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## FEATURES

- Ultralow power (scales automatically with data rate)**
  - As low as 30  $\mu\text{A}$  in measurement mode ( $V_S = 3.3\text{ V}$ )
  - As low as 0.1  $\mu\text{A}$  in standby mode ( $V_S = 3.3\text{ V}$ )
- Low noise performance**
  - 150  $\mu\text{g}/\sqrt{\text{Hz}}$  typical for X- and Y-axes
  - 250  $\mu\text{g}/\sqrt{\text{Hz}}$  typical for the Z-axis
- Embedded, patent pending FIFO technology minimizes host processor load**
- User-selectable resolution**
  - Fixed 10-bit resolution for any  $g$  range
  - Fixed 1024 LSB/ $g$  sensitivity for any  $g$  range
  - Resolution scales from 10-bit at  $\pm 0.5\text{ g}$  to 13-bit at  $\pm 4\text{ g}$
- Built-in motion detection functions for activity/inactivity monitoring**
- Supply and I/O voltage range: 2.0 V to 3.6 V**
- SPI (3-wire and 4-wire) and I<sup>2</sup>C digital interfaces**
- Flexible interrupt modes mappable to two interrupt pins**
- Measurement range selectable via serial command**
- Bandwidth selectable via serial command**
- Wide temperature range ( $-40^\circ\text{C}$  to  $+105^\circ\text{C}$ )**
- 10,000  $g$  shock survival**
- Pb free/RoHS compliant**
- Small and thin: 5 mm  $\times$  5 mm  $\times$  1.45 mm LFCSP package**
- Qualified for automotive applications**

## APPLICATIONS

- Car alarms
- Hill start aid (HSA) systems
- Electronic parking brakes
- Data recorders (black boxes)

## GENERAL DESCRIPTION

The **ADXL313** is a small, thin, low power, 3-axis accelerometer with high resolution (13-bit) measurement up to  $\pm 4\text{ g}$ . Digital output data is formatted as 16-bit twos complement and is accessible through either a serial port interface (SPI) (3-wire or 4-wire) or I<sup>2</sup>C digital interface.

The **ADXL313** is well suited for car alarm or black box applications. It measures the static acceleration of gravity in tilt-sensing applications, as well as dynamic acceleration resulting from motion or shock. Its high resolution (1024 LSB/ $g$ ) and low noise (150  $\mu\text{g}/\sqrt{\text{Hz}}$ ) enable resolution of inclination changes of as little as  $0.1^\circ$ . A built-in FIFO facilitates using oversampling techniques to improve resolution to as little as  $0.025^\circ$  of inclination.

Several built-in sensing functions are provided. Activity and inactivity sensing detects the presence or absence of motion and whether the acceleration on any axis exceeds a user-set level. These functions can be mapped to interrupt output pins. An integrated 32-level FIFO can be used to store data to minimize host processor intervention, resulting in reduced system power consumption.

Low power modes enable intelligent motion-based power management with threshold sensing and active acceleration measurement at extremely low power dissipation.

The **ADXL313** is supplied in a small, thin 5 mm  $\times$  5 mm  $\times$  1.45 mm, 32-lead LFCSP package and is pin compatible with the **ADXL312** accelerometer device.

## FUNCTIONAL BLOCK DIAGRAM

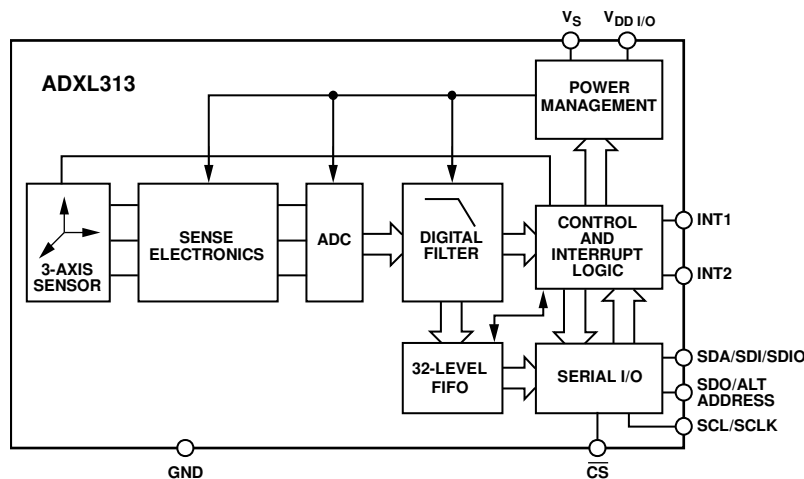


Figure 1.

Rev. B

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Last Content Update: 02/23/2017

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## COMPARABLE PARTS

View a parametric search of comparable parts.

## EVALUATION KITS

- ADXL313 Evaluation Board
- Real Time Eval System for Digital Output Sensor

## DOCUMENTATION

### Data Sheet

- ADXL313: 3-Axis,  $\pm 0.5$  g/ $\pm 1$  g/ $\pm 2$  g/ $\pm 4$  g Digital Accelerometer Data Sheet

## DESIGN RESOURCES

- ADXL313 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

## DISCUSSIONS

View all ADXL313 EngineerZone Discussions.

## SAMPLE AND BUY

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## TABLE OF CONTENTS

Features .....	1	FIFO .....	15
Applications .....	1	Self Test .....	16
General Description .....	1	Register Map .....	17
Functional Block Diagram .....	1	Register Definitions .....	18
Revision History .....	2	Applications Information .....	22
Specifications .....	3	Power Supply Decoupling .....	22
Absolute Maximum Ratings .....	4	Mechanical Considerations for Mounting .....	22
Thermal Resistance .....	4	Threshold .....	22
ESD Caution .....	4	Link Mode .....	22
Pin Configuration and Function Descriptions .....	5	Sleep Mode vs. Low Power Mode .....	22
Typical Performance Characteristics .....	6	Using Self Test .....	23
Theory of Operation .....	8	3200 Hz and 1600 Hz ODR Data Formatting .....	24
Power Sequencing .....	8	Axes of Acceleration Sensitivity .....	25
Power Savings .....	8	Solder Profile .....	26
Serial Communications .....	10	Outline Dimensions .....	27
SPI .....	10	Ordering Guide .....	28
I <sup>2</sup> C .....	13	Automotive Products .....	28
Interrupts .....	15		

## REVISION HISTORY

### 11/15—Rev. A to Rev. B

Change to Register 0x02, Table 14 .....	17
Changes to Register 0x02—PARTID (Read Only) Section .....	18
Change to Preheat Time (T <sub>SMIN</sub> to T <sub>SMAX</sub> ) (t <sub>s</sub> ) Parameter, Table 20 .....	26

### 11/13—Rev. 0 to Rev. A

Changes to Figure 3, Figure 4, and Figure 5 .....	6
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### 4/13—Revision 0: Initial Version

## SPECIFICATIONS

$T_A = -40^\circ\text{C}$  to  $+105^\circ\text{C}$ ,  $V_S = V_{DD I/O} = 3.3\text{ V}$ , acceleration = 0 g, unless otherwise noted.

Table 1.

Parameter <sup>1</sup>	Test Conditions/Comments	Min	Typ	Max	Unit
SENSOR INPUT	Each axis				
Measurement Range	User selectable		$\pm 0.5, \pm 1, \pm 2, \pm 4$		g
Nonlinearity	Percentage of full scale		$\pm 0.5$		%
Micro-Nonlinearity	Measured over any 50 mg interval		$\pm 2$		%
Interaxis Alignment Error			$\pm 0.1$		Degrees
Cross-Axis Sensitivity <sup>2</sup>			$\pm 1$		%
OUTPUT RESOLUTION	Each axis				
All g Ranges	Default resolution		10		Bits
$\pm 0.5\text{ g}$ Range	Full resolution enabled		10		Bits
$\pm 1\text{ g}$ Range	Full resolution enabled		11		Bits
$\pm 2\text{ g}$ Range	Full resolution enabled		12		Bits
$\pm 4\text{ g}$ Range	Full resolution enabled		13		Bits
SENSITIVITY	Each axis				
Sensitivity at $X_{OUT}, Y_{OUT}, Z_{OUT}$	Any g-range, full resolution mode		1024		LSB/g
	$\pm 0.5\text{ g}$ , 10-bit or full resolution	921	1024	1126	LSB/g
	$\pm 1\text{ g}$ , 10-bit resolution	460	512	563	LSB/g
	$\pm 2\text{ g}$ , 10-bit resolution	230	256	282	LSB/g
	$\pm 4\text{ g}$ , 10-bit resolution	115	128	141	LSB/g
Sensitivity Change Due to Temperature			$\pm 0.01$		%/°C
0 g BIAS LEVEL	Each axis				
Initial 0 g Output	$T = 25^\circ\text{C}, X_{OUT}, Y_{OUT}$		$\pm 50$		mg
	$T = 25^\circ\text{C}, Z_{OUT}$		$\pm 75$		mg
0 g Output Drift over Temperature	$-40^\circ\text{C} < T < +105^\circ\text{C}, X_{OUT}, Y_{OUT}$ , referenced to initial 0 g output	-125		+125	mg
	$-40^\circ\text{C} < T < +105^\circ\text{C}, Z_{OUT}$ , referenced to initial 0 g output	-200		+200	mg
0 g Offset Tempco	$X_{OUT}, Y_{OUT}$		$\pm 0.5$		mg/°C
	$Z_{OUT}$		$\pm 0.75$		mg/°C
NOISE PERFORMANCE					
Noise Density	X-, Y-axes		150		$\mu\text{g}/\sqrt{\text{Hz}}$
	Z-axis		250		$\mu\text{g}/\sqrt{\text{Hz}}$
RMS Noise	X-, Y-axes, 100 Hz output data rate (ODR)		1.5		mg rms
	Z-axis, 100 Hz ODR		2.5		mg rms
OUTPUT DATA RATE/BANDWIDTH	User selectable				
Measurement Rate <sup>3</sup>		6.25		3200	Hz
SELF TEST <sup>4</sup>	Data rate $\geq 100\text{ Hz}$ , $2.0\text{ V} \leq V_S \leq 3.6\text{ V}$				
Output Change in X-Axis		0.20		2.36	g
Output Change in Y-Axis		-2.36		-0.20	g
Output Change in Z-Axis		0.30		3.70	g
POWER SUPPLY					
Operating Voltage Range ( $V_S$ )		2.0		3.6	V
Interface Voltage Range ( $V_{DD I/O}$ )		1.7		$V_S$	V
Supply Current	Data rate $> 100\text{ Hz}$	100	170	300	$\mu\text{A}$
	Data rate $< 10\text{ Hz}$	30	55	110	$\mu\text{A}$
Standby Mode Leakage Current			0.1	2	$\mu\text{A}$
Turn-On (Wake-Up) Time <sup>5</sup>			1.4		ms
TEMPERATURE					
Operating Temperature Range		-40		+105	°C

<sup>1</sup> All minimum and maximum specifications are guaranteed. Typical specifications are not guaranteed.

<sup>2</sup> Cross-axis sensitivity is defined as coupling between any two axes.

<sup>3</sup> Bandwidth is half the output data rate.

<sup>4</sup> Self test change is defined as the output (g) when the SELF\_TEST bit = 1 (in the DATA\_FORMAT register, Address 0x31) minus the output (g) when the SELF\_TEST bit = 0 (in the DATA\_FORMAT register). Due to device filtering, the output reaches its final value after  $4 \times \tau$  when enabling or disabling self test, where  $\tau = 1/(\text{data rate})$ .

