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## Panasonic ideas for life

## OVERVIEW

## PROGRAMMABLE LOGIC CONTROLLERS

## Advantages of PLC control



## Powerful hardware solutions

Panasonic PLCs offer an outstanding price-performance ratio which incorporates numerous functions into a very compact body. Even in the smallest size they provide a powerful instruction set which allows the system to handle demanding tasks such as analog control, networking and positioning control.

## Innovative programming software

Our PLC programming software Control FPWIN Pro was one of the first on the market conforming to the international standard IEC 61131-3. Numerous libraries that incorporate a lot of our know-how ensure the reusability of ready-made functions and function blocks and save time for programming and debugging.


## Long-life quality

As with all Panasonic products, the PLCs undergo extremely rigorous testing during development that far exceeds the demands that will actually be placed on them. This is a guarantee for the long life of the product in the application.

## Benefit from good service

In addition to a comprehensive PLC range, Panasonic also offers the high-quality care demanded from a service-oriented company certified according to ISO 9001.
Highly trained application engineers can provide custom designed systems. The sales staff regularly participates in hardware and software training courses.


## Content

| Advantages \& overview | 2-5 | FP Web-Server. | 41 |
| :---: | :---: | :---: | :---: |
| Networking technology . | 6-7 | FP Web Designer . | 42-43 |
| FP-e series . | . . 8-9 | FMU/FSU | 44-45 |
| FPOR series | 10-15 | FP Modem | 46 |
| FPE (Sigma) series. | 16-25 | Progamming software Control FPWIN Pro. | . 47 |
| FP-X series. | 26-31 | Other programming tools | 48-51 |
| FP-X0 series. | 32-33 | KS1.................. | 52 |
| FP2SH series | . $34-39$ | Part number list 53-62 |  |
| Power supply units | . . 40 |  |  |

## Overview



## Selection of products

| Model |  |  | FP-e |  | FPOR |  |  | FP $\Sigma$ (Sigma) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |
| Features |  |  | PLC + Display + Switch <br> - All-in-one controller with six functions <br> - Mountable in a 48 mm square cut in a panel <br> - 14 I/O points (input: 8 , output: 6 ) <br> - Can serve as a temperature controller with a thermocouple input <br> - Motor control by the built-in pulse output <br> - Heater control by the PWM output <br> - Serial communications by the RS232C/RS485 port |  | Pocket-size ultra-compact controller ideal for use in extremely narrow spaces <br> - Ultra-high processing speed of $80 \mathrm{nsec} / \mathrm{step}$ within range of 0 to 3000 steps <br> - Wide selection of program capacity from 16 k to 32 k steps <br> - Wide selection of the number of I/O points from 10 to 128 <br> - Up to 24 thermocouple inputs connectable for multipoint temperature control <br> - Multi-axis control available without expansion units <br> - Battery-less backup of all data |  |  | High performance ultra-compact controller reliably supports the control of higher speed equipment with more functions featured <br> - Excellent basic performance, including program capacity of 32 k steps, operation speed of $0.32 \mu \mathrm{~s} / \mathrm{step}$ and $384 \mathrm{I} / \mathrm{O}$ points <br> - Built-in two-axis 100 kHz pulse output capable of interpolation control <br> - Positioning units capable of controlling network servomotors <br> - Can be equipped with up to three ports for general-purpose serial communication without expansion unit <br> - Compatible with PROFIBUS, DeviceNet, CANopen and other open field networks |  |  |
