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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



## MODELS APLR - APOLLO 6-DIGIT RATE INDICATOR [TIME BASE] AND PBLR - 4/6 DIGIT MODULE FOR USE WITH THE LARGE DIGIT DISPLAY (LDD)

- 6-DIGIT, 0.56" (14.2 mm) HIGH LED DISPLAY (APLR)
- CRYSTAL-CONTROLLED TIME-BASE PROGRAMMABLE UP TO 32.764 SECONDS PROVIDES DIRECT-READING FOR ANY RATE UNITS
- 0.02% ACCURACY
- PROGRAMMABLE DECIMAL POINTS
- FREQUENCY DOUBLING
- PROGRAMMABLE INPUT CIRCUIT, ACCEPTS OUTPUTS FROM A WIDE VARIETY OF SENSORS
- LEADING ZERO BLANKING
- POWER-UP SELF-TEST
- NEMA 4/IP65 SEALED FRONT METAL BEZEL



### DESCRIPTION

The Apollo Time Base Rate Indicators (Model APLR) and Module (Model PBLR), provide the versatility and flexibility needed to accommodate virtually any rate measuring need. Based on Micro-processor technology, this unit represents the optimum in cost/performance ratio.

This unit has the ability to scale for direct readout in terms of the units being measured. Whether a machine produces bottles, cloth, wire, or beverage mix, operation is enhanced when the rate readout is expressed directly in bottles/min., feet/min., gallons/hour, or whatever units are needed in plant operations. The APLR/PBLR can provide this capability through its settable time base, programmable decimal points, and frequency doubling functions.

The APLR/PBLR can also accommodate magnetic pickups, as well as logic (*sourcing output*) sensors and NPN open collector (*sinking output*) sensors.

This unit also has a self-test feature, which checks all the micro-processor and display driver circuitry after power-up (*if enabled*). This self-test also can be used to test the time base select DIP switches and decimal point select DIP switches, to make certain all switches are functioning properly.

Power and input connections are made via a removable terminal block, located at the rear of the unit. Each terminal can accept one #14 AWG wire. DIP switches at the side of the unit are used to program the input configuration.

The Apollo Rate Indicator has a sealed metal die-cast bezel which meets NEMA 4/IP65 specifications for wash-down and/or dust, when properly installed. Two mounting clips are provided for easy installation. The Time Base Rate Indicator uses a 6-digit, 0.56" (14.2 mm) high LED display, which is readable to 23 feet (7 M).

### SAFETY SUMMARY

All safety related regulations, local codes and instructions that appear in the manual or on equipment must be observed to ensure personal safety and to prevent damage to either the instrument or equipment connected to it. If equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

### SPECIFICATIONS

1. **DISPLAY:** 6-Digit, 0.56" (14.2 mm) high LED display. (APLR)
2. **POWER REQUIREMENTS:**

#### APLR

**AC Operation:** Available in two voltages.

- 115 VAC, ±10%, 50/60 Hz, 14 VA or
- 230 VAC, ±10%, 50/60 Hz, 14 VA

**DC Operation:**

24 VDC, 10% @ 0.6 A max.

*Note: All available units can be powered at Terminal #3 from a 11 to 14 VDC, 0.6 A max. power supply.*

