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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



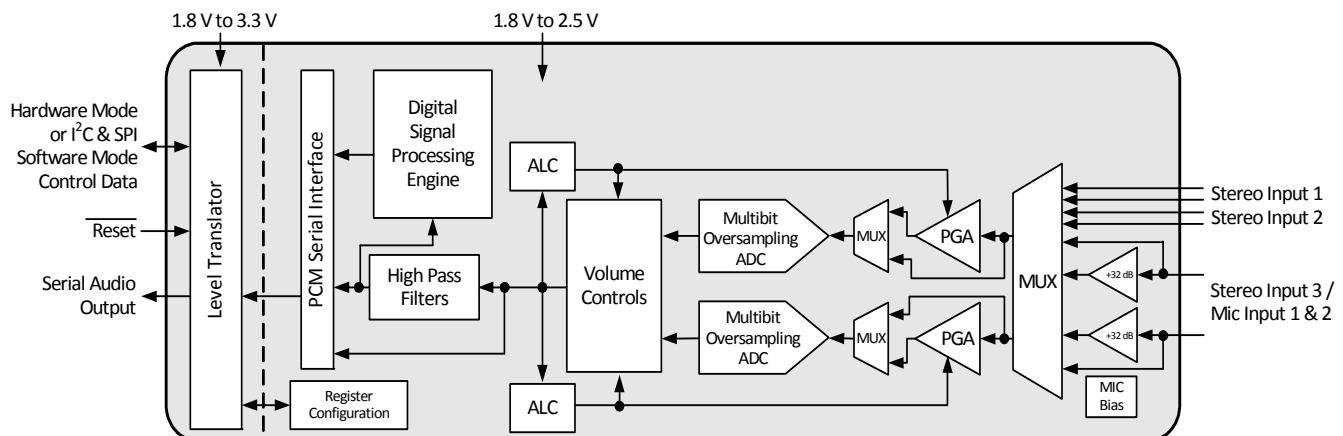
## Low-Power, Stereo Analog-to-Digital Converter

### FEATURES

- ◆ 98-dB dynamic range (A-weighted)
- ◆ –88-dB THD+N
- ◆ Analog gain controls
  - +32-dB or +16-dB mic preamps
  - Analog programmable gain amplifier (PGA)
- ◆ +20-dB digital boost
- ◆ Programmable automatic level control (ALC)
  - Noise gate for noise suppression
  - Programmable threshold and attack/release rates
- ◆ Independent left/right channel control
- ◆ Digital volume control
- ◆ High-pass filter disable for DC measurements
- ◆ Stereo 3:1 analog input MUX
- ◆ Dual mic inputs
  - Programmable, low noise mic bias levels
  - Differential mic mix for common mode noise rejection
- ◆ Very low 64 Fs oversampling clock reduces power consumption

### SYSTEM FEATURES

- ◆ 24-bit conversion
- ◆ 4–96 kHz sample rate
- ◆ Multibit delta–sigma architecture
- ◆ Low power operation
  - Stereo record (ADC): 8.72 mW @ 1.8 V
  - Stereo record (mic to PGA and ADC): 13.73 mW @ 1.8 V
- ◆ Variable power supplies
  - 1.8–2.5-V digital and analog
  - 1.8–3.3-V interface logic
- ◆ Power down management
  - ADC, mic preamplifier, PGA
- ◆ Software Mode (I<sup>2</sup>C™ and SPI™ control)
- ◆ Hardware Mode (standalone control)
- ◆ Flexible clocking options
  - Master or slave operation
- ◆ Digital routing mixes
  - Mono mixes



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## APPLICATIONS

- ◆ Portable audio players
- ◆ Digital microphones
- ◆ Digital voice recorders
- ◆ Voice recognition systems
- ◆ Audio/video capture cards

## GENERAL DESCRIPTION

The CS53L21 is a highly integrated, 24-bit, 96-kHz, low power stereo A/D. Based on multibit, delta-sigma modulation, it allows infinite sample rate adjustment between 4 kHz and 96 kHz. The ADC offers many features suitable for low power, portable system applications.

The ADC input path allows independent channel control of a number of features. An input multiplexer selects between line-level or microphone-level inputs for each channel. The microphone input path includes a selectable programmable-gain preamp stage and a low noise MIC bias voltage supply. A PGA is available for line or microphone inputs and provides analog gain with soft ramp and zero cross transitions. The ADC also features a digital volume attenuator with soft ramp transitions. A programmable ALC and Noise Gate monitor the input signals and adjust the volume levels appropriately.

The Signal Processing Engine (SPE) controls left/right channel volume mixing, channel swap and channel mute functions. All volume-level changes may be configured to occur on soft ramp and zero cross transitions.

The CS53L21 is available in a 32-pin QFN package in both Commercial (-10 to +70° C) and Automotive grades (-40 to +85° C). The CDB53L21 Customer Demonstration board is also available for device evaluation and implementation suggestions. Please see [“Ordering Information” on page 56](#) for complete details.

In addition to its many features, the CS53L21 operates from a low-voltage analog and digital core, making this A/D ideal for portable systems that require extremely low power consumption in a minimal amount of space.

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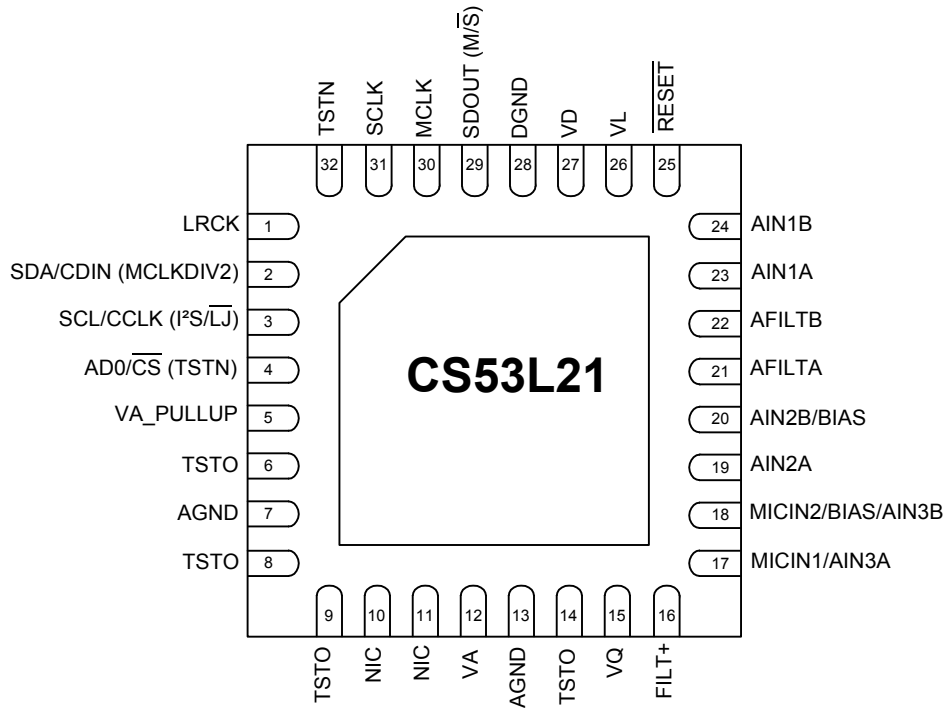
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## 1. PIN DESCRIPTIONS - SOFTWARE (HARDWARE) MODE



