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## FEATURES

400 MSPS internal clock speed
Integrated 14-bit DAC
32-bit tuning word
Phase noise $\leq-120 \mathbf{d B c} / \mathrm{Hz}$ at $\mathbf{1 k H z}$ offset (DAC output)
Excellent dynamic performance
$>80 \mathrm{~dB}$ SFDR at $\mathbf{1 6 0 ~ M H z ~ ( ~} \mathbf{\pm 1 0 0} \mathbf{~ k H z}$ offset) Aоut
Serial input/output (I/O) control
1.8 V power supply

Software and hardware controlled power-down
48-lead TQFP/EP package

PLL REFCLK multiplier ( $4 \times$ to $20 \times$ )
Internal oscillator, can be driven by a single crystal Phase modulation capability
Multichip synchronization

## APPLICATIONS

Agile VHF/UHF LO frequency synthesis
FM chirp source for radar and scanning systems
Nonlinear-shaped PSK/FSK modulator
Test and measurement equipment

FUNCTIONAL BLOCK DIAGRAM


## COMPARABLE PARTS

View a parametric search of comparable parts.

## DOCUMENTATION

## Application Notes

- AN-237: Choosing DACs for Direct Digital Synthesis
- AN-280: Mixed Signal Circuit Technologies
- AN-342: Analog Signal-Handling for High Speed and Accuracy
- AN-345: Grounding for Low-and-High-Frequency Circuits
- AN-419: A Discrete, Low Phase Noise, 125 MHz Crystal Oscillator for the AD9850
- AN-423: Amplitude Modulation of the AD9850 Direct Digital Synthesizer
- AN-543: High Quality, All-Digital RF Frequency Modulation Generation with the ADSP-2181 and the AD9850 DDS
- AN-557: An Experimenter's Project:
- AN-587: Synchronizing Multiple AD9850/AD9851 DDSBased Synthesizers
- AN-605: Synchronizing Multiple AD9852 DDS-Based Synthesizers
- AN-621: Programming the AD9832/AD9835
- AN-632: Provisionary Data Rates Using the AD9951 DDS as an Agile Reference Clock for the ADN2812 ContinuousRate CDR
- AN-769: Generating Multiple Clock Outputs from the AD9540
- AN-823: Direct Digital Synthesizers in Clocking Applications Time
- AN-837: DDS-Based Clock Jitter Performance vs. DAC Reconstruction Filter Performance
- AN-843: Measuring a Loudspeaker Impedance Profile Using the AD5933
- AN-847: Measuring a Grounded Impedance Profile Using the AD5933
- AN-851: A WiMax Double Downconversion IF Sampling Receiver Design
- AN-927: Determining if a Spur is Related to the DDS/DAC or to Some Other Source (For Example, Switching Supplies)
- AN-939: Super-Nyquist Operation of the AD9912 Yields a High RF Output Signal
- AN-953: Direct Digital Synthesis (DDS) with a Programmable Modulus
Data Sheet
- AD9953: 400 MSPS, 14-Bit, 1.8 V CMOS Direct Digital Synthesizer Data Sheet


## Product Highlight

- Introducing Digital Up/Down Converters: VersaCOMM ${ }^{\text {™ }}$ Reconfigurable Digital Converters


## Technical Books

- A Technical Tutorial on Digital Signal Synthesis, 1999


## TOOLS AND SIMULATIONS

- ADIsimDDS (Direct Digital Synthesis)


## REFERENCE MATERIALS $\square$

## Product Selection Guide

- RF Source Booklet


## Technical Articles

- 400-MSample DDSs Run On Only +1.8 VDC
- ADI Buys Korean Mobile TV Chip Maker
- Basics of Designing a Digital Radio Receiver (Radio 101)
- DDS Applications
- DDS Circuit Generates Precise PWM Waveforms
- DDS Design
- DDS Device Produces Sawtooth Waveform
- DDS Device Provides Amplitude Modulation
- DDS IC Initiates Synchronized Signals
- DDS IC Plus Frequency-To-Voltage Converter Make LowCost DAC
- DDS Simplifies Polar Modulation
- Digital Potentiometers Vary Amplitude In DDS Devices
- Digital Up/Down Converters: VersaCOMM ${ }^{\text {™ }}$ White Paper
- Digital Waveform Generator Provides Flexible Frequency Tuning for Sensor Measurement
- Improved DDS Devices Enable Advanced Comm Systems
- Integrated DDS Chip Takes Steps To 2.7 GHz
- Simple Circuit Controls Stepper Motors
- Speedy A/Ds Demand Stable Clocks
- Synchronized Synthesizers Aid Multichannel Systems
- The Year of the Waveform Generator
- Two DDS ICs Implement Amplitude-shift Keying
- Video Portables and Cameras Get HDMI Outputs


## DESIGN RESOURCES

- AD9953 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints


## DISCUSSIONS

View all AD9953 EngineerZone Discussions.

## SAMPLE AND BUY $\square$

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## DOCUMENT FEEDBACK

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## GENERAL DESCRIPTION

The AD9953 is a direct digital synthesizer (DDS) featuring a 14-bit DAC operating up to 400 MSPS. The AD9953 uses advanced DDS technology, coupled with an internal high speed, high performance DAC to form a digitally programmable, complete high frequency synthesizer capable of generating a frequency-agile analog output sinusoidal waveform at up to 200 MHz . The AD9953 includes an integrated $1024 \times 32$ static RAM to support flexible frequency sweep capability in several
modes. The AD9953 is designed to provide fast frequency hopping and fine tuning resolution (32-bit frequency tuning word). The frequency tuning and control words are loaded into the AD9953 via a serial I/O port.
The AD9953 is specified to operate over the extended industrial temperature range of $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$.

## ELECTRICAL SPECIFICATIONS

Table 1. Unless otherwise noted, AVDD, DVDD $=1.8 \mathrm{~V} \pm 5 \%$, DVDD_I/O $=3.3 \mathrm{~V} \pm 5 \%$, R $\mathrm{R}_{\mathrm{SE}}=3.92 \mathrm{k} \Omega$, External Reference Clock Frequency $=20 \mathrm{MHz}$ with REFCLK Multiplier Enabled at 20×. DAC Output Must Be Referenced to AVDD, Not AGND.

| Parameter | Temp | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF CLOCK INPUT CHARACTERISTICS |  |  |  |  |  |
| Frequency Range |  |  |  |  |  |
| REFCLK Multiplier Disabled | FULL | 1 |  | 400 | MHz |
| REFCLK Multiplier Enabled at $4 \times$ | FULL | 20 |  | 100 | MHz |
| REFCLK Multiplier Enabled at 20× | FULL | 4 |  | 20 | MHz |
| Input Capacitance | $25^{\circ} \mathrm{C}$ |  | 3 |  | pF |
| Input Impedance | $25^{\circ} \mathrm{C}$ |  | 1.5 |  | k $\Omega$ |
| Duty Cycle | $25^{\circ} \mathrm{C}$ |  | 50 |  | \% |
| Duty Cycle with REFCLK Multiplier Enabled | $25^{\circ} \mathrm{C}$ | 35 |  | 65 |  |
| REFCLK Input Power ${ }^{1}$ | FULL | -15 | 0 | +3 | dBm |
| DAC OUTPUT CHARACTERISTICS |  |  |  |  |  |
| Resolution |  |  | 14 |  | Bits |
| Full-Scale Output Current | $25^{\circ} \mathrm{C}$ | 5 | 10 | 15 | mA |
| Gain Error | $25^{\circ} \mathrm{C}$ | -10 |  | +10 | \%FS |
| Output Offset | $25^{\circ} \mathrm{C}$ |  |  | 0.6 | $\mu \mathrm{A}$ |
| Differential Nonlinearity | $25^{\circ} \mathrm{C}$ |  | 1 |  | LSB |
| Integral Nonlinearity | $25^{\circ} \mathrm{C}$ |  | 2 |  | LSB |
| Output Capacitance | $25^{\circ} \mathrm{C}$ |  | 5 |  | pF |
| Residual Phase Noise @ 1 kHz Offset, 40 MHz Aout |  |  |  |  |  |
| REFCLK Multiplier Enabled @ 20× | $25^{\circ} \mathrm{C}$ |  | -105 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| REFCLK Multiplier Enabled @ $4 \times$ | $25^{\circ} \mathrm{C}$ |  | -115 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| REFCLK Multiplier Disabled | $25^{\circ} \mathrm{C}$ |  | -132 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| Voltage Compliance Range | $25^{\circ} \mathrm{C}$ | AVDD-0.5 |  | AVDD +0.5 | V |
| Wideband SFDR |  |  |  |  |  |
| 1 MHz to 10 MHz Analog Out | $25^{\circ} \mathrm{C}$ |  | 73 |  | dBc |
| 10 MHz to 40 MHz Analog Out | $25^{\circ} \mathrm{C}$ |  | 67 |  | dBC |
| 40 MHz to 80 MHz Analog Out | $25^{\circ} \mathrm{C}$ |  | 62 |  | dBC |
| 80 MHz to 120 MHz Analog Out | $25^{\circ} \mathrm{C}$ |  | 58 |  | dBC |
| 120 MHz to 160 MHz Analog Out | $25^{\circ} \mathrm{C}$ |  | 52 |  | dBC |
| Narrow-Band SFDR |  |  |  |  |  |
| 40 MHz Analog Out ( $\pm 1 \mathrm{MHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 87 |  | dBC |
| 40 MHz Analog Out ( $\pm 250 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 89 |  | dBC |
| 40 MHz Analog Out ( $\pm 50 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 91 |  | dBc |
| 40 MHz Analog Out ( $\pm 10 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 93 |  | dBc |
| 80 MHz Analog Out ( $\pm 1 \mathrm{MHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 85 |  | dBc |
| 80 MHz Analog Out ( $\pm 250 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 87 |  | dBc |
| 80 MHz Analog Out ( $\pm 50 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 89 |  | dBc |
| 80 MHz Analog Out ( $\pm 10 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 91 |  | dBc |
| 120 MHz Analog Out ( $\pm 1 \mathrm{MHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 83 |  | dBC |
| 120 MHz Analog Out ( $\pm 250 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 85 |  | dBC |
| 120 MHz Analog Out ( $\pm 50 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 87 |  | dBC |
| 120 MHz Analog Out ( $\pm 10 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 89 |  | dBC |
| 160 MHz Analog Out ( $\pm 1 \mathrm{MHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 81 |  | dBC |
| 160 MHz Analog Out ( $\pm 250 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 83 |  | dBC |
| 160 MHz Analog Out ( $\pm 50 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 85 |  | dBc |
| 160 MHz Analog Out ( $\pm 10 \mathrm{kHz}$ ) | $25^{\circ} \mathrm{C}$ |  | 87 |  | dBc |


