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Kind regards,

Team Nexperia

# 74LVC1T45; 74LVCH1T45

# Dual supply translating transceiver; 3-state Rev. 6 — 6 August 2012

**Product data sheet** 

#### **General description** 1.

The 74LVC1T45; 74LVCH1T45 are single bit, dual supply transceivers with 3-state outputs that enable bidirectional level translation. They feature two 1-bit input-output ports (A and B), a direction control input (DIR) and dual supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ). Both V<sub>CC(A)</sub> and V<sub>CC(B)</sub> can be supplied at any voltage between 1.2 V and 5.5 V making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and DIR are referenced to  $V_{CC(A)}$  and pin B is referenced to V<sub>CC(B)</sub>. A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

The devices are fully specified for partial power-down applications using I<sub>OFF</sub>. The I<sub>OFF</sub> circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either  $V_{\text{CC(A)}}$  or  $V_{\text{CC(B)}}$  are at GND level, both A port and B port are in the high-impedance OFF-state.

Active bus hold circuitry in the 74LVCH1T45 holds unused or floating data inputs at a valid logic level.

#### Features and benefits 2.

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 1.2 V to 5.5 V
  - ◆ V<sub>CC(B)</sub>: 1.2 V to 5.5 V
- High noise immunity
- Complies with JEDEC standards:
  - ◆ JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8C (2.7 V to 3.6 V)
  - ◆ JESD36 (4.5 V to 5.5 V)
- ESD protection:
  - HBM JESD22-A114F Class 3A exceeds 4000 V
  - CDM JESD22-C101E exceeds 1000 V
- Maximum data rates:
  - 420 Mbps (3.3 V to 5.0 V translation)
  - 210 Mbps (translate to 3.3 V))
  - 140 Mbps (translate to 2.5 V)
  - 75 Mbps (translate to 1.8 V)
  - 60 Mbps (translate to 1.5 V)
- Suspend mode



- Latch-up performance exceeds 100 mA per JESD 78 Class II
- ±24 mA output drive (V<sub>CC</sub> = 3.0 V)
- Inputs accept voltages up to 5.5 V
- Low power consumption: 16 μA maximum I<sub>CC</sub>
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

#### 3. Ordering information

Table 1. Ordering information

Type number	Package							
	Temperature range	Name	Description	Version				
74LVC1T45GW	–40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363				
74LVCH1T45GW								
74LVC1T45GM	–40 °C to +125 °C	XSON6						
74LVCH1T45GM			6 terminals; body 1 $\times$ 1.45 $\times$ 0.5 mm					
74LVC1T45GF	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads;	SOT891				
74LVCH1T45GF			6 terminals; body 1 $\times$ 1 $\times$ 0.5 mm					
74LVC1T45GN	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads;	SOT1115				
74LVCH1T45GN			6 terminals; body $0.9 \times 1.0 \times 0.35$ mm					
74LVC1T45GS	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads;					
74LVCH1T45GS			6 terminals; body $1.0 \times 1.0 \times 0.35$ mm					

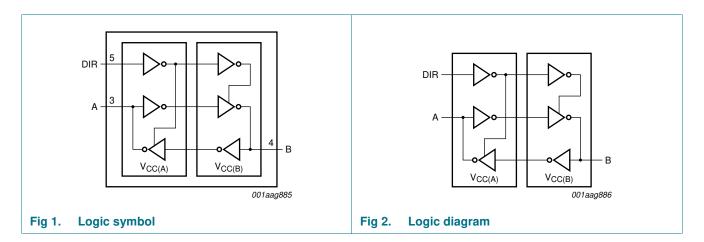
#### 4. Marking

Table 2. Marking

Type number	Marking code <sup>[1]</sup>
74LVC1T45GW	V5
74LVCH1T45GW	X5
74LVC1T45GM	V5
74LVCH1T45GM	X5
74LVC1T45GF	V5
74LVCH1T45GF	X5
74LVC1T45GN	V5
74LVCH1T45GN	X5
74LVC1T45GS	V5
74LVCH1T45GS	X5

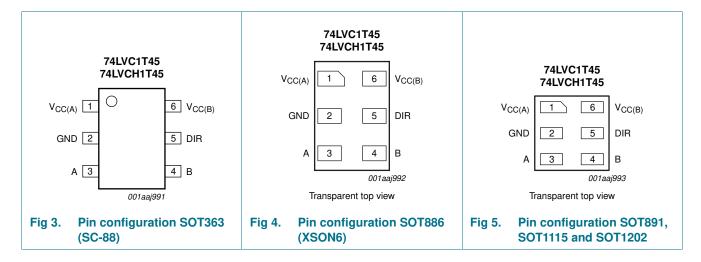
<sup>[1]</sup> The pin 1 indicator is located on the lower left corner of the device, below the marking code.

## 5. Functional diagram



#### 6. Pinning information

#### 6.1 Pinning



#### 6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
$V_{CC(A)}$	1	supply voltage port A and DIR
GND	2	ground (0 V)
Α	3	data input or output
В	4	data input or output
DIR	5	direction control
$V_{CC(B)}$	6	supply voltage port B

#### 7. Functional description

Table 4. Function table[1]

Supply voltage	Input	Input/output[2]				
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	DIR	Α	В			
1.2 V to 5.5 V	L	A = B	input			
1.2 V to 5.5 V	Н	input	B = A			
GND[3]	Χ	Z	Z			

- [1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.
- [2] The input circuit of the data I/O is always active.
- [3] When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into suspend mode.

#### 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	$V_I < 0 V$	-50	-	mA
VI	input voltage		<u>[1]</u> –0.5	+6.5	V
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
Vo	output voltage	Active mode	[1][2][3] —0.5	$V_{CCO} + 0.5$	V
		Suspend or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I <sub>O</sub>	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2] -	±50	mA
I <sub>CC</sub>	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	<u>[4]</u> -	250	mW

<sup>[1]</sup> The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

## 9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.2	5.5	V
$V_{CC(B)}$	supply voltage B		1.2	5.5	V
VI	input voltage		0	5.5	V

74LVC\_LVCH1T45

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<sup>[2]</sup>  $V_{\text{CCO}}$  is the supply voltage associated with the output port.

<sup>[3]</sup>  $V_{CCO} + 0.5 \text{ V}$  should not exceed 6.5 V.

<sup>[4]</sup> For SC-88 package: above 87.5 °C the value of P<sub>tot</sub> derates linearly with 4.0 mW/K. For XSON6 package: above 118 °C the value of P<sub>tot</sub> derates linearly with 7.8 mW/K.

Table 6. Recommended operating conditions ...continued

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{O}$	output voltage	Active mode	<u>[1]</u> 0	$V_{CCO}$	V
		Suspend or 3-state mode	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	V <sub>CCI</sub> = 1.2 V	[2] -	20	ns/V
		$V_{CCI} = 1.4 \text{ V to } 1.95 \text{ V}$	-	20	ns/V
		$V_{CCI} = 2.3 \text{ V to } 2.7 \text{ V}$	-	20	ns/V
		$V_{CCI} = 3 V \text{ to } 3.6 V$	-	10	ns/V
		$V_{CCI} = 4.5 \text{ V to } 5.5 \text{ V}$	-	5	ns/V

<sup>[1]</sup>  $V_{CCO}$  is the supply voltage associated with the output port.

