- Pin headers for spare MCU signals •
- Easy to set up (No jumpers or solder jumpers)
- Dimensions 99 mm x 80 mm



emPower V2 Block Diagram

Effective: 15-10-07

Chapter 2 Functional Description

This section describes the hardware features from a functional point of view.

2.1 Freescale Kinetis K66 MCU (MK66FN2M0VMD18)



The microcontroller used on the emPower board is a NXP K66 device. It is clocked at 180 MHz and comes with 256 KB SRAM as well as 2 MB Flash memory. Peripheral functions provided include two USB2.0 controllers with an integrated HS USB PHY, controllers for Ethernet and SDHC, 16 bit ADC, and several SPI/I2C/CAN/UART units.

2.2 USB Connectors



2.2.1 Hi-Speed USB (HS USB)

The Hi-Speed USB connector is the main USB connection to a host. emPower provides Hi-Speed USB 2.0 device functionality.

2.2.2 USB HOST

The USB HOST provides USB2.0 FS host functionality to a connected device. If this host port is switched on the green "USB HOST POWER" LED is on.

2.2.3 J-Link OB and alternative Debug Access

Quick and easy debug access to the Kinetis microcontroller can be achieved by the J-Link OB, SEGGER's on-board debug probe. It connects through a USB2.0 FS interface to the debug host. Alternatively regular debug probes from the J-Link series (J-Link BASE/PLUS/ ULTRA+/PRO) can be used by means of a Cortex-M debug connector (DEBUG IF, 19 pole, pitch 50 mil). For the connector pinout see https://www.segger.com/jlink-adapters-19pin-cortexm.html

2.3 Ethernet connector



emPower provides 100 MBit fast Ethernet functionality with a RF45 connector. The Ethernet PHY is connected to the K66 MCU via RMII interface.

2.4 Storage Devices



2.4.1 Macronix NAND Flash (MX30LF1GE8ABTI)

Nonvolatile storage capability on emPower V2 is achieved by means of a 1 Gb (128 MB) SLC NAND Flash from Macronix, a leading integrated device manufacturer in the Non-volatile Memory (NVM) market, (part type MX30LF1GE8ABTI). The NAND flash has a built-in ECC controller and therefore presents itself as ECC-free to the driving MCU.

2.4.2 Micro SD card

A micro SD card slot is included on the board, SD card operating voltage is 3.3 V.

2.5 Display adapter connector (J504)

Small TFT displays can be connected to emPower V2 using a simple adapter board providing the connector for the FPC cable of a dedicated display. Display control is restriced to SPI capable controllers and a 3.3 V single supply. 5 V is provided for driving a white backlight LED as well as a PWM signal for backlight dimming. For touch control an I2C connection is routed to this connector too.



Connection Table DISPLAY/J504 (2x 10 pole 100 mil receptacle):

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|-----------|--------|--------|----------|----------|
| PTB18 | BLON/PWM | Pin 1 | Pin 2 | VCC5V | |
| PTB11 | #RESET | Pin 3 | Pin 4 | VCC3V3 | |
| PTB19 | D/#C | Pin 5 | Pin 6 | VCC3V3 | |
| PTB8 | SPARE0 | Pin 7 | Pin 8 | I2C3_SDA | PTE10 |
| PTB9 | SPARE1 | Pin 9 | Pin10 | I2C3_SCL | PTE11 |
| PTB10 | SPARE2 | Pin11 | Pin12 | GND | |
| PTB22 | SPI2_MOSI | Pin13 | Pin14 | GND | |
| PRB23 | SPI2_MISO | Pin15 | Pin16 | GND | |
| PTB21 | SPI2_SCK | Pin17 | Pin18 | GND | |
| PRB20 | SPI2_#CS | Pin19 | Pin20 | GND | |

2.6 Expansion IF Module Connectors (J500-502)

emPower V2 can carry up to three expansion boards for pulling in additional functions, for example CAN/UART transceivers or sensor modules. Mechanical dimensions and pin out of these connectors are compatible to 3.3 V SExI modules, see http://soldercore.com for additional information. Each module connector consists of 2x 8 pole 100 mil receptacles and provides I2C, SPI, UART, a GPIO/timer, an analog input, and power.



