



Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from,Europe,America and south Asia,supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of “Quality Parts,Customers Priority,Honest Operation,and Considerate Service”,our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip,ALPS,ROHM,Xilinx,Pulse,ON,Everlight and Freescale. Main products comprise IC,Modules,Potentiometer,IC Socket,Relay,Connector.Our parts cover such applications as commercial,industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



### FEATURES

#### Low input currents

- 10 pA maximum input bias current (B grade)
- 0.6 pA maximum input offset current (B grade)

#### High CMRR

- 100 dB CMRR (minimum),  $G = 10$  (B grade)
- 80 dB CMRR (minimum) to 5 kHz,  $G = 1$  (B grade)

#### Excellent ac specifications and low power

- 1.5 MHz bandwidth ( $G = 1$ )
- 14 nV/ $\sqrt{\text{Hz}}$  input noise (1 kHz)
- Slew rate: 2 V/ $\mu\text{s}$

- 750  $\mu\text{A}$  quiescent supply current (maximum)

#### Versatile

- MSOP package
- Rail-to-rail output
- Input voltage range to below negative supply rail
- 4 kV ESD protection
- 4.5 V to 36 V single supply
- $\pm 2.25$  V to  $\pm 18$  V dual supply
- Gain set with single resistor ( $G = 1$  to 1000)

#### Qualified for automotive applications

### APPLICATIONS

- Medical instrumentation
- Precision data acquisition
- Transducer interfaces

### GENERAL DESCRIPTION

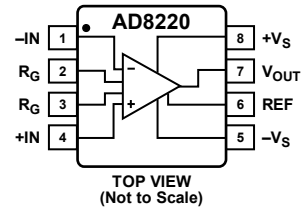
The AD8220 is the first single-supply, JFET input instrumentation amplifier available in an MSOP package. Designed to meet the needs of high performance, portable instrumentation, the AD8220 has a minimum common-mode rejection ratio (CMRR) of 86 dB at dc and a minimum CMRR of 80 dB at 5 kHz for  $G = 1$ . Maximum input bias current is 10 pA and typically remains below 300 pA over the entire industrial temperature range. Despite the JFET inputs, the AD8220 typically has a noise corner of only 10 Hz.

With the proliferation of mixed-signal processing, the number of power supplies required in each system has grown. The AD8220 is designed to alleviate this problem. The AD8220 can operate on a  $\pm 18$  V dual supply, as well as on a single +5 V supply. Its rail-to-rail output stage maximizes dynamic range on the low voltage supplies common in portable applications. Its ability to run on a single 5 V supply eliminates the need to use higher voltage, dual supplies. The AD8220 draws a maximum of 750  $\mu\text{A}$  of quiescent current, making it ideal for battery powered devices.

#### Rev. B

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

### PIN CONFIGURATION



TOP VIEW  
(Not to Scale)

Figure 1.

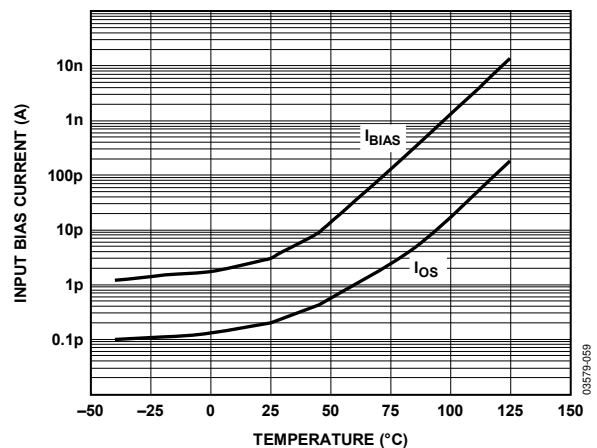


Figure 2. Input Bias Current and Offset Current vs. Temperature

Gain is set from 1 to 1000 with a single resistor. Increasing the gain increases the common-mode rejection. Measurements that need higher CMRR when reading small signals benefit when the AD8220 is set for large gains.

A reference pin allows the user to offset the output voltage. This feature is useful when interfacing with analog-to-digital converters.

The AD8220 is available in an MSOP that takes roughly half the board area of an SOIC. Performance for the A and B grade is specified over the industrial temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ , and the W grade is specified over the automotive temperature range of  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

# AD8220\* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

---

## COMPARABLE PARTS

View a parametric search of comparable parts.

## EVALUATION KITS

- AD62x, AD822x, AD842x Series InAmp Evaluation Board

## DOCUMENTATION

### Application Notes

- AN-1401: Instrumentation Amplifier Common-Mode Range: The Diamond Plot

### Data Sheet

- AD8220: JFET Input Instrumentation Amplifier with Rail-to-Rail Output in MSOP Package Data Sheet

### Technical Books

- A Designer's Guide to Instrumentation Amplifiers, 3rd Edition, 2006

### User Guides

- UG-181: PLC Demo System, Industrial Process Control Demo System

## TOOLS AND SIMULATIONS

- AD8220 SPICE Macro-Model

## REFERENCE DESIGNS

- CN0067
- CN0114

## REFERENCE MATERIALS

### Technical Articles

- Auto-Zero Amplifiers
- Biopotential Electrode Sensors in ECG/EEG/EMG Systems
- High-performance Adder Uses Instrumentation Amplifiers
- MS-2160: Mitigation Strategies for ECG Design Challenges
- Part 1: Simplifying Design of Industrial Process-Control Systems with PLC Evaluation Boards
- Part 2: Simplifying Design of Industrial Process-Control Systems with PLC Evaluation Boards

## DESIGN RESOURCES

- AD8220 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

## DISCUSSIONS

View all AD8220 EngineerZone Discussions.

## SAMPLE AND BUY

Visit the product page to see pricing options.

## TECHNICAL SUPPORT

Submit a technical question or find your regional support number.

## DOCUMENT FEEDBACK

Submit feedback for this data sheet.

---

## TABLE OF CONTENTS

Features .....	1	Power Supply Regulation and Bypassing .....	21
Applications.....	1	Input Bias Current Return Path .....	21
Pin Configuration.....	1	Input Protection .....	21
General Description .....	1	RF Interference .....	22
Revision History .....	2	Common-Mode Input Voltage Range.....	22
Specifications.....	3	Driving an ADC .....	22
Absolute Maximum Ratings.....	8	Applications Information .....	23
ESD Caution.....	8	AC-Coupled Instrumentation Amplifier .....	23
Pin Configuration and Function Descriptions.....	9	Differential Output .....	23
Typical Performance Characteristics .....	10	Electrocardiogram Signal Conditioning .....	25
Theory of Operation .....	19	Outline Dimensions .....	26
Gain Selection .....	20	Ordering Guide .....	26
Layout.....	20	Automotive Products.....	26
Reference Terminal .....	21		

## REVISION HISTORY

### 5/10—Rev. A to Rev. B

Added W Grade.....	Universal
Changes to Features Section and General Description Section .	1
Changes to Specifications Section and Table 1 .....	3
Changes to Table 2.....	5
Updated Outline Dimensions .....	26
Changes to Ordering Guide .....	26
Added Automotive Products Section .....	26

### 5/07—Rev. 0 to Rev. A

Changes to Table 1.....	3
Changes to Table 2.....	5
Changes to Table 3.....	8
Changes to Figure 6 and Figure 7 .....	10
Changes to Figure 23 and Figure 24.....	13
Changes to Theory of Operation.....	19
Changes to Layout .....	20
Changes to Ordering Guide .....	26

### 4/06—Revision 0: Initial Version

## SPECIFICATIONS

$V_{S+} = 15\text{ V}$ ,  $V_{S-} = -15\text{ V}$ ,  $V_{REF} = 0\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $T_{OPR} = -40^\circ\text{C}$  to  $+85^\circ\text{C}$  for A and B grades.  $T_{OPR} = -40^\circ\text{C}$  to  $+125^\circ\text{C}$  for W grade,  $G = 1$ ,  $R_L = 2\text{ k}\Omega^1$ , unless otherwise noted.

Table 1.

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
COMMON-MODE REJECTION RATIO (CMRR)	$T_A$ for A, B grades, $T_{OPR}$ for W grade										
CMRR DC to 60 Hz with 1 k $\Omega$ Source Imbalance	$V_{CM} = \pm 10\text{ V}$										
G = 1		78			86			77			dB
G = 10		94			100			92			dB
G = 100		94			100			92			dB
G = 1000		94			100			92			dB
CMRR at 5 kHz	$V_{CM} = \pm 10\text{ V}$										
G = 1		74			80			72			dB
G = 10		84			90			80			dB
G = 100		84			90			80			dB
G = 1000		84			90			80			dB
NOISE	RTI noise = $\sqrt{(e_{ni}^2 + (e_{no}/G)^2)}$ , $T_A$										
Voltage Noise, 1 kHz											
Input Voltage Noise, $e_{ni}$	$V_{IN+}, V_{IN-} = 0\text{ V}$		14			14	17		14		nV/ $\sqrt{\text{Hz}}$
Output Voltage Noise, $e_{no}$	$V_{IN+}, V_{IN-} = 0\text{ V}$		90			90	100		90		nV/ $\sqrt{\text{Hz}}$
RTI, 0.1 Hz to 10 Hz											
G = 1			5			5			5		$\mu\text{V p-p}$
G = 1000			0.8			0.8			0.8		$\mu\text{V p-p}$
Current Noise	$f = 1\text{ kHz}$		1			1			1		fA/ $\sqrt{\text{Hz}}$
VOLTAGE OFFSET	$V_{OS} = V_{OSI} + V_{OSO}/G$										
Input Offset, $V_{OSI}$	$T_A$	-250		+250	-125		+125	-250		+250	$\mu\text{V}$
Average TC	$T_{OPR}$	-10		+10	-5		+5	-10		+10	$\mu\text{V}/^\circ\text{C}$
Output Offset, $V_{OSO}$	$T_A$	-750		+750	-500		+500	-750		+750	$\mu\text{V}$
Average TC	$T_{OPR}$	-10		+10	-5		+5	-10		+10	$\mu\text{V}/^\circ\text{C}$
Offset RTI vs. Supply (PSR)	$V_S = \pm 5\text{ V}$ to $\pm 15\text{ V}$ , $T_A$ for A, B grades, $T_{OPR}$ for W grade										
G = 1					86				80		dB
G = 10					96				92		dB
G = 100					96				92		dB
G = 1000					96				92		dB
INPUT CURRENT											
Input Bias Current	$T_A$			25			10			25	pA
Over Temperature	$T_{OPR}$		0.3			0.3				100	nA
Input Offset Current	$T_A$			2			0.6			2	pA
Over Temperature	$T_{OPR}$		0.005			0.005				10	nA
DYNAMIC RESPONSE											
Small Signal Bandwidth, -3 dB	$T_A$										
G = 1			1500			1500			1500		kHz
G = 10			800			800			800		kHz
G = 100			120			120			120		kHz
G = 1000			14			14			14		kHz

