imall

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from, Europe, America and south Asia, supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts, Customers Priority, Honest Operation, and Considerate Service", our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip, ALPS, ROHM, Xilinx, Pulse, ON, Everlight and Freescale. Main products comprise IC, Modules, Potentiometer, IC Socket, Relay, Connector. Our parts cover such applications as commercial, industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



ANALOG Unity-Gain Stable, Ultralow Distoltion, DEVICES $1 \text{ nV}/\sqrt{\text{Hz}}$ Voltage Noise, High Speed Op Amp

Data Sheet

FEATURES

Unity-gain stable

Ultralow noise: 1 nV/ \sqrt{Hz} , 2.6 pA/ \sqrt{Hz} Ultralow distortion -117 dBc at 1 MHz **High speed** -3 dB bandwidth: 600 MHz (G = +1) Slew rate: 310 V/us Offset voltage: 230 µV maximum Low input bias current: 100 nA Wide supply voltage range: 5 V to 12 V Supply current: 14.7 mA **High performance pinout Disable mode**

APPLICATIONS

Analog-to-digital drivers Instrumentation Filters IF and baseband amplifiers **DAC buffers Optical electronics**

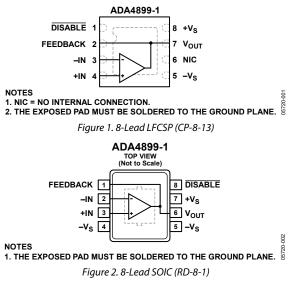
GENERAL DESCRIPTION

The ADA4899-1 is an ultralow noise (1 nV/ \sqrt{Hz}) and distortion (<-117 dBc at 1 MHz) unity-gain stable voltage feedback op amp, the combination of which makes it ideal for 16-bit and 18-bit systems. The ADA4899-1 features a linear, low noise input stage and internal compensation that achieves high slew rates and low noise even at unity gain. The Analog Devices, Inc., proprietary next-generation XFCB process and innovative circuit design enable such high performance amplifiers.

The ADA4899-1 drives 100 Ω loads at breakthrough performance levels with only 15 mA of supply current. With the wide supply voltage range (4.5 V to 12 V), low offset voltage (230 µV maximum), wide bandwidth (600 MHz), and slew rate (310 V/µs), the ADA4899-1 is designed to work in the most demanding applications. The ADA4899-1 also features an input bias current cancellation mode that reduces input bias current by a factor of 60.

CONNECTION DIAGRAMS

ADA4899-1



The ADA4899-1 is available in a 3 mm \times 3 mm LFCSP and an 8-lead SOIC package. Both packages feature an exposed metal paddle that improves heat transfer to the ground plane, which is a significant improvement over traditional plastic packages. The ADA4899-1 is rated to work over the extended industrial temperature range, -40°C to +125°C.

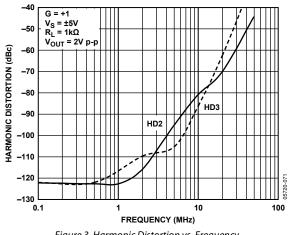


Figure 3. Harmonic Distortion vs. Frequency

Rev. C

Document Feedback

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

One Technology Way, P.O. Box 9106, Norwood, MA 02062-9106, U.S.A. Tel: 781.329.4700 ©2005–2016 Analog Devices, Inc. All rights reserved. **Technical Support** www.analog.com

ADA4899-1* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

COMPARABLE PARTS 🖵

View a parametric search of comparable parts.

EVALUATION KITS

• Universal Evaluation Board for Single High Speed Operational Amplifiers

DOCUMENTATION

Application Notes

- AN-0993: Active Filter Evaluation Board for Analog Devices, Inc., - Low Distortion Pinout Op Amps
- AN-402: Replacing Output Clamping Op Amps with Input Clamping Amps
- AN-417: Fast Rail-to-Rail Operational Amplifiers Ease Design Constraints in Low Voltage High Speed Systems
- AN-581: Biasing and Decoupling Op Amps in Single Supply Applications
- AN-649: Using the Analog Devices Active Filter Design Tool
- AN-931: Understanding PulSAR ADC Support Circuitry

Data Sheet

• ADA4899-1: Unity-Gain Stable, Ultralow Distortion, 1 nV/ √Hz Voltage Noise, High Speed Op Amp Data Sheet

User Guides

- UG-084: Evaluation Board for Single, High Speed Operational Amplifiers (8-Lead, SOIC with Dedicated Feedback Pin and Exposed Paddle)
- UG-755: 8-Lead SOIC Amplifier Evaluation Board User Guide
- UG-919: Universal Evaluation Board for Single, 8-Lead LFCSP Operational Amplifiers

TOOLS AND SIMULATIONS \Box

- Analog Filter Wizard
- Analog Photodiode Wizard
- Power Dissipation vs Die Temp
- VRMS/dBm/dBu/dBV calculators
- ADA4899 SPICE Macro Model

REFERENCE DESIGNS

• CN0080

REFERENCE MATERIALS

Product Selection Guide

- High Speed Amplifiers Selection Table
- SAR ADC & Driver Quick-Match Guide

Tutorials

- MT-032: Ideal Voltage Feedback (VFB) Op Amp
- MT-033: Voltage Feedback Op Amp Gain and Bandwidth
- MT-047: Op Amp Noise
- MT-048: Op Amp Noise Relationships: 1/f Noise, RMS Noise, and Equivalent Noise Bandwidth
- MT-049: Op Amp Total Output Noise Calculations for Single-Pole System
- MT-050: Op Amp Total Output Noise Calculations for Second-Order System
- MT-052: Op Amp Noise Figure: Don't Be Misled
- MT-053: Op Amp Distortion: HD, THD, THD + N, IMD, SFDR, MTPR
- MT-056: High Speed Voltage Feedback Op Amps
- MT-058: Effects of Feedback Capacitance on VFB and CFB Op Amps
- MT-059: Compensating for the Effects of Input Capacitance on VFB and CFB Op Amps Used in Current-to-Voltage Converters
- MT-060: Choosing Between Voltage Feedback and Current Feedback Op Amps

DESIGN RESOURCES

- ADA4899-1 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

View all ADA4899-1 EngineerZone Discussions.