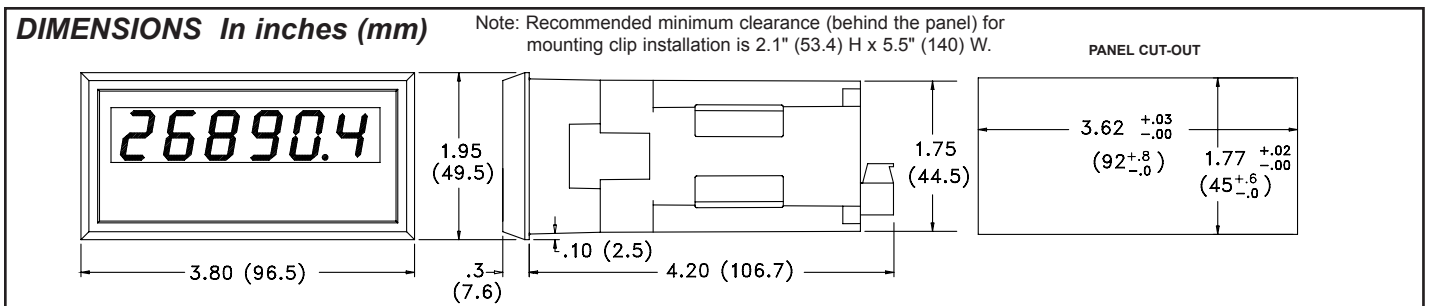
#### PBLR

**AC Operation:** Switch selected via the LDD power supply board, 115/230 (+/-10%), 50/60 Hz, 10 VA for 4-digit, 15 VA for 6 digit (including LDD).

3. **SENSOR POWER:** +12 VDC, ±25% @ 100 mA max.
4. **MAXIMUM OPERATING FREQUENCY:** 10 KHz, 50% duty cycle. 10,000 cps with min. pulse width "ON" and "OFF" times of 50 µsec.
5. **TIME BASE SELECTION RANGE:** 0.004 to 32.764 seconds.
6. **ACCURACY:** 0.02%
7. **MAXIMUM INPUT VOLTAGE AND CURRENT:** When the "SIG IN" (Terminal 5) is driven from external signal voltages, max. voltage swing is ±50 V peak. Input voltage can be dropped by an external series resistance that limits input current to ±5 mA. (*These ratings are for S3 "OFF".*)

**CAUTION: Risk of Danger.**  
Read complete instructions prior to installation and operation of the unit.

**CAUTION: Risk of electric shock.**





The next portion of self-test will display four groups of zeros and/or ones. (The first two digits from the left, in each group, will always show a zero.) In the first group, the third digit represents the 13th (X4096) DIP switch setting. The fourth and fifth digits show the setting for the Decimal Point select DIP switches. (The fourth position digit represents DIP switch 4 and the fifth position digit represents DIP switch 5.) The state of these digits coincide with the table under the “Decimal Point Selection” section. The last digit will always show a one.

The next three groups are shown on the right, and correspond to the DIP switch shown directly above it. (Note: The first two digits in each group are always shown as zeros.)

			9	10	11	12	(DIP SWITCH)
Group 2:	0	0	X	X	X	X	
			5	6	7	8	(DIP SWITCH)
Group 3:	0	0	X	X	X	X	
			1	2	3	4	(DIP SWITCH)
Group 4:	0	0	X	X	X	X	

The X's represent a zero or one (depending on the setting of the DIP switch) in the display. Self-test is automatically exited 8 seconds after the last DIP switch change is made.

## EMC INSTALLATION GUIDELINES

Although this unit is designed with a high degree of immunity to ElectroMagnetic Interference (EMI), proper installation and wiring methods must be followed to ensure compatibility in each application. The type of the electrical noise, source or coupling method into the unit may be different for various installations. Cable length, routing and shield termination are very important and can mean the difference between a successful installation or a troublesome installation. Listed below are some EMC guidelines for successful installation in an industrial environment.

- The unit should be mounted in a metal enclosure, that is properly connected to protective earth.
  - If the bezel is exposed to high Electro-Static Discharge (ESD) levels, above 4 Kv, it should be connected to protective earth. This can be done by making sure the metal bezel makes proper contact to the panel cut-out or connecting the bezel screw with a spade terminal and wire to protective earth.
- Use shielded (screened) cables for all Signal and Control inputs. The shield (screen) pigtail connection should be made as short as possible. The connection point for the shield depends somewhat upon the application. Listed below are the recommended methods of connecting the shield, in order of their effectiveness.
  - Connect the shield only at the panel where the unit is mounted to earth ground (protective earth).
  - Connect the shield to earth ground at both ends of the cable, usually when the noise source frequency is above 1 MHz.
  - Connect the shield to common of the unit and leave the other end of the shield unconnected and insulated from earth ground.
- Never run Signal or Control cables in the same conduit or raceway with AC power lines, conductors feeding motors, solenoids, SCR controls, and heaters, etc. The cables should be run in metal conduit that is properly grounded. This is especially useful in applications where cable runs are long and portable two-way radios are used in close proximity or if the installation is near a commercial radio transmitter.
- Signal or Control cables within an enclosure should be routed as far away as possible from contactors, control relays, transformers, and other noisy components.
- In extremely high EMI environments, the use of external EMI suppression devices, such as ferrite suppression cores, is effective. Install them on Signal and Control cables as close to the unit as possible. Loop the cable through the core several times or use multiple cores on each cable for additional protection. Install line filters on the power input cable to the unit to suppress power line interference. Install them near the power entry point of the enclosure. The following EMI suppression devices (or equivalent) are recommended:

