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DS1923

iButton Hygrochron Temperature/Humidity Logger with 8KB Data-Log Memory

General Description

The DS1923 iButton® temperature/humidity logger is a rugged, self-sufficient system that measures temperature and/or humidity and records the result in a protected memory section. The recording is done at a user-defined rate. A total of 8192 8-bit readings or 4096 16-bit readings, taken at equidistant intervals ranging from 1s to 273hr, can be stored. Additionally, 512 bytes of SRAM store application-specific information and 64 bytes store calibration data. A mission to collect data can be programmed to begin immediately, after a user-defined delay, or after a temperature alarm. Access to the memory and control functions can be password protected. The DS1923 is configured and communicates with a host-computing device through the serial 1-Wire® protocol, which requires only a single data lead and a ground return. Every DS1923 is factory lasered with a guaranteed unique 64-bit registration number that allows for absolute traceability. The durable stainless-steel package is highly resistant to environmental hazards such as dirt, moisture, and shock. Accessories permit the DS1923 to be mounted on almost any object, including containers, pallets, and bags.

Applications

Temperature and Humidity Logging in Food Preparation and Processing

Transportation of Temperature-Sensitive and Humidity-Sensitive Goods, Industrial Production

Warehouse Monitoring

Environmental Studies/Monitoring

Features

- **Digital Hygrometer Measures Humidity with 8-Bit (0.6%RH) or 12-Bit (0.04%RH) Resolution**
- **Operating Range: -20°C to +85°C; 0 to 100%RH (see *Safe Operating Range* Graph)**
- **Automatically Wakes Up, Measures Temperature and/or Humidity, and Stores Values in 8KB of Data-Log Memory in 8-Bit or 16-Bit Format**
- **Digital Thermometer Measures Temperature with 8-Bit (0.5°C) or 11-Bit (0.0625°C) Resolution**
- **Temperature Accuracy Better Than ±0.5°C from -10°C to +65°C with Software Correction**
- **Built-In Capacitive Polymer Humidity Sensor for Humidity Logging**
- **Hydrophobic Filter Protects Sensor Against Dust, Dirt, Contaminants, and Water Droplets/Condensation**
- **Sampling Rate from 1s Up to 273hr**
- **Programmable Recording Start Delay After Elapsed Time or Upon a Temperature Alarm Trip Point**
- **Programmable High and Low Trip Points for Temperature and Humidity Alarms**
- **Quick Access to Alarmed Devices Through 1-Wire Conditional Search Function**
- **512 Bytes of General-Purpose Memory Plus 64 Bytes of Calibration Memory**
- **Two-Level Password Protection of All Memory and Configuration Registers**
- **Communicates to Host with a Single Digital Signal at Up to 15.4kbps at Standard Speed or Up to 125kbps in Overdrive Mode Using 1-Wire Protocol**
- **Individually Calibrated in an NIST-Traceable Chamber**
- **Calibration Coefficients for Temperature and Humidity Factory Programmed Into Nonvolatile (NV) Memory**

Common iButton Can Features

- **Digital Identification and Information by Momentary Contact**
- **Unique Factory-Lasered 64-Bit Registration Number Ensures Error-Free Device Selection and Absolute Traceability Because No Two Parts Are Alike**
- **Built-In Multidrop Controller for 1-Wire Net**
- **Chip-Based Data Carrier Compactly Stores Information**
- **Data Can Be Accessed While Affixed to Object**
- **Button Shape is Self-Aligning with Cup-Shaped Probes**
- **Durable Stainless-Steel Case Engraved with Registration Number Withstands Harsh Environments**
- **Easily Affixed with Self-Stick Adhesive Backing, Latched by Its Flange, or Locked with a Ring Pressed Onto Its Rim**
- **Presence Detector Acknowledges When Reader First Applies Voltage**
- **Meets UL 913, 5th Ed., Rev. 1997-02-24; Intrinsically Safe Apparatus: Approved Under Entity Concept for Use in Class I, Division 1, Group A, B, C, and D Locations**

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
DS1923-F5#	-20°C to +85°C	F5 Can

#Denotes a RoHS-compliant device that may include lead(Pb) that is exempt under the RoHS requirements.

Examples of Accessories

PART	ACCESSORY
DS9096P	Self-Stick Adhesive Pad
DS9101	Multipurpose Clip
DS9093RA	Mounting Lock Ring
DS9093A	Snap-In FOB
DS9092	iButton Probe

Pin Configuration appears at end of data sheet.

iButton Hygrochron Temperature/Humidity Logger with 8KB Data-Log Memory

ABSOLUTE MAXIMUM RATINGS

IO Voltage Range Relative to GND ....-0.3V to +6V
IO Sink Current..20mA
Operating Temperature
and Humidity Range ....-20°C to +85°C, 0 to 100%RH*
Storage Temperature
and Humidity Range ....-40°C to +85°C, 0 to 100%RH*

*See the *Safe Operating Range* graph.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(V_{PUP} = +3.0V to +5.25V, T_A = -20°C to +85°C.) (Note 31)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
IO PIN: GENERAL DATA						
1-Wire Pullup Resistance	R_{PUP}	(Notes 1, 2)			2.2	kΩ
Input Capacitance	C_{IO}	(Note 3)		100	800	pF
Input Load Current	I_L	IO pin at V_{PUP}		6	10	µA
High-to-Low Switching Threshold	V_{TL}	(Notes 4, 5)	0.4		3.2	V
Input Low Voltage	V_{IL}	(Notes 1, 6)			0.3	V
Low-to-High Switching Threshold	V_{TH}	(Notes 4, 7)	0.7		3.4	V
Switching Hysteresis	V_{HY}	(Note 8)	0.09		N/A	V
Output Low Voltage	V_{OL}	At 4mA (Note 9)			0.4	V
Recovery Time (Note 1)	t_{REC}	Standard speed, R_{PUP} = 2.2kΩ	5			µs
		Overdrive speed, R_{PUP} = 2.2kΩ	2			
		Overdrive speed directly prior to reset pulse, R_{PUP} = 2.2kΩ	5			
Rising-Edge Hold-Off Time	t_{REH}	(Note 10)	0.6		2.0	µs
Time-Slot Duration (Note 1)	t_{SLOT}	Standard speed	65			µs
		Overdrive speed, V_{PUP} > 4.5V	8			
		Overdrive speed (Note 11)	**9.5**			
IO PIN: 1-Wire RESET, PRESENCE-DETECT CYCLE						
Reset Low Time (Note 1)	t_{RSTL}	Standard speed, V_{PUP} > 4.5V	480		720	µs
		Standard speed (Note 11)	**690**		720	
		Overdrive speed, V_{PUP} > 4.5V	48		80	
		Overdrive speed (Note 11)	**70**		80	
Presence-Detect High Time	t_{PDH}	Standard speed, V_{PUP} > 4.5V	15		60	µs
		Standard speed (Note 11)	15		**63.5**	
		Overdrive speed (Note 11)	2		**7**	
Presence-Detect Fall Time (Note 12)	t_{FPD}	Standard speed, V_{PUP} > 4.5V	1.5		5	µs
		Standard speed	1.5		8	
		Overdrive speed	0.15		1	

ELECTRICAL CHARACTERISTICS (continued)

