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## Very Low Power, 16-bit \& 20-bit A/D Converters

## Features

## - Very Low Power Consumption

- Single supply +5 V operation: 1.7 mW
- Dual supply $\pm 5 \mathrm{~V}$ operation: 3.2 mW
- Offers superior performance to VFCs and multi-slope integrating ADCs
- Differential Inputs
- Single-channel (CS5507/8) and Four-channel (CS5505/6) pseudo-differential versions
- Either 5 V or 3.3 V Digital Interface
- Linearity Error:
- $\pm 0.0015 \%$ FS (16-bit CS5505/7)
- $\pm 0.0007 \%$ FS (20-bit CS5506/8)
- Output update rates up to 100 Sps
- Flexible Serial Port
- Pin-Selectable Unipolar/Bipolar Ranges


## Description

The CS5505/6/7/8 are a family of low power CMOS A/D converters which are ideal for measuring low-frequency signals representing physical, chemical, and biological processes.

The CS 5507/8 have single-channel differential analog and reference inputs while the CS5505/6 have four pseudo-differential analog input channels. The CS5505/7 have a 16 -bit output word. The CS5506/8 have a 20 -bit output word. The CS5505/6/7/8 sample upon command up to 100 Sps .

The on-chip digital filter offers superior line rejection at 50 and 60 Hz when the device is operated from a 32.768 kHz clock (output word rate $=20 \mathrm{Sps}$ ).

The CS 5505/6/7/8 include on-chip self-calibration circuitry which can be initiated at any time or temperature to ensure minimum offset and full-scale errors.

The CS5505/6/7/8 serial port offers two general-purpose modes for the direct in terface to shift registers or synchronous serial ports of industry-standard microcontrollers.

## ORDERING INFORMATION

See page 30


ANALOG CHARACTERISTICS (TA = TMIN to TMAX; VA $+=5 \mathrm{~V} \pm 10 \% ; \mathrm{VA}-=-5 \mathrm{~V} \pm 10 \%$; VD+ = $3.3 \mathrm{~V} \pm 5 \%$; VREF+ $=2.5 \mathrm{~V}$ (external); VREF- $=0 \mathrm{~V}$; fCLK $=32.768 \mathrm{kHz}$; Bipolar Mode; Rsource $=1 \mathrm{k} \Omega$ with a 10 nF to AGND at AIN; Analog input channel AIN1+; AIN- = AGND; unless otherwise specified.) (Notes 1, 2)


Notes: 1. The AIN pin presents a very high input resistance at dc and a minor dynamic load which scales to the master clock frequency. Both source resistance and shunt capacitance are therefore critical in determining the CS5505/6/7/8's source impedance requirements. For more information refer to the text section Analog Input Impedance Considerations.
2. Specifications guaranteed by design, characterization and/or test.
3. Applies after calibration at the temperature of interest.
4. Total drift over the specified temperature range since calibration at power-up at $25^{\circ} \mathrm{C}$. Recalibration at any temperature will remove these errors.

|  | Unipolar Mode <br> \% FS |  |  | ppm FS | LSB's | Bipolar Mode <br> $\%$ FS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mV | LSB's | 0.26 | 0.0004 | 4 | 0.13 | 0.0002 |
| 10 | 0.50 | 0.0008 | 8 | 0.26 | 0.0004 | 4 |
| 19 | 1.00 | 0.0015 | 15 | 0.50 | 0.0008 | 8 |
| 38 | 2.00 | 0.0030 | 30 | 1.00 | 0.0015 | 15 |
| 76 | 4.00 | 0.0061 | 61 | 2.00 | 0.0030 | 30 |
| 152 | VREF $=2.5 \mathrm{~V}$ |  |  |  |  |  |

CS5505/7; 16-Bit Unit Conversion Factors

* Refer to the Specification Definitions immediately following the Pin Description Section.

Specifications are subject to change without notice.

ANALOG CHARACTERISTICS (TA = Tmin to TMAX; VA $+=5 \mathrm{~V} \pm 10 \%$; VA $=-5 \mathrm{~V} \pm 10 \%$; VD+ = $3.3 \mathrm{~V} \pm 5 \%$; VREF+ $=2.5 \mathrm{~V}$ (external); VREF- $=0 \mathrm{~V}$; fCLK $=32.768 \mathrm{kHz}$; Bipolar Mode; Rsource $=1 \mathrm{k} \Omega$ with a 10 nF to AGND at AIN; Analog input channel AIN1+; AIN- = AGND; unless otherwise specified.) (Notes 1, 2)

| Parameter* |  | CS5506/8-B |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Typ | Max |  |  |
| Specified Temperature Range |  | -40 to +85 |  |  |  | ${ }^{\circ} \mathrm{C}$ |
| Accuracy |  |  |  |  |  |  |
| Linearity Error |  | - | 0.0007 | 0.0015 |  | $\pm \%$ FS |
| Differential Nonlinearity (No Missing Codes) |  | 20 | - | - |  | Bits |
| Full Scale Error | (Note 3) | - | $\pm 4$ | $\pm 32$ |  | LSB20 |
| Full Scale Drift | (Note 4) | - | $\pm 8$ | - |  | LSB20 |
| Unipolar Offset | (Note 3) | - | $\pm 8$ | $\pm 32$ |  | LSB20 |
| Unipolar Offset Drift | (Note 4) | - | $\pm 8$ | - |  | LSB20 |
| Bipolar Offset | (Note 3) | - | $\pm 4$ | $\pm 16$ |  | LSB20 |
| Bipolar Offset Drift | (Note 4) | - | $\pm 4$ | - |  | LSB20 |
| Noise (Referred to Output) |  | - | 2.6 | - |  | $\begin{aligned} & \text { LSB- } \\ & \text { rms20 } \end{aligned}$ |


| mV | Unipolar Mode |  |  | Bipolar Mode |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | LSB's | \% FS | ppm FS | LSB's | \% FS | ppm FS |
| 0.596 | 0.25 | 0.0000238 | 0.24 | 0.13 | 0.0000119 | 0.12 |
| 1.192 | 0.50 | 0.0000477 | 0.47 | 0.26 | 0.0000238 | 0.24 |
| 2.384 | 1.00 | 0.0000954 | 0.95 | 0.50 | 0.0000477 | 0.47 |
| 4.768 | 2.00 | 0.0001907 | 1.91 | 1.00 | 0.0000954 | 0.95 |
| 9.537 | 4.00 | 0.0003814 | 3.81 | 2.00 | 0.0001907 | 1.91 |

