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Resistive Type Touch Screen Controller ICs

BU21023GUL BU21023MUV

General Description

Unlike most resistive touch screen controllers, the BU21023 4-wire resistive touch screen controller enables dual-touch detection and gesture recognition. These intelligent controllers expose a set of registers to a HOST processor and are configured through software. The controllers can detect single point coordinates, dual coordinates, pinch, spread, rotate left and rotate right gestures, enabling pan and zoom operations in applications that previously had to rely exclusively on capacitive touch technology. Resistive touch does not require custom screen development which reduces development cost, and results in faster time to market across a family of products.

Features

- Enables single touch, dual touch & gesture recognition using standard 4-wire resistive touch screens
- Adjustable touch detection threshold allows fine tuning of pressure sensitivity for an application
- Enables measurement of single point touch pressure
- SPI- and 2-wire serial interface for interfacing to HOST processor
- Programmable interrupt polarity
- 10-bit ADC provides sufficient resolution for finger or stylus inputs
- Firmware for internal CPU may be downloaded from HOST processor or from an EEPROM
- Includes filtering options to eliminate false coordinates
- Built in support for intelligent calibration
- Easy to swap X & Y coordinates or adapt to different touch screen connections
- Single 3V power supply
- Available in small packages and temperature ranges
- Ideally suited for consumer

Packages

VCSP50L2 VQFN028V5050 W(Typ) x D(Typ) x H(Max) 2.60mm x 2.60mm x 0.55mm 5.00mm x 5.00mm x 1.00mm





VCSP50L2

VQFN028V5050

Applications

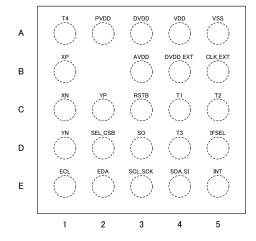
- Products with an LCD can benefit from pan and zoom operations.
- Smart phones, Digital Cameras, Video Cameras, GPS Receivers, Printers,
 Copiers, automotive navigation screens, touch
- Tablet PCs , Notebook PCs, LCD displays (with USB interface)

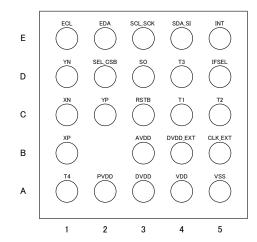
Key Specifications and Lineup

| Parameter | BU21023GUL | BU21023MUV |
|---------------------------|-------------------------------|-------------------------------|
| Screen | 4-wire resistive touch screen | 4-wire resistive touch screen |
| Maximum Detection Point | 2 | 2 |
| Integrated Filter Process | Yes | Yes |
| Gesture Detection | Yes | Yes |
| Supplied Voltage Range(V) | 2.7 to 3.6 | 2.7 to 3.6 |
| Temperature Range(°C) | -20 to +85 | -20 to +85 |
| Host I/F | 4-wire SPI 2-wire serial | 4-wire SPI 2-wire serial |
| Package | VCSP50L2 | VQFN028V5050 |

Pin Configuration and Pin Description

[BU21023GUL]





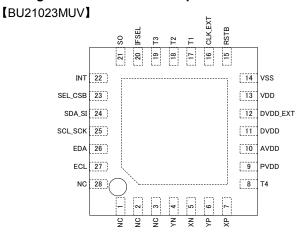
TOP VIEW (BALL SIDE DOWN)

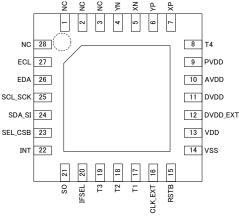
BOTTOM VIEW (BALL SIDE UP)

