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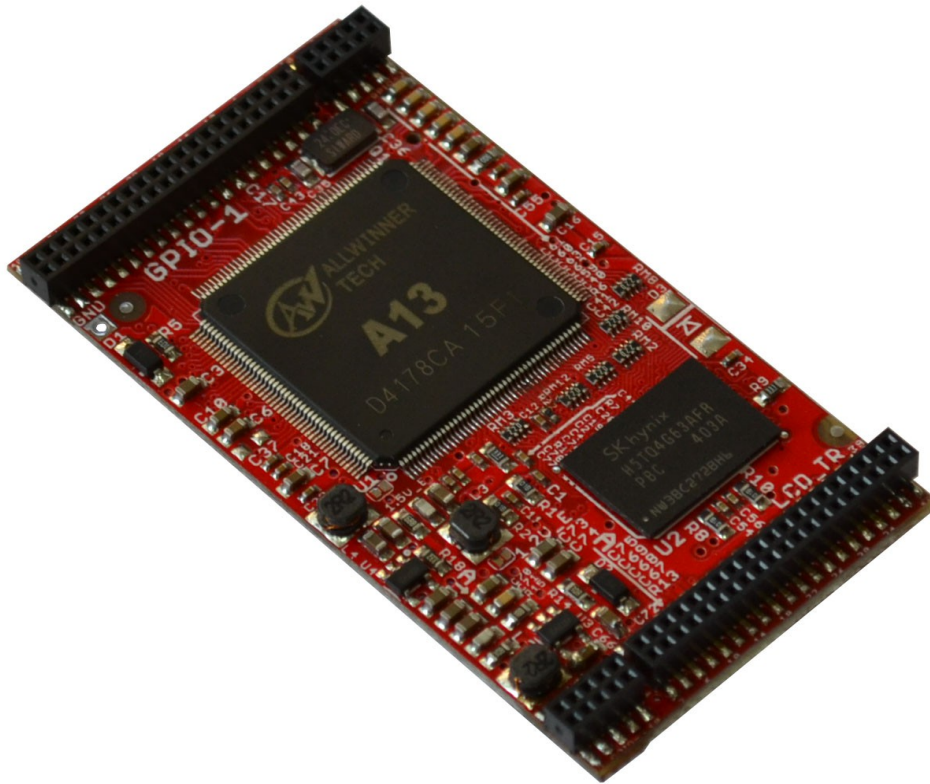
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A13-SOM-256 and A13-SOM-512

System-on-Module boards capable of Linux boot

USER'S MANUAL

Revision B, March 2015
Designed by OLIMEX Ltd, 2014



All boards produced by Olimex LTD are ROHS compliant

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The software is released under GPL.

It is possible that the pictures in this manual differ from the latest revision of the board.

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CHAPTER 1: OVERVIEW

1. Introduction to the chapter

Thank you for choosing this single board computer from Olimex! This document provides a user's guide for the A13-SOM boards. It covers both the -256 and the -512 version board. In the text below 'A13-SOM' is used to address both "A13-SOM-256" and "A13-SOM-512"; if a specific feature is available to only one of the boards then this is specifically mentioned and the board is addressed with the RAM-indicating suffix.

As an overview, this chapter gives the scope of this document and lists the board's features. The document's organization is then detailed.

The A13-SOM development board enables code development of applications running on the A13 microcontroller, manufactured by Allwinner Technology from China.

The A13-SOM board is typically used together with A13-SOM-WIFI or A13-SOM-WIFI-4GB which provides the following expansions over the original design:

- 1) an USB-OTG connector for easier powering or adding USB modules to the board (via a splitter or adapter)
- 2) a built-in WIFI module (Realtek 8188CUS)
- 3) an LCD display connector with 0.1" step
- 4) 4GB NAND memory (only in A13-SOM-WIFI-4GB)

All of the features listed above are also supported in the software releases suitable for the board.

The hardware design of A13-SOM development board is considered intellectual property to Olimex. The hardware design files are considered copyright material and would not be distributed.

The expansion boards available for A13-SOM are an open-source, open-hardware projects and all documentation is available to the customer.

The software support for both boards is open-source and released under GPL license.

1.1 Introduction to SOM (System-On-a-Module)

OLIMEX System-on-Module (SOM) boards are powerful Linux-capable boards. They follow a low-cost modular design which allows rapid product development. Each of these boards has two parts – a main part which nests the processor, the memory and the power control unit and the peripheral part which contains the USB ports, the video output and most of the connectors. SOM designs are targeted at customers who want to apply custom modifications and own solutions based on a specific processor without having to deal with multi layer PCBs with controlled impedance and BGA assembly. This makes it possible to create simple boards (that might be manufactured by your local board manufacturer) containing only the peripherals you need with the dimensions and shape suitable for your specific solution.

Both the main part and the peripheral part of the SOM system have support in the official Android and Debian images distributed by Olimex and maintained by Olimex and the Linux community. These images are typically available at the wiki articles of the boards.

The peripheral part of the SOM design is considered Open Source HardWare (OSHW) and the customer has access to the board source files that we used to manufacture it. The part of the design that has the main microcontroller is considered proprietary design and design files would not be shared. If you are looking for open source design of the processors used please check the OLinuXino boards. OLinuXino board designs are fully open source but harder to implement in own solutions and require more of a hardware experience to do so. Nevertheless, OLinuXino boards are pretty good choice for evaluating the capabilities of the embedded processors.

1.2 Target market of the board

Using the A13-SOM as a stand-alone development board would be more suitable for users with some hardware experience or people already familiar with other single-board Linux boards and designs. As mentioned in the previous chapter the board is meant to be implemented in a hardware design.

Please refer to the list of possible scenarios where a stand-alone A13-SOM (without other peripheral extension boards attached) board might not be suitable for you:

1. If you are a beginner with single-board Linux computers
2. If you are an OSHW purist
3. If you are looking for more straight-forward software development and you are not going to implement the A13-SOM in own hardware products

In the cases above, it might be a better idea to take a look at the OLinuXino boards (like A13-OLinuXino).

It is highly recommended to use A13-SOM with A13-SOM-WIFI initially, unless you have previous experience with SOM or OLinuXino boards manufactured by OLIMEX.