<sup>5</sup> Turn-on and wake-up times are determined by the user-defined bandwidth. At a 100 Hz data rate, the turn-on and wake-up times are each approximately 11.1 ms. For other data rates, the turn-on and wake-up times are each approximately  $\tau + 1.1$  in milliseconds, where  $\tau = 1/(\text{data rate})$ .

## ABSOLUTE MAXIMUM RATINGS

Table 2.

Parameter	Rating
Acceleration	
Any Axis, Unpowered	10,000 <i>g</i>
Any Axis, Powered	10,000 <i>g</i>
$V_S$	-0.3 V to +3.9 V
$V_{DD/I/O}$	-0.3 V to +3.9 V
All Other Pins	-0.3 V to $V_{DD/I/O} + 0.3$ V or 3.9 V, whichever is less
Output Short-Circuit Duration (Any Pin to Ground)	Indefinite
Temperature Range	
Powered	-40°C to +125°C
Storage	-40°C to +125°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 3. Thermal Resistance

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit
32-Lead LFCSP Package	27.27	30	°C/W

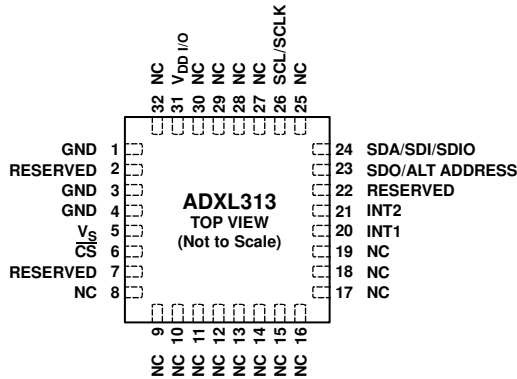
## ESD CAUTION



### ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



- NOTES
1. NC = NO CONNECT. DO NOT CONNECT TO THIS PIN.
  2. THE EXPOSED PAD MUST BE SOLDERED TO THE GROUND PLANE.

11-469-002

Figure 2. Pin Configuration

Table 4. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	GND	This pin must be connected to ground.
2	RESERVED	Reserved. This pin must be connected to $V_S$ or left open.
3	GND	This pin must be connected to ground.
4	GND	This pin must be connected to ground.
5	$V_S$	Supply Voltage.
6	$\overline{CS}$	Chip Select.
7	RESERVED	Reserved. This pin must be left open.
8 to 19	NC	No Connect. Do not connect to this pin.
20	INT1	Interrupt 1 Output.
21	INT2	Interrupt 2 Output.
22	RESERVED	Reserved. This pin must be connected to GND or left open.
23	SDO/ALT ADDRESS	Serial Data Output/Alternate I <sup>2</sup> C Address Select.
24	SDA/SDI/SDIO	Serial Data (I <sup>2</sup> C)/Serial Data Input (SPI 4-Wire)/Serial Data Input/Output (SPI 3-Wire).
25	NC	No Connect. Do not connect to this pin.
26	SCL/SCLK	I <sup>2</sup> C Serial Communications Clock/SPI Serial Communications Clock.
27 to 30	NC	No Connect. Do not connect to this pin.
31	$V_{DD I/O}$	Digital Interface Supply Voltage.
32	NC	No Connect. Do not connect to this pin.
	EP	Exposed Pad. The exposed pad must be soldered to the ground plane.

TYPICAL PERFORMANCE CHARACTERISTICS

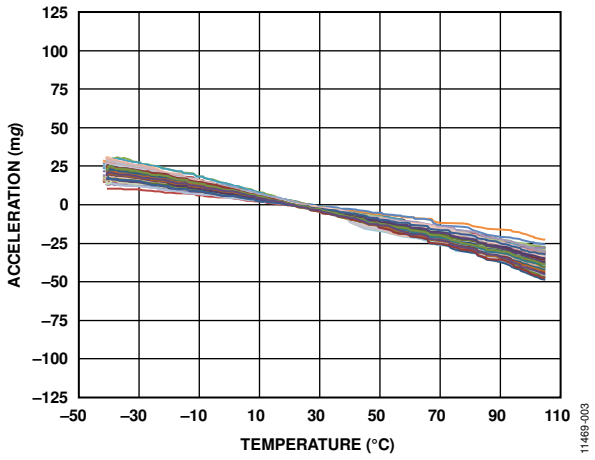


Figure 3. X-Axis Acceleration vs. Temperature, Three Lots (N = 80)

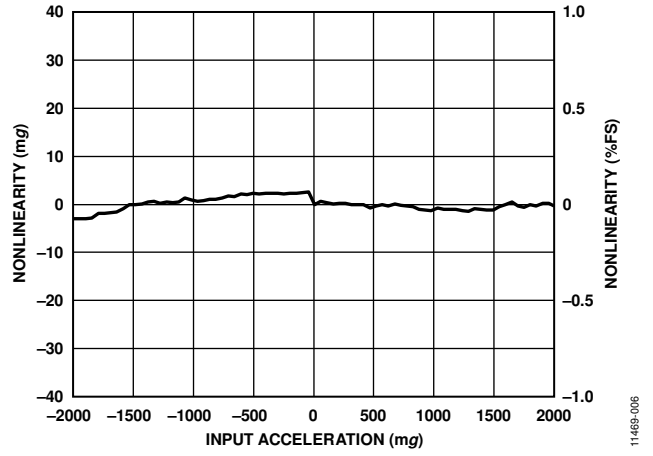


Figure 6. X-Axis Nonlinearity,  $\pm 2$  g Input Range

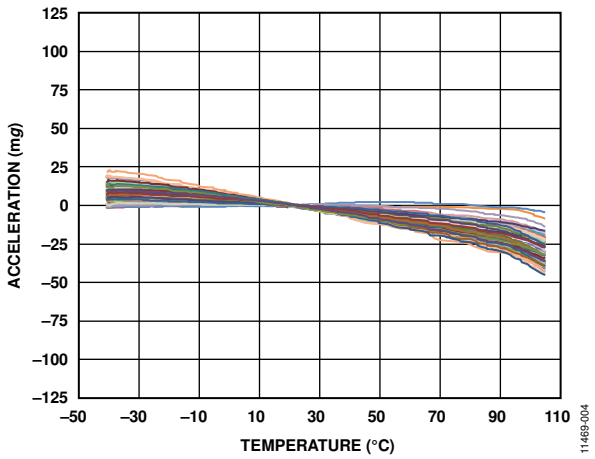


Figure 4. Y-Axis Acceleration vs. Temperature, Three Lots (N = 80)

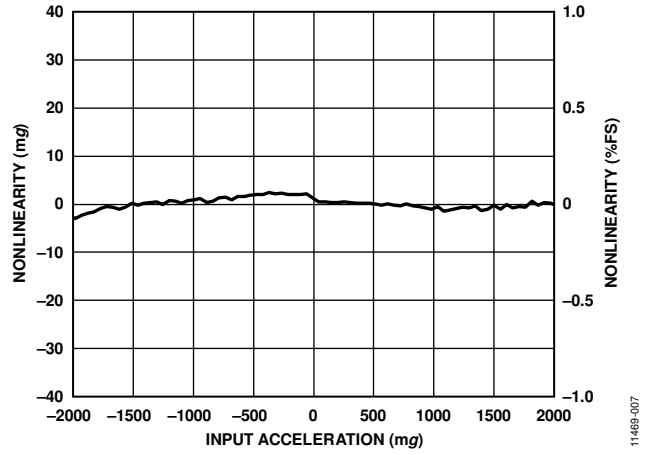


Figure 7. Y-Axis Nonlinearity,  $\pm 2$  g Input Range

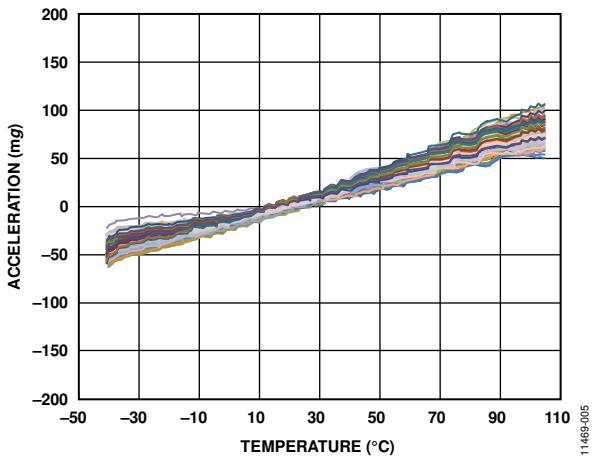


Figure 5. Z-Axis Acceleration vs. Temperature, Three Lots (N = 80)

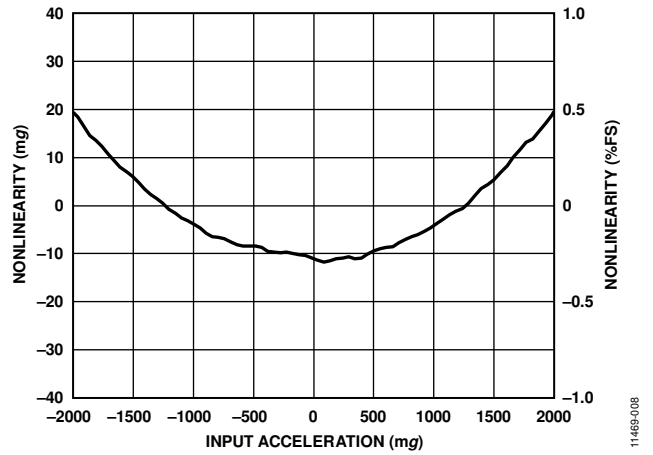


Figure 8. Z-Axis Nonlinearity,  $\pm 2$  g Input Range



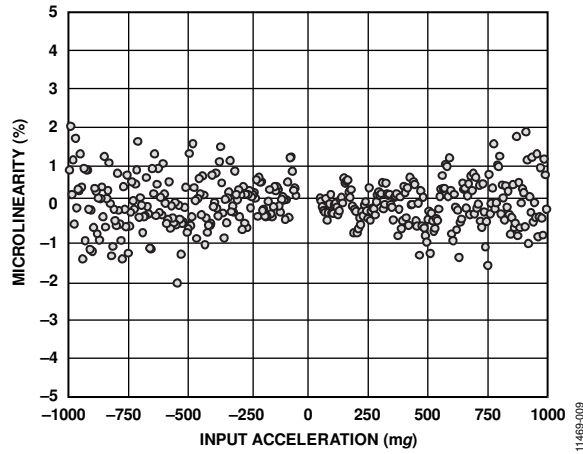


Figure 9. X-Axis Microlinearity, 50 mg Step Size

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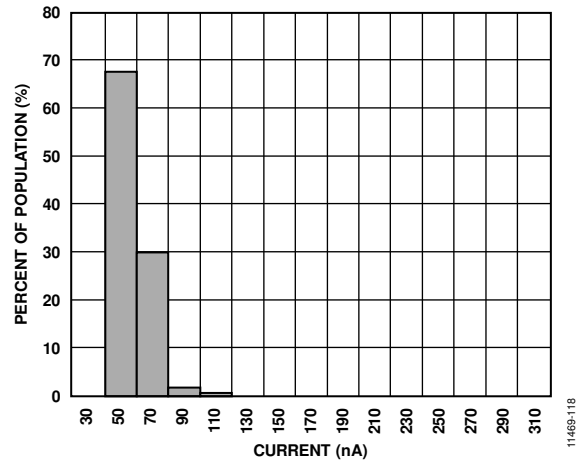


Figure 12. Standby Mode Current Consumption,  $V_S = V_{DD/IO} = 3.3\text{ V}$ ,  $25^\circ\text{C}$

