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HIGH-SPEED 2.5V 256/128K x 36 ASYNCHRONOUS DUAL-PORT STATIC RAM

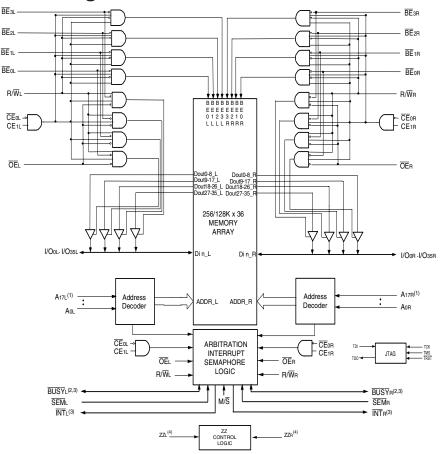
WITH 3.3V OR 2.5V INTERFACE

Features

- True Dual-Port memory cells which allow simultaneous access of the same memory location
- High-speed access
 - Commercial: 10/12/15ns (max.)
 - Industrial: 10/12ns (max.)
- RapidWrite Mode simplifies high-speed consecutive write cycles
- Dual chip enables allow for depth expansion without external logic
- IDT70T651/9 easily expands data bus width to 72 bits or more using the Master/Slave select when cascading more than one device
- M/S = VIH for BUSY output flag on Master,
 M/S = VIL for BUSY input on Slave
- Busy and Interrupt Flags

- On-chip port arbitration logic
- Full on-chip hardware support of semaphore signaling between ports
- Fully asynchronous operation from either port
- Separate byte controls for multiplexed bus and bus matching compatibility
- Sleep Mode Inputs on both ports
- Supports JTAG features compliant to IEEE 1149.1
- Single 2.5V (±100mV) power supply for core
- LVTTL-compatible, selectable 3.3V (±150mV)/2.5V (±100mV) power supply for I/Os and control signals on each port
- Available in a 256-ball Ball Grid Array, 208-pin Plastic Quad Flatpack and 208-ball fine pitch Ball Grid Array.
- Industrial temperature range (-40°C to +85°C) is available for selected speeds
- Green parts available, see ordering information

Functional Block Diagram



NOTES:

- Address A_{17x} is a NC for IDT70T659.
- 2. BUSY is an input as a Slave (M/S=VIL) and an output when it is a Master (M/S=VIH).
- 3. BUSY and INT are non-tri-state totem-pole outputs (push-pull).
- The sleep mode pin shuts off all dynamic inputs, except JTAG inputs, when asserted. OPTx, INTx, M/S and the sleep
 mode pins themselves (ZZx) are not affected during sleep mode.

4009 UIW UI

JULY 2015

Description

The IDT70T651/9 is a high-speed 256/128K x 36 Asynchronous Dual-Port Static RAM. The IDT70T651/9 is designed to be used as a stand-alone 9216/4608K-bit Dual-Port RAM or as a combination MAS-TER/SLAVE Dual-Port RAM for 72-bit-or-more word system. Using the IDT MASTER/SLAVE Dual-Port RAM approach in 72-bit or wider memory system applications results in full-speed, error-free operation without the need for additional discrete logic.

This device provides two independent ports with separate control, address, and I/O pins that permit independent, asynchronous access for reads or writes to any location in memory. An automatic power down

feature controlled by the chip enables (either $\overline{CE}0$ or CE1) permit the on-chip circuitry of each port to enter a very low standby power mode.

The IDT70T651/9 has a RapidWrite Mode which allows the designer to perform back-to-back write operations without pulsing the R/\overline{W} input each cycle. This is especially significant at the 10ns cycle time of the IDT70T651/9, easing design considerations at these high performance levels.

The 70T651/9 can support an operating voltage of either 3.3 V or 2.5 V on one or both ports, controlled by the OPT pins. The power supply for the core of the device (VDD) is at 2.5 V.

Pin Configuration^(1,2,3)

70T651/9BC BC-256^(5,6)

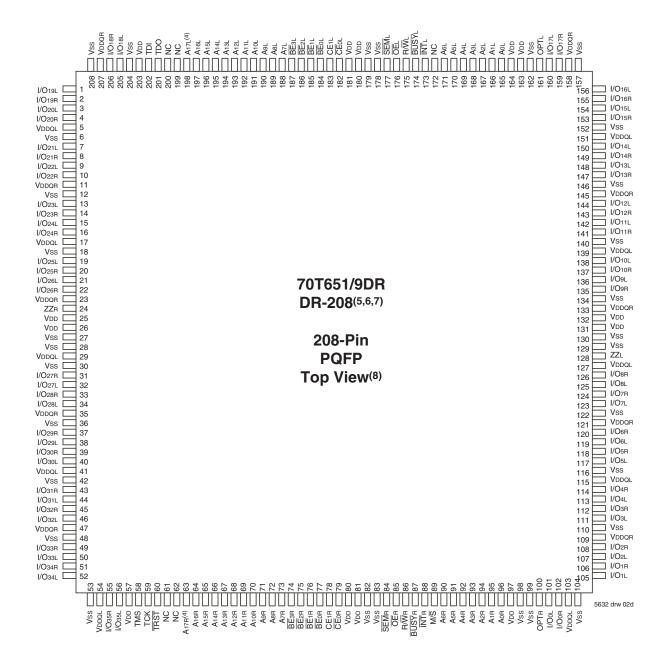
256-Pin BGA Top View

A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16
NC	TDI	NC	A17L ⁽⁴⁾	A 14L	A 11L	A 8L	BE2L	CE1L	OEL	INTL	A 5L	A 2L	A 0L	NC	NC
B1	B2	B3	NC	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16
I/O18L	NC	TDO		A 15L	A 12L	A 9L	BE3L	CE ₀ L	R/WL	NC	A 4L	A 1L	NC	I/O17L	NC
C1	C2	C3	C4	C5	C6	C7	C8	C9	C10	C11	C12	C13	C14	C15	C16
I/O18R	I/O19L	Vss	A 16L	A 13L	A 10L	A 7L	BE ₁ L	BE ₀ L	SEML	BUSYL	A 6L	A 3L	OPTL	I/O17R	I/O16L
D1	D2	D3	D4	D5	D6	d7	d8	D9	D10	d11	D12	D13	D14	D15	D16
I/ O 20R	I/O19R	I/O20L	VDD	Vddql	VDDQL	Vddqr	Vddqr	VDDQL	VDDQL	Vddqr	VDDQR	VDD	I/O15R	I/O15L	I/O16R
E1	E2	E3	E4	E5	E6	E7	E8	E9	E10	E11	E12	E13	E14	E15	E16
I/O21R	I/O21L	I/O22L	VDDQL	VDD	Vdd	V SS	Vss	Vss	Vss	VDD	VDD	VDDQR	I/O13L	I/O14L	I/O14R
F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13	F14	F15	F16
I/O23L	I/O22R	I/ O 23R	VDDQL	Vdd	NC	Vss	Vss	Vss	Vss	Vss	VDD	VDDQR	I/O12R	I/O13R	I/O12L
G1	G2	G3	G4	G5	G6	G7	G8	G9	G10	G11	G12		G14	G15	G16
I/O24R	I/O24L	I/ O 25L	Vddqr	Vss	Vss	V SS	Vss	Vss	Vss	V SS	Vss		I/O10L	I/O11L	I/O11R
H1	H2	H3	h4	H5	H6	H7	H8	H9	H10	H11	H12	H13	H14	H15	H16
I/O26L	I/O25R	I/ O 26R	Vddqr	Vss	Vss	V SS	Vss	Vss	Vss	Vss	Vss	VDDQL	I/O9R	IO 9L	I/O10R
J1	J2	J3	J4	J5	J6	J7	J8	J9	J10	J11	J12	J13	J14	J15	J16
I/O27L	I/O28R	I/ O 27R	VDDQL	ZZ R	Vss	V SS	Vss	V SS	V SS	V ss	ZZ L	Vddqr	I/O8R	I/O 7R	I/O8L
K1	K2	K3	K4	K5	K6	K7	K8	K9	K10	K11	K12	K13	K14	K15	K16
I/O29R	I/O29L	I/O28L	Vddql	Vss	Vss	Vss	Vss	Vss	Vss	Vss	Vss	VDDQR	I/O6R	I/O6L	I/O7L
L1	L2	L3	L4	L5	L6	L7	L8	L9	L10	L11	L12	L13	L14	L15	L16
I/O30L	I/O31R	I/O30R	VDDQR	VDD	NC	Vss	Vss	Vss	Vss	Vss	Vdd	VDDQL	I/O5L	I/O4R	I/O5R
M1	M2	M3	m4	M5	M6	M7	M8	M9	M10	M11	M12	M13	M14	M15	M16
I/O32R	I/O32L	I/O31L	Vddqr	VDD	VDD	Vss	Vss	Vss	Vss	VDD	VDD	VDDQL	I/O3R	I/ОзL	I/O4L
N1	N2	N3	N4	N5	N6	N7	N8	N9	N10	N11	N12	N13	N14	N15	N16
I/O33L	I/O34R	I/ O 33R	Vdd	VDDQR	VDDQR	Vddql	Vddql	Vddqr	VDDQR	VDDQL	Vddql	VDD	I/O2L	I/O1R	I/O2R
P1	P2	P3	P4	P5	P6	P7	P8	P9	P10	P11	P12	P13	P14	P15	P16
I/O35R	I/O34L	TMS	A 16R	A 13R	A 10R	A 7R	BE1R	BE0R	SEMR	BUSYR	A 6R	A 3R	I/O0L	I/ O 0R	I/O1L
R1	R2	R3	R4	R5	R6	R7	R8	R9	R10	R11	R12	R13	R14	R15	R16
I/O35L	NC	TRST	NC	A 15R	A 12R	A 9R	BE3R	CE0R	R/W R	M/S	A 4R	A 1R	OPTR	NC	NC
T1	T2	T3	T4	T5	T6	T7	T8	T9	T10	T11	T12	T13	T14	T15	T16
NC	TCK	NC	A 17R ⁽⁴⁾	A 14R	A 11R	A 8R	BE2R	CE1R	OEr	INTR	A 5R	A 2R	A 0R	NC	NC

5632 drw 02f

- 1. All VDD pins must be connected to 2.5V power supply.
- 2. All VDDQ pins must be connected to appropriate power supply: 3.3V if OPT pin for that port is set to VDD (2.5V), and 2.5V if OPT pin for that port is set to Vss (0V).
- 3. All Vss pins must be connected to ground supply.
- 4. A₁₇x is a NC for IDT70T659.
- 5. Package body is approximately 17mm x 17mm x 1.4mm, with 1.0mm ball-pitch.
- 6. This package code is used to reference the package diagram.