A13-SOM might be is used altogether with A13-SOM-WIFI. In that case, the board's target market widens drastically – the reason for this alteration is the additional hardware that A13-SOM-WIFI – provides easier powering and Internet access, among others. Generally, the processors features are much easier to access.

1.3 Features of A13-SOM boards

The A13-SOM board has the following set of features:

- Allwinner A13 Cortex-A8 processor typically running at 1Ghz
- **256MB or 512MB DDR3 memory, depending on the board version – please note that the 256MB version is not suitable for a smooth Android experience**
- Power management DCDC
- MicroSD card
- UART console connector
- 4 connectors 0.05" step
- Status LEDs
- RESET, UBOOT/HOME buttons
- Dimensions: (2400×2100)mil ~ (61×53)mm

1.4 Board variants

There are two major board variants named: A13-SOM-256 and A13-SOM-512. The 256 version has 256MB of DDR3 RAM memory compared to the 512 version that has double the amount.

It is important to notice that the 256MB of DDR3 RAM are insufficient to run Android OS properly. If you are interested in Android development for Allwinner A13 I recommend you to get the 512MB version of A13-SOM.

A similar board is A13-OLinuXino – it is meant for fully evaluating the capabilities of A13 processor. if you are going to implement A13-SOM into custom design it would be a good idea to first check on the A13-OLinuXino – it would be easier to evaluate the capabilities of the A13 processor, due to the

The other Olimex board with close characteristics is A20-SOM board. It is a bit bigger and a bit more expensive. However, has a generation newer dual-core processor that is better for heavy computations (for instance, high resolution video decoding and encoding). The A20-SOM board also has a bigger extension shield with almost all of the peripherals supported by the A20 processor. This extension is named 'A20-SOM-EVB'.

1.5 Board version used in the manual

A13-SOM-256 revision D board and A13-SOM-512 revision D boards were used while writing this document. It is possible that part of the information is outdated.

1.6 Document organization

Each section in this document covers a separate topic, organized as follows:

- Chapter 1 is an overview of the board usage and features
- Chapter 2 provides a guide for quickly setting up the board and software notes
- Chapter 3 contains the general board diagram and layout
- Chapter 4 describes the component that is the heart of the board: the A13 – Allwinner processor
- Chapter 5 is an explanation of the control circuitry associated with the microcontroller
- Chapter 6 covers the connector pinout, peripherals and jumper description
- Chapter 7 provides the schematics and the dimensions of the board
- Chapter 8 contains the revision history, useful links and support information

CHAPTER 2: SETTING UP THE A13-SOM BOARD

2. Introduction to the chapter

This section helps you set up the SOM development board for the first time. Please consider first the electrostatic warning to avoid damaging the board, then discover the hardware and software required to operate the board.

The procedure to power up the board is given, and a description of the default board behavior is detailed.

2.1 Electrostatic and electrical polarity warning

A13-SOM boards are shipped in a protective anti-static package. The board must not be exposed to high electrostatic potentials. A grounding strap or similar protective device should be worn when handling the board. Avoid touching the component pins or any other metallic element.

If you connect other electrical devices to the SOM board make sure that they have equal electrical polarity. This is also true for a serial cable connected between a PC and the board's DEBUG port. In rare cases different polarity might cause hardware damage to the board.

2.2 Requirements

In order to set up the A13-SOM board optimally one or more additional items may be needed. They might be generally placed in two categories:

Required – items that are needed in order to achieve minimum functionality;

Recommended – items that is good to have in order to be able to interact with the most important of the features of the board;

Note that if A13-SOM-WIFI or A13-SOM-WIFI-4GB is mounted on A13-SOM – the requirements would be different! The requirements below are for a stand-alone use of A13-SOM. Refer to A13-SOM-WIFI's user's manual for adjusted requirements.

Required items:

- 5V-external power supply with proper connectors – A13-SOM has no power jack, only powering pins (5VEXT, GND)
- Output device – USB-SERIAL-CABLE-F + personal computer (for Linux and/or Android debugging) – A13-SOM lacks other options for debugging – you would need a serial cable with level-shifter to interface the board
- SD card with compatible image – if you have the board version with NO additional NAND memory you will need it to use one of the images available. If you decide to use Debian you would also need a card. Official Android and Debian images are available at the wiki article for the board.

Recommended items:

- **A13-SOM-WIFI** – expansion board that can be directly mounted over A13-SOM – it adds USB-mini port, a WIFI module with built-in antenna, LCD display connector with 0.1" step and routes a number of frequently used signals to the easier to access 0.1" row of pinholes. The sources schematics of A13-SOM-WIFI are available for download and the board is considered open hardware.

Some of the above-suggested items can be purchased by Olimex, for instance:

USB-SERIAL-CABLE-F – female USB serial console cable – provides the easiest way of debugging

A13-SOM-256-DEBIAN-SD – a tested, class 10 micro SD card with the latest (by the time of leaving the Olimex facilities) official Debian release, suitable for the 256MB version of the board

A13-SOM-512-DEBIAN-SD – same as above suitable for the 512MB version of the board

A13-SOM-512-ANDROID-SD – a tested, class 10 micro SD card with the latest (by the time of leaving Olimex facilities) official Android Linux release

Probably you noticed that we don't sell A13-SOM-256-ANDROID-SD – that is because we consider that A13-SOM-256 is not capable of running Android smoothly.

2.3 Powering the board

The powering requirements of the A13-SOM are different depending on whether you use it in stand-alone mode or mounted atop A13-SOM-WIFI. The sub-chapters below deal with both scenarios.

2.3.1 Stand-alone powering

If you use the board in stand-alone mode (e.g. it is neither attached to A13-SOM-WIFI nor to any other board of peripherals) there are fewer options for powering it. There is no standard jack for the powering circuit – you might need to make own adapter. Consider that you might need additional cables or connectors. You would need to provide 3.3V DC to one of the two following locations:

1. UART1 pin named “3.3V”; you can use any GND pin available at the board

or

2. Connector GPIO-1's pin 1 (3.3V) and pin 2 (GND)

The minimum consumption is 0.33W (equivalent of 0.1A of current at 3.3V of voltage).

