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### Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





### AN32150B

http://www.semicon.panasonic.co.jp/en/

### LED Driver LSI with Step-up Charge Pump Control Circuit

#### FEATURES

- 7 x 7 LED Matrix Driver
  - (Total LED that can be driven = 49)
- Step-up charge pump DC/DC converter : 300 mA
- LDO : 2-ch.
- GPIO : 3-ch.
- GPO : 6-ch. (They are in common with LED driver terminals.)
- SPI interface / I<sup>2</sup>C interface selectable
- LED drivers (for backlight : 7-ch., for RGB : 3-ch., matrix LED driver : 7  $\times$  7-ch.)
- LED brightness control function with an external illumination sensor
- 55pin Wafer Level Chip Size Package (WLCSP)

#### DESCRIPTION

AN32150B is a LED driver and a light intensity controller. It can drive up to 7 channels of LCD backlight, 3 channels of RGB LEDs and 7 channels of LED matrix.

Voltage is supplied by a step-up charge pump DC/DC converter.

#### **APPLICATIONS**

- Mobile Phone
- Smart Phone
- PCs
- Game Consoles
- Home Appliances etc.



#### Note)

The application circuit is an example. The operation of the mass production set is not guaranteed. Sufficient evaluation and verification is required in the design of the mass production set. The Customer is fully responsible for the incorporation of the above illustrated application circuit in the design of the equipment.

### TYPICAL APPLICATION



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#### **ABSOLUTE MAXIMUM RATINGS**

Parameter	Symbol	Rating	Unit	Note
	VB <sub>MAX</sub>	6.0	V	*1
Supply voltage	VLED <sub>MAX</sub>	6.5	V	*1
	VDD <sub>MAX</sub>	4.3	V	*1
Operating ambience temperature	T <sub>opr</sub>	– 30 to + 85	°C	*2
Operating junction temperature	Tj	– 30 to + 125	°C	*2
Storage temperature	T <sub>stg</sub>	– 55 to + 125	°C	*2
Input Voltage Range	GPIO1, GPIO2, GPIO3, PD2, PD3, SERSEL, SLAVE, SCL, SDA	– 0.3 to 4.3	V	_
	NRESET, LDOCNT	– 0.3 to 6.0	V	_
	PD1	– 0.3 to 4.3	V	_
	LDO1, LDO2, INT	– 0.3 to 6.0	V	_
Output Voltage Range	SW1, SW2, SW3, SW4, SW5, SW6, SW7, LED1, LED2, LED3, LED4, LED5, LED6, LED7, LED8, LED9, LED10, LED11, LED12, LED13, LED14, LED15, LED16, LED17	– 0.3 to 6.5	V	_
ESD	HBM	1.0 to 1.5	kV	_

Note) This product may sustain permanent damage if subjected to conditions higher than the above stated absolute maximum rating. This rating is the maximum rating and device operating at this range is not guaranteeable as it is higher than our stated recommended operating range. When subjected under the absolute maximum rating for a long time, the reliability of the product may be affected.

\*1:  $VB_{MAX} = VBCP = VB$ ,  $VDD_{MAX} = VDD$ ,  $VLED_{MAX} = VLED$ 

The values under the condition not exceeding the above absolute maximum ratings and the power dissipation. \*2: Except for the power dissipation, operating ambient temperature, and storage temperature, all ratings are for

T<sub>a</sub> = 25°C.

#### POWER DISSIPATION RATING

PACKAGE	$\theta_{AL}$	Р <sub>D</sub> (Та=25 °С)	Р <sub>D</sub> (Та=85 °С)
55 pin Wafer Level Chip Size Package (WLCSP)	120.02 °C /W	0.833 W	0.333 W

Note) For the actual usage, please refer to the P<sub>D</sub>-Ta characteristics diagram in the package specification, follow the power supply voltage, load and ambient temperature conditions to ensure that there is enough margin and the thermal design does not exceed the allowable value.



### CAUTION

Although this LSI has built-in ESD protection circuit, it may still sustain permanent damage if not handled properly. Therefore, proper ESD precautions are recommended to avoid electrostatic damage to the MOS gates.

#### **RECOMMENDED OPERATING CONDITIONS**

Parameter	Symbol	Min.	Тур.	Max.	Unit	Note
	VB	3.1	3.6	4.6	V	*1
Supply voltage range	VLED	3.1	4.5	5.8	V	*1
	VDD	1.7	1.85	3.2	V	*1
Input Voltage Range	GPIO1, GPIO2, GPIO3, PD2, PD3, SERSEL, SLAVE, SCL, SDA	- 0.3	_	VDD + 0.3	V	*2
	NRESET, LDOCNT	- 0.3	_	VB + 0.3	V	*2
	PD1	- 0.3	_	VDD + 0.3	V	*2
	LDO1, LDO2, INT	- 0.3		VB + 0.3	V	*2
Output Voltage Range	SW1, SW2, SW3, SW4, SW5, SW6, SW7, LED1, LED2, LED3, LED4, LED5, LED6, LED7, LED8, LED9, LED10, LED11, LED12, LED13, LED14, LED15, LED16, LED17	- 0.3		VLED + 0.3	V	*2

Note) \*1: The values under the condition not exceeding the above absolute maximum ratings and the power dissipation. Do not apply external currents and voltages to any pin not specifically mentioned. Voltage values, unless otherwise specified, are with respect to GND. GND is voltage for AGND, CPGND, LEDGND1, LEDGND2 and LEDGND3.