(V_{PUP} = +3.0V to +5.25V, T_A = -20°C to +85°C.) (Note 31)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Presence-Detect Low Time	t_{PDL}	Standard speed, V_{PUP} > 4.5V	60		240	µs
		Standard speed (Note 11)	60		**287**	
		Overdrive speed, V_{PUP} > 4.5V (Note 11)	**7**		24	
		Overdrive speed (Note 11)	**7**		**28**	
Presence-Detect Sample Time (Note 1)	t_{MSP}	Standard speed, V_{PUP} > 4.5V	65		75	µs
		Standard speed	71.5		75	
		Overdrive speed	8		9	
IO PIN: 1-Wire WRITE						
Write-Zero Low Time (Notes 1, 13)	t_{W0L}	Standard speed	60		120	µs
		Overdrive speed, V_{PUP} > 4.5V (Note 11)	6		**12**	
		Overdrive speed (Note 11)	**7.5**		**12**	
Write-One Low Time (Notes 1, 13)	t_{W1L}	Standard speed	5		15	µs
		Overdrive speed	1		1.95	
IO PIN: 1-Wire READ						
Read Low Time (Notes 1, 14)	t_{RL}	Standard speed	5		15 - δ	µs
		Overdrive speed	1		1.95 - δ	
Read Sample Time (Notes 1, 14)	t_{MSR}	Standard speed	t_{RL} + δ		15	µs
		Overdrive speed	t_{RL} + δ		1.95	
REAL-TIME CLOCK (RTC)						
Accuracy			See *RTC Accuracy* graph			Min/ Month
Frequency Deviation	Δ_F	-20°C to +85°C	-300		+60	ppm
TEMPERATURE CONVERTER						
Conversion Time	t_{CONV}	8-bit mode (Note 15)	30		75	ms
		16-bit mode (11 bits)	240		600	
Thermal Response Time Constant	τ_{RESP}	F5 can package (Note 16)		130		s
Conversion Error Without Software Correction	$\Delta\vartheta$	(Notes 15, 17, 18, 19)	See the *Temperature Accuracy* graph			°C
Conversion Error with Software Correction	$\Delta\vartheta$	(Notes 15, 17, 18, 19)	See the *Temperature Accuracy* graph			°C
HUMIDITY CONVERTER (Note 20)						
Humidity Response Time Constant	τ_{RH}	Slow moving air (Note 21)		30		s
RH Resolution		(Note 22)	8	12	12	Bits
			0.64	0.04	0.04	%RH
RH Range		(Note 23)	0		100	%RH

ELECTRICAL CHARACTERISTICS (continued)

(V_{PUP} = +3.0V to +5.25V, T_A = -20°C to +85°C.) (Note 31)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
RH Accuracy and Interchangeability		With software correction (Notes 18, 19, 24, 25, 26)		±5		%RH
RH Nonlinearity		With software correction (Note 18)		< 1		
RH Hysteresis		(Notes 27, 28)		0.5		%RH
RH Repeatability		(Note 29)		±0.5		%RH
Long-Term Stability		At 50%RH (Note 30)		< 1.0		%RH/ year

Note 1: System requirement.

Note 2: Maximum allowable pullup resistance is a function of the number of 1-Wire devices in the system and 1-Wire recovery times. The specified value here applies to systems with only one device and with the minimum 1-Wire recovery times. For more heavily loaded systems, an active pullup such as that in the DS2480B may be required.

Note 3: Capacitance on the data pin could be 800pF when V_{PUP} is first applied. If a 2.2kΩ resistor is used to pull up the data line, 2.5µs after V_{PUP} has been applied, the parasite capacitance does not affect normal communications.

Note 4: V_{TL} and V_{TH} are functions of the internal supply voltage, which is a function of V_{PUP} and the 1-Wire recovery times. The V_{TH} and V_{TL} maximum specifications are valid at V_{PUP} = 5.25V. In any case, $V_{TL} < V_{TH} < V_{PUP}$.

Note 5: Voltage below which, during a falling edge on IO, a logic 0 is detected.

Note 6: The voltage on IO must be less than or equal to V_{ILMAX} whenever the master drives the line low.

Note 7: Voltage above which, during a rising edge on IO, a logic 1 is detected.

Note 8: After V_{TH} is crossed during a rising edge on IO, the voltage on IO must drop by V_{HY} to be detected as logic 0.

Note 9: The I-V characteristic is linear for voltages less than 1V.

Note 10: The earliest recognition of a negative edge is possible at t_{REH} after V_{TH} has been previously reached.

Note 11: Numbers in **bold** are **not** in compliance with the published iButton device standards. See the *Comparison Table*.

Note 12: Interval during the negative edge on IO at the beginning of a presence-detect pulse between the time at which the voltage is 90% of V_{PUP} and the time at which the voltage is 10% of V_{PUP}.

Note 13: ε in Figure 13 represents the time required for the pullup circuitry to pull the voltage on IO up from V_{IL} to V_{TH}. The actual maximum duration for the master to pull the line low is $t_{W1LMAX} + t_F - \varepsilon$ and $t_{W0LMAX} + t_F - \varepsilon$, respectively.

Note 14: δ in Figure 13 represents the time required for the pullup circuitry to pull the voltage on IO up from V_{IL} to the input high threshold of the bus master. The actual maximum duration for the master to pull the line low is $t_{RLMAX} + t_F$.

Note 15: To conserve battery power, use 8-bit temperature logging whenever possible.

Note 16: This number was derived from a test conducted by Cemagref in Antony, France, in July 2000: www.cemagref.fr/English/index.htm Test Report No. E42.

Note 17: For software-corrected accuracy, assume correction using calibration coefficients with calibration equations for error compensation.

Note 18: Software correction for humidity and temperature is handled automatically using the 1-Wire Viewer Software package available at: **www.ibutton.com**.

Note 19: **Warning:** Not for use as the sole method of measuring or tracking temperature and/or humidity in products and articles that could affect the health or safety of persons, plants, animals, or other living organisms, including but not limited to foods, beverages, pharmaceuticals, medications, blood and blood products, organs, and flammable and combustible products. User shall assure that redundant (or other primary) methods of testing and determining the handling methods, quality, and fitness of the articles and products should be implemented. Temperature and/or humidity tracking with this product, where the health or safety of the aforementioned persons or things could be adversely affected, is only recommended when supplemental or redundant information sources are used. Data-logger products are 100% tested and calibrated at time of manufacture by Maxim to ensure that they meet all data sheet parameters, including temperature accuracy. User shall be responsible for proper use and storage of this product. As with any sensor-based product, user shall also be responsible for occasionally rechecking the accuracy of the product to ensure it is still operating properly.

Note 20: All humidity specifications are determined at +25°C except where specifically indicated.

Note 21: Response time is determined by measuring the 1/e point as the device transitions from 40%RH to 90%RH or 90%RH to 40%RH, whichever is slower. Test was performed at 5L/min airflow.

Note 22: All DS1923 humidity measurements are 12-bit readings. Missioning determines 8-bit or 16-bit data logging. Battery lifetime is the same no matter what RH resolution is logged.

ELECTRICAL CHARACTERISTICS (continued)

(V_{PUP} = +3.0V to +5.25V, T_A = -20°C to +85°C.) (Note 31)

Note 23: Reliability studies have shown that the device survives a minimum of 1000 cycles of condensation and drying, but this product is not guaranteed for extended use in condensing environments.

Note 24: Software-corrected accuracy is accomplished using the method detailed in the *Software Correction Algorithm for Temperature* section.

Note 25: Every DS1923 device is measured and calibrated in a controlled, NIST-traceable RH environment.

Note 26: Higher accuracy versions may be available. Contact the factory for details.

Note 27: If this device is exposed to a high humidity environment (> 70%RH), and then exposed to a lower RH environment, the device reads high for a period of time. The device typically reads within +0.5%RH at 20%RH, 30 minutes after being exposed to continuous 80%RH for 30 minutes.

Note 28: All capacitive RH sensors can change their reading depending upon how long they have spent at high (> 70%RH) or low RH (< 20%RH). This effect is called saturation drift and can be compensated through software, as described in the *Software Saturation Drift Compensation* section.