Do not provide AC voltage to the A13-SOM board! Do not provide more than 3.3V of voltage directly to the A13-SOM board! Providing 5V or more would instantly cause permanent hardware damage!

Consider that the board lacks hardware “wake-up” button. This means that if your OS enters sleep mode you will probably be unable to wake the board using only the LCD. The sleep and stand-by modes had been disabled in the default images. The Android release has an application that disables stand-by.

Sometimes when starting Android it is possible the board to enter battery save mode even before booting fully. Especially, if you have turned off the board without quick boot mode enabled. In this case you should press the PWR button for at least 5 seconds which would allow the board to start.

2.3.2 Mounted powering

Typically, A13-SOM gets evaluated when mounted connected with A13-SOM-WIFI. In this case the former is powered via the latter. The power line, altogether with a number of other important processor lines, is transferred via the 10-pin and 40-pin headers. A13-SOM receives power from A13-SOM-WIFI, but what are the requirements to power A13-SOM-WIFI?

There are two main scenarios for the powering A13-SOM-WIFI (and respectively A13-SOM):

1) a miniUSB cable connected to either a personal computer or a 5V power source; A13-SOM-WIFI has miniUSB connector – note that USB ports of personal computers usually provide up to 0.5A of current – this might be insufficient in certain cases. For example, if you have a lot of peripherals or a display powered by the board.

2) +5V directly provided to GPIO row of pinholes (the pinholes are called +5V and GND – near the PWR_LED and the USB_OTG); these pins can be used to connect a power jack

Some typical consumptions are listed below:

- A13-SOM-512 + A13-SOM-WIFI-4GB running Debian – consumption: 0.45A @ 5V
- A13-SOM-512 + A13-SOM-WIFI-4GB + A13-LCD7-TS running Debian – consumption: 0.75A @ 5V
- A13-SOM-512 + A13-SOM-WIFI-4GB + A13-LCD7-TS running Android – consumption: 0.40A @ 5V

Do not provide AC voltage to the A13-SOM-WIFI board! Do not provide more than 5V of voltage to the A13-SOM-WIFI board!

The default username/password combination for the default Linux image on the SD card (if purchased) is: root/olimex.

Note that it is normal that when the board is powered some integrated circuits might appear hotter than others. This is perfectly normal for some electronic components (for instance – the voltage regulators and the main processor).

2.4 Button functions

The two buttons usually are supported under both Android and Debian:

RESET – used to perform software turn off, software turn on; used to turn on board when powered by battery – has to be held down for at least 5 seconds to perform each action

UBOOT/HOME – used to boot up the board, can be used for navigation in Android

Note that: the board lacks recovery button! This is not a problem if you are using Debian Linux. However, it would make it impossible to wake the board in Android. You would need to disable

automatic sleep

It is recommended to always make a software “turn off” of the board. After that you can safely remove the power supply. If you disconnect the power supply (either the USB or the power supply) before turning off the board you may corrupt your SD card.

If your board has NAND memory you can corrupt the image located on the NAND memory.

2.5 Interacting with the board

The typical and recommended way of interacting with a stand-alone A13-SOM board is via a serial cable connected to a personal computer. You would probably need a cable suitable for such a connection due to the fact that most personal computers lack a serial port nowadays.

We distribute such a cable. Even if you already have such a cable or you decide to purchase it elsewhere it is advisable to check this product page for a reference: [Product page](#)

You need to connect the serial cable lines as follows: RX line to UART1-TX pin; TX line to UART1-RX pin; GND to GND. The last pin of UART1 connector is named 3.3V and it can be used to power the board, if you have other ways of power the board leave 3.3V pin unconnected! Be careful to avoid the connection to the serial cable else there would be a short-circuit. Make sure that the serial cable is connected to your personal computer and recognized properly after driver installation.

Then open a terminal program on the serial (COM) port which the cable is associated with.

After everything else is set, you would need to power the board as explained in “2.3 Powering the board”.

If the A13-SOM is attached to A13-SOM-WIFI in addition to the serial communication you might also use one or more of the two additional mediums to interact with the board:

1. a compatible display via the LCD_CON connector
2. a remote computer using the WIFI-capabilities (probably via SSH connection)

Using the LCD_CON or the WIFI might require additional configurations. Furthermore, it is possible to corrupt the output settings over those interfaces and, thus, lose the output. In such cases, you can always use the serial cable USB-SERIAL-CABLE-F as a reliable way to establish connection to the board.

2.6 Changing the default image resolution

Depending on the display or the screen you want to use with the A13-SOM, you might need to apply software changes to the prebuilt Android or Linux image.

The typical A13-SOM user would not need to edit the files, however.

To ease the process of changing the resolution we have compiled a number of Android images for the Android users (with hard-coded video output settings). Alternatively, for Debian Linux users, we

have provided a shell script that can be executed in order to set preferred video output and resolution.

For Android that you boot from the NAND memory you would need an image suitable for the specific resolution. Download locations to such images might be found at the wiki article for the A13-SOM board here: <https://www.olimex.com/wiki/A13-SOM>.

For Linux Debian you would need to execute a shell script to be able to change the resolution. It is very good idea to use a serial cable for connection to the board from a personal computer since in this case you are dependent on a video resolution (a cable like USB-SERIAL-CABLE-F). When the board boots type:

```
./change_display*
```

