# imall

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from, Europe, America and south Asia, supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts, Customers Priority, Honest Operation, and Considerate Service", our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip, ALPS, ROHM, Xilinx, Pulse, ON, Everlight and Freescale. Main products comprise IC, Modules, Potentiometer, IC Socket, Relay, Connector. Our parts cover such applications as commercial, industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



# Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



### **ADAM-6000 Series**

Ethernet-based Data Acquisition and Control Modules

**User Manual** 

#### Copyright

The documentation and the software included with this product are copyrighted 2017 by Advantech Co., Ltd. All rights are reserved. Advantech Co., Ltd. reserves the right to make improvements in the products described in this manual at any time without notice. No part of this manual may be reproduced, copied, translated or transmitted in any form or by any means without the prior written permission of Advantech Co., Ltd. Information provided in this manual is intended to be accurate and reliable. However, Advantech Co., Ltd. assumes no responsibility for its use, nor for any infringements of the rights of third parties, which may result from its use.

#### Acknowledgements

Intel and Pentium are trademarks of Intel Corporation.

Microsoft Windows and MS-DOS are registered trademarks of

Microsoft Corp.

All other product names or trademarks are properties of their respective owners.

Part Number: 2003600002 June 2017

8th Edition

#### Product Warranty (2 years)

Advantech warrants to you, the original purchaser, that each of its products will be free from defects in materials and workmanship for two years from the date of purchase.

This warranty does not apply to any products which have been repaired or altered by persons other than repair personnel authorized by Advantech, or which have been subject to misuse, abuse, accident or improper installation. Advantech assumes no liability under the terms of this warranty as a consequence of such events.

Because of Advantech's high quality-control standards and rigorous testing, most of our customers never need to use our repair service. If an Advantech product is defective, it will be repaired or replaced at no charge during the warranty period. For out-of-warranty repairs, you will be billed according to the cost of replacement materials, service time and freight. Please consult your dealer for more details.

If you think you have a defective product, follow these steps:

- 1. Collect all the information about the problem encountered. (For example, CPU speed, Advantech products used, other hardware and software used, etc.) Note anything abnormal and list any onscreen messages you get when the problem occurs.
- 2. Call your dealer and describe the problem. Please have your manual, product, and any helpful information readily available.
- 3. If your product is diagnosed as defective, obtain an RMA (return merchandize authorization) number from your dealer. This allows us to process your return more quickly.
- 4. Carefully pack the defective product, a fully-completed Repair and Replacement Order Card and a photocopy proof of purchase date (such as your sales receipt) in a shippable container. A product returned without proof of the purchase date is not eligible for warranty service.
- 5. Write the RMA number visibly on the outside of the package and ship it prepaid to your dealer.

#### **Technical Support and Assistance**

- Step 1. Visit the Advantech web site at **www.advantech.com/support** where you can find the latest information about the product.
- Step 2. Contact your distributor, sales representative, or Advantech's customer service center for technical support if you need additional assistance. Please have the following information ready before you call:
  - Product name and serial number
  - Description of your peripheral attachments
  - Description of your software (OS, version, software, etc.)
  - A complete description of the problem
  - The exact wording of any error messages

