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Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





# 4.2V to 18V Input 1ch Boost Controller

# BD9306AFVM

### **General Description**

BD9306AFVM is a 1-channel DC/DC converter controller. A Step-up DC/DC converter can be configured. In addition, it has a built-in master-slave function which improves synchronization.

#### Features

- 1ch PWM Controlled DC/DC Converter Controller
- Built-in Soft Start Function
- Built-in Master / Slave Function
- Protection Circuits:
  - Under Voltage Lockout Protection Circuit
  - Thermal Shutdown Circuit
  - > Short Protection Circuit of Timer Latch type

# Applications

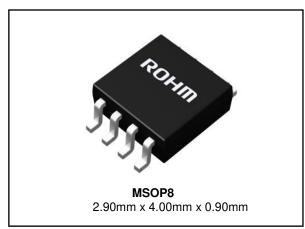
- TV, Power Supply for the TFT-LCD Panels used for LCD TVs, Back Lights
- DSC, DVC, Printer, DVD ,DVD Recorder, Generally Consumer Equipments etc.

#### Key Specifications

- Power Supply Voltage Range: 4.2V to 18V
- Error Amplifier Feed Back Voltage: 1.25±1.6%
- Oscillating Frequency Range: 100kHz to 800kHz
- Standby Current: 0μA(Typ)
- Operating Temperature Range: -40°C to +85°C

#### Package

W(Typ) x D(Typ) x H(Max)



# Typical Application Circuit

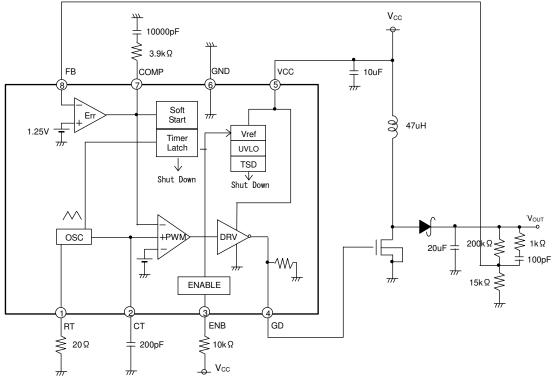
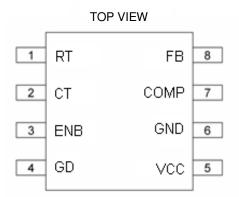


Figure 1. Typical Application Circuit

OProduct structure : Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

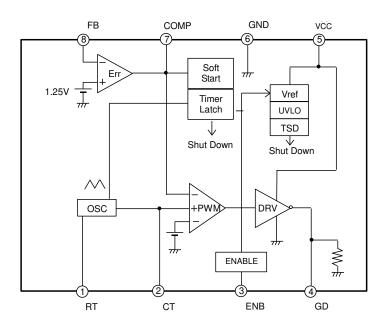
# **Pin Configuration**



#### **Pin Descriptions**

Pin No	Pin Name	Function
1	RT	External timing resistor pin
2	СТ	External timing capacitor pin
3	ENB	Control pin
4	GD	Gate drive output pin
5	VCC	Power supply pin
6	GND	Ground pin
7	COMP	Error amp output pin
8	FB	Error amp inversion input pin

# **Block Diagram**



# **Block Operation**

1. Error Amplifier (Err)

It compares a reference voltage of 1.25V (TYP) and the output feedback voltage. This block produces the COMP terminal voltage that determines the duty cycle.

2. Oscillator (OSC)

This block determines the switching frequency by RT and CT values. The triangular wave is determined by RT and CT.

3. PWM

The duty cycle is determined by comparing the output of Error amplifier and the angular wave of Oscillator. The switching Duty of BD9306AFVM is limited by the maximum duty ratio that is determined by the internal part, and will not be up to 100%.

#### 4. DRV

This block drives the gate of the external power FET by the PWM switching Duty.

5. VREF

This block outputs the internal reference voltage of 2.5V (TYP). This circuit's reference voltage is controlled (ON / OFF) by the ENB terminal.

