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High Frequency Divider/PLL Synthesizer

Data Sheet ADF4007

FEATURES

7.5 GHz bandwidth

Maximum PFD frequency of 120 MHz

Divide ratios of 8, 16, 32, or 64

2.7 V to 3.3 V power supply

Separate charge pump supply (V_P) allows extended tuning voltage in 3 V systems

R_{SET} control of charge pump current

Hardware power-down mode

APPLICATIONS

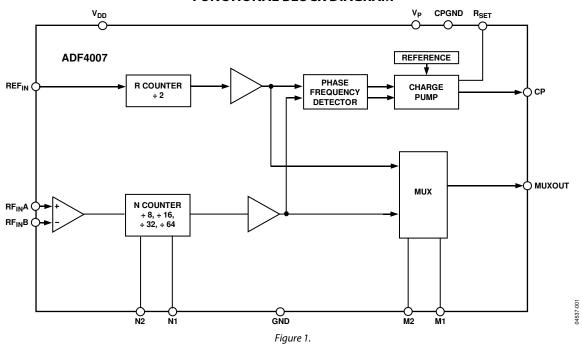
Satellite communications Broadband wireless access CATV Instrumentation Wireless LANs

GENERAL DESCRIPTION

The ADF4007 is a high frequency divider/PLL synthesizer that can be used in a variety of communications applications. It can operate to 7.5 GHz on the RF side and to 120 MHz at the PFD. It consists of a low noise digital PFD (phase frequency detector), a precision charge pump, and a divider/prescaler. The divider/ prescaler value can be set by two external control pins to one of four values (8, 16, 32, or 64). The reference divider is permanently set to 2, allowing an external REF $_{\rm IN}$ frequency of up to 240 MHz.

A complete PLL (phase-locked loop) can be implemented if the synthesizer is used with an external loop filter and a VCO (voltage controlled oscillator). Its very high bandwidth means that frequency doublers can be eliminated in many high frequency systems, simplifying system architecture and reducing cost.

FUNCTIONAL BLOCK DIAGRAM



ADF4007* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

COMPARABLE PARTS 🖳

View a parametric search of comparable parts.

EVALUATION KITS

· ADF4007 Evaluation Board

DOCUMENTATION

Application Notes

- AN-30: Ask the Applications Engineer PLL Synthesizers
- AN-873: Lock Detect on the ADF4xxx Family of PLL Synthesizers

Data Sheet

 ADF4007: High Frequency Divider/PLL Synthesizer Data Sheet

User Guides

 UG-158: Evaluation Board for the 7.5 GHz PLL Frequency Synthesizer

TOOLS AND SIMULATIONS

- ADIsimPLL™
- ADIsimRF

REFERENCE MATERIALS 🖵

Product Selection Guide

RF Source Booklet

Technical Articles

- Phase Locked Loops for High-Frequency Receivers and Transmitters – Part 1
- Phase Locked Loops for High-Frequency Receivers and Transmitters – Part 3
- Phase-Locked Loops for High-Frequency Receivers and Transmitters - Part 2

DESIGN RESOURCES 🖳

- · ADF4007 Material Declaration
- PCN-PDN Information
- · Quality And Reliability
- · Symbols and Footprints

DISCUSSIONS 🖳

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7/12—Rev. A to Rev. B	12/09—Rev. 0 to Rev. A	
Changes to Figure 25	Added Exposed Pad Notation to Figure 2 and Table 3	
Changed Applications Section to Applications Information	Changes to Table 5	6
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Updated Outline Dimensions (Changed CP-20-1 to CP-20-6) 14		
Changes to Ordering Guide14	2/04—Revision 0: Initial Version	

SPECIFICATIONS

 $AV_{DD} = DV_{DD} = 3~V \pm 10\%, AV_{DD} \leq V_{P} \leq 5.5~V, AGND = DGND = CPGND = 0~V, R_{SET} = 5.1~k\Omega, dBm~referred~to~50~\Omega, AV_{DD} = CPGND = 0~V, R_{SET} = 5.1~k\Omega, dBm~referred~to~50~\Omega, dBm~referr$ $T_A = T_{MAX}$ to T_{MIN} , unless otherwise noted.

