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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832
Email \& Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, \#122 Zhenhua RD., Futian, Shenzhen, China

LC²MOS 16-Bit Voltage Output DAC

## FEATURES

16-bit monotonicity over temperature
$\pm 2$ LSBs integral linearity error
Microprocessor compatible with readback capability
Unipolar or bipolar output
Multiplying capability
Low power (100 mW typical)

FUNCTIONAL BLOCK DIAGRAM


Figure 1.
to $00 \ldots . .000$ or $10 \ldots 000$ depending on the state of $\mathrm{R} / \overline{\mathrm{W}}$. This means that the DAC output can be reset to 0 V in both the unipolar and bipolar configurations.

The AD7846 is available in 28-lead plastic, ceramic, and PLCC packages.

## PRODUCT HIGHLIGHTS

1. 16-Bit Monotonicity

The guaranteed 16-bit monotonicity over temperature makes the AD7846 ideal for closed-loop applications.
2. Readback

The ability to read back the DAC register contents minimizes software routines when the AD7846 is used in ATE systems.
3. Power Dissipation

Power dissipation of 100 mW makes the AD7846 the lowest power, high accuracy DAC on the market.

## Rev. G

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One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A.

## COMPARABLE PARTS

View a parametric search of comparable parts.

## DOCUMENTATION

## Data Sheet

- AD7846: LC2MOS16-Bit Voltage Output DAC Data Sheet
- AD7846: Military Data Sheet


## REFERENCE MATERIALS

## Solutions Bulletins \& Brochures

- Digital to Analog Converters ICs Solutions Bulletin


## DESIGN RESOURCES

- AD7846 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints


## DISCUSSIONS

View all AD7846 EngineerZone Discussions.
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## TECHNICAL SUPPORT $\square$

Submit a technical question or find your regional support number.

## DOCUMENT FEEDBACK

Submit feedback for this data sheet.

## AD7846

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## SPECIFICATIONS

$\mathrm{V}_{\mathrm{DD}}=+14.25 \mathrm{~V}$ to +15.75 V ; $\mathrm{V}_{\mathrm{SS}}=-14.25 \mathrm{~V}$ to $-15.75 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}}=+4.75 \mathrm{~V}$ to +5.25 V . Vout loaded with $2 \mathrm{k} \Omega, 1000 \mathrm{pF}$ to 0 V ; $\mathrm{V}_{\mathrm{REF}}=+5 \mathrm{~V}$; $\mathrm{R}_{\text {IN }}$ connected to 0 V . All specifications $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$, unless otherwise noted.

Table 1.

