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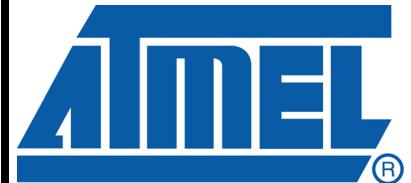
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Features

- High Performance, Low Power 32-bit AVR® Microcontroller
 - Compact Single-cycle RISC Instruction Set Including DSP Instruction Set
 - Built-in Floating-Point Processing Unit (FPU)
 - Read-Modify-Write Instructions and Atomic Bit Manipulation
 - Performing 1.49 DMIPS / MHz
 - Up to 91 DMIPS Running at 66 MHz from Flash (1 Wait-State)
 - Up to 49 DMIPS Running at 33 MHz from Flash (0 Wait-State)
 - Memory Protection Unit
- Multi-hierarchy Bus System
 - High-Performance Data Transfers on Separate Buses for Increased Performance
 - 16 Peripheral DMA Channels Improves Speed for Peripheral Communication
- Internal High-Speed Flash
 - 512 Kbytes, 256 Kbytes, 128 Kbytes, 64 Kbytes Versions
 - Single Cycle Access up to 33 MHz
 - FlashVault™ Technology Allows Pre-programmed Secure Library Support for End User Applications
 - Prefetch Buffer Optimizing Instruction Execution at Maximum Speed
 - 100,000 Write Cycles, 15-year Data Retention Capability
 - Flash Security Locks and User Defined Configuration Area
- Internal High-Speed SRAM, Single-Cycle Access at Full Speed
 - 64 Kbytes (512 KB and 256 KB Flash), 32 Kbytes (128 KB Flash), 16 Kbytes (64 KB Flash)
 - 4 Kbytes on the Multi-Layer Bus System (HSB RAM)
- External Memory Interface on AT32UC3C0 Derivatives
 - SDRAM / SRAM Compatible Memory Bus (16-bit Data and 24-bit Address Buses)
- Interrupt Controller
 - Autovectored Low Latency Interrupt Service with Programmable Priority
- System Functions
 - Power and Clock Manager
 - Internal 115KHz (RCSYS) and 8MHz/1MHz (RC8M) RC Oscillators
 - One 32 KHz and Two Multipurpose Oscillators
 - Clock Failure detection
 - Two Phase-Lock-Loop (PLL) allowing Independent CPU Frequency from USB or CAN Frequency
- Windowed Watchdog Timer (WDT)
- Asynchronous Timer (AST) with Real-Time Clock Capability
 - Counter or Calendar Mode Supported
- Frequency Meter (FREQM) for Accurate Measuring of Clock Frequency
- Ethernet MAC 10/100 Mbps interface
 - 802.3 Ethernet Media Access Controller
 - Supports Media Independent Interface (MII) and Reduced MII (RMII)
- Universal Serial Bus (USB)
 - Device 2.0 and Embedded Host Low Speed and Full Speed
 - Flexible End-Point Configuration and Management with Dedicated DMA Channels
 - On-chip Transceivers Including Pull-Ups
- One 2-channel Controller Area Network (CAN)
 - CAN2A and CAN2B protocol compliant, with high-level mailbox system
 - Two independent channels, 16 Message Objects per Channel



32-bit AVR® Microcontroller

AT32UC3C0512C

AT32UC3C0256C

AT32UC3C0128C

AT32UC3C064C

AT32UC3C1512C

AT32UC3C1256C

AT32UC3C1128C

AT32UC3C164C

AT32UC3C2512C

AT32UC3C2256C

AT32UC3C2128C

AT32UC3C264C

Summary

NOTE: This is a summary document. The complete document is available on the Atmel website at www.atmel.com.



- One 4-Channel 20-bit Pulse Width Modulation Controller (PWM)
 - Complementary outputs, with Dead Time Insertion
 - Output Override and Fault Protection
- Two Quadrature Decoders
- One 16-channel 12-bit Pipelined Analog-To-Digital Converter (ADC)
 - Dual Sample and Hold Capability Allowing 2 Synchronous Conversions
 - Single-Ended and Differential Channels, Window Function
- Two 12-bit Digital-To-Analog Converters (DAC), with Dual Output Sample System
- Four Analog Comparators
- Six 16-bit Timer/Counter (TC) Channels
 - External Clock Inputs, PWM, Capture and Various Counting Capabilities
- One Peripheral Event Controller
 - Trigger Actions in Peripherals Depending on Events Generated from Peripherals or from Input Pins
 - Deterministic Trigger
 - 34 Events and 22 Event Actions
- Five Universal Synchronous/Asynchronous Receiver/Transmitters (USART)
 - Independent Baudrate Generator, Support for SPI, LIN, IrDA and ISO7816 interfaces
 - Support for Hardware Handshaking, RS485 Interfaces and Modem Line
- Two Master/Slave Serial Peripheral Interfaces (SPI) with Chip Select Signals
- One Inter-IC Sound (I2S) Controller
 - Compliant with I2S Bus Specification
 - Time Division Multiplexed mode
- Three Master and Three Slave Two-Wire Interfaces (TWI), 400kbit/s I²C-compatible
- QTouch® Library Support
 - Capacitive Touch Buttons, Sliders, and Wheels
 - QTouch® and QMatrix® Acquisition
- On-Chip Non-intrusive Debug System
 - Nexus Class 2+, Runtime Control, Non-Intrusive Data and Program Trace
 - aWire™ single-pin programming trace and debug interface muxed with reset pin
 - NanoTrace™ provides trace capabilities through JTAG or aWire interface
- 3 package options
 - 64-pin QFN/TQFP (45 GPIO pins)
 - 100-pin TQFP (81 GPIO pins)
 - 144-pin LQFP (123 GPIO pins)
- Two operating voltage ranges:
 - Single 5V Power Supply
 - Single 3.3V Power Supply

1. Description

The AT32UC3C is a complete System-On-Chip microcontroller based on the AVR32UC RISC processor running at frequencies up to 66 MHz. AVR32UC is a high-performance 32-bit RISC microprocessor core, designed for cost-sensitive embedded applications, with particular emphasis on low power consumption, high code density and high performance.

The processor implements a Memory Protection Unit (MPU) and a fast and flexible interrupt controller for supporting modern operating systems and real-time operating systems. Using the Secure Access Unit (SAU) together with the MPU provides the required security and integrity.

Higher computation capabilities are achievable either using a rich set of DSP instructions or using the floating-point instructions.

The AT32UC3C incorporates on-chip Flash and SRAM memories for secure and fast access. For applications requiring additional memory, an external memory interface is provided on AT32UC3C0 derivatives.

The Memory Direct Memory Access controller (MDMA) enables transfers of block of data from memories to memories without processor involvement.

The Peripheral Direct Memory Access (PDCA) controller enables data transfers between peripherals and memories without processor involvement. The PDCA drastically reduces processing overhead when transferring continuous and large data streams.

The AT32UC3C incorporates on-chip Flash and SRAM memories for secure and fast access. The FlashVault technology allows secure libraries to be programmed into the device. The secure libraries can be executed while the CPU is in Secure State, but not read by non-secure software in the device. The device can thus be shipped to end customers, who are able to program their own code into the device, accessing the secure libraries, without any risk of compromising the proprietary secure code.

The Power Manager improves design flexibility and security. Power monitoring is supported by on-chip Power-On Reset (POR), Brown-Out Detectors (BOD18, BOD33, BOD50). The CPU runs from the on-chip RC oscillators, the PLLs, or the Multipurpose Oscillators. The Asynchronous Timer (AST) combined with the 32 KHz oscillator keeps track of the time. The AST can operate in counter or calendar mode.