#### 10. Static characteristics

Table 7. Typical static characteristics at T<sub>amb</sub> = 25 °C

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{OH}$	HIGH-level output voltage	$V_I = V_{IH}$ or $V_{IL}$				
		$I_O = -3 \text{ mA}; V_{CCO} = 1.2 \text{ V}$		-	V	
$V_{OL}$	LOW-level output voltage	$V_I = V_{IH}$ or $V_{IL}$				
		$I_O = 3 \text{ mA}; V_{CCO} = 1.2 \text{ V}$	<u>[1]</u> -	0.07	-	V
l <sub>1</sub>	input leakage current	DIR input; $V_1 = 0 \text{ V to } 5.5 \text{ V}$ ; $V_{CCI} = 1.2 \text{ V to } 5.5 \text{ V}$	[2] -	-	±1	μΑ
I <sub>BHL</sub>	bus hold LOW current	A or B port; $V_I = 0.42 \text{ V}$ ; $V_{CCI} = 1.2 \text{ V}$	[2] _	19	-	μΑ
I <sub>BHH</sub>	bus hold HIGH current	A or B port; $V_I = 0.78 \text{ V}$ ; $V_{CCI} = 1.2 \text{ V}$	[2] _	-19	-	μΑ
I <sub>BHLO</sub>	bus hold LOW overdrive current	A or B port; $V_{CCI} = 1.2 \text{ V}$	[2][3]	19	-	μΑ
I <sub>BHHO</sub>	bus hold HIGH overdrive current	A or B port; $V_{CCI} = 1.2 \text{ V}$	[2][3]	-19	-	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CCO} = 1.2 \text{ V to } 5.5 \text{ V}$	<u>[1]</u> -	-	±1	μΑ
l <sub>OFF</sub>	power-off leakage current	A port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 1.2$ V to 5.5 V	-	-	±1	μΑ
		B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 1.2$ V to 5.5 V	-	-	±1	μΑ
Cı	input capacitance	DIR input; $V_1 = 0$ V or 3.3 V; $V_{CC(A)} = V_{CC(B)} = 3.3$ V	-	2.2	-	pF
$C_{I/O}$	input/output capacitance	A and B port; suspend mode; $V_O = 3.3 \text{ V}$ or 0 V; $V_{CC(A)} = V_{CC(B)} = 3.3 \text{ V}$	-	6.0	-	pF

<sup>[1]</sup>  $V_{\text{CCO}}$  is the supply voltage associated with the output port.

<sup>[2]</sup>  $V_{CCI}$  is the supply voltage associated with the input port.

<sup>[2]</sup>  $V_{CCI}$  is the supply voltage associated with the data input port.

<sup>[3]</sup> To guarantee the node switches, an external driver must source/sink at least I<sub>BHLO</sub>/I<sub>BHHO</sub> when the input is in the range V<sub>IL</sub> to V<sub>IH</sub>.

Table 8. Static characteristics

Symbol	Parameter	Conditions	–40 °C t	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Max	Min	Max	
V <sub>IL</sub>	HIGH-level	data input	[1]				
	input voltage	V <sub>CCI</sub> = 1.2 V	0.8V <sub>CCI</sub>	-	0.8V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	1.7	-	1.7	-	V
		$V_{CCI} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	-	2.0	-	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	0.7V <sub>CCI</sub>	-	0.7V <sub>CCI</sub>	-	V
		DIR input					
		V <sub>CCI</sub> = 1.2 V	0.8V <sub>CC(A)</sub>	-	0.8V <sub>CC(A)</sub>	-	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	0.65V <sub>CC(A)</sub>	-	0.65V <sub>CC(A)</sub>	-	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	1.7	-	1.7	-	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	2.0	-	2.0	-	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	0.7V <sub>CC(A)</sub>	-	0.7V <sub>CC(A)</sub>	-	V
	LOW-level	data input	<u>[1]</u>				
	input voltage	V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CCI</sub>	-	0.2V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	8.0	-	8.0	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	-	0.3V <sub>CCI</sub>	-	0.3V <sub>CCI</sub>	V
		DIR input					
		V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CC(A)</sub>	-	0.2V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CC(A)</sub>	-	0.35V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.8	-	0.8	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	-	$0.3V_{CC(A)}$	-	$0.3V_{CC(A)}$	V
V <sub>OH</sub>	HIGH-level	$V_I = V_{IH}$					
	output voltage	$I_O = -100 \ \mu\text{A};$ $V_{CCO} = 1.2 \ V \ to \ 4.5 \ V$	2 V <sub>CCO</sub> – 0.1	-	V <sub>CCO</sub> - 0.1	-	V
		$I_O = -6 \text{ mA}; V_{CCO} = 1.4 \text{ V}$	1.0	-	1.0	-	V
		$I_{O} = -8 \text{ mA}; V_{CCO} = 1.65 \text{ V}$	1.2	-	1.2	-	V
		$I_{O} = -12 \text{ mA}; V_{CCO} = 2.3 \text{ V}$	1.9	-	1.9	-	V
		$I_{O} = -24 \text{ mA}; V_{CCO} = 3.0 \text{ V}$	2.4	-	2.4	-	V
		$I_{O} = -32 \text{ mA}; V_{CCO} = 4.5 \text{ V}$	3.8	-	3.8	-	V