SAMPLE AND BUY 🖵

Visit the product page to see pricing options.

TECHNICAL SUPPORT 🖵

Submit a technical question or find your regional support number.



Submit feedback for this data sheet.

This page is dynamically generated by Analog Devices, Inc., and inserted into this data sheet. A dynamic change to the content on this page will not trigger a change to either the revision number or the content of the product data sheet. This dynamic page may be frequently modified.

TABLE OF CONTENTS

Features	1
Applications	1
Connection Diagrams	1
General Description	1
Revision History	2
Specifications with ±5 V Supply	3
Specifications with +5 V Supply	4
Absolute Maximum Ratings	5
Maximum Power Dissipation	5
ESD Caution	5
Typical Performance Characteristics	6
Test Circuits	12
Theory of Operation	13

REVISION HISTORY

5/2016—Rev. B to Rev. C	
Changed CP-8-2 to CP-8-13	Throughout
Changes to Figure 1 and Figure 2	
Updated Outline Dimensions	
Changes to Ordering Guide	

6/2007—Rev. A to Rev. B

Changes to Table 1	
Changes to Table 2	
Changes to Figure 21 and Figure 22	
Changes to Packaging Innovation Section	
Changes to Figure 49 and Figure 50	
Updated Outline Dimensions	
-	

4/2006—Rev. 0 to Rev. A

Changes to	igure 2	
onungeo to	-9410	

10/2005—Revision 0: Initial Version

Packaging Innovation	13
DISABLE Pin	13
Applications Information	14
Unity-Gain Operation	14
Recommended Values for Various Gains	14
Noise	15
ADC Driver	15
DISABLE Pin Operation	16
ADA4899-1 Mux	16
Circuit Considerations	16
Outline Dimensions	18
Ordering Guide	

SPECIFICATIONS WITH ± 5 V SUPPLY

 T_{A} = 25°C, G = +1, R_{L} = 1 k Ω to ground, unless otherwise noted.

Table 1.

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE					
–3 dB Bandwidth	V _{OUT} = 25 mV p-p		600		MHz
	$V_{OUT} = 2 V p - p$		80		MHz
Bandwidth for 0.1 dB Flatness	$G = +2, V_{OUT} = 2 V p - p$		35		MHz
Slew Rate	$V_{OUT} = 5 V step$		310		V/µs
Settling Time to 0.1%	$V_{OUT} = 2 V step$		50		ns
NOISE/DISTORTION PERFORMANCE					
Harmonic Distortion, HD2/HD3 (dBc)	f _c = 500 kHz, V _{оит} = 2 V p-p		-123/-123		dBc
	$f_c = 10 \text{ MHz}, V_{OUT} = 2 \text{ V p-p}$		-80/-86		dBc
Input Voltage Noise	f = 100 kHz		1.0		nV/√Hz
Input Current Noise	f = 100 kHz, DISABLE pin floating		2.6		pA/√Hz
input current hoise	f = 100 kHz, DISABLE pin Houting		5.2		pA/√Hz
	I = 100 KHZ, DISABLE PIII = +VS		5.2		рауунд
DC PERFORMANCE			25		
Input Offset Voltage			35	230	μV
Input Offset Voltage Drift			5		μV/°C
Input Bias Current	DISABLE pin floating		-6	-12	μΑ
	$\overline{\text{DISABLE}}$ pin = +Vs		-0.1	-1	μΑ
Input Bias Current Drift			3		nA/°C
Input Bias Offset Current			0.05	0.7	μA
Open-Loop Gain		82	85		dB
INPUT CHARACTERISTICS					
Input Resistance	Differential mode		4		kΩ
•	Common mode		7.3		MΩ
Input Capacitance			4.4		рF
Input Common-Mode Voltage Range			-3.7 to +3.7		V
Common-Mode Rejection Ratio		98	130		dB
DISABLE PIN					
DISABLE Input Threshold Voltage	Output disabled		<2.4		v
Turn-Off Time	·				-
Turn-On Time	50% of DISABLE voltage to 10% of V_{OUT} , $V_{IN} = 0.5 V$		100		ns
Turn-On Time			40		
Turn-On Time	50% of DISABLE voltage to 90% of V_{OUT} , $V_{IN} = 0.5 V$		40		ns
In put Ding Current			17	21	
Input Bias Current	$\overline{\text{DISABLE}} = +V_{\text{s}} \text{ (enabled)}$		17	21	μA
	$\overline{\text{DISABLE}} = -V_{\text{S}}$ (disabled)		-35	-44	μΑ
OUTPUT CHARACTERISTICS					
Output Overdrive Recovery Time (Rise/Fall)	$V_{IN} = -2.5 V \text{ to } +2.5 V, G = +2$		30/50		ns
Output Voltage Swing	$R_L = 1 \ k\Omega$	-3.65 to +3.65	-3.7 to +3.7		V
	$R_L = 100 \ \Omega$	-3.13 to +3.15	-3.25 to +3.25		V
Short-Circuit Current	Sinking/sourcing		160/200		mA
Off Isolation	$f = 1 \text{ MHz}, \overline{\text{DISABLE}} = -V_{\text{S}}$		-48		dB
POWER SUPPLY		1			
Operating Range		4.5		12	v
Quiescent Current			14.7	16.2	mA
Quiescent Current (Disabled)	$\overline{\text{DISABLE}} = -V_{\text{s}}$		1.8	2.1	mA
Positive Power Supply Rejection Ratio	$+V_s = 4 V \text{ to } 6 V \text{ (input referred)}$	84	90	2.1	dB
	-				
Negative Power Supply Rejection Ratio	$-V_s = -6 V$ to $-4 V$ (input referred)	87	93		dB

SPECIFICATIONS WITH +5 V SUPPLY

 V_{S} = 5 V at T_{A} = 25°C, G = +1, R_{L} = 1 k Ω to midsupply, unless otherwise noted.

