# imall

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from, Europe, America and south Asia, supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts, Customers Priority, Honest Operation, and Considerate Service", our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip, ALPS, ROHM, Xilinx, Pulse, ON, Everlight and Freescale. Main products comprise IC, Modules, Potentiometer, IC Socket, Relay, Connector. Our parts cover such applications as commercial, industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





## CLC2011, CLC4011 Low Power, Low Cost, Rail-to-Rail I/O Amplifiers

### **General Description**

The CLC2011 (dual) and CLC4011 (quad) are ultra-low cost, low power, voltage feedback amplifiers. At 2.7V, the CLCx011 family uses only 136 $\mu$ A of supply current per amplifier and are designed to operate from a supply range of 2.5V to 5.5V (±1.25 to ±2.75). The input voltage range exceeds the negative and positive rails.

The CLCx011 family of amplifiers offer high bipolar performance at a low CMOS prices. They offer superior dynamic performance with 4.9MHz small signal bandwidths and  $5.3V/\mu s$  slew rates. The combination of low power, high bandwidth, and rail-to-rail performance make the CLCx011 amplifiers well suited for battery-powered communication/computing systems.

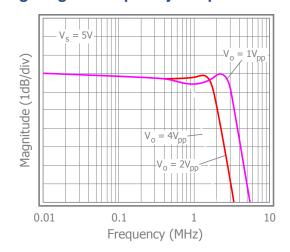
#### FEATURES

- 136µA supply current
- 4.9MHz bandwidth
- Output swings to within 20mV of either rail
- Input voltage range exceeds the rail by >250mV
- 5.3V/µs slew rate
- 21nV/√Hz input voltage noise
- ±35mA linear output current
- Fully specified at 2.7V and 5V supplies

#### APPLICATIONS

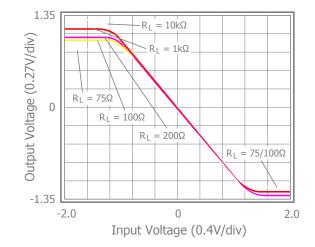
- Portable/battery-powered applications
- Mobile communications, cell phones, pagers
- ADC buffer
- Active filters
- Portable test instruments
- Notebooks and PDA's
- Signal conditioning
- Medical equipment
- Portable medical instrumentation

Ordering Information - back page



## Large Signal Frequency Response

## **Output Swing vs. Load**



## **Absolute Maximum Ratings**

Stresses beyond the limits listed below may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

V <sub>S</sub>	
V <sub>IN</sub>	
Continuous Output Current	40mA to +40mA

### **Operating Conditions**

Supply Voltage Range	2.5 to 5.5V
Operating Temperature Range	40°C to 125°C
Junction Temperature	150°C
Storage Temperature Range	65°C to 150°C
Lead Temperature (Soldering, 10s)	260°C

## **Package Thermal Resistance**

θ <sub>JA</sub> (SOIC-8)	150°C/W
θ <sub>JA</sub> (MSOP-8)	200°C/W
θ <sub>JA</sub> (SOIC-14)	90°C/W
θ <sub>JA</sub> (TSSOP-14)	100°C/W
Package thermal resistance ( $\theta_{JA}$ ), JEDEC stand test boards, still air.	ard, multi-layer

## **ESD Protection**

CLC2011, CLC4011 (HBM) .....2kV ESD Rating for HBM (Human Body Model).

## **Electrical Characteristics at +2.7V**

 $T_A$  = 25°C,  $V_S$  = +2.7V,  $R_f$  =  $R_g$  = 5k $\Omega,~R_L$  = 10k $\Omega$  to  $V_S/2;~G$  = 2; unless otherwise noted.