| Parameter ${ }^{1}$ | J, A Versions | K, B Versions | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: |
| RESOLUTION | 16 | 16 | Bits |  |
| UNIPOLAR OUTPUT <br> Relative Accuracy at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Differential Nonlinearity Error <br> Gain Error at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Offset Error at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Gain $\mathrm{TC}^{2}$ <br> Offset TC ${ }^{2}$ | $\begin{aligned} & \pm 12 \\ & \pm 16 \\ & \pm 1 \\ & \pm 12 \\ & \pm 16 \\ & \pm 12 \\ & \pm 16 \\ & \pm 1 \\ & \pm 1 \end{aligned}$ | $\begin{aligned} & \pm 4 \\ & \pm 8 \\ & \pm 0.5 \\ & \pm 6 \\ & \pm 16 \\ & \pm 6 \\ & \pm 16 \\ & \pm 1 \\ & \pm 1 \end{aligned}$ | LSB typ <br> LSB max <br> LSB max <br> LSB typ <br> LSB max <br> LSB typ <br> LSB max <br> ppm FSR/ ${ }^{\circ} \mathrm{C}$ typ <br> ppm FSR $/{ }^{\circ} \mathrm{C}$ typ | $\begin{aligned} & \mathrm{V}_{\text {REF- }}=0 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=0 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ & 1 \mathrm{LSB}=153 \mu \mathrm{~V} \end{aligned}$ <br> All grades guaranteed monotonic $\text { Vout load }=10 \mathrm{M} \Omega$ |
| BIPOLAR OUTPUT <br> Relative Accuracy at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Differential Nonlinearity Error <br> Gain Error at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Offset Error at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ <br> Bipolar Zero Error at $+25^{\circ} \mathrm{C}$ <br> $\mathrm{T}_{\text {Min }}$ to $\mathrm{T}_{\text {Max }}$ <br> Gain $\mathrm{TC}^{2}$ <br> Offset TC ${ }^{2}$ <br> Bipolar Zero TC² | $\begin{aligned} & \pm 6 \\ & \pm 8 \\ & \pm 1 \\ & \pm 6 \\ & \pm 16 \\ & \pm 6 \\ & \pm 16 \\ & \pm 6 \\ & \pm 12 \\ & \pm 1 \\ & \pm 1 \\ & \pm 1 \end{aligned}$ | $\begin{aligned} & \pm 2 \\ & \pm 4 \\ & \pm 0.5 \\ & \pm 4 \\ & \pm 16 \\ & \pm 4 \\ & \pm 12 \\ & \pm 4 \\ & \pm 8 \\ & \pm 1 \\ & \pm 1 \\ & \pm 1 \end{aligned}$ | LSB typ <br> LSB max <br> LSB max <br> LSB typ <br> LSB max <br> LSB typ <br> LSB max <br> LSB typ <br> LSB max <br> ppm FSR/ ${ }^{\circ}$ Ctyp <br> ppm FSR/ ${ }^{\circ}$ Ctyp <br> ppm FSR/ ${ }^{\circ}$ Ctyp | $\begin{aligned} & \mathrm{V}_{\text {REF- }}=-5 \mathrm{~V}, \mathrm{~V}_{\text {out }}=-10 \mathrm{~V} \text { to }+10 \mathrm{~V} \\ & 1 \mathrm{LSB}=305 \mu \mathrm{~V} \end{aligned}$ <br> All grades guaranteed monotonic <br> Vout load $=10 \mathrm{M} \Omega$ $\text { Vout load }=10 \mathrm{M} \Omega$ |
| REFERENCE INPUT Input Resistance $V_{\text {REF }}$ Range $V_{\text {REF- }}$ Range | $\begin{aligned} & 20 \\ & 40 \\ & V_{S S}+6 \text { to } \\ & V_{D D}-6 \\ & V_{S S}+6 \text { to } \\ & V_{D D}-6 \\ & \hline \end{aligned}$ | $\begin{aligned} & 20 \\ & 40 \\ & V_{S S}+6 \text { to } \\ & V_{D D}-6 \\ & V_{S S}+6 \text { to } \\ & V_{D D}-6 \\ & \hline \end{aligned}$ |  | Resistance from $\mathrm{V}_{\text {REF }}$ to $\mathrm{V}_{\text {REF- }}$ Typically $30 \mathrm{k} \Omega$ |
| OUTPUT CHARACTERISTICS <br> Output Voltage Swing <br> Resistive Load Capacitive Load Output Resistance Short Circuit Current | $\begin{aligned} & V_{S S}+4 \text { to } \\ & V_{D D}-3 \\ & 2 \\ & 1000 \\ & 0.3 \\ & \pm 25 \end{aligned}$ | $\begin{aligned} & \mathrm{V}_{S S}+4 \text { to } \\ & \mathrm{V}_{\mathrm{DD}}-3 \\ & 2 \\ & 1000 \\ & 0.3 \\ & \pm 25 \end{aligned}$ | V max <br> $k \Omega$ min pF max $\Omega$ typ mA typ | To 0 V <br> To 0 V <br> To 0 V or any power supply |
| DIGITAL INPUTS <br> $\mathrm{V}_{\text {IH }}$ (Input High Voltage) <br> VIL (Input Low Voltage) <br> $I_{\text {IN }}$ (Input Current) <br> $\mathrm{C}_{\mathrm{IN}}\left(\right.$ Input Capacitance) ${ }^{2}$ | $\begin{aligned} & 2.4 \\ & 0.8 \\ & \pm 10 \\ & 10 \end{aligned}$ | $\begin{aligned} & 2.4 \\ & 0.8 \\ & \pm 10 \\ & 10 \end{aligned}$ | $\checkmark$ min <br> V max <br> $\mu \mathrm{A}$ max <br> pF max |  |

## AD7846

| Parameter ${ }^{1}$ | J, A Versions | K, B Versions | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: |
| DIGITAL OUTPUTS |  |  |  |  |
| VoL (Output Low Voltage) | 0.4 | 0.4 | $\checkmark$ max | $\mathrm{I}_{\text {SINK }}=1.6 \mathrm{~mA}$ |
| $\mathrm{V}_{\text {он }}$ (Output High Voltage) | 4.0 | 4.0 | $V$ min | $\mathrm{I}_{\text {SOURCE }}=400 \mu \mathrm{~A}$ |
| Floating State Leakage Current | $\pm 10$ | $\pm 10$ | $\mu \mathrm{A}$ max | DB0 to DB15 $=0$ to $\mathrm{V}_{\text {cc }}$ |
| Floating State Output Capacitance ${ }^{2}$ | 10 | 10 | pF max |  |
| POWER REQUIREMENTS ${ }^{3}$ |  |  |  |  |
| $V_{\text {DD }}$ | +11.4/+15.75 | +11.4/+15.75 | $\checkmark$ min/V max |  |
| Vss | -11.4/-15.75 | -11.4/-15.75 | $V$ min/V max |  |
| Vcc | +4.75/+5.25 | +4.75/+5.25 | $\checkmark$ min/V max |  |
| ldo | 5 | 5 | mA max | Vout unloaded |
| Iss | 5 | 5 | mA max | Vout unloaded |
| Icc | 1 | 1 | mA max |  |
| Power Supply Sensitivity ${ }^{4}$ | 1.5 | 1.5 | LSB/V max |  |
| Power Dissipation | 100 | 100 | mW typ | Vout unloaded |

${ }^{1}$ Temperature ranges as follows: J, K versions: $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$; A, B versions: $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.
${ }^{2}$ Guaranteed by design and characterization, not production tested.
${ }^{3}$ The AD7846 is functional with power supplies of $\pm 12 \mathrm{~V}$. See the Typical Performance Characteristics section.
${ }^{4}$ Sensitivity of gain error, offset error, and bipolar zero error to $\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{S S}$ variations.