Table 1.

Parameter	B Version ¹	Unit	Test Conditions/Comments
RF CHARACTERISTICS			
RF Input Frequency (RF _{IN})	1.0/7.0	GHz min/max	RF input level: +5 dBm to -10 dBm
RF Input Frequency	0.5/7.5	GHz min/max	RF input level: $+5$ dBm to -5 dBm, for lower frequencies, ensure that slew rate (SR) > 560 V/ μ s
REF _{IN} CHARACTERISTICS			
REF _{IN} Input Sensitivity	0.8/V _{DD}	V p-p min/max	Biased at AV _{DD} /2 ²
REF _{IN} Input Frequency	20/240	MHz min/max	For f < 20 MHz, use square wave (slew rate > $50 \text{ V/}\mu\text{s}$)
REF _{IN} Input Capacitance	10	pF max	
REF _{IN} Input Current	±100	μA max	
PHASE DETECTOR			
Phase Detector Frequency ³	120	MHz max	
MUXOUT			
MUXOUT Frequency ³	200	MHz max	$C_L = 15 \text{ pF}$
CHARGE PUMP			
I _{CP} Sink/Source	5.0	mA typ	With $R_{SFT} = 5.1 \text{ k}\Omega$
Absolute Accuracy	2.5	% typ	With $R_{SFT} = 5.1 \text{ k}\Omega$
R _{SET} Range	3.0/11	kΩ typ	
I _{cp} Three-State Leakage	10	nA max	$T_A = 85$ °C
Sink and Source Current Matching	2	% typ	$0.5 \text{ V} \le \text{V}_{CP} \le \text{V}_{P} - 0.5 \text{ V}$
I_{CP} vs. V_{CP}	1.5	% typ	$0.5 \text{ V} \le \text{V}_{CP} \le \text{V}_{P} - 0.5 \text{ V}$
I _{CP} vs. Temperature	2	% typ	$VCP = V_p/2$
LOGIC INPUTS			
V _⊪ , Input High Voltage	1.4	V min	
$V_{\scriptscriptstyle IL}$, Input Low Voltage	0.6	V max	
I _{INH} , I _{INL} , Input Current	±1	μA max	$T_A = 25^{\circ}C$
C _{IN} , Input Capacitance	10	pF max	
LOGIC OUTPUTS			
V _{OH} , Output High Voltage	$V_{DD} - 0.4$	V min	$I_{OH} = 100 \mu A$
V _{oL} , Output Low Voltage	0.4	V max	$I_{OL} = 500 \mu A$
POWER SUPPLIES			
AV_{DD}	2.7/3.3	V min/max	
DV_{DD}	AV_{DD}		
V_{P}	AV _{DD} /5.5	V min/max	$AV_{DD} \le V_P \le 5.5 \text{ V}$
$I_{DD}^4 (AI_{DD} + DI_{DD})$	17	mA max	15 mA typ
I _P	2.0	mA max	$T_A = 25$ °C
NOISE CHARACTERISTICS			
Normalized Phase Noise Floor⁵	-219	dBc/Hz typ	

 $^{^1}$ Operating temperature range (B version) is -40°C to $+85^\circ\text{C}$. 2 AC coupling ensures AV_{DD}/2 bias. See Figure 13 for typical circuit.

³ Guaranteed by design. Characterized to ensure compliance.

 $^{^4}T_A = 25^{\circ}\text{C}$; AV_{DD} = DV_{DD} = 3 V; N = 64; RF_{IN} = 7.5 GHz. 5 The synthesizer phase noise floor is estimated by measuring the in-band phase noise at the output of the VCO, PN_{TOT}, and subtracting 20logN (where N is the N divider value) and 10logFPFD. PN_{SYNTH} = PN_{TOT} - 10logF_{PFD} - 20logN. The in-band phase noise (PN_{TOT}) is measured using the HP8562E Spectrum Analyzer from Agilent.