CS5506/8; 20-Bit Unit Conversion Factors

## DYNAMIC CHARACTERISTICS

| Parameter | Symbol | Ratio | Units |
| :--- | :---: | :---: | :---: |
| Modulator Sampling Frequency | $\mathrm{f}_{\mathrm{s}}$ | $\mathrm{f}_{\mathrm{Clk}} / 2$ | Hz |
| Output Update Rate (CONV =1) | fout | $\mathrm{f}_{\mathrm{clk}} / 1622$ | Sps |
| Filter Corner Frequency | $\mathrm{f}-3 \mathrm{~dB}$ | $\mathrm{f}_{\mathrm{Cl}} / 1928$ | Hz |
| Settling Time to $1 / 2$ LSB (FS Step) | $\mathrm{ts}_{\mathrm{s}}$ | $1 / \mathrm{fout}$ | s |

ANALOG CHARACTERISTICS (TA = Tmin to TMAX; VA $+=5 \mathrm{~V} \pm 10 \%$; VA $-=-5 \mathrm{~V} \pm 10 \%$; VD+ = $3.3 \mathrm{~V} \pm 5 \%$; VREF+ = 2.5 V (external); VREF- $=0 \mathrm{~V}$; fCLK $=32.768 \mathrm{kHz}$; Bipolar Mode; Rsource $=1 \mathrm{k} \Omega$ with a 10 nF to AGND at AIN; Analog input channel AIN1+; AIN- = AGND; unless otherwise specified.) (Notes 1, 2)


## Voltage Reference (Output)



## Power Supplies



Notes: 5. Common mode voltage may be at any value as long as AIN+ and AIN- remain within the VA+ and VA- supply voltages.
6. $\mathrm{XIN}=32.768 \mathrm{kHz}$. Guaranteed by design and / or characterization.
7. All outputs unloaded. All inputs CMOS levels. SLEEP mode controlled by M/SLP pin. SLEEP active $=$ M/SLP pin at $(\mathrm{VD}+) / 2$ input level.

5V DIGITAL CHARACTERISTICS (TA = TMIN to TMAX; VA+VD+ = $5 \mathrm{~V} \pm 10 \%$; VA $=-5 \mathrm{~V} \pm 10 \%$; DGND = 0.) All measurements below are performed under static conditions. (Note 2)


Notes: 8. Under normal operation this pin should be tied to VD+ or DGND. Anytime the voltage on the M/SLP pin enters the SLEEP active threshold range the device will enter the power down condition. Returning to the active state requires elapse of the power-on reset period, the oscillator to start-up, and elapse of the wake-up period.
9. $\mathrm{I}_{\mathrm{out}}=-100 \mu \mathrm{~A}$. This guarantees the ability to drive one TTL load. $\left(\mathrm{V}_{\mathrm{OH}}=2.4 \mathrm{~V} @ \mathrm{I}_{\text {out }}=-40 \mu \mathrm{~A}\right)$.
3.3V DIGITAL CHARACTERISTICS (TA = TMIN to $T_{M A X}$; $V A+=5 \mathrm{~V} \pm 10 \%$; VD+ = $3.3 \mathrm{~V} \pm 5 \%$; $\mathrm{VA}-=-5 \mathrm{~V} \pm 10 \%$; DGND $=0$.) All measurements below are performed under static conditions. (Note 2)


5V SWITCHING CHARACTERISTICS (TA = TMIN to TMAX; VA+, VD+ $=5 \mathrm{~V} \pm 10 \%$;
$\mathrm{VA}-=-5 \mathrm{~V} \pm 10 \%$; Input Levels: Logic $0=0 \mathrm{~V}$, Logic $1=\mathrm{VD}+; \mathrm{CL}_{\mathrm{L}}=50 \mathrm{pF}$.) (Note 2)

| Parameter |  |  | Symbol | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Master Clock Frequency: | Internal Oscillator: <br> External Clock: |  | XIN | 30.0 | 32.768 | 53.0 | kHz |
|  |  |  | $\mathrm{f}_{\mathrm{clk}}$ | 30 | - | 163 | kHz |
| Master Clock Duty Cycle |  |  |  | 40 | - | 60 | \% |
| Rise Times: | Any Digital Input Any Digital Output | (Note 10) | trise | - | $50$ | 1.0 | $\begin{aligned} & \mu \mathrm{s} \\ & \mathrm{~ns} \end{aligned}$ |
| Fall Times: | Any Digital Input Any Digital Output | (Note 10) | tfall | - | $20$ | 1.0 | $\begin{aligned} & \mu \mathrm{s} \\ & \mathrm{~ns} \end{aligned}$ |

## Start-Up

| Power-On Reset Period | (Note 11) | tres | - | 10 | - | ms |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| Oscillator Start-up Time | XTAL=32.768 kHz | (Note 12) | tosu | - | 500 | - | ms |
| Wake-up Period |  | (Note 13) | twup | - | $1800 / \mathrm{fclk}^{\prime}$ | - | s |

## Calibration

| CONV Pulse Width $($ CAL $=1)$ | (Note 14) | $\mathrm{tccw}_{\mathrm{ccw}}$ | 100 | - | - | ns |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| CONV and CAL High to Start of Calibration | $\mathrm{t}_{\mathrm{ccl}}$ | - | - | $2 / \mathrm{fclk}_{\mathrm{cl}}+200$ | ns |  |
| Start of Calibration to End of Calibration | $\mathrm{t}_{\mathrm{cal}}$ | - | $3246 / \mathrm{fclk}$ | - | s |  |

## Conversion

| Set Up Time A0, A1 to CONV High | $\mathrm{t}_{\text {sac }}$ | 50 | - | - | ns |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Hold Time A0, A1 after CONV High | thea | 100 | - | - | ns |
| CONV Pulse Width | tcpw | 100 | - | - | ns |
| CONV High to Start of Conversion | $\mathrm{t}_{\text {scn }}$ | - | - | 2/fflk +200 | ns |
| Set Up Time BP/UP stable prior to DRDY falling | tbus | 82/fclk | - | - | s |
| Hold Time BP/UP stable after DRDY falls | tbuh | 0 | - | - | ns |
| Start of Conversion to End of Conversion (Note 15) | tcon | - | 1624/f.flk | - | s |

Notes: 10. Specified using $10 \%$ and $90 \%$ points on waveform of interest.
11. An internal power-on-reset is activated whenever power is applied to the device, or when coming out of a SLEEP state.
12. Oscillator start-up time varies with the crystal parameters. This specification does not apply when using an external clock source.
13. The wake-up period begins once the oscillator starts; or when using an external $\mathrm{f}_{\mathrm{clk}}$, after the power-on reset time elapses.
14. Calibration can also be initiated by pulsing CAL high while CONV $=1$.
15. Conversion time will be $1622 / \mathrm{f} \mathrm{clk}$ if CONV remains high continuously.
3.3V SWITCHING CHARACTERISTICS (TA $=$ Tmin to $^{\text {TMAX }} \mathrm{VA}^{+}=5 \mathrm{~V} \pm 10 \%$;
$\mathrm{VD}+=3.3 \mathrm{~V} \pm 5 \%$; VA- = $-5 \mathrm{~V} \pm 10 \%$; Input Levels: Logic $0=0 \mathrm{~V}$, Logic $1=\mathrm{VD}+; \mathrm{CL}=50 \mathrm{pF}$.) (Note 2)