Pin Configurations^(1,2,3) (con't.)



- 1. All VDD pins must be connected to 2.5V power supply.
- 2. All VDDQ pins must be connected to appropriate power supply: 3.3V if OPT pin for that port is set to VDD (2.5V) and 2.5V if OPT pin for that port is set to Vss (0V).
- 3. All Vss pins must be connected to ground.
- 4. A₁₇x is a NC for IDT70T659.
- 5. Package body is approximately 28mm x 28mm x 3.5mm.
- 6. This package code is used to reference the package diagram.
- 7. 10ns Industrial speed grade is not available in the DR-208 package.
- 8. This text does not indicate orientation of the actual part-marking.

Pin Configurations^(1,2,3)(con't.)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	
Α	I/O19L	I/O18L	Vss	TDO	NC	A _{16L}	A 12L	A ₈ L	<u>BE</u> 1∟	VDD	SEML	ĪNTL	A4L	AoL	OPT∟	I/O17L	Vss	Α
В	I/O20R	Vss	I/O _{18R}	TDI	A _{17L} ⁽⁴⁾	A 13L	A9L	BE ₂ L	<u>CE</u> ₀L	Vss	BUSYL	A5L	A 1L	Vss	VDDQR	I/O16L	I/O _{15R}	В
С	VDDQL	I/O _{19R}	VDDQR	V _{DD}	NC	A ₁₄ L	A _{10L}	BE₃∟	CE ₁ L	Vss	R/WL	A6L	A 2L	V _{DD}	I/O _{16R}	I/O _{15L}	Vss	С
D	I/O22L	Vss	I/O21L	I/O20L	A 15L	A15L A11L A7L BEOL VDD OEL NC A3L VDD L									VDDQL	I/O _{14L}	I/O _{14R}	D
E	I/O23L	I/O22R	VDDQR	I/O21R											I/O13R	Vss	I/O _{13L}	Ε
F	VDDQL	I/O23R	I/O ₂₄ L	Vss										Vss	I/O _{12R}	I/O ₁₁ L	VDDQR	F
G	I/O26L	Vss	I/O _{25L}	I/O24R											VDDQL	I/O _{10L}	I/O _{11R}	G
Н	V _{DD}	I/O ₂₆ R	VDDQR	I/O _{25R}					T651. =-208					V _{DD}	I/O ₉ R	Vss	I/O _{10R}	Н
J	VDDQL	VDD	Vss	ZZR				2	208-E	Ball				ΖΖL	V _{DD}	Vss	VDDQR	J
K	I/O ₂₈ R	Vss	I/O27R	Vss					fpBG p Vie	iΑ				I/O7R	VDDQL	I/O8R	Vss	K
L	I/O29R	I/O ₂₈ L	VDDQR	I/O27L				10	p vie	5 VV ` ′				I/O ₆ R	I/O7L	Vss	I/O ₈ L	L
М	VDDQL	I/O29L	I/O30R	Vss										Vss	I/O ₆ L	I/O ₅ R	VDDQR	M
N	I/O31L	Vss	I/O31R	I/O30L										I/O3R	VDDQL	I/O ₄ R	I/O ₅ L	N
Р	I/O32R	I/O32L	VDDQR	I/O35R	TRST	A 16R	A 12R	A ₈ R	BE _{1R}	V _{DD}	SEMR	ĪNTR	A 4R	I/O ₂ L	I/O3L	Vss	I/O ₄ L	Р
R	Vss	I/O33L	I/O34R	тск	A _{17R} (4)	A _{13R}	A 9R	<u>B</u> E₂R	<u>CE</u> ōR	Vss	BUSYR	A 5R	A 1R	Vss	VDDQL	I/O _{1R}	VDDQR	R
Т	I/O33R	I/O34L	VDDQL	TMS	NC	A ₁₄ R	A _{10R}	ΒΕ₃R	CE _{1R}	Vss	R/W̄R	A ₆ R	A 2R	Vss	I/Oor	Vss	I/O ₂ R	Т
U	Vss	I/O35L	V _{DD}	NC	A 15R	A 11R	A 7R	BEor	VDD	ŌĒR	M/S	Азп	A or	V _{DD}	OPTR	I/OoL	I/O1L	U

5632 drw 02e

- 1. All VDD pins must be connected to 2.5V power supply.
- 2. All VDDQ pins must be connected to appropriate power supply: 3.3V if OPT pin for that port is set to VDD (2.5V) and 2.5V if OPT pin for that port is set to Vss (0V).
- 3. All Vss pins must be connected to ground.
- 4. A₁₇x is a NC for IDT70T659.
- 5. Package body is approximately 15mm x 15mm x 1.4mm with 0.8mm ball pitch.
- 6. This package code is used to reference the package diagram.
- 7. This text does not indicate orientation of the actual part-marking.

Pin Names

Left Port	Right Port	Names
CEOL, CE1L	CE0R, CE1R	Chip Enables (Input)
R/WL	R/W̄R	Read/Write Enable (Input)
ŌĒL	OE R	Output Enable (Input)
A0L - A17L ⁽¹⁾	A0R - A17R ⁽¹⁾	Address (Input)
I/O0L - I/O35L	I/O0R - I/O35R	Data Input/Output
SEML	<u>SEM</u> R	Semaphore Enable (Input)
ĪNTL	ĪNTR	Interrupt Flag (Output)
BUSYL	BUSY R	Busy Flag (Output)
BEOL - BE3L	BEOR - BE3R	Byte Enables (9-bit bytes) (Input)
VDDQL	VDDQR	Power (I/O Bus) (3.3V or 2.5V) ⁽²⁾ (Input)
OPTL	OPTr	Option for selecting VDDQX ^(2,3) (Input)
ZZL	ZZR	Sleep Mode Pin ⁽⁴⁾ (Input)
N	n/s	Master or Slave Select (Input) ⁽⁵⁾
\	/DD	Power (2.5V) ⁽²⁾ (Input)
\	/ss	Ground (0V) (Input)
-	ΠDI	Test Data Input
Т	DO	Test Data Output
Т	CK	Test Logic Clock (10MHz) (Input)
Т	MS	Test Mode Select (Input)
TF	RST	Reset (Initialize TAP Controller) (Input)

5632 tbl 01

- 1. Address A₁₇x is a NC for IDT70T659.
- VDD, OPTx, and VDDQx must be set to appropriate operating levels prior to applying inputs on I/Ox.
- 3. OPTx selects the operating voltage levels for the I/Os and controls on that port. If OPTx is set to VDD (2.5V), then that port's I/Os and controls will operate at 3.3V levels and VDDQX must be supplied at 3.3V. If OPTx is set to Vss (0V), then that port's I/Os and controls will operate at 2.5V levels and VDDQX must be supplied at 2.5V. The OPT pins are independent of one another—both ports can operate at 3.3V levels, both can operate at 2.5V levels, or either can operate at 3.3V with the other at 2.5V.
- 4. The sleep mode pin shuts off all dynamic inputs, except JTAG inputs, when asserted. OPTx, INTx, M/S and the sleep mode pins themselves (ZZx) are not affected during sleep mode. It is recommended that boundry scan not be operated during sleep mode.
- BUSY is an input as a Slave (M/S=VIL) and an output when it is a Master (M/S=VIH).

Truth Table I—Read/Write and Enable Control^(1,2)

ŌĒ	SEM	Œ₀	CE ₁	BE ₃	BE₂	BE ₁	BE₀	R/W	ZZ	Byte 3 I/O27-35	Byte 2 I/O ₁₈₋₂₆	Byte 1 I/O ₉₋₁₇	Byte 0 I/O ₀₋₈	MODE
X	Н	Н	Х	Х	Χ	Х	Х	Χ	L	High-Z	High-Z	High-Z	High-Z	Deselected-Power Down
Х	Н	Χ	L	Χ	Χ	Х	Χ	Χ	L	High-Z	High-Z	High-Z	High-Z	Deselected-Power Down
Х	Н	L	Н	Н	Н	Н	Н	Χ	L	High-Z	High-Z	High-Z	High-Z	All Bytes Deselected
Х	Н	L	Н	Н	Н	Н	L	L	L	High-Z	High-Z	High-Z	Din	Write to Byte 0 Only
Х	Н	L	Н	Н	Н	L	Н	L	L	High-Z	High-Z	Din	High-Z	Write to Byte 1 Only
Х	Н	L	Н	Н	L	Η	Н	L	L	High-Z	Din	High-Z	High-Z	Write to Byte 2 Only
Х	Н	L	Н	L	Н	Η	Н	L	L	DIN	High-Z	High-Z	High-Z	Write to Byte 3 Only
Х	Н	L	Н	Н	Н	L	L	L	L	High-Z	High-Z	Din	Din	Write to Lower 2 Bytes Only
Х	Н	L	Н	L	L	Н	Н	L	L	Din	Din	High-Z	High-Z	Write to Upper 2 bytes Only
Х	Н	L	Н	L	L	L	L	L	L	Din	Din	Din	Din	Write to All Bytes
L	Н	L	Н	Н	Н	Н	L	Н	L	High-Z	High-Z	High-Z	D оит	Read Byte 0 Only
L	Н	L	Н	Н	Н	L	Н	Н	L	High-Z	High-Z	D оит	High-Z	Read Byte 1 Only
L	Н	L	Н	Н	L	Η	Н	Н	L	High-Z	D оит	High-Z	High-Z	Read Byte 2 Only
L	Н	L	Н	L	Н	Η	Н	Н	L	D оит	High-Z	High-Z	High-Z	Read Byte 3 Only
L	Н	L	Н	Н	Н	L	L	Н	L	High-Z	High-Z	D оит	D оит	Read Lower 2 Bytes Only
L	Н	L	Н	L	L	Н	Н	Н	L	D оит	D оит	High-Z	High-Z	Read Upper 2 Bytes Only
L	Н	L	Н	L	L	L	L	Н	L	D оит	D оит	D оит	Douт	Read All Bytes
Н	Н	L	Н	L	L	L	L	Х	L	High-Z	High-Z	High-Z	High-Z	Outputs Disabled
X	Х	Χ	Х	Х	Χ	Х	Х	Χ	Н	High-Z	High-Z	High-Z	High-Z	High-Z Sleep Mode