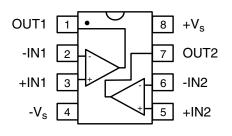
Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency I	Domain Response					
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	$G = +1, V_{OUT} = 0.02V_{pp}$		4.9		MHz
BW <sub>SS</sub>	-3dB Bandwidth	$G = +2, V_{OUT} = 0.2V_{pp}$		3.2		MHz
BW <sub>LS</sub>	Large Signal Bandwidth	$G = +2, V_{OUT} = 2V_{pp}$		1.4		MHz
GBWP	Gain Bandwidth Product	G = +11, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		2.5		MHz
Time Doma	in Response				-	•
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		163		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 1V step		500		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%
SR	Slew Rate	1V step		5.3		V/µs
Distortion/N	loise Response	÷	•			
HD2	2nd Harmonic Distortion	$10 \text{kHz}, \text{V}_{\text{OUT}} = 1 \text{V}_{\text{pp}}$		-72		dBc
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = $1$ V <sub>pp</sub>		-72		dBc
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = $1$ V <sub>pp</sub>		0.03		%
e <sub>n</sub>	Input Voltage Noise	>10kHz		21		nV/√Hz
X	Oracatalla	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB
DC Perform	ance					•
V <sub>IO</sub>	Input Offset Voltage			0.5		mV
d <sub>VIO</sub>	Average Drift			5		μV/°C
I <sub>B</sub>	Input Bias Current			90		nA
dl <sub>B</sub>	Average Drift			32		pA/°C
PSRR	Power Supply Rejection Ratio	DC	55	83		dB
A <sub>OL</sub>	Open Loop Gain	$V_{OUT} = V_S / 2$		90		dB
I <sub>S</sub>	Supply Current	per channel		136		μA
Input Chara	cteristics					
R <sub>IN</sub>	Input Resistance	Non-inverting		12		ΜΩ
C <sub>IN</sub>	Input Capacitance			2		pF
CMIR	Common Mode Input Range			-0.25 to 2.95		V
CMRR	Common Mode Rejection Ratio	DC		81		dB
Output Cha	racteristics					
		$R_L = 10k\Omega$ to $V_S / 2$		0.02 to 2.68		V
V <sub>OUT</sub>	Output Voltage Swing	$R_L = 1k\Omega$ to $V_S / 2$		0.05 to 2.63		V
		$R_L$ = 200 $\Omega$ to $V_S$ / 2		0.11 to 2.52		V
I <sub>OUT</sub>	Output Current			±30		mA

## **Electrical Characteristics at +5V**

 $T_A$  = 25°C,  $V_S$  = +5V,  $R_f$  =  $R_g$  = 5k $\Omega$ ,  $R_L$  = 10k $\Omega$  to  $V_S/2;$  G = 2; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency I	Domain Response					
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	$G = +1, V_{OUT} = 0.02V_{pp}$		4.3		MHz
BW <sub>SS</sub>	-3dB Bandwidth	$G = +2, V_{OUT} = 0.2V_{pp}$				MHz
BW <sub>LS</sub>	Large Signal Bandwidth	$G = +2$ , $V_{OUT} = 2V_{pp}$		2.3		MHz
GBWP	Gain Bandwidth Product	$G = +11, V_{OUT} = 0.2V_{pp}$		2.5		MHz
Time Doma	in Response					,
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		110		ns
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 2V step		470		ns
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%
SR	Slew Rate	2V step		9		V/µs
Distortion/N	loise Response					,
HD2	2nd Harmonic Distortion	10kHz, V <sub>OUT</sub> = $1$ V <sub>pp</sub>		-73		dBc
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = $1$ V <sub>pp</sub>		-75		dBc
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = $1$ V <sub>pp</sub>		0.03		%
e <sub>n</sub>	Input Voltage Noise	>10kHz		22		nV/√Hz
V	Questally	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB
DC Perform	ance					
V <sub>IO</sub>	Input Offset Voltage		-8	1.5	8	mV
d <sub>VIO</sub>	Average Drift			15		μV/°C
I <sub>B</sub>	Input Bias Current			90	450	nA
dl <sub>B</sub>	Average Drift			40		pA/°C
PSRR	Power Supply Rejection Ratio	DC	55	85		dB
A <sub>OL</sub>	Open Loop Gain	$V_{OUT} = V_S / 2$		80		dB
I <sub>S</sub>	Supply Current	per channel		160	235	μΑ
Input Chara	cteristics					
R <sub>IN</sub>	Input Resistance	Non-inverting		12		ΜΩ
C <sub>IN</sub>	Input Capacitance			2		pF
CMIR	Common Mode Input Range			-0.25 to 5.25		V
CMRR	Common Mode Rejection Ratio	DC	58	80		dB
Output Cha	racteristics	· ·				
		$R_L = 10k\Omega$ to $V_S / 2$	0.08 to 4.92	0.04 to 4.96		V
V <sub>OUT</sub> Output Voltage Swing	Output Voltage Swing	$R_L = 1k\Omega$ to $V_S / 2$		0.07 to 4.9		V
		$R_L$ = 200 $\Omega$ to $V_S$ / 2		0.14 to 4.67		V
I <sub>OUT</sub>	Output Current			±35		mA