 Table 8.
 Static characteristics ...continued

Symbol	Parameter	Conditions		-40 °C t	o +85 °C	-40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
V <sub>OL</sub>	LOW-level	$V_I = V_{IL}$	[2]					
	output voltage	$I_O = 100 \mu A;$ $V_{CCO} = 1.2 \text{ V to } 4.5 \text{ V}$		-	0.1	-	0.1	V
		$I_O = 6 \text{ mA}; V_{CCO} = 1.4 \text{ V}$		-	0.3	-	0.3	V
		$I_O = 8 \text{ mA}; V_{CCO} = 1.65 \text{ V}$		-	0.45	-	0.45	V
		$I_O = 12 \text{ mA}; V_{CCO} = 2.3 \text{ V}$		-	0.3	-	0.3	V
		$I_O = 24 \text{ mA}; V_{CCO} = 3.0 \text{ V}$		-	0.55	-	0.55	V
		$I_O = 32 \text{ mA}; V_{CCO} = 4.5 \text{ V}$		-	0.55	-	0.55	V
I <sub>I</sub>	input leakage current	DIR input; $V_I = 0 \text{ V to } 5.5 \text{ V};$ $V_{CCI} = 1.2 \text{ V to } 5.5 \text{ V}$		-	±2	-	±10	μА
I <sub>BHL</sub>	bus hold LOW	A or B port	[1]					
	current	$V_I = 0.49 \text{ V}; V_{CCI} = 1.4 \text{ V}$		15	-	10	-	μΑ
		V <sub>I</sub> = 0.58 V; V <sub>CCI</sub> = 1.65 V		25	-	20	-	μΑ
		$V_{I} = 0.70 \text{ V}; V_{CCI} = 2.3 \text{ V}$		45	-	45	-	μΑ
		$V_{I} = 0.80 \text{ V}; V_{CCI} = 3.0 \text{ V}$		100	-	80	-	μΑ
		V <sub>I</sub> = 1.35 V; V <sub>CCI</sub> = 4.5 V		100	-	100	-	μΑ
I <sub>BHH</sub>	bus hold HIGH current	A or B port	[1]					
		V <sub>I</sub> = 0.91 V; V <sub>CCI</sub> = 1.4 V		-15	-	-10	-	μΑ
		V <sub>I</sub> = 1.07 V; V <sub>CCI</sub> = 1.65 V		-25	-	-20	-	μΑ
		V <sub>I</sub> = 1.60 V; V <sub>CCI</sub> = 2.3 V		-45	-	-45	-	μΑ
		V <sub>I</sub> = 2.00 V; V <sub>CCI</sub> = 3.0 V		-100	-	-80	-	μΑ
		V <sub>I</sub> = 3.15 V; V <sub>CCI</sub> = 4.5 V		-100	-	-100	-	μΑ
I <sub>BHLO</sub>	bus hold LOW	A or B port	[1][3]				0.1 V 0.3 V 0.45 V 0.3 V 0.55 V 0.55 V ±10  -	
	overdrive current	V <sub>CCI</sub> = 1.6 V		125	-	125	-	μΑ
	Current	V <sub>CCI</sub> = 1.95 V		200	-	200	-	μΑ
		$V_{CCI} = 2.7 V$		300	-	300	-	μΑ
		$V_{CCI} = 3.6 V$		500	-	500	-	μΑ
		$V_{CCI} = 5.5 V$		900	-	900	-	μΑ
I <sub>BHHO</sub>	bus hold HIGH	A or B port	[1][3]					
	overdrive current	V <sub>CCI</sub> = 1.6 V		-125	-	-125	-	μΑ
	Julient	V <sub>CCI</sub> = 1.95 V		-200	-	-200	-	μΑ
		$V_{CCI} = 2.7 V$		-300	-	-300	-	μΑ
		$V_{CCI} = 3.6 V$		-500	-	-500	-	μА
		$V_{CCI} = 5.5 V$		-900	-	-900	-	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CCO} = 1.2 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μΑ

 Table 8.
 Static characteristics ...continued

Symbol	Parameter	Conditions		-40 °C 1	to +85 °C	-40 °C to	+125 °C	Unit
l power off				Min	Max	Min	Max	
I <sub>OFF</sub>	power-off leakage current	A port; $V_I$ or $V_O$ = 0 V to 5.5 V; $V_{CC(A)}$ = 0 V; $V_{CC(B)}$ = 1.2 V to 5.5 V	•	-	±2	-	±10	μА
		B port; $V_I$ or $V_O = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 1.2$ V to 5.5 V		-	±2	-	±10	μА
I <sub>CC</sub>	supply current	A port; $V_I = 0 V \text{ or } V_{CCI}$ ; $I_O = 0 A$	[1]					
		$V_{CC(A)}$ , $V_{CC(B)} = 1.2 \text{ V to } 5.5 \text{ V}$		-	8	-	8	μΑ
		$V_{CC(A)}$ , $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	3	-	3	μΑ
		$V_{CC(A)} = 5.5 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	2	-	2	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-2	-	-2	-	μΑ
		B port; $V_I = 0 \text{ V or } V_{CCI}$ ; $I_O = 0 \text{ A}$						
		$V_{CC(A)}$ , $V_{CC(B)} = 1.2 \text{ V to } 5.5 \text{ V}$		-	8	-	8	μΑ
		$V_{CC(A)}$ , $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	3	-	3	μΑ
		$V_{CC(B)} = 5.5 \text{ V}; V_{CC(A)} = 0 \text{ V}$		-	2	-	2	μΑ
		$V_{CC(B)} = 0 \text{ V}; V_{CC(A)} = 5.5 \text{ V}$		-2	-	-2	-	μΑ
		A plus B port $(I_{CC(A)} + I_{CC(B)})$ ; $I_O = 0$ A; $V_I = 0$ V or $V_{CCI}$						
		$V_{CC(A)}$ , $V_{CC(B)} = 1.2 \text{ V to } 5.5 \text{ V}$		-	16	-	16	μΑ
		$V_{CC(A)}, V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	4	-	4	μΑ
$\Delta I_{CC}$	additional	$V_{CC(A)}$ , $V_{CC(B)} = 3.0 \text{ V to } 5.5 \text{ V}$						
	supply current	A port; A port at $V_{CC(A)} - 0.6 \text{ V}$ ; DIR at $V_{CC(A)}$ ; B port = open	[4]	-	50	-	75	μА
		DIR input; DIR at $V_{CC(A)} - 0.6 \text{ V}$ ; A port at $V_{CC(A)}$ or GND; B port = open		-	50	-	75	μА
		B port; B port at $V_{CC(B)} - 0.6 \text{ V}$ ; DIR at GND; A port = open	[4]	-	50	-	75	μА

<sup>[1]</sup>  $V_{\text{CCI}}$  is the supply voltage associated with the data input port.

<sup>[2]</sup>  $V_{CCO}$  is the supply voltage associated with the output port.

<sup>[3]</sup> To guarantee the node switches, an external driver must source/sink at least  $I_{BHLO}/I_{BHHO}$  when the input is in the range  $V_{IL}$  to  $V_{IH}$ .

<sup>[4]</sup> For non bus hold parts only (74LVC1T45).

## 11. Dynamic characteristics

Table 9. Typical dynamic characteristics at  $V_{CC(A)} = 1.2 \text{ V}$  and  $T_{amb} = 25 \text{ °C}$ Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for waveforms see <u>Figure 6</u> and <u>Figure 7</u>

Symbol	Parameter	Conditions	$V_{CC(B)}$						
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>PLH</sub>	LOW to HIGH	A to B	10.6	8.1	7.0	5.8	5.3	5.1	ns
	propagation delay	B to A	10.6	9.5	9.0	8.5	8.3	8.2	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	10.1	7.1	6.0	5.3	5.2	5.4	ns
	propagation delay	B to A	10.1	8.6	8.1	7.8	7.6	7.6	ns
t <sub>PHZ</sub> F	HIGH to OFF-state	DIR to A	9.4	9.4	9.4	9.4	9.4	9.4	ns
	propagation delay	DIR to B	12.0	9.4	9.0	7.8	8.4	7.9	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	7.1	7.1	7.1	7.1	7.1	7.1	ns
	propagation delay	DIR to B	9.5	7.8	7.7	6.9	7.6	7.0	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A	20.1	17.3	16.7	15.4	15.9	15.2	ns
	propagation delay	DIR to B	17.7	15.2	14.1	12.9	12.4	12.2	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A	22.1	18.0	17.1	15.6	16.0	15.5	ns
	propagation delay	DIR to B	19.5	16.5	15.4	14.7	14.6	14.8	ns