6. Protection Circuits (UVLO / TSD)

UVLO (low-voltage Lock Out circuit) shuts down the circuits when the voltage is below 3.5V (MIN). TSD (temperature protection circuit) shuts down the IC when the temperature reaches 175°C (TYP).

7. Soft Start Circuit

The Soft Start Circuit limits the current when the output voltage is slowly increasing during start-up. Through this, the overshoot of output voltage and current sinking can be prevented.

8. Timer Latch

It is an output short protection circuit that detects if the output of error amplifier (COMP voltage) is more than 1.7V (TYP). If the COMP voltage becomes more than 1.7V, the counter begins to operate. The LATCH is locked when the counter counts to 2200 and the GD output shuts down. The frequency of counter is determined by RT and CT. Once the LATCH was locked, the GD output will not operate until it is restarted by ENB or VCC. If the output short is removed while the Timer latch is counting, the counter will be reset.

### Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Limit	Unit
Power Supply Voltage (Note 2)	Vcc	20	V
Power Dissipation	Pd	0.58 (Note 1)	W
Operating Temperature Range	Topr	-40 to +85	°C
Storage Temperature Range	Tstg	-55 to +150	°C
Maximum Junction Temperature	Tjmax	150	°C

(Note 1) When mounted on a glass epoxy 4-layer board (70 mm x 70 mm x 1.6 mm). Derate by 4.7 mW/°C for Ta over 25°C.

(Note 2) Must not exceed Pd.

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

### Recommended Operating Conditions (Ta=-40°C to +85°C)

Parameter	Symbol		Unit		
Farameter	Symbol	Min	Тур	Max	Unit
Power Supply Voltage	Vcc	4.2	12	18	V
Control Voltage	V <sub>ENB</sub>	-	-	Vcc	V
Timing Capacitance	Сст	100	-	1000	pF
Timing Resistance	R <sub>RT</sub>	5	-	50	kΩ
Oscillating Frequency	fosc	100	-	800	kHz

# Electrical Characteristics (Unless otherwise specified Ta=25°C, V<sub>CC</sub>=12V, C<sub>CT</sub>=200pF, R<sub>RT</sub>=20kΩ)

cifical characteristics (Unless	Utilei wise	specifieu			$, \mathbf{o}_{c_1-\mathbf{z}}$	μι, π <sub>R1</sub> -20κ32 <i>)</i>
Demension	O male al		Limit		11	O a sa diti a sa a
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Triangular Waveform Oscillator Blo	ck】					
Oscillating Frequency	fosc	165	220	275	kHz	Vcc=5V
Charge Threshold Voltage	V <sub>OSC</sub> +	0.80	0.85	0.90	V	
Discharge Threshold Voltage	Vosc -	0.20	0.25	0.30	V	
Under-voltage Lockout Protection	Circuit					
Threshold Voltage	V <sub>UT</sub>	3.5	-	4.2	V	
Error Amp Block						
Feed Back Voltage	V <sub>FB</sub>	1.230	1.250	1.270	V	
Input Bias Current	I <sub>IB</sub>	-	0.05	1	μA	V <sub>FB</sub> =1.5V
COMP Sink Current	loi	35	50	65	μA	V <sub>FB</sub> =1.5V V <sub>COMP</sub> =1.25V
COMP Source Current	loo	35	50	65	μA	VFB=1.0V VCOMP=1.25V
Gate Drive Block						
ON-Resistance	Ron	-	5	-	Ω	
Gate Drive Voltage L	Vgdl	-	0	0.5	V	No Load
Gate Drive Voltage H	V <sub>GDH</sub>	V <sub>cc</sub> -0.5	Vcc	-	V	No Load
MAX Duty	MDT	—	83	—	%	Vcc=5V
Control Block						
ON Voltage	V <sub>ON</sub>	2	-	-	V	
OFF Voltage	VOFF	-	-	0.3	V	
ENB Sink Current	IENB	40	60	90	μA	V <sub>ENB</sub> =5V
Soft Start Block						
Soft Start Time	ts	-	10	-	ms	
Timer Latch Protection Circuit						
Latch Detection COMP Voltage	VLC	1.5	1.7	1.9	V	
Latch Delay OSC Count Number	CNT	-	2200	-	COUNT	
Latch Delay Time	DLY	-	10	-	ms	
Overall	- <u>n</u>					
Standby Current	ISTBY	-	0	10	μA	ENB=OFF
Average Consumption Current	Icc	1.0	1.5	2.5	mA	No Switching

