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**Revision History AS4C64M 8D1 -**

Revision	Details	Date
Rev 1.0	Preliminary datasheet	February 2014
Rev 2.0	Typing error data rate 800bps/pin to 400bps/pin page 1	October 2014

## 512M – (64M x 8 bit) DDR Synchronous DRAM (SDRAM)

Confidential

(Rev. 2.0, Oct. /2014)

### Features

- Fast clock rate: 200MHz
- Differential Clock CK &  $\overline{CK}$
- Bi-directional DQS
- DLL enable/disable by EMRS
- Fully synchronous operation
- Internal pipeline architecture
- Four internal banks, 16M x 8-bit for each bank
- Programmable Mode and Extended Mode registers
  - CAS Latency: 2, 2.5, 3
  - Burst length: 2, 4, 8
  - Burst Type: Sequential & Interleaved
- Individual byte write mask control
- DM Write Latency = 0
- Auto Refresh and Self Refresh
- 8192 refresh cycles / 64ms
- Precharge & active power down
- Operating temperature range:  $T_A = 0 \sim 70^\circ\text{C}$
- Power supplies:  $V_{DD} \text{ \& \ } V_{DDQ} = 2.5V \pm 0.2V$
- Interface: SSTL\_2 I/O Interface
- Package: 66 Pin TSOP II, 0.65mm pin pitch
- Package: 60-Ball, 8x13x1.2 mm (max) TFBGA
  - All parts ROHS Compliant

### Overview

The 512Mb DDR SDRAM is a high-speed CMOS double data rate synchronous DRAM containing 512 Mbits. It is internally configured as a quad 16M x 8-bit DRAM with a synchronous interface (all signals are registered on the positive edge of the clock signal, CK).

Data outputs occur at both rising edges of CK and  $\overline{CK}$ . Read and write accesses to the SDRAM are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of a BankActivate command which is then followed by a Read or Write command. The DDR SDRAM provides programmable Read or Write burst lengths of 2, 4, or 8. An auto precharge function may be enabled to provide a self-timed row precharge that is initiated at the end of the burst sequence. The refresh functions, either Auto or Self Refresh are easy to use. In addition, The DDR SDRAM features programmable DLL option. By having a programmable mode register and extended mode register, the system can choose the most suitable modes to maximize its performance. These devices are well suited for applications requiring high memory bandwidth, result in a device particularly well suited to high performance main memory and graphics applications.

Table 1. Ordering Information

Part Number	Clock Frequency	Data Rate	Power Supply	Package
AS4C64M8D1-5TCN	200MHz	400Mbps/pin	VDD 2.5V, VDDQ 1.8V	66pin TSOP II
AS4C64M8D1-5TIN	200MHz	400Mbps/pin	VDD 2.5V, VDDQ 1.8V	66 pin TSOP II
AS4C64M8D1-5BCN	200MHz	400Mbps/pin	VDD 2.5V, VDDQ 1.8V	60 ball TFBGA
AS4C64M8D1-5BIN	200MHz	400Mbps/pin	VDD 2.5V, VDDQ 1.8V	60 ball TFBGA

T: indicated 66 pin TSOP II B: indicates 60-ball 8 x 10 x 1.2mm (max) TFBGA package

C: indicates commercial temperature

I: indicates industrial temperature

N: indicates Pb and Halogen Free - ROHS Compliant

Table 2. Speed Grade Information

Speed Grade	Clock Frequency	CAS Latency	tRCD (ns)	tRP (ns)
DDR1-400	200 MHz	2.5	15	15

Figure 1. Pin Assignment (Top View)

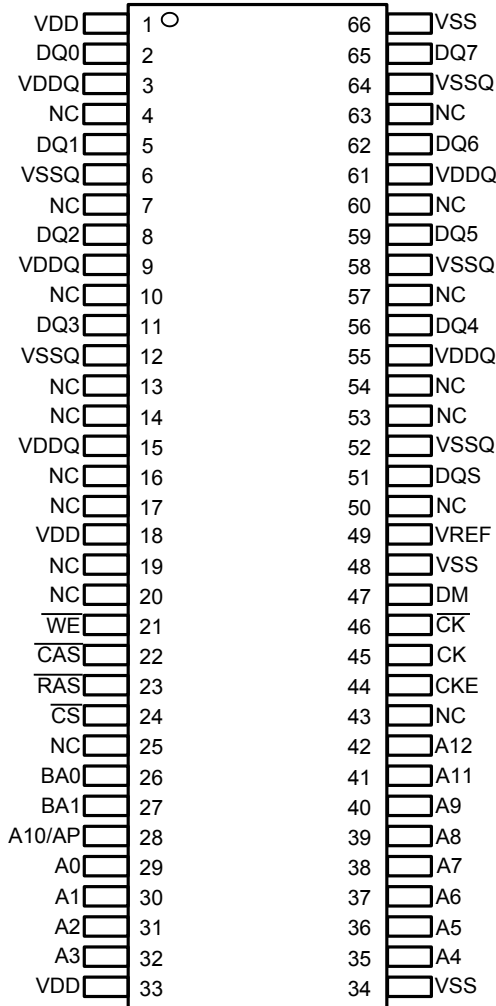
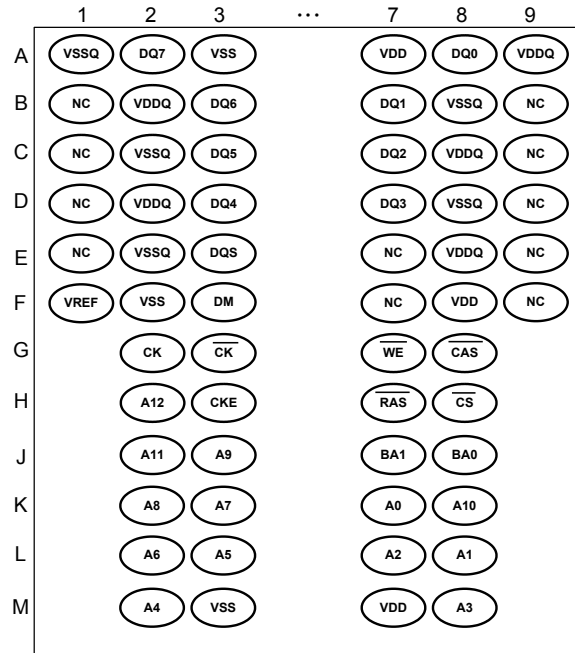
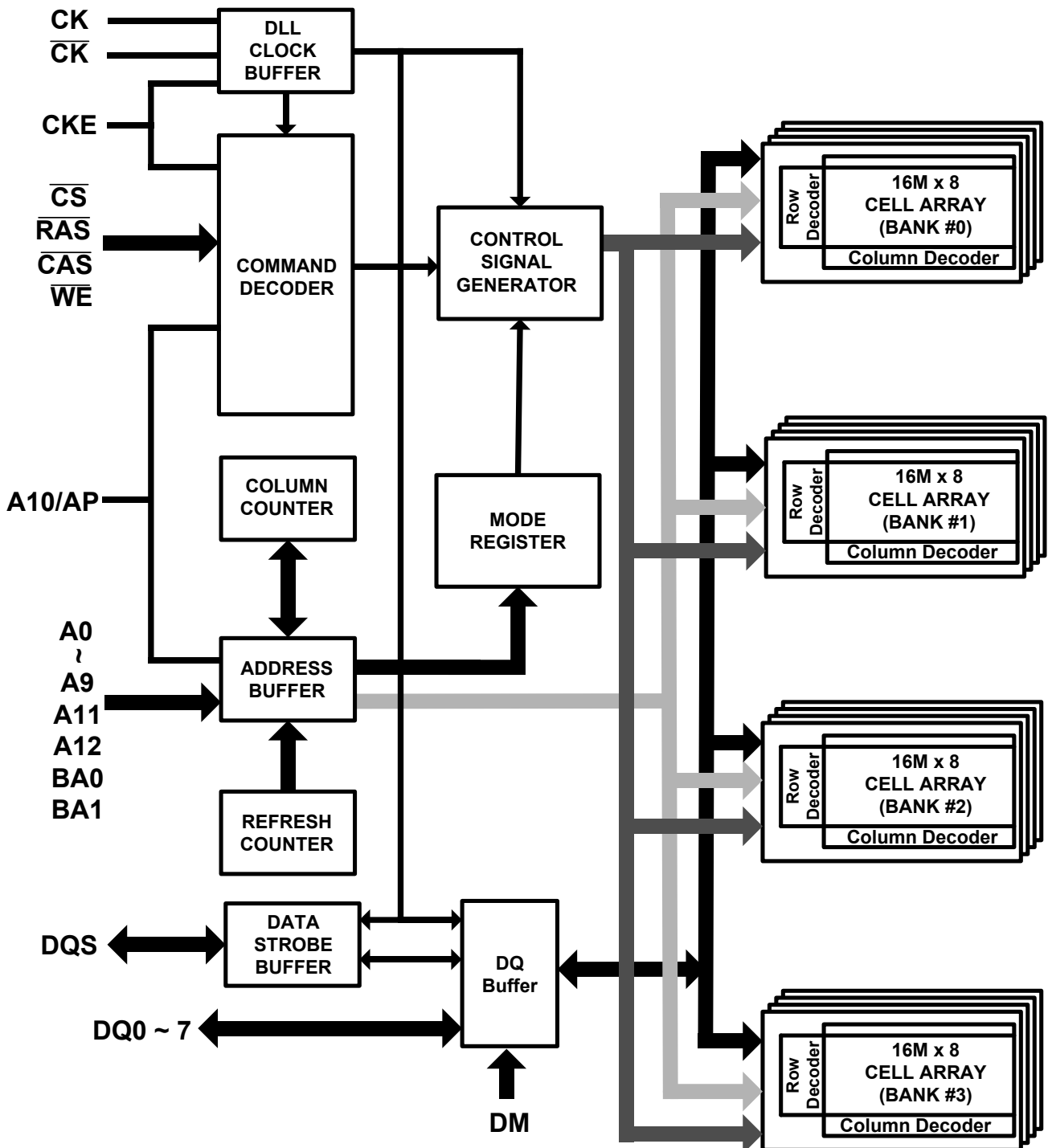


