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## Data Sheet

## FEATURES

## RF bandwidth to 13.5 GHz

High and low speed FMCW ramp generation
25-bit fixed modulus allows subhertz frequency resolution
PFD frequencies up to 130 MHz
Normalized phase noise floor of $\mathbf{- 2 2 4 ~ d B c / H z}$ FSK and PSK functions
Sawtooth and triangular waveform generation
Ramp superimposed with FSK
Ramp with 2 different sweep rates
Ramp delay, frequency readback, and interrupt functions
Programmable phase control
2.7 V to 3.45 V analog power supply
1.8 V to 2 V digital power supply

Programmable charge pump currents
3-wire serial interface
Digital lock detect
ESD performance: 3000 V HBM, 1000 V CDM
Qualified for automotive applications

## APPLICATIONS

## FMCW radars

Communications test equipment
Communications infrastructure

## GENERAL DESCRIPTION

The ADF4169 is a 13.5 GHz , fractional-N frequency synthesizer with modulation and both fast and slow waveform generation capability. The device uses a 25 -bit fixed modulus, allowing subhertz frequency resolution.
The ADF4169 consists of a low noise digital phase frequency detector (PFD), a precision charge pump, and a programmable reference divider. The $\Sigma$ - $\Delta$-based fractional interpolator allows programmable fractional-N division. The INT and FRAC registers define an overall N divider as $\mathrm{N}=\mathrm{INT}+\left(\mathrm{FRAC} / 2^{25}\right)$.

The ADF4169 can be used to implement frequency shift keying (FSK) and phase shift keying (PSK) modulation. Frequency sweep modes are also available to generate various waveforms in the frequency domain, for example, sawtooth waveforms and triangular waveforms. Sweeps can be set to run automatically or with each step manually triggered by an external pulse. The ADF4169 features cycle slip reduction (CSR) circuitry, which enables faster lock times without the need for modifications to the loop filter.

Control of all on-chip registers is via a simple 3-wire interface. The ADF4169 operates with an analog power supply in the range of 2.7 V to 3.45 V and a digital power supply in the range of 1.8 V to 2 V . The device can be powered down when not in use.

FUNCTIONAL BLOCK DIAGRAM


Rev. 0

\section*{COMPARABLE PARTS

View a parametric search of comparable parts.

## EVALUATION KITS

- ADF4159 Evaluation Board


## DOCUMENTATION

## Data Sheet

- ADF4169: Direct Modulation/Fast Waveform Generating, 13.5 GHz, Fractional-N Frequency Synthesizer Data Sheet


## DESIGN RESOURCES $\square$

- ADF4169 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints


## DISCUSSIONS

View all ADF4169 EngineerZone Discussions.
SAMPLE AND BUY $\square$
Visit the product page to see pricing options.

## TECHNICAL SUPPORT $\square$

Submit a technical question or find your regional support number.

## DOCUMENT FEEDBACK

Submit feedback for this data sheet.

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## SPECIFICATIONS

$\mathrm{AV}_{\mathrm{DD}}=\mathrm{V}_{\mathrm{P}}=2.7 \mathrm{~V}$ to $3.45 \mathrm{~V}, \mathrm{DV}_{\mathrm{DD}}=\mathrm{SDV} \mathrm{VD}_{\mathrm{D}}=1.9 \mathrm{~V}, \mathrm{AGND}=\mathrm{DGND}=\mathrm{SDGND}=\mathrm{CPGND}=0 \mathrm{~V}, \mathrm{f}_{\mathrm{PFD}}=130 \mathrm{MHz}, \mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, dBm referred to $50 \Omega$, unless otherwise noted.

Table 1.

| Parameter ${ }^{1}$ | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| RF CHARACTERISTICS RF Input Frequency, RFin Prescaler Output Frequency | 0.5 |  | 13.5 2 | $\mathrm{GHz}$ $\mathrm{GHz}$ | -10 dBm minimum to 0 dBm maximum; for lower frequencies, ensure a slew rate $\geq$ $400 \mathrm{~V} / \mu \mathrm{s}$ <br> For higher frequencies, use $8 / 9$ prescaler |
| REFERENCE CHARACTERISTICS <br> REF ${ }_{\text {IN }}$ Input Frequency <br> Reference Doubler Enabled REF In Input Capacitance REFIN Input Current | 10 $10$ |  | $\begin{aligned} & 260 \\ & \\ & \\ & 50 \\ & 1.2 \\ & \pm 100 \end{aligned}$ | MHz <br> MHz <br> pF <br> $\mu \mathrm{A}$ | -5 dBm minimum to +9 dBm maximum biased at 1.9/2 (ac coupling ensures 1.9/2 bias); for frequencies $<10 \mathrm{MHz}$, use a dccoupled, CMOS-compatible square wave with a slew rate $>25 \mathrm{~V} / \mu \mathrm{s}$ <br> Bit DB20 in Register R2 set to 1 |
| PHASE FREQUENCY DETECTOR, PFD Phase Detector Frequency, $\mathrm{f}_{\mathrm{PFD}}{ }^{2}$ |  |  | 130 | MHz |  |
| CHARGE PUMP (CP) <br> ICP Sink/Source Current <br> High Value <br> Low Value <br> Absolute Accuracy <br> $\mathrm{R}_{\text {SEt }}$ Range <br> Icp Three-State Leakage Current <br> Sink and Source Matching <br> $I_{c P}$ vs. VCP <br> IcP vs. Temperature | 4.59 | 4.8 300 2.5 5.1 1 2 2 2 | 5.61 | mA <br> $\mu \mathrm{A}$ <br> \% <br> k $\Omega$ <br> nA <br> \% <br> \% <br> \% | Programmable <br> $R_{\text {SET }}=5.1 \mathrm{k} \Omega$ $\mathrm{R}_{\text {SEt }}=5.1 \mathrm{k} \Omega$ <br> Sink and source current $\begin{aligned} & 0.5 \mathrm{~V}<\mathrm{V}_{\mathrm{CP}}<\mathrm{V}_{\mathrm{P}}-0.5 \mathrm{~V} \\ & 0.5 \mathrm{~V}<\mathrm{V}_{\mathrm{CP}}<\mathrm{V}_{\mathrm{P}}-0.5 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{CP}}=\mathrm{V}_{\mathrm{P}} / 2 \end{aligned}$ |
| LOGIC INPUTS <br> Input Voltage High, $\mathrm{V}_{\mathrm{INH}}$ <br> Input Voltage Low, VINL <br> Input Current, $\mathrm{I}_{\mathrm{NH}} / \mathrm{I}_{\mathrm{INL}}$ <br> Input Capacitance, $\mathrm{CIN}_{\mathrm{IN}}$ | 1.17 |  | $\begin{aligned} & 0.4 \\ & \pm 1 \\ & 10 \end{aligned}$ | V <br> V <br> $\mu \mathrm{A}$ <br> pF |  |
| LOGIC OUTPUTS <br> Output Voltage High, V он <br> Output Voltage Low, Vol <br> Output High Current, loн | DVDD-0.4 |  | $\begin{aligned} & 0.3 \\ & 100 \end{aligned}$ | V <br> V <br> $\mu \mathrm{A}$ | CMOS output selected $\mathrm{loL}=500 \mu \mathrm{~A}$ |
| POWER SUPPLIES <br> AVDD <br> DV $V_{D D}, S D V_{D D}$ <br> $V_{p}$ <br> AldD <br> Dlod <br> Ip <br> Power-Down Mode | $\begin{aligned} & 2.7 \\ & 1.8 \\ & 2.7 \end{aligned}$ | $\begin{aligned} & 26 \\ & 7.5 \\ & 5.5 \\ & 2 \end{aligned}$ | 3.45 2 3.45 40 12 7 | V <br> V <br> V <br> mA <br> mA <br> mA <br> $\mu \mathrm{A}$ | Supply current drawn by $A V_{D D} ; f_{\text {PFD }}=130 \mathrm{MHz}$ Supply current drawn by DVD; ffFD $=130 \mathrm{MHz}$ Supply current drawn by $V_{P} ; f_{\text {PFD }}=130 \mathrm{MHz}$ |