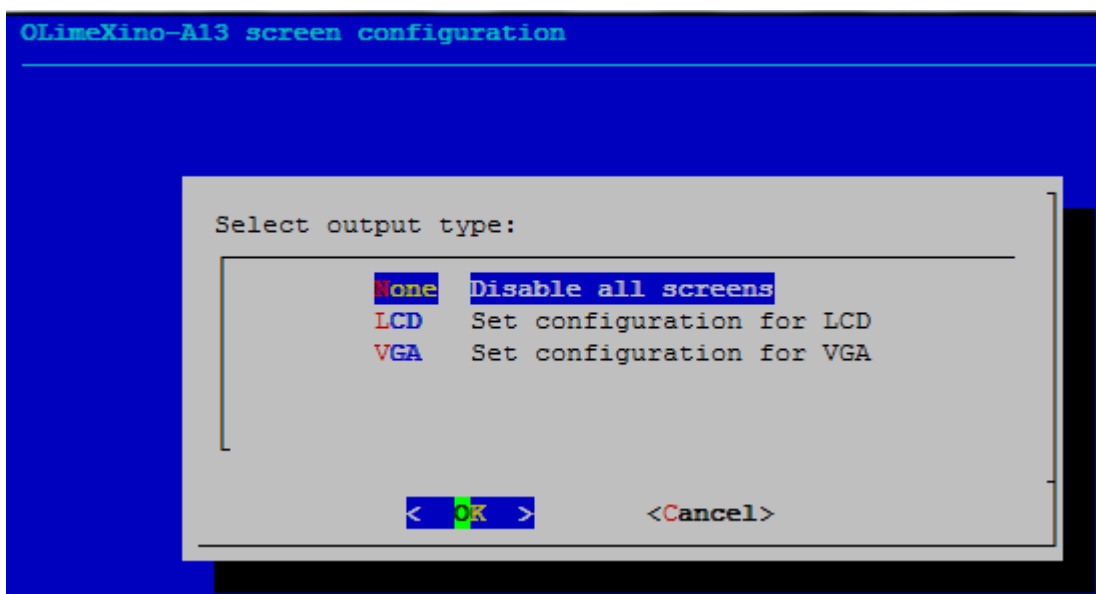
or

```
./change_display_a13.sh
```

It looks like this:

```
root@a13-OLinuXino-Micro-SOM:~# ./change_display_a13.sh
fexc-bin: /tmp/screen/script.bin: version: 0.1.2
fexc-bin: /tmp/screen/script.bin: size: 29588 (58 sections)
```

Then the main menu of the video configuration script shows up:



Choose the resolution and the interface (LCD or VGA). Note that VGA output is hard to implement and requires both additional hardware and good soldering experience.

The supported resolutions are listed on the next page.

For LCD:

1. 4.3" (480×272)
2. 7" (800×480)
3. 10" (1024×600)

For VGA (A13-SOM lacks VGA support on hardware level):

0. 1680×1050
1. 1440×900
2. 1360×768
3. 1280×1024
4. 1024×768
5. 800×600
6. 640×480
7. 1920×1080
8. 1280×720

Depending on the display or the screen you want to use with the A13-SOM, you might need to apply software changes to the prebuilt Android or Linux image. The easiest way would be to do it on the board itself but it can be done offline too (manipulating the image located on the microSD card via a microSD card reader).

The tools for script.bin changing are located in /opt/sunxi-tools directory:

```
#cd /opt/sunxi-tools  
#./chscr.sh
```

This will convert script.bin file from sdcad to script.fex file and the file will be opened using nano editor. Now you can change the board modules and parameters, save the changes ("CTRL"+"X"; confirm with "Y") and exit ("CTRL"+"X" again) from nano editor.

```
#./wrscr.sh
```

this will convert script.fex to script.bin and the script.bin file will be written to the microSD card.

```
reboot
```

Reboot the board and the new settings would be enabled.

Alternatively, you can do the changes on the microSD card off the board. You would need to remove the microSD card and explore it in a microSD card reader. You would need to edit the configuration file script.bin and edit the settings inside. This file is usually located in the main partition of a prepared microSD card. Script.bin can't be opened in the binary format so you would need to convert it to .fex file format first. There are ready-to-use tools that convert script.bin <-> script.fex. Note that script.bin/fex contains configuration settings and definitions not only for the video output but also for the pin descriptions and names; power setting and much more. If you really want to modify and customize the default images (to change port functions, port names, to disable specific peripherals) you would need to be able to edit the script files. Please refer to the

following web page for more information: http://linux-sunxi.org/Fex_Guide
 More information on script editing might be found in the following wiki article: [FEX edit](#)

The typical A13-SOM user would not need to edit the files, however.

2.7 Connecting and calibrating a display

A13-SOM itself has no direct way of connecting an Olimex display (with or without touchscreen component). Using a display without A13-SOM-WIFI is possible via cables but hard to accomplish and impractical. It is recommended to try to use a display only if you also have A13-SOM-WIFI at your disposal.

Unlike other OLIMEX Allwinner boards, the A13-SOM lacks a row of pins that allows the user to connect a display out-of-the-box. The board's LCD_TR connector is female and has a smaller 0.05" step. This means that if you use a display made by OLIMEX, you would need additional 2×20 MALE-MALE 0.05" header to convert the female connector to male. The 0.05" headers are somehow hard to find so we sell them here: [0.05" step connectors](#). There is also something very important to notice – since a stand-alone A13-SOM gets powered by 3.3V – this means that you will not be able to power the display via the board (the Olimex-made displays require 5V of voltage). You would need to power the display externally.

Newer displays made by Olimex have both 0.1" and 0.05" step connectors. So if you are going to need only the display and a cable (sold separately).

The displays recommended for the board at the moment of writing might be found in the table below:

Display name	Size of display in inches	Native resolution in pixels	Official Debian image support	Official Android image support	Link to product page
LCD-OlinuXino-4.3TS	4.3	480×272	Yes	No	Product page
LCD-OLinuXino-7	7	800×480	Yes	Yes	Product page
LCD-OLinuXino-7TS	7	800×480	Yes	Yes	Product page
LCD-OLinuXino-10	10	1024×600	Yes	Yes	Product page
LCD-OLinuXino-10TS	10	1024×600	Yes	Yes	Product page

The displays whose names contain “TS” - include a resistive touch screen component.

The cable used for connection depends on the specific board you are using and more specifically it depends on the pitch of the LCD connector of the board. We have two cables – both 40-pins ones but one for the bigger pitch (0.1") and the other for the smaller one (0.05"). Each of the displays listed in the table above has two connectors suitable for both cables:

CABLE-IDC40-6cm – 6cm long cable suitable for 0.1" step connectors – [Product page](#)

CABLE-40-40-10CM – 10cm long cable suitable for 0.05" step connectors – [Product page](#)

2.7.1 Android calibration

Calibrating a display under Android is pretty straightforward from the Android application.