The device includes six identical 16-bit Timer/Counter (TC) channels. Each channel can be independently programmed to perform frequency measurement, event counting, interval measurement, pulse generation, delay timing, and pulse width modulation.

The PWM module provides four channels with many configuration options including polarity, edge alignment and waveform non overlap control. The PWM channels can operate independently, with duty cycles set independently from each other, or in interlinked mode, with multiple channels updated at the same time. It also includes safety feature with fault inputs and the ability to lock the PWM configuration registers and the PWM pin assignment.

The AT32UC3C also features many communication interfaces for communication intensive applications. In addition to standard serial interfaces like UART, SPI or TWI, other interfaces like flexible CAN, USB and Ethernet MAC are available. The USART supports different communication modes, like SPI mode and LIN mode.

The Inter-IC Sound Controller (I2SC) provides a 5-bit wide, bidirectional, synchronous, digital audio link with off-chip audio devices. The controller is compliant with the I2S bus specification.



The Full-Speed USB 2.0 Device interface supports several USB Classes at the same time thanks to the rich End-Point configuration. The On-The-GO (OTG) Host interface allows device like a USB Flash disk or a USB printer to be directly connected to the processor.

The media-independent interface (MII) and reduced MII (RMII) 10/100 Ethernet MAC module provides on-chip solutions for network-connected devices.

The Peripheral Event Controller (PEVC) allows to redirect events from one peripheral or from input pins to another peripheral. It can then trigger, in a deterministic time, an action inside a peripheral without the need of CPU. For instance a PWM waveform can directly trigger an ADC capture, hence avoiding delays due to software interrupt processing.

The AT32UC3C features analog functions like ADC, DAC, Analog comparators. The ADC interface is built around a 12-bit pipelined ADC core and is able to control two independent 8-channel or one 16-channel. The ADC block is able to measure two different voltages sampled at the same time. The analog comparators can be paired to detect when the sensing voltage is within or outside the defined reference window.

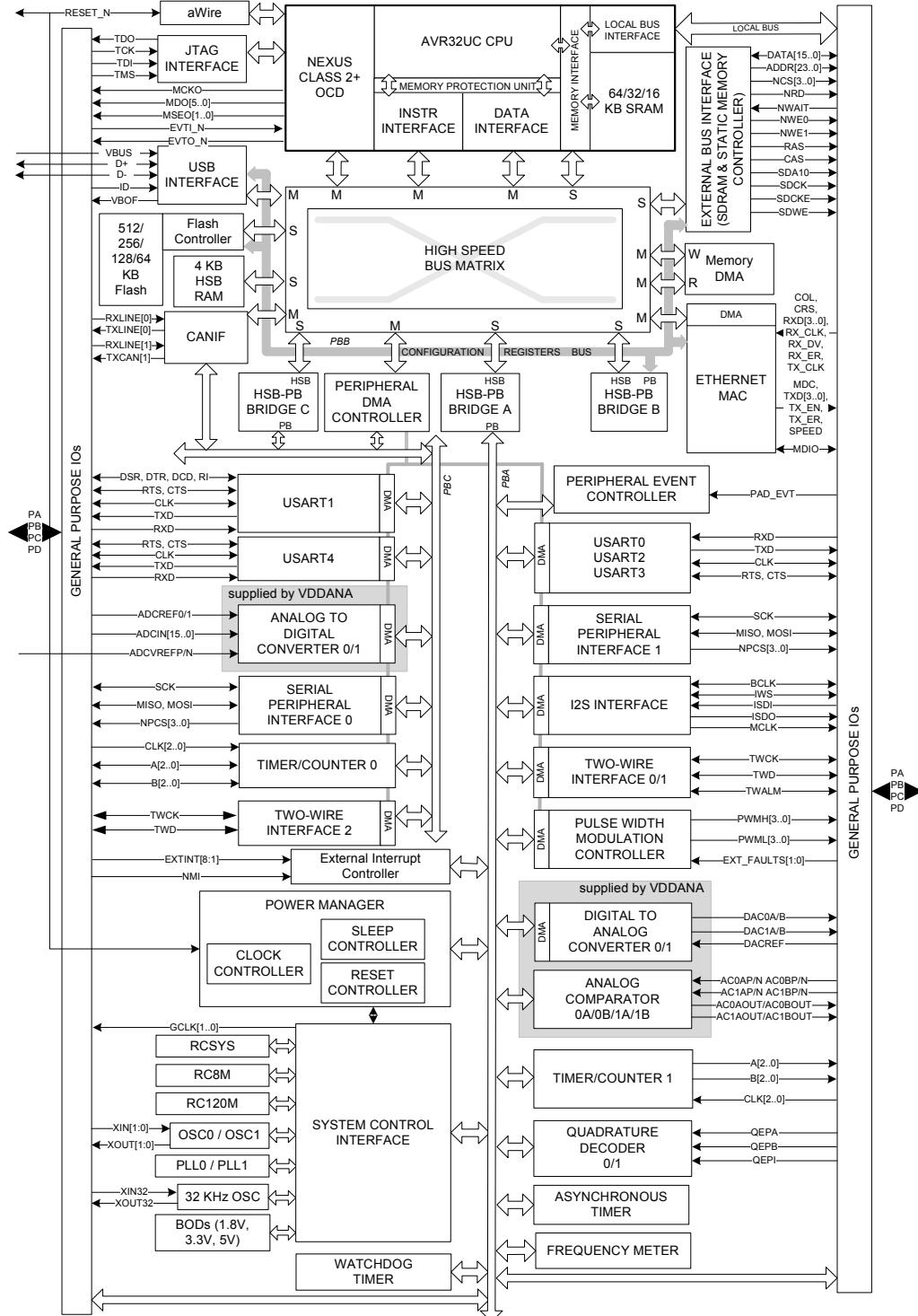
Atmel offers the QTouch library for embedding capacitive touch buttons, sliders, and wheels functionality into AVR microcontrollers. The patented charge-transfer signal acquisition offers robust sensing and included fully debounced reporting of touch keys and includes Adjacent Key Suppression® (AKS®) technology for unambiguous detection of key events. The easy-to-use QTouch Suite toolchain allows you to explore, develop, and debug your own touch applications.

AT32UC3C integrates a class 2+ Nexus 2.0 On-Chip Debug (OCD) System, with non-intrusive real-time trace, full-speed read/write memory access in addition to basic runtime control. The Nanotrace interface enables trace feature for aWire- or JTAG-based debuggers. The single-pin aWire interface allows all features available through the JTAG interface to be accessed through the RESET pin, allowing the JTAG pins to be used for GPIO or peripherals.

2. Overview

2.1 Block diagram

Figure 2-1. Block diagram



2.2 Configuration Summary

Table 2-1. Configuration Summary

Feature	AT32UC3C0512C/ AT32UC3C0256C/ AT32UC3C0128C/ AT32UC3C064C	AT32UC3C1512C/ AT32UC3C1256C/ AT32UC3C1128C/ AT32UC3C164C	AT32UC3C2512C/ AT32UC3C2256C/ AT32UC3C2128C/ AT32UC3C264C
Flash	512/256/128/64 KB	512/256/128/64 KB	512/256/128/64 KB
SRAM	64/64/32/16KB	64/64/32/16KB	64/64/32/16KB
HSB RAM	4 KB		
EBI	1	0	0
GPIO	123	81	45
External Interrupts	8	8	8
TWI	3	3	2
USART	5	5	4
Peripheral DMA Channels	16	16	16
Peripheral Event System	1	1	1
SPI	2	2	1
CAN channels	2	2	2
USB	1	1	1
Ethernet MAC 10/100	1 RMII/MII	1 RMII/MII	1 RMII only
I2S	1	1	1
Asynchronous Timers	1	1	1
Timer/Counter Channels	6	6	3
PWM channels	4x2		
QDEC	2	2	1
Frequency Meter	1		
Watchdog Timer	1		
Power Manager	1		
Oscillators	PLL 80-240 MHz (PLL0/PLL1) Crystal Oscillator 0.4-20 MHz (OSC0) Crystal Oscillator 32 KHz (OSC32K) RC Oscillator 115 kHz (RCSYS) RC Oscillator 8 MHz (RC8M) RC Oscillator 120 MHz (RC120M)		
	0.4-20 MHz (OSC1)		-
12-bit ADC number of channels	1 16	1 16	1 11
12-bit DAC number of channels	1 4	1 4	1 2