ABSOLUTE MAXIMUM RATINGS

 $T_A = 25$ °C, unless otherwise noted.

Table 2.

1 4010 2.			
Parameter	Rating		
AV _{DD} to GND ¹	-0.3 V to +3.6 V		
AV_{DD} to DV_{DD}	-0.3 V to +0.3 V		
V_P to GND	-0.3 V to +5.8 V		
V_{p} to AV_{DD}	-0.3 V to +5.8 V		
Digital I/O Voltage to GND	$-0.3 \text{ V to V}_{DD} + 0.3 \text{ V}$		
Analog I/O Voltage to GND	$-0.3 \text{ V to V}_{P} + 0.3 \text{ V}$		
REF _{IN} , RF _{IN} A, RF _{IN} B to GND	$-0.3 \text{ V to V}_{DD} + 0.3 \text{ V}$		
Operating Temperature Range			
Industrial (B Version)	−40°C to +85°C		
Storage Temperature Range	−65°C to +125°C		
Maximum Junction Temperature	150°C		
CSP θ_{JA} Thermal Impedance	122°C/W		
Lead Temperature, Soldering			
Vapor Phase (60 s)	215°C		
Infrared (15 s)	220°C		
Transistor Count			
CMOS	6425		
Bipolar	303		

 $^{^{1}}$ GND = AGND = DGND = 0 V.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

This device is a high performance RF integrated circuit with an ESD rating of <2 kV, and it is ESD sensitive. Proper precautions should be taken for handling and assembly.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

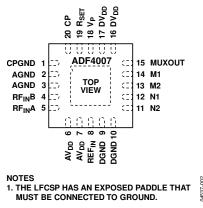


Figure 2. Pin Configuration

Table 3. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	CPGND	Charge Pump Ground. The ground return path of the charge pump.
2, 3	AGND	Analog Ground. The ground return path of the prescaler.
4	RF _{IN} B	Complementary Input to the RF Prescaler. This point must be decoupled to the ground plane with a small bypass capacitor, typically 100 pF.
5	RF _{IN} A	Input to the RF Prescaler. This small signal input is ac-coupled to the external VCO.
6, 7	AV_DD	Analog Power Supply. This pin can range from 2.7 V to 3.3 V. Decoupling capacitors to the analog ground plane should be placed as close as possible to this pin. AV _{DD} must be the same value as DV _{DD} .
8	REF _{IN}	Reference Input. A CMOS input with a nominal threshold of $V_{DD}/2$ and a dc equivalent input resistance of 100 k Ω . This input can be driven from a TTL or CMOS crystal oscillator, or it can be ac-coupled.
9, 10	DGND	Digital Ground.
11, 12	N2, N1	These two bits set the N value. See Table 4.
13, 14	M2, M1	These two bits set the status of MUXOUT and PFD polarity. See Table 5.
15	MUXOUT	This multiplexer output allows either the N divider output or the R divider output to be accessed externally.
16, 17	DV_{DD}	Digital Power Supply. This pin can range from 2.7 V to 3.3 V. Decoupling capacitors to the digital ground plane should be placed as close as possible to this pin. DV _{DD} must be the same value as AV_{DD} .
18	V _P	Charge Pump Power Supply. This pin should be greater than or equal to V_{DD} . In systems where V_{DD} is 3 V, it can be set to 5 V and used to drive a VCO with a tuning range of up to 5 V.
19	R _{SET}	Connecting a resistor between this pin and CPGND sets the maximum charge pump output current. The nominal voltage potential at the R_{SET} pin is 0.66 V. The relationship between I_{CP} and R_{SET} is
		$I_{CPMAX} = \frac{25.5}{R_{SET}}$
		Therefore, if $R_{SET} = 5.1 \text{ k}\Omega$, then $I_{CP} = 5 \text{ mA}$.
20	СР	Charge Pump Output. When enabled, this pin provides $\pm I_{CP}$ to the external loop filter, which in turn drives the external VCO.
21	EP	Exposed Pad.

