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Features

- Single Voltage Read/Write Operation: 1.65V to 1.95V
- Access Time 80 ns
- Sector Erase Architecture
 - Thirty-one 32K Word (64K Bytes) Sectors with Individual Write Lockout
 - Eight 4K Word (8K Bytes) Sectors with Individual Write Lockout
- Fast Word Program Time 10 µs
- Fast Sector Erase Time 100 ms
- Suspend/Resume Feature for Erase and Program
 - Supports Reading and Programming from Any Sector by Suspending Erase of a Different Sector
 - Supports Reading Any Word in the Non-suspending Sectors by Suspending Programming of Any Other Word
- Low-power Operation
 - 10 mA Active
 - 15 µA Standby
- Data Polling, Toggle Bit, Ready/Busy for End of Program Detection
- VPP Pin for Write Protection and Accelerated Program Operation
- RESET Input for Device Initialization
- Sector Lockdown Support
- TSOP and CBGA Package Options
- Top or Bottom Boot Block Configuration Available
- 128-bit Protection Register
- Minimum 100,000 Erase Cycles
- Common Flash Interface (CFI)

1. Description

The AT49SV163D(T) is a 1.8-volt 16-megabit Flash memory organized as 1,048,576 words of 16 bits each. The memory is divided into 39 sectors for erase operations. The device is offered in a 48-lead TSOP and a 48-ball CBGA package. The device has $\overline{\text{CE}}$ and $\overline{\text{OE}}$ control signals to avoid any bus contention. This device can be read or reprogrammed using a single power supply, making it ideally suited for in-system programming.

The device powers on in the read mode. Command sequences are used to place the device in other operation modes such as program and erase. The device has the capability to protect the data in any sector (see "Sector Lockdown" on page 6).

To increase the flexibility of the device, it contains an Erase Suspend and Program Suspend feature. This feature will put the erase or program on hold for any amount of time and let the user read data from or program data to any of the remaining sectors within the memory. The end of a program or an erase cycle is detected by the READY/BUSY pin, Data Polling or by the toggle bit.

The VPP pin provides data protection. When the V_{PP} input is below 0.4V, the program and erase functions are inhibited. When V_{PP} is at 1.65V or above, normal program and erase operations can be performed. With V_{PP} at 10.0V, the program (Dual-word Program command) operation is accelerated.



16-megabit (1M x 16) 1.8-volt Only Flash Memory

AT49SV163D AT49SV163DT



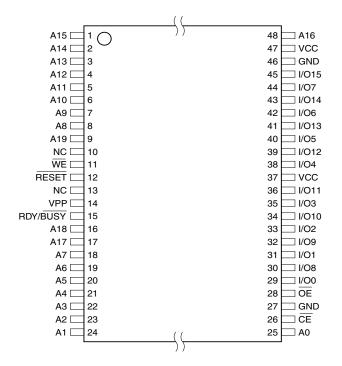


A six-byte command (Enter Single Pulse Program Mode) sequence to remove the requirement of entering the three-byte program sequence is offered to further improve programming time. After entering the six-byte code, only single pulses on the write control lines are required for writing into the device. This mode (Single Pulse Word Program) is exited by powering down the device, or by pulsing the $\overline{\text{RESET}}$ pin low for a minimum of 500 ns and then bringing it back to V_{CC} . Erase, Erase Suspend/Resume and Program Suspend/Resume commands will not work while in this mode; if entered they will result in data being programmed into the device. It is not recommended that the six-byte code reside in the software of the final product but only exist in external programming code.

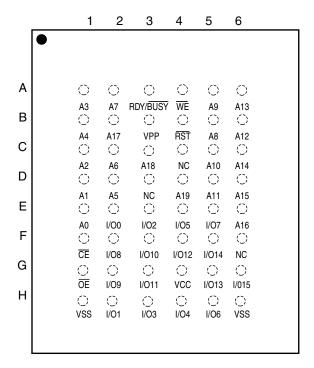
2. Pin Configurations

Pin Name	Function
A0 - A19	Addresses
CE	Chip Enable
ŌĒ	Output Enable
WE	Write Enable
RESET	Reset
RDY/BUSY	READY/BUSY Output
VPP	Write Protection
I/O0 - I/O15	Data Inputs/Outputs
NC	No Connect

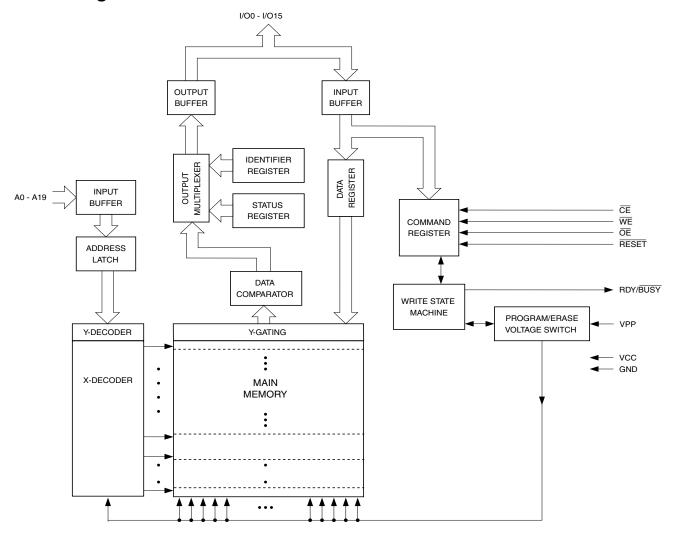
2.1 TSOP Top View (Type 1)



2.2 CBGA Top View (Ball Down)



3. Block Diagram



4. Device Operation

4.1 Command Sequences

When the device is first powered on, it will be reset to the read or standby mode, depending upon the state of the control line inputs. In order to perform other device functions, a series of command sequences are entered into the device. The command sequences are shown in the "Command Definition Table" on page 12 (I/O8 - I/O15 are don't care inputs for the command codes). The command sequences are written by applying a low pulse on the $\overline{\text{WE}}$ or $\overline{\text{CE}}$ input with $\overline{\text{CE}}$ or $\overline{\text{WE}}$ low (respectively) and $\overline{\text{OE}}$ high. The address is latched on the falling edge of $\overline{\text{CE}}$ or $\overline{\text{WE}}$, whichever occurs last. The data is latched by the first rising edge of $\overline{\text{CE}}$ or $\overline{\text{WE}}$. Standard microprocessor write timings are used. The address locations used in the command sequences are not affected by entering the command sequences.





