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Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



Independent Clock Quad HOTLink II™ Transceiver with Reclocker

Features

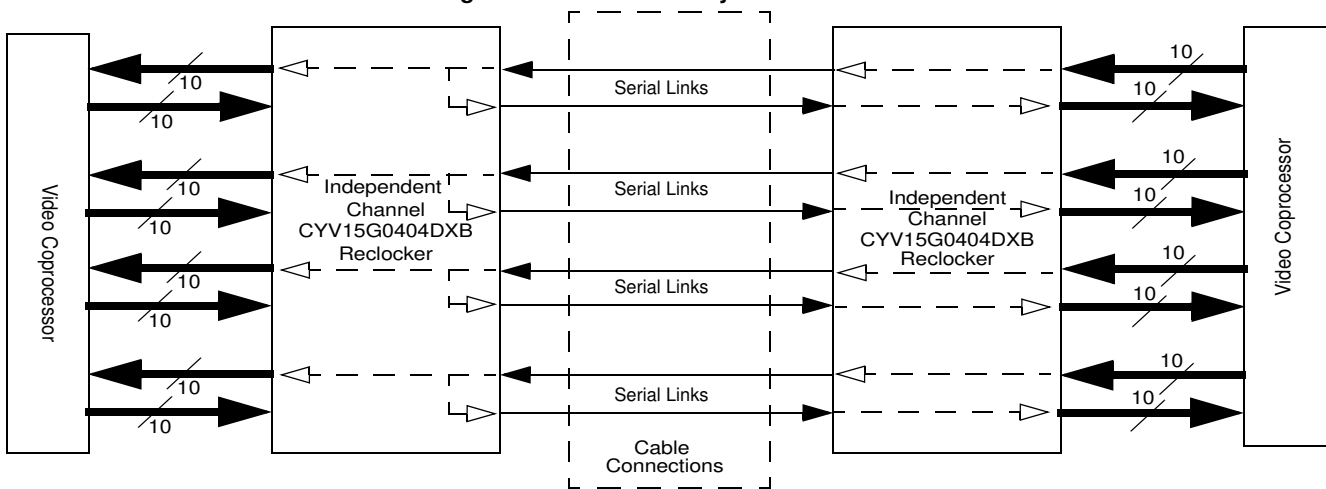
- Quad channel transceiver for 195 to 1500 MBaud serial signaling rate
 - Aggregate throughput of up to 12 Gbits/second
- Second-generation HOTLink® technology
- Compliant to multiple standards
 - SMPTE-292M, SMPTE-259M, DVB-ASI, Fibre Channel, ES-CON, and Gigabit Ethernet (IEEE802.3z)
 - 10 bit uncoded data or 8B/10B coded data
- Truly independent channels
 - Each channel is able to:
 - Perform reclocker function
 - Operate at a different signaling rate
 - Transport a different data format
- Internal phase-locked loops (PLLs) with no external PLL components
- Selectable differential PECL compatible serial inputs per channel
 - Internal DC restoration
- Redundant differential PECL compatible serial outputs per channel
 - No external bias resistors required
 - Signaling rate controlled edge rates
 - Source matched for 50Ω transmission lines
- MultiFrame™ Receive Framer provides alignment options
 - Comma or full K28.5 detect
 - Single or multibyte Framer for byte alignment
 - Low latency option
- Selectable input and output clocking options

- Synchronous LVTTTL parallel interface
- JTAG boundary scan
- Built In Self Test (BIST) for at-speed link testing
- Link quality indicator by channel
 - Analog signal detect
 - Digital signal detect
- Low power 3W at 3.3V typical
- Single 3.3V supply
- 256 ball thermally enhanced BGA
- 0.25μ BiCMOS technology
- JTAG device ID '0C811069'x

Functional Description

The CYV15G0404DXB Independent Clock Quad HOTLink II™ Transceiver is a point-to-point or point-to-multipoint communications building block enabling the transfer of data over a variety of high speed serial links including SMPTE 292, SMPTE 259, and DVB-ASI video applications. The signaling rate can be anywhere in the range of 195 to 1500 MBaud for each serial link. Each channel operates independently with its own reference clock allowing different rates. Each transmit channel accepts parallel characters in an input register, encodes each character for transport, and then converts it to serial data. Each receive channel accepts serial data and converts it to parallel data, decodes the data into characters, and presents these characters to an output register. The received serial data can also be reclocked and retransmitted through the serial outputs. [Figure 1](#) illustrates typical connections between independent video coprocessors and corresponding CYV15G0404DXB chips.

Figure 1. HOTLink II™ System Connections



The CYV15G0404DXB satisfies the SMPTE-259M and SMPTE-292M compliance according to SMPTE EG34-1999 Pathological Test Requirements.

As a second generation HOTLink device, the CYV15G0404DXB extends the HOTLink family with enhanced levels of integration and faster data rates, while maintaining serial link compatibility (data, command, and BIST) with other HOTLink devices. The transmit (TX) section of the CYV15G0404DXB Quad HOTLink II consists of four independent byte-wide channels. Each channel accepts either 8-bit data characters or preencoded 10-bit transmission characters. Data characters may be passed from the transmit input register to an integrated 8B/10B Encoder to improve their serial transmission characteristics. These encoded characters are then serialized and output from dual Positive ECL (PECL) compatible differential transmission-line drivers at a bit rate of either 10 or 20 times the input reference clock for that channel.

The receive (RX) section of the CYV15G0404DXB Quad HOTLink II consists of four independent byte wide channels. Each channel accepts a serial bit stream from one of two PECL-compatible differential line receivers, and using a completely integrated Clock and Data Recovery PLL, recovers the timing information necessary for data reconstruction. Each recovered bit stream is deserialized and framed into characters,

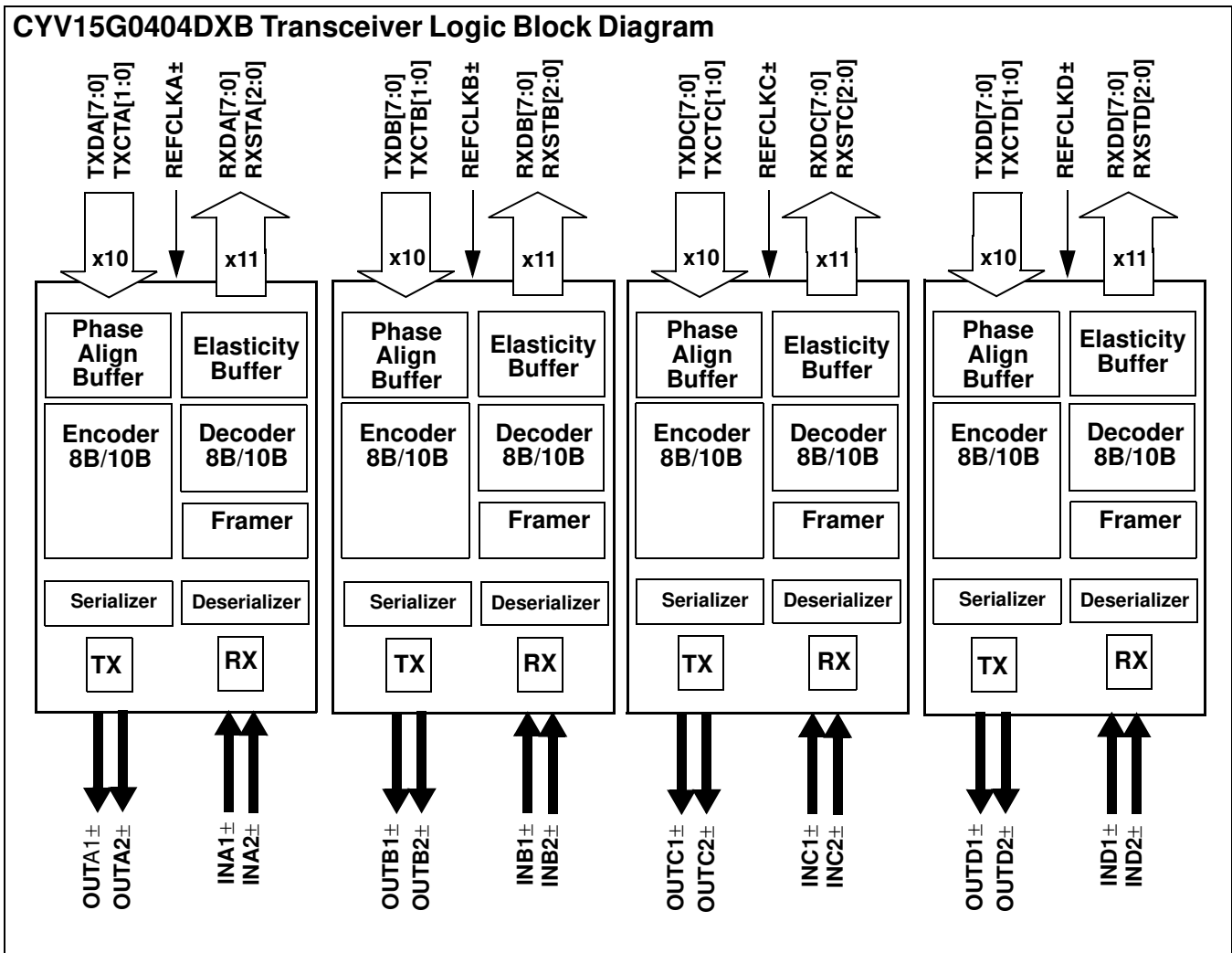
8B/10B decoded, and checked for transmission errors. Recovered decoded characters are then written to an internal elasticity buffer, and presented to the destination host system.

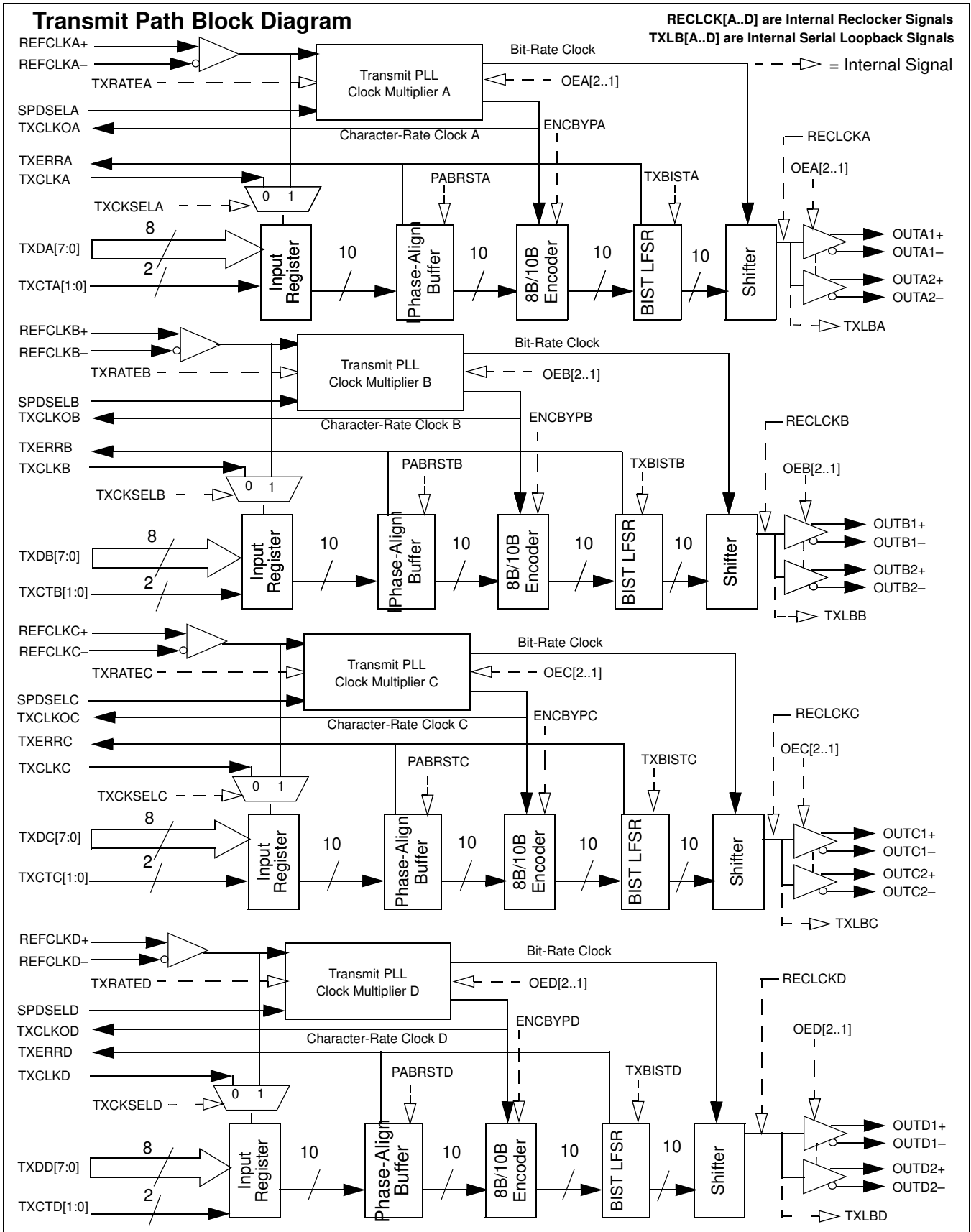
The integrated 8B/10B encoder or decoder may be bypassed for systems that present externally encoded or scrambled data at the parallel interface.

