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DATASHEET

Description

The 9DBU0231 is a member of IDT's 1.5V Ultra-Low-Power (ULP) PCle family. The device has 2 output enables for clock management.

Recommended Application

1.5V PCle Gen1-2-3 Zero-Delay/Fan-out Buffer (ZDB/FOB)

Output Features

• 2 - 1-167MHz Low-Power (LP) HCSL DIF pairs

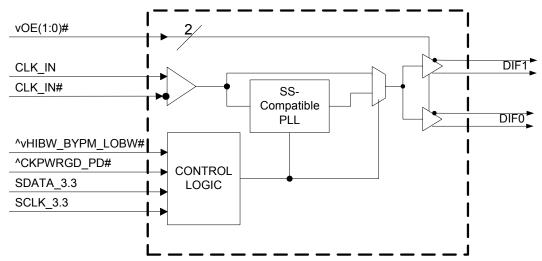
Key Specifications

- DIF cycle-to-cycle jitter <50ps
- DIF output-to-output skew <50ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- DIF additive phase jitter is <100fs rms for PCle Gen3
- DIF additive phase jitter <350fs rms for 12k-20MHz

Features/Benefits

- LP-HCSL outputs; save 4 resistors compared to standard HCSL outputs
- 35mW typical power consumption in PLL mode; eliminates thermal concerns
- Spread Spectrum (SS) compatible; allows SS for EMI reduction
- OE# pins; support DIF power management
- HCSL compatible differential input; can be driven by common clock sources
- SMBus-selectable features; optimize signal integrity to application
 - slew rate for each output
 - · differential output amplitude
- Pin/SMBus selectable PLL bandwidth and PLL Bypass; optimize PLL to application
- Outputs blocked until PLL is locked; clean system start-up
- Device contains default configuration; SMBus interface not required for device control
- 3.3V tolerant SMBus interface works with legacy controllers
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

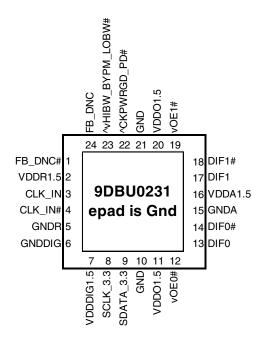
Block Diagram



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Pin Configuration



24-pin VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor ^v prefix indicates internal 120KOhm pull up AND pull down resistor (biased to VDD/2) v prefix indicates internal 120KOhm pull down resistor

SMBus Address Selection Table

| Address | + Read/Write bit |
|---------|------------------|
| 1101101 | х |

Power Management Table

| CKPWRGD PD# | CLK IN | SMBus | OEx# Pin | DIF | PLL | |
|--------------|---------|---------|-----------|----------|-----------|-----------------|
| CKPW NGD_PD# | CLK_III | OEx bit | OEX# PIII | True O/P | Comp. O/P | PLL |
| 0 | Х | Х | Х | Low | Low | Off |
| 1 | Running | 0 | Х | Low | Low | On ¹ |
| 1 | Running | 1 | 0 | Running | Running | On ¹ |
| 1 | Running | 1 | 1 | Low | Low | On ¹ |

^{1.} If Bypass mode is selected, the PLL will be off, and outputs will be running.

Power Connections

| Pin Numb | er | Description |
|----------|-------|-----------------------|
| VDD | GND | Description |
| 2 | 5 | Input receiver analog |
| 7 | 6 | Digital Power |
| 11,20 | 10,21 | DIF outputs |
| 16 | 15 | PLL Analog |

Note: epad on this device is not electrically connected to the die. It should be connected to ground for best thermal performance.

PLL Operating Mode

| | | Byte1 [7:6] | Byte1 [4:3] |
|-----------------|-----------|-------------|-------------|
| HiBW_BypM_LoBW# | MODE | Readback | Control |
| 0 | PLL Lo BW | 00 | 00 |
| M | Bypass | 01 | 01 |
| 1 | PLL Hi BW | 11 | 11 |