11469-118

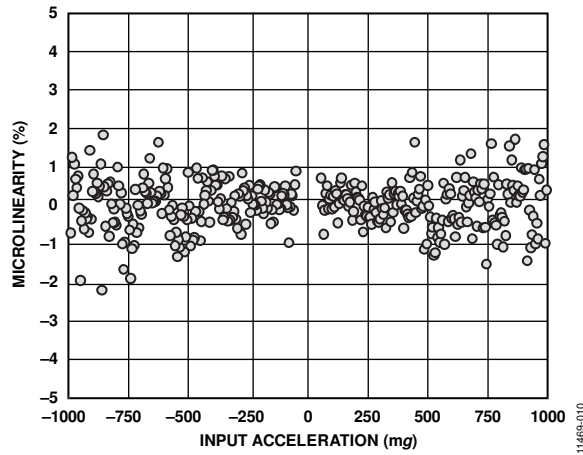


Figure 10. Y-Axis Microlinearity, 50 mg Step Size

11469-010

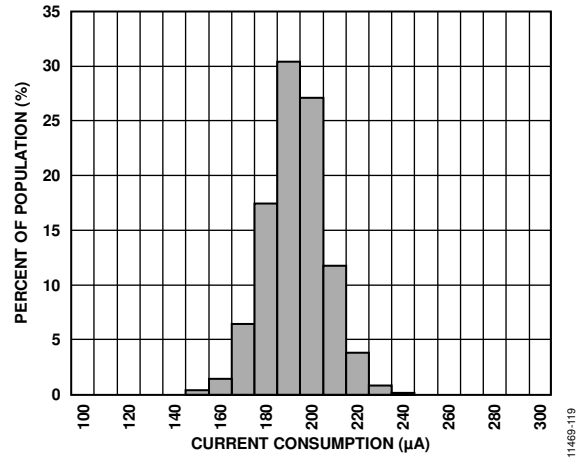


Figure 13. Current Consumption, Measurement Mode, Data Rate = 100 Hz,  $V_S = V_{DD/IO} = 3.3\text{ V}$ ,  $25^\circ\text{C}$

11469-119

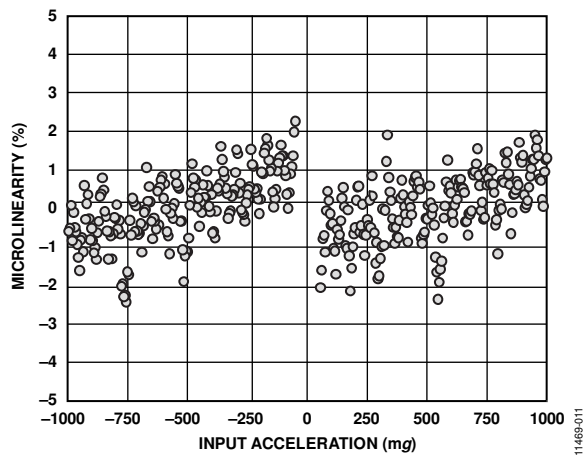


Figure 11. Z-Axis Microlinearity, 50 mg Step Size

11469-011

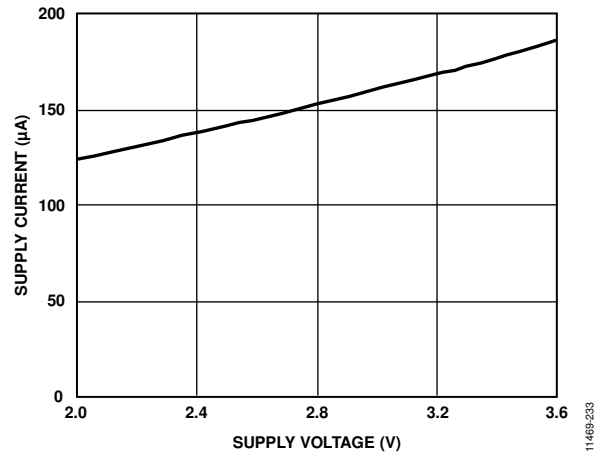


Figure 14. Supply Current vs. Supply Voltage,  $V_S$  at  $25^\circ\text{C}$

11469-233

## THEORY OF OPERATION

The ADXL313 is a complete 3-axis acceleration measurement system with a selectable measurement range of  $\pm 0.5 g$ ,  $\pm 1 g$ ,  $\pm 2 g$ , or  $\pm 4 g$ . It measures both dynamic acceleration resulting from motion or shock and static acceleration, such as gravity, which allows it to be used as a tilt sensor.

The sensor is a polysilicon surface-micromachined structure built on top of a silicon wafer. Polysilicon springs suspend the structure over the surface of the wafer and provide a resistance against acceleration forces.

Deflection of the structure is measured using differential capacitors that consist of independent fixed plates and plates attached to the moving mass. Acceleration deflects the beam and unbalances the differential capacitor, resulting in a sensor output whose amplitude is proportional to acceleration. Phase-sensitive demodulation is used to determine the magnitude and polarity of the acceleration.

### POWER SEQUENCING

Power can be applied to  $V_S$  or  $V_{DD I/O}$  in any sequence without damaging the ADXL313. All possible power-on modes are summarized in Table 5. The interface voltage level is set with the interface supply voltage,  $V_{DD I/O}$ , which must be present to ensure that the ADXL313 does not create a conflict on the communication bus. For single-supply operation,  $V_{DD I/O}$  can be the same as the main supply,  $V_S$ . In a dual-supply application, however,  $V_{DD I/O}$  can differ from  $V_S$  to accommodate the desired interface voltage, as long as  $V_S$  is greater than or equal to  $V_{DD I/O}$ .

After  $V_S$  is applied, the device enters standby mode, where power consumption is minimized and the device waits for  $V_{DD I/O}$  to be applied and for the command to enter measurement mode to be received. (This command can be initiated by setting the measure bit in the POWER\_CTL register (Address 0x2D).) In addition, any register can be written to or read from to configure the part while the device is in standby mode. It is recommended that the device be configured in standby mode before measurement mode is enabled. Clearing the measure bit returns the device to the standby mode.

Table 7. Power Sequencing

Condition	$V_S$	$V_{DD I/O}$	Description
Power Off	Off	Off	The device is completely off, but there is a potential for a communication bus conflict.
Bus Disabled	On	Off	The device is on in standby mode, but communication is unavailable, and the device creates a conflict on the communication bus. Minimize the duration of this state during power-up to prevent a conflict.
Bus Enabled	Off	On	No functions are available, but the device does not create a conflict on the communication bus.
Standby or Measurement	On	On	The device is in standby mode, awaiting a command to enter measurement mode, and all sensor functions are off. After the device is instructed to enter measurement mode, all sensor functions are available.

## POWER SAVINGS

### Power Modes

The ADXL313 automatically modulates its power consumption in proportion to its output data rate, as outlined in Table 5. If additional power savings are desired, a lower power mode is available. In this mode, the internal sampling rate is reduced, allowing for power savings in the 12.5 Hz to 400 Hz data rate range at the expense of slightly greater noise. To enter low power mode, set the LOW\_POWER bit (Bit 4) in the BW\_RATE register (Address 0x2C). The current consumption in low power mode is shown in Table 6 for cases where there is an advantage to using low power mode. Use of low power mode for a data rate not shown in Table 6 does not provide any advantage over the same data rate in normal power mode. Therefore, it is recommended that only data rates shown in Table 6 be used in low power mode. The current consumption values shown in Table 5 and Table 6 are for a  $V_S$  of 3.3 V.

Table 5. Current Consumption vs. Data Rate  
( $T_A = 25^\circ C$ ,  $V_S = V_{DD I/O} = 3.3 V$ )

Output Data Rate (Hz)	Bandwidth (Hz)	Rate Code	$I_{DD}$ ( $\mu A$ )
3200	1600	1111	170
1600	800	1110	115
800	400	1101	170
400	200	1100	170
200	100	1011	170
100	50	1010	170
50	25	1001	115
25	12.5	1000	82
12.5	6.25	0111	65
6.25	3.125	0110	57

Table 6. Current Consumption vs. Data Rate, Low Power Mode  
( $T_A = 25^\circ C$ ,  $V_S = V_{DD I/O} = 3.3 V$ )

Output Data Rate (Hz)	Bandwidth (Hz)	Rate Code	$I_{DD}$ ( $\mu A$ )
400	200	1100	115
200	100	1011	82
100	50	1010	65
50	25	1001	57
25	12.5	1000	50
12.5	6.25	0111	43

**Autosleep Mode**

Additional power savings can be obtained by having the [ADXL313](#) automatically switch to sleep mode during periods of inactivity. To enable this feature, set the THRESH\_INACT register (Address 0x25) to an acceleration threshold value. Levels of acceleration below this threshold are regarded as no activity. Set TIME\_INACT (Address 0x26) to an appropriate inactivity time period. Then set the AUTO\_SLEEP bit and the link bit in the POWER\_CTL register (Address 0x2D). If the device does not detect a level of acceleration in excess of THRESH\_INACT for TIME\_INACT seconds, the device is transitioned to sleep mode automatically. Current consumption at less than 10 Hz data rates used in this mode is typically 55  $\mu$ A for a  $V_s$  of 3.3 V.

**Standby Mode**

For even lower power operation, standby mode can be used. In standby mode, current consumption is reduced to 0.1  $\mu$ A (typical). In this mode, no measurements are made. Standby mode is entered by clearing the measure bit (Bit 3) in the POWER\_CTL register (Address 0x2D). Placing the device into standby mode preserves the contents of the FIFO.

## SERIAL COMMUNICATIONS

I<sup>2</sup>C and SPI digital communications are available. In both cases, the ADXL313 operates as a slave. I<sup>2</sup>C mode is enabled if the  $\overline{CS}$  pin is tied high to  $V_{DD I/O}$ . The  $\overline{CS}$  pin must always be tied high to  $V_{DD I/O}$  or be driven by an external controller because there is no default mode if the  $\overline{CS}$  pin is left unconnected. Therefore, not taking these precautions may result in an inability to communicate with the part. In SPI mode, the  $\overline{CS}$  pin is controlled by the bus master. In both SPI and I<sup>2</sup>C modes of operation, ignore data transmitted from the ADXL313 to the master device during writes to the ADXL313.

### SPI

For SPI communication, either 3- or 4-wire configuration is possible, as shown in the connection diagrams in Figure 15 and Figure 16. Clearing the SPI bit in the DATA\_FORMAT register (Address 0x31) selects 4-wire mode, whereas setting the SPI bit selects 3-wire mode. The maximum SPI clock speed is 5 MHz with 100 pF maximum loading, and the timing scheme follows clock polarity (CPOL) = 1 and clock phase (CPHA) = 1. If power is applied to the ADXL313 before the clock polarity and phase of the host processor are configured, the  $\overline{CS}$  pin must be brought high before changing the clock polarity and phase. When using the 3-wire SPI configuration, it is recommended that the SDO pin be either pulled up to  $V_{DD I/O}$  or pulled down to GND via a 10 k $\Omega$  resistor.

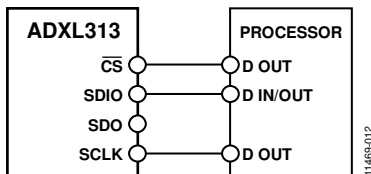


Figure 15. 3-Wire SPI Connection Diagram

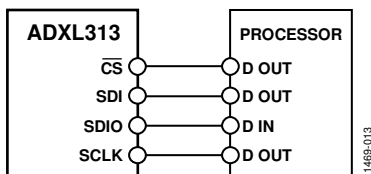


Figure 16. 4-Wire SPI Connection Diagram

$\overline{CS}$  is the serial port enable line and is controlled by the SPI master. This line must go low at the start of a transmission and high at the end of a transmission, as shown in Figure 17 to Figure 19. SCLK is the serial port clock and is supplied by the SPI master. SCLK idles high during a period of no transmission. SDI and SDO are the serial data input and output, respectively. Data is updated on the falling edge of SCLK and sampled on the rising edge of SCLK.