Important: initially the boards are calibrated for a specific display and resolution. If you re-write the image (no matter whether the SD card or the NAND memory) you might need to use a mouse to calibrate the display initially. It might be impossible to calibrate it only by using the touch component over the display.

2.7.2 Debian calibration

The command that allows calibrating in Debian Linux is:

```
ts_calibrate
```

The default Debian video output configuration is set to 7 inch LCD display (800×480). If you want to change to other video output resolution refer to chapter 2.6 Changing the default image resolution.

If the problem is under Debian Linux make sure you are properly logged in the LXDE interface! Else applying calibration would not happen for the current user – if you are calibrating from the X graphical interface make sure that you are logged as user “olimex” (if calibrating without the X, the user is “root”).

```
#su olimex
```

enter the password: “olimex”, then calibrate the touch screen and reboot the board

```
#sudo reboot
```

2.8 Software support

We maintain Linux and Android images for SD card which might be downloaded for free and modified as the user wishes. The latest images and updates are featured at the wiki article of the device: <https://www.olimex.com/wiki/A13-SOM>.

We usually try to provide details on how to build the Linux and the Android images at our wordpress page: <http://olimex.wordpress.com/>.

Another useful place is the Olimex forums where a lot of people share their experience and advice: <https://www.olimex.com/forum/>.

The official images are a constant work-in-progress – newer releases are packed with better hardware support, newer kernels and extra features.

You are more than welcome to send or share your suggestions and ideas at our e-mail, the public forums or irc channel. We would attempt to help in almost every case. We listen to the feedback and if the majority of users suggest a software change or update we try to implement such. Customer feedback is very important for the overall state of the software support. However, do not expect full

Linux or Android software support.

We can share our experience. We can give you full details for things we have tried. We can point you to a resource or a guide. We can give you general directions to solving a specific problem or places to look for more information. However, we won't install a piece of software for you or write custom program for you. We won't provide a specific software solution to a specific software problem.