# AD8220

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Settling Time 0.01%	10 V step, $T_A$										
G = 1			5			5			5		$\mu\text{s}$
G = 10			4.3			4.3			4.3		$\mu\text{s}$
G = 100			8.1			8.1			8.1		$\mu\text{s}$
G = 1000			58			58			58		$\mu\text{s}$
Settling Time 0.001%	10 V step, $T_A$										
G = 1			6			6			6		$\mu\text{s}$
G = 10			4.6			4.6			4.6		$\mu\text{s}$
G = 100			9.6			9.6			9.6		$\mu\text{s}$
G = 1000			74			74			74		$\mu\text{s}$
Slew Rate											
G = 1 to 100	$T_A$	2			2			2			V/ $\mu\text{s}$
<b>GAIN</b>	$G = 1 + (49.4 \text{ k}\Omega/R_G)$ , $T_A$ for A, B grades, $T_{OPR}$ for W grade										
Gain Range		1		1000	1		1000	1		1000	V/V
Gain Error	$V_{OUT} = \pm 10 \text{ V}$										
G = 1		-0.06		+0.06	-0.04		+0.04	-0.1		+0.1	%
G = 10		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
G = 100		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
G = 1000		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
Gain Nonlinearity	$V_{OUT} =$ $-10 \text{ V to } +10 \text{ V}, T_A$										
G = 1	$R_L = 10 \text{ k}\Omega$		10	15		10	15		10	15	ppm
G = 10	$R_L = 10 \text{ k}\Omega$		5	10		5	10		5	10	ppm
G = 100	$R_L = 10 \text{ k}\Omega$		30	60		30	60		30	60	ppm
G = 1000	$R_L = 10 \text{ k}\Omega$		400	500		400	500		400	500	ppm
G = 1	$R_L = 2 \text{ k}\Omega$		10	15		10	15		10	15	ppm
G = 10	$R_L = 2 \text{ k}\Omega$		10	15		10	15		10	15	ppm
G = 100	$R_L = 2 \text{ k}\Omega$		50	75		50	75		50	75	ppm
Gain vs. Temperature											
G = 1			3	10		2	5		3	10	ppm/ $^{\circ}\text{C}$
G > 10				-50			-50			-50	ppm/ $^{\circ}\text{C}$
<b>INPUT</b>											
Impedance (Pin to Ground) <sup>2</sup>	$T_A$		$10^4    5$			$10^4    5$			$10^4    5$		$\text{G}\Omega    \mu\text{F}$
Input Operating Voltage Range <sup>3</sup>	$V_S = \pm 2.25 \text{ V to } \pm 18 \text{ V}$ for dual supplies	$-V_S - 0.1$		$+V_S - 2$	$-V_S - 0.1$		$+V_S - 2$	$-V_S - 0.1$		$+V_S - 2$	V
Over Temperature	$T_{OPR}$	$-V_S - 0.1$		$+V_S - 2.1$	$-V_S - 0.1$		$+V_S - 2.1$	$-V_S - 0.1$		$+V_S - 2.2$	V
<b>OUTPUT</b>											
Output Swing	$R_L = 10 \text{ k}\Omega, T_A$	-14.7		+14.7	-14.7		+14.7	-14.7		+14.7	V
Over Temperature	$T_{OPR}$	-14.6		+14.6	-14.6		+14.6	-14.3		+14.3	V
Short-Circuit Current	$T_A$		15			15			15		mA
<b>REFERENCE INPUT</b>											
$R_{IN}$	$T_A$		40			40			40		$\mu\text{A}$
$I_{IN}$	$V_{IN+}, V_{IN-} = 0 \text{ V}$			70			70			70	V
Voltage Range		$-V_S$		$+V_S$	$-V_S$		$+V_S$			$+V_S$	V/V
Gain to Output	$T_A$		$1 \pm 0.0001$			$1 \pm 0.0001$			$1 \pm 0.0001$		V/V

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit	
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max		
POWER SUPPLY												
Operating Range		±2.25 <sup>4</sup>		±18	±2.25 <sup>4</sup>		±18	±2.25 <sup>4</sup>		±18	V	
Quiescent Current	T <sub>A</sub>				750				750			μA
Over Temperature	T <sub>OPR</sub>				850				850			μA
TEMPERATURE RANGE												
For Specified Performance	T <sub>OPR</sub>	-40		+85	-40		+85	-40		+125	°C	

<sup>1</sup> When the output sinks more than 4 mA, use a 47 pF capacitor in parallel with the load to prevent ringing. Otherwise, use a larger load, such as 10 kΩ.

<sup>2</sup> Differential and common-mode input impedance can be calculated from the pin impedance:  $Z_{DIFF} = 2(Z_{PIN})$ ;  $Z_{CM} = Z_{PIN}/2$ .

<sup>3</sup> The AD8220 can operate up to a diode drop below the negative supply but the bias current increases sharply. The input voltage range reflects the maximum allowable voltage where the input bias current is within the specification.

<sup>4</sup> At this supply voltage, ensure that the input common-mode voltage is within the input voltage range specification.

$V_S = +5\text{ V}$ ,  $V_{S-} = 0\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$ ,  $T_A = 25^\circ\text{C}$ ,  $T_{OPR} = -40^\circ\text{C}$  to  $+85^\circ\text{C}$  for A and B grades.  $T_{OPR} = -40^\circ\text{C}$  to  $+125^\circ\text{C}$  for W grade,  $G = 1$ ,  $R_L = 2\text{ k}\Omega^1$ , unless otherwise noted.

**Table 2.**

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
COMMON-MODE REJECTION RATIO (CMRR)											
CMRR DC to 60 Hz with 1 kΩ Source Imbalance	T <sub>A</sub> for A, B grades, T <sub>OPR</sub> for W grade V <sub>CM</sub> = 0 to 2.5 V										
G = 1		78			86			77			dB
G = 10		94			100			92			dB
G = 100		94			100			92			dB
G = 1000		94			100			92			dB
CMRR at 5 kHz	V <sub>CM</sub> = 0 to 2.5 V										
G = 1		74			80			72			dB
G = 10		84			90			80			dB
G = 100		84			90			80			dB
G = 1000		84			90			80			dB
NOISE											
Voltage Noise, 1 kHz	RTI noise = $\sqrt{(e_{ni}^2 + (e_{no}/G)^2)}$ , T <sub>A</sub> V <sub>S</sub> = ±2.5 V										
Input Voltage Noise, e <sub>ni</sub>	V <sub>IN+</sub> , V <sub>IN-</sub> = 0 V, V <sub>REF</sub> = 0 V	14			14 17			14			nV/√Hz
Output Voltage Noise, e <sub>no</sub>	V <sub>IN+</sub> , V <sub>IN-</sub> = 0 V, V <sub>REF</sub> = 0 V	90			90 100			90			nV/√Hz
RTI, 0.1 Hz to 10 Hz											
G = 1		5			5			5			μV p-p
G = 1000		0.8			0.8			0.8			μV p-p
Current Noise	f = 1 kHz	1			1			1			fA/√Hz
VOLTAGE OFFSET											
Input Offset, V <sub>OSI</sub>	V <sub>OS</sub> = V <sub>OSI</sub> + V <sub>OSO</sub> /G T <sub>A</sub>	-300		+300	-200		+200	-300		+300	μV
Average TC	T <sub>OPR</sub>	-10		+10	-5		+5	-10		10	μV/°C
Output Offset, V <sub>OSO</sub>	T <sub>A</sub>	-800		+800	-600		+600	-800		+800	μV
Average TC	T <sub>OPR</sub>	-10		+10	-5		+5	-10		+10	μV/°C
Offset RTI vs. Supply (PSR)	T <sub>A</sub> for A, B grades, T <sub>OPR</sub> for W grade										
G = 1		86			86			80			dB
G = 10		96			100			92			dB
G = 100		96			100			92			dB
G = 1000		96			100			92			dB

# AD8220

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
INPUT CURRENT											
Input Bias Current	T <sub>A</sub>			25			10			25	pA
Over Temperature	T <sub>OPR</sub>		0.3			0.3			100		nA
Input Offset Current	T <sub>A</sub>			2			0.6			2	pA
Over Temperature	T <sub>OPR</sub>		0.005			0.005			10		nA
DYNAMIC RESPONSE											
Small Signal Bandwidth, -3 dB	T <sub>A</sub>										
G = 1			1500			1500			1500		kHz
G = 10			800			800			800		kHz
G = 100			120			120			120		kHz
G = 1000			14			14			14		kHz
Settling Time 0.01%	T <sub>A</sub>										
G = 1	3 V step		2.5			2.5			2.5		μs
G = 10	4 V step		2.5			2.5			2.5		μs
G = 100	4 V step		7.5			7.5			7.5		μs
G = 1000	4 V step		30			30			30		μs
Settling Time 0.001%	T <sub>A</sub>										
G = 1	3 V step		3.5			3.5			3.5		μs
G = 10	4 V step		3.5			3.5			3.5		μs
G = 100	4 V step		8.5			8.5			8.5		μs
G = 1000	4 V step		37			37			37		μs
Slew Rate	T <sub>A</sub>										
G = 1 to 100		2			2				2		V/μs
GAIN											
Gain Range	G = 1 + (49.4 kΩ/R <sub>G</sub> ), T <sub>A</sub> for A, B grades, T <sub>OPR</sub> for W grade	1		1000	1		1000	1		1000	V/V
Gain Error	V <sub>OUT</sub> = 0.3 V to 2.9 V for G = 1, V <sub>OUT</sub> = 0.3 V to 3.8 V for G > 1										
G = 1		-0.06		+0.06	-0.04		+0.04	-0.1		+0.1	%
G = 10		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
G = 100		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
G = 1000		-0.3		+0.3	-0.2		+0.2	-0.8		+0.8	%
Nonlinearity	V <sub>OUT</sub> = 0.3 V to 2.9 V for G = 1, V <sub>OUT</sub> = 0.3 V to 3.8 V for G > 1, T <sub>A</sub>										
G = 1	R <sub>L</sub> = 10 kΩ		35	50		35	50			50	ppm
G = 10	R <sub>L</sub> = 10 kΩ		35	50		35	50			50	ppm
G = 100	R <sub>L</sub> = 10 kΩ		50	75		50	75			75	ppm
G = 1000	R <sub>L</sub> = 10 kΩ		650	750		650	750			750	ppm
G = 1	R <sub>L</sub> = 2 kΩ		35	50		35	50			50	ppm
G = 10	R <sub>L</sub> = 2 kΩ		35	50		35	50			50	ppm
G = 100	R <sub>L</sub> = 2 kΩ		50	75		50	75			75	ppm
Gain vs. Temperature											
G = 1			3	10		2	5		3	10	ppm/°C
G > 10				-50			-50			-50	ppm/°C
INPUT											
Impedance (Pin to Ground) <sup>2</sup>	T <sub>A</sub>		10 <sup>4</sup>   6			10 <sup>4</sup>   6			10 <sup>4</sup>   6		GΩ  pF
Input Voltage Range <sup>3</sup>	T <sub>A</sub>	-0.1		+V <sub>S</sub> - 2	-0.1		+V <sub>S</sub> - 2				V
Over Temperature	T <sub>OPR</sub>	-0.1		+V <sub>S</sub> - 2.1	-0.1		+V <sub>S</sub> - 2.1	-0.1		+V <sub>S</sub> - 2.2	V

Parameter	Test Conditions	A Grade			B Grade			W Grade			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
OUTPUT											
Output Swing	$R_L = 10\text{ k}\Omega$	0.15		4.85	0.15		4.85	0.15		4.85	V
Over Temperature	$T_{OPR}$	0.2		4.80	0.2		4.80	0.3		4.70	V
Short-Circuit Current			15			15			15		mA
REFERENCE INPUT											
$R_{IN}$	$T_A$		40			40			40		k $\Omega$
$I_{IN}$	$V_{IN+}, V_{IN-} = 0\text{ V}$			70			70			70	$\mu\text{A}$
Voltage Range		$-V_S$		$+V_S$	$-V_S$		$+V_S$	$-V_S$		$+V_S$	V
Gain to Output	$T_A$		$1 \pm$ 0.0001			$1 \pm$ 0.0001			$1 \pm$ 0.0001		V/V
POWER SUPPLY											
Operating Range		4.5		36	4.5		36	4.5		36	V
Quiescent Current	$T_A$			750			750			750	$\mu\text{A}$
Over Temperature	$T_{OPR}$			850			850			1000	$\mu\text{A}$
TEMPERATURE RANGE											
$T_{OPR}$ , For Specified Performance	$T_{OPR}$	-40		+85	-40		+85	-40		+125	$^{\circ}\text{C}$

<sup>1</sup> When the output sinks more than 4 mA, use a 47 pF capacitor in parallel with the load to prevent ringing. Otherwise, use a larger load, such as 10 k $\Omega$ .

<sup>2</sup> Differential and common-mode impedance can be calculated from the pin impedance:  $Z_{DIFF} = 2(Z_{PIN})$ ;  $Z_{CM} = Z_{PIN}/2$ .

<sup>3</sup> The AD8220 can operate up to a diode drop below the negative supply but the bias current increases sharply. The input voltage range reflects the maximum allowable voltage where the input bias current is within the specification.

## ABSOLUTE MAXIMUM RATINGS

Table 3.

Parameter	Rating
Supply Voltage	±18 V
Power Dissipation	See Figure 3
Output Short-Circuit Current	Indefinite <sup>1</sup>
Input Voltage (Common Mode)	±Vs
Differential Input Voltage	±Vs
Storage Temperature Range	−65°C to +125°C
Operating Temperature Range <sup>2</sup>	−40°C to +125°C
Lead Temperature (Soldering 10 sec)	300°C
Junction Temperature	140°C
$\theta_{JA}$ (4-Layer JEDEC Standard Board)	135°C/W
Package Glass Transition Temperature	140°C
ESD (Human Body Model)	4 kV
ESD (Charge Device Model)	1 kV
ESD (Machine Model)	0.4 kV

<sup>1</sup> Assumes the load is referenced to midsupply.