| Parameter ${ }^{1}$ | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| NOISE CHARACTERISTICS |  |  |  |  |  |
| Normalized Phase Noise Floor ${ }^{3}$ |  |  |  |  | Phase-locked loop (PLL) bandwidth $(B W)=$ 1 MHz |
| Integer-N Mode |  | -224 |  | $\mathrm{dBc} / \mathrm{Hz}$ | FRAC $=0$; see $\Sigma$ - $\Delta$ Modulator Mode section |
| Fractional-N Mode |  | -217 |  | $\mathrm{dBc} / \mathrm{Hz}$ |  |
| Normalized 1/f Noise ( $\left.\mathrm{PN}_{1-}\right)^{4}$ |  | -120 |  | $\mathrm{dBc} / \mathrm{Hz}$ | Measured at 10 kHz offset, normalized to 1 GHz |
| Phase Noise Performance ${ }^{5}$ |  |  |  |  | At the voltage controlled oscillator (VCO) output |
| 12,002 MHz Output ${ }^{6}$ |  | -96 |  | $\mathrm{dBc} / \mathrm{Hz}$ | At 50 kHz offset, 100 MHz PFD frequency |

${ }^{1}$ Operating temperature: $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$.
${ }^{2}$ Guaranteed by design. Sample tested to ensure compliance.
${ }^{3}$ This specification can be used to calculate phase noise for any application. Use the formula ((Normalized Phase Noise Floor) +10 log(fpFD) +20 logN) to calculate in-band phase noise performance as seen at the VCO output.
${ }^{4}$ The PLL phase noise is composed of flicker ( $1 / \mathrm{f}$ ) noise plus the normalized PLL noise floor. The formula for calculating the $1 / \mathrm{f}$ noise contribution at an RF frequency (f $\mathrm{f}_{\mathrm{RF}}$ ) and at an offset frequency (f) is given by $\mathrm{PN}=\mathrm{PN}_{1 \_f}+10 \log (10 \mathrm{kHz} / \mathrm{f})+20 \log \left(\mathrm{f}_{\mathrm{RF}} / 1 \mathrm{GHz}\right)$. Both the normalized phase noise floor and flicker noise are modeled in ADIsimPLL ${ }^{\text {™ }}$.
${ }^{5}$ The phase noise performance is measured with a modified EV-ADF4159EB3Z evaluation board and the Rohde \& Schwarz ${ }^{\circledR}$ FSUP signal source analyzer.
${ }^{6} f_{\text {REFIN }}=100 \mathrm{MHz}, \mathrm{f}_{\text {PFD }}=100 \mathrm{MHz}$, offset frequency $=50 \mathrm{kHz}$, RFout $=12,002 \mathrm{MHz}, \mathrm{N}=120.02$, and loop bandwidth $=250 \mathrm{kHz}$.

## TIMING SPECIFICATIONS

$A V_{\mathrm{DD}}=\mathrm{V}_{\mathrm{P}}=2.7 \mathrm{~V}$ to $3.45 \mathrm{~V}, \mathrm{DV}_{\mathrm{DD}}=\mathrm{SDV} \mathrm{VD}_{\mathrm{D}}=1.9 \mathrm{~V}, \mathrm{AGND}=\mathrm{DGND}=\mathrm{SDGND}=\mathrm{CPGND}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{dBm}$ referred to $50 \Omega$, unless otherwise noted.

Table 2. Write Timing

| Parameter | Limit at T $_{\text {min }}$ to $\mathbf{T}_{\text {max }}$ | Unit | Description |
| :--- | :--- | :--- | :--- |
| $\mathrm{t}_{1}$ | 20 | ns min | LE setup time |
| $\mathrm{t}_{2}$ | 10 | ns min | DATA to CLK setup time |
| $\mathrm{t}_{3}$ | 10 | ns min | DATA to CLK hold time |
| $\mathrm{t}_{4}$ | 25 | ns min | CLK high duration |
| $\mathrm{t}_{5}$ | 25 | ns min | CLK low duration |
| $\mathrm{t}_{6}$ | 10 | ns min | CLK to LE setup time |
| $\mathrm{t}_{7}$ | 20 | ns min | LE pulse width |

## Write Timing Diagram



Figure 2. Write Timing Diagram

ADF4169

Table 3. Read Timing

| Parameter | Limit at TMIN to TMAX | Unit | Description |
| :--- | :--- | :--- | :--- |
| $\mathrm{t}_{1}{ }^{1}$ | $\mathrm{t}_{\text {PFD }}+20$ | ns min | TX |
| $\mathrm{t}_{2}$ | 20 | ns min | CLK setup time |
| $\mathrm{t}_{3}$ | 25 | ns min | CLK high duration to data (on MUXOUT) |
| $\mathrm{t}_{4}$ | 25 | ns min | CLK low duration |
| $\mathrm{t}_{5}$ | 10 | ns min | CLK to LE setup time |

[^0]
## Read Timing Diagram



Figure 3. Read Timing Diagram


Figure 4. Load Circuit for MUXOUT Timing, $C_{L}=10 \mathrm{pF}$

## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{GND}=\mathrm{AGND}=\mathrm{DGND}=\mathrm{SDGND}=\mathrm{CPGND}=$ 0 V , unless otherwise noted.