| No. | Pin Name | I/O | | Fur | nction | | Figure | | | |
|-----|----------|-----|-----------|----------------------------------|-------------|-----------------------|--------|--|--|--|
| D1 | YN | I/O | Screen | creen interface | | | | | | |
| C1 | XN | I/O | Screen | creen interface | | | | | | |
| C2 | YP | I/O | Screen | interface | | | Е | | | |
| B1 | XP | I/O | Screen | interface | | | Е | | | |
| A1 | T4 | I/O | Test pir | 1 | | | Е | | | |
| A2 | PVDD | 0 | Regulat | tor output (for supply screen | voltage) | | - | | | |
| В3 | AVDD | 0 | Regulat | tor output (for supply analog | block) | | - | | | |
| A3 | DVDD | I/O | Regulat | tor output (for supply digital b | lock) or si | upply digital voltage | - | | | |
| B4 | DVDD_EXT | 1 | Digital v | oltage enable (H=Hi-z , L=D | VDD Enal | ole) | Е | | | |
| A4 | VDD | - | Supply | upply voltage | | | | | | |
| A5 | VSS | - | Ground | round | | | | | | |
| C3 | RSTB | I | H/W res | /W reset | | | | | | |
| B5 | CLK_EXT | I | Supply | external clock for debug | | | Α | | | |
| C4 | T1 | I | Test pir | 1 | | | Α | | | |
| C5 | T2 | I | Test pir | 1 | | | Α | | | |
| D4 | Т3 | I | Test pir | 1 | | | Α | | | |
| D5 | IFSEL | I | Interfac | e select pin (L=SPI, H=2-wire | e serial) | | Α | | | |
| D3 | SO | 0 | SPI | Serial data output | 2-wire | - | F | | | |
| E5 | INT | 0 | Interrup | t output | | | С | | | |
| D2 | SEL_CSB | I | SPI | Chip select | 2-wire | Slave address select | С | | | |
| E4 | SDA_SI | I/O | SPI | Serial data input | 2-wire | Serial data in-out | С | | | |
| E3 | SCL_SCK | I | SPI | Serial clock input | 2-wire | Serial clock input | С | | | |
| E2 | EDA | I/O | EEPRO | EEPROM SDA | | | | | | |
| E1 | ECL | 0 | EEPRO | EEPROM SCL | | | | | | |

- 1. Please use 1.0µF capacitors between AVDD and DVDD to GND, and leave PVDD terminal open.
- 2. If DVDD_EXT="H", the DVDD pin can be connected to an external 1.8V power source.
- 3. Please pull up the ECL, EDA, and INT pins using 10k ohm resistors as shown in the application diagram at the end of this document. ECL and EDA pins may be directly connected to GND if an external EEPROM is not being used. Please connect a 0.1µF capacitor between T4 and GND. T1, T2 & T3 pins should be connected to GND.
- 4. When using the 2 wire serial interface, please pull up the SCL_SCK, SDA_SI pins via 10k ohms and leave SO unconnected.
- 5. Please note that the values of resistors and capacitors mentioned here are only recommended values.
- 6. RSTB should be held low until supply voltage VDD has ramped up and has reached a stable level.
- 7. The polarity of INT pin is programmable via register 0x30.
- 8. Connect CLK_EXT to GND for normal use.
- 9. INT terminal is used as input pin in test mode.

Pin Configuration and Pin Description - continued





TOP VIEW (LEAD SIDE DOWN)

BOTTOM VIEW (LEAD SIDE UP)