## CLC2011 Pin Configurations SOIC-8 / MSOP-8

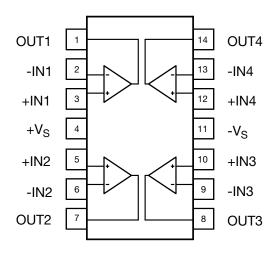


## **CLC2011 Pin Assignments**

## SOIC-8 / MSOP-8

Pin No.	Pin Name	Description			
1	OUT1	Output, channel 1			
2	-IN1	Negative input, channel 1			
3	+IN1	Positive input, channel 1			
4	-V <sub>S</sub>	Negative supply			
5	+IN2	Positive input, channel 2			
6	-IN2	Negative input, channel 2			
7	OUT2	Output, channel 2			
8	+V <sub>S</sub>	Positive supply			

## CLC4011 Pin Configuration SOIC-14 / TSSOP-14



## **CLC4011 Pin Assignments**

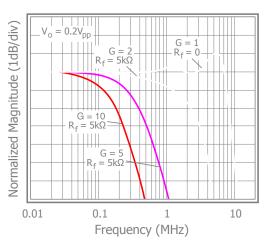
#### SOIC-14 / TSSOP-14

Pin No.	Pin Name	Description
1	OUT1	Output, channel 1
2	-IN1	Negative input, channel 1
3	+IN1	Positive input, channel 1
4	+V <sub>S</sub>	Positive supply
5	+IN2	Positive input, channel 2
6	-IN2	Negative input, channel 2
7	OUT2	Output, channel 2
8	OUT3	Output, channel 3
9	-IN3	Negative input, channel 3
10	+IN3	Positive input, channel 3
11	-V <sub>S</sub>	Negative supply
12	+IN4	Positive input, channel 4
13	-IN4	Negative input, channel 4
14	OUT4	Output, channel 4

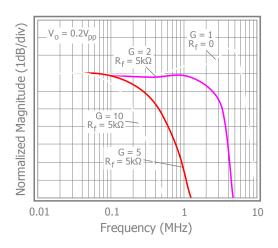
## **Typical Performance Characteristics**

 $T_A = 25^{\circ}C$ ,  $V_S = +2.7V$ ,  $R_f = R_g = 5k\Omega$ ,  $R_L = 10k\Omega$  to  $V_S/2$ ; G = 2; unless otherwise noted.

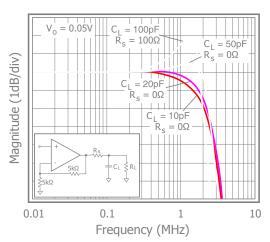
Non-Inverting Frequency Response at  $V_S = 5V$ 



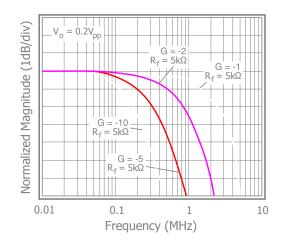
#### Non-Inverting Frequency Response at $V_S = 2.7V$



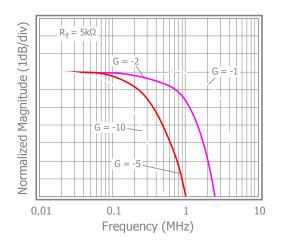
Frequency Response vs CL



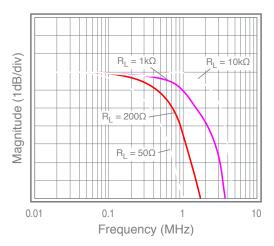
#### Inverting Frequency Response at $V_S = 5V$