## AC PERFORMANCE CHARACTERISTICS

These characteristics are included for design guidance and are not subject to test. $\mathrm{V}_{\text {REF }+}=+5 \mathrm{~V}$; $\mathrm{V}_{\mathrm{DD}}=+14.25 \mathrm{~V}$ to $+15.75 \mathrm{~V} ; \mathrm{V}_{\mathrm{SS}}=-14.25 \mathrm{~V}$ to $-15.75 \mathrm{~V} ; \mathrm{V}_{\mathrm{CC}}=+4.75 \mathrm{~V}$ to +5.25 V ; $\mathrm{R}_{\mathrm{IN}}$ connected to 0 V , unless otherwise noted.

Table 2.

| Parameter | Limit at $\mathrm{T}_{\text {min }}$ to $\mathrm{T}_{\text {max }}$ (All Versions) | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: |
| Output Settling Time ${ }^{1}$ | 6 | $\mu \mathrm{s}$ max | To 0.006\% FSR, Vout loaded, $\mathrm{V}_{\text {REF- }}=0 \mathrm{~V}$, typically $3.5 \mu \mathrm{~S}$ |
|  | 9 | $\mu \mathrm{s}$ max | To $0.003 \%$ FSR, Vout loaded, $\mathrm{V}_{\text {REF }-}=-5 \mathrm{~V}$, typically $6.5 \mu \mathrm{~s}$ |
| Slew Rate | 7 | V/ $\mu \mathrm{s}$ typ |  |
| Digital-to-Analog Glitch |  |  |  |
| Impulse | 70 | nV-sec typ | DAC alternately loaded with $10 . . .0000$ and $01 . . .1111$, Vout unloaded |
| AC Feedthrough | 0.5 | mV p-p typ | $\mathrm{V}_{\text {REF- }}=0 \mathrm{~V}, \mathrm{~V}_{\text {REF }+}=1 \mathrm{Vrms}, 10 \mathrm{kHz}$ sine wave, DAC loaded with all Os |
| Digital Feedthrough | 10 | nV-sec typ | DAC alternately loaded with all 1 s and all $0 \mathrm{~s} . \overline{\mathrm{CS}}$ high |
| Output Noise Voltage Density, 1 kHz to 100 kHz | 50 | $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ typ | Measured at $V_{\text {out, }}$ DAC loaded with $0111011 \ldots 11$, $\mathrm{V}_{\mathrm{REF}+}=\mathrm{V}_{\text {REF- }}=0 \mathrm{~V}$ |

${ }^{1} \overline{\mathrm{LDAC}}=0$. Settling time does not include deglitching time of $2.5 \mu \mathrm{~s}$ (typ).

## TIMING CHARACTERISTICS

$\mathrm{V}_{\mathrm{DD}}=+14.25 \mathrm{~V}$ to $+15.75 \mathrm{~V}, \mathrm{~V}_{\mathrm{SS}}=-14.25 \mathrm{~V}$ to $-15.75 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}=+4.75 \mathrm{~V}$ to +5.25 V , unless otherwise noted.
Table 3.

| Parameter ${ }^{1}$ | Limit at $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ (All Versions) | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: |
| $\mathrm{t}_{1}$ | 0 | ns min | R/W to $\overline{\mathrm{CS}}$ setup time |
| $\mathrm{t}_{2}$ | 60 | ns min | $\overline{\mathrm{CS}}$ pulse width (write cycle) |
| $\mathrm{t}_{3}$ | 0 | ns min | $R / \bar{W}$ to $\overline{C S}$ hold time |
| $\mathrm{t}_{4}$ | 60 | ns min | Data setup time |
| $\mathrm{t}_{5}$ | 0 | ns min | Data hold time |
| $\mathrm{t}_{6}{ }^{2}$ | 120 | ns max | Data access time |
| $\mathrm{t}_{7}{ }^{3}$ | 10 | ns min | Bus relinquish time |
|  | 60 | ns max |  |
| $\mathrm{t}_{8}$ | 0 | ns min | $\overline{\mathrm{CLR}}$ setup time |
| $\mathrm{t}_{9}$ | 70 | ns min | $\overline{\mathrm{CLR}}$ pulse width |
| $\mathrm{t}_{10}$ | 0 | ns min | $\overline{\mathrm{CLR}}$ hold time |
| $\mathrm{t}_{11}$ | 70 | ns min | $\overline{\text { LDAC }}$ pulse width |
| $\mathrm{t}_{12}$ | 130 | ns min | $\overline{\text { CS }}$ pulse width (read cycle) |

${ }^{1}$ Timing specifications are sample tested at $+25^{\circ} \mathrm{C}$ to ensure compliance. All input control signals are specified with $\mathrm{t}_{\mathrm{R}}=\mathrm{t}_{\mathrm{F}}=5 \mathrm{~ns}(10 \%$ to $90 \%$ of $+5 \mathrm{~V})$ and timed from a voltage level of 1.6 V .
${ }^{2} \mathrm{t}_{6}$ is measured with the load circuits of Figure 3 and Figure 4 and defined as the time required for an output to cross 0.8 V or 2.4 V .
${ }^{3} \mathrm{t}_{7}$ is defined as the time required for an output to change 0.5 V when loaded with the circuits of Figure 5 and Figure 6.