<sup>2</sup> Temperature for specified performance is −40°C to +85°C. For performance to 125°C, see the Typical Performance Characteristics section.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Figure 3 shows the maximum safe power dissipation in the package vs. the ambient temperature for the MSOP on a 4-layer JEDEC standard board.  $\theta_{JA}$  values are approximations.

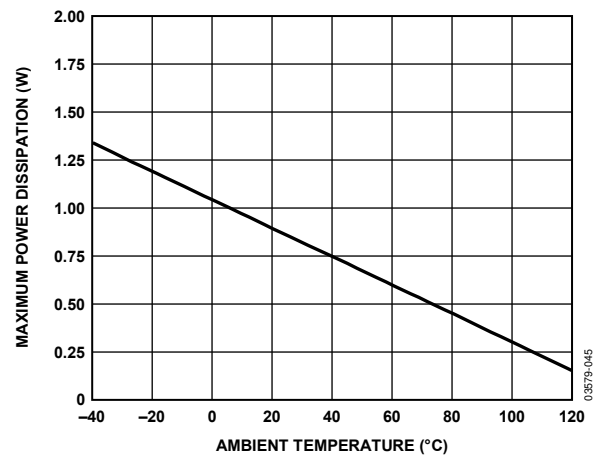


Figure 3. Maximum Power Dissipation vs. Ambient Temperature

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

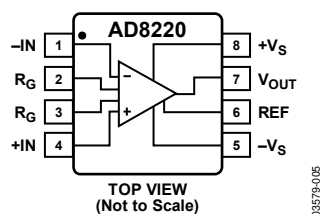


Figure 4. Pin Configuration

Table 4. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	-IN	Negative Input Terminal (True Differential Input)
2, 3	R <sub>G</sub>	Gain Setting Terminals (Place Resistor Across the R <sub>G</sub> Pins)
4	+IN	Positive Input Terminal (True Differential Input)
5	-V <sub>S</sub>	Negative Power Supply Terminal
6	REF	Reference Voltage Terminal (Drive This Terminal with a Low Impedance Voltage Source to Level-Shift the Output)
7	V <sub>OUT</sub>	Output Terminal
8	+V <sub>S</sub>	Positive Power Supply Terminal

TYPICAL PERFORMANCE CHARACTERISTICS

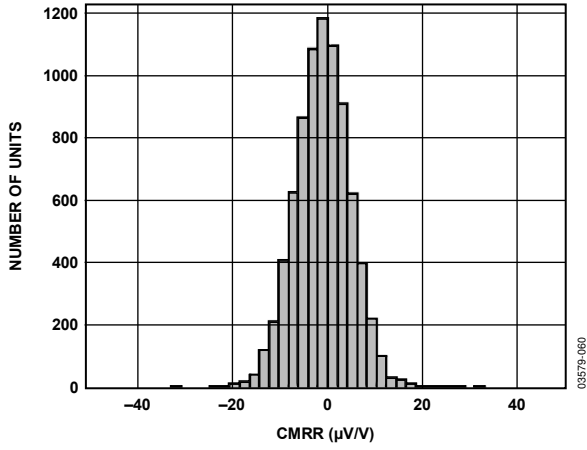


Figure 5. Typical Distribution of CMRR ( $G = 1$ )

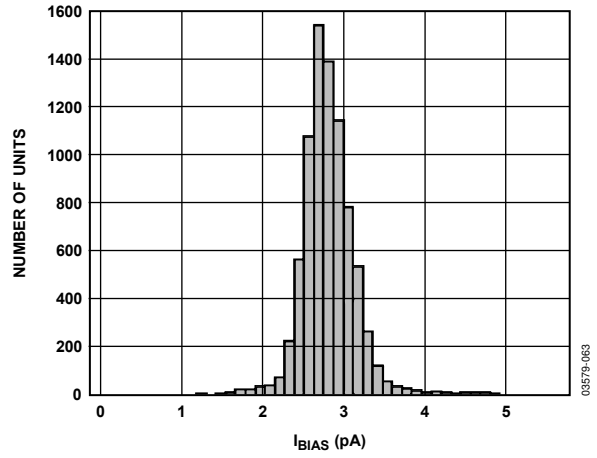


Figure 8. Typical Distribution of Input Bias Current

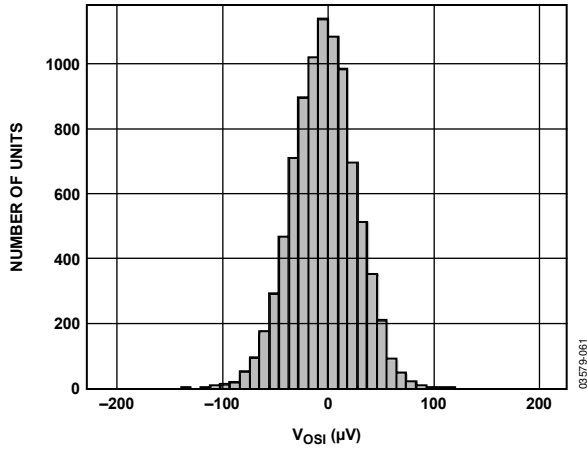


Figure 6. Typical Distribution of Input Offset Voltage

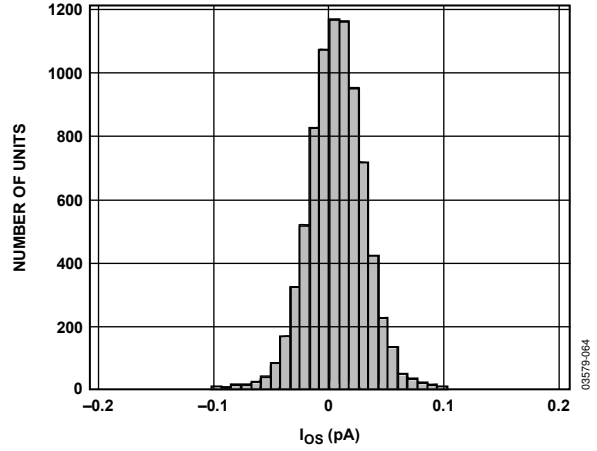


Figure 9. Typical Distribution of Input Offset Current

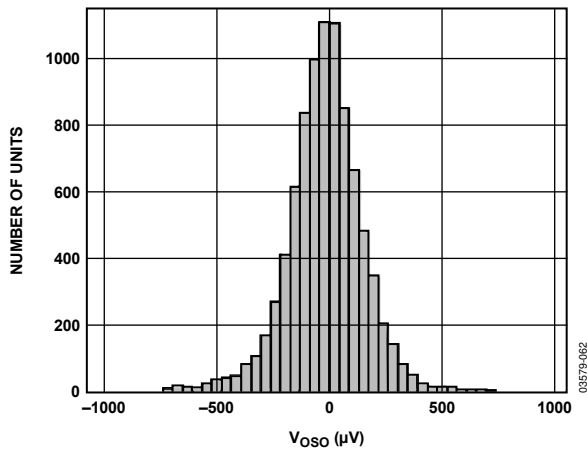


Figure 7. Typical Distribution of Output Offset Voltage

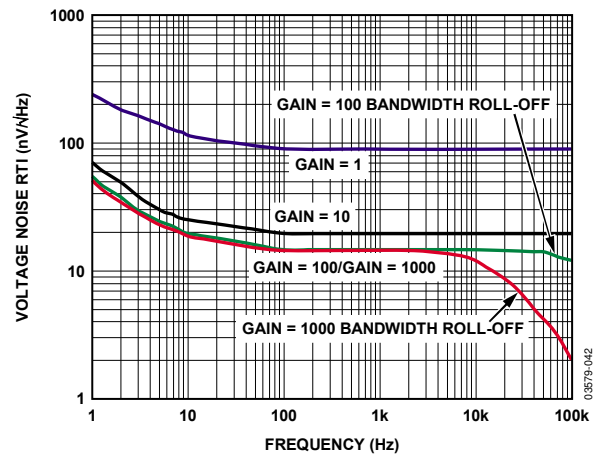


Figure 10. Voltage Spectral Density vs. Frequency

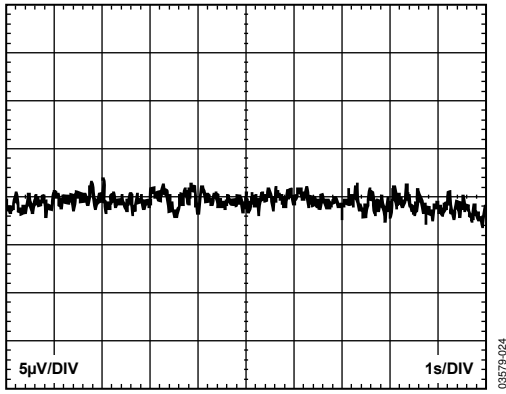


Figure 11. 0.1 Hz to 10 Hz RTI Voltage Noise (G = 1)

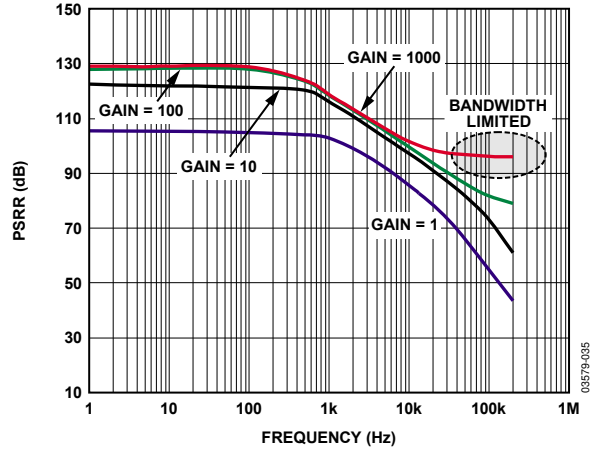


Figure 14. Positive PSRR vs. Frequency, RTI

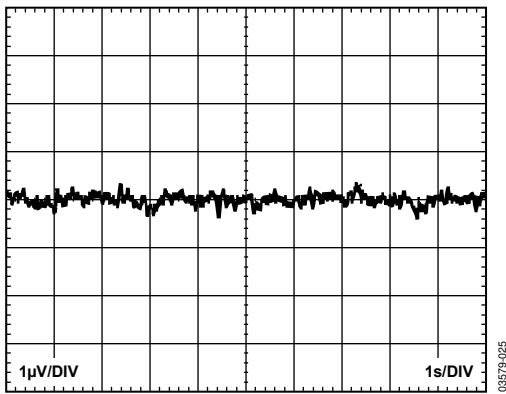


Figure 12. 0.1 Hz to 10 Hz RTI Voltage Noise (G = 1000)