Pin Name	#	Pin Description
LRCK	1	<b>Left Right Clock (Input/Output)</b> - Determines which channel, Left or Right, is currently active on the serial audio data line.
SDA/CDIN (MCLKDIV2)	2	<b>Serial Control Data (Input/Output)</b> - SDA is a data I/O in I <sup>2</sup> C Mode. CDIN is the input data line for the control port interface in SPI Mode. <b>MCLK Divide by 2 (Input)</b> - Hardware Mode: Divides the MCLK by 2 prior to all internal circuitry.
SCL/CCLK (I <sup>2</sup> S/LJ)	3	<b>Serial Control Port Clock (Input)</b> - Serial clock for the serial control port. <b>Interface Format Selection (Input)</b> - Hardware Mode: Selects between I <sup>2</sup> S and left-Justified interface formats for the ADC.
AD0/ $\overline{\text{CS}}$ (TSTN)	4	<b>Address Bit 0 (I<sup>2</sup>C) / Control Port Chip Select (SPI) (Input)</b> - AD0 is a chip address pin in I <sup>2</sup> C Mode; $\overline{\text{CS}}$ is the chip-select signal for SPI format. <b>Test In (Input)</b> - Hardware Mode: This pin is an input used for test purposes only and should be tied to DGND for normal operation.
VA_PULLUP	5	<b>Reference Pull-up (Input)</b> - This pin is an input used for test purposes only and must be pulled-up to VA using a 47 k $\Omega$ resistor.
TSTO	6	<b>Test Out (Output)</b> - This pin is an output used for test purposes only and must be left "floating" (no connection external to the pin).
AGND	7	<b>Analog Ground (Input)</b> - Ground reference for the internal analog section.
TSTO	8	<b>Test Out (Output)</b> - This pin is an output used for test purposes only and must be left "floating" (no connection external to the pin).

TSTO	9	<b>Test Out (Output)</b> - This pin is an output used for test purposes only and must be left “floating” (no connection external to the pin).
NIC	10	<b>.Not Internally Connected</b> - This pin is not connected internal to the device and may be connected to ground or left “floating”. No other external connection should be made to this pin.
NIC	11	
VA	12	<b>Analog Power (Input)</b> - Positive power for the internal analog section.
AGND	13	<b>Analog Ground (Input)</b> - Ground reference for the internal analog section.
TSTO	14	<b>Test Out (Output)</b> - This pin is an output used for test purposes only and must be left “floating” (no connection external to the pin).
VQ	15	<b>Quiescent Voltage (Output)</b> - Filter connection for internal quiescent voltage.
FILT+	16	<b>Positive Voltage Reference (Output)</b> - Positive reference voltage for the internal sampling circuits.
MICIN1/ AIN3A	17	<b>Microphone Input 1 (Input)</b> - The full-scale level is specified in the ADC Analog Characteristics specification table.
MICIN2/ BIAS/AIN3B	18	<b>Microphone Input 2 (Input/Output)</b> - The full-scale level is specified in the ADC Analog Characteristics specification table. This pin can also be configured as an output to provide a low noise bias supply for an external microphone. Electrical characteristics are specified in the DC Electrical Characteristics table.
AIN2A	19	<b>Analog Input (Input)</b> - The full-scale level is specified in the ADC Analog Characteristics specification table.
AIN2B/BIAS	20	<b>Analog Input (Input/Output)</b> - The full-scale level is specified in the ADC Analog Characteristics specification table. This pin can also be configured as an output to provide a low noise bias supply for an external microphone. Electrical characteristics are specified in the DC Electrical Characteristics table.
AFILTA	21	<b>Filter Connection (Output)</b> - Filter connection for the ADC inputs.
AFILTB	22	
AIN1A	23	<b>Analog Input (Input)</b> - The full-scale level is specified in the ADC Analog Characteristics specification table.
AIN1B	24	
$\overline{\text{RESET}}$	25	<b>Reset (Input)</b> - The device enters a low power mode when this pin is driven low.
VL	26	<b>Digital Interface Power (Input)</b> - Determines the required signal level for the serial audio interface and host control port. Refer to the Recommended Operating Conditions for appropriate voltages.
VD	27	<b>Digital Power (Input)</b> - Positive power for the internal digital section.
DGND	28	<b>Digital Ground (Input)</b> - Ground reference for the internal digital section.
SDOUT (M/S)	29	<b>Serial Audio Data Output (Output)</b> - Output for two’s complement serial audio data. <b>Serial Port Master/Slave (Input/Output)</b> - Hardware Mode Startup Option: Selects between Master and Slave Mode for the serial port.
MCLK	30	<b>Master Clock (Input)</b> - Clock source for the delta-sigma modulators.
SCLK	31	<b>Serial Clock (Input/Output)</b> -- Serial clock for the serial audio interface.
TSTN	32	<b>Test In (Input)</b> - This pin is an input used for test purposes only and should be tied to DGND for normal operation.
Thermal Pad	-	Thermal relief pad for optimized heat dissipation. See “QFN Thermal Pad” on page 53.