Figure 1.1 Ball Assignment (Top View)



**Figure 2. Block Diagram**


## Pin Descriptions

**Table 2. Pin Details**

Symbol	Type	Description
CK, $\overline{CK}$	Input	<b>Differential Clock:</b> CK and $\overline{CK}$ are differential clock inputs. All address and control input signals are sampled on the crossing of the positive edge of CK and negative edge of $\overline{CK}$ . Input and output data is referenced to the crossing of CK and $\overline{CK}$ (both directions of the crossing)
CKE	Input	<b>Clock Enable:</b> CKE activates (HIGH) and deactivates (LOW) the CK signal. If CKE goes low synchronously with clock, the internal clock is suspended from the next clock cycle and the state of output and burst address is frozen as long as the CKE remains low. When all banks are in the idle state, deactivating the clock controls the entry to the Power Down and Self Refresh modes.
BA0, BA1	Input	<b>Bank Activate:</b> BA0 and BA1 define to which bank the BankActivate, Read, Write, or BankPrecharge command is being applied.
A0-A12	Input	<b>Address Inputs:</b> A0-A12 are sampled during the BankActivate command (row address A0-A12) and Read/Write command (column address A0-A9, A11 with A10 defining Auto Precharge).
$\overline{CS}$	Input	<b>Chip Select:</b> $\overline{CS}$ enables (sampled LOW) and disables (sampled HIGH) the command decoder. All commands are masked when $\overline{CS}$ is sampled HIGH. $\overline{CS}$ provides for external bank selection on systems with multiple banks. It is considered part of the command code.
$\overline{RAS}$	Input	<b>Row Address Strobe:</b> The $\overline{RAS}$ signal defines the operation commands in conjunction with the $\overline{CAS}$ and $\overline{WE}$ signals and is latched at the positive edges of CK. When $\overline{RAS}$ and $\overline{CS}$ are asserted "LOW" and $\overline{CAS}$ is asserted "HIGH," either the BankActivate command or the Precharge command is selected by the $\overline{WE}$ signal. When the $\overline{WE}$ is asserted "HIGH," the BankActivate command is selected and the bank designated by BA is turned on to the active state. When the $\overline{WE}$ is asserted "LOW," the Precharge command is selected and the bank designated by BA is switched to the idle state after the precharge operation.
$\overline{CAS}$	Input	<b>Column Address Strobe:</b> The $\overline{CAS}$ signal defines the operation commands in conjunction with the $\overline{RAS}$ and $\overline{WE}$ signals and is latched at the positive edges of CK. When $\overline{RAS}$ is held "HIGH" and $\overline{CS}$ is asserted "LOW," the column access is started by asserting $\overline{CAS}$ "LOW." Then, the Read or Write command is selected by asserting $\overline{WE}$ "HIGH" or "LOW".
$\overline{WE}$	Input	<b>Write Enable:</b> The $\overline{WE}$ signal defines the operation commands in conjunction with the $\overline{RAS}$ and $\overline{CAS}$ signals and is latched at the positive edges of CK. The $\overline{WE}$ input is used to select the BankActivate or Precharge command and Read or Write command.
DQS	Input / Output	<b>Data Strobe:</b> Output with read data, input with write data. Edge--aligned with read data, centered in write data. Used to capture write data.
DM	Input	<b>Data Input Mask:</b> Input data is masked when DM is sampled HIGH during a write cycle.
DQ0 – DQ7	Input / Output	<b>Data Bus:</b> Data Input/output.
V <sub>DD</sub>	Supply	<b>Power Supply:</b> 2.5V ± 0.2V
V <sub>SS</sub>	Supply	<b>Ground</b>

V <sub>DDQ</sub>	Supply	<b>DQ Power:</b> 2.5V ± 0.2V. Provide isolated power to DQs for improved noise immunity.
V <sub>SSQ</sub>	Supply	<b>DQ Ground:</b> Provide isolated ground to DQs for improved noise immunity.
V <sub>REF</sub>	Supply	<b>SSTL_2 reference Voltage</b>
NC	-	<b>No Connect:</b> These pins should be left unconnected.

## Operation Mode

Fully synchronous operations are performed to latch the commands at the positive edges of CK. Table 3 shows the truth table for the operation commands.

**Table 3. Truth Table (Note (1), (2))**

Command	State	CKE <sub>n-1</sub>	CKE <sub>n</sub>	DM	BA0,1	A10	A0-9, 11-12	$\overline{CS}$	RAS	CAS	$\overline{WE}$
BankActivate	Idle <sup>(3)</sup>	H	X	X	V	Row address		L	L	H	H
BankPrecharge	Any	H	X	X	V	L	X	L	L	H	L
PrechargeAll	Any	H	X	X	X	H	X	L	L	H	L
Write	Active <sup>(3)</sup>	H	X	X	V	L	Column address (A0 ~ A9)	L	H	L	L
Write and AutoPrecharge	Active <sup>(3)</sup>	H	X	X	V	H		L	H	L	L
Read	Active <sup>(3)</sup>	H	X	X	V	L	Column address (A0 ~ A9)	L	H	L	H
Read and Autoprecharge	Active <sup>(3)</sup>	H	X	X	V	H		L	H	L	H
Mode Register Set	Idle	H	X	X	OP code			L	L	L	L
Extended MRS	Idle	H	X	X	OP code			L	L	L	L
No-Operation	Any	H	X	X	X	X	X	L	H	H	H
Burst Stop	Active <sup>(4)</sup>	H	X	X	X	X	X	L	H	H	L
Device Deselect	Any	H	X	X	X	X	X	H	X	X	X
AutoRefresh	Idle	H	H	X	X	X	X	L	L	L	H
SelfRefresh Entry	Idle	H	L	X	X	X	X	L	L	L	H
SelfRefresh Exit	Idle (SelfRefresh)	L	H	X	X	X	X	H	X	X	X
								L	H	H	H
Precharge Power Down Mode Entry	Idle	H	L	X	X	X	X	H	X	X	X
								L	H	H	H
Precharge Power Down Mode Exit	Any (PowerDown)	L	H	X	X	X	X	H	X	X	X
								L	H	H	H
Active Power Down Mode Entry	Active	H	L	X	X	X	X	H	X	X	X
								L	V	V	V
Active Power Down Mode Exit	Any (PowerDown)	L	H	X	X	X	X	H	X	X	X
								L	H	H	H
Data Input Mask Disable	Active	H	X	L	X	X	X	X	X	X	X
Data Input Mask Enable	Active	H	X	H	X	X	X	X	X	X	X

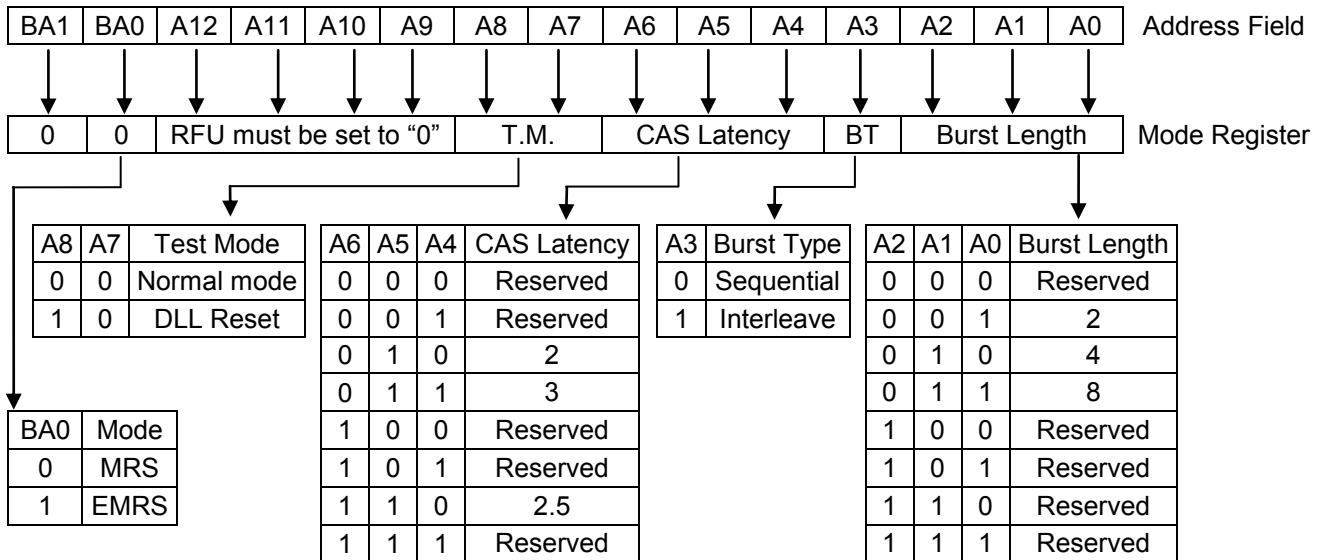
- Note:**
1. V=Valid data, X=Don't Care, L=Low level, H=High level
  2. CKE<sub>n</sub> signal is input level when commands are provided.  
CKE<sub>n-1</sub> signal is input level one clock cycle before the commands are provided.
  3. These are states of bank designated by BA signal.
  4. Device state is 2, 4, and 8 burst operation.



