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# **AK1590**

## 1GHz Delta-Sigma Fractional-N Frequency Synthesizer

#### 1. Overview

AK1590 is a Delta-Sigma Fractional-N PLL (Phase Locked Loop) frequency synthesizer with a frequency switching function, covering a wide range of frequencies from 60 to 1000MHz. This product consists of an 18-bit Delta-Sigma modulator, a low-noise phase frequency comparator, a highly accurate charge pump, a reference divider and dual-module prescaler (P/P+1) and frequency offset adjustable circuits.

	2. Features
Operating frequency:	60 to 1000MHz
Programmable charge pump current:	In a normal operating scheme, the charge pump current can be set
	in 8 steps, in the range from 20 to 168µA.
	In a Fast Lockup scheme, the charge pump current can be set in
	8 steps, in the range from 0.8 to 2.3mA.
Supply Voltage:	2.7 to 5.5 V (PVDD pin)
Separate power supply for the charge pump:	PVDD to 5.5V (CPVDD pin)
On-chip power-saving features	
Frequency offset adjustable function:	No glitch operation for AFC(Automatic Frequency Control) and
	DFM(Digital Frequency Modulation)
General-purpose output:	Two general-purpose output ports to control peripheral parts
Low phase noise:	-201dBc/Hz
Low consumption current:	2.5mA typ
Package:	24pin QFN (0.5mm pitch, 4mm×4mm×0.7mm)
Operating temperature:	-40 to +85°C

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In this specification, the following notations are used for specific signal and register names:

[Name]: Pin name

<Name> : Register group name (Address name)

{Name} : Register bit name

## 3. Block Diagram

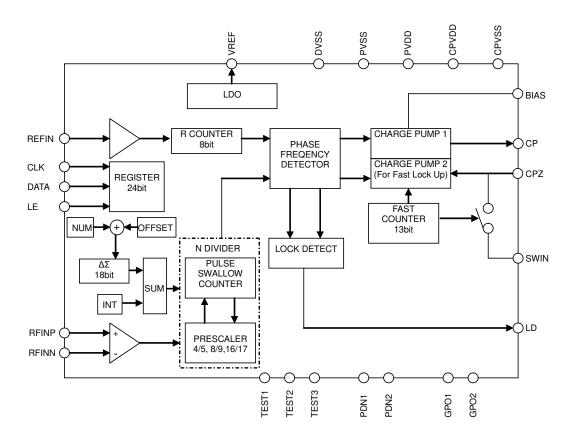


Fig. 1 Block Diagram

## 4. Pin Functional Description

**Table 1 Pin Function** 

No.	Name	I/O	Pin Functions	Power down	Remarks
1	CPVDD	Р	Power supply for charge pump		
2	TEST3	DI	Test pin 3. This pin must be connected to ground.		Internal pull-down, Schmidt trigger input
3	TEST1	DI	Test pin 1. This pin must be connected to ground.		Internal pull-down, Schmidt trigger input
4	LE	DI	Load enable		Schmidt trigger input
5	DATA	DI	Serial data input		Schmidt trigger input
6	CLK	DI	Serial clock		Schmidt trigger input
7	LD	DO	Lock detect	Low	
8	PDN2	DI	Power down pin for PLL		Schmidt trigger input
9	PDN1	DI	Power down signal for LDO		Schmidt trigger input
10	REFIN	Al	Reference input		
11	TEST2	DI	Test pin 2. This pin must be connected to ground.		Internal pull-down, Schmidt trigger input
12	GPO1	DO	General-purpose output pin 1	Low	
13	GPO2	DO	General-purpose output pin 2	Low	
14	DVSS	G	Digital ground pin		
15	VREF	AIO	Connect to LDO reference voltage capacitor	Low	
16	RFINN	Al	Prescaler input		
17	RFINP	Al	Prescaler input		
18	PVDD	Р	Power supply for peripherals		
19	BIAS	AIO	Resistance pin for setting charge pump output current		
20	PVSS	G	Ground pin for peripherals		
21	CP	AO	Charge pump output	Hi-Z	
22	CPZ	AIO	Connect to the loop filter capacitor		Note 1, Note 2
23	SWIN	Al	Connect to resistance pin for Fast Lockup		Note 1, Note 2
24	CPVSS	G	Ground pin for charge pump		

- Note 1) For detailed functional descriptions, see the section "Charge Pump and Loop Filter" in "8. Block Functional Description" below.
- Note 2) The input voltage from [CPZ] pin is used in the internal circuit. [CPZ] pin must not be open even when the Fast Lockup feature is unused. For the output destination from [CPZ] pin, see "Fig.5 Loop Filter Schematic". [SWIN] pin could be open when the Fast Lockup feature is not used.

The state of loop filter switch is ON when "[PDN1]=Low, [PDN2]=Low" or "[PDN1]=High, [PDN2]=Low".