Chapter	1	Understanding Your System	2
-	1.1	Introduction	2
		Figure 1.1:ADAM-6000 System Architecture	2
	1.2	Major Features	3
		1.2.1 Ethernet-enabled DA&C I/O Modules	3
		1.2.2 Intelligent I/O Modules	3
		1.2.3 Mixed I/O to Fit All Applications	3
		1.2.4 Remote Monitoring & Diagnosis	3
		1.2.5 Industrial Standard Modbus/TCP Protocol	4
		1.2.6 Customized Web Page	4
		1.2.7 Modbus/TCP Software Support	5
	1.3	Specifications	5
	1.4	Dimensions	6
		Figure 1.2:ADAM-6000 Module Dimension	6
	1.5	LED Status	6
		Figure 1.3:LED Indicators	6
		1.5.1 Locate	7
Chapter	2	Selecting Your Hardware	. 10
	21	Selecting an I/O Module	10
		Table 2.1:I/O Selection Guidelines	11
	2.2	Selecting a Link Terminal & Cable	12
		Figure 2.1:Ethernet Terminal and Cable Connection	12
		Table 2.2:Ethernet RJ-45 port Pin Assignment	12
	2.3	Selecting an Operator Interface	13
Chapter	3	Hardware Installation Guide	. 16
	3.1	Determining the Proper Environment	16
		3.1.1 Package Contents	16
		3.1.2 System Requirements	16
	3.2	Mounting	17
		3.2.1 Panel Mounting	17
		Figure 3.1:Panel Mounting Dimensions	17
		Figure 3.2: Fix Module on the Bracket	18
		3.2.2 DIN-rail mounting	18
		Figure 3.3: Fix Module on the DIN-rail Adapter	19
		Figure 3.4:Secure Module to a DIN-rail	20
	3.3	Wiring & Connections	20
		3.3.1 Power Supply Wiring	20
		Figure 3.5:ADAM-6000 Module Power Wiring	21
		3.3.2 I/O Module Wiring	21
Chapter	4	I/O Module Introduction	. 24
	4.1	Analog Input Modules	24
		4.1.1 ADAM-6015	24
		Figure 4.1:ADAM-6015 RTD Input Wiring	26
		4.1.2 ADAM-6017	27
		Figure 4.2: ADAM-6017 Analog Input Wiring	29

			Figure 4.3: ADAM-6017 Analog Input Type Setting	29
			Figure 4.4: ADAM-6017 Digital Output Wiring	30
		4.1.3	ADAM-6018	31
			Figure 4.5: ADAM-6018 8-ch Thermocouple Input	31
			Figure 4.6: ADAM-6018 Thermocouple Input Wiring	33
			Figure 4.7: ADAM-6018 Digital Output Wiring	
		4.1.4	ADAM-6024	35
			Figure 4.8: ADAM-6024 Jumper Settings	
			Figure 4.9: ADAM-6024 AI/O Wiring	38
			Figure 4.10:ADAM-6024 DI Wiring	38
			Figure 4.11:ADAM-6024 DO Wiring	39
	4.2	Digital	I/O Modules	. 40
		4.2.1	ADAM-6050	40
			Figure 4.12:ADAM-6050 Digital Input Wiring	41
			Figure 4.13:ADAM-6050 Digital Output Wiring	42
		4.2.2	ADAM-6051	43
			Figure 4.14:ADAM-6051 Digital Input Wiring	45
			Figure 4.15:ADAM-6051 Counter (Frequency) Input	.45
			Figure 4.16:ADAM-6051 DO Wiring	46
		4.2.3	ADAM-6052	47
			Figure 4.17:ADAM-6052 Jumper Settings	48
			Figure 4.18:ADAM-6052 DI Wiring	49
			Figure 4.19:ADAM-6052 Digital Output Wiring	50
		4.2.4	ADAM-6060	51
			Figure 4.20: ADAM-6060 Digital Input Wiring	53
			Figure 4.21: ADAM-6060 Relay Output Wiring	53
		4.2.5	ADAM-6066	54
			Figure 4.22: ADAM-6066 Digital Input Wiring	56
			Figure 4.23: ADAM-6066 Relay Output Wiring	56
		4.2.6	Digital Output Diagnostic Function	57
			Figure 4.24: Abnormal DO Diagnostic Status	58
			Figure 4.25:Normal DO Diagnostic Status	59
Chapter	5	Syste	m Configuration Guide	62
	51	System	Hardware Configuration	62
	0.1	5.1.1	System Requirements	62
		5.1.2	Communication Interface	62
	5.2	Install	ADAM.NET Utility Software	. 62
	5.3	ADAM	1.NET Utility Overview	. 63
		5.3.1	ADAM.NET Utility Operation Window	63
			Figure 5.1: ADAM.NET Utility Operation Window	63
			Figure 5.2: ADAM.NET Utility Toolbar	68
		5.3.2	Search ADAM-6000 Modules	70
			Figure 5.3: Access Control Setting	79
			Figure 5.4: Modbus address setting	80
		5.3.3	I/O Module Configuration	81