Table 4.

| Parameter | Rating |
| :---: | :---: |
| AV $\mathrm{DD}^{\text {to GND }}$ | -0.3 V to +3.9 V |
| DV ${ }_{\text {D }}$ to GND | -0.3 V to +2.4 V |
| $V_{p}$ to GND | -0.3 V to +3.9 V |
| $\mathrm{V}_{\mathrm{P}}$ to $\mathrm{AV} \mathrm{V}_{\text {D }}$ | -0.3 V to +0.3 V |
| Digital Input/Output Voltage to GND | -0.3 V to $\mathrm{DV}_{\mathrm{DD}}+0.3 \mathrm{~V}$ |
| Analog Input/Output Voltage to GND | -0.3 V to $\mathrm{AV}_{\mathrm{DD}}+0.3 \mathrm{~V}$ |
| REFin to GND | -0.3 V to $\mathrm{DV} \mathrm{VD}^{+0.3 \mathrm{~V}}$ |
| RFin to GND | -0.3 V to $\mathrm{AV} \mathrm{DD}^{+0.3 \mathrm{~V}}$ |
| Operating Temperature Range, Industrial | $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Maximum Junction Temperature | $150^{\circ} \mathrm{C}$ |
| Reflow Soldering |  |
| Peak Temperature | $260^{\circ} \mathrm{C}$ |
| Time at Peak Temperature | 40 sec |
| ESD |  |
| Charged Device Model (CDM) | 1000 V |
| Human Body Model (HBM) | 3000 V |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

Thermal impedance $\left(\theta_{\text {IA }}\right)$ is specified for a device with the exposed pad soldered to AGND.

Table 5. Thermal Resistance

| Package Type | $\boldsymbol{\theta}_{\mathrm{JA}}$ | Unit |
| :--- | :--- | :--- |
| 24-Lead LFCSP_WQ | 30.4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Table 6. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 | CPGND | Charge Pump Ground. This pin is the ground return path for the charge pump. |
| 2,3 | AGND | Analog Ground. |
| 4 | RFin $B$ | Complementary Input to the RF Prescaler. Decouple this pin to the ground plane with a small bypass capacitor, typically 100 pF . |
| 5 | RFinA | Input to the RF Prescaler. This small signal input is normally ac-coupled from the VCO. |
| 6, 7, 8 | $A V_{\text {DD }}$ | Positive Power Supplies for the RF Section. Place decoupling capacitors to the ground plane as close as possible to these pins. |
| 9 | REFIN | Reference Input. This CMOS input has a nominal threshold of $\mathrm{DV} \mathrm{VD}_{\mathrm{D}} / 2$ and an equivalent input resistance of $100 \mathrm{k} \Omega$. It can be driven from a TTL or CMOS crystal oscillator, or it can be ac-coupled. |
| 10 | DGND | Digital Ground. |
| 11 | SDGND | Digital $\Sigma-\Delta$ Modulator Ground. This pin is the ground return path for the $\Sigma-\Delta$ modulator. |
| 12 | TX ${ }_{\text {data }}$ | Transmit Data Pin. This pin provides the transmitted data in FSK or PSK mode and also controls some ramping functionality. |
| 13 | CE | Chip Enable (1.9V Logic). A logic low on this pin powers down the device and places the charge pump output into three-state mode. |
| 14 | CLK | Serial Clock Input. This input is used to clock in the serial data to the registers. The data is latched into the input shift register on the CLK rising edge. This input is a high impedance CMOS input. |
| 15 | DATA | Serial Data Input. The serial data is loaded most significant bit (MSB) first; the three least significant bits (LSBs) are the control bits. This input is a high impedance CMOS input. |
| 16 | LE | Load Enable Input. When LE is high, the data stored in the input shift register is loaded into one of the eight latches; the latch is selected using the control bits. This input is a high impedance CMOS input. |
| 17 | MUXOUT | Multiplexer Output. This pin allows various internal signals to be accessed externally. |
| 18 | SDV ${ }_{\text {DD }}$ | Power Supply for the Digital $\Sigma-\Delta$ Modulator. Place decoupling capacitors to the ground plane as close as possible to this pin. |
| 19 | DV ${ }_{\text {DD }}$ | Positive Power Supply for the Digital Section. Place decoupling capacitors to the digital ground plane as close as possible to this pin. |
| 20, 21 | SW1, SW2 | Fast Lock Switches. |
| 22 | $V_{P}$ | Charge Pump Power Supply. The voltage on this pin must be greater than or equal to AV $\mathrm{DD}^{\text {. }}$ |
| 23 | RSET | Reset. Connecting a resistor between this pin and ground sets the maximum charge pump output current. The relationship between $\mathrm{I}_{\mathrm{CP}}$ and $\mathrm{R}_{\text {SEt }}$ is as follows: $I_{\text {CP_MAX }}=24.48 / R_{\text {SET }}$ <br> where: $\begin{aligned} & I_{C P \_m A X}=4.8 \mathrm{~mA} . \\ & R_{\text {SET }}=5.1 \mathrm{k} \Omega . \end{aligned}$ |
| 24 | CP | Charge Pump Output. When the charge pump is enabled, this output provides $\pm \mathrm{lcp}$ to the external loop filter, which, in turn, drives the external VCO. |
| 25 | EPAD | Exposed Pad. The LFCSP has an exposed pad that must be connected to AGND. |

TYPICAL PERFORMANCE CHARACTERISTICS


Figure 6. Phase Noise at $12.002 \mathrm{GHz}, f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}$, Bleed Current $=11.03 \mu \mathrm{~A}$


Figure 7. Sawtooth Ramp, $f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3, C L K_{2}=26, D E V=1024$, DEV_OFFSET $=8$, Number of Steps $=64$


Figure 8. Sawtooth Ramp with Delay, $f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$,
Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3, C L K_{2}=26, D E V=1024$,
DEV_OFFSET $=8$, Number of Steps $=64$, Delay Word $=1000$


Figure 9. Sawtooth Burst, $f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3, C L K_{2}=26, D E V=1024$, DEV_OFFSET $=8$, Number of Steps $=64$


Figure 10. Dual Sawtooth Ramp, $f_{\text {PFD }}=100 \mathrm{MHz}, I_{c P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3$; First Ramp: $C L K_{2}=26, D E V=1024$, DEV_OFFSET = 8, Number of Steps = 64; Second Ramp: $C L K_{2}=52$, $D E V=1024$, DEV_OFFSET $=7$, Number of Steps $=64$


Figure 11. Triangle Ramp, $f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3, C L K_{2}=26, D E V=1024$, DEV_OFFSET $=8$, Number of Steps $=64$


Figure 12. Fast Ramp (Triangle Ramp with Different Slopes), $f_{P F D}=100 \mathrm{MHz}$, $I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}, C L K_{1}=3$; Up Ramp: $C L K_{2}=26$, $D E V=1024, D E V \_O F F S E T=8$, Number of Steps $=64$; Down Ramp: $C L K_{2}=70$, $D E V=16,384$, DEV_OFFSET $=8$, Number of Steps $=4$


Figure 13. Phase Shift Keying (PSK), Loop Bandwidth $=250 \mathrm{kHz}$,
Phase Value $=1024$, Data Rate $=20 \mathrm{kHz}$