#### Inverting Frequency Response at V<sub>S</sub> = 2.7V



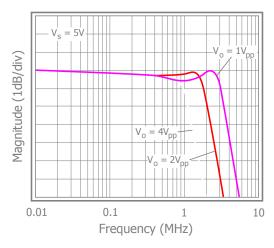




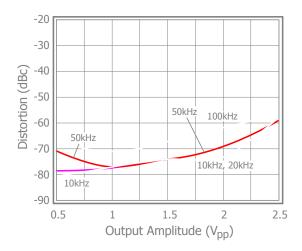
## **Typical Performance Characteristics**

 $T_A = 25^{\circ}C$ ,  $V_S = +2.7V$ ,  $R_f = R_g = 5k\Omega$ ,  $R_L = 10k\Omega$  to  $V_S/2$ ; G = 2; unless otherwise noted.

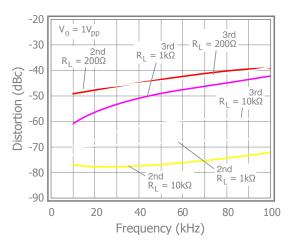
Frequency Response vs. V<sub>OUT</sub>



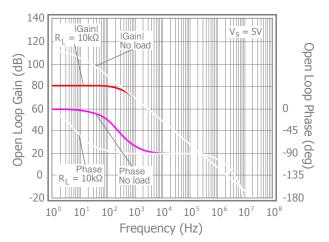
#### 2nd Harmonic Distortion vs $V_{OUT}$



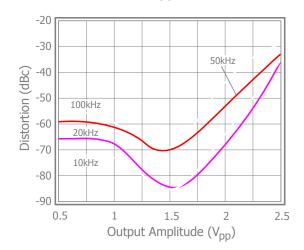
2nd & 3rd Harmonic Distortion at  $V_S = 2.7V$ 



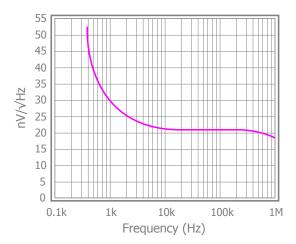
#### Open Loop Gain & Phase vs. Frequency



3rd Harmonic Distortion vs VOUT



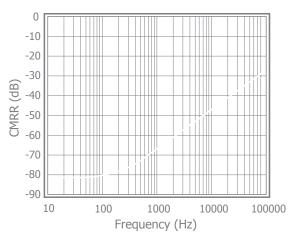
Input Voltage Noise



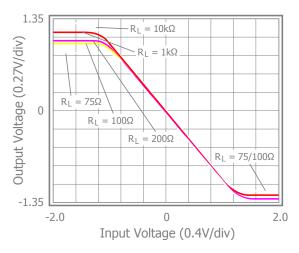
## **Typical Performance Characteristics**

 $T_A = 25^{\circ}C$ ,  $V_S = +2.7V$ ,  $R_f = R_g = 5k\Omega$ ,  $R_L = 10k\Omega$  to  $V_S/2$ ; G = 2; unless otherwise noted.

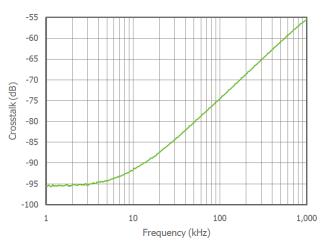
#### CMRR



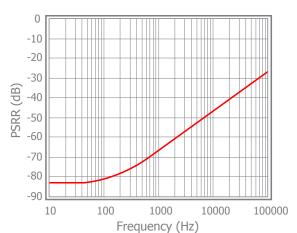
Output Swing vs. Load



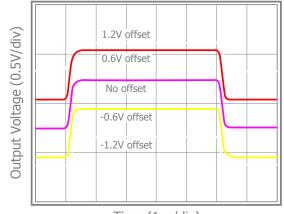








#### Pulse Response vs. Common Mode Voltage



Time (1µs/div)

## **Application Information**

#### **General Description**

The CLCx011 family of amplifiers are single supply, general purpose, voltage-feedback amplifiers. They are fabricated on a complimentary bipolar process, feature a rail-to-rail input and output, and are unity gain stable.

#### **Basic Operation**

Figures 1, 2, and 3 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applications.