Table 4. N Truth Table

N2	N1	N Value
0	0	8
0	1	16
1	0	32
1	1	64

Table 5. M Truth Table

M2	M1	Operation	Description
0	0	СР	Active
		MUXOUT	V_{DD}
		PFD polarity	+ve
0	1	СР	Three-state
		MUXOUT	R divider output/2
		PFD polarity	+ve
1	0	СР	Active
		MUXOUT	N divider output
		PFD polarity	+ve
1	1	СР	Active
		MUXOUT	GND
		PFD polarity:	-ve

TYPICAL PERFORMANCE CHARACTERISTICS

Table 6. S-Parameter Data for the RF Input

Table 6. 3-Paramete	er Data for the KF mp	ut
Frequency ¹	MagS11	AngS11
0.60000	0.87693	-19.9279
0.70000	0.85834	-23.5610
0.80000	0.85044	-26.9578
0.90000	0.83494	-30.8201
1.00000	0.81718	-34.9499
1.10000	0.80229	-39.0436
1.20000	0.78917	-42.3623
1.30000	0.77598	-46.3220
1.40000	0.75578	-50.3484
1.50000	0.74437	-54.3545
1.60000	0.73821	-57.3785
1.70000	0.72530	-60.6950
1.80000	0.71365	-63.9152
1.90000	0.70699	-66.4365
2.00000	0.70380	-68.4453
2.10000	0.69284	-70.7986
2.20000	0.67717	-73.7038
2.30000	0.67107	-75.8206
2.40000	0.66556	-77.6851
2.50000	0.65640	-80.3101
2.60000	0.63330	-82.5082
2.70000	0.61406	-85.5623
2.80000	0.59770	-87.3513
2.90000	0.56550	-89.7605
3.00000	0.54280	-93.0239
3.10000	0.51733	-95.9754
3.20000	0.49909	-99.1291
3.30000	0.47309	-102.208
3.40000	0.45694	-106.794
3.50000	0.44698	-111.659
3.60000	0.43589	-117.986
3.70000	0.42472	-125.620
3.80000	0.41175	-133.291
3.90000	0.41055	-140.585
4.00000	0.40983	-147.970
4.10000	0.40182	-155.978
4.20000	0.41036	-162.939

Frequency ¹	MagS11	AngS11
4.30000	0.41731	-168.232
4.40000	0.43126	-174.663
4.50000	0.42959	-179.797
4.60000	0.42687	174.379
4.70000	0.43450	171.537
4.80000	0.42275	167.201
4.90000	0.40662	163.534
5.00000	0.39103	159.829
5.10000	0.37761	157.633
5.20000	0.34263	152.815
5.30000	0.30124	147.632
5.40000	0.27073	144.304
5.50000	0.23590	138.324
5.60000	0.17550	131.087
5.70000	0.12739	124.568
5.80000	0.09058	119.823
5.90000	0.06824	114.960
6.00000	0.04465	84.4391
6.10000	0.04376	34.2210
6.20000	0.06621	4.70571
6.30000	0.08498	-12.6228
6.40000	0.10862	-26.6069
6.50000	0.12161	-38.5860
6.60000	0.12917	-47.1990
6.70000	0.12716	-55.8515
6.80000	0.11678	-63.0234
6.90000	0.10533	-66.9967
7.00000	0.09643	-75.4961
7.10000	0.08919	-89.2055
7.20000	0.08774	-103.786
7.30000	0.09289	-127.153
7.40000	0.10803	-150.582
7.50000	0.13956	-170.971

¹Frequency unit: GHz; parameter type: s; data format: MA; keyword: R; impedance: 50.