VDD is voltage for VDD. VB is voltage for VB and VBCP. VLED is voltage for VLED.

\*2: (VDD + 0.3 ) V must not exceed 4.3 V. (VB + 0.3 ) V must not exceed 6 V.

(VLED + 0.3) V must not exceed 6.5 V.

### **ELECTRICAL CHARACTERISTICS**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \circ C \pm 2 \circ C$  unless otherwise specified

Paramotor		Symbol	hol Condition		Limits			Note	
	Falailielei	Symbol	Condition	Min	Тур	Max	Unit	Note	
Curr	ent consumption								
( 8	Current consumption (1) at OFF mode	ICC1	VB = 4.6 V LDOCNT = Low	_	0	1	μA		
( 2	Current consumption (2) at LDO1 and LDO2 normal mode	ICC2	LDO1 to 2PS = [0] (LDO1, 2 normal mode) LDO1ON = [1] (LDO1 ON) VB = 4.6 V LDOCNT = High		130	300	μΑ	_	
( a L	Current consumption (3) at LDO1 OFF mode, _DO2 power save mode	ICC3	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = 4.6 V LDOCNT = High		10	25	μA	_	
( 2 1 1	Current consumption (4) at VB through mode, _DO1 OFF mode, _DO2 power save mode	ICC4	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = 4.6 V LDOCNT = High VB through mode $I_{CPOUT} = 0 \text{ mA}$ LED10ON = [1] (Current 0)	_	1.0	3.0	mA	_	
( 2 ( 1 1	Current consumption (5) at charge pump 1.5× (600 kHz operating) mode, _DO1 OFF mode, _DO2 power save mode	ICC5	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = $3.1 \text{ V}$ LDOCNT = High LED10ON = [1] (current 0) Charge Pump ON, $1.5\times$ , 600 kHz operating mode I <sub>CPOUT</sub> = 0 mA		2.0	5.0	mA		

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

	Demonster	O. makes I	Condition		Limits		11	Nete
	Parameter	Symbol	Condition	Min	Тур	Мах	Unit	Note
Cu	rrent consumption					1		
	Current consumption (6) at charge pump 1.5× (1.2 MHz operating) mode, LDO1 OFF mode, LDO2 power save mode	ICC6	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = $3.1 \text{ V}$ LDOCNT = High LED10ON = [1] (current 0) Charge Pump ON, $1.5\times$ , 1.2  MHz operating mode $I_{CPOUT} = 0 \text{ mA}$		5.0	9.0	mA	
Ret	ference voltage							
	Output voltage	VREF	VB = 3.1 V to 4.6 V	1.21	1.24	1.27	V	_
Vo	tage regulator (LDO1) normal mo	de loutma	x = –100 mA					
	Output voltage (1) 1.85 V mode	VL11	VB = 3.1 V to 4.6 V I <sub>LDO1</sub> = -10 µA to -100 mA	1.79	1.85	1.91	V	_
	Output voltage (2) 2.85 V mode	VL12	VB = 3.1 V to 4.6 V I <sub>LDO1</sub> = -10 μA to -100 mA	2.76	2.85	2.94	v	_
	Short circuit protection current (1) 1.85 V mode	IPT11	LDOCNT = High V <sub>LDO1</sub> = 0 V	20	50	150	mA	_
	Short circuit protection current (2) 2.85 V mode	IPT12	LDOCNT = High V <sub>LDO1</sub> = 0 V	20	50	150	mA	_
	Ripple rejection (1) 1.85 V mode	PSL11	VB = 3.6 V + 0.2 V[p-p] f = 1 kHz I <sub>LDO1</sub> = -50 mA PSL11 = 20 log(acV <sub>LDO1</sub> / 0.2)	_	-70	-60	dB	
	Ripple rejection (2) 1.85 V mode	PSL12	VB = 3.6 V + 0.2 V[p-p] f = 10 kHz I <sub>LDO1</sub> = -50 mA PSL12 = 20 log(acV <sub>LDO1</sub> / 0.2)	_	-60	-50	dB	_
	Ripple rejection (3) 2.85 V mode	PSL13	VB = 3.6 V + 0.2 V[p-p] f = 1 kHz I <sub>LDO1</sub> = -50 mA PSL13 = 20 log(acV <sub>LDO1</sub> / 0.2)	_	-70	-60	dB	
	Ripple rejection (4) 2.85 V mode	PSL14	VB = 3.6 V + 0.2 V[p-p] f = 10 kHz I <sub>LDO1</sub> = -50 mA PSL14 = 20 log(acV <sub>LDO1</sub> / 0.2)	_	-60	-50	dB	

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \ ^{\circ}C \pm 2 \ ^{\circ}C$  unless otherwise specified

