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## Precision, 20 MHz, CMOS, Rail-to-Rail Input/Output Operational Amplifiers

## Data Sheet **AD8615/AD8616/AD8618**

#### **FEATURES**

**Low offset voltage: 65 µV maximum Single-supply operation: 2.7 V to 5.0 V Low noise: 8 nV/√Hz Wide bandwidth: >20 MHz Slew rate: 12 V/µs High output current: 150 mA No phase reversal Low input bias current: 1 pA Low supply current: 2 mA Unity-gain stable** 

#### **APPLICATIONS**

**Barcode scanners Battery-powered instrumentation Multipole filters Sensors ASIC input or output amplifiers Audio Photodiode amplification** 

#### **GENERAL DESCRIPTION**

The AD8615/AD8616/AD8618 are single/dual/quad, rail**-**torail, input and output, single-supply amplifiers featuring very low offset voltage, wide signal bandwidth, and low input voltage and current noise. The parts use a patented trimming technique that achieves superior precision without laser trimming. The AD8615/AD8616/AD8618 are fully specified to operate from 2.7 V to 5 V single supplies.

The combination of >20 MHz bandwidth, low offset, low noise, and low input bias current makes these amplifiers useful in a wide variety of applications. Filters, integrators, photodiode amplifiers, and high impedance sensors all benefit from the combination of performance features. AC applications benefit from the wide bandwidth and low distortion. The AD8615/AD8616/ AD8618 offer the highest output drive capability of the DigiTrim® family, which is excellent for audio line drivers and other low impedance applications.

Applications for the parts include portable and low powered instrumentation, audio amplification for portable devices, portable phone headsets, bar code scanners, and multipole filters. The ability to swing rail-to-rail at both the input and output enables designers to buffer CMOS ADCs, DACs, ASICs, and other wide output swing devices in single-supply systems.

**Rev. G Document Feedback** 

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### **PIN CONFIGURATIONS**



Figure 5. 14-Lead SOIC (R-14)

The AD8615/AD8616/AD8618 are specified over the extended industrial temperature range (−40°C to +125°C). The AD8615 is available in 5-lead TSOT-23 package. The AD8616 is available in 8-lead MSOP and narrow SOIC surface-mount packages; the MSOP version is available in tape and reel only. The AD8618 is available in 14-lead SOIC and TSSOP packages.

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**1/04—Revision 0: Initial Version**

### **SPECIFICATIONS**

 $\rm V_S$  = 5 V,  $\rm V_{\rm CM}$  = Vs/2, T $\rm A$  = 25°C, unless otherwise noted.

### **Table 1.**



 $V_s = 2.7$  V,  $V_{CM} = V_s/2$ ,  $T_A = 25$ °C, unless otherwise noted.

### **Table 2.**



### ABSOLUTE MAXIMUM RATINGS

#### **Table 3.**



Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **THERMAL RESISTANCE**

θ<sub>JA</sub> is specified for the worst-case conditions, that is, θ<sub>JA</sub> is specified for a device soldered in a circuit board for surface-mount packages.

#### **Table 4.**



#### **ESD CAUTION**



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

### TYPICAL PERFORMANCE CHARACTERISTICS



Figure 6. Input Offset Voltage Distribution



Figure 7. Offset Voltage Drift Distribution







Figure 9. Input Bias Current vs. Temperature



Figure 10. Output Voltage to Supply Rail vs. Load Current



Figure 11. Output Saturation Voltage vs. Temperature

### Data Sheet **AD8615/AD8616/AD8618**



Figure 12. Open-Loop Gain and Phase vs. Frequency



Figure 13. Closed-Loop Output Voltage Swing vs. Frequency



Figure 14. Output Impedance vs. Frequency









Figure 17. Small-Signal Overshoot vs. Load Capacitance

04648-015



Figure 18. Supply Current vs. Temperature







Figure 20. Voltage Noise Density vs. Frequency















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### Data Sheet **AD8615/AD8616/AD8618**



Figure 27. Input Offset Voltage vs. Common-Mode Voltage (200 Units, Five Wafer Lots Including Process Skews)



Figure 28. Input Offset Voltage vs. Common-Mode Voltage (200 Units, Five Wafer Lots Including Process Skews)



Figure 29. Output Voltage to Supply Rail vs. Load Current



### APPLICATIONS INFORMATION **INPUT OVERVOLTAGE PROTECTION**

If the voltage applied at either input exceeds the supplies, place external resistors in series with the inputs. The resistor values can be determined by the equation

$$
\frac{V_{IN} - V_{SY}}{R_S} < 5 \, \text{mA}
$$

The extremely low input bias current allows the use of larger resistors, which allows the user to apply higher voltages at the inputs. The use of these resistors adds thermal noise, which contributes to the overall output voltage noise of the amplifier.