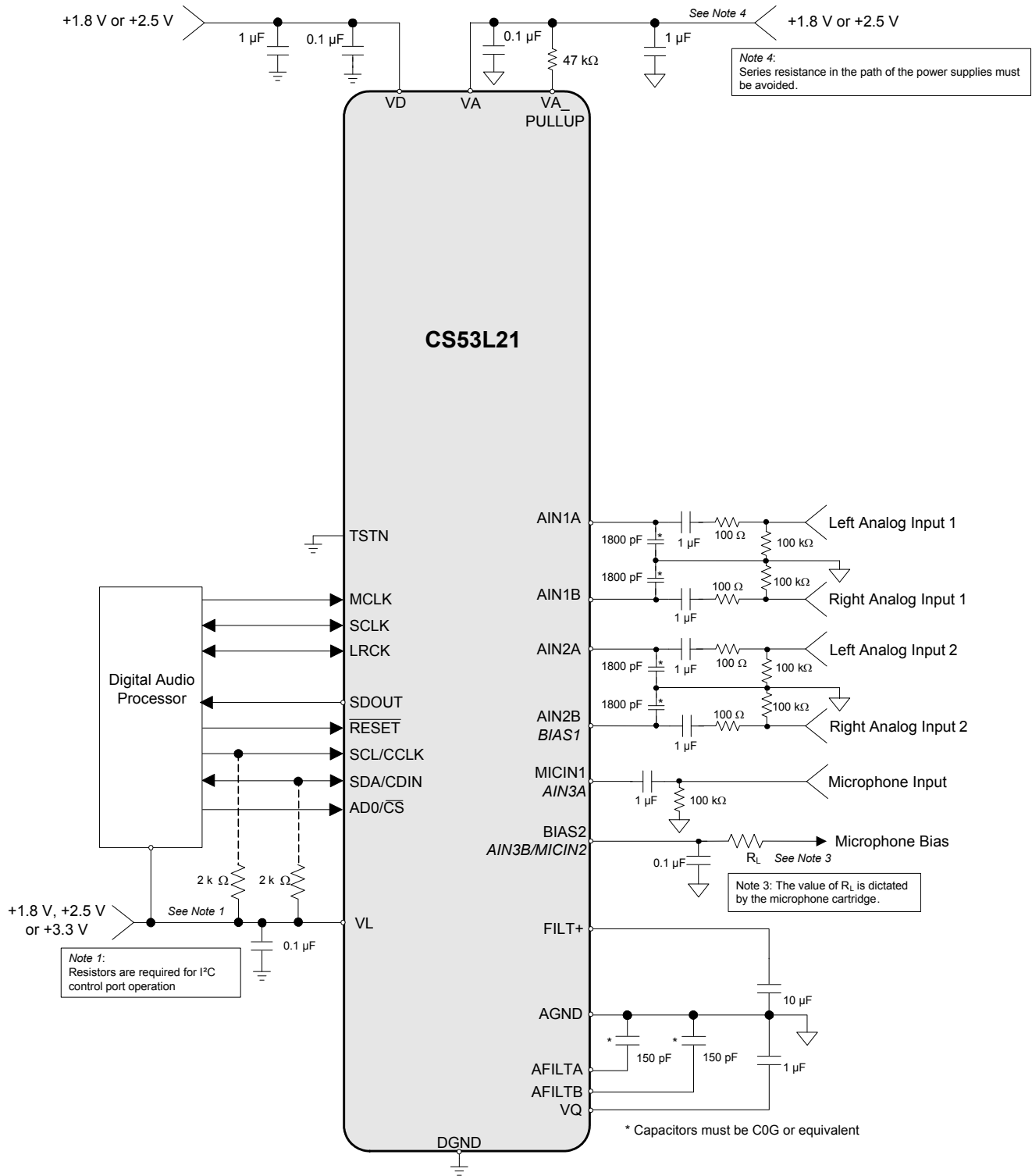


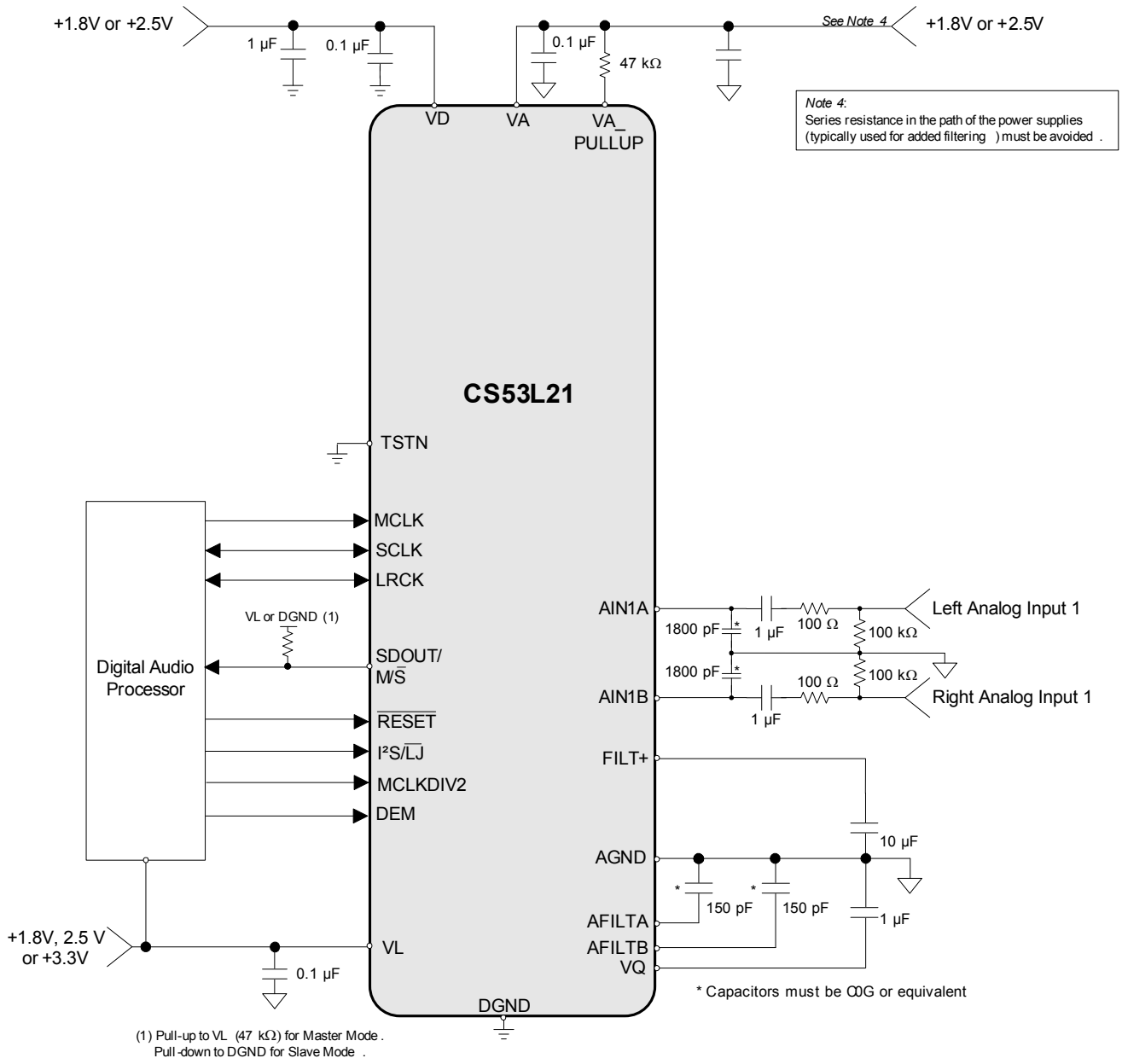
## 1.1 Digital I/O Pin Characteristics

The logic level for each input should not exceed the maximum ratings for the VL power supply.

Pin Name SW/(HW)	I/O	Driver	Receiver
RESET	Input	-	1.8 V - 3.3 V
SCL/CCLK (I <sup>2</sup> S/LJ)	Input	-	1.8 V - 3.3 V, with Hysteresis
SDA/CDIN (MCLKDIV2)	Input/Output	1.8 V - 3.3 V, CMOS/Open Drain	1.8 V - 3.3 V, with Hysteresis
AD0/CS (DEM)	Input	-	1.8 V - 3.3 V
MCLK	Input	-	1.8 V - 3.3 V
LRCK	Input/Output	1.8 V - 3.3 V, CMOS	1.8 V - 3.3 V
SCLK	Input/Output	1.8 V - 3.3 V, CMOS	1.8 V - 3.3 V
SDOUT (M/S)	Input/Output	1.8 V - 3.3 V, CMOS	1.8 V - 3.3 V

**Table 1. I/O Power Rails**

**2. TYPICAL CONNECTION DIAGRAMS**

**Figure 1. Typical Connection Diagram (Software Mode)**



**Figure 2. Typical Connection Diagram (Hardware Mode)**

### 3. CHARACTERISTIC AND SPECIFICATION TABLES

(All Min/Max characteristics and specifications are guaranteed over the Specified Operating Conditions. Typical performance characteristics and specifications are derived from measurements taken at nominal supply voltages and  $T_A = 25^\circ \text{C}$ .)

#### SPECIFIED OPERATING CONDITIONS

(AGND=DGND=0 V, all voltages with respect to ground.)

Parameters	Symbol	Min	Max	Units	
DC Power Supply (Note 1)					
Analog Core	VA	1.65	2.63	V	
Digital Core	VD	1.65	2.63	V	
Serial/Control Port Interface	VL	1.65	3.47	V	
Ambient Temperature	$T_A$	Commercial - CNZ	-10	+70	$^\circ\text{C}$
		Automotive - DNZ	-40	+85	$^\circ\text{C}$

**Note:**

1. The device will operate properly over the full range of the analog, digital core and serial/control port interface supplies.

#### ABSOLUTE MAXIMUM RATINGS

(AGND = DGND = 0 V; all voltages with respect to ground.)

Parameters	Symbol	Min	Max	Units
DC Power Supply	Analog VA	-0.3	3.0	V
	Digital VD	-0.3	3.0	V
	Serial/Control Port Interface VL	-0.3	4.0	V
Input Current (Note 2)	$I_{in}$	-	$\pm 10$	mA
Analog Input Voltage (Note 3)	$V_{IN}$	AGND-0.7	VA+0.7	V
Digital Input Voltage (Note 3)	$V_{IND}$	-0.3	VL+ 0.4	V
Ambient Operating Temperature (power applied)	$T_A$	-50	+115	$^\circ\text{C}$
Storage Temperature	$T_{stg}$	-65	+150	$^\circ\text{C}$

**WARNING:** Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

**Notes:**

2. Any pin except supplies. Transient currents of up to  $\pm 100$  mA on the analog input pins will not cause SCR latch-up.
3. The maximum over/under voltage is limited by the input current.