Figure 14. Frequency Shift Keying (FSK), Loop Bandwidth $=250 \mathrm{kHz}$, DEV $=1049$, DEV_OFFSET $=9$, Data Rate $=20 \mathrm{kHz}$


Figure 15. FSK Ramp, $f_{P F D}=100 \mathrm{MHz}, I_{C P}=2.5 \mathrm{~mA}$, Loop Bandwidth $=250 \mathrm{kHz}$, $C L K_{1}=3, C L K_{2}=26, D E V=1024, D E V \_O F F S E T=8$, Number of Steps $=64 ;$ FSK: $D E V=-512, D E V \_O F F S E T=8$


Figure 16. RFIN Sensitivity at Nominal Temperature


Figure 17. Charge Pump Output Characteristics

## THEORY OF OPERATION <br> REFERENCE INPUT SECTION

Figure 18 shows the reference input stage. The SW1 and SW2 switches are normally closed (NC in Figure 18). The SW3 internal switch is normally open (NO in Figure 18). When power-down is initiated, SW3 is closed, and SW1 and SW2 are opened. In this way, no loading of the $\mathrm{REF}_{\text {IN }}$ pin occurs during power-down.


Figure 18. Reference Input Stage

## RF INPUT STAGE

Figure 19 shows the RF input stage. The input stage is followed by a two-stage limiting amplifier to generate the current-mode logic (CML) clock levels required for the prescaler.


Figure 19. RF Input Stage

## RF INT DIVIDER

The RF INT CMOS divider allows a division ratio in the PLL feedback counter (see Figure 20). Division ratios from 23 to 4095 are allowed.


Figure 20. RF INT Divider

## 25-BIT FIXED MODULUS

The ADF4169 has a 25-bit fixed modulus. This modulus allows output frequencies to be spaced with a resolution of

$$
\begin{equation*}
f_{R E S}=f_{P F D} / 2^{25} \tag{1}
\end{equation*}
$$

where $f_{P P D}$ is the frequency of the phase frequency detector (PFD).
For example, with a PFD frequency of 100 MHz , frequency steps of 2.98 Hz are possible. Due to the architecture of the $\Sigma-\Delta$ modulator, there is a fixed $+\left(f_{\text {PFD }} / 2^{26}\right)$ offset on the VCO output. To remove this offset, see the $\Sigma-\Delta$ Modulator Mode section.

## INT, FRAC, AND R COUNTER RELATIONSHIP

The INT and FRAC values, in conjunction with the R counter, make it possible to generate output frequencies that are spaced by fractions of the PFD frequency.

The RF VCO frequency ( $\mathrm{RF}_{\text {out }}$ ) equation is

$$
\begin{equation*}
R F_{\text {OUT }}=\left(I N T+\left(F R A C / 2^{25}\right)\right) \times f_{\text {PFD }} \tag{2}
\end{equation*}
$$

where:
$R F_{\text {out }}$ is the output frequency of the external VCO.
INT is the preset divide ratio of the binary 12-bit counter
(23 to 4095).
$F R A C$ is the numerator of the fractional division (0 to $\left(2^{25}-1\right)$ ).
The PFD frequency ( $\mathrm{f}_{\text {PFD }}$ ) equation is

$$
\begin{equation*}
f_{P F D}=R E F_{I N} \times((1+D) /(R \times(1+T))) \tag{3}
\end{equation*}
$$

where:
$R E F_{\text {IN }}$ is the reference input frequency.
$D$ is the REF $_{\text {IN }}$ doubler bit ( 0 or 1 ).
$R$ is the preset divide ratio of the binary 5 -bit programmable reference ( R ) counter (1 to 32 ).
$T$ is the REF $_{\text {IN }}$ divide by 2 bit ( 0 or 1 ).

## R COUNTER

The 5-bit R counter allows the reference input ( $\mathrm{REF}_{\text {IN }}$ ) frequency to be divided down to supply the reference clock to the PFD. Division ratios from 1 to 32 are allowed.

## PHASE FREQUENCY DETECTOR AND CHARGE PUMP

The PFD takes inputs from the R counter and N counter and produces an output proportional to the phase and frequency difference between them. Figure 21 shows a simplified schematic of the PFD.


Figure 21. PFD Simplified Schematic
The PFD includes a fixed delay element that sets the width of the antibacklash pulse, which is typically 1 ns . This pulse ensures that there is no dead zone in the PFD transfer function and gives a consistent reference spur level.

## MUXOUT AND LOCK DETECT

The multiplexer output on the ADF4169 allows the user to access various internal points on the chip. The state of MUXOUT is controlled by the M4, M3, M2, and M1 bits in Register R0 (see Figure 25). Figure 22 shows the MUXOUT section in block diagram form.


## INPUT SHIFT REGISTER

The ADF4169 digital section includes a 5-bit R counter, a 12-bit INT counter, and a 25 -bit FRAC counter. Data is clocked into the 32-bit input shift register on each rising edge of CLK. The data is clocked in MSB first. Data is transferred from the input shift register to one of eight latches on the rising edge of LE.

The destination latch is determined by the state of the three control bits (C3, C2, and C1) in the input shift register. As shown in Figure 2, the control bits are the three LSBs (DB2, DB1, and DB0, respectively). Table 7 shows the truth table for these bits. Figure 23 and Figure 24 provide a summary of how the latches are programmed.

Table 7. Truth Table for the C3, C2, and C1 Control Bits

| Control Bits |  |  | Register |
| :--- | :--- | :--- | :--- |
| C3 | C2 | C1 |  |
| 0 | 0 | 0 | R0 |
| 0 | 0 | 1 | R1 |
| 0 | 1 | 0 | R2 |
| 0 | 1 | 1 | R3 |
| 1 | 0 | 0 | R4 |
| 1 | 0 | 1 | R5 |
| 1 | 1 | 0 | R6 |
| 1 | 1 | 1 | R7 |

## PROGRAM MODES

Table 7 and Figure 25 through Figure 32 show how the program modes are set up in the ADF4169.
The following settings in the ADF4169 are double buffered: LSB fractional value, phase value, charge pump current setting, reference divide by 2 , reference doubler, R counter value, and $\mathrm{CLK}_{1}$ divider value. Before the device uses a new value for any double-buffered setting, the following two events must occur:

1. The new value is latched into the device by writing to the appropriate register.
2. A new write is performed to Register 0 (R0).

For example, updating the fractional value involves a write to the 13 LSB bits in Register R1 and the 12 MSB bits in Register R0. Register R1 must be written to first, followed by the write to R0. The frequency change begins after the write to Register R0. Double buffering ensures that the bits written to Register R1 do not take effect until after the write to Register R0.