Note 29: Individual RH readings always include a noise component (repeatability). To minimize measurement error, average as many samples as is reasonable.

Note 30: Like all relative humidity sensors, when exposed to contaminants and/or conditions toward the limits of the safe operating range, accuracy degradation can result (see the *Safe Operating Range* graph). For maximum long-term stability, the sensor should not be exposed or subjected to organic solvents, corrosive agents (e.g., strong acids, SO_2, H_2SO_4, Cl_2, HCL, H_2S) and strong bases (i.e., compounds with a pH greater than 7). Dust settling on the filter surface does not affect the sensor performance except to possibly decrease the speed of response. For more information on the RH sensor's tolerance to chemicals visit: http://content.honeywell.com/sensing/prodinfo/humiditymoisture/technical/c15_144.pdf.

Note 31: Guaranteed by design; not production tested to -20°C.

COMPARISON TABLE

PARAMETER	LEGACY VALUES				DS1923 VALUES			
	STANDARD SPEED (µs)		OVERDRIVE SPEED (µs)		STANDARD SPEED (µs)		OVERDRIVE SPEED (µs)	
	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX
t_{SLOT} (including t_{REC})	61	(undefined)	7	(undefined)	65*	(undefined)	**9.5**	(undefined)
t_{RSTL}	480	(undefined)	48	80	**690**	720	**70**	80
t_{PDH}	15	60	2	6	15	**63.5**	2	**7**
t_{PDL}	60	240	8	24	60	**287**	**7**	**28**
t_{W0L}	60	120	6	16	60	120	**7.5**	**12**

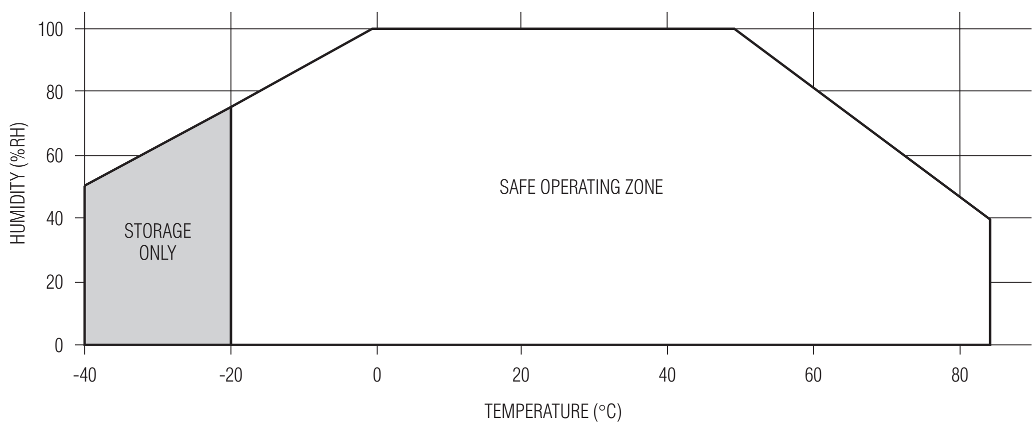
**Intentional change; longer recovery time requirement due to modified 1-Wire front-end.*

***Note:** Numbers in **bold** are **not** in compliance with the published iButton device standards.*

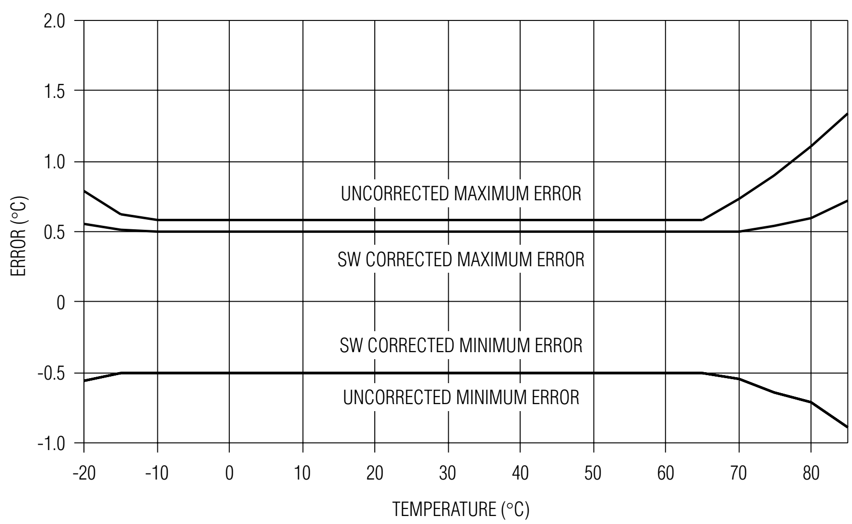
iButton CAN PHYSICAL SPECIFICATION

SIZE	See the *Package Information* section.
WEIGHT	Ca. 5.0 grams
SAFETY	Meets UL 913, 5th Ed., Rev. 1997-02-24; Intrinsically Safe Apparatus, approval under Entity Concept for use in Class I, Division 1, Group A, B, C, and D Locations.