Note 3) Power down means the state where [PDN1]=[PDN2]=Low after power on.

Al: Analog input pin	AO: Analog output pin	AIO: Analog I/O pin	DI: Digital input pin
DO: Digital output pin	P: Power supply pin	G: Ground pin	

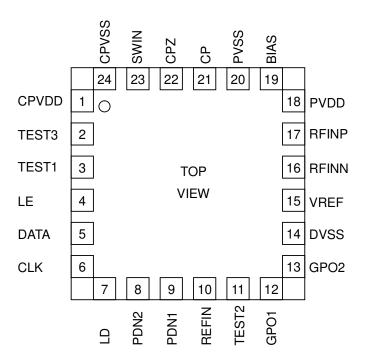


Fig. 2 Package Pin Layout

#### 5. Absolute Maximum Ratings

**Table 2 Absolute Maximum Ratings** 

Parameter	Symbol	Min.	Max.	Unit	Remarks
Cupaly Valtage	VDD1	-0.3	6.5	V	Note 1, Note 2
Supply Voltage	VDD2	-0.3	6.5	٧	Note 1, Note 3
	VSS1	0	0	٧	Voltage ground level, Note 4
Ground Level	VSS2	0	0	٧	Voltage ground level, Note 5
	VSS3	0	0	٧	Voltage ground level, Note 6
Analog Input Voltage	VAIN1	VSS1-0.3	VDD1+0.3	٧	Note 1, Note 7, Note 10
Analog Input Voltage	VAIN2	VSS2-0.3	VDD2+0.3	٧	Note 1, Note 8, Note 10
Digital Input Voltage	VDIN	VSS3-0.3	VDD1+0.3	٧	Note 1, Note 9, Note 10
Input Current	IIN	-10	10	mA	
Storage Temperature	Tstg	-55	125	°C	

Note 1) 0V reference for all voltages.

Note 2) Applied to [PVDD] pin.

Note 3) Applied to [CPVDD] pin

Note 4) Applied to [PVSS] pin.

Note 5) Applied to [CPVSS] pin.

Note 6) Applied to [DVSS] pin.

Note 7) Applied to [REFIN], [RFINN] and [RFINP] pins.

Note 8) Applied to [CPZ] and [SWIN] pins.

Note 9) Applied to [CLK], [DATA], [LE], [PDN1] and [PDN2] pins.

Note 10) Maximum must not be over 6.5V.

Exceeding these maximum ratings may result in damage to AK1590. Normal operation is not guaranteed at these extremes.

## 6. Recommended Operating Range

**Table 3 Recommended Operating Range** 

Parameter	Symbol	Min.	Тур.	Max.	Unit	Remarks
Operating Temperature	Ta	-40		85	°C	
Supply Voltage	VDD1	2.7	3.3	5.5	٧	Applied to [PVDD] pin
Supply Vollage	VDD2	VDD1	5.0	5.5	٧	Applied to [CPVDD] pin

VDD1 and VDD2 can be driven individually within the recommended operating range.

The specifications are applicable within the recommended operating range (supply voltage / operating temperature).

## 7. Electrical Characteristics

## 1. Digital DC Characteristics

**Table 4 Digital DC Characteristics** 

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit	Remarks
High level input voltage	Vih		0.8×VDD1			V	Note 1
Low level input voltage	Vil				0.2×VDD1	V	Note 1
High level input current	lih	Vih = VDD1 = 5.5V	-1		1	μА	Note 1
Low level input current	lil	Vil = 0V, VDD1 = 5.5V	-1		1	μΑ	Note 1
High level output voltage	Voh	loh = -500μA	VDD1-0.4			V	Note 2
Low level output voltage	Vol	lol = 500μA			0.4	V	Note 2

Note 1) Applied to [CLK], [DATA], [LE], [PDN1] and [PDN2] pins.

Note 2) Applied to [LD], [GPO1] and [GPO2] pins.

#### 2. Serial Interface Timing

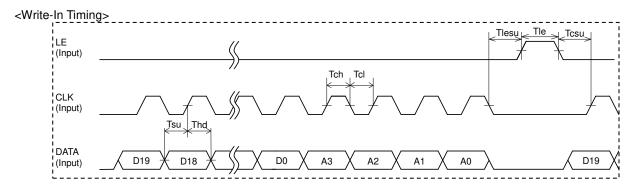


Fig. 3 Serial Interface Timing Chart

Parameter	Symbol	Min.	Тур.	Max.	Unit	Remarks
Clock L level hold time	Tcl	40			ns	
Clock H level hold time	Tch	40			ns	
Clock setup time	Tcsu	20			ns	
Data setup time	Tsu	20			ns	
Data hold time	Thd	20			ns	
LE Setup Time	Tlesu	20			ns	
LE Pulse Width	Tle	40			ns	

- Note 1) While [LE] pin is setting at "Low", 24 iteration clocks have to be set with [CLK] pin. If 25 or more clocks are set, the last 24 clocks synchronized data are valid.
- Note 2) OFFSET register must be written at the lower speed than calculated frequency by "1/3.5×RF Frequency/(INT+7)". If the writing speed is faster than this, the setting is invalid.

