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**FEATURES**

- ◆ Octal T1/E1 short haul analog front end which supports 100 Ω T1 twisted pair, 120 Ω E1 twisted pair and 75 Ω E1 coaxial applications
- ◆ Built-in transmit pre-equalization meets G.703 & T1.102
- ◆ Digital/Analog LOS detector meets ITU G.775, ETS 300 233 and T1.231
- ◆ ITU G.772 non-intrusive monitoring for in-service testing for any one of channel 1 to channel 7
- ◆ Low impedance transmit drivers with high-Z
- ◆ Selectable hardware and parallel/serial host interface
- ◆ Hitless Protection Switching (HPS) for 1 to 1 protection without relays
- ◆ JTAG boundary scan for board test
- ◆ 3.3 V supply with 5 V tolerant I/O
- ◆ Low power consumption
- ◆ Operating temperature range: -40°C to +85°C
- ◆ Available in 144-pin Thin Quad Flat Pack (TQFP) and 160-pin Plastic Ball Grid Array (PBGA) packages  
Green package options available

**FUNCTIONAL BLOCK DIAGRAM**

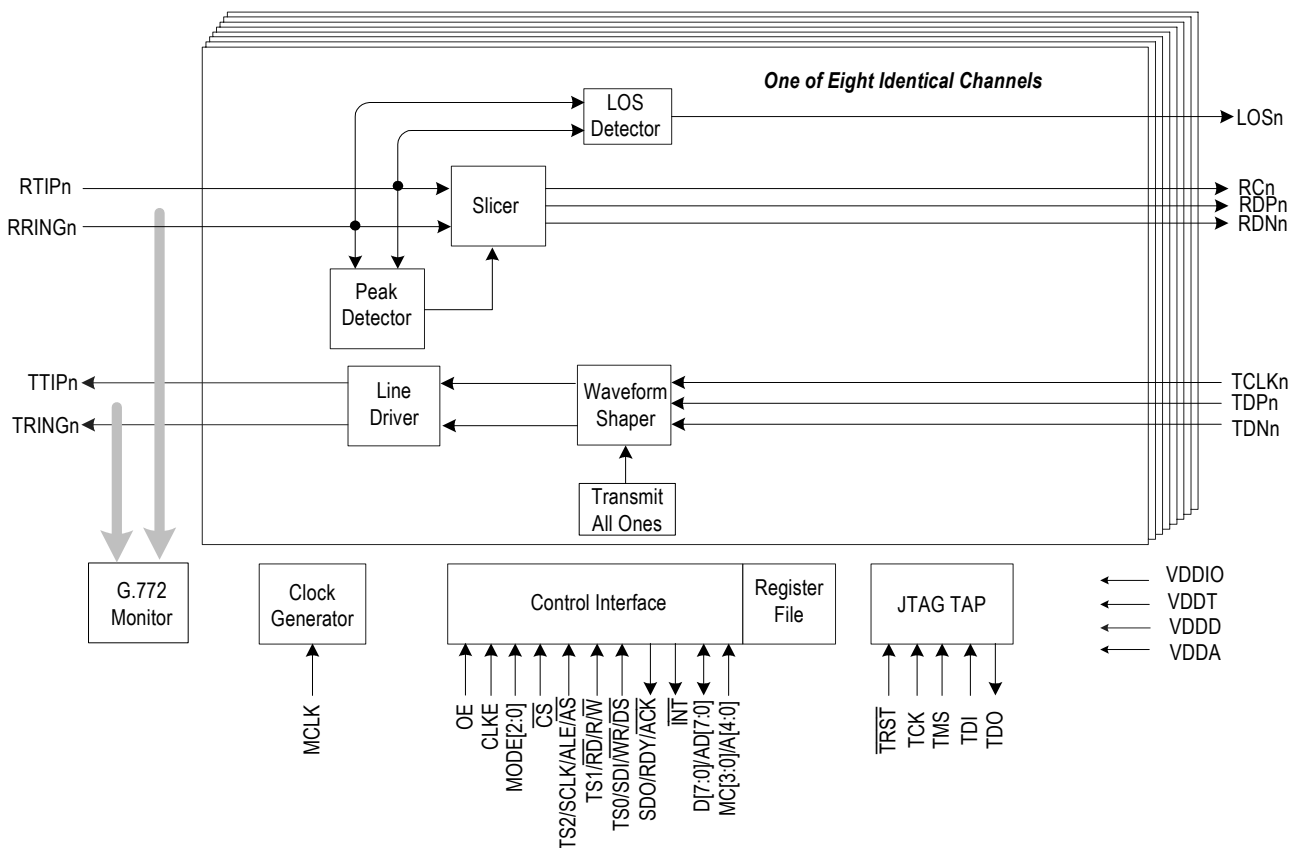


Figure-1 Block Diagram

# PIN CONFIGURATIONS

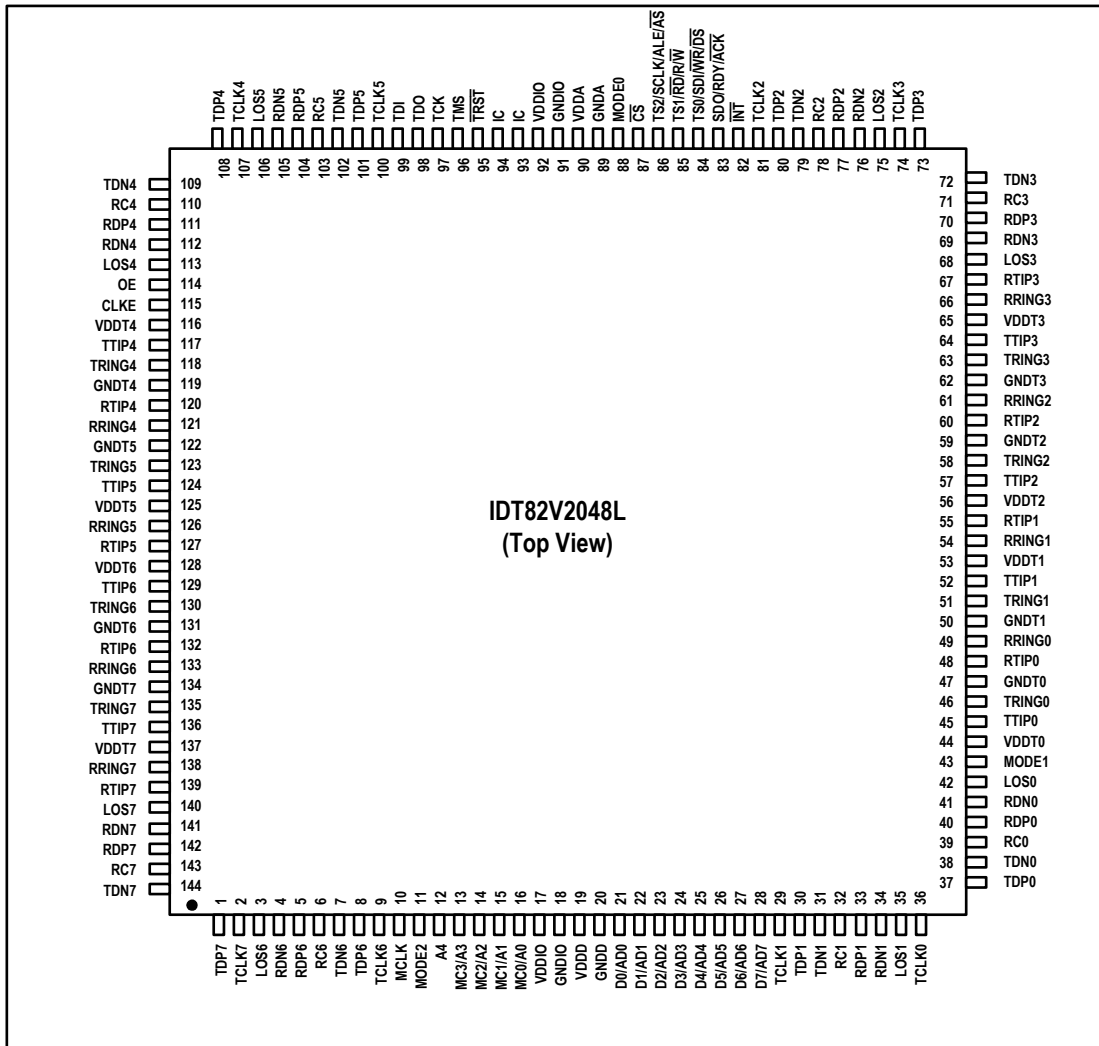


Figure-2 TQFP144 Package Pin Assignment

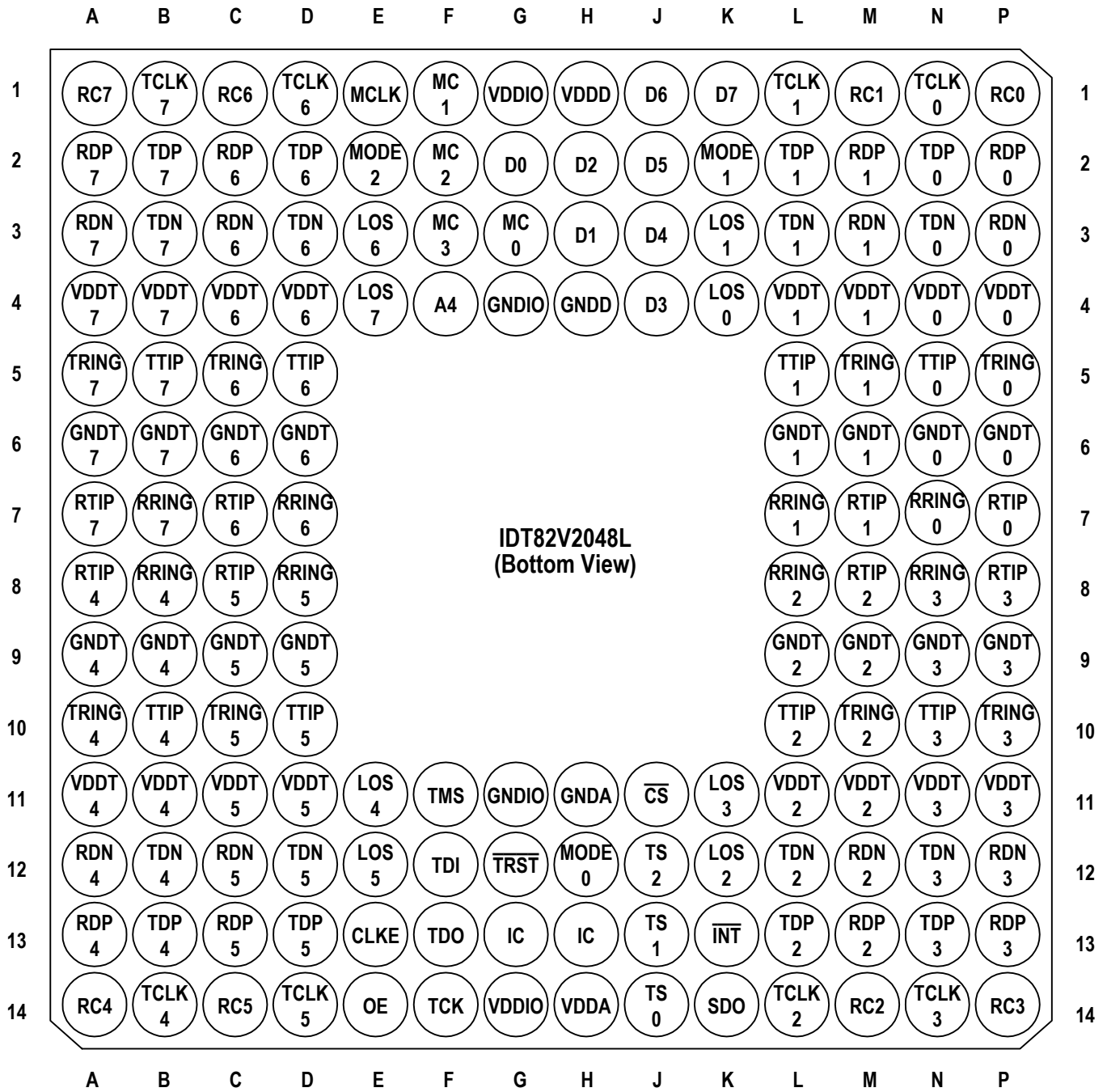


Figure-3 PBGA160 Package Pin Assignment



# 1 PIN DESCRIPTION

Table-1 Pin Description

Name	Type	Pin No.		Description
		TQFP144	PBGA160	
<b>Transmit and Receive Line Interface</b>				
TTIP0	Analog Output	45	N5	<b>TTIPn/TRINGn: Transmit Bipolar Tip/Ring for Channel 0~7</b> These pins are the differential line driver outputs. They will be in high impedance state if pin OE is low or the corresponding pin TCLKn is low (pin OE is global control, while pin TCLKn is per-channel control). In host mode, each pin can be in high impedance by programming a '1' to the corresponding bit in register OE <sup>(1)</sup> .
TTIP1		52	L5	
TTIP2		57	L10	
TTIP3		64	N10	
TTIP4		117	B10	
TTIP5		124	D10	
TTIP6		129	D5	
TTIP7		136	B5	
TRING0		46	P5	
TRING1		51	M5	
TRING2		58	M10	
TRING3		63	P10	
TRING4		118	A10	
TRING5		123	C10	
TRING6	130	C5		
TRING7	135	A5		
RTIP0	Analog Input	48	P7	<b>RTIPn/RRINGn: Receive Bipolar Tip/Ring for Channel 0~7</b> These pins are the differential line receiver inputs.
RTIP1		55	M7	
RTIP2		60	M8	
RTIP3		67	P8	
RTIP4		120	A8	
RTIP5		127	C8	
RTIP6		132	C7	
RTIP7		139	A7	
RRING0		49	N7	
RRING1		54	L7	
RRING2		61	L8	
RRING3		66	N8	
RRING4		121	B8	
RRING5		126	D8	
RRING6	133	D7		
RRING7	138	B7		

<sup>1</sup>. Register name is indicated by bold capital letter. For example, **OE** indicates Output Enable Register.

Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description															
		TQFP144	PBGA160																
<b>Transmit and Receive Digital Data Interface</b>																			
TDP0 TDP1 TDP2 TDP3 TDP4 TDP5 TDP6 TDP7  TDN0 TDN1 TDN2 TDN3 TDN4 TDN5 TDN6 TDN7	I	37 30 80 73 108 101 8 1  38 31 79 72 109 102 7 144	N2 L2 L13 N13 B13 D13 D2 B2  N3 L3 L12 N12 B12 D12 D3 B3	<p><b>TDPn/TDNn: Positive/Negative Transmit Data for Channel 0~7</b> The NRZ data to be transmitted for positive/negative pulse is input on this pin. Data on TDPn/TDNn are active high and are sampled on the falling edges of TCLKn.</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>TDPn</th> <th>TDNn</th> <th>Output Pulse</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Space</td> </tr> <tr> <td>0</td> <td>1</td> <td>Negative Pulse</td> </tr> <tr> <td>1</td> <td>0</td> <td>Positive Pulse</td> </tr> <tr> <td>1</td> <td>1</td> <td>Space</td> </tr> </tbody> </table>	TDPn	TDNn	Output Pulse	0	0	Space	0	1	Negative Pulse	1	0	Positive Pulse	1	1	Space
TDPn	TDNn	Output Pulse																	
0	0	Space																	
0	1	Negative Pulse																	
1	0	Positive Pulse																	
1	1	Space																	
TCLK0 TCLK1 TCLK2 TCLK3 TCLK4 TCLK5 TCLK6 TCLK7	I	36 29 81 74 107 100 9 2	N1 L1 L14 N14 B14 D14 D1 B1	<p><b>TCLKn: Transmit Clock for Channel 0~7</b> The clock of 1.544 MHz (for T1 mode) or 2.048 MHz (for E1 mode) for transmit is input on this pin. The transmit data at TDPn or TDNn is sampled into the device on the falling edges of TCLKn. Different combinations of TCLKn and MCLK result in different transmit mode. It is summarized as <a href="#">Table-2 System Interface Configuration</a>.</p>															
RDP0 RDP1 RDP2 RDP3 RDP4 RDP5 RDP6 RDP7  RDN0 RDN1 RDN2 RDN3 RDN4 RDN5 RDN6 RDN7	O  High Impedance	40 33 77 70 111 104 5 142  41 34 76 69 112 105 4 141	P2 M2 M13 P13 A13 C13 C2 A2  P3 M3 M12 P12 A12 C12 C3 A3	<p><b>RDPn/RDNn: Positive/Negative Receive Data for Channel 0~7</b> These pins output the raw RZ sliced data. The active polarity of RDPn/RDNn is determined by pin CLKE. When pin CLKE is low, RDPn/RDNn is active low. When pin CLKE is high, RDPn/RDNn is active high. RDPn/RDNn will remain active during LOS. RDPn/RDNn is set into high impedance when the corresponding receiver is powered down.</p>															