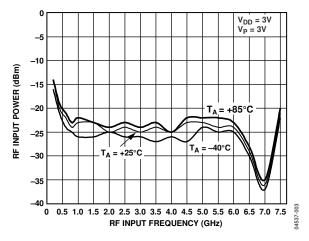


Figure 3. Input Sensitivity

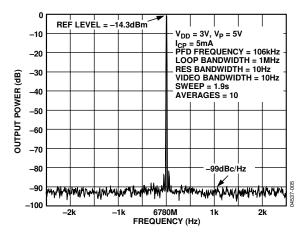


Figure 4. Phase Noise (6.78 GHz RF $_{
m OUT}$, 106 MHz PFD, and 1 MHz Loop Bandwidth)

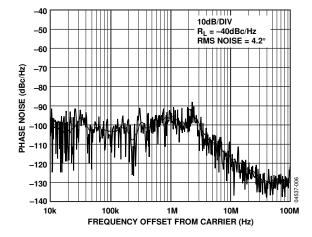


Figure 5. Integrated Phase Noise (6.78 GHz RF $_{
m OUT}$, 106 MHz PFD, and 1 MHz Loop Bandwidth)

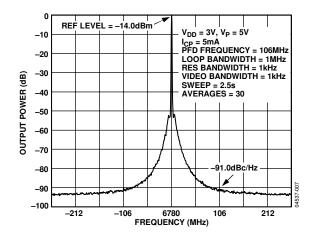


Figure 6. Reference Spurs (6.78 GHz RF_{OUT}, 106 MHz PFD, and 1 MHz Loop Bandwidth)

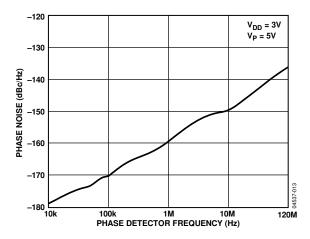


Figure 7. Phase Noise (Referred to CP Output) vs. PFD Frequency

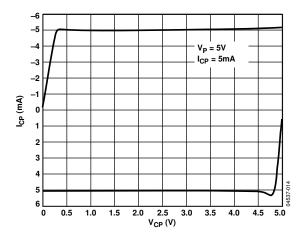


Figure 8. Charge Pump Output Characteristics

THEORY OF OPERATION

REFERENCE INPUT SECTION

The reference input stage is shown in Figure 9. SW1 and SW2 are normally closed switches. SW3 is normally open. When power-down is initiated, SW3 is closed and SW1 and SW2 are opened. This ensures that there is no loading of the ${\rm REF}_{\rm IN}$ pin on power-down.

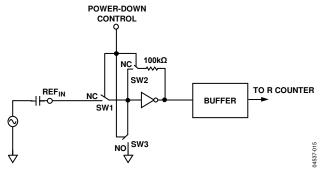


Figure 9. Reference Input Stage

RF INPUT STAGE

The RF input stage is shown in Figure 10. It is followed by a 2-stage limiting amplifier to generate the CML clock levels needed for the prescaler.

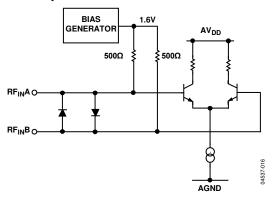


Figure 10. RF Input Stage

PRESCALER P

The prescaler, operating at CML levels, takes the clock from the RF input stage and divides it down to a manageable frequency for the PFD. The prescaler can be selected to be either 8, 16, 32, or 64, and is effectively the N value in the PLL synthesizer. The terms N and P are used interchangeably in this data sheet. N1 and N2 set the prescaler values. The prescaler value should be chosen so that the prescaler output frequency is always less than or equal to 120 MHz, the maximum specified PFD frequency. Thus, with an RF frequency of 4 GHz, a prescaler value of 64 is valid, but a value of 32 or less is not valid.

$$f_{VCO} = [N] \times \frac{f_{REFIN}}{2}$$

R COUNTER

The R counter is permanently set to 2. It allows the input reference frequency to be divided down by 2 to produce the reference clock to the phase frequency detector (PFD).

PHASE FREQUENCY DETECTOR (PFD) AND CHARGE PUMP

The PFD takes inputs from the R counter and the N counter (prescaler, P) and produces an output proportional to the phase and frequency difference between them. Figure 11 is a simplified schematic. The PFD includes a fixed, 3 ns delay element that controls the width of the antibacklash pulse. This pulse ensures that there is no dead zone in the PFD transfer function and minimizes phase noise and reference spurs.

