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## ROHM

Structure	:	Silicon Monolithic Integrated Circuit
Product Name	:	Power Driver For CD/D/D Players
Device Name	:	BD8201FM
Externals dimensional drawing	:	Figure 1
POWER DI SSI PATI ON	:	Figure 2
BLOCK DI AGRAM	:	Figure 3
Applied circuit chart	:	Fi gure 4
Features	:	<ul> <li>It is 4ch driver IC of BTL driver 3 ch and Loading driver 1 ch.</li> <li>Loading driver is high Drange type of MDS Output</li> <li>With Loading driver Output voltage setting terminal.</li> <li>With NUTE SW</li> <li>A built in the real shutdown circuit is installed.</li> </ul>

- A built-in thermal shutdown circuit is installed.
- Built in Power-supply voltage descent Mute.
- BIAS Voltage descent Mute.
- HSOP-N28 Package

#### • ABSOLUTE MAXI MUM RATI NOS (Ta=25°C)

Paraneter	Synbol	Limits	Uhit
Power Supply Voltage	Vcc	15	V
Power Dissipation	Pd	2.2 *	W
Operating Temperature Range	Topr	-40 to +85	°C
Storage Temperature Range	Tstg	-55 to +150	°C

\*1 When nounted on the glass/epoxy board with the size: 70 nmx70 nm, the thickness: 1.6 nm, and the rate of copper foil occupancy area: 3% or less. Over Ta=25°C, derating at the rate of 17.6 nW/°C.

#### • Range of operation power-supply voltage

Paranæter	Syntool	MIN	TYP	MAX	Uhit
BTL driver Pre part power-supply voltage	PREVCC	4. 5	7.5	14	٧
BTL driver CH1 part power-supply voltage	VCC1	4. 5	7.5	PREVCC	۷
BTL driver CH2,3 part power-supply voltage	VCC23	4. 5	5. 0	PREVCC	٧
Loading driver power-supply voltage	LDVCC	4. 5	7.5	14	V

## rohm

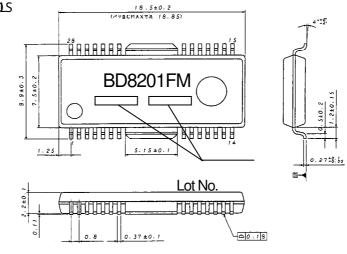
#### • ELECTRI C CHARACTERI STI CS

(Uhl ess ot her wise not ed Ta=25°C, PREVCC=LD/CC=VCC1=7.5V, VCC23=5V, BLAS=1.65V, RL=8Ω)

		MIN	TYP.	MAX.	Unit	Condition
Paraneter	Synbol	MUIN	TTP.			
Circuit Current (at no signal) (LDVcc)	ICLD	-	-	1.5	nA	Under braking
Circuit Current (at no signal) (Vcc1)	I CC1	-	-	1.0	nA	No I oad applied
Circuit Current (at no signal) (Vcc23)	ICC23	-	-	1. 0	nA1	No Ioad applied
Circuit Current (at no signal) (PreVcc)	I COPRE	-	-	25	nAA	No Ioad applied
<btl chi∼chb="" driver=""></btl>						
Output Offset Voltage	VOFS	- 50	0	+50	ntγ	
Naxinoum Output Annolitude (CH1)	VOM	4.7	5.4	-	V	
Maxinoum Output Annolitude (CH2,3)	VO1/23	3.7	4.0	-	V	
Olosed circuit voltage gain (CH1)	G/C1	9	12	15	dB	RI N≠10KΩ
Closed circuit voltage gain (CH2, 3)	G/C2	16	18	20	dB	
Positive and negative voltage gain (CH1 ~ CH3)	ΔG/C	- 2. 0	0	2.0	dB	
Mute ON Voltage	VMON	GD	-	0.5	V	
Mute • Rel ease vol tage	VMOFF	2, 0	-	PREVCC	V	
Muteterminal inflow current	I NUTE	-	50	100	μA	VNUTE=3. 3V
Bias Terninal Input Current	IBLAS	-	50	100	μA	
<loading block="" ch4="" driver=""></loading>						
Output Offset Voltage	VOFSL	- 35	0	+35	ntγ	Uhder braking
Input terninal threshold voltage H	ИИ	2, 8	-	LDVCC	V	
Input terminal threshold voltageM	MIV	1. 2	-	2, 1	V	
Input terninal threshold voltage L	٧IL	GD	-	0.5	V	
Maxinoum Output Annolitude	VOMLD	6.7	-	_	V	RL=9Ω
Voltage gain (Loading)	GALD	4.0	6.0	8.0	dB	LDCONT=1V
Positive and negative voltage gain (Loading)	Δ G/LD	- 2, 0	0	2.0	dB	
Input terminal inflow current	IIN	-	30	60	μA	LDI N=3. 3V
Terminal LDCONT inflow current	ILDC	-	25	80	μA	LDCONT=3, 3V

• Not designed for radiation resistance.