NOTES: 5632 tbl 02

Truth Table II - Semaphore Read/Write Control⁽¹⁾

			Inp	uts ⁽¹⁾				Out	puts						
CE(2)	R/W	ŌĒ	BE ₃	<u>B</u> E₂	BE ₁	BE₀	SEM	I/O1-35 I/O0		Mode					
Н	Н	L	L	L	L	L	L	DATAout	DATAout	Read Data in Semaphore Flag ⁽³⁾					
Н	1	Χ	Χ	Χ	Χ	L	L	Х	DATAIN	Write I/Oo into Semaphore Flag					
L	Χ	Χ	Χ	Χ	Χ	Χ	L			Not Allowed					

- 1. There are eight semaphore flags written to I/Oo and read from all the I/Os (I/Oo-I/O35). These eight semaphore flags are addressed by Ao-A2.
- 2. \overline{CE} = L occurs when \overline{CE}_0 = V_{IL} and CE₁ = V_{IH}. \overline{CE} = H when \overline{CE}_0 = V_{IH} and/or CE₁ = V_{IL}.
- 3. Each byte is controlled by the respective $\overline{BE}n$. To read data $\overline{BE}n$ = Vil.

^{1. &}quot;H" = VIH, "L" = VIL, "X" = Don't Care.

^{2.} It is possible to read or write any combination of bytes during a given access. A few representative samples have been illustrated here.

Recommended Operating Temperature and Supply Voltage⁽¹⁾

Grade	Ambient Temperature	GND	V DD
Commercial	0°C to +70°C	0V	2.5V <u>+</u> 100mV
Industrial	-40°C to +85°C	0V	2.5V <u>+</u> 100mV

NOTF:

5632 tbl 04

1. This is the parameter TA. This is the "instant on" case temperature.

Capacitance⁽¹⁾

(TA = +25°C, F = 1.0MHz) PQFP ONLY

Symbol	Parameter	Conditions ⁽²⁾	Max.	Unit
CIN	Input Capacitance	VIN = 3dV	8	pF
Соит ⁽³⁾	Output Capacitance	Vout = 3dV	10.5	pF

NOTES:

 These parameters are determined by device characterization, but are not production tested.

3dV references the interpolated capacitance when the input and output switch from 0V to 3V or from 3V to 0V.

3. Cout also references CI/O.

Absolute Maximum Ratings(1)

Symbol	Rating	Commercial & Industrial	Unit
VTERM (VDD)	VDD Terminal Voltage with Respect to GND	-0.5 to 3.6	V
Vterm ⁽²⁾ (Vddq)	VDDQ Terminal Voltage with Respect to GND	-0.3 to VDDQ + 0.3	V
V _{TERM} ⁽²⁾ (INPUTS and I/O's)	Input and I/O Terminal Voltage with Respect to GND	-0.3 to VDDQ + 0.3	V
TBIAS ⁽³⁾	Temperature Under Bias	-55 to +125	°C
Tstg	Storage Temperature	-65 to +150	°C
TJN	Junction Temperature	+150	°C
IOUT(For VDDQ = 3.3V)	DC Output Current	50	mA
IOUT(For VDDQ = 2.5V)	DC Output Current	40	mA

NOTES:

5632 tbl 07

- Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS
 may cause permanent damage to the device. This is a stress rating only and
 functional operation of the device at these or any other conditions above those
 indicated in the operational sections of this specification is not implied. Exposure
 to absolute maximum rating conditions for extended periods may affect
 reliability.
- This is a steady-state DC parameter that applies after the power supply has reached its nominal operating value. Power sequencing is not necessary; however, the voltage on any Input or I/O pin cannot exceed VDDQ during power supply ramp up.
- 3. Ambient Temperature under DC Bias. No AC Conditions. Chip Deselected.

Recommended DC Operating Conditions with VDDQ at 2.5V

Symbol	Parameter	Min.	Тур.	Max.	Unit
VDD	Core Supply Voltage	2.4	2.5	2.6	V
VDDQ	I/O Supply Voltage ⁽³⁾	2.4	2.5	2.6	٧
Vss	Ground	0	0	0	V
VIH	Input High Volltage (Address, Control & Data I/O Inputs) ⁽³⁾	1.7		VDDQ + 100mV ⁽²⁾	V
VIH	Input High Voltage - JTAG	1.7		VDD + 100mV ⁽²⁾	V
Vн	Input High Voltage - ZZ, OPT, M/S	VDD - 0.2V		VDD + 100mV ⁽²⁾	V
VL	Input Low Voltage	-0.3 ⁽¹⁾	-	0.7	V
VIL	Input Low Voltage - ZZ, OPT, M/S	-0.3 ⁽¹⁾		0.2	V

5632 tbl 05

NOTES:

- 1. VIL (min.) = -1.0V for pulse width less than tRc/2 or 5ns, whichever is less.
- 2. VIH (max.) = VDDQ + 1.0V for pulse width less than trc/2 or 5ns, whichever is
- To select operation at 2.5V levels on the I/Os and controls of a given port, the OPT pin for that port must be set to Vss(0V), and VDDQX for that port must be supplied as indicated above.

Recommended DC Operating Conditions with VDDQ at 3.3V

Symbol	Parameter	Min.	Тур.	Max.	Unit
VDD	Core Supply Voltage	2.4	2.5	2.6	٧
VDDQ	I/O Supply Voltage ⁽³⁾	3.15	3.3	3.45	V
Vss	Ground	0	0	0	٧
VIH	Input High Voltage (Address, Control &Data I/O Inputs) ⁽³⁾	2.0		VDDQ + 150mV ⁽²⁾	V
Vн	Input High Voltage - JTAG	1.7		VDD + 100mV ⁽²⁾	>
Vн	Input High Voltage - ZZ, OPT, M/S	VDD - 0.2V	_	VDD + 100mV ⁽²⁾	٧
VIL	Input Low Voltage	-0.3 ⁽¹⁾		0.8	V
VIL	Input Low Voltage - ZZ, OPT, M/S	-0.3 ⁽¹⁾		0.2	٧

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- 1. VIL (min.) = -1.0V for pulse width less than tRC/2 or 5ns, whichever is less.
- VIH (max.) = VDDQ + 1.0V for pulse width less than trc/2 or 5ns, whichever is less.
- To select operation at 3.3V levels on the I/Os and controls of a given port, the OPT pin for that port must be set to VDD (2.5V), and VDDQX for that port must be supplied as indicated above.

DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range (VDD = 2.5V ± 100mV)

			70T6	51/9S	
Symbol	Parameter	Test Conditions	Min.	Max.	Unit
Iu	Input Leakage Current ⁽¹⁾	VDDQ = Max., VIN = 0V to VDDQ		10	μΑ
Iu	JTAG & ZZ Input Leakage Current ^(1,2)	V _{DD} = Max., V _{IN} = 0V to V _{DD}		<u>+</u> 30	μΑ
lLO	Output Leakage Current ^(1,3)	CE0 = VIH or CE1 = VIL, VOUT = 0V to VDDQ	_	10	μΑ
Vol (3.3V)	Output Low Voltage ⁽¹⁾	IOL = +4mA, VDDQ = Min.	_	0.4	V
Vон (3.3V)	Output High Voltage ⁽¹⁾	Iон = -4mA, V _{DDQ} = Min.	2.4	_	V
Vol (2.5V)	Output Low Voltage ⁽¹⁾	IOL = +2mA, VDDQ = Min.	_	0.4	V
Vон (2.5V)	Output High Voltage ⁽¹⁾	Iон = -2mA, V _{DDQ} = Min.	2.0		V

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NOTES:

- 1. VDDQ is selectable (3.3V/2.5V) via OPT pins. Refer to page 6 for details.
- 2. Applicable only for TMS, TDI and TRST inputs.
- 3. Outputs tested in tri-state mode.

DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range⁽³⁾ (VDD = 2.5V ± 100mV)

					Co	70T651/9S10 Com'l & Ind ⁽⁷⁾		1/9\$12 m'l Ind	70T651/9S15 Com'l Only		
Symbol	Parameter	Test Condition	Versio	n	Typ. ⁽⁴⁾	Max.	Typ. ⁽⁴⁾	Max.	Typ. ⁽⁴⁾	Max.	Unit
IDD	Dynamic Operating Current (Both	CEL and CER= VIL, Outputs Disabled	COM'L	S	300	405	300	355	225	305	mA
	Ports Active)	f = fMAX ⁽¹⁾	IND	S	300	445	300	395			
ISB1 ⁽⁶⁾	Standby Current (Both Ports - TTL	CEL = CER = VIH f = fMAX ⁽¹⁾	COM'L	S	90	120	75	105	60	85	mA
	Level Inputs)	T = TMAX*'	IND	S	90	145	75	130		_	
ISB2 ⁽⁶⁾	Standby Current (One Port - TTL	CE"A" = VIL and CE"B" = VIH ⁽⁵⁾ Active Port Outputs Disabled,	COM'L	S	200	265	180	230	150	200	mA
	Level Inputs)	f = fmax ⁽¹⁾	IND	S	200	290	180	255		_	
ISB3	Full Standby Current (Both Ports - CMOS	Both Ports $\overline{CE}L$ and $\overline{CE}R \ge VDDQ - 0.2V$,	COM'L	S	2	10	2	10	2	10	mA
	Level Inputs)	$VIN \ge VDDQ - 0.2V \text{ or } VIN \le 0.2V,$ $f = 0^{(2)}$	IND	S	2	20	2	20	—		
ISB4 ⁽⁶⁾	Full Standby Current (One Port - CMOS Level Inputs)	$\overline{\text{CE}}$ "A" $\leq 0.2 \text{V}$ and $\overline{\text{CE}}$ "B" $\geq \text{VDDQ} - 0.2 \text{V}^{(5)}$ $\overline{\text{VIN}} \geq \text{VDDQ} - 0.2 \text{V}$ or $\overline{\text{VIN}} \leq 0.2 \text{V}$,	COM'L	S	200	265	180	230	150	200	mA
	Level ilipuis)	Active Port, Outputs Disabled, $f = fmax^{(1)}$	IND	S	200	290	180	255			
IZZ	Sleep Mode Current (Both Ports - TTL	ZZL = ZZR = VIH f = fMaX ⁽¹⁾	COM'L	S	2	10	2	10	2	10	mA
	Level Inputs)	I - IWAX	IND	S	2	20	2	20		_	

NOTES

- Atf=fMAX, address and control lines (except Output Enable) are cycling at the maximum frequency read cycle of 1/trc, using "AC TEST CONDITIONS" at input levels of GND to 3.3V.
- $2. \quad \text{$f$=0$ means no address or control lines change. Applies only to input at CMOS level standby.}$
- $3. \quad \text{Port "A" may be either left or right port. Port "B" is the opposite from port "A"}.$
- 4. VDD = 3.3V, TA = 25°C for Typ, and are not production tested. IDD DC(f=0) = 100mA (Typ).
- 5. $\overline{CE}x = VIL \text{ means } \overline{CE}0x = VIL \text{ and } CE1x = VIH$
 - $\overline{CE}x = VIH \text{ means } \overline{CE}0x = VIH \text{ or } CE1x = VIL$
 - $\overline{CE}x \le 0.2V$ means $\overline{CE}0x \le 0.2V$ and $CE1x \ge VDDQx 0.2V$
 - $\overline{CE}x \ge V_{DDQX} 0.2V$ means $\overline{CE}_{0X} \ge V_{DDQX} 0.2V$ or $CE_{1X} \le 0.2V$.
 - "X" represents "L" for left port or "R" for right port.
- 6. IsB1, IsB2 and IsB4 will all reach full standby levels (IsB3) on the appropriate port(s) if ZZL and /or ZZR = VIH.
- 7. 10ns Industrial speed grade is available in BF-208 and BC-256 packages only.

AC Test Conditions (VDDQ - 3.3V/2.5V)

Input Pulse Levels	GND to 3.0V / GND to 2.4V
Input Rise/Fall Times	2ns Max.
Input Timing Reference Levels	1.5V/1.25V
Output Reference Levels	1.5V/1.25V
Output Load	Figure 1

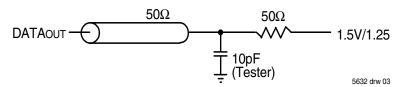


Figure 1. AC Output Test load.

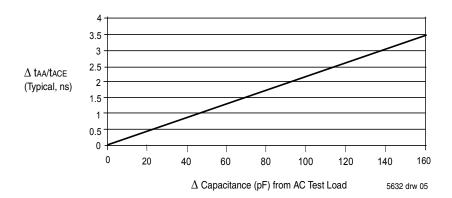


Figure 3. Typical Output Derating (Lumped Capacitive Load).

AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range⁽⁴⁾

			70T651/9S10 Com'l Only		70T651/9S12 Com'l & Ind		70T651/9S15 Com'l Only		
Symbol	Parameter	Parameter Min. Max.		Min.	Max.	Min.	Max.	Unit	
READ CYCLI	Ē					-			
trc	Read Cycle Time	10		12		15	_	ns	
taa	Address Access Time	_	10	_	12	_	15	ns	
tace	Chip Enable Access Time ⁽³⁾	_	10		12	_	15	ns	
tabe	Byte Enable Access Time ⁽³⁾		5		6		7	ns	
taoe	Output Enable Access Time		5		6		7	ns	
tон	Output Hold from Address Change	3		3		3	_	ns	
tLZ	Output Low-Z Time ^(1,2)	0		0		0	_	ns	
tHZ	Output High-Z Time ^(1,2)	0	4	0	6	0	8	ns	
tpu	Chip Enable to Power Up Time ⁽²⁾	0		0		0	_	ns	
tpD	Chip Disable to Power Down Time ⁽²⁾		8		8	_	12	ns	
tsop	Semaphore Flag Update Pulse (OE or SEM)		4		6	_	8	ns	
tsaa	Semaphore Address Access Time	2	10	2	12	2	15	ns	

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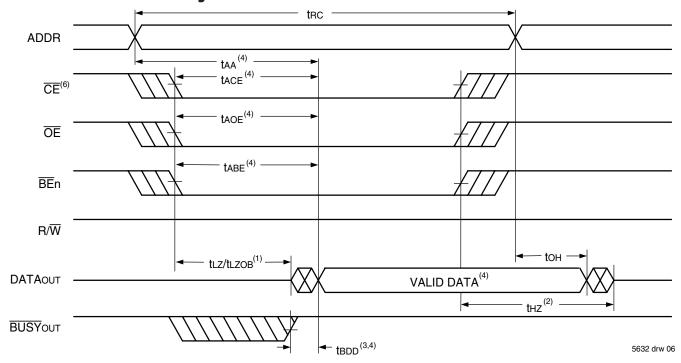
AC Electrical Characteristics Over the Operating Temperature and Supply Voltage⁽⁴⁾

			70T651/9S10 Com'l Only		70T651/9S12 Com'l & Ind		70T651/9S15 Com'l Only	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
WRITE CYCL	E							
twc	Write Cycle Time	10	_	12		15	_	ns
tew	Chip Enable to End-of-Write ⁽³⁾	8	_	10		12	_	ns
taw	Address Valid to End-of-Write	8	_	10	_	12	_	ns
tas	Address Set-up Time ⁽³⁾	0	_	0		0	_	ns
twp	Write Pulse Width	8	_	10	_	12	_	ns
twr	Write Recovery Time	0	_	0	_	0	_	ns
tow	Data Valid to End-of-Write	6	_	8	_	10	_	ns
tон	Data Hold Time ⁽⁴⁾	0	_	0	_	0	_	ns
twz	Write Enable to Output in High-Z ^(1,2)	_	4		6	_	8	ns
tow	Output Active from End-of-Write ^(1,2,4)	0	_	0		0	_	ns
tswrd	SEM Flag Write to Read Time	5	_	5		5	_	ns
tsps	SEM Flag Contention Window	5		5		5	_	ns

NOTES

- 1. Transition is measured 0mV from Low or High-impedance voltage with Output Test Load (Figure 1).
- 2. This parameter is guaranteed by device characterization, but is not production tested.
- 3. To access RAM, $\overline{\text{CE}}$ = VIL and $\overline{\text{SEM}}$ = VIH. To access semaphore, $\overline{\text{CE}}$ = VIH and $\overline{\text{SEM}}$ = VIL. Either condition must be valid for the entire tew time. $\overline{\text{CE}}$ = VIL when $\overline{\text{CE}}$ 0 = VIL and CE1 = VIH. $\overline{\text{CE}}$ 0 = VIH and/or CE1 = VIL.
- 4. These values are valid regardless of the power supply level selected for I/O and control signals (3.3V/2.5V). See page 6 for details.
- 5. 10ns Industrial speed grade is available in BF-208 and BC-256 packages only.

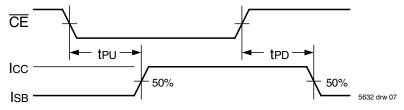
Waveform of Read Cycles⁽⁵⁾



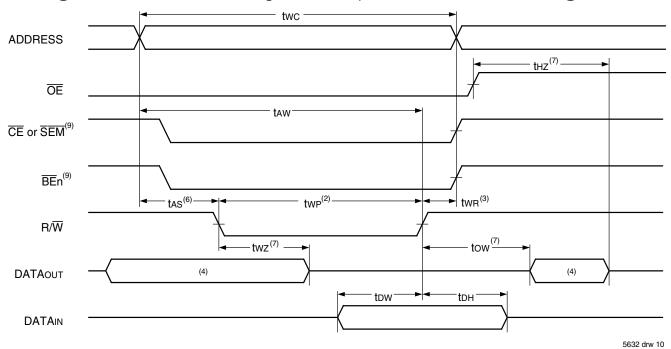
NOTES:

- 1. Timing depends on which signal is asserted last, $\overline{\text{OE}},$ $\overline{\text{CE}}$ or $\overline{\text{BE}}\text{n}.$
- 2. Timing depends on which signal is de-asserted first \overline{CE} , \overline{OE} or $\overline{BE}n$.
- 3. tbdd delay is required only in cases where the opposite port is completing a write operation to the same address location. For simultaneous read operations BUSY has no relation to valid output data.
- 4. Start of valid data depends on which timing becomes effective last tAOE, tACE, tAA, tABE or tBDD.
- 5. $\overline{\text{SEM}}$ = VIH.
- 6. \overline{CE} = L occurs when \overline{CE}_0 = VIL and CE1 = VIH. \overline{CE} = H when \overline{CE}_0 = VIH and/or CE1 = VIL.