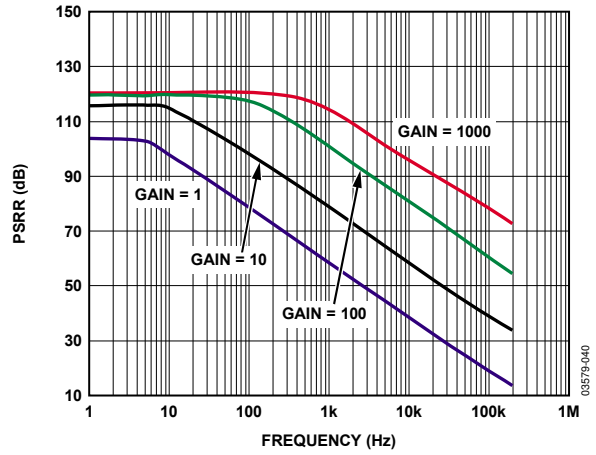


Figure 15. Negative PSRR vs. Frequency, RTI

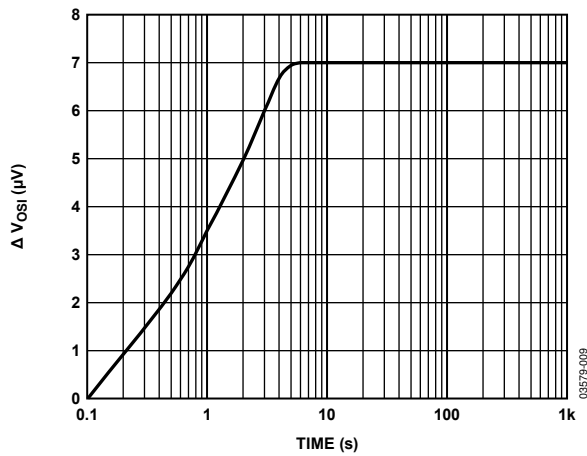


Figure 13. Change in Input Offset Voltage vs. Warmup Time

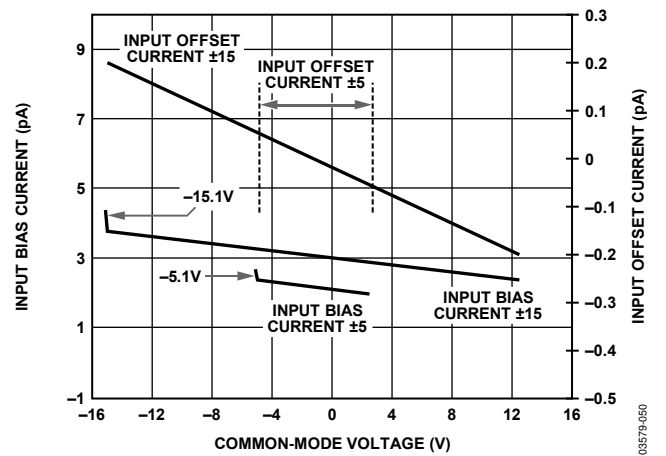


Figure 16. Input Bias Current and Input Offset Current vs. Common-Mode Voltage

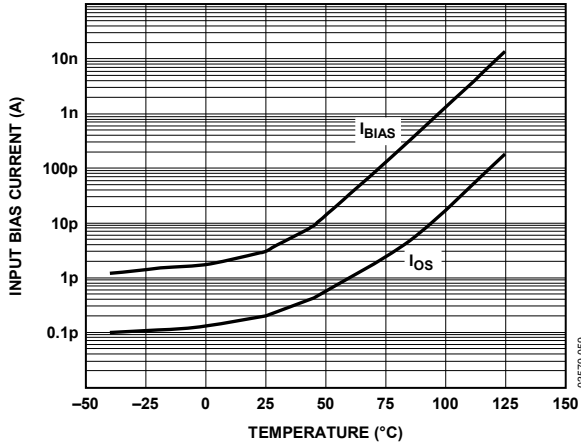


Figure 17. Input Bias Current and Offset Current vs. Temperature,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

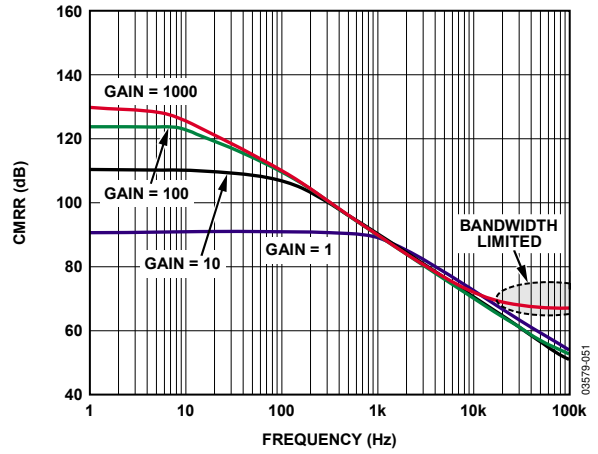


Figure 20. CMRR vs. Frequency, 1 kΩ Source Imbalance

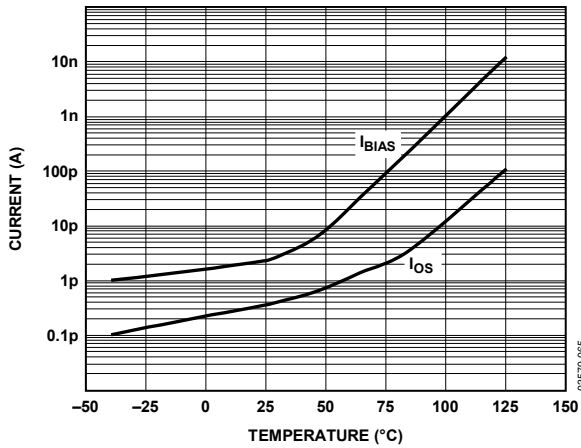


Figure 18. Input Bias Current and Offset Current vs. Temperature,  $V_S = +5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

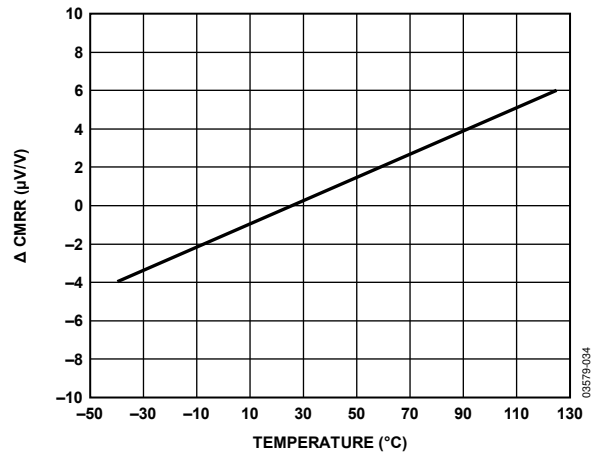


Figure 21. Change in CMRR vs. Temperature,  $G = 1$

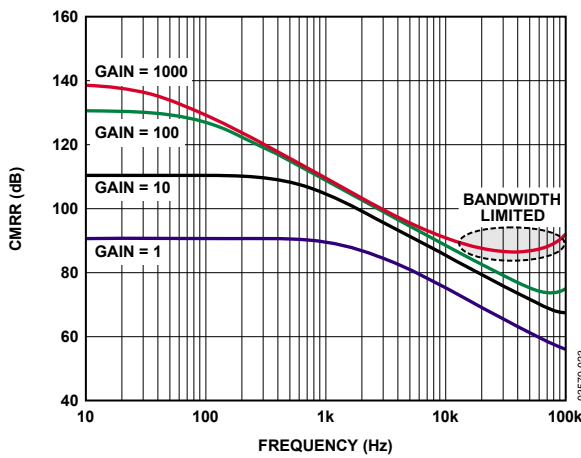


Figure 19. CMRR vs. Frequency

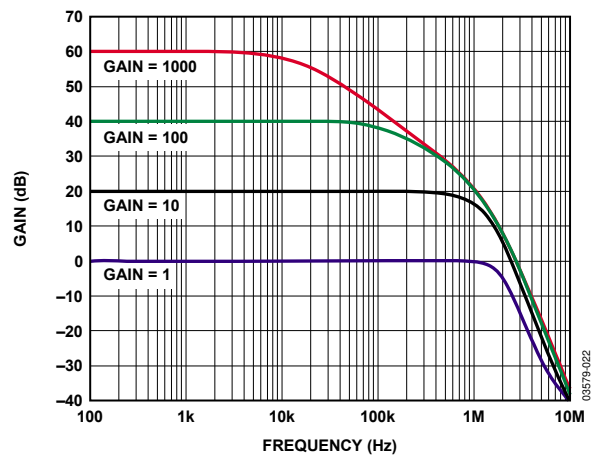


Figure 22. Gain vs. Frequency

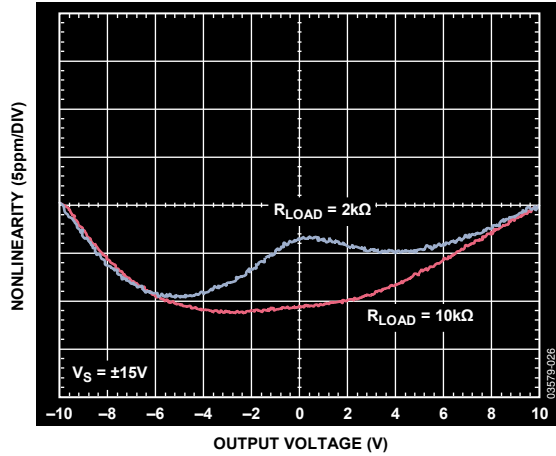


Figure 23. Gain Nonlinearity,  $G = 1$

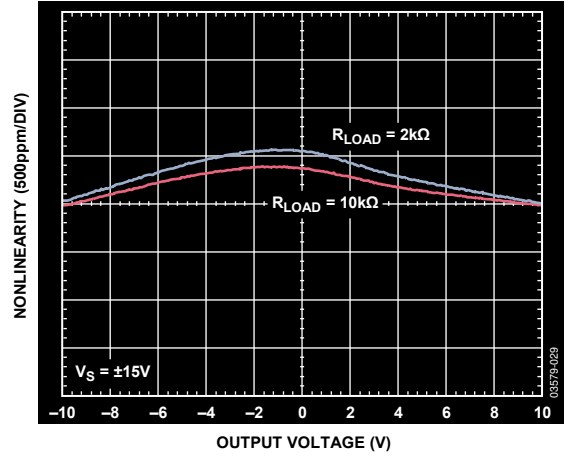


Figure 26. Gain Nonlinearity,  $G = 1000$

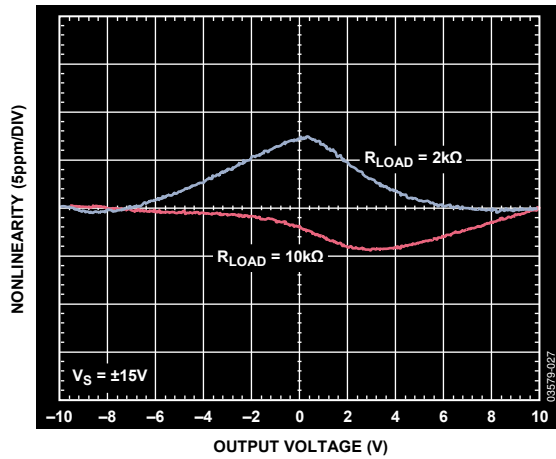


Figure 24. Gain Nonlinearity,  $G = 10$

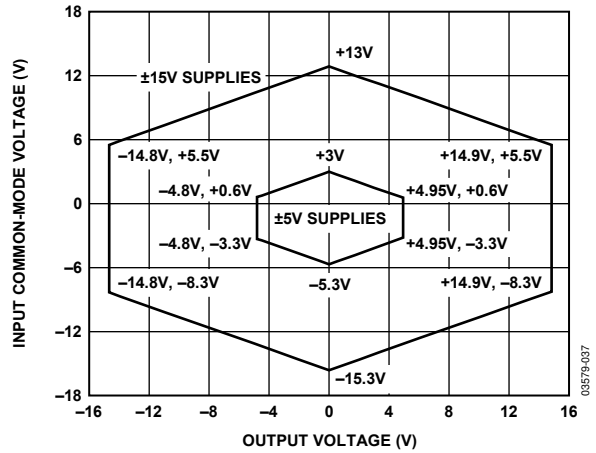


Figure 27. Input Common-Mode Voltage Range vs. Output Voltage,  $G = 1, V_{REF} = 0V$

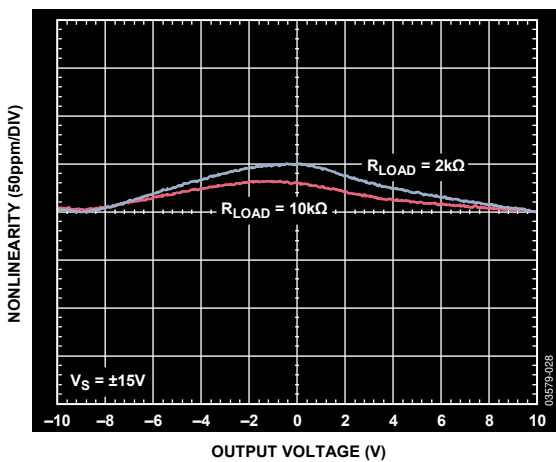


Figure 25. Gain Nonlinearity,  $G = 100$

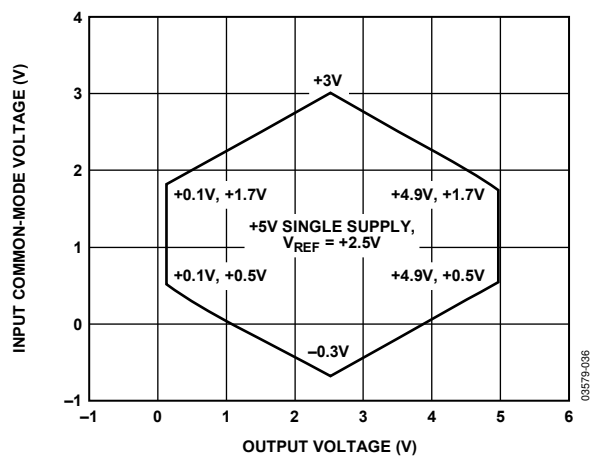


Figure 28. Input Common-Mode Voltage Range vs. Output Voltage,  $G = 1, V_S = +5V, V_{REF} = 2.5V$