Table 2-1. Configuration Summary

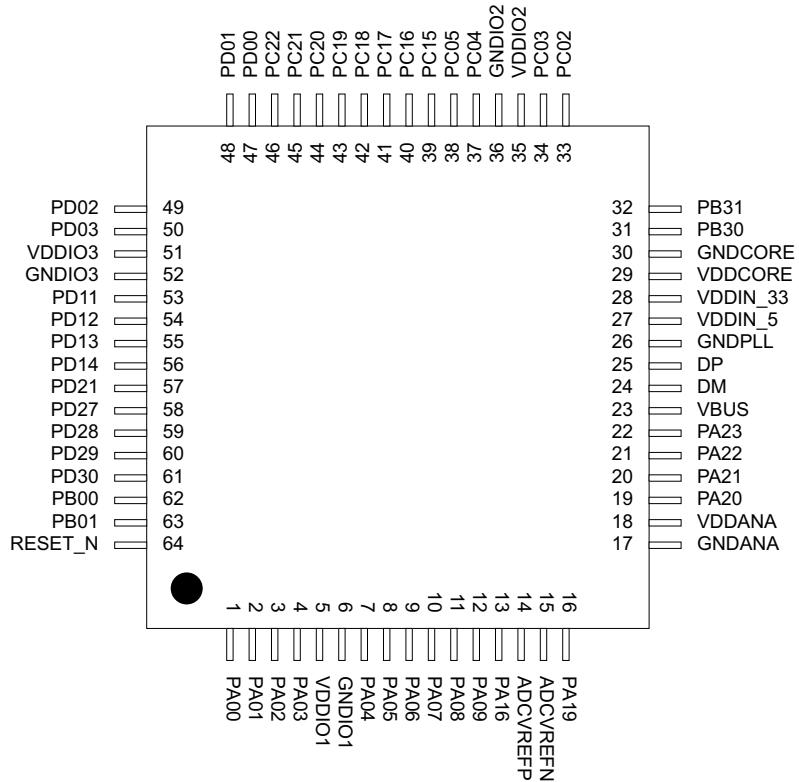
Feature	AT32UC3C0512C/ AT32UC3C0256C/ AT32UC3C0128C/ AT32UC3C064C	AT32UC3C1512C/ AT32UC3C1256C/ AT32UC3C1128C/ AT32UC3C164C	AT32UC3C2512C/ AT32UC3C2256C/ AT32UC3C2128C/ AT32UC3C264C
Analog Comparators	4	4	2
JTAG		1	
aWire		1	
Max Frequency		66 MHz	
Package	LQFP144	TQFP100	TQFP64/QFN64

3. Package and Pinout

3.1 Package

The device pins are multiplexed with peripheral functions as described in [Table 3-1 on page 11](#).

Figure 3-1. QFN64/TQFP64 Pinout



Note: on QFN packages, the exposed pad is unconnected.

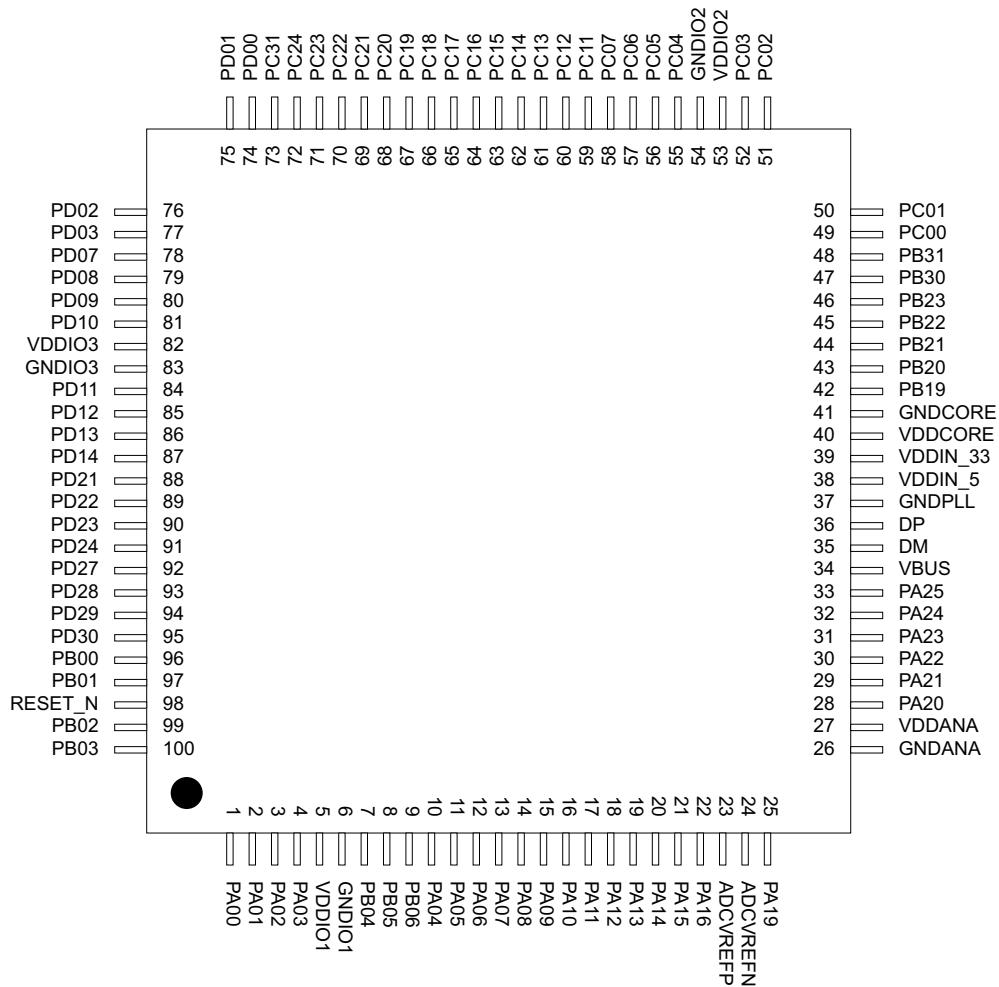
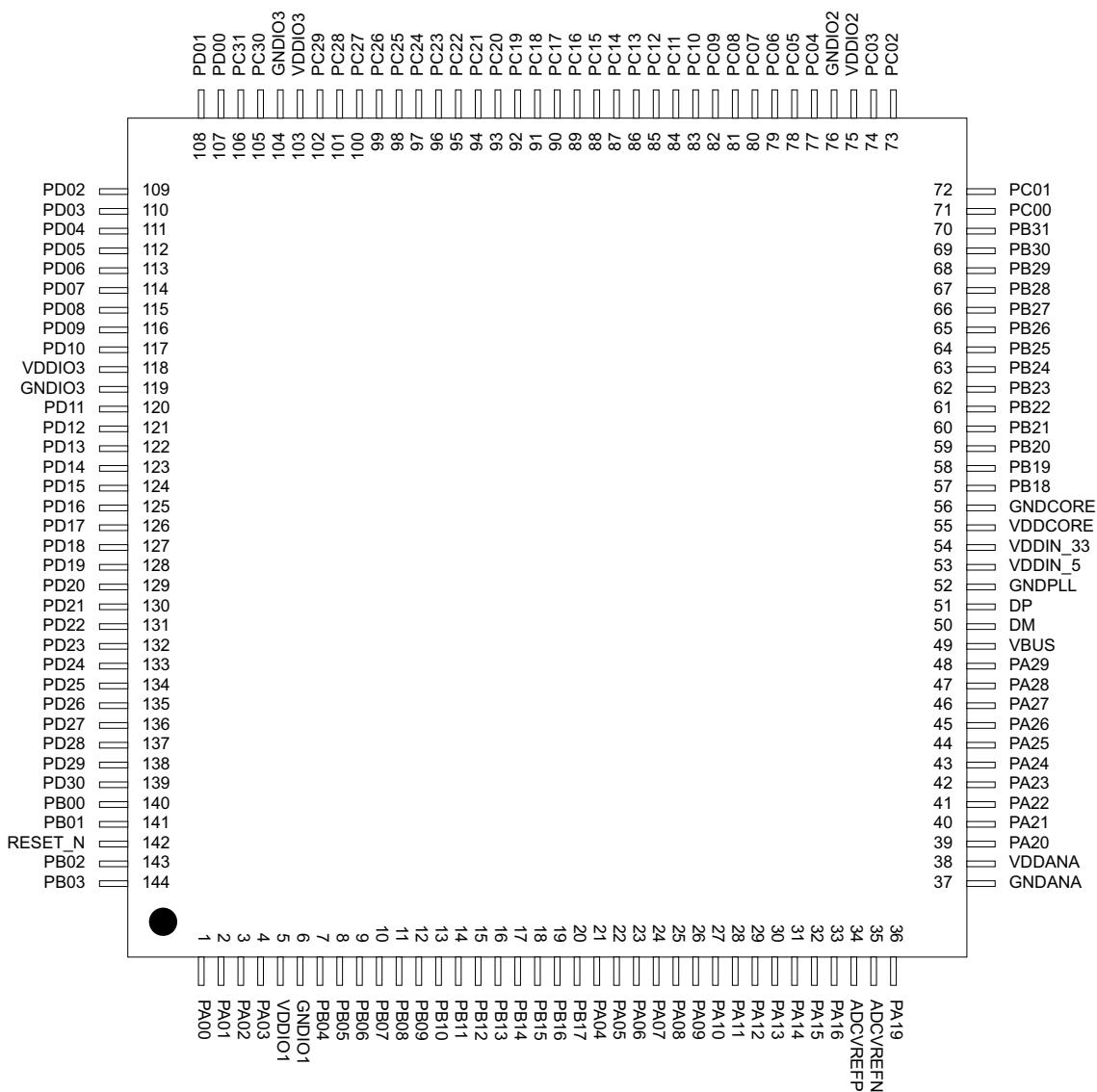
Figure 3-2. TQFP100 Pinout