	Paramotor	Symbol	Condition		Limits		Unit	Note
	Parameter	Symbol Condition		Min	Тур	Max	Unit	Note
Vo	ltage regulator (LDO1) power sav	ve mode : lo	utmax = – 15 mA (loutmax = –	• 5 mA a	at 2.85 V	setting	)	
	Output voltage (1)	VLPS11	VB = 3.1 V to 4.6 V I <sub>LDO1</sub> = – 10 μA to – 15 mA	1.79	1.85	1.91	V	_
	Output voltage (2)	VLPS12	VB = 3.1 V to 4.6 V $I_{LDO1}$ = - 10 $\mu$ A to - 5 mA	2.76	2.85	2.94	V	
Vo	Itage regulator (LDO2) normal mo	ode loutmax	k = − 100 mA					
	Output voltage	VL2	VB = 3.1 V to 4.6 V $I_{LDO2}$ = - 10 µA to - 100 mA	2.76	2.85	2.94	V	
	Short circuit protection current	IPT2	LDOCNT = High V <sub>LDO2</sub> = 0 V	20	50	150	mA	
	Ripple rejection (1)	PSL21	VB = 3.6 V + 0.2 V[p-p] f = 1 kHz I <sub>LDO2</sub> = - 50 mA PSL21 = 20 log(acV <sub>LDO2</sub> / 0.2)	_	- 70	- 60	dB	_
	Ripple rejection (2)	PSL22	VB = 3.6 V +0.2 V[p-p] f = 10 kHz I <sub>LDO2</sub> = - 50 mA PSL22 = 20 log(acV <sub>LDO2</sub> / 0.2)		- 60	- 50	dB	
Vo	Itage regulator (LDO2) power sav	ve mode lou	utmax = – 5 mA					
	Output voltage	VLPS2	VB = 3.1 V to 4.6 V $I_{LDO2} = -10 \ \mu A$ to $-5 \ m A$	2.76	2.85	2.94	V	

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

	Baramatar	Symbol Condition			Limits		Unit	Note	
	Farameter	Symbol	Condition	Min	Тур	Мах	Unit	Note	
Ch	arge pump DC/DC converter		,						
	Oscillator frequency	FDC1	VB = 3.1 V to 4.6 V	1.92	2.40	2.88	MHz		
VB	through switch								
	Resistance at switch ON	RVBS	$VB = 4.5 V$ $I_{CPOUT} = -30 mA$ $RVBS = (V_{VBCP} - V_{CPOUT}) / 30$ $mA$	_	0.6	1	Ω		
sc	SCAN switch								
	Resistance at switch ON	RSCAN	VLED = 4.5 V $I_{SW1}$ to $I_{SW7}$ = 20 mA RSCAN = $V_{SW1}$ to $V_{SW7}$ / 20 mA	_	1	2	Ω		
Cu	rrent regulator (LED1 to 7)								
	Output current (1)	IBL1	At 31.750 mA setting $V_{LED1}$ to $V_{LED7} = 1 V$ IBL1 = I <sub>LED1</sub> to I <sub>LED7</sub>	30.132	31.718	33.304	mA	*1	
	Output current (2)	IBL2	At 1 mA setting $V_{LED1}$ to $V_{LED7} = 1 V$ IBL2 = I <sub>LED1</sub> to I <sub>LED7</sub>	0.948	0.998	1.048	mA	*1	
	Current step	IBSTEP	Minimum current step	0	125	250	μA		
	Off leak current	IBLOFF	OFF setting $V_{LED1}$ to $V_{LED7}$ = 4.5 V IBLOFF = I <sub>LED1</sub> to I <sub>LED7</sub>	_	_	1	μA	_	
	Error between channels	IBLCH	At 16 mA setting Current error between each channel and the median of LED1 to LED7	- 5	_	5	%	_	

Note) \*1 : Allowable value at the time when the recommended parts (ERJ2RHD393X) is connected to IREF.

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

Devenenter	Cumhal	Condition		Limits		Unit	Nata
Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note
Current regulator (LED8 to 1	0)						
Output current (1)	IRGB1	At 31.750 mA setting $V_{LED8}$ to $V_{LED10} = 1 V$ IRGB1 = ILED8 to LED10	30.087	31.671	33.254	mA	*1
Output current (2)	IRGB2	At 1 mA setting $V_{LED8}$ to $V_{LED10} = 1 V$ IRGB2 = I <sub>LED8</sub> to I <sub>LED10</sub>	0.946	0.996	1.046	mA	*1
Current step	IRGBSTEP	Minimum current step	0	125	250	μA	_
Off leak current	IRGBOFF	OFF setting $V_{LED8}$ to $V_{LED10} = 4.5 V$ IRGBOFF = $I_{LED8}$ to $I_{LED10}$	_		1	μA	
Error between channels	IRGBCH	At 16 mA setting Current error between each channel and the median of LED8 to LED10	-5	_	5	%	_
Current regulator (LED11 to	17)			1	1	1	
Output current (1)	IMX1	At 1 mA setting $V_{LED11}$ to $V_{LED17} = 1 V$ IMX1 = $I_{LED11}$ to $I_{LED17}$	0.943	0.993	1.043	mA	*1
Output current (2)	IMX2	At 2 mA setting $V_{LED11}$ to $V_{LED17} = 1 V$ IMX2 = I <sub>LED11</sub> to I <sub>LED17</sub>	1.891	1.990	2.090	mA	*1
Output current (3)	IMX3	At 4 mA setting $V_{LED11}$ to $V_{LED17} = 1 V$ IMX3 = I <sub>LED11</sub> to I <sub>LED17</sub>	3.768	3.966	4.164	mA	*1
Output current (4)	IMX4	At 8 mA setting $V_{LED11}$ to $V_{LED17} = 1 V$ $IMX4 = I_{LED11}$ to $I_{LED17}$	7.558	7.956	8.354	mA	*1
Output current (5)	IMX5	At 15 mA setting $V_{LED11}$ to $V_{LED17} = 1 V$ IMX5 = $I_{LED11}$ to $I_{LED17}$	14.172	14.918	15.663	mA	*1
Off leak current	IMXOFF	OFF setting $V_{LED11}$ to $V_{LED17}$ = 4.5 V IMXOFF = I <sub>LED11</sub> to I <sub>LED17</sub>	_	_	1	μA	
Error between channels	ІМХСН	At 15 mA setting Current error between each channel and the median of LED11 to LED17	- 5	_	5	%	_