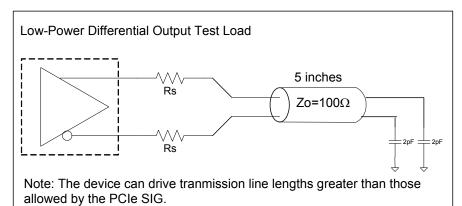
Pin Descriptions

| Pin# | Pin Name | Pin Type | Description |
|------|-------------------|---------------|---|
| 1 | FB_DNC# | DNC | Complement clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not |
| 2 | VDDR1.5 | PWR | connect anything to this pin. 1.5V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately. |
| 3 | CLK_IN | IN | True Input for differential reference clock. |
| 4 | CLK_IN# | IN | Complementary Input for differential reference clock. |
| 5 | GNDR | GND | Analog Ground pin for the differential input (receiver) |
| 6 | GNDDIG | GND | Ground pin for digital circuitry |
| 7 | VDDDIG1.5 | PWR | 1.5V digital power (dirty power) |
| 8 | SCLK_3.3 | IN | Clock pin of SMBus circuitry, 3.3V tolerant. |
| 9 | SDATA_3.3 | I/O | Data pin for SMBus circuitry, 3.3V tolerant. |
| 10 | GND | GND | Ground pin. |
| 11 | VDDO1.5 | PWR | Power supply for outputs, nominally 1.5V. |
| 12 | vOE0# | IN | Active low input for enabling DIF pair 0. This pin has an internal pull-down. |
| 13 | DIF0 | OUT | 1 =disable outputs, 0 = enable outputs Differential true clock output |
| 14 | DIF0# | OUT | Differential Complementary clock output |
| 15 | GNDA | GND | Ground pin for the PLL core. |
| 16 | VDDA1.5 | PWR | 1.5V power for the PLL core. |
| 17 | DIF1 | OUT | Differential true clock output |
| 18 | DIF1# | OUT | Differential Complementary clock output |
| | vOE1# | IN | Active low input for enabling DIF pair 1. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 20 | VDDO1.5 | PWR | Power supply for outputs, nominally 1.5V. |
| 21 | GND | GND | Ground pin. |
| 22 | ^CKPWRGD_PD# | IN | Input notifies device to sample latched inputs and start up on first high assertion. Low enters Power Down Mode, subsequent high assertions exit Power Down Mode. This pin has internal pull-up resistor. |
| 23 | ^vHIBW_BYPM_LOBW# | LATCHED IN | Trilevel input to select High BW, Bypass or Low BW mode. See PLL Operating Mode Table for Details. |
| 24 | FB_DNC | DNC | True clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not connect anything to this pin. |
| 25 | ePad | GND | Connect epad to ground. |

NOTE: DNC indicates Do Not Connect anything to this pin.



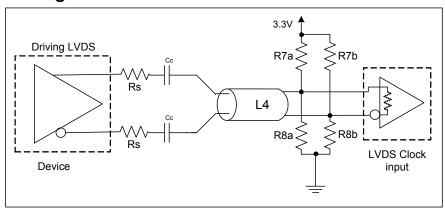
Test Loads



Alternate Differential Output Terminations

| Rs | Zo | Units |
|----|-----|---------|
| 33 | 100 | Ohms |
| 27 | 85 | Offilis |

Driving LVDS



Driving LVDS inputs

| Diving 11 De inpute | | | | | | |
|---------------------|--------------|--------------------------------|------|--|--|--|
| | ` | | | | | |
| | Receiver has | Receiver has Receiver does not | | | | |
| Component | termination | have termination | Note | | | |
| R7a, R7b | 10K ohm | 140 ohm | | | | |
| R8a, R8b | 5.6K ohm | 75 ohm | | | | |
| Cc | 0.1 uF | 0.1 uF | | | | |
| Vcm | 1.2 volts | 1.2 volts | | | | |



Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9DBU0231. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|---------------------------|-------------|---------------------------|------|-----|----------------------|-------|-------|
| Supply Voltage | VDDx | | -0.5 | | 2 | ٧ | 1,2 |
| Input Voltage | V_{IN} | | -0.5 | | V _{DD} +0.5 | V | 1,3 |
| Input High Voltage, SMBus | V_{IHSMB} | SMBus clock and data pins | | | 3.3 | V | 1 |
| Storage Temperature | Ts | | -65 | | 150 | °C | 1 |
| Junction Temperature | Tj | | | | 125 | ô | 1 |
| Input ESD protection | ESD prot | Human Body Model | 2000 | | | V | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Clock Input Parameters

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| · · · · · · · · · · · · · · · · · · · | p | personner community con | | | | | |
|---------------------------------------|--------------------|--|-----|-----|------|-------|-------|
| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
| Input Common Mode Voltage - DIF_IN | V _{COM} | Common Mode Input Voltage | 200 | | 725 | mV | 1 |
| Input Swing - DIF_IN | V _{SWING} | Differential value | 300 | | 1450 | mV | 1 |
| Input Slew Rate - DIF_IN | dv/dt | Measured differentially | 0.4 | | 8 | V/ns | 1,2 |
| Input Leakage Current | I _{IN} | $V_{IN} = V_{DD}$, $V_{IN} = GND$ | -5 | | 5 | uA | |
| Input Duty Cycle | d _{tin} | Measurement from differential wavefrom | 45 | 50 | 55 | % | 1 |
| Input Jitter - Cycle to Cycle | J_{DIFIn} | Differential Measurement | 0 | | 150 | ps | 1 |

¹ Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

³ Not to exceed 2.0V.