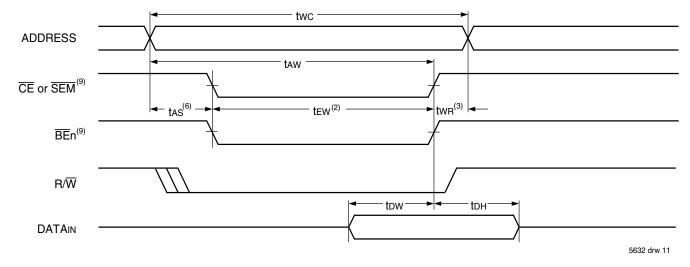
Timing of Power-Up Power-Down



Timing Waveform of Write Cycle No. 1, R/\overline{W} Controlled Timing^(1,5,8)



Timing Waveform of Write Cycle No. 2, CE Controlled Timing^(1,5,8)



- 1. R/\overline{W} or \overline{CE} or $\overline{BE}n$ = VIH during all address transitions for Write Cycles 1 and 2.
- 2. A write occurs during the overlap ($\underline{\text{tew}}$ or $\underline{\text{twp}}$) of a $\overline{\text{CE}}$ = V_{IL} , $\overline{\text{BEn}}$ = V_{IL} , and a $R\overline{\text{NW}}$ = V_{IL} for memory array writing cycle.
- 3. twn is measured from the earlier of \overline{CE} , \overline{BE} n or R/\overline{W} (or \overline{SEM} or R/\overline{W}) going HIGH to the end of write cycle.
- 4. During this period, the I/O pins are in the output state and input signals must not be applied.
- 5. If the CE or SEM = VIL transition occurs simultaneously with or after the R/W = VIL transition, the outputs remain in the High-impedance state.
- 6. Timing depends on which enable signal is asserted last, $\overline{\text{CE}}$ or R/\overline{W} .
- 7. This parameter is guaranteed by device characterization, but is not production tested. Transition is measured 0mV from steady state with the Output Test Load (Figure 1).
- 8. If OE = VIL during RW controlled write cycle, the write pulse width must be the larger of twp or (twz + tow) to allow the I/O drivers to turn off and data to be placed on the bus for the required tow. If OE = VIH during an RW controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified twp.
- 9. To access RAM, $\overline{CE} = VIL$ and $\overline{SEM} = VIH$. To access semaphore, $\overline{CE} = VIH$ and $\overline{SEM} = VIL$. tew must be met for either condition. $\overline{CE} = VIL$ when $\overline{CE}_0 = VIL$ and $\overline{CE}_0 = VIH$ and $\overline{CE}_0 = VIH$

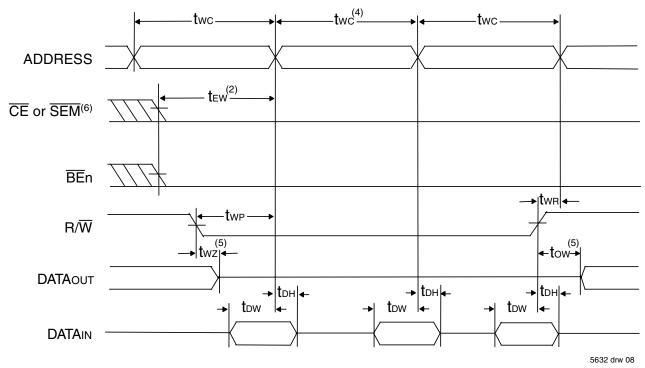
RapidWrite Mode Write Cycle

Unlike other vendors' Asynchronous Random Access Memories, the IDT70T651/9 is capable of performing multiple back-to-back write operations without having to pulse the R/\overline{W} , \overline{CE} , or $\overline{BE}n$ signals high during address transitions. This RapidWrite Mode functionality allows the system designer to achieve optimum back-to-back write cycle performance without the difficult task of generating narrow reset pulses every cycle, simplifying system design and reducing time to market.

During this new RapidWrite Mode, the end of the write cycle is now defined by the ending address transition, instead of the R/\overline{W} or \overline{CE} or \overline{BE} n transition to the inactive state. R/\overline{W} , \overline{CE} , and \overline{BE} n can be held active throughout the address transition between write cycles. Care must be

taken to still meet the Write Cycle time (twc), the time in which the Address inputs must be stable. Input data setup and hold times (tow and toh) will now be referenced to the ending address transition. In this RapidWrite Mode the I/O will remain in the Input mode for the duration of the operations due to R/\overline{W} being held low. All standard Write Cycle specifications must be adhered to. However, tas and twR are only applicable when switching between read and write operations. Also, there are two additional conditions on the Address Inputs that must also be met to ensure correct address controlled writes. These specifications, the Allowable Address Skew (taks) and the Address Rise/Fall time (tarf), must be met to use the RapidWrite Mode. If these conditions are not met there is the potential for inadvertent write operations at random intermediate locations as the device transitions between the desired write addresses.

Timing Waveform of Write Cycle No. 3, RapidWrite Mode Write Cycle^(1,3)



- 1. $\overline{\text{OE}}$ = V_{IL} for this timing waveform as shown. $\overline{\text{OE}}$ may equal V_{IH} with same write functionality; I/O would then always be in High-Z state.
- 2. A write occurs during the overlap (tew or twp) of a $\overline{CE} = V_{IL}$, $\overline{BE}n = V_{IL}$, and a $R/\overline{W} = V_{IL}$ for memory array writing cycle. The last transition LOW of \overline{CE} , $\overline{BE}n$, and R/\overline{W} initiates the write sequence. The first transition HIGH of \overline{CE} , $\overline{BE}n$, and R/\overline{W} terminates the write sequence.
- 3. If the CE or SEM = V L transition occurs simultaneously with or after the R/W = V L transition, the outputs remain in the High-impedance state.
- 4. The timing represented in this cycle can be repeated multiple times to execute sequential RapidWrite Mode writes.
- 5. This parameter is guaranteed by device characterization, but is not production tested. Transition is measured 0mV from steady state with the Output Test Load (Figure 1).
- 6. To access RAM, $\overline{CE} = VIL$ and $\overline{SEM} = VIH$. To access semaphore, $\overline{CE} = VIH$ and $\overline{SEM} = VIL$. tew must be met for either condition. $\overline{CE} = VIL$ when $\overline{CE}_0 = VIL$ and $\overline{CE}_1 = VIH$ and $\overline{CE}_2 = VIH$ and $\overline{CE}_3 = VIH$ and $\overline{CE}_4 = VIH$ and $\overline{CE}_5 = VIH$ and \overline

AC Electrical Characteristics over the Operating Temperature Range and Supply Voltage Range for RapidWrite Mode Write Cycle⁽¹⁾

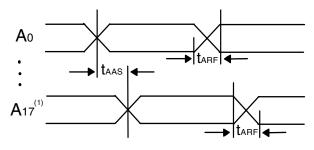
Symbol	Parameter	Min	Max	Unit
taas	Allowable Address Skew for RapidWrite Mode		1	ns
tarf	Address Rise/Fall Time for RapidWrite Mode	1.5		V/ns

NOTE:

5632 tbl 14

1. Timing applies to all speed grades when utilizing the RapidWrite Mode Write Cycle.

Timing Waveform of Address Inputs for RapidWrite Mode Write Cycle

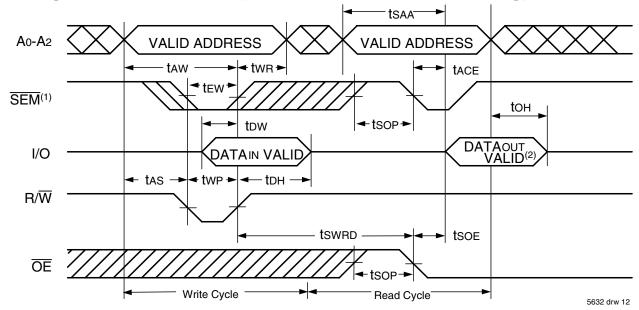


5632 drw 09

NOTE:

1. A₁₆ for IDT70T659.

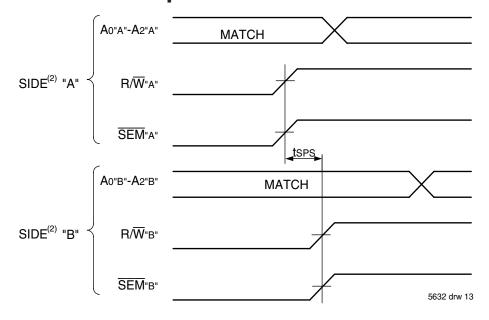
Timing Waveform of Semaphore Read after Write Timing, Either Side⁽¹⁾



NOTES:

- 2. "DATAOUT VALID" represents all I/O's (I/Oo I/O35) equal to the semaphore value.

Timing Waveform of Semaphore Write Contention (1,3,4)



- 1. Dor = Dol = VIL, $\overline{CE}L = \overline{CE}R = VIH$. Refer to Truth Table II for appropriate \overline{BE} controls.
- 2. All timing is the same for left and right ports. Port "A" may be either left or right port. "B" is the opposite from port "A".
- 3. This parameter is measured from R/\overline{W}^*A^* or \overline{SEM}^*A^* going HIGH to R/\overline{W}^*B^* or \overline{SEM}^*B^* going HIGH.
- 4. If tsps is not satisfied, the semaphore will fall positively to one side or the other, but there is no guarantee which side will be granted the semaphore flag.

AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range

Chl	Donomator		70T651/9S10 Com'l Only		70T651/9S12 Com'l & Ind		70T651/9S15 Com'l Only	
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
BUSY TIMING	(M/S=ViH)							
tbaa	BUSY Access Time from Address Match	_	10	_	12		15	ns
tBDA	BUSY Disable Time from Address Not Matched	_	10	_	12		15	ns
tBAC	BUSY Access Time from Chip Enable Low		10		12		15	ns
tBDC	BUSY Disable Time from Chip Enable High		10		12		15	ns
taps	Arbitration Priority Set-up Time ⁽²⁾	2.5	_	2.5		2.5		ns
tBDD	BUSY Disable to Valid Data ⁽³⁾	_	10	_	12		15	ns
twn	Write Hold After BUSY ⁽⁵⁾	8	_	10		12		ns
BUSY TIMING	i (M/S=Vil)							
twB	BUSY Input to Write ⁽⁴⁾	0	_	0	_	0		ns
twn	Write Hold After BUSY ⁽⁵⁾	8		10		12		ns
PORT-TO-POR	RT DELAY TIMING							
twdd	Write Pulse to Data Delay ⁽¹⁾		22	_	25		30	ns
todd	Write Data Valid to Read Data Delay ⁽¹⁾	_	20	_	22		25	ns

5632 tbl 15b

NOTES:

- 1. Port-to-port delay through RAM cells from writing port to reading port, refer to "Timing Waveform of Write with Port-to-Port Read and \overline{BUSY} (M/ \overline{S} = ViH)".
- 2. To ensure that the earlier of the two ports wins.
- 3. tBDD is a calculated parameter and is the greater of the Max. spec, twDD twP (actual), or tDDD tDW (actual).
- 4. To ensure that the write cycle is inhibited on port "B" during contention on port "A".
- 5. To ensure that a write cycle is completed on port "B" after contention on port "A".
- 6. 10ns Industrial speed grade is available in BF-208 and BC-256 packages only.

AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range^(1,2,3)

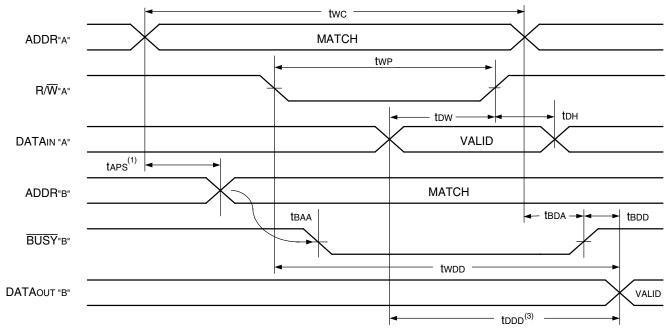
0	P	70T651/9S10 Com'l Only		70T651/9S12 Com'l & Ind		70T651/9S15 Com'l Only	
Symbol	Symbol Parameter		Max.	Min.	Max.	Min.	Max.
SLEEP MODE	SLEEP MODE TIMING (ZZx=Vih)						
tzzs	Sleep Mode Set Time	10	_	12	_	15	_
tzzr	Sleep Mode Reset Time	10	_	12	_	15	_
tzzpd	Sleep Mode Power Down Time			12	_	15	_
tzzpu	Sleep Mode Power Up Time		0		0	_	0

NOTES:

5632 tbl 15c

- 1. Timing is the same for both ports.
- 2. The sleep mode pin shuts off all dynamic inputs, except JTAG inputs, when asserted. OPTx, INTx, M/S and the sleep mode pins themselves (ZZx) are not affected during sleep mode. It is recommended that boundary scan not be operated during sleep mode.
- 3. These values are valid regardless of the power supply level selected for I/O and control signals (3.3V/2.5V). See page 6 for details.
- 4. 10ns Industrial speed grade is available in BF-208 and BC-256 packages only.
- 5. This parameter is guaranteed by device characterization, but is not production tested.

Timing Waveform of Write with Port-to-Port Read and \overline{BUSY} (M/ \overline{S} = VIH) $^{(2,4,5)}$

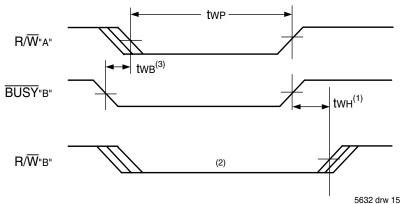


NOTES:

5632 drw 14

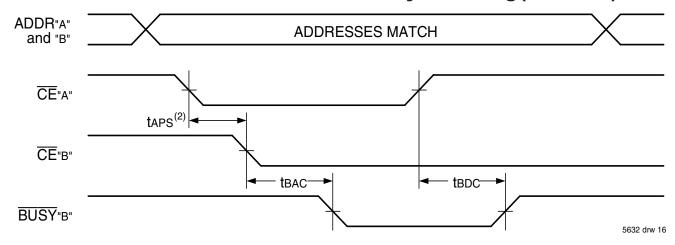
- 1. To ensure that the earlier of the two ports wins. taps is ignored for $M/\overline{S} = VIL$ (SLAVE).
- 2. $\overline{CE}_{0L} = \overline{CE}_{0R} = V_{IL}$; $CE_{1L} = CE_{1R} = V_{IH}$.
- 3. \overline{OE} = V_{IL} for the reading port.
- 4. If M/S = VIL (slave), BUSY is an input. Then for this example BUSY A = VIH and BUSY B input is shown above.
- 5. All timing is the same for left and right ports. Port "A" may be either the left or right port. Port "B" is the port opposite from port "A".

Timing Waveform of Write with \overline{BUSY} (M/ \overline{S} = VIL)

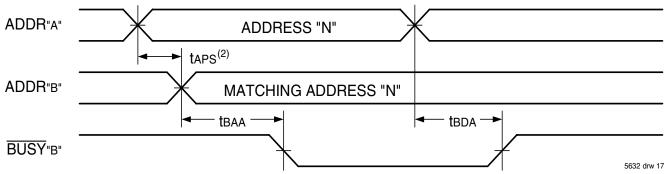


- 1. twh must be met for both BUSY input (SLAVE) and output (MASTER).
- 2. BUSY is asserted on port "B" blocking R/W"B", until BUSY"B" goes HIGH.
- 3. twb only applies to the slave mode.

Waveform of \overline{BUSY} Arbitration Controlled by \overline{CE} Timing (M/ \overline{S} = VIH)(1)



Waveform of \overline{BUSY} Arbitration Cycle Controlled by Address Match Timing (M/ \overline{S} = ViH)^(1,3,4)



NOTES:

- 1. All timing is the same for left and right ports. Port "A" may be either the left or right port. Port "B" is the port opposite from port "A".
- 2. If taps is not satisfied, the BUSY signal will be asserted on one side or another but there is no guarantee on which side BUSY will be asserted.
- 3. $\overline{CE}x = V_{IL}$ when $\overline{CE}_{0x} = V_{IL}$ and $\overline{CE}_{1x} = V_{IH}$. $\overline{CE}x = V_{IH}$ when $\overline{CE}_{0x} = V_{IH}$ and/or $\overline{CE}_{1x} = V_{IL}$.
- 4. $\overline{CE}_{0x} = \overline{OE}_{x} = \overline{BE}_{nx} = V_{IL}$. $CE_{1x} = V_{IH}$.

AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range^(1,2)

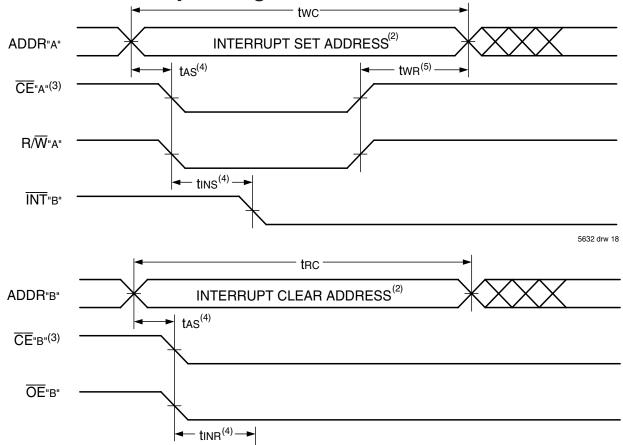
Opera	ating remperature and outpry voitage Kange										
		70T651/9S10 Com'l Only		70T651/9S12 Com'l & Ind		70T651/9S15 Com'l Only					
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit			
INTERRUPT	TIMING										
tas	Address Set-up Time	0		0	_	0	_	ns			
twr	Write Recovery Time	0		0	_	0	_	ns			
tins	Interrupt Set Time	_	10	_	12	_	15	ns			
tinr	Interrupt Reset Time		10	_	12		15	ns			

NOTES:

5632 tbl 16a

- 1. Timing is the same for both ports.
- 2. These values are valid regardless of the power supply level selected for I/O and control signals (3.3V/2.5V). See page 6 for details.
- 3. 10ns Industrial speed grade is available in BF-208 and BC-256 packages only.

Waveform of Interrupt Timing⁽¹⁾



NOTES:

- 1. All timing is the same for left and right ports. Port "A" may be either the left or right port. Port "B" is the port opposite from port "A".
- Refer to Interrupt Truth Table.

ĪNT_{"B"}

- 3. $\overline{CEx} = V_{IL}$ means $\overline{CE}_{0x} = V_{IL}$ and $CE_{1x} = V_{IH}$. $\overline{CE}_{x} = V_{IH}$ means $\overline{CE}_{0x} = V_{IH}$ and/or $CE_{1x} = V_{IL}$.
- 4. Timing depends on which enable signal ($\overline{\text{CE}}$ or R/\overline{W}) is asserted last.
- 5. Timing depends on which enable signal (CE or R/W) is de-asserted first.