		Figure 5.5: Channel & GCL Configuration	81
		Figure 5.6: Channels Range Configuration Area	82
		Figure 5.7: Integration Time Configuration Area	83
		Figure 5.8: Analog Input Trend Log	85
		Figure 5.9: Analog Input Average Setting	86
		Figure 5.10: Analog Input Alarm Mode Configuration	ı 89
		Figure 5.11: ADAM-6015 Channel Configuration	91
		Figure 5.12:ADAM-6024 Output Tab	92
		5.3.4 Universal Digital Input and Output Module	
		(ADAM-6050) 93	
		Figure 5.13:ADAM-6050 Channel Setting	93
		Figure 5.14: Fail Safe Value Configuration	95
		Figure 5.15:Individual Channel Configuration: DI	96
		Figure 5.16:Low to High Delay Output Mode	102
		Figure 5.17:Low to High Delay Output Mode	103
		5.3.5 Peer-to-Peer Function	104
		Figure 5.18:Basic mode for Peer-to-Peer	105
		Figure 5.19:Advanced mode for Peer-to-Peer	105
		Figure 5.20:Peer-to-Peer Configuration Tab	107
		Figure 5.21:Peer-to-Peer Basic Mode Configuration	108
		Figure 5.22: Building the Mapping Relationship	109
		Figure 5.23:P-to-P Advanced Mode Configuration	110
		Figure 5.24:Copy One Setting to Other Channels	112
	5.4	ADAM-6000 Web Server	113
	5.5	Java Applet Customization	113
		5.5.1 Introduction	113
		Figure 5.25:Structure of the ADAM6060.jar file	11/
	5 (	Figure 5.26.Firmware Opgrade	118
	5.6	Source Code of Java Applet Example	119
Chapter	6	Planning Your Application Program	128
	6.1	Introduction	128
	6.2	ADAM .NET Class Library	128
		Figure 6.1:Modifying ADAM-6050 .NET	130
	6 0	Figure 6.2: Launching ADAM .NET Class Library	132
	6.3	Modbus Protocol for ADAM-6000 Modules	133
		6.2.2 Modbus Fibiocol Structure	133
	6.4	ASCII Commands for ADAM 6000 Modulos	134
	0.4	6.4.1 Syntax of ASCII	140
		6.4.2 System Command Set	141
		6 4 3 Analog Input Command Set	147
		6.4.4 Analog Input Alarm Command Set	164
		6.4.5 Universal I/O Command Set	174
		6.4.6 Digital Input/Output Command Set	187
	65	SNMP for ADAM-6000 Modules	192
	0.5	6.5.1 ADAM MIB file	192