| | Pin name | I/O | | Fı | ınction | | Figure | | |
|-----|----------|------|-----------|---|-----------|----------------------|--------|--|--|
| No. | | ., 0 | | | | | | | |
| 1 | NC | - | | - | | | | | |
| 2 | NC | - | | | - | | - | | |
| 3 | NC | - | | | - | | - | | |
| 4 | YN | I/O | Screen | interface | | | E | | |
| 5 | XN | I/O | Screen | interface | | | E | | |
| 6 | YP | I/O | Screen | interface | | | E | | |
| 7 | XP | I/O | Screen | interface | | | E | | |
| 8 | T4 | I/O | Test pir | | | | E | | |
| 9 | PVDD | 0 | Regulat | or output (for supply screen | voltage) | | - | | |
| 10 | AVDD | 0 | Regulat | or output (for supply analog | block) | | - | | |
| 11 | DVDD | I/O | Regulat | Regulator output (for supply digital block) or supply digital voltage | | | | | |
| 12 | DVDD_EXT | I | Digital v | igital voltage enable (H=Hi-Z , L=DVDD enable) | | | | | |
| 13 | VDD | - | Supply | Supply voltage | | | | | |
| 14 | VSS | - | Ground | Ground | | | | | |
| 15 | RSTB | I | H/W res | H/W reset | | | | | |
| 16 | CLK_EXT | I | Supply | external clock for debug | | | Α | | |
| 17 | T1 | I | Test pir | | | | Α | | |
| 18 | T2 | I | Test pir | | | | Α | | |
| 19 | T3 | I | Test pir | | | | Α | | |
| 20 | IFSEL | I | Interfac | e select pin (L=SPI, H=2-wi | e serial) | | Α | | |
| 21 | SO | 0 | SPI | Serial data output | 2-wire | - | F | | |
| 22 | INT | 0 | Interrup | t output | | 1 | С | | |
| 23 | SEL_CSB | - | SPI | Chip select | 2-wire | Slave address select | С | | |
| 24 | SDA_SI | I/O | SPI | Serial data input | 2-wire | Serial data in-out | С | | |
| 25 | SCL_SCK | | SPI | Serial clock input | 2-wire | Serial clock input | С | | |
| 26 | EDA | I/O | EEPRO | M SDA | 1 | 1 | С | | |
| 27 | ECL | 0 | EEPRO | M SCL | | | С | | |
| 28 | NC | - | | | - | | - | | |
| | 1 | | 1 | | | | 1 | | |

- 1. Please use 1.0µF capacitors between AVDD and DVDD to GND, and leave PVDD terminal open.
- 2. If DVDD_EXT="H", the DVDD pin can be connected to an external 1.8V power source.
- 3. Please pull up the ECL, EDA, and INT pins using 10k ohm resistors as shown in the application diagram at the end of this document. ECL and EDA pins may be directly connected to GND if an external EEPROM is not being used. Please connect a 0.1µF capacitor between T4 and GND. T1, T2 & T3 pins should be connected to GND.
- 4. When using the 2 wire serial interface, please pull up the SCL_SCK, SDA_SI pins via 10k ohms and leave SO unconnected.
- 5. Please note that the values of resistors and capacitors mentioned here are only recommended values.
- 6. RSTB should be held low until supply voltage VDD has ramped up and has reached a stable level.
- 7. The polarity of INT pin is programmable via register 0x30.
- 8. Connect CLK_EXT to GND for normal use.
- 9. INT terminal is used as input pin in test mode.
- 10. Unconnected NC terminals.
- 11. Please connect thermal PAD (Exposed PAD) to GND.

I/O equivalence circuit

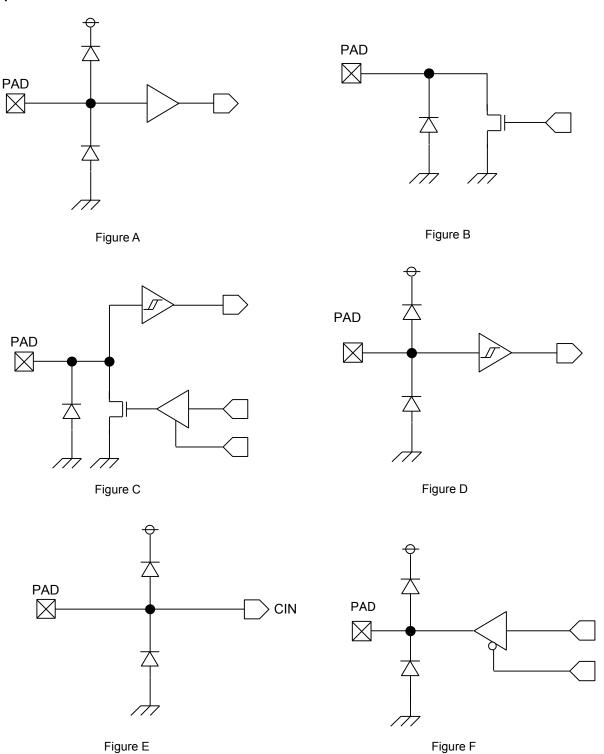
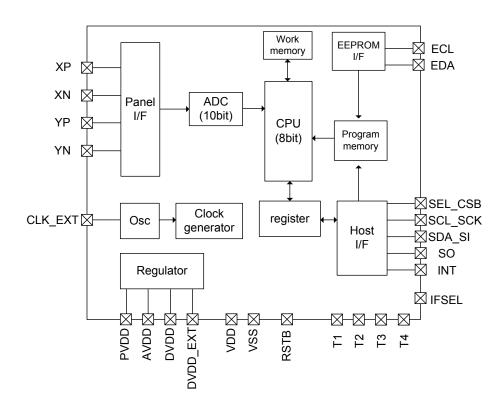