Table 2.

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
DYNAMIC PERFORMANCE					
–3 dB Bandwidth	V _{оит} = 25 mV p-p		535		MHz
	V _{OUT} = 2 V p-p		60		MHz
Bandwidth for 0.1 dB Flatness	$G = +2, V_{OUT} = 2 V p - p$		25		MHz
Slew Rate	$V_{OUT} = 2 V step$		185		V/µs
Settling Time to 0.1%	$V_{OUT} = 2 V step$		50		ns
NOISE/DISTORTION PERFORMANCE					
Harmonic Distortion, HD2/HD3 (dBc)	f _c = 500 kHz, V _{оит} = 1 V р-р		-100/-113		dBc
	f _c = 10 MHz, V _{out} = 1 V p-p		-89/-100		dBc
Input Voltage Noise	f = 100 kHz		1.0		nV/√Hz
Input Current Noise	f = 100 kHz, DISABLE pin floating		2.6		pA/√Hz
input current roise	$f = 100 \text{ kHz}, \overline{\text{DISABLE pin}} = +V_s$		5.2		pA/√Hz
			J.2		P// //12
DC PERFORMANCE			-	210	
Input Offset Voltage			5	210	μV
Input Offset Voltage Drift			5		μV/°C
Input Bias Current	DISABLE pin floating		-6	-12	μΑ
	$\overline{\text{DISABLE}}$ pin = +Vs		-0.2	-1.5	μΑ
Input Bias Offset Current			0.05		μΑ
Input Bias Offset Current Drift			2.5		nA/°C
Open-Loop Gain		76	80		dB
INPUT CHARACTERISTICS					
Input Resistance	Differential mode		4		kΩ
	Common mode		7.7		MΩ
Input Capacitance			4.4		рF
Input Common-Mode Voltage Range			1.3 to 3.7		v
Common-Mode Rejection Ratio		90	114		dB
DISABLE PIN					
DISABLE Input Threshold Voltage	Output disabled		<2.4		v
Turn-Off Time					-
Tum-On Time	50% of DISABLE voltage to 10% of V _{OUT} , $V_{IN} = 0.5 V$		100		ns
			60		
Turn-On Time	50% of DISABLE voltage to 90% of V _{OUT} , $V_{IN} = 0.5 V$		60		ns
Input Bias Current	$\overline{\text{DISABLE}} = +V_{\text{s}} \text{ (enabled)}$		16	18	
input bias current					μA
	$\overline{\text{DISABLE}} = -V_{\text{S}}$ (disabled)		-33	-42	μΑ
OUTPUT CHARACTERISTICS					
Overdrive Recovery Time (Rise/Fall)	$V_{IN} = 0 V$ to 2.5 V, G = +2		50/70		ns
Output Voltage Swing	$R_L = 1 \ k\Omega$	1.25 to 3.75	1.2 to 3.8		V
	$R_L = 100 \ \Omega$	1.4 to 3.6	1.35 to 3.65		V
Short-Circuit Current	Sinking/sourcing		60/80		mA
Off Isolation	$f = 1 \text{ MHz}, \overline{\text{DISABLE}} = -V_s$		-48		dB
POWER SUPPLY					
Operating Range		4.5		12	v
Quiescent Current			14.3	16	mA
Quiescent Current (Disabled)	$\overline{\text{DISABLE}} = -V_{\text{S}}$		1.5	1.7	mA
Positive Power Supply Rejection Ratio	$+V_{s} = 4.5 V \text{ to } 5.5 V, -V_{s} = 0 V (\text{input referred})$	84	90		dB
Negative Power Supply Rejection Ratio		86	90		dB

ABSOLUTE MAXIMUM RATINGS

Table 3.

Parameter	Rating
Supply Voltage	12.6 V
Power Dissipation	See Figure 4
Differential Input Voltage	±1.2 V
Differential Input Current	±10 mA
Storage Temperature Range	–65°C to +150°C
Operating Temperature Range	–40°C to +125°C
Lead Temperature (Soldering 10 sec)	300°C
Junction Temperature	150°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

MAXIMUM POWER DISSIPATION

The maximum safe power dissipation in the ADA4899-1 package is limited by the associated rise in junction temperature (T_j) on the die. The plastic encapsulating the die locally reaches the junction temperature. At approximately 150°C, which is the glass transition temperature, the plastic changes its properties. Even temporarily exceeding this temperature limit may change the stresses that the package exerts on the die, permanently shifting the parametric performance of the ADA4899-1. Exceeding a junction temperature of 150°C for an extended period can result in changes in silicon devices, potentially causing failure.

The still-air thermal properties of the package and PCB (θ_{JA}), the ambient temperature (T_A), and the total power dissipated in the package (P_D) determine the junction temperature of the die. The junction temperature is calculated as

$$T_J = T_A + (P_D \times \theta_{\rm JA})$$

The power dissipated in the package (P_D) is the sum of the quiescent power dissipation and the power dissipated in the package due to the load drive for all outputs. The quiescent power is the voltage between the supply pins (V_S) times the quiescent current (I_S). Assuming the load (R_L) is referenced to midsupply, the total drive power is V_S/2 × I_{OUT}, some of which is dissipated in the package and some in the load (V_{OUT} × I_{OUT}).

The difference between the total drive power and the load power is the drive power dissipated in the package.