		6.5.2	SNMP Trap Configuration	192
			Figure 6.3:Trap specific type table	193
			Figure 6.4: Trap configuration by ADAM.Net Utili 194	ty
Chapter	7	Graj	ohic Condition Logic(GCL)	196
	7.1	Overv	riew	196
	7.2	GCL	Configuration Environment	197
			Figure 7.1:GCL Configuration Environment	197
			Figure 7.2: Four Stages for One Logic Rule	199
	7.3	Confi	gure Four Stages of One Logic Rule	201
		7.3.1	Input Condition Stage	201
			Figure 7.3:Input Condition Stage Configuration	202
			Figure 7.4:Engineer Unit and Current Value	204
			Figure 7.5:Scaling Function of Analog Input Mode	205
		7.3.2	Logic Stage	208
			Figure 7.6:Logic Stage Configuration	208
		7.3.3	Execution Stage	210
			Figure 7.7:Execution Stage Configuration	210
			Figure 7.8:Send to Next Rule Function	211
		724	Figure 7.9: The Next Logic Rule	212
		1.3.4	Support Stage	212
			Figure 7.10:Output Stage Configuration	213
	7.4	<b>.</b> .	Figure /.11:Remote Message Output	218
	7.4	Intern	al Flag for Logic Cascade and Feedback	220
		/.4.1	Figure 7 12: A rebitecture of Local Logic Cascade	220
			Figure 7.12: Architecture of Local Logic Cascade	221
			Figure 7.14:Configuration of Logic Rule 2	221
			Figure 7.15: Configuration of Logic Rule 3	222 222
			Figure 7.16: Distributed Logic Cascade	222
			Figure 7.17: Configuration of Logic Rule 1	223
			Figure 7.18:Configuration of Logic Rule 2	224
			Figure 7 19: Configuration of Logic Rule 3	225
		742	Feedback	225
		7.1.2	Figure 7 20 Building Logic Feedback	225
	75	Down	load Logic and Online Monitoring	226
	1.5	Down	Figure 7.21:Online Monitoring Function	226
			Figure 7.22:GCL Execution Sequence	228
	7.6	Tvpic	al Applications with GCL	229
		51	Figure 7.23:Ladder Diagram for On/Off Control	229
			Figure 7.24:GCL Logic for On/Off Control	230
			Figure 7.25: Time Chart for Sequence Control	231
			Figure 7.26:GCL Logic for Sequence Control	232
			Figure 7.27: Time Chart for 12 DI to 1 DO	233
			Figure 7.28:GCL Logic for 12 DI to 1 DO	234
			Figure 7.29:Time Chart for Flicker Application	234

		Figure 7.30:GCL Logic for Flicker	
		Figure 7.31: Time Chart for Rising Edge	
		Figure 7.32:Ladder Diagram for Rising Edge	
		Figure 7.33:GCL Logic for Rising Edge	
		Figure 7.34: Time Chart for Falling Edge	
		Figure 7.35:Ladder Diagram for Falling Edge	
		Figure 7.36:GCL Logic for Falling Edge	
		Figure 7.37: Time Chart for Sequence Control	
		Figure 7.38:GCL Logic for Sequence Control	
		Figure 7.39:GCL Logic for Event Trigger	
		Figure 7.40:Event Trigger Configuration	
Appendix A	Desig	gn Worksheets	244
		Table A.1:I/O Data Base	
		Table A.2:Summary Required Modules	
	-	Table A.3: Table for Programming	
Appendix B	Data	Formats and I/O Range	248
B.1	ADAN	A-6000 Commands Data Formats	248
	B.1.1	Command Structure	
		Figure B.1:Request Comment Structure	
		Figure B.2:Response Comment Structure	
	B.1.2	Modbus Function Code Introductions	
5.4		Table B.1:Response Comment Structure	
B.2	ADAN D 2 1	A-6000 I/O Modbus Mapping Table	
	B.2.1	ADAM (017	
	B.2.2	ADAM (01)	
	B.2.3	ADAM-6018	
	B.2.4	ADAM-6024	
	B.2.5	ADAM (051	
	B.2.0	ADAM (052	
	B.2./	ADAM (0(0)(0)(	
	В.2.8	ADAM-0000/0000	
Appendix C	Grou	inding Reference	308
C.1	Field (	Grounding and Shielding Application	308
C.2	Groun	ding	309
	C.2.1	The Earth' for Reference	
	<b>C 2 2</b>	Figure C.1: Think of the Earth as a Ground	
	C.2.2	The Frame Ground' and 'Grounding Bar'	
		Figure C.2: Grounding Bar	
	<b>a a a</b>	Figure C.3:Normal and Common Mode.	
	C.2.3	Normal Mode and Common Mode	
		Figure C.4:Normal and Common Mode	
	C.2.4	Wire impedance	
		Figure C.5:High Voltage Transmission	
	~ • -	Figure C.6: Wire Impedance	
	C.2.5	Single Point Grounding	