Safe Operating Range

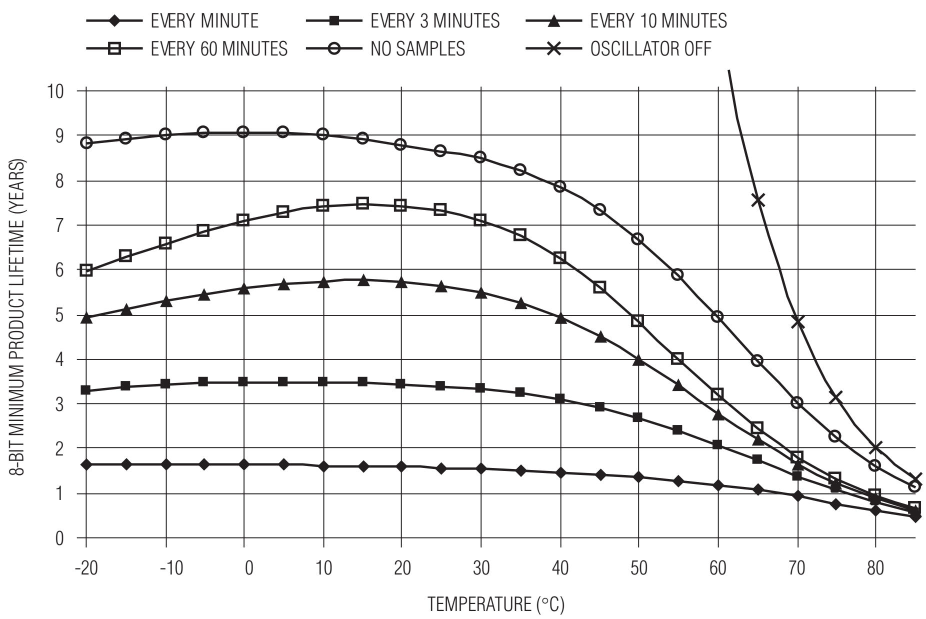


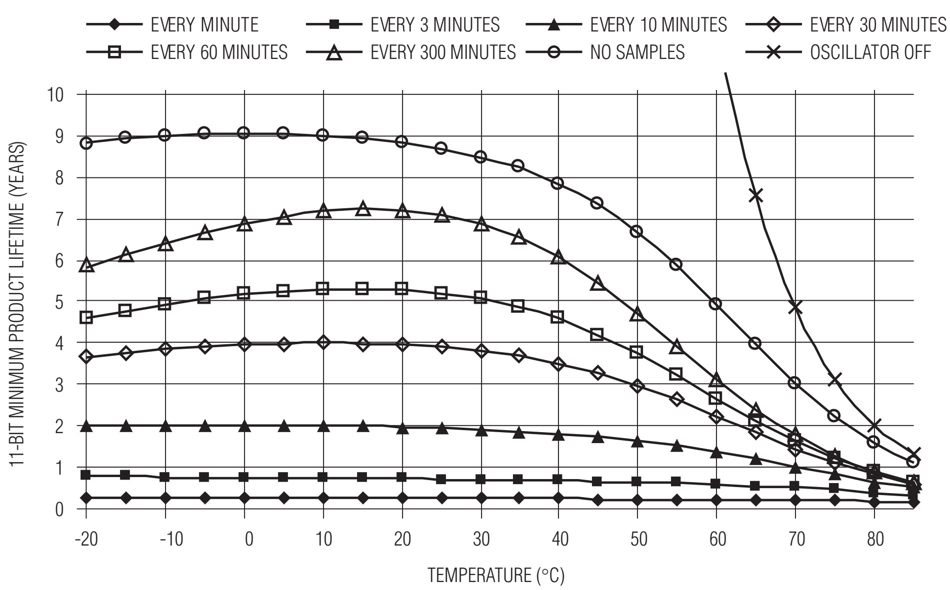
Temperature Accuracy



NOTE: THE GRAPHS ARE BASED ON 11-BIT DATA.

Minimum Lifetime vs. Temperature, Slow Sampling (Temperature Only)

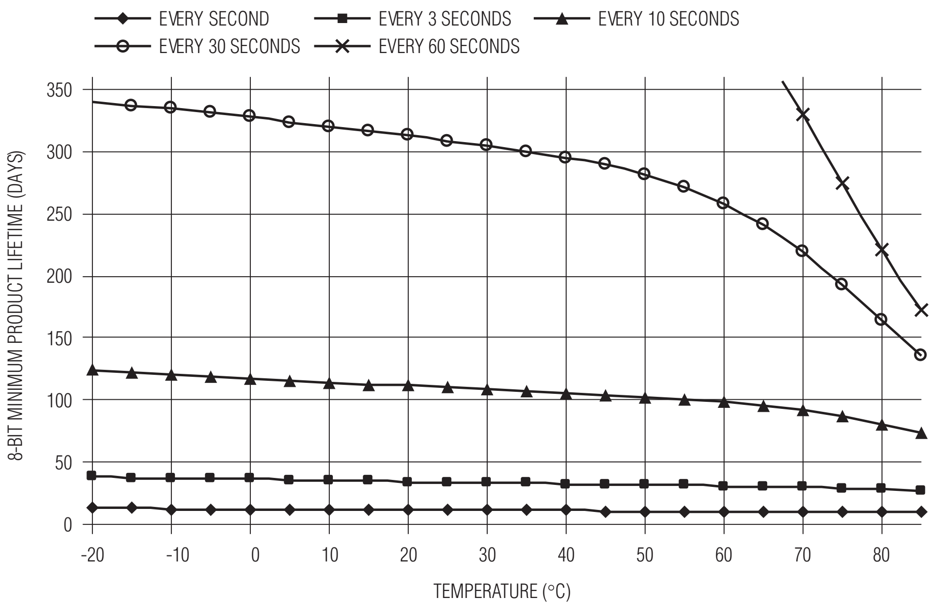


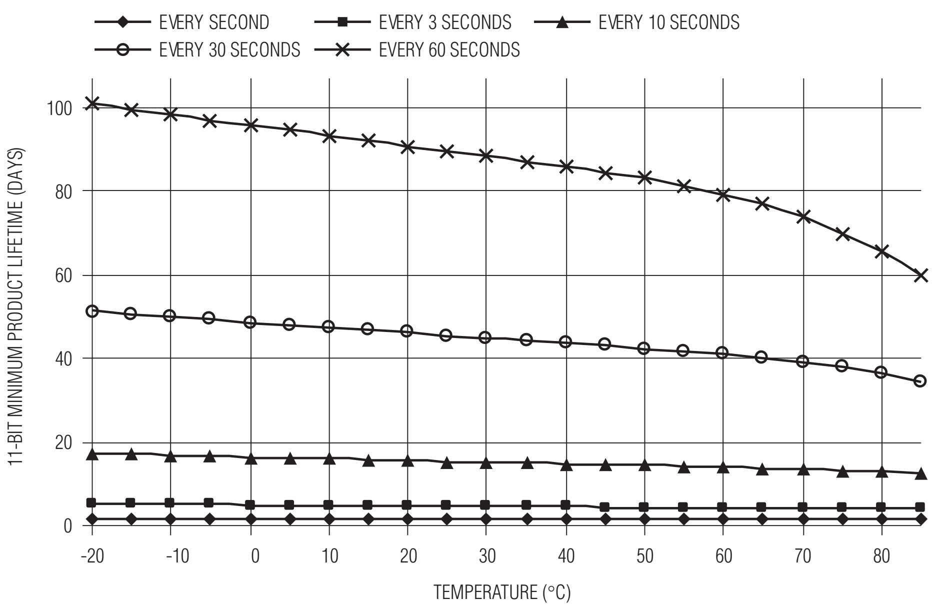


DS1923

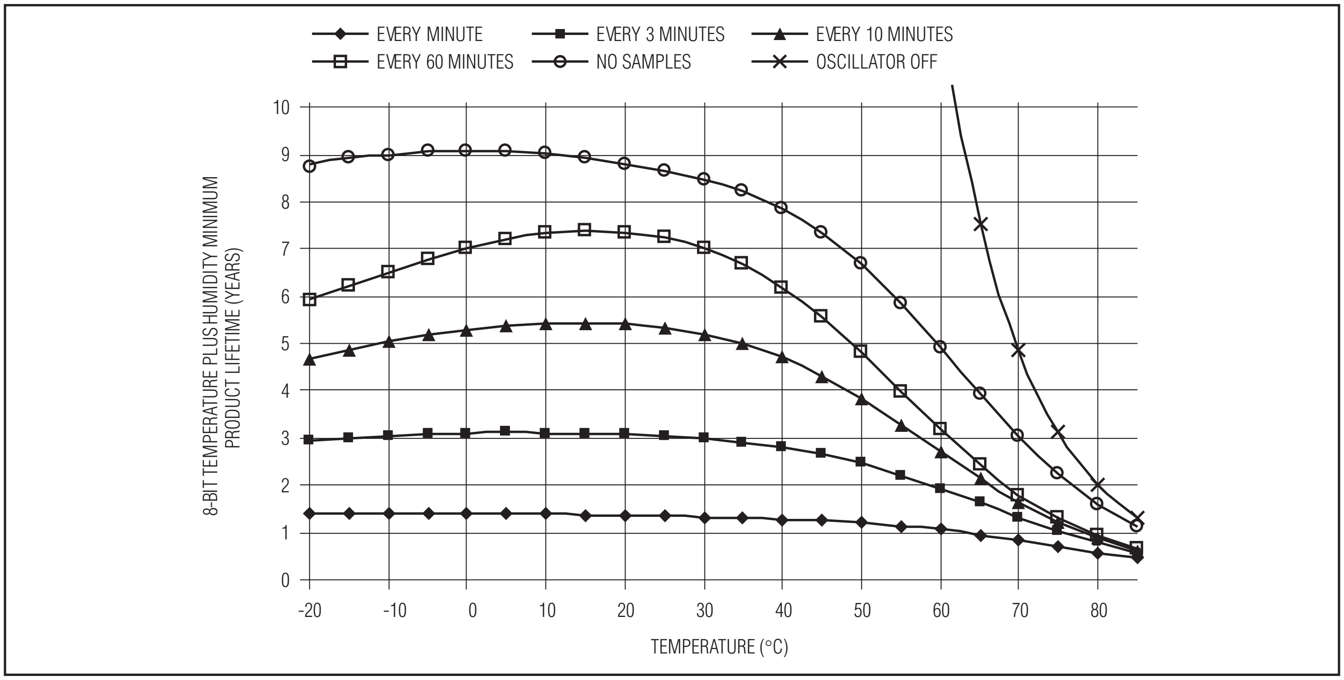
iButton Hygrochron Temperature/Humidity Logger with 8KB Data-Log Memory