## REGISTER MAPS

FRAC／INT REGISTER（RO）

| $\left(\begin{array}{l} \text { z } \\ 0 \\ \sum_{4} \end{array}\right.$ | MUXOUT CONTROL |  |  |  | 12－BIT INTEGER VALUE（INT） |  |  |  |  |  |  |  |  |  |  |  | 12－BIT MSB FRACTIONAL VALUE （FRAC） |  |  |  |  |  |  |  |  |  |  |  | BITSCONTROL |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | B16 | DB15 | DB14 | DB13 | B12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DBO |
| R1 | M4 | м3 | M2 | M1 | N12 | N11 | N10 | N9 | N8 | N7 | N6 | N5 | N4 | N3 | N2 | N1 | F25 | F24 | F23 | F22 | F21 | F20 | F19 | F18 | F17 | F16 | F15 | F14 | С3（0） | C2（0） | C1（0） |

LSB FRAC REGISTER（R1）

| RES | ERVE |  |  | 13－BIT LSB FRACTIONAL VALUE <br> （FRAC） |  |  |  |  |  |  |  |  |  |  |  |  | 12－BIT PHASE VALUE DBB |  |  |  |  |  |  |  |  |  |  |  | CONTROLBITS |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | P1 | F13 | F12 | F11 | F10 | F9 | F8 | F7 | F6 | F5 | F4 | F3 | F2 | F1 | P12 | P11 | P10 | P9 | P8 | P7 | P6 | P5 | P4 | P3 | P2 | P1 | C3（0） | C2（0） | C1（1） |

R DIVIDER REGISTER（R2）

| RESERVED |  |  | ¢్ల | $\begin{gathered} \text { CBB } \\ \text { CURRENT } \\ \text { SETTING } \end{gathered}$ |  |  |  |  |  |  |  | 5－BIT R COUNTER |  |  |  |  | 12－BIT CLK $_{1}$ DIVIDER VALUE ${ }^{\text {dBB }}$ |  |  |  |  |  |  |  |  |  |  |  | $\begin{aligned} & \text { CONTROL } \\ & \text { BITS } \end{aligned}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | B15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | CR1 | CPI4 | CPI3 | CP12 | CPI1 | 0 | P1 | U2 | U1 | R5 | R4 | R3 | R2 | R1 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | C3（0） | C2（1） | C1（0） |

FUNCTION REGISTER（R3）

| RESERVED |  |  |  |  |  |  | NEG BLEED CURRENT |  |  |  | RESERVED |  |  |  | ـــ | $\begin{aligned} & \text { ün } \\ & \text { z } \end{aligned}$ |  |  |  |  |  | 咅 | 号 | 号 |  |  |  |  | $\begin{aligned} & \text { CONTROL } \\ & \text { BITS } \end{aligned}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | 818 | DB17 | DB16 | DB15 | DB14 | DB | 312 | DB11 | B10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | NB3 | NB2 | NB1 | 0 | 0 | 0 | 0 | 1 | L1 | NS1 | U12 | 0 | 0 | RM2 | RM1 | 0 | 0 | U11 | U10 | U9 | U8 | 07 | С3（0） | C2（1） | C1（1） |

NOTES
1．DBB $=$ DOUBLE－BUFFERED BITS．
Figure 23．Register Summary 1

CLOCK REGISTER（R4）

| $\begin{aligned} & \text { 山 } \\ & \text { 山 } \end{aligned}$ | $\stackrel{\Sigma-\Delta}{\text { MODULATOR MODE }}$ |  |  |  |  | RAMP STATUS |  |  |  |  | $\begin{aligned} & \text { CLK } \\ & \text { DIV } \\ & \text { MODE } \end{aligned}$ |  | 12－BIT $\mathrm{CLK}_{2}$ DIVIDER VALUE |  |  |  |  |  |  |  |  |  |  |  | $\begin{aligned} & \vec{~} \\ & \omega \\ & \bar{\Delta} \\ & \underset{u}{u} \end{aligned}$ |  | SER |  |  | ONTR BITS |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | DB28 | DB27 | DB26 | DB25 | DB24 | DB23 | DB22 | DB21 | DB20 | DB19 | DB18 | DB17 | DB16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| LS1 | S5 | S4 | S3 | S2 | S1 | R5 | R4 | R3 | R2 | R1 | C2 | C1 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | CS1 | 0 | 0 | 0 | C3（1） | C2（0） | C1（0） |

DEVIATION REGISTER（R5）

| $\left\lvert\, \begin{aligned} & \stackrel{\rightharpoonup}{u} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{w}} \\ & \stackrel{u}{w} \end{aligned}\right.$ |  |  | $\left\|\begin{array}{c} \underset{\sim}{\underset{\sim}{u}} \\ \stackrel{\rightharpoonup}{\underset{\sim}{w}} \\ \underset{\sim}{u} \end{array}\right\|$ |  | $\begin{aligned} & \stackrel{\rightharpoonup}{0} \\ & \stackrel{\rightharpoonup}{x} \\ & \underset{\sim}{4} \\ & \stackrel{y}{2} \end{aligned}$ |  |  |  |  | IT DET | $\begin{aligned} & \text { viatier } \\ & \text { wor } \end{aligned}$ | RON | 16－BIT DEVIATION WORD |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | $\begin{gathered} \text { CONTROL } \\ \text { BITS } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DB31 | DB30 | DB29 | D828 |  |  | DB25 | 324 | DB23 | DB22 | DB21 | B20 | DB19 | DB18 | DB17 |  | DB15 | DB14 |  | DB12 | B11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DBO |
| 0 | 0 | TR1 | 0 | 12 | 11 | 0 | 0 | DS1 | D04 | D03 | DO2 | D01 | D16 | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | c3（1） | c20） | c1（1） |

STEP REGISTER（R6）

| RESERVED |  |  |  |  |  |  |  | 岗 | 20－BIT STEP WORD |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | $\begin{aligned} & \text { CONTROL } \\ & \text { BITS } \end{aligned}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | D830 | 329 | D828 | D827 | 826 | DB2 |  | DB23 | D822 | D821 | DB20 | DB19 | DB18 | D817 | DB16 | DB15 | DB14 | ［PB13 | D812 | OB1 | DB10 | DB9 | D88 | DB7 | D86 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SSE1 | S20 | S19 | S18 | S17 | S16 | S15 | S14 | S13 | S12 | S11 | S10 | s9 | s8 | s7 | S6 | s5 | S4 | S3 | s2 | S1 | с3（1） | c2（1） | C1（0） |

DELAY REGISTER（R7）

| Reserved |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | $\begin{aligned} & \text { zün } \\ & \stackrel{e}{4} \\ & \stackrel{e}{6} \\ & \stackrel{\rightharpoonup}{4} \end{aligned}$ | 12－BIT DELAY START WORD |  |  |  |  |  |  |  |  |  |  |  | $\begin{gathered} \text { CONTROL } \\ \text { BITS } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 DB30 | DB29 | B28 | B27 | DB26 |  |  | B23 | DB22 | DB |  | B20 | DB1 | B | B | 17 | B16 | DB15 | DB14 | DB13 | DB12 | DB11 | DB10 | DB9 | DB8 | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | TD1 | st | T1 | TR1 | FR | 0 | RD | 1 | DC1 | DSE1 | DS12 | DS11 | DS10 | Ds9 | DS8 | DS7 | DS6 | DS5 | DS4 | DS3 | DS2 | DS1 | c3（1） | c2（1） | （1） |

NOTES
1．DBB＝DOUBLE－BUFFERED BITS．

## FRAC/INT REGISTER (RO) MAP

When Bits DB[2:0] are set to 000, the on-chip FRAC/INT register (Register R0) is programmed (see Figure 25).