² Slew rate measured through +/-75mV window centered around differential zero



Electrical Characteristics-Input/Supply/Common Parameters-Normal Operating Conditions

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| TA = T _{AMB} , Supply Voltages | per normai c | operation conditions, See Test Loads for Loading Con | uitions | | | | |
|---|------------------------|---|----------------------|--------|----------------------|--------|--------------|
| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
| Supply Voltage | VDDx | Supply voltage for core and analog | 1.425 | 1.5 | 1.575 | V | |
| Ambient Operating | T_{AMB} | Commmercial range | 0 | 25 | 70 | °C | 1 |
| Temperature | AMB | Industrial range | -40 | 25 | 85 | °C | 1 |
| Input High Voltage | V_{IH} | Single-ended inputs, except SMBus | 0.75 V _{DD} | | $V_{DD} + 0.3$ | V | |
| Input Mid Voltage | V_{IM} | Single-ended tri-level inputs ('_tri' suffix) | $0.4~V_{DD}$ | | 0.6 V _{DD} | V | |
| Input Low Voltage | V_{IL} | Single-ended inputs, except SMBus | -0.3 | | 0.25 V _{DD} | V | |
| | I _{IN} | Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$ | -5 | | 5 | uA | |
| Input Current | | Single-ended inputs | | | | | |
| Input Current | I_{INP} | $V_{IN} = 0 \text{ V}$; Inputs with internal pull-up resistors | -200 | | 200 | uA | |
| | | V _{IN} = VDD; Inputs with internal pull-down resistors | | | | | |
| Input Fraguanay | F_{ibyp} | Bypass mode | 1 | | 167 | MHz | 2 |
| Input Frequency | F_{ipll} | 100MHz PLL mode | 20 | 100.00 | 110 | MHz | 2 |
| Pin Inductance | L_{pin} | | | | 7 | nH | 1 |
| | C _{IN} | Logic Inputs, except DIF_IN | 1.5 | | 5 | pF | 1 |
| Capacitance | C _{INDIF_IN} | DIF_IN differential clock inputs | 1.5 | | 2.7 | pF | 1,5 |
| | C _{OUT} | Output pin capacitance | | | 6 | pF | 1 |
| Clls Ctabilization | T _{STAB} | From V _{DD} Power-Up and after input clock | | | 1 | | 1.0 |
| Clk Stabilization | | stabilization or de-assertion of PD# to 1st clock | | | _ ' | ms | 1,2 |
| Input SS Modulation | f | Allowable Frequency for PCIe Applications | 30 | | 33 | kHz | |
| Frequency PCIe | f _{MODINPCle} | (Triangular Modulation) | 30 | | - 55 | KIIZ | |
| Input SS Modulation | f _{MODIN} | Allowable Frequency for non-PCIe Applications | 0 | | 66 | kHz | |
| Frequency non-PCle | ·WODIN | (Triangular Modulation) | _ | | | | |
| OE# Latency | t _{LATOE#} | DIF start after OE# assertion | 1 | | 3 | clocks | 1,3 |
| | | DIF stop after OE# deassertion DIF output enable after | | | | | |
| Tdrive_PD# | t _{DRVPD} | PD# de-assertion | | | 300 | us | 1,3 |
| Tfall | t _F | Fall time of single-ended control inputs | | | 5 | ns | 2 |
| Trise | t _R | Rise time of single-ended control inputs | | | 5 | ns | 2 |
| SMBus Input Low Voltage | V _{ILSMB} | c. c. cg.c onded control inputo | | | 0.6 | V | - |
| SMBus Input High Voltage | VIHSMB | V _{DDSMB} = 3.3V, see note 4 for V _{DDSMB} < 3.3V | 2.1 | | 3.3 | V | 4 |
| SMBus Output Low Voltage | VOLSMB | @ I _{PULLUP} | 2.1 | | 0.4 | V | - |
| SMBus Sink Current | I _{PULLUP} | @ V _{OL} | 4 | | Ų. , | mA | 1 |
| Nominal Bus Voltage | V _{DDSMB} | Bus Voltage | 1.425 | | 3.3 | V | |
| SCLK/SDATA Rise Time | t _{RSMB} | (Max VIL - 0.15) to (Min VIH + 0.15) | 1.120 | | 1000 | ns | 1 |
| SCLK/SDATA Fall Time | t _{FSMB} | (Min VIH + 0.15) to (Max VIL - 0.15) | | | 300 | ns | 1 |
| SMBus Operating | | | | | | | |
| Frequency | f _{MAXSMB} | Maximum SMBus operating frequency | | | 400 | kHz | 6 |
| | | | | | | | |