For example, a 10 kΩ resistor has less than 13 nV/ $\sqrt{Hz}$  of thermal noise and less than 10 nV of error voltage at room temperature.

### **OUTPUT PHASE REVERSAL**

The AD8615/AD8616/AD8618 are immune to phase inversion, a phenomenon that occurs when the voltage applied at the input of the amplifier exceeds the maximum input common mode.

Phase reversal can cause permanent damage to the amplifier and can create lock ups in systems with feedback loops.



#### **DRIVING CAPACITIVE LOADS**

Although the AD8615/AD8616/AD8618 are capable of driving capacitive loads of up to 500 pF without oscillating, a large amount of overshoot is present when operating at frequencies above 100 kHz. This is especially true when the amplifier is configured in positive unity gain (worst case). When such large capacitive loads are required, the use of external compensation is highly recommended.

This reduces the overshoot and minimizes ringing, which in turn improves the frequency response of the AD8615/AD8616/ AD8618. One simple technique for compensation is the snubber, which consists of a simple RC network. With this circuit in place, output swing is maintained and the amplifier is stable at all gains.

Figure 38 shows the implementation of the snubber, which reduces overshoot by more than 30% and eliminates ringing that can cause instability. Using the snubber does not recover the loss of bandwidth incurred from a heavy capacitive load.



Figure 37. Driving Heavy Capacitive Loads Without Compensation





Figure 39. Driving Heavy Capacitive Loads Using the Snubber Network

#### **OVERLOAD RECOVERY TIME**

Overload recovery time is the time it takes the output of the amplifier to come out of saturation and recover to its linear region. Overload recovery is particularly important in applications where small signals must be amplified in the presence of large transients. Figure 40 and Figure 41 show the positive and negative overload recovery times of the AD8616. In both cases, the time elapsed before the AD8616 comes out of saturation is less than 1 μs. In addition, the symmetry between the positive and negative recovery times allows excellent signal rectification without distortion to the output signal.





### **D/A CONVERSION**

The AD8616 can be used at the output of high resolution DACs. The low offset voltage, fast slew rate, and fast settling time make the part suitable to buffer voltage output or current output DACs.

Figure 42 shows an example of the AD8616 at the output of the AD5542. The AD8616's rail-to-rail output and low distortion help maintain the accuracy needed in data acquisition systems and automated test equipment.



#### **LOW NOISE APPLICATIONS**

Although the AD8618 typically has less than 8 nV/ $\sqrt{Hz}$  of voltage noise density at 1 kHz, it is possible to reduce it further. A simple method is to connect the amplifiers in parallel, as shown in Figure 43. The total noise at the output is divided by the square root of the number of amplifiers. In this case, the total noise is approximately 4 nV/ $\sqrt{Hz}$  at room temperature. The 100  $\Omega$ resistor limits the current and provides an effective output resistance of 50  $Ω$ .



Figure 43. Noise Reduction

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### **HIGH SPEED PHOTODIODE PREAMPLIFIER**

The AD8615/AD8616/AD8618 are excellent choices for I-to-V conversions. The very low input bias, low current noise, and high unity-gain bandwidth of the parts make them suitable, especially for high speed photodiode preamplifiers.

In high speed photodiode applications, the diode is operated in a photoconductive mode (reverse biased). This lowers the junction capacitance at the expense of an increase in the amount of dark current that flows out of the diode.

The total input capacitance, C1, is the sum of the diode and op amp input capacitances. This creates a feedback pole that causes degradation of the phase margin, making the op amp unstable. Therefore, it is necessary to use a capacitor in the feedback to compensate for this pole.

To get the maximum signal bandwidth, select

$$
C2 = \sqrt{\frac{C1}{2\pi R2 f_U}}
$$

where  $f_U$  is the unity-gain bandwidth of the amplifier.