| Parameter | Temp | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| TIMING CHARACTERISTICS |  |  |  |  |  |
| Serial Control Bus |  |  |  |  |  |
| Maximum Frequency | FULL |  | 25 |  | Mbps |
| Minimum Clock Pulse Width Low | FULL | 7 |  |  |  |
| Minimum Clock Pulse Width High | FULL | 7 |  |  | ns |
| Maximum Clock Rise/Fall Time | FULL |  | 2 |  | ns |
| Minimum Data Setup Time DVDD_I/O $=3.3 \mathrm{~V}$ | FULL | 3 |  |  | ns |
| Minimum Data Setup Time DVDD_I/O $=1.8 \mathrm{~V}$ | FULL | 5 |  |  | ns |
| Minimum Data Hold Time | FULL | 0 |  |  | ns |
| Maximum Data Valid Time | FULL |  | 25 |  | ns |
| Wake-Up Time ${ }^{2}$ | FULL |  | 1 |  | ms |
| Minimum Reset Pulse Width High | FULL | 5 |  |  | SYSCLK Cycles ${ }^{3}$ |
| I/O UPDATE (PS0/PS1) to SYNC_CLK Setup Time DVDD_I/O = 3.3 V | FULL | 4 |  |  | ns |
| I/O UPDATE (PS0/PS1) to SYNC_CLK Setup Time DVDD_I/O = 1.8V | FULL | 6 |  |  | ns |
| I/O UPDATE (PS0/PS1), SYNC_CLK Hold Time | FULL | 0 |  |  | ns |
| Latency |  |  |  |  |  |
| I/O UPDATE (PSO/PS1) to Frequency Change Prop Delay | $25^{\circ} \mathrm{C}$ | 24 |  |  | SYSCLK Cycles |
| I/O UPDATE (PS0/PS1) to Phase Offset Change Prop Delay | $25^{\circ} \mathrm{C}$ | 24 |  |  | SYSCLK Cycles |
| I/O UPDATE (PS0/PS1) to Amplitude Change Prop Delay | $25^{\circ} \mathrm{C}$ | 16 |  |  | SYSCLK Cycles |
| CMOS LOGIC INPUTS |  |  |  |  |  |
| Logic 1 Voltage @ DVDD_I/O ( $\operatorname{Pin} 43)=1.8 \mathrm{~V}$ | $25^{\circ} \mathrm{C}$ | 1.25 |  |  | V |
| Logic 0 Voltage @ DVDD_I/O $($ Pin 43) $=1.8 \mathrm{~V}$ | $25^{\circ} \mathrm{C}$ |  |  | 0.6 | V |
| Logic 1 Voltage @ DVDD_I/O (Pin 43) $=3.3 \mathrm{~V}$ | $25^{\circ} \mathrm{C}$ | 2.2 |  |  | V |
| Logic 0 Voltage @ DVDD_I/O (Pin 43) = 3.3 V | $25^{\circ} \mathrm{C}$ |  |  | 0.8 | V |
| Logic 1 Current | $25^{\circ} \mathrm{C}$ |  | 3 | 12 | $\mu \mathrm{A}$ |
| Logic 0 Current | $25^{\circ} \mathrm{C}$ |  |  | 12 | $\mu \mathrm{A}$ |
| Input Capacitance | $25^{\circ} \mathrm{C}$ |  | 2 |  | pF |
| CMOS LOGIC OUTPUTS (1 mA Load) DVDD_I/O = 1.8V |  |  |  |  |  |
| Logic 1 Voltage | $25^{\circ} \mathrm{C}$ | 1.35 |  |  | V |
| Logic 0 Voltage | $25^{\circ} \mathrm{C}$ |  |  | 0.4 | V |
| CMOS LOGIC OUTPUTS ( 1 mA Load) DVDD_I/O $=3.3 \mathrm{~V}$ |  |  |  |  |  |
| Logic 1 Voltage | $25^{\circ} \mathrm{C}$ | 2.8 |  |  | V |
| Logic 0 Voltage | $25^{\circ} \mathrm{C}$ |  |  | 0.4 | V |
| POWER CONSUMPTION (AVDD = DVDD $=1.8 \mathrm{~V}$ ) |  |  |  |  |  |
| Single-Tone Mode | $25^{\circ} \mathrm{C}$ |  | 162 | 171 | mW |
| Rapid Power-Down Mode | $25^{\circ} \mathrm{C}$ |  | 150 | 160 | mW |
| Full-Sleep Mode | $25^{\circ} \mathrm{C}$ |  | 20 | 27 | mW |
| SYNCHRONIZATION FUNCTION ${ }^{4}$ |  |  |  |  |  |
| Maximum SYNC Clock Rate (DVDD_I/O $=1.8 \mathrm{~V}$ ) | $25^{\circ} \mathrm{C}$ | 62.5 |  |  | MHz |
| Maximum SYNC Clock Rate (DVDD_I/O = 3.3 V) | $25^{\circ} \mathrm{C}$ | 100 |  |  | MHz |
| SYNC_CLK Alignment Resolution ${ }^{5}$ | $25^{\circ} \mathrm{C}$ |  | $\pm 1$ |  | SYSCLK Cycles |

${ }^{1}$ To achieve the best possible phase noise, the largest amplitude clock possible should be used. Reducing the clock input amplitude will reduce the phase noise performance of the device.
${ }^{2}$ Wake-up time refers to the recovery from analog power-down modes (see the Power-Down Functions of the AD9953 section). The longest time required is for the reference clock multiplier PLL to relock to the reference. The wake-up time assumes there is no capacitor on DACBP and that the recommended PLL loop filter values are used.
${ }^{3}$ SYSCLK cycle refers to the actual clock frequency used on-chip by the DDS. If the reference clock multiplier is used to multiply the external reference clock frequency, the SYSCLK frequency is the external frequency multiplied by the reference clock multiplication factor. If the reference clock multiplier is not used, the SYSCLK frequency is the same as the external reference clock frequency.
${ }^{4}$ SYNC_CLK $=1 / 4$ SYSCLK rate. For SYNC_CLK rates $\geq 50 \mathrm{MHz}$, the high speed sync enable bit, CFR2<11>, should be set.
${ }^{5}$ This parameter indicates that the digital synchronization feature cannot overcome phase delays (timing skew) between system clock rising edges. If the system clock edges are aligned, the synchronization function should not increase the skew between the two edges.