## ANALOG CHARACTERISTICS (COMMERCIAL - CNZ)

(Test Conditions (unless otherwise specified): Input sine wave (relative to digital full scale): 1 kHz through passive input filter; Measurement Bandwidth is 10 Hz to 20 kHz unless otherwise specified. Sample Frequency = 48 kHz)

Parameter (Note 4)		VA = 2.5 V (nominal)			VA = 1.8 V (nominal)			Unit	
		Min	Typ	Max	Min	Typ	Max		
<b>Analog In to ADC (PGA bypassed)</b>									
Dynamic Range	A-weighted	93	99	-	90	96	-	dB	
	unweighted	90	96	-	87	93	-	dB	
Total Harmonic Distortion + Noise	-1 dBFS	-	-86	-80	-	-84	-78	dB	
	-20 dBFS	-	-76	-	-	-73	-	dB	
	-60 dBFS	-	-36	-	-	-33	-	dB	
<b>Analog In to PGA to ADC</b>									
<b>Dynamic Range</b>									
PGA Setting: 0 dB	A-weighted	92	98	-	89	95	-	dB	
	unweighted	89	95	-	86	92	-	dB	
PGA Setting: +12 dB	A-weighted	85	91	-	82	88	-	dB	
	unweighted	82	88	-	79	85	-	dB	
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-1 dBFS	-	-88	-81	-	-86	-80	dB
		-60 dBFS	-	-35	-	-	-32	-	dB
	PGA Setting: +12 dB	-1 dBFS	-	-85	-79	-	-83	-77	dB
<b>Analog In to MIC Pre-Amp (+16 dB) to PGA to ADC</b>									
<b>Dynamic Range</b>									
PGA Setting: 0 dB	A-weighted	-	86	-	-	83	-	dB	
	unweighted	-	83	-	-	80	-	dB	
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-1 dBFS	-	-76	-	-74	-	dB	
<b>Analog In to MIC Pre-Amp (+32 dB) to PGA to ADC</b>									
<b>Dynamic Range</b>									
PGA Setting: 0 dB	A-weighted	-	78	-	-	75	-	dB	
	unweighted	-	74	-	-	71	-	dB	
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-1 dBFS	-	-74	-	-71	-	dB	
<b>Other Characteristics</b>									
DC Accuracy									
Interchannel Gain Mismatch		-	0.2	-	-	0.2	-	dB	
Gain Drift		-	±100	-	-	±100	-	ppm/°C	
Offset Error		SDOUT Code with HPF On	-	352	-	-	352	-	LSB
Input									
Interchannel Isolation		-	90	-	-	90	-	dB	
Full-scale Input Voltage	ADC	0.74•VA	0.78•VA	0.82•VA	0.74•VA	0.78•VA	0.82•VA	Vpp	
	PGA (0 dB)	0.75•VA	0.794•VA	0.83•VA	0.75•VA	0.794•VA	0.83•VA	Vpp	
	MIC (+16 dB)		0.129•VA			0.129•VA		Vpp	
	MIC (+32 dB)		0.022•VA			0.022•VA		Vpp	
Input Impedance (Note 5)	ADC	-	20	-	-	20	-	kΩ	
	PGA	-	39	-	-	39	-	kΩ	
	MIC	-	50	-	-	50	-	kΩ	

4. Referred to the typical full-scale voltage. Applies to all THD+N and Dynamic Range values in the table.

5. Measured between AINxx and AGND.

**ANALOG CHARACTERISTICS (AUTOMOTIVE - DNZ)**

(Test Conditions (unless otherwise specified): Input sine wave (relative to full scale): 1 kHz through passive input filter; Measurement Bandwidth is 10 Hz to 20 kHz unless otherwise specified. Sample Frequency = 48 kHz)

Parameter (Note 4)		VA = 2.5 V (nominal)			VA = 1.8 V (nominal)			Unit
		Min	Typ	Max	Min	Typ	Max	
<b>Analog In to ADC</b>								
Dynamic Range	A-weighted	91	99	-	88	96	-	dB
	unweighted	78	96	-	85	93	-	dB
Total Harmonic Distortion + Noise	-1 dBFS	-	-86	-78	-	-84	-76	dB
	-20 dBFS	-	-76	-	-	-73	-	dB
	-60 dBFS	-	-36	-	-	-33	-	dB
<b>Analog In to PGA to ADC</b>								
<b>Dynamic Range</b>								
PGA Setting: 0 dB	A-weighted	90	98	-	87	95	-	dB
	unweighted	87	95	-	84	92	-	dB
PGA Setting: +12 dB	A-weighted	83	91	-	80	88	-	dB
	unweighted	80	88	-	77	85	-	dB
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-	-88	-80	-	-86	-78	dB
	-1 dBFS	-	-88	-80	-	-86	-78	dB
	-60 dBFS	-	-35	-	-	-32	-	dB
PGA Setting: +12 dB	-1 dBFS	-	-85	-77	-	-83	-75	dB
<b>Analog In to MIC Pre-Amp (+16 dB) to PGA to ADC</b>								
<b>Dynamic Range</b>								
PGA Setting: 0 dB	A-weighted	-	86	-	-	83	-	dB
	unweighted	-	83	-	-	80	-	dB
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-	-76	-	-	-74	-	dB
	-1 dBFS	-	-76	-	-	-74	-	dB
<b>Analog In to MIC Pre-Amp (+32 dB) to PGA to ADC</b>								
<b>Dynamic Range</b>								
PGA Setting: 0 dB	A-weighted	-	78	-	-	75	-	dB
	unweighted	-	74	-	-	71	-	dB
Total Harmonic Distortion + Noise	PGA Setting: 0 dB	-	-74	-	-	-71	-	dB
	-1 dBFS	-	-74	-	-	-71	-	dB
<b>Other Characteristics</b>								
DC Accuracy								
Interchannel Gain Mismatch		-	0.1	-	-	0.1	-	dB
Gain Drift		-	±100	-	-	±100	-	ppm/°C
Offset Error SDOUT Code with HPF On		-	352	-	-	352	-	LSB
Input								
Interchannel Isolation		-	90	-	-	90	-	dB
Full-scale Input Voltage	ADC	0.74•VA	0.78•VA	0.82•VA	0.74•VA	0.78•VA	0.82•VA	Vpp
	PGA (0 dB)	0.75•VA	0.794•VA	0.83•VA	0.75•VA	0.794•VA	0.83•VA	Vpp
	MIC (+16 dB)		0.129•VA			0.129•VA		Vpp
	MIC (+32 dB)		0.022•VA			0.022•VA		Vpp
Input Impedance (Note 5)	ADC	18	-	-	18	-	-	kΩ
	PGA	40	-	-	40	-	-	kΩ
	MIC	50	-	-	50	-	-	kΩ

## ADC DIGITAL FILTER CHARACTERISTICS

Parameter (Note 6)	Min	Typ	Max	Unit
Passband (Frequency Response) to -0.1 dB corner	0	-	0.46	F <sub>s</sub>
Passband Ripple	-0.09	-	0.17	dB
Stopband	0.6	-	-	F <sub>s</sub>
Stopband Attenuation	33	-	-	dB
Total Group Delay	-	7.6/F <sub>s</sub>	-	s
<b>High-Pass Filter Characteristics (48 kHz F<sub>s</sub>)</b>				
Frequency Response	-3.0 dB	-	3.7	Hz
	-0.13 dB	-	24.2	Hz
Phase Deviation @ 20 Hz	-	10	-	Deg
Passband Ripple	-	-	0.17	dB
Filter Settling Time	-	10 <sup>5</sup> /F <sub>s</sub>	0	s

6. Response is clock-dependent and will scale with F<sub>s</sub>. Note that the response plots (Figures 23 to 26) have been normalized to F<sub>s</sub> and can be denormalized by multiplying the X-axis scale by F<sub>s</sub>. HPF parameters are for F<sub>s</sub> = 48 kHz.