	Figure C.7:Single Point Grounding (1)	
	Figure C.8:Single point grounding (2)	
C.3	Shielding	314
	C.3.1 Cable Shield	
	Figure C.9:Single isolated cable	
	Figure C.10:Double isolated cable	
	C.3.2 System Shielding	
	Figure C.11:System Shielding	
	Figure C.12: The characteristic of the cable	
	Figure C.13:System Shielding (1)	
	Figure C.14:System Shielding (2)	
C.4	Noise Reduction Techniques	
	Figure C.15:Noise Reduction Techniques	
C.5	Check Point List	319
Appendix D	REST for ADAM-6000	322
D.1	REST Introduction	
D.2	REST Resources for ADAM	322
	D.2.1 Analoginput	
	D.2.2 Analogoutput	
	D.2.3 Digitalinput	
	D.2.4 Digitaloutput	
	D.2.5 Counter	
Appendix E	HTML 5	330
E1	HTML 5 Introduction	330
E.2	Monitor and Control Remotely via ADAM-6000	Web
Server	330	
Appendix F	New Version Enhancement	334
F1	Enhancement Introduction	334
F.2	Intelligent Function Enhancement	

# CHAPTER

# Understanding Your System

Sections include:

- Introduction
- Major Features
- Specifications
- Dimensions
- LED Status

# Chapter 1 Understanding Your System

#### 1.1 Introduction

ADAM-6000 Ethernet-based data acquisition and control modules provide I/O, data acquisition, and networking in one module to build a costeffective, distributed monitoring and control solution for a wide variety of applications. Through standard Ethernet networking, ADAM-6000 retrieves I/O values from sensors, and can publish them as a real-time I/O values to networking nodes via LAN, Intranet, or Internet. With Ethernetenabled technology, ADAM-6000 series modules build up a cost-effective DA&C system for building automation, environmental monitoring, facility management and intelligent manufacturing applications. Please refer to Figure 1-1 for a brief overview of the ADAM-6000 system architecture.



Figure 1.1: ADAM-6000 System Architecture

#### 1.2.1 Ethernet-enabled DA&C I/O Modules

ADAM-6000 is based on popular Ethernet networking standards used in most business environments. Users can easily add ADAM-6000 I/O modules to existing Ethernet networks, or use ADAM-6000 modules in new Ethernet-enabled manufacturing networks. ADAM-6000 modules feature a 10/100 Mbps Ethernet chip and support popular industrial Modbus/TCP protocols over TCP/IP for data connection. ADAM-6000 also supports UDP protocol over Ethernet networking. With UDP/IP, ADAM-6000 I/O modules can actively send I/O data streams to 8 Ethernet nodes. Through Ethernet networking, HMI/SCADA systems, and controllers, users can access or gather real-time data from ADAM-6000 Ethernet enabled DA&C modules. This data can then be integrated with business systems to compile valuable business information.

**Note:** Some intelligent functions are only provided by the ADAM-6000-CE version. See details in Appendix F.

#### 1.2.2 Intelligent I/O Modules

ADAM-6000 series have pre-built intelligent math functions to empower system capacity. The Digital Input module provide counter, totalizer functions; the Digital Output module provide pulse output, delay output functions; the Analog Input module provide the max./min./average data values and the Analog Output module provide the PID loop control functions.

#### 1.2.3 Mixed I/O to Fit All Applications

ADAM-6000 series mixed I/O design provides the most cost-effective I/O for applications. The most common used I/O type for single functions are collected in one module. This design concept not only saves I/O usage and costs, but also speeds up I/O relative operations. For small DA&C system or standalone control units from mid to large scales, ADAM-6000's mixed I/O design can easily adapt to application needs with one or two modules only. With additional embedded control modules, ADAM-6000 can easily create a localized, less complex, and more distributed I/O architecture.

#### 1.2.4 Remote Monitoring & Diagnosis

Each ADAM-6000 module features a pre-built I/O module web page to display real-time I/O data values, alarms, and module status thru LAN or Internet. Through any Internet browser, users can monitor real-time I/O

data values and alarms at local or remote sites. The web-enabled monitoring system requires no programming.