Figure 2. Timing Diagram


Figure 3. Load Circuit for Access Time ( $t_{6}$ )_High Z to $\mathrm{VOH}_{\mathrm{OH}}$


Figure 4. Load Circuits for Bus Relinquish Time ( $t_{6}$ ) _High Z to Vol


Figure 5. Load Circuit for Access Time ( $t_{7}$ )—High Z to $\mathrm{VOH}_{\mathrm{OH}}$


Figure 6. Load Circuits for Bus Relinquish Time ( $t_{7}$ ) —High Z to $V_{O L}$

## AD7846

## ABSOLUTE MAXIMUM RATINGS

Table 4.

| Parameter | Rating |
| :---: | :---: |
| $V_{\text {DD }}$ to DGND | -0.4 V to +17 V |
| $V_{\text {cc }}$ to DGND | $-0.4 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD}}+0.4 \mathrm{~V}, \text { or }+7 \mathrm{~V}$ <br> (whichever is lower) |
| $\mathrm{V}_{5 s}$ to DGND | +0.4 V to -17 V |
| $V_{\text {REF }}$ to DGND | $\mathrm{V}_{\mathrm{DD}}+0.4 \mathrm{~V}, \mathrm{~V}_{S S}-0.4 \mathrm{~V}$ |
| $V_{\text {Ref- }}$ to DGND | $\mathrm{V}_{\text {DD }}+0.4 \mathrm{~V}, \mathrm{~V}_{S S}-0.4 \mathrm{~V}$ |
| Vout to DGND ${ }^{1}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{DD}}+0.4 \mathrm{~V}, \mathrm{~V}_{\mathrm{SS}}-0.4 \mathrm{~V} \text {, or } \pm 10 \mathrm{~V} \\ & \text { (whichever is lower) } \end{aligned}$ |
| Rin to DGND | $\mathrm{V}_{\mathrm{DD}}+0.4 \mathrm{~V}, \mathrm{~V}_{S S}-0.4 \mathrm{~V}$ |
| Digital Input Voltage to DGND | -0.4 V to $\mathrm{V}_{\text {cc }}+0.4 \mathrm{~V}$ |
| Digital Output Voltage to DGND | -0.4 V to $\mathrm{V}_{\text {cc }}+0.4 \mathrm{~V}$ |
| Power Dissipation (Any Package) |  |
| To $+75^{\circ} \mathrm{C}$ | 1000 mW |
| Derates above $+75^{\circ} \mathrm{C}$ | $10 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ |
| Operating Temperature Range |  |
| J, K Versions | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| A, B Versions | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering) | $+300^{\circ} \mathrm{C}$ |

[^0]Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



Figure 7. PDIP Pin Configuration


Figure 8. CERDIP Pin Configuration

Table 5. Pin Function Descriptions

| Pin | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 to 3 | DB2 to DB0 | Data I/Os. DB0 is LSB. |
| 4 | $V_{\text {DD }}$ | Positive Supply for Analog Circuitry. This is +15 V nominal. |
| 5 | Vout | DAC Output Voltage. |
| 6 | Rin | Input to Summing Resistor of DAC Output Amplifier. This is used to select output voltage ranges. See Table 6. |
| 7 | $\mathrm{V}_{\text {REF+ }}$ | $\mathrm{V}_{\text {REF }}$ Input. The DAC is specified for $\mathrm{V}_{\text {REF }+}=+5 \mathrm{~V}$. |
| 8 | $\mathrm{V}_{\text {REF- }}$ | $\mathrm{V}_{\text {REF- }}$ Input. For unipolar operation connect $\mathrm{V}_{\text {REF- }}$ to 0 V , and for bipolar operation connect it to -5 V . The device is specified for both conditions. |
| 9 | $V_{\text {ss }}$ | Negative Supply for the Analog Circuitry. This is -15 V nominal. |
| 10 to 19 | DB15 to DB6 | Data I/Os. DB15 is MSB. |
| 20 | DGND | Ground for Digital Circuitry. |
| 21 | $V_{\text {cc }}$ | Positive Supply for Digital Circuitry. This is +5 V nominal. |
| 22 | R/ $\bar{W}$ | $\mathrm{R} / \overline{\mathrm{W}}$ Input. This pin can be used to load data to the DAC or to read back the DAC latch contents. |
| 23 | $\overline{C S}$ | Chip Select Input. This pin selects the device. |
| 24 | $\overline{\mathrm{CLR}}$ | Clear Input. The DAC can be cleared to 000... 000 or $100 \ldots 000$. See Table 7. |
| 25 | $\overline{\text { LDAC }}$ | Asynchronous Load Input to DAC. |
| 26 to 28 | DB5 to DB3 | Data I/Os. |

Table 6. Output Voltage Ranges

| Output Range | $\mathbf{V}_{\text {REF }}$ | $\mathbf{V}_{\text {REF- }}$ | R $_{\text {IN }}$ |
| :--- | :--- | :--- | :--- |
| 0 V to +5 V | +5 V | 0 V | V out |
| 0 V to +10 V | +5 V | 0 V | 0 V |
| +5 V to -5 V | +5 V | -5 V | $\mathrm{~V}_{\text {out }}$ |
| +5 V to -5 V | +5 V | 0 V | +5 V |
| +10 V to -10 V | +5 V | -5 V | 0 V |

## AD7846

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 9. AC Feedthrough, $V_{\text {REF }+}=1 \mathrm{Vrms}, 10 \mathrm{kHz}$ Sine Wave


Figure 10. AC Feedthrough to Vout vs. Frequency


Figure 11. Large Signal Frequency Response


Figure 12. Noise Spectral Density


Figure 13. Digital-to-Analog Glitch Impulse Without Internal Deglitcher (10... 000 to 011... 111 Transition)


Figure 14. Digital-to-Analog Glitch Impulse with Internal Deglitcher (10... 000 to 011... 111 Transition)


Figure 15. Pulse Response (Large Signal)


Figure 16. Pulse Response (Small Signal)


[^1]

Figure 18. Typical Integral Nonlinearity vs. $V_{D D} V_{S S}$


Figure 19. Typical Differential Nonlinearity vs. $V_{D D} / V_{S S}$

## AD7846

## TERMINOLOGY

## Least Significant Bit

This is the analog weighting of 1 bit of the digital word in a DAC. For the AD7846, $1 \mathrm{LSB}=\left(\mathrm{V}_{\text {Ref+ }}-\mathrm{V}_{\text {Ref- }}\right) / 2^{16}$.