To read or write multiple bytes in a single transmission, the multiple-byte bit, located after the R/W bit in the first byte transfer (MB in Figure 17 to Figure 19), must be set. After the register addressing and the first byte of data, each subsequent set of clock pulses (eight clock pulses) causes the ADXL313 to point to the next register for a read or write. This shifting continues until the clock pulses cease and  $\overline{CS}$  is deasserted. To perform reads or writes on different, nonsequential registers,  $\overline{CS}$  must be deasserted between transmissions, and the new register must be addressed separately.

The timing diagram for 3-wire SPI reads or writes is shown in Figure 17. The 4-wire equivalents for SPI reads and writes are shown in Figure 18 and Figure 19, respectively. For correct operation of the part, the logic thresholds and timing parameters in Table 8 and Table 9 must be met at all times.

Use of the 3200 Hz and 1600 Hz output data rates is recommended only with SPI communication rates greater than or equal to 2 MHz. The 800 Hz output data rate is recommended only for communication speeds greater than or equal to 400 kHz, and the remaining data rates scale proportionally. For example, the minimum recommended communication speed for a 200 Hz output data rate is 100 kHz. Operation at an output data rate below the recommended minimum may result in undesirable effects on the acceleration data, including missing samples or additional noise.

Table 8. SPI Digital Input/Output

Parameter	Test Conditions/Comments	Limit <sup>1</sup>		Unit
		Min	Max	
Digital Input				
Low Level Input Voltage ( $V_{IL}$ )			$0.3 \times V_{DD I/O}$	V
High Level Input Voltage ( $V_{IH}$ )		$0.7 \times V_{DD I/O}$		V
Low Level Input Current ( $I_{IL}$ )	$V_{IN} = V_{DD I/O}$		0.1	$\mu$ A
High Level Input Current ( $I_{IH}$ )	$V_{IN} = 0V$	-0.1		$\mu$ A
Digital Output				
Low Level Output Voltage ( $V_{OL}$ )	$I_{OL} = 10\text{ mA}$		$0.2 \times V_{DD I/O}$	V
High Level Output Voltage ( $V_{OH}$ )	$I_{OH} = -4\text{ mA}$	$0.8 \times V_{DD I/O}$		V
Low Level Output Current ( $I_{OL}$ )	$V_{OL} = V_{OL, max}$	10		mA
High Level Output Current ( $I_{OH}$ )	$V_{OH} = V_{OH, min}$		-4	mA
Pin Capacitance	$f_{IN} = 1\text{ MHz}, V_{IN} = 2.5\text{ V}$		8	pF

<sup>1</sup> Limits based on characterization results; not production tested.

Table 9. SPI Timing ( $T_A = 25^\circ\text{C}$ ,  $V_S = V_{DD I/O} = 3.3\text{ V}$ )<sup>1</sup>

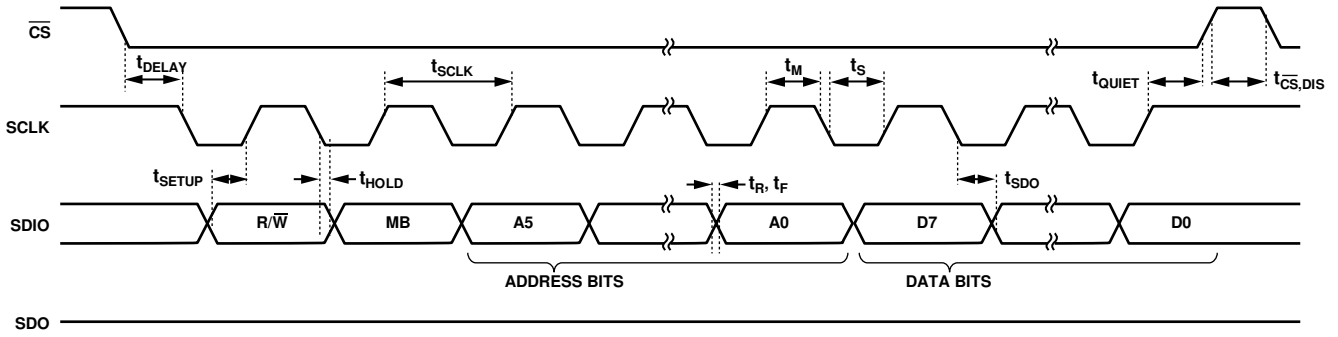
Parameter	Limit <sup>2, 3</sup>		Unit	Description
	Min	Max		
$f_{SCLK}$		5	MHz	SPI clock frequency.
$t_{SCLK}$	200		ns	$1/(SPI\text{ clock frequency})$ mark-space ratio for the SCLK input is 40/60 to 60/40.
$t_{DELAY}$	5		ns	$\overline{CS}$ falling edge to SCLK falling edge.
$t_{QUIET}$	5		ns	SCLK rising edge to $\overline{CS}$ rising edge.
$t_{DIS}$		10	ns	$\overline{CS}$ rising edge to SDO disabled.
$t_{\overline{CS}, DIS}$	150		ns	$\overline{CS}$ deassertion between SPI communications.
$t_S$	$0.3 \times t_{SCLK}$		ns	SCLK low pulse width (space).
$t_M$	$0.3 \times t_{SCLK}$		ns	SCLK high pulse width (mark).
$t_{SETUP}$	5		ns	SDI valid before SCLK rising edge.
$t_{HOLD}$	5		ns	SDI valid after SCLK rising edge.
$t_{SDO}$		40	ns	SCLK falling edge to SDO/SDIO output transition.
$t_R^4$		20	ns	SDO/SDIO output high to output low transition.
$t_F^4$		20	ns	SDO/SDIO output low to output high transition.

<sup>1</sup> The  $\overline{CS}$ , SCLK, SDI, and SDO pins are not internally pulled up or down; they must be driven for proper operation.

<sup>2</sup> Limits based on characterization results, characterized with  $f_{SCLK} = 5\text{ MHz}$  and bus load capacitance of 100 pF; not production tested.

<sup>3</sup> The timing values are measured corresponding to the input thresholds ( $V_{IL}$  and  $V_{IH}$ ) given in Table 8.

<sup>4</sup> Output rise and fall times measured with capacitive load of 150 pF.



NOTES  
1.  $t_{SDO}$  IS ONLY PRESENT DURING READS.

Figure 17. SPI 3-Wire Read/Write

11469-014

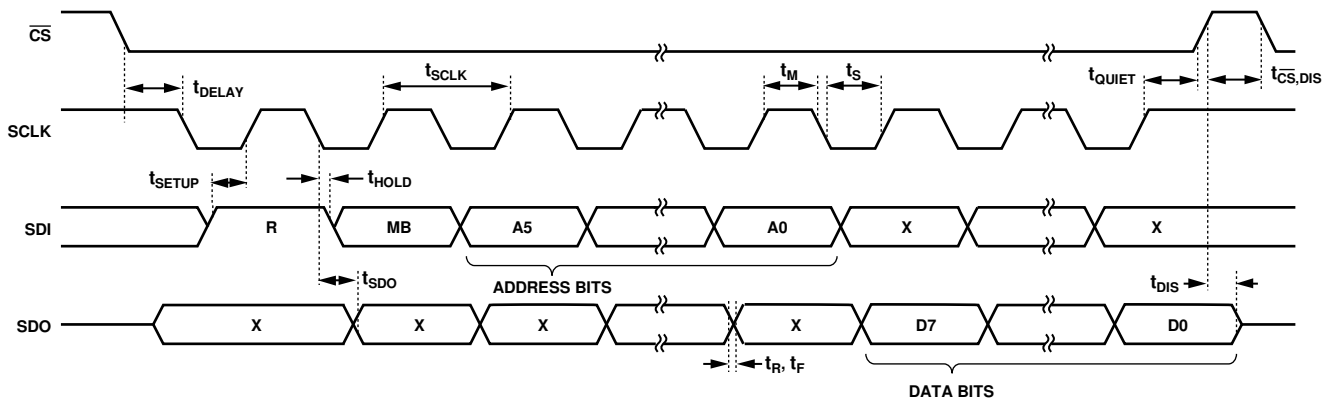


Figure 18. SPI 4-Wire Read

11469-015

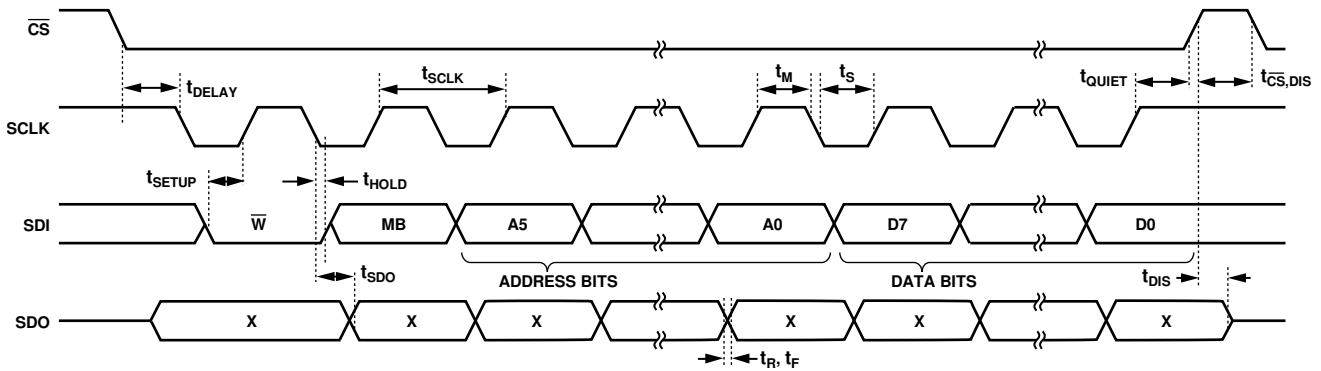


Figure 19. SPI 4-Wire Write

11469-016

I<sup>2</sup>C

With  $\overline{CS}$  tied high to  $V_{DD\ I/O}$ , the ADXL313 is in I<sup>2</sup>C mode, requiring a simple 2-wire connection, as shown in Figure 20. The ADXL313 conforms to the *UM10204 I<sup>2</sup>C-Bus Specification and User Manual*, Rev. 03—19 June 2007, available from NXP Semiconductor. It supports standard (100 kHz) and fast (400 kHz) data transfer modes if the bus parameters given in Table 10 and Table 11 are met. Single- or multiple-byte reads/writes are supported, as shown in Figure 21. With the ALT ADDRESS pin high, the 7-bit I<sup>2</sup>C address for the device is 0x1D, followed by the R/W bit. This translates to 0x3A for a write and 0x3B for a read. An alternate I<sup>2</sup>C address of 0x53 (followed by the R/W bit) can be chosen by grounding the ALT ADDRESS pin (Pin 23). This translates to 0xA6 for a write and 0xA7 for a read.