## ABSOLUTE MAXIMUM RATINGS

Table 2.

| Parameter | Rating |
| :--- | :--- |
| Maximum Junction Temperature | $150^{\circ} \mathrm{C}$ |
| DVDD_I/O (Pin 43) | 4 V |
| AVDD, DVDD | 2 V |
| Digital Input Voltage (DVDD_I/O $=3.3 \mathrm{~V})$ | -0.7 V to +5.25 V |
| Digital Input Voltage (DVDD_I/O $=1.8 \mathrm{~V})$ | -0.7 V to +2.2 V |
| Digital Output Current | 5 mA |
| Storage Temperature | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Operating Temperature | $-40^{\circ} \mathrm{C}$ to $+105^{\circ} \mathrm{C}$ |
| Lead Temperature $(10$ sec Soldering) | $300^{\circ} \mathrm{C}$ |
| $\theta_{\mathrm{JA}}$ | $38^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\theta_{\mathrm{Jc}}$ | $15^{\circ} \mathrm{C} / \mathrm{W}$ |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |



DAC OUTPUTS


MUST TERMINATE OUTPUTS TO AVDD. DO OUTEXCEED THE NOT EXCEED THE COMPLIANCE RATING.

Figure 2. Equivalent Input and Output Circuits

## PIN CONFIGURATION



Figure 3. 48-Lead TQFP/EP

Note that the exposed paddle on the bottom of the package forms an electrical connection for the DAC and must be attached to analog ground. Note that Pin 43, DVDD_I/O, can be powered to 1.8 V or 3.3 V ; however, the DVDD pins (Pin 2 and Pin 34) can only be powered to 1.8 V .

## PIN FUNCTION DESCRIPTIONS

Table 3. 48-Lead TQFP/EP

| Pin No. | Mnemonic | I/O | Description |
| :---: | :---: | :---: | :---: |
| 1 | I/O UPDATE | I | The rising edge transfers the contents of the internal buffer memory to the I/O registers. This pin must be set up and held around the SYNC_CLK output signal. |
| 2,34 | DVDD | 1 | Digital Power Supply Pins (1.8V). |
| 3, 33, 42 | DGND | 1 | Digital Power Ground Pins. |
| $\begin{aligned} & 4,6,13 \\ & 16,18,19 \\ & 25,27,29 \end{aligned}$ | AVDD | 1 | Analog Power Supply Pins (1.8V). |
| $\begin{aligned} & 5,7,14 \\ & 15,17,22, \\ & 26,32 \end{aligned}$ | AGND | I | Analog Power Ground Pins. |
| 8 | $\overline{\text { OSC }} / \overline{\text { REFCLK }}$ | I | Complementary Reference Clock/Oscillator Input. When the REFCLK port is operated in singleended mode, REFCLK should be decoupled to AVDD with a $0.1 \mu \mathrm{~F}$ capacitor. |
| 9 | OSC/REFCLK | I | Reference Clock/Oscillator Input. See Clock Input section for details on the OSCILLATOR/REFCLK operation. |
| 10 | CRYSTAL OUT | 0 | Output of the Oscillator Section. |
| 11 | CLKMODESELECT | I | Control Pin for the Oscillator Section. When high, the oscillator section is enabled. When low, the oscillator section is bypassed. |
| 12 | LOOP_FILTER | 1 | This pin provides the connection for the external zero compensation network of the REFCLK multiplier's PLL loop filter. The network consists of a $1 \mathrm{k} \Omega$ resistor in series with a $0.1 \mu \mathrm{~F}$ capacitor tied to AVDD. |
| 20 | $\overline{\text { IOUT }}$ | 0 | Complementary DAC Output. Should be biased through a resistor to AVDD, not AGND. |
| 21 | IOUT | 0 | DAC Output. Should be biased through a resistor to AVDD, not AGND. |
| 23 | DACBP | 1 | DAC Biasline Decoupling Pin. A $0.1 \mu \mathrm{~F}$ capacitor to AGND is recommended. |
| 24 | DAC_Rset | I | A resistor ( $3.92 \mathrm{k} \Omega$ nominal) connected from AGND to DAC_Rset establishes the reference current for the DAC. |
| 35 | PWRDWNCTL | 1 | Input Pin Used as an External Power-Down Control (see Table 10 for details). |
| 36 | RESET | 1 | Active High Hardware Reset Pin. Assertion of the RESET pin forces the AD9953 to the initial state, as described in the I/O port register map. |
| 37 | IOSYNC | I | Asynchronous Active High Reset of the Serial Port Controller. When high, the current I/O operation is immediately terminated, enabling a new I/O operation to commence once IOSYNC is returned low. If unused, ground this pin; do not allow this pin to float. |
| 38 | SDO | 0 | When operating the I/O port as a 3-wire serial port, this pin serves as the serial data output. When operated as a 2-wire serial port, this pin is unused and can be left unconnected. |
| 39 | $\overline{\mathrm{CS}}$ | I | This pin functions as an active low chip select that allows multiple devices to share the I/O bus. |
| 40 | SCLK | 1 | This pin functions as the serial data clock for I/O operations. |
| 41 | SDIO | I/O | When operating the I/O port as a 3-wire serial port, this pin serves as the serial data input only. When operated as a 2-wire serial port, this pin is the bidirectional serial data pin. |
| 43 | DVDD_I/O | 1 | Digital Power Supply (for I/O Cells Only, 3.3 V). |
| 44 | SYNC_IN | I | Input Signal Used to Synchronize Multiple AD9953s. This input is connected to the SYNC_CLK output of a master AD9953. |
| 45 | SYNC_CLK | 0 | Clock Output Pin that Serves as a Synchronizer for External Hardware. |
| 46 | OSK | 1 | Input Pin Used to Control the Direction of the Shaped On-Off Keying Function when Programmed for Operation. OSK is synchronous to the SYNC_CLK pin. When OSK is not programmed, this pin should be tied to DGND. |
| 47,48 | PS0, PS1 | 1 | Input pin used to select one of the four internal profiles. Profile <1:0> are synchronous to the SYNC_CLK pin. Any change in these inputs transfers the contents of the internal buffer memory to the I/O registers (sends an internal I/O UPDATE). |
| <49> | AGND | I | The exposed paddle on the bottom of the package is a ground connection for the DAC and must be attached to AGND in any board layout. |

TYPICAL PERFORMANCE CHARACTERISTICS


Figure 4. Fout $=1 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, WBSFDR


Figure 5. Fout $=10 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, WBSFDR


Figure 6. Fout $=40 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, WBSFDR


Figure 7. Fout $=80 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, WBSFDR


Figure 8. Fout $=120 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, WBSFDR


Figure 9. Fout $=160 \mathrm{MHz}, F C L K=400$ MSPS, WBSFDR


Figure 10. Fout $=1.1 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR,$\pm 1 \mathrm{MHz}$


Figure 11. Fout $=10 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR,$\pm 1 \mathrm{MHz}$


Figure 12. Fout $=39.9 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR,$\pm 1 \mathrm{MHz}$


Figure 13. Fout $=80.3 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR, $\pm 1 \mathrm{MHz}$


Figure 14. Fout $=120.2 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR,$\pm 1 \mathrm{MHz}$


Figure 15. Fout $=160 \mathrm{MHz}, F C L K=400 \mathrm{MSPS}$, NBSFDR, $\pm 1 \mathrm{MHz}$


Figure 16. Residual Phase Noise with Fout $=159.5 \mathrm{MHz}, F_{\subset L K}=400$ MSPS (Green), $4 \times 100$ MSPS (Red), and $20 \times 20$ MSPS (Blue)


Figure 17. Residual Peak-to-Peak Jitter of DDS and Comparator Operating Together at 160 MHz


Figure 18. Residual Phase Noise with Fout $=9.5 \mathrm{MHz}, F_{\angle L K}=400 \mathrm{MSPS}$ (Green), $4 \times 100$ MSPS (Red), and $20 \times 20$ MSPS (Blue)


Figure 19. Comparator Rise and Fall Time at 160 MHz

## THEORY OF OPERATION

## COMPONENT BLOCKS

## DDS Core

The output frequency ( $f_{o}$ ) of the DDS is a function of the frequency of the system clock (SYSCLK), the value of the frequency tuning word (FTW), and the capacity of the accumulator ( $2^{32}$, in this case). The exact relationship is given below with $f_{S}$ defined as the frequency of SYSCLK.

$$
\begin{aligned}
& f_{O}=(F T W)\left(f_{S}\right) / 2^{32} \quad \text { with } 0 \leq F T W \leq 2^{31} \\
& f_{O}=f_{S} \times\left(1-\left(F T W / 2^{32}\right)\right) \text { with } 2^{31}<F T W<2^{32}-1
\end{aligned}
$$

The value at the output of the phase accumulator is translated to an amplitude value via the $\operatorname{COS}(\mathrm{x})$ functional block and routed to the DAC.
In certain applications, it is desirable to force the output signal to zero phase. Simply setting the FTW to 0 does not accomplish this; it only results in the DDS core holding its current phase value. Thus, a control bit is required to force the phase accumulator output to zero.