## Mode Register Set (MRS)

The Mode Register stores the data for controlling various operating modes of a DDR SDRAM. It programs CAS Latency, Burst Type, and Burst Length to make the DDR SDRAM useful for a variety of applications. The default value of the Mode Register is not defined; therefore the Mode Register must be written by the user. Values stored in the register will be retained until the register is reprogrammed. The Mode Register is written by asserting Low on  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ ,  $\overline{WE}$ , BA1 and BA0 (the device should have all banks idle with no bursts in progress prior to writing into the mode register, and CKE should be High). The state of address pins A0~A12 and BA0, BA1 in the same cycle in which  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$  and  $\overline{WE}$  are asserted Low is written into the Mode Register. A minimum of two clock cycles, tMRD, are required to complete the write operation in the Mode Register. The Mode Register is divided into various fields depending on functionality. The Burst Length uses A0~A2, Burst Type uses A3, and CAS Latency (read latency from column address) uses A4~A6. A logic 0 should be programmed to all the undefined addresses to ensure future compatibility. Reserved states should not be used to avoid unknown device operation or incompatibility with future versions. Refer to the table for specific codes for various burst lengths, burst types and CAS latencies.

**Table 4. Mode Register Bitmap**



- Burst Length Field (A2~A0)

This field specifies the data length of column access using the A2~A0 pins and selects the Burst Length to be 2, 4, 8.

**Table 5. Burst Length**

A2	A1	A0	Burst Length
0	0	0	Reserved
0	0	1	2
0	1	0	4
0	1	1	8
1	0	0	Reserved
1	0	1	Reserved
1	1	0	Reserved
1	1	1	Reserved

- Addressing Mode Select Field (A3)

The Addressing Mode can be one of two modes, either Interleave Mode or Sequential Mode. Both Sequential Mode and Interleave Mode support burst length of 2, 4 and 8.

**Table 6. Addressing Mode**

A3	Addressing Mode
0	Sequential
1	Interleave

- Burst Definition, Addressing Sequence of Sequential and Interleave Mode

**Table 7. Burst Address ordering**

Burst Length	Start Address			Sequential	Interleave
	A2	A1	A0		
2	X	X	0	0, 1	0, 1
	X	X	1	1, 0	1, 0
4	X	0	0	0, 1, 2, 3	0, 1, 2, 3
	X	0	1	1, 2, 3, 0	1, 0, 3, 2
	X	1	0	2, 3, 0, 1	2, 3, 0, 1
	X	1	1	3, 0, 1, 2	3, 2, 1, 0
8	0	0	0	0, 1, 2, 3, 4, 5, 6, 7	0, 1, 2, 3, 4, 5, 6, 7
	0	0	1	1, 2, 3, 4, 5, 6, 7, 0	1, 0, 3, 2, 5, 4, 7, 6
	0	1	0	2, 3, 4, 5, 6, 7, 0, 1	2, 3, 0, 1, 6, 7, 4, 5
	0	1	1	3, 4, 5, 6, 7, 0, 1, 2	3, 2, 1, 0, 7, 6, 5, 4
	1	0	0	4, 5, 6, 7, 0, 1, 2, 3	4, 5, 6, 7, 0, 1, 2, 3
	1	0	1	5, 6, 7, 0, 1, 2, 3, 4	5, 4, 7, 6, 1, 0, 3, 2
	1	1	0	6, 7, 0, 1, 2, 3, 4, 5	6, 7, 4, 5, 2, 3, 0, 1
1	1	1	7, 0, 1, 2, 3, 4, 5, 6	7, 6, 5, 4, 3, 2, 1, 0	

- CAS Latency Field (A6~A4)

This field specifies the number of clock cycles from the assertion of the Read command to the first read data. The minimum whole value of CAS Latency depends on the frequency of CK. The minimum whole value satisfying the following formula must be programmed into this field.  $t_{CAC}(\min) \leq \text{CAS Latency} \times t_{CK}$

**Table 8. CAS Latency**

A6	A5	A4	CAS Latency
0	0	0	Reserved
0	0	1	Reserved
0	1	0	2 clocks
0	1	1	3 clocks
1	0	0	Reserved
1	0	1	Reserved
1	1	0	2.5 clocks
1	1	1	Reserved

- Test Mode field (A8~A7)

These two bits are used to enter the test mode and must be programmed to "00" in normal operation.

**Table 9. Test Mode**

A8	A7	Test Mode
0	0	Normal mode
1	0	DLL Reset

- (BA0, BA1)

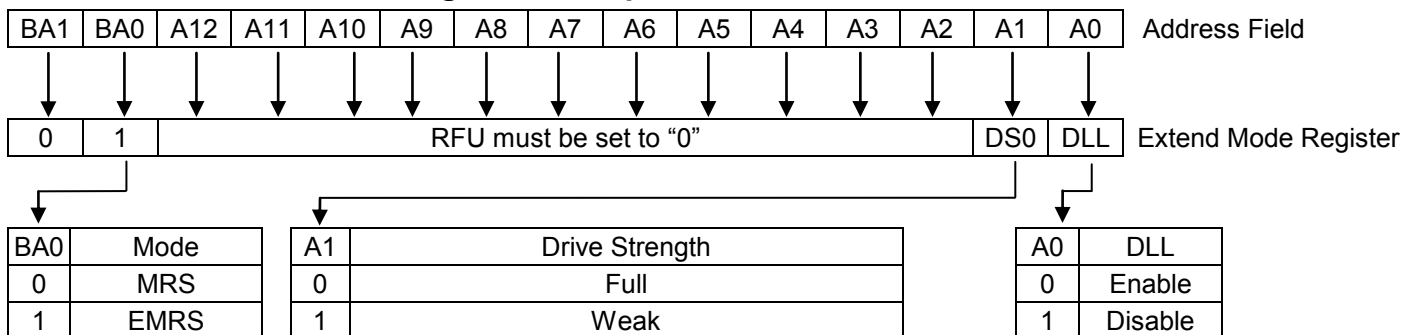
**Table 10. MRS/EMRS**

BA1	BA0	A12 ~ A0
RFU	0	MRS Cycle
RFU	1	Extended Functions (EMRS)

## Extended Mode Register Set (EMRS)

The Extended Mode Register Set stores the data for enabling or disabling DLL and selecting output driver strength. The default value of the extended mode register is not defined, therefore must be written after power up for proper operation. The Extended Mode Register is written by asserting Low on  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ ,  $\overline{WE}$ , BA1 and BA0 (the device should have all banks idle with no bursts in progress prior to writing into the mode register, and CKE should be High). The state of A0 ~ A12, BA0 and BA1 is written in the mode register in the same cycle as  $\overline{CS}$ ,  $\overline{RAS}$ ,  $\overline{CAS}$ , and  $\overline{WE}$  going low. The DDR SDRAM should be in all bank precharge with CKE already high prior to writing into the extended mode register. A1 is used for setting driver strength to normal, or weak. Two clock cycles are required to complete the write operation in the extended mode register. The mode register contents can be changed using the same command and clock cycle requirements during operation as long as all banks are in the idle state. A0 is used for DLL enable or disable. "High" on BA0 is used for EMRS. Refer to the table for specific codes.

**Table 11. Extended Mode Register Bitmap**



**Table 12. Absolute Maximum Rating**

Symbol	Item	Rating	Unit
V <sub>IN</sub> , V <sub>OUT</sub>	Input, Output Voltage	- 0.5~ V <sub>DDQ</sub> + 0.5	V
V <sub>DD</sub> , V <sub>DDQ</sub>	Power Supply Voltage	- 1~3.6	V
T <sub>A</sub>	Ambient Temperature	0~70	°C
T <sub>STG</sub>	Storage Temperature	- 55~150	°C
T <sub>SOLDER</sub>	Soldering Temperature	260	°C
P <sub>D</sub>	Power Dissipation	1	W
I <sub>OS</sub>	Short Circuit Output Current	50	mA

Note1: Stress greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device.