#### **Typical Performance Curves**

(Unless otherwise specified, V<sub>CC</sub>=12V, Ta=25°C)

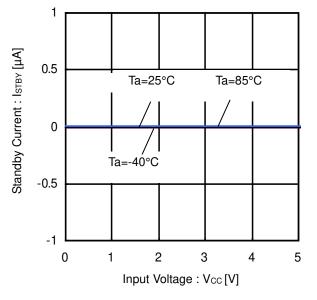


Figure 2. Standby Current vs Input Voltage

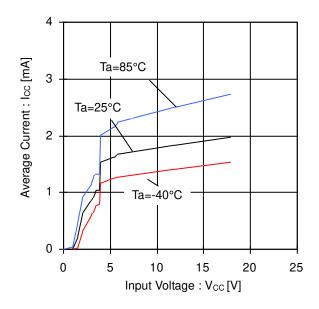


Figure 3. Average Consumption Current vs Input Voltage

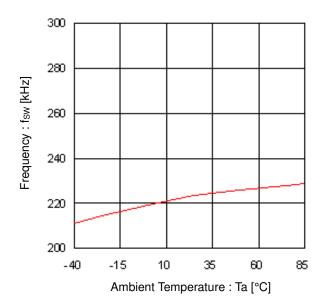


Figure 4. Frequency vs Ambient Temperature

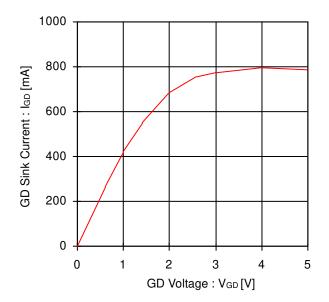


Figure 5. GD Sink Current vs GD Voltage

(Unless otherwise specified, Vcc=12V, Ta=25°C)

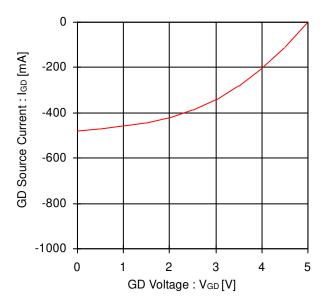


Figure 6. GD Source Current vs GD Voltage

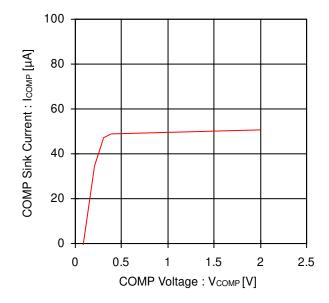


Figure 7. COMP Sink Current vs COMP Voltage

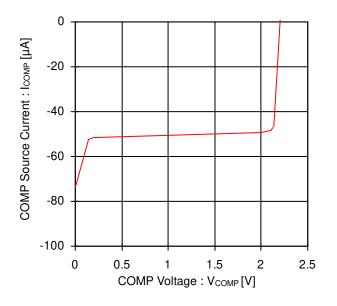


Figure 8. COMP Source Current vs COMP Voltage

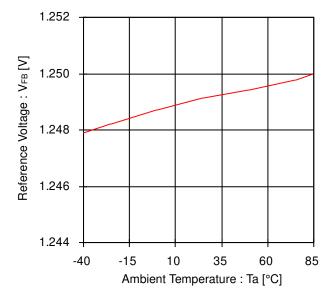


Figure 9. Reference Voltage vs Ambient Temperature

#### **Typical Performance Curves - continued**

(Unless otherwise specified, Vcc=12V, Ta=25°C)