At power-up, the clear phase accumulator bit is set to Logic 1, but the buffer memory for this bit is cleared (Logic 0 ). Therefore, upon power-up, the phase accumulator will remain clear until the first I/O UPDATE is issued.

## Phase-Locked Loop (PLL)

The PLL allows multiplication of the REFCLK frequency. Control of the PLL is accomplished by programming the 5-bit REFCLK multiplier portion of Control Function Register No. 2, Bits <7:3>.

When programmed for values ranging from 0x04 to 0x14 ( 4 decimal to 20 decimal), the PLL multiplies the REFCLK input frequency by the corresponding decimal value. However, the maximum output frequency of the PLL is restricted to 400 MHz . Whenever the PLL value is changed, the user should be aware that time must be allocated to allow the PLL to lock (approximately 1 ms ).
The PLL is bypassed by programming a value outside the range of 4 to 20 (decimal). When bypassed, the PLL is shut down to conserve power.

## Clock Input

The AD9953 supports various clock methodologies. Support for differential or single-ended input clocks and enabling of an onchip oscillator and/or a phase-locked loop (PLL) multiplier is all controlled via user programmable bits. The AD9953 may be configured in one of six operating modes to generate the system clock. The modes are configured using the CLKMODESELECT pin, CFR1<4>, and CFR2<7:3>. Connecting the external pin CLKMODESELECT to Logic High enables the on-chip crystal oscillator circuit. With the on-chip oscillator enabled, users of the AD9953 connect an external crystal to the REFCLK and REFCLKB inputs to produce a low frequency reference clock in the range of 20 MHz to 30 MHz . The signal generated by the oscillator is buffered before it is delivered to the rest of the chip. This buffered signal is available via the CRYSTAL OUT pin. Bit CFR1 $<4>$ can be used to enable or disable the buffer, turning on or off the system clock. The oscillator itself is not powered down in order to avoid long start-up times associated with turning on a crystal oscillator. Writing CFR2<9> to Logic High enables the crystal oscillator output buffer. Logic Low at CFR2<9> disables the oscillator output buffer.
Connecting CLKMODESELECT to Logic Low disables the on-chip oscillator and the oscillator output buffer. With the oscillator disabled, an external oscillator must provide the REFCLK and/or REFCLKB signals. For differential operation, these pins are driven with complementary signals. For singleended operation, a $0.1 \mu \mathrm{~F}$ capacitor should be connected between the unused pin and the analog power supply. With the capacitor in place, the clock input pin bias voltage is 1.35 V . In addition, the PLL may be used to multiply the reference frequency by an integer value in the range of 4 to 20 . Table 4 summarizes the clock modes of operation. Note that the PLL multiplier is controlled via the CFR2<7:3> bits, independent of the CFR1<4> bit.

Table 4. Clock Input Modes of Operation

| CFR1<4> | CLKMODESELECT | CFR2<7:3> | Oscillator Enabled? | System Clock | Frequency Range ( MHz ) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Low | High | $3<\mathrm{M}<21$ | Yes | Fcık $=$ Fosc $\times$ M | $80<$ FLık $^{\text {< }} 400$ |
| Low | High | $\mathrm{M}<4$ or $\mathrm{M}>20$ | Yes | $\mathrm{F}_{\text {CLK }}=\mathrm{F}_{\text {OSC }}$ | $20<\mathrm{F}$ CLK $<30$ |
| Low | Low | $3<\mathrm{M}<21$ | No | $\mathrm{F}_{\text {CLK }}=\mathrm{F}_{\text {OSC }} \times \mathrm{M}$ | $80<\mathrm{F}$ CLK $<400$ |
| Low | Low | $\mathrm{M}<4$ or $\mathrm{M}>20$ | No | Fcık $=$ Fosc | $10<\mathrm{F}$ сLK $<400$ |
| High | X | X | No | $\mathrm{F}_{\text {cık }}=0$ | N/A |

## DAC Output

The AD9953 incorporates an integrated 14-bit current output DAC. Unlike most DACs, this output is referenced to AVDD, not AGND.

Two complementary outputs provide a combined full-scale output current (Iout). Differential outputs reduce the amount of common-mode noise that might be present at the DAC output, offering the advantage of an increased signal-to-noise ratio. The full-scale current is controlled by an external resistor ( $\mathrm{R}_{\text {SET }}$ ) connected between the DAC_R sEt $^{\text {pin }}$ and the DAC ground (AGND_DAC). The full-scale current is proportional to the resistor value as follows:

$$
R_{S E T}=39.19 / I_{\text {OUT }}
$$

The maximum full-scale output current of the combined DAC outputs is 15 mA , but limiting the output to 10 mA provides the best spurious-free dynamic range (SFDR) performance. The DAC output compliance range is AVDD +0.5 V to AVDD -0.5 V . Voltages developed beyond this range will cause excessive DAC distortion and could potentially damage the DAC output circuitry. Proper attention should be paid to the load termination to keep the output voltage within this compliance range.

## Serial IO Port

The AD9953 serial port is a flexible, synchronous serial communications port that allows easy interface to many industrystandard microcontrollers and microprocessors. The serial I/O port is compatible with most synchronous transfer formats, including both the Motorola 6905/11 SPI ${ }^{\oplus}$ and Intel ${ }^{\oplus} 8051$ SSR protocols.
The interface allows read/write access to all registers that configure the AD9953. MSB first or LSB first transfer formats are supported. The AD9953's serial interface port can be configured as a single pin I/O (SDIO), which allows a 2-wire interface or two unidirectional pins for in/out (SDIO/SDO), which in turn enables a 3-wire interface. Two optional pins, IOSYNC and $\overline{\mathrm{CS}}$, enable greater flexibility for system design in the AD9953.

## Register Map and Descriptions

The register map is listed in Table 5.

## AD9953

Table 5. Register Map

| Register <br> Name <br> (Serial <br> Address) | Bit <br> Range | (MSB) <br> Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | $\begin{aligned} & \text { (LSB) } \\ & \text { Bit } 0 \\ & \hline \end{aligned}$ | Default Value OR Profile |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control Function Register No. 1 (CFR1) (0x00) | <7:0> | Digital PowerDown | Comp <br> Power- <br> Down | DAC <br> PowerDown | Clock Input PowerDown | External <br> Power- <br> Down <br> Mode | Linear Sweep No Dwell | SYNC_CLK <br> Out <br> Disable | Not Used | 0x00 |
|  | <15:8> | Load SRR <br> @ I/O UD | AutoClr Freq. Accum. | AutoClr Phase Accum. | Enable SINE Output | Clear Freq. Accum. | Clear <br> Phase <br> Accum | $\begin{aligned} & \hline \text { SDIO } \\ & \text { Input } \\ & \text { Only } \\ & \hline \end{aligned}$ | LSB First | 0x00 |
|  | <23:16> | Automatic Sync Enable | Software Manual Sync | Linear <br> Sweep <br> Enable | Not Used | Not Used | Not Used | Not Used | Not Used | 0x00 |
|  | <31:24> | RAM Enable | RAM <br> Dest. Is <br> Phase <br> Word | Internal Profile Control <2:0> |  |  | Load ARR <br> @ I/O UD | OSK Enable | Auto OSK Keying | 0x00 |
| Control | <7:0> | REFCLK Multiplier $0 \times 00$ or $0 \times 01$, or $0 \times 02$ or $0 \times 03$ : Bypass Multiplier $0 \times 04$ to $0 \times 14$ : $4 \times$ to $20 \times$ Multiplication |  |  |  |  | VCO Range | Charge Pump Current$<1: 0>$ |  | 0x00 |
| Register <br> No. 2 (CFR2) <br> (0x01) | <15:8> | Not Used |  |  |  | High Speed Sync Enable | Hardware Manual Sync Enable | CRYSTAL OUT Pin Active | Not Used | 0x00 |
|  | <23:16> | Not Used |  |  |  |  |  |  |  | 0x18 |
| Amplitude Scale Factor (ASF) <br> ( $0 \times 02$ ) | <7:0> | Amplitude Scale Factor Register <7:0> |  |  |  |  |  |  |  | 0x00 |
|  | <15:8> | Auto Ramp Contro | $\begin{aligned} & \text { aate Speed } \\ & <1: 0> \end{aligned}$ | Amplitude Scale Factor Register < 13:8> |  |  |  |  |  | 0x00 |
| Amplitude Ramp Rate (ARR) (0x03) | <7:0> | Amplitude Ramp Rate Register <7:0> |  |  |  |  |  |  |  | 0x00 |
| Frequency Tuning Word (FTW0) (0x04) | <7:0> | Frequency Tuning Word No. $0<7: 0>$ |  |  |  |  |  |  |  | 0x00 |
|  | <15:8> | Frequency Tuning Word No. $0<15: 8>$ |  |  |  |  |  |  |  | 0x00 |
|  | <23:16> | Frequency Tuning Word No. $0<23: 16>$ |  |  |  |  |  |  |  | 0x00 |
|  | <31:24> | Frequency Tuning Word No. $0<31: 24>$ |  |  |  |  |  |  |  | 0x00 |
| PhaseOffset Word(POW0)(0x05) | <7:0> | Phase Offset Word No. $0<7: 0>$ |  |  |  |  |  |  |  | 0x00 |
|  | <15:8> | Not Use | <1:0> | Phase Offset Word No. 0 <13:8> |  |  |  |  |  | 0x00 |
| Frequency Tuning Word (FTW1) (0x06) | <7:0> | Frequency Tuning Word No. $1<7: 0>$ |  |  |  |  |  |  |  | 0x00 |
|  | <15:8> | Frequency Tuning Word No. $1<15: 8>$ |  |  |  |  |  |  |  | 0x00 |
|  | <23:16> | Frequency Tuning Word No. $1<23: 16>$ |  |  |  |  |  |  |  | 0x00 |
|  | <31:24> | Frequency Tuning Word No. 1 <31:24> |  |  |  |  |  |  |  | 0x00 |