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

 $^{^{4}}$ For $V_{DDSMB} < 3.3V$, $V_{IHSMB} >= 0.8xV_{DDSMB}$

⁵DIF_IN input

⁶The differential input clock must be running for the SMBus to be active



Electrical Characteristics-DIF Low-Power HCSL Outputs

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|------------------------|-------------------|---|-----------------------|------|------|-------|-------|
| Slew rate | dV/dt | Scope averaging on, fast setting (100MHz) | 1.4 | 2.4 | 3.5 | V/ns | 1,2,3 |
| Siew late | dV/dt | Scope averaging on, slow setting (100MHz) | 0.9 | 1.7 | 2.5 | V/ns | 1,2,3 |
| Slew rate matching | ∆dV/dt | Slew rate matching, Scope averaging on | | 2.7 | 20 | % | 1,2,4 |
| Voltage High | V _{HIGH} | Statistical measurement on single-ended signal using oscilloscope math function. (Scope | 630 | 735 | 850 | mV | 7 |
| Voltage Low | V_{LOW} | averaging on) | -150 | -16 | 150 | 111 V | 7 |
| Max Voltage | Vmax | Measurement on single ended signal using | | 779 | 1150 | mV | 7 |
| Min Voltage | Vmin | absolute value. (Scope averaging off) | eraging off) -300 -45 | | | IIIV | 7 |
| Vswing | Vswing | Scope averaging off | 300 | 1503 | | mV | 1,2 |
| Crossing Voltage (abs) | Vcross_abs | Scope averaging off | 250 | 405 | 550 | mV | 1,5 |
| Crossing Voltage (var) | Δ-Vcross | Scope averaging off | | 12 | 140 | mV | 1,6 |

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Current Consumption

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|--------------------------|----------------------|--|-----|-------|------|-------|-------|
| Operating Supply Current | I _{DDR} | VDDR @100MHz | | 3 | 6 | mA | 1 |
| | I _{DDDIG} | VDDIG, All outputs @100MHz | | 0.125 | 0.25 | mA | 1 |
| | I _{DDAO} | VDDA+VDDO, PLL Mode, All outputs @100MHz | | 13 | 17 | mA | 1 |
| | I _{DDRPD} | VDDR, CKPWRGD_PD# = 0 | | 0.1 | 0.3 | mA | 1,2,3 |
| Powerdown Current | I _{DDDIGPD} | VDDDIG, CKPWRGD_PD# = 0 | | 0.1 | 0.2 | mA | 1,2 |
| | I _{DDAOPD} | VDDA+VDDO, CKPWRGD_PD# = 0 | | 0.7 | 1 | mA | 1,2 |

¹ Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

⁷ At default SMBus settings.

² Input clock stopped.

³ In bypass mode, the PLL is off and IDDAO is ~50% of this value.



Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| AIVIDY - - - - - - - - - - - - | | peraner containers, coe reet leader or leading of | | | | | |
|--|--|---|------|------|---------------------------------|-------|-------|
| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
| DLL Bandwidth | DW. | -3dB point in High BW Mode (100MHz) | 2.2 | 3.6 | 4.8 | MHz | 1,5 |
| PLL Bandwidth | $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | 1 | 1.6 | 2.5 | MHz | 1,5 | |
| PLL Jitter Peaking | t _{JPEAK} | Peak Pass band Gain (100MHz) | | 1.3 | 2.5 | dB | 1 |
| Duty Cycle | t _{DC} | Measured differentially, PLL Mode | 45 | 50.2 | 55 | % | 1 |
| Duty Cycle Distortion | t _{DCD} | Measured differentially, Bypass Mode @100MHz | -1 | -0.5 | 0 | % | 1,3 |
| Ckow Input to Output | t _{pdBYP} | Bypass Mode, V _T = 50% | 3400 | 4300 | 5200 | ps | 1 |
| Skew, Input to Output | t _{pdPLL} | PLL Mode V _T = 50% | 0 | 50 | 4.8 MHz 2.5 MHz 2.5 dB 55 % 0 % | 1,4 | |
| Skew, Output to Output | t _{sk3} | V _T = 50% | | 37 | 50 | ps | 1,4 |
| Jitter, Cycle to cycle | +. | PLL mode | | 24.1 | 50 | ps | 1,2 |
| Jitter, Cycle to Cycle | t _{jcyc-cyc} | Additive Jitter in Bypass Mode | | 0.1 | 5 | ps | 1,2 |