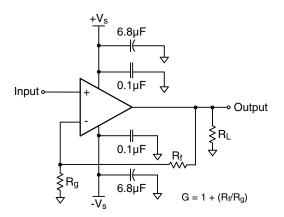


Figure 1: Typical Non-Inverting Gain Circuit

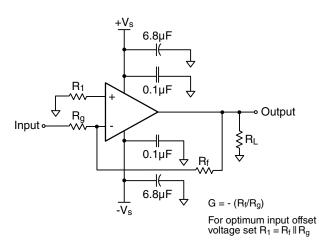


Figure 2: Typical Inverting Gain Circuit

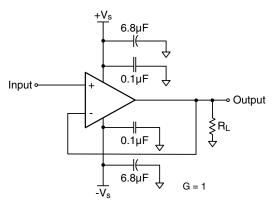


Figure 3: Unity Gain Circuit

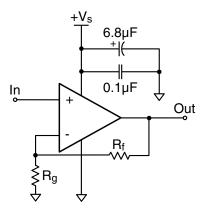


Figure 4: Single Supply Non-Inverting Gain Circuit

#### **Power Dissipation**

Power dissipation should not be a factor when operating under the stated  $10k\Omega$  load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond it's intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value Theta<sub>JA</sub> ( $\theta_{JA}$ ) is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\theta_{JA} \times P_D)$$

Where  $\mathsf{T}_{\mathsf{Ambient}}$  is the temperature of the working environment.

In order to determine  $P_D$ , the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{supply} - P_{load}$$

Supply power is calculated by the standard power equation.

$$P_{supply} = V_{supply} \times I_{RMSsupply}$$
$$V_{supply} = V_{S+} - V_{S-}$$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{load})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rload<sub>eff</sub>) will need to include the effect of the feedback network. For instance, Rload<sub>eff</sub> in Figure 3 would be calculated as:

$$R_L \parallel (R_f + R_g)$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here,  $P_D$  can be found from

$$P_D = P_{Quiescent} + P_{Dynamic} - P_{load}$$

Quiescent power can be derived from the specified  $I_S$  values along with known supply voltage,  $V_{supply}$ . Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{load})_{RMS} = V_{peak} / \sqrt{2}$$

$$(I_{load})_{RMS} = (V_{load})_{RMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{Dynamic} = (V_{S+} - V_{load})_{RMS} \times (I_{load})_{RMS}$$

Assuming the load is referenced in the middle of the power rails or  $V_{\mbox{supply}}/2.$ 

The CLC2011 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions. Figure 5 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

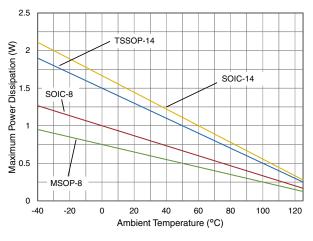


Figure 5. Maximum Power Derating

#### Input Common Mode Voltage

The common mode input range extends to 250mV below ground and to 250mV above Vs, in single supply operation. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition. If the absolute maximum input voltage (700mV beyond either rail) is exceeded, externally limit the input current to  $\pm$ 5mA as shown in Figure 6.

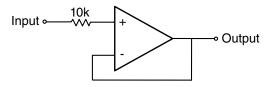


Figure 6. Circuit for Input Current Protection

#### **Driving Capacitive Loads**

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance,  $R_S$ , between the amplifier and the load to help improve stability and settling performance. Refer to Figure 7.

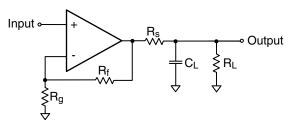


Figure 7. Addition of R<sub>S</sub> for Driving Capacitive Loads

Table 1 provides the recommended  $R_S$  for various capacitive loads. The recommended  $R_S$  values result in approximately <1dB peaking in the frequency response. The Frequency Response vs. CL plot, on page 6, illustrates the response of the CLCx011.

C <sub>L</sub> (pF)	R <sub>S</sub> (Ω)	-3dB BW (MHz)
10pF	0	2.2
20pF	0	2.4
50pF	0	2.5
100pF	100	2

Table 1: Recommended R<sub>S</sub> vs. C<sub>L</sub>

For a given load capacitance, adjust  ${\sf R}_S$  to optimize the tradeoff between settling time and bandwidth. In general, reducing  ${\sf R}_S$  will increase bandwidth at the expense of additional overshoot and ringing.