<sup>[1]</sup> t<sub>PZH</sub> and t<sub>PZL</sub> are calculated values using the formula shown in Section 14.4 "Enable times"

Table 10. Typical dynamic characteristics at  $V_{CC(B)} = 1.2 \text{ V}$  and  $T_{amb} = 25 \text{ °C}$ Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for waveforms see <u>Figure 6</u> and <u>Figure 7</u>

Symbol	Parameter	Conditions			Vc	C(A)			Unit
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>PLH</sub>	LOW to HIGH	A to B	10.6	9.5	9.0	8.5	8.3	8.2	ns
	propagation delay	B to A	10.6	8.1	7.0	5.8	5.3	5.1	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	10.1	8.6	8.1	7.8	7.6	7.6	ns
	propagation delay	B to A	10.1	7.1	6.0	5.3	5.2	5.4	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	9.4	6.5	5.7	4.1	4.1	3.0	ns
	propagation delay	DIR to B	12.0	6.1	5.4	4.6	4.3	4.0	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	7.1	4.9	4.5	3.2	3.4	2.5	ns
	propagation delay	DIR to B	9.5	7.3	6.6	5.9	5.7	5.6	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A	20.1	15.4	13.6	11.7	11.0	10.7	ns
	propagation delay	DIR to B	17.7	14.4	13.5	11.7	11.7	10.7	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A	22.1	13.2	11.4	9.9	9.5	9.4	ns
	propagation delay	DIR to B	19.5	15.1	13.8	11.9	11.7	10.6	ns

<sup>[1]</sup>  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in Section 14.4 "Enable times"

Table 11. Typical power dissipation capacitance at  $V_{CC(A)} = V_{CC(B)}$  and  $T_{amb} = 25 \, ^{\circ}C \, \frac{[1][2]}{CC(B)}$ 

Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		V <sub>CC(A)</sub> ar	nd V <sub>CC(B)</sub>		Unit
			1.8 V	2.5 V	3.3 V	5.5 V	
$C_{PD}$	power dissipation capacitance	A port: (direction A to B); B port: (direction B to A)	2	3	3	4	pF
		A port: (direction B to A); B port: (direction A to B)	15	16	16	18	pF

[1]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i = 10$  MHz;  $V_I = GND$  to  $V_{CC}$ ;  $t_r = t_f = 1$  ns;  $C_L = 0$  pF;  $R_L = \infty \Omega$ .

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>										Unit
			1.5 V ±	± 0.1 V	1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V =	± 0.3 V	5.0 V ±	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.4 V to 1.6 V	'		•				•	•	'		•	
t <sub>PLH</sub>	LOW to HIGH	A to B	2.8	21.3	2.4	17.6	2.0	13.5	1.7	11.8	1.6	10.5	ns
	propagation delay	B to A	2.8	21.3	2.6	19.1	2.3	14.9	2.3	12.4	2.2	12.0	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.6	19.3	2.2	15.3	1.8	11.8	1.7	10.9	1.7	10.8	ns
	propagation delay	B to A	2.6	19.3	2.4	17.3	2.3	13.2	2.2	11.3	2.3	11.0	ns
$t_{\text{PHZ}}$	HIGH to OFF-state	DIR to A	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	ns
	propagation delay	DIR to B	3.5	24.8	3.5	23.6	3.0	11.0	3.3	11.3	2.8	10.3	ns
$t_{\text{PLZ}}$	LOW to OFF-state	DIR to A	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	ns
	propagation delay	DIR to B	2.8	18.3	3.0	17.2	2.5	9.4	3.0	10.1	2.5	9.4	ns
$t_{PZH}$	OFF-state to HIGH	DIR to A [1]	-	39.6	-	36.3	-	24.3	-	22.5	-	21.4	ns
	propagation delay	DIR to B 🗓	-	32.7	-	29.0	-	24.9	-	23.2	-	21.9	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	44.1	-	40.9	-	24.2	-	22.6	-	21.3	ns
	propagation delay	DIR to B 🗓	-	38.0	-	34.0	-	30.5	-	29.6	-	29.5	ns
V <sub>CC(A)</sub> =	1.65 V to 1.95 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.6	19.1	2.2	17.7	2.2	9.3	1.7	7.2	1.4	6.8	ns
	propagation delay	B to A	2.4	17.6	2.2	17.7	2.3	16.0	2.1	15.5	1.9	15.1	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.4	17.3	2.0	14.3	1.6	8.5	1.8	7.1	1.7	7.0	ns
	propagation delay	B to A	2.2	15.3	2.0	14.3	2.1	12.9	2.0	12.6	1.8	12.2	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	ns
	propagation delay	DIR to B	3.2	24.1	3.2	21.9	2.7	11.5	3.0	10.3	2.5	8.2	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	ns
	propagation delay	DIR to B	2.5	17.6	2.6	16.0	2.2	9.2	2.7	8.4	2.4	6.4	ns

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Table 12. Dynamic characteristics for temperature range –40 °C to +85 °C ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