Figure 3-3. LQFP144 Pinout

3.2 Peripheral Multiplexing on I/O lines

3.2.1 Multiplexed Signals

Each GPIO line can be assigned to one of the peripheral functions. The following table describes the peripheral signals multiplexed to the GPIO lines.

Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type ⁽¹⁾	GPIO function					
							A	B	C	D	E	F
1	1	1	PA00	0	VDDIO1	x1/x2		CANIF - TXLINE[1]				
2	2	2	PA01	1	VDDIO1	x1/x2		CANIF - RXLINE[1]	PEVC - PAD_EVT [0]			
3	3	3	PA02	2	VDDIO1	x1/x2	SCIF - GCLK[0]		PEVC - PAD_EVT [1]			
4	4	4	PA03	3	VDDIO1	x1/x2	SCIF - GCLK[1]	EIC - EXTINT[1]				
7	10	21	PA04	4	VDDANA	x1/x2	ADCIN0	USBC - ID	ACIFA0 - ACAOUT			
8	11	22	PA05	5	VDDANA	x1/x2	ADCIN1	USBC - VBOF	ACIFA0 - ACBOUT			
9	12	23	PA06	6	VDDANA	x1/x2	ADCIN2	AC1AP1	PEVC - PAD_EVT [2]			
10	13	24	PA07	7	VDDANA	x1/x2	ADCIN3	AC1AN1	PEVC - PAD_EVT [3]			
11	14	25	PA08	8	VDDANA	x1/x2	ADCIN4	AC1BP1	EIC - EXTINT[2]			
12	15	26	PA09	9	VDDANA	x1/x2	ADCIN5	AC1BN1				
	16	27	PA10	10	VDDANA	x1/x2	ADCIN6	EIC - EXTINT[4]	PEVC - PAD_EVT [13]			
	17	28	PA11	11	VDDANA	x1/x2	ADCIN7	ADCREF1	PEVC - PAD_EVT [14]			
	18	29	PA12	12	VDDANA	x1/x2	AC1AP0	SPI0 - NPCS[0]	AC1AP0 or DAC1A			
	19	30	PA13	13	VDDANA	x1/x2	AC1AN0	SPI0 - NPCS[1]	ADCIN15			
	20	31	PA14	14	VDDANA	x1/x2	AC1BP0	SPI1 - NPCS[0]				
	21	32	PA15	15	VDDANA	x1/x2	AC1BN0	SPI1 - NPCS[1]	AC1BN0 or DAC1B			
13	22	33	PA16	16	VDDANA	x1/x2	ADCREF0		DACREF			
14	23	34	ADC REFP									
15	24	35	ADC REFN									

Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type (1)	GPIO function					
							A	B	C	D	E	F
16	25	36	PA19	19	VDDANA	x1/x2	ADCIN8	EIC - EXTINT[1]				
19	28	39	PA20	20	VDDANA	x1/x2	ADCIN9	AC0AP0	AC0AP0 or DAC0A			
20	29	40	PA21	21	VDDANA	x1/x2	ADCIN10	AC0BN0	AC0BN0 or DAC0B			
21	30	41	PA22	22	VDDANA	x1/x2	ADCIN11	AC0AN0	PEVC - PAD_EVT [4]		MACB - SPEED	
22	31	42	PA23	23	VDDANA	x1/x2	ADCIN12	AC0BP0	PEVC - PAD_EVT [5]		MACB - WOL	
	32	43	PA24	24	VDDANA	x1/x2	ADCIN13	SPI1 - NPCS[2]				
	33	44	PA25	25	VDDANA	x1/x2	ADCIN14	SPI1 - NPCS[3]	EIC - EXTINT[0]			
		45	PA26	26	VDDANA	x1/x2	AC0AP1	EIC - EXTINT[1]				
		46	PA27	27	VDDANA	x1/x2	AC0AN1	EIC - EXTINT[2]				
		47	PA28	28	VDDANA	x1/x2	AC0BP1	EIC - EXTINT[3]				
		48	PA29	29	VDDANA	x1/x2	AC0BN1	EIC - EXTINT[0]				
62	96	140	PB00	32	VDDIO1	x1	USART0 - CLK	CANIF - RXLINE[1]	EIC - EXTINT[8]	PEVC - PAD_EVT [10]		
63	97	141	PB01	33	VDDIO1	x1		CANIF - TXLINE[1]		PEVC - PAD_EVT [11]		
		99	143	34	VDDIO1	x1		USBC - ID	PEVC - PAD_EVT [6]	TC1 - A1		
		100	144	PB03	35	VDDIO1	x1		USBC - VBOF	PEVC - PAD_EVT [7]		
	7	7	PB04	36	VDDIO1	x1/x2	SPI1 - MOSI	CANIF - RXLINE[0]	QDEC1 - QEPI		MACB - TXD[2]	
	8	8	PB05	37	VDDIO1	x1/x2	SPI1 - MISO	CANIF - TXLINE[0]	PEVC - PAD_EVT [12]	USART3 - CLK	MACB - TXD[3]	
	9	9	PB06	38	VDDIO1	x2/x4	SPI1 - SCK		QDEC1 - QEPA	USART1 - CLK	MACB - TX_ER	
		10	PB07	39	VDDIO1	x1/x2	SPI1 - NPCS[0]	EIC - EXTINT[2]	QDEC1 - QEPI		MACB - RX_DV	
		11	PB08	40	VDDIO1	x1/x2	SPI1 - NPCS[1]	PEVC - PAD_EVT [1]	PWM - PWML[0]		MACB - RXD[0]	
		12	PB09	41	VDDIO1	x1/x2	SPI1 - NPCS[2]		PWM - PWML[0]		MACB - RXD[1]	
		13	PB10	42	VDDIO1	x1/x2	USART1 - DTR	SPI0 - MOSI	PWM - PWML[1]			



Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type ⁽¹⁾	GPIO function					
							A	B	C	D	E	F
			14	PB11	43	VDDIO1	x1/x2	USART1 - DSR	SPI0 - MISO	PWM - PWMH[1]		
			15	PB12	44	VDDIO1	x1/x2	USART1 - DCD	SPI0 - SCK	PWM - PWML[2]		
			16	PB13	45	VDDIO1	x1/x2	USART1 - RI	SPI0 - NPCS[0]	PWM - PWMH[2]		MACB - RX_ER
			17	PB14	46	VDDIO1	x1/x2	USART1 - RTS	SPI0 - NPCS[1]	PWM - PWML[3]		MACB - MDC
			18	PB15	47	VDDIO1	x1/x2	USART1 - CTS	USART1 - CLK	PWM - PWMH[3]		MACB - MDIO
			19	PB16	48	VDDIO1	x1/x2	USART1 - RXD	SPI0 - NPCS[2]	PWM - EXT_FAULTS[0]		CANIF - RXLINE[0]
			20	PB17	49	VDDIO1	x1/x2	USART1 - TXD	SPI0 - NPCS[3]	PWM - EXT_FAULTS[1]		CANIF - TXLINE[0]
			57	PB18	50	VDDIO2	x1/x2	TC0 - CLK2		EIC - EXTINT[4]		
	42	58	PB19	51	VDDIO2	x1/x2	TC0 - A0	SPI1 - MOSI	IISC - ISDO			MACB - CRS
	43	59	PB20	52	VDDIO2	x1/x2	TC0 - B0	SPI1 - MISO	IISC - ISDI	ACIFA1 - ACAOUT		MACB - COL
	44	60	PB21	53	VDDIO2	x2/x4	TC0 - CLK1	SPI1 - SCK	IISC - IMCK	ACIFA1 - ACBOUT		MACB - RXD[2]
	45	61	PB22	54	VDDIO2	x1/x2	TC0 - A1	SPI1 - NPCS[3]	IISC - ISCK	SCIF - GCLK[0]		MACB - RXD[3]
	46	62	PB23	55	VDDIO2	x1/x2	TC0 - B1	SPI1 - NPCS[2]	IISC - IWS	SCIF - GCLK[1]		MACB - RX_CLK
		63	PB24	56	VDDIO2	x1/x2	TC0 - CLK0	SPI1 - NPCS[1]				
		64	PB25	57	VDDIO2	x1/x2	TC0 - A2	SPI1 - NPCS[0]	PEVC - PAD_EVT [8]			
		65	PB26	58	VDDIO2	x2/x4	TC0 - B2	SPI1 - SCK	PEVC - PAD_EVT [9]			MACB - TX_EN
		66	PB27	59	VDDIO2	x1/x2	QDEC0 - QEPA	SPI1 - MISO	PEVC - PAD_EVT [10]	TC1 - CLK0		MACB - TXD[0]
		67	PB28	60	VDDIO2	x1/x2	QDEC0 - QEPB	SPI1 - MOSI	PEVC - PAD_EVT [11]	TC1 - B0		MACB - TXD[1]
		68	PB29	61	VDDIO2	x1/x2	QDEC0 - QEPI	SPI0 - NPCS[0]	PEVC - PAD_EVT [12]	TC1 - A0		
31	47	69	PB30	62	VDDIO2	x1						
32	48	70	PB31	63	VDDIO2	x1						
	49	71	PC00	64	VDDIO2	x1/x2	USBC - ID	SPI0 - NPCS[1]	USART2 - CTS	TC1 - B2		CANIF - TXLINE[1]
	50	72	PC01	65	VDDIO2	x1/x2	USBC - VBOF	SPI0 - NPCS[2]	USART2 - RTS	TC1 - A2		CANIF - RXLINE[1]

Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type ⁽¹⁾	GPIO function					
							A	B	C	D	E	F
33	51	73	PC02	66	VDDIO2	x1	TWIMSO - TWD	SPI0 - NPCS[3]	USART2 - RXD	TC1 - CLK1	MACB - MDC	
34	52	74	PC03	67	VDDIO2	x1	TWIMSO - TWCK	EIC - EXTINT[1]	USART2 - TXD	TC1 - B1	MACB - MDIO	
37	55	77	PC04	68	VDDIO2	x1	TWIMS1 - TWD	EIC - EXTINT[3]	USART2 - TXD	TC0 - B1		
38	56	78	PC05	69	VDDIO2	x1	TWIMS1 - TWCK	EIC - EXTINT[4]	USART2 - RXD	TC0 - A2		
	57	79	PC06	70	VDDIO2	x1	PEVC - PAD_EVT [15]	USART2 - CLK	USART2 - CTS	TC0 - CLK2	TWIMS2 - TWD	TWIMS0 - TWALM
	58	80	PC07	71	VDDIO2	x1	PEVC - PAD_EVT [2]	EBI - NCS[3]	USART2 - RTS	TC0 - B2	TWIMS2 - TWCK	TWIMS1 - TWALM
		81	PC08	72	VDDIO2	x1/x2	PEVC - PAD_EVT [13]	SPI1 - NPCS[1]	EBI - NCS[0]		USART4 - TXD	
		82	PC09	73	VDDIO2	x1/x2	PEVC - PAD_EVT [14]	SPI1 - NPCS[2]	EBI - ADDR[23]		USART4 - RXD	
		83	PC10	74	VDDIO2	x1/x2	PEVC - PAD_EVT [15]	SPI1 - NPCS[3]	EBI - ADDR[22]			
	59	84	PC11	75	VDDIO2	x1/x2	PWM - PWMHI[3]	CANIF - RXLINE[1]	EBI - ADDR[21]	TC0 - CLK0		
	60	85	PC12	76	VDDIO2	x1/x2	PWM - PWML[3]	CANIF - TXLINE[1]	EBI - ADDR[20]	USART2 - CLK		
	61	86	PC13	77	VDDIO2	x1/x2	PWM - PWMH[2]	EIC - EXTINT[7]		USART0 - RTS		
	62	87	PC14	78	VDDIO2	x1/x2	PWM - PWML[2]	USART0 - CLK	EBI - SDCKE	USART0 - CTS		
39	63	88	PC15	79	VDDIO2	x1/x2	PWM - PWMH[1]	SPI0 - NPCS[0]	EBI - SDWE	USART0 - RXD	CANIF - RXLINE[1]	
40	64	89	PC16	80	VDDIO2	x1/x2	PWM - PWML[1]	SPI0 - NPCS[1]	EBI - CAS	USART0 - TXD	CANIF - TXLINE[1]	
41	65	90	PC17	81	VDDIO2	x1/x2	PWM - PWMH[0]	SPI0 - NPCS[2]	EBI - RAS	IISC - ISDO		USART3 - TXD
42	66	91	PC18	82	VDDIO2	x1/x2	PWM - PWML[0]	EIC - EXTINT[5]	EBI - SDA10	IISC - ISDI		USART3 - RXD
43	67	92	PC19	83	VDDIO3	x1/x2	PWM - PWML[2]	SCIF - GCLK[0]	EBI - DATA[0]	IISC - IMCK		USART3 - CTS
44	68	93	PC20	84	VDDIO3	x1/x2	PWM - PWMH[2]	SCIF - GCLK[1]	EBI - DATA[1]	IISC - ISCK		USART3 - RTS
							PWM - EXT_FAULTS[0]	CANIF - RXLINE[0]	EBI - DATA[2]	IISC - IWS		
45	69	94	PC21	85	VDDIO3	x1/x2	PWM - EXT_FAULTS[1]	CANIF - TXLINE[0]	EBI - DATA[3]		USART3 - CLK	
46	70	95	PC22	86	VDDIO3	x1/x2	QDEC1 - QEPB	CANIF - RXLINE[1]	EBI - DATA[4]	PEVC - PAD_EVT [3]		
	71	96	PC23	87	VDDIO3	x1/x2						



Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type ⁽¹⁾	GPIO function					
							A	B	C	D	E	F
	72	97	PC24	88	VDDIO3	x1/x2	QDEC1 - QEPA	CANIF - TXLINE[1]	EBI - DATA[5]	PEVC - PAD_EVT [4]		
		98	PC25	89	VDDIO3	x1/x2		TC1 - CLK2	EBI - DATA[6]	SCIF - GCLK[0]	USART4 - TXD	
		99	PC26	90	VDDIO3	x1/x2	QDEC1 - QEPI	TC1 - B2	EBI - DATA[7]	SCIF - GCLK[1]	USART4 - RXD	
		100	PC27	91	VDDIO3	x1/x2		TC1 - A2	EBI - DATA[8]	EIC - EXTINT[0]	USART4 - CTS	
		101	PC28	92	VDDIO3	x1/x2	SPI1 - NPCS[3]	TC1 - CLK1	EBI - DATA[9]		USART4 - RTS	
		102	PC29	93	VDDIO3	x1/x2	SPI0 - NPCS[1]	TC1 - B1	EBI - DATA[10]			
		105	PC30	94	VDDIO3	x1/x2	SPI0 - NPCS[2]	TC1 - A1	EBI - DATA[11]			
	73	106	PC31	95	VDDIO3	x1/x2	SPI0 - NPCS[3]	TC1 - B0	EBI - DATA[12]	PEVC - PAD_EVT [5]	USART4 - CLK	
47	74	107	PD00	96	VDDIO3	x1/x2	SPI0 - MOSI	TC1 - CLK0	EBI - DATA[13]	QDEC0 - QEPI	USART0 - TXD	
48	75	108	PD01	97	VDDIO3	x1/x2	SPI0 - MISO	TC1 - A0	EBI - DATA[14]	TC0 - CLK1	USART0 - RXD	
49	76	109	PD02	98	VDDIO3	x2/x4	SPI0 - SCK	TC0 - CLK2	EBI - DATA[15]	QDEC0 - QEPA		
50	77	110	PD03	99	VDDIO3	x1/x2	SPI0 - NPCS[0]	TC0 - B2	EBI - ADDR[0]	QDEC0 - QEpb		
		111	PD04	100	VDDIO3	x1/x2	SPI0 - MOSI		EBI - ADDR[1]			
		112	PD05	101	VDDIO3	x1/x2	SPI0 - MISO		EBI - ADDR[2]			
		113	PD06	102	VDDIO3	x2/x4	SPI0 - SCK		EBI - ADDR[3]			
	78	114	PD07	103	VDDIO3	x1/x2	USART1 - DTR	EIC - EXTINT[5]	EBI - ADDR[4]	QDEC0 - QEPI	USART4 - TXD	
	79	115	PD08	104	VDDIO3	x1/x2	USART1 - DSR	EIC - EXTINT[6]	EBI - ADDR[5]	TC1 - CLK2	USART4 - RXD	
	80	116	PD09	105	VDDIO3	x1/x2	USART1 - DCD	CANIF - RXLINE[0]	EBI - ADDR[6]	QDEC0 - QEPA	USART4 - CTS	
	81	117	PD10	106	VDDIO3	x1/x2	USART1 - RI	CANIF - TXLINE[0]	EBI - ADDR[7]	QDEC0 - QEpb	USART4 - RTS	
53	84	120	PD11	107	VDDIO3	x1/x2	USART1 - TXD	USBC - ID	EBI - ADDR[8]	PEVC - PAD_EVT [6]	MACB - TXD[0]	
54	85	121	PD12	108	VDDIO3	x1/x2	USART1 - RXD	USBC - VBOF	EBI - ADDR[9]	PEVC - PAD_EVT [7]	MACB - TXD[1]	
55	86	122	PD13	109	VDDIO3	x2/x4	USART1 - CTS	USART1 - CLK	EBI - SDCK	PEVC - PAD_EVT [8]	MACB - RXD[0]	
56	87	123	PD14	110	VDDIO3	x1/x2	USART1 - RTS	EIC - EXTINT[7]	EBI - ADDR[10]	PEVC - PAD_EVT [9]	MACB - RXD[1]	

Table 3-1. GPIO Controller Function Multiplexing

TQFP / QFN 64	TQFP 100	LQFP 144	PIN	G P I O	Supply	Pin Type ⁽¹⁾	GPIO function					
							A	B	C	D	E	F
			124	PD15	111	VDDIO3	x1/x2	TC0 - A0	USART3 - TXD	EBI - ADDR[11]		
			125	PD16	112	VDDIO3	x1/x2	TC0 - B0	USART3 - RXD	EBI - ADDR[12]		
			126	PD17	113	VDDIO3	x1/x2	TC0 - A1	USART3 - CTS	EBI - ADDR[13]	USART3 - CLK	
			127	PD18	114	VDDIO3	x1/x2	TC0 - B1	USART3 - RTS	EBI - ADDR[14]		
			128	PD19	115	VDDIO3	x1/x2	TC0 - A2		EBI - ADDR[15]		
			129	PD20	116	VDDIO3	x1/x2	TC0 - B2		EBI - ADDR[16]		
57	88	130	PD21	117	VDDIO3	x1/x2	USART3 - TXD	EIC - EXTINT[0]	EBI - ADDR[17]	QDEC1 - QEPI		
	89	131	PD22	118	VDDIO1	x1/x2	USART3 - RXD	TC0 - A2	EBI - ADDR[18]	SCIF - GCLK[0]		
	90	132	PD23	119	VDDIO1	x1/x2	USART3 - CTS	USART3 - CLK	EBI - ADDR[19]	QDEC1 - QEPA		
	91	133	PD24	120	VDDIO1	x1/x2	USART3 - RTS	EIC - EXTINT[8]	EBI - NWE1	QDEC1 - QEpb		
		134	PD25	121	VDDIO1	x1/x2	TC0 - CLK0	USBC - ID	EBI - NWE0		USART4 - CLK	
		135	PD26	122	VDDIO1	x1/x2	TC0 - CLK1	USBC - VBOF	EBI - NRD			
58	92	136	PD27	123	VDDIO1	x1/x2	USART0 - TXD	CANIF - RXLINE[0]	EBI - NCS[1]	TC0 - A0	MACB - RX_ER	
59	93	137	PD28	124	VDDIO1	x1/x2	USART0 - RXD	CANIF - TXLINE[0]	EBI - NCS[2]	TC0 - B0	MACB - RX_DV	
60	94	138	PD29	125	VDDIO1	x1/x2	USART0 - CTS	EIC - EXTINT[6]	USART0 - CLK	TC0 - CLK0	MACB - TX_CLK	
61	95	139	PD30	126	VDDIO1	x1/x2	USART0 - RTS	EIC - EXTINT[3]	EBI - NWAIT	TC0 - A1	MACB - TX_EN	

Note: 1. Refer to "Electrical Characteristics" on page 50 for a description of the electrical properties of the pin types used.
See Section 3.3 for a description of the various peripheral signals.