#### 1.2.5 Industrial Standard Modbus/TCP Protocol

ADAM-6000 modules support the popular industrial standard, Modbus/ TCP protocol, to connect with Ethernet Controller or HMI/SCADA software built with Modbus/TCP drivers. Advantech also provides an OPC server for Modbus/TCP to integrate ADAM-6000 I/O real-time data values with OPC client enabled software, freeing users from driver development.

#### 1.2.6 Customized Web Page

Since ADAM-6000 modules have a built in default web page, users can monitor and control the I/O status from anywhere through a browser. Moreover, ADAM-6000 modules can download user-defined web pages for individual applications. Advantech has provided sample programs of Java Script\* for users reference to design their own operator interface, then download it into the specific ADAM-6000 modules via Windows Utility.

\*ADAM series support JavaScript libraries (\*js files), users can import this file from the ADAM utility tool. Java Scripting language works with WWW and HTML documents and objects. ADAM provides basic libraries via jQuery v1.8.2 software on the CD package, users can update new versions online from http://jquery.com/download/

Advantech Adam/Apax .NET Utility (Win3)	2) Version 2.05.05	
Pie         Pie           Pie	Information     Network     Stream     Administration     Furneware     Peer to Peer/Event   Access Control   Modbur       File     Howstering File     Image: Stream     File       File     Howstering File     Configuration file       File     Configuration file       File     File	Address   Brown Download Save as Upload
ADAM-6251:		

**Note:** Download the JavaScript file to the ADAM Module via the Adam/ Apax Utility

#### 1.2.7 Modbus/TCP Software Support

The ADAM-6000s firmware has a built-in Modbus/TCP server. Advantech provides the ADAM.NET class library and Windows ADAM.NET utility for users. Users can configure this DA&C system via Windows utility; integrate with HMI software package via Modbus/TCP driver. Users can also purchase an Advantech OPC server to operate Modbus/ TCP.

#### 1.3 Specifications

Ethernet:	10/100 Base-T
Wiring:	UTP, category 5 or greater
Bus Connection: RJ45 modular jack	
Comm. Protocol:	Modbus/TCP on TCP/IP and UDP
Data Transfer Rate:	Up to 100 Mbps
	Unregulated 10 to 30 VDC
Status Indicator:	Power, CPU, Communication
	(Link, Collide, 10/100 Mbps, Tx, Rx)
Case:	PC with captive mounting hardware
Screw Terminal Block:	Accepts wire size #14-28 AWG, stripped length:6.5 mm

NOTE: Equipment will operate below 30% humidity, however, static electricity problems occur much more frequently at lower humidity levels. Make sure you take adequate precautions when you touch the equipment. Consider using ground straps, anti-static floor coverings, etc. if you use the equipment in low humidity environments.

#### 1.4 Dimensions

 60.00
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1
 1

The following diagram shows the dimensions of the I/O modules. (mm)

Figure 1.2: ADAM-6000 Module Dimension

#### 1.5 LED Status

There are two LEDs on the ADAM-6000 I/O Series front panel. Each LED has two indicators to represent system status, as explained below:



#### Figure 1.3: LED Indicators

LED	Color		Indication	Behavior
Status	Orange (when	Red	Blink	Module is normally running
	on at the same time)		ON for 30s	When user enable LOCATE function.
Link		Green	ON	Ethernet is connected.
Speed	Orange (when speed	Red	ON	Ethernet speed is 100 Mbps
Com	the same time)	Green	Blink	Module is transmitting or receiving data

#### 1.5.1 Locate

This helps user get ADAM module status via LED lights. (Status LED will be constantly on RED or 30 seconds when enabled.)

		Ethernet	
Status Speed	Link Com	Tadomikini         Metvock         Jamual         Administration         Ferroven         Pere to PereEvent           Famoven         Version         [A1.00.B01]         Device Name:         [ADAd-6251]           Device Description:         [ADAd-6251]         Device Name:         [ADAd-6251]	t   Access Control   Modifies Address   Locats Enable   Apply   ADAM Web Page
		Description Stot Moltals 6251 ADAM-6251 16-ch solated dignkt inper molta	<u> </u>



## Selecting Your Hardware

Sections include:

- Selecting an I/O Module
- Selecting a Link Terminal & Cable
- Selecting an Operator Interface

# **Chapter 2 Selecting Your Hardware**

#### 2.1 Selecting an I/O Module

To organize an ADAM-6000 remote data acquisition & control system, you need to select I/O modules to interface the host PC with field devices or processes that you have previously determined. There are several things should be considered when you select the I/O modules.