Symbol	Parameter	Conditions					Vcc	C(B)					Unit
			1.5 V	± 0.1 V	1.8 V =	Ŀ 0.15 V	2.5 V :	± 0.2 V	3.3 V	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	35.2	-	33.7	-	25.2	-	23.9	-	21.8	ns
	propagation delay	DIR to B [1]	-	29.6	-	28.2	-	19.8	-	17.7	-	17.3	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	39.4	-	36.2	-	24.4	-	22.9	-	20.4	ns
	propagation delay	DIR to B 🗓	-	34.4	-	31.4	-	25.6	-	24.2	-	24.1	ns
V <sub>CC(A)</sub> =	2.3 V to 2.7 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	17.9	2.3	16.0	1.5	8.5	1.3	6.2	1.1	4.8	ns
	propagation delay	B to A	2.0	13.5	2.2	9.3	1.5	8.5	1.4	8.0	1.0	7.5	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.3	15.8	2.1	12.9	1.4	7.5	1.3	5.4	0.9	4.6	ns
	propagation delay	B to A	1.8	11.8	1.9	8.5	1.4	7.5	1.3	7.0	0.9	6.2	ns
$t_{\text{PHZ}}$	HIGH to OFF-state	DIR to A	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	ns
	propagation delay	DIR to B	3.0	22.5	3.0	21.4	2.5	11.0	2.8	9.3	2.3	6.9	ns
$t_{PLZ}$	LOW to OFF-state	DIR to A	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	ns
	propagation delay	DIR to B	2.3	14.6	2.5	13.2	2.0	9.0	2.5	8.4	1.8	5.3	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	28.1	-	22.5	-	17.5	-	16.4	-	12.8	ns
	propagation delay	DIR to B 🗓	-	23.7	-	21.8	-	14.3	-	12.0	-	10.6	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	34.3	-	29.9	-	18.5	-	16.3	-	13.1	ns
	propagation delay	DIR to B 🗓	-	23.9	-	21.0	-	15.6	-	13.5	-	12.7	ns
V <sub>CC(A)</sub> =	3.0 V to 3.6 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	17.1	2.1	15.5	1.4	8.0	8.0	5.6	0.7	4.4	ns
	propagation delay	B to A	1.7	11.8	1.7	7.2	1.3	6.2	0.7	5.6	0.6	5.4	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.2	15.6	2.0	12.6	1.3	7.0	8.0	5.0	0.7	4.0	ns
	propagation delay	B to A	1.7	10.9	1.8	7.1	1.3	5.4	8.0	5.0	0.7	4.5	ns
$t_{\text{PHZ}}$	HIGH to OFF-state	DIR to A	2.3	7.3	2.3	7.3	2.3	7.3	2.3	7.3	2.7	7.3	ns
	propagation delay	DIR to B	2.9	18.0	2.9	16.5	2.3	10.1	2.7	8.6	2.2	6.3	ns
$t_{PLZ}$	LOW to OFF-state	DIR to A	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	ns
	propagation delay	DIR to B	2.3	13.6	2.4	12.5	1.9	7.8	2.3	7.1	1.7	4.9	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	25.4	-	19.7	-	14.0	-	12.7	-	10.3	ns
	propagation delay	DIR to B [1]	-	22.7	-	21.1	-	13.6	-	11.2	-	10.0	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	28.9	-	23.6	-	15.5	-	13.6	-	10.8	ns
	propagation delay	DIR to B [1]	-	22.9	-	19.9	-	14.3	-	12.3	-	11.3	ns
V <sub>CC(A)</sub> =	4.5 V to 5.5 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.2	16.6	1.9	15.1	1.0	7.5	0.7	5.4	0.5	3.9	ns
	propagation delay	B to A	1.6	10.5	1.4	6.8	1.0	4.8	0.7	4.4	0.5	3.9	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.3	15.3	1.8	12.2	1.0	6.2	0.7	4.5	0.5	3.5	ns
	propagation delay	B to A	1.7	10.8	1.7	7.0	0.9	4.6	0.7	4.0	0.5	3.5	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	ns
	propagation delay												

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

Symbol	Parameter	Parameter Conditions		V <sub>CC(B)</sub>										
			1.5 V ±	Ŀ 0.1 V	1.8 V ±	0.15 V	2.5 V ±	Ŀ 0.2 V	3.3 V ±	0.3 V	5.0 V ±	0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
$t_{PLZ}$	LOW to OFF-state	DIR to A	1.4	3.7	1.4	3.7	1.3	3.7	1.0	3.7	0.9	3.7	ns	
	propagation delay	DIR to B	2.3	13.1	2.4	12.1	1.9	7.4	2.3	7.0	1.8	4.5	ns	
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	23.6	-	18.9	-	12.2	-	11.4	-	8.4	ns	
	propagation delay	DIR to B 🗓	-	20.3	-	18.8	-	11.2	-	9.1	-	7.6	ns	
t <sub>PZL</sub>	propagation dolay	DIR to A [1]	-	28.1	-	23.1	-	14.3	-	12.0	-	9.2	ns	
		propagation delay	DIR to B [1]	-	20.7	-	17.6	-	11.6	-	9.9	-	8.9	ns

<sup>[1]</sup> t<sub>PZH</sub> and t<sub>PZL</sub> are calculated values using the formula shown in <u>Section 14.4 "Enable times"</u>

Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

Symbol	Parameter	Conditions					Vcc	(B)					Unit
			1.5 V	± 0.1 V	1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.4 V to 1.6 V							1	1	1			
t <sub>PLH</sub>	LOW to HIGH	A to B	2.5	23.5	2.1	19.4	1.8	14.9	1.5	13.0	1.4	11.6	ns
	propagation delay	B to A	2.5	23.5	2.3	21.1	2.0	16.4	2.0	13.7	1.9	13.2	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.3	21.3	1.9	16.9	1.6	13.0	1.5	12.0	1.5	11.9	ns
	propagation delay	B to A	2.3	21.3	2.1	19.1	2.0	14.6	1.9	12.5	2.0	12.1	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	ns
	propagation delay	DIR to B	3.1	27.3	3.1	26.0	2.7	12.1	2.9	12.5	2.5	11.4	ns
$t_{PLZ}$	LOW to OFF-state	DIR to A	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	ns
	propagation delay	DIR to B	2.5	20.2	2.7	19.0	2.2	10.4	2.7	11.2	2.2	10.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	43.7	-	40.1	-	26.8	-	24.9	-	23.6	ns
	propagation delay	DIR to B [1]	-	36.1	-	32.0	-	27.5	-	25.6	-	24.2	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	48.6	-	45.1	-	26.7	-	25.0	-	23.5	ns
	propagation delay	DIR to B [1]	-	41.9	-	37.5	-	33.6	-	32.6	-	32.5	ns
V <sub>CC(A)</sub> =	1.65 V to 1.95 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	21.1	1.9	19.5	1.9	10.3	1.5	8.0	1.2	7.5	ns
	propagation delay	B to A	2.1	19.4	1.9	19.5	2.0	17.6	1.8	17.1	1.7	16.7	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.1	19.1	1.8	15.8	1.4	9.4	1.6	7.9	1.5	7.7	ns
	propagation delay	B to A	1.9	16.9	1.8	15.8	1.8	14.2	1.8	13.9	1.6	13.5	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	ns
	propagation delay	DIR to B	2.8	26.6	2.8	24.1	2.4	12.7	2.7	11.4	2.2	9.1	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	ns
	propagation delay	DIR to B	2.2	19.4	2.3	17.6	1.9	10.2	2.4	9.3	2.1	7.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	38.8	-	37.1	-	27.8	-	26.4	-	24.1	ns
	propagation delay	DIR to B [1]	-	32.7	-	31.1	-	21.9	-	19.6	-	19.1	ns

Table 13. Dynamic characteristics for temperature range –40 °C to +125 °C ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for wave forms see <u>Figure 6</u> and <u>Figure 7</u>