3.2.2 Peripheral Functions

Each GPIO line can be assigned to one of several peripheral functions. The following table describes how the various peripheral functions are selected. The last listed function has priority in case multiple functions are enabled on the same pin.

Table 3-2. Peripheral Functions

Function	Description
GPIO Controller Function multiplexing	GPIO and GPIO peripheral selection A to F
Nexus OCD AUX port connections	OCD trace system

Table 3-2. Peripheral Functions

Function	Description
aWire DATAOUT	aWire output in two-pin mode
JTAG port connections	JTAG debug port
Oscillators	OSC0, OSC32

3.2.3 Oscillator Pinout

The oscillators are not mapped to the normal GPIO functions and their muxings are controlled by registers in the System Control Interface (SCIF). Please refer to the SCIF chapter for more information about this.

Table 3-3. Oscillator pinout

QFN64/ TQFP64 pin	TQFP100 pin	LQFP144 pin	Pad	Oscillator pin
31	47	69	PB30	xin0
	99	143	PB02	xin1
62	96	140	PB00	xin32
32	48	70	PB31	xout0
	100	144	PB03	xout1
63	97	141	PB01	xout32

3.2.4 JTAG port connections

If the JTAG is enabled, the JTAG will take control over a number of pins, irrespectively of the I/O Controller configuration.

Table 3-4. JTAG pinout

QFN64/ TQFP64 pin	TQFP100 pin	LQFP144 pin	Pin name	JTAG pin
2	2	2	PA01	TDI
3	3	3	PA02	TDO
4	4	4	PA03	TMS
1	1	1	PA00	TCK

3.2.5 Nexus OCD AUX port connections

If the OCD trace system is enabled, the trace system will take control over a number of pins, irrespectively of the GPIO configuration. Three different OCD trace pin mappings are possible,

depending on the configuration of the OCD AXS register. For details, see the AVR32UC Technical Reference Manual.

Table 3-5. Nexus OCD AUX port connections

Pin	AXS=0	AXS=1	AXS=2
EVTI_N	PA08	PB19	PA10
MDO[5]	PC05	PC31	PB06
MDO[4]	PC04	PC12	PB15
MDO[3]	PA23	PC11	PB14
MDO[2]	PA22	PB23	PA27
MDO[1]	PA19	PB22	PA26
MDO[0]	PA09	PB20	PA19
EVTO_N	PD29	PD29	PD29
MCKO	PD13	PB21	PB26
MSEO[1]	PD30	PD08	PB25
MSEO[0]	PD14	PD07	PB18

3.2.6 Other Functions

The functions listed in [Table 3-6](#) are not mapped to the normal GPIO functions. The aWire DATA pin will only be active after the aWire is enabled. The aWire DATAOUT pin will only be active after the aWire is enabled and the 2_PIN_MODE command has been sent.

Table 3-6. Other Functions

QFN64/ TQFP64 pin	TQFP100 pin	LQFP144 pin	Pad	Oscillator pin
64	98	142	RESET_N	aWire DATA
3	3	3	PA02	aWire DATAOUT

3.3 Signals Description

The following table give details on the signal name classified by peripherals.

Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
Power				
VDDIO1 VDDIO2 VDDIO3	I/O Power Supply	Power Input		4.5V to 5.5V or 3.0V to 3.6 V
VDDANA	Analog Power Supply	Power Input		4.5V to 5.5V or 3.0V to 3.6 V



Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
VDDIN_5	1.8V Voltage Regulator Input	Power Input		Power Supply: 4.5V to 5.5V or 3.0V to 3.6 V
VDDIN_33	USB I/O power supply	Power Output/ Input		Capacitor Connection for the 3.3V voltage regulator or power supply: 3.0V to 3.6 V
VDDCORE	1.8V Voltage Regulator Output	Power output		Capacitor Connection for the 1.8V voltage regulator
GNDIO1 GNDIO2 GNDIO3	I/O Ground	Ground		
GNDANA	Analog Ground	Ground		
GNDCORE	Ground of the core	Ground		
GNDPLL	Ground of the PLLs	Ground		
Analog Comparator Interface - ACIFA0/1				
AC0AN1/AC0AN0	Negative inputs for comparator AC0A	Analog		
AC0AP1/AC0AP0	Positive inputs for comparator AC0A	Analog		
AC0BN1/AC0BN0	Negative inputs for comparator AC0B	Analog		
AC0BP1/AC0BP0	Positive inputs for comparator AC0B	Analog		
AC1AN1/AC1AN0	Negative inputs for comparator AC1A	Analog		
AC1AP1/AC1AP0	Positive inputs for comparator AC1A	Analog		
AC1BN1/AC1BN0	Negative inputs for comparator AC1B	Analog		
AC1BP1/AC1BP0	Positive inputs for comparator AC1B	Analog		
ACAOOUT/ACBOUT	analog comparator outputs	output		
ADC Interface - ADCIFA				
ADCIN[15:0]	ADC input pins	Analog		
ADCREF0	Analog positive reference 0 voltage input	Analog		
ADCREF1	Analog positive reference 1 voltage input	Analog		
ADCVREFP	Analog positive reference connected to external capacitor	Analog		



Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
ADCVREFN	Analog negative reference connected to external capacitor	Analog		
Auxiliary Port - AUX				
MCKO	Trace Data Output Clock	Output		
MDO[5:0]	Trace Data Output	Output		
MSEO[1:0]	Trace Frame Control	Output		
EVTI_N	Event In	Output	Low	
EVTO_N	Event Out	Output	Low	
aWire - AW				
DATA	aWire data	I/O		
DATAOUT	aWire data output for 2-pin mode	I/O		
Controller Area Network Interface - CANIF				
RXLINE[1:0]	CAN channel rxline	I/O		
TXLINE[1:0]	CAN channel txline	I/O		
DAC Interface - DACIFB0/1				
DAC0A, DAC0B	DAC0 output pins of S/H A	Analog		
DAC1A, DAC1B	DAC output pins of S/H B	Analog		
DACREF	Analog reference voltage input	Analog		
External Bus Interface - EBI				
ADDR[23:0]	Address Bus	Output		
CAS	Column Signal	Output	Low	
DATA[15:0]	Data Bus	I/O		
NCS[3:0]	Chip Select	Output	Low	
NRD	Read Signal	Output	Low	
NWAIT	External Wait Signal	Input	Low	
NWE0	Write Enable 0	Output	Low	
NWE1	Write Enable 1	Output	Low	
RAS	Row Signal	Output	Low	
SDA10	SDRAM Address 10 Line	Output		

Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
SDCK	SDRAM Clock	Output		
SDCKE	SDRAM Clock Enable	Output		
SDWE	SDRAM Write Enable	Output	Low	
External Interrupt Controller - EIC				
EXTINT[8:1]	External Interrupt Pins	Input		
NMI_N = EXTINT[0]	Non-Maskable Interrupt Pin	Input	Low	
General Purpose Input/Output - GPIOA, GPIOB, GPIOC, GPIOD				
PA[29:19] - PA[16:0]	Parallel I/O Controller GPIOA	I/O		
PB[31:0]	Parallel I/O Controller GPIOB	I/O		
PC[31:0]	Parallel I/O Controller GPIOC	I/O		
PD[30:0]	Parallel I/O Controller GPIOD	I/O		
Inter-IC Sound (I2S) Controller - IISC				
IMCK	I2S Master Clock	Output		
ISCK	I2S Serial Clock	I/O		
ISDI	I2S Serial Data In	Input		
ISDO	I2S Serial Data Out	Output		
IWS	I2S Word Select	I/O		
JTAG				
TCK	Test Clock	Input		
TDI	Test Data In	Input		
TDO	Test Data Out	Output		
TMS	Test Mode Select	Input		
Ethernet MAC - MACB				
COL	Collision Detect	Input		
CRS	Carrier Sense and Data Valid	Input		
MDC	Management Data Clock	Output		
MDIO	Management Data Input/Output	I/O		
RXD[3:0]	Receive Data	Input		

Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
RX_CLK	Receive Clock	Input		
RX_DV	Receive Data Valid	Input		
RX_ER	Receive Coding Error	Input		
SPEED	Speed	Output		
TXD[3:0]	Transmit Data	Output		
TX_CLK	Transmit Clock or Reference Clock	Input		
TX_EN	Transmit Enable	Output		
TX_ER	Transmit Coding Error	Output		
WOL	Wake-On-LAN	Output		
Peripheral Event Controller - PEVC				
PAD_EVT[15:0]	Event Input Pins	Input		
Power Manager - PM				
RESET_N	Reset Pin	Input	Low	
Pulse Width Modulator - PWM				
PWMH[3:0] PWML[3:0]	PWM Output Pins	Output		
EXT_FAULT[1:0]	PWM Fault Input Pins	Input		
Quadrature Decoder- QDEC0/QDEC1				
QEPA	QEPA quadrature input	Input		
QEPB	QEPB quadrature input	Input		
QEPI	Index input	Input		
System Controller Interface- SCIF				
XIN0, XIN1, XIN32	Crystal 0, 1, 32K Inputs	Analog		
XOUT0, XOUT1, XOUT32	Crystal 0, 1, 32K Output	Analog		
GCLK0 - GCLK1	Generic Clock Pins	Output		
Serial Peripheral Interface - SPI0, SPI1				
MISO	Master In Slave Out	I/O		
MOSI	Master Out Slave In	I/O		

Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
NPCS[3:0]	SPI Peripheral Chip Select	I/O	Low	
SCK	Clock	Output		
Timer/Counter - TC0, TC1				
A0	Channel 0 Line A	I/O		
A1	Channel 1 Line A	I/O		
A2	Channel 2 Line A	I/O		
B0	Channel 0 Line B	I/O		
B1	Channel 1 Line B	I/O		
B2	Channel 2 Line B	I/O		
CLK0	Channel 0 External Clock Input	Input		
CLK1	Channel 1 External Clock Input	Input		
CLK2	Channel 2 External Clock Input	Input		
Two-wire Interface - TWIMS0, TWIMS1, TWIMS2				
TWALM	SMBus SMBALERT	I/O	Low	Only on TWIMS0, TWIMS1
TWCK	Serial Clock	I/O		
TWD	Serial Data	I/O		
Universal Synchronous Asynchronous Receiver Transmitter - USART0, USART1, USART2, USART3, USART4				
CLK	Clock	I/O		
CTS	Clear To Send	Input	Low	
DCD	Data Carrier Detect	Input	Low	Only USART1
DSR	Data Set Ready	Input	Low	Only USART1
DTR	Data Terminal Ready	Output	Low	Only USART1
RI	Ring Indicator	Input	Low	Only USART1
RTS	Request To Send	Output	Low	
RXD	Receive Data	Input		
TXD	Transmit Data	Output		
Universal Serial Bus Device - USB				
DM	USB Device Port Data -	Analog		

Table 3-7. Signal Description List

Signal Name	Function	Type	Active Level	Comments
DP	USB Device Port Data +	Analog		
VBUS	USB VBUS Monitor and OTG Negotiation	Analog Input		
ID	ID Pin of the USB Bus	Input		
VBOF	USB VBUS On/off: bus power control port	Output		

3.4 I/O Line Considerations

3.4.1 JTAG pins

The JTAG is enabled if TCK is low while the RESET_N pin is released. The TCK, TMS, and TDI pins have pull-up resistors when JTAG is enabled. The TCK pin always have pull-up enabled during reset. The TDO pin is an output, driven at VDDIO1, and has no pull-up resistor. The JTAG pins can be used as GPIO pins and muxed with peripherals when the JTAG is disabled. Please refer to [Section 3.2.4](#) for the JTAG port connections.

3.4.2 RESET_N pin

The RESET_N pin integrates a pull-up resistor to VDDIO1. As the product integrates a power-on reset cell, the RESET_N pin can be left unconnected in case no reset from the system needs to be applied to the product.

The RESET_N pin is also used for the aWire debug protocol. When the pin is used for debugging, it must not be driven by external circuitry.

3.4.3 TWI pins

When these pins are used for TWI, the pins are open-drain outputs with slew-rate limitation and inputs with inputs with spike-filtering. When used as GPIO-pins or used for other peripherals, the pins have the same characteristics as GPIO pins.

3.4.4 GPIO pins

All I/O lines integrate programmable pull-up and pull-down resistors. Most I/O lines integrate drive strength control, see [Table 3-1](#). Programming of this pull-up and pull-down resistor or this drive strength is performed independently for each I/O line through the GPIO Controllers.

After reset, I/O lines default as inputs with pull-up/pull-down resistors disabled. After reset, output drive strength is configured to the lowest value to reduce global EMI of the device.

When the I/O line is configured as analog function (ADC I/O, AC inputs, DAC I/O), the pull-up and pull-down resistors are automatically disabled.

4. Processor and Architecture

Rev: 2.1.2.0

This chapter gives an overview of the AVR32UC CPU. AVR32UC is an implementation of the AVR32 architecture. A summary of the programming model, instruction set, and MPU is presented. For further details, see the *AVR32 Architecture Manual* and the *AVR32UC Technical Reference Manual*.

4.1 Features

- 32-bit load/store AVR32A RISC architecture
 - 15 general-purpose 32-bit registers
 - 32-bit Stack Pointer, Program Counter and Link Register reside in register file
 - Fully orthogonal instruction set
 - Privileged and unprivileged modes enabling efficient and secure operating systems
 - Innovative instruction set together with variable instruction length ensuring industry leading code density
 - DSP extension with saturating arithmetic, and a wide variety of multiply instructions
- 3-stage pipeline allowing one instruction per clock cycle for most instructions
 - Byte, halfword, word, and double word memory access
 - Multiple interrupt priority levels
- MPU allows for operating systems with memory protection
- FPU enables hardware accelerated floating point calculations
- Secure State for supporting FlashVault technology

4.2 AVR32 Architecture

AVR32 is a new, high-performance 32-bit RISC microprocessor architecture, designed for cost-sensitive embedded applications, with particular emphasis on low power consumption and high code density. In addition, the instruction set architecture has been tuned to allow a variety of microarchitectures, enabling the AVR32 to be implemented as low-, mid-, or high-performance processors. AVR32 extends the AVR family into the world of 32- and 64-bit applications.

Through a quantitative approach, a large set of industry recognized benchmarks has been compiled and analyzed to achieve the best code density in its class. In addition to lowering the memory requirements, a compact code size also contributes to the core's low power characteristics. The processor supports byte and halfword data types without penalty in code size and performance.

Memory load and store operations are provided for byte, halfword, word, and double word data with automatic sign- or zero extension of halfword and byte data. The C-compiler is closely linked to the architecture and is able to exploit code optimization features, both for size and speed.

In order to reduce code size to a minimum, some instructions have multiple addressing modes. As an example, instructions with immediates often have a compact format with a smaller immediate, and an extended format with a larger immediate. In this way, the compiler is able to use the format giving the smallest code size.

Another feature of the instruction set is that frequently used instructions, like add, have a compact format with two operands as well as an extended format with three operands. The larger format increases performance, allowing an addition and a data move in the same instruction in a