## Relative Accuracy

Relative accuracy or endpoint nonlinearity is a measure of the maximum deviation from a straight line passing through the endpoints of the DAC transfer function. It is measured after adjusting for both endpoints (that is, offset and gain errors are adjusted out) and is normally expressed in least significant bits or as a percentage of full-scale range.

## Differential Nonlinearity

Differential nonlinearity is the difference between the measured change and the ideal change between any two adjacent codes. A specified differential nonlinearity of $\pm 1$ LSB over the operating temperature range ensures monotonicity.

## Gain Error

Gain error is a measure of the output error between an ideal DAC and the actual device output with all 1 s loaded after offset error has been adjusted out. Gain error is adjustable to zero with an external potentiometer.

## Offset Error

This is the error present at the device output with all 0s loaded in the DAC. It is due to op amp input offset voltage and bias current and the DAC leakage current.

## Bipolar Zero Error

When the AD7846 is connected for bipolar output and $10 \ldots 000$ is loaded to the DAC, the deviation of the analog output from the ideal midscale of 0 V is called the bipolar zero error.

Digital-to-Analog Glitch Impulse
This is the amount of charge injected from the digital inputs to the analog output when the inputs change state. This is normally specified as the area of the glitch in either pA-sec or nV-sec depending upon whether the glitch is measured as a current or a voltage.

## Multiplying Feedthrough Error

This is an ac error due to capacitive feedthrough from either of the $\mathrm{V}_{\text {ref }}$ terminals to $\mathrm{V}_{\text {out }}$ when the DAC is loaded with all 0 s.

## Digital Feedthrough

When the DAC is not selected (that is, $\overline{\mathrm{CS}}$ is held high), high frequency logic activity on the digital inputs is capacitively coupled through the device to show up as noise on the Vout pin. This noise is digital feedthrough.

## CIRCUIT DESCRIPTION <br> DIGITAL SECTION

Figure 20 shows the digital control logic and on-chip data latches in the AD7846. Table 7 is the associated truth table. The digital-to-analog converter (DAC) has two latches that are controlled by four signals: $\overline{\mathrm{CS}}, \mathrm{R} / \overline{\mathrm{W}}, \overline{\mathrm{LDAC}}$, and $\overline{\mathrm{CLR}}$. The input latch is connected to the data bus (DB15 to DB0). A word is written to the input latch by bringing $\overline{\mathrm{CS}}$ low and $\mathrm{R} / \overline{\mathrm{W}}$ low. The contents of the input latch can be read back by bringing $\overline{\mathrm{CS}}$ low and $\mathrm{R} / \overline{\mathrm{W}}$ high. This feature is called readback and is used in system diagnostic and calibration routines.
Data is transferred from the input latch to the DAC latch with the $\overline{\mathrm{LDAC}}$ strobe. The equivalent analog value of the DAC latch contents appears at the DAC output. The $\overline{\mathrm{CLR}}$ pin resets the DAC latch contents to $000 \ldots 000$ or $100 \ldots 000$, depending on the state of $\mathrm{R} / \overline{\mathrm{W}}$. Writing a $\overline{\mathrm{CLR}}$ loads $000 \ldots 000$ and reading a $\overline{\mathrm{CLR}}$ loads 100...000. To reset a DAC to 0 V in a unipolar system, the user should assert $\overline{\mathrm{CLR}}$ while $\mathrm{R} / \overline{\mathrm{W}}$ is low; to reset to 0 V in a bipolar system, assert the $\overline{\mathrm{CLR}}$ while $\mathrm{R} / \overline{\mathrm{W}}$ is high.


Figure 20. Input Control Logic

Table 7. Control Logic Truth Table

| $\overline{\mathbf{C S}}$ | $\mathbf{R} / \overline{\mathbf{W}}$ | $\overline{\mathbf{L D A C}}$ | $\overline{\mathbf{C L R}}$ | Function |
| :--- | :--- | :--- | :--- | :--- |
| 1 | X | X | X | 3-state DAC I/O latch in high-Z state |
| 0 | 0 | X | X | DAC I/O latch loaded with DB15 <br> to DB0 |
| 0 | 1 | X | X | Contents of DAC I/O latch available <br> on DB15 to DB0 |
| X | X | 0 | 1 | Contents of DAC I/O latch transferred <br> to DAC latch |
| X | 0 | X | 0 | DAC latch loaded with 000...000 <br> X 1 |
| X | 0 | DAC latch loaded with 100...000 |  |  |

## DIGITAL-TO-ANALOG CONVERSION

Figure 21 shows the digital-to-analog section of the AD7846. There are three DACs, each of which has its own buffer amplifiers. DAC1 and DAC2 are 4-bit DACs. They share a 16 -resistor string but have their own analog multiplexers. The voltage reference is applied to the resistor string. DAC3 is a 12-bit voltage mode DAC with its own output stage.