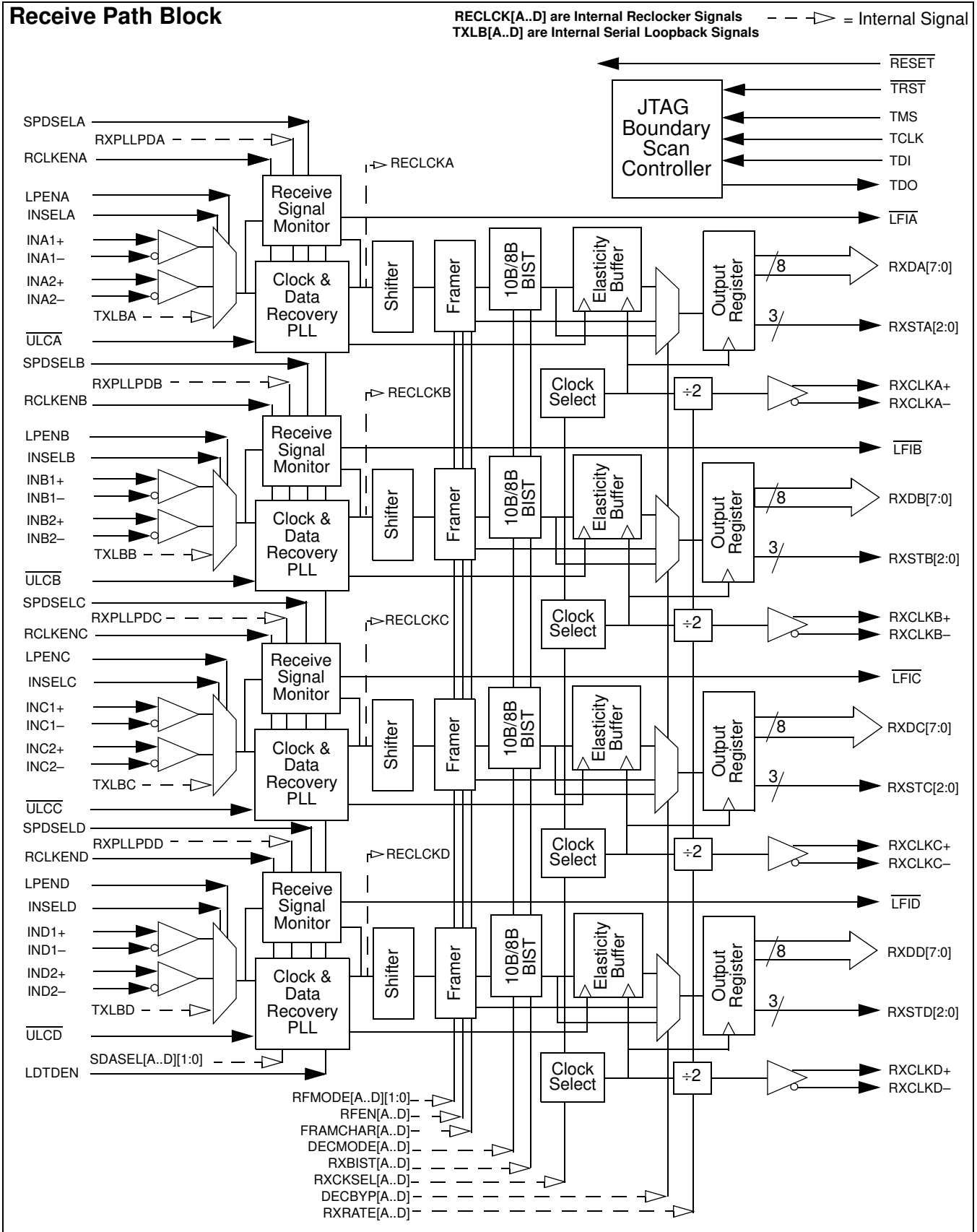
The parallel IO interface may be configured for numerous forms of clocking to provide the highest flexibility in system architecture. In addition to clocking the transmit path with a local reference clock, the receive interface may also be configured to present data relative to a recovered clock or to a local reference clock.

Each transmit and receive channel contains an independent BIST pattern generator and checker. This BIST hardware allows at speed testing of the high speed serial data paths in each transmit and receive section, and across the interconnecting links.

The CYV15G0404DXB is ideal for port applications where different data rates and serial interface standards are necessary for each channel. Some applications include multi-format routers and switchers.

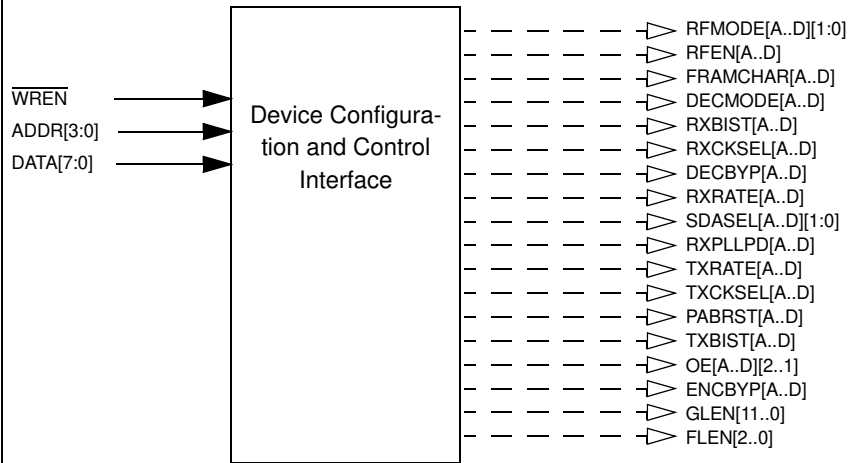






Device Configuration and Control Block

-- ▷ = Internal Signal



Pin Configuration (Top View)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
A	IN C1-	OUT C1-	IN C2-	OUT C2-	V _{CC}	IN D1-	OUT D1-	GND	IN D2-	OUT D2-	IN A1-	OUT A1-	GND	IN A2-	OUT A2-	V _{CC}	IN B1-	OUT B1-	IN B2-	OUT B2-
B	IN C1+	OUT C1+	IN C2+	OUT C2+	V _{CC}	IN D1+	OUT D1+	GND	IN D2+	OUT D2+	IN A1+	OUT A1+	GND	IN A2+	OUT A2+	V _{CC}	IN B1+	OUT B1+	IN B2+	OUT B2+
C	TDI	TMS	INSEL C	INSEL B	V _{CC}	\overline{ULCD}	\overline{ULCC}	GND	DATA [7]	DATA [5]	DATA [3]	DATA [1]	GND	RCLK ENB	SPD SELD	V _{CC}	LDTD EN	\overline{TRST}	LPEND	TDO
D	TCLK		INSEL D	INSEL A	V _{CC}	\overline{ULCA}	SPD SELC	GND	DATA [6]	DATA [4]	DATA [2]	DATA [0]	GND	LPENB	\overline{ULCB}	V _{CC}	LPENA	VCC	SCAN EN2	TMEN3
E	V _{CC}	V _{CC}	V _{CC}	V _{CC}													V _{CC}	V _{CC}	V _{CC}	V _{CC}
F	RX DC[6]	RX DC[7]	TX DC[0]	RCLK END													RCLK ENA	RX STB[1]	TX CLKOB	RX STB[0]
G	TX DC[7]	\overline{WREN}	TX DC[4]	TX DC[1]													SPD SELB	LP ENC	SPD SELA	RX DB[1]
H	GND	GND	GND	GND													GND	GND	GND	GND
J	TX CTC[1]	TX DC[5]	TX DC[2]	TX DC[3]													RX STB[2]	RX DB[0]	RX DB[5]	RX DB[2]
K	RX DC[2]	REF CLKC-	TX CTC[0]	TX CLKC													RX DB[3]	RX DB[4]	RX DB[7]	\overline{LFIB}
L	RX DC[3]	REF CLKC+	\overline{LFIC}	TX DC[6]													RX DB[6]	RX CLKB+	RX CLKB-	TX DB[6]
M	RX DC[4]	RX DC[5]	RCLK ENC	TX ERR C													REF CLKB+	REF CLKB-	TX ERR B	TX CLKB
N	GND	GND	GND	GND													GND	GND	GND	GND
P	RX DC[1]	RX DC[0]	RX STC[0]	RX STC[1]													TX DB[5]	TX DB[4]	TX DB[3]	TX DB[2]
R	RX STC[2]	TX CLKOC	RX CLKC+	RX CLKC-													TX DB[1]	TX DB[0]	TX CTB[1]	TX DB[7]
T	V _{CC}	V _{CC}	V _{CC}	V _{CC}													V _{CC}	V _{CC}	V _{CC}	V _{CC}
U	TX DD[0]	TX DD[1]	TX DD[2]	TX CTD[1]	V _{CC}	RX DD[2]	RX DD[1]	GND	TX CTA[1]	ADDR [0]	REF CLKD-	TX DA[1]	GND	TX DA[4]	TX CTA[0]	V _{CC}	RX DA[2]	TX CTB[0]	RX STA[2]	RX STA[1]
V	TX DD[3]	TX DD[4]	TX CTD[0]	RX DD[6]	V _{CC}	RX DD[3]	RX STD[0]	GND	RX STD[2]	ADDR [2]	REF CLKD+	TX CLKOA	GND	TX DA[3]	TX DA[7]	V _{CC}	RX DA[7]	RX DA[3]	RX DA[0]	RX STA[0]
W	TX DD[5]	TX DD[7]	\overline{LFID}	RX CLKD-	V _{CC}	RX DD[4]	RX STD[1]	GND	ADDR [3]	ADDR [1]	RX CLKA+	TX ERRA	GND	TX DA[2]	TX DA[6]	V _{CC}	\overline{LFIA}	REF CLKA+	RX DA[4]	RX DA[1]
Y	TX DD[6]	TX CLKD	RX DD[7]	RX CLKD+	V _{CC}	RX DD[5]	RX DD[0]	GND	TX CLKOD	NC ⁽¹⁾	TX CLKA	RX CLKA-	GND	TX DA[0]	TX DA[5]	V _{CC}	TX ERRD	REF CLKA-	RX DA[6]	RX DA[5]

Pin Configuration (Bottom View)