RC0 RC1 RC2 RC3 RC4 RC5 RC6 RC7	O  High Impedance	39 32 78 71 110 103 6 143	P1 M1 M14 P14 A14 C14 C1 A1	<p><b>RCn: Receive Pulse for Channel 0~7</b> RCn is the output of an internal exclusive OR (XOR) which is connected with RDPn and RDNn. The clock is recovered from the signal on RCn. If receiver n is powered down, the corresponding RCn will be in high impedance.</p>															

Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description																		
		TQFP144	PBGA160																			
MCLK	I	10	E1	<p><b>MCLK: Master Clock</b> This is an independent, free running reference clock. A clock of 1.544 MHz (for T1 mode) or 2.048 MHz (for E1 mode) is supplied to this pin as the clock reference of the device for normal operation. When MCLK is low, all the receivers are powered down, and the output pins RCn, RDPn and RDNn are switched to high impedance. In transmit path, the operation mode is decided by the combination of MCLK and TCLKn (See <a href="#">Table-2 System Interface Configuration</a> for details). <b>NOTE:</b> Wait state generation via RDY/ACK is not available if MCLK is not provided.</p>																		
LOS0 LOS1 LOS2 LOS3 LOS4 LOS5 LOS6 LOS7	O	42 35 75 68 113 106 3 140	K4 K3 K12 K11 E11 E12 E3 E4	<p><b>LOSn: Loss of Signal Output for Channel 0~7</b> A high level on this pin indicates the loss of signal when there is no transition over a specified period of time or no enough ones density in the received signal. The transition will return to low automatically when there is enough transitions over a specified period of time with a certain ones density in the received signal. The LOS assertion and desertion criteria are described in <a href="#">2.4.3 Loss of Signal (LOS) Detection</a>.</p>																		
<b>Hardware/Host Control Interface</b>																						
MODE2	I (Pulled to VDDIO/2)	11	E2	<p><b>MODE2: Control Mode Select 2<sup>(2)</sup></b> The signal on this pin determines which control mode is selected to control the device:</p> <table border="1"> <thead> <tr> <th>MODE2</th> <th>Control Interface</th> </tr> </thead> <tbody> <tr> <td>Low</td> <td>Hardware Mode</td> </tr> <tr> <td>VDDIO/2</td> <td>Serial Host Interface</td> </tr> <tr> <td>High</td> <td>Parallel Host Interface</td> </tr> </tbody> </table> <p>Hardware control pins include MODE[2:0], TS[2:0], CLKE and OE. Serial host Interface pins include <math>\overline{CS}</math>, SCLK, SDI, SDO and <math>\overline{INT}</math>. Parallel host Interface pins include <math>\overline{CS}</math>, A[4:0], D[7:0], <math>\overline{WR/DS}</math>, <math>\overline{RD/R/W}</math>, <math>\overline{ALE/AS}</math>, <math>\overline{INT}</math> and RDY/ACK. The device supports multiple parallel host interface as follows (refer to <i>MODE1</i> and <i>MODE0</i> pin descriptions below for details):</p> <table border="1"> <thead> <tr> <th>MODE[2:0]</th> <th>Host Interface</th> </tr> </thead> <tbody> <tr> <td>100</td> <td>Non-multiplexed Motorola Mode Interface</td> </tr> <tr> <td>101</td> <td>Non-multiplexed Intel Mode Interface</td> </tr> <tr> <td>110</td> <td>Multiplexed Motorola Mode Interface</td> </tr> <tr> <td>111</td> <td>Multiplexed Intel Mode Interface</td> </tr> </tbody> </table>	MODE2	Control Interface	Low	Hardware Mode	VDDIO/2	Serial Host Interface	High	Parallel Host Interface	MODE[2:0]	Host Interface	100	Non-multiplexed Motorola Mode Interface	101	Non-multiplexed Intel Mode Interface	110	Multiplexed Motorola Mode Interface	111	Multiplexed Intel Mode Interface
MODE2	Control Interface																					
Low	Hardware Mode																					
VDDIO/2	Serial Host Interface																					
High	Parallel Host Interface																					
MODE[2:0]	Host Interface																					
100	Non-multiplexed Motorola Mode Interface																					
101	Non-multiplexed Intel Mode Interface																					
110	Multiplexed Motorola Mode Interface																					
111	Multiplexed Intel Mode Interface																					
MODE1	I	43	K2	<p><b>MODE1: Control Mode Select 1<sup>(2)</sup></b> In parallel host mode, the parallel interface operates with separate address bus and data bus when this pin is low, and operates with multiplexed address and data bus when this pin is high. In serial host mode or hardware mode, this pin should be grounded.</p>																		
MODE0	I	88	H12	<p><b>MODE0: Control Mode Select 0<sup>(2)</sup></b> In parallel host mode, the parallel host interface is configured for Motorola compatible hosts when this pin is low, or for Intel compatible hosts when this pin is high. In serial host mode or hardware mode, this pin should be grounded.</p>																		
$\overline{CS}$	I (Pulled to VDDIO/2)	87	J11	<p><b><math>\overline{CS}</math>: Chip Select (Active Low)</b> In host mode, this pin is asserted low by the host to enable host interface. A high to low transition must occur on this pin for each read/write operation and the level must not return to high until the operation is over. In hardware control mode, this pin should be pulled to VDDIO/2.</p>																		