• OUTLINE DIMENSIONS, SYMBOLS

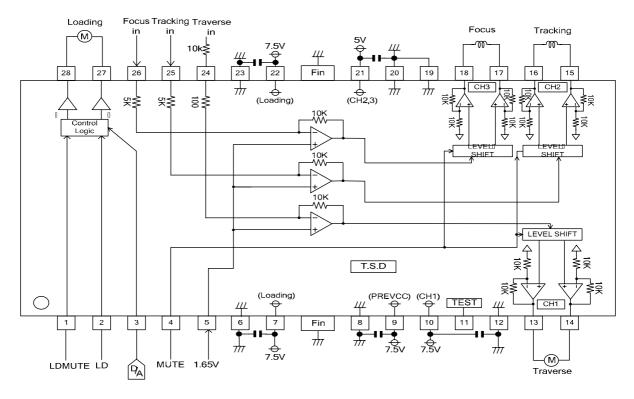


1218: EX141-6002

(UNIT: mm)

## ROHM

#### APPLICATION CIRCUIT DIAGRAM



T.S.D: (Thermal shutdown) Resistance unit :  $[\Omega]$ 

• Each terminal explanation

No	Pin Name	Description		Pin Name	Description		
1	LONUTE	Loading driver NOTE terninal	15	VO2(+)	BTL driver (CH2) positive output terminal		
2	LCIN	Loading driver input terminal	16	VO2(-)	BTL driver (CH2) negative output terminal		
3	LDCON	Loading driver Voltage setting terminal	17	VCB(+)	BTL driver (CHB) positive output terminal		
4	NUTE	BTL driver NUTE terminal (CH1, CH2, CH3)	18	VOB(-)	BTL driver (CHB) negative output terninal		
5	BIAS	Biasinput terminal	19	GND	GND terminal (CH2, CH3 POWER part)		
6	LDGND	GND terminal (Loading driver part)	20	GND	GND terminal (CH2,CH3 POWER part)		
7	LD/CC	VCC terninnal (Loading driver part)	21	VCC2, 3	Power supply voltage terninal (CH2, CHB POWER part)		
8	PREGND	(BTL driver , Pre part)	22	LD/CC	VCC terninal (Loading driver part)		
9	PREVCC	(BTL driver , Pre part)	23	LDGND	GND terminal (Loading driver part)		
10	VCC1	VCC terminal (CHI POWER part)	24	VINI	CH1 input terminal		
11	TEST	Input terminal for TEST mode	25	VI N2	CH2 input terminal		
12	GND	GND terminal (CH1 POWER part)	26	VI NB	CHB input terminal		
13	VOI(-)	BTL driver (CH1) negative output terminal	27	LDOJT(-)	Loading driver negative output terminal		
14	VOI( +)	BTL driver (CH1) positive output terminal	28	LDOUT(+)	Loading driver positive output		

Note: The positive or negative polarity of driver outputs is determined by the input polarity.

• Function Description

1. MUTE(Pin 4)

BTL driver part (CH1 to CH3) can be switched mode ONV OFF by inputting H lever (above 2.0V) or L level (below 0.5V) to this terminal.

2.LDMUTE(Pin 1)

Loading driver part can be switched ON/OFF by inputting H level (above 2.0V) or L level (below 0.5V) to this terminal.

3.BIAS dropping mute

Setting BIAS terminal (Pin5) voltage to 0.7 or below (Typ.) will activate mute function for BTL driver part (CH1 to CH3). Set BIAS terminal voltage to 1.1V or above.

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#### 4. The following table shows logics for loading driver operation.