¹ Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Phase Jitter Parameters

 $TA = T_{AMB}$; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | INDUSTRY LIMIT | UNITS | Notes |
|---|---------------------------|--|--------|-----|-----|-------------------|-------------|--------------|
| TAILAMETER | t _{jphPCleG1} | PCIe Gen 1 | IVIIIA | 30 | 58 | 86 | ps (p-p) | 1,2,3,5 |
| PARAMETER Phase Jitter, PLL Mode Additive Phase Jitter, Bypass Mode | _ | PCle Gen 2 Lo Band 10kHz < f < 1.5MHz | | 0.9 | 1.4 | 3 | ps (rms) | 1,2,3,5 |
| | t _{jphPCleG2} | PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | 2.1 | 2.6 | 3.1 | ps (rms) | 1,2,3,5 |
| | t _{jphPCleG3} | PCIe Gen 3 Common Clock Architecture (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz) | | 0.5 | 0.6 | 1 | ps (rms) | 1,2,3,5 |
| | t _{jphPCleG3SRn} | PCIe Gen 3 Separate Reference No Spread (SRnS) (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz) | | 0.5 | 0.6 | 0.7 | ps (rms) | 1,2,3,5 |
| | t _{iphPCleG1} | PCle Gen 1 | | 0.1 | 5 | N/A | ps (p-p) | 1,2,3,5 |
| | | PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz | | 0.1 | 0.5 | N/A | ps (rms) | 1,2,3,4 5 |
| | t _{jphPCleG2} | PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | 0.1 | 0.3 | N/A | ps (rms) | 1,2,3,4 |
| | t _{jphPCleG3} | PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz) | | 0.2 | 0.3 | N/A | ps (rms) | 1,2,3,4 |
| Бураss Mode | t _{jph125M0} | 125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz | | 200 | 300 | N/A | fs (rms) | 1,6 |
| | t _{jph125M1} | 125MHz, 12KHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz | | 313 | 350 | N/A | fs (rms) | 1,6 |

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

⁴ All outputs at default slew rate

⁵ The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

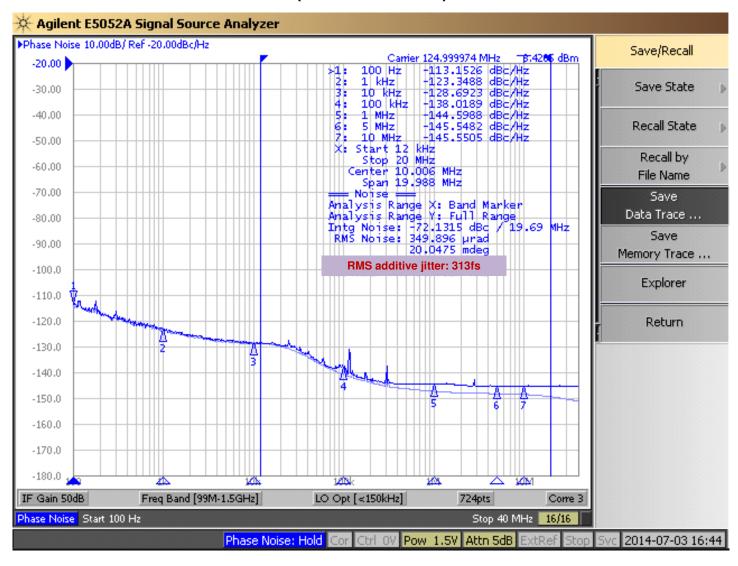
⁴ For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

⁵ Driven by 9FGU0831 or equivalent

⁶ Rohde&Schartz SMA100



Additive Phase Jitter Plot: 125M (12kHz to 20MHz)





General SMBus Serial Interface Information

How to Write

- · Controller (host) sends a start bit
- · Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

| | Index Blo | ock ' | Write Operation |
|-----------|------------|--------|----------------------|
| Controll | er (Host) | | IDT (Slave/Receiver) |
| Т | starT bit | | |
| Slave A | Address | | |
| WR | WRite | | |
| | | | ACK |
| Beginning | g Byte = N | | |
| | | | ACK |
| Data Byte | Count = X | | |
| | | | ACK |
| Beginnin | g Byte N | | |
| | | | ACK |
| 0 | | × | |
| 0 | | X Byte | 0 |
| 0 | | e | 0 |
| | | | 0 |
| Byte N | + X - 1 | | |
| | | | ACK |
| Р | stoP bit | | |

Note: SMBus Address is Latched on SADR pin.