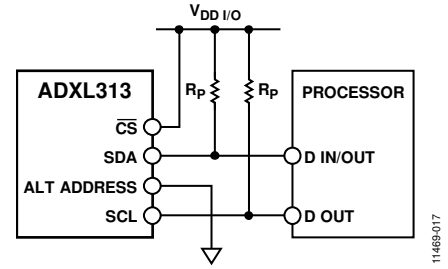


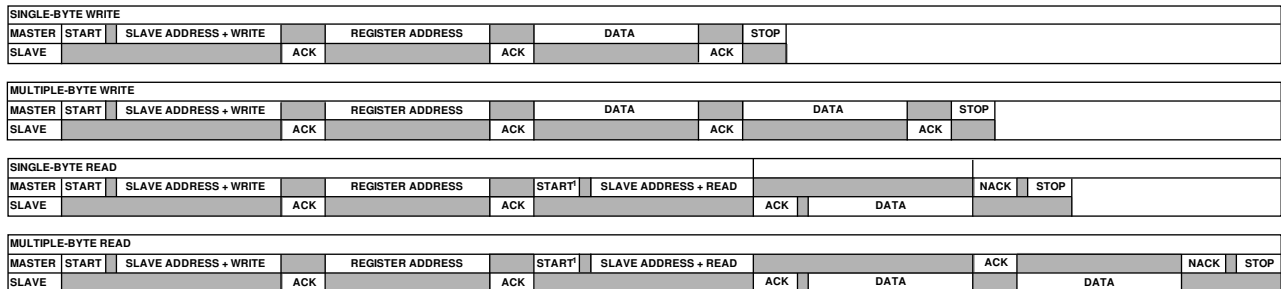
Figure 20. I<sup>2</sup>C Connection Diagram (Address 0x53)

If other devices are connected to the same I<sup>2</sup>C bus, the nominal operating voltage level of these other devices cannot exceed  $V_{DD\ I/O}$  by more than 0.3 V. External pull-up resistors,  $R_p$ , are necessary for proper I<sup>2</sup>C operation. To ensure proper operation, refer to the *UM10204 I<sup>2</sup>C-Bus Specification and User Manual*, Rev. 03—19 June 2007, when selecting pull-up resistor values.

Table 10. I<sup>2</sup>C Digital Input/Output

Parameter	Test Conditions/Comments	Limit <sup>1</sup>		Unit
		Min	Max	
Digital Input				
Low Level Input Voltage ( $V_{IL}$ )			$0.3 \times V_{DD\ I/O}$	V
High Level Input Voltage ( $V_{IH}$ )		$0.7 \times V_{DD\ I/O}$		V
Low Level Input Current ( $I_{IL}$ )	$V_{IN} = V_{DD\ I/O}$		0.1	$\mu A$
High Level Input Current ( $I_{IH}$ )	$V_{IN} = 0\ V$	-0.1		$\mu A$
Digital Output				
Low Level Output Voltage ( $V_{OL}$ )	$V_{DD\ I/O} < 2\ V, I_{OL} = 3\ mA$		$0.2 \times V_{DD\ I/O}$	V
	$V_{DD\ I/O} \geq 2\ V, I_{OL} = 3\ mA$		400	mV
Low Level Output Current ( $I_{OL}$ )	$V_{OL} = V_{OL, max}$	3		mA
Pin Capacitance	$f_{IN} = 1\ MHz, V_{IN} = 2.5\ V$		8	pF

<sup>1</sup> Limits based on characterization results; not production tested.



NOTES  
 1. THIS START IS EITHER A RESTART OR A STOP FOLLOWED BY A START.  
 2. THE SHADED AREAS REPRESENT WHEN THE DEVICE IS LISTENING.

Figure 21. I<sup>2</sup>C Device Addressing

Table 11. I<sup>2</sup>C Timing (T<sub>A</sub> = 25°C, V<sub>S</sub> = V<sub>DD I/O</sub> = 3.3 V)

Parameter	Limit <sup>1, 2</sup>		Unit	Description
	Min	Max		
f <sub>SCL</sub>		400	kHz	SCL clock frequency
t <sub>1</sub>	2.5		μs	SCL cycle time
t <sub>2</sub>	0.6		μs	SCL high time
t <sub>3</sub>	1.3		μs	SCL low time
t <sub>4</sub>	0.6		μs	Start/repeated start condition hold time
t <sub>5</sub>	100		ns	Data setup time
t <sub>6</sub> <sup>3, 4, 5, 6</sup>	0	0.9	μs	Data hold time
t <sub>7</sub>	0.6		μs	Setup time for repeated start
t <sub>8</sub>	0.6		μs	Stop condition setup time
t <sub>9</sub>	1.3		μs	Bus-free time between a stop condition and a start condition
t <sub>10</sub>		300	ns	Rise time of both SCL and SDA when receiving
	0		ns	Rise time of both SCL and SDA when receiving or transmitting
t <sub>11</sub>		250	ns	Fall time of SDA when receiving
		300	ns	Fall time of both SCL and SDA when transmitting
	20 + 0.1 C <sub>b</sub> <sup>7</sup>		ns	Fall time of both SCL and SDA when transmitting or receiving
C <sub>b</sub>		400	pF	Capacitive load for each bus line

<sup>1</sup> Limits based on characterization results, with f<sub>SCL</sub> = 400 kHz and a 3 mA sink current; not production tested.

<sup>2</sup> All values referred to the V<sub>IH</sub> and the V<sub>IL</sub> levels given in Table 10.

<sup>3</sup> t<sub>6</sub> is the data hold time that is measured from the falling edge of SCL. It applies to data in transmission and acknowledge.

<sup>4</sup> A transmitting device must internally provide an output hold time of at least 300 ns for the SDA signal (with respect to V<sub>IH, min</sub> of the SCL signal) to bridge the undefined region of the falling edge of SCL.

<sup>5</sup> The maximum t<sub>6</sub> value must be met only if the device does not stretch the low period (t<sub>3</sub>) of the SCL signal.

<sup>6</sup> The maximum value for t<sub>6</sub> is a function of the clock low time (t<sub>3</sub>), the clock rise time (t<sub>10</sub>), and the minimum data setup time (t<sub>5(min)</sub>). This value is calculated as

$$t_{6(max)} = t_3 - t_{10} - t_{5(min)}$$

<sup>7</sup> C<sub>b</sub> is the total capacitance of one bus line in picofarads.

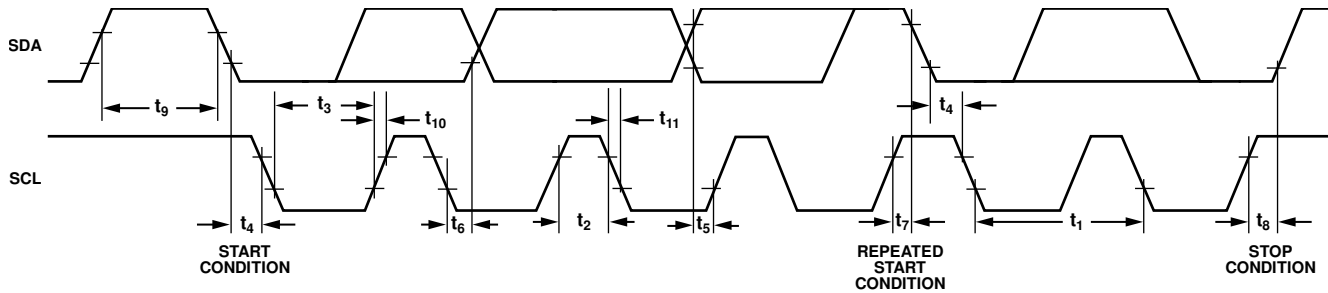


Figure 22. I<sup>2</sup>C Timing Diagram

11469-01B



## INTERRUPTS

The ADXL313 provides two output pins for driving interrupts: INT1 and INT2. Both interrupt pins are push-pull, low impedance pins with output specifications shown in Table 12. The default configuration of the interrupt pins is active high. This can be changed to active low by setting the INT\_INVERT bit in the DATA\_FORMAT register (Address 0x31). All functions can be used simultaneously, with the only limiting feature being that some functions may need to share interrupt pins.

Interrupts are enabled by setting the appropriate bit in the INT\_ENABLE register (Address 0x2E) and are mapped to either the INT1 or INT2 pin based on the contents of the INT\_MAP register (Address 0x2F). When initially configuring the interrupt pins, it is recommended that the functions and interrupt mapping be completed before enabling the interrupts. When changing the configuration of an interrupt, it is recommended that the interrupt be disabled first, by clearing the bit corresponding to that function in the INT\_ENABLE register, and then the function be reconfigured before enabling the interrupt again. Configuration of the functions while the interrupts are disabled helps to prevent the accidental generation of an interrupt.

The interrupt functions are latched and cleared either by reading the data registers (Address 0x32 to Address 0x37) until the interrupt condition is no longer valid for the data-related interrupts or by reading the INT\_SOURCE register (Address 0x30) for the remaining interrupts. The following sections describe the interrupts that can be set in the INT\_ENABLE register and monitored in the INT\_SOURCE register.

### DATA\_READY

The DATA\_READY bit is set when new data is available and is cleared when no new data is available.

### Activity

The activity bit is set when acceleration greater than the value stored in the THRESH\_ACT register (Address 0x24) is sensed.

### Inactivity

The inactivity bit is set when acceleration of less than the value stored in the THRESH\_INACT register (Address 0x25) is sensed for more time than is specified in the TIME\_INACT register (Address 0x26). The maximum value for TIME\_INACT is 255 sec.

### Watermark

The watermark bit is set when the number of samples in the FIFO equals the value stored in the samples bits in the FIFO\_CTL register (Address 0x38). The watermark bit is cleared automatically when the FIFO is read, and the content returns to a value below the value stored in the samples bits.

### Overrun

The overrun bit is set when new data replaces unread data. The precise operation of the overrun function depends on the FIFO mode. In bypass mode, the overrun bit is set when new data replaces unread data in the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers (Address 0x32 to Address 0x37). In all other modes, the overrun bit is set when the FIFO is filled. The overrun bit is automatically cleared when the contents of FIFO are read.

### FIFO

The ADXL313 contains patent pending technology for an embedded memory management system with a 32-level FIFO that can be used to minimize host processor burden. This buffer has four modes: bypass, FIFO, stream, and trigger (see Table 17). Each mode is selected by the settings of the FIFO\_MODE bits in the FIFO\_CTL register (Address 0x38).

### Bypass Mode

In bypass mode, the FIFO is not operational and, therefore, remains empty.

Table 12. Interrupt Pin Digital Output

Parameter	Test Conditions/Comments	Limit <sup>1</sup>		Unit
		Min	Max	
Digital Output				
Low Level Output Voltage (V <sub>OL</sub> )	I <sub>OL</sub> = 300 μA		0.2 × V <sub>DD I/O</sub>	V
High Level Output Voltage (V <sub>OH</sub> )	I <sub>OH</sub> = -150 μA	0.8 × V <sub>DD I/O</sub>		V
Low Level Output Current (I <sub>OL</sub> )	V <sub>OL</sub> = V <sub>OL, max</sub>	300		μA
High Level Output Current (I <sub>OH</sub> )	V <sub>OH</sub> = V <sub>OH, min</sub>		-150	μA
Pin Capacitance	f <sub>IN</sub> = 1 MHz, V <sub>IN</sub> = 2.5 V		8	pF
Rise/Fall Time				
Rise Time (t <sub>r</sub> ) <sup>2</sup>	C <sub>LOAD</sub> = 150 pF		210	ns
Fall Time (t <sub>f</sub> ) <sup>3</sup>	C <sub>LOAD</sub> = 150 pF		150	ns

<sup>1</sup> Limits based on characterization results, not production tested.

<sup>2</sup> Rise time is measured as the transition time from V<sub>OL, max</sub> to V<sub>OH, min</sub> of the INTx pin.

<sup>3</sup> Fall time is measured as the transition time from V<sub>OH, min</sub> to V<sub>OL, max</sub> of the INTx pin.