| CPU (control unit) model |  |  | Basic type | Thermocouple input type | C10/C14/C16 | C32 | T32/F32 | C24 | C28 | C32 |
| Maximum controllable I/O points |  |  | 14 points | 12 points | 106 to 112 points |  |  | 376 points | 380 points | 384 points |
| Connectable expansion units |  |  | N/A |  | 3 units |  |  | 7 units (right: 3 left: 4) |  |  |
| Program capacity |  |  | 2.7k steps |  | A (built-in memory) |  |  | 32k steps |  |  |
| Comment memory |  |  | N/A |  |  |  |  | A (built-in memory) |  |  |
| Operation speed |  |  | 0.9us/step (basic instructions) |  | 0.08-0.58 ${ }^{\text {s/step (basic instructions) }}$ |  |  | $0.32 \mu \mathrm{~s} / \mathrm{step}$ (basic instructions) |  |  |
| Data registers |  |  | 1660 words |  | 12k words ${ }^{\text {c }}$ |  |  | 32,765 words |  |  |
| Internal relays |  |  | 1008 points (63 words) |  |  |  |  | 4096 points (256 words) |  |  |
|  | Ethernet |  | A (with FP Web-Server 2) |  | A (with FP Web-Server 2) |  |  | A (with FP Web-Server 2) |  |  |
|  | PROFIBUS DP |  | N/A |  | Slave |  |  | A (master, slave) |  |  |
|  | DeviceNet |  | N/A |  | N/A |  |  | A (master, slave) |  |  |
|  | CANopen |  | N/A |  | N/A |  |  | A (master, slave) |  |  |
|  | PROFINETIO |  | N/A |  | N/A |  |  | A (slave) |  |  |
|  | Modbus-RTU |  | A (RS485 type) |  | A (RS232C) |  |  | A (communication cassette/unit) |  |  |
|  | CC-Link |  | N/A |  | A (slave, CC-Link unit) |  |  | A (slave, CC-Link unit) |  |  |
|  | Computer link (MEWTOCOL-COM) |  | A (Tool port, COM port) |  | A (Tool port, COM port) |  |  | A (Tool port, communication cassette) |  |  |
|  | Program controlled |  | A (COM port) |  | A (Tool port, COM port) |  |  | A (Tool port, communication cassette) |  |  |
|  | 들000 | W | N/A |  | N/A |  |  | N/A |  |  |
|  |  | W0 | N/A |  | A |  |  | A (RS485 communication cassette) |  |  |
|  |  | W2 | N/A |  | N/A |  |  | N/A |  |  |
|  |  | VE | N/A |  | N/A |  |  | N/A |  |  |
|  | Remote I/O (MEWNET-F) |  | N/A |  | A (64-point slave stations, I/O link unit) |  |  | A (64-point slave stations, I/O link unit) |  |  |
|  | S-LINK |  | N/A |  | A (FPO-SL1 control unit) |  |  | A (S-LINK unit) |  |  |
|  | Built-in pulse output |  | $2 \mathrm{axes} / 10 \mathrm{kHz}$ | $2 \mathrm{axes} / 5 \mathrm{kHz}$ | 4 axes/50kHz (C16,C32,T32, F32) |  |  | $2 \mathrm{axes} / 100 \mathrm{kHz}$ (transistor output type) |  |  |
|  | Positioning unit |  | N/A |  | N/A |  |  | 2-axis/4-axis type unit, up to 16 axes |  |  |
|  | PWM output |  | 2 points/1kHz/1000 resolution |  | 4 points/6Hz to 4.8kHz (C16, C32, T32, F32) |  |  | 2 points/12kHz/1000 resolution (transistor output type) |  |  |
|  | High-speed counter |  | $4 \mathrm{ch} / 10 \mathrm{kHz}$ | $4 \mathrm{ch} / 5 \mathrm{kHz}$ | single phase: $6 \mathrm{ch} / 50 \mathrm{kHz}$; 2-phase: $3 \mathrm{ch} / 15 \mathrm{kHz}$ |  |  | $4 \mathrm{ch} / 50 \mathrm{kHz}$ |  |  |
| $\Perp$©©ভ | Voltage/current input |  | N/A |  | $8 \mathrm{ch} / \mathrm{unit}$ |  | 2-ch input and 1-ch output mixed unit | $8 \mathrm{ch} / \mathrm{unit}$ | 2-ch input and <br> 1-ch output mixed unit |  |
|  | Voltag | /current output | N/A |  | $4 \mathrm{ch} / \mathrm{unit}$ |  |  | $4 \mathrm{ch} / \mathrm{unit}$ |  |  |
|  | Temperature input |  | N/A | 2 ch (thermocouple) | 8 ch thermocouple unit, 6 ch RTD unit |  |  | 8 ch thermocouple unit, 6 ch RTD unit, 2 thermistor inputs on the CPU |  |  |
| Calendar timer (clock function) |  |  | A (calendar timer type) |  | A (T32 only) |  |  | A |  |  |
| Others |  |  | Front panel switch input: 8 points |  |  |  |  | Potentiometer input: 2 points |  |  |