Figure BU21023GUL / BU21023MUV I/O Equivalent Circuit

Block Diagram and Description of each Block

【BU21023GUL / BU21023MUV】



| Screen I/F | 4-wire resistive touch screen interface |
|-----------------|---|
| ADC | 10-bit A/D converter |
| osc | Internal 20MHz oscillator block with optional external clock input |
| Regulator | Internal regulator provides 1.8V DVDD supply. DVDD can also be supplied from an external source if DVDD_EXT pin is tied high. |
| Clock Generator | System clock and timing generation (10MHz CPU clock) |
| CPU Core | For dual touch processing, programmability and HOST interface |
| Work Memory | Data memory for CPU |
| Program Memory | Program memory for CPU. Code can be downloaded by HOST processor or from an external EEPROM |
| EEPROM I/F | To connect to external EEPROM when downloading program memory from EEPROM. Use of external EEPROM is optional. |
| Host I/F | 4-wire SPI or 2-wire serial interface provides access to registers |

Absolute Maximum Ratings

| Tato maximum ratingo | | | | | | | | |
|------------------------------|------------|-----------------|------------------------------|------|------------|--|--|--|
| Param | eter | Symbol | Rating | Unit | Conditions | | | |
| Power Supply Voltage | | V_{DD} | V _{DD} -0.3 to +4.5 | | | | | |
| Input Voltage | | V _{IN} | -0.3 to V _{DD} +0.3 | ٧ | | | | |
| Rower Discinction | BU21023GUL | Pd | 0.83 ^(Note 1) | W | | | | |
| Power Dissipation BU21023MUV | | Fu | 0.70 ^(Note 2) | W | | | | |
| Storage Temperature Range | | Tstg | -50 to +125 | °C | | | | |

⁽Note1) Derate by 8.30 mW /°C centigrade when ambient temperature exceeds 25°C. Measured using PCB measuring 50mm x58mm.

Recommended Operating Conditions

| Parameter | Symbol | | Rating | | Unit | Conditions | |
|-----------------------------|----------|-------------|--------|------|-------|------------|--|
| Parameter | Symbol | Min Typ Max | | Max | Offic | Conditions | |
| Power Supply Voltage | V_{DD} | 2.70 | 3.00 | 3.60 | V | | |
| Digital Core Power Supply | DV_DD | 1.62 | 1.80 | 1.98 | V | DVDD_EXT=H | |
| Operating Temperature Range | Topr | -20 | +25 | +85 | °C | | |

Note: The BU21023 controllers can be operated with a single 3V V_{DD} supply.

Electrical Characteristics (Ta=25°C, V_{DD}=3.00V)

| Parameter | Symbol | | Limit | | Unit | Conditions |
|----------------------------------|------------------|----------------------|-----------|----------------------|-------|-------------|
| Farameter | Syllibol | Min | Тур | Max | Offic | Conditions |
| Low-Level Input Voltage | V _{IL} | -0.5 | - | $0.2xV_{DD}$ | ٧ | |
| High-Level Input Voltage | V _{IH} | 0.8xV _{DD} | - | V _{DD} +0.5 | V | |
| Low-Level Output Voltage | V _{OL} | - | - | 0.4 | ٧ | |
| High-Level Output Voltage | V _{OH} | V _{DD} -0.4 | - | - | > | |
| Standby Current | I _{ST} | - | - | 1 | μΑ | RSTB=L |
| Sleep Current1 | I _{CC1} | - | 60 | 100 | μΑ | DVDD_EXT =L |
| Sleep Current2 | I _{CC2} | - | 10 | 20 | μΑ | DVDD_EXT =H |
| Operating Current | I _{DD} | - | 4 | 6 | mA | No Load |
| Oscillation Frequency | Freq | 18 | 20 | 22 | MHz | |
| Resolution | Ad | | 1024x1024 | | Bit | |
| Differential Non-Linearity Error | DNL | -3.0 | - | +3.0 | LSB | |
| Integral Non-Linearity Error | INL | -3.0 | - | +3.0 | LSB | |