Note) \*1 : Allowable value at the time when the recommended parts (ERJ2RHD393X) is connected to IREF.

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \circ C \pm 2 \circ C$  unless otherwise specified

	Devementer	Symbol	Condition		Limits			Nata
	Parameter	Symbol		Min	Тур	Max	Unit	Note
٥v	ervoltage detection							
	Detection voltage	VOV	Charge pump DC/DC overvoltage detection	5.3	5.5	5.7	V	_
Ste	ep-up mode switch of charge pur	np						
	Detection voltage (1)	VLD1	LED1 to LED7 pin voltage at the time when the step-up mode switch of charge pump changes		0.35	0.40	V	_
	Detection voltage (2)	VLD2	LED8, 9 and 10 pin voltage at the time when the step-up mode switch of charge pump changes	_	0.35	0.40	V	_
Mir	nimum voltage at which LED driv	er can keep	constant current value					
	Minimum voltage at which LED driver can keep constant current value	VLD3	95% LED current value at the time when LED1 to LED17 pin voltage is set to 1 V. Minimum value of LED1 to LED17 pin voltage		0.20	0.35	V	



#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

	Perometer		Symbol Condition		Limits			Note
	Farameter	Symbol	Condition	Min	Тур	Мах	Unit	Note
GP	IO I/F							
	High lovel input veltage range (1)		High-level recognition voltage of GPIO1 to 3.					
	at 1.85 V mode operation	VIH1	IOVSEL1 to 3 = [1]	1.5	—	+0.3	V	—
			(Output voltage LDO1 level setting) LDO1VSEL = [0]					
	Low-level input voltage range (1)	VIL1	Low-level recognition voltage of GPIO1 to 3. IOVSEL1 to 3 = [1]	- 0.3	_	0.4	V	_
	at 1.85 V mode operation		(Output voltage LDO1 level setting) LDO1VSEL = [0]					
	High-level input voltage range (2) at 2.85 V mode operation	VIH2	High-level recognition voltage of GPIO1 to 3. LDO1VSEL = [1]	2.3	—	LDO1 + 0.3	V	_
	Low-level input voltage range (2) at 2.85 V mode operation	VIL2	Low-level recognition voltage of GPIO1 to 3. LDO1VSEL = [1]	- 0.3	—	0.6	V	
	High-level input current	IIH1	$V_{GPIO1}$ to $V_{GPIO3}$ = 2.85 V IIH1 = I <sub>GPIO1</sub> to I <sub>GPIO3</sub>		0	1	μA	_
	Low-level input current	IIL1	$V_{GPIO1}$ to $V_{GPIO3} = 0 V$ IIL1 = I <sub>GPIO1</sub> to I <sub>GPIO3</sub>		0	1	μA	
	High-level output voltage (1)	VOH1	V <sub>GPI01</sub> to V <sub>GPI03</sub> = – 2 mA IOVSEL1 to 3 = [0] (Output voltage LDO2 level setting)	LDO2 × 0.8	_	_	V	_
	Low-level output voltage (1)	VOL1	I <sub>GPIO1</sub> to I <sub>GPIO3</sub> = 2 mA IOVSEL1 to 3 = [0] (Output voltage LDO2 level setting)			LDO2 × 0.2	V	
	High-level output voltage (2)	VOH2	I <sub>GPIO1</sub> to I <sub>GPIO3</sub> = – 2 mA IOVSEL1 to 3 = [1] (Output voltage LDO1 level setting)	LDO1 × 0.8	_	_	V	
	Low-level output voltage (2)	VOL2	I <sub>GPIO1</sub> to I <sub>GPIO3</sub> = 2 mA IOVSEL1 ~ 3 = [1] (Output voltage LDO1 level setting)	_	_	LDO1 × 0.2	V	_
	Pull-down resistance	RPD	$I_{GPIO1}$ to $I_{GPIO3} = 5 \ \mu A$ RPD = $V_{GPIO1}$ to $V_{GPIO3} / 5 \ \mu A$	60	110	210	kΩ	_