Connection Table EXPIF_0/J500:

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|-----------------------|--------|--------|----------|----------|
| PTC5 | SPI0_SCK | Pin 1 | Pin16 | UART4_TX | PTE24 |
| PTC6 | SPI0_MOSI | Pin 2 | Pin15 | VCC5V | |
| PTC7 | SPI0_MISO | Pin 3 | Pin14 | VCC3V3 | |
| PTC4 | SPI0_#CS0 | Pin 4 | Pin13 | GND | |
| | ADC1_DP0/ ADC0_DP3 | Pin 5 | Pin12 | UART4_RX | PTE25 |
| PTE10 | I2C3_SDA | Pin 6 | Pin11 | VCC5V | |
| PTE11 | I2C3_SCL | Pin 7 | Pin10 | VCC3V3 | |
| PTE7 | GPIO/PWM | Pin 8 | Pin 9 | GND | |

Connection EXPIF_1/Table J501:

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|-------------------------|--------|--------|----------|----------|
| PTC5 | SPI0_SCK | Pin 1 | Pin16 | UART2_TX | PTD3 |
| PTC6 | SPI0_MOSI | Pin 2 | Pin15 | VCC5V | |
| PTC7 | SPI0_MISO | Pin 3 | Pin14 | VCC3V3 | |
| PTC3 | SPI0_#CS1 | Pin 4 | Pin13 | GND | |
| | ADC0_SE16/ ADC0_SE21 | Pin 5 | Pin12 | UART2_RX | PTD2 |
| PTE10 | I2C3_SDA | Pin 6 | Pin11 | VCC5V | |
| PTE11 | I2C3_SCL | Pin 7 | Pin10 | VCC3V3 | |
| PTE8 | GPIO/PWM | Pin 8 | Pin 9 | GND | |

Connection Table EXPIF_3/J502:

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|-------------------------|--------|--------|----------|----------|
| PTC5 | SPI0_SCK | Pin 1 | Pin16 | UART0_TX | PTB17 |
| PTC6 | SPI0_MOSI | Pin 2 | Pin15 | VCC5V | |
| PTC7 | SPI0_MISO | Pin 3 | Pin14 | VCC3V3 | |
| PTC2 | SPI0_#CS2 | Pin 4 | Pin13 | GND | |
| | ADC1_SE16/ ADC0_SE22 | Pin 5 | Pin12 | UART0_RX | PTB16 |
| PTE10 | I2C3_SDA | Pin 6 | Pin11 | VCC5V | |
| PTE11 | I2C3_SCL | Pin 7 | Pin10 | VCC3V3 | |
| PTE9 | GPIO/PWM | Pin 8 | Pin 9 | GND | |

2.7 Pin Headers (J505-506)

All spare MCU signals are accessible via a 2x 5 pole 100 mil pin header.



Connection Table SPARE_A/J505:

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|--------|--------|--------|--------|----------|
| PTA5 | | Pin 1 | Pin 2 | | PTA24 |
| PTA25 | | Pin 3 | Pin 4 | | PTA26 |
| PTA27 | | Pin 5 | Pin 6 | | PTA28 |
| PTA29 | | Pin 7 | Pin 8 | | PTB3 |
| | GND | Pin 9 | Pin10 | VCC3V3 | |

Connection Table SPARE_B/J506:

| GPIO-Pin | SIGNAL | Header | Header | SIGNAL | GPIO-Pin |
|----------|-------------------------|--------|--------|-------------------------|----------|
| | ADC1_SE10 (ball G10) | Pin 1 | Pin 2 | ADC1_SE11 (ball G9) | |
| | ADC1_SE12 (ball F12) | Pin 3 | Pin 4 | ADC1_SE13 (ball F11) | |
| PTE27 | | Pin 5 | Pin 6 | | PTA11 |
| - (nc) | -(nc) | Pin 7 | Pin 8 | -(nc) | -(nc) |
| | GND | Pin 9 | Pin10 | VCC3V3 | |

2.8 Joystick, user/reset buttons, rotary input, LEDs



The joystick (NAV) is a five-way navigation switch connecting to MCU GPIO port C. Idle state is high.

Connection Table:

| Direction | GPIO |
|-----------|-------|
| "UP" | PTC15 |
| "DOWN" | PTC16 |
| "LEFT" | PTC14 |
| "RIGHT" | PTC17 |
| "PUSH" | PTC18 |

The user button (USER) connects to PTC19. Idle state is high.

The reset buttons (RESET) performs a hard reset of the MCU if pressed.

The rotary input is a potentiometer generating an analog voltage for ADC0 input SE23 (ball L3).

4 bi-color (red/green) user LEDs are connected to MCU GPIO port C. LED off state is high. Connection Table:

| LED | Color | GPIO |
|------|-------|-------|
| LED0 | red | PTC13 |
| LED0 | green | PTC12 |
| LED1 | red | PTC11 |
| LED1 | green | PTC10 |
| LED2 | red | PTC9 |
| LED2 | green | PTC8 |
| LED3 | red | PTC1 |
| LED3 | green | PTC0 |

2.9 Power Supply

The emPower V2 board is powered by USB only. There are two USB device ports, Main USB (B-type connector, HS USB) and J-Link OB USB (Mini USB connector), which both can be used for this purpose in any combination (Main USB, OB USB, both). Current consumption drawn strongly depends on the application and connected peripherals. Idle consumption is approx. 85 mA. If the board is powered, the green "POWER" LED is on.



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Chapter 3 Schematics

This section contains the emPower schematics.

3.1 MCU