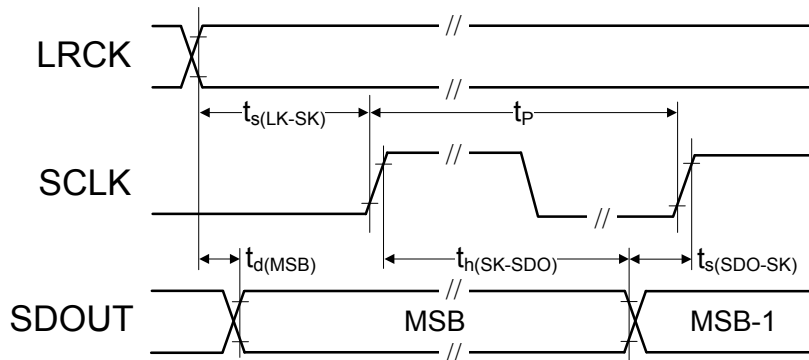
## SWITCHING SPECIFICATIONS - SERIAL PORT

(Inputs: Logic 0 = DGND, Logic 1 = VL, SDOUT C<sub>LOAD</sub> = 15 pF.)

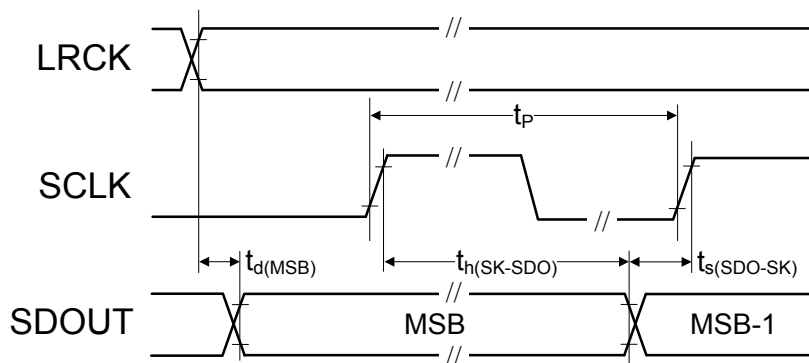
Parameters	Symbol	Min	Max	Units	
RESET pin Low Pulse Width (Note 7)		1	-	ms	
MCLK Frequency		1.024	38.4	MHz	
MCLK Duty Cycle (Note 8)		45	55	%	
<b>Slave Mode</b>					
Input Sample Rate (LRCK)	Quarter-Speed Mode	F <sub>s</sub>	4	12.5	kHz
	Half-Speed Mode	F <sub>s</sub>	8	25	kHz
	Single-Speed Mode	F <sub>s</sub>	4	50	kHz
	Double-Speed Mode	F <sub>s</sub>	50	100	kHz
LRCK Duty Cycle		45	55	%	
SCLK Frequency	1/t <sub>p</sub>	-	64•F <sub>s</sub>	Hz	
SCLK Duty Cycle		45	55	%	
LRCK Setup Time Before SCLK Rising Edge	t <sub>s(LK-SK)</sub>	40	-	ns	
LRCK Edge to SDOUT MSB Output Delay	t <sub>d(MSB)</sub>	-	52	ns	
SDOUT Setup Time Before SCLK Rising Edge	t <sub>s(SDO-SK)</sub>	20	-	ns	
SDOUT Hold Time After SCLK Rising Edge	t <sub>h(SK-SDO)</sub>	30	-	ns	

Parameters	Symbol	Min	Max	Units
<b>Master Mode (Note 9)</b>				
Output Sample Rate (LRCK)	All Speed Modes (Note 10) $F_s$	-	$\frac{MCLK}{128}$	Hz
LRCK Duty Cycle		45	55	%
SCLK Frequency	$1/t_p$	-	$64 \cdot F_s$	Hz
SCLK Duty Cycle		45	55	%
LRCK Edge to SDOUT MSB Output Delay	$t_{d(MSB)}$	-	52	ns
SDOUT Setup Time Before SCLK Rising Edge	$t_{s(SDO-SK)}$	20	-	ns
SDOUT Hold Time After SCLK Rising Edge	$t_{h(SK-SDO)}$	30	-	ns

7. After powering up the CS53L21,  $\overline{RESET}$  should be held low after the power supplies and clocks are settled.
8. See “Example System Clock Frequencies” on page 51 for typical MCLK frequencies.
9. See “Master” on page 29.
10. “MCLK” refers to the external master clock applied.



**Figure 3. Serial Audio Interface Slave Mode Timing**



**Figure 4. Serial Audio Interface Master Mode Timing**

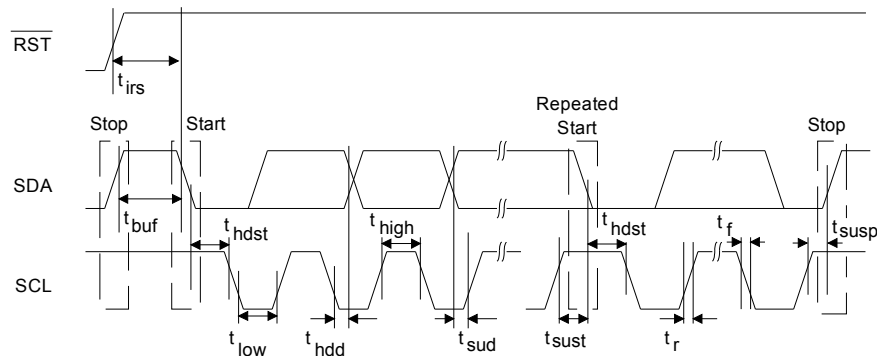


## SWITCHING SPECIFICATIONS - I<sup>2</sup>C CONTROL PORT

(Inputs: Logic 0 = DGND, Logic 1 = VL, SDA C<sub>L</sub> = 30 pF)

Parameter	Symbol	Min	Max	Unit
SCL Clock Frequency	f <sub>scl</sub>	-	100	kHz
RESET Rising Edge to Start	t <sub>irs</sub>	500	-	ns
Bus Free Time Between Transmissions	t <sub>buf</sub>	4.7	-	μs
Start Condition Hold Time (prior to first clock pulse)	t <sub>hdst</sub>	4.0	-	μs
Clock Low time	t <sub>low</sub>	4.7	-	μs
Clock High Time	t <sub>high</sub>	4.0	-	μs
Setup Time for Repeated Start Condition	t <sub>sust</sub>	4.7	-	μs
SDA Hold Time from SCL Falling	t <sub>hdd</sub>	0	-	μs
SDA Setup time to SCL Rising	t <sub>sud</sub>	250	-	ns
Rise Time of SCL and SDA	t <sub>rc</sub>	-	1	μs
Fall Time SCL and SDA	t <sub>fc</sub>	-	300	ns
Setup Time for Stop Condition	t <sub>susp</sub>	4.7	-	μs
Acknowledge Delay from SCL Falling	t <sub>ack</sub>	300	3450	ns

11. Data must be held for sufficient time to bridge the transition time, t<sub>fc</sub>, of SCL.



**Figure 5. Control Port Timing - I<sup>2</sup>C**

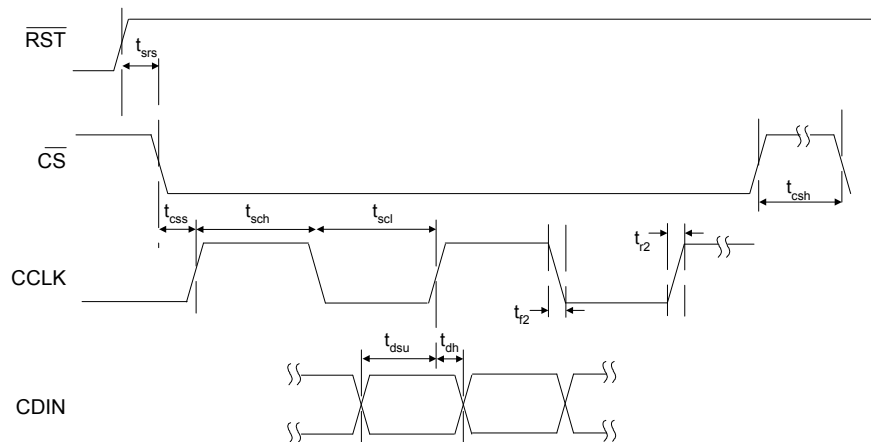
## SWITCHING CHARACTERISTICS - SPI CONTROL PORT