Ferrite Suppression Cores for signal and control cables:

- Fair-Rite # 0443167251 (RLC #FCOR0000)
- TDK # ZCAT3035-1330A
- Steward #28B2029-0A0

Line Filters for input power cables:

- Schaffner # FN610-1/07 (RLC #LFIL0000)
- Schaffner # FN670-1.8/07
- Corcom #1VB3
- Corcom #1VR3

**Note:** Reference manufacturer's instructions when installing a line filter.

- Long cable runs are more susceptible to EMI pickup than short cable runs. Therefore, keep cable runs as short as possible.

## WIRING CONNECTIONS

As depicted in the drawing showing the rear view of the Apollo Rate Indicator, there is a terminal block where all wiring connections are made. All conductors should meet voltage and current ratings for each terminal. Also cabling should conform to appropriate standards of good installation, local codes and regulations. It is recommended that power supplied to the unit (AC or DC) be protected by a fuse or circuit breaker. Remove the block for easy access to the terminal screws. To remove the block, pull from the back of the block until it slides clear of the terminal block shroud.

Enclosed with the PBLR module is an adhesive backed label(s) showing the terminal block pin-out. This label is for wiring reference only, do not use for specifications. This label should be applied to the appropriate location by the user.



**CAUTION:** The terminal block should NOT be removed with power applied to the unit. The module should not be removed from the LDD with power applied to the LDD or the module.

Terminal 3 is the “DC” (+12 V) terminal. This terminal is for sensor supply and can provide up to 100 mA of current. An external +11 V to +14 VDC can also be applied to this terminal to power the unit in the absence of A.C. power.

Terminal 4 is the “COMM.” (common) terminal, which is the common line to which the sensor and other input commons are connected.

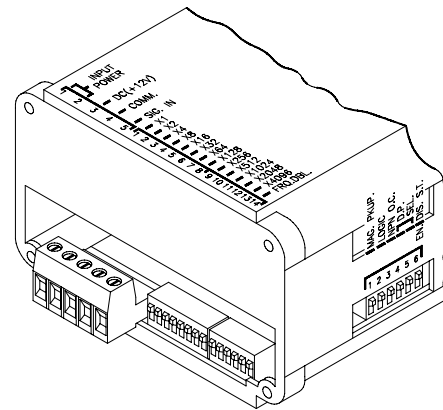
Terminal 5 is the “SIG. IN” (signal in) terminal. When the signal at this terminal goes low, a count will be registered in the unit. (See “Input Ratings” under “Specifications” section.)

### POWER WIRING (A.C. Version)

Primary AC power is connected to Terminals 1 and 2 (marked VAC 50/60 Hz, located on the left-hand side of the block). For best results, the AC power should be relatively “clean” and within the specified  $\pm 10\%$  variation limit. Drawing power from heavily loaded circuits or from circuits that also power loads that cycle on and off, should be avoided.

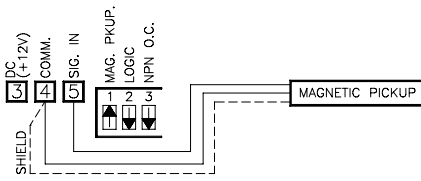
### POWER WIRING (APLR D.C. Version only)

The DC Version unit will operate from a 24 VDC power supply. The positive wire of the DC power source connects to Terminal #1 and the minus “-” to Terminal #2.