How to Read

- Controller (host) will send a start bit
- · Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- · Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

| | Index Block F | Read O | peration |
|------|-----------------|----------|----------------------|
| Cor | ntroller (Host) | | IDT (Slave/Receiver) |
| Т | starT bit | | |
| SI | ave Address | | |
| WR | WRite | | |
| | | | ACK |
| Begi | nning Byte = N | | |
| | | | ACK |
| RT | Repeat starT | | |
| SI | ave Address | | |
| RD | ReaD | | |
| | | | ACK |
| | | | |
| | | | Data Byte Count=X |
| | ACK | | |
| | | | Beginning Byte N |
| | ACK | | |
| | | <u>e</u> | 0 |
| | 0 | X Byte | 0 |
| | 0 | × | 0 |
| | 0 | | |
| | | | Byte N + X - 1 |
| N | Not acknowledge | | |
| Р | stoP bit | | |



SMBus Table: Output Enable Register ¹

| Byte 0 | Name | Control Function | Туре | 0 | 1 | Default |
|--------|----------|------------------|------|---------|---------|---------|
| Bit 7 | Reserved | | | | | |
| Bit 6 | Reserved | | | | | |
| Bit 5 | DIF OE1 | Output Enable | RW | Low/Low | Enabled | 1 |
| Bit 4 | Reserved | | | | | |
| Bit 3 | DIF OE0 | Output Enable | RW | Low/Low | Enabled | 1 |
| Bit 2 | | Reserved | | | | 1 |
| Bit 1 | Reserved | | | | | 1 |
| Bit 0 | | Reserved | | | | 1 |

^{1.} A low on these bits will overide the OE# pin and force the differential output Low/Low

SMBus Table: PLL Operating Mode and Output Amplitude Control Register

| Byte 1 | Name | Control Function | Type | 0 1 | | Default |
|--------|-----------------|-------------------------------|-----------------|---|----------------|---------|
| Bit 7 | PLLMODERB1 | PLL Mode Readback Bit 1 | R | See PLL Operating Mode Table | | Latch |
| Bit 6 | PLLMODERB0 | PLL Mode Readback Bit 0 | R | | | Latch |
| Bit 5 | PLLMODE_SWCNTRL | Enable SW control of PLL Mode | RW | Values in B1[7:6] Values in B1[4:3] set PLL Mode set PLL Mode | | 0 |
| Bit 4 | PLLMODE1 | PLL Mode Control Bit 1 | RW ¹ | See PLL Operating Mode Table | | 0 |
| Bit 3 | PLLMODE0 | PLL Mode Control Bit 0 | RW ¹ | See FLL Operat | ing wode rable | 0 |
| Bit 2 | | Reserved | | | | 1 |
| Bit 1 | AMPLITUDE 1 | Controls Output Amplitude | RW | 00 = 0.55V | 01 = 0.65V | 1 |
| Bit 0 | AMPLITUDE 0 | Controls Output Amplitude | RW | 10= 0.75V | 11 = 0.85V | 0 |

^{1.} B1[5] must be set to a 1 for these bits to have any effect on the part.

SMBus Table: DIF Slew Rate Control Register

| | | 9 | | | | | |
|--------|------------------|---------------------|------|--------------|--------------|---------|--|
| Byte 2 | Name | Control Function | Туре | e 0 1 | | Default | |
| Bit 7 | | Reserved | | | | | |
| Bit 6 | Reserved | | | | | | |
| Bit 5 | SLEWRATESEL DIF1 | Slew Rate Selection | RW | Slow Setting | Fast Setting | 1 | |
| Bit 4 | Reserved | | | | | | |
| Bit 3 | SLEWRATESEL DIF0 | Slew Rate Selection | RW | Slow Setting | Fast Setting | 1 | |
| Bit 2 | Reserved | | | | | 1 | |
| Bit 1 | Reserved | | | | | 1 | |
| Bit 0 | | Reserved | | | | 1 | |

SMBus Table: FB Slew Rate Control Register

| Byte 3 | Name | Control Function | Туре | 0 | 1 | Default | |
|--------|----------------|------------------------|------|--------------|--------------|---------|--|
| Bit 7 | | Reserved | | | | 1 | |
| Bit 6 | | Reserved | | | | 1 | |
| Bit 5 | | Reserved | | | | | |
| Bit 4 | | Reserved | | | | | |
| Bit 3 | | Reserved | | | | 0 | |
| Bit 2 | | Reserved | | | | 1 | |
| Bit 1 | Reserved | | | | | 1 | |
| Bit 0 | SLEWRATESEL FB | Adjust Slew Rate of FB | RW | Slow Setting | Fast Setting | 1 | |

Byte 4 is Reserved and reads back 'hFF



SMBus Table: Revision and Vendor ID Register

| Byte 5 | Name | Control Function | Туре | 0 | 1 | Default |
|--------|------|------------------|------|------------|-------|---------|
| Bit 7 | RID3 | | R | | 0 | |
| Bit 6 | RID2 | Revision ID | R | A rev | 0 | |
| Bit 5 | RID1 | REVISION | R | A IEV | 0 | |
| Bit 4 | RID0 | | R | | 0 | |
| Bit 3 | VID3 | | R | | | 0 |
| Bit 2 | VID2 | VENDOR ID | R | 0001 | - IDT | 0 |
| Bit 1 | VID1 | VENDOR ID | R | 0001 = IDT | | 0 |
| Bit 0 | VID0 | | R | | | 1 |