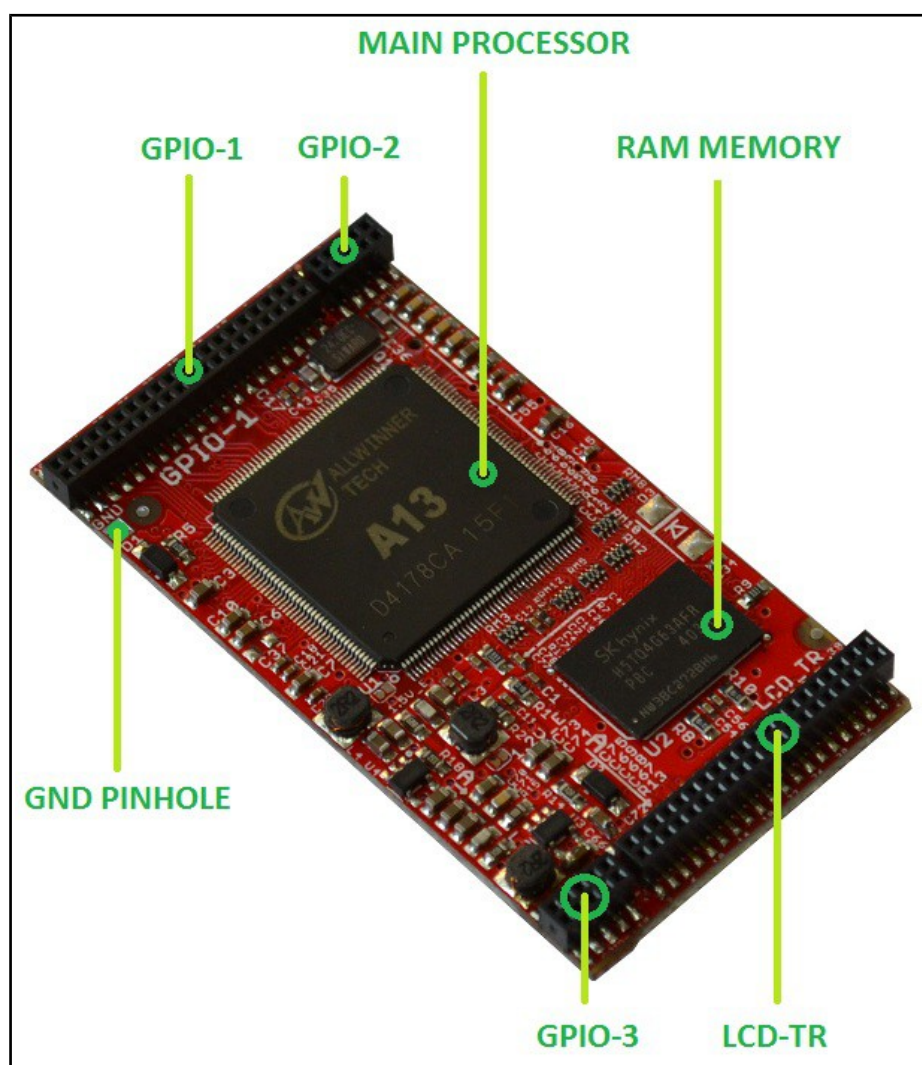
CHAPTER 3: BOARD DESCRIPTION

3. Introduction to the chapter

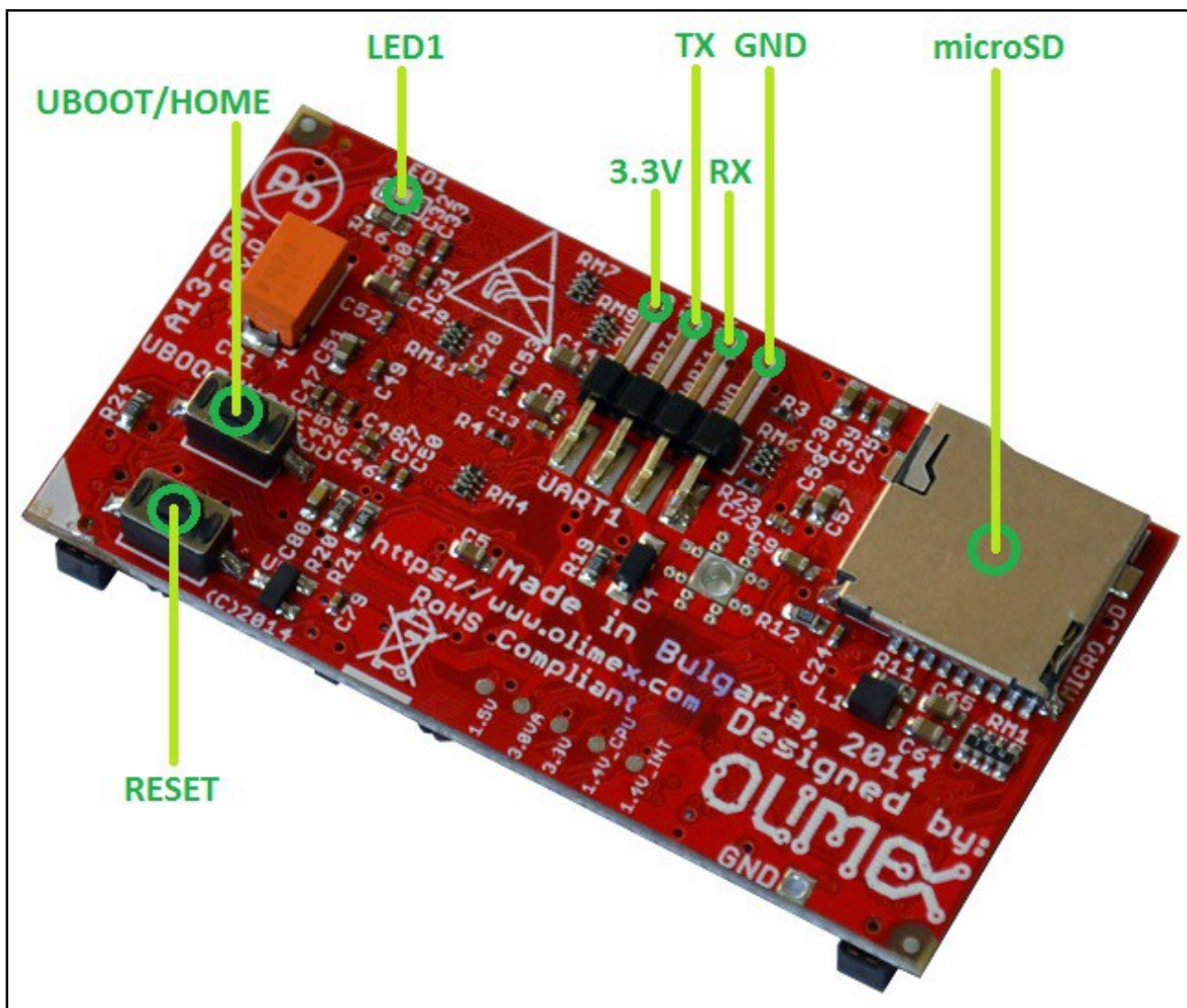
Here you get acquainted with the main parts of the board. Note the names used on the board might differ from the names used below to describe them. For the actual names check the A13-SOM board itself.

3.1 Layout (top view)

The picture below shows the top side of the board and highlights the most important parts:



3.2 Layout (bottom view)



CHAPTER 4: THE ALLWINNER A13 MICROCONTROLLER

4. Introduction to the chapter

In this chapter is located the information about the heart of A13-SOM – its microcontroller. The information is a modified version of the datasheet provided by its manufacturers.

4.1 The processor

The full list of features might be found below:

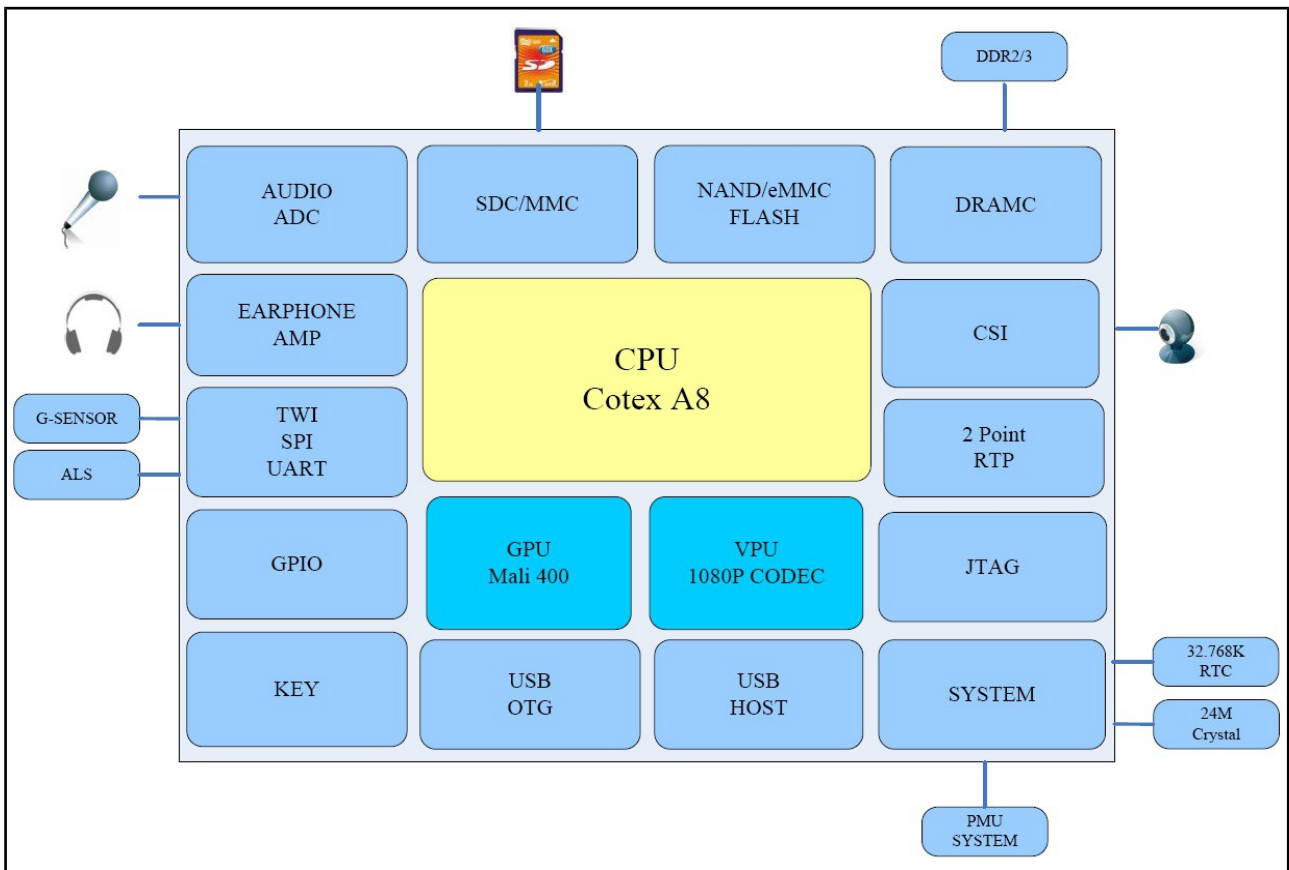
- CPU/GPU
 - ARM Cortex-A8 Core
 - 32KB D-Cache/ 32KB I-Cache
 - 256KB L2 Cache
 - Mali-400 3-D Engine
- VPU
 - HD Video Decoding
 - 1920*1080@30fps
 - Support H.264, H.263, VC1, Mpeg1/2/4
 - Divx 3/4/5/6, Xvid, VP6/8, AVS etc
 - HD Video Encoding
 - Support encoding in H.264 format
 - Up to 1920*1080 at 30fps
- DPU
 - LCD Interfaces: CPU, RGB
- Memory
 - DDR2/DDR3: Up to 533MHz
 - 16 bits Data Bus
 - Memory capacity up to 512MB
 - MLC/TLC/SLC/EF-NAND
 - 2 flash chips, ECC 64-bit
 - Support NAND of 5xnm, 4xnm, 3xnm, 2xnm
 - Support NADN of Samsung, Toshiba, Hynix
- Peripherals
 - USB2.0 OTG, USB2.0 HOST
 - (OHCI/EHCI)
 - SD Card V.3.0, eMMC V.4.2
 - SPI, TWI and UART
 - integrated Audio Codec
 - CSI
- R-TP Controller
 - 4-wire resistive TP interface
 - 2 points and gesture detection
- Boot Devices
 - NAND Flash
 - SPI Nor Flash