Figure 1. Calibration Timing (Not to Scale)


Figure 2. Conversion Timing (Not to Scale)

5V SWITCHING CHARACTERISTICS (TA = TMIN to TMAX; VA,$+ V D+=5 V \pm 10 \%$;
$\mathrm{VA}-=-5 \mathrm{~V} \pm 10 \%$; Input Levels: Logic $0=0 \mathrm{~V}$, Logic $1=\mathrm{VD}+; \mathrm{CL}_{\mathrm{L}}=50 \mathrm{pF}$.) (Note 2)

| Parameter | Symbol | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| SSC Mode (M/SLP = VD+) |  |  |  |  |  |
| Access Time: <br> CS Low to SDATA out (DRDY = low) <br> DRDY falling to MSB (CS = low) | tcsd1 tdfd |  | $2 / f_{\mathrm{clk}}$ | 2/fclk 3/fclk | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |
| SDATA Delay Time: SCLK falling to next SDATA bit | tdd1 | - | 80 | 250 | ns |
| SCLK Delay Time SDATA MSB bit to SCLK rising | tcd1 | - | 1/fflk | - | ns |
| Serial Clock (Out) $\begin{array}{r}\text { Pulse Width High } \\ \text { Pulse Width Low }\end{array}$ | $\begin{aligned} & \text { tph1 } \\ & \text { tpl1 } \end{aligned}$ | - | 1/fclk 1/fclk | $-$ | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |
| Output Float Delay: $\quad \begin{array}{r}\text { CS high to output Hi-Z (Note 16) } \\ \text { SCLK rising to SDATA Hi-Z }\end{array}$ | $\begin{aligned} & \mathrm{tfd1} \\ & \mathrm{tfd} 2 \end{aligned}$ | - | 1/fclk | $2 / \mathrm{fclk}^{2}$ | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |
| SEC Mode (M/SLP = DGND) |  |  |  |  |  |
| Serial Clock (In) | $\mathrm{f}_{\text {sclk }}$ | 0 | - | 2.5 | MHz |
| Serial Clock (In) $\begin{array}{r}\text { Pulse Width High } \\ \text { Pulse Width Low }\end{array}$ | $\begin{gathered} \text { tph2 } \\ \text { tpl2 } \end{gathered}$ | $\begin{aligned} & 200 \\ & 200 \end{aligned}$ |  | - | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |
| Access Time: $\quad$ CS Low to data valid (Note 17) | tcsd2 | - | 60 | 200 | ns |
| Maximum Delay time: $\quad$ SCLK falling to new SDATA bit | tdd2 | - | 150 | 310 | ns |
| $\begin{aligned} \text { Output Float Delay: } & \begin{array}{r}\text { CS high to output Hi-Z (Note 16) } \\ \text { SCLK falling to SDATA Hi-Z }\end{array}\end{aligned}$ | $\begin{aligned} & \mathrm{tfd} 3 \\ & \mathrm{tfd} 4 \end{aligned}$ | - | $\begin{gathered} 60 \\ 160 \end{gathered}$ | $\begin{aligned} & 150 \\ & 300 \end{aligned}$ | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |

Notes: 16. If $\overline{\mathrm{CS}}$ is returned high before all data bits are output, the SDATA and SCLK outputs will complete the current data bit and then go to high impedance.
17. If $\overline{C S}$ is activated asynchronously to DRDY, CS will not be recognized if it occ urs when DRDY is high for 2 clock cycles. The propagation delay time may be as great as 2 f clk cycles plus 200 ns . To guarantee proper clocking of SDATA when using asynchronous CS, SCLK(i) should not be taken high sooner than $2 \mathrm{f}_{\mathrm{clk}}+200 \mathrm{~ns}$ after $\overline{\mathrm{CS}}$ goes low.
18. SDATA transitions on the falling edge of SCLK. Note that a rising SCLK must occur to enable the serial port shifting mechanism before falling edges can be recognized.
 $5 \%$; VA- $=-5 \mathrm{~V} \pm 10 \%$; Input Levels: Logic $0=0 \mathrm{~V}$, Logic $1=\mathrm{VD}+; \mathrm{CL}_{\mathrm{L}}=50 \mathrm{pF}$.) (Note 2)

| Parameter | Symbol | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| SSC Mode (M/SLP = VD+) |  |  |  |  |  |
| Access Time: <br> CS Low to SDATA out (DRDY = low) <br> DRDY falling to MSB (CS = low) | tcsd1 tdfd |  | $2 / f_{\mathrm{clk}}$ | 2/fclk <br> 3/fclk | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |
| SDATA Delay Time: SCLK falling to next SDATA bit | tdd1 | - | 265 | 400 | ns |
| SCLK Delay Time SDATA MSB bit to SCLK rising | tcd1 | - | 1/fclk | - | ns |
| Serial Clock (Out) $\begin{array}{r}\text { Pulse Width High } \\ \text { Pulse Width Low }\end{array}$ | $\begin{aligned} & \text { tph1 } \\ & \text { tpl1 } \end{aligned}$ | - | 1/fclk 1/fclk |  | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |
| $\begin{aligned} \text { Output Float Delay: } & \begin{array}{r}\text { CS high to output Hi-Z (Note 16) } \\ \text { SCLK rising to SDATA Hi-Z }\end{array}\end{aligned}$ | $\begin{aligned} & \mathrm{tfd} 1 \\ & \mathrm{tfd} 2 \end{aligned}$ | - | 1/fclk | 2/fclk | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |
| SEC Mode (M/SLP = DGND) |  |  |  |  |  |
| Serial Clock (In) | $\mathrm{f}_{\text {sclk }}$ | 0 | - | 1.25 | MHz |
| Serial Clock (In)Pulse Width High <br> Pulse Width Low | $\begin{aligned} & \text { tph2 } \\ & \text { tpl2 } \end{aligned}$ | $\begin{aligned} & 200 \\ & 200 \end{aligned}$ | - | - | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |
| Access Time: CS Low to data valid (Note 17) | $\mathrm{tcsd}^{\text {c }}$ | - | 100 | 200 | ns |
| Maximum Delay time: $\quad$ SCLK falling to new SDATA bit | tdd2 | - | 400 | 600 | ns |
| Output Float Delay: $\quad \begin{array}{r}\text { CS high to output Hi-Z (Note 16) } \\ \text { SCLK falling to SDATA Hi-Z }\end{array}$ | $\begin{aligned} & \mathrm{tfd3} \\ & \mathrm{tfd} 4 \end{aligned}$ | - | $\begin{gathered} 70 \\ 320 \end{gathered}$ | $\begin{aligned} & 150 \\ & 500 \end{aligned}$ | $\begin{aligned} & \text { ns } \\ & \text { ns } \end{aligned}$ |