#### 3. Analog Circuit Characteristics

The resistance of  $27k\Omega$  is connected to [BIAS] pin, VDD1 = 2.7V to 5.5V, VDD2 = VDD1 to 5.5V,  $-40^{\circ}C \le Ta \le 85^{\circ}C$ 

Parameter	Min.	Тур.	Max.	Unit	Remarks
	RF Ch	aracteris	stics		
Input Sensitivity	-10		+5	dBm	
	60		500	MHz	Prescaler 4/5
Input Frequency	60		1000	MHz	Prescaler 8/9,16/17
	REFIN (	Characte	ristics		
Input Sensitivity	0.4		2	Vpp	
Input Frequency	5		40	MHz	
	Р	rescaler			,
Maximum Allowable Prescaler Output Frequency			125	MHz	
	Pha	se Detec	tor	J	1
Phase Detector Frequency			5	MHz	
	Cha	arge Pun	пр	1	
Charge Pump 1 Maximum Current		168.9		μА	
Charge Pump 1 Minimum Current		21.1		μА	
Charge Pump 2 Maximum Current		2.32		mA	
Charge Pump 2 Minimum Current		0.84		mA	
Icp TRI-STATE Leak Current		1		nA	0.6 ≤ Vcpo ≤ VDD2-0.7
Mismatch between Source and Sink Currents (Note 1)			10	%	Vcpo = VDD2/2, Ta = 25°C
Icp vs. Vcpo (Note 2)			15	%	0.5 ≤ Vcpo ≤ VDD2-0.5, Ta = 25°C
	R	egulator		1	
VREF Rise Time			50	μS	
	Current	Consun	nption		
IDD1			10	^	Power Down mode
			10	μΑ	[PDN1]="Low", [PDN2]="Low"
IDD2		2.4	3.6	mΛ	[PDN1]="High", [PDN2]="High"
1002		2.4	3.0	mA	IDD for [PVDD]
IDD3		0.17		mA	[PDN1]="High", [PDN2]="High"
	0	0.17		IIIA	IDD for [CPVDD] (Note 3)
IDD4		0.5		mA	Power Save mode
		0.0		111/1	[PDN1]="High", [PDN2]="Low"

Note 1) Mismatch between Source and Sink Currents:  $[(|Sink|-|Source|)/\{(|Sink|+|Source|)/2\}] \times 100 \ [\%]$ 

Note 2) See "Fig. 4 Charge Pump Characteristics - Voltage vs. Current": lcp vs. Vcpo:  $[\{1/2\times(|I1|-|I2|)\}/\{1/2\times(|I1|+|I2|)\}]\times 100 \ [\%]$ 

Note 3) IDD3 is the current that consumes constantly at [CPVDD]. This does not include the operation current in Fast Lockup mode.

- Note 4) When both [PDN1] and [PDN2] are "High", the total current consumption is equivalent to "IDD2+IDD3".
- Note 5) In the shipment test, the exposed pad on the center of the back of package is connected to ground.

#### Resistance Connected to BIAS Pin for Setting Charge Pump Output Current

Parameter	Min.	Тур.	Max.	Unit	Remarks
BIAS resistance	22	27	33	kΩ	

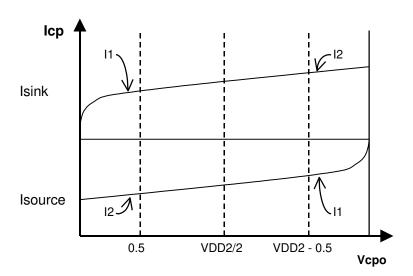


Fig. 4 Charge Pump Characteristics - Voltage vs. Current

#### 8. Block Functional Descriptions

#### 1. Frequency Setup

AK1590 is a Fractional-N type synthesizer that takes 2<sup>18</sup> as the denominator, which calculates the integer and numerator to be set using the following formulas:

```
Frequency setting = F_{PFD} \times (Integer + Numerator / 2^{18})

Integer = ROUND (Target Frequency / F_{PFD})

Numerator = ROUND {(Target Frequency - Integer × F_{PFD}) / (F_{PFD} / 2^{18})}
```

Note) ROUND: Rounded off to the nearest integer

F<sub>PFD</sub>: Phase Frequency Detector comparative Frequency (= [REFIN] input frequency / R divider ratio)

#### Calculation examples

Example 1) The numerator is positive; when the target frequency is 950.0375MHz and F<sub>PFD</sub> is 1MHz.