## Compatible network diagram



## Compatible network table

|  | Network | Applications and features | Transmission cable | Transmission speed | Transmission distance | Supported function |  |  |  | Compatible PLCs |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | PLC Link | $\begin{aligned} & \text { Master/ } \\ & \text { Slave } \end{aligned}$ | $\begin{gathered} \text { Remote } \\ \text { I/O } \\ \text { systems } \end{gathered}$ | $\begin{aligned} & \text { MEW- } \\ & \text { TECOL- } \\ & \text { COM } \end{aligned}$ | FP2SH | FP-X | FP-X0 | FPI (Sig- ma) | FPOR | FP-e |
| Ethernet |  | - Connection to PCs or workstations by a stan-- For data collection and operation control | UTP cable or transceiver cable | 10Mbit/s / 100Mbit/s | $\begin{array}{\|c} \text { Max. distance } \\ 100 \mathrm{~m} \end{array}$ | A | A | N/A | N/A | A | A(x1) | $\mathrm{A}(\mathrm{x} 1)$ | A | A | A |
|  | CC-Link | - Capable of $10 \mathrm{Mbit} / \mathrm{s}$ high-speed or 1200 m long distance communications | $\begin{gathered} \text { CC-Link } \\ \begin{array}{c} \text { dedicated cable } \\ \text { (twisted pair } \\ \text { cable) } \end{array} \\ \hline \end{gathered}$ | 10Mbit/s (100m) <br> 5Mbit/s (160m) <br> $2.5 \mathrm{Mbit} / \mathrm{s}(400 \mathrm{~m})$ <br> 625kbit/s (900m) <br> 156kbit/s (1200m) |  | N/A | A | A | N/A | N/A | A | N/A | A | A | N/A |
|  | $\underset{D P}{\text { PROFIBUS- }}$ | - One of the world's most <br> popular open fieldbuses <br> - 12Mbit/s high-speed <br> communications <br> - Transmission up to 12 km is possible by using a repeater | Type A cable fo PROFIBUS-DP (twisted pair cable) | 12Mbit/s | 12 km when using a repeater) | N/A | A | A | N/A | $\underset{\substack{\text { (master/ } \\ \text { slave) }}}{ }$ | A(x2) | A(x2) | $\left\|\begin{array}{c} \text { A } \\ \text { (mas- } \\ \text { terl } \\ \text { slave) } \end{array}\right\|$ | $\begin{gathered} \text { A } \\ \text { (slave) } \end{gathered}$ | N/A |
|  | DeviceNet | - Developed based on CAN, as popular as PROFIBUS. <br> - Master-slave configuration as well as peer-topeer configuration is possible |  | 500kbit/s ( 100 m ) 250kbit/s (250m) 125kbit/s ( 500 m ) |  | N/A | A | N/A | N/A | $\left\|\begin{array}{c} A(\text { mas- } \\ \text { ter/slave }) \end{array}\right\|$ | N/A | N/A | $\left\|\begin{array}{c} \text { (master } \\ \text { slave) } \end{array}\right\|$ | N/A | N/A |
|  | CANopen | - As with DeviceNet, CAN-based industrial network <br> - Widespread, particularly in Europe 128 -station multi-master-slave communications | $\begin{gathered} \text { Twisted-pair } \\ \text { shielded cable } \\ \text { Also compa- } \\ \text { tible with four- } \\ \text { wire power bus } \\ \text { cables } \end{gathered}$ | 1Mbit/s $\underset{(500 \mathrm{~m})}{(25 \mathrm{~m})}$ to $10 \mathrm{kbit} / \mathrm{s}$ |  | N/A | A | N/A | N/A | $\left\|\begin{array}{c} A(\text { mas- } \\ \text { ter/slave }) \end{array}\right\|$ |  |  | $\left\|\begin{array}{c} \text { A } \\ \text { (master } \\ \text { slave) } \end{array}\right\|$ | N/A | N/A |
|  | Profinet 10 | - Real time, open industrial <br> Ethernet communication <br> - Three types are classified: 10 controllers, <br> 10 devices and IO supervisors | Standard PROFINET Ethernet cable with standard RJ45 connecto <br> RJ45 connecto | Full duplex, 100Mbits |  | N/A | $\begin{gathered} A \\ \text { A slave } \\ \text { only) } \end{gathered}$ | N/A | N/A |  |  |  | $\left\|\begin{array}{\|c\|} \text { A } \\ \text { device } \end{array}\right\|$ | N/A | N/A |
|  | MEWNET-VE | - 10-Mbit/s high-speed large-capacity PLC link <br> - 4 layers, 254 nodes 8 k -bit link relay, 8 k -word link data | UTP-cable or transceiver cable | 10Mbit's | $\begin{array}{\|l\|} \hline \text { Max. distance } \\ 100 \mathrm{~m} \end{array}$ | A | N/A | N/A | N/A | A |  |  | N/A | N/A | N/A |
|  | MEWNET-WO | - PLC link capable of mixed connection of FP2SH, FP2, FP-X, and FPE (Sigma) <br> - Distributed control allows target PLCs to be selected | Twisted-pair | 115 kbit/s | 1200 m | A | N/A | N/A | N/A | A | A | A(x3) | A | N/A | N/A |
|  | $\begin{aligned} & \text { MEWNET- } \\ & \text { W2 } \end{aligned}$ | - 32 stations, 1200 m max. <br> - 4 k bit link relay, <br> 4k word link data | Twisted-pair | 500kbit/s ( 800 m ) 250kbit/s ( 1200 m ) |  | A | N/A | N/A | N/A | A |  |  | N/A | N/A | N/A |
|  | MEWNET-W | - 16 stations, 800 m max. <br> - 1k bit link relay, 128 word link data | Twisted-pair cable | 500kbits | 800 m | A | N/A | N/A | N/A | A |  |  | N/A | N/A | N/A |
|  | $\begin{gathered} \text { C-NET } \\ \text { (RS485) } \end{gathered}$ | - Capable of $1: \mathrm{N}$ MEWTOCOL-COM connections) for small-size PLCs and other RS485 devices | VCTF or twist- ed-pair cable | $\begin{aligned} & \text { 19,200bit/s / } \\ & 9600 \mathrm{bit} / \mathrm{s} \end{aligned}$ | 1200m | N/A | A | N/A | A | A | A | A(x3) | A | A | A |
|  | $\underset{(\mathrm{RS} 232 \mathrm{C})}{\mathrm{cCu}}$ | - 1:1 computer links (MEWTOCOL communications) by RS232C <br> - For communications with GT Displays, PV Imagechecker, etc. | RS232C | 19,200bit/s / $9600 \mathrm{bit} / \mathrm{s}$ | 15m | N/A | A | N/A | A | A |  |  | A | A | A |
|  | Modem (phone line) | - Capable of monitoring PLCs in remote locations or updating programs via the public elephone line | RS232C and phone line | 56kbit's | Up to 20km | A | A | N/A | A | A | A | N/A | A | A | A |

Notes

1) : FP Web-Server 2
2) : slave, FP0 DP-S unit
3) : for L40MR/L60MR

## Timer, counter, hour meter, temperature controller \& PLC in one unit

## Features

- 5-character, 2-line, 3-color display
- Front operation switch
- Easy programming using wizard
- Smooth debug
- Panel mounted type

Display modes and functions


Displays any characters and numerical values, and numerical data can be changed.

## S mode

(Switch mode)


Can also display characters and numerical values. Operation switches can be used for input.

## R mode

(Register mode)


Operation memory in the controller can be monitored and its data can be changed.

## I mode

(I/O monitor mode)


I/O status ( $\mathrm{X}, \mathrm{Y}$ ) in the controller can be displayed.