Symbol	Parameter	Conditions					Vcc	C(B)					Unit
			1.5 V	± 0.1 V	1.8 V ±	Ŀ 0.15 V	2.5 V	± 0.2 V	3.3 V :	± 0.3 V	5.0 V ±	Ŀ 0.5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	43.5	-	39.9	-	26.9	-	25.3	-	22.6	ns
	propagation delay	DIR to B	-	38.0	-	34.7	-	28.3	-	26.8	-	26.6	ns
V <sub>CC(A)</sub> =	2.3 V to 2.7 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.0	19.7	2.0	17.6	1.3	9.4	1.1	6.9	0.9	5.3	ns
	propagation delay	B to A	1.8	14.9	1.9	10.3	1.3	9.4	1.2	8.8	0.9	8.3	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.0	17.4	1.8	14.2	1.2	8.3	1.1	6.0	8.0	5.1	ns
	propagation delay	B to A	1.6	13.0	1.7	9.4	1.2	8.3	1.1	7.7	8.0	6.9	ns
$t_{PHZ}$	HIGH to OFF-state	DIR to A	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	ns
	propagation delay	DIR to B	2.7	24.8	2.7	23.6	2.2	12.1	2.5	10.3	2.0	7.6	ns
$t_{PLZ}$	LOW to OFF-state	DIR to A	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	ns
	propagation delay	DIR to B	2.0	16.1	2.2	14.6	1.8	9.9	2.2	9.3	1.6	5.9	ns
t <sub>PZH</sub>	OFF-state to HIGH propagation delay	DIR to A	-	31.0	-	24.9	-	19.3	-	18.1	-	14.2	ns
	propagation delay	DIR to B	-	26.1	-	24.0	-	15.8	-	13.3	-	11.7	ns
$t_{PZL}$	OFF-state to LOW	DIR to A	-	37.8	-	33.0	-	20.4	-	18.0	-	14.5	ns
	propagation delay	DIR to B	-	26.4	-	23.2	-	17.3	-	15.0	-	14.1	ns
$V_{CC(A)} =$	3.0 V to 3.6 V												
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	2.0	18.9	1.8	17.1	1.2	8.8	0.7	6.2	0.6	4.9	ns
		B to A	1.5	13.0	1.5	8.0	1.1	6.9	0.6	6.2	0.5	6.0	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	1.9	17.2	1.8	13.9	1.1	7.7	0.7	5.5	0.6	4.4	ns
	propagation delay	B to A	1.5	12.0	1.6	7.9	1.1	6.0	0.7	5.5	0.6	5.0	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.0	8.1	2.0	8.1	2.0	8.1	2.0	8.1	2.4	8.1	ns
	propagation delay	DIR to B	2.6	19.8	2.6	18.2	2.0	11.2	2.4	9.5	1.9	7.0	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	ns
		DIR to B	2.0	15.0	2.1	13.8	1.7	8.6	2.0	7.9	1.5	5.4	ns
t <sub>PZH</sub>	OFF-state to HIGH propagation delay	DIR to A [1]	-	28.0	-	21.8	-	15.5	-	14.1	-	11.4	ns
		DIR to B	-	25.1	-	23.3	-	15.0	-	12.4	-	11.1	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	31.8	-	26.1	-	17.2	-	15.0	-	12.0	ns
		DIR to B	-	25.3	-	22.0	-	15.8	-	13.6	-	12.5	ns
	4.5 V to 5.5 V												
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	1.9	18.3	1.7	16.7	0.9	8.3	0.6	6.0	0.4	4.3	ns
		B to A	1.4	11.6	1.2	7.5	0.9	5.3	0.6	4.9	0.4	4.3	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	2.0	16.9	1.6	13.5	0.9	6.9	0.6	5.0	0.4	3.9	ns
		B to A	1.5	11.9	1.5	7.7	0.8	5.1	0.6	4.4	0.4	3.9	ns
t <sub>PHZ</sub>	HIGH to OFF-state propagation delay	DIR to A	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	ns
		DIR to B	2.6	19.1	2.6	17.8	2.0	10.7	2.4	8.8	2.2	6.3	ns
$t_{PLZ}$	LOW to OFF-state	DIR to A	1.2	4.1	1.2	4.1	1.1	4.1	0.9	4.1	8.0	4.1	ns
	propagation delay [	DIR to B	2.0	14.5	2.1	13.4	1.7	8.2	2.0	7.7	1.6	5.0	ns

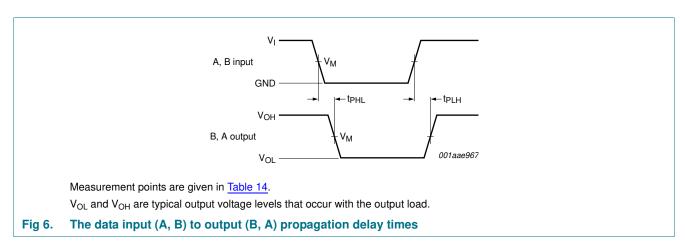
Table 13. Dynamic characteristics for temperature range –40 °C to +125 °C ...continued

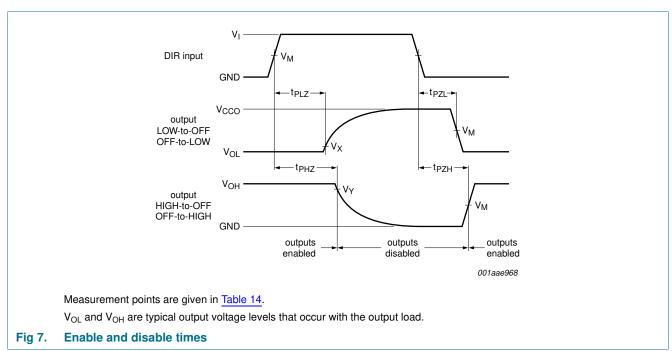
Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7

Symbol	Parameter	Conditions		S V <sub>CC(B)</sub>										Unit
			1.	.5 V ±	0.1 V	1.8 V ±	0.15 V	2.5 V ±	0.2 V	3.3 V ±	0.3 V	5.0 V ±	0.5 V	
			N	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
$t_{PZH}$	OFF-state to HIGH	DIR to A	11	-	26.1	-	20.9	-	13.5	-	12.6	-	9.3	ns
	propagation delay	DIR to B	<u> </u>	-	22.4	-	20.8	-	12.4	-	10.1	-	8.4	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A	<u> </u>	-	31.0	-	25.5	-	15.8	-	13.2	-	10.2	ns
	propagation delay	DIR to B	]	-	22.9	-	19.5	-	12.9	-	11.0	-	9.9	ns

<sup>[1]</sup> t<sub>PZH</sub> and t<sub>PZL</sub> are calculated values using the formula shown in Section 14.4 "Enable times"

#### 12. Waveforms



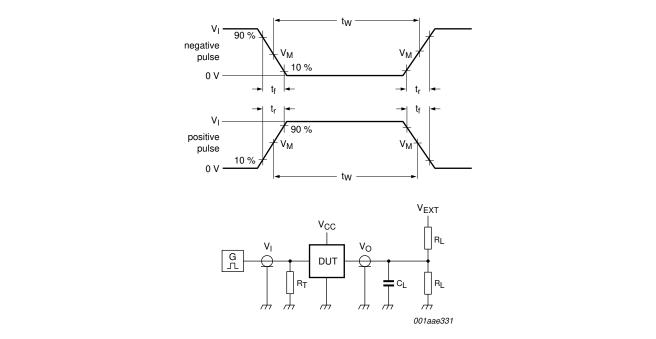


74LVC\_LVCH1T45

Table 14. Measurement points

Supply voltage	Input <sup>[1]</sup>	Output[2]		
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
1.2 V to 1.6 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.1 V$	V <sub>OH</sub> – 0.1 V
1.65 V to 2.7 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.15 V$	$V_{OH}-0.15~V$
3.0 V to 5.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

- [1]  $V_{CCI}$  is the supply voltage associated with the data input port.
- [2]  $V_{CCO}$  is the supply voltage associated with the output port.