- SD Card
- USB
- Powerful Acceleration
 - Graphic (3D, Mali400 MP)
 - VPU (1080P)
 - APU
 - E-Reader
- Ultra-low System Power Consumption
 - Smart Backlight: auto adjust backlight
 - acc. to the image display
- Package
 - eLQFP176

More information can be found on Allwinner's web site at the following web-address:
<http://www.allwinnertech.com/product/A13.html>

4.2 Block diagram

The block diagram is taken from Allwinner's web-site.



CHAPTER 5: CONTROL CIRCUITY

5. Introduction to the chapter

Here you can find information about reset circuit and quartz crystals locations, the power supply circuit is also briefly discussed.

5.1 Reset

The board can be reset by the RST button. The reset circuit includes Microchip's MCP130T-300I, designed to keep a microcontroller in reset until the system voltage has reached the proper level and stabilized.

The board should be turned off either by the standard OS menu or “poweroff” command or any other software shutdown procedure. After the choice is confirmed it is safe to disconnect the power supply unit from the board.

5.2 Clocks

24 MHz quartz crystal Q1 is found at pins 91 (X24MOUT) and 92 (X24MIN) of the A13 processor.

5.3 Power supply circuit

The current consumption for A13-SOM when used separately is around 0.1A when connected to a 3.3V voltage source (provided either at GPIO-1's pin 1 or UART1 3.3V pin).

There are several GND pin and pinhole locations. You can use any of the board's GND for powering purposes.

The typical consumption of the 512 for the board when combined with A13-SOM-WIFI-4GB might be found below:

Setup	Operating system	Typical current consumption, in Amperes, at 5V of voltage
A13-SOM-512 + A13-SOM-WIFI-4GB	Debian	0.45A
A13-SOM-512 + A13-SOM-WIFI-4GB + A13-LCD7-TS	Debian	0.75A
A13-SOM-512 + A13-SOM-WIFI-4GB + A13-LCD7-TS	Android	0.40A

The current consumed usually reaches peaks during start-up when different modules are initialized. Make sure the supply you provide is capable of powering the board. Note that if there are additional modules powered by the board, the total power supply requirement would grow. For example, bigger LCD displays powered via the A13-SOM almost double the current consumption.

For more info on how to power the board refer to chapter “2.3 Powering the board”.

CHAPTER 6: CONNECTORS AND PINOUT

6. Introduction to the chapter

In this chapter are presented the connectors that can be found on the board all together with their pinout and notes about them. Jumpers functions are described. Notes and info on specific peripherals are presented. Notes regarding the interfaces are given.

6.1 Communication with A13-SOM

There is only one way to communicate with A13-SOM without hardware modifications – it is via a serial cable. If A13-SOM-WIFI is also used, you might also interface the setup via a display or via SSH.

The direct communication method is via the serial interface. Through male UART1 connector capable of delivering some information on the COM port of your computer – and then use your favorite terminal program (puTTY, teraterm, etc) to receive the data/send commands. You can use USB-SERIAL-CABLE-F with the UART1 interface allowing you to connect to a personal computer with a free USB port.

Note that the levels at board's UART1 are in CMOS levels (3.3V) and you would need a MAX232 convertor to bring them to TTL ones! This includes the RX and TX line.

It is highly recommended to have an USB-SERIAL-CABLE-F (or similar product) even if you intend to use the board with a monitor or display. Serial cables usually have built-in MAX232 convertor. In case you set wrong display settings you would be able to recover the settings via the UART1 connection.

For more information please refer to chapter “2.5 Interacting with the board”.

6.1.1 UART1 interface

The UART1 interface might be used for serial communication between the board and a personal computer by default. In case of video output problem a cable might provide needed feedback and greatly reduce the efforts needed to repair the board or to adjust the software setting.