## Ramp On

When Bit DB31 is set to 1 , the ramp function is enabled. When Bit DB31 is set to 0 , the ramp function is disabled.

## MUXOUT Control

The on-chip multiplexer of the ADF4169 is controlled by Bits DB[30:27]. See Figure 25 for the truth table.

## 12-Bit Integer Value (INT)

Bits $\mathrm{DB}[26: 15]$ set the INT value, which forms part of the overall feedback division factor. For more information, see the INT, FRAC, and R Counter Relationship section.

## 12-Bit MSB Fractional Value (FRAC)

Bits $\mathrm{DB}[14: 3]$, along with Bits $\mathrm{DB}[27: 15]$ in the LSB FRAC register (Register R1), set the FRAC value that is loaded into the fractional interpolator. The FRAC value forms part of the overall feedback division factor. These 12 bits are the MSBs of the 25-bit FRAC value; Bits DB[27:15] in the LSB FRAC register (Register R1) are the LSBs. For more information, see the RF Synthesizer Worked Example section.


## LSB FRAC REGISTER (R1) MAP

When Bits DB[2:0] are set to 001, the on-chip LSB FRAC register (Register R1) is programmed (see Figure 26).

## Reserved Bits

All reserved bits must be set to 0 for normal operation.

## Phase Adjustment

Bit DB28 enables and disables phase adjustment. The phase shift is generated by the value programmed in Bits $\mathrm{DB}[14: 3]$.

## 13-Bit LSB Fractional Value (FRAC)

Bits DB [27:15], along with Bits $\mathrm{DB}[14: 3$ ] in the FRAC/INT register (Register R0), set the FRAC value that is loaded into the fractional interpolator. The FRAC value forms part of the overall feedback division factor.


Figure 26. LSB FRAC Register (R1) Map

## R DIVIDER REGISTER (R2) MAP

When Bits DB [2:0] are set to 010, the on-chip R divider register (Register R2) is programmed (see Figure 27).

## Reserved Bits

All reserved bits must be set to 0 for normal operation.

## CSR Enable

When Bit DB28 is set to 1, cycle slip reduction (CSR) is enabled. CSR is a method for improving lock times. Note that the signal at the PFD must have a $50 \%$ duty cycle for CSR to work. In addition, the charge pump current setting must be set to its minimum value. For more information, see the Cycle Slip Reduction for Faster Lock Times section.
The CSR feature can be used only when the phase detector polarity setting is positive (Bit DB6 = 1 in Register R3). CSR cannot be used if the phase detector polarity setting is negative (Bit DB6 $=0$ in Register R3).

## Charge Pump (CP) Current Setting

Bits DB [27:24] set the charge pump current (see Figure 27). Set these bits to the charge pump current that the loop filter is designed with. Best practice is to design the loop filter for a charge pump current of 2.5 mA or 2.81 mA and then use the programmable charge pump current to tweak the frequency response. See the Reference Doubler section for information on setting the charge pump current when the doubler is enabled.

## Prescaler

The dual-modulus prescaler ( $\mathrm{P} / \mathrm{P}+1$ ), along with the INT, FRAC, and fixed modulus values, determines the overall division ratio from $\mathrm{RF}_{\text {IN }}$ to the PFD input. Bit DB22 sets the prescaler value.
Operating at CML levels, the prescaler takes the clock from the RF input stage and divides it down for the counters. The prescaler is based on a synchronous $4 / 5$ core. When the prescaler is set to $4 / 5$, the maximum RF frequency allowed is 8 GHz . Therefore, when operating the ADF4169 at frequencies greater than 8 GHz , the prescaler must be set to $8 / 9$. The prescaler limits the INT value as follows:

- Prescaler $=4 / 5: \mathrm{N}_{\mathrm{MIN}}=23$
- Prescaler $=8 / 9: \mathrm{N}_{\text {MIN }}=75$


## RDIV2

When Bit DB21 is set to 1 , the R divider is enabled and a divide by 2 toggle flip-flop is inserted between the R counter and the PFD. This feature provide a $50 \%$ duty cycle signal at the PFD.

## Reference Doubler

When Bit DB20 is set to 0 , the reference doubler is disabled, and the $\mathrm{REF}_{\text {IN }}$ signal is fed directly to the 5 -bit R counter. When Bit DB20 is set to 1, the reference doubler is enabled, and the $\mathrm{REF}_{\mathbb{N}}$ frequency is multiplied by a factor of 2 before the signal is fed into the 5 -bit R counter. When the doubler is disabled, the $\mathrm{REF}_{\text {IN }}$ falling edge is the active edge at the PFD input to the fractional synthesizer. When the doubler is enabled, both the rising and falling edges of REF IN become active edges at the PFD input.
When the reference doubler is enabled, for optimum phase noise performance, it is recommended to only use charge pump current settings 0 b 0000 to 0 b 0111 , that is, 0.31 mA to 2.5 mA . In this case, best practice is to design the loop filter for a charge pump current of 1.25 mA or 1.57 mA and then use the programmable charge pump current to tweak the frequency response.
For more information on using the reference doubler, see the Clock Register (R4) Map section.

## 5-Bit R Counter

The 5-bit R counter (Bits DB[19:15]) allows the input reference frequency ( $\mathrm{REF}_{\text {IN }}$ ) to be divided down to supply the reference clock to the PFD. Division ratios from 1 to 32 are allowed.

## 12-Bit CLK ${ }_{1}$ Divider Value

Bits $\mathrm{DB}\left[14: 3\right.$ ] program the $\mathrm{CLK}_{1}$ divider value, which determines the duration of the time step in ramp mode.


Figure 27. R Divider Register (R2) Map

## FUNCTION REGISTER (R3) MAP

When Bits DB [2:0] are set to 011, the on-chip function register (Register R3) is programmed (see Figure 28).

## Reserved Bits

All reserved bits except Bit DB17 must be set to 0 for normal operation. Bit DB17 must be set to 1 for normal operation.