Figure 3. Timing Relationships; SSC Mode (Not to Scale)


Figure 4. Timing Relationships; SEC Mode (Not to Scale)

## RECOMMENDED OPERATING CONDITIONS (DGND = ov) (Note 19)

| Parameter | Symbol | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DC Power Supplies: Positive Digital | VD+ | 3.15 | 5.0 | 5.5 | V |
| (VA+)-(VA-) | Vdiff | 4.75 | 10 | 11 | V |
| Positive Analog | VA+ | 4.5 | 5.0 | 11 | V |
| Negative Analog | VA- | 0 | -5.0 | -5.5 | V |
| Analog Reference Voltage (Note 20) | (VREF+)-(VREF-) | 1.0 | 2.5 | 3.6 | V |
| Analog Input Voltage: (Note 21) |  |  |  |  |  |
| Unipolar | VAIN | 0 | - | (VREF+)-(VREF-) | V |
| Bipolar | VAIN | -((VREF+)-(VREF-)) | - | +((VREF+)-(VREF-)) | V |

Notes: 19. All voltages with respect to ground.
20. The CS5505/6/7/8 can be operated with a reference voltage as low as 100 mV ; but with a corresponding reduction in nois e-free resolution. The common mode voltage of the voltage reference may be any value as long as +V REF and -VREF remain inside the supply values of VA+ and VA-.
21. The CS5505/6/7/8 can acc ept input voltages up to the analog supplies (VA+ and VA-). In unipolar mode the CS5505/6/7/8 will output all 1's if the dc input magnitude ( (AIN+)-(AIN-)) exceeds ((VREF+)-(VREF-)) and will output all 0's if the input becomes more negative than 0 Volts. In bipolar mode the CS5505/6/7/8 will output all 1's if the dc input magnitude ((AIN+)-(AIN-)) exceeds ((VREF+)-(VREF-)) and will output all 0's if the input becomes more negative in magnitude than -((VREF+)-(VREF-)).

## ABSOLUTE MAXIMUM RATINGS*

| Parameter | Symbol | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DC Power Supplies: Digital Ground (Note 22) | DGND | -0.3 | - | (VD+)-0.3 | V |
| Positive Digital (Note 23) | VD+ | -0.3 | - | 6.0 or VA+ | V |
| Positive Analog | VA+ | -0.3 | - | 12.0 | V |
| Negative Analog | VA- | +0.3 | - | -6.0 | V |
| (VA+)-(VA-) | Vdiff1 | -0.3 | - | 12.0 | V |
| (VA+)-(VD+) | $\mathrm{V}_{\text {diff2 }}$ | -0.3 | - | 12.0 | V |
| Input Current, Any Pin Except Supplies (Notes 24, 25) | lin | - | - | $\pm 10$ | mA |
| Analog Input Voltage AIN and VREF pins | VINA | (VA-)-0.3 | - | (VA+)+0.3 | V |
| Digital Input Voltage | VIND | -0.3 | - | (VD+)+0.3 | V |
| Ambient Operating Temperature | TA | -55 | - | 125 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | Tstg | -65 | - | 150 | ${ }^{\circ} \mathrm{C}$ |

Notes: 22. No pin should go more positive than (VA+)+0.3V.
23. $\mathrm{VD}+$ must always be less than ( $\mathrm{VA}+$ )+0.3 V , and can never exceed 6.0 V .
24. Applies to all pins including continuous overvoltage conditions at the analog input (AIN) pin.
25. Transient currents of up to 100 mA will not cause SCR latch-up. Maximum input current for a power supply pin is $\pm 50 \mathrm{~mA}$.

* WARNING: Operation at or beyond these limits may result in permanent damage to the device.

Normal operation is not guaranteed at these extremes.

## GENERAL DESCRIPTION

The CS5505/6/7/8 are very low power monolithic CMOS A/D converters designed specifically for measurement of dc signals. The CS5505/7 are 16-bit converters (a four channel and a single channel version). The CS5506/8 are 20-bit converters (a four channel and a single channel version). Each of the devices includes a delta-sigma charge-balance converter, a voltage reference, a calibration microcontroller with SRAM, a digital filter and a serial interface. The CS5505 and CS5506 include a four channel pseudo-differential (all four channels have the same reference measurement node) multiplexer.

The CS5505/6/7/8 include an on-chip reference but can also utilize an off-chip reference for precision applications. The CS5505/6/7/8 can be used to measure either unipolar or bipolar signals. The devices use self-calibration to insure excellent offset and gain accuracy.

The CS5505/6/7/8 are optimized to operate from a 32.768 kHz crystal but can be driven by an external clock whose frequency is between 30 kHz and 163 kHz . When the digital filter is operated with a 32.768 kHz clock, the filter has zeros precisely at 50 and 60 Hz line frequencies and multiples thereof.

The CS5505/6/7/8 use a "start convert" command to latch the input channel selection and to start a convolution cycle on the digital filter. Once the filter cycle is completed, the output port is updated. When operated with a 32.768 kHz clock the ADC converts and updates its output port at 20 samples $/ \mathrm{sec}$. The throughput rate per channel is the output update rate divided by the number of channels being multiplexed. The output port includes a serial interface with two modes of operation.

The CS5505/6/7/8 can operate from dual polarity power supplies ( +5 and -5 ), from a single +5 volt supply, or with +10 volts on the analog and
+5 on the digital. They can also operate with dual polarity ( +5 and -5 ), or from a single +5 volt supply on the analog and +3.3 on the digital.

## THEORY OF OPERATION FOR THE CS5505/6/7/8

The front page of this data sheet illustrates the block diagram of the CS5505/6.

## Basic Converter Operation

The CS5505/6/7/8 A/D converters have four operating states. These are start-up, calibration, conversion and sleep. When power is first applied, the device enters the start-up state. The first step is a power-on reset delay of about 10 ms which resets all of the logic in the device. To proceed with start-up, the oscillator must then begin oscillating. After the power-on reset the device enters the wake-up period for 1800 clock cycles after clock is present. This allows the delta-sigma modulator and other circuitry (which are operating with very low currents) to reach a stable bias condition prior to entering into either the calibration or conversion states. During the 1800 cycle wake-up period, the device can accept an input command. Execution of this command will not occur until the complete wake-up period elapses. If no command is given, the device enters the standby mode.

## Calibration

After the initial application of power, the CS5505/6/7/8 must enter the calibration state prior to performing accurate conversions. During calibration, the chip executes a two-step process. The device first performs an offset calibration and then follows this with a gain calibration. The two calibration steps determine the zero reference point and the full scale reference point of the converter's transfer function. From these points it calibrates the zero point and a gain
slope to be used to properly scale the output digital codes when doing conversions.