Note2: These voltages are relative to V<sub>SS</sub>

**Table 13. Recommended D.C. Operating Conditions (T<sub>A</sub> = 0 ~ 70 °C)**

Symbol	Parameter	Min.	Max.	Unit
V <sub>DD</sub>	Power Supply Voltage	2.3	2.7	V
V <sub>DDQ</sub>	Power Supply Voltage (for I/O Buffer)	2.3	2.7	V
V <sub>REF</sub>	Input Reference Voltage	0.49 x V <sub>DDQ</sub>	0.51 x V <sub>DDQ</sub>	V
V <sub>IH</sub> (DC)	Input High Voltage (DC)	V <sub>REF</sub> + 0.15	V <sub>DDQ</sub> + 0.3	V
V <sub>IL</sub> (DC)	Input Low Voltage (DC)	-0.3	V <sub>REF</sub> - 0.15	V
V <sub>TT</sub>	Termination Voltage	V <sub>REF</sub> - 0.04	V <sub>REF</sub> + 0.04	V
V <sub>IN</sub> (DC)	Input Voltage Level, CK and $\overline{CK}$ inputs	-0.3	V <sub>DDQ</sub> + 0.3	V
V <sub>ID</sub> (DC)	Input Different Voltage, CK and $\overline{CK}$ inputs	0.36	V <sub>DDQ</sub> + 0.6	V
I <sub>I</sub>	Input leakage current	-2	2	μA
I <sub>OZ</sub>	Output leakage current	-5	5	μA
I <sub>OH</sub>	Output High current (V <sub>OUT</sub> = 1.95V)	-16.2	-	mA
I <sub>OL</sub>	Output Low current (V <sub>OUT</sub> = 0.35V)	16.2	-	mA

Note : All voltages are referenced to V<sub>SS</sub>.

**Table 14. Capacitance (V<sub>DD</sub> = 2.5V, f = 1MHz, T<sub>A</sub> = 25 °C)**

Symbol	Parameter	Min.	Max.	Unit
C <sub>IN1</sub>	Input Capacitance (CK, $\overline{CK}$ )	2	3	pF
C <sub>IN2</sub>	Input Capacitance (All other input-only pins)	2	3	pF
C <sub>I/O</sub>	DQ, DQS, DM Input/Output Capacitance	4	5	pF

Note: These parameters are guaranteed by design, periodically sampled and are not 100% tested

**Table 15. D.C. Characteristics ( $V_{DD} = 2.5V \pm 0.2V$ ,  $T_A = 0 \sim 70 \text{ }^\circ\text{C}$ )**

Parameter & Test Condition	Symbol	-5	Unit
		Max.	
<b>OPERATING CURRENT:</b> One bank; Active-Precharge; $t_{RC}=t_{RC}(\text{min})$ ; $t_{CK}=t_{CK}(\text{min})$ ; DQ,DM and DQS inputs changing once per clock cycle; Address and control inputs changing once every two clock cycles.	IDD0	80	mA
<b>OPERATING CURRENT:</b> One bank; BL=4; reads - Refer to the following page for detailed test conditions	IDD1	90	mA
<b>PRECHARGE POWER-DOWN STANDBY CURRENT:</b> All banks idle; power-down mode; $t_{CK}=t_{CK}(\text{min})$ ; CKE = LOW	IDD2P	5	mA
<b>PRECHARGE FLOATING STANDBY CURRENT:</b> CS = HIGH; all banks idle; CKE = HIGH; $t_{CK} = t_{CK}(\text{min})$ ; address and other control inputs changing once per clock cycle; $V_{IN} = V_{REF}$ for DQ, DQS and DM	IDD2F	35	mA
<b>PRECHARGE QUIET STANDBY CURRENT:</b> CS =HIGH; all banks idle; CKE =HIGH; $t_{CK}=t_{CK}(\text{min})$ address and other control inputs stable at $\geq V_{IH}(\text{min})$ or $\leq V_{IL}(\text{max})$ ; $V_{IN} = V_{REF}$ for DQ, DQS and DM	IDD2Q	35	mA
<b>ACTIVE POWER-DOWN STANDBY CURRENT</b> : one bank active; power-down mode; CKE=LOW; $t_{CK}=t_{CK}(\text{min})$	IDD3P	20	mA
<b>ACTIVE STANDBY CURRENT</b> : $\overline{CS}$ =HIGH;CKE=HIGH; one bank active ; $t_{RC}=t_{RC}(\text{max})$ ; $t_{CK}=t_{CK}(\text{min})$ ;Address and control inputs changing once per clock cycle; DQ,DQS,and DM inputs changing twice per clock cycle	IDD3N	65	mA
<b>OPERATING CURRENT BURST READ</b> : BL=2; READS; Continuous burst; one bank active; Address and control inputs changing once per clock cycle; $t_{CK}=t_{CK}(\text{min})$ ; $I_{out}=0\text{mA}$ ;50% of data changing on every transfer	IDD4R	130	mA
<b>OPERATING CURRENT BURST Write</b> : BL=2; WRITES; Continuous Burst ;one bank active; address and control inputs changing once per clock cycle; $t_{CK}=t_{CK}(\text{min})$ ; DQ,DQS,and DM changing twice per clock cycle; 50% of data changing on every transfer	IDD4W	130	mA
<b>AUTO REFRESH CURRENT</b> : $t_{RC}=t_{RFC}(\text{min})$ ; $t_{CK}=t_{CK}(\text{min})$	IDD5	140	mA
<b>SELF REFRESH CURRENT:</b> Self Refresh Mode ; CKE $\leq 0.2V$ ; $t_{CK}=t_{CK}(\text{min})$	IDD6	6	mA
<b>BURST OPERATING CURRENT 4 bank operation:</b> Four bank interleaving READs; BL=4;with Auto Precharge; $t_{RC}=t_{RC}(\text{min})$ ; $t_{CK}=t_{CK}(\text{min})$ ; Address and control inputs change only during Active, READ , or WRITE command	IDD7	210	mA

**Table 16. Electrical Characteristics and Recommended A.C. Operating Condition**

( $V_{DD} = 2.5V \pm 0.2V$ ,  $T_A = 0 \sim 70^\circ C$ )

Symbol	Parameter	-5		Unit	Note	
		Min.	Max.			
t <sub>CK</sub>	Clock cycle time	CL = 2	7.5	12	ns	
		CL = 2.5	6	12	ns	
		CL = 3	5	12	ns	
t <sub>CH</sub>	Clock high level width	0.45	0.55	t <sub>CK</sub>		
t <sub>CL</sub>	Clock low level width	0.45	0.55	t <sub>CK</sub>		
t <sub>HP</sub>	Clock half period	t <sub>CLMIN</sub> or t <sub>CHMIN</sub>	-	ns	2	
t <sub>HZ</sub>	Data-out-high impedance time from CK, $\overline{CK}$	-	0.7	ns	3	
t <sub>LZ</sub>	Data-out-low impedance time from CK, $\overline{CK}$	-0.7	0.7	ns	3	
t <sub>DQ<sub>SCK</sub></sub>	DQS-out access time from CK, $\overline{CK}$	-0.6	0.6	ns		
t <sub>AC</sub>	Output access time from CK, $\overline{CK}$	-0.7	0.7	ns		
t <sub>DQ<sub>SQ</sub></sub>	DQS-DQ Skew	-	0.4	ns		
t <sub>RP<sub>RE</sub></sub>	Read preamble	0.9	1.1	t <sub>CK</sub>		
t <sub>RP<sub>ST</sub></sub>	Read postamble	0.4	0.6	t <sub>CK</sub>		
t <sub>DQ<sub>SS</sub></sub>	CK to valid DQS-in	0.72	1.25	t <sub>CK</sub>		
t <sub>WP<sub>PRES</sub></sub>	DQS-in setup time	0	-	ns	4	
t <sub>WP<sub>RE</sub></sub>	DQS Write preamble	0.25	-	t <sub>CK</sub>		
t <sub>WP<sub>ST</sub></sub>	DQS write postamble	0.4	0.6	t <sub>CK</sub>	5	
t <sub>DQ<sub>SH</sub></sub>	DQS in high level pulse width	0.35	-	t <sub>CK</sub>		
t <sub>DQ<sub>SL</sub></sub>	DQS in low level pulse width	0.35	-	t <sub>CK</sub>		
t <sub>IS</sub>	Address and Control input setup time	0.7	-	ns	6	
t <sub>IH</sub>	Address and Control input hold time	0.7	-	ns	6	
t <sub>DS</sub>	DQ & DM setup time to DQS	0.4	-	ns		
t <sub>DH</sub>	DQ & DM hold time to DQS	0.4	-	ns		
t <sub>QH</sub>	DQ/DQS output hold time from DQS	t <sub>HP</sub> - t <sub>QHS</sub>	-	ns		
t <sub>RC</sub>	Row cycle time	55	-	ns		
t <sub>RFC</sub>	Refresh row cycle time	70	-	ns		
t <sub>RAS</sub>	Row active time	40	70K	ns		
t <sub>RCD</sub>	Active to Read or Write delay	15	-	ns		
t <sub>RP</sub>	Row precharge time	15	-	ns		
t <sub>RRD</sub>	Row active to Row active delay	10	-	ns		
t <sub>WR</sub>	Write recovery time	15	-	ns		
t <sub>WTR</sub>	Internal Write to Read Command Delay	2	-	t <sub>CK</sub>		
t <sub>M<sub>RD</sub></sub>	Mode register set cycle time	10	-	ns		
t <sub>REFI</sub>	Average Periodic Refresh interval	-	7.8	μs	7	
t <sub>XSRD</sub>	Self refresh exit to read command delay	200	-	t <sub>CK</sub>		
t <sub>XSNR</sub>	Self refresh exit to non-read command delay	75	-	ns		
t <sub>DAL</sub>	Auto Precharge write recovery + precharge time	t <sub>WR</sub> +t <sub>RP</sub>	-	ns		
t <sub>DIPW</sub>	DQ and DM input pulse width	1.75	-	ns		
t <sub>IPW</sub>	Control and Address input pulse width	2.2	-	ns		
t <sub>QHS</sub>	Data Hold Skew Factor	-	0.5	ns		
t <sub>DSS</sub>	DQS falling edge to CK setup time	0.2	-	t <sub>CK</sub>		
t <sub>DSH</sub>	DQS falling edge hold time from CK	0.2	-	t <sub>CK</sub>		