<sup>2</sup>. In host mode, register e-AFE has to be set to 'FFH' for proper device operation. See [Expanded Register Description on page 28](#) for more details.

Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description
		TQFP144	PBGA160	
TS2/SCLK/ ALE/ $\overline{AS}$	I	86	J12	<p><b>TS2: Template Select 2</b> In hardware control mode, the signal on this pin is the most significant bit for the transmit template select. Refer to <a href="#">2.5.1 Waveform Shaper</a> for details.</p> <p><b>SCLK: Shift Clock</b> In serial host mode, the signal on this pin is the shift clock for the serial interface. Data on pin SDO is clocked out on falling edges of SCLK if pin CLKE is high, or on rising edges of SCLK if pin CLKE is low. Data on pin SDI is always sampled on rising edges of SCLK.</p> <p><b>ALE: Address Latch Enable</b> In parallel Intel multiplexed host mode, the address on AD[4:0] is sampled into the device on the falling edges of ALE (signals on AD[7:5] are ignored). In non-multiplexed host mode, ALE should be pulled high.</p> <p><b><math>\overline{AS}</math>: Address Strobe (Active Low)</b> In parallel Motorola multiplexed host mode, the address on AD[4:0] is latched into the device on the falling edges of <math>\overline{AS}</math> (signals on AD[7:5] are ignored). In non-multiplexed host mode, <math>\overline{AS}</math> should be pulled high.</p>
TS1/ $\overline{RD}$ / $\overline{R\overline{W}}$	I	85	J13	<p><b>TS1: Template Select 1</b> In hardware control mode, the signal on this pin is the second most significant bit for the transmit template select. Refer to <a href="#">2.5.1 Waveform Shaper</a> for details.</p> <p><b><math>\overline{RD}</math>: Read Strobe (Active Low)</b> In parallel Intel multiplexed or non-multiplexed host mode, this pin is active low for read operation.</p> <p><b><math>\overline{R\overline{W}}</math>: Read/Write Select</b> In parallel Motorola multiplexed or non-multiplexed host mode, the pin is active low for write operation and high for read operation.</p>
TS0/SDI/ $\overline{WR}$ / $\overline{DS}$	I	84	J14	<p><b>TS0: Template Select 0</b> In hardware control mode, the signal on this pin is the least significant bit for the transmit template select. Refer to <a href="#">2.5.1 Waveform Shaper</a> for details.</p> <p><b>SDI: Serial Data Input</b> In serial host mode, this pin input the data to the serial interface. Data on this pin is sampled on the rising edges of SCLK.</p> <p><b><math>\overline{WR}</math>: Write Strobe (Active Low)</b> In parallel Intel host mode, this pin is active low during write operation. The data on D[7:0] (in non-multiplexed mode) or AD[7:0] (in multiplexed mode) is sampled into the device on the rising edges of <math>\overline{WR}</math>.</p> <p><b><math>\overline{DS}</math>: Data Strobe (Active Low)</b> In parallel Motorola host mode, this pin is active low. During a write operation (<math>\overline{R\overline{W}} = 0</math>), the data on D[7:0] (in non-multiplexed mode) or AD[7:0] (in multiplexed mode) is sampled into the device on the rising edges of <math>\overline{DS}</math>. During a read operation (<math>\overline{R\overline{W}} = 1</math>), the data is driven to D[7:0] (in non-multiplexed mode) or AD[7:0] (in multiplexed mode) by the device on the rising edges of <math>\overline{DS}</math>. In parallel Motorola non-multiplexed host mode, the address information on the 5 bits of address bus A[4:0] are latched into the device on the falling edges of <math>\overline{DS}</math>.</p>



Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description
		TQFP144	PBGA160	
$\overline{\text{SDO}}/\text{RDY}/\overline{\text{ACK}}$	O	83	K14	<p><b>SDO: Serial Data Output</b> In serial host mode, the data is output on this pin. In serial write operation, SDO is always in high impedance. In serial read operation, SDO is in high impedance only when SDI is in address/command byte. Data on pin SDO is clocked out of the device on the falling edges of SCLK if pin CLKE is high, or on the rising edges of SCLK if pin CLKE is low.</p> <p><b>RDY: Ready Output</b> In parallel Intel host mode, the high level of this pin reports to the host that bus cycle can be completed, while low reports the host must insert wait states.</p> <p><b><math>\overline{\text{ACK}}</math>: Acknowledge Output (Active Low)</b> In parallel Motorola host mode, the low level of this pin indicates that valid information on the data bus is ready for a read operation or acknowledges the acceptance of the written data during a write operation.</p>
$\overline{\text{INT}}$	O Open Drain	82	K13	<p><b><math>\overline{\text{INT}}</math>: Interrupt (Active Low)</b> This is an open drain, active low interrupt output. Two sources may cause the interrupt. Refer to <a href="#">2.19 Interrupt Handling</a> for details.</p>
D7/AD7 D6/AD6 D5/AD5 D4/AD4 D3/AD3 D2/AD2 D1/AD1 D0/AD0	I/O   High Imped- ance	28 27 26 25 24 23 22 21	K1 J1 J2 J3 J4 H2 H3 G2	<p><b>Dn: Data Bus 7~0</b> In non-multiplexed host mode, these pins are the bi-directional data bus.</p> <p><b>ADn: Address/Data Bus 7~0</b> In multiplexed host mode, these pins are the multiplexed bi-directional address/data bus. In hardware mode, these pins should be tied to VDDIO/2. In serial host mode, these pins should be grounded.</p>

Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description																																		
		TQFP144	PBGA160																																			
A4 MC3/A3 MC2/A2 MC1/A1 MC0/A0	I	12 13 14 15 16	F4 F3 F2 F1 G3	<p><b>MCn: Performance Monitor Configuration 3~0</b></p> <p>In hardware control mode, A4 must be connected to GND. MC[3:0] are used to select a transmitter or receiver of channel 1 to 7 for non-intrusive monitoring. Channel 0 is used as the monitoring channel. If a transmitter is monitored, signals on the corresponding pins TTIPn and TRINGn are internally transmitted to RTIP0 and RRING0 pins. If a receiver is monitored, signals on the corresponding pins RTIPn and RRINGn are internally transmitted to RTIP0 and RRING0 pins. The monitored is then output to RDP0 and RDNO pins.</p> <p>Performance Monitor Configuration determined by MC[3:0] is shown below. Note that if MC[2:0] = 000, the device is in normal operation of all the channels.</p> <table border="1"> <thead> <tr> <th>MC[3:0]</th> <th>Monitoring Configuration</th> </tr> </thead> <tbody> <tr><td>0000</td><td>Normal operation without monitoring</td></tr> <tr><td>0001</td><td>Monitor Receiver 1</td></tr> <tr><td>0010</td><td>Monitor Receiver 2</td></tr> <tr><td>0011</td><td>Monitor Receiver 3</td></tr> <tr><td>0100</td><td>Monitor Receiver 4</td></tr> <tr><td>0101</td><td>Monitor Receiver 5</td></tr> <tr><td>0110</td><td>Monitor Receiver 6</td></tr> <tr><td>0111</td><td>Monitor Receiver 7</td></tr> <tr><td>1000</td><td>Normal operation without monitoring</td></tr> <tr><td>1001</td><td>Monitor Transmitter 1</td></tr> <tr><td>1010</td><td>Monitor Transmitter 2</td></tr> <tr><td>1011</td><td>Monitor Transmitter 3</td></tr> <tr><td>1100</td><td>Monitor Transmitter 4</td></tr> <tr><td>1101</td><td>Monitor Transmitter 5</td></tr> <tr><td>1110</td><td>Monitor Transmitter 6</td></tr> <tr><td>1111</td><td>Monitor Transmitter 7</td></tr> </tbody> </table> <p>In host mode operation, the monitoring channel is selected in the PMON register. The signals monitored by channel 0 can be routed to TTIP0/RING0 by activating the remote loopback in this channel (refer to <a href="#">2.13 G.772 Monitoring</a>).</p> <p><b>An: Address Bus 4~0</b></p> <p>When pin MODE1 is low, the parallel host interface operates with separate address and data bus. In this mode, the signal on this pin is the address bus of the host interface.</p> <p>When pin MODE1 is high or in serial host mode, these pins should be tied to GND.</p>	MC[3:0]	Monitoring Configuration	0000	Normal operation without monitoring	0001	Monitor Receiver 1	0010	Monitor Receiver 2	0011	Monitor Receiver 3	0100	Monitor Receiver 4	0101	Monitor Receiver 5	0110	Monitor Receiver 6	0111	Monitor Receiver 7	1000	Normal operation without monitoring	1001	Monitor Transmitter 1	1010	Monitor Transmitter 2	1011	Monitor Transmitter 3	1100	Monitor Transmitter 4	1101	Monitor Transmitter 5	1110	Monitor Transmitter 6	1111	Monitor Transmitter 7
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1100	Monitor Transmitter 4																																					
1101	Monitor Transmitter 5																																					
1110	Monitor Transmitter 6																																					
1111	Monitor Transmitter 7																																					
OE	I	114	E14	<p><b>OE: Output Driver Enable</b></p> <p>Pulling this pin low can drive all driver output into high impedance for redundancy application without external mechanical relays. In this condition, all other internal circuits remain active.</p>																																		
CLKE	I	115	E13	<p><b>CLKE: Clock Edge Select</b></p> <p>The signal on this pin determines the active edge of RCn, RDPn, RDNn and SCLK. Refer to <a href="#">2.3 Clock Edges</a> for details.</p>																																		
<b>JTAG Signals</b>																																						
$\overline{\text{TRST}}$	I Pull-up	95	G12	<p><b><math>\overline{\text{TRST}}</math>: JTAG Test Port Reset (Active Low)</b></p> <p>This is the active low asynchronous reset to the JTAG Test Port. This pin has an internal pull-up resistor and can be left disconnected.</p>																																		
TMS	I Pull-up	96	F11	<p><b>TMS: JTAG Test Mode Select</b></p> <p>The signal on this pin controls the JTAG test performance and is clocked into the device on the rising edges of TCK. This pin has an internal pull-up resistor and can be left disconnected.</p>																																		
TCK	I	97	F14	<p><b>TCK: JTAG Test Clock</b></p> <p>The clock of the JTAG test is input on this pin. The data on TDI and TMS are clocked into the device on rising edges of TCK while the data on TDO pin is clocked out of the device on falling edges of TCK. This pin should be connected to GNDIO or VDDIO pin when unused.</p>																																		