Integer = 950.0375MHz / 1MHz = 950.0375 It is rounded off to 950 (decimal) = 3B6 (hexadecimal) = 0011 1011 0110 (binary) Numerator =  $(950.0375MHz - 950 \times 1MHz) / (1MHz / 2^{18}) = 9830.4$  It is rounded off to 9830 (decimal) = 2666 (hexadecimal) = 10 0110 0110 0110 (binary) Frequency setting =1MHz ×  $(950 + 9830 / 2^{18}) = 950.0374985MHz$  (In this case the frequency error is 1.5Hz.)

Example 2) The numerator is negative; when the target frequency is 950.550MHz and F<sub>PFD</sub> is 1MHz.

```
Integer = 950.550MHz / 1MHz = 950.550

It is rounded off to 951 (decimal) = 3B7 (hexadecimal) = 0011 1011 0111 (binary)

Numerator = (950.550MHz - 951 \times 1MHz) / (1MHz / 2^{18}) = -117964.8

It is rounded off to -117965 (decimal), which is reduced from 2^{18} to be converted into binary for 2's complementary expression.

2^{18} - 117965 (decimal) = 144179 (decimal) = 23333 (hexadecimal) = 10 0011 0011 0011 0011 0011 (binary)

Frequency setting =1MHz × (951 + (-117965/2^{18})) = 950.5499992MHz
```

#### Calculation of 2's complement representation

1) Positive number: Binary expression (Unmanipulated) exp. 100 (decimal) 64 (hexadecimal) = 110 0100 (binary)

(In this case the frequency error is 0.8Hz.)

2) Negative number:  $2^{18}$  minus this number in binary expression exp. -100 (decimal)  $2^{18}$  - 100 = 262044 (decimal) = 3FF9C (hexadecimal) = 11 1111 1111 1001 1100 (binary)

#### 2. Charge Pump and Loop Filter

AK1590 has two charge pumps; Charge Pump 1 for normal operation and Charge Pump 2 for Fast Lockup mode.

The internal timer is used to switch these two charge pumps to achieve a Fast Lock PLL.

The loop filter is external and connected to [CP], [SWIN] and [CPZ] pins. [CPZ] pin should be connected to R2 and C2, which are intermediate nodes, even if the Fast Lockup is not used. Therefore, R2 must be connected to [CP] pin, while C2 must be connected to the ground.

R2 and R2' are connected in parallel with internal switch in Fast Lockup. These R2 and R2' parallel resistance value is required for calculating loop bandwidth and phase margin in Fast Lockup operation.

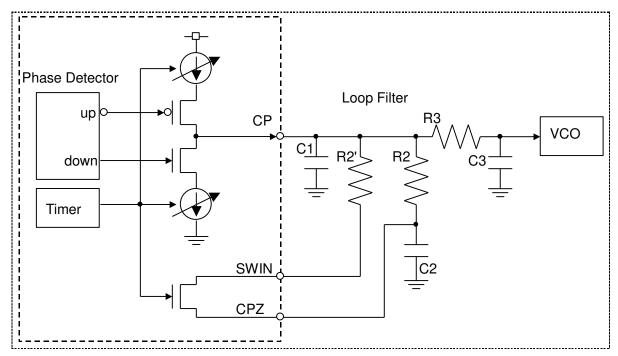


Fig. 5 Loop Filter Schematic

#### 3. Fast Lockup Mode

Setting D[16] = {FASTEN} in <Address4> to "1" enables the Fast Lockup mode for AK1590.

Changing a frequency setting (The frequency changes at the rising edge of [LE], when <Address1> and <Address2> are accessed.) or [PDN2] pin is turned from "Low" to "High" with {FASTEN}=1 enables the Fast Lockup mode. The loop filter switch turns ON during the timer period specified by the counter value in D[12:0] = {FAST[12:0]} in <Address4>, and the charge pump for the Fast Lockup mode (Charge Pump 2) is enabled. After the timer period elapsed, the loop filter switch turns OFF. The charge pump for normal operation (Charge Pump 1) is enabled. D[12:0] ={ FAST[12:0]} in <Address4> is used to set the timer period for this mode.

The following formula is used to calculate the time period:

Phase detector frequency cycle × counter value set in {FAST[12:0]}

The charge pump current can be adjusted with the register setting in 8 steps in normal operation (Charge Pump 1) and 8 steps in the Fast Lockup operation (Charge Pump 2).

The charge pump current for normal operation (Charge Pump 1) is determined by the setting in {CP1[2:0]}, which is a 3-bit address of D[17:15] in <Address2>, and a value of the resistance connected to [BIAS] pin. The following formulas show the relationship between the resistance value, the register setting and the current.

Charge Pump 1 minimum current (CP1\_min) = 0.57 / Resistance connected to [BIAS] pin Charge Pump 1 current = CP1\_min × ({CP1[2:0]} + 1)

The charge pump current for the Fast Lockup mode operation (Charge Pump 2 current) is determined by the setting in {CP2[2:0]}, which is a 3-bit address of D[15:13] in <Address4>, and a value of the resistance connected to [BIAS] pin. The following formulas show the relationship between the resistance value, the register setting and the current.