**Table 17. Recommended A.C. Operating Conditions ( $V_{DD} = 2.5V \pm 0.2V$ ,  $T_A = 0 \sim 70 \text{ }^\circ\text{C}$ )**

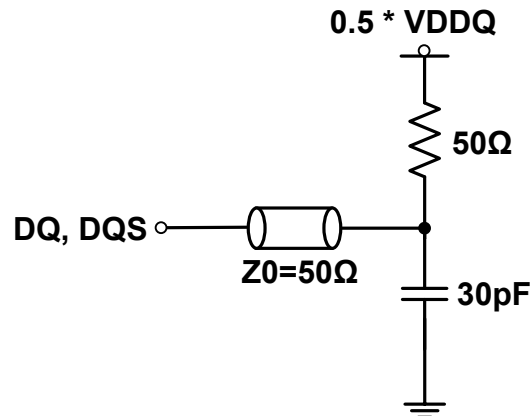
Symbol	Parameter	Min.	Max.	Unit
$V_{IH}$ (AC)	Input High Voltage (AC)	$V_{REF} + 0.31$	-	V
$V_{IL}$ (AC)	Input Low Voltage (AC)	-	$V_{REF} - 0.31$	V
$V_{ID}$ (AC)	Input Different Voltage, CK and $\overline{CK}$ inputs	0.7	$V_{DDQ} + 0.6$	V
$V_{IX}$ (AC)	Input Crossing Point Voltage, CK and $\overline{CK}$ inputs	$0.5 \times V_{DDQ} - 0.2$	$0.5 \times V_{DDQ} + 0.2$	V

**Note:**

- 1) Enables on-chip refresh and address counters.
- 2)  $\text{Min}(t_{CL}, t_{CH})$  refers to the smaller of the actual clock low time and actual clock high time as provided to the device.
- 3)  $t_{HZ}$  and  $t_{LZ}$  transitions occur in the same access time windows as valid data transitions. These parameters are not referenced to a specific voltage level, but specify when the device output is no longer driving(HZ), or begins driving(LZ).
- 4) The specific requirement is that DQS be valid (High, Low, or at some point on a valid transition) on or before this CLK edge. A valid transition is defined as monotonic, and meeting the input slew rate specifications of the device. When no writes were previously in progress on the bus, DQS will be transitioning from High-Z to logic LOW. If a previous write was in progress, DQS could be HIGH, LOW, or transitioning from HIGH to LOW at this time, depending on  $t_{DQSS}$ .
- 5) The maximum limit for this parameter is not a device limit. The device will operate with a greater value for this parameter, but system performance (bus turnaround) will degrade accordingly.
- 6) For command/address and CK &  $\overline{CK}$  slew rate  $\geq 1.0V/ns$ .
- 7) A maximum of eight AUTO REFRESH commands can be posted to any given DDR SDRAM device.
- 8) Power-up sequence is described in Note 10
- 9) A.C. Test Conditions

**Table 18. SSTL \_2 Interface**

Reference Level of Output Signals ( $V_{REF}$ )	$0.5 \times V_{DDQ}$
Output Load	Reference to the Test Load
Input Signal Levels	$V_{REF} + 0.31 \text{ V} / V_{REF} - 0.31 \text{ V}$
Input Signals Slew Rate	1 V/ns
Reference Level of Input Signals	$0.5 \times V_{DDQ}$

**Figure 3. SSTL\_2 A.C. Test Load**

**10) Power up Sequence**

Power up must be performed in the following sequence.

- 1) Apply power to  $V_{DD}$  before or at the same time as  $V_{DDQ}$ ,  $V_{TT}$  and  $V_{REF}$  when all input signals are held "NOP" state and maintain CKE "LOW".
- 2) Start clock and maintain stable condition for minimum 200 $\mu$ s.
- 3) Issue a "NOP" command and keep CKE "HIGH"
- 4) Issue a "Precharge All" command.
- 5) Issue EMRS – enable DLL.
- 6) Issue MRS – reset DLL. (An additional 200 clock cycles are required to lock the DLL).
- 7) Precharge all banks of the device.
- 8) Issue two or more Auto Refresh commands.
- 9) Issue MRS – with A8 to low to initialize the mode register.



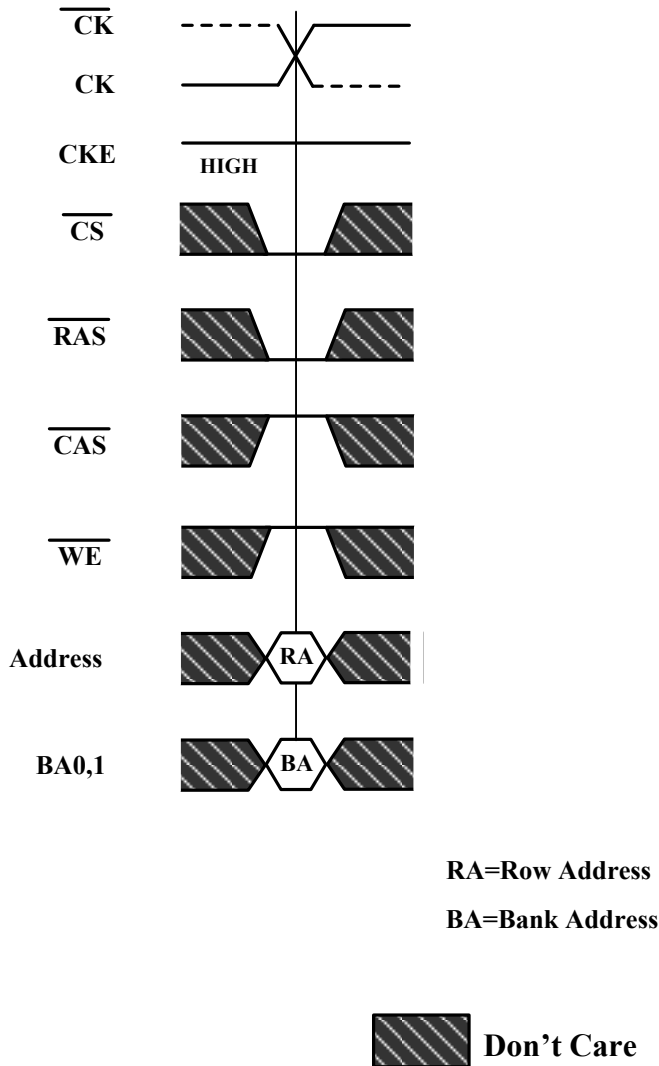
**Timing Waveforms**
**Figure 4. Activating a Specific Row in a Specific Bank**