Table-1 Pin Description (Continued)

Name	Type	Pin No.		Description
		TQFP144	PBGA160	
TDO	O High Impedance	98	F13	<b>TDO: JTAG Test Data Output</b> The serial data of the JTAG test is output on this pin. The data on TDO pin is clocked out of the device on the falling edges of TCK. TDO is a high impedance output signal. It is active only when scanning of data is over. This pin should be left float when unused.
TDI	I Pull-up	99	F12	<b>TDI: JTAG Test Data Input</b> The serial data of the JTAG test is input on this pin. The data on TDI pin is clocked into the device on the rising edges of TCK. This pin has an internal pull-up resistor and it can be left disconnected.
<b>Power Supplies and Grounds</b>				
VDDIO	-	17 92	G1 G14	3.3 V I/O Power Supply
GNDIO	-	18 91	G4 G11	I/O GND
VDDT0 VDDT1 VDDT2 VDDT3 VDDT4 VDDT5 VDDT6 VDDT7	-	44 53 56 65 116 125 128 137	N4, P4 L4, M4 L11, M11 N11, P11 A11, B11 C11, D11 C4, D4 A4, B4	<b>3.3 V/5 V Power Supply for Transmitter Driver</b> All VDDT pins must be connected to 3.3 V or all VDDT must be connected to 5 V. It is not allowed to leave any of the VDDT pins open (not-connected) even if the channel is not used. T1 is only 5V VDDT.
GNDT0 GNDT1 GNDT2 GNDT3 GNDT4 GNDT5 GNDT6 GNDT7	-	47 50 59 62 119 122 131 134	N6, P6 L6, M6 L9, M9 N9, P9 A9, B9 C9, D9 C6, D6 A6, B6	<b>Analog GND for Transmitter Driver</b>
VDDD VDDA	-	19 90	H1 H14	3.3 V Digital/Analog Core Power Supply
GNDD GNDA	-	20 89	H4 H11	Digital/Analog Core GND
<b>Others</b>				
IC	-	93	G13	<b>IC: Internal Connection</b> Internal use. Leave it open for normal operation.
IC	-	94	H13	<b>IC: Internal Connection</b> Internal use. Leave it open for normal operation.

## 2 FUNCTIONAL DESCRIPTION

### 2.1 OVERVIEW

The IDT82V2048L is a fully integrated octal short-haul analog front end (AFE), which contains eight transmit and receive channels for use in either T1 or E1 applications. The raw sliced data (no retiming) is output to the system. Transmit equalization is implemented with low-impedance output drivers that provide shaped waveforms to the transformer, guaranteeing template conformance. Moreover, testing functions, such as JTAG boundary scan is provided. The device is optimized for flexible software control through a serial or parallel host mode interface. Hardware control is also available. [Figure-1 on page 1](#) shows one of the eight identical channels operation.

### 2.2 T1/E1 MODE SELECTION

T1/E1 mode selection configures the device globally. In Hardware control Mode, the template selection pins TS[2:0], determine whether the operation mode is T1 or E1 (see [Table-5 on page 14](#)). In Software Mode, the register **TS** determines whether the operation mode is T1 or E1.

#### 2.2.1 SYSTEM INTERFACE

The system interface of each channel operates in Dual Rail Mode with data recovery, that is, with raw data slicing only and without clock recovery.

The Dual Rail interface consist of TDPn<sup>1</sup>, TDNn, TCLKn, RDPn, RDNn and RCn. Data transmitted from TDPn and TDNn appears on TTIPn and TRINGn at the line interface. The interface of the AFE is shown in [Figure-4](#). Pin RDPn and RDNn, are raw RZ slice outputs and internally connected to an XOR which is fed to the RCn output for external clock recovery applications.

##### 2.2.1.1 SYSTEM INTERFACE CONFIGURATION

For normal transmit and receive operation, the device is configured as follows:

In host mode, MCLK can be either clocked or pulled high. If MCLK is pulled high, TCLK1 has to be provided for proper device operation. In addition, register **e-AFE**<sup>2</sup> has to be set to 'FFH' to ensure proper device operation. See [Expanded Register Description on page 28](#) for details.

In hardware mode, MCLK has to be pulled high and TCLK1 has to be provided for proper device operation.

Depending on the state of TCLK1 and TCLKn, the transmitter will Transmit All Ones (TAOS), will go into power down, or will go into high impedance.

The status of TCLK1 and TCLKn has no effect on the receive paths. By setting MCLK low, all the receive paths are powered down.

[Table-2](#) summarizes the different combinations between MCLK and TCLKn.

<sup>1</sup> The footprint 'n' (n = 0 - 7) indicates one of the eight channels.

<sup>2</sup> The first letter 'e-' indicates expanded register.

Table-2 System Interface Configuration

Host or Hardware Mode	MCLK	TCLK1	TCLKn	AFEn in e-AFE	Transmitter Mode
Transmit and Receive Normal Operation					
Host <sup>(1)</sup> only	Clocked	Clocked	Clocked	1	Normal operation
Host or Hardware <sup>(2)</sup>	High	Clocked	Clocked	DC <sup>(3)</sup>	Normal operation
Transmit Interface Modes					
Host only	Clocked	High ( $\geq 16$ MCLK)		1	Transmit All Ones (TAOS) signals to the line side in the corresponding transmit channel.
		Low ( $\geq 64$ MCLK)			Corresponding transmit channel is set into power down state.
Host or Hardware	High/Low	TCLK1 is clocked	TCLKn is high ( $\geq 16$ TCLK1)	DC	Transmit All Ones (TAOS) signals to the line side in the corresponding transmit channel.
			TCLKn is low ( $\geq 64$ TCLK1)		Corresponding transmit channel is set into power down state.
		TCLK1 is unavailable.	DC	All eight transmitters (TTIPn & TRINGn) are in high impedance.	
Receive Interface Modes					
Host or Hardware	Low	The receive path is not affected by the status of TCLK1 or TCLKn.		DC	All the receive paths are powered down.

<sup>1</sup>. In host mode, register e-AFE must be set to 'FFH' for proper operation. See [Expanded Register Description on page 28](#) for details.

<sup>2</sup>. In hardware mode, MCLK must be pulled high and TCLK1 provided for proper operation.

<sup>3</sup>. DC means Don't Care

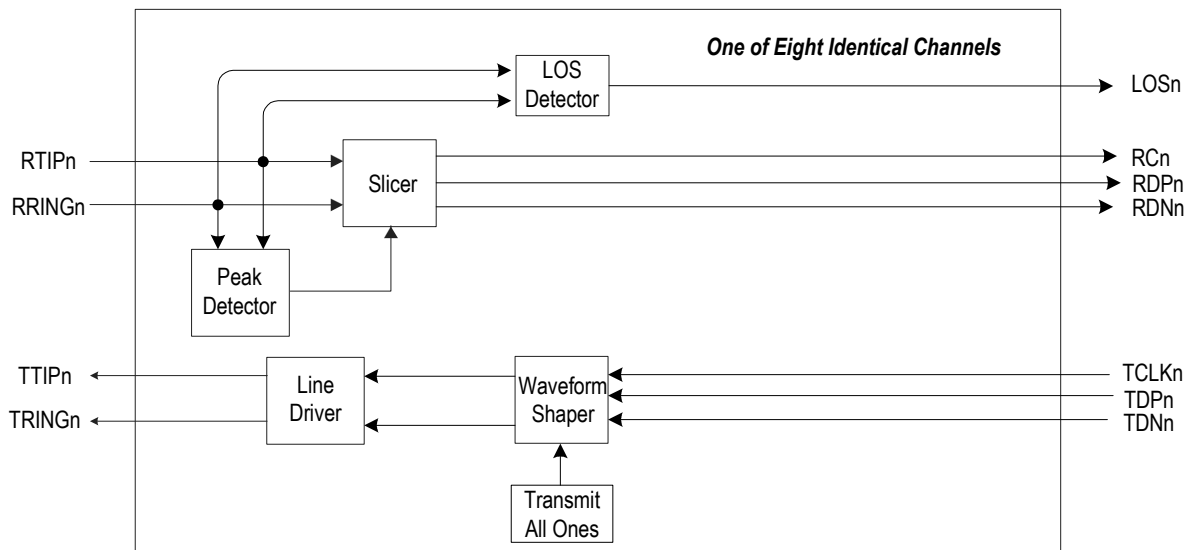


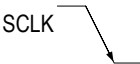

Figure-4 Analog Front End (AFE) Interface



### 2.3 CLOCK EDGES

The active edge of SCLK is selectable. If pin CLKE is high, the active edge of SCLK is the falling edge. On the contrary, if CLKE is low, the active edge SCLK is the rising edge. Pin SDO is always active high, and the output signals are valid on the active edge of SCLK. See [Table-3 Active Clock Edge and Active Level](#) for details. Pin CLKE is used to set the active level for RDPn/RDNn raw slicing output: high for active high polarity and low for active low. It should be noted that data on pin SDI are always active high and are sampled on the rising edges of SCLK. The data on pin TDPn or TDNn are also always active high but are sampled on the falling edges of TCLKn, despite the level on CLKE.