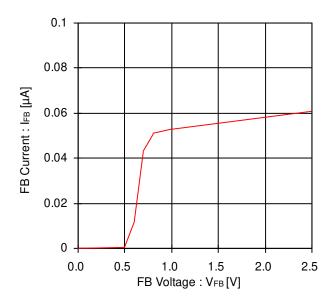


Figure 10. FB Input Bias Current vs FB Voltage

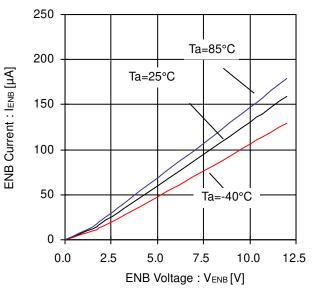


Figure 11. ENB Input Current vs ENB Voltage

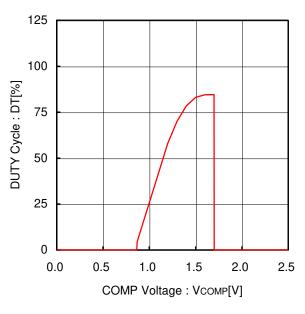


Figure 12. DUTY Cycle vs COMP Voltage

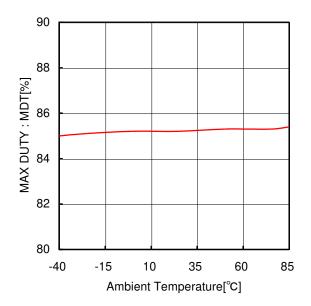


Figure 13. MAX DUTY vs Ambient Temperature

#### **Typical Performance Curves - continued**

(Unless otherwise specified, Vcc=12V, Ta=25°C)

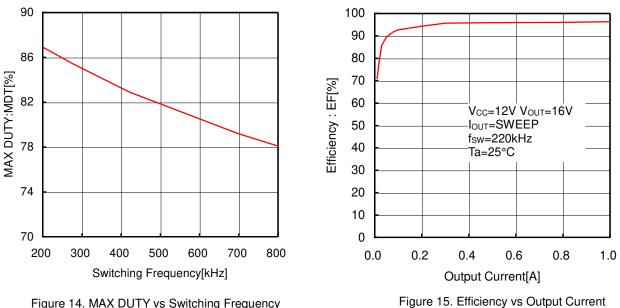


Figure 14. MAX DUTY vs Switching Frequency

# **Typical Waveforms**

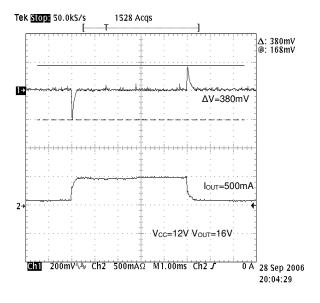


Figure 16. Load Response

#### **Application Information**

#### **1.Selecting Application Components**

 Setting the Output L Constant (Step Down DC/DC) The inductance L used for output was decided by the rated current I<sub>LR</sub> and input current maximum value I<sub>OMAX</sub> of the inductance.

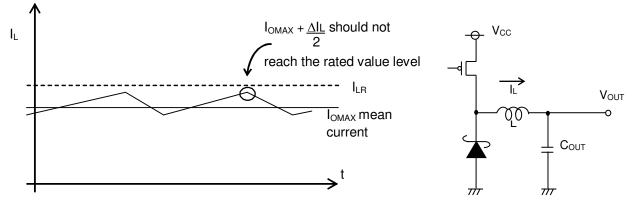
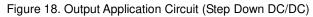


Figure 17. Coil Current Waveform (Step Down DC/DC)



Adjust so that  $I_{OMAX} + \Delta I_L/2$  does not reach the rated current value  $I_{LR}$ . At this time,  $\Delta I_L$  can be obtained by the following equation.

$$\Delta I_L = \frac{1}{L} \times \left( V_{CC} - V_{OUT} \right) \times \frac{V_{OUT}}{V_{CC}} \times \frac{1}{f} \quad [A]$$

Set a sufficient margin because the inductance L value may have  $\pm$  30% dispersion. If the coil current exceeds the rating current I<sub>LR</sub> of the coil, it can cause damage to the IC internal elements.

#### (2) Setting the Output L Constant (Step Up DC/DC)

The inductance L to use for output is decided by the rated current I<sub>LR</sub> and input current maximum value I<sub>INMAX</sub> of the inductance.