SMBus Table: Device Type/Device ID

| Byte 6 | Name | Control Function | Type | 0 | 1 | Default | |
|--------|--------------|---------------------|------|----------------|-----------------------|---------|--|
| Bit 7 | Device Type1 | e Type1 Parisa Tima | | 00 = FGx, 01 = | DBx ZDB/FOB, | 0 | |
| Bit 6 | Device Type0 | - Device Type | R | 10 = DMx, 1 | 1 | | |
| Bit 5 | Device ID5 | | R | | | 0 | |
| Bit 4 | Device ID4 | 1 | R | | 0 | | |
| Bit 3 | Device ID3 | Device ID | R | 000100 bina | 0100 binary or 02 hex | | |
| Bit 2 | Device ID2 | - Device ID | R | 000100 billa | ry or oz nex | 0 | |
| Bit 1 | Device ID1 | | R | | | 1 | |
| Bit 0 | Device ID0 | 1 | R | | | 0 | |

SMBus Table: Byte Count Register

| Byte 7 | Name | Control Function | Туре | 0 | 1 | Default |
|--------|----------|------------------------|------|------------------------|-----------------------|---------|
| Bit 7 | Reserved | | | | | |
| Bit 6 | Reserved | | | | | |
| Bit 5 | Reserved | | | | | 0 |
| Bit 4 | BC4 | | RW | | | 0 |
| Bit 3 | BC3 | | RW | Writing to this regist | er will configure how | 1 |
| Bit 2 | BC2 | Byte Count Programming | RW | many bytes will be r | read back, default is | 0 |
| Bit 1 | BC1 | | RW | = 8 b | ytes. | 0 |
| Bit 0 | BC0 | | RW | | | 0 |



Marking Diagrams





Notes:

- 1. "LOT" is the lot sequence number.
- 2. YYWW is the last two digits of the year and week that the part was assembled.
- 3. Line 2: truncated part number
- 4. "L" denotes RoHS compliant package.
- 5. "I" denotes industrial temperature range device.

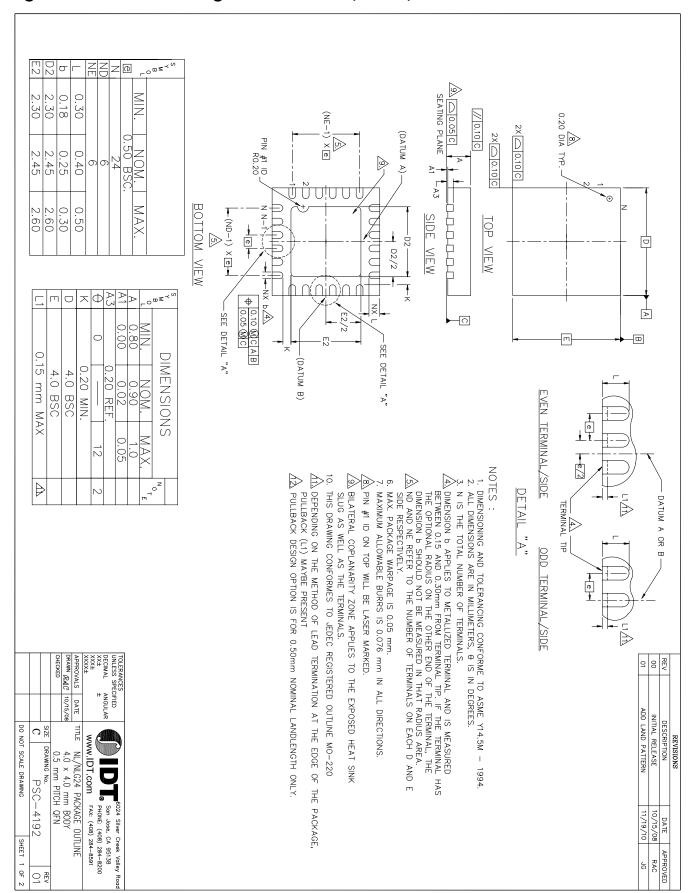
Thermal Characteristics

| PARAMETER | SYMBOL | CONDITIONS | PKG | TYP VALUE | UNITS | NOTES |
|--------------------|----------------|---------------------------------|--------------|--------------|-------|-------|
| | Θ_{JC} | Junction to Case | | 62 | °C/W | 1 |
| | Θ_{Jb} | Junction to Base | 5.4 | | °C/W | 1 |
| Thermal Resistance | Θ_{JA0} | Junction to Air, still air | NLG20 50 | °C/W | 1 | |
| Theimai nesistance | Θ_{JA1} | Junction to Air, 1 m/s air flow | NLG24 | 43 | °C/W | 1 |
| | Θ_{JA3} | Junction to Air, 3 m/s air flow | - | | °C/W | 1 |
| | Θ_{JA5} | Junction to Air, 5 m/s air flow | | | °C/W | 1 |