Figure 44. High Speed Photodiode Preamplifier

### **ACTIVE FILTERS**

The low input bias current and high unity-gain bandwidth of the AD8616 make it an excellent choice for precision filter design.

Figure 45 shows the implementation of a second-order, low-pass filter. The Butterworth response has a corner frequency of 100 kHz and a phase shift of 90°. The frequency response is shown in Figure 46.



Figure 45. Second-Order, Low-Pass Filter



Figure 46. Second-Order Butterworth, Low-Pass Filter Frequency Response

#### **POWER DISSIPATION**

Although the AD8615/AD8616/AD8618 are capable of providing load currents up to 150 mA, the usable output, load current, and drive capability are limited to the maximum power dissipation allowed by the device package.

In any application, the absolute maximum junction temperature for the AD8615/AD8616/AD8618 is 150°C. This should never be exceeded because the device could suffer premature failure. Accurately measuring power dissipation of an integrated circuit is not always a straightforward exercise; Figure 47 is a design aid for setting a safe output current drive level or selecting a heat sink for the package options available on the AD8616.



Figure 47. Maximum Power Dissipation vs. Ambient Temperature

These thermal resistance curves were determined using the AD8616 thermal resistance data for each package and a maximum junction temperature of 150°C.

### Data Sheet **AD8615/AD8616/AD8618**

The following formula can be used to calculate the internal junction temperature of the AD8615/AD8616/AD8618 for any application:

 $T_I = P_{DISS} \times \theta_{IA} + T_A$ 

where:

 $T_J$  = junction temperature  $P<sub>DISS</sub>$  = power dissipation  $\theta_{JA}$  = package thermal resistance, junction-to-case  $T_A$  = ambient temperature of the circuit

To calculate the power dissipated by the AD8615/AD8616/ AD8618, use the following:

 $P_{DISS} = I_{LOAD} \times (V_S - V_{OUT})$ 

where:

 $I_{LOAD}$  = output load current  $V_s$  = supply voltage  $V_{OUT} =$  output voltage

The quantity within the parentheses is the maximum voltage developed across either output transistor.

#### **POWER CALCULATIONS FOR VARYING OR UNKNOWN LOADS**

Often, calculating power dissipated by an integrated circuit to determine if the device is being operated in a safe range is not as simple as it may seem. In many cases, power cannot be directly measured. This may be the result of irregular output waveforms or varying loads. Indirect methods of measuring power are required.

There are two methods to calculate power dissipated by an integrated circuit. The first is to measure the package temperature and the board temperature. The second is to directly measure the circuit's supply current.

#### **Calculating Power by Measuring Ambient Temperature and Case Temperature**

The two equations for calculating the junction temperature are

 $T_J = T_A + P \theta_{JA}$ 

where:

 $T_l$  = junction temperature

 $T_A$  = ambient temperature

 $\theta_{JA}$  = the junction-to-ambient thermal resistance

 $T_I = T_C + P \theta_{IC}$ 

where:  $T<sub>C</sub>$  is case temperature.

 $\theta_{JA}$  and  $\theta_{JC}$  are given in the data sheet.

The two equations for calculating P (power) are

$$
T_A + P \theta_{JA} = T_C + P \theta_{JC}
$$

$$
P = (T_A - T_C)/(\theta_{JC} - \theta_{IA})
$$

Once the power is determined, it is necessary to recalculate the junction temperature to ensure that the temperature was not exceeded.

The temperature should be measured directly on and near the package but not touching it. Measuring the package can be difficult. A very small bimetallic junction glued to the package can be used, or an infrared sensing device can be used, if the spot size is small enough.

#### **Calculating Power by Measuring Supply Current**

If the supply voltage and current are known, power can be calculated directly. However, the supply current can have a dc component with a pulse directed into a capacitive load, which can make the rms current very difficult to calculate. This difficulty can be overcome by lifting the supply pin and inserting an rms current meter into the circuit. For this method to work, make sure the current is delivered by the supply pin being measured. This is usually a good method in a single-supply system; however, if the system uses dual supplies, both supplies may need to be monitored.

### OUTLINE DIMENSIONS





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### **ORDERING GUIDE**



 $1 Z =$  RoHS Compliant Part.

### **NOTES**

### **NOTES**

### **NOTES**

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