Truth Table III — Interrupt Flag^(1,4)

	Left Port					Right Port				
R/WL	CEL	ŌĒL	A17L-A0L ⁽⁵⁾	ĪNT∟	R/W̄R	CER	ŌĒ R	A17R-A0R ⁽⁵⁾	ĪNTR	Function
L	L	Х	3FFFF	Х	Х	Х	Х	Х	L ⁽²⁾	Set Right INTR Flag
Х	Х	Х	Х	Х	Х	L	L	3FFFF	H ⁽³⁾	Reset Right INTR Flag
Х	Х	Х	Х	L ⁽³⁾	L	L	Х	3FFFE	Х	Set Left INTL Flag
Х	L	L	3FFFE	H ⁽²⁾	Х	Х	Х	Х	Х	Reset Left INTL Flag

NOTES

5632 tbl 17

5632 drw 19

- 1. Assumes $\overline{BUSY}L = \overline{BUSY}R = VIH$. $\overline{CE}_{0x} = VIL$ and $CE_{1x} = VIH$.
- 2. If $\overline{BUSY}L = VIL$, then no change.
- 3. If $\overline{BUSY}R = VIL$, then no change.
- 4. $\overline{\text{INT}}_{\text{L}}$ and $\overline{\text{INT}}_{\text{R}}$ must be initialized at power-up.
- 5. A_{17x} is a NC for IDT70T659. Therefore, Interrupt Addresses are 1FFFF and 1FFFE.

Truth Table IV — Address BUSY Arbitration

	In	puts	Out	puts	
CE _L (5)	CE _R (5)	Aol-A17L ⁽⁴⁾ Aor-A17R	BUSY _L (1)	BUSY _R (1)	Function
Х	Х	NO MATCH	Н	Н	Normal
Н	Х	MATCH	Н	Н	Normal
Х	Н	MATCH	Н	Н	Normal
L	L	MATCH	(2)	(2)	Write Inhibit ⁽³⁾

5632 tbl 18

NOTES:

- 1. Pins BUSYL and BUSYR are both outputs when the part is configured as a master. Both are inputs when configured as a slave. BUSY outputs on the IDT70T651/9 are push-pull, not open drain outputs. On slaves the BUSY input internally inhibits writes.
- 2. "L" if the inputs to the opposite port were stable prior to the address and enable inputs of this port. "H" if the inputs to the opposite port became stable after the address and enable inputs of this port. If taps is not met, either BUSYL or BUSYR = LOW will result. BUSYL and BUSYR outputs can not be LOW simultaneously.
- 3. Writes to the left port are internally ignored when BUSYL outputs are driving LOW regardless of actual logic level on the pin. Writes to the right port are internally ignored when BUSYR outputs are driving LOW regardless of actual logic level on the pin.
- 4. A17 is a NC for IDT70T659. Address comparison will be for A0 A16.
- 5. $\overline{CE}x = L$ means $\overline{CE}0x = V_{IL}$ and $CE_1x = V_{IH}$. $\overline{CE}x = H$ means $\overline{CE}0x = V_{IH}$ and/or $CE_1x = V_{IL}$.

Truth Table V — Example of Semaphore Procurement Sequence (1,2,3)

Functions	Do - D35 Left	Do - D35 Right	Status
No Action	1	1	Semaphore free
Left Port Writes "0" to Semaphore	0	1	Left port has semaphore token
Right Port Writes "0" to Semaphore	0	1	No change. Right side has no write access to semaphore
Left Port Writes "1" to Semaphore	1	0	Right port obtains semaphore token
Left Port Writes "0" to Semaphore	1	0	No change. Left port has no write access to semaphore
Right Port Writes "1" to Semaphore	0	1	Left port obtains semaphore token
Left Port Writes "1" to Semaphore	1	1	Semaphore free
Right Port Writes "0" to Semaphore	1	0	Right port has semaphore token
Right Port Writes "1" to Semaphore	1	1	Semaphore free
Left Port Writes "0" to Semaphore	0	1	Left port has semaphore token
Left Port Writes "1" to Semaphore	1	1	Semaphore free

5632 tbl 19

- 1. This table denotes a sequence of events for only one of the eight semaphores on the IDT70T651/9.
- 2. There are eight semaphore flags written to via I/Oo and read from all I/O's (I/Oo-I/O35). These eight semaphores are addressed by Ao A2.
- 3. $\overline{\text{CE}} = \text{ViH}, \overline{\text{SEM}} = \text{ViL}$ to access the semaphores. Refer to the Semaphore Read/Write Control Truth Table.

Functional Description

The IDT70T651/9 provides two ports with separate control, address and I/O pins that permit independent access for reads or writes to any location in memory. The IDT70T651/9 has an automatic power down feature controlled by $\overline{\text{CE}}$. The $\overline{\text{CE}}$ 0 and CE1 control the on-chip power down circuitry that permits the respective port to go into a standby mode when not selected ($\overline{\text{CE}}$ = HIGH). When a port is enabled, access to the entire memory array is permitted.

Interrupts

If the user chooses the interrupt function, a memory location (mail

box or message center) is assigned to each port. The left port interrupt flag ($\overline{\text{INTL}}$) is asserted when the right port writes to memory location 3FFFE (HEX), where a write is defined as $\overline{\text{CER}} = R/\overline{\text{WR}} = \text{VIL}$ per the Truth Table. The left port clears the interrupt through access of address location 3FFFE when $\overline{\text{CEL}} = \overline{\text{OEL}} = \text{VIL}$, $R/\overline{\text{W}}$ is a "don't care". Likewise, the right port interrupt flag ($\overline{\text{INTR}}$) is asserted when the left port writes to memory location 3FFFF (HEX) and to clear the interrupt flag ($\overline{\text{INTR}}$), the right port must read the memory location 3FFFF. The message (36 bits) at 3FFFE or 3FFFF (1FFFF or 1FFFE for IDT70T659) is user-defined since it is an addressable SRAM location. If the interrupt function is not used, address locations 3FFFE and 3FFFF are not used

as mail boxes, but as part of the random access memory. Refer to Truth Table III for the interrupt operation.

Busy Logic

Busy Logic provides a hardware indication that both ports of the RAM have accessed the same location at the same time. It also allows one of the two accesses to proceed and signals the other side that the RAM is "Busy". The $\overline{\text{BUSY}}$ pin can then be used to stall the access until the operation on the other side is completed. If a write operation has been attempted from the side that receives a $\overline{\text{BUSY}}$ indication, the write signal is gated internally to prevent the write from proceeding.

The use of \overline{BUSY} logic is not required or desirable for all applications. In some cases it may be useful to logically OR the \overline{BUSY} outputs together and use any \overline{BUSY} indication as an interrupt source to flag the event of an illegal or illogical operation. If the write inhibit function of \overline{BUSY} logic is not desirable, the \overline{BUSY} logic can be disabled by placing the part in slave mode with the $\overline{M/S}$ pin. Once in slave mode the \overline{BUSY} pin operates solely as a write inhibit input pin. Normal operation can be programmed by tying the \overline{BUSY} pins HIGH. If desired, unintended write operations can be prevented to a port by tying the \overline{BUSY} pin for that port LOW.

The BUSY outputs on the IDT70T651/9 RAM in master mode, are push-pull type outputs and do not require pull up resistors to operate.

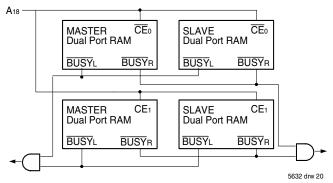


Figure 3. Busy and chip enable routing for both width and depth expansion with IDT70T651/9 Dual-Port RAMs.

If these RAMs are being expanded in depth, then the BUSY indication for the resulting array requires the use of an external AND gate.

Width Expansion with Busy Logic Master/Slave Arrays

When expanding an IDT70T651/9 RAM array in width while using \overline{BUSY} logic, one master part is used to decide which side of the RAMs array will receive a \overline{BUSY} indication, and to output that indication. Any number of slaves to be addressed in the same address range as the master use the \overline{BUSY} signal as a write inhibit signal. Thus on the IDT70T651/9 RAM the \overline{BUSY} pin is an output if the part is used as a master (M/ \overline{S} pin = VIH), and the \overline{BUSY} pin is an input if the part used as a slave (M/ \overline{S} pin = VIL) as shown in Figure 3.

If two or more master parts were used when expanding in width, a split decision could result with one master indicating $\overline{\text{BUSY}}$ on one side of the array and another master indicating $\overline{\text{BUSY}}$ on one other side of the array. This would inhibit the write operations from one port for part of a word and inhibit the write operations from the other port for the other part of the word.

The BUSY arbitration on a master is based on the chip enable and address signals only. It ignores whether an access is a read or write. In a master/slave array, both address and chip enable must be valid long enough for a BUSY flag to be output from the master before the actual write pulse can be initiated with the R/W signal. Failure to observe this timing can result in a glitched internal write inhibit signal and corrupted data in the slave.

Semaphores

The IDT70T651/9 is an extremely fast Dual-Port 256/128K x 36 CMOS Static RAM with an additional 8 address locations dedicated to binary semaphore flags. These flags allow either processor on the left or right side of the Dual-Port RAM to claim a privilege over the other processor for functions defined by the system designer's software. As an example, the semaphore can be used by one processor to inhibit the other from accessing a portion of the Dual-Port RAM or any other shared resource.

The Dual-Port RAM features a fast access time, with both ports being completely independent of each other. This means that the activity on the left port in no way slows the access time of the right port. Both ports are identical in function to standard CMOS Static RAM and can be read from or written to at the same time with the only possible conflict arising from the simultaneous writing of, or a simultaneous READ/WRITE of, a non-semaphore location. Semaphores are protected against such ambiguous situations and may be used by the system program to avoid any conflicts in the non-semaphore portion of the Dual-Port RAM. These devices have an automatic power-down feature controlled by $\overline{\text{CE}}$ 0 and $\overline{\text{CE}}$ 1, the Dual-Port RAM chip enables, and $\overline{\text{SEM}}$, the semaphore enable. The $\overline{\text{CE}}$ 0, $\overline{\text{CE}}$ 1, and $\overline{\text{SEM}}$ pins control onchip power down circuitry that permits the respective port to go into standby mode when not selected.

Systems which can best use the IDT70T651/9 contain multiple processors or controllers and are typically very high-speed systems which are software controlled or software intensive. These systems can benefit from a performance increase offered by the IDT70T651/9s hardware semaphores, which provide a lockout mechanism without requiring complex programming.