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

	Paramotor	Symbol	Condition		Limits		Unit	Note
	Falameter	Symbol	Condition	Min	Тур	Max	Unit	Note
LD	OCNT							
	High-level input voltage range	VIH3	High-level recognition voltage	1.6		VB + 0.3	V	
	Low-level input voltage range	VIL3	Low-level recognition voltage	- 0.3	—	0.4	V	_
	High-level input current	IIH2	$V_{LDOCNT}$ = 3.6 V	_	0	1	μA	—
	Low-level input current	IIL2	V <sub>LDOCNT</sub> = 0 V		0	1	μA	—
NR	NRESET							
	High-level input voltage range	VIH4	High-level recognition voltage	1.5		VB + 0.3	V	_
	Low-level input voltage range	VIL4	Low-level recognition voltage	- 0.3		0.6	V	
	High-level input current	IIH3	V <sub>NRESET</sub> = 3.6 V	_	0	1	μA	_
	Low-level input current	IIL3	V <sub>NRESET</sub> = 0 V		0	1	μA	_
ІМТ	ſ							
	ON resistance	RINTON	I <sub>INT</sub> = 5 mA RINTON = V <sub>INT</sub> / 5 mA			50	Ω	

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \circ C \pm 2 \circ C$  unless otherwise specified

Paramotor		Symbol Condition			Unit	Note		
	Falameter	Symbol	Condition	Min	Тур	Мах	Unit	Note
l²C	I/F							
	High-level input voltage	VIH5	High-level recognition voltage of SDA, SCL	0.7 × VDD	_	VDD + 0.5, 3.2	V	*2
	Low-level input voltage	VIL5	Low-level recognition voltage of SDA, SCL	- 0.5	—	0.3 × VDD	V	
	Low-level output voltage 1		VDD > 2 V I <sub>SDA</sub> = 3 mA	0		0.4	V	
	Low-level output voltage 2		VDD < 2 V I <sub>SDA</sub> = 3 mA	0	_	0.2 × VDD	V	
	Input current each I/O pin	li	$V_{SDA}$ , $V_{SCL}$ = 0.1 V to 2.88 V	- 10	0	10	μA	—
	SCL clock frequency	f <sub>SCL</sub>	—	0	_	400	kHz	
Light Intensity Control								
	PD1 pin ON resistance	RPD10N	—			100	Ω	
	PD3 pin ON resistance	RPD3ON	—	—	—	50	Ω	_
	A/D converted value (1)	AD1	V <sub>PD2</sub> = VLPS2 / 256 Read value of the register, ADC_DATA[9:2]	—	1	5	LSB	_
	A/D converted value (2)	AD2	$V_{PD2}$ = VLPS2 × 128 / 256 Read value of the register, ADC_DATA[9:2]	124	128	132	LSB	
	A/D converted value (3) AD3		$V_{PD2}$ = VLPS2 × 255 / 256 Read value of the register, ADC_DATA[9:2]	251	255		LSB	_

Note) \*2 : Maximum value of High-level input voltage range is the lower one of (VDD + 0.5 V) and 3.2 V.

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \ ^\circ C \pm 2 \ ^\circ C$  unless otherwise specified

Boromotor	Symbol	Symbol Condition		Limits			Nata
Farameter	Symbol			Тур	Max	Unit	Note
Current consumption							
Current consumption (1) at OFF mode	ICC1	VB = 3.1 V to 4.6 V LDOCNT = Low	_	0	_	μA	*3
Current consumption (2) at LDO1 and LDO2 normal mode	ICC2	LDO1 to 2PS = [0] (LDO1, 2 normal mode) LDO1ON = [1] (LDO1 ON) VB = 3.1 V to 4.6 V LDOCNT = High	_	130	_	μΑ	*3
Current consumption (3) at LDO1 OFF mode, LDO2 power save mode	ICC3	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = 3.1 V to 4.6 V LDOCNT = High	_	10	_	μA	*3
Current consumption (4) at VB through mode, LDO1 OFF mode, LDO2 power save mode	ICC4	LDO2 PS = [1] (LDO2 power save mode) LDO1ON = [0] (LDO1 OFF) VB = $3.1$ V to $4.6$ V LDOCNT = High VB through mode $I_{CPOUT} = 0$ mA LED10ON = [1] (Current 0)		1.0		mA	*3

Note) \*3 : Typical Design Value

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \ ^\circ C \pm 2 \ ^\circ C$  unless otherwise specified

Parameter		Symbol Condition		Limits			Unit	Noto
				Min	Min Typ Max		Unit	Note
Vo	ltage regulator (LDO1) power sav	e mode lo	utmax = – 15 mA (loutmax = –	5 mA a	t 2.85 V	setting)		
	Ripple rejection (1) at power save mode	PSL11	1.85 V mode VB = 3.6 V + 0.2 V[p-p] f = 1 kHz $I_{LDO1} = -7.5 \text{ mA}$ PSL11 = 20 log(acV <sub>LDO1</sub> / 0.2)	_	- 40	_	dB	*3
	Ripple rejection (2) at power save mode	PSL12	1.85 V mode VB = 3.6 V + 0.2 V[p-p] f = 10 kHz $I_{LDO1} = -7.5 \text{ mA}$ PSL12 = 20 log(acV <sub>LDO1</sub> / 0.2)		- 30		dB	*3
Vo	Voltage regulator (LDO2) power save mode loutmax = – 5 mA							
	Ripple rejection (1) at power save mode		VB = 3.6 V + 0.2 V[p-p] f = 1 kHz I <sub>LDO2</sub> = - 2.5 mA PSL21 = 20 log(acV <sub>LDO2</sub> / 0.2)	_	- 40	_	dB	*3
	Ripple rejection (2) at power save mode	PSL22	VB = 3.6 V + 0.2 V[p-p] f = 10 kHz I <sub>LDO2</sub> = - 2.5 mA PSL22 = 20 log(acV <sub>LDO2</sub> / 0.2)	_	- 30		dB	*3