**FIFO Mode**

In FIFO mode, data from measurements of the x-, y-, and z-axes are stored in the FIFO. When the number of samples in the FIFO equals the level specified in the samples bits of the FIFO\_CTL register (Address 0x38), the watermark interrupt is set. The FIFO continues accumulating samples until it is full (32 samples from measurements of the x-, y-, and z-axes) and then stops collecting data. After the FIFO stops collecting data, the device continues to operate; therefore, features such as activity detection can be used after the FIFO is full. The watermark interrupt continues to occur until the number of samples in the FIFO is less than the value stored in the samples bits of the FIFO\_CTL register.

**Stream Mode**

In stream mode, data from measurements of the x-, y-, and z-axes is stored in FIFO. When the number of samples in the FIFO equals the level specified in the samples bits of the FIFO\_CTL register (Address 0x38), the watermark interrupt is set. FIFO continues accumulating samples and holds the latest 32 samples from measurements of the x-, y-, and z-axes, discarding older data as new data arrives. The watermark interrupt continues occurring until the number of samples in FIFO is less than the value stored in the samples bits of the FIFO\_CTL register.

**Trigger Mode**

In trigger mode, the FIFO accumulates samples, holding the latest 32 samples from measurements of the x-, y-, and z-axes. After a trigger event occurs and an interrupt is sent to the INT1 or INT2 pin (determined by the trigger bit in the FIFO\_CTL register), FIFO keeps the last n samples (where n is the value specified by the samples bits in the FIFO\_CTL register) and then operates in FIFO mode, collecting new samples only when the FIFO is not full. A delay of at least 5  $\mu$ s must be present between the trigger event occurring and the start of reading data from the FIFO to allow the FIFO to discard and retain the necessary samples. Additional trigger events cannot be recognized until the trigger mode is reset. To reset the trigger mode, set the device to bypass mode and then set the device back to trigger mode. Note that the FIFO data must be read first because placing the device into bypass mode clears FIFO.

**Retrieving Data from FIFO**

The FIFO data is read through the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers (Address 0x32 to Address 0x37). When the FIFO is in FIFO, stream, or trigger mode, reads to the DATA\_Xx, DATA\_xY, and DATA\_Zx registers read data stored in the FIFO. Each time data is read from the FIFO, the oldest x-, y-, and z-axes data is placed into the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers.

If a single-byte read operation is performed, the remaining bytes of data for the current FIFO sample are lost. Therefore, all axes of interest must be read in a burst (or multiple-byte) read operation. To ensure that the FIFO has completely popped (that is, that new data has completely moved into the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers), there must be at least 5  $\mu$ s between the end of reading the data registers and the start of a new read of the FIFO or a read of the FIFO\_STATUS register (Address 0x39). The end of reading a data register is signified by the transition from Register 0x37 to Register 0x38 or by the  $\overline{CS}$  pin going high.

For SPI operation at 1.6 MHz or less, the register addressing portion of the transmission is a sufficient delay to ensure that the FIFO has completely popped. For SPI operation greater than 1.6 MHz, it is necessary to deassert the  $\overline{CS}$  pin to ensure a total delay of 5  $\mu$ s; otherwise, the delay is not sufficient. The total delay necessary for 5 MHz operation is at most 3.4  $\mu$ s. This is not a concern when using I<sup>2</sup>C mode because the communication rate is low enough to ensure a sufficient delay between FIFO reads.

**SELF TEST**

The ADXL313 incorporates a self test feature that effectively tests its mechanical and electronic systems simultaneously. When the self test function is enabled (via the SELF\_TEST bit in the DATA\_FORMAT register, Address 0x31), an electrostatic force is exerted on the mechanical sensor. This electrostatic force moves the mechanical sensing element in the same manner as acceleration, and it is additive to the acceleration experienced by the device. This added electrostatic force results in an output change in the x-, y-, and z-axes. Because the electrostatic force is proportional to  $V_s^2$ , the output change varies with  $V_s$ . The self test feature of the ADXL313 also exhibits a bimodal behavior. However, the limits shown in Table 1 and Table 13 are valid for all potential self test values across the entire allowable voltage range. Use of the self test feature at data rates of less than 100 Hz or at 1600 Hz may yield values outside these limits. Therefore, the part must be in normal power operation (LOW\_POWER bit = 0 in the BW\_RATE register, Address 0x2C) and be placed into a data rate of 100 Hz through 800 Hz or 3200 Hz for the self test function to operate correctly.

**Table 13. Self Test Output ( $T_A = 25^\circ\text{C}$ ,  $2.0\text{ V} \leq V_s \leq 3.6\text{ V}$ )**

Axis	Min (g)	Max (g)
X	0.20	2.36
Y	-2.36	+0.20
Z	0.30	3.70

## REGISTER MAP

Table 14. Register Map

Reg.	Name	Type	D7	D6	D5	D4	D3	D2	D1	D0	Reset Value	
0x00	DEVID_0	R	DEVID_0[7:0]									0xAD
0x01	DEVID_1	R	DEVID_1[7:0]									0x1D
0x02	PARTID	R	PARTID[7:0]									0xCB
0x03	REVID	R	REVID[7:0]									0x00
0x04	XID	R	XID[7:0]									0x00
0x05 to 0x17	Reserved	RSVD	Reserved									
0x18	SOFT_RESET	R/W	SOFT_RESET[7:0]									0x00
0x19 to 0x1D	Reserved	RSVD	Reserved									
0x1E	OFSX	R/W	OFSX[7:0]									0x00
0x1F	OFSY	R/W	OFSY[7:0]									0x00
0x20	OFSZ	R/W	OFSZ[7:0]									0x00
0x21 to 0x23	Reserved	RSVD	Reserved									
0x24	THRESH_ACT	R/W	THRESH_ACT[7:0]									0x00
0x25	THRESH_INACT	R/W	THRESH_INACT[7:0]									0x00
0x26	TIME_INACT	R/W	TIME_INACT[7:0]									0x00
0x27	ACT_INACT_CTL	R/W	ACT_AC/DC	ACT_X	ACT_Y	ACT_Z	INACT_AC/DC	INACT_X	INACT_Y	INACT_Z	0x00	
0x28 to 0x2B	Reserved	RSVD	Reserved									
0x2C	BW_RATE	R/W	0	0	0	LOW_POWER	Rate[3:0]			0x0A		
0x2D	POWER_CTL	R/W	0	I2C_DISABLE	Link	AUTO_SLEEP	Measure	Sleep	Wake-up[1:0]		0x00	
0x2E	INT_ENABLE	R/W	DATA_READY	0	0	Activity	Inactivity	0	Watermark	Overrun	0x00	
0x2F	INT_MAP	R/W	DATA_READY	0	0	Activity	Inactivity	0	Watermark	Overrun	0x00	
0x30	INT_SOURCE	R	DATA_READY	0	0	Activity	Inactivity	0	Watermark	Overrun	0x02	
0x31	DATA_FORMAT	R/W	SELF_TEST	SPI	INT_INVERT	0	FULL_RES	Justify	Range[1:0]		0x00	
0x32	DATA_X0	R	DATA_X0[7:0]									0x00
0x33	DATA_X1	R	DATA_X1[7:0]									0x00
0x34	DATA_Y0	R	DATA_Y0[7:0]									0x00
0x35	DATA_Y1	R	DATA_Y1[7:0]									0x00
0x36	DATA_Z0	R	DATA_Z0[7:0]									0x00
0x37	DATA_Z1	R	DATA_Z1[7:0]									0x00
0x38	FIFO_CTL	R/W	FIFO_MODE[1:0]		Trigger	Samples[4:0]					0x00	
0x39	FIFO_STATUS	R	FIFO_TRIG	0	Entries							0x00

**REGISTER DEFINITIONS****Register 0x00—DEVID\_0 (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
1	0	1	0	1	1	0	1

The DEVID\_0 register holds a fixed device ID identifying Analog Devices, Inc., as the device manufacturer. The default value of this register is 0xAD.

**Register 0x01—DEVID\_1 (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
0	0	0	1	1	1	0	1

The DEVID\_1 register holds a fixed device ID that further enhances traceability of the ADXL313. The default value of this register is 0x1D.

**Register 0x02—PARTID (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
1	1	0	0	1	0	1	1

The PARTID register identifies the device as an ADXL313. The default hexadecimal value stored in this register, 0xCB, is meant to be interpreted as an octal value that corresponds to 313. If the user does not read back 0xCB from this register, assume that the device under test is not an ADXL313 device.

**Register 0x03—REVID (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
REVID[7:0]							

The number contained in the REVID register represents the silicon revision of the ADXL313. This number is incremented for any major silicon revision.

**Register 0x04—XID (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
XID[7:0]							

The XID register stores a semiunique serial number that is generated from the device trim and calibration process.

**Register 0x18—SOFT\_RESET (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
SOFT_RESET[7:0]							

Writing a value of 0x52 to Register 0x18 triggers the soft reset function of the ADXL313. The soft reset returns the ADXL313 to the beginning of its power-on initialization routine, clearing the configuration settings that were written to the memory map, which allows easy reconfiguration of the ADXL313 device.

**Register 0x1E—OFSX (Read/Write),****Register 0x1F—OFSY (Read/Write),****Register 0x20—OFSZ (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
OFSX[7:0]							
OFSY[7:0]							
OFSZ[7:0]							

The OFSX, OFSY, and OFSZ registers are each eight bits and offer user set offset adjustments in two's complement format, with a scale factor of 3.9 mg/LSB (that is, 0x7F = 0.5 g). The value stored in the offset registers is automatically added to the acceleration data, and the resulting value is stored in the output data registers.

**Register 0x24—THRESH\_ACT (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
THRESH_ACT[7:0]							

The THRESH\_ACT register is eight bits and holds the threshold value for detecting activity. The data format is unsigned; therefore, the magnitude of the activity event is compared with the value in the THRESH\_ACT register. The scale factor is 15.625 mg/LSB. A value of 0 may result in undesirable behavior if the activity interrupt is enabled.

**Register 0x25—THRESH\_INACT (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
THRESH_INACT[7:0]							

The THRESH\_INACT register is eight bits and holds the threshold value for detecting inactivity. The data format is unsigned; therefore, the magnitude of the inactivity event is compared with the value in the THRESH\_INACT register. The scale factor is 15.625 mg/LSB. A value of 0 may result in undesirable behavior if the inactivity interrupt is enabled.

**Register 0x26—TIME\_INACT (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
TIME_INACT[7:0]							

The TIME\_INACT register is eight bits and contains an unsigned time value. Acceleration must be less than the value in the THRESH\_INACT register for the amount of time represented by TIME\_INACT for inactivity to be declared. The scale factor is 1 sec/LSB. Unlike the other interrupt functions, which use unfiltered data (see the Threshold section), the inactivity function uses filtered output data. At least one output sample must be generated for the inactivity interrupt to be triggered. This results in the function appearing unresponsive if the TIME\_INACT register is set to a value less than the time constant of the output data rate. A value of 0 results in an interrupt when the output data is less than the value in the THRESH\_INACT register.

**Register 0x27—ACT\_INACT\_CTL (Read/Write)**

D7	D6	D5	D4
ACT_AC/DC	ACT_X	ACT_Y	ACT_Z
D3	D2	D1	D0
INACT_AC/DC	INACT_X	INACT_Y	INACT_Z

**ACT\_AC/DC and INACT\_AC/DC Bits**

A setting of 0 selects dc-coupled operation, and a setting of 1 enables ac-coupled operation. In dc-coupled operation, the current acceleration magnitude is compared directly with THRESH\_ACT and THRESH\_INACT to determine whether activity or inactivity is detected.