Figure 5. t<sub>RCD</sub> and t<sub>RRD</sub> Definition

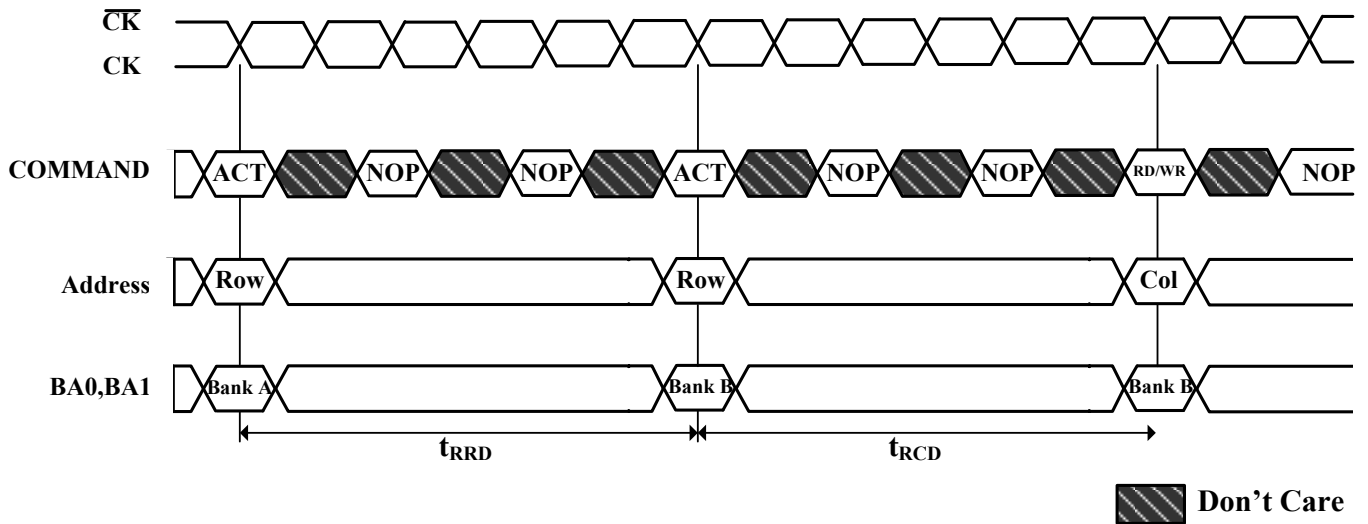
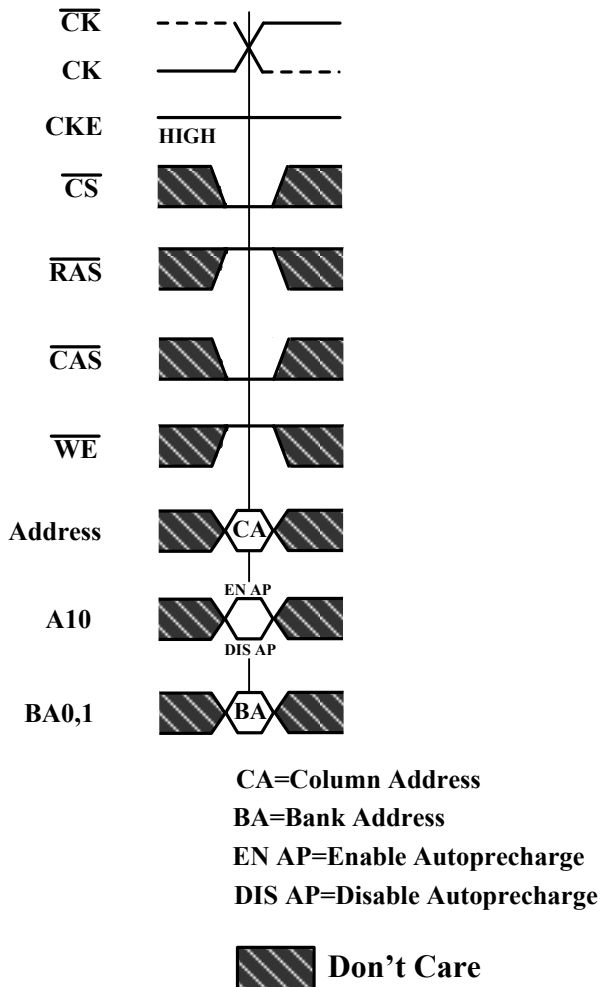
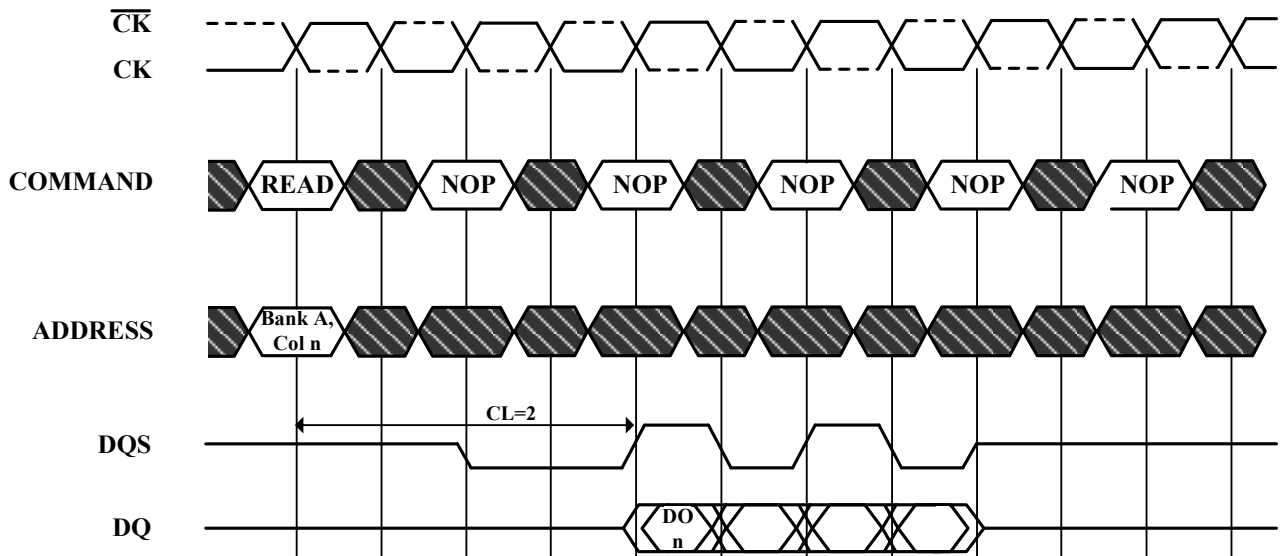


Figure 6. READ Command



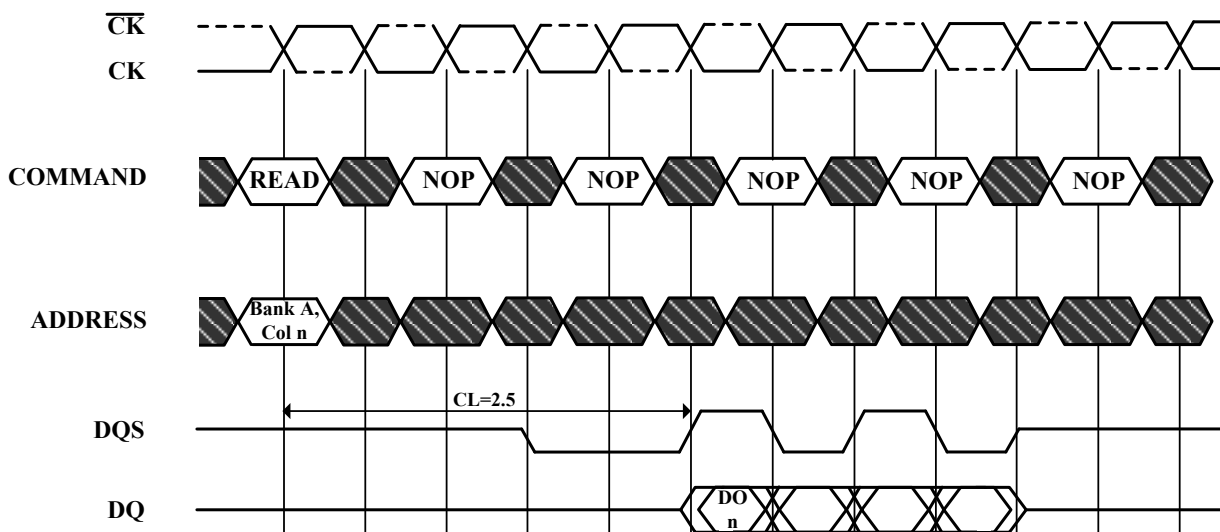
**Figure 7. Read Burst Required CAS Latencies (CL=2)**


DO n=Data Out from column n

Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n

 Don't Care

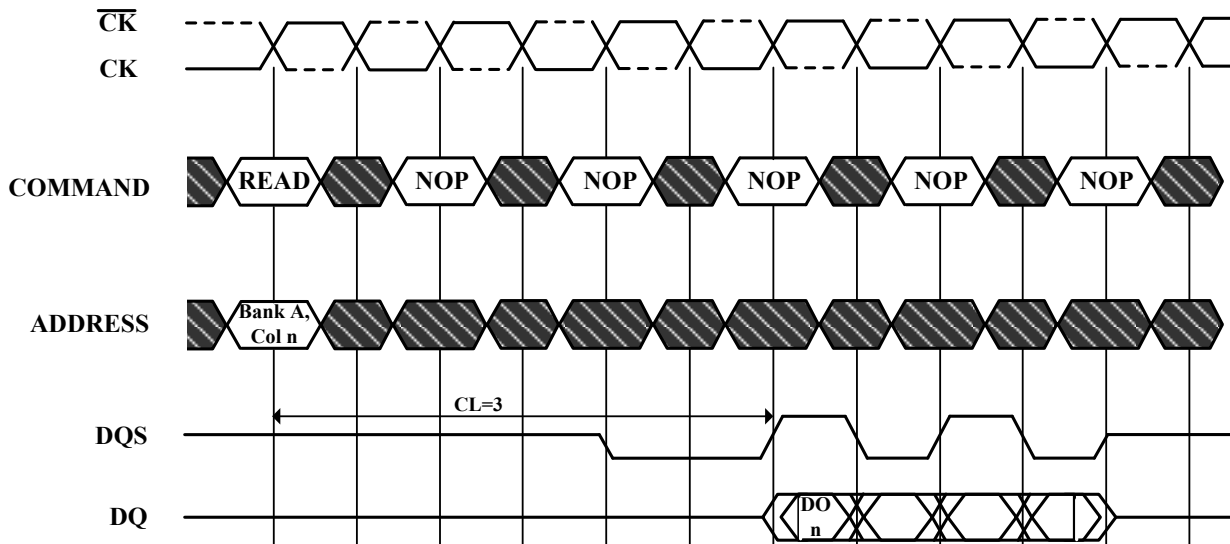
**Read Burst Required CAS Latencies (CL=2.5)**