4.2 Read

The AT49SV163D(T) is accessed like an EPROM. When \overline{CE} and \overline{OE} are low and \overline{WE} is high, the data stored at the memory location determined by the address pins are asserted on the outputs. The outputs are put in the high impedance state whenever \overline{CE} or \overline{OE} is high. This dual-line control gives designers flexibility in preventing bus contention.

4.3 Reset

A $\overline{\text{RESET}}$ input pin is provided to ease some system applications. When $\overline{\text{RESET}}$ is at a logic high level, the device is in its standard operating mode. A low level on the $\overline{\text{RESET}}$ input halts the present device operation and puts the outputs of the device in a high impedance state. When a high level is reasserted on the $\overline{\text{RESET}}$ pin, the device returns to the read or standby mode, depending upon the state of the control inputs.

4.4 Erase

Before a word can be reprogrammed, it must be erased. The erased state of memory bits is a logical "1". The entire device can be erased by using the Chip Erase command or individual sectors can be erased by using the Sector Erase command.

4.4.1 Chip Erase

The entire device can be erased at one time by using the six-byte chip erase software code. After the chip erase has been initiated, the device will internally time the erase operation so that no external clocks are required. The maximum time to erase the chip is t_{FC} .

If the sector lockdown has been enabled, the chip erase will not erase the data in the sector that has been locked out; it will erase only the unprotected sectors. After the chip erase, the device will return to the read or standby mode.

4.4.2 Sector Erase

As an alternative to a full chip erase, the device is organized into 39 sectors (SA0 - SA38) that can be individually erased. The Sector Erase command is a six-bus cycle operation. The sector address is latched on the falling \overline{WE} edge of the sixth cycle while the 30H data input command is latched on the rising edge of \overline{WE} . The sector erase starts after the rising edge of \overline{WE} of the sixth cycle. The erase operation is internally controlled; it will automatically time to completion. The maximum time to erase a sector is t_{SEC} . When the sector programming lockdown feature is not enabled, the sector will erase (from the same Sector Erase command). An attempt to erase a sector that has been protected will result in the operation terminating immediately.

4.5 Word Programming

Once a memory block is erased, it is programmed (to a logical "0") on a word-by-word basis. Programming is accomplished via the internal device command register and is a four-bus cycle operation. The device will automatically generate the required internal program pulses.

Any commands written to the chip during the embedded programming cycle will be ignored. If a hardware reset happens during programming, the data at the location being programmed will be corrupted. Please note that a data "0" cannot be programmed back to a "1"; only erase operations can convert "0"s to "1"s. Programming is completed after the specified t_{BP} cycle time. The Data Polling feature or the Toggle Bit feature may be used to indicate the end of a program cycle. If the erase/program status bit is a "1", the device was not able to verify that the erase or program operation was performed successfully.

AT49SV163D(T)

4.6 VPP Pin

The circuitry of the AT49SV163D(T) is designed so that the device cannot be programmed or erased if the V_{PP} voltage is less that 0.4V. When V_{PP} is at 1.65V or above, normal program and erase operations can be performed. The VPP pin cannot be left floating.

4.7 Program/Erase Status

The device provides several bits to determine the status of a program or erase operation: I/O2, I/O3, I/O5, I/O6 and I/O7. The "Status Bit Table" on page 11 and the following four sections describe the function of these bits. To provide greater flexibility for system designers, the AT49SV163D(T) contains a programmable configuration register. The configuration register allows the user to specify the status bit operation. The configuration register can be set to one of two different values, "00" or "01". If the configuration register is set to "00", the part will automatically return to the read mode after a successful program or erase operation. If the configuration register is set to a "01", a Product ID Exit command must be given after a successful program or erase operation before the part will return to the read mode. It is important to note that whether the configuration register is set to a "00" or to a "01", any unsuccessful program or erase operation requires using the Product ID Exit command to return the device to read mode. The default value (after power-up) for the configuration register is "00". Using the four-bus cycle Set Configuration Register command as shown in the "Command Definition Table" on page 12, the value of the configuration register can be changed. Voltages applied to the RESET pin will not alter the value of the configuration register. The value of the configuration register will affect the operation of the I/O7 status bit as described below.

4.7.1 Data Polling

The AT49SV163D(T) features Data Polling to indicate the end of a program cycle. If the status configuration register is set to a "00", during a program cycle an attempted read of the last word loaded will result in the complement of the loaded data on I/O7. Once the program cycle has been completed, true data is valid on all outputs and the next cycle may begin. During a chip or sector erase operation, an attempt to read the device will give a "0" on I/O7. Once the program or erase cycle has completed, true data will be read from the device. Data Polling may begin at any time during the program cycle. Please see "Status Bit Table" on page 11 for more details.

If the status bit configuration register is set to a "01", the I/O7 status bit will be low while the device is actively programming or erasing data. I/O7 will go high when the device has completed a program or erase operation. Once I/O7 has gone high, status information on the other pins can be checked.

The Data Polling status bit must be used in conjunction with the erase/program and V_{PP} status bit as shown in the algorithm in Figures 4-1 and 4-2 on page 9.

4.7.2 Toggle Bit

In addition to Data Polling the AT49SV163D(T) provides another method for determining the end of a program or erase cycle. During a program or erase operation, successive attempts to read data from the memory will result in I/O6 toggling between one and zero. Once the program cycle has completed, I/O6 will stop toggling and valid data will be read. Examining the toggle bit may begin at any time during a program cycle. Please see "Status Bit Table" on page 11 for more details.

The toggle bit status bit should be used in conjunction with the erase/program and V_{PP} status bit as shown in the algorithm in Figures 4-3 and 4-3 on page 10.