Minimum Lifetime vs. Temperature, Fast Sampling (Temperature Only)

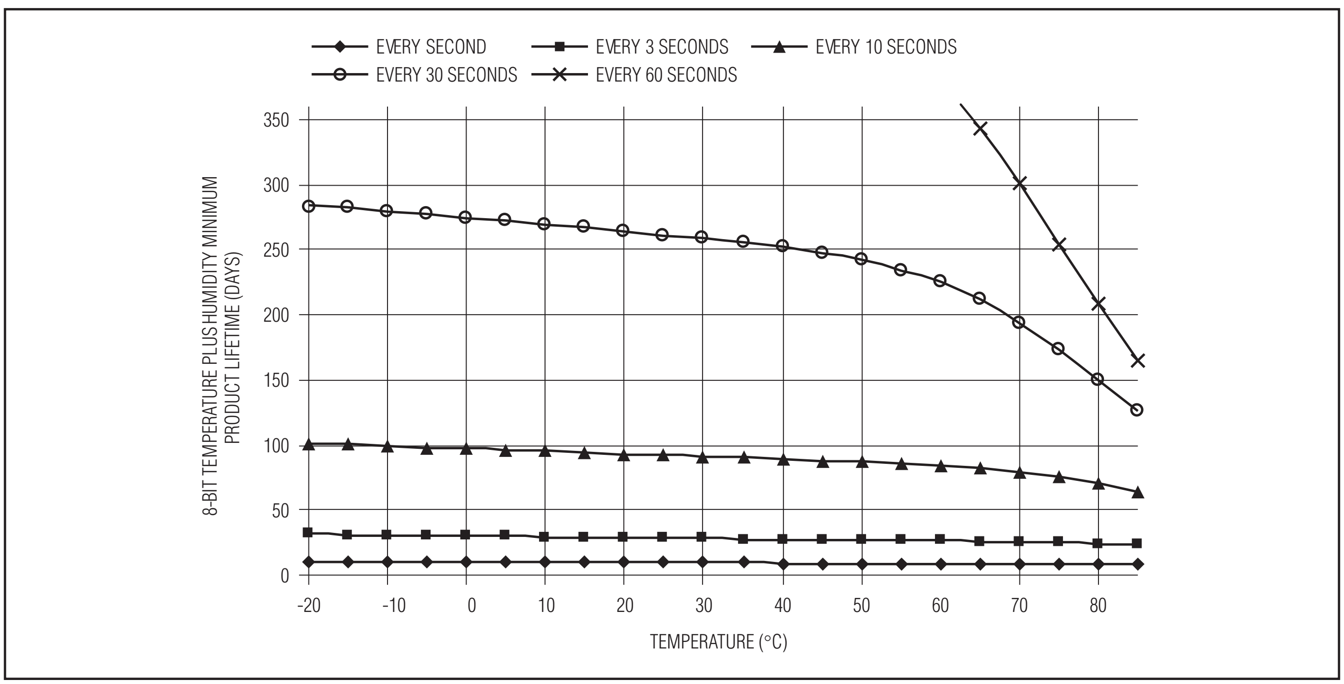




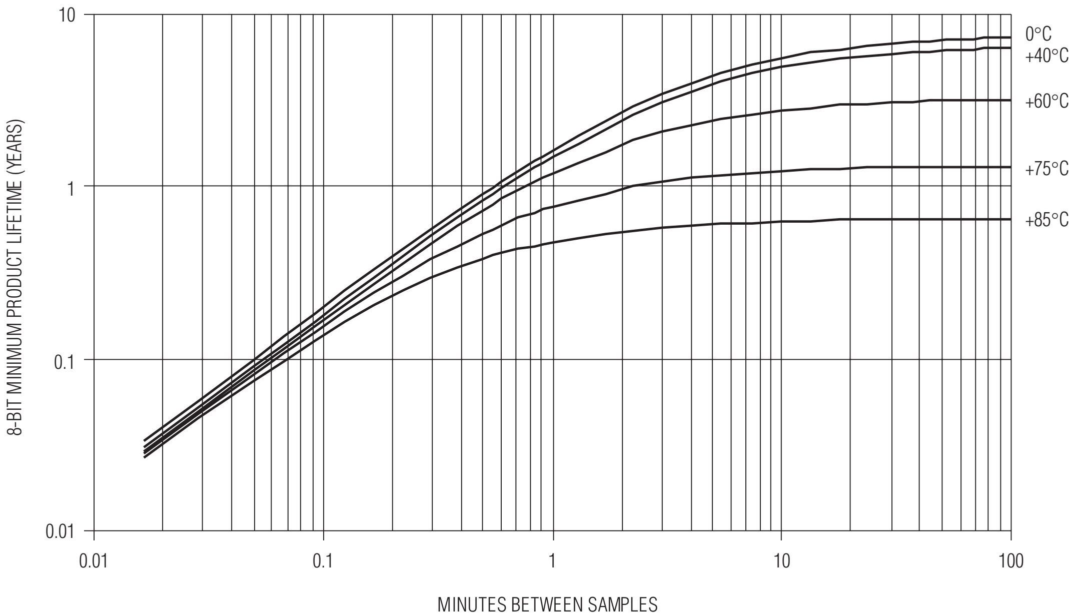
Minimum Lifetime vs. Temperature, Slow Sampling (Temperature with Humidity)



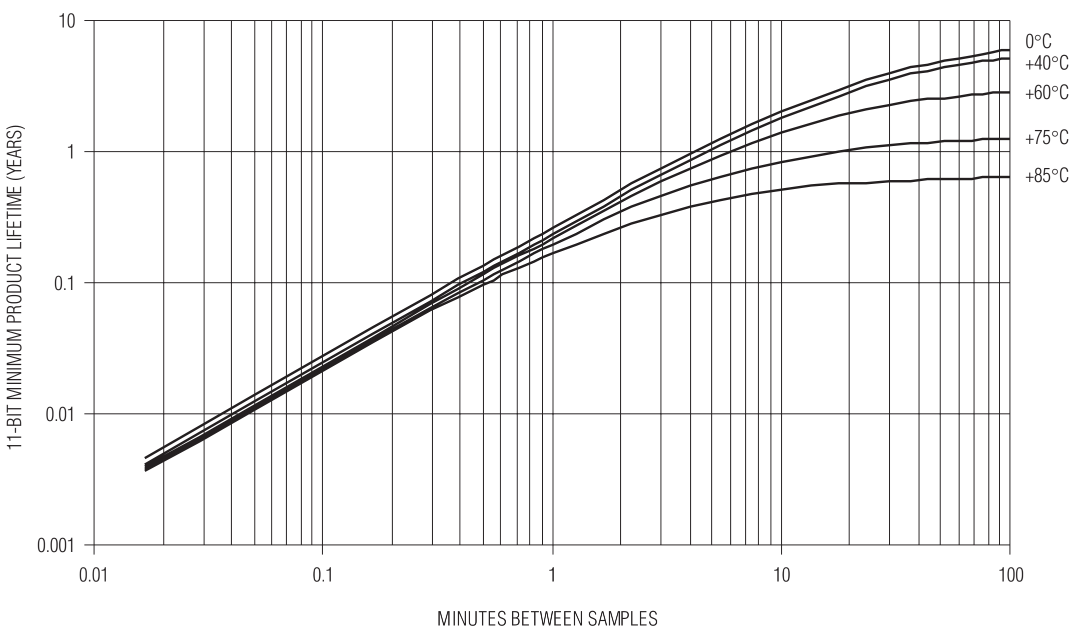
Minimum Lifetime vs. Temperature, Fast Sampling (Temperature with Humidity)