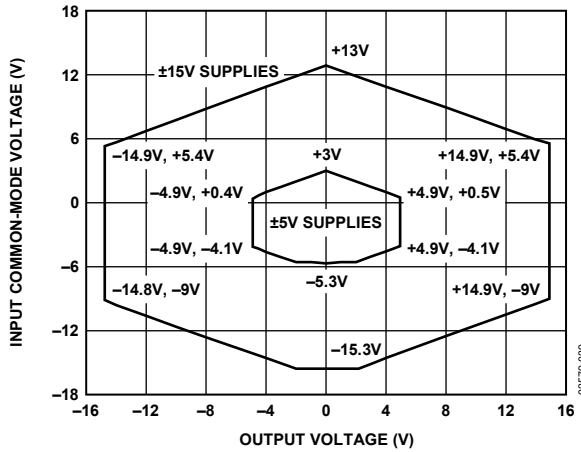


Figure 29. Input Common-Mode Voltage Range vs. Output Voltage,  $G = 100$ ,  $V_{REF} = 0V$

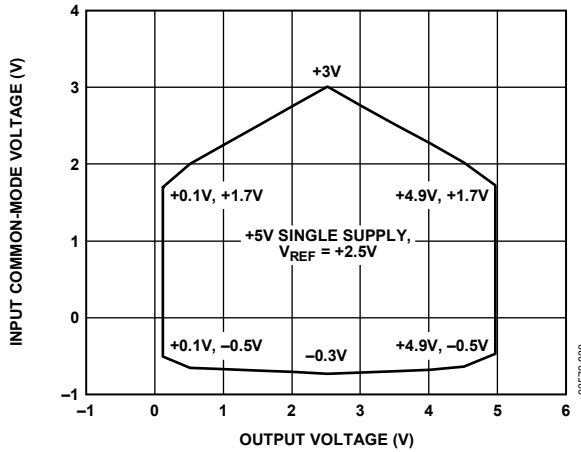


Figure 30. Input Common-Mode Voltage Range vs. Output Voltage,  $G = 100$ ,  $V_S = +5V$ ,  $V_{REF} = 2.5V$

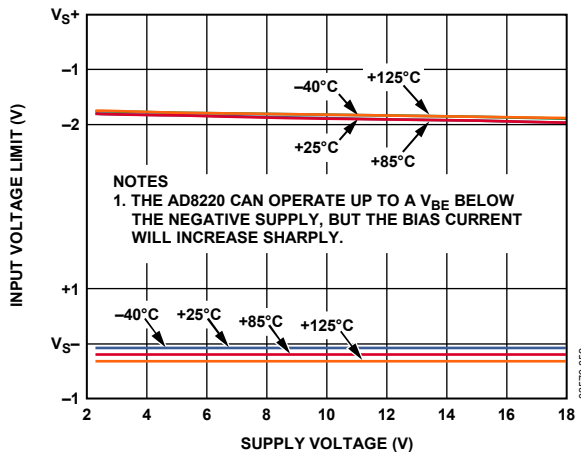


Figure 31. Input Voltage Limit vs. Supply Voltage,  $G = 1$ ,  $V_{REF} = 0V$

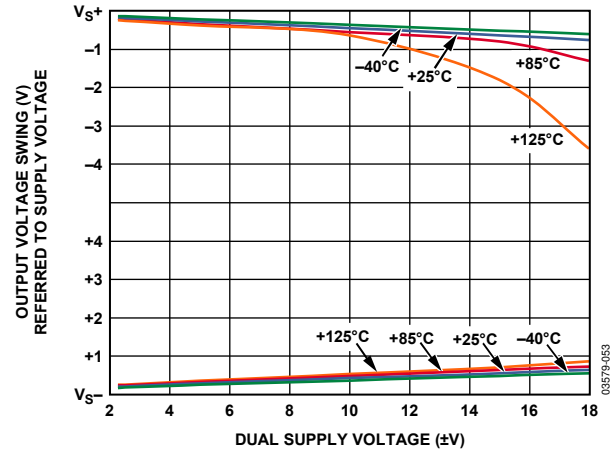


Figure 32. Output Voltage Swing vs. Supply Voltage,  $R_{LOAD} = 2k\Omega$ ,  $G = 10$ ,  $V_{REF} = 0V$

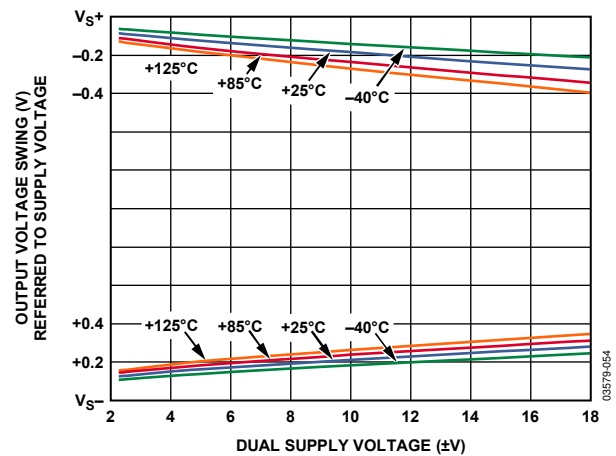


Figure 33. Output Voltage Swing vs. Supply Voltage,  $R_{LOAD} = 10k\Omega$ ,  $G = 10$ ,  $V_{REF} = 0V$

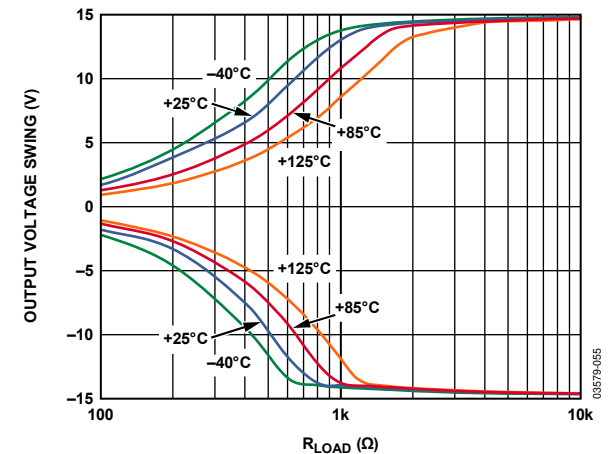


Figure 34. Output Voltage Swing vs. Load Resistance  $V_S = \pm 15V$ ,  $V_{REF} = 0V$

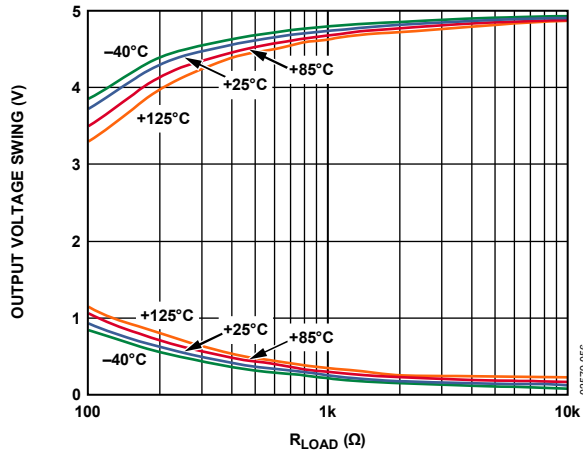


Figure 35. Output Voltage Swing vs. Load Resistance  $V_S = +5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

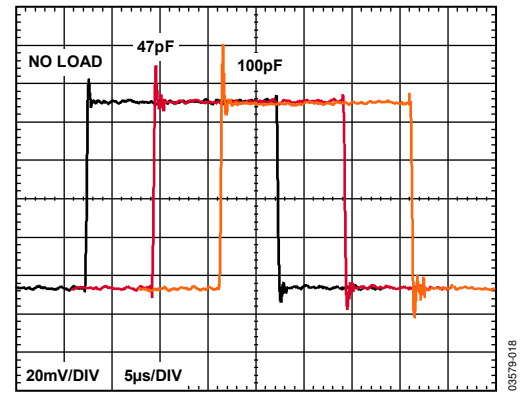


Figure 38. Small Signal Pulse Response for Various Capacitive Loads,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

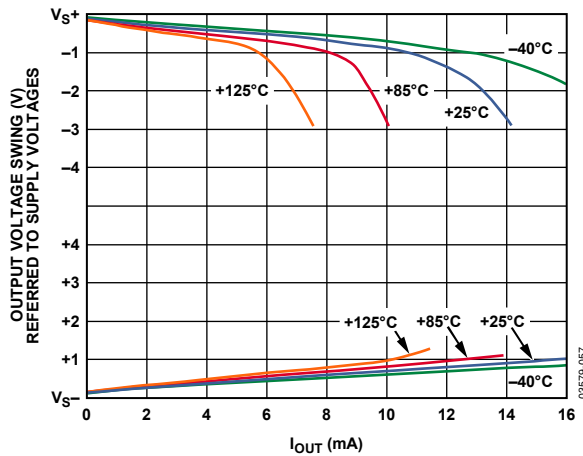


Figure 36. Output Voltage Swing vs. Output Current,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

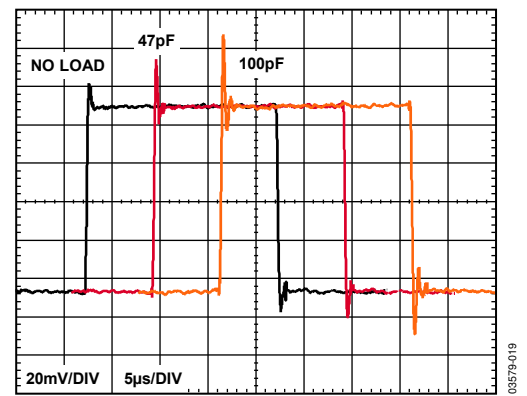


Figure 39. Small Signal Pulse Response for Various Capacitive Loads,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

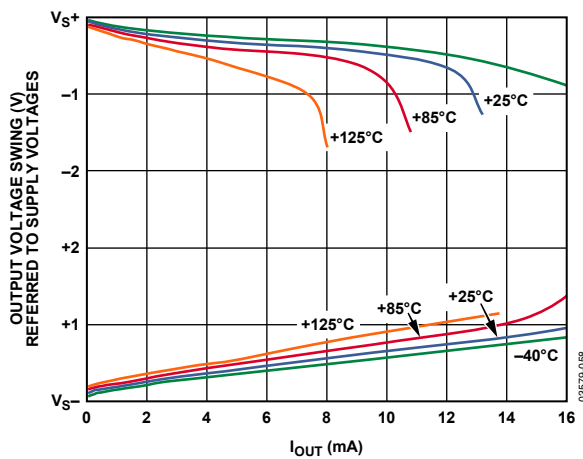


Figure 37. Output Voltage Swing vs. Output Current,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

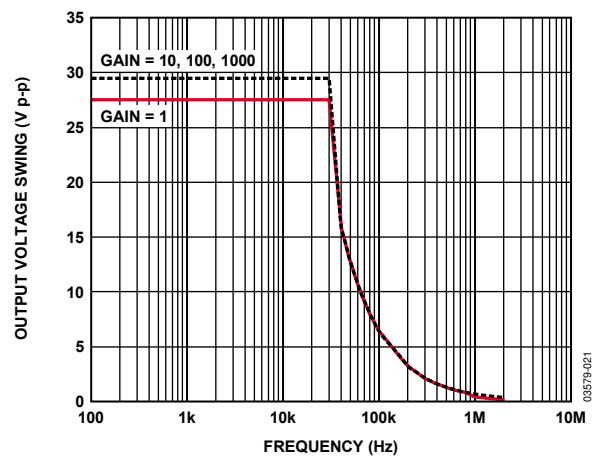


Figure 40. Output Voltage Swing vs. Large Signal Frequency Response

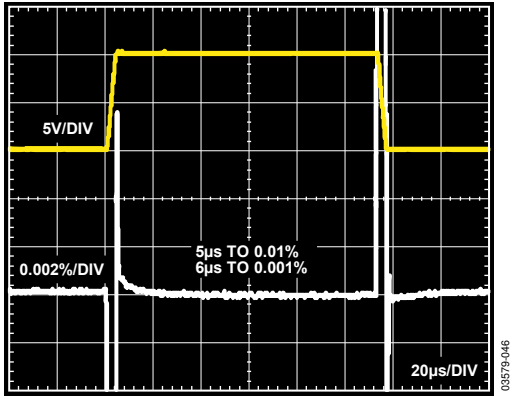


Figure 41. Large Signal Pulse Response and Settle Time,  $G = 1$ ,  $R_{LOAD} = 10\text{ k}\Omega$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