 P_D = Quiescent Power + (Total Drive Power – Load Power)

$$P_D = \left(V_S \times I_S\right) + \left(\frac{V_S}{2} \times \frac{V_{OUT}}{R_L}\right) - \frac{V_{OUT}^2}{R_L}$$

RMS output voltages should be considered. If R_L is referenced to V_S -, as in single-supply operation, the total drive power is $V_S \times I_{OUT}$. If the rms signal levels are indeterminate, consider the worst case, when $V_{OUT} = V_S/4$ for R_L to midsupply.

$$P_D = \left(V_S \times I_S\right) + \frac{\left(V_S/4\right)^2}{R_I}$$

In single-supply operation with $R_{\rm L}$ referenced to $V_{S}\text{-},$ the worst case is $V_{\rm OUT}$ = $V_{S}/2.$

Airflow increases heat dissipation, effectively reducing θ_{JA} . In addition, more metal directly in contact with the package leads from metal traces, through holes, ground, and power planes reduces the θ_{JA} . Soldering the exposed paddle to the ground plane significantly reduces the overall thermal resistance of the package.

Figure 4 shows the maximum safe power dissipation in the package vs. the ambient temperature for the exposed paddle (EPAD) 8-lead SOIC (70°C/W) and 8-lead LFCSP (70°C/W) packages on a JEDEC standard 4-layer board. θ_{JA} values are approximations.

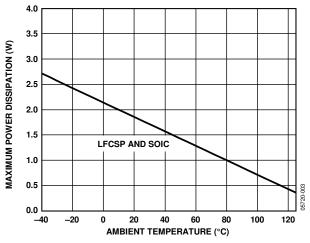


Figure 4. Maximum Power Dissipation vs. Ambient Temperature

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

TYPICAL PERFORMANCE CHARACTERISTICS

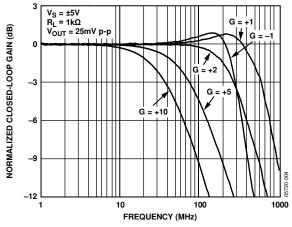


Figure 5. Small Signal Frequency Response for Various Gains, $R_L = 1 k\Omega$

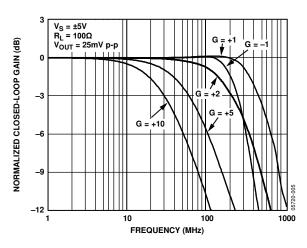


Figure 6. Small Signal Frequency Response for Various Gains, $R_L = 100 \Omega$

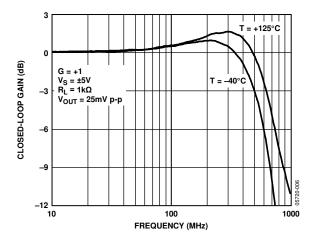


Figure 7. Small Signal Frequency Response for Various Temperatures

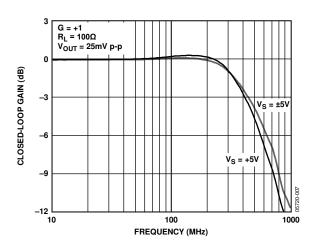
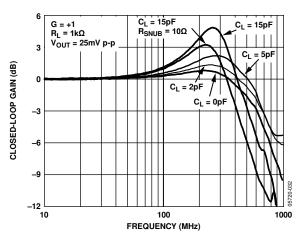


Figure 8. Small Signal Frequency Response for Various Supply Voltages



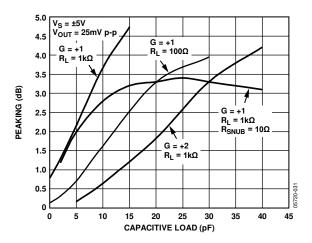


Figure 9. Small Signal Frequency Response for Capacitive Loads

Figure 10. Small Signal Frequency Response Peaking vs. Capacitive Load for Various Gains

Data Sheet

0.1 0 CLOSED-LOOP GAIN (dB) -0.1 V_{OUT} = 100mV p-p -0.2 V_{OUT} = 2V p-p -0.3 -0.4 G = +2 $V_S = \pm 5V$ $R_L = 150\Omega$ -0.5 10 100 1 FREQUENCY (MHz)