Minimum Product Lifetime vs. Sample Rate (Temperature Only)

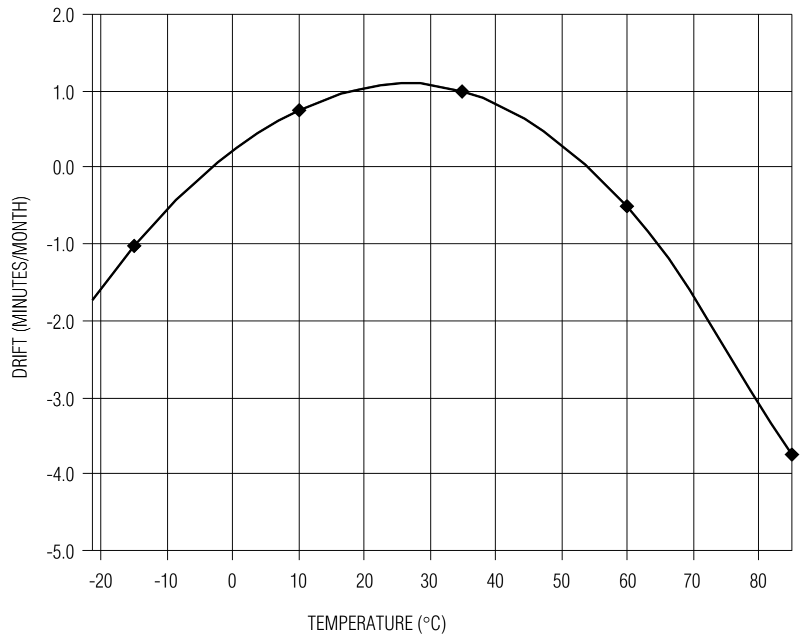


NOTE: WITH HUMIDITY LOGGING ACTIVATED, THE LIFETIME IS REDUCED BY LESS THAN 11% FOR THE SAMPLE RATES OF 3MIN. AND SLOWER, AND BY A MAXIMUM OF 20% FOR SAMPLE RATES OF 1MIN. AND FASTER.



NOTE: WITH HUMIDITY LOGGING ACTIVATED, THE LIFETIME IS REDUCED BY A MAXIMUM OF 4%. THE INCREMENTAL ENERGY CONSUMED BY HUMIDITY LOGGING IS INDEPENDENT OF THE HUMIDITY LOGGING RESOLUTION.

RTC Accuracy (Typical)



Detailed Description

The DS1923 is an ideal device to monitor for extended periods of time the temperature and humidity of any object it is attached to or shipped with, such as fresh produce, medical drugs and supplies, and for use in refrigerators and freezers, as well as for logging climatic data during the transport of sensitive objects and critical processes such as curing. A 1.27mm diameter hole in the lid of the device allows for air to reach the humidity sensor. The rest of the electronics inside the DS1923 is sealed so that it is not exposed to ambient humidity. Note that the initial sealing level of the DS1923 achieves the equivalent of IP56. Aging and use conditions can degrade the integrity of the seal over time, so for applications with significant exposure to liquids, sprays, or other similar environments, it is recommended to place the Hygrochron™ under a shield to protect it (refer to Application Note 4126: *Understanding the IP (Ingress Protection) Ratings of iButton Data Loggers and Capsule*). The hydrophobic filter may not protect the DS1923 from destruction in the event of full submersion in liquid. Software for setup and data retrieval through the 1-Wire interface is available for free download from the iButton website (**www.ibutton.com**).

Hygrochron is a trademark of Maxim Integrated Products, Inc.

This software also includes drivers for the serial and USB port of a PC and routines to access the general-purpose memory for storing application-specific or equipment-specific data files.

All iButton data loggers are calibrated/validated against NIST traceable reference devices. Maxim offers a web application to generate validation certificates for the DS1922L, DS1922T, DS1922E, and DS1923 (temperature portion only) data loggers. Input is the iButton device ROM code (or list of codes) and the output is a validation certificate in PDF format. For more information, refer to Application Note 4629: *iButton® Data-Logger Calibration and NIST Certificate FAQs*.

Overview

The block diagram in Figure 1 shows the relationships between the major control and memory sections of the DS1923. The device has six main data components: 64-bit lasered ROM; 256-bit scratchpad; 512-byte general-purpose SRAM; two 256-bit register pages of timekeeping, control, status, and counter registers and passwords; 64 bytes of calibration memory; and 8192 bytes of data-logging memory. Except for the ROM and the scratchpad, all other memory is arranged in a single linear address space. The data-logging memory, counter registers, and several other registers are

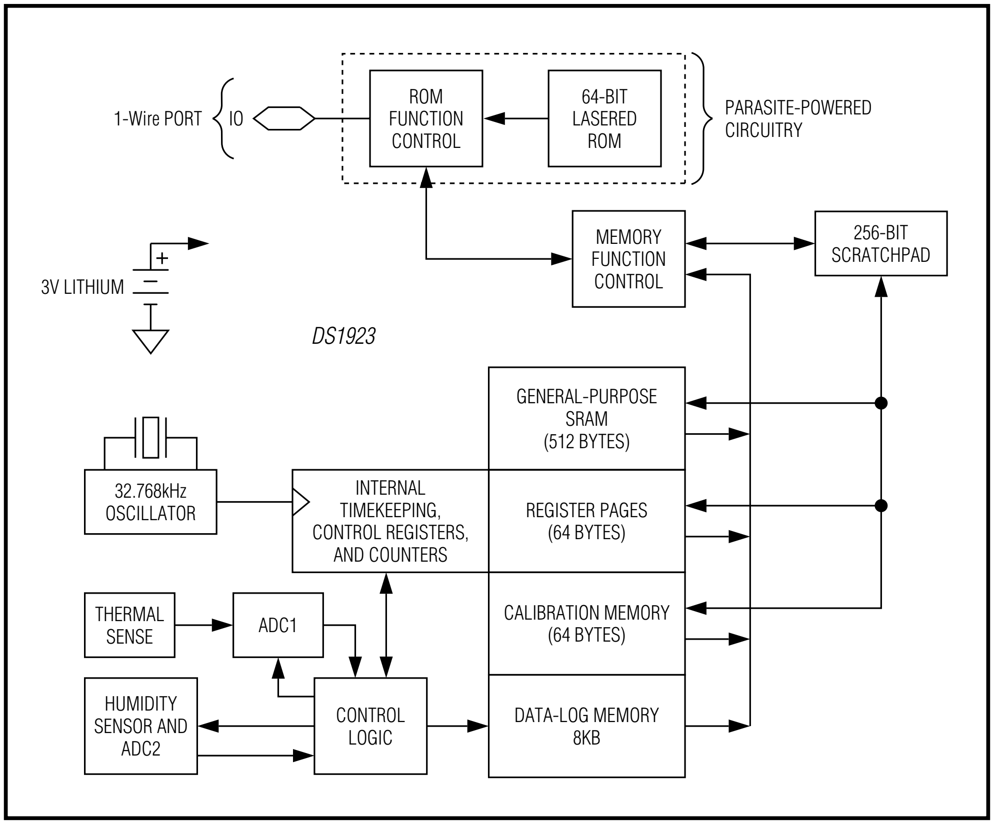


Figure 1. Block Diagram

read only for the user. Both register pages are write protected while the device is programmed for a mission. The password registers, one for a read password and another one for a read/write password, can only be written, never read.