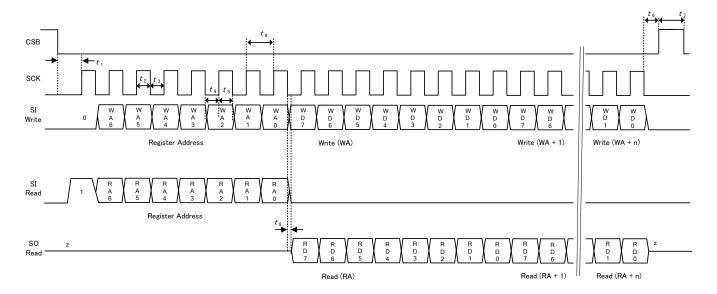
⁽Note 2) Derate by 7.04mW /°C centigrade when ambient temperature exceeds 25°C. Measured using PCB(1 layer) measuring 74.2x74.2x1.6t mm

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

It is also possible to supply 1.8V DV_{DD} from an external source if the DVDD_EXT pin is connected to logic high.

HOST-I/F mode (4-wire SPI)

(SCK=SCL_SCK, SI=SDA_SI, CSB=SEL_CSB, SO=SO)



Condition: V_{DD} = 3.0V Ta=25°C

| Parameter | Cymbal | | Limit | | Linit | Conditions |
|------------------------|----------------|-----|-------|-----|-------|------------|
| Parameter | Symbol | Min | Тур | Max | Unit | Conditions |
| CSB Setup Time | t ₁ | 30 | - | - | ns | |
| SCK "H" Level Period | t ₂ | 30 | - | - | ns | |
| SCK "L" Level Period | t ₃ | 30 | - | - | ns | |
| SI Setup Time | t ₄ | 20 | - | - | ns | |
| SI Holding Time | t ₅ | 20 | - | - | ns | |
| CSB Holding Time | t ₆ | 20 | - | - | ns | |
| CSB "H" Level Time | t ₇ | 50 | - | - | ns | |
| Data Output Delay Time | t ₈ | - | - | 15 | ns | |
| SCK Frequency | t ₉ | - | - | 15 | MHz | |

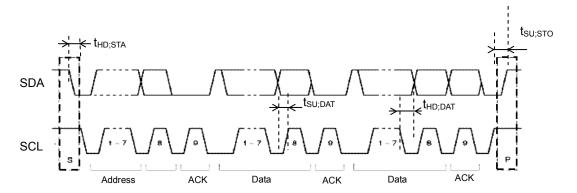
Note: SPI interface is selected by tying IFSEL pin to logic low. IFSEL= logic high selects the 2-wire Interface

HOST-I/F mode (2-wire serial)

(SCL=SCL_SCK, SDA=SDA_SI)

The 2-wire serial mode presents an I^2C interface for all practical purposes, but it is not a complete implementation conforming to the I^2C specification. BU21023MUV/BU21023GUL devices can co-exist with other I^2C devices on the same bus. The slave address for 2-wire serial communication is 5Ch or 5Dh. This is determined by the SEL_CSB pin.

SEL_CSB = "L" : Slave address = 5Ch SEL_CSB = "H" : Slave address = 5Dh



Condition: V_{DD} = 3.0V Ta=25°C

| Parameter | Symbol | | Limit | | Linit | Conditions |
|---------------------------|---------------------|-----|-------|-----|-------|------------|
| Parameter | Symbol | Min | Тур | Max | Unit | Conditions |
| SCL Clock Frequency | f _{SCL} | 0 | - | 400 | kHz | |
| START Condition Hold Time | t _{HD:STA} | 0.6 | - | - | μs | |
| SCL "L" | t _{LOW} | 1.3 | - | - | μs | |
| SCL "H" | t _{HIGH} | 0.6 | - | - | μs | |
| Data Hold Time | t _{HD:DAT} | 0.1 | - | - | μs | |
| Data Setup Time | t _{SU:DAT} | 0.1 | - | - | μs | |
| STOP Condition Setup Time | tsu:sto | 0.6 | - | - | μs | |