(Inputs: Logic 0 = DGND, Logic 1 = VL)

Parameter	Symbol	Min	Max	Units
CCLK Clock Frequency	$f_{sck}$	0	6.0	MHz
RESET Rising Edge to $\overline{CS}$ Falling	$t_{srs}$	20	-	ns
$\overline{CS}$ Falling to CCLK Edge	$t_{css}$	20	-	ns
$\overline{CS}$ High Time Between Transmissions	$t_{csh}$	1.0	-	$\mu$ s
CCLK Low Time	$t_{scl}$	66	-	ns
CCLK High Time	$t_{sch}$	66	-	ns
CDIN to CCLK Rising Setup Time	$t_{dsu}$	40	-	ns
CCLK Rising to DATA Hold Time	$t_{dh}$	15	-	ns
Rise Time of CCLK and CDIN	$t_{r2}$	-	100	ns
Fall Time of CCLK and CDIN	$t_{f2}$	-	100	ns

12. Data must be held for sufficient time to bridge the transition time of CCLK.

13. For  $f_{sck} < 1$  MHz.



**Figure 6. Control Port Timing - SPI Format**

## DC ELECTRICAL CHARACTERISTICS

(AGND = 0 V; all voltages with respect to ground.)

Parameters	Min	Typ	Max	Units	
<b>VQ Characteristics</b>					
Nominal Voltage	-	0.5•VA	-	V	
Output Impedance	-	23	-	kΩ	
DC Current Source/Sink (Note 14)	-	-	10	μA	
FILT+	-	VA	-	V	
<b>MIC BIAS Characteristics</b>					
Nominal Voltage	MICBIAS_LVL[1:0] = 00	-	0.8•VA	-	V
	MICBIAS_LVL[1:0] = 01	-	0.7•VA	-	V
	MICBIAS_LVL[1:0] = 10	-	0.6•VA	-	V
	MICBIAS_LVL[1:0] = 11	-	0.5•VA	-	V
DC Current Source	-	-	1	mA	
Power Supply Rejection Ratio (PSRR)	1 kHz	-	50	-	dB
Power Consumption (Normal Operation Worse Case)	1 kHz	-	-	30	mW
<b>Power Supply Rejection Ratio (PSRR) (Note 15)</b>	1 kHz	-	60	-	dB

14. The DC current draw represents the allowed current draw from the VQ pin due to typical leakage through electrolytic de-coupling capacitors.

15. Valid with the recommended capacitor values on FILT+ and VQ. Increasing the capacitance will also increase the PSRR.

## DIGITAL INTERFACE SPECIFICATIONS AND CHARACTERISTICS

Parameters (Note 16)	Symbol	Min	Max	Units
Input Leakage Current	$I_{in}$	-	±10	μA
Input Capacitance		-	10	pF
1.8 V - 3.3 V Logic				
High-Level Output Voltage ( $I_{OH} = -100 \mu A$ )	$V_{OH}$	$V_L - 0.2$	-	V
Low-Level Output Voltage ( $I_{OL} = 100 \mu A$ )	$V_{OL}$	-	0.2	V
High-Level Input Voltage	$V_{IH}$	0.68•VL	-	V
Low-Level Input Voltage	$V_{IL}$	-	0.32•VL	V

16. See “Digital I/O Pin Characteristics” on page 8 for serial and control port power rails.

## POWER CONSUMPTION

See (Note 17)

	Operation	Power Control. Registers								Typical Current (mA)				Total Power (mW <sub>rms</sub> )				
		02h				03h				V	i <sub>VA</sub>	i <sub>VD</sub>	i <sub>VL</sub> (Note 18)					
		Reserved bit 6	Reserved bit 5	PDN_PGAB	PDN_PGAA	PDN_ADCB	PDN_ADCA	PDN	PDN_MICB						PDN_MICA	PDN_MICBIAS		
1	Off (Note 19)	x	x	x	x	x	x	x	x	x	x	x	1.8	0	0	0	0	0
													2.5	0	0	0	0	0
2	Standby (Note 20)	x	x	x	x	x	x	x	1	x	x	x	1.8	0.01	0.02	0	0.05	
													2.5	0.01	0.03	0	0.10	
3	Mono Record	ADC	1	1	1	1	1	0	0	1	1	1	1.8	1.85	2.03	0.03	7.05	
														2.5	2.07	3.05	0.05	12.94
	PGA to ADC	1	1	1	0	1	0	0	1	1	1	1.8	2.35	2.03	0.03	7.95		
												2.5	2.58	3.08	0.05	14.29		
	MIC to PGA to ADC (with Bias)	1	1	1	0	1	0	0	1	0	0	1.8	3.67	2.05	0.03	10.36		
												2.5	3.95	3.09	0.05	17.71		
MIC to PGA to ADC (no Bias)	1	1	1	0	1	0	0	1	0	1	1.8	3.27	2.03	0.03	9.61			
											2.5	3.52	3.08	0.05	16.62			
4	Stereo Record	ADC	1	1	1	1	0	0	0	1	1	1	1.8	2.69	2.12	0.03	8.72	
														2.5	2.93	3.18	0.04	15.40
	PGA to ADC	1	1	0	0	0	0	0	1	1	1	1.8	3.65	2.12	0.03	10.45		
												2.5	3.91	3.17	0.04	17.84		
	MIC to PGA to ADC (no Bias)	1	1	0	0	0	0	0	0	0	1	1.8	5.48	2.11	0.03	13.73		
												2.5	5.76	3.17	0.04	22.45		

17. Unless otherwise noted, test conditions are as follows: All zeros input, slave mode, sample rate = 48 kHz; No load. Digital (VD) and logic (VL) supply current will vary depending on speed mode and master/slave operation.

18. VL current will slightly increase in master mode.

19.  $\overline{\text{RESET}}$  pin 25 held LO, all clocks and data lines are held LO.

20.  $\overline{\text{RESET}}$  pin 25 held HI, all clocks and data lines are held HI.

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## 4. APPLICATIONS

### 4.1 Overview

#### 4.1.1 Architecture

The CS53L21 is a highly integrated, low power, 24-bit audio A/D. The ADC operates at  $64F_s$ , where  $F_s$  is equal to the system sample rate. The different clock rates maximize power savings while maintaining high performance. The A/D operates in one of four sample rate speed modes: Quarter, Half, Single and Double. It accepts and is capable of generating serial port clocks (SCLK, LRCK) derived from an input Master Clock (MCLK).

#### 4.1.2 Line and MIC Inputs

The analog input portion of the A/D allows selection from and configuration of multiple combinations of stereo and microphone (MIC) sources. Six line inputs with configuration for two MIC inputs (or one MIC input with common mode rejection), two MIC bias outputs and independent channel control (including a high-pass filter disable function) are available. A Programmable Gain Amplifier (PGA), MIC boost, and Automatic Level Control (ALC), with noise gate settings, provide analog gain and adjustment. Digital volume controls, including gain, boost, attenuation and inversion are also available.

#### 4.1.3 Signal Processing Engine

The ADC data has independent volume controls and mixing functions such as mono mixes and left/right channel swaps.

#### 4.1.4 Device Control (Hardware or Software Mode)

In Software Mode, all functions and features may be controlled via a two-wire I<sup>2</sup>C or three-wire SPI control port interface. In Hardware Mode, a limited feature set may be controlled via stand-alone control pins.

#### 4.1.5 Power Management

Two Software Mode control registers provide independent power-down control of the ADC, PGA, MIC pre-amp and MIC bias, allowing operation in select applications with minimal power consumption.