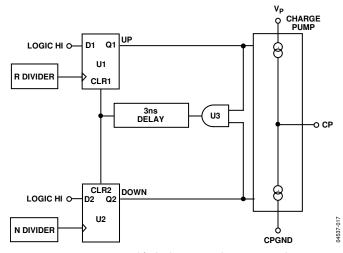


Figure 11. PFD Simplified Schematic and Timing (In Lock)

MUXOUT

The output multiplexer on the ADF4007 allows the user to access various internal points on the chip. The state of MUXOUT is controlled by the M2 and M1 pins. Figure 12 shows the MUXOUT section in block diagram form.

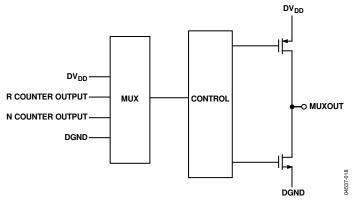


Figure 12. MUXOUT Circuit

PFD Polarity

The PFD polarity is set by the state of M2 and M1 pins as given in the Table 5. The ability to set the polarity allows the use of VCOs with either positive or negative tuning characteristics. For standard VCOs with positive characteristics (output frequency increases with increasing tuning voltage), the polarity should be set to positive. This is accomplished by tying M2 and M1 to a logic low state.

CP Output

The CP output state is also controlled by the state of M2 and M1. It can be set either to active (so that the loop can be locked) or to three-state (open the loop). The normal state is CP output active.

APPLICATIONS INFORMATION

FIXED HIGH FREQUENCY LOCAL OSCILLATOR

Figure 13 shows the ADF4007 being used with the HMC358MS8G VCO from Hittite Microwave Corporation to produce a fixed-frequency LO (local oscillator), which could be used in satellite or CATV applications. In this case, the desired LO is 6.7 GHz.

The reference input signal is applied to the circuit at FREF $_{\rm IN}$ and, in this case, is terminated in 50 $\Omega.$ Many systems would have either a TCXO or an OCXO driving the reference input without any 50 Ω termination. To bias the REF $_{\rm IN}$ pin at AV $_{\rm DD}/2$, ac coupling is used. The value of the coupling capacitor used depends on the input frequency. The equivalent impedance at the input frequency should be less than 10 $\Omega.$ Given that the dc input impedance at the REF $_{\rm IN}$ pin is 100 k Ω , less than 0.1% of the signal is lost.

The charge pump output of the ADF4007 drives the loop filter. In calculating the loop filter component values, a number of items need to be considered. In this example, the loop filter was designed so that the overall phase margin for the system is 45°.

Other PLL system specifications are as follows:

 $K_D = 5 \text{ mA}$

 $K_v = 100 \text{ MHz/V}$

Loop Bandwidth = 300 kHz

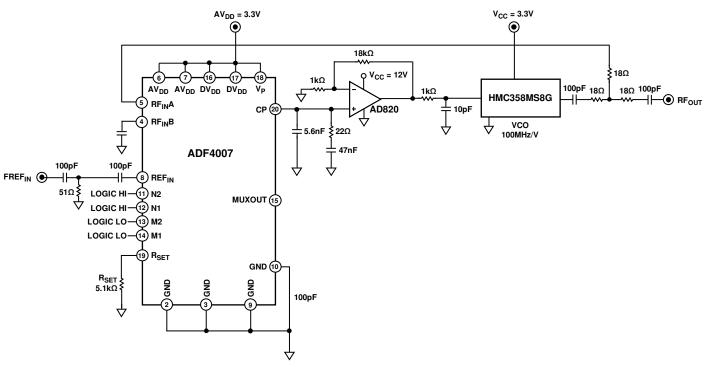
 $F_{PFD} = 106 \text{ MHz}$

N = 64

All these specifications are needed and used with the ADIsimPLL to derive the loop filter component values shown in Figure 13.

The circuit in Figure 13 gives a typical phase noise performance of $-100~\mathrm{dBc/Hz}$ at 10 kHz offset from the carrier. Spurs are heavily attenuated by the loop filter and are below $-90~\mathrm{dBc}$.