## Specifications

| Model |  |  | AFPE224300 <br> Basic type (RS232C) | AFPE224302 <br> Basic type (RS485) | AFPE224305 RTC type (RS232C) | AFPE214325 <br> Thermocouple input type (RS232C) | AFPE214322 <br> Thermocouple input type (RS485) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Control unit |  | 14 points [Input: 8, Output: 6 (Tr. NPN: 5/Ry: 1)] |  |  | 12 points [Input: 6, Output: 6 (Tr. NPN: 5/Ry: 1)] |  |
|  | Front switch input |  | 8 points |  |  |  |  |
| Program memory |  | Built-in memory | Built-in EEPROM |  |  |  |  |
| Program capacity |  |  | 2720 steps |  |  |  |  |
| Processing speed |  |  | 0.9 $\mathrm{s} / \mathrm{step}$ (for basic instruction) |  |  |  |  |
| Clock/calendar function |  |  | - |  | Available (year, month, day, hour, minute, second and day of week). However, this can only be used when a battery has been installed. |  | - |
| Battery life |  |  | - |  | 220 days or more (actual usage value: approx. 870 days $\left(25^{\circ} \mathrm{C}\right)$ (Periodic replacement interval: 1 year) (Value applies when no power is supplied at all.) |  | - |
| Pulse catch input/ Interrupt input |  |  | 6 points in total (X0 and X1:50 $5 \mathrm{~s}, \mathrm{X} 2$ to X 5 : $100 \mu \mathrm{~s}$ ) |  |  |  |  |
| COM port note |  |  | RS232C | RS485 | RS232C | RS232C | RS485 |
| Periodical interrupt |  |  | 0.5 ms to 30 s |  |  |  |  |
|  | High speed counter <br> * The combination of 1-phase $\times 2 \mathrm{ch}$ and 2 -phase $\times 1 \mathrm{ch}$ is also possible for the highspeed counter |  | Counter mode: Addition/subtraction (1-phase) - input points: 4ch (max.) |  |  |  |  |
|  | $\begin{aligned} & 凶 \stackrel{y}{3} \\ & \frac{0}{3} \\ & \text { Q } \\ & \hline \end{aligned}$ | Output points | 2 independent points ( Y 0 and Y 1 ) (No interpolation function) |  |  |  |  |
|  |  | Output frequency | 40 Hz to 10 kHz (YO/Y1: 1-point) $\quad 40 \mathrm{~Hz}$ to 5 kHz (Y0/Y1: 2-points) |  |  | 40 Hz to 5 kHz (1-point) 40 Hz to 2.5 kHz (2-points) |  |
|  | $\sum_{i} \frac{5}{3}$ | Output points | 2 points (Y0 and Y1) |  |  |  |  |
|  |  | Output frequency | Frequency: 0.15 Hz to 1 kHz Duty: $0.1 \%$ to $99.9 \%$ |  |  |  |  |

## Optimized for a wide range of applications

## Equipped with RS485 and RS232C interfaces

Up to 99 MEWTOCOL-COM stations possible with RS485 (RS485 type)

Up to 32 computer link stations are possible using a C-NET adapter and up to 99 are possible using a commercially available adapter. You can easily monitor operation status or perform control.


## Can even handle temperature control

Two-point K-type thermocouple ( -30 to $300^{\circ} \mathrm{C}$ ) connection possible (equipped with thermocouple input)
Can be used in place of a temperature controller or used to control them.


With RS232C, communication possible with up to two ports (RS232C type)


## PID instruction function

High-performance temperature control can be achieved with the PID instruction.


## Equipped with high-speed counter for support of 2-axis independent positioning

Pulse output function
The unit comes equipped with 2 channels for pulse output of up to 10 kHz pulses. Since these two channels can be separately controlled, the FP-e is also suitable for 2 -axis independent positioning.


## High-speed counter function

In single phase, the 4-channel total is 10 kHz , and in 2-phase the 2-channel total is 2 kHz total speed, making the FP-e suitable for inverter control, etc. (One half for the type with thermocouple input.)



## FPOR series: The ultra-compact PLCs

## Features

- Ultra high-speed processing enhances productivity
- An ultra high speed of $0.08 \mu \mathrm{~s} /$ step for basic instructions for the first 3000 steps and $0.58 \mu \mathrm{~s} /$ step thereafter. The FPOR is ideal for positioning and process automation applications, e.g. in labeling machines.
- Large programming capacity of 16 k or 32 k steps
- Generous data register of up to 12 k or 32 k words
- Independent comment memory for documenting purposes
- USB2.0 port provides high-speed program transfer
- The new F-type FPOR provides maintenance-free and complete backup of all data without requiring a battery. Industry's first!
- Highly advanced, built-in positioning functions for up to 4 axes (servo/stepping motor)
- Jog operation
- Individual settings for acceleration and deceleration for ramp functions
- Target speed can be changed by an external signal input during jog operation or trapezoidal control
- Can read encoder signals of up to 50 kHz (pulse frequency measurement)
- 6-channel high-speed counters and 4-axis pulse outputs can be used simultaneously
- FPOR units provide various kinds of networking communication using a built-in interface or expansion units
- Ethernet (Modbus TCP/IEC60870)
- Profibus
- CC-Link
- MEWNET-W0
- C-NET
- RS232C + RS484 serial communication
- FPOR - same ultra compact size as FP0
- FPOR - fully compatible with FPO units