DO n=Data Out from column n

Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n

 Don't Care

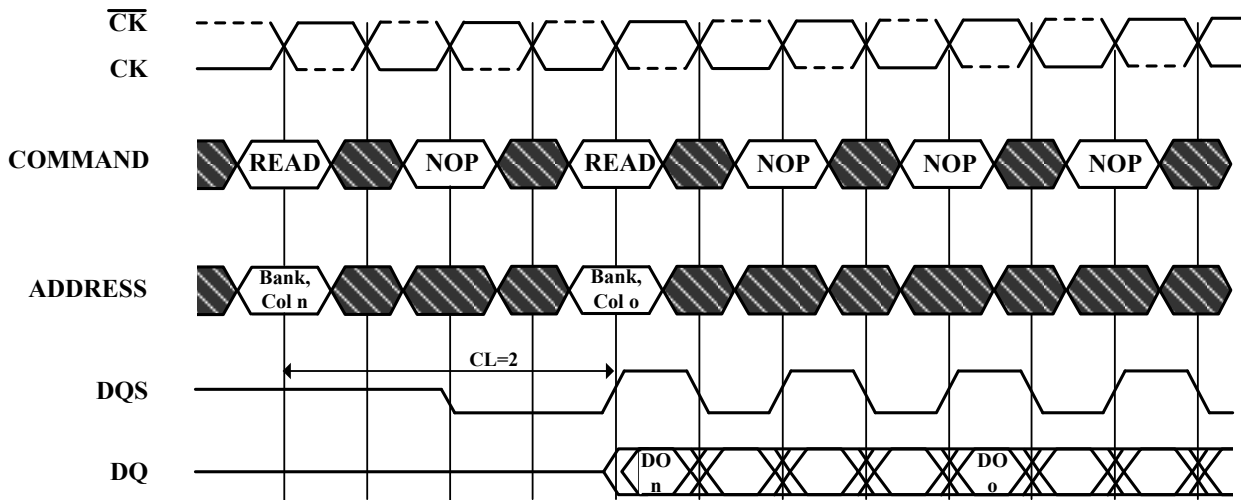
**Read Burst Required CAS Latencies (CL=3)**


DO n=Data Out from column n

Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n

 Don't Care

**Figure 8. Consecutive Read Bursts Required CAS Latencies (CL=2)**


**DO n (or o)=Data Out from column n (or column o)**

**Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first)**

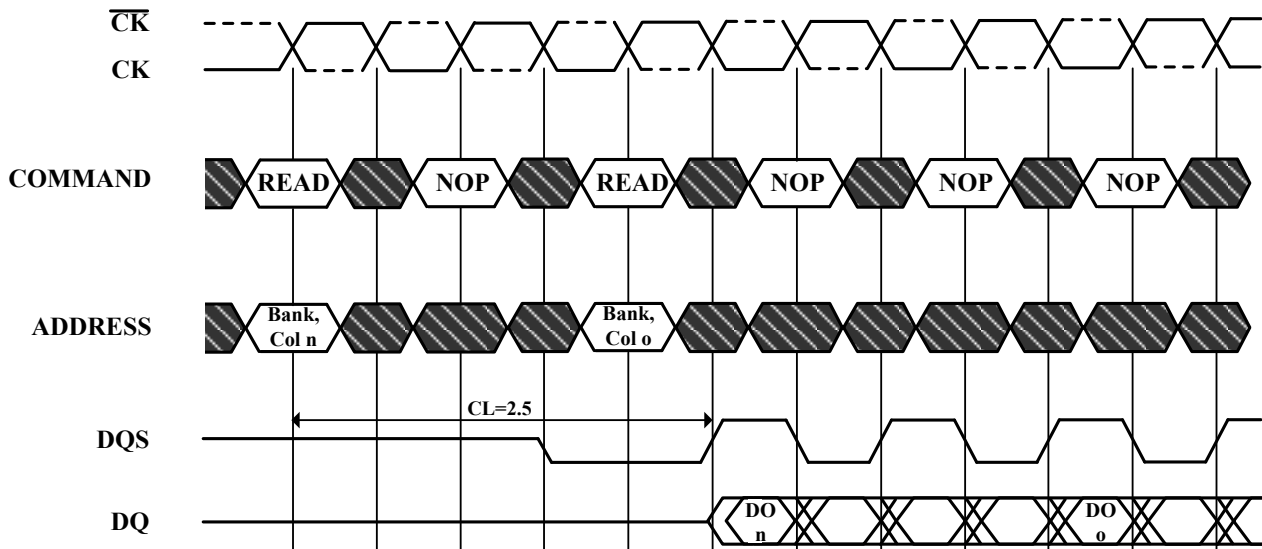
**3 subsequent elements of Data Out appear in the programmed order following DO n**

**3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o**

**Read commands shown must be to the same device**

 **Don't Care**

## Consecutive Read Bursts Required CAS Latencies (CL=2.5)



**DO n (or o)=Data Out from column n (or column o)**

**Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first)**

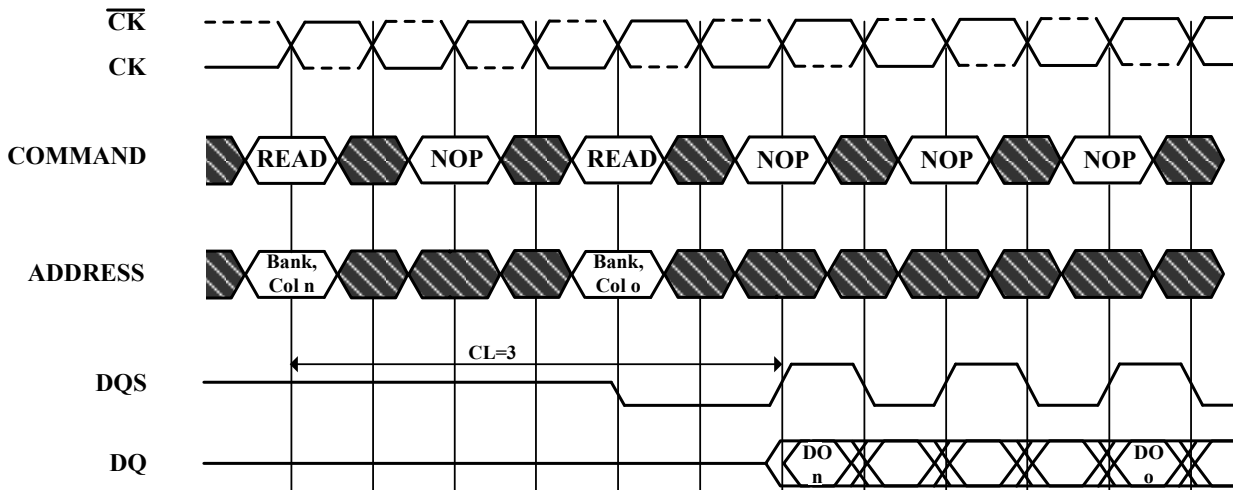
**3 subsequent elements of Data Out appear in the programmed order following DO n**

**3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o**

**Read commands shown must be to the same device**

 **Don't Care**

## Consecutive Read Bursts Required CAS Latencies (CL=3)



DO n (or o)=Data Out from column n (or column o)

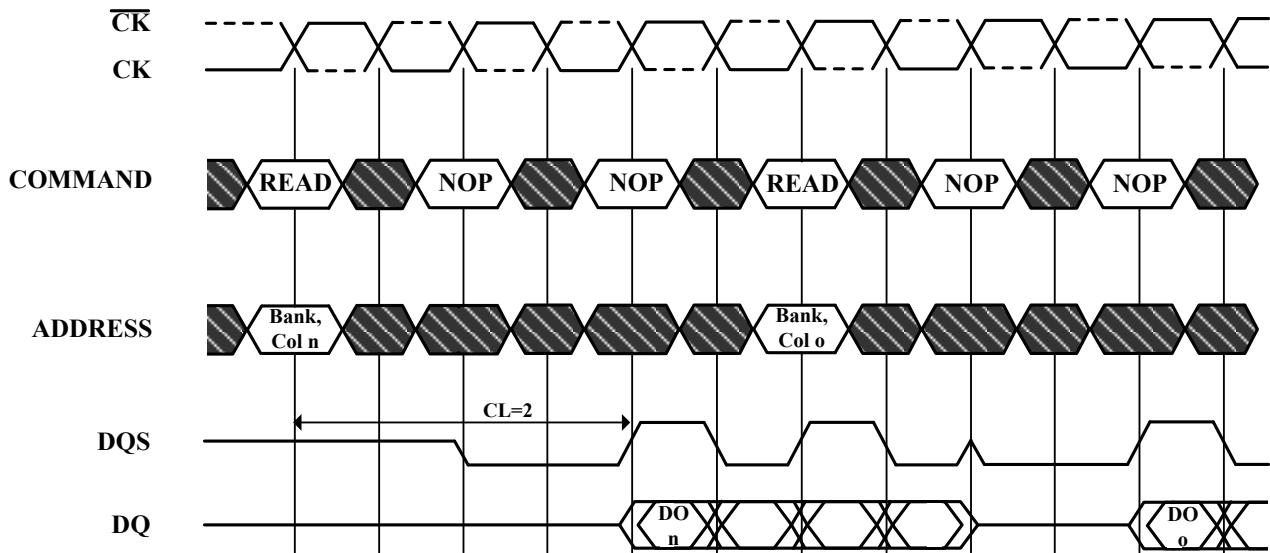
Burst Length=4 or 8 (if 4, the bursts are concatenated; if 8, the second burst interrupts the first)