#### **Overdrive Recovery**

An overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies, based on whether the input or output is overdriven and by how much the range is exceeded. The CLCx011 will typically recover in less than 50ns from an overdrive condition. Figure 8 shows the CLC2011 in an overdriven condition.

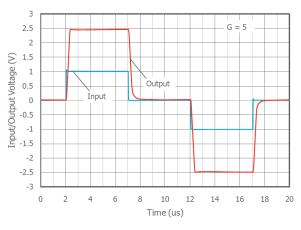


Figure 8: Overdrive Recovery

#### **Layout Considerations**

General layout and supply bypassing play major roles in high frequency performance. Exar has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8µF and 0.1µF ceramic capacitors for power supply decoupling
- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

#### **Evaluation Board Information**

The following evaluation boards are available to aid in the testing and layout of these devices:

Evaluation Board #	Products
CEB006	CLC2011 in SOIC
CEB010	CLC2011 in MSOP
CEB019	CLC4011 in TSSOP
CEB018	CLC4011 in SOIC

#### **Evaluation Board Schematics**

Evaluation board schematics and layouts are shown in Figures 9-16 These evaluation boards are built for dualsupply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -V $_{\rm S}$  to ground.
- 2. Use C3 and C4, if the  $-V_S$  pin of the amplifier is not directly connected to the ground plane.

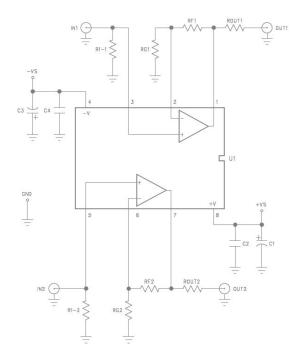


Figure 9. CEB006 & CEB010 Schematic

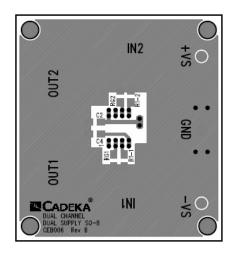


Figure 10. CEB006 Top View

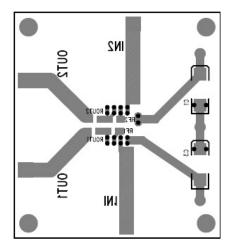


Figure 11. CEB006 Bottom View

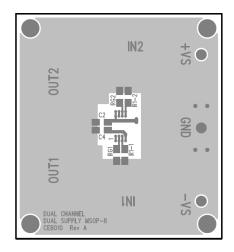


Figure 12. CEB010 Top View

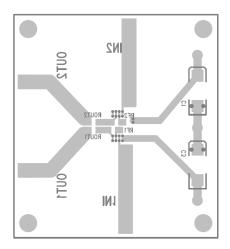
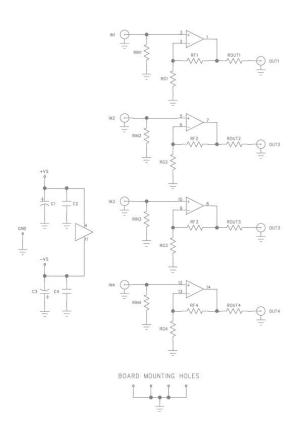