## 4.2 Hardware Mode

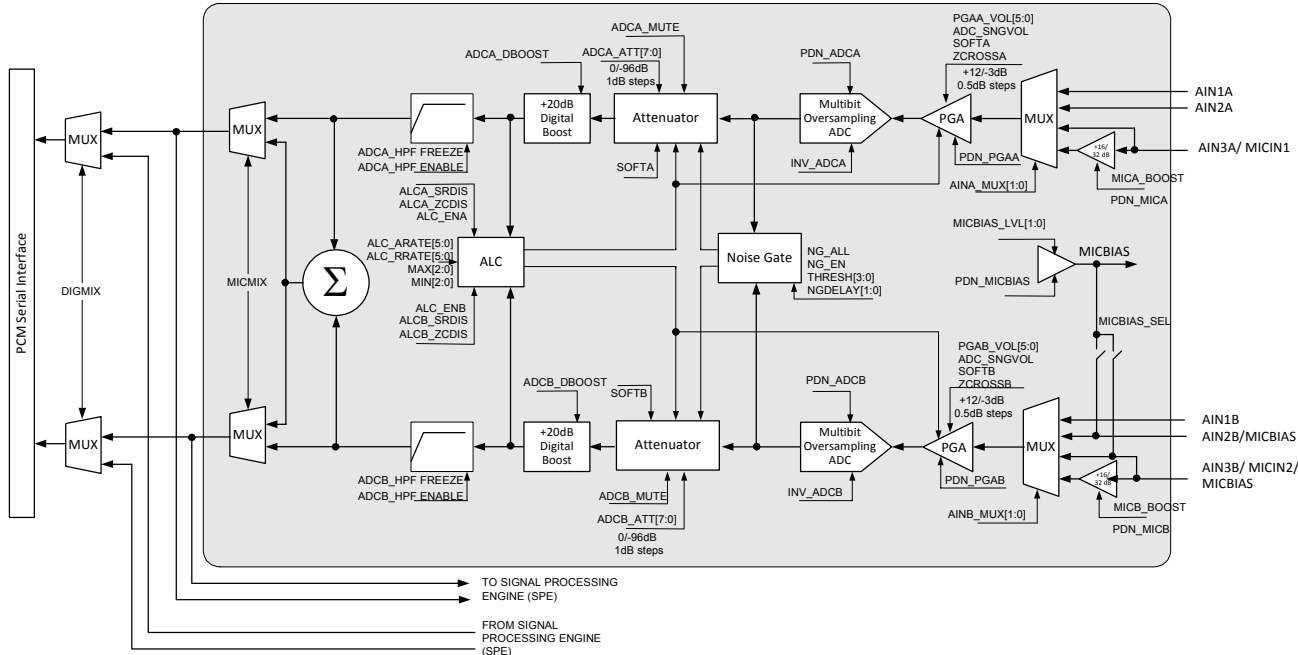
A limited feature set is available when the A/D powers up in Hardware Mode (see “[Recommended Power-Up Sequence](#)” on page 30) and may be controlled via stand-alone control pins. [Table 2](#) shows a list of functions/features, the default configuration and the associated stand-alone control available.

Hardware Mode Feature/Function Summary				
Feature/Function		Default Configuration	Stand-Alone Control	Note
Power Control	Device PGAx ADCx MIC Bias MICx Preamp	Powered Up Powered Up Powered Up Powered Down Powered Down	-	-
Auto-Detect		Enabled	-	-
Speed Mode	Serial Port Slave Serial Port Master	Auto-Detect Speed Mode Single-Speed Mode	-	-
MCLK Divide		(Selectable)	“MCLKDIV2” pin 2	see Section 4.5 on page 28
Serial Port Master / Slave Selection		(Selectable)	“M/S” pin 29	see Section 4.5 on page 28
Interface Control	ADC	(Selectable)	“I <sup>2</sup> S/LJ” pin 3	see Section 4.6 on page 30
ADC Volume and Gain	Digital Boost Soft Ramp Zero Cross Invert PGAx Attenuator ALC Noise Gate	Disabled Disabled Disabled Disabled 0 dB 0 dB Disabled Disabled	-	-
ADCx High-Pass Filter ADCx High-Pass Filter Freeze		Enabled Continuous DC Subtraction	-	-
Line/MIC Input Select		AIN1A to PGAA AIN1B to PGAB	-	-
ADC mix Volume and Gain	Invert Soft Ramp Zero Cross	Disabled Enabled Enabled	-	-
Signal Processing Engine (SPE)	MIX	Disabled	-	-
Data Selection (SPE Enable)		ADC Data to SPE	-	-
Channel Swap	ADC	ADCA = L; ADCB = R	-	-

**Table 2. Hardware Mode Feature Summary**

### 4.3 Analog Inputs

AINxA and AINxB are the analog inputs, internally biased to VQ, that accepts line-level and MIC-level signals, allowing various gain and signal adjustments for each channel.



**Figure 7. Analog Input Architecture**

#### 4.3.1 Digital Code, Offset and DC Measurement

The ADC output data is in two's complement binary format. For inputs above positive full scale or below negative full scale, the ADC will output 7FFFFFFH or 800000H, respectively and cause the ADC overflow bit to be set to a '1'.

Given the two's complement format, low-level signals may cause the MSB of the serial data to periodically toggle between '1' and '0', possibly introducing noise into the system as the bit switches back and forth. To prevent this phenomena, a constant DC offset is added to the serial data bringing the low-level signal just above the point at which the MSB would normally toggle, thus reducing the noise introduced. Note that this offset is not removed (refer to [“Analog Characteristics \(Commercial - CNZ\)”](#) on page 12 and/or [“Analog Characteristics \(Automotive - DNZ\)”](#) on page 13 for the specified offset level).

The A/D may be used to measure DC voltages by disabling the high-pass filter for the designated channel. DC levels are measured relative to VQ and will be decoded as positive two's complement binary numbers above VQ and negative two's complement binary numbers below VQ.

Software Controls:	“Status (Address 20h) (Read Only)” on page 50, “ADC Control (Address 06h)” on page 41.
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### 4.3.2 High-Pass Filter and DC Offset Calibration

The high-pass filter continuously subtracts a measure of the DC offset from the output of the decimation filter. If the high-pass filter is “frozen” during normal operation, the current value of the DC offset for the corresponding channel is held. It is this DC offset that will continue to be subtracted from the conversion result. This feature makes it possible to perform a system DC offset calibration by:

1. Running the A/D with the high-pass filter enabled and the DC offset not “frozen” until the filter settles. See the Digital Filter Characteristics for filter settling time.
2. Freezing the DC offset.

The high-pass filters are controlled using the ADCx\_HPFRZ and ADCx\_HPFEN bits.

If a particular ADC channel is used to measure DC voltages, the high-pass filter may be disabled using the ADCx\_HPFEN bit.

Software Controls:	“ADC Control (Address 06h)” on page 41.
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### 4.3.3 Digital Routing

The digital output of the ADC may be internally routed to the Signal Processing Engine (SPE). ADC output volume may be controlled using the ADCMIX [6:0] bits, and channel swaps can be done using the ADCA[1:0] and ADCB[1:0] bits. This “processed” ADC data can be selected for output in place of the ADC output data using the DIGMIX bit.

Software Controls:	“ADCx Mixer Volume Control: ADCA (Address 0Eh) and ADCB (Address 0Fh)” on page 46, “Interface Control (Address 04h)” on page 39.
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### 4.3.4 Differential Inputs

The stereo pair inputs act as a single differential input when the MICMIX bit is enabled. This provides common mode rejection of noise in digitally intense PCBs, where the microphone signal traverses long traces, or across long microphone cables as illustrated in [Figure 8](#).

Since the mixer provides a differential combination of the two signals, the potential input mix may exceed the maximum full-scale input and result in clipping. The level out of the mixer, therefore, is automatically attenuated 6 dB. Gain may be applied using either the analog PGA or MIC preamp or the digital ADCMIX volume control to readjust a small signal to desired levels.