# CONNECTIONS & CONFIGURATION SWITCH SET-UP FOR VARIOUS SENSOR OUTPUTS

## COUNT SWITCH OR ISOLATED TRANSISTOR OUTPUTS

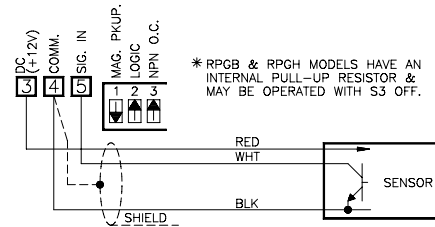


### RECOMMENDED RULES FOR MAGNETIC PICKUP CONNECTIONS

1. Use 2-wire shielded cable for magnetic pickup signal leads.
2. Never run signal cable in conduit, troughs, or cable bundles with power carrying conductors.
3. Connect the shield to the common Terminal "4" at the input of the instrument. Do NOT connect the shield at the pickup end, leave it "open" and insulate the exposed shield to prevent electrical contact with the frame or case. (Shielded cable, supplied on most RLC magnetic pickups, has open shield on pickup end.)

## SENSORS WITH CURRENT SINK OUTPUT (NPN O.C.)

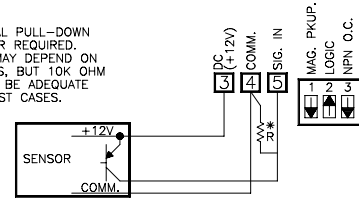
[Includes ASTC, LMPC, PSAC, RPGC, (RPGB, RPHG) \* , LSC]



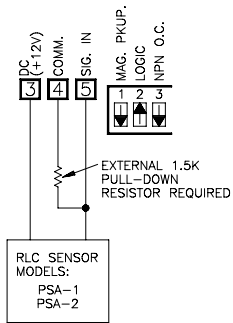
\* RPGB & RPHG MODELS HAVE AN INTERNAL PULL-UP RESISTOR & MAY BE OPERATED WITH S3 OFF.

## SENSORS WITH CURRENT SOURCE OUTPUT (PNP O.C.)

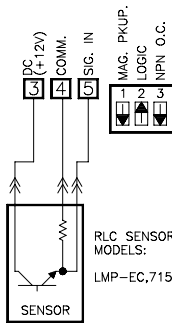
\* EXTERNAL PULL-DOWN RESISTOR REQUIRED. VALUE MAY DEPEND ON SENSORS, BUT 10K OHM SHOULD BE ADEQUATE FOR MOST CASES.



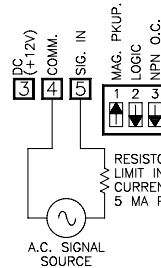
## TWO WIRE PROXIMITY SENSORS



## OLDER STYLE, SENSORS WITH -EF OUTPUT

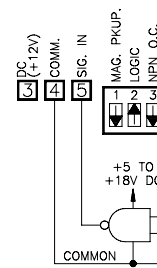


## A.C. INPUTS FROM TACH. GENERATORS, INVERTERS, ETC.

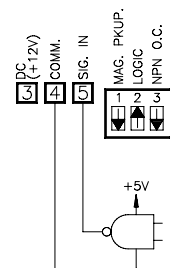


A.C. POWER SOURCE SUCH AS INVERTERS WITH MORE THAN 50V OUTPUT, SHOULD BE COUPLED WITH A STEP-DOWN ISOLATION TRANSFORMER.

## INPUT FROM CMOS & OTHER BI-POLAR OUTPUTS



## INPUT FROM TTL



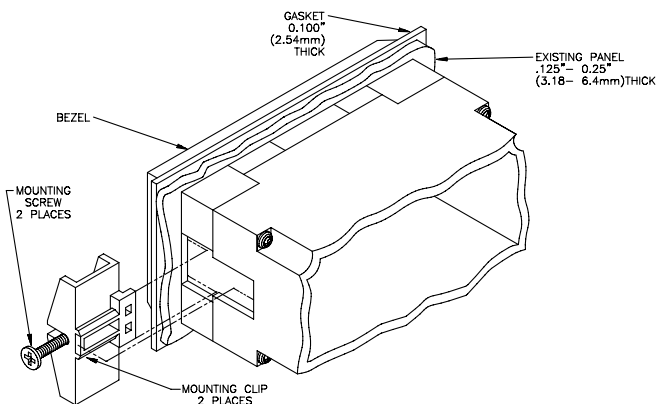
## INSTALLATION ENVIRONMENT

The unit should be installed in a location that does not exceed the maximum operating temperature and provides good air circulation. Placing the unit near devices that generate excessive heat should be avoided.