Figure 2 shows the hierarchical structure of the 1-Wire protocol. The bus master must first provide one of the eight ROM function commands: Read ROM, Match ROM, Search ROM, Conditional Search ROM, Skip ROM, Overdrive-Skip ROM, Overdrive-Match ROM, or Resume. Upon completion of an Overdrive-ROM command executed at standard speed, the device enters overdrive mode, where all subsequent communication occurs at a higher speed. The protocol required for these ROM function commands is described in Figure 11. After a ROM function command is successfully executed, the memory and control functions become accessible and the master can provide any one of the eight available commands. The protocol for these memory and control function commands is described in Figure 9. **All data is read and written least significant bit first.**

Parasite Power

The block diagram (Figure 1) shows the parasite-powered circuitry. This circuitry "steals" power whenever the IO input is high. IO provides sufficient power as long as the specified timing and voltage requirements are met. The advantages of parasite power are twofold: 1) By parasiting off this input, battery power is not consumed for 1-Wire ROM function commands, and 2) if the battery is exhausted for any reason, the ROM may still be read normally. The remaining circuitry of the DS1923 is solely operated by battery energy.

64-Bit Lasered ROM

Each DS1923 contains a unique ROM code that is 64 bits long. The first 8 bits are a 1-Wire family code. The next 48 bits are a unique serial number. The last 8 bits are a cyclic redundancy check (CRC) of the first 56 bits (see Figure 3 for details). The 1-Wire CRC is generated using a polynomial generator consisting of a shift register and XOR gates as shown in Figure 4. The polynomial is $X^8 + X^5 + X^4 + 1$. Additional information about the 1-Wire CRC is available in Application Note 27: *Understanding and Using Cyclic Redundancy Checks with Maxim iButton Products*.

The shift register bits are initialized to 0. Then, starting with the least significant bit of the family code, one bit at a time is shifted in. After the 8th bit of the family code has been entered, the serial number is entered. After the last bit of the serial number has been entered, the shift register contains the CRC value. Shifting in the 8 bits of CRC returns the shift register to all 0s.