·Write protocol

| S | SLAVE ADDRESS | W A | REGISTER ADDRESS | Α | WRITE DATA | Α | Р |
|---|-------------------|----------|------------------|---|------------|---|---|
| | 7bit = 5Ch or 5Dh | <u> </u> | 8bit | | | | |

·Read protocol

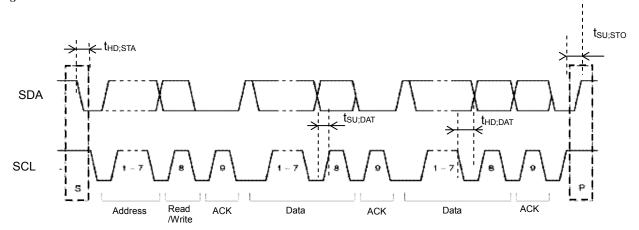
| S | SLAVE ADDRESS | W | Α | REGISTER ADDRESS | Α | S | SLAVE ADDRESS | R | Α | READ DATA | N P |
|---|-------------------|------|------|------------------|---|---|-------------------------|-----|-------|-----------|-----|
| | 7bit = 5Ch or 5Dh | | | 8bit | | | 7bit = 5Ch or 5Dh | | | 8bit | |
| | | fron | n Ma | aster to Slave | | S | = START condition | | | | |
| | | fron | n Sl | ave to Master | | Р | = STOP condition | | | | |
| | | • | | | | R | = data direction READ (| (SD | A HI | GH) | |
| | | | | | | W | = data direction WRITE | (SI | DA LO | OW) | |
| | | | | | | Α | = acknowledge (SDA Lo | WC |) | | |
| | | | | | | Ν | = not acknowledge (SD | ΑH | IIGH) | | |

EEPROM I/F

(SCL=ECL, SDA=EDA)

BU21023 controllers include an EEPROM interface for firmware download. Device address of EEPROM is set via register 0x51(EEPROM_ADDR).

Timing Chart



Condition: V_{DD} = 3.0V Ta=25°C

| Condition: V _{DD} = 3.0V Ta=25 C | | | Limit | | | Condition |
|---|---------------------|-----|-------|-----|------|-----------|
| Parameter | Symbol | Min | Тур | Max | Unit | Condition |
| SCL Clock Frequency | f _{SCL} | 270 | 310 | 350 | kHz | |
| START Hold Time | t _{HD:STA} | 0.7 | - | 0.9 | μs | |
| SCL "L" Width | t _{LOW} | 1.4 | - | 1.8 | μs | |
| SCL "H" Width | t _{HIGH} | 1.4 | - | 1.8 | μs | |
| Data Hold Time | t _{HD:DAT} | 0.7 | - | 0.9 | μs | |
| Data Setup Time | t _{SU:DAT} | 0.7 | - | 0.9 | μs | |
| STOP Setup Time | t _{su:sto} | 0.7 | - | 0.9 | μs | |

Protocol

Start

| s | SLAVE ADDRESS | WA | WORD ADDRESS(n) | Α | S | SLAVE ADDRESS | R | Α | READ DATA(n) | N | Р | |
|---|---------------|----|-----------------|---|---|---------------|---|---|--------------|---|---|--|
|---|---------------|----|-----------------|---|---|---------------|---|---|--------------|---|---|--|

Stop

^{*}IC does not support the write command.

^{*}IC supports the following read command.

Background Information

A resistive touch screen is made up of multiple layers of sandwiched resistive films and protective coatings all sitting on top of an LCD display. Resistive touch screens work by direct contact of a stylus or a finger flexing a pair of resistive films, hence any blunt pointing instrument or a gloved finger may be used.