	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
A	OUT B2-	IN B2-	OUT B1-	IN B1-	V _{CC}	OUT A2-	IN A2-	GND	OUT A1-	IN A1-	OUT D2-	IN D2-	GND	OUT D1-	IN D1-	V _{CC}	OUT C2-	IN C2-	OUT C1-	IN C1-
B	OUT B2+	IN B2+	OUT B1+	IN B1+	V _{CC}	OUT A2+	IN A2+	GND	OUT A1+	IN A1+	OUT D2+	IN D2+	GND	OUT D1+	IN D1+	V _{CC}	OUT C2+	IN C2+	OUT C1+	IN C1+
C	TDO	LP END	TRST	LDTD EN	V _{CC}	SPD SELD	RCLK ENB	GND	DATA [1]	DATA [3]	DATA [5]	DATA [7]	GND	ULCC	ULCD	V _{CC}	IN SELB	IN SELC	TMS	TDI
D	TMEN3	SCAN EN2	VCC	LP ENA	V _{CC}	ULCB	LP ENB	GND	DATA [0]	DATA [2]	DATA [4]	DATA [6]	GND	SPD SELC	ULCA	V _{CC}	IN SELA	IN SELD	RESET	TCLK
E	V _{CC}	V _{CC}	V _{CC}	V _{CC}													V _{CC}	V _{CC}	V _{CC}	V _{CC}
F	RX STB[0]	TX CLKOB	RX STB[1]	RCLK ENA													RCLK END	TX DC[0]	RX DC[7]	Rx DC[6]
G	RX DB[1]	SPD SELA	LP ENC	SPD SELB													TX DC[1]	TX DC[4]	WREN	TX DC[7]
H	GND	GND	GND	GND													GND	GND	GND	GND
J	RX DB[2]	RX DB[5]	RX DB[0]	RX STB[2]													TX DC[3]	TX DC[2]	TX DC[5]	TX CTC[1]
K	LFIB	RX DB[7]	RX DB[4]	RX DB[3]													TX CLKC	TX CTC[0]	REF CLKC-	RX DC[2]
L	TX DB[6]	RX CLKB-	RX CLKB+	RX DB[6]													TX DC[6]	LFIC	REF CLKC+	RX DC[3]
M	TX CLKB	TX ERRB	REF CLKB-	REF CLKB+													TX ERRC	RCLK ENC	RX DC[5]	RX DC[4]
N	GND	GND	GND	GND													GND	GND	GND	GND
P	TX DB[2]	TX DB[3]	TX DB[4]	TX DB[5]													RX STC[1]	RX STC[0]	RX DC[0]	RX DC[1]
R	TX DB[7]	TX CTB[1]	TX DB[0]	TX DB[1]													RX CLKC-	RX CLKC+	TX CLKOC	RX STC[2]
T	V _{CC}	V _{CC}	V _{CC}	V _{CC}													V _{CC}	V _{CC}	V _{CC}	V _{CC}
U	RX STA[1]	RX STA[2]	TX CTB[0]	RX DA[2]	V _{CC}	TX CTA[0]	TX DA[4]	GND	TX DA[1]	REF CLKD-	ADDR [0]	TXC TA[1]	GND	RX DD[1]	RX DD[2]	V _{CC}	TX CTD[1]	TX DD[2]	TX DD[1]	TX DD[0]
V	RX STA[0]	RX DA[0]	RX DA[3]	RX DA[7]	V _{CC}	TX DA[7]	TX DA[3]	GND	TX CLKOA	REF CLKD+	ADDR [2]	RX STD[2]	GND	RX STD[0]	RX DD[3]	V _{CC}	RX DD[6]	TX CTD[0]	TX DD[4]	TX DD[3]
W	RX DA[1]	RX DA[4]	REF CLKA+	LFIA	V _{CC}	TX DA[6]	TX DA[2]	GND	TX ERRA	RX CLKA+	ADDR [1]	ADDR [3]	GND	RX STD[1]	RX DD[4]	V _{CC}	RX CLKD-	LFID	TX DD[7]	TX DD[5]
Y	RX DA[5]	RX DA[6]	REF CLKA-	TX ERRD	V _{CC}	TX DA[5]	TX DA[0]	GND	RX CLKA-	TX CLKA	NC ^[1]	TX CLKOD	GND	RX DD[0]	RX DD[5]	V _{CC}	RX CLKD+	RX DD[7]	TX CLKD	TX DD[6]

Note
1. NC=Do Not Connect

Pin Definitions

CYV15G0404DXB Quad HOTLink II Transceiver

Name	I/O Characteristics	Signal Description
Transmit Path Data and Status Signals		
TXDA[7:0] TXDB[7:0] TXDC[7:0] TXDD[7:0]	LVTTTL Input, synchronous, sampled by the associated TXCLKx [↑] or REFCLKx [↑] [2]	Transmit Data Inputs. TXDx[7:0] data inputs are captured on the rising edge of the transmit interface clock. The transmit interface clock is selected by the TXCKSELx latch via the device configuration interface, and passed to the encoder or Transmit Shifter. When the Encoder is enabled, TXDx[7:0] specifies the specific data or command character sent.
TXCTA[1:0] TXCTB[1:0] TXCTC[1:0] TXCTD[1:0]	LVTTTL Input, synchronous, sampled by the associated TXCLKx [↑] or REFCLKx [↑] [2]	Transmit Control. TXCTx[1:0] inputs are captured on the rising edge of the transmit interface clock. The transmit interface clock is selected by the TXCKSELx latch through the device configuration interface, and passed to the encoder or transmit shifter. The TXCTA[1:0] inputs identify how the associated TXDx[7:0] characters are interpreted. When the encoder is bypassed, these inputs are interpreted as data bits. When the encoder is enabled, these inputs determine if the TXDx[7:0] character is encoded as data, a special character code, or replaced with other special character codes. See Table 3 for details.
TXERRA TXERRB TXERRC TXERRD	LVTTTL Output, synchronous to REFCLKx [↑] [3], synchronous to RXCLKx when selected as REFCLKx, asynchronous to transmit channel enable/disable, asynchronous to loss or return of REFCLKx [±]	Transmit Path Error. TXERRx is asserted HIGH to indicate detection of a transmit phase align buffer underflow or overflow. If an underflow or overflow condition is detected, TXERRx, for the channel in error, is asserted HIGH and remains asserted until either a word sync sequence is transmitted on that channel, or the transmit phase align buffer is recentered with the PABRSTx latch through the device configuration interface. When TXBISTx = 0, the BIST progress is presented on the associated TXERRx output. The TXERRx signal pulses HIGH for one transmit character clock period to indicate a pass through the BIST sequence once every 511 or 527 (depending on RXCKSELx) character times. If RXCKSELx = 1, a one character pulse occurs every 527 character times. If RXCKSELx = 0, a one character pulse occurs every 511 character times. TXERRx is also asserted HIGH, when any of these conditions is true: <ul style="list-style-type: none"> ■ The TXPLL for the associated channel is powered down. This occurs when OE2x and OE1x for a given channel are simultaneous disabled by setting OE2x = 0 and OE1x = 0. ■ The absence of the REFCLKx[±] signal.
Transmit Path Clock Signals		
REFCLKA [±] REFCLKB [±] REFCLKC [±] REFCLKD [±]	Differential LVPECL or single ended LVTTTL input clock	Reference Clock. REFCLKx [±] clock inputs are used as the timing references for the transmit and receive PLLs. These input clocks may also be selected to clock the transmit and receive parallel interfaces. When driven by a single ended LVCMOS or LVTTTL clock source, connect the clock source to either the true or complement REFCLKx input, and leave the alternate REFCLKx input open (floating). When driven by an LVPECL clock source, the clock must be a differential clock, using both inputs.
TXCLKA TXCLKB TXCLKC TXCLKD	LVTTTL Clock Input, internal pull down	Transmit Path Input Clock. When configuration latch TXCKSELx = 0, the associated TXCLKx input is selected as the character-rate input clock for the TXDx[7:0] and TXCTx[1:0] inputs. In this mode, the TXCLKx input must be frequency-coherent to its associated TXCLKOx output clock, but may be offset in phase by any amount. Once initialized, TXCLKx is allowed to drift in phase as much as ±180 degrees. If the input phase of TXCLKx drifts beyond the handling capacity of the phase align buffer, TXERRx is asserted to indicate the loss of data, and remains asserted until the phase align buffer is initialized. The phase of the TXCLKx input clock relative to its associated REFCLKx [±] is initialized when the configuration latch PABRSTx is written as 0. When the associated TXERRx is deasserted, the phase align buffer is initialized and input characters are correctly captured.

Notes

2. When REFCLKx[±] is configured for half rate operation, these inputs are sampled relative to both the rising and falling edges of the associated REFCLKx[±].
3. When REFCLKx[±] is configured for half rate operation, these outputs are presented relative to both the rising and falling edges of the associated REFCLKx[±].

Pin Definitions (continued)
CYV15G0404DXB Quad HOTLink II Transceiver

Name	I/O Characteristics	Signal Description
TXCLKOA TXCLKOB TXCLKOC TXCLKOD	LVTTTL Output	Transmit Clock Output. TXCLKOx output clock is synthesized by each channel's transmit PLL and operates synchronous to the internal transmit character clock. TXCLKOx operates at either the same frequency as REFCLKx± (TXRATE = 0), or at twice the frequency of REFCLKx± (TXRATE = 1). The transmit clock outputs have no fixed phase relationship to REFCLKx±.
Receive Path Data and Status Signals		
RXDA[7:0] RXDB[7:0] RXDC[7:0] RXDD[7:0]	LVTTTL Output, synchronous to the selected RXCLK± output or REFCLKx± input	Parallel Data Output. RXDx[7:0] parallel data outputs change relative to the receive interface clock. The receive interface clock is selected by the RXCKSELx latch. If RXCLKx± is a full rate clock, the RXCLKx± clock outputs are complementary clocks operating at the character rate. The RXDx[7:0] outputs for the associated receive channels follow rising edge of RXCLKx+ or falling edge of RXCLKx-. If RXCLKx± is a half rate clock, the RXCLKx± clock outputs are complementary clocks operating at half the character rate. The RXDx[7:0] outputs for the associated receive channels follow both the falling and rising edges of the associated RXCLKx± clock outputs.
RXSTA[2:0] RXSTB[2:0] RXSTC[2:0] RXSTD[2:0]	LVTTTL Output, synchronous to the selected RXCLK± output or REFCLKx± input	Parallel Status Output. RXSTA[2:0] status outputs change relative to the receive interface clock. The receive interface clock is selected by the RXCKSELx latch. If RXCLKx± is a full rate clock, the RXCLKx± clock outputs are complementary clocks operating at the character rate. The RXSTAx[2:0] outputs for the associated receive channels follow rising edge of RXCLKx+ or falling edge of RXCLKx-. If RXCLKx± is a half rate clock, the RXCLKx± clock outputs are complementary clocks operating at half the character rate. The RXSTAx[2:0] outputs for the associated receive channels follow both the falling and rising edges of the associated RXCLKx± clock outputs. When the decoder is bypassed, RXSTx[1:0] become the two low-order bits of the 10-bit received character. RXSTx[2] = HIGH indicates the presence of a Comma character in the Output Register. When the decoder is enabled, RXSTx[2:0] provide status of the received signal. See Table 11 for a list of received character status.
Receive Path Clock Signals		
RXCLKA± RXCLKB± RXCLKC± RXCLKD±	LVTTTL Output Clock	Receive Clock Output. RXCLKx± is the receive interface clock used to control timing of the RXDx[7:0] and RXSTA[2:0] parallel outputs. The source of the RXCLKx± outputs is selected by the RXCKSELx latch via the device configuration interface. These true and complement clocks are used to control timing of data output transfers. These clocks are output continuously at either the dual-character rate (1/20 th the serial bit-rate) or character rate (1/10 th the serial bit-rate) of the data being received, as selected by RXRATEx. When configured such that the output data path is clocked by the REFCLKx± instead of a recovered clock, the RXCLKx± output drivers present a buffered or divided form (depending on RXRATEx) of the associated REFCLKx± that are delayed in phase to align with the data. This phase difference allows the user to select the optimal clock (REFCLKx± or RXCLK±) for setup or hold timing for their specific system. When REFCLKx± is a full rate clock, the RXCLKx± rate depends on the value of RXRATEx. When REFCLKx± is a half rate clock and RXCKSELx = 0, the RXCLKx± rate depends on the value of RXRATEx. When REFCLKx± is a half rate clock and RXCKSELx=1, the RXCLKx± rate does not depend on the value of RXRATEx and operates at the same rate as REFCLKx±.
Device Control Signals		
RESET	LVTTTL Input, asynchronous, internal pull up	Asynchronous Device Reset. RESET initializes all state machines, counters, and configuration latches in the device to a known state. RESET must be asserted LOW for a minimum pulse width. When the reset is removed, all state machines, counters, and configuration latches are at an initial state. As per the JTAG specifications, the device RESET cannot reset the JTAG controller. Therefore, the JTAG controller has to be reset separately. Refer to JTAG Support on page 23 for the methods to reset the JTAG state machine. See Table 9 for the initialize values of the device configuration latches.