Note) \*3 : Typical Design Value

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $~~T_a$  = 25  $^{\circ}C$   $\pm$  2  $^{\circ}C$  unless otherwise specified

	Parameter	Symbol Condition		Limits			Unit	Noto
	Faranieter			Min	Тур Мах		Unit	Note
l²C	I/F							
	Hysteresis of Schmitt trigger input 1	Vhys1	V <sub>DD</sub> > 2 V, Hysteresis voltage of SDA, SCL	0.05 × VDD	_	_	V	*4 *5
	Hysteresis of Schmitt trigger input 2	Vhys2	V <sub>DD</sub> < 2 V, Hysteresis voltage of SDA, SCL		_	_	V	*4 *5
	Output fall time from $V_{\text{IHmin}}$ to $V_{\text{ILmax}}$	Tof	$\begin{array}{l} Bus \ capacitance: 10 \ pF \\ to \ 400 \ pF \\ I_P \leq 6 \ mA \ (V_{OLmax} = 0.6 \ V) \\ I_P: Max. \ sink \ current \end{array}$	$\begin{array}{c} 20 \text{ +} \\ 0.1 \times \text{C}_{\text{b}} \end{array}$	_	250	ns	*4 *5
	Pulse width of spikes which must be suppressed by the input filter	Tsp	_	0	_	50	ns	*4 *5
	Capacitance for each I/O pin	Ci	_			10	pF	*4 *5

Note) \*4 : The timing of Fast-mode Plus devices in I<sup>2</sup>C-bus is specified in Page.19. All values referred to  $V_{IHMIN}$  and  $V_{ILMAX}$  level.

\*5 : These are values checked by design but not production tested.

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note)  $T_a = 25 \text{ °C} \pm 2 \text{ °C}$  unless otherwise specified

Deveryoter		Cumple of	L	11	Nata			
	Parameter	Symbol	Condition	Min	Тур	Max	Unit	Note
I <sup>2</sup> C I/F (continued)								
	Hold time (repeated)	t <sub>hd:sta</sub>	The first clock pulse is generated after $t_{HD:STA}$	0.6	_	_	μS	*4 *5
	Low period of the SCL clock	t <sub>LOW</sub>	_	1.3	—	_	μS	*4 *5
	High period of the SCL clock	t <sub>HIGH</sub>	_	0.6	_	_	μS	*4 *5
	Set-up time for a repeat START condition	t <sub>su:sta</sub>	_	0.6	_		μS	*4 *5
	Data hold time	t <sub>HD:DAT</sub>	_	0	_	0.9	μS	*4 *5
	Data set-up time	t <sub>SU:DAT</sub>	_	100	_		ns	*4 *5
	Rise time of both SDA and SCL signals	tr	_	$\begin{array}{c} 20 \text{ +} \\ 0.1 \times C_{b} \end{array}$	_	300	ns	*4 *5
	Fall time of both SDA and SCL signals	t <sub>f</sub>	_	$\begin{array}{c} 20 \ + \\ 0.1 \times C_b \end{array}$	_	300	ns	*4 *5
	Set-up time of STOP condition	t <sub>su:sto</sub>	_	0.6	_		μS	*4 *5
	Bus free time between a STOP and START condition	t <sub>BUF</sub>	_	1.3	_		μS	*4 *5
	Capacitive load for each bus line	C <sub>b</sub>	_		_	400	pF	*4 *5
	Noise margin at the Low-level for each connected device	$V_{aL}$	_	0.1 × VDD	_		V	*4 *5
	Noise margin at the High-level for each connected device	V <sub>aH</sub>	_	0.2 × VDD	_		V	*4 *5

Note) \*4 : The timing of Fast-mode Plus devices in I<sup>2</sup>C-bus is specified in Page.19. All values referred to V<sub>IHMIN</sub> and V<sub>ILMAX</sub> level. \*5 : These are values checked by design but not production tested.