The loop filter output drives the VCO, which, in turn, is fed back to the RF input of the PLL synthesizer and also drives the RF output terminal. A T-circuit configuration provides 50 Ω matching between the VCO output, the RF output, and the RF $_{\rm IN}$ terminal of the synthesizer.



NOTE DECOUPLING CAPACITORS (0.1mF/10pF) ON AV $_{\rm DD}$, DV $_{\rm DD}$, AND V $_{\rm P}$ OF THE ADF4007 AND ON V $_{\rm CC}$ OF THE AD820 AND THE HMC358MS8G HAVE BEEN OMITTED FROM THE DIAGRAM TO AID CLARITY.

Figure 13. 6.78 GHz Local Oscillator Using the ADF4007

USING THE ADF4007 AS A DIVIDER

In addition to its use as a standard PLL synthesizer, the ADF4007 can also be used as a high frequency counter/divider with a value of 8, 16, 32, or 64. This can prove useful in a wide variety of applications where a higher frequency signal is readily available. Figure 14 shows the ADF4007 used in this manner with the ADF4360-7.

This part is an integrated synthesizer and VCO, in this case operating over a range of 1200 MHz to 1500 MHz. With divide-by-8 chosen in the ADF4007 (N2 = 0, N1 = 0), the output range is 150 MHz to 187.50 MHz.

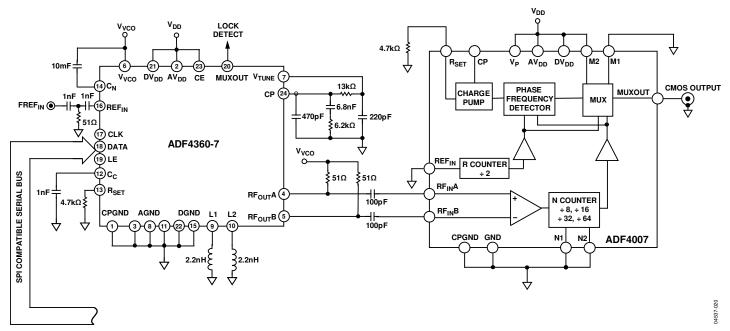


Figure 14. Using the ADF4007 to Divide-Down the Output of the ADF4360-7

PCB DESIGN GUIDELINES FOR CHIP SCALE PACKAGE

The lands on the chip scale package (CP-20-6) are rectangular. The printed circuit board pad for these should be 0.1 mm longer than the package land length and 0.05 mm wider than the package land width. Center the land on the pad to ensure that the solder joint size is maximized.

The bottom of the chip scale package has a central thermal pad. The thermal pad on the printed circuit board should be at least as large as this exposed pad. The printed circuit board should have a clearance of at least 0.25 mm between the thermal pad and the inner edges of the pad pattern to ensure that shorting is avoided.

Thermal vias may be used on the printed circuit board thermal pad to improve thermal performance of the package. If vias are used, they should be incorporated in the thermal pad at 1.2 mm pitch grid. The via diameter should be between 0.30 mm and 0.33 mm, and the via barrel should be plated with 1 oz. copper to plug the via.

Connect the printed circuit board thermal pad to AGND.

OUTLINE DIMENSIONS

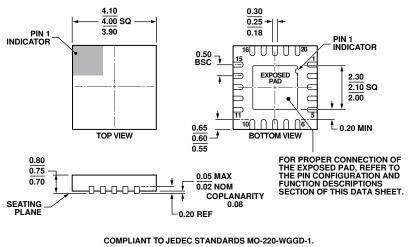


Figure 15. 20-Lead Lead Frame Chip Scale Package [LFCSP_WQ] 4 mm × 4 mm Body, Very Very Thin Quad (CP-20-6) Dimensions shown in millimeters

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
ADF4007BCPZ	−40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
ADF4007BCPZ-RL	−40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
ADF4007BCPZ-RL7	−40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
EVAL-ADF4007EBZ1		Evaluation Board	

 $^{^{1}}$ Z = RoHS compliant part.

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