## Control Register Bit Descriptions

## Control Function Register. No. 1 (CFR1)

The CFR1 is used to control the various functions, features, and modes of the AD9953. The functionality of each bit is below.
CFR1<31>: RAM Enable Bit
CFR $1<31>=0$ (default). The RAM is powered down to conserve power. Single-tone mode of operation is active.
CFR1<31> = 1 . If CFR1<31> is active, the RAM is enabled for operation. Access control for normal operation is controlled via the mode control bits of the RSCW for the current profile.

## CFR1<30>: RAM Destination Bit

CFR1<30> $=0$ (default). If CFR1<31> is active, a Logic 0 on the RAM destination bit (CFR1<30> $=0$ ) configures the AD9953 such that the RAM output drives the phase accumulator (i.e., the frequency tuning word). If CFR1<31> is inactive, CFR1<30> is a Don't Care.

CFR $1<30>=1$. If CFR $1<31>$ is active, a Logic 1 on the RAM destination bit (CFR1<30> = 1) configures the AD9953 such that the RAM output drives the phase-offset adder (i.e., sets the phase offset of the DDS core).
CFR1<29:27>: Not Used
CFR1<26>: Amplitude Ramp Rate Load Control Bit
CFR1<26> = 0 (default). The amplitude ramp rate timer is loaded only upon timeout (timer $==1$ ) and is not loaded due to an I/O UPDATE input signal.

CFR1<26> = 1 . The amplitude ramp rate timer is loaded upon timeout (timer $==1$ ) or at the time of an I/O UPDATE input signal.

## CFR1<25>: Shaped On-Off Keying Enable Bit

CFR1<25> = 0 (default). Shaped on-off keying is bypassed.
CFR $1<25>=1$. Shaped on-off keying is enabled. When enabled, CFR1<24> controls the mode of operation for this function.
CFR1<24>: Auto Shaped On-Off Keying Enable Bit (Only Valid when CFR1<25> Is Active High)
CFR1<24> $=0$ (default). When CFR1<25> is active, a Logic 0 on CFR1<24> enables the manual shaped on-off keying operation. Each amplitude sample sent to the DAC is multiplied by the amplitude scale factor. See the Shaped On-Off Keying section for details.

CFR $1<24>=1$. When CFR $1<25>$ is active, a Logic 1 on CFR1<24> enables the auto shaped on-off keying operation. Toggling the OSK pin high will cause the output scalar to ramp up from zero scale to the amplitude scale factor at a rate determined by the amplitude ramp rate. Toggling the OSK pin low
will cause the output to ramp down from the amplitude scale factor to zero scale at the amplitude ramp rate. See the Shaped On-Off Keying section for details.

CFR1<23>: Automatic Synchronization Enable Bit
CFR1<23> $=0$ (default). The automatic synchronization feature of multiple AD9953s is inactive.
CFR1<23> $=1$. The automatic synchronization feature of multiple AD9953s is active. The device will synchronize its internal synchronization clock (SYNC_CLK) to align to the signal present on the SYNC_IN input. See the Synchronizing Multiple AD9953s section for details.
CFR1<22>: Software Manual Synchronization of Multiple AD9953s

CFR1<22> = 0 (default). The manual synchronization feature is inactive.

CFR1 $<22>=1$. The software controlled manual synchronization feature is executed. The SYNC_CLK rising edge is advanced by one SYNC_CLK cycle and this bit is cleared. To advance the rising edge multiple times, this bit needs to be set for each advance. See the Synchronizing Multiple AD9953s section for details.

CFR1<21:14>: Not Used
CFR1<13>: Auto-Clear Phase Accumulator Bit
CFR1 $<13>=0$ (default). The current state of the phase accumulator remains unchanged when the frequency tuning word is applied.
CFR1<13> = 1 . This bit automatically synchronously clears (loads 0 s into) the phase accumulator for one cycle upon reception of an I/O UPDATE signal.
CFR1<12>: Sine/Cosine Select Bit
CFR1<12> = 0 (default). The angle-to-amplitude conversion logic employs a COSINE function.
CFR1<12> = 1 . The angle-to-amplitude conversion logic employs a SINE function.

CFR1<11>: Not Used
CFR1<10>: Clear Phase Accumulator
CFR $1<10\rangle=0$ (default). The phase accumulator functions as normal.

CFR $1<10\rangle=1$. The phase accumulator memory elements are cleared and held clear until this bit is cleared.

## CFR1<9>: SDIO Input Only

CFR1<9> $=0$ (default). The SDIO pin has bidirectional operation (2-wire serial programming mode).

CFR1<9> = 1 . The serial data I/O pin (SDIO) is configured as an input only pin (3-wire serial programming mode).
CFR1<8>: LSB First
CFR1<8> $=0$ (default). MSB first format is active.
CFR1<8> = 1 . The serial interface accepts serial data in LSB first format.

CFR1<7>: Digital Power-Down Bit
CFR1<7> $=0$ (default). All digital functions and clocks are active.
CFR1<7> = 1 . All non-IO digital functionality is suspended, lowering the power significantly.

CFR1<6>: Not Used
CFR1<5>: DAC Power-Down Bit
CFR1<5> $=0$ (default). The DAC is enabled for operation.
CFR $1<5>=1$. The DAC is disabled and is in its lowest power dissipation state.

## CFR1<4>: Clock Input Power-Down Bit

CFR1<4> = 0 (default). The clock input circuitry is enabled for operation.
CFR $1<4>=1$. The clock input circuitry is disabled and the device is in its lowest power dissipation state.

## CFR1<3>: External Power-Down Mode

CFR1<3> $=0$ (default). The external power-down mode selected is the rapid recovery power-down mode. In this mode, when the PWRDWNCTL input pin is high, the digital logic and the DAC digital logic are powered down. The DAC bias circuitry, PLL, oscillator, and clock input circuitry are not powered down.
CFR1<3> = 1 . The external power-down mode selected is the full power-down mode. In this mode, when the PWRDWNCTL input pin is high, all functions are powered down. This includes the DAC and PLL, which take a significant amount of time to power up.

CFR1<2>: Not Used
CFR1<1>: SYNC_CLK Disable Bit
CFR1<1> $=0$ (default). The SYNC_CLK pin is active.
CFR1<1> $=1$. The SYNC_CLK pin assumes a static Logic 0 state to keep noise generated by the digital circuitry at a
minimum. However, the synchronization circuitry remains active (internally) to maintain normal device timing.
CFR $1<0>$ : Not Used, Leave at 0

## Control Function Register No. 2 (CFR2)

The CFR2 is used to control the various functions, features, and modes of the AD9953, primarily related to the analog sections of the chip.