Touch screen resolution

The resolution of a touch screen is typically measured in dots per inch (dpi) and is a function of the physical size of the touch screen and the ADC used in the conversion circuitry. For example, a 3.5 inch x 5 inch screen used with the BU21023 devices can provide a theoretical resolution of 1024 /5 = 204 dpi. In the case of resistive touch screens, the direct contact nature of its operation and finger thickness often impose an upper limit on the effective system resolution that may be achieved, regardless of the resolution of the ADC itself.

Description of Function

The BU21023 devices connect to a standard 4-wire resistive touch screen on one side and to a HOST processor on the other side. The BU21023 include the analog and digital circuitry to process and provide dual touch coordinate data and pinch, spread gesture information to the HOST.

The BU21023 devices include an internal CPU and provide a high degree of programmability by exposing a set of registers that can be accessed by a HOST through SPI or 2-wire serial interfaces. The IFSEL pin determines whether SPI or 2-wire serial interface is selected, The BU21023 devices include an INT pin whose polarity can be programmed via registers. When an interrupt occurs, for example, due to touch detection, the HOST processor is required to read an interrupt status register to determine the cause of the interrupt and take appropriate action.

The program memory of the internal CPU may be initialized via the HOST interface or via an external EEPROM. This is selected by a register setting.

The BU21023 devices support two sensing modes; continuous and interval sensing modes, that are register- selectable. In the continuous sensing mode, the embedded CPU reads Z, X & Y coordinates continuously when a touch is detected. The interval sensing mode allows a delay to be inserted between each cycle.

The BU21023 devices enable optimization of touch detection threshold for a given screen. They also include several sophisticated calibration algorithms.

Often, a description of the registers followed by flow charts requires application note to explain the steps in finer detail.

The application note also includes information on touch screen parameters that one should look for when selecting resistive touch screens for multi-touch.

Application Examples

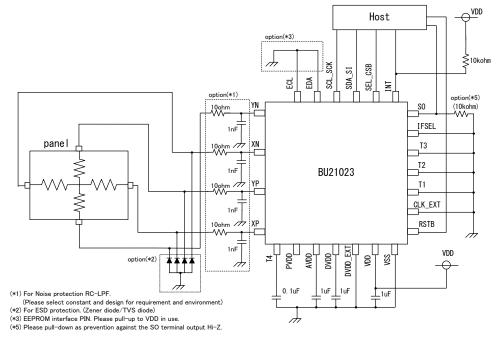
[BU21023GUL BU21023MUV]

BU21023GUL/MUV support 2 HOST interfaces (4-wire SPI and 2-wire serial bus).

The figures shown below are application circuits when each interface is used.

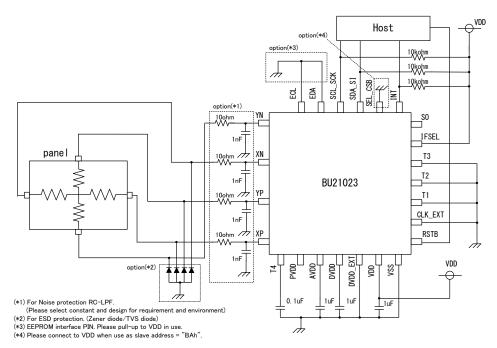
(Although BU21023GUL is CSP package, it is shown in similar figure for comparison.)

- *Please connect the terminal of ECL/EDA to GND when downloading the firmware from the HOST. ECL and EDA pins pull up to VDD if an external EEPROM is used. (example : $10k\Omega$)
- *Please insert TVS diode or Zener diode to each sensor line to enhance resistance to ESD.
- *Please pull up the INT terminal to VDD or HOST IO voltage (max 4.5V).
- *In the case of 4-wire SPI use, please pull down the SO terminal to GND. If not in use, connect it to the GND.



Example 1: BU21023GUL/MUV Application Circuit (4-wireSPI)

In the case of 2-wire serial interface use, please pull up the INT, SCL_SCK, SDA_SI terminal to VDD or HOST IO voltage(max4.5V).