The bezel should be cleaned only with a soft cloth and neutral soap product. Do NOT use solvents.

Continuous exposure to direct sunlight may accelerate the aging process of the bezel.

Do not use tools of any kind (screwdrivers, pens, pencils, etc.) to operate the keypad of the unit.



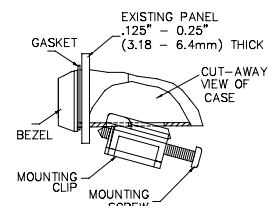
## INSTALLATION

PBLR installation information is contained in the LDD bulletin. Refer to that bulletin for instructions on installing the module.

The unit meets NEMA 4/IP65 requirements for indoor use, when properly installed. The units are intended to be mounted into an enclosed panel with a gasket to provide a water-tight seal. Two mounting clips and screws are provided for easy installation. Consideration should be given to the thickness of the panel. A panel which is too thin may distort and not provide a water-tight seal. (Recommended minimum panel thickness is 1/8".)

Cut the panel opening to the specified dimensions. Remove burrs and clean around the panel opening. Slide the panel gasket over the rear of the unit to the back of the bezel. Insert the unit into the panel. As depicted in the drawing, install the screws into the narrow end of the mounting clips. Thread the screws into the clips until the pointed end just protrudes through the other side. Install each of the mounting clips by inserting the wide lip of the clips into the wide end of the hole, located on either side of the case. Then snap the clip onto the case.

Tighten the screws evenly to apply uniform compression, thus providing a water-tight seal. **CAUTION:** Only minimum pressure is required to seal panel. Do **NOT** overtighten screws.



## TIME BASE SETTING PROCEDURE

The Apollo Time Base Rate Indicator has a time base selection range of 0.004 sec. to 32.764 sec. For a minimum time base (0.004 sec.), the X1 DIP switch is set to "ON". For the maximum time base, all the DIP switches would be set to "ON" (these add up to 8191). Therefore, a specific time base is achieved by adding up the appropriate individual time base increments.

The time base increment total is computed according to the following formula:

$$\text{TIME BASE INCREMENT} = \frac{(\text{Display Readout Desired}) \times \text{DDP} \times (15,000)}{\text{TOTAL (TBIT)} \quad [(\text{Known RPM}) \times (\text{Known PPR})] *}$$

\* - Input Pulse Rate Per Minute.

**DDP:** Use one of the following numbers in the above formula for the Display Decimal Point (DDP) position.

0	=	1
0.0	=	10
0.00	=	100

DISPLAY READOUT DESIRED = 1800 (Direct Readout in RPM)  
 REVOLUTIONS PER MINUTE = 1800  
 PULSES PER REVOLUTION = 60

$$\text{TBIT} = \frac{1,800 \times 1 \times 15,000}{1,800 \times 60} = 250 \left[ \begin{array}{l} \text{round to the nearest} \\ \text{whole number} \end{array} \right]$$

The appropriate Time Base switches, which together add up to 250, are then set "ON". Start by selecting the first increment which is greater than half the desired TBIT, and add subsequent increments that are more than half the difference needed.

TBIT = 250			
DIP switch 8	-	128	Needed = 122
DIP switch 7	-	64	Needed = 58
DIP switch 6	-	32	Needed = 26
DIP switch 5	-	16	Needed = 10
DIP switch 4	-	8	Needed = 2
DIP switch 2	-	2	

As shown above, DIP switches 2 and 4-8 are all set to "ON". If it is desired to know what the time is in seconds, multiply 250 x 0.004 sec. = 1 sec.

*Note: This is the set-up for a one-second time base, which allows for direct readout of RPM.*

## FLOW RATE INDICATION APPLICATION

A positive displacement pump is driven by a gear reducer and an AC motor. An ARCJ NEMA C FLANGE is mounted to the end of this AC motor.