¹ePad soldered to board

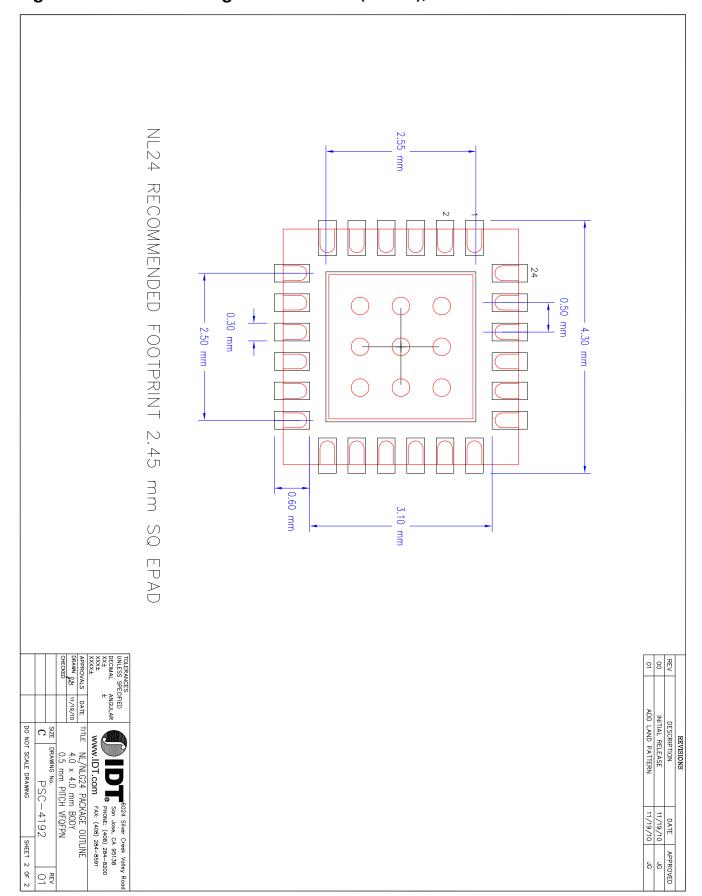


Package Outline and Package Dimensions (NLG24)





Package Outline and Package Dimensions (NLG24), cont.





Ordering Information

| Part / Order Number | Shipping Packaging | Package | Temperature | |
|---------------------|--------------------|---------------|---------------|--|
| 9DBU0231AKLF | Tubes | 24-pin VFQFPN | 0 to +70° C | |
| 9DBU0231AKLFT | Tape and Reel | 24-pin VFQFPN | 0 to +70° C | |
| 9DBU0231AKILF | Tubes | 24-pin VFQFPN | -40 to +85° C | |
| 9DBU0231AKILFT | Tape and Reel | 24-pin VFQFPN | -40 to +85° C | |

[&]quot;LF" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

Revision History

| Rev. | Initiator | Issue Date | Description | Page # | |
|-------|-----------|---|--|---------|--|
| A RDW | | 7/14/2014 | . Updated electrical tables with char data. | | |
| | DDW | | 2. Added an additive phase jitter plot. | Various | |
| | INDVV | | 3. Added 12kHz to 20MHz additive phase jitter spec. | vanous | |
| | | | 4. Updated Amplitude control bit descriptions in Byte 1. | | |
| B RDW | 9/19/2014 | Updated SMBus Input High/Low parameters conditions, MAX values, | 6 | | |
| | | and footnotes. | | | |
| C RDW | | | 1. Updated pin out and pin descriptions to show ePad on package | | |
| | 4/3/2015 | connected to ground. | 1-4 | | |
| | TIDVV | 4/3/2013 | 2. Updated front page text to standard format for these devices. Added | 1-4 | |
| | | | explicit bullet indicated Spread Spectrum compatibility. | | |
| D RDW | | 4/22/2014 | Updated Clock Input Parameters table to be consistent with PCle | | |
| | BDW | | Vswing parameter. | 1,5 | |
| | אטוו | | 2. Minor updates to front page text for family consistency. | 1,5 | |
| | | | 3. Add note about epad to Power Connections table. | | |

[&]quot;A" is the device revision designator (will not correlate with the datasheet revision).



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