## Spezifications for the CPU types of the FPOR

| CPU type | C10 series (relay output) | C14 series (relay output) | C16 series (transistor output) | C32 series (transistor output) | T32 series (transistor output) | F32 series (transistor output) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of inputs | 6 | 8 | 8 | 16 | 16 | 16 |
| Number of outputs | 4 relay | 6 relay | 8 NPN/PNP | 16 NPN/PNP | 16 NPN/PNP | 16 NPN/PNP |
| Output capacity | 2A | 2A | 0.2A | 0.2A | 0.2A | 0.2A |
| Digital I/O (max.) | 106 | 110 | 112 | 128 | 128 | 128 |
| Internal relays (R) | 4096 |  |  |  |  |  |
| Processing speed | Up to 3000 steps: $0.08 \mu \mathrm{~s} /$ step (basic instruction) After 3000 steps: $0.58 \mu \mathrm{~s} /$ step (basic instruction) |  |  |  |  |  |
| Program memory | EEPROM (no back-up battery required) |  |  |  |  |  |
| Program capacity | 16,000 steps |  |  | 32,000 steps |  |  |
| Data register (DT) | 12,315 words |  |  | 32,765 words |  |  |
| Memory backup (Flash ROM) | Backup with F12, P13 instruction for all areas |  |  |  |  |  |
|  | Auto backup when power is off: <br> Counters: 16 <br> Internal relays: 128 <br> Data register: 315 words |  |  |  |  | -- |
| Memory backup (RAM) | -- |  |  |  | Backup of the entire area by a built-in secondary battery | Backup of the entire area by FRAM (without the need for a battery) |
| High-speed counter | Single-phase: 6 channels (50kHz); 2-phase: 3 channels (15kHz ) |  |  |  |  |  |
| Pulse output | -- |  | 4 channels (50kHz), two channels can be controlled individually |  |  |  |
| PWM output | -- |  | 4 channels ( 6 Hz to 4.8 kHz ) |  |  |  |
| RS232C interface | Up to two serial interfaces |  |  |  |  |  |
| RS485 port | One RS485 port is mounted on each of C10MRS, C14MRS, C16MT, C16MP, C32MT, C32MP, T32MT, T32MP, F32MT, F32MP type (3P terminal block) Transmission speed (Baud rate): 19,200bits/s 115,200bits/s, Transmission distance: 1200m 9.843ft. Communication method: half duplex |  |  |  |  |  |
| Clock/calendar function | -- |  |  |  | Available | -- |
| Other functions | Rewriting in RUN mode, download in RUN mode (incl. comments) 8-character password setting, and program upload protection |  |  |  |  |  |
| Operating voltage | 24 V DC ( $\pm 10 \%$ ) |  |  |  |  |  |

## A wide variety of both single and combined units

## Control units

Relay output type


Transistor output type


| 32 points |  |
| :---: | :---: |
| Input | Output |
| 16 points | 16 points |

AFPORC32P (PNP), AFP0RC32TC (NPN) AFPORC32CP (PNP), AFPORC32CT (NPN) with 2nd RS232C AFPORC32MT, AFPORC32MP with RS485


AFPORT32CP (PNP) AFP0RT32CT (NPN) with 2nd RS232C
AFPORT32MT
AFP0RF32MT with RS485

| 32 points (F-type) |  |
| :---: | :---: |
| Input | Output |
| 16 points | 16 points |
|  |  |
| AFPORF32CP (PNP), |  |
| AFPORF32CT (NPN) with |  |
| 2nd RS232C |  |
| AFPORT32MP |  |
| AFPORF32MP with RS485 |  |

## FP Memory Loader

## AFP8670

- Read or write programs(up to 60 k steps) from or to a PLC
- Personal computer is not required - Applicable with FPOR, FP-e, FP乏 (Sigma), FP-X and FP2SH



## S-LINK MASTER CPU

 FP0-SL1- Control of 64 input and 64 output points is possible with one unit
- Simple connection of S-LINK I/O devices
- Sensors can be easily connected with plug-in connections



## Up to three expansion units can be directly connected without connection cables

The expansion unit can be attached easily without any cables to the control unit. Special expansion cables, backplanes, and so forth, are unnecessary as the expansion unit employs a stacking system that uses expansion connectors and lock levers on the surface of the unit itself.


## A maximum of 3 expansion units can be added to the control unit

## Digital I/O units

Relay output type


AFPORE8RS

| 16 points |  |
| :---: | :---: |
| Input <br> 8 points | Output <br> 8 points |
| AFPORE16RS |  |



Analog I/O units


- Input (12 bit):
$\pm 10 \mathrm{~V}, 0-5 \mathrm{~V}$,
0-20mA
- Output (12 bit):
$\pm 10 \mathrm{~V}, 0-20 \mathrm{~mA}$

- 

$\pm 10 \mathrm{~V}$

Temperature control units


- K, J, T, R type thermocouples can be used
- Resolution: $0.1^{\circ} \mathrm{C}$
- Accuracy: $0.8^{\circ} \mathrm{C}$ (R type: $3^{\circ} \mathrm{C}$ )

- Pt100, Pt1000, Ni1000
- Temperature range: -200 to $500^{\circ} \mathrm{C}$
- Temperature range:
-100 to $1500^{\circ} \mathrm{C}$


## Networking units



## Add-on unit

## Switch 2A loads within the network

Switch electrically insulated loads of AC 250VAC reliably using the FP0 Relay Terminal FP0-RT8Y-6A directly within the network.


The FPO-RT8Y-6A unit provides reliable insulation between peripheral equipment and the PLC system, even for large electrical loads.
Standardized MIL connectors establish a direct connection to the FPO unit. Thereby the FPO can act as decentralized intelligence on site and be placed directly next to the power element of the machine - be it the motor, a protective device, a magnetic valve, etc.

Many more connection products are available, please refer to "Panasonic connection technology for PLC" catalog

## Specifications FP0-RT8Y-6A



## FPOR positioning

## Jog positioning control (F171 instruction)

Motion can be started without a preset target value. When a stop signal is input, the target value is set, and the motion is slowed to a stop.


## Useful for

Labelers: Stopping the motion at a constant distance from the point where a label end detection signal is triggered

- Processing machines: Stopping the motion at a constant distance from the point where a processing object edge detection signal is triggered, and cut/drill the object


## Changing the speed (F171 and F172 instructions)

The target speed can be changed by an external signal input during the jog or trapezoidal control operation.