The magnetic pickup (which senses the gear) of the ARCJ adapter kit feeds pulses to the APLR. The sensing gear, in combination with the pump and reducer, provides 560 pulses for every gallon of fluid passing through the pump. The Model APLR is used to read directly in tenths of gallons/min. in flow rates up to 45 gallons/min. The following logical steps can be used to determine the time base value required for direct readout. At 45 GPM, the number of output pulses would be as follows:

$$45 \text{ gallons/min.} \times 560 \text{ pulses/gallon} = 25,200 \text{ pulses/min.}$$

Using the TBIT formula:

$$\text{TBIT} = \frac{(45) \times (10) * \times 15,000}{25,200 **}$$

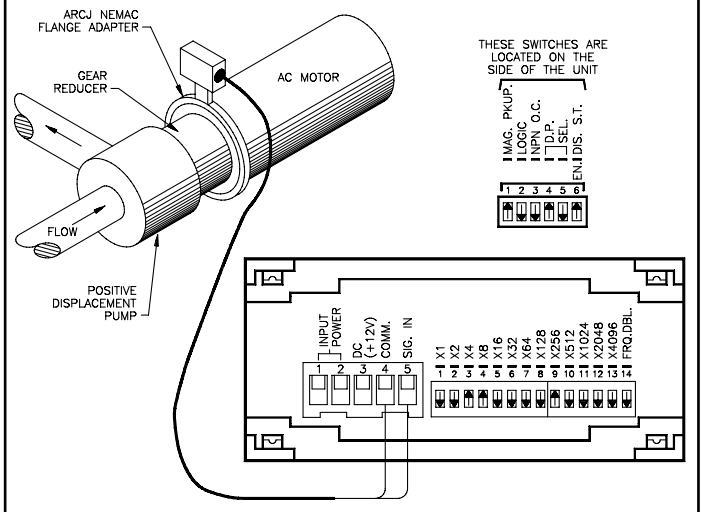
$$= 267.857 \left[ \begin{array}{l} \text{round to the nearest} \\ \text{whole number} \end{array} \right]$$

\* - For Tenths Position      \*\* - Input Pulse Rate Per Minute

$$\text{TBIT} = 268$$

DIP switch 9	-	256	Needed = 12
DIP switch 4	-	8	Needed = 4
DIP switch 3	-	4	

From the above calculation, DIP switches 3, 4, and 9, would be set to the "ON" position. The tenths position decimal point must also be set to "ON". So the display will show 45.0 when 45 gallons are passing through the pump every minute.



## WEB SPEED INDICATION APPLICATION

A newspaper publishing company wants to know the rate at which their printing press is operating. A fifty-tooth timing sprocket is mounted to the shaft of one of the press rollers. An MP-62TA magnetic pickup is used to sense the moving teeth. Direct readout is obtained by setting the time base to a period in which the number of teeth passing the pickup is numerically equal to the desired readout. Using the TBIT formula, the following calculations are performed:

$$\begin{aligned} \text{TIME BASE INCREMENT} &= \frac{(\text{Display Readout Desired}) \times (15,000)}{\text{TOTAL (TBIT)}} \\ &= \frac{(632) \times (15,000)}{(1419) \times (50)} \\ &= 133.6 \left[ \begin{array}{l} \text{round to the nearest} \\ \text{whole number} \end{array} \right] \end{aligned}$$

\* - Input Pulse Rate Per Minute.

	TBIT = 134		
DIP switch 8 . . . . .	- 128	Needed =	6
DIP switch 3 . . . . .	- 4	Needed =	2
DIP switch 2 . . . . .	- 2		