	INPUT		001		
LDMUTE	L D I N	LDCONT	OUT+	OUT-	FUNCTION
L	Х	Х	Hi Z	Hi Z	High impedance
Н	Х	<0.7V	Hi Z	Hi Z	High impedance
Н	L	>0.7V	L	Н	REV mode
Н	Н	>0.7V	Н	L	FWD mode
н	M or HiZ	>0.7V	L	L	Break mode

Although the output voltage can be changed by the input voltage through the LDCONT terminal (gain 6dB Typ.), it never exceeds the maximum output voltage restricted by the power supply voltage even if applying a voltage much larger than the normal value.

Also, output of loading driver corresponded to LDCONT terminal becomes High-impedance mode by setting LDCONT terminal (3pin) to 0.7V or below. 5. Protection circuit for VCC and GND fault

This IC contains protection circuit for VCC and GND fault to prevent itself from breaking caused by short between BTL driver output pin and VCC (VCC fault) or BTL driver output pin and GND (GND fault).

Make sure output pin should not short to VCC or GND. However in case VCC and GND fault occur, internal circuit prevents IC from breaking by limiting current. (available for only CH1, CH2, CH3)

Protection circuit for GND fault is contained to prevent from breaking caused by short between loading driver output pin and GND. Make sure output pin should not short to GND. However in case GND fault occurs, internal circuit prevents IC from breaking by limiting current.

#### Caution on use

1. Bypass capacitor

Connect bypass capacitor ( $0.1\mu$  F) close to this IC pin between power supplies. Also, connect capacitor ( $10\mu$  F ~ ) which is greater capacity and small ESR close to power supply terminal for reducing impedance.

#### 2.TEST terminal

TEST terminal is pulled-up in IC, therefore use it as open or by shorted with VCC.

#### 3 About absolute maximum ratings

Exceeding the absolute maximum ratings, such as the applied voltage or the operating temperature range, may cause permanent device damage. As these cases cannot be limited to the broken short mode or the open mode, if a special mode where the absolute maximum ratings may be exceeded is assumed, it is recommended to take mechanical safety measures such as attaching fuses.

#### 4 .About power supply lines

As a measure against the back current regenerated by a counter electromotive force of the motor, a capacitor to be used as a regenerated-current path can be installed between the power supply and GND and its capacitance value should be determined after careful check that any problems, for example, a leak capacitance of the electrolytic capacitor at low temperature, are not found in various characteristics.

#### 5. About GND potential

The electric potential of the GND terminal must be kept lowest in the circuitry at any operation states

#### 6 .About thermal design

With consideration of the power dissipation (Pd) under conditions of actual use, a thermal design provided with an enough margin should be done.

#### 7 .About operations in a strong electric field

When used in a strong electric field, note that a malfunction may occur.

#### 8 .ASO

When using this IC, the output Tr must be set not to exceed the values specified in the absolute maximum ratings and ASO.

#### 9. Thermal shutdown circuit

This IC incorporates a thermal shutdown circuit (TSD circuit). When the chip temperature reaches the value shown below, the coil output to the motor will be set to open. The thermal shutdown circuit is designed only to shut off the IC from a thermal nuraway and not intended to protect or guarantee the entire IC functions. Therefore, users cannot assume that the TSD circuit once activated can be used continuously in the subsequent operations.

TSD ON Temperature [°C] (typ.)	Hysteresis Temperature [°C] ((yp. )
175	25

#### 10. About earth wiring patterns

When a small signal GND and a large current GND are provided, it is recommended that the large current GND pattern and the small signal GND pattern should be separated and grounded at a single point of the reference point of the set in order to prevent the voltage of the small signal GND from being affected by a voltage change caused by the resistance of the pattern wiring and the large current.

Make sure that the GND wiring patterns of the external components will not change, too.

#### 11. About each input terminal

This IC is a monolithic IC which has a P<sup>+</sup>isolations and P substrate to isolate elements each other.

This P layer and an N layer in each element forma PN junction to construct various parasitic elements.

Due to the IC structure, the parasitic elements are inevitably created by the potential relationship.

Activation of the parasitic elements can cause interference between circuits and may result in a malfunction or, consequently, a fatal damage. Therefore, make sure that the IC must not be used under

conditions that may activate the parasitic elements, for example, applying the lower voltage than the ground level(GND, P substrate) to the input terminals.

Note that, while not applying the power supply voltage to the IC, any voltage must not be applied to the input terminals. In addition, do not apply the voltage to input terminals without applying the

power supply voltage to the IC. Also while applying the power supply voltage, each input terminal must be the power supply voltage or less; or within the guaranteed values in the electric characteristics.

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Appendix1-Rev2.0

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