The analog inputs may also be used as a differential input pair as illustrated in [Figure 9](#). The two channels are differentially combined when the MICMIX bit is enabled.

#### 4.3.4.1 External Passive Components

The microphone input is internally biased to VQ. Input signals must be AC coupled using external capacitors with values consistent with the desired high-pass filter design. The MICINx input resistance of 50 kΩ may be combined with an external capacitor of 1 μF to achieve the cutoff frequency defined by the equation,

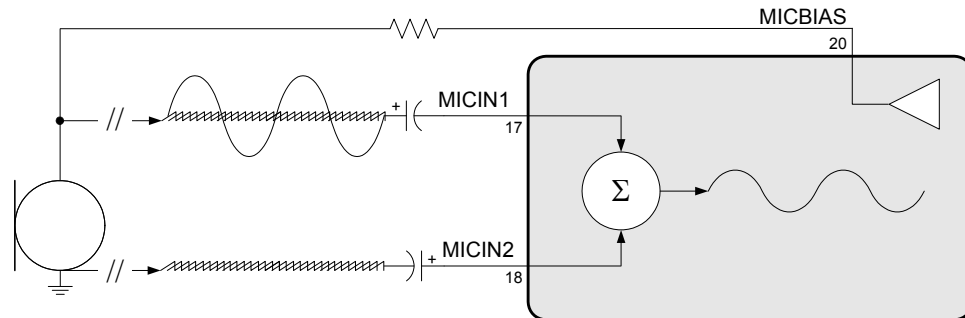
$$f_c = \frac{1}{2\pi(50 \text{ k}\Omega)(1 \text{ }\mu\text{F})} = 3.18 \text{ Hz}$$

An electrolytic capacitor must be placed such that the positive terminal is positioned relative to the side with the greater bias voltage. The MICBIAS voltage level is controlled by the MICBIAS\_LVL[1:0] bits.

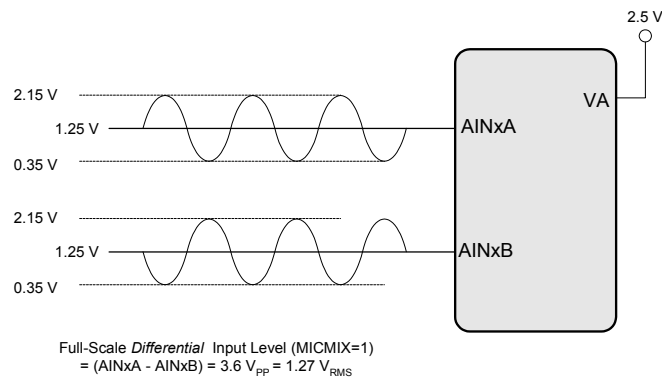


The MICBIAS series resistor must be selected based on the requirements of the particular microphone used. The MICBIAS output pin is selected using the MICBIAS\_SEL bit.

Software Controls:	"Interface Control (Address 04h)" on page 39, "MIC Control (Address 05h)" on page 40.
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**Figure 8. MIC Input Mix w/Common Mode Rejection**



**Figure 9. Differential Input**

### 4.3.5 Analog Input Multiplexer

A stereo 4-to-1 analog input multiplexer selects between a line-level input source, or a mic-level input source, depending on the PDN\_PGAX and AINx\_MUX[1:0] bit settings. Signals may be routed to or bypassed around the PGA. To conserve power, the PGAs may be powered down allowing the user to select from multiple line-level sources and route the stereo signal directly to the ADC. When using the MIC pre-amp, however, the PGA must be powered up.

Analog input channel B may also be used as an output for the MIC bias voltage. The MICBIAS\_SEL bit routes the bias voltage to either of two pins. The multiplexer must then select from the remainder of the two input channels.

Each ADC, PGA and MIC preamp has an associated input resistance. When selecting between these paths, the input resistance to the A/D will change accordingly. Refer to the input resistance characteristics in the [Characteristic and Specification Tables](#) for the input resistance of each path.

Software Controls:	"Power Control 1 (Address 02h)" on page 36, "MIC Control (Address 05h)" on page 40 "ADCx Input Select, Invert and Mute (Address 07h)" on page 42.
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### 4.3.6 MIC and PGA Gain

The MIC-level input passes through a +16 dB or +32 dB analog gain stage prior to the input multiplexer, allowing it to be used for microphone level signals without the need for any external gain. The PGA must be powered up when using the MIC preamp.

The PGA stage provides an additional +12 dB to -3 dB of analog gain in 0.5 dB steps.

Software Controls:	<a href="#">"Power Control 1 (Address 02h)"</a> on page 36, <a href="#">"ADCx Input Select, Invert and Mute (Address 07h)"</a> on page 42, <a href="#">"ALCX and PGAX Control: ALCA, PGAA (Address 0Ah) and ALCB, PGAB (Address 0Bh)"</a> on page 45, <a href="#">"MIC Control (Address 05h)"</a> on page 40.
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### 4.3.7 Automatic Level Control (ALC)

When enabled, the ALC monitors the analog input signal after the digital attenuator, detects when peak levels exceed the maximum threshold settings and lowers, first, the PGA gain settings and then increases the digital attenuation levels at a programmable attack rate and maintains the resulting level below the maximum threshold.

When input signal levels fall below the minimum threshold, digital attenuation levels are decreased first and the PGA gain is then increased at a programmable release rate and maintains the resulting level above the minimum threshold.

Attack and release rates are affected by the ADC soft ramp/zero cross settings and sample rate, Fs. ALC soft ramp and zero cross dependency may be independently enabled/disabled.

*Recommended settings:* Best level control may be realized with the fastest attack and slowest release setting with soft ramp enabled in the control registers. **Note: 1.)** The maximum realized gain must be set in the PGAX\_VOL register. **2.)** The ALC maintains the output signal between the MIN and MAX thresholds. As the input signal level changes, the level-controlled output may not always be the same but will always fall within the thresholds.

Software Controls:	<a href="#">"ALC Enable and Attack Rate (Address 1Ch)"</a> on page 47, <a href="#">"ALC Release Rate (Address 1Dh)"</a> on page 48, <a href="#">"ALC Threshold (Address 1Eh)"</a> on page 48, <a href="#">"ALCX and PGAX Control: ALCA, PGAA (Address 0Ah) and ALCB, PGAB (Address 0Bh)"</a> on page 45.
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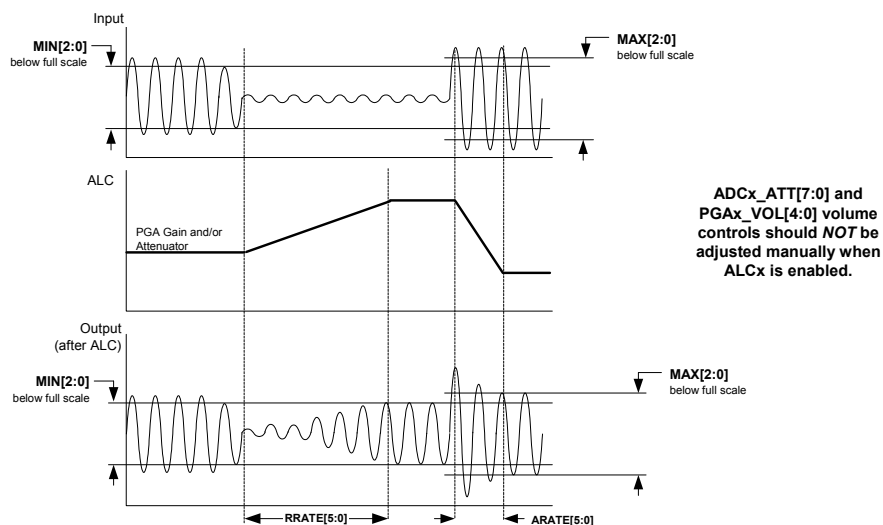


Figure 10. ALC