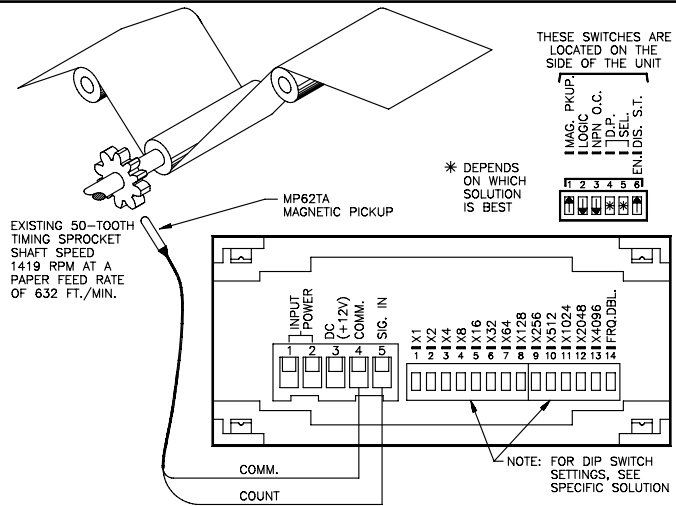
DIP switches 2, 3, and 8, are set to "ON". If the rounding error introduced above is unacceptable, the display could be scaled up by a factor of 10 and then a decimal point turned on in the tenths position. The calculations would be as follows:

$$\text{TBIT} = (\text{Display Readout Desired} \times 10) \times 15,000$$

$$= \frac{(6320) \times (15,000)}{(1419) \times (50)}$$

$$\text{TBIT} = 1336$$

DIP switch 11 . . . . .	- 1024	Needed =	312
DIP switch 9 . . . . .	- 256	Needed =	56
DIP switch 6 . . . . .	- 32	Needed =	24
DIP switch 5 . . . . .	- 16	Needed =	8
DIP switch 4 . . . . .	- 8		



Now DIP switches, 4, 5, 6, 9, and 11, are set to "ON". Also, the tenths position decimal point would be set to "ON". (Note: If the time base is now too long, approximately 5.3 sec. the "FRQ. DBL." DIP switch can be set to "ON", then only half the time base will be necessary.

$$\text{TBIT} = \frac{(6320) \times (15,000)}{(1419) \times (2) \times (50)}$$

$$\text{TBIT} = 668$$

DIP switch 10 . . . . .	- 512	Needed =	156
DIP switch 8 . . . . .	- 128	Needed =	28
DIP switch 5 . . . . .	- 16	Needed =	12
DIP switch 4 . . . . .	- 8	Needed =	4
DIP switch 3 . . . . .	- 4		

DIP switches 3, 4, 5, 8, and 10, are all set to "ON" along with the tens position decimal point. The time base, in seconds, is  $668 \times 0.004 = 2.67$  sec.

## TROUBLESHOOTING

For further technical assistance, contact technical support at the appropriate company numbers listed.

## ORDERING INFORMATION

MODEL NO.	DESCRIPTION	PART NUMBERS FOR AVAILABLE SUPPLY VOLTAGES		
		230 VAC	115 VAC	24 VDC
APLR	Apollo Time Base Rate Indicator	APLR0610	APLR0600	APLR0630

For more information on Pricing, Enclosures & Panel Mount Kits refer to the RLC Catalog or contact your local RLC distributor.

## PERSONALITY MODULE

MODEL NO.	DESCRIPTION	PART NUMBERS
		115/230 VAC
PBLR *	Apollo Time Base Rate Module for use with the 4 or 6 digit Large Digit Display	PBLR0600

\* Requires an LDD for use.

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#### **LIMITED WARRANTY**

The Company warrants the products it manufactures against defects in materials and workmanship for a period limited to two years from the date of shipment, provided the products have been stored, handled, installed, and used under proper conditions. The Company's liability under this limited warranty shall extend only to the repair or replacement of a defective product, at The Company's option. The Company disclaims all liability for any affirmation, promise or representation with respect to the products.

The customer agrees to hold Red Lion Controls harmless from, defend, and indemnify RLC against damages, claims, and expenses arising out of subsequent sales of RLC products or products containing components manufactured by RLC and based upon personal injuries, deaths, property damage, lost profits, and other matters which Buyer, its employees, or sub-contractors are or may be to any extent liable, including without limitation penalties imposed by the Consumer Product Safety Act (P.L. 92-573) and liability imposed upon any person pursuant to the Magnuson-Moss Warranty Act (P.L. 93-637), as now in effect or as amended hereafter.

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