Figure 11. 0.1 dB Flatness for Various Output Voltages

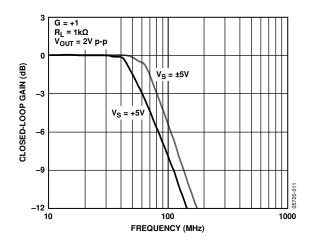


Figure 12. Large Signal Frequency Response for Various Supply Voltages

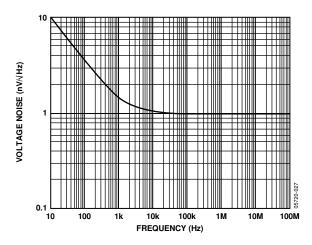


Figure 13. Voltage Noise vs. Frequency

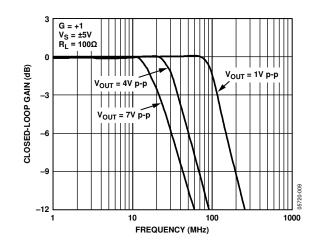


Figure 14. Large Signal Frequency Response for Various Output Voltages

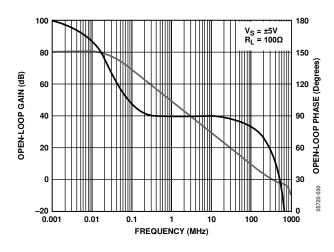


Figure 15. Open-Loop Gain/Phase vs. Frequency

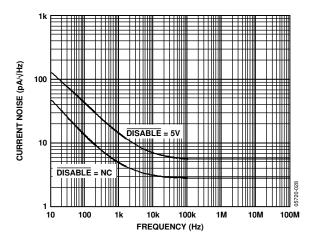


Figure 16. Input Current Noise vs. Frequency

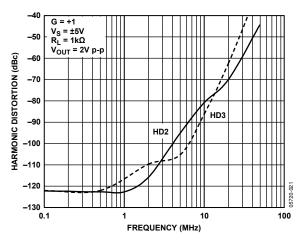


Figure 17. Harmonic Distortion vs. Frequency

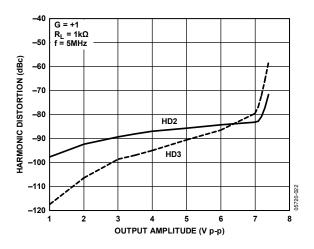


Figure 18. Harmonic Distortion vs. Output Amplitude

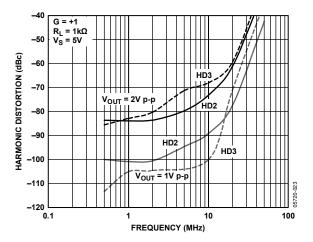


Figure 19. Harmonic Distortion vs. Frequency

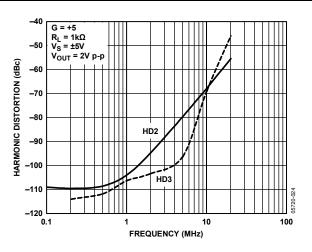


Figure 20. Harmonic Distortion vs. Frequency

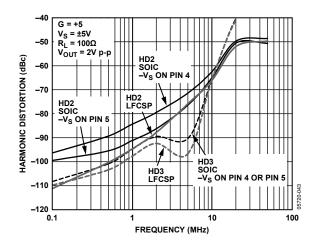


Figure 21. Harmonic Distortion vs. Frequency for Various Pinouts and Packages

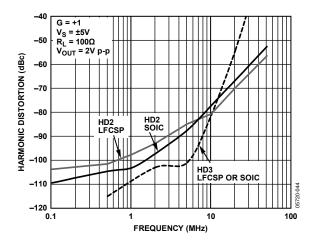
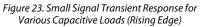


Figure 22. Harmonic Distortion vs. Frequency for Both Packages

Data Sheet

0.10 G = +1 C_L = 15pF $C_L = 5pF$ V_S = ±5V C_L = 15pF ----R_{SNUB} = 10Ω 0.08 $R_L = 1k\Omega$ 0.06 (2) 0.04 (3) 0.02 (4) 0.02 (7) 0 $C_L = 0 p F$ -0.06 -0.08 05720-041 -0.10 0 5 10 15 TIME (ns)



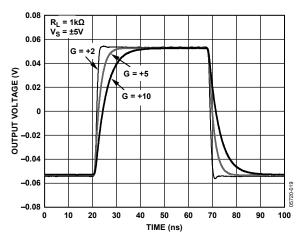


Figure 24. Small Signal Transient Response for Various Gains

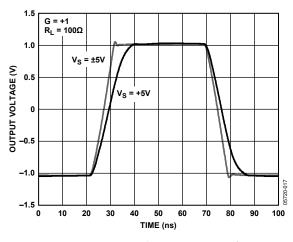


Figure 25. Large Signal Transient Response for Various Supply Voltages, $R_L = 100 \Omega$

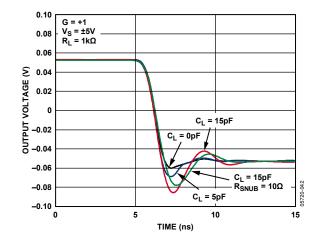


Figure 26. Small Signal Transient Response for Various Capacitive Loads (Falling Edge)

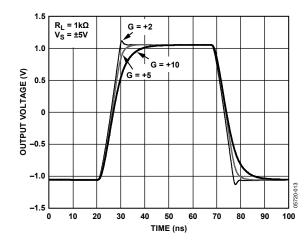


Figure 27. Large Signal Transient Response for Various Gains

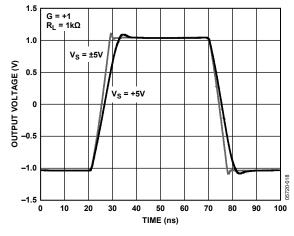
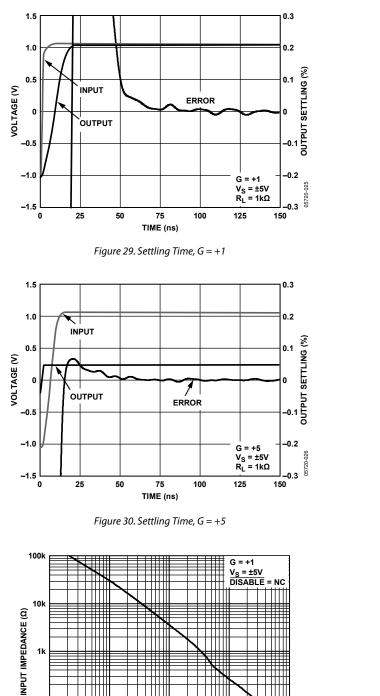


Figure 28. Large Signal Transient Response for Various Supply Voltages, $R_L = 1 k\Omega$



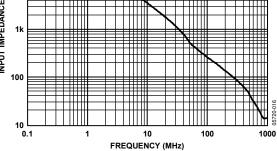


Figure 31. Input Impedance vs. Frequency

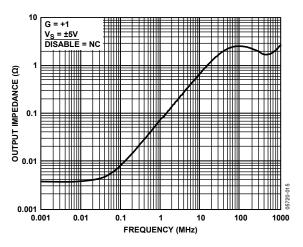
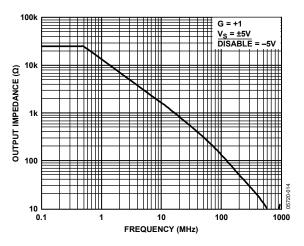