#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 V

Note) T<sub>a</sub> = 25 °C  $\pm$  2 °C unless otherwise specified

Parameter		Symbol Condition			Limits			
		Symbol	Symbol			Max	Unit	Note
SP	l interface characteristics (VDD =	= 1.85 V ± 3%	%) Reception timing					
	SCL cycle time	tscyc1	—	_	152	_	ns	*3
	SCL cycle time High period	twhc1	_		70	_	ns	*3
	SCL cycle time Low period	twlc1	_		70	_	ns	*3
	Serial data setup time	tss1	_		62	_	ns	*3
	Serial data hold time	tsh1	_		62	_	ns	*3
	Transmitting and receiving interval	tcsw1	—	_	62	_	ns	*3
	Chip enable setup time	tcss1	—	_	5	_	ns	*3
	Chip enable hold time	tcgh1	—		5	_	ns	*3
SP	l interface characteristics (VDD =	= 1.85 V ± 3%	%) Transmission timing					
	SCL cycle time	tscyc1	_	_	152	_	ns	*3
	SCL cycle time High period	twhc1	_	_	70	_	ns	*3
	SCL cycle time Low period	twlc1	_		70	_	ns	*3
	Serial data setup time	tss1	_		62	_	ns	*3
	Serial data hold time	tsh1	_		62	_	ns	*3
	Transmitting and receiving interval	tcsw1	—	_	62	_	ns	*3
	Chip enable setup time		—	_	5	_	ns	*3
	Chip enable hold time	tcgh1	—	_	5	_	ns	*3
	DC delay time	Only read mode	_	30	_	ns	*3	

Note) \*3 : Typical Design Value

#### SPI interface timing chart (SERSEL = High)



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#### **ELECTRICAL CHARACTERISTICS (continued)**

VB = VBCP = 3.6 V, VLED = 4.5 V, VDD = 1.85 VNote)  $T_a = 25 \text{ }^\circ\text{C} \pm 2 \text{ }^\circ\text{C} \text{ unless otherwise specified}$ 



 $V_{ILMAX} = 0.3_{VDD}$  $V_{IHMIN} = 0.7_{VDD}$ 

S: START condition

Sr : Repeat START condition

P: STOP condition



### **PIN CONFIGURATION**

**TOP VIEW** 



### AN32150B

#### **PIN FUNCTIONS**

Pin No.	Pin name	Туре	Description	Pin processing at unused
A1	SW1	Output	Control switch pin for matrix driver Connected to A column of matrix LED.	Open
A2	LDO2	Output	LDO2 (2.85 V) output pin	(Required pin)
A3	VB	Power supply	Power supply connection pin for BGR and LDO circuits	(Required pin)
A4	LDO1	Output	LDO1 (1.85 V / 2.85 V) output pin (Default : 1.85 V output)	(Required pin)
A5	CPOUT	Output	Charge pump output pin (Output pin for VB through SW)	Open
A6	CN1	Output	Capacitor connection pin for charge pump DC/DC converter	Open
A7	VBCP	Power supply	Power supply connection pin for charge pump DC/DC converter and for through switch	(Required pin)
A8	CPGND	Ground	GND for charge pump DC/DC converter	Connect to GND
B1	SW3	Output	Control switch pin for matrix driver Connected to C column of matrix LED.	Open
B2	SW2	Output	Control switch pin for matrix driver Connected to B column of matrix LED.	Open
B3	VREFD	Output	Capacitor connection pin for BGR circuit	(Required pin)
B4	GPIO1	Input / Output	GPIO input / output port pin (Default input mode with pull-down)	Recommended to connect to GND
B5	CP1	Output	Capacitor connection pin for charge pump DC/DC converter	Open
B6	CP2	Output	Capacitor connection pin for charge pump DC/DC converter	Open
B7	CN2	Output	Capacitor connection pin for charge pump DC/DC converter	Open
B8	IREF	Output	Resistor connection pin for constant current setup	(Required pin)
C1	SW4	Output	Control switch pin for matrix driver Connected to D column of matrix LED.	Open
C2	VLED	Power supply	Power supply for matrix driver Connected to the output of battery or step-up charge pump DC/DC converter.	Connect to VBAT or CPOUT (Open disabled)
C3	LDOCNT	Input	BGR circuit, ON/OFF control pin of LDO1 and LDO2	(Required pin)
C4	GPIO2	Input / Output	GPIO input / output port pin (Default input mode with pull-down) At SERSEL pin = High (SPI mode) : SCE pin	Recommended to connect to GND
C5	GPIO3	Input / Output	GPIO input / output port pin (Default input mode with pull-down)	Recommended to connect to GND
C6	INT	Output	Interrupt output pin	Open
C7	PD2	Input	Photo diode connection pin	Connect to GND
C8	PD1	Output	Photo diode connection pin	Open
D1	SW5	Output	Control switch pin for matrix driver Connected to E column of matrix LED.	Open
D2	SW6	Output	Control switch pin for matrix driver Connected to F column of matrix LED.	Open
D3	AGND	Ground	GND for analog block	Connect to GND
D4	NRESET	Input	Reset input pin	(Required pin)
D5	SCL	Input	SPI / I <sup>2</sup> C interface common clock input pin	(Required pin)