> Useful for
> - Speed synchronization of transfer/processing equipment

Built-in 4-axis pulse outputs (Transistor output type)
Multi-axis (4-axis) control is available without expansion units.


Simultaneously usable high speed counters ( 6 channels) and pulse outputs (4 channels)

The right-hand figure, the speed of conveyor 1 , which is inverter-controlled, is measured based on the encoder pulse count, and pulses are output to the slave motor (for jog operation) according to the measured speed in order to synchronize the speed of conveyor 2.


Individual settings for acceleration and deceleration (F171, F172, F174, and F175 instructions)


Individually settable within a range of 1 ms to $32,767 \mathrm{~ms}$

## Useful for

■ Labelers: Starting the operation at a relatively low acceleration to prevent tape from breaking Stopping the operation at high deceleration when detecting
the label end to save the tape the label end to save the tape

Measuring the pulse frequency (F178 instruction)
Pulses input in a specified period by a single instruction are counted, and the frequency is calculated.


Two sets can simultaneously undergo two-axis linear interpolation (F175 instruction).


## Built-in multipoint PWM outputs (4 channels)

A single FPOR unit can control the speeds of up to six DC motors/fan motors. It also can serve as an analog voltage output unit.



## FP $\Sigma$ (Sigma): The next generation compact PLC

## Features

- Abundant program capacity - 32k steps
- The 32k step program capacity can accommodate an in-crease in the number of programs accompanying functionality enhancements, expansions, or changes of equipment.
- Equipped with an independent comment memory
- All of 100,000 I/O comments, 5000 lines of line-space comments, and 5000 lines of remark comments are saved in FPE (Sigma) together with programs.
- Equipped with a high-speed RISC processor Equipped with an RISC processor, achieving high-speed processing with a scan time of less than 2 ms for 5000 steps.
- High-speed positioning unit The 4Mbps maximum frequency and startup speed of 0.005 ms allow use for linear servo control.
- Simple temperature control A temperature control program can be written in only one line by using the PID F356 (EZPID) instruction, facilitating temperature control by a PLC,
 which had previously been considered difficult.

| Performance specifications |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Part number |  | 32k type | $\begin{gathered} \text { FPG-C32T2H } \\ \text { FPG-C32T2HTM } \end{gathered}$ | $\begin{gathered} \text { FPG-C24R2H } \\ \text { FPG-C24R2HTM } \end{gathered}$ | $\begin{gathered} \text { FPG-C28P2H } \\ \text { FPG-C28P2HTM } \end{gathered}$ |
|  | Control unit |  | 32 points (DC input: 16, NPN output: 16) | 24 points (DC input: 16 , relay output: 8) | 28 points (DC input: 16, PNP output: 12) |
|  | With FPOR expansion units |  | Max. 128 points (up to 3 units) when using transistor output type expansion units | Max. 120 points (up to 3 units) when using transistor output type expansion units | Max. 124 points (up to 3 units) when using transistor output type expansion units |
|  | With F expan | $\Sigma \text { (Sigma) }$ <br> on units | Max. 288 points (up to 4 units) when using transistor output type expansion units | Max. 280 points (up to 4 units) when using transistor output type expansion units | Max. 284 points (up to 4 units) when using NPN output type expansion units |
|  | With F (Sigma) | OR and FPE expansion units | Max. 384 points when using transistor output type expansion units | Max. 376 points when using transistor output type expansion units | Max. 380 points when using NPN output type expansion units |
| Programming method/ Control method |  |  | Relay symbol/cyclic operation |  |  |
| Program memory |  |  | Built-in flash ROM (without backup battery) |  |  |
| Program capacity |  |  | 32k steps (32k type) |  |  |
|  | Basic |  | 93 |  |  |
|  | High-speed |  | 218 | 216 | 218 |
| Operation speed |  |  | Basic instruction: $0.32 \mu \mathrm{~s} / \mathrm{step}$ (32k type) |  |  |
|  | Internal relays (R) |  | 4096 points (32k type): R0 to R255F |  |  |
|  | Timers/counters (T/C) |  |  <br> Timer: counts in units of up to 32767 times (units: $1 \mathrm{~ms}, 10 \mathrm{~ms}, 100 \mathrm{~ms}$, or 1 s ). <br> Counter: Counts 1 to 32,767 |  |  |
|  | Link relays (L) |  | 2048 points (32k type) |  |  |
|  | Data registers (DT) |  | 32,765 words (DT0 to DT32764) ${ }^{\text {1) }}$ |  |  |
|  | Link data registers (LD) |  | 256 words (32k type) |  |  |
|  | Index registers (IX,IY) |  | 14 words (10 to ID) |  |  |
| Master Control Relay points (MCR) |  |  | 256 |  |  |
| Labels (JMP + LOOP) |  |  | 256 |  |  |
| Differential points |  |  | Unlimited |  |  |
| Number of step ladder |  |  | 1000 stages |  |  |
| Number of subroutines |  |  | 100 |  |  |
| Pulse catch input |  |  | 8 points ( X 0 to X 7 ) |  |  |
| Interrupt program |  |  | 9 programs (8 external input points (X0 to X 7 ), 1 periodical interrupt point ' 0.5 ms to 30 s ') |  |  |
| Self-diagnostic function |  |  | E. g. watchdog timer, program syntax check |  |  |
| Clock/Calendar function |  |  | Available (year, month, day, hour, minute, second and day of week); however, this function can only be used when a battery has been installed ${ }^{3}$. |  |  |
| Potentiometer (Volume) input |  |  | 2 points, resolution: 10 bits (K0 to K1000) |  |  |
| Battery life |  |  | 220 days or more (actual usage value: approx. 840 days $\left(25^{\circ} \mathrm{C}\right)$. Suggested replacement interval: 1 year. Value applies when no power at all is supplied. |  |  |
| Comment storage |  |  | All kinds of comments, including I/O comments, remarks and block comments, can be stored (without backup battery). |  |  |
| Link function |  |  | Computer Link (1:1, 1:N) ${ }^{4)}$ General-purpose communication (1:1, 1:N) ${ }^{4)}{ }^{5}$ ) PLC Link ${ }^{6}$ |  |  |
| Other functions |  |  | Online editing, constant scan, forced on/off, password, floating-point operation and PID processing |  |  |
| Linear/Circular interpolation for positioning |  |  | Available | Not available | Available |