The calibration state is entered whenever the CAL and CONV pins are high at the same time. The state of the CAL and CONV pins at poweron and when coming out of sleep are recognized as commands, but will not be executed until the end of the 1800 clock cycle wake-up period. Note that any time CONV transitions from low to high, the multiplexer inputs A0 and A1 are latched internal to the CS5505 and CS5506 devices. These latched inputs select the analog input channel which will be used once conversion commences.

If CAL and CONV become active (high) during the 1800 clock cycle wake-up time, the converter will wait until the wake-up period elapses before executing the calibration. If the wake-up time has elapsed, the converter will be in the standby mode waiting for instruction and will enter the calibration cycle immediately. The calibration lasts for 3246 clock cycles. Calibration coefficients are then retained in the SRAM (static RAM) for use during conversion.

At the end of the calibration cycle, the on-chip microcontroller checks the logic state of the CONV signal. If the CONV input is low the device will enter the standby mode where it waits for further instruction. If the CONV signal is high at the end of the calibration cycle, the converter will enter the conversion state and perform a conversion on the input channel which was selected when CONV transitioned from low to high. The CAL signal can be returned low any time after calibration is initiated. CONV can also be returned low, but it should never be taken low and then taken back high until the calibration period has ended and the converter is in the standby state. If CONV is taken low and then high again with CAL high while the converter is calibrating, the device will interrupt the current calibration cycle and start a new one. If CAL is taken low and CONV is taken low and
then high during calibration, the calibration cycle will continue as the conversion command is disregarded. The states of $\mathrm{A} 0, \mathrm{~A} 1$ and $\mathrm{BP} / \overline{\mathrm{UP}}$ are not important during calibrations.

If an "end of calibration" signal is desired, pulse the CAL signal high while leaving the CONV signal high continuously. Once the calibration is completed, a conversion will be performed. At the end of the conversion, $\overline{\text { DRDY }}$ will fall to indicate the first valid conversion after the calibration has been completed.

See Understanding Converter Calibration for details on how the converter calibrates its transfer function.

## Conversion

The conversion state can be entered at the end of the calibration cycle, or whenever the converter is idle in the standby mode. If CONV is taken high to initiate a calibration cycle ( CAL also high), and remains high until the calibration cycle is completed (CAL is taken low after CONV transitions high), the converter will begin a conversion upon completion of the calibration period. The device will perform a conversion on the input channel selected by the A0 and A1 inputs when CONV transitioned high. Table 1 indicates the multiplexer channel selection truth table for A 0 and A 1 .

| A1 | A0 | Channel addressed |
| :---: | :---: | :---: |
| 0 | 0 | AIN1 |
| 0 | 1 | AIN2 |
| 1 | 0 | AIN3 |
| 1 | 1 | AIN4 |

## Table 1. Multiplexer Truth Table

The A0 and A1 inputs are latched internal to the 4-channel devices (CS5505/6) when CONV rises. A0 and A1 have internal pull-down circuits which default the multiplexer to channel

AIN1. The BP/ $\overline{\mathrm{UP}}$ pin is not a latched input. The $\mathrm{BP} / \overline{\mathrm{UP}}$ pin controls how the output word from the digital filter is processed. In bipolar mode the output word computed by the digital filter is offset by 8000 H in the 16 -bit CS5505/7 or 80000H in 20-bit CS5506/8 (see Understanding Converter Calibration). BP/UP can be changed after a conversion is started as long as it is stable for 82 clock cycles of the conversion period prior to $\overline{\text { DRDY }}$ falling. If one wishes to intermix measurement of bipolar and unipolar signals on various input channels, it is best to switch the $\mathrm{BP} / \overline{\mathrm{UP}}$ pin immediately after $\overline{\mathrm{DRDY}}$ falls and leave $\mathrm{BP} / \overline{\mathrm{UP}}$ stable until $\overline{\mathrm{DRDY}}$ falls again. If the converter is beginning a conversion starting from the standby state, BP/UP can be changed at the same time as A 0 and A 1 .

The digital filter in the CS5505/6/7/8 has a Finite Impulse Response and is designed to settle to full accuracy in one conversion time. Therefore, the multiplexer can be changed at the conversion rate.

If CONV is left high, the CS5505/6/7/8 will perform continuous conversions on one channel. The conversion time will be 1622 clock cycles. If conversion is initiated from the standby state, there may be up to two XIN clock cycles of uncertainty as to when conversion actually begins. This is because the internal logic operates at one half the external clock rate and the exact phase of the internal clock may be $180^{\circ}$ out of phase relative to the XIN clock. When a new conversion is initiated from the standby state, it will take up to two XIN clock cycles to begin. Actual conversion will use 1624 clock cycles before $\overline{\text { DRDY }}$ goes low to indicate that the serial port has been updated. See the Serial Interface Logic section of the data sheet for information on reading data from the serial port.

In the event the $\mathrm{A} / \mathrm{D}$ conversion command (CONV going positive) is issued during the conversion state, the current conversion will be
terminated and a new conversion will be initiated.

## Voltage Reference

The CS5505/6/7/8 uses a differential voltage reference input. The positive input is VREF+ and the negative input is VREF-. The voltage between VREF+ and VREF- can range from 1 volt minimum to 3.6 volts maximum. The gain slope will track changes in the reference without recalibration, accommodating ratiometric applications.

The CS5505/6/7/8 include an on-chip voltage reference which outputs 2.5 volts on the VREFOUT pin. This voltage is referenced to the VA+ pin and will track changes relative to VA+. The VREFOUT output requires a $0.1 \mu \mathrm{~F}$ capacitor connected between VREFOUT and VA+ for stability. When using the internal reference, the VREFOUT signal should be connected to the VREF- input and the VREF+ pin should be connected to the VA+ supply. The internal voltage reference is capable of sourcing $3 \mu \mathrm{~A}$ maximum and sinking $50 \mu \mathrm{~A}$ maximum. If a more precise reference voltage is required, an external voltage reference should be used. If an external voltage reference is used, the VREFOUT pin of the internal reference should be connected directly to VA-. It cannot be left open unless the $0.1 \mu \mathrm{~F}$ capacitor is in place for stability.


Figure 5. External Reference Connections


Figure 6. Internal Reference Connections
External reference voltages can range from 1.0 volt minimum to 3.6 volts maximum. The common mode voltage range of the external reference can allow the reference to lie at any voltage between the VA+ and VA- supply rails. Figures 5 and 6 illustrate how the CS5505/6/7/8 converters are connected for external and for internal voltage reference use, respectively.

## Analog Input Range

The analog input range is set by the magnitude of the voltage between the VREF+ and VREFpins. In unipolar mode the input range will equal the magnitude of the voltage reference. In bipolar mode the input voltage range will equate to plus and minus the magnitude of the voltage reference. While the voltage reference can be as great as 3.6 volts, its common mode voltage can be any value as long as the reference inputs VREF+ and VREF- stay within the supply volt-
ages for the A/D. The differential input voltage can also have any common mode value as long as the maximum signal magnitude stays within the supply voltages.