The four MSBs of the 16-bit digital code drive DAC1 and DAC2, and the 12 LSBs control DAC3. Using DAC1 and DAC2, the MSBs select a pair of adjacent nodes on the resistor string and present that voltage to the positive and negative inputs of DAC3. This DAC interpolates between these two voltages to produce the analog output voltage.
To prevent nonmonotonicity in the DAC due to amplifier offset voltages, DAC1 and DAC2 leap along the resistor string. For example, when switching from Segment 1 to Segment 2, DAC1 switches from the bottom of Segment 1 to the top of Segment 2 while DAC2 stays connected to the top of Segment 1 . The code driving DAC3 is automatically complemented to compensate for the inversion of its inputs. This means that any linearity effects due to amplifier offset voltages remain unchanged when switching from one segment to the next and 16-bit monotonicity is ensured if DAC3 is monotonic. Thus, 12-bit resistor matching in DAC3 guarantees overall 16-bit monotonicity. This is much more achievable than 16-bit matching, which a conventional R-2R structure needs.


Figure 21. Digital-to-Analog Conversion

## OUTPUT STAGE

The output stage of the AD7846 is shown in Figure 22. It is capable of driving a $2 \mathrm{k} \Omega / 1000 \mathrm{pF}$ load. It also has a resistor feedback network that allows the user to configure it for gains of 1 or 2 . Table 6 shows the different output ranges that are possible.
An additional feature is that the output buffer is configured as a track-and-hold amplifier. Although normally tracking its input, this amplifier is placed in a hold mode for approximately $2.5 \mu \mathrm{~s}$ after the leading edge of $\overline{\mathrm{LDAC}}$. This short state keeps the DAC output at its previous voltage while the AD7846 is internally changing to its new value. Thus, any glitches that occur in the transition are not seen at the output. In systems where the $\overline{\text { LDAC }}$ is tied permanently low, the deglitching is not in
operation. Figure 13 and Figure 14 show the outputs of the AD7846 without and with the deglitcher.


Figure 22. Output Stage

## UNIPOLAR BINARY OPERATION

Figure 23 shows the AD7846 in the unipolar binary circuit configuration. The DAC is driven by the AD586 +5 V reference. Because $\mathrm{R}_{\mathrm{IN}}$ is tied to 0 V , the output amplifier has a gain of 2 and the output range is 0 V to +10 V . If a 0 V to +5 V range is required, $\mathrm{R}_{\text {IN }}$ should be tied to $\mathrm{V}_{\text {out }}$, configuring the output stage for a gain of 1 . Table 8 gives the code table for the circuit of Figure 23.


Table 8. Code Table for Figure 23

| Binary Number in DAC Latch | LSB ${ }^{1}$ |  |
| :--- | :--- | :---: |
| Analog Output (Vout) |  |  |
| MSB | $+10(65,535 / 65,536) \mathrm{V}$ |  |
| 1111111111111111 | $+10(32,768 / 65,536) \mathrm{V}$ |  |
| 1000000000000000 | $+10(1 / 65,536) \mathrm{V}$ |  |
| 0000000000000001 | 0 V |  |
| 0000000000000000 | ${ }^{1} \mathrm{LSB}=10 \mathrm{~V} / 2^{16}=10 \mathrm{~V} / 65,536=152 \mu \mathrm{~V}$ |  |

Offset and gain can be adjusted in Figure 23 as follows:

- To adjust offset, disconnect the $\mathrm{V}_{\text {ref- }}$ input from 0 V , load the DAC with all 0 s , and adjust the $\mathrm{V}_{\text {ref- }}$ voltage until Vout $=0 \mathrm{~V}$.
- For gain adjustment, the AD7846 should be loaded with all 1 s and R 1 adjusted until $\mathrm{V}_{\text {out }}=10(65,535) /(65,536)=$ 9.999847 V . If a simple resistor divider is used to vary the $\mathrm{V}_{\text {REF- }}$ voltage, it is important that the temperature coefficients of these resistors match that of the DAC input resistance ( $-300 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ ). Otherwise, extra offset errors are introduced over temperature. Many circuits do not require these offset and gain adjustments. In these circuits, R1 can be omitted. Pin 5 of the AD586 can be left open circuit and Pin 8 (VRef-) of the AD7846 tied to 0 V .


## AD7846

## BIPOLAR OPERATION

Figure 24 shows the AD7846 set up for $\pm 10 \mathrm{~V}$ bipolar operation. The AD588 provides precision $\pm 5 \mathrm{~V}$ tracking outputs that are fed to the $V_{\text {ref+ }}$ and $V_{\text {Ref- }}$ inputs of the AD7846. The code table for Figure 24 is shown in Table 9.

*ADDITIONAL PINS OMITTED FOR CLARITY
Figure 24. Bipolar $\pm 10$ V Operation
Table 9. Offset Binary Code Table for Figure 24

| Binary Number in DAC Latch |  |
| :--- | :--- |
| MSB LSB $^{1}$ | Analog Output (Vout) |
| 1111111111111111 |  |
| 1000000000000001 | $+10(1 / 32,768) \mathrm{V}$ |
| 1000000000000000 | 0 V |
| 0111111111111111 | $-10(1 / 32,768) \mathrm{V}$ |
| 0000000000000000 | $-10(32,768 / 32,768) \mathrm{V}$ |

${ }^{1} \mathrm{LSB}=10 \mathrm{~V} / 2^{15}=10 \mathrm{~V} / 32,768=305 \mu \mathrm{~V}$.