Pin Definitions (continued)
CYV15G0404DXB Quad HOTLink II Transceiver

Name	I/O Characteristics	Signal Description
LDTDEN	LVTTTL Input, internal pull up	Level Detect Transition Density Enable. When LDTDEN is HIGH, the signal level detector, range controller, and transition density detector are all enabled to determine if the RXPLL tracks REFCLKx± or the selected input serial data stream. If the signal level detector, range controller, or transition density detector are out of their respective limits while LDTDEN is HIGH, the RXPLL locks to REFCLK± until such a time they become valid. The (SDASEL[A..D][1:0]) configure the trip level of the signal level detector. The transition density detector limit is one transition in every 60 consecutive bits. When LDTDEN is LOW, only the range controller determines if the RXPLL tracks REFCLKx± or the selected input serial data stream. For the cases when RXCKSELx = 0 (recovered clock), it is recommended to set LDTDEN = HIGH.
RCLKENA RCLKENB RCLKENC RCLKEND	LVTTTL Input, internal pull down	Reclocker Enable. When RCLKENx is HIGH, the RXPLL performs clock and data recovery functions on the input serial data stream and routes the deserialized data to the RXDx[7:0] and RXSTA[2:0] parallel data outputs as configured by DECBYPx. It also presents the reclocked serial data to the enabled differential serial outputs. When RCLKENx is LOW, the receive reclocker is disabled and the TXDx[7:0] parallel data inputs and TXCTx[1:0] inputs are interpreted (as configured by ENCBYPx) to generate appropriate 10-bit characters that are presented to the differential serial outputs. The reclocker feature is optimized to be used for SMPTE video applications.
ULCA ULCB ULCC ULCD	LVTTTL Input, internal pull up	Use Local Clock. When ULCx is LOW, the RXPLL is forced to lock to REFCLKx± instead of the received serial data stream. While ULCx is LOW, the LFLx for the associated channel is LOW indicating a link fault. When ULCx is HIGH, the RXPLL performs Clock and Data Recovery functions on the input data streams. This function is used in applications in which a stable RXCLKx± is needed. In cases when there is an absence of valid data transitions for a long period of time, or the high-gain differential serial inputs (INx±) are left floating, there may be brief frequency excursions of the RXCLKx± outputs from REFCLKx±.
SPDSELA SPDSELB SPDSELC SPDSELD	3-Level Select ^[4] static control input	Serial Rate Select. The SPDSELx inputs specify the operating signaling rate range of each channel's transmit and receive PLL. LOW = 195 – 400 MBd MID = 400 – 800 MBd HIGH = 800 – 1500 MBd.
INSELA INSELB INSELC INSELD	LVTTTL Input, asynchronous	Receive Input Selector. The INSELx input determines which external serial bit stream is passed to the receiver's clock and data recovery circuit. When INSELx is HIGH, the primary differential serial data input, INx1±, is selected for the associated receive channel. When INSELx is LOW, the secondary differential serial data input, INx2±, is selected for the associated receive channel.
LPENA LPENB LPENC LPEND	LVTTTL Input, asynchronous, internal pull down	Loop Back Enable. The LPENx input enables the internal serial loop back for the associated channel. When LPENx is HIGH, the transmit serial data from the associated channel is internally routed to the associated receive Clock and Data Recovery (CDR) circuit. All enabled serial drivers on the channel are forced to differential logic-1, and the serial data inputs are ignored. When LPENx is LOW, the internal serial loop back function is disabled.

Notes

- 3-Level Select inputs are used for static configuration. These are ternary inputs that make use of logic levels of LOW, MID, and HIGH. The LOW level is usually implemented by direct connection to V_{SS} (ground). The HIGH level is usually implemented by direct connection to V_{CC} (power). The MID level is usually implemented by not connecting the input (left floating), which allows it to self bias to the proper level.
- See [Device Configuration and Control Interface](#) for detailed information on the operation of the Configuration Interface.

Pin Definitions (continued)
CYV15G0404DXB Quad HOTLink II Transceiver

Name	I/O Characteristics	Signal Description
LFIA LFIB LFIC LFID	LVTTTL Output, asynchronous	Link Fault Indication Output. LFlx is an output status indicator signal. LFlx is the logical OR of five internal conditions. LFlx is asserted LOW when any of these conditions are true: <ul style="list-style-type: none"> ■ Received serial data rate outside expected range ■ Analog amplitude below expected levels ■ Transition density lower than expected ■ Receive channel disabled ■ $\overline{\text{ULCx}}$ is LOW ■ No REFCLKx±.
Device Configuration and Control Bus Signals		
WREN	LVTTTL input, asynchronous, internal pull up	Control Write Enable. The WREN input writes the values of the DATA[7:0] bus into the latch specified by the address location on the ADDR[3:0] bus. ^[5]
ADDR[3:0]	LVTTTL input asynchronous, internal pull up	Control Addressing Bus. The ADDR[3:0] bus is the input address bus used to configure the device. The WREN input writes the values of the DATA[7:0] bus into the latch specified by the address location on the ADDR[3:0] bus. ^[5] Table 9 lists the configuration latches within the device, and the initialization value of the latches upon the assertion of RESET. Table 10 shows how the latches are mapped in the device.
DATA[7:0]	LVTTTL input asynchronous, internal pull up	Control Data Bus. The DATA[7:0] bus is the input data bus used to configure the device. The WREN input writes the values of the DATA[7:0] bus into the latch specified by address location on the ADDR[3:0] bus. ^[5] Table 9 lists the configuration latches within the device, and the initialization value of the latches upon the assertion of RESET. Table 10 shows how the latches are mapped in the device.
Internal Device Configuration Latches		
RFMODE[A..D][1:0]	Internal Latch ^[6]	Reframe Mode Select.
FRAMCHAR[A..D]	Internal Latch ^[6]	Framing Character Select.
DECMODE[A..D]	Internal Latch ^[6]	Receiver Decoder Mode Select.
DECBYP[A..D]	Internal Latch ^[6]	Receiver Decoder Bypass.
RXCKSEL[A..D]	Internal Latch ^[6]	Receive Clock Select.
RXRATE[A..D]	Internal Latch ^[6]	Receive Clock Rate Select.
SDASEL[A..D][1:0]	Internal Latch ^[6]	Signal Detect Amplitude Select.
ENCBYP[A..D]	Internal Latch ^[6]	Transmit Encoder Bypass.
TXCKSEL[A..D]	Internal Latch ^[6]	Transmit Clock Select.
TXRATE[A..D]	Internal Latch ^[6]	Transmit PLL Clock Rate Select.
RFEN[A..D]	Internal Latch ^[6]	Reframe Enable.
RXPLLPD[A..D]	Internal Latch ^[6]	Receive Channel Power Control.
RXBIST[A..D]	Internal Latch ^[6]	Receive Bist Disabled.
TXBIST[A..D]	Internal Latch ^[6]	Transmit Bist Disabled.
OE2[A..D]	Internal Latch ^[6]	Differential Serial Output Driver 2 Enable.
OE1[A..D]	Internal Latch ^[6]	Differential Serial Output Driver 1 Enable.
PABRST[A..D]	Internal Latch ^[6]	Transmit Clock Phase Alignment Buffer Reset.
GLEN[11..0]	Internal Latch ^[6]	Global Latch Enable.
FGLEN[2..0]	Internal Latch ^[6]	Force Global Latch Enable.

Note
6. See *Device Configuration and Control Interface* for detailed information on the internal latches.

Pin Definitions (continued)
CYV15G0404DXB Quad HOTLink II Transceiver

Name	I/O Characteristics	Signal Description
Factory Test Modes		
SCANEN2	LVTTTL input, internal pull down	Factory Test 2. SCANEN2 input is for factory testing only. Leave this input as a NO CONNECT or GND only.
TMEN3	LVTTTL input, internal pull down	Factory Test 3. TMEN3 input is for factory testing only. Leave this input as a NO CONNECT or GND only.
Analog I/O		
OUTA1± OUTB1± OUTC1± OUTD1±	CML Differential Output	Primary Differential Serial Data Output. The OUTx1± PECL-compatible CML outputs (+3.3V referenced) are capable of driving terminated transmission lines or standard fiber-optic transmitter modules, and must be AC coupled for PECL compatible connections.
OUTA2± OUTB2± OUTC2± OUTD2±	CML Differential Output	Secondary Differential Serial Data Output. The OUTx2± PECL-compatible CML outputs (+3.3V referenced) are capable of driving terminated transmission lines or standard fiber optic transmitter modules, and must be AC coupled for PECL compatible connections.
INA1± INB1± INC1± IND1±	Differential Input	Primary Differential Serial Data Input. The INx1± input accepts the serial data stream for deserialization and decoding. The INx1± serial stream is passed to the receive CDR circuit to extract the data content when INSELx = HIGH.
INA2± INB2± INC2± IND2±	Differential Input	Secondary Differential Serial Data Input. The INx2± input accepts the serial data stream for deserialization and decoding. The INx2± serial stream is passed to the receiver CDR circuit to extract the data content when INSELx = LOW.
JTAG Interface		
TMS	LVTTTL Input, internal pull up	Test Mode Select. Used to control access to the JTAG Test Modes. If maintained high for ≥5 TCLK cycles, the JTAG test controller is reset.
TCLK	LVTTTL Input, internal pull down	JTAG Test Clock.
TDO	3-State LVTTTL Output	Test Data Out. JTAG data output buffer. High-Z while JTAG test mode is not selected.
TDI	LVTTTL Input, internal pull up	Test Data In. JTAG data input port.
TRST	LVTTTL Input, internal pull up	JTAG reset signal. When asserted (LOW), this input asynchronously resets the JTAG test access port controller.
Power		
V _{CC}		+3.3V Power.
GND		Signal and Power Ground for all internal circuits.

CYV15G0404DXB HOTLink II Operation

The CYV15G0404DXB is a highly configurable, independent clocking, quad-channel transceiver designed to support reliable transfer of large quantities of data, using high speed serial links from multiple sources to multiple destinations. This device supports four single byte channels.

CYV15G0404DXB Transmit Data Path
Input Register

The bits in the Input Register for each channel support different assignments, based on if the input data is encoded or unencoded. These assignments are shown in [Table 1](#).

When the ENCODER is enabled, each input register captures eight data bits and two control bits on each input clock cycle.

When the encoder is bypassed, the control bits are part of the preencoded 10-bit character.

When the encoder is enabled, the TXCTx[1:0] bits are interpreted along with the associated TXDx[7:0] character to generate a specific 10-bit transmission character.

Phase Align Buffer

Data from each input register is passed to the associated phase align buffer, when the TXDx[7:0] and TXCTx[1:0] input registers are clocked using TXCLKx_i (TXCKSELx = 0 and TXRATEx = 0). When the TXDx[7:0] and TXCTx[1:0] input registers are clocked using REFCLKx± (TXCKSELx = 1) and REFCLKx± is a full rate clock, the associated phase alignment buffer in the transmit path is bypassed. These buffers are used to absorb clock phase differences between the TXCLKx input clock and the internal character clock for that channel.

Once initialized, TXCLKx is allowed to drift in phase as much as ±180 degrees. If the input phase of TXCLKx drifts beyond the handling capacity of the phase align buffer, TXERRx is asserted to indicate the loss of data, and remains asserted until the phase align buffer is initialized. The phase of the TXCLKx relative to its associated internal character rate clock is initialized when the configuration latch PABRSTx is written as 0. When the associated TXERRx is deasserted, the phase align buffer is initialized and input characters are correctly captured.

Table 1. Input Register Bit Assignments^[7]

Signal Name	Unencoded	Encoded
TXDx[0] (LSB)	DINx[0]	TXDx[0]
TXDx[1]	DINx[1]	TXDx[1]
TXDx[2]	DINx[2]	TXDx[2]
TXDx[3]	DINx[3]	TXDx[3]
TXDx[4]	DINx[4]	TXDx[4]
TXDx[5]	DINx[5]	TXDx[5]
TXDx[6]	DINx[6]	TXDx[6]
TXDx[7]	DINx[7]	TXDx[7]
TXCTx[0]	DINx[8]	TXCTx[0]
TXCTx[1] (MSB)	DINx[9]	TXCTx[1]

Note
7. LSB shifted out first.

If the phase offset between the initialized location of the input clock and REFCLKx exceeds the skew handling capabilities of the phase align buffer, an error is reported on that channel's TXERRx output. This output indicates an error continuously until the phase align buffer for that channel is reset. While the error remains active, the transmitter for that channel outputs a continuous C0.7 character to indicate to the remote receiver that an error condition is present in the link.

Each phase align buffer may be individually reset with minimal disruption of the serial data stream. When a phase align buffer error is present, the transmission of a word sync sequence recenters the phase align buffer and clears the error indication.

Note. K28.5 characters may be added or removed from the data stream during the phase align buffer reset operation. When used with non-Cypress devices that require a complete 16-character word sync sequence for proper receive elasticity buffer operation, follow the phase alignment buffer reset by a word sync sequence to ensure proper operation.

Encoder

Each character received from the Input register or phase align buffer is passed to the encoder logic. This block interprets each character and any associated control bits, and outputs a 10-bit transmission character.

Depending on the operational mode, the generated transmission character may be

- The 10-bit preencoded character accepted in the input register.
- The 10-bit equivalent of the 8-bit Data character accepted in the input register
- The 10-bit equivalent of the 8-bit Special Character code accepted in the input register
- The 10-bit equivalent of the C0.7 violation character if a phase align buffer overflow or underflow error is present
- A character that is part of the 511-character BIST sequence
- A K28.5 character generated as an individual character or as part of the 16-character Word Sync Sequence

Data Encoding

Raw data, as received directly from the transmit input register, is seldom in a form suitable for transmission across a serial link. The characters must usually be processed or transformed to guarantee

- a minimum transition density (to allow the receive PLL to extract a clock from the serial data stream)
- A DC-balance in the signaling (to prevent baseline wander)
- Run length limits in the serial data (to limit the bandwidth requirements of the serial link)
- the remote receiver a way of determining the correct character boundaries (framing)

When the encoder is enabled (ENCBYPx = 1), the characters transmitted are converted from data or special character codes to 10-bit transmission characters, using an integrated 8B/10B encoder. When directed to encode the character as a special character code, the encoder uses the special character encoding rules listed in Table 15. When directed to encode the character as a data character, it is encoded using the data character encoding rules in Table 14.