The A/D converter is intended to measure dc or low frequency inputs. It is designed to yield accurate conversions even with noise exceeding the input voltage range as long as the spectral components of this noise will be filtered out by the digital filter. For example, with a 3.0 volt reference in unipolar mode, the converter will accurately convert an input dc signal up to 3.0 volts with up to $15 \%$ overrange for 60 Hz noise. A 3.0 volt dc signal could have a 60 Hz component which is 0.5 volts above the maximum input of 3.0 ( 3.5 volts peak; 3.0 volts dc plus 0.5 volts peak noise) and still accurately convert the input signal (XIN = 32.768 kHz ). This assumes that the signal plus noise amplitude stays within the supply voltages.

The CS5505/6/7/8 converters output data in binary format when converting unipolar signals and in offset binary format when converting bipolar signals. Table 2 outlines the output coding for the 16-bit CS5505/7 and the 20-bit CS5506/8 in both unipolar and bipolar measurement modes.

| CS5505 and CS5507 (16 Bit) |  |  | CS5506 and CS5508 (20 Bit) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Unipolar Input Voltage | Output Codes | Bipolar Input Voltage | Unipolar Input Voltage | Output Codes | Bipolar Input Voltage |
| >(VREF - 1.5 LSB) | FFFF | >(VREF - 1.5 LSB) | >(VREF - 1.5 LSB) | FFFFF | >(VREF - 1.5 LSB) |
| VREF - 1.5 LSB | $\begin{aligned} & \frac{\text { FFFF }}{\text { FFFE }} \end{aligned}$ | VREF-1.5 LSB | VREF - 1.5 LSB | $\begin{aligned} & \text { FFFFF } \\ & \hline \text { FFFFE } \end{aligned}$ | VREF - 1.5 LSB |
| VREF/2-0.5 LSB | $\frac{8000}{7 F F F}$ | -0.5 LSB | VREF/2-0.5 LSB | $\frac{80000}{7 F F F F}$ | -0.5 LSB |
| +0.5 LSB | $\frac{0001}{0000}$ | -VREF + 0.5 LSB | +0.5 LSB | $\frac{00001}{00000}$ | -VREF + 0.5 LSB |
| <(+0.5 LSB) | 0000 | <(-VREF + 0.5 LSB) | <(+0.5 LSB) | 00000 | $<(-\mathrm{VREF}+0.5 \mathrm{LSB})$ |

Note: VREF = (VREF+) - (VREF-); Table excludes common mode voltage on the signal and reference inputs.
Table 2. Output Coding

## Understanding Converter Calibration

Calibration can be performed at any time. A calibration sequence will minimize offset errors and set the gain slope scale factor. The deltasigma modulator in the converter is a differential modulator. To calibrate out offset error, the converter internally connects the modulator differential inputs to an internal VREF- voltage and measures the 1's density output from the modulator. It stores the digital code representation for this 1's density in SRAM and remembers this code as being the zero scale point for the A/D conversion. The converter then connects the negative modulator differential input to the VREF- input and the positive modulator differential input to the VREF+ voltage. The 1's density output from the modulator is then recorded. The converter uses the digital representation of this 1 's density along with the digital code for the zero scale point and calculates a gain scale factor. The gain scale factor is stored in SRAM and used for calculating the proper output codes during conversions.

The states of $\mathrm{A} 0, \mathrm{~A} 1$ and $\mathrm{BP} / \overline{\mathrm{UP}}$ are ignored during calibration but should remain stable throughout the calibration period to minimize noise.

When conversions are performed in unipolar mode or in bipolar mode, the converter uses the same calibration factors to compute the digital output code. The only difference is that in bipolar mode the on-chip microcontroller offsets the computed output word by a code value of

8000 H (16-bit) or 80000 H (20-bit) and multiplies the LSB size by two. This means that the bipolar measurement range is not calibrated from full scale positive to full scale negative. Instead it is calibrated from the bipolar zero scale point to full scale positive. The slope factor is then extended below bipolar zero to accommodate the negative input signals. The converter can be used to convert both unipolar and bipolar signals by changing the $\mathrm{BP} / \overline{\mathrm{UP}}$ pin. Recalibration is not required when switching between unipolar and bipolar modes.

## Converter Performance

The CS5505/6/7/8 A/D converters have excellent linearity performance. Calibration minimizes the errors in offset and gain. The CS5505/7 devices have no missing code performance to 16 -bits. The CS5506/8 devices have no missing code performance to 20-bits. Figure 7 illustrates the DNL of the 16 -bit CS5505. The converters achieve Common Mode Rejection (CMR) at dc of 105 dB typical, and CMR at 50 and 60 Hz of 120 dB typical.

The CS5505/6/7/8 can experience some drift as temperature changes. The CS5505/6/7/8 use chopper-stabilized techniques to minimize drift. Measurement errors due to offset or gain drift can be eliminated at any time by recalibrating the converter.


Figure 7. CS5505 Differential Nonlinearity plot.

## Analog Input Impedance Considerations

The analog input of the CS5505/6/7/8 can be modeled as illustrated in Figure 8 (the model ignores the multiplexer switch resistance). Capacitors ( 15 pF each) are used to dynamically sample each of the inputs (AIN+ and AIN-). Every half XIN cycle the switch alternately connects the capacitor to the output of the buffer and then directly to the AIN pin. Whenever the sample capacitor is switched from the output of the buffer to the AIN pin, a small packet of charge (a dynamic demand of current) is required from the input source to settle the voltage of the sample capacitor to its final value. The voltage on the output of the buffer may differ up to 100 mV from the actual input voltage due to the offset voltage of the buffer. Timing allows one half of a XIN clock cycle for the voltage on the sample capacitor to settle to its final value. The equation which defines the settling time is:

$$
\mathrm{V}_{\mathrm{e}}=\mathrm{V}_{\max } \mathrm{e}^{-\mathrm{t} / \mathrm{RC}}
$$

Where Ve is the final settled value, $\mathrm{V}_{\text {max }}$ is the maximum error voltage value of the input signal, R is the value of the input source resistance, C is the 15 pF sample capacitor plus the value of any stray or additional capacitance at the input pin. The value of $t$ is equal to $1 /(2 \mathrm{XIN})$.


Figure 8. Analog Input Model
$\mathrm{V}_{\text {max }}$ occurs the instant the sample capacitor is switched from the buffer output to the AIN pin. Prior to switching, AIN has an error estimated as being less than or equal to $\mathrm{V}_{\mathrm{e}} . \mathrm{V}_{\text {max }}$ is equal to the prior error ( $\mathrm{V}_{\mathrm{e}}$ ) plus the additional error from the buffer offset. The estimate for $\mathrm{V}_{\text {max }}$ is:

$$
\mathrm{V}_{\max }=\mathrm{V}_{\mathrm{e}}+100 \mathrm{mV} \frac{15 \mathrm{pF}}{\left(15 \mathrm{pF}+\mathrm{C}_{\mathrm{EXT}}\right)}
$$

Where CEXT is the combination of any external or stray capacitance.