Software handshaking between processors offers the maximum in system flexibility by permitting shared resources to be allocated in varying configurations. The IDT70T651/9 does not use its semaphore flags to control any resources through hardware, thus allowing the system designer total flexibility in system architecture.

An advantage of using semaphores rather than the more common methods of hardware arbitration is that wait states are never incurred in either processor. This can prove to be a major advantage in very high-speed systems.

How the Semaphore Flags Work

The semaphore logic is a set of eight latches which are independent of the Dual-Port RAM. These latches can be used to pass a flag, or token, from one port to the other to indicate that a shared resource is in use. The semaphores provide a hardware assist for a use assignment method called "Token Passing Allocation." In this method, the state of a semaphore latch is used as a token indicating that a shared resource is in use. If the left processor wants to use this resource, it requests the token by setting the latch. This processor then

verifies its success in setting the latch by reading it. If it was successful, it proceeds to assume control over the shared resource. If it was not successful in setting the latch, it determines that the right side processor has set the latch first, has the token and is using the shared resource. The left processor can then either repeatedly request that semaphore's status or remove its request for that semaphore to perform another task and occasionally attempt again to gain control of the token via the set and test sequence. Once the right side has relinquished the token, the left side should succeed in gaining control.

The semaphore flags are active LOW. A token is requested by writing a zero into a semaphore latch and is released when the same side writes a one to that latch.

The eight semaphore flags reside within the IDT70T651/9 in a separate memory space from the Dual-Port RAM. This address space is accessed by placing a low input on the $\overline{\text{SEM}}$ pin (which acts as a chip select for the semaphore flags) and using the other control pins (Address, $\overline{\text{CE0}}$, CE1,R/ $\overline{\text{W}}$ and $\overline{\text{BEn}}$) as they would be used in accessing a standard Static RAM. Each of the flags has a unique address which can be accessed by either side through address pins A0 – A2. When accessing the semaphores, none of the other address pins has any effect.

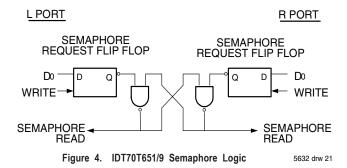
When writing to a semaphore, only data pin D0 is used. If a low level is written into an unused semaphore location, that flag will be set to a zero on that side and a one on the other side (see Truth Table V). That semaphore can now only be modified by the side showing the zero. When a one is written into the same location from the same side, the flag will be set to a one for both sides (unless a semaphore request from the other side is pending) and then can be written to by both sides. The fact that the side which is able to write a zero into a semaphore subsequently locks out writes from the other side is what makes semaphore flags useful in interprocessor communications. (A thorough discussion on the use of this feature follows shortly.) A zero written into the same location from the other side will be stored in the semaphore request latch for that side until the semaphore is freed by the first side.

When a semaphore flag is read, its value is spread into all data bits so that a flag that is a one reads as a one in all data bits and a flag containing a zero reads as all zeros for a semaphore read, the \overline{SEM} , \overline{BEn} , and \overline{OE} signals need to be active. (Please refer to Truth Table II). Furthermore, the read value is latched into one side's output register when that side's semaphore select (\overline{SEM} , \overline{BEn}) and output enable (\overline{OE}) signals go active. This serves to disallow the semaphore from changing state in the middle of a read cycle due to a write cycle from the other side.

A sequence WRITE/READ must be used by the semaphore in order to guarantee that no system level contention will occur. A processor requests access to shared resources by attempting to write a zero into a semaphore location. If the semaphore is already in use, the semaphore request latch will contain a zero, yet the semaphore flag will appear as one, a fact which the processor will verify by the subsequent read (see Table V). As an example, assume a processor writes a zero to the left port at a free semaphore location. On a subsequent read, the processor will verify that it has written successfully to that location and will assume control over the resource in question. Meanwhile, if a processor on the right side attempts to write a zero to the same semaphore flag it will fail, as will be verified by the fact that a one will be read from that semaphore on the right side during subsequent read. Had a sequence of READ/WRITE been used instead, system contention problems could have occurred during

the gap between the read and write cycles.

It is important to note that a failed semaphore request must be followed by either repeated reads or by writing a one into the same location. The reason for this is easily understood by looking at the simple logic diagram of the semaphore flag in Figure 4. Two semaphore request latches feed into a semaphore flag. Whichever latch is first to present a zero to the semaphore flag will force its side of the semaphore flag LOW and the other side HIGH. This condition will continue until a one is written to the same semaphore request latch. If the opposite side semaphore flag will flip over to the other side as soon as a one is written into the first request latch. The opposite side flag will now stay LOW until its semaphore request latch is written to a one. From this it is easy to



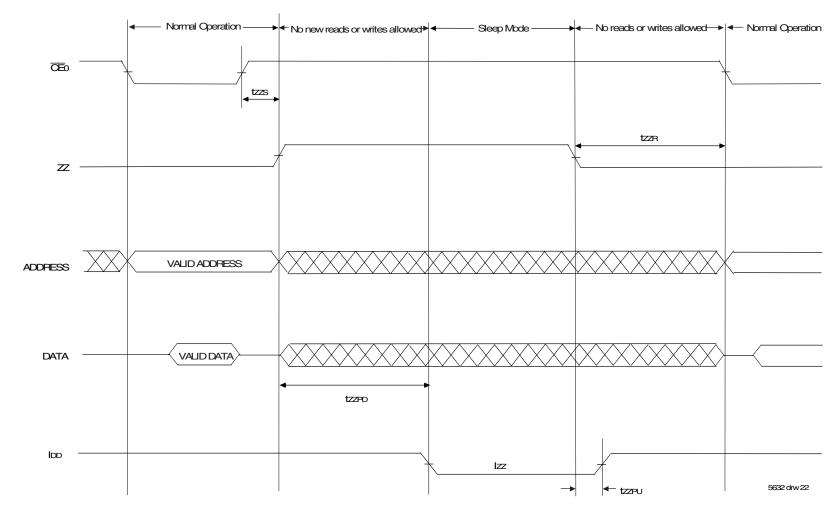
understand that, if a semaphore is requested and the processor which requested it no longer needs the resource, the entire system can hang up until a one is written into that semaphore request latch.

The critical case of semaphore timing is when both sides request a single token by attempting to write a zero into it at the same time. The semaphore logic is specially designed to resolve this problem. If simultaneous requests are made, the logic guarantees that only one side receives the token. If one side is earlier than the other in making the request, the first side to make the request will receive the token. If both requests arrive at the same time, the assignment will be arbitrarily made to one port or the other.

One caution that should be noted when using semaphores is that semaphores alone do not guarantee that access to a resource is secure. As with any powerful programming technique, if semaphores are misused or misinterpreted, a software error can easily happen.

Initialization of the semaphores is not automatic and must be handled via the initialization program at power-up. Since any sema-phore request flag which contains a zero must be reset to a one, all semaphores on both sides should have a one written into them at initialization from both sides to assure that they will be free when needed.

Timing Waveform of Sleep Mode^(1,2)



- NOTES: 1. CE1 = VIH.
- 2. All timing is same for Left and Right ports.

Sleep Mode

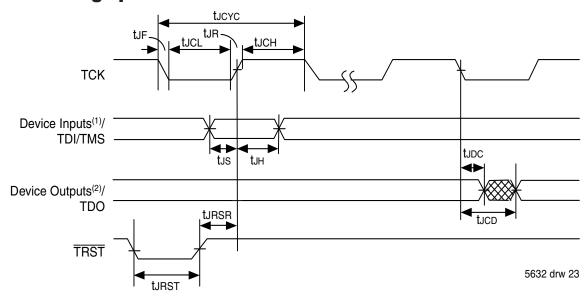
The IDT70T651/9 is equipped with an optional sleep or low power mode on both ports. The sleep mode pin on both ports is active high. During normal operation, the ZZ pin is pulled low. When ZZ is pulled high, the port will enter sleep mode where it will meet lowest possible power conditions. The sleep mode timing diagram shows the modes of operation: Normal Operation, No Read/Write Allowed and Sleep Mode.

For a period of time prior to sleep mode and after recovering from sleep mode (tzzs and tzzr), new reads or writes are not allowed. If a write or read

operation occurs during these periods, the memory array may be corrupted. Validity of data out from the RAM cannot be guaranteed immediately after ZZ is asserted (prior to being in sleep).

During sleep mode the RAM automatically deselects itself. The RAM disconnects its internal buffer. All outputs will remain in high-Z state while in sleep mode. All inputs are allowed to toggle. The RAM will not be selected and will not perform any reads or writes.

JTAG Timing Specifications



NOTES:

- 1. Device inputs = All device inputs except TDI, TMS, TCK and TRST.
- 2. Device outputs = All device outputs except TDO.

JTAG AC Electrical Characteristics^(1,2,3,4,5)

			70T651/9	
Symbol	Parameter	Min.	Max.	Units
tucyc	JTAG Clock Input Period	100	_	ns
tлсн	JTAG Clock HIGH	40	_	ns
tucL	JTAG Clock Low	40	_	ns
tur	JTAG Clock Rise Time	_	3 ⁽¹⁾	ns
tJF	JTAG Clock Fall Time	_	3 ⁽¹⁾	ns
turst	JTAG Reset	50		ns
tursr	JTAG Reset Recovery	50		ns
tuco	JTAG Data Output	_	25	ns
tupc	JTAG Data Output Hold	0		ns
tus	JTAG Setup	15		ns
tлн	JTAG Hold	15	_	ns

- 1. Guaranteed by design.
- 30pF loading on external output signals.
- 3. Refer to AC Electrical Test Conditions stated earlier in this document.
- 4. JTAG operations occur at one speed (10MHz). The base device may run at any speed specified in this datasheet.
- 5. JTAG cannot be tested in sleep mode.