#### **PIN FUNCTIONS (continued)**

Pin No.	Pin name	Туре	Description	Pin processing at unused
D6	SDA	Input / Output	Data input / output pin for I <sup>2</sup> C interface At SERSEL pin = High (SPI mode) : Data input pin	(Required pin)
D7	VDD	Power supply	Power supply for I <sup>2</sup> C interface	(Required pin)
D8	PD3	Input	Detection resistor connection pin for photo diode adjustment	Open
E1	SW7	Output	Control switch pin for matrix driver Connected to G column of matrix LED.	Open
E2 E3	LEDGND3 LEDGND2	Ground	GND for matrix LED	Connect to GND
E4	SLAVE	Input / Output	Slave address selection pin for I <sup>2</sup> C interface At SERSEL pin = High (SPI mode) : SDO pin	(Required pin)
E5	SERSEL	Input	I <sup>2</sup> C / SPI interface selection pin	Connect to GND or VDD
E6	LEDGND1	Ground	GND for BL pin	Connect to GND
E7	LED1	Output	Constant current output pin for LED driver	Open
F1	LED16	Output	Constant current circuit, PWM control output pin Connected to the 6th row of matrix LED. And GPO (open drain) output pin	Open
F2	LED14	Output	Constant current circuit, PWM control output pin Connected to the 4th row of matrix LED.	Open
F3	LED12	Output	Constant current circuit, PWM control output pin Connected to the 2nd row of matrix LED.	Open
F4	LED10	Output	Constant current output pin for LED driver, and GPO (open drain) output pin	Open
F5	LED8	Output	Constant current output pin for LED driver, and GPO (open drain) output pin	Open
F6	LED6	Output	Constant current output pin for LED driver	Open
F7	LED4	Output	Constant current output pin for LED driver	Open
F8	LED2	Output	Constant current output pin for LED driver	Open
G1	LED17	Output	Constant current circuit, PWM control output pin Connected to the 7th row of matrix LED. And GPO (open drain) output pin	Open
G2	LED15	Output	Constant current circuit, PWM control output pin Connected to the 5th row of matrix LED. And GPO (open drain) output pin	Open
G3	LED13	Output	Constant current circuit, PWM control output pin Connected to the 3rd row of matrix LED.	Open
G4	LED11	Output	Constant current circuit, PWM control output pin Connected to the 1st row of matrix LED.	Open
G5	LED9	Output	Constant current output pin for LED driver, and GPO (open drain) output pin	Open
G6	LED7	Output	Constant current output pin for LED driver	Open
G7	LED5	Output	Constant current output pin for LED driver	Open
G8	LED3	Output	Constant current output pin for LED driver	Open



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#### FUNCTIONAL BLOCK DIAGRAM



Note) This block diagram is for explaining functions. Part of the block diagram may be omitted, or it may be simplified.



### OPERATION

#### 1. Power-on / Power-off sequence

Description of each mode

Mode	LDOCNT	LDO10N	LDO2STB	LDO1PS	LDO2PS	Notes		
OFF	Low	0	0	0	0	<ul> <li>The serial signal is not received at LDOCNT = Low.</li> <li>It is necessary to set LDOCNT to High for the return from OFF mode.</li> </ul>		
OFF ↓ Power save	Low ↓ High	1	0	1	1	<ul> <li>The serial signal can be received after 5 ms from LDOCNT = High.</li> <li>The setting of registers is initialized after this LSI return from OFF mode. Then LDO1 and LDO2 operate in power save mode respectively.</li> </ul>		
Normal	High	0/1	0	0	0	<ul> <li>When NRESET is set to Low, the setting of registers is initialized. Then LDO1 and LDO2 operate in power save mode respectively.</li> <li>The serial signal is turned LDO1 on or off.</li> <li>LDO2 turns on at LDOCNT = High.</li> <li>The serial signal is not received at NRESET = Low.</li> <li>Low period of one or more internal clocks is required during NRESET = Low.</li> <li>NRESET prohibits the input signal of those other than a rectangle wave.</li> <li>When NRESET is set to Low, all the registers are set to the default value.</li> </ul>		
Normal / power save ↓ OFF	High ↓ Low	0	0	0/1 ↓ 0	0/1 ↓ 0	<ul> <li>The setting order to change into OFF mode is as follows.</li> <li>LDOCNT = Low → NRESET = Low, or NRESET = Low → LDOCNT = Low</li> </ul>		
$ \begin{array}{c} Normal \\ \downarrow \\ Power save \\ Power save \\ \downarrow \\ Normal \end{array} $	High	0/1	0	0/1	0/1	<ul> <li>LDO1, 2 can be individually shifted to power save mode by the serial signal.</li> <li>It is possible to return from power save mode to normal mode with serial signal.</li> </ul>		
Normal / power save ↓ OFF(LDO1 only)	/ power ve High ↓ O1 only) Low		al / power ave ↓ DO1 only) High ↓ ↓ Low 1 1		1	0/1	0/1	<ul> <li>When LDO1 output is used as power supply for I<sup>2</sup>C I/F and LDO1 is turned OFF by LDO1ON via serial interface, LDO1 cannot return to ON mode via serial interface.</li> <li>When LDO1 output is used as power supply fro I<sup>2</sup>C I/F, write [1] in LDO2STB first. After that, LDOCNT changes from High to Low, and LDO1 only shifts to OFF mode.</li> </ul>
OFF(LDO1 only) ↓ Normal / power save	Low ↓ High					<ul> <li>If LDOCNT is set to High from Low, this LSI can shift from standby to normal mode.</li> </ul>		



#### **OPERATION** (continued)

#### 1. Power-on / Power-off sequence (continued)

1.1 Shift to LDO1, 2 power save mode from OFF mode at the rising edge of VB



Note) Set LDOCNT to High-level after VB, VBCP reach 3.1 V or more. LDO1, LDO2 operate at power save mode after they just rise.

#### 1.2 Shift to OFF mode from LDO1, 2 normal / power save mode