3 subsequent elements of Data Out appear in the programmed order following DO n

3 (or 7) subsequent elements of Data Out appear in the programmed order following DO o

Read commands shown must be to the same device

 Don't Care

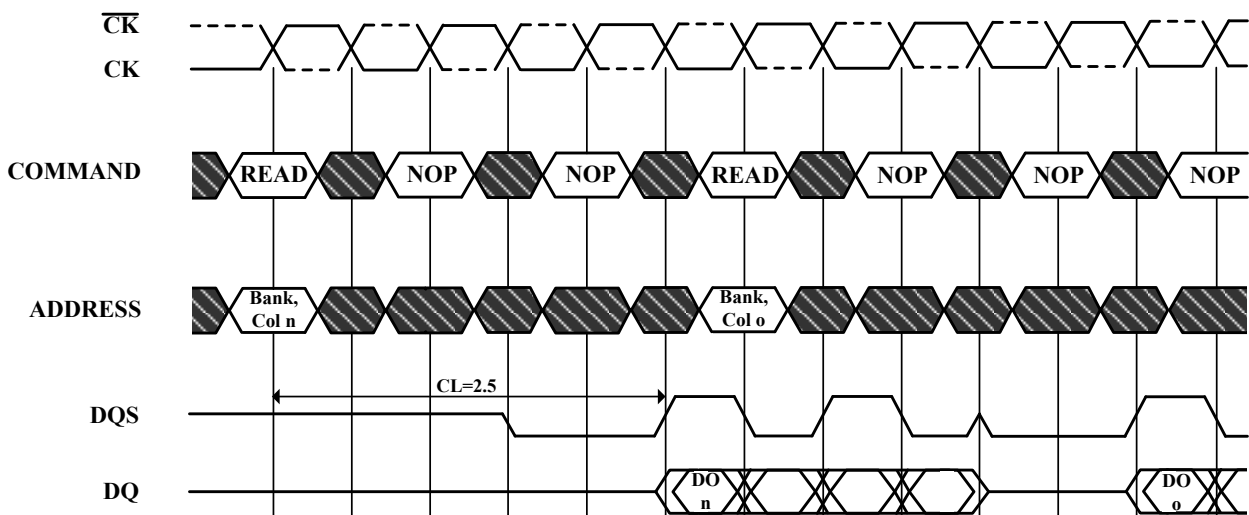
**Figure 9. Non-Consecutive Read Bursts Required CAS Latencies (CL=2)**


DO n (or o)=Data Out from column n (or column o)

Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n  
(and following DO o)

 Don't Care

**Non-Consecutive Read Bursts Required CAS Latencies (CL=2.5)**


DO n (or o)=Data Out from column n (or column o)

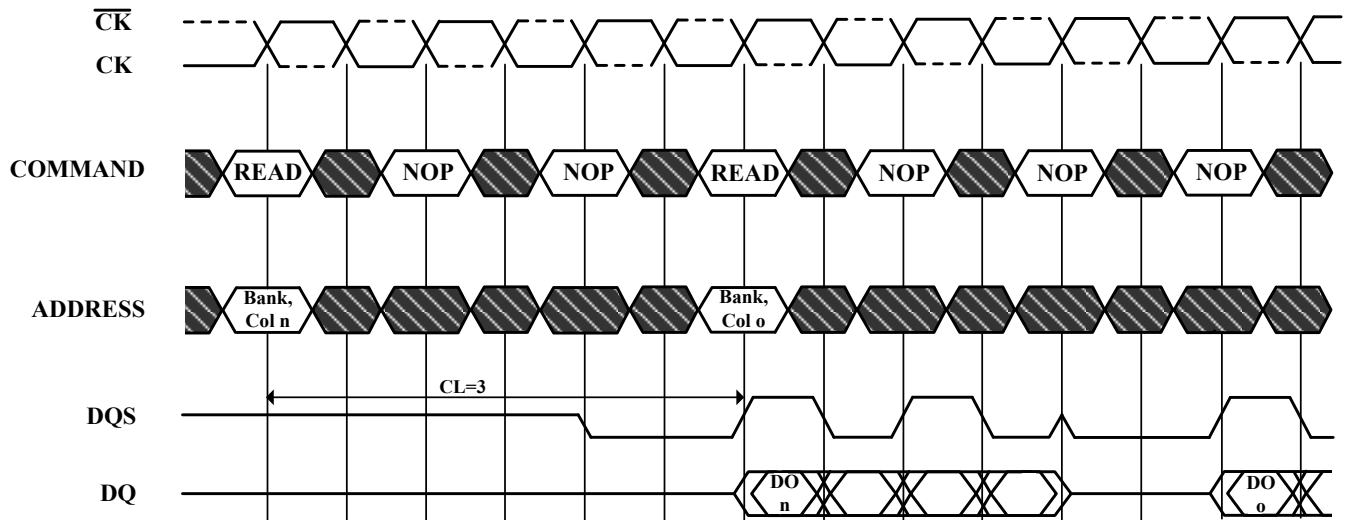
Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n  
(and following DO o)

 Don't Care



## Non-Consecutive Read Bursts Required CAS Latencies (CL=3)

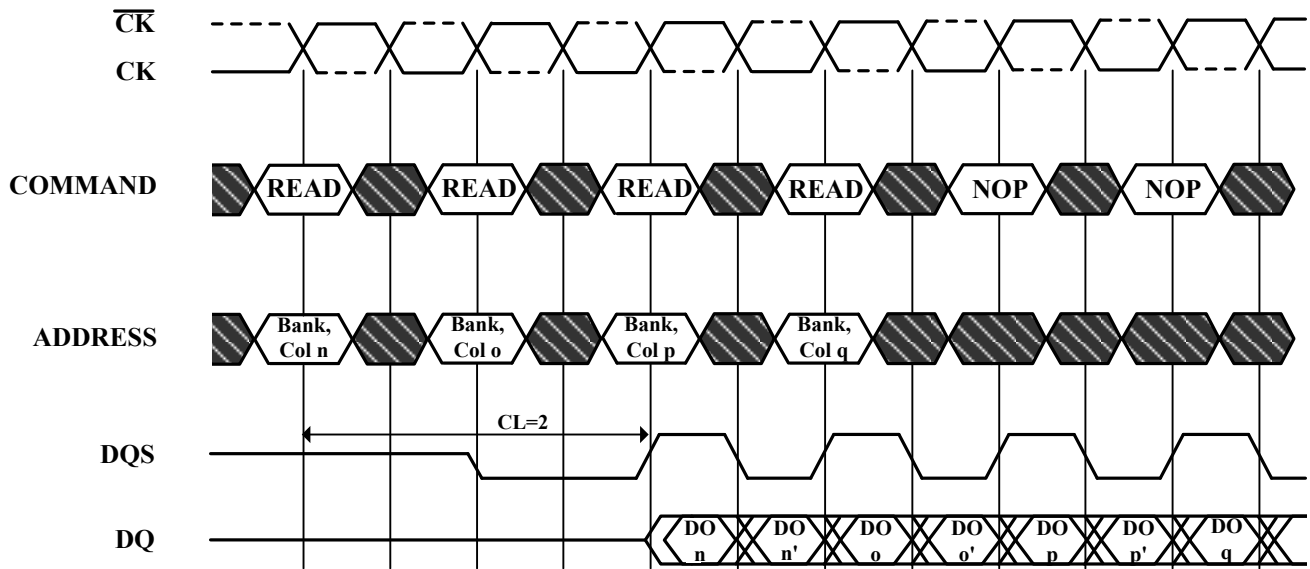


DO n (or o)=Data Out from column n (or column o)

Burst Length=4

3 subsequent elements of Data Out appear in the programmed order following DO n (and following DO o)

 Don't Care

**Figure 10. Random Read Accesses Required CAS Latencies (CL=2)**


DO n, etc. =Data Out from column n, etc.

n', etc. =the next Data Out following DO n, etc. according to the programmed burst order

Burst Length=2,4 or 8 in cases shown. If burst of 4 or 8, the burst is interrupted

Reads are to active rows in any banks

 Don't Care