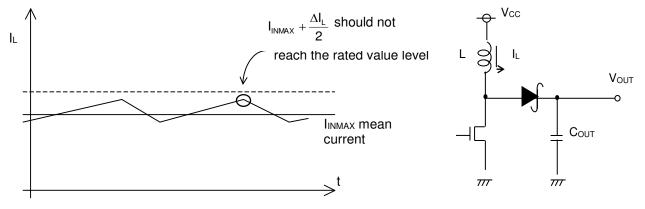


Figure 19. Coil Current Waveform (Step Up DC/DC)



Adjust so that  $I_{INMAX} + \Delta I_L / 2$  does not reach the rated current value  $I_{LR}$ . At this time,  $\Delta I_L$  can be obtained by the following equation.

$$\Delta I_{L} = \frac{1}{L} V_{CC} \times \frac{V_{OUT} - V_{CC}}{V_{OUT}} \times \frac{1}{f} \quad [A]$$

where: *f* is the switching frequency

Set a sufficient margin because the inductance L value may have  $\pm$  30% dispersion. If the coil current exceeds the rating current I<sub>LR</sub> of the coil, it can cause damage to the IC internal elements.

# BD9306AFVM

(3) Setting the Output Capacitor

For the output capacitor C, select a capacitor which has a larger value at the ripple voltage V<sub>PP</sub> allowance value and the drop voltage allowance value when there's a sudden load change.

Output ripple voltage is determined by the following equation.

$$\Delta V pp = \Delta I_L \times R_{ESR} + \frac{\Delta I_L}{2C_{OUT}} \times \frac{V_{OUT}}{V_{CC}} \times \frac{1}{f} [V] \qquad (\text{Step Down DC/DC})$$
  
$$\Delta V pp = I_{LMAX} \times R_{ESR} + \frac{1}{fC_{OUT}} \times \frac{V_{CC}}{V_{OUT}} \times \left(I_{LMAX} - \frac{\Delta I_L}{2}\right) [V] \qquad (\text{Step Up DC/DC})$$

Apply the setting so that the voltage is within the allowable ripple voltage range.

For the drop voltage during the sudden load change (V<sub>DR</sub>), perform a rough calculation by the following equation.  $V = -\frac{\Delta I}{\Delta I} \times 10 \, \mu \, \text{sec} = [V]$ 

$$V_{DR} = \frac{\Delta u}{C_{OUT}} \times 10 \,\mu \,\text{sec} \quad [V$$

However, 10  $\mu$ s is the rough calculation value of the DC/DC response speed. Set the capacitance while considering a sufficient margin so that these two values are within the standard value range.

(4) Setting of Feedback Resistance Constant Refer to the following formula for setting of feedback resistance.

$$V_{OUT} = \frac{R_1 + R_2}{R_2} \times 1.25 \ [V]$$

It is recommend to use  $10k\Omega$  to  $330k\Omega$  setting range. If a resistance below  $10k\Omega$  was set, voltage efficiency will be dropped. If a resistance of more than  $330k\Omega$  was set, the offset voltage becomes large because of the internal error amplifier's input bias current of  $0.05\mu A(Typ)$ . Please set the maximum setting voltage of BD9306AFVM (step up) in such a way that Duty : (V<sub>OUT</sub> - V<sub>CC</sub>) / V<sub>OUT</sub> is less than 70%.

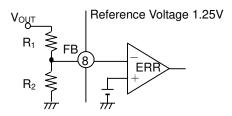


Figure 21. Feedback Resistance Setting

(5) Setting of Oscillating Frequency

The angular wave oscillation frequency can be set by connecting a resistor and a capacitor to RT (Pin 1) and CT (Pin 2) respectively. The charge and discharge currents at the capacitor of CT will be determined by the RT resistor. Refer to the configuration below for setting the RT's resistor and the CT's capacitor.

 $R_{RT}$ : 5k $\Omega$  to 50k $\Omega$ , C<sub>CT</sub>: 100pF to 1000pF. The frequency range of 100kHz to 800kHz are recommended. Remember that the switching will stop if your setting is off this range.