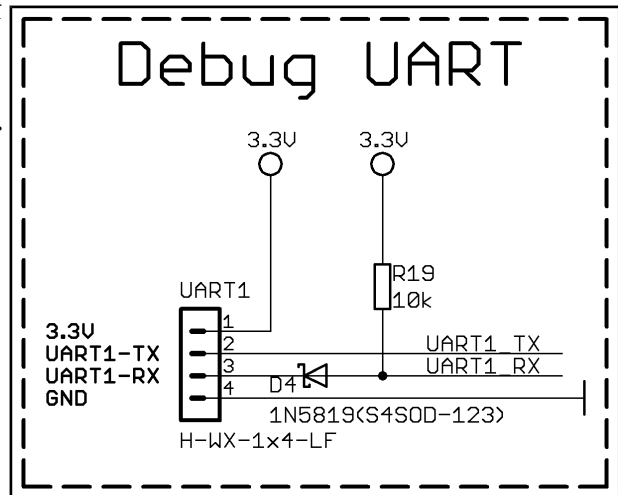
Note that by default only UART1 is defined as a port suitable for serial debug. You can use our USB-SERIAL-CABLE-F for debugging.

Even when A13-SOM is mounted on A13-SOM-WIFI the default debug port remains UART1 (despite that it gets additional pins on the big board also for easier access).

Consider table below when connecting the USB-SERIAL-CABLE-F according to the wire color code. The RX line of the cable (GREEN wire) should go to TX line of the target board; the TX line of the cable (RED wire) should go to the RX line of the target board. The BLUE wire should go to the target's GND line. Make sure to leave free the first pin (named "3.3") when connecting the serial cable.

The table of UART1 signals might be found below:

UART1		
Pin #	Signal name	Processor pin
1	3.3	VCC
2	UART1-TX	A7
3	UART1-RX	B7
4	GND	GND



6.2 MicroSD card connector

The micro SD card slot is primarily used for booting the operating system.

The board works with micro SDHC cards up to 32GB of storage.

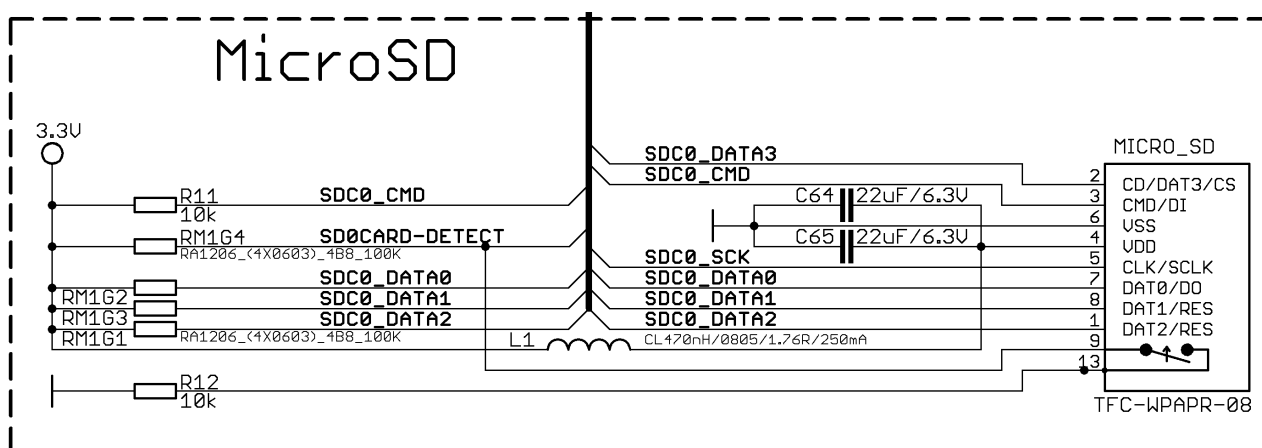
As a general precaution be careful with the SD cards you purchase. There is a big percentage of fake cards due to the low effort required to counterfeit popular brands and the big demand for SD cards worldwide. When in doubt – try the same operation with another card from another brand.

Olimex sells microSD cards prepared with Linux or Android images, that have been tested – please refer to chapter “2.2 Requirements”. Currently these are with either 4GB and 8GB of storage (depending on the purchase date). Of course, if you already have a large enough microSD card you can download the official Linux image from the wiki pages: <https://www.olimex.com/wiki/A13-SOM>.

When removing the card, please make sure that you release it from the connector by pushing and NOT by pulling the card directly (this can damage both the connector and the microSD card).

6.2.1 SD/MMC slot

The schematic related to the SD/MMC (microSD connector) is shown below:



SD/MMC slot is a microSD card slot connector, located on the top of the board.

This slot is typically used for booting the OS, due to the larger capacities of the microSD cards (compared to SD or MMC cards). It is suggested to have an SD card with a proper Linux/Android image especially if you have ordered a version of the board without NAND memory. It is also recommended to use Class 10 (10MByte/sec) card for faster read/write operations, lower class cards (especially higher capacity ones) might slow down the whole system.

The table with the microSD card signals might be found below:

SD/MMC1 connector		
Pin #	Connector signal name	Wire name (processor pin number)
1	DAT2/RES	SDC0_DATA2 (113)
2	CD/DAT3/CS	SDC0_DATA3 (112)
3	CMD/DI	SDC0_CMD (111)
4	VDD	SD_VCC
5	CLK/SCLK	SDC0_SCLK (110)
6	VSS	GND
7	DAT0/DO	SDC0_DATA0 (108)
8	DAT1/RES	SDC0_DATA1 (107)
9	CARD DETECT(SYMBOL)	SD0CARD-DETECT (155)
13	GND	GND

6.3 Power pins for external power supply

There are two power pins suitable for powering the board. These are located on different places of A13-SOM – one at the UART1 connector, the other on GPIO1 connector. To power the board you need to provide 3.3V to one of them. You can use any of the pins or the pinholes named GND.

The required current may vary depending on the peripherals connected to the board. The power supply should be capable of providing at least 0.5A of current.