Charge Pump 2 minimum current (CP2\_min) = 5.7 / Resistance connected to [BIAS] pin Charge Pump 2 current = CP2\_min × ({CP2[2:0]} + 4)

The allowed range for the resistance (connected to [BIAS] pin) is from 22 to  $33k\Omega$  for both normal and Fast Lockup mode operations. For details of current settings, see "10. Register Functional Description".

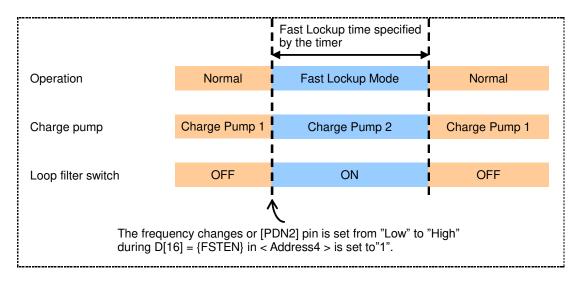


Fig. 6 Timing Chart for Fast Lockup Mode

#### 4. Lock Detect (LD) Signal

In AK1590, "lock detect" output can be selected by D[11] = {LD} in <Address3>. When D[11] is set to "1", the phase detector output provides a phase detection status as an analog level (comparison result). This is called "Analog Lock Detect".

When D[11] is set to "0", the lock detect signal outputs according to the on-chip logic. This is called "Digital Lock Detect".

#### 4.1 Analog Lock Detect

In analog lock detect, the phase detector output comes from [LD] pin.

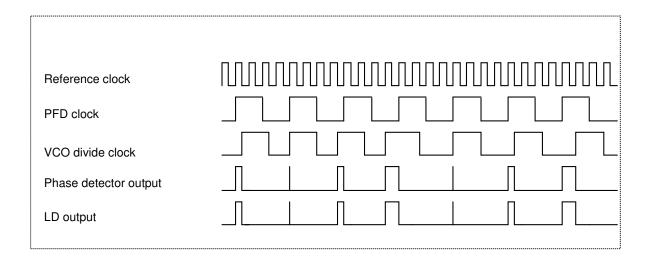


Fig. 7 Analog Lock Detect Operation

#### 4.2 Digital Lock Detect

In digital lock detect, [LD] pin outputs "Low" when the frequency is set. The output of [LD] pin turns from "Low" to "High" (which means "locked state") when a phase error smaller than T is detected for 63 times consecutively. If the phase error that is larger than T is detected for 63 times consecutively during [LD] pin outputs "High", the output of [LD] pin turns to "Low" (which means "unlocked state").

The accuracy of the phase detect is set by {LDCKSEL[1:0]}.

```
{LDCKSEL[1:0]} is set to "00": T = REFIN cycle (This is not available for the reference dividing ratio \leq 3.) {LDCKSEL[1:0]} is set to "01": T = REFIN cycle \times 2 (This is not available for the reference dividing ratio \leq 5.) {LDCKSEL[1:0]} is set to "10": T = REFIN cycle \times 3 (This is not available for the reference dividing ratio \leq 6.)
```

Since AK1590 is a Delta-Sigma Fractional-N type, a phase error up to 7 times larger than the VCO period frequency may occur in the phase detector. Therefore {LDCKSEL[1:0]} setting should be large enough to cover the amplitude of the Delta-Sigma Fractional frequency. However, if the VCO frequency does not satisfy either of the following formula, the digital lock detect is not available. In such case, the analog lock detect should be used.

Example 1)

```
When [REFIN] input frequency = 33.6MHz, {DITH} = 1, {LDCKSEL[1:0]} = "10"; 33.6MHz / (2+1) \times 7 = 78.4MHz
```

As a result, the digital lock detect is not available if the VCO frequency is equivalent to or smaller than 78.4MHz.

Example 2)

```
When [REFIN] input frequency = 33.6MHz, \{DITH\} = 0, \{LDCKSEL[1:0]\} = "01"; 33.6MHz / (1+1) \times 4 = 67.2MHz
```

As a result, the digital lock detect is not available if the VCO frequency is equivalent to or smaller than 67.2MHz.