[^0]4) An optional communication cassette (RS232C type) is required in order to use 1:1 communication.
5) An optional communication cassette (RS485 type) is required in order to use $1: \mathrm{N}$ communication.
6) An optional communication cassette (RS485 type) is required. The number of points actually available for use is determined by the hardware configuration.

## Control units: Outstanding performance in a compact design

FP $\Sigma$ - Transistor output type


| 24 points |  |
| :---: | :---: |
| Input <br> 16 points | Output relay <br> 8 points |
| Screw terminal type <br> FPG-C24R2H |  |

FPE - Transistor output type with thermistor input
FPS - Relay output type with thermistor input


## High expansion capability

FP $\Sigma$ can use the expansion units of the FPOR on the right-hand side. New FP $\Sigma$ units can be added to the left hand side.

Max. 4 expansion units each 64 I/Os = 256 I/Os
...up to 384 I/O!


Parallel expansion BUS


Control unit max. 32 I/Os


Max. 3 expansion units each $32 \mathrm{I} / \mathrm{Os}=96 \mathrm{I} / \mathrm{Os}$


## Expansion units: Wide variety - left side



FP $\Sigma$ positioning expansion units


## Expansion units left side: Network units

FP $\Sigma$ Fieldbus master expansion units


BACnet Slave

FPG-BACIP-S FPG-BACMSTP-S


Other network units


| 3channel RS485 |
| :---: |
|  |
| AFPG951T34 |

## Analog value processing: <br> Analog units FPGAD44D50 / FPGAD44D250

## Features

- Multimode A/D or D/A conversion. Voltage or current can be set separately for each channel.
- 4 analog inputs (current input: $50 \Omega$ input impedance, FPGAD44D50) 4 analog inputs (current input: $250 \Omega$ input impedance, FPGAD44D250) - standard 0 to 10 V or 0 to 20 mA
- 4 analog outputs: -10 V to $+10 \mathrm{~V}, 4$ to 20 mA
- High resolution: 16-bit input and 12-bit output
- Fast conversion speed: Inputs: 10 ms / 4 channels: outputs: $10 \mathrm{~ms} / 4$ channels
- MC terminal type connector


## General specifications

|  | Description |
| :--- | :--- |
| Rated voltage | 24 VDC |
| Operating voltage | 21.6 to 26.4 VDC |
| Current consumption | $<100 \mathrm{~mA}$ |
| Ambient temperature | $0^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$ |
| Storage temperature | $-20^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| Size | $90 \times 30 \times 60 \mathrm{~mm}(\mathrm{~W} \times \mathrm{L} \times \mathrm{H})$ |
| Weight | 150 g |



## Analog input specification

| Article no. |  | FPGAD44D50 | FPGAD44D250 |
| :---: | :---: | :---: | :---: |
| No. of channels |  | 4 channels/unit |  |
| Input range | Voltage: | 0 to 10V |  |
|  | Current: | 0 to 20 mA |  |
| Digital value |  | 0 to 10V, 0 to 20mA; K0 to K65535 |  |
| Resolution |  | 16-bit (1/65536) |  |
| Conversion speed | Voltage: | 10ms / 4 channels |  |
|  | Current: |  |  |
| Accuracy | Voltage: | $\begin{gathered} 0.1 \% \text { at } 25^{\circ} \mathrm{C}, \\ 1 \% \text { at } 55^{\circ} \mathrm{C} \end{gathered}$ |  |
| Input impedance | Voltage: | $100 \mathrm{k} \Omega$ | - |
|  | Current: | $50 \Omega$ | $250 \Omega$ |
| Max. input range | Voltage: | +15V |  |
|  | Current: | +30mA |  |
| Insulation method |  | Between analog input terminals and FPइ circuit: Optocoupler (no isolation between channels) |  |

Analog output specifications

| Article no. |  | FPGAD44D50 | FPGAD44D250 |
| :---: | :---: | :---: | :---: |
| No. of channels |  | 4 channels/unit |  |
| Output range | Voltage: | 0 to $10 \mathrm{~V},-10 \mathrm{~V}$ to +10 V |  |
|  | Current: | 4 to 20 mA |  |
| Digital value |  | 4 to $20 \mathrm{~mA}, 0$ to 10 V ; K0 to K4095 |  |
|  |  | -10V to +10V; K-4095 to K4095 |  |
| Resolution |  | 12-bit (1/4096) plus sign |  |
| Conversion speed |  | $10 \mathrm{~ms} / 4$ channels |  |
| Accuracy | Voltage: | $0.1 \%$ at $25^{\circ} \mathrm{C}$ |  |
|  | Current: | $0.3 \%$ at $25^{\circ} \mathrm{C}, 3 \%$ at $55^{\circ} \mathrm{C}$ |  |
| Input impedance | Voltage: | $100 \mathrm{k} \Omega$ | - |
|  | Current: | $50 \Omega$ | $250 \Omega$ |
| Permissible load resistance |  | Current: < $300 \Omega$ | Voltage: > 1k $\Omega$ |
| Insulation method |  | Between analog input terminals and FP乏 circuit: Optocoupler (no isolation between channels) |  |

## Specially designed for positioning application

## Max. 100kHz pulse output performance is now standard.

Powerful device capable of linear interpolation and circular interpolation.