CFR2<23:12>: Not Used
CFR2<11>: High Speed Sync Enable Bit
CFR2 $<11>=0$ (default). The high speed sync enhancement is off.
CFR2 $<11>=1$. The high speed sync enhancement is on. This bit should be set when attempting to use the auto-
synchronization feature for SYNC_CLK inputs beyond 50 MHz , (200 MSPS SYSCLK). See the Synchronizing Multiple AD9953s section for details.

CFR2<10>: Hardware Manual Sync Enable Bit
CFR $2<10>=0$ (default). The hardware manual sync function is off.
CFR2<10> $=1$. The hardware manual sync function is enabled. While this bit is set, a rising edge on the SYNC_IN pin will cause the device to advance the SYNC_CLK rising edge by one REFCLK cycle. Unlike the software manual sync enable bit, this bit does not self clear. Once the hardware manual sync mode is enabled, it will stay enabled until this bit is cleared. See the Synchronizing Multiple AD9953s section for details.
CFR2<9>: CRYSTAL OUT Enable Bit
CFR2<9> $=0$ (default). The CRYSTAL OUT pin is inactive.
CFR2<9> = 1 . The CRYSTAL OUT pin is active. When active, the crystal oscillator circuitry output drives the CRYSTAL OUT pin, which can be connected to other devices to produce a reference frequency. The oscillator will respond to crystals in the range of 20 MHz to 30 MHz .

CFR2<8>: Not Used

## CFR2<7:3>: Reference Clock Multiplier Control Bits

This 5-bit word controls the multiplier value out of the clockmultiplier (PLL) block. Valid values are decimal 4 to 20 ( 0 x 04 to 0x14). Values entered outside this range will bypass the clock multiplier. See the Phase-Locked Loop (PLL) section for details.
CFR2<2>: VCO Range Control Bit
This bit is used to control the range setting on the VCO. When CFR $2<2>==0$ (default), the VCO operates in a range of 100 MHz to 250 MHz . When CFR2<2> == 1, the VCO operates in a range of 250 MHz to 400 MHz .

## CFR2<1:0>: Charge Pump Current Control Bits

These bits are used to control the current setting on the charge pump. The default setting, CFR $2<1: 0>$, sets the charge pump current to the default value of $75 \mu \mathrm{~A}$. For each bit added ( 01,10 , 11), $25 \mu \mathrm{~A}$ of current is added to the charge pump current: $100 \mu \mathrm{~A}, 125 \mu \mathrm{~A}$, and $150 \mu \mathrm{~A}$.

## Other Register Descriptions

## Amplitude Scale Factor (ASF)

The ASF register stores the 2 -bit auto ramp rate speed value and the 14-bit amplitude scale factor used in the output shaped keying (OSK) operation. In auto OSK operation, ASF <15:14> tells the OSK block how many amplitude steps to take for each increment or decrement. For ASF $<15: 14>=\{00,01,10,11\}$, the increment/decrement is set to $\{1,2,4,8\}$, respectively. ASF $<13: 0>$ sets the maximum value achievable by the OSK internal multiplier. In manual OSK mode, ASF $<15: 14>$ has no effect. ASF $<13: 0>$ provides the output scale factor directly. If the OSK enable bit is cleared, CFR $1<25\rangle=0$, this register has no effect on device operation.

## Amplitude Ramp Rate (ARR)

The ARR register stores the 8-bit amplitude ramp rate used in the auto OSK mode. This register programs the rate at which the amplitude scale factor counter increments or decrements. If the OSK is set to manual mode, or if OSK enable is cleared, this register has no effect on device operation.

## Frequency Tuning Word 0 (FTW0)

The frequency tuning word is a 32-bit register that controls the rate of accumulation in the phase accumulator of the DDS core. Its specific role is dependent on the device mode of operation.

## Phase Offset Word (POW)

The phase offset word is a 14-bit register that stores a phase offset value. This offset value is added to the output of the phase accumulator to offset the current phase of the output signal. The exact value of phase offset is given by the following formula:

$$
\Phi=\left(\frac{P O W}{2^{14}}\right) \times 360^{\circ}
$$

## RAM Segment Control Words (RSCW0, RSCW1, RSCW2, and RSCW3)

When the linear sweep enable bit CFR1<21> is clear, Registers 0x07, 0x08, 0x09, and 0x0A act as the RAM segment control words for each of the RAM segments. Each of the RAM segment control words is comprised of a RAM segment address ramp rate, a final address value, a beginning address value, a RAM segment mode control, and a no-dwell bit.
RAM Segment Address Ramp Rate, RSCW<39:24>
For RAM modes that step through address values, such as
ramping, this 16-bit word defines the number of SYNC_CLK cycles the RAM controller dwells at each address. A value of 0 is invalid. Any other value from 1 to 65535 may be used.
RAM Segment Final Address $R S C W<9: 8>, R S C W<23: 16>$
This discontinuous 10 -bit sequence defines the final address value for the given RAM segment. The order in which the bits are listed is the order in which the bits must be written. RSCW<23>, even though during the write operation is more significant than RSCW<9>, is only the third MSB of the final address value. RSCW<9>, even though it comes later in the RSCW than RSCW $<23>$, is the MSB of the final address value.
RAM Segment Beginning Address RSCW<3:0>, <15:10>
This discontinuous 10 -bit sequence defines the final address value for the given RAM segment. The order in which the bits are listed is the order in which the bits must be written. RSCW $\langle 15\rangle$, even though during the write operation is more significant than RSCW $<3>$, is only the fifth MSB of the final address value. RSCW $<3>$, even though it comes later in the RSCW than RSCW $<15>$, is the MSB of the final address value.

## RAM Segment Mode Control RSCW<7:5>

This 3-bit sequence determines the RAM segment's mode of operation. There are only five possible RAM modes, so only values of 0 to 5 are valid. See Table 6 to determine the bit combination for various RAM modes.

## RAM Segment No-Dwell Bit RSCW<4>

This bit sets the no-dwell feature of sweeping profiles. In profiles that sweep from a defined beginning to a defined end, the RAM controller can either dwell at the final address until the next profile is selected or, when this bit is set, the RAM controller will return to the beginning address and dwell there until the next profile is selected.

## RAM

The AD9953 incorporates a $1024 \times 32$ block of SRAM. The RAM is a bidirectional single port. Both read and write operations from and to the RAM are valid, but they cannot occur simultaneously. Write operations from the serial I/O port have precedence, and if an attempt to write to RAM is made during a read operation, the read operation will be halted. The RAM is controlled in multiple ways, dictated by the modes of operation described in the RAM Segment Control Word <7:5> as well as data in the control function register. Read/write control for the RAM will be described for each mode supported.
When the RAM enable bit (CFR1<31>) is set, the RAM output optionally drives the input to the phase accumulator or the phase offset adder, depending on the state of the RAM destination bit (CFR1<30>). If CFR1<30> is a Logic 1 , the RAM output is connected to the phase offset adder and supplies the phase offset control word(s) for the device. When CFR $1<30>$ is Logic 0 (default condition), the RAM output is connected to the
input of the phase accumulator and supplies the frequency tuning word(s) for the device. When the RAM output drives the phase accumulator, the phase offset word (POW, Address 0x05) drives the phase-offset adder. Similarly, when the RAM output drives the phase offset adder, the frequency tuning word (FTW, Address 0x04) drives the phase accumulator. When CFR1<31> is Logic 0 , the RAM is inactive unless being written to via the serial port. The power-up state of the AD9953 is the single-tone mode, in which the RAM enable bit is inactive. The RAM is segmented into four unique slices controlled by the Profile<1:0> input pins.

All RAM writes/reads, unless otherwise specified, are controlled by the Profile $<1: 0>$ input pins and the respective RAM segment control word. The RAM can be written to during normal operation, but any I/O operation that commands the RAM to be written immediately suspends read operation from the RAM, causing the current mode of operation to be nonfunctional. This excludes single-tone mode, as the RAM is not read in this mode.

Writing the RAM is accomplished as follows. After configuring the desired RAM segment control words, the desired RAM segment must be selected via the profile select pins PS $<1: 0>$. During the instruction byte, write the address for the RAM, 0x0B. The serial port and RAM controller will work in conjunction to determine the width of the profile and the serial port will accept the defined number of 32 -bit words sequentially from the beginning address to the ending address. Consider the following example:

- The RAM Segment Control Word 1 lists the beginning RAM address at 256 and the ending address at 511.
- $\quad \mathrm{PS} 0=1$ and $\mathrm{PS} 1=0$.
- The instruction byte is 10001001 .

The RAM controller would configure the serial port to expect 256 32-bit words. The first 32 bits would be parsed as a word and sent to RAM Address 256. The next 32 bits would be parsed and sent to 257 , and so forth, all the way through until the 256 word was sent (grand total of 8,192 data bits in this operation).