Figure 22. Frequency Setting

(6) Selection of Input Capacitor

For DC/DC converter, the capacitor at the input side is also necessary because maximum current will be flowing between input and output. Therefore, it is recommended that an input capacitor with over  $10\mu$ F and low ESR below  $100m\Omega$ . If a selected capacitor is outside this range, excessive large ripple voltage will overlap with the input voltage which may cause IC malfunction. However, this condition varies with negative overcurrent, input voltage, output voltage, inductor's value, and switching frequency so make sure to have a margin check with actual devices.

(7) Selection of Output Rectifier Diode

Schottky barrier diode is recommended as the diode for rectification at the output stage of DC/DC converter. Refer below for choosing the maximum inductor current, the maximum output voltage, and the power supply voltage. <step-down DC/DC>

	Maximum inductor current	$I_{OMAX} + \frac{\Delta I_L}{2}$	<	Diode's rated current	
	Power supply voltage	Vcc	<	Diode's rated voltage	
ep-up	DC/DC> Maximum inductor current	$I_{INMAX} + \frac{\Delta I_L}{2}$	<	Diode's rated current	
	Maximum output voltage	Vomax	<	Diode's rated voltage	

Furthermore, each parameter has a deviation of 30% to 40%, so design in such a way that you have provided enough margin for the deviation in your design.

(8) Setting of Power FET

<ste

If step-up DC/DC is configured by BD9306AFVM, Nch FET is necessary. Consider the following conditions when you choose:

<step-down DC/DC>

votop doi				
	Maximum inductor current	$I_{OMAX} + \frac{\Delta I_L}{2}$	<	FET's rated current
	Power supply voltage	Vcc	<	FET's rated voltage
	Power supply voltage	Vcc	>	FET's gate ON voltage
	Gate capacitance (Note 1)	CGATE	<	2000pF
<step-up< td=""><td>DC/DC&gt;</td><td></td><td></td><td></td></step-up<>	DC/DC>			
	Maximum inductor current	$I_{INMAX} + \frac{\Delta I_L}{2}$	<	FET's rated current
	Maximum output voltage	Vomax	<	FET's rated voltage
	Power supply voltage	Vcc	>	FET's gate ON voltage
			-	
	Gate capacitance (Note 1)	Cgate	<	2000pF

Furthermore, each parameter has a deviation of 30% to 40%, so design in such a way that you have provided enough margin for the deviation in your design.

(Note 1) If the Gate capacity becomes large, the switching speed will be slower, which may cause heat generation and breakdown, so check thoroughly the actual devices.

# (9) Phase Compensation

Phase Setting Method

The following conditions are required to ensure the stability of the negative feedback circuit.

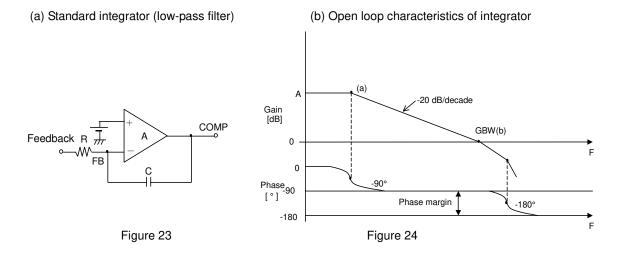
Phase lag should be 150° or lower when gain is 1 (0 dB) (phase margin of 30° or higher).

Because DC/DC converter applications are sampled using the switching frequency, the overall GBW should be set to 1/10 the switching frequency or lower. The target application characteristics can be summarized as follows:

- Phase lag should be 150° or lower when gain is 1 (0 dB) (phase margin of 30° or higher).
- The GBW at that time (i.e., the frequency of a 0-dB gain) is 1/10 of the switching frequency or below.

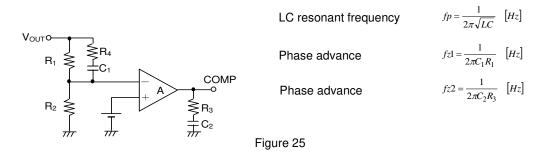
In other words, because the response is limited by the GBW, it is necessary to use higher switching frequencies to raise response.

One way to maintain stability through phase compensation involves cancellation of the secondary phase lag (-180°) caused by LC resonance with a secondary phase advance (by inserting 2 phase advances). The GBW (i.e., the frequency with the gain set to 1) is determined by the phase compensation capacitor connected to the error amp. Increase the capacitance if a GBW reduction is required.