From the settling time equation, an equation for the maximum acceptable source resistance is derived.
$R s_{\max }=\frac{-1}{2 \text { XIN }(15 \mathrm{pF}+\text { CEXT }) \ln \left[\frac{\mathrm{V}_{\mathrm{e}}}{\mathrm{V}_{\mathrm{e}}+\frac{15 \mathrm{pF}(100 \mathrm{mv})}{\left(15 \mathrm{pF}+\mathrm{C}_{\text {EXT }}\right)}}\right]}$

This equation assumes that the offset voltage of the buffer is 100 mV , which is the worst case. The value of Ve is the maximum error voltage which is acceptable.

For a maximum error voltage (Ve) of $10 \mu \mathrm{~V}$ in the CS5505 (1/4LSB at 16-bits) and 600 nV in the CS5506 (1/4LSB at 20-bits), the above equation indicates that when operating from a 32.768 kHz XIN, source resistances up to $110 \mathrm{k} \Omega$ in the CS5505 or $84 \mathrm{k} \Omega$ in the CS5506 are acceptable in the absence of external capacitance $($ CEXT $=0)$. If higher input source resistances are desired the master clock rate can be reduced to yield a longer settling time.

The VREF+ and VREF- inputs have nearly the same structure as the AIN+ and AIN- inputs. Therefore, the discussion on analog input impedance applies to the voltage reference inputs as well.

## Digital Filter Characteristics

The digital filter in the CS5505/6/7/8 is the combination of a comb filter and a low pass filter. The comb filter has zeros in its transfer function which are optimally placed to reject line interference frequencies ( 50 and 60 Hz and their multiples) when the CS5505/6/7/8 is clocked at 32.768 kHz . Figures 9, 10 and 11 illustrate the magnitude and phase characteristics of the filter.


Frequency (Hz)
Figure 9. Filter Magnitude Plot to 260 Hz


Figure 10. Filter Magnitude Plot to 50 Hz

Figure 9 illustrates the filter attenuation from dc to 260 Hz . At exactly $50,60,100$, and 120 Hz the filter provides over 120 dB of rejection. Table 3 indicates the filter attenuation for each of the potential line interference frequencies when the converter is operating with a 32.768 kHz clock. The converter yields excellent attenuation of these interference frequencies even if the fundamental line frequency should vary $\pm 1 \%$ from its specified frequency. The -3 dB corner frequency of the filter when operating from a 32.768 kHz clock is 17 Hz . Figure 11 illustrates that the phase characteristics of the filter are precisely linear phase.

| Frequency <br> (Hz) | Notch <br> Depth <br> $(\mathbf{d B})$ | Frequency <br> $(\mathbf{H z})$ | Minimum <br> Attenuation <br> $(\mathbf{d B})$ |
| :---: | :---: | :---: | :---: |
| 50 | 125.6 | $50 \pm 1 \%$ | 55.5 |
| 60 | 126.7 | $60 \pm 1 \%$ | 58.4 |
| 100 | 145.7 | $100 \pm 1 \%$ | 62.2 |
| 120 | 136.0 | $120 \pm 1 \%$ | 68.4 |
| 150 | 118.4 | $150 \pm 1 \%$ | 74.9 |
| 180 | 132.9 | $180 \pm 1 \%$ | 87.9 |
| 200 | 102.5 | $200 \pm 1 \%$ | 94.0 |
| 240 | 108.4 | $240 \pm 1 \%$ | 104.4 |

Table 3. Filter Notch Attenuation (XIN $=\mathbf{3 2 . 7 6 8} \mathbf{~ k H z}$ )


Figure 11. Filter Phase Plot to 50 Hz

If the CS5505/6/7/8 is operated at a clock rate other than 32.768 kHz , the filter characteristics, including the comb filter zeros, will scale with the operating clock frequency. Therefore, optimum rejection of line frequency interference will occur with the CS5505/6/7/8 running at 32.768 kHz . The CS5505/6/7/8 can be used with external clock rates from 30 kHz to 163 kHz .

## Anti-Alias Considerations for Spectral Measurement Applications

Input frequencies greater than one half the output word rate $(C O N V=1)$ may be aliased by the converter. To prevent this, input signals should be limited in frequency to no greater than one half the output word rate of the converter (when CONV =1). Frequencies close to the modulator sample rate (XIN/2) and multiples thereof may also be aliased. If the signal source includes spectral components above one half the output word rate (when CONV $=1$ ) these com-
ponents should be removed by means of lowpass filtering prior to the A/D input to prevent aliasing. Spectral components greater than one half the output word rate on the VREF inputs (VREF+ and VREF-) may also be aliased. Filtering of the reference voltage to remove these spectral components from the reference voltage is desirable.

## Crystal Oscillator

The CS5505/6/7/8 is designed to be operated using a 32.768 kHz "tuning fork" type crystal. One end of the crystal should be connected to the XIN input. The other end should be attached to XOUT. Short lead lengths should be used to minimize stray capacitance. Figure 12 illustrates the gate oscillator, and a simplified version of the control logic used on the chip.

Over the industrial temperature range ( -40 to $+85^{\circ} \mathrm{C}$ ) the on-chip gate oscillator will oscillate


Figure 12. Gate Oscillator and Control Logic
with other crystals in the range of 30 kHz to 53 kHz .

The chip will operate with external clock frequencies from 30 kHz to 163 kHz .

The 32.768 kHz crystal is normally specified as a time-keeping crystal with tight specifications for both initial frequency and for drift over temperature. To maintain excellent frequency stability, these crystals are specified only over limited operating temperature ranges (i.e. -10 to $+60^{\circ} \mathrm{C}$ ) by the manufacturers. Applications of these crystals with the CS5505/6/7/8 do not require tight initial tolerance or low tempco drift. Therefore, a lower cost crystal with looser initial tolerance and tempco will generally be adequate for use with the CS5505/6/7/8 converters. Also check with the manufacturer about wide temperature range application of their standard crystals. Generally, even those crystals specified for limited temperature range will operate over much larger ranges if frequency stability over temperature is not a requirement. The frequency stability can be as bad as $\pm 3000$ ppm over the operating temperature range and still be typically better than the line frequency ( 50 or 60 Hz ) stability over cycle to cycle during the course of a day.

## Serial Interface Logic

The digital filter in the CS5505/6/7/8 takes 1624 clock cycles to compute an output word once a conversion begins. At the end of the conversion cycle, the filter will attempt to update the serial port. Two clock cycles prior to the update DRDY will go high. When DRDY goes high just prior to a port update it checks to see if the port is either empty or unselected $(\overline{\mathrm{CS}}=1)$. If the port is empty or unselected, the digital filter will update the port with a new output word.

When new data is put into the port $\overline{\text { DRDY }}$ will go low.