Test data is given in Table 15.

R<sub>L</sub> = Load resistance.

C<sub>L</sub> = Load capacitance including jig and probe capacitance.

 $R_T$  = Termination resistance.

 $V_{\text{EXT}}$  = External voltage for measuring switching times.

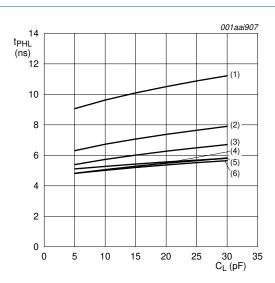
Fig 8. Test circuit for measuring switching times

Table 15. Test data

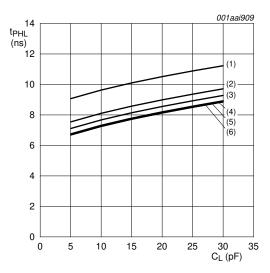
Supply voltage	Input		Load		V <sub>EXT</sub>				
$V_{CC(A)}, V_{CC(B)}$	V <sub>I</sub> [1]	Δt/ΔV[2]	CL	R <sub>L</sub>	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]		
1.2 V to 5.5 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V <sub>CCO</sub>		

- [1]  $V_{CCI}$  is the supply voltage associated with the data input port.
- [2] dV/dt ≥ 1.0 V/ns
- [3]  $V_{\text{CCO}}$  is the supply voltage associated with the output port.

## 13. Typical propagation delay characteristics

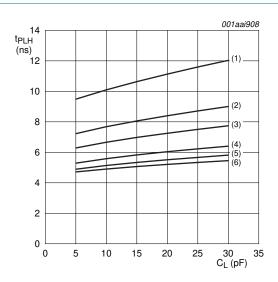


a. HIGH to LOW propagation delay (A to B)

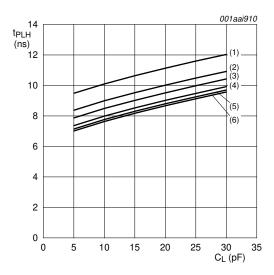


- c. HIGH to LOW propagation delay (B to A)
- (1)  $V_{CC(B)} = 1.2 \text{ V}.$
- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

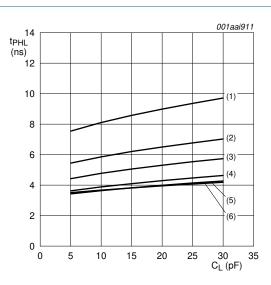


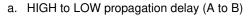


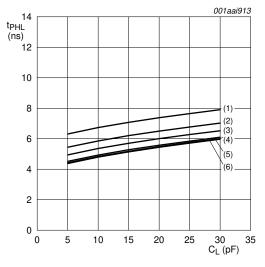
b. LOW to HIGH propagation delay (A to B)



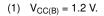
d. LOW to HIGH propagation delay (B to A)





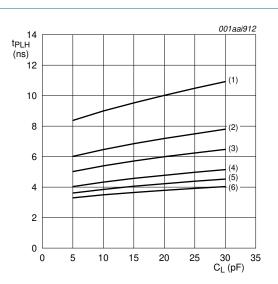


c. HIGH to LOW propagation delay (B to A)

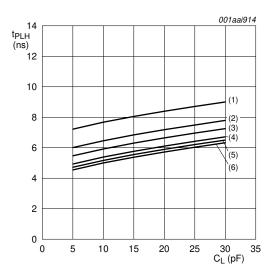


- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

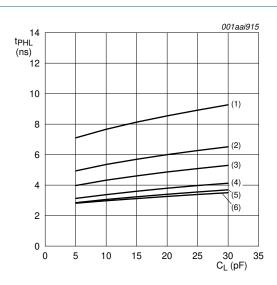
Fig 10. Typical propagation delay vs load capacitance; T<sub>amb</sub> = 25 °C; V<sub>CC(A)</sub> = 1.5 V

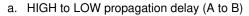


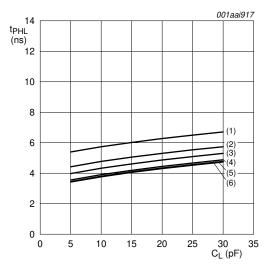
b. LOW to HIGH propagation delay (A to B)



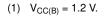
d. LOW to HIGH propagation delay (B to A)





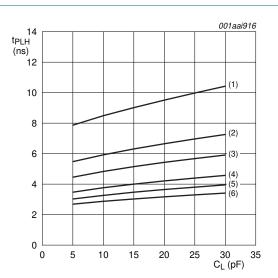


c. HIGH to LOW propagation delay (B to A)

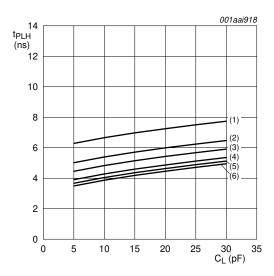


- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

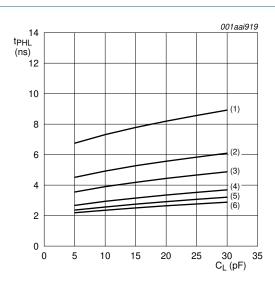
Fig 11. Typical propagation delay vs load capacitance; T<sub>amb</sub> = 25 °C; V<sub>CC(A)</sub> = 1.8 V

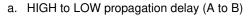


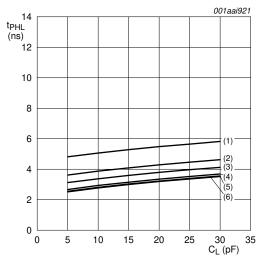
b. LOW to HIGH propagation delay (A to B)



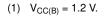
d. LOW to HIGH propagation delay (B to A)





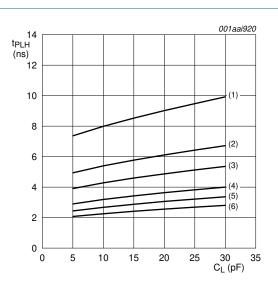


c. HIGH to LOW propagation delay (B to A)

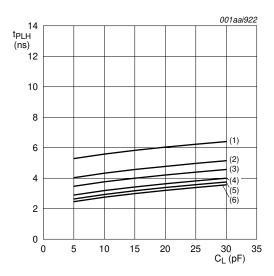


- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

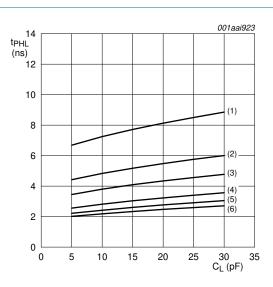
Fig 12. Typical propagation delay vs load capacitance; T<sub>amb</sub> = 25 °C; V<sub>CC(A)</sub> = 2.5 V