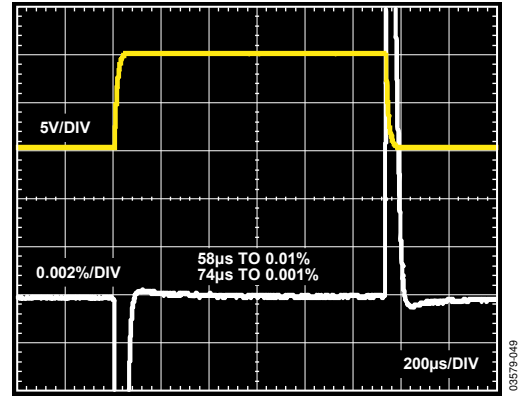


Figure 44. Large Signal Pulse Response and Settle Time,  $G = 1000$ ,  $R_{LOAD} = 10\text{ k}\Omega$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

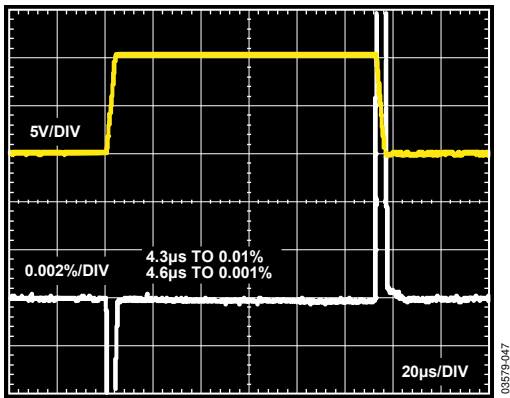


Figure 42. Large Signal Pulse Response and Settle Time,  $G = 10$ ,  $R_{LOAD} = 10\text{ k}\Omega$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

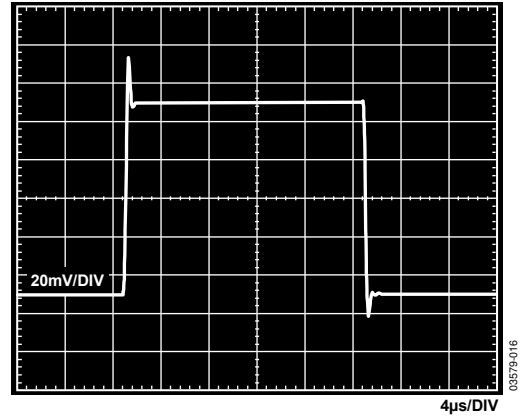


Figure 45. Small Signal Pulse Response,  $G = 1$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

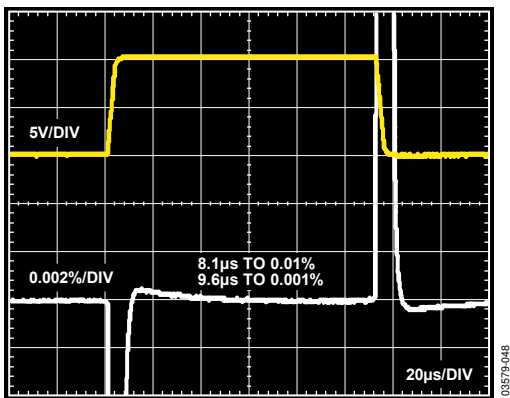


Figure 43. Large Signal Pulse Response and Settle Time,  $G = 100$ ,  $R_{LOAD} = 10\text{ k}\Omega$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

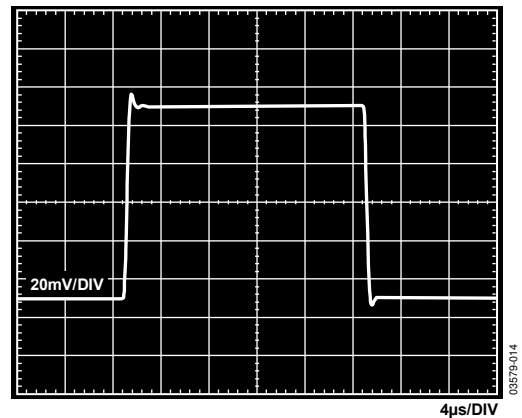


Figure 46. Small Signal Pulse Response,  $G = 10$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

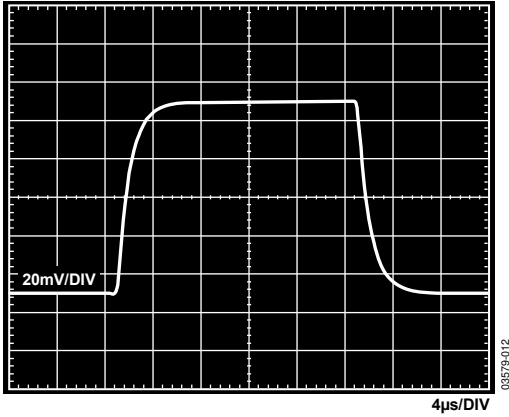


Figure 47 Small Signal Pulse Response,  $G = 100$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

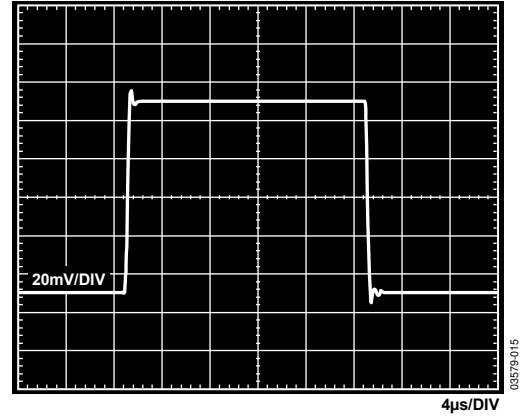


Figure 50. Small Signal Pulse Response,  $G = 10$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

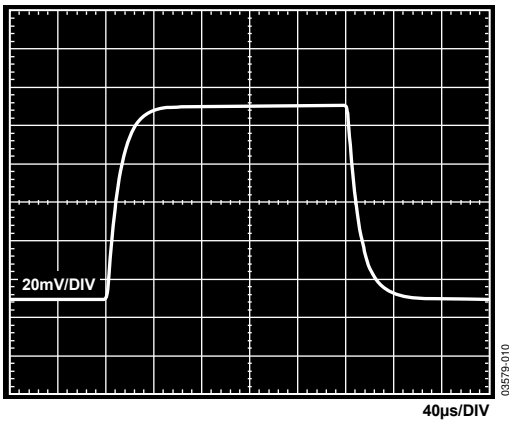


Figure 48. Small Signal Pulse Response,  $G = 1000$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = \pm 15\text{ V}$ ,  $V_{REF} = 0\text{ V}$

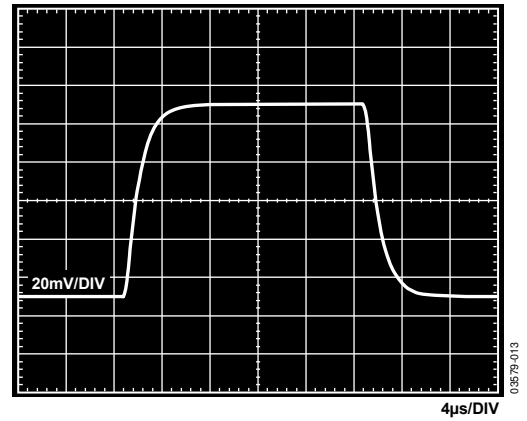


Figure 51. Small Signal Pulse Response,  $G = 100$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

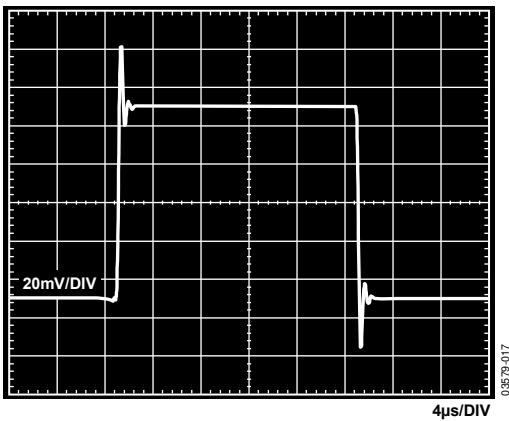


Figure 49. Small Signal Pulse Response,  $G = 1$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

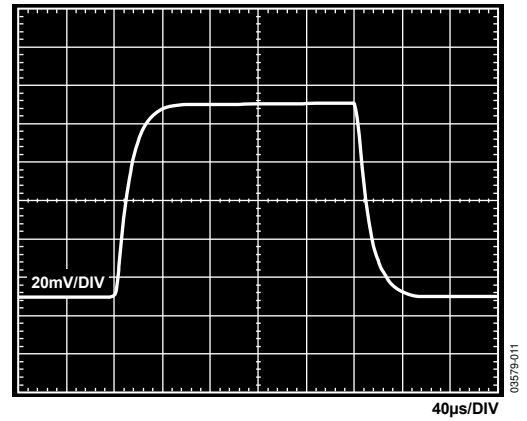


Figure 52. Small Signal Pulse Response,  $G = 1000$ ,  $R_{LOAD} = 2\text{ k}\Omega$ ,  $C_{LOAD} = 100\text{ pF}$ ,  $V_S = 5\text{ V}$ ,  $V_{REF} = 2.5\text{ V}$

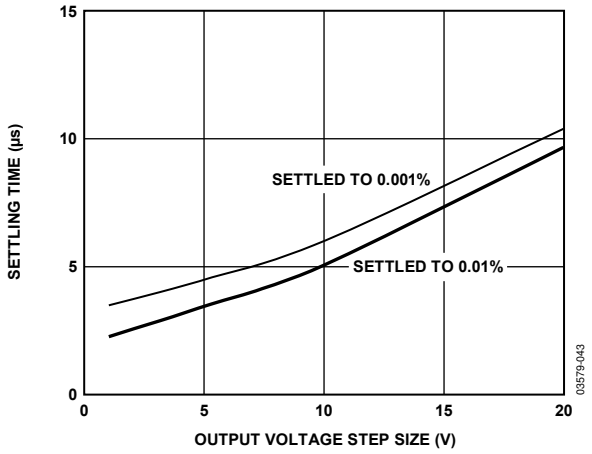


Figure 53. Settling Time vs. Output Voltage Step Size ( $G = 1$ )  $\pm 15$  V,  $V_{REF} = 0$  V

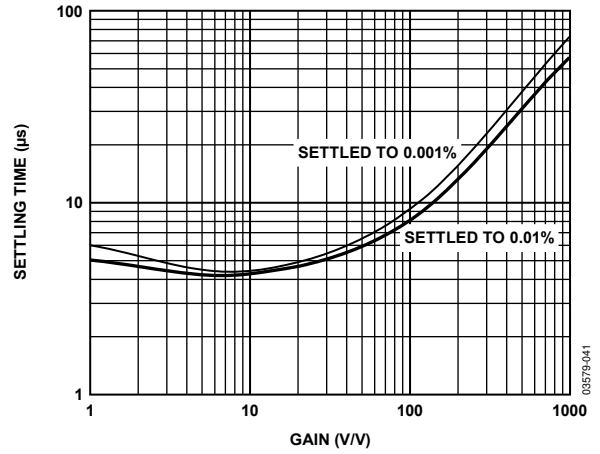


Figure 54. Settling Time vs. Gain for a 10 V Step,  $V_S = \pm 15$  V,  $V_{REF} = 0$  V