In ac-coupled operation for activity detection, the acceleration value at the start of activity detection is taken as a reference value. New samples of acceleration are then compared to this reference value and, if the magnitude of the difference exceeds the THRESH\_ACT value, the device triggers an activity interrupt.

Similarly, in ac-coupled operation for inactivity detection, a reference value is used for comparison and is updated whenever the device exceeds the inactivity threshold. After the reference value is selected, the device compares the magnitude of the difference between the reference value and the current acceleration with THRESH\_INACT. If the difference is less than the value in THRESH\_INACT for the time in TIME\_INACT, the device is considered inactive and the inactivity interrupt is triggered.

#### ACT\_x and INACT\_x Bits

A setting of 1 enables x-, y-, or z-axis participation in detecting activity or inactivity. A setting of 0 excludes the selected axis from participation. If all axes are excluded, the function is disabled. For activity detection, all participating axes are logically ORed, causing the activity function to trigger when any of the participating axes exceeds the threshold. For inactivity detection, all participating axes are logically ANDed, causing the inactivity function to trigger only if all participating axes are below the threshold for the specified period of time.

#### Register 0x2C—BW\_RATE (Read/Write)

D7	D6	D5	D4	D3	D2	D1	D0
0	0	0	LOW_POWER	Rate			

#### LOW\_POWER Bit

A setting of 0 in the LOW\_POWER bit selects normal operation, and a setting of 1 selects reduced power operation, which has somewhat higher noise (see the Power Modes section for details).

#### Rate Bits

These bits select the device bandwidth and output data rate (see Table 5 and Table 6 for details). The default value is 0x0A, which translates to a 100 Hz output data rate. Select an output data rate that is appropriate for the communication protocol and frequency selected. Selecting too high of an output data rate with a low communication speed results in samples being discarded.

#### Register 0x2D—POWER\_CTL (Read/Write)

D7	D6	D5	D4
0	I2C_DISABLE	Link	AUTO_SLEEP
D3	D2	D1	D0
Measure	Sleep	Wake-up	

#### I2C\_Disable Bit

The ADXL313 is capable of communicating via SPI or I<sup>2</sup>C transmission protocols. Typically, these protocols do not overlap; however, situations may arise where SPI transactions can imitate an I<sup>2</sup>C start command. This causes the ADXL313 to respond unexpectedly, causing a communications issue with other devices on the network. To ensure that the ADXL313 does

not interpret SPI commands as an I<sup>2</sup>C start condition, assert the I2C\_Disable bit.

#### Link Bit

A setting of 1 in the link bit with both the activity and inactivity functions enabled delays the start of the activity function until inactivity is detected. After activity is detected, inactivity detection begins, preventing the detection of activity. This bit serially links the activity and inactivity functions. When this bit is set to 0, the inactivity and activity functions are concurrent. Additional information can be found in the Link Mode section.

When clearing the link bit, it is recommended that the part be placed into standby mode and then set back to measurement mode with a subsequent write. This is done to ensure that the device is properly biased if sleep mode is manually disabled; otherwise, the first few samples of data after the link bit is cleared may have additional noise, especially if the device was asleep when the bit was cleared.

#### AUTO\_SLEEP Bit

If the link bit is set, a setting of 1 in the AUTO\_SLEEP bit sets the ADXL313 to switch to sleep mode when inactivity is detected (that is, when acceleration is below the THRESH\_INACT value for at least the time indicated by TIME\_INACT). A setting of 0 disables automatic switching to sleep mode. See the description of the sleep bit in the Sleep Bit section for more information.

When clearing the AUTO\_SLEEP bit, it is recommended that the part be placed into standby mode and then set back to measurement mode with a subsequent write. This is done to ensure that the device is properly biased if sleep mode is manually disabled; otherwise, the first few samples of data after the AUTO\_SLEEP bit is cleared may have additional noise, especially if the device was asleep when the bit was cleared.

#### Measure Bit

A setting of 0 in the measure bit places the part into standby mode, and a setting of 1 places the part into measurement mode. The ADXL313 powers up in standby mode with minimum power consumption.

#### Sleep Bit

A setting of 0 in the sleep bit puts the part into the normal mode of operation, and a setting of 1 places the part into sleep mode. Sleep mode suppresses DATA\_READY (see Register 0x2E, Register 0x2F, and Register 0x30), stops transmission of data to the FIFO, and switches the sampling rate to one specified by the wake-up bits. In sleep mode, only the activity function can be used.

When clearing the sleep bit, it is recommended that the part be placed into standby mode and then set back to measurement mode with a subsequent write. This is done to ensure that the device is properly biased if sleep mode is manually disabled; otherwise, the first few samples of data after the sleep bit is cleared may have additional noise, especially if the device was asleep when the bit was cleared.

**Wake-Up Bits**

These bits control the frequency of readings in sleep mode as described in Table 15.

**Table 15. Frequency of Readings in Sleep Mode**

Setting		Frequency (Hz)
D1	D0	
0	0	8
0	1	4
1	0	2
1	1	1

**Register 0x2E—INT\_ENABLE (Read/Write)**

D7	D6	D5	D4
DATA_READY	0	0	Activity
D3	D2	D1	D0
Inactivity	0	Watermark	Overrun

Setting bits in this register to a value of 1 enables their respective functions to generate interrupts, whereas a value of 0 prevents the functions from generating interrupts. The DATA\_READY, watermark, and overrun bits enable only the interrupt output; the functions are always enabled. It is recommended that interrupts be configured before enabling their outputs.

**Register 0x2F—INT\_MAP (Read/Write)**

D7	D6	D5	D4
DATA_READY	0	0	Activity
D3	D2	D1	D0
Inactivity	0	Watermark	Overrun

Any bits set to 0 in this register send their respective interrupts to the INT1 pin, whereas bits set to 1 send their respective interrupts to the INT2 pin. All selected interrupts for a given pin are ORed.

**Register 0x30—INT\_SOURCE (Read Only)**

D7	D6	D5	D4
DATA_READY	0	0	Activity
D3	D2	D1	D0
Inactivity	0	Watermark	Overrun

Bits set to 1 in this register indicate that their respective functions have triggered an event, whereas a value of 0 indicates that the corresponding event has not occurred. The DATA\_READY, watermark, and overrun bits are always set if the corresponding events occur, regardless of the INT\_ENABLE register settings, and are cleared by reading data from the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers. The DATA\_READY and watermark bits may require multiple reads, as indicated in the FIFO mode descriptions in the FIFO section. Other bits, and the corresponding interrupts, are cleared by reading the INT\_SOURCE register.

**Register 0x31—DATA\_FORMAT (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
SELF_TEST	SPI	INT_INVERT	0	FULL_RES	Justify	Range	

The DATA\_FORMAT register controls the presentation of data to Register 0x32 through Register 0x37. All data, except that for the ±4 g range, must be clipped to avoid rollover.

**SELF\_TEST Bit**

A setting of 1 in the SELF\_TEST bit applies a self test force to the sensor, causing a shift in the output data. A value of 0 disables the self test force.

**SPI Bit**

A value of 1 in the SPI bit sets the device to 3-wire SPI mode, and a value of 0 sets the device to 4-wire SPI mode.

**INT\_INVERT Bit**

A value of 0 in the INT\_INVERT bit sets the interrupts to active high, and a value of 1 sets the interrupts to active low.

**FULL\_RES Bit**

When this bit is set to a value of 1, the device is in full resolution mode, where the output resolution increases with the g range set by the range bits to maintain 1024 LSB/g sensitivity. When the FULL\_RES bit is set to 0, the device is in 10-bit mode, and the range bits determine the maximum g range and scale factor.

**Justify Bit**

A setting of 1 in the justify bit selects left (MSB) justified mode, and a setting of 0 selects right justified (LSB) mode with sign extension.

**Range Bits**

These bits set the g range as described in Table 16.

**Table 16. g Range Setting**

Setting		Range (g)
D1	D0	
0	0	±0.5
0	1	±1
1	0	±2
1	1	±4

**Register 0x32 and Register 0x33—DATA\_X0, DATA\_X1 (Read Only),**  
**Register 0x34 and Register 0x35—DATA\_Y0, DATA\_Y1 (Read Only),**  
**Register 0x36 and Register 0x37—DATA\_Z0, DATA\_Z1 (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
DATA_X0[7:0]							
DATA_X1[7:0]							
DATA_Y0[7:0]							
DATA_Y1[7:0]							
DATA_Z0[7:0]							
DATA_Z1[7:0]							

These six bytes (Register 0x32 to Register 0x37) are eight bits each and hold the output data for each axis. Register 0x32 and Register 0x33 hold the output data for the x-axis, Register 0x34 and Register 0x35 hold the output data for the y-axis, and Register 0x36 and Register 0x37 hold the output data for the z-axis.

The output data is twos complement, with DATA\_x0 as the least significant byte and DATA\_x1 as the most significant byte, where x represents X, Y, or Z. The DATA\_FORMAT register (Address 0x31) controls the format of the data. It is recommended that a multiple-byte read of all registers be performed to prevent a change in data between reads of sequential registers.

**Register 0x38—FIFO\_CTL (Read/Write)**

D7	D6	D5	D4	D3	D2	D1	D0
FIFO_MODE		Trigger	Samples				

#### FIFO\_MODE Bits

These bits set the FIFO mode, as described in Table 17.

**Table 17. FIFO Modes**

Setting		Mode	Function
D7	D6		
0	0	Bypass	FIFO is bypassed.
0	1	FIFO	FIFO collects up to 32 values and then stops collecting data, collecting new data only when FIFO is not full.
1	0	Stream	FIFO holds the last 32 data values. When FIFO is full, the oldest data is overwritten with newer data.
1	1	Trigger	When triggered by the trigger bit, FIFO holds the last data samples before the trigger event and then continues to collect data until full. New data is collected only when FIFO is not full.

#### Trigger Bit

A value of 0 in the trigger bit links the trigger event to INT1, and a value of 1 links the trigger event to INT2.

#### Samples Bits

The function of these bits depends on the FIFO mode selected (see Table 18). Entering a value of 0 in the samples bits immediately sets the watermark status bit in the INT\_SOURCE register, regardless of which FIFO mode is selected. Undesirable operation may occur if a value of 0 is used for the samples bits when trigger mode is used.

**Table 18. Samples Bits Functions**

FIFO Mode	Samples Bits Function
Bypass	None.
FIFO	Specifies how many FIFO entries are needed to trigger a watermark interrupt.
Stream	Specifies how many FIFO entries are needed to trigger a watermark interrupt.
Trigger	Specifies how many FIFO samples are retained in the FIFO buffer before a trigger event.

**0x39—FIFO\_STATUS (Read Only)**

D7	D6	D5	D4	D3	D2	D1	D0
FIFO_TRIG		0	Entries				

#### FIFO\_TRIG Bit

A 1 in the FIFO\_TRIG bit corresponds to a trigger event occurring, and a 0 means that a FIFO trigger event has not occurred.

#### Entries Bits

These bits report how many data values are stored in the FIFO. Access to collect the data from the FIFO is provided through the DATA\_Xx, DATA\_Yx, and DATA\_Zx registers. FIFO reads must be done in burst or multiple-byte mode because each FIFO level is cleared after any read (single- or multiple-byte) of the FIFO. The FIFO stores a maximum of 32 entries, which equates to a maximum of 33 entries available at any given time because an additional entry is available at the output filter of the device.