#### □ Setup example

{DITH} = D[14] in <Address3> is set to "1" (DITH ON):

	Digital Lock Detect Available	Digital Lock Detect Unavailable
VCO frequency	180MHz	70MHz
[REFIN] input	12.8MHz	32MHz
frequency	12.0IVID2	SZIVINZ
{LDCKSEL[1:0]}	"00"	"10"
Calculation	180MHz > 12.8/(0+1) × 7 = 89.6MHz	70MHz < 32/(2+1) × 7 = 74.67MHz

#### $\{DITH\} = D[14]$ in <Address3> is set to "0" (DITH OFF):

	Digital Lock Detect Available	Digital Lock Detect Unavailable
VCO frequency	180MHz	60MHz
[REFIN] input frequency	12.8MHz	32MHz
{LDCKSEL[1:0]}	"00"	"01"
Calculation	180MHz > 12.8/(0+1) × 4 = 51.2MHz	60MHz < 32/(1+1) × 4 = 64MHz

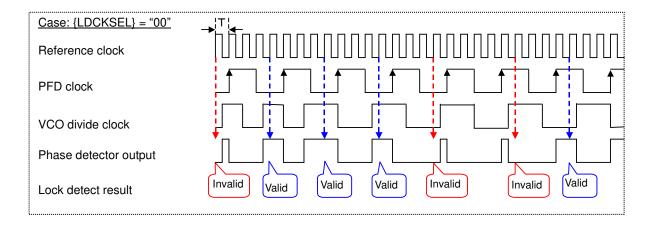


Fig. 8 Digital Lock Detect Operation

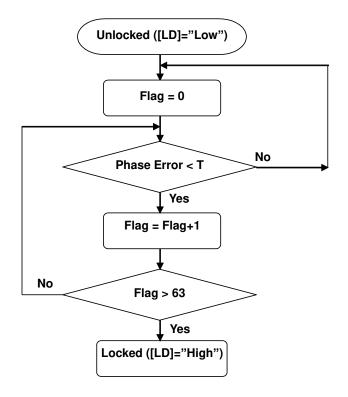


Fig. 9 Transition Flow Chart: Unlocked State to Locked State

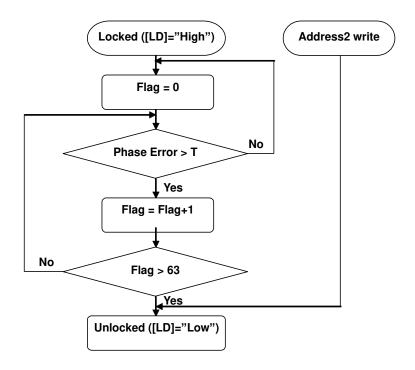


Fig. 10 Transition Flow Chart: Locked State to Unlocked State

#### 5. Reference Input

The reference input can be set with a dividing number in the range of 4 to 255 using {R[7:0]}, which is a 8-bit address in <Address3>. A dividing number from 0 to 3 cannot be set.

#### 6. Prescaler and Swallow Counter

The dual modulus prescaler (P/P+1) and the swallow counter are used to provide a large dividing ratio.

The prescaler is set by {PRE[1:0]}, which is a 2-bit address in <Address3>.

When  $\{PRE[1:0]\}$  ="00", P = 4 is selected and then an integer from 89 to 8191 can be set.

When {PRE[1:0]} ="01", P = 8 is selected and then an integer from 201 to 16383 can be set.

When {PRE[1:0]} ="10" or "11", P = 16 is selected and then an integer from 521 to 32767 can be set.

For details of how to calculate an integer, see the section "Frequency Setup" in "8. Block Functional Description".

#### 7. Operation Mode

AK1590 can be operated in Power Down or Power Save mode as necessary by using the external control pins [PDN1] and [PDN2].

Power On

See "13. Power-up Sequence".

#### Normal Operation

Pin	name	Mode				
PDN1	PDN2	woue				
"Low"	"Low"	Power Down mode				
"Low"	"High"	Prohibited				
"High"	"Low"	Power Save mode (Note 1 and Note 2)				
"High"	"High"	Normal Operation mode				

- Note 1) Registers setting can be acceptable after 50µs from [PDN1] is set to "High". The charge pump is in Hi-Z state during this period.
- Note 2) Registers value are maintained when [PDN2] is set to "Low" during normal operation mode.

## 9. Register Map

Name	Data		Add	ress	
Num		0	0	0	1
Int		0	0	1	0
Div	D19 to D0	0	0	1	1
Cp_fast	D19 10 D0	0	1	0	0
GPO		0	1	0	1
Offset		0	1	1	0