Full-scale and bipolar zero adjustment are provided by varying the gain and balance on the AD588. R2 varies the gain on the AD588 while R3 adjusts the +5 V and -5 V outputs together with respect to ground.
For bipolar zero adjustment on the AD7846, load the DAC with $100 \ldots 000$ and adjust R3 until Vout $=0 \mathrm{~V}$. Full scale is adjusted by loading the DAC with all 1 s and adjusting R 2 until $\mathrm{V}_{\text {out }}=$ 9.999694 V .

When bipolar zero and full-scale adjustment are not needed, R2 and R3 can be omitted, Pin 12 on the AD588 should be connected to Pin 11, and Pin 5 should be left floating. If a user wants a 5 V output range, there are two choices. By tying Pin 6 ( $\mathrm{R}_{\text {IN }}$ ) of the AD7846 to Vout (Pin 5), the output stage gain is reduced to unity and the output range is $\pm 5 \mathrm{~V}$. If only a positive 5 V reference is available, bipolar $\pm 5 \mathrm{~V}$ operation is still possible. Tie $\mathrm{V}_{\text {Ref- }}$ to 0 V and connect $\mathrm{R}_{\text {IN }}$ to $\mathrm{V}_{\text {Ref+. }}$. This also gives a $\pm 5 \mathrm{~V}$ output range. However, the linearity, gain, and offset error specifications are the same as the unipolar 0 V to 5 V range.

## MULTIPLYING OPERATION

The AD7846 is a full multiplying DAC. To obtain four-quadrant multiplication, tie $\mathrm{V}_{\text {Ref- }}$ to 0 V , apply the ac input to $\mathrm{V}_{\text {REF }}$, and tie $\mathrm{R}_{\mathrm{IN}}$ to $\mathrm{V}_{\mathrm{REF}+.}$. Figure 11 shows the large signal frequency response when the DAC is used in this fashion.

## POSITION MEASUREMENT APPLICATION

Figure 25 shows the AD7846 in a position measurement application using an linear variable displacement transducer (LVDT), an AD630 synchronous demodulator and a comparator to make a 16-bit LVDT-to-digital converter. The LVDT is excited with a fixed frequency and fixed amplitude sine wave (usually 2.5 kHz , 2 V p-p). The outputs of the secondary coil are in antiphase and their relative amplitudes depend on the position of the core in the LVDT. The AD7846 output interpolates between these two inputs in response to the DAC input code. The AD630 is set up so that it rectifies the DAC output signal. Thus, if the output of the DAC is in phase with the $V_{\text {REF+ }}$ input, the inverting input to the comparator is positive, and if it is in phase with $V_{\text {REF-, }}$, the output is negative. By turning on each bit of the DAC in succession starting with the MSB and deciding to leave it on or turn it off based on the comparator output, a 16-bit measurement of the core position is obtained.

*ADDITIONAL PINS OMITTED FOR CLARITY
Figure 25. AD7846 in Position Measurement Application

## MICROPROCESSOR INTERFACING

## AD7846-TO-8086 INTERFACE

Figure 26 shows the 8086 16-bit processor interfacing to the AD7846. The double buffering feature of the DAC is not used in this circuit because $\overline{\mathrm{LDAC}}$ is permanently tied to 0 V . AD0 to AD15 (the 16-bit data bus) are connected to the DAC data bus (DB0 to DB15). The 16-bit word is written to the DAC in one MOV instruction and the analog output responds immediately. In this example, the DAC address is $0 \times \mathrm{xD} 000$.


Figure 26. AD7846-to-8086 Interface Circuit
In a multiple DAC system, the double buffering of the AD7846 allows the user to simultaneously update all DACs. In Figure 27, a 16 -bit word is loaded to the input latches of each of the DACs in sequence. Then, with one instruction to the appropriate address, $\overline{\mathrm{CS} 4}$ (that is, $\overline{\mathrm{LDAC}}$ ) is brought low, updating all the DACs simultaneously.


## AD7846-TO-MC68000 INTERFACE

Interfacing between the AD7846 and MC68000 is accomplished using the circuit of Figure 28. The following routine writes data to the DAC latches and then outputs the data via the DAC latch.

```
1000 MOVE.W #W, The desired DAC data,
DO W, is loaded into
    Data Register 0. W
    may be any value
    between 0 and 65535
    (decimal) or 0 and
    FFFF (hexadecimal).
MOVE.W DO, The data, W, is
        $E000 transferred between
    DO and the DAC
    register.
MOVE.W #228, Control is returned
TRAP D7 to the System Monitor
            #14 using these two
                            instructions.
```



Figure 28. AD7846-to-MC68000 Interface

Figure 27. AD7846-to-8086 Interface: Multiple DAC System

## DIGITAL FEEDTHROUGH

In the preceding interface configurations, most digital inputs to the AD7846 are directly connected to the microprocessor bus.
Even when the device is not selected, these inputs are constantly changing. The high frequency logic activity on the bus can feed through the DAC package capacitance to show up as noise on the analog output. To minimize this digital feedthrough, isolate
the DAC from the noise source. Figure 29 shows an interface circuit that isolates the DAC from the bus.