The 8B/10B encoder is standards compliant with ANSI/NCITS ASC X3 230-1994 Fibre Channel, IEEE 802.3z Gigabit Ethernet, the IBM® ESCON® and FICON™ channels, ETSI DVB-ASI, and ATM Forum standards for data transport.

Many of the special character codes listed in Table 15 may be generated by more than one input character. The CYV15G0404DXB is designed to support two independent (but non-overlapping) special character code tables. This allows the CYV15G0404DXB to operate in mixed environments with other Cypress HOTLink devices using the enhanced Cypress command code set, and the reduced command sets of other non-Cypress devices. Even when used in an environment that normally uses non-Cypress Special Character codes, the selective use of Cypress command codes can permit operation where running disparity and error handling must be managed.

Following conversion of each input character from eight bits to a 10-bit transmission character, it is passed to the transmit shifter and is shifted out LSB first, as required by ANSI and IEEE standards for 8B/10B coded serial data streams.

Transmit Modes

Encoder Bypass

When the Encoder is bypassed, the character captured from the TXDx[7:0] and TXCTx[1:0] input register is passed directly to the transmit shifter without modification. With the encoder bypassed, the TXCTx[1:0] inputs are considered part of the data character and do not perform a control function that would otherwise modify the interpretation of the TXDx[7:0] bits. The bit usage and mapping of these control bits when the Encoder is bypassed is shown in Table 2.

Table 2. Encoder Bypass Mode

Signal Name	Bus Weight	10B Name
TXDx[0] (LSB)	2 ⁰	a ^[7]
TXDx[1]	2 ¹	b
TXDx[2]	2 ²	c
TXDx[3]	2 ³	d
TXDx[4]	2 ⁴	e
TXDx[5]	2 ⁵	i
TXDx[6]	2 ⁶	f
TXDx[7]	2 ⁷	g
TXCTx[0]	2 ⁸	h
TXCTx[1] (MSB)	2 ⁹	j

When the encoder is enabled, the TXCTx[1:0] data control bits control the interpretation of the TXDx[7:0] bits and the characters generated by them. These bits are interpreted as listed in Table 3.

Table 3. Transmit Modes

TXCTx[1]	TXCTx[0]	Characters Generated
0	0	Encoded data character
0	1	K28.5 fill character
1	0	Special character code
1	1	16-character Word Sync Sequence

Word Sync Sequence

When TXCTx[1:0] = 11, a 16-character sequence of K28.5 characters, known as a word sync sequence, is generated on the associated channel. This sequence of K28.5 characters may start with either a positive or negative disparity K28.5 (as determined by the current running disparity and the 8B/10B coding rules). The disparity of the second and third K28.5 characters in this sequence are reversed from what normal 8B/10B coding rules would generate. The remaining K28.5 characters in the sequence follow all 8B/10B coding rules. The disparity of the generated K28.5 characters in this sequence follow a pattern of either ++-+-+--+--+--+--+--+ or -+--+--+--+--+--+--+.

The generation of this sequence, once started, cannot be stopped until all 16 characters have been sent. The content of the associated input registers are ignored for the duration of this

sequence. At the end of this sequence, if the TXCTx[1:0] = 11 condition is sampled again, the sequence restarts and remains uninterrupted for the following 15 character clocks.

Transmit BIST

Each transmit channel contains an internal pattern generator that can be used to validate both the link and device operation. These generators are enabled by the associated TXBISTx latch through the device configuration interface. When enabled, a register in the associated transmit channel becomes a signature pattern generator by logically converting to a Linear Feedback Shift Register (LFSR). This LFSR generates a 511-character (or 526-character) sequence that includes all data and special character codes, including the explicit violation symbols. This provides a predictable yet pseudo-random sequence that can be matched to an identical LFSR in the attached Receiver(s).

A device reset (RESET sampled LOW) presets the BIST enable latches to disable BIST on all channels.

All data and data-control information present at the associated TXDx[7:0] and TXCTx[1:0] inputs are ignored when BIST is active on that channel. If the receive channels are configured for reference clock operation, each pass is preceded by a 16-character word sync sequence to allow elasticity buffer alignment and management of clock frequency variations.

Transmit PLL Clock Multiplier

Each Transmit PLL Clock Multiplier accepts a character rate or half character-rate external clock at the associated REFCLKx± input, and that clock is multiplied by 10 or 20 (as selected by TXRATEx) to generate a bit rate clock for use by the transmit shifter. It also provides a character rate clock used by the transmit paths, and outputs this character rate clock as TXCLKOx.

Each clock multiplier PLL is able to accept a REFCLKx± input between 19.5 MHz and 150 MHz, however, this clock range is limited by the operating mode of the CYV15G0404DXB clock multiplier (TXRATEx) and by the level on the associated SPDSELx input.

SPDSELx are 3-level select^[4] inputs that select one of three operating ranges for the serial data outputs and inputs of the associated channel. The operating serial signaling rate and allowable range of REFCLKx± frequencies are listed in Table 4.

Table 4. Operating Speed Settings

SPDSELx	TXRATE	REFCLKx± Frequency (MHz)	Signaling Rate (MBaud)
LOW	1	reserved	195 – 400
	0	19.5 – 40	
MID (Open)	1	20 – 40	400 – 800
	0	40 – 80	
HIGH	1	40 – 75	800 – 1500
	0	80 – 150	

The REFCLKx± inputs are differential inputs with each input internally biased to 1.4V. If the REFCLKx+ input is connected to a TTL, LVTTTL, or LVCMOS clock source, the input signal is recognized when it passes through the internally biased reference point. When driven by a single-ended TTL, LVTTTL, or LVCMOS clock source, connect the clock source to either the true or complement REFCLKx input, and leave the alternate REFCLKx input open (floating).

When both the REFCLKx+ and REFCLKx- inputs are connected, the clock source must be a differential clock. This can either be a differential LVPECL clock that is DC- or AC-coupled or a differential LVTTTL or LVCMOS clock.

By connecting the REFCLKx- input to an external voltage source, it is possible to adjust the reference point of the REFCLKx+ input for alternate logic levels. When doing so, ensure that the input differential crossing point remains within the parametric range supported by the input.

Serial Output Drivers

The serial output interface drivers use differential Current Mode Logic (CML) drivers to provide source matched drivers for transmission lines. These drivers accept data from the transmit shifters. They have signal swings equivalent to that of standard PECL drivers, and are capable of driving AC-coupled optical modules or transmission lines. When configured for local loopback (LPENx = HIGH), all enabled serial drivers are configured to drive a static differential logic 1.

Transmit Channels Enabled

Each driver can be enabled or disabled separately using the device configuration interface.

When a driver is disabled through the configuration interface, it is internally powered down to reduce device power. If both serial drivers for a channel are in this disabled state, the associated internal logic for that channel is also powered down. A device reset (RESET sampled LOW) disables all output drivers.^[8]

CYV15G0404DXB Receive Data Path

Serial Line Receivers

Two differential line receivers, INx1± and INx2±, are available on each channel for accepting serial data streams. The active serial line receiver on a channel is selected using the associated INSELx input. The serial line receiver inputs are differential, and can accommodate wire interconnect and filtering losses or transmission line attenuation greater than 16 dB. For normal operation, these inputs should receive a signal of at least $V_{DIFF} > 100\text{ mV}$, or 200 mV peak-to-peak differential. Each Line Receiver can be DC- or AC-coupled to +3.3V powered fiber optic interface modules (any ECL/PECL family, not limited to 100K PECL) or AC-coupled to +5V powered optical modules. The common mode tolerance of these line receivers accommodates a wide range of signal termination voltages. Each receiver provides internal DC-restoration, to the center of the receiver's common mode range, for AC-coupled signals.

Notes

8. When a disabled transmit channel (i.e., both outputs disabled) is re-enabled, the data on the serial outputs may not meet all timing specifications for up to 250 ms.
9. The peak amplitudes listed in this table are for typical waveforms that have generally 3 – 4 transitions for every ten bits. In a worse case environment the signals may have a sign-wave appearance (highest transition density with repeating 0101...). Signal peak amplitudes levels within this environment type could increase the values in the table above by approximately 100 mV.

The local internal loopback (LPENx) allows the serial transmit data outputs to be routed internally back to the clock and data recovery circuit associated with each channel. When configured for local loopback, the associated transmit serial driver outputs are forced to output a differential logic-1. This prevents local diagnostic patterns from being broadcast to attached remote receivers.

Signal Detect/Link Fault

Each selected line receiver (that is routed to the clock and data recovery PLL) is simultaneously monitored for:

- Analog amplitude above amplitude level selected by SDASELx
- Transition density above the specified limit
- Range controls report the received data stream inside normal frequency range ($\pm 1500\text{ ppm}$)
- Receive channel enabled
- The presence of a reference clock
- \overline{ULCx} is not asserted.

All of these conditions must be valid for the signal detect block to indicate a valid signal is present. This status is presented on the LFIx (Link Fault Indicator) output associated with each receive channel, which changes synchronous to the selected receive interface clock.

Analog Amplitude

While most signal monitors are based on fixed constants, the analog amplitude level detection is adjustable to allow operation with highly attenuated signals, or in high noise environments. The analog amplitude level detection is set by the SDASELx latch via device configuration interface. The SDASELx latch sets the trip point for the detection of a valid signal at one of three levels, as listed in Table 5. This control input affects the analog monitors for all receive channels.

Table 5. Analog Amplitude Detect Valid Signal Levels^[9]

SDASEL	Typical Signal with Peak Amplitudes Above
00	Analog Signal Detector is disabled
01	140 mV p-p differential
10	280 mV p-p differential
11	420 mV p-p differential

The analog signal detect monitors are active for the line receiver as selected by the associated INSELx input. When configured for local loopback, no input receivers are selected, and the LFIx output for each channel reports only the receive VCO frequency out-of-range and transition density status of the associated transmit signal. When local loopback is active, the associated analog signal detect monitor is disabled.

Transition Density

The transition detection logic checks for the absence of transitions spanning greater than six transmission characters (60 bits). If no transitions are present in the data received, the detection logic for that channel asserts LFIx.

Range Controls

The CDR circuit includes logic to monitor the frequency of the PLL Voltage Controlled Oscillator (VCO) used to sample the incoming data stream. This logic ensures that the VCO operates at, or near the rate of the incoming data stream for two primary cases:

- When the incoming data stream resumes after a time in which it has been “missing.”
- When the incoming data stream is outside the acceptable signaling rate range.

To perform this function, the frequency of the RXPLL VCO is periodically compared to the frequency of the REFCLKx± input.

If the VCO is running at a frequency beyond ±1500 ppm, as defined by the REFCLKx± frequency, it is periodically forced to the correct frequency (as defined by REFCLKx±, SPDSELx, and TXRATEx) and then released in an attempt to lock to the input data stream.

The sampling and relock period of the range control is calculated in the following manner: RANGE_CONTROL_SAMPLING_PERIOD = (RECOVERED BYTE CLOCK PERIOD) * (4096).

During the time that the range control forces the RXPLL VCO to track REFCLKx±, the LFIx output is asserted LOW. After a valid serial data stream is applied, it may take up to one RANGE_CONTROL_SAMPLING_PERIOD before the PLL locks to the input data stream, after which LFIx should be HIGH.

Receive Channel Enabled

The CYV15G0404DXB contains four receive channels that can be independently enabled and disabled. Each channel can be enabled or disabled separately through the RXPLLPDx input latch as controlled by the device configuration interface. When the RXPLLPDx latch = 0, the associated PLL and analog circuitry of the channel is disabled. Any disabled channel indicates a constant link fault condition on the LFIx output. When RXPLLPDx = 1, the associated PLL and receive channel is enabled to receive and decode a serial stream.

Note. When a disabled receive channel is reenabled, the status of the associated LFIx output and data on the parallel outputs for the associated channel may be indeterminate for up to 2 ms.

Clock/Data Recovery

The extraction of a bit-rate clock and recovery of bits from each received serial stream is performed by a separate CDR block within each receive channel. The clock extraction function is performed by an integrated PLL that tracks the frequency of the transitions in the incoming bit stream and align the phase of the internal bit rate clock to the transitions in the selected serial data stream.

Each CDR accepts a character rate (bit-rate ÷ 10) or half-character rate (bit-rate ÷ 20) reference clock from the associated REFCLKx± input. This REFCLKx± input is used to

- Ensure that the VCO (within the CDR) is operating at the correct frequency (rather than a harmonic of the bit-rate)
- Reduce PLL acquisition time
- Limit unlocked frequency excursions of the CDR VCO when there is no input data present at the selected serial line receiver.