Figure 32. Output Impedance vs. Frequency





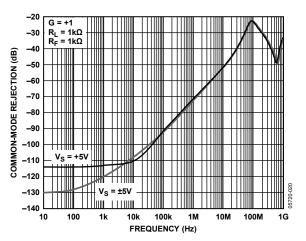
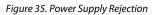
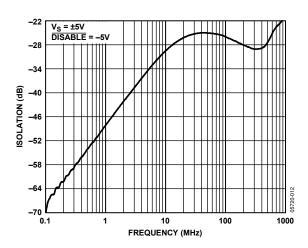


Figure 34. Common-Mode Rejection vs. Frequency

Data Sheet

0 -10 -20 SUPPLY REJECTION (dB) -30 -40 -50 -PSR -60 +PSR -70 -80 -90 5720 -100 0.001 0.01 0.1 1 10 100 1000 FREQUENCY (MHz)







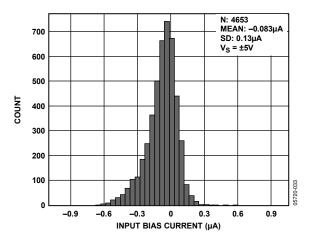


Figure 37. Input Bias Current Distribution

N: 4651 MEAN: -4.92µV SD: 29.22µV V_S = 5V 500 400 300 COUNT 200 100 034 5720 0 -200 -150 -100 -50 0 50 100 150 200

Figure 38. Input Offset Voltage Distribution ($V_S = 5 V$)

VOLTAGE OFFSET (µV)

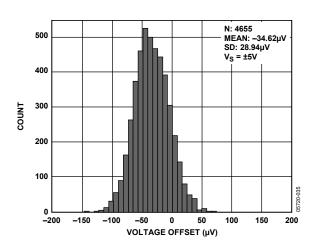


Figure 39. Input Offset Voltage Distribution ($V_s = \pm 5 V$)

TEST CIRCUITS

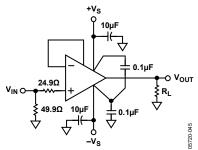


Figure 40. Typical Noninverting Load Configuration

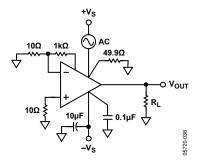


Figure 41. Positive Power Supply Rejection

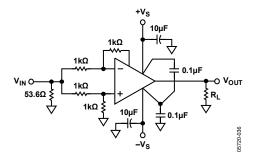


Figure 42. Common-Mode Rejection

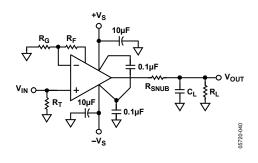


Figure 43. Typical Capacitive Load Configuration

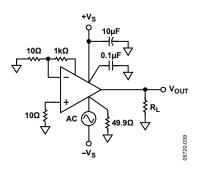
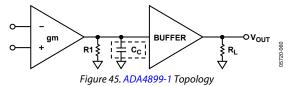


Figure 44. Negative Power Supply Rejection

THEORY OF OPERATION

The ADA4899-1 is a voltage feedback op amp that combines unity-gain stability with a 1 nV/ \sqrt{Hz} input noise. It employs a highly linear input stage that can maintain greater than -80 dBc (at 2 V p-p) distortion out to 10 MHz while in a unity-gain configuration. This rare combination of low gain stability, input-referred noise, and extremely low distortion is the result of Analog Devices proprietary op amp architecture and high speed complementary bipolar processing technology.

The simplified ADA4899-1 topology, shown in Figure 45, is a single gain stage with a unity-gain output buffer. It has over 80 dB of open-loop gain and maintains precision specifications such as CMRR, PSRR, and offset to levels that are normally associated with topologies having two or more gain stages.



A pair of internally connected diodes limits the differential voltage between the noninverting input and the inverting input of the ADA4899-1. Each set of diodes has two series diodes connected in antiparallel, which limits the differential voltage between the inputs to approximately ±1.2 V. All of the ADA4899-1 pins are ESD protected with voltage-limiting diodes connected between both rails. The protection diodes can handle 10 mA. Currents should be limited through these diodes to 10 mA or less by using a series limiting resistor.

PACKAGING INNOVATION

The ADA4899-1 is available in both a SOIC and an LFCSP, each of which has a thermal pad that allows the device to run cooler, thereby increasing reliability. To help avoid routing around the pad when laying out the board, both packages have a dedicated feedback pin on the opposite side of the package for ease in connecting the feedback network to the inverting input. The secondary output pin also isolates the interaction of any capacitive load on the output and the self-inductance of the package and bond wire from the feedback loop. When using the dedicated feedback pin, inductance in the primary output helps to isolate capacitive loads from the output impedance of the amplifier.

Both the SOIC and LFCSP have modified pinouts to improve heavy load second harmonic distortion performance. The intent of both is to isolate the negative supply pin from the noninverting input. The LFCSP accomplishes this by rotating the standard 8-lead package pinout counterclockwise by one pin, which puts the supply and output pins on the right side of the package and the input pins on the left side of the package. The SOIC is slightly different with the intent of both isolating the inputs from the supply pins and giving the user the option of using the ADA4899-1 in a standard SOIC board layout with little or no modification. Taking the unused Pin 5 and making it a second negative supply pin allows for both an input isolated layout and a traditional layout to be supported.

DISABLE PIN

A three-state input pin is provided on the ADA4899-1 for a high impedance disable and an optional input bias current cancellation circuit. The high impedance output allows several ADA4899-1 devices to drive the same ADC or output line time interleaved. Pulling the DISABLE pin low activates the high impedance state (see Table 7 for threshold levels). When the DISABLE pin is left floating (open), the ADA4899-1 operates normally. With the DISABLE pin pulled within 0.7 V of the positive supply, an optional input bias current cancellation circuit is turned on, which lowers the input bias current to less than 200 nA. In this mode, the user can drive the ADA4899-1 from a high dc source impedance and still maintain minimal output-referred offset without having to use impedance matching techniques. In addition, the ADA4899-1 can be ac-coupled while setting the bias point on the input with a high dc impedance network. The input bias current cancellation circuit doubles the input-referred current noise, but this effect is minimal as long as the wideband impedances are kept low (see Figure 16).