## Negative Bleed Current

Bits $\mathrm{DB}[24: 22]$ set the negative bleed current value ( $\mathrm{I}_{\text {BLEED }}$ ). Calculate Ibleed using the following formula, and then select the value of Bits DB [24:22] that is closest to the calculated value.

$$
I_{\text {BLEED }}=\left(4 \times I_{C P}\right) / N
$$

where:
$I_{C P}$ is the charge pump current.
$N$ is the N counter value.

## Negative Bleed Current Enable

DB21 enables a negative bleed current in the charge pump. When the charge pump is operating in a nonlinear region, phase noise and spurious performance can degrade. Negative bleed current operates by pushing the charge pump operation region away from this nonlinear region. The programmability feature controls how far the region of operation is moved. If the current is too little, the charge pump remains in the nonlinear region; if the current is too high, the charge pump becomes unstable or degrades the maximum PFD frequency. It is necessary to experiment with various charge pump currents to find the optimum performance.
The formula for calculating the optimum negative bleed current is shown in the Negative Bleed Current section; however, experimentation may show a different current gives the optimum result.

## Loss of Lock (LOL)

Bit DB16 enables or disables the loss of lock indication. When this bit is set to 0 , the device indicates loss of lock even when the reference is removed. This feature provides an advantage over the standard implementation of lock detect. For more robust operation, set this bit to 1 . The loss of lock does not operate as expected when negative bleed current is enabled.

## N SEL

Bit DB15 can be used to circumvent the issue of pipeline delay between updates of the integer and fractional values in the N counter. Typically, the INT value is loaded first, followed by the FRAC value. This order can cause the N counter value to be incorrect for a brief period of time equal to the pipeline delay (about four PFD cycles). This delay has no effect if the INT value was not updated. However, if the INT value has changed, this incorrect N counter value can cause the PLL to overshoot in frequency while it tries to lock to the temporarily incorrect N counter value. After the correct fractional value is loaded, the PLL quickly locks to the correct frequency. Introducing an additional delay to the loading of the INT value using the N SEL bit causes the INT and FRAC values to be loaded at the same time, preventing frequency overshoot. The delay is turned on by setting Bit DB15 to 1.

## $\Sigma-\Delta$ Reset

For most applications, Bit DB14 is set to 0 . When this bit is set to 0 , the $\Sigma-\Delta$ modulator is reset on each write to Register R0. If it is not required that the $\Sigma-\Delta$ modulator be reset on each write to Register R0, set this bit to 1 .

## Ramp Mode

Bits $\mathrm{DB}[11: 10]$ determine the type of generated waveform (see Figure 28 and the Waveform Generation section).

## PSK Enable

When Bit DB9 is set to 1, PSK modulation is enabled. When this bit is set to 0 , PSK modulation is disabled. For more information, see the Phase Shift Keying section.

## FSK Enable

When Bit DB8 is set to 1 , FSK modulation is enabled. When this bit is set to 0 , FSK modulation is disabled. For more information, see the Frequency Shift Keying section.

## Lock Detect Precision (LDP)

The digital lock detect circuit monitors the PFD up and down pulses (logical OR of the up and down pulses; see Figure 21). Every $32^{\text {nd }}$ pulse is measured. The LDP bit (Bit DB7) specifies the length of each lock detect reference cycle.

- $\quad \operatorname{LDP}=0$ : if five consecutive pulses of less than 14 ns are measured, digital lock detect is asserted.
- $\operatorname{LDP}=1$ : if five consecutive pulses of less than 6 ns are measured, digital lock detect is asserted.

Digital lock detect remains asserted until the pulse width exceeds 22 ns , a write to Register R0 occurs, or the device is powered down. For more robust operation, set LDP $=1$.

## Phase Detector (PD) Polarity

Bit DB6 sets the phase detector polarity. When the VCO characteristics are positive, set this bit to 1 . When the VCO characteristics are negative, set this bit to 0 .

## Power-Down

Bit DB5 provides the programmable power-down mode. Setting this bit to 1 performs a power-down. Setting this bit to 0 returns the synthesizer to normal operation. When the device is in software power-down mode, it retains all information in its registers. The register contents are lost only when the supplies are removed.
When power-down is activated, the following events occur:

- All active dc current paths are removed.
- The RF synthesizer counters are forced to their load state conditions.
- The charge pump is forced into three-state mode.
- The digital lock detect circuitry is reset.
- The $\mathrm{RF}_{\text {IN }}$ input is debiased.
- The input shift register remains active and capable of loading and latching data.


## Charge Pump Three-State

When Bit DB4 is set to 1 , the charge pump is placed into threestate mode. For normal charge pump operation, set this bit to 0 .

## RF Counter Reset

Bit DB3 is the RF counter reset bit. When this bit is set to 1 , the RF synthesizer counters are held in reset. For normal operation, set this bit to 0 .


Figure 28. Function Register (R3) Map

## CLOCK REGISTER (R4) MAP

When Bits DB[2:0] are set to 100, the on-chip clock register (Register R4) is programmed (see Figure 29).

If the reference doubler ( $\mathrm{R} 2, \mathrm{DB} 20$ ) is enabled, the last write to R4 must have the ramp status ( DB [25:21]) set to 0b11000.
To use the ramp complete to MUXOUT ramp status with the reference doubler enabled, two writes to R 4 are required:

1. Program Register R4 with the ramp status $=0 b 00011$, followed by Step 2
2. Program Register R4 with the ramp status $=0 \mathrm{~b} 11000$.

## LE SEL

In some applications, it is necessary to synchronize the LE pin with the reference signal. To do this, Bit DB31 must be set to 1 . Synchronization is performed internally on the device.

## $\boldsymbol{\Sigma}-\Delta$ Modulator Mode

To completely disable the $\Sigma-\Delta$ modulator, set Bits DB[30:26] to 0b01110, which disables the $\Sigma-\Delta$ modulator and puts the ADF4169 into integer-N mode, and the channel spacing becomes equal to the PFD frequency. Both the 12-bit MSB fractional value (Register R0, $\mathrm{DB}[14: 3]$ ) and the 13-bit LSB fractional value (Register R1, DB[27:15]) must be set to 0 . After writing to Register R4, Register R3 must be written to twice, to trigger an RF counter reset. (That is, write Register R3 with Bit DB3 $=1$, then write Register R3 with Bit DB3 $=0$.)
All features driven by the $\Sigma-\Delta$ modulator are disabled, such as ramping, PSK, FSK, and phase adjust.
Disabling the $\Sigma-\Delta$ modulator also removes the fixed $+\left(\mathrm{f}_{\mathrm{PFD}} / 2^{26}\right)$ offset on the VCO output.
For normal operation, set these bits to 0 b 00000 .

## Ramp Status

Bits $\mathrm{DB}[25: 21]$ provide access to the following advanced features (see Figure 29):

- Readback to MUXOUT option: the synthesizer frequency at the moment of interruption can be read back (see the Interrupt Modes and Frequency Readback section).
- Ramp complete to MUXOUT option: a logic high pulse is output on the MUXOUT pin at the end of each ramp.
- Charge pump up and charge pump down options: the charge pump is forced to constantly output up or down pulses, respectively.
When using the readback to MUXOUT or ramp complete to MUXOUT option, the MUXOUT control bits in Register R0 (Bits $\mathrm{DB}[30: 27]$ ) must be set to 1111 .