Regardless of the type of signal present, the CDR attempts to recover a data stream from it. If the signalling rate of the recovered data stream is outside the limits set by the range control monitors, the CDR tracks REFCLKx± instead of the data stream. Once the CDR output (RXCLK±) frequency returns close to REFCLKx± frequency, the CDR input is switched back to the input data stream. If no data is present at the selected line receiver, this switching behavior may result in brief RXCLK± frequency excursions from REFCLKx±. However, the validity of the input data stream is indicated by the LFIx output. The frequency of REFCLKx± is required to be within ±1500 ppm of the frequency of the clock that drives the REFCLKx± input of the remote transmitter to ensure a lock to the incoming data stream.

For systems using multiple or redundant connections, the LFIx can be output to select an alternate data stream. When an LFIx indication is detected, external logic can toggle selection of the associated INx1± and INx2± input through the associated INSELx input. When a port switch takes place, it is necessary for the receive PLL for that channel to reacquire the new serial stream and frame to the incoming character boundaries.

Reclocker

The CYV15G0404DXB contains a reclocker mode on each receive channel that can be independently enabled and disabled. When the reclocker mode is enabled by RCLKENx, the received serial data is reclocked and transmitted through the enabled differential serial outputs of the selected channel. In the reclocker mode, the RXPLL performs clock and data recovery functions on the input serial data stream and the reclocked serial data is routed to the enabled differential serial outputs. The serial data is also routed to the deserializer and the deserialized data is presented to the RXDx[7:0] and RXSTA[2:0] parallel data outputs as configured by DECBYPx. When the reclocker is enabled, the data on the TXDx[7:0] and TXCT[1:0] is ignored and not transmitted through the enabled serial outputs.

Deserializer/Framer

Each CDR circuit extracts bits from the associated serial data stream and clocks these bits into the shifter/framer at the bit clock rate. When enabled, the framer examines the data stream looking for one or more COMMA or K28.5 characters at all possible bit positions. The location of this character in the data stream determines the character boundaries of all following characters.

Framing Character

The CYV15G0404DXB allows selection of different framing characters on each channel. Two combinations of framing characters are supported to meet the requirements of different interfaces. The selection of the framing character is made

through the FRAMCHARx latches through the configuration interface.

The specific bit combinations of these framing characters are listed in Table 6. When the specific bit combination of the selected framing character is detected by the framer, the boundaries of the characters present in the received data stream are known.

Table 6. Framing Character Selector

FRAMCHARx	Bits Detected in Framer	
	Character Name	Bits Detected
0	COMMA+ COMMA-	00111110XX ^[10] or 11000001XX
1	-K28.5 +K28.5	0011111010 or 1100000101

Framer

The framer on each channel operates in one of three different modes. Each framer is enabled or disabled using the RFENx latches using the configuration interface. When the framer is disabled (RFENx = 0), no combination of received bits alters the frame information.

When the low latency framer is selected (RFMODEx[1:0] = 00), the framer operates by stretching the recovered character clock until it aligns with the received character boundaries. In this mode the framer starts its alignment process on the first detection of the selected framing character. To reduce the impact on external circuits that use the recovered clock, the clock period is not stretched by more than two bit periods in any one clock cycle. When operated with a character rate output clock, the output of properly framed characters may be delayed by up to nine character clock cycles from the detection of the selected framing character. When operated with a half character rate output clock, the output of properly framed characters may be delayed by up to 14 character clock cycles from the detection of the framing character.

When RFMODEx[1:0] = 10, the Cypress-Mode Multi-Byte framer is selected. The required detection of multiple framing characters makes the associated link much more robust to incorrect framing due to aliased SYNC characters in the data stream. In this mode, the framer does not adjust the character clock boundary, but instead aligns the character to the already recovered character clock. This ensures that the recovered clock does not contain any significant phase changes or hops during normal operation or framing, and allows the recovered clock to be replicated and distributed to other external circuits or components using PLL-based clock distribution elements. In this framing mode the character boundaries are only adjusted if the selected framing character is detected at least twice within a span of 50 bits, with both instances on identical 10-bit character boundaries.

When RFMODEx[1:0] = 01, the Alternate-mode Multi-Byte Framer is enabled. Like the Cypress-mode Multi-Byte Framer, multiple framing characters must be detected before the character boundary is adjusted. In this mode, the data stream must contain a minimum of four of the selected framing

characters, received as consecutive characters, on identical 10-bit boundaries, before character framing is adjusted.

10B/8B Decoder Block

The decoder logic block performs two primary functions:

- Decoding the received transmission characters to data and special character codes
- Comparing generated BIST patterns with received characters to permit at-speed link and device testing

The framed parallel output of each deserializer shifter is passed to its associated 10B/8B Decoder where, if the decoder is enabled, the input data is transformed from a 10-bit transmission character back to the original data or special character code. This block uses the 10B/8B decoder patterns in Table 14 and Table 15. Received special code characters are decoded using Table 15. Valid data characters are indicated by a 000b bit combination on the associated RXSTx[2:0] status bits, and special character codes are indicated by a 001b bit combination of these status outputs. Framing characters, invalid patterns, disparity errors, and synchronization status are presented as alternate combinations of these status bits.

When DECBYPx = 0, the 10B/8B decoder is bypassed through the configuration interface. When bypassed, raw 10-bit characters are passed through the receiver and presented at the RXDx[7:0] and the RXSTA[1:0] outputs as 10-bit wide characters.

When the decoder is enabled by setting DECBYPx = 1 through the configuration interface, the 10-bit transmission characters are decoded using Table 14 and Table 15. Received Special characters are decoded using Table 15. The columns used in Table 15 are determined by the DECMODEx latch through the device configuration interface. When DECMODEx = 0 the ALTERNATE table is used and when DECMODEx = 1 the CYPRESS table is used.

Receive BIST Operation

The receiver channel contains an internal pattern checker that can be used to validate both device and link operation. These pattern checkers are enabled by the associated RXBISTx latch using the device configuration interface. When enabled, a register in the associated receive channel becomes a signature pattern generator and checker by logically converting to a Linear Feedback Shift Register (LFSR). This LFSR generates a 511-character or 526-character sequence that includes all data and special character codes, including the explicit violation symbols. This provides a predictable yet pseudo random sequence that can be matched to an identical LFSR in the attached transmitters. When synchronized with the received data stream, the associated Receiver checks each character in the Decoder with each character generated by the LFSR and indicates compare errors and BIST status at the RXSTx[2:0] bits of the Output Register.

When BIST is first recognized as being enabled in the Receiver, the LFSR is preset to the BIST-loop start code of D0.0. This code D0.0 is sent only once per BIST loop. The status of the BIST progress and any character mismatches are presented on the RXSTx[2:0] status outputs.

Note

10. The standard definition of a Comma contains only seven bits. However, since all valid Comma characters within the 8B/10B character set also have the eighth bit as an inversion of the seventh bit, the compare pattern is extended to a full eight bits to reduce the possibility of a framing error.

Code rule violations or running disparity errors that occur as part of the BIST loop do not cause an error indication. $RXSTx[2:0]$ indicates 010b or 100b for one character period per BIST loop to indicate loop completion. This status can be used to check test pattern progress. These same status values are presented when the decoder is bypassed and BIST is enabled on a receive channel.

The specific status reported by the BIST state machine are listed in [Table 11](#). These same codes are reported on the receive status outputs.

The specific patterns checked by each receiver are described in detail in the Cypress application note “HOTLink Built-In Self-Test.” The sequence compared by the CYV15G0404DXB is identical to that in the CY7B933, CY7C924DX, and CYP(V)15G0401DXB, allowing interoperable systems to be built when used at compatible serial signaling rates.

If the number of invalid characters received ever exceeds the number of valid characters by 16, the receive BIST state machine aborts the compare operations and resets the LFSR to the D0.0 state to look for the start of the BIST sequence again.

When Receive BIST is enabled on a channel, do not enable the low latency framer. The BIST sequence contains an aliased K28.5 framing character, which causes the receiver to update its character boundaries incorrectly.

The receive BIST state machine requires the characters to be correctly framed for it to detect the BIST sequence. If the low latency framer is enabled, the framer misaligns to an aliased SYNC character within the BIST sequence. If the alternate multi-byte framer is enabled and the receiver outputs are clocked relative to a recovered clock, it is generally necessary to frame the receiver before BIST is enabled. If the receive outputs are clocked relative to $REFCLKx\pm$, the transmitter precedes every 511 character BIST sequence with a 16 character word sync sequence.^[11]

A device reset (RESET sampled LOW) presets the BIST enable latches to disable BIST on all channels.

Receive Elasticity Buffer

Each receive channel contains an elasticity buffer that is designed to support multiple clocking modes. These buffers allow data to be read using a clock that is asynchronous in both frequency and phase from the elasticity buffer write clock, or to be read using a clock that is frequency coherent but with uncontrolled phase relative to the elasticity buffer write clock.

If the chip is configured for operation with a recovered clock, the elasticity buffer is bypassed.

Each elasticity buffer is 10 characters deep, and supports an 11 bit wide data path. It is capable of supporting a decoded character and three status bits for each character present in the buffer. The write clock for these buffers is always the recovered clock for the associated read channel.

Receive Modes

When the receive channel is clocked by $REFCLKx\pm$, the $RXCLKx\pm$ outputs present a buffered or divided (depending on

$RXRATEx$) and delayed form of $REFCLKx\pm$. In this mode, the receive elasticity buffers are enabled. For $REFCLKx\pm$ clocking, the elasticity buffers must be able to insert K28.5 characters and delete framing characters as appropriate.

The insertion of a K28.5 or deletion of a framing character can occur at any time on any channel. However, the actual timing of these insertions and deletions is controlled in part by how the transmitter sends its data. Insertion of a K28.5 character can only occur when the receiver has a framing character in the elasticity buffer. Likewise, to delete a framing character, one must also be in the elasticity buffer. To prevent a buffer overflow or underflow on a receive channel, a minimum density of framing characters must be present in the received data streams.

When the receive channel output register is clocked by a recovered clock, no characters are added or deleted and the receiver elasticity buffer is bypassed.

Power Control

The CYV15G0404DXB supports user control of the powered up or down state of each transmit and receive channel. The receive channels are controlled by the $RXPLLDPx$ latch through the device configuration interface. When $RXPLLDPx = 0$, the associated PLL and analog circuitry of the channel is disabled. The transmit channels are controlled by the $OE1x$ and the $OE2x$ latches through the device configuration interface. When a driver is disabled through the configuration interface, it is internally powered down to reduce device power. If both serial drivers for a channel are in this disabled state, the associated internal logic for that channel is powered down as well.

Device Reset State

When the CYV15G0404DXB is reset by assertion of RESET, all state machines, counters, and configuration latches in the device are initialized to a reset state, and the elasticity buffer pointers are set to a nominal offset. Additionally, the JTAG controller must also be reset to ensure valid operation (even if JTAG testing is not performed). See the [JTAG Support](#) section for JTAG state machine initialization. See [Table 9](#) for the initialize values of the configuration latches.

Following a device reset, it is necessary to enable the transmit and receive channels used for normal operation. This is done by sequencing the appropriate values on the device configuration interface.^[5]

Output Bus

Each receive channel presents an 11-signal output bus consisting of

- An 8-bit data bus
- A 3-bit status bus.

The signals present on this output bus are modified by the present operating mode of the CYV15G0404DXB as selected by the $DECBYPx$ configuration latch. This mapping is shown in [Table 7](#).

Note

11. When the receive paths are configured for $REFCLKx\pm$ operation, each pass must be preceded by a 16-character Word Sync Sequence to allow management of clock frequency variations.

Table 7. Output Register Bit Assignments

Signal Name	BYPASS ACTIVE (DECBYPx = 0)	DECODER (DECBYP = 1)
RXSTx[2] (LSB)	COMDET _x	RXSTx[2]
RXSTx[1]	DOUTx[0]	RXSTx[1]
RXSTx[0]	DOUTx[1]	RXSTx[0]
RxDx[0]	DOUTx[2]	RxDx[0]
RxDx[1]	DOUTx[3]	RxDx[1]
RxDx[2]	DOUTx[4]	RxDx[2]
RxDx[3]	DOUTx[5]	RxDx[3]
RxDx[4]	DOUTx[6]	RxDx[4]
RxDx[5]	DOUTx[7]	RxDx[5]
RxDx[6]	DOUTx[8]	RxDx[6]
RxDx[7] (MSB)	DOUTx[9]	RxDx[7]

When the 10B/8B decoder is bypassed, the framed 10-bit value is presented to the associated output register, along with a status output signal indicating if the character in the output register is one of the selected framing characters. The bit usage and mapping of the external signals to the raw 10B transmission character is shown in [Table 8](#).