Point (a) 
$$fa = \frac{1}{2\pi RCA} [Hz]$$
 Point (b)  $fb = GBW = \frac{1}{2\pi RC} [Hz]$ 

The error amp performs the phase compensation at points (a) and (b) and it acts as a low-pass filter. For DC/DC converter applications, R refers to feedback resistors connected in parallel. From the LC resonance of output, the number of phase advances to be inserted is two.



Set a phase advance frequency close to the LC resonant frequency for the purpose of canceling the LC resonance.

(Note) If high-frequency noise is generated in the output, FB is affected through capacitor C<sub>1</sub>. Therefore, insert the resistor  $R_4$ =1k $\Omega$  or so, which is in series with capacitor C<sub>1</sub>.

#### 2. Example of Application

(Note) We strongly recommend the following application circuit examples but check thoroughly the characteristics before putting using them.

When you made changes at the external circuit, design a sufficient margin after considering the deviation, etc. of the external components and ROHM IC in terms of not only the static characteristic but also the transient characteristic. Moreover, understand that our company can not confirm fully with regard to the patent right.

#### <Master Slave Function>

The master slave function is built-in. Synchronous switching is possible by the multi-connection of BD9305AFVM/ BD9306AFVM ICs. The following drawing shows an example of circuit connection in which BD9305AFVM is connected on the master side and BD9306AFVM is connected on the slave side.

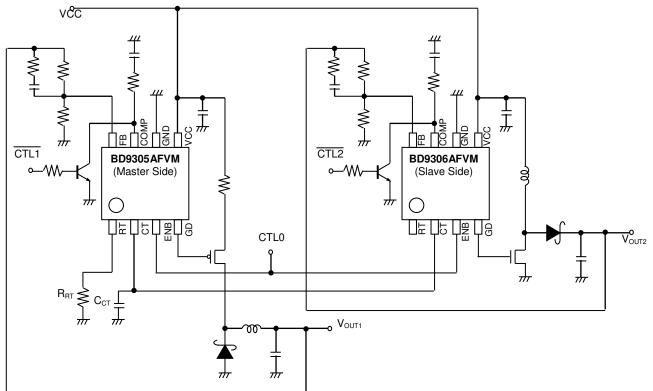


Figure 26. Master Slave Application Circuit

In the circuit above, BD9306AFVM is synchronized with the switching frequency which is determined by RT and CT of BD9305AFVM (master). In addition, the ON/OFF of output can be controlled by connecting the switch to the COMP terminal. (Refer to the following table)

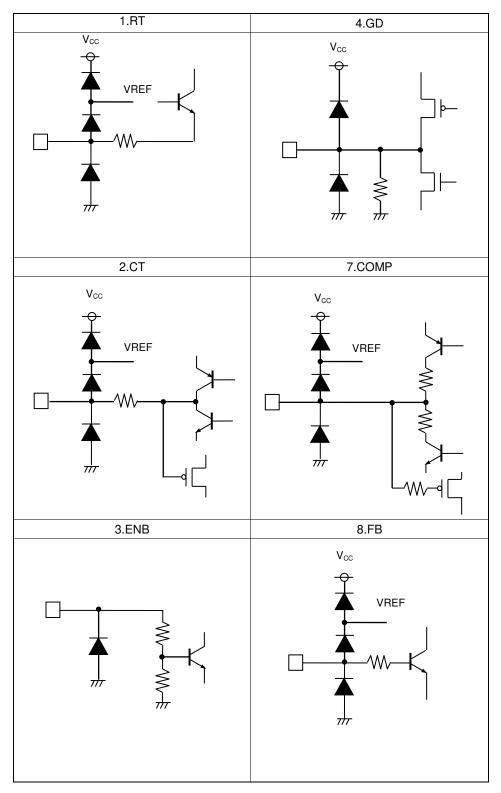
	Control	signal corresponden		
Output state			Control signal	
V <sub>OUT1</sub>	V <sub>OUT2</sub>	CTL0	CTL1	CTL2
OFF	OFF	Low	(Note)	(Note)
OFF	ON	High	High	Low
ON	OFF	High	Low	High
ON	ON	High	Low	Low

#### Control signal correspondence table

(Note) The same in either case of High / Low.