## Clock Divider Mode

Bits DB[20:19] enable ramp divider mode or fast lock divider mode. If neither is being used, set these bits to 0b00.

## 12-Bit CLK ${ }_{2}$ Divider Value

Bits DB [18:7] program the clock divider (the $\mathrm{CLK}_{2}$ timer) when the device operates in ramp mode (see the Timeout Interval section). The $\mathrm{CLK}_{2}$ timer also determines how long the loop remains in wideband mode when fast lock mode is used (see the Fast Lock Mode section).

## Clock Divider Select

When Bit DB6 is set to $0, \mathrm{CLK}_{2}$ is used as the $\mathrm{CLK}_{2}$ value for a standard ramp, such as sawtooth or triangular. When Bit DB6 is set to $1, \mathrm{CLK}_{2}$ is used as the $\mathrm{CLK}_{2}$ value for the second ramp of the fast ramp or dual ramp functions. For more information, see the Waveform Deviations and Timing section.

## Reserved Bits

All reserved bits ( $\mathrm{DB}[5: 3]$ ) must be set to 0 for normal operation.


Figure 29. Clock Register (R4) Map

## DEVIATION REGISTER (R5) MAP

When Bits DB [2:0] are set to 101, the on-chip deviation register (Register R5) is programmed (see Figure 30).

## Reserved Bit

The reserved bit must be set to 0 for normal operation.

## TX $\boldsymbol{X}_{\text {DATA }}$ Invert

When Bit DB30 is set to 0 , events triggered by TX DATA occur on the rising edge of the TX Data pulse. When Bit DB30 is set to 1 , events triggered by TX ${ }_{\text {DATA }}$ occur on the falling edge of the TX ${ }_{\text {data }}$ pulse.

## TX DATA Ramp Clock (CLK)

When Bit DB29 is set to 0 , the clock divider clock is used to clock the ramp. When Bit DB29 is set to 1, the TX DATA clock is used to clock the ramp.

## Interrupt

Bits DB [27:26] determine which type of interrupt is used. This feature is used for reading back the INT and FRAC value of a ramp at a given moment in time (a rising edge on the TX $\mathrm{XATA}^{\text {pin }}$ triggers the interrupt). From the INT and FRAC bits, the frequency can be obtained. After readback, the sweep can continue or stop at the readback frequency. For more information, see the Interrupt Modes and Frequency Readback section.

## FSK Ramp Enable

When Bit DB25 is set to 1, the FSK ramp is enabled. When Bit DB25 is set to 0 , the FSK ramp is disabled.

## Dual Ramp Enable

When Bit DB24 is set to 1 , the second ramp is enabled. When Bit DB24 is set to 0 , the second ramp is disabled.

## Deviation Select (DEV SEL)

When Bit DB23 is set to 0 , the first deviation word is selected. When Bit DB23 is set to 1 , the second deviation word is selected.

## 4-Bit Deviation Offset Word

Bits $\mathrm{DB}[22: 19]$ determine the deviation offset word (DEV_OFFSET). The deviation offset word affects the deviation resolution.

## 16-Bit Deviation Word

Bits $\mathrm{DB}[18: 3]$ determine the signed deviation word. The deviation word defines the deviation step.


Figure 30. Deviation Register (R5) Map

## STEP REGISTER (R6) MAP

When Bits DB[2:0] are set to 110, the on-chip step register (Register R6) is programmed (see Figure 31).

## Reserved Bits

All reserved bits must be set to 0 for normal operation.

## Step Select

When Bit DB23 is set to 0 , Step Word 1 is selected. When Bit DB23 is set to 1, Step Word 2 is selected.

## 20-Bit Step Word

Bits $\mathrm{DB}[22: 3$ ] determine the step word. The step word is the number of steps in the ramp.


Figure 31. Step Register (R6) Map

## DELAY REGISTER (R7) MAP

When Bits DB [2:0] are set to 111, the on-chip delay register (Register R7) is programmed (see Figure 32).

## Reserved Bits

All reserved bits must be set to 0 for normal operation.

## TX $X_{\text {DATA }}$ Trigger Delay

When Bit DB23 is set to 0 , there is no delay before the start of the ramp when using TX DATA to trigger a ramp. When Bit DB23 is set to 1 , a delay is enabled before the start of the ramp if the delayed start is enabled via Bit DB15.

## Triangular (TRI) Delay

When Bit DB22 is set to 1, a delay is enabled between each section of a triangular ramp, resulting in a clipped ramp. This setting works only for triangular ramps and when the ramp delay is activated. When Bit DB22 is set to 0 , the delay between triangular ramps is disabled.

## Single Full Triangle

When Bit DB21 is set to 1 , the single full triangle function is enabled. When Bit DB21 is set to 0 , the single full triangle function is disabled. For more information, see the Waveform Generation section.

## Fast Ramp

When Bit DB19 is set to 1 , the triangular waveform is activated with two different slopes. This waveform can be used as an alternative to the sawtooth ramp because it mitigates the overshoot at the end of the ramp in a waveform. Fast ramp is achieved by changing the top frequency to the bottom frequency in a series of small steps instead of one big step. When Bit DB19 is set to 0 , the fast ramp function is disabled (see the Fast Ramp Mode section).

## Ramp Delay

When Bit DB17 is set to 1 , the delay between ramps function is enabled. When Bit DB17 is set to 0, this function is disabled.

## Delay Clock Select (DEL CLK SEL)

When Bit DB16 is set to 0 , the PFD CLK is selected as the delay clock. When Bit DB16 is set to $1, \mathrm{PFD}$ CLK $\times \mathrm{CLK}_{1}$ is selected as the delay clock. ( $\mathrm{CLK}_{1}$ is set by Bits DB [14:3] in Register R2.)

## Delayed Start Enable (DEL START EN)

When Bit DB15 is set to 1, the delayed start is enabled. When Bit DB15 is set to 0 , the delayed start is disabled.

## 12-Bit Delay Start Word

Bits $\mathrm{DB}[14: 3$ ] determine the delay start word. The delay start word affects the duration of the ramp start delay.

## $T X_{\text {DAtA }}$ Trigger

When Bit DB20 is set to 1 , a logic high on TX DAta activates the ramp. When Bit DB20 is set to 0 , this function is disabled.


Figure 32. Delay Register ( $R 7$ ) Map


[^0]:    ${ }^{1} t_{\text {PFD }}$ is the period of the PFD frequency; for example, if the PFD frequency is $50 \mathrm{MHz}, \mathrm{t}_{\text {PFD }}=20 \mathrm{~ns}$.