## THEORY OF OPERATION

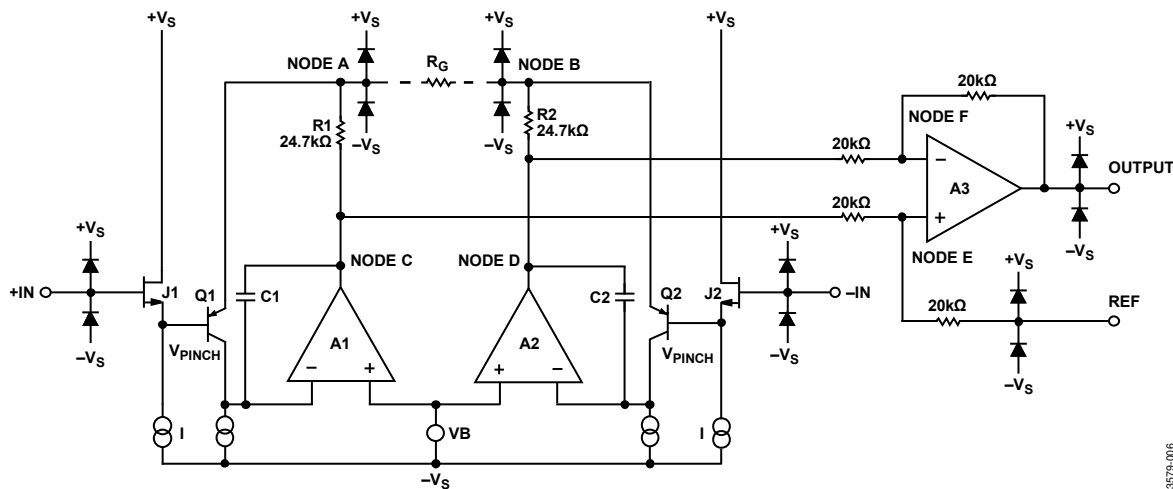


Figure 55. Simplified Schematic

03579-016

The AD8220 is a JFET input, monolithic instrumentation amplifier based on the classic 3-op amp topology (see Figure 55). Input Transistor J1 and Input Transistor J2 are biased at a fixed current so that any input signal forces the output voltages of A1 and A2 to change accordingly; the input signal creates a current through  $R_G$  that flows in R1 and R2 such that the outputs of A1 and A2 provide the correct, gained signal. Topologically, J1, A1, and R1 and J2, A2, and R2 can be viewed as precision current feedback amplifiers that have a gain bandwidth of 1.5 MHz. The common-mode voltage and amplified differential signal from A1 and A2 are applied to a difference amplifier that rejects the common-mode voltage but amplifies the differential signal. The difference amplifier employs 20 kΩ laser-trimmed resistors that result in an in-amp with gain error less than 0.04%. New trim techniques were developed to ensure that CMRR exceeds 86 dB ( $G = 1$ ).

Using JFET transistors, the AD8220 offers an extremely high input impedance, extremely low bias currents of 10 pA maximum, a low offset current of 0.6 pA maximum, and no input bias current noise. In addition, input offset is less than 125  $\mu\text{V}$  and drift is less than 5  $\mu\text{V}/^\circ\text{C}$ . Ease of use and robustness were considered. A common problem for instrumentation amplifiers is that at high gains, when the input is overdriven,<sup>1</sup> an excessive milliampere input bias current can result and the output can undergo phase reversal. The AD8220 has none of these problems; its input bias current is limited to less than 10  $\mu\text{A}$ , and the output does not phase reverse under overdrive fault conditions.

<sup>1</sup> Overdriving the input at high gains refers to when the input signal is within the supply voltages but the amplifier cannot output the gained signal. For example, at a gain of 100, driving the amplifier with 10 V on  $\pm 15$  V constitutes overdriving the inputs since the amplifier cannot output 100 V.

The AD8220 has extremely low load-induced nonlinearity. All amplifiers that comprise the AD8220 have rail-to-rail output capability for enhanced dynamic range. The input of the AD8220 can amplify signals with wide common-mode voltages even slightly lower than the negative supply rail. The AD8220 operates over a wide supply voltage range. It can operate from either a single +4.5 V to +36 V supply or a dual  $\pm 2.25$  V to  $\pm 18$  V. The transfer function of the AD8220 is

$$G = 1 + \frac{49.4 \text{ k}\Omega}{R_G}$$

Users can easily and accurately set the gain using a single, standard resistor. Because the input amplifiers employ a current feedback architecture, the AD8220 gain-bandwidth product increases with gain, resulting in a system that does not suffer as much bandwidth loss as voltage feedback architectures at higher gains. A unique pinout enables the AD8220 to meet a CMRR specification of 80 dB through 5 kHz ( $G = 1$ ). The balanced pinout, shown in Figure 56, reduces parasitics that adversely affect CMRR performance. In addition, the new pinout simplifies board layout because associated traces are grouped together. For example, the gain setting resistor pins are adjacent to the inputs, and the reference pin is next to the output.

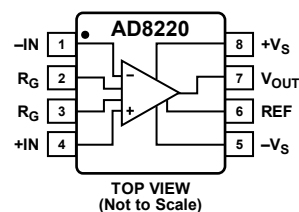


Figure 56. Pin Configuration

03579-005

# AD8220

## GAIN SELECTION

Placing a resistor across the  $R_G$  terminals sets the AD8220 gain, which can be calculated by referring to Table 5 or by using the gain equation

$$R_G = \frac{49.4 \text{ k}\Omega}{G - 1}$$

**Table 5. Gains Achieved Using 1% Resistors**

1% Standard Table Value of $R_G$ ( $\Omega$ )	Calculated Gain
49.9 k	1.990
12.4 k	4.984
5.49 k	9.998
2.61 k	19.93
1.00 k	50.40
499	100.0
249	199.4
100	495.0
49.9	991.0

The AD8220 defaults to  $G = 1$  when no gain resistor is used. Gain accuracy is determined by the absolute tolerance of  $R_G$ . The TC of the external gain resistor increases the gain drift of the instrumentation amplifier. Gain error and gain drift are kept to a minimum when the gain resistor is not used.

## LAYOUT

Careful board layout maximizes system performance. In applications that need to take advantage of the low input bias current of the AD8220, avoid placing metal under the input path to minimize leakage current. To maintain high CMRR over frequency, lay out the input traces symmetrically and lay out the traces of the  $R_G$  resistor symmetrically. Ensure that the traces maintain resistive and capacitive balance; this holds for additional PCB metal layers under the input and  $R_G$  pins. Traces from the

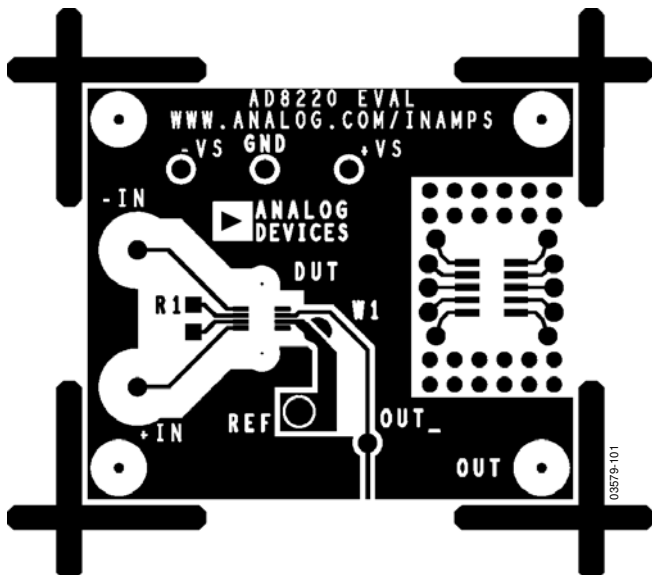


Figure 57. Example Layout—Top Layer of the AD8220 Evaluation Board

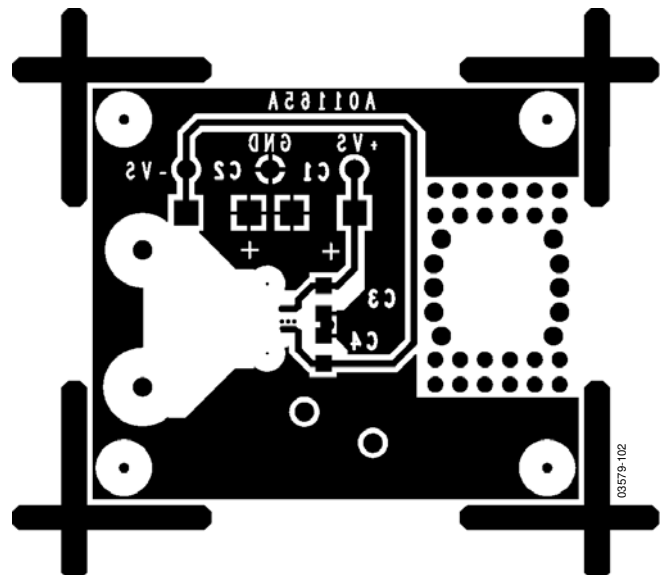


Figure 58. Example Layout—Bottom Layer of the AD8220 Evaluation Board

gain setting resistor to the  $R_G$  pins should be kept as short as possible to minimize parasitic inductance. An example layout is shown in Figure 57 and Figure 58. To ensure the most accurate output, the trace from the REF pin should either be connected to the AD8220 local ground (see Figure 59) or connected to a voltage that is referenced to the AD8220 local ground.

## Common-Mode Rejection Ratio (CMRR)

The AD8220 has high CMRR over frequency giving it greater immunity to disturbances, such as line noise and its associated harmonics, in contrast to typical in-amps whose CMRR falls off around 200 Hz. These in-amps often need common-mode filters at the inputs to compensate for this shortcoming. The AD8220 is able to reject CMRR over a greater frequency range, reducing the need for input common-mode filtering.

A well-implemented layout helps to maintain the high CMRR over frequency of the AD8220. Input source impedance and capacitance should be closely matched. In addition, source resistance and capacitance should be placed as close to the inputs as possible.

## Grounding

The output voltage of the AD8220 is developed with respect to the potential on the reference terminal. Care should be taken to tie REF to the appropriate local ground (see Figure 59).

In mixed-signal environments, low level analog signals need to be isolated from the noisy digital environment. Many ADCs have separate analog and digital ground pins. Although it is convenient to tie both grounds to a single ground plane, the current traveling through the ground wires and PC board can cause a large error. Therefore, separate analog and digital ground returns should be used to minimize the current flow from sensitive points to the system ground.

## REFERENCE TERMINAL

The reference terminal, REF, is at one end of a 20 k $\Omega$  resistor (see Figure 55). The output of the instrumentation amplifier is referenced to the voltage on the REF terminal; this is useful when the output signal needs to be offset to voltages other than common. For example, a voltage source can be tied to the REF pin to level-shift the output so that the AD8220 can interface with an ADC. The allowable reference voltage range is a function of the gain, common-mode input, and supply voltages. The REF pin should not exceed either +V<sub>s</sub> or -V<sub>s</sub> by more than 0.5 V.

For best performance, especially in cases where the output is not measured with respect to the REF terminal, source impedance to the REF terminal should be kept low, because parasitic resistance can adversely affect CMRR and gain accuracy.

## POWER SUPPLY REGULATION AND BYPASSING

The AD8220 has high PSRR. However, for optimal performance, a stable dc voltage should be used to power the instrumentation amplifier. Noise on the supply pins can adversely affect performance. As in all linear circuits, bypass capacitors must be used to decouple the amplifier.

A 0.1  $\mu$ F capacitor should be placed close to each supply pin. A 10  $\mu$ F tantalum capacitor can be used further away from the part (see Figure 59). In most cases, it can be shared by other precision integrated circuits.

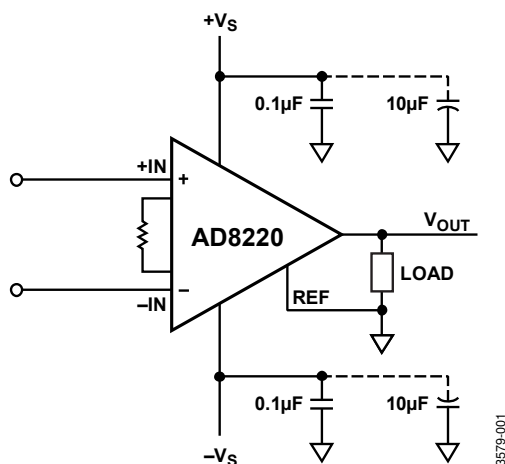


Figure 59. Supply Decoupling, REF and Output Referred to Ground

## INPUT BIAS CURRENT RETURN PATH

The AD8220 input bias current is extremely small at less than 10 pA. Nonetheless, the input bias current must have a return path to common. When the source, such as a transformer, cannot provide a return current path, one should be created (see Figure 60).