## Pulse output max. 100kHz

Because command processing at speeds up to 100 kHz is available, high-speed, high-precision positioning is enabled. Along with stepping motor control, the specs also ensure plenty of scope for controlling servo motors.

Possible to combine with pulse-train input drivers. Single unit enables two-axis control.


## Rapid 0.02ms start (when JOG operation controls are executed)

The time taken to execute the JOG operation, from the instant the trigger (execution condition) goes on to the time of pulse output, is 0.02 ms and 0.2 ms even with trapezoidal control. Control time is reduced even for machines that quickly and repeatedly restart.

## Linear interpolation and circular interpolation are built in (FPG-C32T2H-A and FPG-C28P2H-A)

Interpolation functions enable simultaneous control of two axes.
Applications that a compact PLC couldn't previously cope with are no longer a challenge.


## And there's more:

## Smooth acceleration/deceleration

You can choose to set either 30 or 60 steps of acceleration/ deceleration. This feature means you can achieve smoother movement during long acceleration/ deceleration periods of stepping motors.
Settings allow a maximum 60 accelaration/deceleration steps.


## Support for CW/CCW method

Reduce overall costs by designing systems that combine with servo motors and small stepping motors without support for Pulse and Sign method.


## High-speed, high-precision positioning

## Programming with convenient and easy-tounderstand instructions

- Uses a preset value table for starting speed, target speed, acceleration/deceleration time, and other factors. Easy-tounderstand programming is possible since numbers can be specified intuitively.
- Comes with dedicated instructions for each mode: trapezoidal control, home return, JOG operation, free table operation, linear interpolation and circular interpolation.


## Home position return

- Pulse output diagram (when the near home input is not used).

Home search automatically reverses the motor rotation when the positive or negative limit switch is reached and searches for the home position or near home position.

## Linear interpolation

- Positioning locus.


A control function that automatically defines the continuum of points in a straight line based on only two coordinate positions.

## Selectable home return mode

- The home return method may be specified even in situations such as when only a single sensor is being used, depending on the design.
- When the home position return is completed, a deviation counter clear signal can also be output.


## JOG operation

- Pulse output diagram.


This refers to an operation in which the motor is rotated only while operation commands are being input. This is used to forcibly rotate the motor using input from an external switch, for instance when making adjustments. Depending on the circumstances, unlimited feeding can be accomplished with the JOG operation.

## Circular interpolation

- Positioning locus.
- Pass and center position methods are available.


Allows points to be smoothly traversed by arced paths for which the user specifies the orientation plane, the radius of curvature, motion path profile and direction of motion.

## Precise positioning

## Features

- Fast startup of 0.02 or 0.005 ms makes cycle time reduction possible
- Feedback pulse count function makes output pulse counting from external encoders possible
- JOG positioning control supports a wide range of applications
- 4 types of S-curve acceleration/deceleration control makes smooth startup and stopping possible:

Sine curve, quadratic curve, cycloid curve and cubic curve


- The FPE (Sigma) positioning unit can handle simultaneous startup of multiple axes, enabling simultaneous control of linear interpolation and other elements through user programs
- Transistor output type (open collector) and line driver output type are available

| Unit type and product number |  |  |
| :---: | :---: | :---: |
| Type | Output type | Part number |
| 1-axis type | Transistor output type | FPG-PP11 |
| 2-axis type | Transistor output type | FPG-PP21 |
| 1-axis type | Line driver output type | FPG-PP12 |
| 2-axis type | Line driver output type | FPG-PP22 |

Positioning control using a stepping motor


Positioning control using a servo motor


1-axis and 2-axis types are available.
Multiple axes (up to 2 axes) can be controlled with a single unit.

## RTEX multi-axis network servo system

The RTEX positioning units support Minas A4N and Minas A5N network servo drives. A mutually optimized system consisting of PLC and servo drive greatly simplifies installation.


## System configuration:

- Maximum number of control axes: 16. Realization of highly accurate 2-axis circular interpolation, 3-axis linear interpolation and 3 -axis spiral interpolation with high-speed 100Mbps communication.
- With 3 types in the product range, for 2 axes, 4 axes and 8 axes provide flexible support even for control of small numbers of axes.
- Loop wiring RTEX* provides high reliability by creating smooth communication conditions in which data always flows in the same direction.
*Panasonic Realtime Express


## Specifications:




[^0]:    Notes: 1) If no battery is used, only the fixed area is backed up (counters 16 points: C1008 to C1023, internal relays 128 points: R900 to R97F, data registers 55 words: DT32710 to DT32764). When the optional battery is used, hold-type data can be backed up. Areas to be held and not held can be specified using the system registers.
    2) The number of points can be increased by using an auxiliary timer.
    3) Precision of clock/calendar function:

    - At $0^{\circ} \mathrm{C} 32^{\circ} \mathrm{F}$, less than 119 seconds error per month.

    At $25^{\circ} \mathrm{C}$, less than 51 seconds error per month.
    At $55^{\circ} \mathrm{C}$, less than 148 seconds error per month.