## APPLICATIONS INFORMATION

### POWER SUPPLY DECOUPLING

A 1  $\mu\text{F}$  tantalum capacitor ( $C_S$ ) at  $V_S$  and a 0.1  $\mu\text{F}$  ceramic capacitor ( $C_{I/O}$ ) at  $V_{DD\ I/O}$  placed close to the ADXL313 supply pins is recommended to adequately decouple the accelerometer from noise on the power supply. If additional decoupling is necessary, a resistor or ferrite bead, no larger than 100  $\Omega$ , in series with  $V_S$  may be helpful. Additionally, increasing the bypass capacitance on  $V_S$  to a 10  $\mu\text{F}$  tantalum capacitor in parallel with a 0.1  $\mu\text{F}$  ceramic capacitor may also improve noise.

Take care to ensure that the connection from the ADXL313 ground to the power supply ground has low impedance because noise transmitted through ground has an effect similar to noise transmitted through  $V_S$ . It is recommended that  $V_S$  and  $V_{DD\ I/O}$  be separate supplies to minimize digital clocking noise on the  $V_S$  supply. If this is not possible, additional filtering of the supplies as previously mentioned may be necessary.

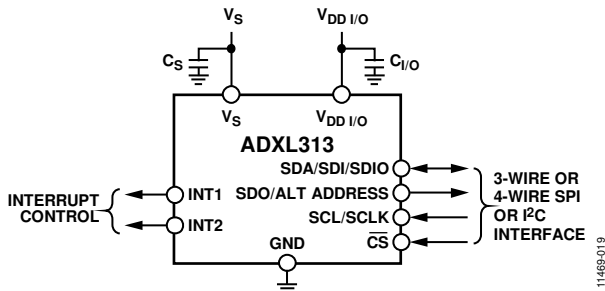


Figure 23. Application Diagram

### MECHANICAL CONSIDERATIONS FOR MOUNTING

Mount the ADXL313 on the PCB in a location close to a hard mounting point of the PCB to the case. Mounting the ADXL313 at an unsupported PCB location, as shown in Figure 24, may result in large, apparent measurement errors due to undamped PCB vibration. Placing the accelerometer near a hard mounting point ensures that any PCB vibration at the accelerometer is above the accelerometer’s mechanical sensor resonant frequency and, therefore, effectively invisible to the accelerometer. Multiple mounting points close to the sensor and/or a thicker PCB also help to reduce the effect of system resonance on the performance of the sensor.

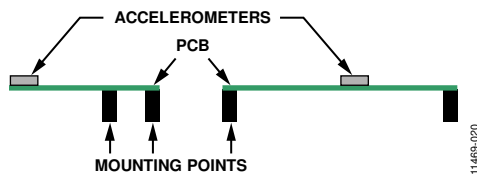


Figure 24. Incorrectly Placed Accelerometers

### THRESHOLD

The lower output data rates are achieved by decimating a common sampling frequency inside the device. The activity detection function is performed using undecimated data. Because the bandwidth of the output data varies with the data rate and is lower than the bandwidth of the undecimated data, the high frequency and high  $g$  data that are used to determine activity may not be present if the output of the accelerometer is examined. This may result in functions triggering when acceleration data does not appear to meet the conditions set by the user for the corresponding function.

### LINK MODE

The function of the link bit in the POWER\_CTL register (Address 0x2D) is to reduce the number of activity interrupts that the processor must service by setting the device to look for activity only after inactivity. For proper operation of this feature, the processor must still respond to the activity and inactivity interrupts by reading the INT\_SOURCE register (Address 0x30) and, therefore, clearing the interrupts. If an activity interrupt is not cleared, the part cannot go into autosleep mode.

### SLEEP MODE vs. LOW POWER MODE

In applications where a low data rate and low power consumption are desired (at the expense of noise performance), it is recommended that low power mode be used. The use of low power mode preserves the functionality of the DATA\_READY interrupt and the FIFO for postprocessing of the acceleration data. Sleep mode, while offering a low data rate and low power consumption, is not intended for data acquisition.

However, when sleep mode is used in conjunction with the autosleep mode and the link mode, the part can automatically switch to a low power, low sampling rate mode when inactivity is detected. To prevent the generation of redundant inactivity interrupts, the inactivity interrupt is automatically disabled and activity is enabled. When the ADXL313 is in sleep mode, the host processor can also be placed into sleep mode or low power mode to save significant system power. When activity is detected, the accelerometer automatically switches back to the original data rate of the application and provides an activity interrupt that can be used to wake up the host processor. Similar to when inactivity occurs, detection of activity events is disabled and inactivity is enabled.



## USING SELF TEST

The self test change is defined as the difference between the acceleration output of an axis with self test enabled and the acceleration output of the same axis with self test disabled (see Endnote 4 of Table 1). This definition assumes that the sensor does not move between these two measurements because, if the sensor moves, a nonself test related shift corrupts the test.

Proper configuration of the ADXL313 is also necessary for an accurate self test measurement. Set the part with a data rate greater than or equal to 100 Hz. This is done by ensuring that a value greater than or equal to 0x0A is written into the rate bits (Bit D3 through Bit D0) in the BW\_RATE register (Address 0x2C). The part must also be placed into normal power operation by ensuring that the LOW\_POWER bit in the BW\_RATE register is cleared (LOW\_POWER bit = 0) for accurate self test measurements. It is recommended that the part be set to full resolution,  $\pm 4$  g mode to ensure that there is sufficient dynamic range for the entire self test shift. This is done by setting Bit D3 of the DATA\_FORMAT register (Address 0x31) and writing a value of 0x03 to the range bits (Bit D1 and Bit D0) of the DATA\_FORMAT register. This results in a high dynamic range for measurement and 1024 LSB/g sensitivity.

After the part is configured for accurate self test measurement, several samples of x-, y-, and z-axis acceleration data should be retrieved from the sensor and averaged together. The number of samples averaged is a choice of the system designer, but a recommended starting point is 0.1 sec worth of data, which corresponds to 10 samples at 100 Hz data rate. Store and label the averaged values appropriately as the self test disabled data, that is,  $X_{ST\_OFF}$ ,  $Y_{ST\_OFF}$ , and  $Z_{ST\_OFF}$ .

Next, enable self test by setting Bit D7 of the DATA\_FORMAT register (Address 0x31). The output needs some time (about four samples) to settle after enabling self test. After allowing the output to settle, take several samples of the x-, y-, and z-axis acceleration data, and average them. It is recommended that the same number of samples be taken for this average as was previously taken. Store and label these averaged values appropriately as the value with self test enabled, that is,  $X_{ST\_ON}$ ,  $Y_{ST\_ON}$ , and  $Z_{ST\_ON}$ . Self test can then be disabled by clearing Bit D7 of the DATA\_FORMAT register (Address 0x31).

With the stored values for self test enabled and disabled, the self test change is as follows:

$$X_{ST} = X_{ST\_ON} - X_{ST\_OFF}$$

$$Y_{ST} = Y_{ST\_ON} - Y_{ST\_OFF}$$

$$Z_{ST} = Z_{ST\_ON} - Z_{ST\_OFF}$$

Because the measured output for each axis is expressed in LSBs,  $X_{ST}$ ,  $Y_{ST}$ , and  $Z_{ST}$  are also expressed in LSBs. These values can be converted to acceleration ( $g$ ) by multiplying each value by the sensitivity, 1024 LSB/g, when configured for full resolution mode. When operating in 10-bit mode, the self test delta in LSBs varies according to the selected  $g$  range, even though the self test force, in  $g$ , remains unchanged. Using a range below  $\pm 4$  g may result in insufficient dynamic range and should be considered when selecting the range of operation for measuring self test.

If the self test change is within the valid range, the test is considered successful. Generally, a part is considered to pass if the minimum magnitude of change is achieved. However, a part that changes by more than the maximum magnitude is not necessarily a failure.

## 3200 Hz AND 1600 Hz ODR DATA FORMATTING

The following section applies for 3200 Hz and 1600 Hz output data rates only. This section can be ignored for all other data rates.

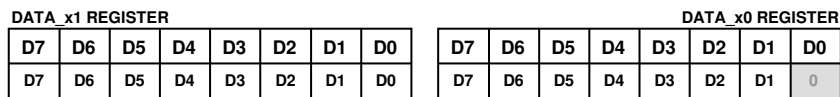
For 3200 Hz and 1600 Hz output data rates, when the ADXL313 is configured for either a  $\pm 0.5 g$  output range or the full resolution mode is enabled, the LSB of the output data-word is always 0. If the acceleration data-word is right justified, this corresponds to Bit D0 of the DATA\_x0 register, as shown in Figure 25 and Table 19.

When data is left justified and the part is operating in  $\pm 0.5 g$  mode, the LSB of the output data-word is Bit D6 of the DATAx0 register. In full resolution operation, the location of the LSB changes according to the selected output range. Table 19 and Figure 26 demonstrate how the position of the LSB changes when full resolution mode is enabled.

**Table 19. Conditions for Which the LSB Is Set to 0 (3200 Hz and 1600 Hz Output Data Rates Only)**

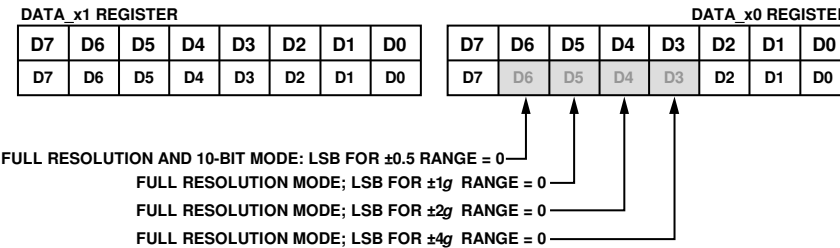
Justify (0x31[2])	FULL_RES (0x31[3])	Range (g)	LSB Bit Position
0	0 or 1	$\pm 0.5$	D0
0	1	$\pm 1$	D0
0	1	$\pm 2$	D0
0	1	$\pm 4$	D0
1	0 or 1	$\pm 0.5$	D6
1	1	$\pm 1$	D5
1	1	$\pm 2$	D4
1	1	$\pm 4$	D3

The use of 3200 Hz and 1600 Hz output data rates for fixed 10-bit operation in the  $\pm 1 g$ ,  $\pm 2 g$ , and  $\pm 4 g$  output ranges provides an LSB that is valid and that changes according to the applied acceleration. Therefore, in these modes of operation, Bit D0 is not always 0 when output data is right justified, and Bit D6 is not always 0 when output data is left justified.



**FOR THE RIGHT JUSTIFIED DATA:**  
 WHEN OPERATING THE ADXL313 WITH AN OUTPUT RATE OF EITHER 3200Hz OR 1600Hz, THE D0 BIT OF THE DATA\_x0 REGISTER IS ALWAYS 0 UNDER EITHER OF THE FOLLOWING CONDITIONS:  
 1) FULL RESOLUTION MODE IS ENABLED (ANY g RANGE), OR  
 2) DEVICE RANGE IS SET TO  $\pm 0.5g$

Figure 25. Right Justified Data Formatting: 3200 Hz and 1600 Hz Output Data Rate



**FOR THE LEFT JUSTIFIED DATA:**  
 WHEN OPERATING THE ADXL313 WITH AN OUTPUT RATE OF EITHER 3200Hz OR 1600Hz, THE LSB OF THE ACCELERATION DATA-WORD IS ALWAYS 0 UNDER THE FOLLOWING CONDITIONS:  
 1) FULL RESOLUTION MODE IS ENABLED (ANY g RANGE), OR  
 2) DEVICE RANGE IS SET TO  $\pm 0.5g$ .  
 FULL RESOLUTION MODE CAUSES THE LOCATION OF THE LSB TO CHANGE ACCORDING TO THE SELECTED g RANGE. ALTHOUGH ITS LOCATION MAY CHANGE, ITS VALUE WILL REMAIN 0.

Figure 26. Left Justified Data Formatting: 3200 Hz and 1600 Hz Output Data Rate