**Table-3 Active Clock Edge and Active Level**

Pin CLKE	Pin RDPn and RDNn	Pin SDO	
	Slicer Output		
High	Active High		Active High
Low	Active Low		Active High

### 2.4 RECEIVER

In receive path, the line signals couple into RRINGn and RTIPn via a transformer and are converted into RZ digital pulses by a data slicer. Adaptation for attenuation is achieved using an integral peak detector that sets the slicing levels. The recovered data on pin RDPn/RDNn in an undecoded dual rail RZ format. Loss of signal is detected. This change in status may be enabled to generate an interrupt.

#### 2.4.1 PEAK DETECTOR AND SLICER

The slicer determines the presence and polarity of the received pulses. The raw positive slicer output appears on RDPn while the negative slicer output appears on RDNn. The slicer circuit has a built-in peak detector from which the slicing threshold is derived. The slicing threshold is default to 50% (typical) of the peak value.

Signals with an attenuation of up to 12 dB (from 2.4 V) can be recovered by the receiver. To provide immunity from impulsive noise, the peak detectors are held above a minimum level of 0.150 V typically, despite the received signal level.

**Table-4 LOS Condition**

		Standard			Signal on LOSn
		ANSI T1.231 for T1	G.775 for E1	ETSI 300 233 for E1	
LOS Detected	Continuous Intervals	175	32	2048 (1 ms)	High
	Amplitude <sup>(1)</sup>	below typical 200 mVp	below typical 200 mVp	below typical 200 mVp	
LOS Cleared	Density	12.5% (16 marks in a sliding 128-bit period) with no more than 99 continuous zeros	12.5% (4 marks in a sliding 32-bit period) with no more than 15 continuous zeros	12.5% (4 marks in a sliding 32-bit period) with no more than 15 continuous zeros	Low
	Amplitude <sup>(1)</sup>	exceed typical 250 mVp	exceed typical 250 mVp	exceed typical 250 mVp	

<sup>1</sup>. LOS levels at device (RTIPn, RRINGn) with all ones signal. For more detail regarding the LOS parameters, please refer to [Receiver Characteristics on page 38](#).

#### 2.4.2 DATA RECOVERY

The analog line signal are converted to RZ digital bit streams on the RDPn/RDNn pins and internally connected to an XOR which is fed to the RCn output for external clock recovery applications.

#### 2.4.3 LOSS OF SIGNAL (LOS) DETECTION

The Loss of Signal Detector monitors the amplitude and density of the received signal on receiver line before the transformer (measured on port A, B shown in [Figure-7](#)). The loss condition is reported by pulling pin LOSn high. At the same time, LOS alarm registers track LOS condition. When LOS is detected or cleared, an interrupt will generate if not masked. In host mode, the detection supports the ANSI T1.231 for T1 mode, ITU G.775 and ETSI 300 233 for E1 mode. In hardware mode, it supports the ITU G.775 and ANSI T1.231.

[Table-4](#) summarizes the conditions of LOS. During LOS, the RDPn/RDNn continue to output the sliced data.

## 2.5 TRANSMITTER

In transmit path, data in NRZ format is clocked into the device on TDPn and TDNn. The data is sampled into the device on falling edges of TCLKn. The shape of the pulses are user programmable to ensure that the T1/E1 pulse template is met after the signal passes through different cable lengths or types.

### 2.5.1 WAVEFORM SHAPER

T1 pulse template, specified in the DSX-1 Cross-Connect by ANSI T1.102, is illustrated in [Figure-5](#). The device has built-in transmit waveform templates, corresponding to 5 levels of pre-equalization for cable of a length from 0 to 655 ft with each increment of 133 ft.

E1 pulse template, specified in ITU-T G.703, is shown in [Figure-6](#). The device has built-in transmit waveform templates for cable of 75 Ω or 120 Ω.

Any one of the six built-in waveforms can be chosen in both hardware mode and host mode. In hardware control mode, setting pins TS[2:0] can select the required waveform template for all the transmitters, as shown in [Table-5](#). In host mode, the waveform template can be configured on a per-channel basis. Bits TSIA[2:0] in register **TSIA** are used to select the channel and bits TS[2:0] in register **TS** are used to select the required waveform template.

The built-in waveform shaper uses an internal high frequency clock which is 16XMCLK as the clock reference. This function will be bypassed when MCLK is unavailable.

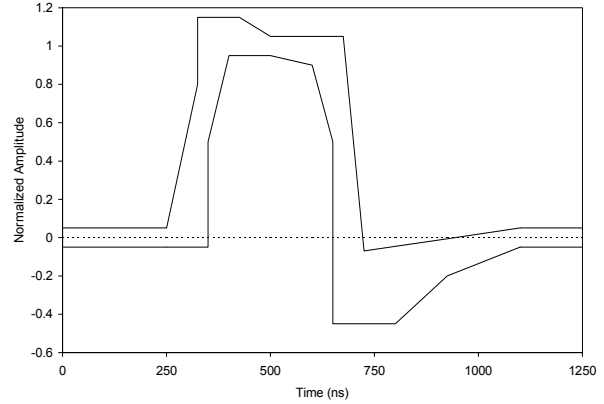


Figure-5 DSX-1 Waveform Template

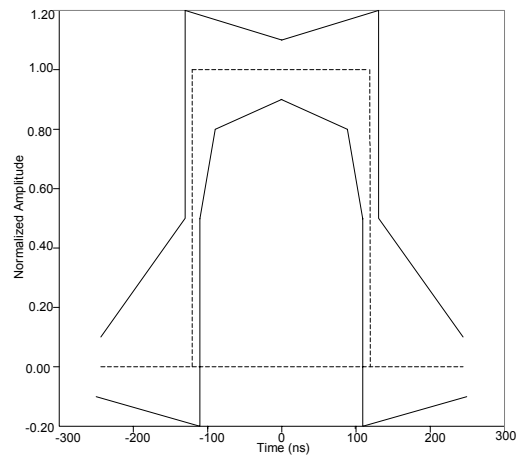


Figure-6 CEPT Waveform Template

Table-5 Built-in Waveform Template Selection

TS2	TS1	TS0	Service	Clock Rate	Cable Length	Maximum Cable Loss (dB) <sup>(1)</sup>	
0	0	0	E1	2.048 MHz	120 Ω/75 Ω Cable	-	
0	0	1	Reserved				-
0	1	0	Reserved				-
0	1	1	T1	1.544 MHz	0-133 ft. ABAM	0.6	
1	0	0			133-266 ft. ABAM	1.2	
1	0	1			266-399 ft. ABAM	1.8	
1	1	0			399-533 ft. ABAM	2.4	
1	1	1			533-655 ft. ABAM	3.0	

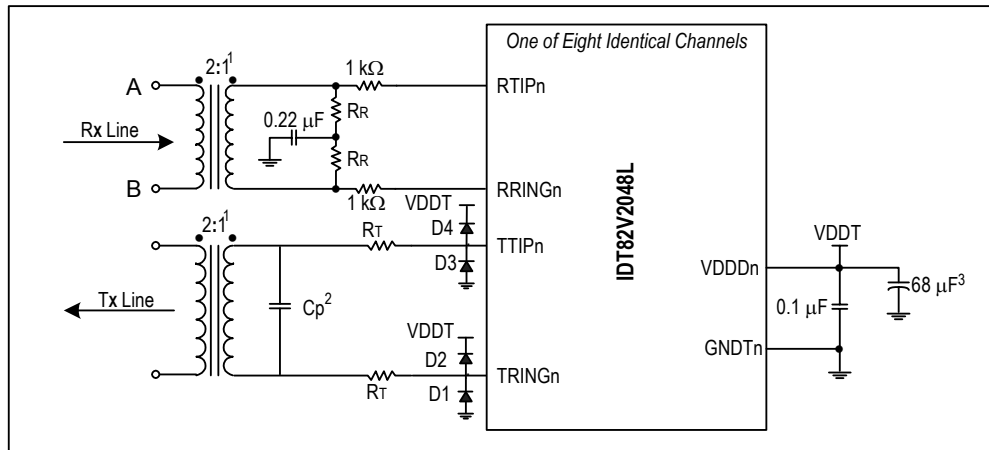
<sup>1</sup>. Maximum cable loss at 772 kHz.

## 2.6 LINE INTERFACE CIRCUITRY

The transmit and receive interface RTIPn/RRINGn and TTIPn/TRINGn connections provide a matched interface to the cable. [Figure-7](#) shows the appropriate external components to connect with the cable for one transmit/receive channel. [Table-6](#) summarizes the component values based on the specific application.

Table-6 External Components Values

Component	E1		T1
	75 Ω Coax	120 Ω Twisted Pair	100 Ω Twisted Pair, VDDT = 5.0 V
R <sub>T</sub>	9.5 Ω ± 1%	9.5 Ω ± 1%	9.1 Ω ± 1%
R <sub>R</sub>	9.31 Ω ± 1%	15 Ω ± 1%	12.4 Ω ± 1%
C <sub>p</sub>	2200 pF		1000 pF
D1 - D4	Nihon Inter Electronics - EP05Q03L, 11EQS03L, EC10QS04, EC10QS03L; Motorola - MBR0540T1		



NOTE:

1. Pulse T1124 transformer is recommended to be used in Standard (STD) operating temperature range (0°C to 70°C), while Pulse T1114 transformer is recommended to be used in Extended (EXT) operating temperature range is -40°C to +85°C. See Transformer Specifications Table for details.
2. Typical value. Adjust for actual board parasitics to obtain optimum return loss.
3. Common decoupling capacitor for all VDDT and GNDT pins. One per chip.

Figure-7 External Transmit/Receive Line Circuitry

## 2.7 TRANSMIT DRIVER POWER SUPPLY

All transmit driver power supplies must be 5.0 V or 3.3 V.

In E1 mode, despite the power supply voltage, the 75 Ω/120 Ω lines are driven through a pair of 9.5 Ω series resistors and a 1:2 transformer.

In T1 mode, only 5.0 V can be selected, 100 Ω lines are driven through a pair of 9.1 Ω series resistors and a 1:2 transformer.

In harsh cable environment, series resistors are required to improve the transmit return loss performance and protect the device from surges coupling into the device.