Table 8. Decoder Bypass Mode

Signal Name	Bus Weight	10 Bit Name
RXSTx[2] (LSB)	COMDET _x	
RXSTx[1]	2 ⁰	a
RXSTx[0]	2 ¹	b
RxDx[0]	2 ²	c
RxDx[1]	2 ³	d
RxDx[2]	2 ⁴	e
RxDx[3]	2 ⁵	i
RxDx[4]	2 ⁶	f
RxDx[5]	2 ⁷	g
RxDx[6]	2 ⁸	h
RxDx[7] (MSB)	2 ⁹	j

The COMDET_x status output operates the same regardless of the bit combination selected for character framing by the FRAMCHAR_x latch. COMDET_x is HIGH when the character in the output register contains the selected framing character at the proper character boundary, and LOW for all other bit combinations.

When the low-latency framer and half rate receive port clocking are also enabled, the framer stretches the recovered clock to the nearest 20-bit boundary such that the rising edge of RXCLK_{x+} occurs when COMDET_x is present on the associated output bus.

When the Cypress or alternate mode framer is enabled and half rate receive port clocking is also enabled, the output clock is not modified when framing is detected, but a single pipeline stage may be added or subtracted from the data stream by the framer logic such that the rising edge of RXCLK_{x+} occurs when COMDET_x is present on the associated output bus.

This adjustment only occurs when the framer is enabled. When the framer is disabled, the clock boundaries are not adjusted, and COMDET_x may be asserted during the rising edge of RXCLK_{x-} (if an odd number of characters were received following the initial framing).

Receive Status Bits

When the 10B/8B decoder is enabled, each character presented at the output register includes three associated status bits. These bits are used to identify

- If the contents of the data bus are valid
- The type of character present
- The state of receive BIST operations
- Character violations

These conditions often overlap; for example, a valid data character received with incorrect running disparity is not reported as a valid data character. It is instead reported as a decoder violation of some specific type. This implies a hierarchy or priority level to the various status bit combinations. The hierarchy and value of each status are listed in [Table 11](#).

A second status mapping, listed in [Table 11](#), is used when the receive channel is configured for BIST operation. This status is used to report receive BIST status and progress.

BIST Status State Machine

When a receive path is enabled to look for and compare the received data stream with the BIST pattern, the RXSTx[2:0] bits identify the present state of the BIST compare operation.

The BIST state machine has multiple states, as shown in [Figure 2](#) and [Table 11](#). When the receive PLL detects an out-of-lock condition, the BIST state is forced to the Start-of-BIST state, regardless of the present state of the BIST state machine. If the number of detected errors ever exceeds the number of valid matches by greater than 16, the state machine is forced to the WAIT_FOR_BIST state where it monitors the receive path for the first character of the next BIST sequence (D0.0). Also, if the Elasticity Buffer ever hits an overflow/underflow condition, the status is forced to the BIST_START until the buffer is re-centered (approximately nine character periods).

To ensure compatibility between the source and destination systems when operating in BIST modes, the sending and receiving ends of the link must use the same receive clock configuration.

Device Configuration and Control Interface

The CYP(V)15G0404DX is highly configurable through the configuration interface. The configuration interface allows the device to be configured globally or allows each channel to be configured independently. [Table 9](#) lists the configuration latches within the device including the initialization value of the latches upon the assertion of RESET. [Table 10](#) shows how the latches are mapped in the device. Each row in the [Table 10](#) maps to a 8-bit latch bank. There are 16 such write-only latch banks. When WREN = 0, the logic value in the DATA[7:0] is latched to the latch bank specified by the values in ADDR[3:0]. The second column of [Table 10](#) specifies the channels associated with the corresponding latch bank. For example, the first three latch banks (0, 1 and 2) consist of configuration bits for channel A. The latch banks

12, 13, and 14 consist of global configuration bits and the last latch bank (15) is the mask latch bank that can be configured to perform bit-by-bit configuration.

Global Enable Function

The global enable function, controlled by the GLENx bits, is a feature that is used to reduce the number of write operations needed to setup the latch banks. This function is beneficial in systems that use a common configuration in multiple channels. The GLENx bit is present in bit 0 of latch banks 0 through 11 only. Its default value (1) enables the global update of the latch bank's contents. Setting the GLENx bit to 0 disables this functionality.

Latch Banks 12, 13, and 14 load values in the related latch banks in a global manner. A write operation to latch bank 12 could do a global write to latch banks 0, 3, 6, and 9 depending on the value of GLENx in these latch banks; latch bank 13 could do a global write to latch banks 1, 4, 7, and 10; and latch banks 14 could do a global write to latch banks 2, 5, 8, and 11. The GLENx bit cannot be modified by a global write operation.

Force Global Enable Function

FGLENx forces the global update of the target latch banks, but does not change the contents of the GLENx bits. If FGLENx = 1 for the associated global channel, FGLENx forces the global update of the target latch banks.

Mask Function

An additional latch bank (15) is used as a global mask vector to control the update of the configuration latch banks on a bit-by-bit

basis. A logic 1 in a bit location allows for the update of that same location of the target latch bank(s), whereas a logic 0 disables it. The reset value of this latch bank is FFh, thereby making its use optional by default. The mask latch bank is not maskable. The FGLEN functionality is not affected by the bit 0 value of the mask latch bank.

Latch Types

There are two types of latch banks: static (S) and dynamic (D). Each channel is configured by two static and one dynamic latch bank. The S type contain those settings that normally do not change for a given application, while the D type controls the settings that could change dynamically during the application's lifetime. The first row of latches for each channel (address numbers 0, 3, 7, and 10) are the static receiver control latches. The second row of latches for each channel (address numbers 1, 4, 8, and 11) are the static transmitter control latches. The third row of latches for each channel (address numbers 2, 5, 9, and 12) are the dynamic control latches that are associated with enabling dynamic functions within the device.

Latch Bank 14 is also useful for those users that do not need the latch-based programmable feature of the device. This latch bank could be used in those applications that do not need to modify the default value of the static latch banks, and that can afford a global (that is, not independent) control of the dynamic signals. In this case, this feature becomes available when ADDR[3:0] is left unchanged with a value of "1110" and WREN is left asserted. The signals present in DATA[7:0] effectively become global control pins, and for the latch banks 2, 5, 8, and 11.

Table 9. Device Configuration and Control Latch Descriptions

Name	Signal Description
RFMODEA[1:0] RFMODEB[1:0] RFMODEC[1:0] RFMODED[1:0]	Reframe Mode Select. The initialization value of the RFMODEx [1:0] latches = 10. RFMODEx is used to select the operating mode of the framer. When RFMODEx[1:0] = 00, the low-latency framer is selected. This frames on each occurrence of the selected framing character(s) in the received data stream. This mode of framing stretches the recovered clock for one or multiple cycles to align that clock with the recovered data. When RFMODEx[1:0] = 01, the alternate mode Multi-Byte parallel framer is selected. This requires detection of the selected framing character(s) in the received serial bit stream, on identical 10-bit boundaries, on four directly adjacent characters. The recovered character clock remains in the same phasing regardless of character offset. When RFMODEx[1:0] =10, the Cypress-mode Multi-Byte parallel framer is selected. This requires a pair of the selected framing character(s), on identical 10-bit boundaries, within a span of 50 bits, before the character boundaries are adjusted. The recovered character clock remains in the same phasing regardless of character offset. RFMODEx[1:0] = 11 is reserved for test.
FRAMCHARA FRAMCHARB FRAMCHARC FRAMCHARD	Framing Character Select. The initialization value of the FRAMCHARx latch = 1. FRAMCHARx is used to select the character or portion of a character used for framing of each channel's received data stream. When FRAMCHARx = 1, the framer looks for either disparity of the K28.5 character. When FRAMCHARx = 0, the framer looks for either disparity of the 8-bit Comma characters. The specific bit combinations of these framing characters are listed in Table 6 .
DECMODEA DECMODEB DECMODEC DECMODED	Receiver Decoder Mode Select. The initialization value of the DECMODEx latch = 1. DECMODEx selects the Decoder Mode used for the associated channel. When DECMODEx = 1 and decoder is enabled, the Cypress Decoding Mode is used. When DECMODEx = 0 and decoder is enabled, the Alternate Decoding mode is used. When the decoder is enabled (DECBYPx = 1), the 10-bit transmission characters are decoded using Table 14 and Table 15 . The column used in the Special Characters Table 15 is determined by the DECMODEx latch.
DECBYPA DECBYPB DECBYPC DECBYPD	Receiver Decoder Bypass. The initialization value of the DECBYPx latch = 1. DECBYPx selects if the Receiver Decoder is enabled or bypassed. When DECBYPx = 1, the decoder is enabled and the Decoder Mode is selected by DECMODEx. When DECBYPx = 0, the decoder is bypassed and raw 10-bit characters are passed through the receiver.

Table 9. Device Configuration and Control Latch Descriptions (continued)

Name	Signal Description
RXCKSELA RXCKSELB RXCKSELC RXCKSELD	<p>Receive Clock Select. The initialization value of the RXCKSELx latch = 1. RXCKSELx selects the receive clock source used to transfer data to the Output Registers and the clock source for the RXCLK± output. When RXCKSELx = 1, the associated Output Registers, are clocked by REFCLKx± at the associated RXCLKx± output buffer. When RXCKSELx = 0, the associated Output Registers, are clocked by the Recovered Byte clock at the associated RXCLKx± output buffer. These output clocks may operate at the character-rate or half the character-rate as selected by RXRATEx.</p>
RXRATEA RXRATEB RXRATEC RXRATED	<p>Receive Clock Rate Select. The initialization value of the RXRATEx latch = 1. RXRATEx is used to select the rate of the RXCLKx± clock output.</p> <p>When RXRATEx = 1 and RXCKSELx = 0, the RXCLKx± clock outputs are complementary clocks that follow the recovered clock operating at half the character rate. Data for the associated receive channels should be latched alternately on the rising edge of RXCLKx+ and RXCLKx-.</p> <p>When RXRATEx = 0 and RXCKSELx = 0, the RXCLKx± clock outputs are complementary clocks that follow the recovered clock operating at the character rate. Data for the associated receive channels should be latched on the rising edge of RXCLKx+ or falling edge of RXCLKx-.</p> <p>When RXRATEx = 1 with RXCKSELx = 1 and REFCLKx± is a full rate clock, the RXCLKx± clock outputs are complementary clocks that follow the reference clock operating at half the character rate. Data for the associated receive channels should be latched alternately on the rising edge of RXCLKx+ and RXCLKx-.</p> <p>When RXRATEx = 0 with RXCKSELx = 1 and REFCLKx± is a full rate clock, the RXCLKx± clock outputs are complementary clocks that follow the reference clock operating at the character rate. Data for the associated receive channels should be latched on the rising edge of RXCLKx+ or falling edge of RXCLKx-.</p> <p>When RXCKSELx = 1 and REFCLKx± is a half rate clock, the value of RXRATEx is not interpreted and the RXCLKx± clock outputs are complementary clocks that follow the reference clock operating at half the character rate. Data for the associated receive channels should be latched alternately on the rising edge of RXCLKx+ and RXCLKx-.</p>
SDASEL1A[1:0] SDASEL1B[1:0] SDASEL1C[1:0] SDASEL1D[1:0]	<p>Primary Serial Data Input Signal Detector Amplitude Select. The initialization value of the SDASEL1x[1:0] latch = 10. SDASEL1x[1:0] selects the trip point for the detection of a valid signal for the INx1± Primary Differential Serial Data Inputs.</p> <p>When SDASEL1x[1:0] = 00, the Analog Signal Detector is disabled.</p> <p>When SDASEL1x[1:0] = 01, the typical p-p differential voltage threshold level is 140 mV.</p> <p>When SDASEL1x[1:0] = 10, the typical p-p differential voltage threshold level is 280 mV.</p> <p>When SDASEL1x[1:0] = 11, the typical p-p differential voltage threshold level is 420 mV.</p>
SDASEL2A[1:0] SDASEL2B[1:0] SDASEL2C[1:0] SDASEL2D[1:0]	<p>Secondary Serial Data Input Signal Detector Amplitude Select. The initialization value of the SDASEL2x[1:0] latch = 10. SDASEL2x[1:0] selects the trip point for the detection of a valid signal for the INx2± Secondary Differential Serial Data Inputs.</p> <p>When SDASEL2x[1:0] = 00, the Analog Signal Detector is disabled</p> <p>When SDASEL2x[1:0] = 01, the typical p-p differential voltage threshold level is 140 mV.</p> <p>When SDASEL2x[1:0] = 10, the typical p-p differential voltage threshold level is 280 mV.</p> <p>When SDASEL2x[1:0] = 11, the typical p-p differential voltage threshold level is 420 mV.</p>
ENCBYPA ENCBYPB ENCBYPC ENCBYPD	<p>Transmit Encoder Bypassed. The initialization value of the ENCBYPx latch = 1. ENCBYPx selects if the Transmit Encoder is enabled or bypassed. When ENCBYPx = 1, the Transmit encoder is enabled. When ENCBYPx = 0, the Transmit Encoder is bypassed and raw 10-bit characters are transmitted.</p>
TXCKSELA TXCKSELB TXCKSELC TXCKSELD	<p>Transmit Clock Select. The initialization value of the TXCKSELx latch = 1. TXCKSELx selects the clock source used to write data into the Transmit Input Register. When TXCKSELx = 1, the associated input register, TXDx[7:0] and TXCTx[1:0], is clocked by REFCLKx↑. In this mode, the phase alignment buffer in the transmit path is bypassed. When TXCKSELx = 0, the associated TXCLKx↑ is used to clock in the input registers, TXDx[7:0] and TXCTx[1:0].</p>