4.7.3 Erase/Program Status Bit

The device offers a status bit on I/O5, which indicates whether the program or erase operation has exceeded a specified internal pulse count limit. If the status bit is a "1", the device is unable to verify that an erase or a word program operation has been successfully performed. If a program (Sector Erase) command is issued to a protected sector, the protected sector will not be programmed (erased). The device will go to a status read mode and the I/O5 status bit will be set high, indicating the program (erase) operation did not complete as requested. Once the erase/program status bit has been set to a "1", the system must write the Product ID Exit command to return to the read mode. The erase/program status bit is a "0" while the erase or program operation is still in progress. Please see "Status Bit Table" on page 11 for more details.

4.7.4 VPP Status Bit

The AT49SV163D(T) provides a status bit on I/O3, which provides information regarding the voltage level of the VPP pin. During a program or erase operation, if the voltage on the VPP pin is not high enough to perform the desired operation successfully, the I/O3 status bit will be a "1". Once the V_{PP} status bit has been set to a "1", the system must write the Product ID Exit command to return to the read mode. On the other hand, if the voltage level is high enough to perform a program or erase operation successfully, the V_{PP} status bit will output a "0". Please see "Status Bit Table" on page 11 for more details.

4.8 Sector Lockdown

Each sector has a programming lockdown feature. This feature prevents programming of data in the designated sectors once the feature has been enabled. These sectors can contain secure code that is used to bring up the system. Enabling the lockdown feature will allow the boot code to stay in the device while data in the rest of the device is updated. This feature does not have to be activated; any sector's usage as a write-protected region is optional to the user.

At power-up or reset, all sectors are unlocked. To activate the lockdown for a specific sector, the six-bus cycle Sector Lockdown command must be issued. Once a sector has been locked down, the contents of the sector is read-only and cannot be erased or programmed.

4.8.1 Sector Lockdown Detection

A software method is available to determine if programming of a sector is locked down. When the device is in the software product identification mode (see "Software Product Identification Entry/Exit" sections on page 23), a read from address location 00002H within a sector will show if programming the sector is locked down. If the data on I/O0 is low, the sector can be programmed; if the data on I/O0 is high, the program lockdown feature has been enabled and the sector cannot be programmed. The software product identification exit code should be used to return to standard operation.

4.8.2 Sector Lockdown Override

The only way to unlock a sector that is locked down is through reset or power-up cycles. After power-up or reset, the content of a sector that is locked down can be erased and reprogrammed.

4.9 Erase Suspend/Erase Resume

The Erase Suspend command allows the system to interrupt a sector or chip erase operation and then program or read data from a different sector within the memory. After the Erase Suspend command is given, the device requires a maximum time of 15 µs to suspend the erase operation. After the erase operation has been suspended, the system can then read data or program data to any other sector within the device. An address is not required during the Erase Suspend command. During a sector erase suspend, another sector cannot be erased. To resume the sector erase operation, the system must write the Erase Resume command. The Erase Resume command is a one-bus cycle command. The device also supports an erase suspend during a complete chip erase. While the chip erase is suspended, the user can read from any sector within the memory that is protected. The command sequence for a chip erase suspend and a sector erase suspend are the same.

4.10 Program Suspend/Program Resume

The Program Suspend command allows the system to interrupt a programming operation and then read data from a different word within the memory. After the Program Suspend command is given, the device requires a maximum of 20 µs to suspend the programming operation. After the programming operation has been suspended, the system can then read data from any other word that is not contained in the sector in which the programming operation was suspended. An address is not required during the program suspend operation. To resume the programming operation, the system must write the Program Resume command. The program suspend and resume are one-bus cycle commands. The command sequence for the erase suspend and program suspend are the same, and the command sequence for the erase resume and program resume are the same.

4.11 Product Identification

The product identification mode identifies the device and manufacturer as Atmel[®]. It is accessed using a software operation.

For details, see "Operating Modes" on page 16 or "Software Product Identification Entry/Exit" sections on page 23.

4.12 128-bit Protection Register

The AT49SV163D(T) contains a 128-bit register that can be used for security purposes in system design. The protection register is divided into two 64-bit blocks. The two blocks are designated as block A and block B. The data in block A is non-changeable and is programmed at the factory with a unique number. The data in block B is programmed by the user and can be locked out such that data in the block cannot be reprogrammed. To program block B in the protection register, the four-bus cycle Program Protection Register command must be used as shown in the "Command Definition Table" on page 12. To lock out block B, the four-bus cycle Lock Protection Register command must be used as shown in the "Command Definition Table". Data bit D1 must be zero during the fourth bus cycle. All other data bits during the fourth bus cycle are don't cares. To determine whether block B is locked out, the Product ID Entry command is given followed by a read operation from address 80H. If data bit D1 is zero, block B is locked. If data bit D1 is one, block B can be reprogrammed. Please see the "Protection Register Addressing Table" on page 13 for the address locations in the protection register. To read the protection register, the Product ID Entry command is given followed by a normal read operation from an address within the protection register. After determining whether block B is protected or not, or reading the protection register, the Product ID Exit command must be given prior to performing any other operation.





4.13 RDY/BUSY

An open-drain READY/BUSY output pin provides another method of detecting the end of a program or erase operation. RDY/BUSY is actively pulled low during the internal program and erase cycles and is released at the completion of the cycle. The open-drain connection allows for OR-tying of several devices to the same RDY/BUSY line. Please see "Status Bit Table" on page 11 for more details.

4.14 Common Flash Interface (CFI)

CFI is a published, standardized data structure that may be read from a flash device. CFI allows system software to query the installed device to determine the configurations, various electrical and timing parameters, and functions supported by the device. CFI is used to allow the system to learn how to interface to the flash device most optimally. The two primary benefits of using CFI are ease of upgrading and second source availability. The command to enter the CFI Query mode is a one-bus cycle command which requires writing data 98h to address 55h. The CFI Query command can be written when the device is ready to read data or can also be written when the part is in the product ID mode. Once in the CFI Query mode, the system can read CFI data at the addresses given in "Common Flash Interface Definition Table" on page 24. To exit the CFI Query mode, the product ID exit command must be given.