Example 2: BU21023GUL/MUV Application Circuit (2-wire Serial bus)

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

Operational Notes - continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

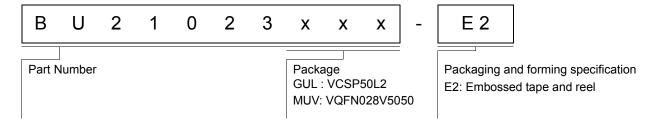
13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

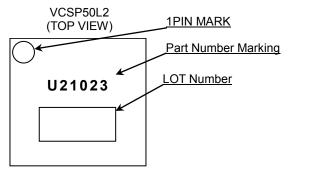
14. Others

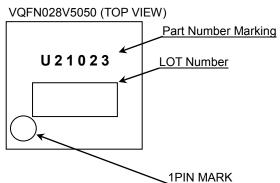
In case of use this IC, please peruse some other detail documents, we called Functional description, Application note.

Ordering Information



Marking Diagrams





Physical Dimension, Tape and Reel Information Package Name VCSP50L2 (BU21023GUL) 2.60 ± 0.05 0.1 ± 0.05 0.55MAX □ 0.06 S $24-\phi 0.25 \pm 0.05$ 0.3 ± 0.05 • 0.05 AB E D $P=0.5 \times 4$ $(\phi 0.15)$ INDEX POST В 0.3 ± 0.05 (Unit: mm) P=0.5 × 4 <Tape and Reel information> Embossed carrier tape Quantity 3000pcs Direction The direction is the 1pin of product is at the upper left when you hold of feed reel on the left hand and you pull out the tape on the right hand Direction of feed Reel *Order quantity needs to be multiple of the minimum quantity.

Physical Dimension, Tape and Reel Information - continued Package Name VQFN028V5050 (BU21023MUV) 5.0±0.1 000000 PIN MARK OMAX 0.08S 2.7±0.1 CO. 2 $\overline{00000}$ 28 22 \mathfrak{m} 21 15 0.25+0.05 (UNIT:mm) PKG: VQFN028V5050 Drawing No. EX473-5002-2 <Tape and Reel information> Таре Embossed carrier tape Quantity 2500pcs Direction (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand of feed Direction of feed Reel *Order quantity needs to be multiple of the minimum quantity.

Revision History

| vision History Date | Revision | Changes | | | |
|----------------------|----------|---|--|--|--|
| 07.Oct.2013 001 | | | | | |
| | | New Release | | | |
| 07.Feb.2014 | 002 | Remove the description of BU21024FV-M Added 3D package image | | | |
| 17.Mar.2014 | 003 | Change description p10 from "other document" to "application note". | | | |
| 7.June.2016 | 004 | P1 fix miss description Features (old) I ² C (new) 2-wire serial P1 fix miss description Key Specifications and Lineup (old) Pakage (new) Package P3 Add the description of the thermal PAD connection. P5 fix miss description (old) 2-wire I ² C (new) 2-wire serial P6 fix miss description PCB(1 layer) (old) 70x70x1.6mm ³ (new) 74.2x74.2x1.6t mm. P8 Add condition description (new) Condition: VDD = 3.0V Ta=25°C P9 Add condition description (new) Condition: VDD = 3.0V Ta=25°C P10 fix miss description (old) For example, a 3"x5" screen used (new) For example, a 3.5 inch x 5 inch screen used P10 fix miss description (old) I ² C (new) 2-wire serial P11 Application Examples Example 1: BU21023GUL/MUV Application Circuit (4-wireSPI) Add 1uF (VDD-VSS) as bypass capacitor. Change the circuit symbol of TVS diode. Add annotations. Example 2: BU21023GUL/MUV Application Circuit (2-wire Serial bus) Add 1uF (VDD-VSS) as bypass capacitor. Change the circuit symbol of TVS diode. Add annotations. | | | |

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| JAPAN | USA | EU | CHINA |
|---------|--------|------------|--------|
| CLASSⅢ | CLASSⅢ | CLASS II b | СГУССШ |
| CLASSIV | | CLASSⅢ | CLASSⅢ |

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- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
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- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

Precautions Regarding Application Examples and External Circuits

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 - [d] the Products are exposed to high Electrostatic
- Even under ROHM recommended storage condition, solderability of products out of recommended storage time period
 may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is
 exceeding the recommended storage time period.
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