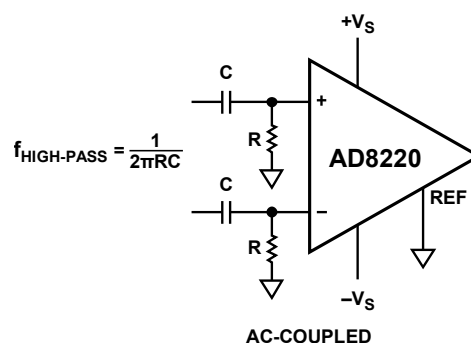
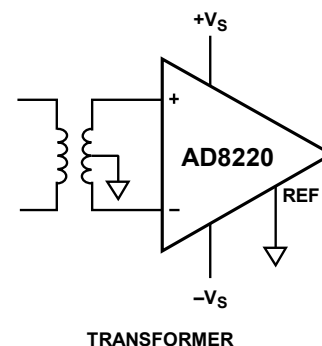


Figure 60. Creating an I<sub>BIAS</sub> Path

## INPUT PROTECTION

All terminals of the AD8220 are protected against ESD. (ESD protection is guaranteed to 4 kV, human body model.) In addition, the input structure allows for dc overload conditions a diode drop above the positive supply and a diode drop below the negative supply. Voltages beyond a diode drop of the supplies cause the ESD diodes to conduct and enable current to flow through the diode. Therefore, an external resistor should be used in series with each of the inputs to limit current for voltages above +V<sub>s</sub>. In either scenario, the AD8220 safely handles a continuous 6 mA current at room temperature.

For applications where the AD8220 encounters extreme overload voltages, as in cardiac defibrillators, external series resistors and low leakage diode clamps, such as BAV199Ls, FJH1100s, or SP720s, should be used.

# AD8220

## RF INTERFERENCE

RF rectification is often a problem in applications where there are large RF signals. The problem appears as a small dc offset voltage. The AD8220 by its nature has a 5 pF gate capacitance,  $C_G$ , at its inputs. Matched series resistors form a natural low-pass filter that reduces rectification at high frequency (see Figure 61). The relationship between external, matched series resistors and the internal gate capacitance is expressed as follows:

$$FilterFreq_{DIFF} = \frac{1}{2\pi RC_G}$$

$$FilterFreq_{CM} = \frac{1}{2\pi RC_G}$$

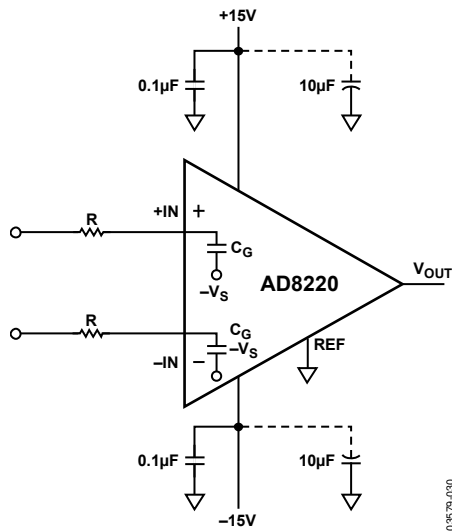


Figure 61. RF Filtering Without External Capacitors

To eliminate high frequency common-mode signals while using smaller source resistors, a low-pass RC network can be placed at the input of the instrumentation amplifier (see Figure 62). The filter limits the input signal bandwidth according to the following relationship:

$$FilterFreq_{DIFF} = \frac{1}{2\pi R(2C_D + C_C + C_G)}$$

$$FilterFreq_{CM} = \frac{1}{2\pi R(C_C + C_G)}$$

Mismatched  $C_C$  capacitors result in mismatched low-pass filters. The imbalance causes the AD8220 to treat what would have been a common-mode signal as a differential signal. To reduce the effect of mismatched external  $C_C$  capacitors, select a value of  $C_D$  greater than 10 times  $C_C$ . This sets the differential filter frequency lower than the common-mode frequency.

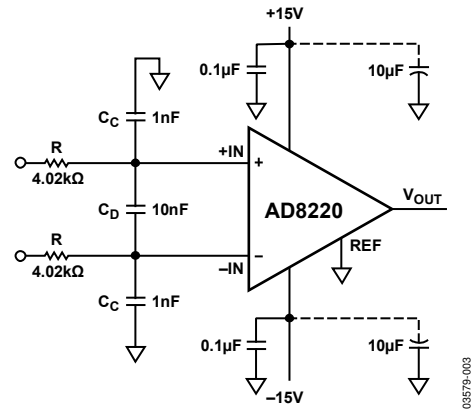


Figure 62. RFI Suppression

## COMMON-MODE INPUT VOLTAGE RANGE

The common-mode input voltage range is a function of the input range and the outputs of Internal Amplifier A1, Internal Amplifier A2, and Internal Amplifier A3, the reference voltage, and the gain. Figure 27 to Figure 30 show common-mode voltage ranges for various supply voltages and gains.

## DRIVING AN ADC

An instrumentation amplifier is often used in front of an ADC to provide CMRR and additional conditioning, such as a voltage level shift and gain (see Figure 63). In this example, a 2.7 nF capacitor and a 1 kΩ resistor create an antialiasing filter for the AD7685. The 2.7 nF capacitor also serves to store and deliver the necessary charge to the switched capacitor input of the ADC. The 1 kΩ series resistor reduces the burden of the 2.7 nF load from the amplifier. However, large source impedance in front of the ADC can degrade THD.

The example shown in Figure 63 is for sub-60 kHz applications. For higher bandwidth applications where THD is important, the series resistor needs to be small. At worst, a small series resistor can load the AD8220, potentially causing the output to overshoot or ring. In such cases, a buffer amplifier, such as the AD8615, should be used after the AD8220 to drive the ADC.

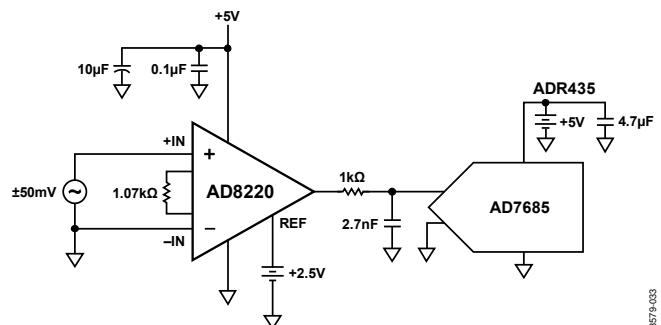


Figure 63. Driving an ADC in a Low Frequency Application

## APPLICATIONS INFORMATION

### AC-COUPLED INSTRUMENTATION AMPLIFIER

Measuring small signals that are in the noise or offset of the amplifier can be a challenge. Figure 64 shows a circuit that can improve the resolution of small ac signals. The large gain reduces the referred input noise of the amplifier to 14 nV/√Hz. Therefore, smaller signals can be measured because the noise floor is lower. DC offsets that would have been gained by 100 are eliminated from the AD8220 output by the integrator feedback network.

At low frequencies, the OP1177 forces the AD8220 output to 0 V. Once a signal exceeds  $f_{\text{HIGH-PASS}} = \frac{1}{2\pi RC}$ , the AD8220 outputs the amplified input signal.

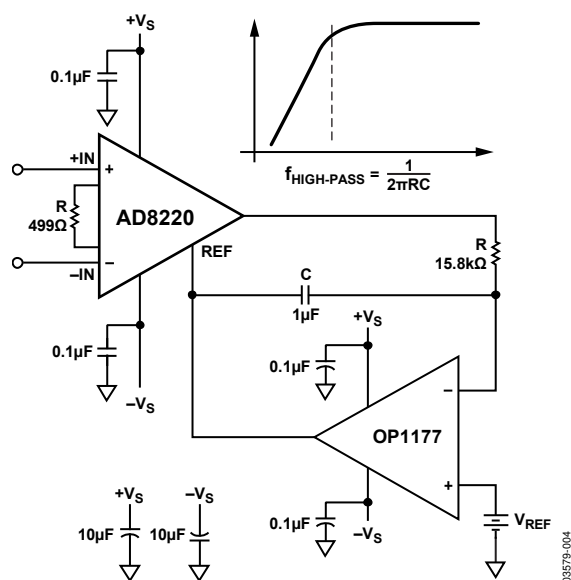


Figure 64. AC-Coupled Circuit

### DIFFERENTIAL OUTPUT

In certain applications, it is necessary to create a differential signal. New high resolution ADCs often require a differential input. In other cases, transmission over a long distance can require differential processing for better immunity to interference.

Figure 65 shows how to configure the AD8220 to output a differential signal. An OP1177 op amp is used to create a differential voltage. Errors from the op amp are common to both outputs and are thus common mode. Likewise, errors from using mismatched resistors cause a common-mode dc offset error. Such errors are rejected in differential signal processing by differential input ADCs or instrumentation amplifiers.

When using this circuit to drive a differential ADC,  $V_{\text{REF}}$  can be set using a resistor divider from the reference of the ADC to make the output ratiometric with the ADC as shown in Figure 66.

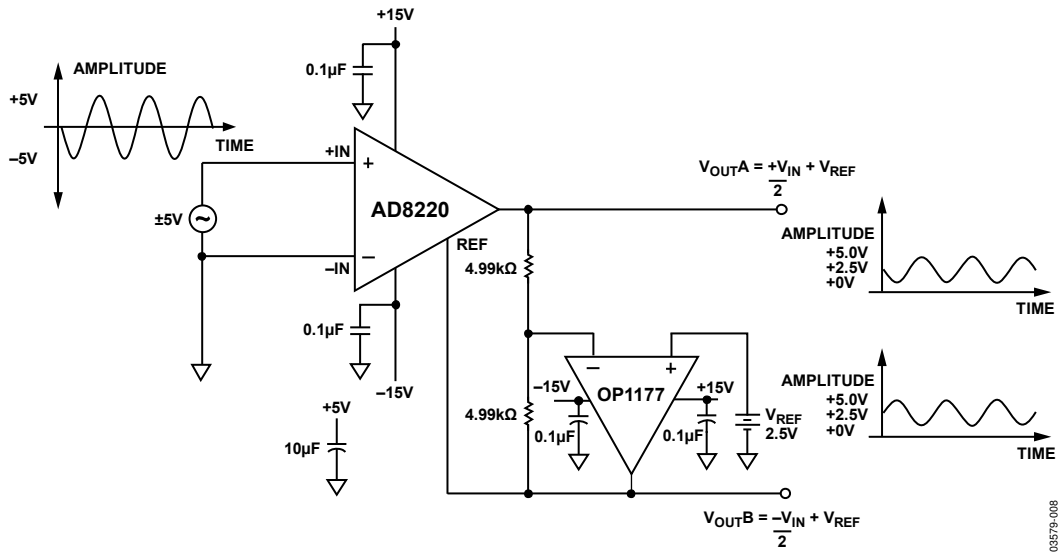


Figure 65. Differential Output with Level Shift

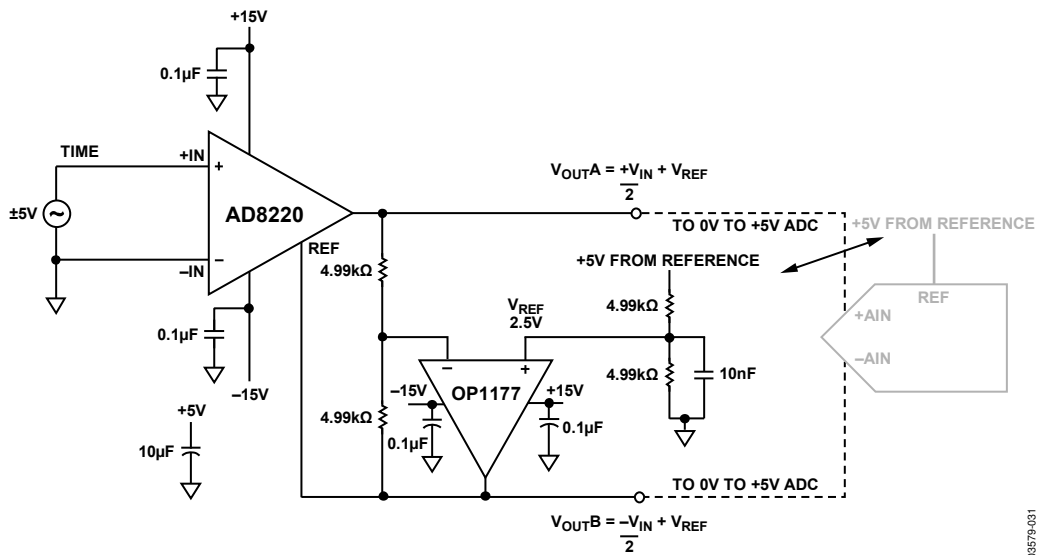


Figure 66. Configuring the AD8220 to Output A Ratiometric, Differential Signal