4.15 Hardware Data Protection

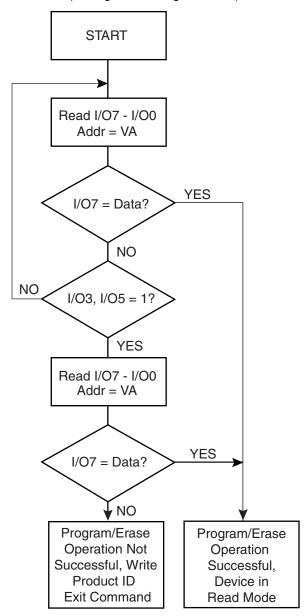
The Hardware Data Protection feature protects against inadvertent programs to the AT49SV163D(T) in the following ways: (a) V_{CC} sense: if V_{CC} is below 1.65V (typical), the program function is inhibited. (b) V_{CC} power-on delay: once V_{CC} has reached the V_{CC} sense level, the device will automatically time out 10 ms (typical) before programming. (c) Program inhibit: holding any one of \overline{OE} low, \overline{CE} high or \overline{WE} high inhibits program cycles. (d) Program inhibit: V_{PP} is less than V_{ILPP} .

4.16 Input Levels

While operating with a 1.65V to 1.95V power supply, the address inputs and control inputs $(\overline{OE}, \overline{CE} \text{ and } \overline{WE})$ may be driven from 0 to 5.5V without adversely affecting the operation of the device. The I/O lines can only be driven from 0 to V_{CC} + 0.6V.



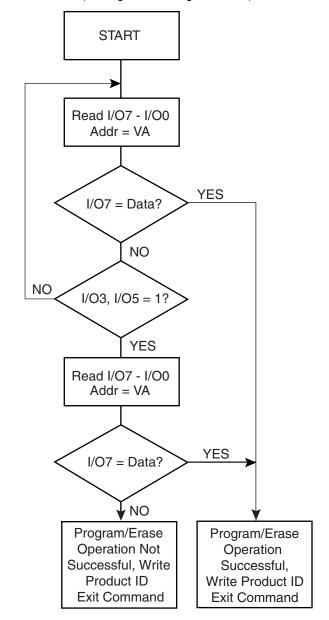
Figure 4-1. Data Polling Algorithm (Configuration Register = 00)



Notes: 1. VA = Valid address for programming. During a sector erase operation, a valid address is any sector address within the sector being erased. During chip erase, a valid address is any non-protected sector address.

2. I/O7 should be rechecked even if I/O5 = "1" because I/O7 may change simultaneously with I/O5.

Figure 4-2. Data Polling Algorithm (Configuration Register = 01)



- Notes: 1. VA = Valid address for programming. During a sector erase operation, a valid address is any sector address within the sector being erased. During chip erase, a valid address is any non-protected sector address.
 - 2. I/O7 should be rechecked even if I/O5 = "1" because I/O7 may change simultaneously with I/O5.

Figure 4-3. Toggle Bit Algorithm (Configuration Register = 00)

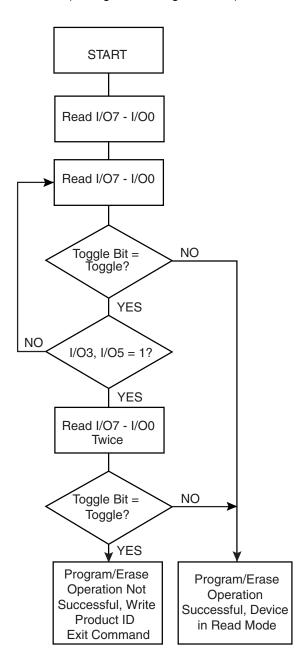
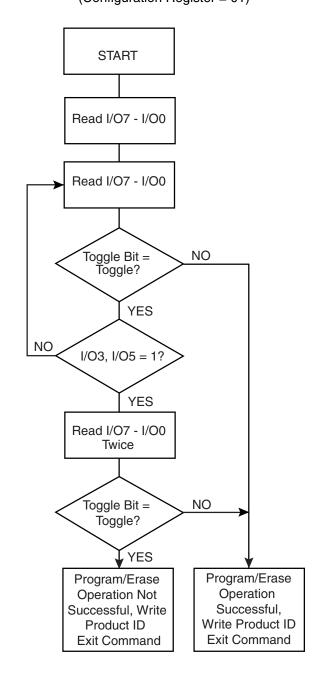


Figure 4-4. Toggle Bit Algorithm (Configuration Register = 01)



Note: 1. The system should recheck the toggle bit even if I/O5 = "1" because the toggle bit may stop toggling as I/O5 changes to "1".

Note: 1. The system should recheck the toggle bit even if I/O5 = "1" because the toggle bit may stop toggling as I/O5 changes to "1".



5. Status Bit Table

	Status Bit						
	1/07	1/07	1/06	I/O5 ⁽¹⁾	I/O3 ⁽²⁾	1/02	RDY/BUSY
Configuration Register	00	01	00/01	00/01	00/01	00/01	00/01
Programming	Ī/O7	0	TOGGLE	0	0	1	0
Erasing	0	0	TOGGLE	0	0	TOGGLE	0
Erase Suspended & Read Erasing Sector	1	1	1	0	0	TOGGLE	1
Erase Suspended & Read Non-erasing Sector	DATA	DATA	DATA	DATA	DATA	DATA	1
Erase Suspended & Program Non-erasing Sector	Ī/O7	0	TOGGLE	0	0	TOGGLE	0
Erase Suspended & Program Suspended and Reading from Non- suspended Sectors	DATA	DATA	DATA	DATA	DATA	DATA	1
Program Suspended & Read Programming Sector	I/O7	1	1	0	0	TOGGLE	1
Program Suspended & Read Non-programming Sector	DATA	DATA	DATA	DATA	DATA	DATA	1

Notes: 1. I/O5 switches to a "1" when a program or an erase operation has exceeded the maximum time limits or when a program or sector erase operation is performed on a protected sector.



^{2.} I/O3 switches to a "1" when the V_{PP} level is not high enough to successfully perform program and erase operations.