- What type of I/O signal is applied in your system?
- How much I/O is required to your system?
- How will you place the modules to handle I/O points in individual areas of an entire field site?
- How many modules are required for distributed I/O point arrangement?
- How many hubs are required for the connection of these devices?
- What is the required voltage range for each I/O module?
- What isolation environment is required for each I/O module?
- What are the noise and distance limitations for each I/O module?

Refer to table 2-1 for I/O module selection guidelines

Table 2.1: I/O	Table 2.1: I/O Selection Guidelines					
Type of I/O module:	For these types of field devices or operations (examples):	Explanation:				
Discrete input module and block I/O module	Selector switches, push but- tons, photoelectric eyes, limit switches, circuit breakers, prox- imity switches, level switches, motor starter contacts, relay contacts, thumb-wheel switches	Input modules sense ON/OFF or OPENED/ CLOSED signals				
Discrete out- put module and block I/O module	Alarms, control relays, fans, lights, horns, valves, motor starters, solenoids	Output module signals interface with ON/OFF or OPENED/CLOSED devices				
Analog input module	Thermocouple signals, RTD signals, temperature transduc- ers, pressure transducers, load cell transducers, humidity trans- ducers, flow transducers, potentiometers.	Convert continuous analog signals into input values for host device				
Analog output module	Analog valves, actuators, chart recorders, electric motor drives, analog meters	Interpret host device's output to analog sig- nals (generally through transducers) for field devices.				

•

#### 2.2 Selecting a Link Terminal & Cable

Use the RJ-45 connector to connect the Ethernet port of the ADAM-6000 to the Hub. The cable for connection should be Category 3 (for 10Mbps data rate) or Category 5 (for 100Mbps data rate) UTP/STP cable, which is compliant with EIA/TIA 586 specifications. Maximum length between the Hub and any ADAM-6000 modules is up to 100 meters (approx. 300 ft).



Figure 2.1: Ethernet Terminal and Cable Connection

Table 2.2: Ethernet RJ-45 port Pin Assignment				
PIN NUMBER	SIGNAL	FUNCTION		
1	RD+	Receive (+)		
2	RD-	Receive (-)		
3	TD+	Transmit (+)		
4	(Not Used)	-		
5	(Not Used)	-		
6	TD-	Transmit (-)		
7	(Not Used)	-		
8	(Not Used)	-		

#### 2.3 Selecting an Operator Interface

To complete your Data Acquisition and Control system, selecting the operator interface is necessary. Adopting the Modbus/TCP Protocol, ADAM-6000 I/O modules exhibit high ability in system integration for various applications.

You can read the real-time status of ADAM-6000 modules through the web page from the following browser.

•Microsoft Internet Explorer (version 9 or later)

•Google Chrome (version 30 or later)

•Safari (version 6 or later)

•Firefox (version 25 or later)

If you want to integrate ADAM-6000 I/O with HMI (Human Machine Interface) software in a SCADA (Supervisory Control and Data Acquisition) system, there are a lot of HMI software packages, which support Modbus/TCP driver.

- Advantech PM Designer
- Wonderware InTouch
- Any other software that supports the Modbus/TCP protocol

You can also purchase Advantech OPC Server, the easiest-to-use data exchange tool in the world. Any HMI software designed with OPC Client is able to access ADAM-6000 I/O modules.

• Modbus/TCP OPC Server

If you want to develop your own applications, the ADAM.NET Class Library will be the best tool to build up users' operator interface.

With these ready-to-go application software packages, tasks such as remote data acquisition, process control, historical trending and data analysis require only a few keystrokes.



# Hardware Installation Guide

Sections include:

- Determining the Proper Environment
- Mounting
- Wiring & Connections