Similarly in the case of connecting three or more than three, synchronization is still possible by connecting the CT terminal of Master and the CT terminal of Slave.

# I/O Equivalent Circuits



### **Operational Notes**

#### 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

#### 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

#### 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

#### 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

#### 5. Thermal Consideration

Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the maximum junction temperature rating.

#### 6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

#### 7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

#### 8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

#### 9. **Testing on Application Boards**

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

#### 10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

#### 11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

### **Operational Notes – continued**

#### 12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

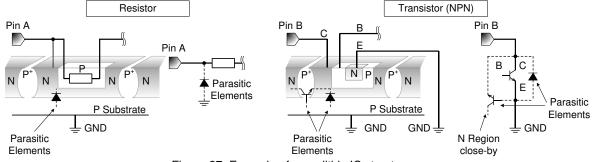


Figure 27. Example of monolithic IC structure

#### 13. Thermal Shutdown Circuit(TSD)

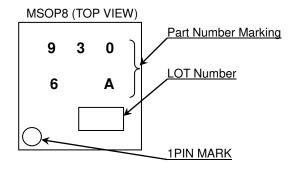
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

# **Ordering Information**

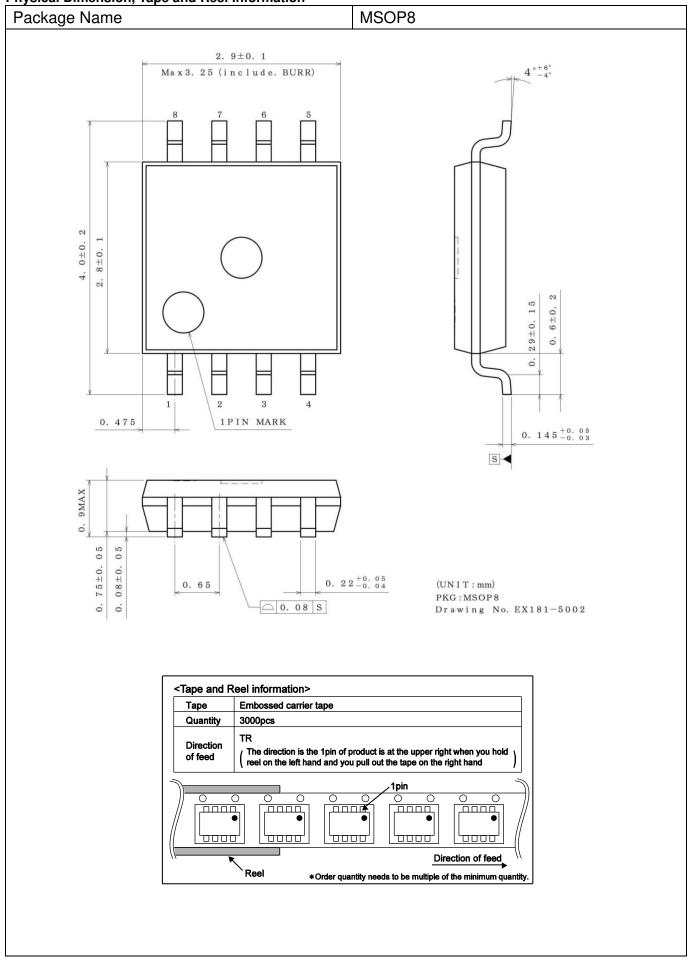


# **Marking Diagram**



# Datasheet

#### **Physical Dimension, Tape and Reel Information**



# **Revision History**

Date	Revision	Changes
13.Nov.2015	001	New Release

# Notice

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(Note1) Medical Equipment Classification of the Specific Applications
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JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASS II b	CLASSII
CLASSⅣ	CLASSII	CLASSⅢ	CLASSII

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  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### Precaution for Mounting / Circuit board design

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- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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#### Precaution for Storage / Transportation

- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
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  - [b] the temperature or humidity exceeds those recommended by ROHM
  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- 2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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