Figure 13. CEB010 Bottom View



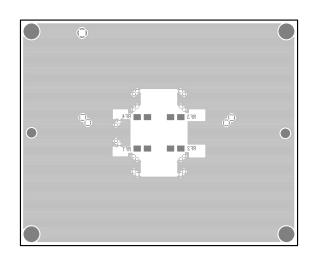


Figure 16. CEB018 Bottom View

Figure 14. CEB018 Schematic

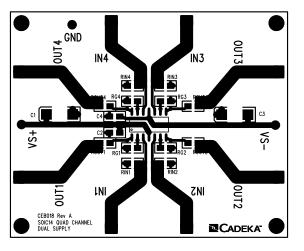
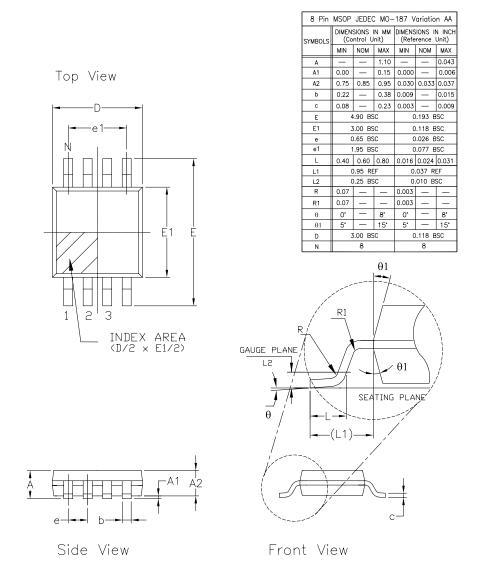


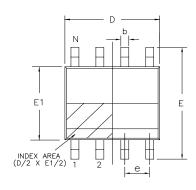
Figure 15. CEB018 Top View

## Mechanical Dimensions MSOP-8

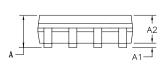


## **Mechanical Dimensions**

## SOIC-8 Package



Top View





2

RECOMMENDED PCB LAND PATTERN

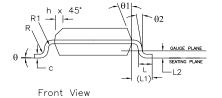
0.53mm

-

4.93mm

Ν

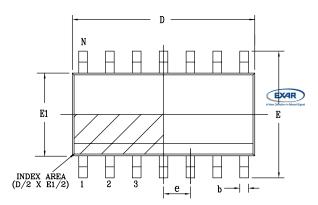
1.98mm



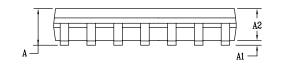
1.27mm

Side View

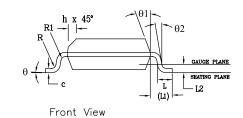
### **SOIC-14 Package**



Top View



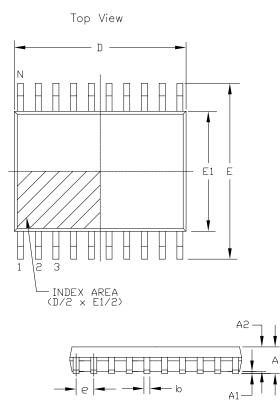
Side View

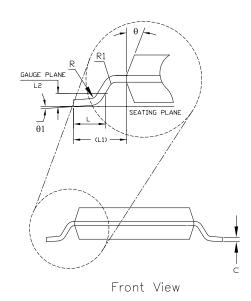


8 Pin SOICN JEDEC MS-012 Variation AA									
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)					
	MIN	NOM	MAX	MIN	NOM	MAX			
A	1.35	—	1.75	0.053	—	0.069			
A1	0.10	—	0.25	0.004	—	0.010			
A2	1.25	—	1.65	0.049	—	0.065			
b	0.31	—	0.51	0.012	—	0.020			
с	0.17	—	0.25	0.007	_	0.010			
E	6	5.00 BSC	)	C	.236 BS	С			
E1		3.90 BSC	)	0.154 BSC					
е		1.27 BSC	2	0.050 BSC					
h	0.25	_	0.50	0.010	—	0.020			
L	0.40	—	1.27	0.016	—	0.050			
L1		1.04 REF	-	0	.041 REF	-			
L2	0.25 BSC			0	.010 BS(	2			
R	0.07	—	—	0.003	—	—			
R1	0.07	—	_	0.003	_	—			
θ	0*	—	8°	0*		8'			
θ1	5°	_	15°	5°	_	15°			
θ2	0°	_	_	0°	_	_			
D	4	4.90 BSC	;	0.193 BSC					
N		8			8				