APPLICATIONS INFORMATION UNITY-GAIN OPERATION

The ADA4899-1 schematic for unity-gain configuration is nearly a textbook example (see Figure 46). The only exception is the small 24.9 Ω series resistor at the noninverting input. The series resistor is only required in unity-gain configurations; higher gains negate the need for the resistor. In Table 4, it can be seen that the overall noise contribution of the amplifier and the 24.9 Ω resistor is equivalent to the noise of a single 87 Ω resistor.

Figure 47 shows the small signal frequency response for the unity-gain amplifier shown in Figure 46.

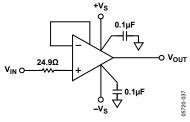


Figure 46. Unity-Gain Schematic

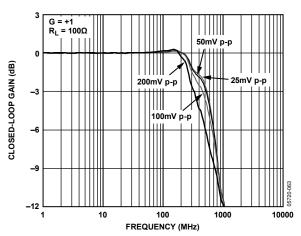


Figure 47. Small Signal Frequency Response for Various Output Voltages

RECOMMENDED VALUES FOR VARIOUS GAINS

Table 4 provides a handy reference for determining various gains and associated performance. For noise gains greater than one, the Series Resistor R_S is not required. Resistor R_F and Resistor R_G are kept low to minimize their contribution to the overall noise performance of the amplifier.

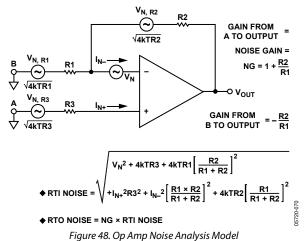
Gain	R _F (Ω)	R _G (Ω)	Rs (Ω)	–3 dB SS BW (MHz) (25 mV p-p)	Slew Rate (V/µs) (2 V Step)	ADA4899-1 Voltage Noise (nV/√Hz)	Total Voltage Noise (nV/√Hz)
+1	0	Not applicable	24.9	605	274	1	1.2
-1	100	100	0	294	265	2	2.7
+2	100	100	0	277	253	2	2.7
+5	200	49.9	0	77	227	5	6.5
+10	453	49.9	0	37	161	10	13.3

Table 4. Conditions: $V_s = \pm 5 V$, $T_A = 25^{\circ}C$, $R_L = 1 k\Omega$

NOISE

To analyze the noise performance of an amplifier circuit, first identify the noise sources, then determine if the source has a significant contribution to the overall noise performance of the amplifier. To simplify the noise calculations, noise spectral densities were used, rather than actual voltages to leave bandwidth out of the expressions (noise spectral density, which is generally expressed in nV/\sqrt{Hz} , is equivalent to the noise in a 1 Hz bandwidth).

The noise model shown in Figure 48 has six individual noise sources: the Johnson noise of the three resistors, the op amp voltage noise, and the current noise in each input of the amplifier. Each noise source has its own contribution to the noise at the output. Noise is generally specified referred to input (RTI), but it is often simpler to calculate the noise referred to the output (RTO) and then divide by the noise gain to obtain the RTI noise.



All resistors have a Johnson noise that is calculated by

 $\sqrt{(4kBTR)}$

where:

k is Boltzmann's Constant (1.38×10^{-23} J/K).

B is the bandwidth in Hz.

T is the absolute temperature in Kelvin.

R is the resistance in ohms.

A simple relationship that is easy to remember is that a 50 Ω resistor generates a Johnson noise of 1 nV \sqrt{Hz} at 25°C.

In applications where noise sensitivity is critical, take care not to introduce other significant noise sources to the amplifier. Each resistor is a noise source. Attention to design, layout, and component selection is critical to maintain low noise performance. A summary of noise performance for the amplifier and associated resistors can be seen in Table 4.

ADC DRIVER

The ultralow noise and distortion performance of the ADA4899-1 makes it an excellent candidate for driving 16-bit ADCs. The schematic for a single-ended input buffer using the ADA4899-1 and the AD7677, a 1 MSPS, 16-bit ADC, is shown in Figure 49. Table 5 shows the performance data of the ADA4899-1 and the AD7677.

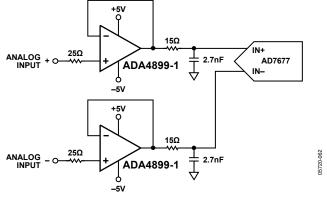


Figure 49. Single-Ended Input ADC Driver

Table 5. ADA4899-1, Single-Ended Driver for AD7677 16-Bit,
1 MSPS, $f_c = 50 \text{ kHz}$

Parameter	Measurement (dB)
Second Harmonic Distortion	-116.5
Third Harmonic Distortion	-111.9
THD	-108.6
SFDR	+101.4
SNR	+92.6

The ADA4899-1 configured as a single-ended-to-differential driver for the AD7677 is shown in Figure 50. Table 6 shows the associated performance.