Note that to make use of the AD7846 readback feature using the isolation technique of Figure 29, the latch needs to be bidirectional.


Figure 29. AD7846 Interface Circuit Using Latches to Minimize Digital Feedthrough

## AD7846

## APPLICATION HINTS

## NOISE

In high resolution systems, noise is often the limiting factor. With a 10 V span, a 16 -bit LSB is $152 \mu \mathrm{~V}(-96 \mathrm{~dB})$. Thus, the noise floor must stay below -96 dB in the frequency range of interest. Figure 12 shows the noise spectral density for the AD7846.

## GROUNDING

As well as noise, the other prime consideration in high resolution DAC systems is grounding. With an LSB size of $152 \mu \mathrm{~V}$ and a load current of $5 \mathrm{~mA}, 1 \mathrm{LSB}$ of error can be introduced by series resistance of only $0.03 \Omega$.
Figure 30 shows recommended grounding for the AD7846 in a typical application.

*ADIITIONAL PINS OMITTED FOR CLARITY

R1 to R5 represent lead and track resistances on the printed circuit board. R1 is the resistance between the analog power supply ground and the signal ground. Because current flowing in R1 is very low (bias current of AD588 sense amplifier), the effect of R1 is negligible. R2 and R3 represent track resistance between the AD588 outputs and the AD7846 reference inputs. Because of the force and sense outputs on the AD588, these resistances will also have a negligible effect on accuracy.
R4 is the resistance between the DAC output and the load. If $R_{L}$ is constant, then R4 introduces a gain error only that can be trimmed out in the calibration cycle. R5 is the resistance between the load and the analog common. If the output voltage is sensed across the load, R5 introduces a further gain error, which can be trimmed out. If, on the other hand, the output voltage is sensed at the analog supply common, R5 appears as part of the load and therefore introduces no errors.

## PRINTED CIRCUIT BOARD LAYOUT

Figure 31 shows the AD7846 in a typical application with the AD588 reference, producing an output analog voltage in the $\pm 10 \mathrm{~V}$ range. Full-scale and bipolar zero adjustment are provided by Potentiometer R2 and Potentiometer R3. Latches ( $2 \times 74$ LS245) isolate the DAC digital inputs from the active microprocessor bus and minimize digital feedthrough.


Figure 31. Schematic for AD7846 Board

## OUTLINE DIMENSIONS


$\begin{array}{lc}\text { CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS } & \text { ¢ } \\ \text { (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR } \\ \text { REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN. } & \vdots .0\end{array}$
Figure 32. 28-Lead Ceramic Dual In-Line Package [CERDIP] (Q-28-2)
Dimensions shown in inches and (millimeters)


CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN. CORNER LEADS MAY BE CONFIGURED AS WHOLE LEADS.

Figure 33. 28-Lead Plastic Dual In-Line Package [PDIP]
Wide Body
(N-28-2)
Dimensions shown in inches and (millimeters)


CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR

Figure 34. 28-Terminal Ceramic Leadless Chip Carrier [LCC]

$$
(E-28-1)
$$

Dimensions shown in inches and (millimeters)


COMPLIANT TO JEDEC STANDARDS MO-047-AB
CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 35. 28-Lead Plastic Leaded Chip Carrier [PLCC] (P-28)
Dimensions shown in inches and (millimeters)

## AD7846

## ORDERING GUIDE

| Model ${ }^{1}$ | Temperature Range | Relative Accuracy | Package Description | Package Option |
| :---: | :---: | :---: | :---: | :---: |
| 5962-89697013A | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Terminal Ceramic Leadless Chip Carrier [LCC] | E-28-1 |
| 5962-8969701XA | $-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Ceramic Dual In-Line Package [CERDIP] | Q-28-2 |
| AD7846JN | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Dual In-Line Package [PDIP] | N-28-2 |
| AD7846JNZ | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Dual In-Line Package [PDIP] | N-28-2 |
| AD7846KN | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8 \mathrm{LSB}$ | 28-Lead Plastic Dual In-Line Package [PDIP] | N-28-2 |
| AD7846KNZ | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8$ LSB | 28-Lead Plastic Dual In-Line Package [PDIP] | N-28-2 |
| AD7846JP | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846JP-REEL | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846JPZ | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846JPZ-REEL | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846KP | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8 \mathrm{LSB}$ | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846KP-REEL | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8 \mathrm{LSB}$ | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846KPZ | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846KPZ-REEL | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | $\pm 8$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846AP | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846APZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846AQ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 16$ LSB | 28-Lead Ceramic Dual In-Line Package [CERDIP] | Q-28-2 |
| AD7846BP | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 8$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846BPZ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 8$ LSB | 28-Lead Plastic Leaded Chip Carrier [PLCC] | P-28 |
| AD7846ACHIPS | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $\pm 16$ LSB |  | DIE |

[^2]|  |
| ---: |
| AD7846 |

NOTES

## AD7846

## NOTES


[^0]:    ${ }^{\top} V_{\text {out }}$ can be shorted to $D G N D, V_{D D}, V_{S S}$, or $V_{C C}$ provided that the power dissipation of the package is not exceeded.

[^1]:    Figure 17. Spectral Response of Digitally Constructed Sine Wave

[^2]:    ${ }^{1} Z=$ RoHS Compliant Part.