Table-7 Transformer Specifications<sup>(1)</sup>

Electrical Specification @ 25°C										Package/Schematic
Part No.		Turns Ratio (Pri: sec ± 2%)		OCL @ 25°C (mH MIN)		L <sub>L</sub> (μH MAX)		C <sub>www</sub> (pF MAX)		
STD Temp.	EXT Temp.	Transmit	Receive	Transmit	Receive	Transmit	Receive	Transmit	Receive	
T1124	T1114	1:2CT	1CT:2	1.2	1.2	.6	.6	35	35	TOU/3

<sup>1</sup> Pulse T1124 transformer is recommended to be used in Standard (STD) operating temperature range (0°C to 70°C), while Pulse T1114 transformer is recommended to be used in Extended (EXT) operating temperature range is -40°C to +85°C.

## 2.8 POWER DRIVER FAILURE MONITOR

An internal power Driver Failure Monitor (DFMON), parallel connected with TTIPn and TRINGn, can detect short circuit failure between TTIPn and TRINGn pins. Bit SCPB in register GCF decides whether the output driver short circuit protection is enabled. When the short circuit protection is enabled, the driver output current is limited to a typical value: 180 mA<sub>p</sub>. Also, register DF, DFI and DFM will be available. When DFMON will detect a short circuit, register DF will be set. With a short circuit failure detected, register DFI will be set and an interrupt will be generated on pin INT.

## 2.9 TRANSMIT LINE SIDE SHORT CIRCUIT

In E1 or T1 with 5 V VDDT, a pair of 9.5 Ω serial resistors connect with TTIPn and TRINGn pins and limit the output current. In this case, the output current is a limited value which is always lower than the typical line short circuit current 180 mA<sub>p</sub>, even if the transmit line side is shorted.

Refer to [Table-6 External Components Values](#) for details.

## 2.10 LINE PROTECTION

In transmit side, the Schottky diodes D1~D4 are required to protect the line driver and improve the design robustness. In receive side, the series resistors of 1 k $\Omega$  are used to protect the receiver against current surges coupled in the device. The series resistors do not affect the receiver sensitivity, since the receiver impedance is as high as 120 k $\Omega$  typically.

## 2.11 HITLESS PROTECTION SWITCHING (HPS)

The IDT82V2048L transceivers include an output driver with high impedance feature for T1/E1 redundancy applications. This feature reduces the cost of redundancy protection by eliminating external relays. Details of HPS are described in relative Application Note.

## 2.12 TRANSMIT ALL ONES (TAOS)

In hardware mode, the TAOS mode is set by pulling pin TCLKn high for more than 16 MCLK cycles. In host mode, TAOS mode is set by programming register **TAO**. In addition, automatic TAOS signals are inserted by setting register **ATAO** when Loss of Signal occurs. Note that the TAOS generator adopts MCLK as a timing reference. In order to assure that the output frequency is within specified limits, MCLK must have the applicable stability.

Refer to [Figure-8 TAOS Data Path](#).

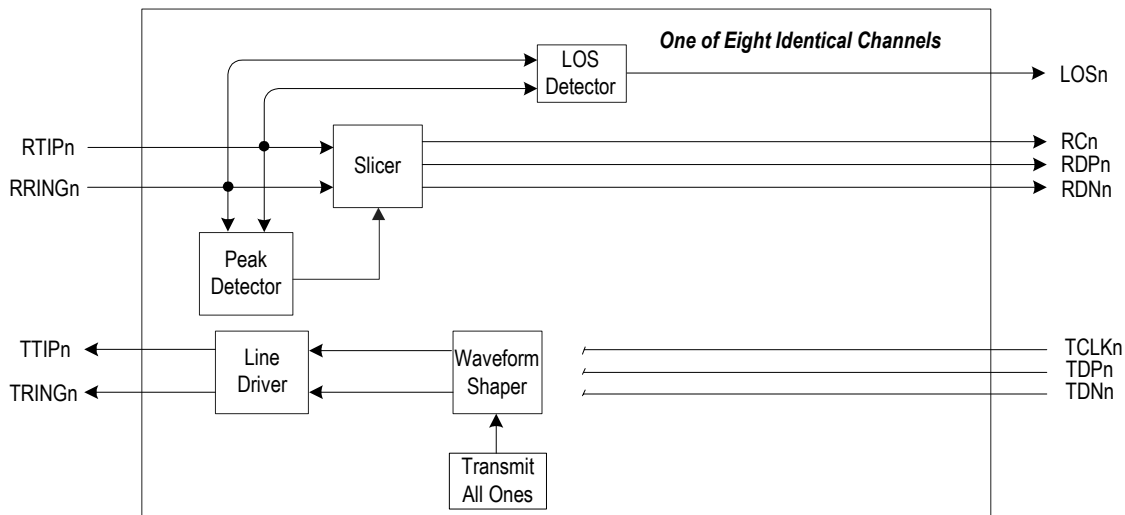


Figure-8 TAOS Data Path

## 2.13 G.772 MONITORING

The eight channels of IDT82V2048L can all be configured to work as regular transceivers. In applications using only seven channels (channels 1 to 7), channel 0 is configured to non-intrusively monitor any of the other channels' inputs or outputs on the line side. The monitoring is non-intrusive per ITU-T G.772. [Figure-9](#) shows the Monitoring Principle. The receiver path or transmitter path to be monitored is configured by pin MC[3:0] in hardware mode or by **PMON** in host mode.

The signal which is monitored can be observed digitally at the output pin RC0, RDP0 and RDN0. LOS detector is still in use in channel 0 for the monitored signal.

In monitoring mode, a clock and data recovery circuit can be enabled for Remote Loopback operation. In Remote Loopback operation, the signal which is being monitored will be also output on TTIP0 and TRING0 pins. The output signal can then be connected to a standard test equipment for non-intrusive monitoring. RC0 pin will also output the recovered clock (DPLL).

The remote loopback is only available in host mode operation.

To enable the remote loopback, bit 0 in register **RL0** has to be set, and bit 0 in register **e-AFE** has to be cleared. The register setting are: register **RL0** set '01'H, register **e-AFE** set 'FE'H.

For normal operation register **RL0** has to be set '00H' and register **e-AFE** has to be set 'FFH'.

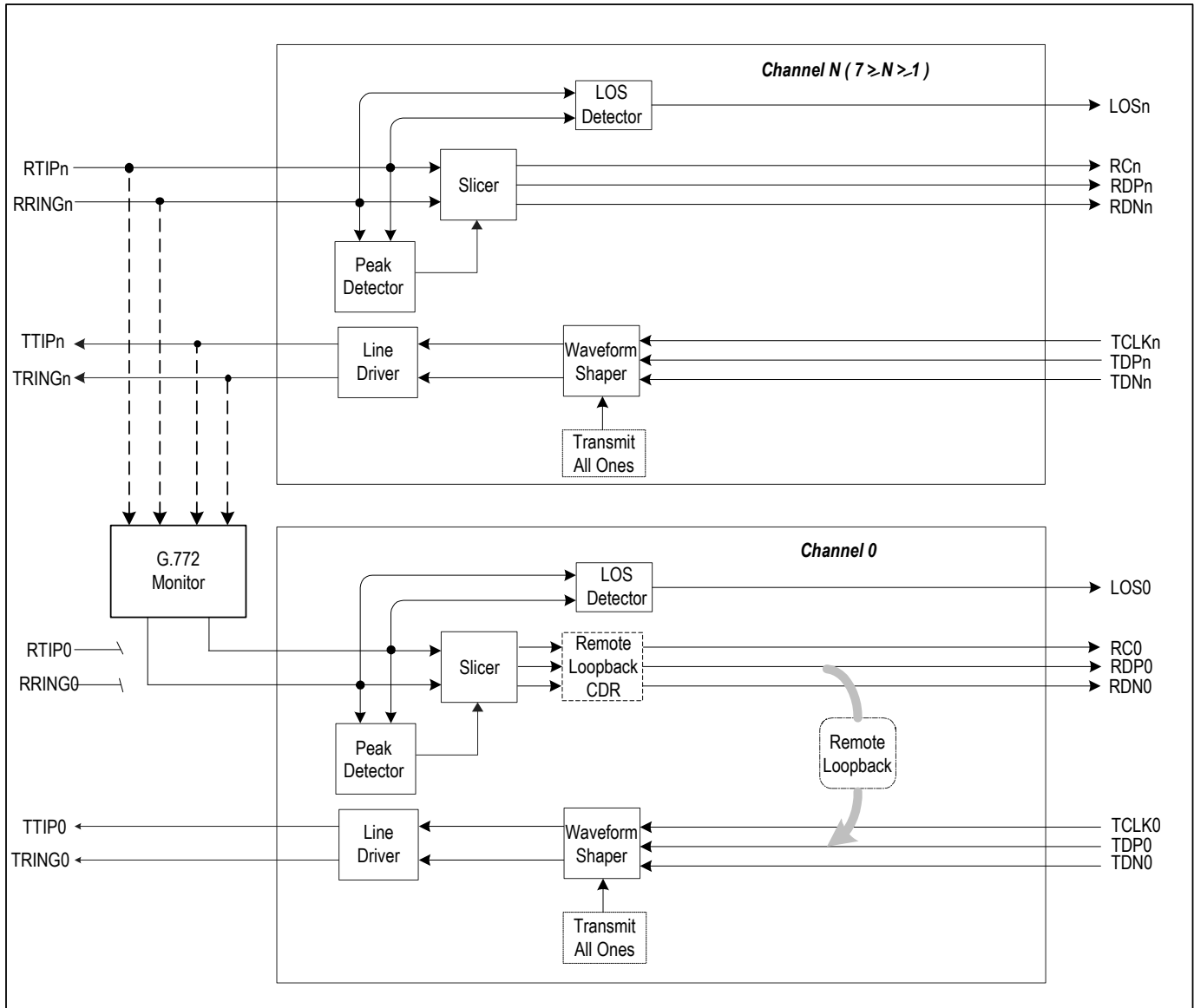


Figure-9 Monitoring Principle

**2.14 SOFTWARE RESET**

Writing register **RS** will cause software reset by initiating about 1  $\mu$ s reset cycle. This operation set all the registers to their default value.

**2.15 POWER ON RESET**

During power up, an internal reset signal sets all the registers to default values. The power-on reset takes at least 10  $\mu$ s, starting from when the power supply exceeds 2/3 VDDA.