Table 9. Device Configuration and Control Latch Descriptions (continued)

Name	Signal Description
TXRATEA TXRATEB TXRATEC TXRATED	Transmit PLL Clock Rate Select. The initialization value of the TXRATE _x latch = 0. TXRATE _x is used to select the clock multiplier for the Transmit PLL. When TXRATE _x = 0, each transmit PLL multiplies the associated REFCLK _{x±} input by 10 to generate the serial bit-rate clock. When TXRATE _x = 0, the TXCLKO _x output clocks are full rate clocks and follow the frequency and duty cycle of the associated REFCLK _{x±} input. When TXRATE _x = 1, each Transmit PLL multiplies the associated REFCLK _{x±} input by 20 to generate the serial bit-rate clock. When TXRATE _x = 1, the TXCLKO _x output clocks are twice the frequency rate of the REFCLK _{x±} input. When TXCKSEL _x = 1 and TXRATE _x = 1, the Transmit Data Inputs are captured using both the rising and falling edges of REFCLK _x . TXRATE _x = 1 and SPDSEL _x is LOW, is an invalid state and this combination is reserved.
RFENA RFENB RFENC RFEND	Reframe Enable. The initialization value of the RFEN _x latch = 1. RFEN _x selects if the receiver framer is enabled or disabled. When RFEN _x = 1, the associated channel's framer is enabled to frame per the presently enabled framing mode and selected framing character. When RFEN _x = 0, the associated channel's framer is disabled, and no received bits alters the frame offset.
RXPLLPDA RXPLLPDB RXPLLPDC RXPLLPDD	Receive Channel Enable. The initialization value of the RXPLLPD _x latch = 0. RXPLLPD _x selects if the associated receive channel is enabled or powered-down. When RXPLLPD _x = 0, the associated PLL and analog circuitry is powered-down. When RXPLLPD _x = 1, the associated PLL and analog circuitry is enabled.
RXBISTA RXBISTB RXBISTC RXBISTD	Receive Bist Disabled. The initialization value of the RXBIST _x latch = 1. RXBIST _x selects if receive BIST is disabled or enabled. When RXBIST _x = 1, the receiver BIST function is disabled. When RXBIST _x = 0, the receive BIST function is enabled.
TXBISTA TXBISTB TXBISTC TXBISTD	Transmit Bist Disabled. The initialization value of the TXBIST _x latch = 1. TXBIST _x selects if the transmit BIST is disabled or enabled. When TXBIST _x = 1, the transmit BIST function is disabled. When TXBIST _x = 0, the transmit BIST function is enabled.
OE2A OE2B OE2C OE2D	Secondary Differential Serial Data Output Driver Enable. The initialization value of the OE2 _x latch = 0. OE2 _x selects if the OUT2 _± secondary differential output drivers are enabled or disabled. When OE2 _x = 1, the associated serial data output driver is enabled allowing data to be transmitted from the transmit shifter. When OE2 _x = 0, the associated serial data output driver is disabled. When a driver is disabled via the configuration interface, it is internally powered down to reduce device power. If both serial drivers for a channel are in this disabled state, the associated internal logic for that channel is also powered down. A device reset (RESET sampled LOW) disables all output drivers.
OE1A OE1B OE1C OE1D	Primary Differential Serial Data Output Driver Enable. The initialization value of the OE1 _x latch = 0. OE1 _x selects if the OUT1 _± primary differential output drivers are enabled or disabled. When OE1 _x = 1, the associated serial data output driver is enabled allowing data to be transmitted from the transmit shifter. When OE1 _x = 0, the associated serial data output driver is disabled. When a driver is disabled via the configuration interface, it is internally powered down to reduce device power. If both serial drivers for a channel are in this disabled state, the associated internal logic for that channel is also powered down. A device reset (RESET sampled LOW) disables all output drivers.
PABRSTA PABRSTB PABRSTC PABRSTD	Transmit Clock Phase Alignment Buffer Reset. The initialization value of the PABRST _x latch = 1. The PABRST _x is used to re-center the Transmit Phase Align Buffer. When the configuration latch PABRST _x is written as a 0, the phase of the TXCLK _x input clock relative to its associated REFCLK _{x±/±} is initialized. PABRST is an asynchronous input, but is sampled by each TXCLK _x ↑ to synchronize it to the internal clock domain. PABRST _x is a self clearing latch. This eliminates the requirement of writing a 1 to complete the initialization of the Phase Alignment Buffer.
GLEN[11..0]	Global Enable. The initialization value of the GLEN _x latch = 1. The GLEN _x is used to reconfigure several channels simultaneously in applications where several channels may have the same configuration. When GLEN _x = 1 for a given address, that address is allowed to participate in a global configuration. When GLEN _x = 0 for a given address, that address is disabled from participating in a global configuration.
FGLEN[2..0]	Force Global Enable. The initialization value of the FGLEN _x latch is NA. The FGLEN _x latch forces a Global Enable no matter what the setting is on the GLEN _x latch. If FGLEN _x = 1 for the associated Global channel, FGLEN forces the global update of the target latch banks.

Device Configuration Strategy

The following is a series of ordered events needed to load the configuration latches on a per channel basis:

1. Pulse $\overline{\text{RESET}}$ Low after device power up. This operation resets all four channels. Initialize the JTAG state machine to its reset state as detailed in the [JTAG Support](#) section.
2. Set the static receiver latch bank for the target channel. May be performed using a global operation, if the application permits it. [Optional step if the default settings match the desired configuration.]
3. Set the static transmitter latch bank for the target channel. May be performed using a global operation, if the application permits it. [Optional step if the default settings match the desired configuration.]

4. Set the dynamic bank of latches for the target channel. Enable the Receive PLLs and transmit channels. May be performed using a global operation, if the application permits it. [Required step.]
5. Reset the Phase Alignment Buffer for the target channel. May be performed using a global operation, if the application permits it. [Optional if phase align buffer is bypassed.]

When a receive channel is configured with the decoder bypassed and the receive clock selected as recovered clock in half rate mode (DECBYPx = 0, RXRATEx = 0, RXCKSELx = 0), the channel cannot be dynamically reconfigured to enable the decoder with RXCLKx selected as the REFCLKx (DECBYPx = 1, RXCKSELx = 1). If such a change is desired, a global reset should be performed and all channels should be reconfigured to the desired settings.

Table 10. Device Control Latch Configuration Table

ADDR	Channel	Type	DATA7	DATA6	DATA5	DATA4	DATA3	DATA2	DATA1	DATA0	Reset Value
0 (0000b)	A	S	RFMODEA[1]	RFMODEA[0]	FRAMCHARA	DECMODEA	DECBYPA	RXCKSELA	RXRATEA	GLEN0	10111111
1 (0001b)	A	S	SDASEL2A[1]	SDASEL2A[0]	SDASEL1A[1]	SDASEL1A[0]	ENCBYPA	TXCKSELA	TXRATEA	GLEN1	10101101
2 (0010b)	A	D	RFENA	RXPLLPDA	RXBISTA	TXBISTA	OE2A	OE1A	PABRSTA	GLEN2	10110011
3 (0011b)	B	S	RFMODEB[1]	RFMODEB[0]	FRAMCHARB	DECMODEB	DECBYPB	RXCKSELB	RXRATEB	GLEN3	10111111
4 (0100b)	B	S	SDASEL2B[1]	SDASEL2B[0]	SDASEL1B[1]	SDASEL1B[0]	ENCBYPB	TXCKSELB	TXRATEB	GLEN4	10101101
5 (0101b)	B	D	RFENB	RXPLLPDB	RXBISTB	TXBISTB	OE2B	OE1B	PABRSTB	GLEN5	10110011
6 (0110b)	C	S	RFMODEC[1]	RFMODEC[0]	FRAMCHARC	DECMODEC	DECBYPC	RXCKSELC	RXRATEC	GLEN6	10111111
7 (0111b)	C	S	SDASEL2C[1]	SDASEL2C[0]	SDASEL1C[1]	SDASEL1C[0]	ENCBYPC	TXCKSELC	TXRATEC	GLEN7	10101101
8 (1000b)	C	D	RFENC	RXPLLPDC	RXBISTC	TXBISTC	OE2C	OE1C	PABRSTC	GLEN8	10110011
9 (1001b)	D	S	RFMODED[1]	RFMODED[0]	FRAMCHARD	DECMODED	DECBYPD	RXCKSEL D	RXRATE D	GLEN9	10111111
10 (1010b)	D	S	SDASEL2D[1]	SDASEL2D[0]	SDASEL1D[1]	SDASEL1D[0]	ENCBYPD	TXCKSEL D	TXRATED	GLEN10	10101101
11 (1011b)	D	D	RFEND	RXPLLPDD	RXBISTD	TXBISTD	OE2D	OE1D	PABRSTD	GLEN11	10110011
12 (1100b)	GLOBAL	S	RFMODEGL[1]	RFMODEGL[0]	FRAMCHARGL	DECMODEGL	DECBYPGL	RXCKSELGL	RXRATEGL	FGLEN0	N/A
13 (1101b)	GLOBAL	S	SDASEL2GL[1]	SDASEL2GL[0]	SDASEL1GL[1]	SDASEL1GL[0]	ENCBPGL	TXCKSELGL	TXRATEGL	FGLEN1	N/A
14 (1110b)	GLOBAL	D	RFENGL	RXPLLPDGL	RXBISTGL	TXBISTGL	OE2GL	OE1GL	PABRSTGL	FGLEN2	N/A
15 (1111b)	MASK	D	D7	D6	D5	D4	D3	D2	D1	D0	11111111

JTAG Support

The CYV15G0404DXB contains a JTAG port to allow system level diagnosis of device interconnect. Of the available JTAG modes, boundary scan, and bypass are supported. This capability is present only on the LVTTTL inputs and outputs and the REFCLKx± clock input. The high-speed serial inputs and outputs are not part of the JTAG test chain.

To ensure valid device operation after power up (including non-JTAG operation), the JTAG state machine must also be initialized to a reset state. This is done in addition to the device

reset (using $\overline{\text{RESET}}$). The JTAG state machine is initialized using TRST (asserting it LOW and de-asserting it or leaving it asserted), or by asserting TMS HIGH for at least five consecutive TCLK cycles. This is necessary to ensure that the JTAG controller does not enter any of the test modes after device power up. In this JTAG reset state, the rest of the device is in normal operation.

Note. The order of device reset (using $\overline{\text{RESET}}$) and JTAG initialization does not matter.

3-Level Select Inputs

Each 3-Level select inputs reports as two bits in the scan register. These bits report the LOW, MID, and HIGH state of the associated input as 00, 10, and 11 respectively.

JTAG ID

The JTAG device ID for the CYV15G0404DXB is '0C811069'x

Receive Character Status Bits

RXSTx[2:0]	Priority	Description	
		Normal Status	Receive BIST Status (Receive BIST = Enabled)
000	7	Normal character received. The valid Data character on the output bus meets all the formatting requirements of Data characters listed in Table 14 .	BIST Data Compare. Character compared correctly.
001	7	Special code detected. The valid special character on the output bus meets all the formatting requirements of Special Code characters listed in Table 15 , but is not the presently selected framing character or a decoder violation indication.	BIST Command Compare. Character compared correctly.
010	2	Receive Elasticity buffer underrun/overflow error. The receive buffer was not able to add/drop a K28.5 or framing character	BIST Last Good. Last Character of BIST sequence detected and valid.
011	5	Framing character detected. This indicates that a character matching the patterns identified as a framing character (as selected by FRAMCHARx) was detected. The decoded value of this character is present in the associated output bus.	
100	4	Codeword violation. The character on the output bus is a C0.7. This indicates that the received character cannot be decoded into any valid character.	BIST Last Bad. Last Character of BIST sequence detected invalid.
101	1	Loss of sync. This indicates a PLL Out of Lock condition	BIST Start. Receive BIST is enabled on this channel, but character compares have not yet commenced. This also indicates a PLL Out of Lock condition, and Elasticity Buffer overflow/underflow conditions.
110	6	Running disparity error. The character on the output bus is a C4.7, C1.7, or C2.7.	BIST Error. While comparing characters, a mismatch was found in one or more of the decoded character bits.
111	3	Reserved	BIST Wait. The receiver is comparing characters. but has not yet found the start of BIST character to enable the LFSR.

Figure 2. Receive BIST State Machine