Command Definition Table

Command	Bus	1st Cy		2nd E Cyc			Bus cle		Bus /cle	5th E Cyc		6th B Cyc	
Sequence	Cycles	Addr	Data	Addr	Data	Addr	Data	Addr	Data	Addr	Data	Addr	Data
Read	1	Addr	D _{OUT}										
Chip Erase	6	555	AA	AAA ⁽²⁾	55	555	80	555	AA	AAA	55	555	10
Sector Erase	6	555	AA	AAA	55	555	80	555	AA	AAA	55	SA ⁽³⁾	30
Word Program	4	555	AA	AAA	55	555	A0	Addr	D _{IN}				
Dual Word Program ⁽⁴⁾	5	555	AA	AAA	55	555	E0	Addr0	D _{IN0}	Addr1	D _{IN1}		
Enter Single Pulse Program Mode	6	555	AA	AAA	55	555	80	555	AA	AAA	55	555	A0
Single Pulse Word Program	1	Addr	D _{IN}										
Sector Lockdown	6	555	AA	AAA ⁽²⁾	55	555	80	555	AA	AAA	55	SA ⁽³⁾⁽⁵⁾	60
Erase/Program Suspend	1	XXX	В0										
Erase/Program Resume	1	XXX	30										
Product ID Entry	3	555	AA	AAA	55	555	90						
Product ID Exit ⁽⁶⁾	3	555	AA	AAA	55	555	F0 ⁽⁷⁾						
Product ID Exit ⁽⁶⁾	1	XXX	F0 ⁽⁷⁾										
Program Protection Register	4	555	AA	AAA	55	555	CO	Addr ⁽⁸⁾	D _{IN}				
Lock Protection Register - Block B	4	555	AA	AAA	55	555	CO	080	X0				
Status of Block B Protection	4	555	AA	AAA	55	555	90	80	D _{OUT} ⁽⁹⁾				
Set Configuration Register	4	555	AA	AAA	55	555	D0	xxx	00/01 ⁽¹⁰⁾				
CFI Query ⁽¹¹⁾	1	X55	98										

- Notes: 1. The DATA FORMAT shown for each bus cycle is as follows; I/O7 I/O0 (Hex). I/O15 I/O8 are don't care. The ADDRESS FORMAT shown for each bus cycle is as follows: A11 - A0 (Hex). Address A19 through A11 are don't care.
 - 2. Since A11 is a Don't Care, AAA can be replaced with 2AA.
 - 3. SA = sector address. Any word address within a sector can be used to designate the sector address (see pages 14 15 for details).
 - 4. This fast programming option enables the user to program two words in parallel only when $V_{PP} = 9.5V$. The Addresses, Addr0 and Addr1, of the two words, D_{IN0} and D_{IN1}, must only differ in address A0. This command should be used during manufacturing purposes only.
 - 5. Once a sector is in the lockdown mode, data in the protected sector cannot be changed unless the chip is reset or power cycled.
 - 6. Either one of the Product ID Exit commands can be used.
 - 7. Bytes of data other than F0 may be used to exit the Product ID mode. However, it is recommended that F0 be used.
 - 8. Any addresses within the user programmable protection register region. Address locations are shown on "Protection Register Addressing Table" on page 13.
 - 9. If data bit D1 is "0", block B is locked. If data bit D1 is "1", block B can be reprogrammed.
 - 10. The default state (after power-up) of the configuration register is "00".
 - 11. When accessing the data in the CFI table, the address format is A15 A0 (Hex).

7. Absolute Maximum Ratings*

Temperature under Bias55°C to +125°C
Storage Temperature65°C to +150°C
All Input Voltages (including NC Pins) with Respect to Ground0.6V to +6.25V
All Output Voltages with Respect to Ground0.6V to V_{CC} + 0.6V
Voltage on V _{PP} with Respect to Ground0.6V to + 9.5V

*NOTICE:

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

8. Protection Register Addressing Table

Address	Use	Block	A 7	A 6	A 5	A 4	А3	A2	A 1	Α0
81	Factory	Α	1	0	0	0	0	0	0	1
82	Factory	Α	1	0	0	0	0	0	1	0
83	Factory	Α	1	0	0	0	0	0	1	1
84	Factory	Α	1	0	0	0	0	1	0	0
85	User	В	1	0	0	0	0	1	0	1
86	User	В	1	0	0	0	0	1	1	0
87	User	В	1	0	0	0	0	1	1	1
88	User	В	1	0	0	0	1	0	0	0

Note: All address lines not specified in the above table must be "0" when accessing the protection register, i.e., A19 - A8 = 0.





9. AT49SV163D - Sector Address Table

Sector	Size (Bytes/Words)	Address Range (A19 - A0)
SA0	8K/4K	00000 - 00FFF
SA1	8K/4K	01000 - 01FFF
SA2	8K/4K	02000 - 02FFF
SA3	8K/4K	03000 - 03FFF
SA4	8K/4K	04000 - 04FFF
SA5	8K/4K	05000 - 05FFF
SA6	8K/4K	06000 - 06FFF
SA7	8K/4K	07000 - 07FFF
SA8	64K/32K	08000 - 0FFFF
SA9	64K/32K	10000 - 17FFF
SA10	64K/32K	18000 - 1FFFF
SA11	64K/32K	20000 - 27FFF
SA12	64K/32K	28000 - 2FFFF
SA13	64K/32K	30000 - 37FFF
SA14	64K/32K	38000 - 3FFFF
SA15	64K/32K	40000 - 47FFF
SA16	64K/32K	48000 - 4FFFF
SA17	64K/32K	50000 - 57FFF
SA18	64K/32K	58000 - 5FFFF
SA19	64K/32K	60000 - 67FFF
SA20	64K/32K	68000 - 6FFFF
SA21	64K/32K	70000 - 77FFF
SA22	64K/32K	78000 - 7FFFF
SA23	64K/32K	80000 - 87FFF
SA24	64K/32K	88000 - 8FFFF
SA25	64K/32K	90000 - 97FFF
SA26	64K/32K	98000 - 9FFFF
SA27	64K/32K	A0000 - A7FFF
SA28	64K/32K	A8000 - AFFFF
SA29	64K/32K	B0000 - B7FFF
SA30	64K/32K	B8000 - BFFFF
SA31	64K/32K	C0000 - C7FFF
SA32	64K/32K	C8000 - CFFFF
SA33	64K/32K	D0000 - D7FFF
SA34	64K/32K	D8000 - DFFFF
SA35	64K/32K	E0000 - E7FFF
SA36	64K/32K	E8000 - EFFFF
SA37	64K/32K	F0000 - F7FFF
SA38	64K/32K	F8000 - FFFFF