**2.16 POWER DOWN**

Each transmit channel will be powered down by pulling pin TCLKn low for more than 64 MCLK cycles (if MCLK is available) or about 30  $\mu$ s (if MCLK is not available). In host mode, each transmit channel will also be powered down by setting bit TPDNn in register **e-TPDN** to '1'.

All the receivers will be powered down when MCLK is low. When MCLK is clocked or high, setting bit RPDNn in register **e-RPDN** to '1' will configure the corresponding receiver to be powered down.

**2.17 INTERFACE WITH 5 V LOGIC**

The IDT82V2048L can interface directly with 5 V TTL family devices. The internal input pads are tolerant to 5 V output from TTL and CMOS family devices.



2.18 HOST INTERFACE

The host interface provides access to read and write the registers in the device. The interface consists of serial host interface and parallel host interface. By pulling pin MODE2 to VDDIO/2 or high, the device can be set to work in serial mode and in parallel mode respectively. In host mode operation, expanded register e-FAE has to be set to 'FFH' for proper device operation. See [Expanded Register Description on page 28](#) for details.

2.18.1 PARALLEL HOST INTERFACE

The interface is compatible with Motorola and Intel host. Pins MODE[1:0] are used to select the operating mode of the parallel host interface. When pin MODE1 is pulled low, the host uses separate address bus and data bus. When high, multiplexed address/data bus is used. When pin MODE0 is pulled low, the parallel host interface is configured for Motorola compatible hosts. When pin MODE0 is pulled high, the parallel host interface is configured for Intel compatible hosts. See [Table-1 Pin Description](#) for more details. The host interface pins in each operation mode is tabulated in [Table-8](#):

Table-8 Parallel Host Interface Pins

MODE[2:0]	Host Interface	Generic Control, Data and Output Pin
100	Non-multiplexed Motorola interface	$\overline{CS}$ , $\overline{ACK}$ , $\overline{DS}$ , $\overline{R/W}$ , $\overline{AS}$ , A[4:0], D[7:0], $\overline{INT}$
101	Non-multiplexed Intel interface	$\overline{CS}$ , RDY, $\overline{WR}$ , $\overline{RD}$ , ALE, A[4:0], D[7:0], $\overline{INT}$
110	Multiplexed Motorola interface	$\overline{CS}$ , $\overline{ACK}$ , $\overline{DS}$ , $\overline{R/W}$ , $\overline{AS}$ , AD[7:0], $\overline{INT}$
111	Multiplexed Intel interface	$\overline{CS}$ , RDY, $\overline{WR}$ , $\overline{RD}$ , ALE, AD[7:0], $\overline{INT}$

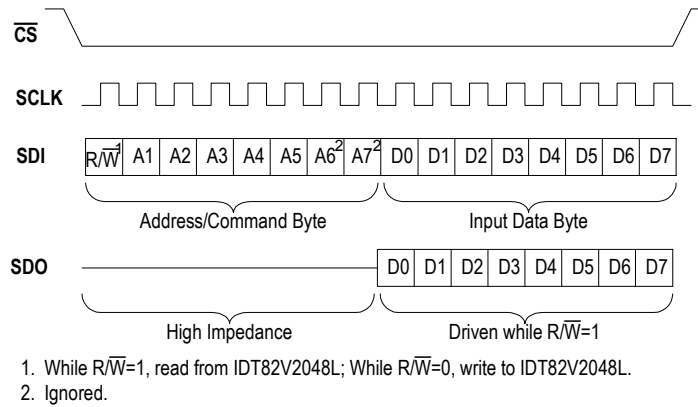


Figure-10 Serial Host Mode Timing

2.18.2 SERIAL HOST INTERFACE

By pulling pin MODE2 to VDDIO/2, the device operates in the serial host Mode. In this mode, the registers are accessible through a 16-bit word which contains an 8-bit command/address byte (bit  $R/\overline{W}$  and 5-address-bit A1~A5, A6 and A7 bits are ignored) and a subsequent 8-bit data byte (D7~D0), as shown in [Figure-10](#). When bit  $R/\overline{W}$  is set to '1', data is read out from pin SDO. When bit  $R/\overline{W}$  is set to '0', data on pin SDI is written into the register whose address is indicated by address bits A5~A1. Refer to [Figure-10 Serial Host Mode Timing](#).

## 2.19 INTERRUPT HANDLING

### 2.19.1 INTERRUPT SOURCES

There are two kinds of interrupt sources:

1. *Status change in register **LOS**. The analog/digital loss of signal detector continuously monitors the received signal to update the specific bit in register **LOS** which indicates presence or absence of a LOS condition.*
2. *Status change in register **DF**. The automatic power driver circuit continuously monitors the output drivers signal to update the specific bit in register **DFM** which indicates presence or absence of an output driver short circuit condition.*

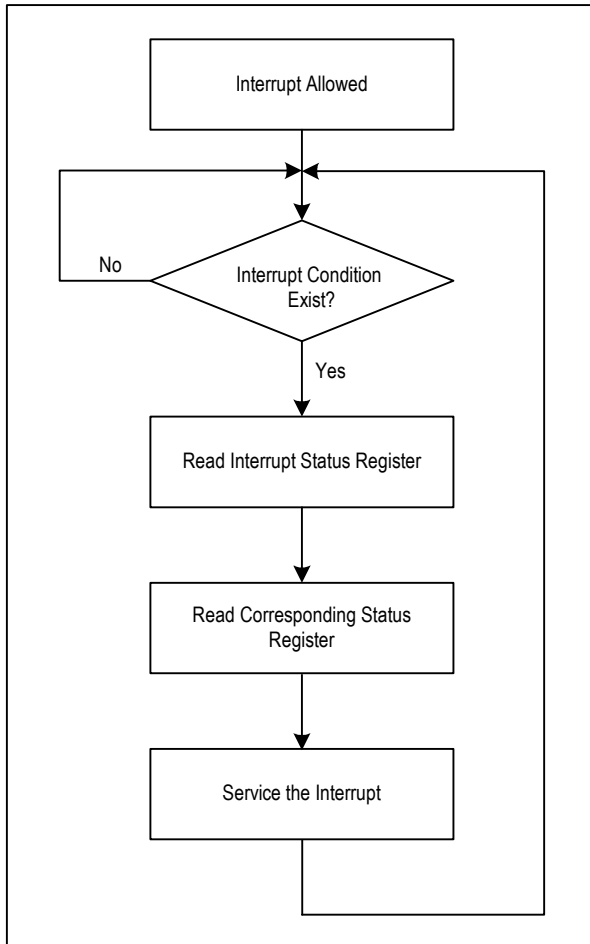
### 2.19.2 INTERRUPT ENABLE

The IDT82V2048L provides a latched interrupt output ( $\overline{\text{INT}}$ ) and the two kinds of interrupts are all reported by this pin. When the Interrupt Mask register: **LOSM** and **DFM**, are set to '1', the Interrupt Status register: **LOSI** and **DFI**, are enabled respectively. Whenever there is a transition ('0' to '1' or '1' to '0') in the corresponding status register, the Interrupt Status register will change into '1', which means an interrupt occurs, and there will be a high to low transition on  $\overline{\text{INT}}$  pin. An external pull-up resistor of approximately 10 k $\Omega$  is required to support the wire-OR operation of  $\overline{\text{INT}}$ . When any of the two Interrupt Mask registers is set to '0' (the power-on default value is '0'), the corresponding Interrupt Status register is disabled and the transition on status register is ignored.

### 2.19.3 INTERRUPT CLEARING

When an interrupt occurs, the Interrupt Status registers: **LOSI** and **DFI**, are read to identify the interrupt source. These registers will be cleared to '0' after the corresponding status registers: **LOS** and **DF** are read. The Status registers will be cleared once the corresponding conditions are met.

Pin  $\overline{\text{INT}}$  is pulled high when there is no pending interrupt left. The interrupt handling in the interrupt service routine is shown in [Figure-11](#).



**Figure-11** Interrupt Service Routine

### 3 PROGRAMMING INFORMATION

#### 3.1 REGISTER LIST AND MAP

There are 18 primary registers (including an Address Pointer Control Register and 4 expanded registers in the device).

Whatever the control interface is, 5 address bits are used to set the registers. In non-multiplexed parallel interface mode, the five dedicated address bits are A[4:0]. In multiplexed parallel interface mode, AD[4:0] carries the address information. In serial interface mode, A[5:1] are used to address the register.

The Register **ADDP**, addressed as 11111 or 1F Hex, switches between primary registers bank and expanded registers bank.

By setting register **ADDP** to 'AAH', the 5 address bits point to the expanded register bank, that is, 4 expanded registers are available. By clearing register **ADDP**, the primary registers are available.

#### 3.2 RESERVED AND TEST REGISTERS

Primary Registers, whose address are 01H, 0CH, 13H to 1EH, are reserved. Expanded registers, whose address are 00H, 01H, 05H, 06H, 08H to 0FH, are reserved. Expanded registers, whose address are 10H to 1EH, are used for test and must be set to '0' (default).