Name	D19	D18	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Address
Num	0	0	NUM [17]	NUM [16]	NUM [15]	NUM [14]	NUM [13]	NUM [12]	NUM [11]	NUM [10]	NUM [9]	NUM [8]	NUM [7]	NUM [6]	NUM [5]	NUM [4]	NUM [3]	NUM [2]	NUM [1]	NUM [0]	0x01
Int	0	0	CP1 [2]	CP1 [1]	CP1 [0]	INT [14]	INT [13]	INT [12]	INT [11]	INT [10]	INT [9]	INT [8]	INT [7]	INT [6]	INT [5]	INT [4]	INT [3]	INT [2]	INT [1]	INT [0]	0x02
Div	0	0	0	0	CP HiZ	DITH	LDCK SEL[1]	LDCK SEL[0]	LD	CP POLA	PRE [1]	PRE [0]	R [7]	R [6]	R [5]	R [4]	R [3]	R [2]	R [1]	R [0]	0x03
Cp_fast	0	0	0	FAST EN	CP2 [2]	CP2 [1]	CP2 [0]	FAST [12]	FAST [11]	FAST [10]	FAST [9]	FAST [8]	FAST [7]	FAST [6]	FAST [5]	FAST [4]	FAST [3]	FAST [2]	FAST [1]	FAST [0]	0x04
GPO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	GPO 2	GPO 1	0x05
Offset	0	0	OFST [17]	OFST [16]	OFST [15]	OFST [14]	OFST [13]	OFST [12]	OFST [11]	OFST [10]	OFST [9]	OFST [8]	OFST [7]	OFST [6]	OFST [5]	OFST [4]	OFST [3]	OFST [2]	OFST [1]	OFST [0]	0x06

- Note 1) Writing into address 0x01 is enabled when writing into address 0x02 is performed. Be sure to write into address 0x01 first and then address 0x02.
- Note 2) The initial register values are not defined just after [PDN1] releases ([PDN1] set to "High"). Therefore, even after [PDN1] is set to "High", each bit value remains undefined. In order to set all register values, it is required to write the data in all addresses of the register.

## 10. Register Functional Description

#### < Address 1: Num >

D19	D18	D[17:0]	Address
0	0	NUM[17:0]	0001

Note) Writing into address 0x01 is enabled when writing into address 0x02 is performed.

#### NUM[17:0]: Set the numerator in 2's complementary representation.

#### < Address 2: Int >

D19	D18	D[17:15]	D[14:0]	Address
0	0	CP1[2:0]	INT[14:0]	0010

#### CP1[2:0]: Set the current value for the charge pump in normal operation (Charge Pump 1).

Charge Pump 1 current is determined by the following formula:

CP1\_min = 0.57 / Resistance connected to [BIAS] pin

Charge Pump 1 current = CP1\_min × ({CP1[2:0]} + 1)

D[17.15]	Cha	rge Pump 1 current	[μΑ]
D[17:15]	22kΩ	27kΩ	33kΩ
000	25.9	21.1	17.3
001	51.8	42.2	34.5
010	77.7	63.3	51.8
011	103.6	84.4	69.1
100	129.5	100.6	86.4
101	155.5	126.7	103.6
110	181.4	147.8	120.9
111	207.3	168.9	138.2

#### INT[14:0] : Set the integer.

When  $\{PRE[1:0]\}$  ="00", P = 4 is selected and then an integer from 89 to 8191 can be set. When  $\{PRE[1:0]\}$  ="01", P = 8 is selected and then an integer from 201 to 16383 can be set.

When  $\{PRE[1:0]\}$  ="10" or "11", P = 16 is selected and then an integer from 521 to 32767 can be set.

#### < Address 3: Div >

D19	D18	D17	D16	D15	D14	D[13:12]	D11	D10	D[9:8]	D[7:0]	Addres
0	0	0	0	CPHIZ	DITH	LDCKSEL[1:0]	LD	CPPOLA	PRE[1:0]	R[7:0]	0011

#### CPHIZ: Select normal or TRI-STATE for the CP1/CP2 output.

D15	Function	Remarks			
0	Charge pumps are activated	Use this setting for normal operation			
1	TRI-STATE	Note 1)			

Note 1) The charge pump output is put in Hi-Z state.

#### DITH: Select dithering ON or OFF for a delta-sigma circuit.

D1	Function	Remarks			
0	DITH OFF	Low Noise mode			
1	DITH ON	Low Spurious mode			

It is used to control the turning On or Off for dithering to cancel cyclical noise.

When OFFSET register is used, set DITH=0(OFF).

#### LDCKSEL[1:0] : Set phase error values for lock detect.

D13	D12	Function	Remarks
0	0	1 cycle of the REFIN clock	
0	1	2 cycles of the REFIN clock	
1	0	3 cycles of the REFIN clock	
1	1	Prohibited	

For detailed functional descriptions, see the section "Lock Detect (LD) Signal" in "8. Block Functional Description".

#### LD: Select analog or digital for the lock detect.

D11	Function	Remarks
0	Digital Lock Detect	
1	Analog Lock Detect	

For detailed functional descriptions, see the section "Lock Detect (LD) Signal" in "8. Block Functional Description".

#### CPPOLA: Select positive or negative output polarity for Charge Pump 1 and Charge Pump 2.

D10	Function	Remarks
0	Positive	
1	Negative	

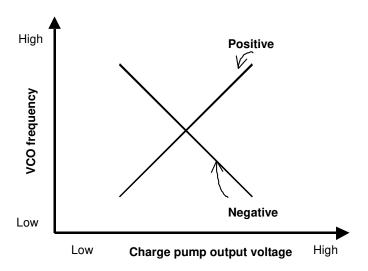


Fig. 11 Charge Pump slope Polarity

PRE[1:0] : Select a dividing ratio for the prescaler.