10. AT49SV163DT - Sector Address Table

Sector	Size (Bytes/Words)	Address Range (A19 - A0)
SA0	64K/32K	00000 - 07FFF
SA1	64K/32K	08000 - 0FFFF
SA2	64K/32K	10000 - 17FFF
SA3	64K/32K	18000 - 1FFFF
SA4	64K/32K	20000 - 27FFF
SA5	64K/32K	28000 - 2FFFF
SA6	64K/32K	30000 - 37FFF
SA7	64K/32K	38000 - 3FFFF
SA8	64K/32K	40000 - 47FFF
SA9	64K/32K	48000 - 4FFFF
SA10	64K/32K	50000 - 57FFF
SA11	64K/32K	58000 - 5FFFF
SA12	64K/32K	60000 - 67FFF
SA13	64K/32K	68000 - 6FFFF
SA14	64K/32K	70000 - 77FFF
SA15	64K/32K	78000 - 7FFFF
SA16	64K/32K	80000 - 87FFF
SA17	64K/32K	88000 - 8FFFF
SA18	64K/32K	90000 - 97FFF
SA19	64K/32K	98000 - 9FFFF
SA20	64K/32K	A0000 - A7FFF
SA21	64K/32K	A8000 - AFFFF
SA22	64K/32K	B0000 - B7FFF
SA23	64K/32K	B8000 - BFFFF
SA24	64K/32K	C0000 - C7FFF
SA25	64K/32K	C8000 - CFFFF
SA26	64K/32K	D0000 - D7FFF
SA27	64K/32K	D8000 - DFFFF
SA28	64K/32K	E0000 - E7FFF
SA29	64K/32K	E8000 - EFFFF
SA30	64K/32K	F0000 - F7FFF
SA31	8K/4K	F8000 - F8FFF
SA32	8K/4K	F9000 - F9FFF
SA33	8K/4K	FA000 - FAFFF
SA34	8K/4K	FB000 - FBFFF
SA35	8K/4K	FC000 - FCFFF
SA36	8K/4K	FD000 - FDFFF
SA37	8K/4K	FE000 - FEFFF
SA38	8K/4K	FF000 - FFFFF





11. DC and AC Operating Range

	AT49SV163D(T)-80	
Operating Temperature (Case)	Ind.	-40°C - 85°C
V _{CC} Power Supply		1.65V to 1.95V

12. Operating Modes

Mode	CE	ŌĒ	WE	RESET	V _{PP} ⁽¹⁾	Ai	I/O
Read	V_{IL}	V_{IL}	V_{IH}	V _{IH}	X ⁽²⁾	Ai	D _{OUT}
Program/Erase ⁽³⁾	V_{IL}	V_{IH}	V_{IL}	V _{IH}	V _{IHPP} ⁽⁴⁾	Ai	D _{IN}
Standby/Program Inhibit	V _{IH}	X ⁽²⁾	Х	V _{IH}	Х	X	High-Z
	Х	Χ	V_{IH}	V _{IH}	X		
Program Inhibit	Χ	V_{IL}	Х	V _{IH}	X		
	Χ	Χ	Х	V _{IH}	V _{ILPP} ⁽⁵⁾		
Output Disable	Х	V_{IH}	Х	V _{IH}	X		High-Z
Reset	Х	Х	Х	V _{IL}	Х	X	High-Z
Product Identification						$A0 = V_{IL}, A1 - A19 = V_{IL}$	Manufacturer Code ⁽⁷⁾
Software ⁽⁶⁾				V _{IH}		A0 = V _{IH} , A1 - A19 = V _{IL}	Device Code ⁽⁷⁾

Notes: 1. The VPP pin can be tied to V_{CC} . For faster program operations, V_{PP} can be set to 9.5V \pm 0.5V.

- 2. X can be $V_{\rm IL}$ or $V_{\rm IH}$. 3. Refer to "Program Cycle Waveforms" on page 21.
- 4. V_{IHPP} (min) = 1.65V
- 5. V_{ILPP} (max) = 0.4V.
- 6. See details under "Software Product Identification Entry/Exit" on page 23.
- 7. Manufacturer Code: 001FH, Device Code: 02C0H AT49SV163D; 02C2H (x16) - AT49SV163DT.

13. DC Characteristics

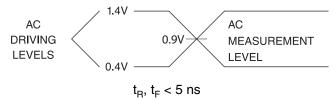
Symbol	Parameter	Condition	Min	Тур	Max	Units
ILI	Input Load Current	$V_{IN} = 0V \text{ to } V_{CC}$			2	μΑ
I _{LO}	Output Leakage Current	$V_{I/O} = 0V \text{ to } V_{CC}$			2	μΑ
I _{SB}	V _{CC} Standby Current CMOS	$\overline{\text{CE}} = \text{V}_{\text{CC}} - 0.3 \text{V to V}_{\text{CC}}$		15	25	μΑ
I _{CC} ⁽¹⁾	V _{CC} Active Read Current	f = 5 MHz; I _{OUT} = 0 mA		10	15	mA
I _{CC1}	V _{CC} Programming Current				15	mA
I _{PP1}	V _{PP} Input Load Current				10	μΑ
V _{IL}	Input Low Voltage				0.4	V
V _{IH}	Input High Voltage		V _{CC} - 0.2			V
V _{OL1}	Output Low Voltage	I _{OL} = 2.1 mA			0.25	V
V _{OL2}	Output Low Voltage	I _{OL} = 1.0 mA			0.1	V
V _{OH1}	Output High Voltage	I _{OH} = -400 μA	1.4			V
V _{OH2}	Output High Voltage	I _{OH} = -100 μA	V _{CC} - 0.1			V

Note: 1. In the erase mode, I_{CC} is 15 mA.