Table-9 Primary Register List

Address			Register	R/W	Explanation
Hex	Serial Interface A7-A1	Parallel Interface A7-A0			
00	XX00000	XXX00000	ID	R	Device ID Register
01	XX00001	XXX00001			Reserved
02	XX00010	XXX00010	RL0	R/W	G.772 Monitoring, Remote Loopback Configuration Register
03	XX00011	XXX00011	TAO	R/W	Transmit All Ones Configuration Register
04	XX00100	XXX00100	LOS	R	Loss of Signal Status Register
05	XX00101	XXX00101	DF	R	Driver Fault Status Register
06	XX00110	XXX00110	LOSM	R/W	LOS Interrupt Mask Register
07	XX00111	XXX00111	DFM	R/W	Driver Fault Interrupt Mask Register
08	XX01000	XXX01000	LOSI	R	LOS Interrupt Status Register
09	XX01001	XXX01001	DFI	R	Driver Fault Interrupt Status Register
0A	XX01010	XXX01010	RS	W	Software Reset Register
0B	XX01011	XXX01011	PMON	R/W	Performance Monitor Configuration Register
0C	XX01100	XXX01100			Reserved
0D	XX01101	XXX01101	LAC	R/W	LOS/AIS Criteria Configuration Register
0E	XX01110	XXX01110	ATAO	R/W	Automatic TAOS Configuration Register
0F	XX01111	XXX01111	GCF	R/W	Global Configuration Register
10	XX10000	XXX10000	TSIA	R/W	Indirect Address Register for Transmit Template Select
11	XX10001	XXX10001	TS	R/W	Transmit Template Select Register
12	XX10010	XXX10010	OE	R/W	Output Enable Configuration Register
13	XX10011	XXX10011			Reserved
14	XX10100	XXX10100			
15	XX10101	XXX10101			
16	XX10110	XXX10110			
17	XX10111	XXX10111			
18	XX11000	XXX11000			
19	XX11001	XXX11001			
1A	XX11010	XXX11010			
1B	XX11011	XXX11011			
1C	XX11100	XXX11100			
1D	XX11101	XXX11101			
1E	XX11110	XXX11110			
1F	XX11111	XXX11111	ADDP	R/W	

Table-10 Expanded (Indirect Address Mode) Register List

Address			Register	R/W	Explanation			
Hex	Serial Interface A7-A1	Parallel Interface A7-A0						
00	XX00000	XXX00000	Reserved					
01	XX00001	XXX00001						
02	XX00010	XXX00010						
03	XX00011	XXX00011	e-AFE	R/W	AFE Enable Register			
04	XX00100	XXX00100	e-RPDN	R/W	Receiver n Powerdown Enable/Disable Register			
05	XX00101	XXX00101	e-TPDN	R/W	Transmitter n Powerdown Enable/Disable Register			
06	XX00110	XXX00110	Reserved					
07	XX00111	XXX00111						
08	XX01000	XXX01000	e-EQUA	R/W	Enable Equalizer Enable/Disable Register			
09	XX01001	XXX01001	Reserved					
0A	XX01010	XXX01010						
0B	XX01011	XXX01011						
0C	XX01100	XXX01100						
0D	XX01101	XXX01101						
0E	XX01110	XXX01110						
0F	XX01111	XXX01111						
10	XX10000	XXX10000						
11	XX10001	XXX10001						
12	XX10010	XXX10010						
13	XX10011	XXX10011						
14	XX10100	XXX10100						
15	XX10101	XXX10101						
16	XX10110	XXX10110						
17	XX10111	XXX10111	Test					
18	XX11000	XXX11000						
19	XX11001	XXX11001						
1A	XX11010	XXX11010						
1B	XX11011	XXX11011						
1C	XX11100	XXX11100						
1D	XX11101	XXX11101						
1E	XX11110	XXX11110						
1F	XX11111	XXX11111				ADDP	R/W	Address pointer control register for switching between primary register bank and expanded register bank

Table-11 Primary Register Map

Register	Address R/W Default	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ID	00H R Default	ID 7 R 0	ID 6 R 0	ID 5 R 0	ID 4 R 1	ID 3 R 0	ID 2 R 0	ID 1 R 0	ID 0 R 0
RL0	02H R/W Default	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	RL0 R/W 0
TAO	03H R/W Default	TAO 7 R/W 0	TAO 6 R/W 0	TAO 5 R/W 0	TAO 4 R/W 0	TAO 3 R/W 0	TAO 2 R/W 0	TAO 1 R/W 0	TAO 0 R/W 0
LOS	04H R Default	LOS 7 R 0	LOS 6 R 0	LOS 5 R 0	LOS 4 R 0	LOS 3 R 0	LOS 2 R 0	LOS 1 R 0	LOS 0 R 0
DF	05H R Default	DF 7 R 0	DF 6 R 0	DF 5 R 0	DF 4 R 0	DF 3 R 0	DF 2 R 0	DF 1 R 0	DF 0 R 0
LOSM	06H R/W Default	LOSM 7 R/W 0	LOSM 6 R/W 0	LOSM 5 R/W 0	LOSM 4 R/W 0	LOSM 3 R/W 0	LOSM 2 R/W 0	LOSM 1 R/W 0	LOSM 0 R/W 0
DFM	07H R/W Default	DFM 7 R/W 0	DFM 6 R/W 0	DFM 5 R/W 0	DFM 4 R/W 0	DFM 3 R/W 0	DFM 2 R/W 0	DFM 1 R/W 0	DFM 0 R/W 0
LOSI	08H R Default	LOSI 7 R 0	LOSI 6 R 0	LOSI 5 R 0	LOSI 4 R 0	LOSI 3 R 0	LOSI 2 R 0	LOSI 1 R 0	LOSI 0 R 0
DFI	09H R Default	DFI 7 R 0	DFI 6 R 0	DFI 5 R 0	DFI 4 R 0	DFI 3 R 0	DFI 2 R 0	DFI 1 R 0	DFI 0 R 0
RS	0AH W Default	RS 7 W 1	RS 6 W 1	RS 5 W 1	RS 4 W 1	RS 3 W 1	RS 2 W 1	RS 1 W 1	RS 0 W 1
PMON	0BH R/W Default	- R/W 0	- R/W 0	- R/W 0	- R/W 0	MC 3 R/W 0	MC 2 R/W 0	MC 1 R/W 0	MC 0 R/W 0
LAC	0DH R/W Default	LAC 7 R/W 0	LAC 6 R/W 0	LAC 5 R/W 0	LAC 4 R/W 0	LAC 3 R/W 0	LAC 2 R/W 0	LAC 1 R/W 0	LAC 0 R/W 0
ATAO	0EH R/W Default	ATAO 7 R/W 0	ATAO 6 R/W 0	ATAO 5 R/W 0	ATAO 4 R/W 0	ATAO 3 R/W 0	ATAO 2 R/W 0	ATAO 1 R/W 0	ATAO 0 R/W 0
GCF	0FH R/W Default	- R/W 0	- R/W 0	SCPB R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0
TSIA	10 Hex R/W Default	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	TSIA 2 R/W 0	TSIA 1 R/W 0	TSIA 0 R/W 0



Table-11 Primary Register Map (Continued)

Register	Address R/W Default	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TS	11 Hex R/W Default	- R/W 0	- R/W 0	- R/W 0	- R/W 0	- R/W 0	TS 2 R/W 0	TS 1 R/W 0	TS 0 R/W 0
OE	12 Hex R/W Default	OE 7 R/W 0	OE 6 R/W 0	OE 5 R/W 0	OE 4 R/W 0	OE 3 R/W 0	OE 2 R/W 0	OE 1 R/W 0	OE 0 R/W 0
ADDP	1F Hex R/W Default	ADDP 7 R/W 0	ADDP 6 R/W 0	ADDP 5 R/W 0	ADDP 4 R/W 0	ADDP 3 R/W 0	ADDP 2 R/W 0	ADDP 1 R/W 0	ADDP 0 R/W 0

Table-12 Expanded (Indirect Address Mode) Register Map

Register	Address R/W Default	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
e-AFE <sup>(1)</sup>	02H R/W Default	AFE 7 R/W 0	AFE 6 R/W 0	AFE 5 R/W 0	AFE 4 R/W 0	AFE 3 R/W 0	AFE 2 R/W 0	AFE 1 R/W 0	AFE 0 R/W 0
e-RPDN	03H R/W Default	RPDN 7 R/W 0	RPDN 6 R/W 0	RPDN 5 R/W 0	RPDN 4 R/W 0	RPDN 3 R/W 0	RPDN 2 R/W 0	RPDN 1 R/W 0	RPDN 0 R/W 0
e-TPDN	04H R/W Default	TPDN 7 R/W 0	TPDN 6 R/W 0	TPDN 5 R/W 0	TPDN 4 R/W 0	TPDN 3 R/W 0	TPDN 2 R/W 0	TPDN 1 R/W 0	TPDN 0 R/W 0
e-EQUA	07H R/W Default	EQUA 7 R/W 0	EQUA 6 R/W 0	EQUA 5 R/W 0	EQUA 4 R/W 0	EQUA 3 R/W 0	EQUA 2 R/W 0	EQUA 1 R/W 0	EQUA 0 R/W 0
ADDP	1FH R/W Default	ADDP 7 R/W 0	ADDP 6 R/W 0	ADDP 5 R/W 0	ADDP 4 R/W 0	ADDP 3 R/W 0	ADDP 2 R/W 0	ADDP 1 R/W 0	ADDP 0 R/W 0

<sup>1</sup> In host mode, register e-AFE has to be set to 'FFH' for proper device operation. See e-AFE: AFE Enable Selection Register (R/W, Expanded Address = 02H) on page 28 for more details.

### 3.3 REGISTER DESCRIPTION

#### 3.3.1 PRIMARY REGISTERS

**ID:** Device ID Register (R, Address = 00H)

Symbol	Position	Default	Description
ID[7:0]	ID.7-0	10H	An 8-bit word is pre-set into the device as the identification and revision number. This number is different with the functional changes and is mask programmed.

**RL0:** G.772 Monitoring, Remote Loopback Configuration Register (R/W, Address = 02H)

Symbol	Position	Default	Description
-	RL.7-1	0000000	Reserved
RL[0]	RL.0	0	0 = Normal operation. (Default) 1 = Remote loopback enabled.

**TAO:** Transmit All Ones Configuration Register (R/W, Address = 03H)

Symbol	Position	Default	Description
TAO[7:0]	TAO.7-0	00H	0 = Normal operation. (Default) 1 = Transmit all ones.

**LOS:** Loss of Signal Status Register (R, Address = 04H)

Symbol	Position	Default	Description
LOS[7:0]	LOS.7-0	00H	0 = Normal operation. (Default) 1 = Loss of signal detected.

**DF:** Driver Fault Status Register (R, Address = 05H)

Symbol	Position	Default	Description
DF[7:0]	DF.7-0	00H	0 = Normal operation. (Default) 1 = Driver fault detected.

**LOSM:** Loss of Signal Interrupt Mask Register (R/W, Address = 06H)

Symbol	Position	Default	Description
LOSM[7:0]	LOSM.7-0	00H	0 = LOS interrupt is not allowed. (Default) 1 = LOS interrupt is allowed.

**DFM:** Driver Fault Interrupt Mask Register (R/W, Address = 07H)

Symbol	Position	Default	Description
DFM[7:0]	DFM.7-0	00H	0 = Driver fault interrupt not allowed. (Default) 1 = Driver fault interrupt allowed.

**LOSI:** Loss of Signal Interrupt Status Register (R, Address = 08H)

Symbol	Position	Default	Description
LOSI[7:0]	LOSI.7-0	00H	0 = (Default). Or after a <b>LOS</b> read operation. 1 = Any transition on <b>LOS<sub>n</sub></b> (Corresponding <b>LOSM<sub>n</sub></b> is set to '1').