D9	D8	Function	Remarks
0	0	P=4	
0	1	P=8	
1	0	P=16	
1	1	P=16	

R[7:0]: Set a dividing ratio for the reference clock.

This can be set in the range from 4 (4 divisions) to 255 (255 divisions). 0 to 3 cannot be set.

9 ( )									•
D7	D6	D5	D4	D3	D2	D1	D0	Function	Remarks
0	0	0	0	0	0	0	0	0	Prohibited
0	0	0	0	0	0	0	1	1	Prohibited
0	0	0	0	0	0	1	0	2	Prohibited
0	0	0	0	0	0	1	1	3	Prohibited
	DATA								
1	1	1	1	1	1	0	1	253	
1	1	1	1	1	1	1	0	254	
1	1	1	1	1	1	1	1	255	

## < Address 4: Cp\_fast >

D19	D18	D17	D16	D[15:13]	D[12:0]	Addres
0	0	0	FASTEN	CP2[2:0]	FAST[12:0]	0100

#### FASTEN: Enable or disables the Fast Lockup mode.

D16	Function	Remarks
0	The switchover settings specified in CP2[2:0] and FAST[12:0] are disabled.	
1	The switchover settings specified in CP2[2:0] and FAST[12:0] are enabled.	

# CP2[2:0]: Set the current value for the charge pump for the Fast Lockup mode (Charge Pump 2).

Charge Pump 2 current is determined by the following formula:

CP2\_min = 5.7 / Resistance connected to [BIAS] pin

Charge Pump 2 current =  $CP2\_min \times (\{CP2[2:0]\} + 4) [mA]$ 

D[45,42]	Charge Pump 2 current [mA]							
D[15:13]	22kΩ	27kΩ	33kΩ					
000	1.04	0.84	0.69					
001	1.30	1.06	0.86					
010	1.55	1.27	1.04					
011	1.81	1.48	1.21					
100	2.07	1.69	1.38					
101	2.33	1.90	1.55					
110	2.59	2.11	1.73					
111	2.85	2.32	1.90					

#### FAST[12:0] : Set the FAST counter value.

A decimal number from 1 to 8191 can be set. This counter value is used to set the time period during which the charge pump for the Fast Lockup mode is ON.

The charge pump for the Fast Lockup mode is turned OFF after the time period calculated by "this count value × the reference clock cycle". 0 cannot be set.

D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Function	Remarks
0	0	0	0	0	0	0	0	0	0	0	0	0	0	Prohibited
0	0	0	0	0	0	0	0	0	0	0	0	1	1	
0	0	0	0	0	0	0	0	0	0	0	1	0	2	
	DATA													
1	1	1	1	1	1	1	1	1	1	1	0	1	8189	
1	1	1	1	1	1	1	1	1	1	1	1	0	8190	
1	1	1	1	1	1	1	1	1	1	1	1	1	8191	

#### < Address 5: GPO >

D[19:2]	D1	D0	Address
0	GPO2	GPO1	0101

#### GPO2: Set the state of [GPO2] pin

This value controls the General-Purpose Output pin GPO2.

The voltage applied to PVDD pin determines the "High" output level.

D1	Function	Remarks
0	"Low" output from the GPO2 pin	
1	"High" output from the GPO2 pin	

#### GPO1: Set the state of [GPO1] pin

This value controls the General-Purpose Output pin GPO1.

The voltage applied to the PVDD pin determines the "High" output level.

D0	Function	Remarks
0	"Low" output from the GPO1 pin	
1	"High" output from the GPO1 pin	

#### < Address 6: Offset >

D19	D18	D[17:0]	Address
0	0	OFST[17:0]	0110

#### OFST[17:0]: Set the adjustable frequency offset in 2's complementary representation.

This register designates offset from carrier frequency.

After this register is accessed, {NUM[17:0]} is recalculated and {NUM[17:0]}+{OFST[17:0]} are used in delta-sigma and N-divider as the numerator. When this register is not used, this register must be written 00000 (hexadecimal).

When this register is used continuously as below,

$$\{\mathsf{OFST}\}(0) \to \{\mathsf{OFST}\}(1) \to \ldots \to \{\mathsf{OFST}\}(k-1) \to \{\mathsf{OFST}\}(k) \to \{\mathsf{OFST}\}(k+1) \to \ldots$$

{NUM} and {OFST} can be set in the below range.

 $-131072 \le |\{NUM\}+\{OFST\}| \le 131071 \text{ (decimal)}$ 

 $|\{OFST\}(k)-\{OFST\}(k-1)| \le 2000 \text{ (decimal)}$ 

When this register is used in out of this range, the circuit of delta-sigma modulator may cause unexpected glitches in VCO control voltage.

When OFFSET register is used, set DITH=0(OFF).