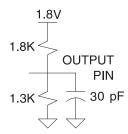




14. Input Test Waveforms and Measurement Level



15. Output Test Load



16. Pin Capacitance

 $f = 1 \text{ MHz}, T = 25^{\circ}C^{(1)}$

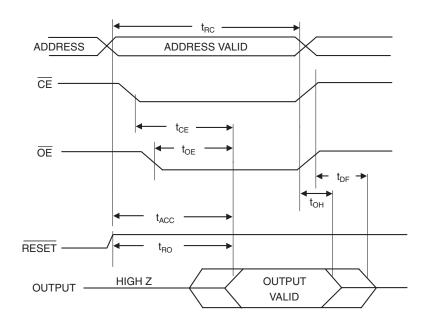
Symbol	Тур	Max	Units	Conditions
C _{IN}	4	6	pF	$V_{IN} = 0V$
C _{OUT}	8	12	pF	V _{OUT} = 0V

Note: 1. This parameter is characterized and is not 100% tested.

17. AC Read Characteristics

		AT49SV1	AT49SV163D(T)-80		
Symbol	Parameter	Min	Max	Units	
t _{RC}	Read Cycle Time	80		ns	
t _{ACC}	Address to Output Delay		80	ns	
t _{CE} ⁽¹⁾	CE to Output Delay		80	ns	
t _{OE} ⁽²⁾	OE to Output Delay	0	35	ns	
t _{DF} ⁽³⁾⁽⁴⁾	CE or OE to Output Float	0	25	ns	
t _{OH}	Output Hold from \overline{OE} , \overline{CE} or Address, whichever occurred first	0		ns	
t _{RO}	RESET to Output Delay		100	ns	

18. AC Read Waveforms⁽¹⁾⁽²⁾⁽³⁾⁽⁴⁾



- Notes: 1. \overline{CE} may be delayed up to t_{ACC} t_{CE} after the address transition without impact on t_{ACC} .

 2. \overline{OE} may be delayed up to t_{CE} t_{OE} after the falling edge of \overline{CE} without impact on t_{CE} or by t_{ACC} t_{OE} after an address change without impact on t_{ACC} .

 3. t_{DF} is specified from \overline{OE} or \overline{CE} , whichever occurs first (CL = 5 pF).

 - 4. This parameter is characterized and is not 100% tested.

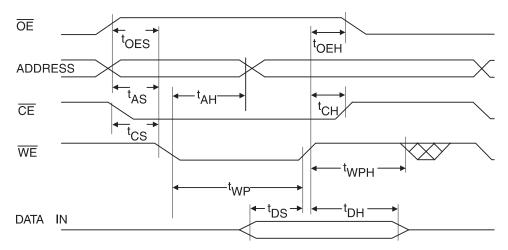


19. AC Word Load Characteristics

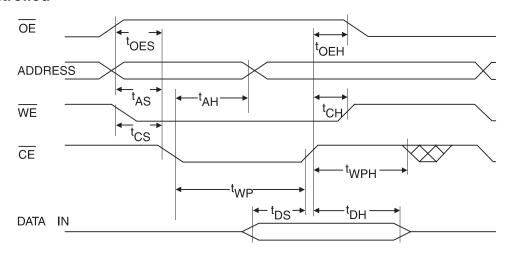
Symbol	Parameter	Min	Max	Units
t _{AS} , t _{OES}	Address, OE Setup Time	0		ns
t _{AH}	Address Hold Time	25		ns
t _{CS}	Chip Select Setup Time	0		ns
t _{CH}	Chip Select Hold Time	0		ns
t _{WP}	Write Pulse Width (WE or CE)	35		ns
t _{WPH}	Write Pulse Width High	15		ns
t _{DS}	Data Setup Time	25		ns
t _{DH} , t _{OEH}	Data, OE Hold Time	0		ns

20. AC Word Load Waveforms

20.1 WE Controlled



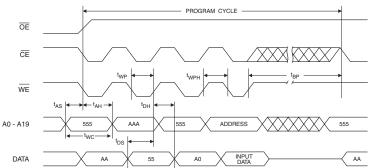
20.2 CE Controlled



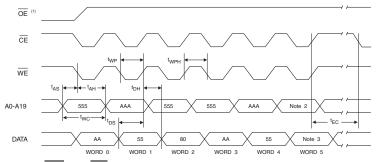
21. Program Cycle Characteristics

Symbol	Parameter	Min	Тур	Max	Units
t _{BP}	Word Programming Time		10	120	μs
t _{BPD}	Word Programming Time in Dual Programming Mode		5	60	μs
t _{AS}	Address Setup Time	0			ns
t _{AH}	Address Hold Time	25			ns
t _{DS}	Data Setup Time	25			ns
t _{DH}	Data Hold Time	0			ns
t _{WP}	Write Pulse Width	35			ns
t _{WPH}	Write Pulse Width High	15			ns
t _{WC}	Write Cycle Time	70			ns
t _{RP}	Reset Pulse Width	500			ns
t _{EC}	Chip Erase Cycle Time		16		seconds
t _{SEC1}	Sector Erase Cycle Time (4K Word Sectors)		0.1	2.0	seconds
t _{SEC2}	Sector Erase Cycle Time (32K Word Sectors)		0.5	6.0	seconds
t _{ES}	Erase Suspend Time			15	μs
t _{PS}	Program Suspend Time			10	μs

22. Program Cycle Waveforms



23. Sector or Chip Erase Cycle Waveforms



Notes: 1. \overline{OE} must be high only when \overline{WE} and \overline{CE} are both low.

- 2. For chip erase, the address should be 555. For sector erase, the address depends on what sector is to be erased. (See note 3 under "Command Definition Table" on page 12.)
- 3. For chip erase, the data should be 10H, and for sector erase, the data should be 30H.





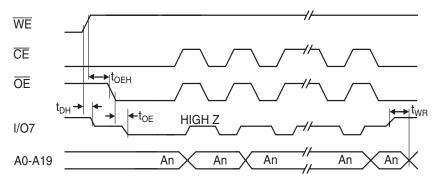
24. Data Polling Characteristics⁽¹⁾

Symbol	Parameter	Min	Тур	Max	Units
t _{DH}	Data Hold Time	10			ns
t _{OEH}	OE Hold Time	10			ns
t _{OE}	ŌĒ to Output Delay ⁽²⁾				ns
t _{WR}	Write Recovery Time	0			ns

Notes: 1. These parameters are characterized and not 100% tested.