PACKAGE OUTLINE NSOIC .150" BODY JEDEC MS-012							
SYMBO	YMBOLS COMMON DIMENSIONS IN MI				COMMON (Refer		
		MIN	NOM	MAX	MIN	NOM	MAX
A		1.35	—	1.75	0.053	-	0.069
A1		0.10	—	0.25	0.004	_	0.010
A2		1.25	—	1.65	0.049	—	0.065
b		0.31	—	0.51	0.012	_	0.020
с		0.17	—	0.25	0.007	—	0.010
Ε			6.00 BSC	;	C	.236 BS	iC
E1			3.90 BSC	;	C	.154 BS	C
е			1.27 BSC	)	C	.050 BS	C
h		0.25	—	0.50	0.010	_	0.020
L		0.40		1.27	0.016		0.050
L1			1.04 REF			.041 RE	
L2			0.25 BSC	2	0.010 BSC		
R		0.07	—	_	0.003	—	—
R1		0.07	—	—	0.003	—	—
θ		0.	—	8'	0.	—	8'
θ1		5'	—	15	5*	_	15
02		0"	—	—	0.	—	—
D				SEE VARI			
N			S	SEE VARI	ATIONS		
			VA	RIATION			
VARIATIONS	[	DIMENSIONS IN MM (Control Unit) DIMENSIONS IN INCH (Reference Unit)					N
SNO	MI	N NO	M MAX	X MIN	NOM	MAX	
AA		4.90	BSC		0.193 BSC		8
AB		8.65 BSC 0.341 BSC				14	
AC		9.90 BSC 0.390 BSC 16					16

#### **TSSOP-14 Package**





Side View

14	14 Pin TSSOP JEDEC MO-153 Variation AB-1							
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)				
	MIN	NOM	MAX	MIN	NOM	MAX		
А	—	—	1.20	—		0.047		
A1	0.05	_	0.15	0.002	_	0.006		
A2	0.80	1.00	1.05	0.031	0.039	0.041		
b	0.19	—	0.30	0.007	_	0.012		
с	0.09	—	0.20	0.004	_	0.008		
E	6	.40 BS	С	0.252 BSC				
E1	4.30	4.40	4.50	0.169	0.173	0.177		
е	C	.65 BS	C	0.026 BSC				
L	0.45	0.60	0.75	0.018	0.024	0.030		
L1	1	.00 RE	F	0	.039 R	EF		
L2	0	).25 BS	SC	0	010 B	SC		
R	0.09	—	_	0.035		—		
R1	0.09	—	_	0.035	—	—		
θ	12" REF				2° RE	F		
θ1	0*	_	8'	0.	_	8*		
D	4.90	5.00	5.10	0.193	0.197	0.200		
N		14			14			

А

## **Ordering Information**

Part Number	Package	Green	Operating Temperature Range	Packaging
CLC2011 Ordering Information	on			
CLC2011ISO8X	SOIC-8	Yes	-40°C to +125°C	Tape & Reel
CLC2011ISO8MTR	SOIC-8	Yes	-40°C to +125°C	Mini Tape & Reel
CLC2011ISO8EVB	Evaluation Board	N/A	N/A	N/A
CLC2011IMP8X	MSOP-8	Yes	-40°C to +125°C	Tape & Reel
CLC2011IMP8MTR	MSOP-8	Yes	-40°C to +125°C	Mini Tape & Reel
CLC2011IMP8EVB	Evaluation Board	N/A	N/A	N/A
CLC4011 Ordering Information	on .			
CLC4011ISO14X	SOIC-14	Yes	-40°C to +125°C	Tape & Reel
CLC4011ISO14MTR	SOIC-14	Yes	-40°C to +125°C	Mini Tape & Reel
CLC4011ISO14EVB	Evaluation Board	N/A	N/A	N/A
CLC4011ITP14X	TSSOP-14	Yes	-40°C to +125°C	Tape & Reel
CLC4011ITP14MTR	TSSOP-14	Yes	-40°C to +125°C	Mini Tape & Reel
CLC4011ITP14EVB	EVB Evaluation Board		N/A	N/A

Moisture sensitivity level for all parts is MSL-1. Mini tape and reel quantity is 250.

## **Revision History**

Revision	Date	Description
1D (ECN 1504-01)	January 19, 2015	Reformat into Exar data sheet template. Updated PODs and thermal resistance numbers. Updated ordering information table to include MTR and EVB part numbers. Increased operating temperature to +125°C.

#### For Further Assistance:

Email: <u>CustomerSupport@exar.com</u> or <u>HPATechSupport@exar.com</u> Exar Technical Documentation: <u>http://www.exar.com/techdoc/</u>

#### Exar Corporation Headquarters and Sales Offices

 48760 Kato Road
 Tel.: +1 (510) 668-7000

 Fremont, CA 94538 - USA
 Fax: +1 (510) 668-7001

#### NOTICE

EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contained here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.