## MODES OF OPERATION

## Single-Tone Mode

In single-tone mode, the DDS core uses a single tuning word. Whatever value is stored in FTW0 is supplied to the phase accumulator. This value can only be changed manually, which is done by writing a new value to FTW0 and by issuing an I/O UPDATE. Phase adjustment is possible through the phase offset register.

## RAM Controlled Modes of Operation

## Direct Switch Mode

Direct switch mode enables FSK or PSK modulation. The AD9953 is programmed for direct switch mode by writing the RAM enable bit true and programming the RAM segment mode control bits of each desired profile to Logic 000(b). This mode simply reads the RAM contents at the RAM segment beginning address for the current profile. No address ramping is enabled in direct switch mode.

To perform 4-tone FSK, the user programs each RAM segment control word for direct switch mode and a unique beginning address value. In addition, the RAM enable bit is written true, which enables the RAM, and the RAM destination bit is written false, setting the RAM output to be the frequency tuning word. The Profile $<1: 0>$ inputs are the 4 -tone FSK data inputs. When the profile is changed, the frequency tuning word stored in the new profile is loaded into the phase accumulator and is used to increment the currently stored value in a phase continuous fashion. The phase offset word drives the phase-offset adder. Two-tone FSK is accomplished by using only one profile pin for data.

Programming the AD9953 for PSK modulation is similar to FSK except the RAM destination bit is set to a Logic 1, enabling the RAM output to drive the phase offset adder. The FTW0 drives the input to the phase accumulator. Toggling the profile pins changes (modulates) the current phase value. The upper 14 bits of the RAM drive the phase adder ( $\langle 31: 18>$ ). Bits $\langle 17: 0\rangle$ of the RAM output are unused when the RAM destination bit is set. The no-dwell bit is a Don't Care in direct switch mode.

## Ramp-Up Mode

Ramp-up mode, in conjunction with the segmented RAM capability, allows up to four different sweep profiles to be programmed into the AD9953. The AD9953 is programmed for ramp-up mode by writing the RAM enable bit true and programming the RAM mode control bits of each profile to be used to Logic 001(b). As in all modes that enable the memory, the RAM destination bit controls whether the RAM output drives the phase accumulator or the phase offset adder.

Upon starting a sweep (via an I/O UPDATE or change in profile bits), the RAM address generator loads the RAM segment beginning address bits of the current RSCW, driving the RAM output from this address, and the ramp rate timer loads the RAM segment address ramp rate bits. When the ramp rate timer finishes a cycle, the RAM address generator increments to the next address and the timer reloads the ramp rate bits and begins a new countdown cycle. This sequence continues until the RAM address generator has incremented to an address equal to the RAM segment final address bits of the current RSCW.

If the no-dwell bit is clear when the RAM address generator equals the final address, the generator stops incrementing as the terminal frequency has been reached. The sweep is complete and does not restart until an I/O UPDATE or change in profile is detected to enable another sweep from the beginning to the final RAM address as described above.

If the no-dwell bit is set when the RAM address generator equals the final address, after the next ramp rate timer cycle the phase accumulator is cleared. The phase accumulator remains cleared until another sweep is initiated via an I/O UPDATE input or change in profile.
Another application for ramp-up mode is nonsymmetrical FSK modulation. With the RAM configured for two segments, using the Profile $<0>$ bit as the data input allows nonsymmetrical ramped FSK.

## Bidirectional Ramp Mode

Bidirectional ramp mode allows the AD9953 to offer a symmetrical sweep between two frequencies using the Profile $<0>$ signal as the control input. The AD9953 is programmed for bidirectional ramp mode by writing the RAM enable bit true and the RAM mode control bits of RSCW0 to Logic 010(b). In bidirectional ramp mode, the Profile $<1>$ input is ignored and the Profile<0> input is the ramp direction indicator. In this mode, the memory is not segmented and uses only a single beginning and final address. The address registers that affect the control of the RAM are located in the RSCW associated with Profile 0.
Upon entering this mode (via an I/O UPDATE or changing Profile<0>), the RAM address generator loads the RAM segment beginning address bits of RSCW0 and the ramp rate timer loads the RAM segment address ramp rate bits. The RAM drives data from the beginning address, and the ramp rate timer begins to count down to 1 . While operating in this mode, toggling the Profile $<0>$ pin does not cause the device to generate an internal I/O UPDATE. When the Profile $<0>$ pin is acting as the ramp direction indicator, any transfer of data from the I/O buffers to the internal registers can only be initiated by a rising edge on the I/O UPDATE pin.
RAM address control now is a function of the Profile $<0>$ input. When the Profile $<0>$ bit is a Logic 1 , the RAM address generator increments to the next address when the ramp rate timer completes a cycle (and reloads to start the timer again). As in the ramp-up mode, this sequence continues until the RAM address generator has incremented to an address equal to the final address as long as the Profile $<0>$ input remains high. If the Profile $<0>$ input goes low, the RAM address generator immediately decrements and the ramp rate timer is reloaded. The RAM address generator will continue to decrement at the ramp rate period until the RAM address is equal to the beginning address as long as the Profile $<0>$ input remains low.

The sequence of ramping up and down is controlled via the Profile $<0>$ input signal for as long as the part is programmed into this mode. The no-dwell bit is a Don't Care in this mode as is all data in the RAM segment control words associated with Profiles 1,2 , and 3 . Only the information in the RAM segment control word for Profile 0 is used to control the RAM in the bidirectional ramp mode.

## Continuous Bidirectional Ramp Mode

Continuous bidirectional ramp mode allows the AD9953 to offer an automatic symmetrical sweep between two frequencies. The AD9953 is programmed for continuous bidirectional ramp mode by writing the RAM enable bit true and the RAM mode control bits of each profile to be used to Logic 011(b).
Upon entering this mode (via an I/O UPDATE or changing Profile $<1: 0>$ ), the RAM address generator loads the RAM segment beginning address bits of the current RSCW and the ramp rate timer loads the RAM segment address ramp rate bits. The RAM drives data from the beginning address, and the ramp rate timer begins to count down to 1 . When the ramp rate timer completes a cycle, the RAM address generator increments to the next address, and the timer reloads the ramp rate bits and continues counting down. This sequence continues until the RAM address generator has incremented to an address equal to the RAM segment final address bits of the current RSCW. Upon reaching this terminal address, the RAM address generator will decrement in value at the ramp rate until it reaches the RAM segment beginning address. Upon reaching the beginning address, the entire sequence repeats.
The entire sequence repeats for as long as the part is programmed for this mode. The no-dwell bit is a Don't Care in this mode. In general, this mode is identical in control to the bidirectional ramp mode except the ramp up and down is automatic (no external control via the Profile $<0>$ input) and switching profiles is valid. Once in this mode, the address generator ramps from the beginning address to the final address, then back to the beginning address at the rate programmed into the ramp rate register. This mode enables generation of an automatic saw tooth sweep characteristic.

## Continuous Recirculate Mode

Continuous recirculate mode allows the AD9953 to offer an automatic, continuous unidirectional sweep between two frequencies. The AD9953 is programmed for continuous recirculate mode by writing the RAM enable bit true and the RAM mode control bits of each profile to be used to Logic 100(b).

Upon entering this mode (via an I/O UPDATE or changing Profile $<1: 0>$ ), the RAM address generator loads the RAM segment beginning address bits of the current RSCW and the ramp rate timer loads the RAM segment address ramp rate bits. The RAM drives data from the beginning address, and the ramp rate timer begins to count down to 1 . When the ramp rate timer completes a cycle, the RAM address generator increments to the
next address, and the timer reloads the ramp rate bits and continues counting down. This sequence continues until the RAM address generator has incremented to an address equal to the RAM segment final address bits of the current RSCW. Upon reaching this terminal address, the RAM address generator reloads the RAM segment beginning address bits and the sequence repeats.
The sequence of circulating through the specified RAM addresses repeats for as long as the part is programmed for this mode. The no-dwell bit is a Don't Care in this mode.

## RAM Controlled Modes of Operation Notes and

 Summary
## Notes:

1. The user must ensure that the beginning address is lower than the final address.
2. Changing profiles or issuing an I/O UPDATE automatically terminates the current sweep and starts the next sweep.
3. Setting the RAM destination bit true such that the RAM output drives the phase offset adder is valid. While the above discussion describes a frequency sweep, a phase sweep operation is also available.
The AD9953 offers five modes of RAM controlled operation (see Table 6).