2. See t_{OE} spec in "AC Read Characteristics" on page 19.

25. Data Polling Waveforms



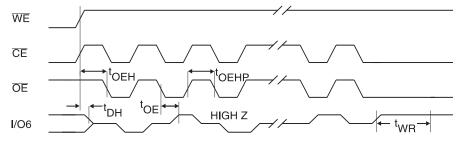
26. Toggle Bit Characteristics⁽¹⁾

Symbol	Parameter	Min	Тур	Max	Units
t _{DH}	Data Hold Time	10			ns
t _{OEH}	OE Hold Time	10			ns
t _{OE}	OE to Output Delay ⁽²⁾				ns
t _{OEHP}	OE High Pulse	50			ns
t _{WR}	Write Recovery Time	0			ns

Notes: 1. These parameters are characterized and not 100% tested.

2. See t_{OE} spec in "AC Read Characteristics" on page 19.

27. Toggle Bit Waveforms⁽¹⁾⁽²⁾⁽³⁾



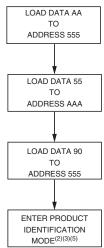
Notes: 1. Toggling either \overline{OE} or \overline{CE} or both \overline{OE} and \overline{CE} will operate toggle bit. The t_{OEHP} specification must be met by the toggling input(s).

2. Beginning and ending state of I/O6 will vary.

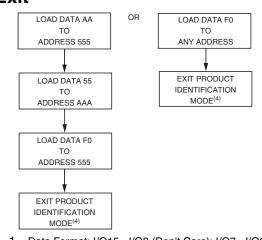
3. Any address location may be used but the address should not vary.



28. Software Product Identification Entry⁽¹⁾

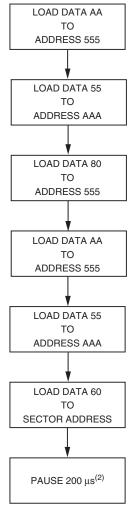


29. Software Product Identification Exit⁽¹⁾⁽⁶⁾



- Notes: 1. Data Format: I/O15 I/O8 (Don't Care); I/O7 I/O0 (Hex) Address Format: A11 - A0 (Hex), A-1, and A11 - A19 (Don't Care).
 - 2. A1 A19 = V_{IL} . Manufacturer Code is read for A0 = V_{IL} ; Device Code is read for $A0 = V_{IH}$. Additional Device Code is read from address 0003H.
 - 3. The device does not remain in identification mode if powered down.
 - 4. The device returns to standard operation mode.
 - 5. Manufacturer Code: 001FH Device Code: 02C0H - AT49SV163D; 02C2H - AT49SV163DT. Additional Device Code: 0001H - AT49SV163D(T)
 - 6. Either one of the Product ID Exit commands can be used.

30. Sector Lockdown Enable Algorithm⁽¹⁾



Notes: 1. Data Format: I/O15 - I/O8 (Don't Care); I/O7 - I/O0 (Hex) Address Format: A11 - A0 (Hex), A-1, and A11 - A19 (Don't Care).

2. Sector Lockdown feature enabled.



31. Common Flash Interface Definition Table

Address	Data	Comments
10h	0051h	"Q"
11h	0052h	"R"
12h	0059h	"Y"
13h	0002h	
14h	0000h	
15h	0041h	
16h	0000h	
17h	0000h	
18h	0000h	
19h	0000h	
1Ah	0000h	
1Bh	0017h	VCC min write/erase
1Ch	0019h	VCC max write/erase
1Dh	0090h	VPP min voltage
1Eh	00A0h	VPP max voltage
1Fh	0004h	Typ word write – 10 μs
20h	0002h	Typ dual word program time – 5 μs
21h	0009h	Typ sector erase, 500 ms
22h	000Eh	Typ chip erase, 16,000 ms
23h	0004h	Max word write/typ time
24h	0004h	Max dual word program time/typ time
25h	0004h	Max sector erase/typ sector erase
26h	0004h	Max chip erase/ typ chip erase
27h	0015h	Device size
28h	0001h	x16 device
29h	0000h	x16 device
2Ah	0002h	Max number of bytes in multiple byte write = 4
2Bh	0000h	Max number of bytes in multiple byte write = 4
2Ch	0002h	2 regions, x = 2
2Dh	0007h	8K bytes, Y = 7
2Eh	0000h	8K bytes, Y = 7
2Fh	0020h	8K bytes, Z = 32
30h	0000h	8K bytes, Z = 32
31h	001Eh	64K bytes, Y = 30
32h	0000h	64K bytes, Y = 30
33h	0000h	64K bytes, Z = 256
34h	0001h	64K bytes, Z = 256

31. Common Flash Interface Definition Table (Continued)

Address	Data	Comments		
VENDOR SPECIFIC EXTENDED QUERY				
41h	0050h	"Р"		
42h	0052h	"R"		
43h	0049h	"In		
44h	0031h	Major version number, ASCII		
45h	0030h	Minor version number, ASCII		
46h	0087h	Bit 0 – chip erase supported, 0 – no, 1 – yes Bit 1 – erase suspend supported, 0 – no, 1 – yes Bit 2 – program suspend supported, 0 – no, 1 – yes Bit 3 – simultaneous operations supported, 0 – no, 1 – yes Bit 4 – burst mode read supported, 0 – no, 1 – yes Bit 5 – page mode read supported, 0 – no, 1 – yes Bit 6 – queued erase supported, 0 – no, 1 – yes Bit 7 – protection bits supported, 0 – no, 1 – yes		
47h	0000h (top) or 0001h (bottom)	Bit 0 – top ("0") or bottom ("1") boot block device undefined bits are "0"		
48h	0000h	Bit 0 – 4 word linear burst with wrap around, 0 – no, 1 – yes Bit 1 – 8 word linear burst with wrap around, 0 – no, 1 – yes Bit 2 – continuos burst, 0 - no, 1 - yes Undefined bits are "0"		
49h	0000h	Bit 0 – 4 word page, 0 – no, 1 – yes Bit 1 – 8 word page, 0 – no, 1 – yes Undefined bits are "0"		
4Ah	0080h	Location of protection register lock byte, the section's first byte		
4Bh	0003h	# of bytes in the factory prog section of prot register – 2*n		
4Ch	0003h	# of bytes in the user prog section of prot register – 2*n		