Data can be read from the serial port in either of two modes. The M/SLP pin determines which serial mode is selected. Serial port mode selection is as follows:

SSC (Synchronous Self-Clocking) mode; M/SLP = VD+, or SEC (Synchronous External Clocking) mode; M/SLP = DGND. Timing diagrams which illustrate the SSC and SEC timing are in the tables section of this data sheet.

## Synchronous Self-Clocking Mode

The serial port operates in the SSC mode when the M/SLP pin is connected to the VD+ pin on the part. In SSC mode the CS5505/6/7/8 furnishes both the serial output data (SDATA) and the serial clock (SCLK). When the serial port is updated at the end of a conversion, $\overline{\text { DRDY falls. }}$ If $\overline{\mathrm{CS}}$ is low, the SDATA and SCLK pins will come out of the high impedance state two XIN clock cycles after DRDY falls. The MSB data bit will be presented for two cycles of XIN clock. The SCLK signal will rise in the middle of the MSB data bit. When SCLK then returns low the (MSB-1) bit will appear. Subsequent data bits will be output on each falling edge of SCLK until the LSB data bit is output. After the LSB data bit is output, the SCLK will fall at which time both the SDATA and SCLK outputs will return to the high impedance output state. $\overline{\mathrm{DRDY}}$ will return high at this time.

If $\overline{\mathrm{CS}}$ is taken low after DRDY falls, the MSB data bit will appear within two XIN clock cycles after $\overline{\mathrm{CS}}$ is taken low. $\overline{\mathrm{CS}}$ need not be held low for the entire data output. If $\overline{\mathrm{CS}}$ is returned high during a data bit the port will complete the output of that bit and then go into the Hi-Z state. The port can be reselected any time prior to the completion of the next conversion (DRDY falling) to allow the remaining data bits to be output.

## Synchronous External-Clocking Mode

The serial port operates in the SEC mode when the M/SLP pin is connected to the DGND pin. SDATA is the output pin for the serial data. When CS goes low after new data becomes available (DRDY goes low), the SDATA pin comes out of Hi-Z with the MSB data bit present. SCLK is the input pin for the serial clock in the SEC mode. If the MSB data bit is on the SDATA pin, the first rising edge of SCLK enables the shifting mechanism. This allows the falling edges of SCLK to shift subsequent data bits out of the port. Note that if the MSB data bit is output and the SCLK signal is high, the first falling edge of SCLK will be ignored because the shifting mechanism has not become activated. After the first rising edge of SCLK, each subsequent falling edge will shift out the serial data. Once the LSB is present, the falling edge of SCLK will cause the SDATA output to go to Hi-Z and $\overline{\mathrm{DRDY}}$ to return high. The serial port register will be updated with a new data word upon the completion of another conversion if the serial port has been emptied, or if the $\overline{\mathrm{CS}}$ is inactive (high).
$\overline{\mathrm{CS}}$ can be operated asynchronously to the $\overline{\text { DRDY signal. The DRDY signal need not be }}$ monitored as long as the $\overline{\mathrm{CS}}$ signal is taken low for at least two XIN clock cycles plus 200 ns prior to SCLK being toggled. This ensures that CS has gained control over the serial port.

## Sleep Mode

The CS5505/6/7/8 devices offer two methods of putting the device into a SLEEP condition to conserve power. Calibration words will be retained in SRAM during either sleep condition. The M/SLP pin can be put into the SLEEP threshold to lower the operating power used by the device to about $1 \%$ of nominal. Alternately, the clock into the XIN pin can be stopped. This will lower the power consumed by the converter to about $30 \%$ of nominal. In both cases, the
converter must go through a wake-up sequence prior to conversions being initiated. This wakeup sequence includes the 10 msec . (typ.) power-on-reset delay, the start-up of the oscillator (unless an external clock is used), and the 1800 clock cycle wake-up delay after the clock begins. When coming out of the sleep condition, the converter will latch the A0 and A1 inputs.

Figure 13 illustrates how to use a gate and resistors to bias the M/SLP pin into the SLEEP threshold region when using the converter in the SSC mode. To use the SEC mode return resistor R1 to DGND instead of the supply. When in the SEC mode configuration the CS5505/6/7/8 will enter the SLEEP threshold when the logic control input is a logic 1 (VD+). Note that large resistors can be used to conserve power while in sleep. The input leakage of the pin is typically less than $1 \mu \mathrm{~A}$ even at $125{ }^{\circ} \mathrm{C}$, although the worst case specification tables indicate a leakage


Figure 13. Sleep Threshold Control
of $10 \mu \mathrm{~A}$ maximum.

## Power Supplies and Grounding

The analog and digital supply pins to the CS5505/6/7/8 are brought out on separate pins to minimize noise coupling between the analog and digital sections of the chip. Note that there is no
analog ground pin. No analog ground pin is required because the inputs for measurement and for the voltage reference are differential and require no ground. In the digital section of the chip the supply current flows into the VD+ pin and out of the DGND pin. As a CMOS device, the CS5505/6/7/8 requires that the supply voltage on the VA+ pin always be more positive than the voltage on any other pin of the device. If this requirement is not met, the device can latch-up or be damaged. In all circumstances the VA+ voltage must remain more positive than the

VD+ or DGND pins; VD+ must remain more positive than the DGND pin.

The following power supply options are possible:

$$
\begin{array}{lrr}
\mathrm{VA}+=+5 \mathrm{~V} \text { to }+10 \mathrm{~V}, \quad \mathrm{VA}-=0 \mathrm{~V}, & \mathrm{VD}+=+5 \mathrm{~V} \\
\mathrm{VA}+=+5 \mathrm{~V}, & \mathrm{VA}-=-5 \mathrm{~V}, & \mathrm{VD}+=+5 \mathrm{~V} \\
\mathrm{VA}+=+5 \mathrm{~V}, & \mathrm{VA}-=0 \mathrm{~V} \text { to }-5 \mathrm{~V}, & \mathrm{VD}+=+3.3 \mathrm{~V}
\end{array}
$$

The CS5505/6/7/8 cannot be operated with a 3.3 V digital supply if VA+ is greater than +5.5 V .


Note: To use the internal 2.5 volt reference see Figure 6.
Figure 14. CS5505/6 System Connection Diagram Using External Reference, Single Supply

Figure 15 illustrates the CS5505/6 using dual supplies of +5 and -5 V .
under any operating condition. Remember to investigate transient power-up conditions, when one power supply may have a faster rise time.


Note: To use the internal 2.5 volt reference see Figure 6.
Figure 15. CS5505/6 System Connection Diagram Using External Reference, Dual Supplies


Note: (1) To use the internal 2.5 volt reference see Figure 6.
(2) VD+ must never exceed VA+. Examine power-up conditions.

Figure 16. CS5505/6 System Connection Diagram Using External Reference, Dual Supply, +10V Analog, +5V Digital