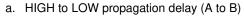


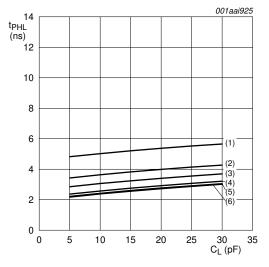
b. LOW to HIGH propagation delay (A to B)



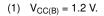
d. LOW to HIGH propagation delay (B to A)





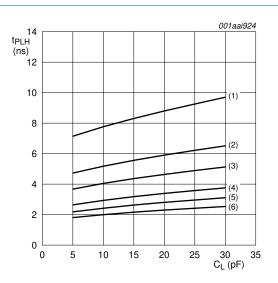


c. HIGH to LOW propagation delay (B to A)

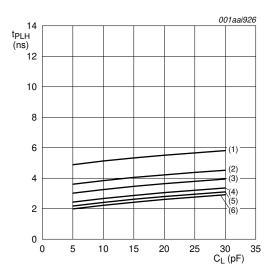


- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

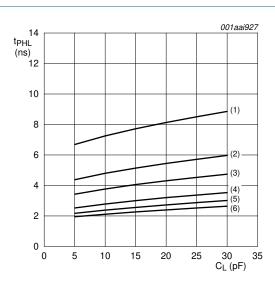
Fig 13. Typical propagation delay vs load capacitance; T<sub>amb</sub> = 25 °C; V<sub>CC(A)</sub> = 3.3 V

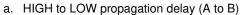


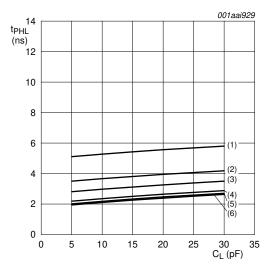
b. LOW to HIGH propagation delay (A to B)



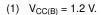
d. LOW to HIGH propagation delay (B to A)





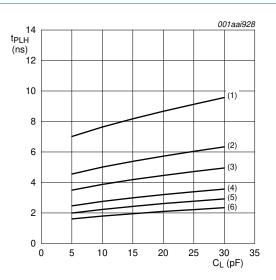


c. HIGH to LOW propagation delay (B to A)

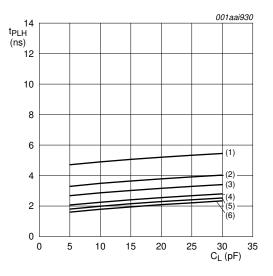


- (2)  $V_{CC(B)} = 1.5 \text{ V}.$
- (3)  $V_{CC(B)} = 1.8 \text{ V}.$
- (4)  $V_{CC(B)} = 2.5 \text{ V}.$
- (5)  $V_{CC(B)} = 3.3 \text{ V}.$
- (6)  $V_{CC(B)} = 5.0 \text{ V}.$

Fig 14. Typical propagation delay vs load capacitance;  $T_{amb} = 25 \, ^{\circ}C$ ;  $V_{CC(A)} = 5 \, V$ 



b. LOW to HIGH propagation delay (A to B)



d. LOW to HIGH propagation delay (B to A)

## 14. Application information

#### 14.1 Unidirectional logic level-shifting application

The circuit given in <u>Figure 15</u> is an example of the 74LVC1T45; 74LVCH1T45 being used in a unidirectional logic level-shifting application.

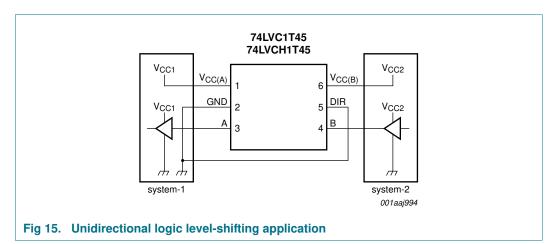
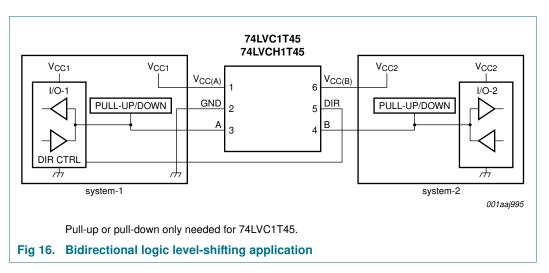


Table 16. Description unidirectional logic level-shifting application

Pin	Name	Function	Description
1	$V_{CC(A)}$	$V_{CC1}$	supply voltage of system-1 (1.2 V to 5.5 V)
2	GND	GND	device GND
3	Α	OUT	output level depends on V <sub>CC1</sub> voltage
4	В	IN	input threshold value depends on V <sub>CC2</sub> voltage
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	$V_{CC(B)}$	$V_{CC2}$	supply voltage of system-2 (1.2 V to 5.5 V)

#### 14.2 Bidirectional logic level-shifting application

<u>Figure 16</u> shows the 74LVC1T45; 74LVCH1T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.



<u>Table 17</u> provides a sequence that illustrates data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 17. Description bidirectional logic level-shifting application[1]

State	DIR CTRL	I/O-1	I/O-2	Description
1	Н	output	input	system-1 data to system-2
2	Н	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold.
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 are still disabled. The bus-line state depends on bus hold.
4	L	input	output	system-2 data to system-1

<sup>[1]</sup> H = HIGH voltage level;

L = LOW voltage level;

Z = high-impedance OFF-state.

#### 14.3 Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

Table 18. Typical total supply current  $(I_{CC(A)} + I_{CC(B)})$ 

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>					Unit	
	0 V	1.8 V	2.5 V	3.3 V	5.0 V		
0 V	0	< 1	< 1	< 1	< 1	μΑ	
1.8 V	< 1	< 2	< 2	< 2	2	μΑ	
2.5 V	< 1	< 2	< 2	< 2	< 2	μΑ	
3.3 V	< 1	< 2	< 2	< 2	< 2	μΑ	
5.0 V	< 1	2	< 2	< 2	< 2	μΑ	

#### 14.4 Enable times

Calculate the enable times for the 74LVC1T45; 74LVCH1T45 using the following formulas:

- $t_{PZH}$  (DIR to A) =  $t_{PLZ}$  (DIR to B) +  $t_{PLH}$  (B to A)
- $t_{PZL}$  (DIR to A) =  $t_{PHZ}$  (DIR to B) +  $t_{PHL}$  (B to A)
- $t_{PZH}$  (DIR to B) =  $t_{PLZ}$  (DIR to A) +  $t_{PLH}$  (A to B)
- $t_{PZL}$  (DIR to B) =  $t_{PHZ}$  (DIR to A) +  $t_{PHL}$  (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74LVC1T45; 74LVCH1T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.