Table 6. RAM Modes of Operation

| RSCW<7:5> <br> (Binary) | Mode | Notes |
| :--- | :--- | :--- |
| 000 | Direct Switch | No Sweeping, Profiles <br> Valid, No Dwell Invalid <br> Sweeping, Profiles Valid, <br> No Dwell Valid <br> Sweeping, Profile <0> Is a <br> Direction Control Bit, No <br> Dwell Invalid <br> Sweeping, Profiles Valid, <br> 001 |
| Ramp Up <br> Bidirectional <br> Ramp | Continuous <br> Bidirectional <br> Ramp <br> Continuous <br> Recirculate <br> Open Invalid | Sweeping, Profiles Valid, <br> No Dwell Invalid <br> Invalid Mode—Default To <br> Direct Switch |
| $101,110,111$ |  |  |

## Internal Profile Control

The AD9953 offers a mode in which a composite frequency sweep can be built, for which the timing control is software programmable. The internal profile control capability disengages the Profile $<1: 0>$ pins and enables the AD9953 to take control of switching between profiles. Modes are defined that allow continuous or single burst profile switches for three combinations of profile selection bits. These are listed in Table 7. When any of the CFR1<29:27> bits are active, the internal profile control mode is engaged. Internal profile control
is only valid when the device is operating in RAM mode. There is no internal profile control for linear sweeping operations.
When the internal profile control mode is engaged, the RAM segment mode control bits are Don't Care and the device operates all profiles as if these mode control bits were programmed for ramp-up mode. Switching between profiles occurs when the RAM address generator has exhausted the memory contents for the current profile.

Table 7. Internal Profile Control

| CFR1<29:27> <br> (Binary) | Mode Description |
| :--- | :--- |
| 000 | Internal Control Inactive <br> Internal Control Active, Single Burst, Activate <br> Profile 0, Then 1, Then Stop <br> Internal Control Active, Single Burst, Activate <br> Profile 0, Then 1, Then 2, Then Stop <br> Internal Control Active, Single Burst, Activate <br> Profile 0, Then 1, Then 2, Then 3, Then Stop |
| 010 | Internal Control Active, Continuous, Activate <br> Profile 0, Then 1, Then Loop Starting 0 <br> Internal Control Active, Continuous, Activate <br> Profile 0, Then 1, Then 2, Then Loop Starting 0 |
| 100 | Internal Control Active, Continuous, Activate <br> Profile 0, Then 1, Then 2, Then 3, Then Loop |
| Starting 0 |  |
| Invalid |  |

A single burst mode is one in which the composite sweep is executed once. For example, assume the device is programmed for ramp-up mode and the CFR1<29:27> bits are written to Logic 010(b). Upon receiving an I/O UPDATE, the internal control logic signals the device to begin executing the ramp-up mode sequence for Profile 0 . Upon reaching the RAM segment final address value for Profile 0, the device automatically switches to Profile 1 and begins executing that ramp-up sequence. Upon reaching the RAM segment final address value for Profile 1, the device automatically switches to Profile 2 and begins executing that ramp-up sequence. When the RAM segment final address value for Profile 2 is reached, the sequence is over and the composite sweep has completed. Issuing another I/O UPDATE restarts the burst process.
A continuous internal profile control mode is one in which the composite sweep is continuously executed for as long as the device is programmed into that mode. Using the example above, except programming the CFR1<29:27> bits to Logic 101(b), the operation would be identical until the RAM segment final address value for Profile 2 is reached. At this point, instead of stopping the sequence, it repeats, starting with Profile 0 .

## PROGRAMMING AD9953 FEATURES

## Phase Offset Control

A 14-bit phase offset $(\theta)$ may be added to the output of the phase accumulator by means of the control registers. This feature provides the user with two different methods of phase control.
The first method is a static phase adjustment where a fixed phase offset is loaded into the appropriate phase offset register and left unchanged. The result is that the output signal is offset by a constant angle relative to the nominal signal. This allows the user to phase align the DDS output with some external signal, if necessary.
The second method of phase control is where the user regularly updates the phase offset register via the I/O port. By properly modifying the phase offset as a function of time, the user can implement a phase modulated output signal. However, both the speed of the I/O port and the frequency of SYSCLK limit the rate at which phase modulation can be performed.
The AD9953 allows for a programmable continuous zeroing of the phase accumulator as well as a clear and release or automatic zeroing function. Each feature is individually controlled via the CFR1 bits. CFR1<13> is the automatic clear phase
accumulator bit. CFR1<10> clears the phase accumulator and holds the value to zero.

## Continuous Clear Bit

The continuous clear bit is simply a static control signal that, when active high, holds the phase accumulator at zero for the entire time the bit is active. When the bit goes low, inactive, the phase accumulator is allowed to operate.

## Clear and Release Function

When set, the auto-clear phase accumulator clears and releases the phase accumulator upon receiving an I/O UPDATE. The automatic clearing function is repeated for every subsequent I/O UPDATE until the appropriate auto-clear control bit is cleared.

## Shaped On-Off Keying

The shaped on-off keying function of the AD9953 allows the user to control the ramp-up and ramp-down time of an on-off emission from the DAC. This function is used in burst transmissions of digital data to reduce the adverse spectral impact of short, abrupt bursts of data.
Auto and manual shaped on-off keying modes are supported. The auto mode generates a linear scale factor at a rate determined by the amplitude ramp rate (ARR) register controlled by an external pin (OSK). Manual mode allows the user to directly control the output amplitude by writing the scale factor value into the amplitude scale factor (ASF) register.

The shaped on-off keying function may be bypassed (disabled) by clearing the OSK enable bit (CFR1<25> = 0).

The modes are controlled by two bits located in the most significant byte of the control function register (CFR). CFR1<25> is the shaped on-off keying enable bit. When CFR $1<25>$ is set, the output scaling function is enabled and CFR1<25> bypasses the function. CFR1<24> is the internal shaped on-off keying active bit. When CFR1<24> is set, internal shaped on-off keying mode is active; CFR1<24> is cleared, external shaped on-off keying mode is active. CFR1<24> is a Don't Care if the shaped on-off keying enable bit (CFR1<25>) is cleared. The power-up condition is shaped on-off keying disabled (CFR1<25> $=0$ ). Figure 20 shows the block diagram of the OSK circuitry.

## AUTO Shaped On-Off Keying Mode Operation

The auto shaped on-off keying mode is active when CFR1<25> and CFR1<24> are set. When auto shaped on-off keying mode is enabled, a single scale factor is internally generated and applied to the multiplier input for scaling the output of the DDS core block (see Figure 20). The scale factor is the output of a 14 -bit counter that increments/decrements at a rate determined by the contents of the 8 -bit output ramp rate register. The scale factor increases if the OSK pin is high and decreases if the OSK pin is low. The scale factor is an unsigned value such that all 0 s multiply the DDS core output by 0 (decimal) and 0x3FFF multiplies the DDS core output by 16383 (decimal).
For those users who use the full amplitude ( 14 bits) but need fast ramp rates, the internally generated scale factor step size is controlled via the ASF $<15: 14>$ bits. Table 8 describes the increment/decrement step size of the internally generated scale factor per the ASF $<15: 14>$ bits.

A special feature of this mode is that the maximum output amplitude allowed is limited by the contents of the amplitude scale factor register. This allows the user to ramp to a value less than full scale.

Table 8. Auto-Scale Factor Internal Step Size

| ASF<15:14> (Binary) | Increment/Decrement Size |
| :--- | :--- |
| 00 | 1 |
| 01 | 2 |
| 10 | 4 |
| 11 | 8 |

## OSK Ramp Rate Timer

The OSK ramp rate timer is a loadable down counter, which generates the clock signal to the 14-bit counter that generates the internal scale factor. The ramp rate timer is loaded with the value of the ASFR every time the counter reaches 1 (decimal). This load and countdown operation continues for as long as the timer is enabled, unless the timer is forced to load before reaching a count of 1 .
If the load OSK timer bit (CFR1<26>) is set, the ramp rate timer is loaded upon an I/O UPDATE or upon reaching a value of 1 . The ramp timer can be loaded before reaching a count of 1 by three methods.

The first method of loading is by changing the OSK input pin. When the OSK input pin changes state, the ASFR value is loaded into the ramp rate timer, which then proceeds to count down as normal.

The second method in which the sweep ramp rate timer can be loaded before reaching a count of 1 is if the load OSK timer bit (CFR1<26>) is set and an I/O UPDATE is issued.
The third method in which the sweep ramp rate timer can be loaded before reaching a count of 1 is when going from the inactive auto shaped on-off keying mode to the active auto shaped on-off keying mode; that is, when the sweep enable bit is being set.


Figure 20. On-Off Shaped Keying Block Diagram