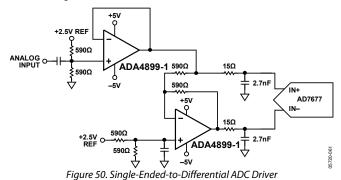


Table 6. ADA4899-1, Single Ended-to-Differential Driver for
AD7677 16-Bit, 1 MSPS, $f_c = 500 \text{ kHz}$

Parameter	Measurement (dB)		
THD	-92.7		
SFDR	+91.8		
SNR	+90.6		

DISABLE PIN OPERATION

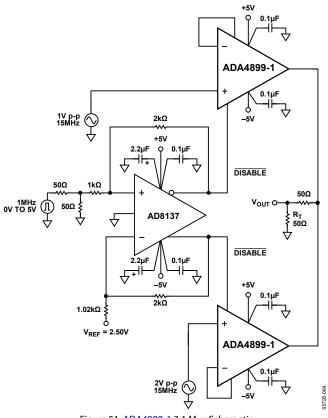
The ADA4899-1 DISABLE pin performs three functions: enable, disable, and reduction of the input bias current. When the DISABLE pin is brought to within 0.7 V of the positive supply, the input bias current circuit is enabled, which reduces the input bias current by a factor of 100. In this state, the input current noise doubles from 2.6 pA/ $\sqrt{\text{Hz}}$ to 5.2 pA/ $\sqrt{\text{Hz}}$. Table 7 outlines the DISABLE pin operation.

Table 7. DISABLE Pin Truth Table

Supply Voltage	±5 V	+5 V
Disable	-5 V to +2.4 V	0 V to 2.4 V
Enable	Open	Open
Low Input Bias Current	4.3 V to 5 V	4.3 V to 5 V

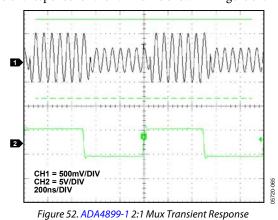
ADA4899-1 MUX

With a true output disable, the ADA4899-1 can be used in multiplexer applications. The outputs of two ADA4899-1 devices are wired together to form a 2:1 mux. Figure 51 shows the 2:1 mux schematic.





An AD8137 differential amplifier is used as a level translator that converts the TTL input to a complementary ± 3 V output to drive the DISABLE pins of the ADA4899-1 devices. The transient response for the 2:1 mux is shown in Figure 52.



CIRCUIT CONSIDERATIONS

Careful and deliberate attention to detail when laying out the ADA4899-1 board yields optimal performance. Power supply bypassing, parasitic capacitance, and component selection all contribute to the overall performance of the amplifier.

PCB Layout

Because the ADA4899-1 can operate up to 600 MHz, it is essential that RF board layout techniques be employed. All ground and power planes under the pins of the ADA4899-1 should be cleared of copper to prevent the formation of parasitic capacitance between the input pins to ground and the output pins to ground. A single mounting pad on a SOIC footprint can add as much as 0.2 pF of capacitance to ground if the ground plane is not cleared from under the mounting pads. The low distortion pinout of the ADA4899-1 reduces the distance between the output and the inverting input of the amplifier. This helps minimize the parasitic inductance and capacitance of the feedback path, which reduces ringing and second harmonic distortion.

Power Supply Bypassing

Power supply bypassing for the ADA4899-1 has been optimized for frequency response and distortion performance. Figure 40 shows the recommended values and location of the bypass capacitors. Power supply bypassing is critical for stability, frequency response, distortion, and PSR performance. The 0.1 μ F capacitors shown in Figure 40 should be as close to the supply pins of the ADA4899-1 as possible. The electrolytic capacitors should be directly adjacent to the 0.1 μ F capacitors. The capacitor between the two supplies helps improve PSR and distortion performance. In some cases, additional paralleled capacitors can help improve frequency and transient response.

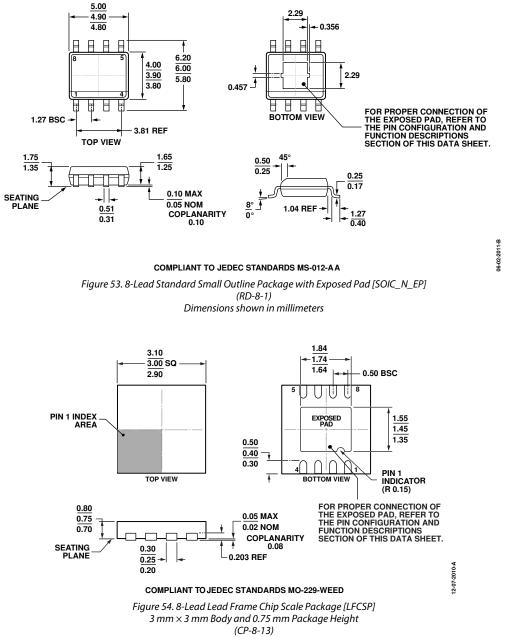
Grounding

Use ground and power planes where possible. Ground and power planes reduce the resistance and inductance of the power planes and ground returns. The returns for the input, output terminations, bypass capacitors, and R_G should all be kept as close to the ADA4899-1 as possible. The output load ground and the bypass capacitor grounds should be returned to the same point on the ground plane to minimize parasitic trace

inductance, ringing, and overshoot and to improve distortion performance.

The ADA4899-1 packages feature an exposed paddle. For optimum electrical and thermal performance, solder this paddle to ground. For more information on high speed circuit design, see *A Practical Guide to High-Speed Printed-Circuit-Board Layout*.

OUTLINE DIMENSIONS



Dimensions shown in millimeters

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option	Branding	Ordering Quantity
ADA4899-1YRDZ	-40°C to +125°C	8-Lead SOIC_N_EP	RD-8-1		1
ADA4899-1YRDZ-R7	-40°C to +125°C	8-Lead SOIC_N_EP	RD-8-1		1,000
ADA4899-1YRDZ-RL	-40°C to +125°C	8-Lead SOIC_N_EP	RD-8-1		2,500
ADA4899-1YCPZ-R2	-40°C to +125°C	8-Lead LFCSP	CP-8-13		250
ADA4899-1YCPZ-R7	-40°C to +125°C	8-Lead LFCSP	CP-8-13	HBC	1,500
ADA4899-1YCPZ-RL	-40°C to +125°C	8-Lead LFCSP	CP-8-13	HBC	5,000

 1 Z = RoHS Compliant Part.

NOTES

NOTES



www.analog.com