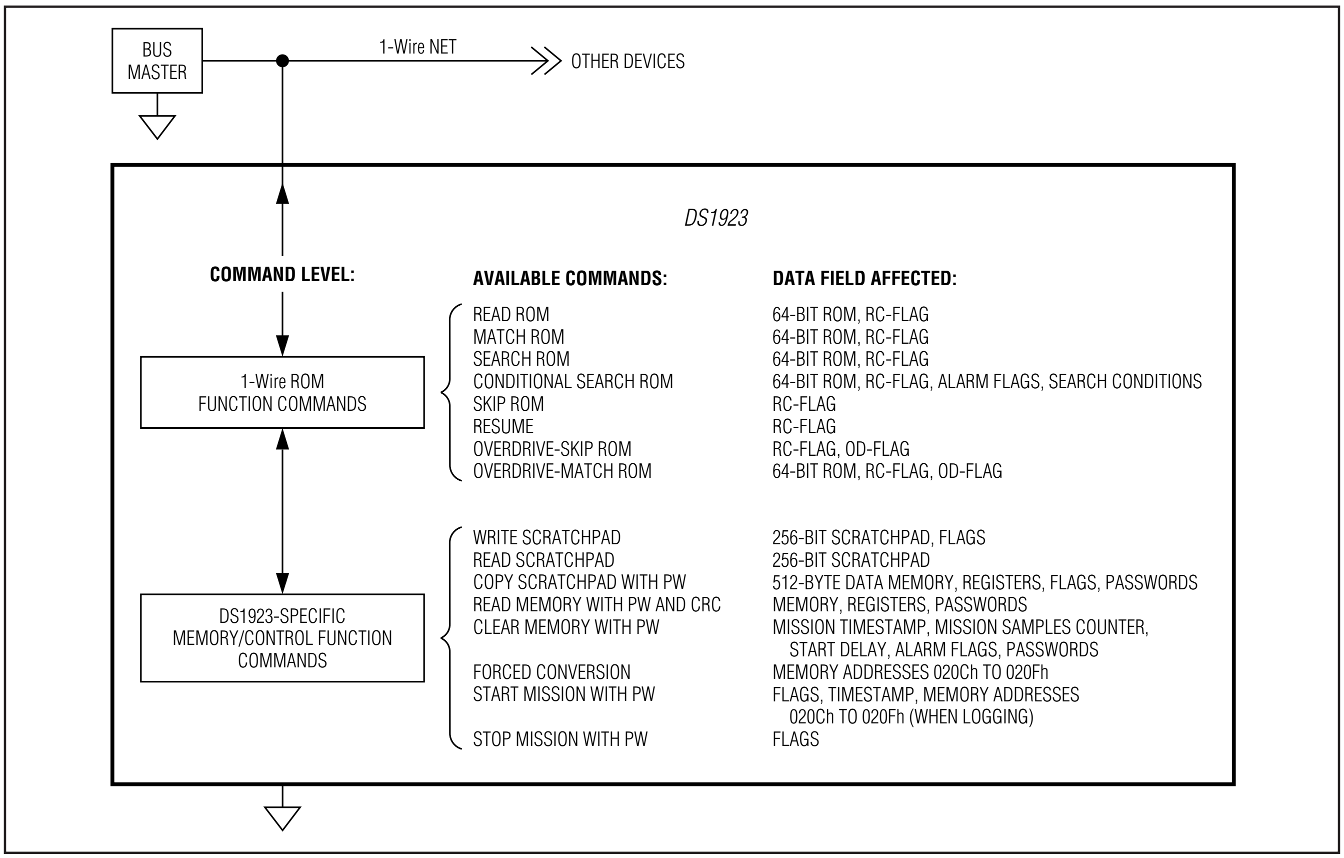


Figure 2. Hierarchical Structure for 1-Wire Protocol

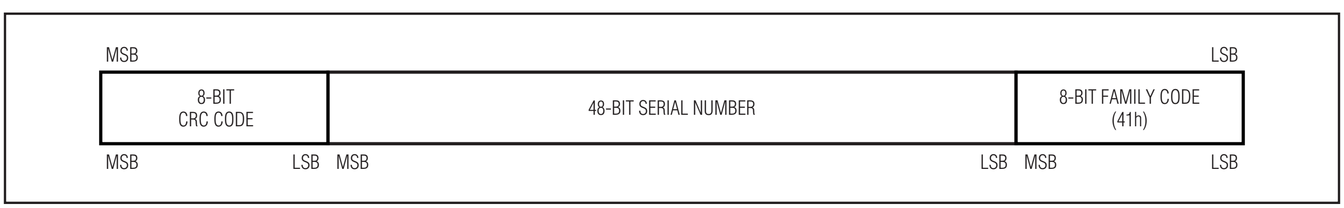


Figure 3. 64-Bit Lasered ROM

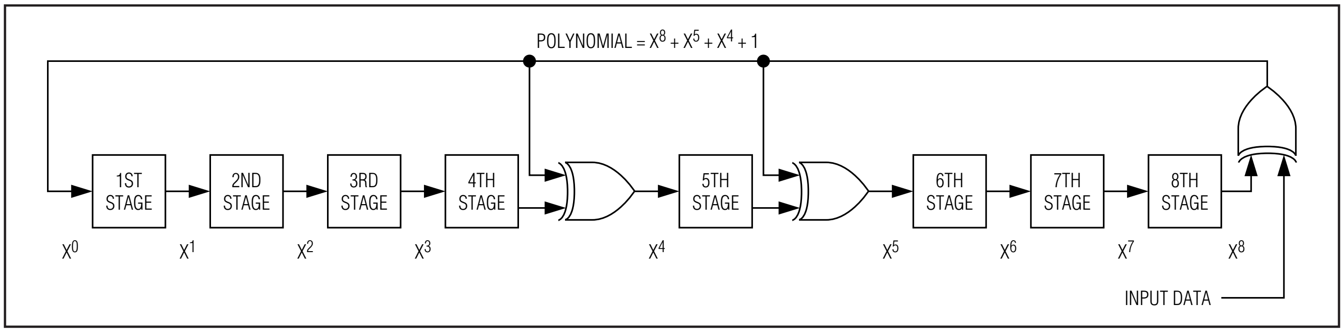


Figure 4. 1-Wire CRC Generator

ADDRESS		
	32-BYTE INTERMEDIATE STORAGE SCRATCHPAD	
0000h TO 001Fh	**32-BYTE GENERAL-PURPOSE SRAM (R/W)**	PAGE 0
0020h TO 01FFh	**GENERAL-PURPOSE SRAM (R/W)**	PAGES 1 TO 15
0200h TO 021Fh	**32-BYTE REGISTER PAGE 1**	PAGE 16
0220h TO 023Fh	**32-BYTE REGISTER PAGE 2**	PAGE 17
0240h TO 025Fh	**CALIBRATION MEMORY PAGE 1 (R/W)**	PAGE 18
0260h TO 027Fh	**CALIBRATION MEMORY PAGE 2 (R/W)**	PAGE 19
0280h TO 0FFFh	(RESERVED FOR FUTURE EXTENSIONS)	PAGES 20 TO 127
1000h TO 2FFFh	**DATA-LOG MEMORY (READ ONLY)**	PAGES 128 TO 383

Figure 5. Memory Map

Memory

Figure 5 shows the DS1923 memory map. Pages 0 to 15 contain 512 bytes of general-purpose SRAM. The various registers to set up and control the device fill pages 16 and 17, called register pages 1 and 2 (see Figure 6 for details). Pages 18 and 19 can be used as storage space for calibration data. The data-log logging memory starts at address 1000h (page 128) and extends over 256 pages. The memory pages 20 to 127 are reserved for future extensions. The scratchpad is an additional page that acts as a buffer when writing to the SRAM memory or the register pages. The calibration memory holds data from the device calibration that can be used to further improve the accuracy of temperature and humidity readings. See the *Software Correction Algorithm* sections for details. The last byte of the calibration memory page stores an 8-bit CRC of the preceding 31 bytes. Page 19 is an exact copy of the data in page 18. While the user can overwrite the calibration memory, this is not recommended. See the *Security by Password* section for ways to protect the memory. The access type for the register pages is register-specific and depends on whether the device is programmed for a mission. Figure 6 shows the details. The data-log memory is read only for the user. It is written solely under supervision of the on-chip control logic. Due to the special behavior of the write access logic (write scratchpad, copy scratchpad), it is recommended to only write full pages at a time. This also applies to the register pages. See the *Address Registers and Transfer Status* section for details.

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	FUNCTION	ACCESS*	
0200h	0	10 Seconds			Single Seconds				Real-Time Clock Registers	R/W	R
0201h	0	10 Minutes			Single Minutes						
0202h	0	12/24	20 Hour AM/PM	10 Hour	Single Hours						
0203h	0	0	10 Date		Single Date						
0204h	CENT	0	0	10 Months	Single Months						
0205h	10 Years				Single Years						
0206h	Low Byte								Sample Rate	R/W	R
0207h	0	0	High Byte								
0208h	Low Threshold								Temperature Alarms	R/W	R
0209h	High Threshold										
020Ah	Low Threshold								Humidity Alarms	R/W	R
020Bh	High Threshold										
020Ch	Low Byte			0	0	0	0	0	Latest Temperature	R	R
020Dh	High Byte										
020Eh	Low Byte								Latest Humidity	R	R
020Fh	High Byte										
0210h	0	0	0	0	0	0	ETHA	ETLA	Temperature Alarm Enable	R/W	R
0211h	1	1	1	1	1	1	EHHA	EHLA	Humidity Alarm Enable	R/W	R
0212h	0	0	0	0	0	0	EHSS	EOSC	RTC Control	R/W	R
0213h	1	1	SUTA	RO	HLFS	TLFS	EHL	ETL	Mission Control	R/W	R
0214h	BOR	1	1	1	HHF	HLF	THF	TLF	Alarm Status	R	R
0215h	1	1	0	WFTA	MEMCLR	0	MIP	0	General Status	R	R
0216h	Low Byte								Start Delay Counter	R/W	R
0217h	Center Byte										
0218h	High Byte										

**The left entry in the ACCESS column is valid between missions. The right entry shows the applicable access type while a mission is in progress.*

Figure 6. Register Pages Map

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	FUNCTION	ACCESS*	
0219h	0	10 Seconds			Single Seconds				Mission Timestamp	R	R
021Ah	0	10 Minutes			Single Minutes						
021Bh	0	12/24	20 Hour AM/PM	10 Hour	Single Hours						
021Ch	0	0	10 Date		Single Date						
021Dh	CENT	0	0	10 Months	Single Months						
021Eh	10 Years				Single Years						
021Fh	(No Function; Reads 00h)								—	R	R
0220h	Low Byte								Mission Samples Counter	R	R
0221h	Center Byte										
0222h	High Byte										
0223h	Low Byte								Device Samples Counter	R	R
0224h	Center Byte										
0225h	High Byte										
0226h	Configuration Code								Flavor	R	R
0227h	EPW								PW Control	R/W	R
0228h	First Byte								Read Access Password	W	—
…	…										
022Fh	Eighth Byte										
0230h	First Byte								Full Access Password	W	—
…	…										
0237h	Eighth Byte										
0238h	(No function; all these bytes read 00h)								—	R	R
…											
023Fh											

**The left entry in the ACCESS column is valid between missions. The right entry shows the applicable access type while a mission is in progress.*

Figure 6. Register Pages Map (continued)

Detailed Register Descriptions

Timekeeping and Calendar

The RTC and calendar information is accessed by reading/writing the appropriate bytes in the register page, address 0200h to 0205h. For readings to be valid, all RTC registers must be read sequentially starting at address 0200h. Some of the RTC bits are set to 0. These bits always read 0 regardless of how they are written. The number representation of the RTC registers is binary-coded decimal (BCD) format.

The DS1923's RTC can run in either 12hr or 24hr mode. Bit 6 of the Hours register (address 0202h) is defined as the 12hr or 24hr mode select bit. When high, the 12hr mode is selected. In the 12hr mode, bit 5 is the AM/PM bit with logic 1 being PM. In the 24hr mode, bit 5 is the 20hr bit (20hr to 23hr). The CENT bit, bit 7 of the Months register, can be written by the user. This bit changes its state when the years counter transitions from 99 to 00.

The calendar logic is designed to automatically compensate for leap years. For every year value that is either 00 or a multiple of 4, the device adds a 29th of February. This works correctly up to (but not including) the year 2100.

Sample Rate

The content of the Sample Rate register (addresses 0206h, 0207h) specifies the time elapse (in seconds if EHSS = 1, or minutes if EHSS = 0) between two temperature/humidity-logging events. The sample rate can be any value from 1 to 16,383, coded as an unsigned 14-bit binary number. If EHSS = 1, the shortest time between logging events is 1s and the longest (sample rate = 3FFFh) is 4.55hr. If EHSS = 0, the shortest is 1min and the longest time is 273.05hr (sample rate = 3FFFh). The EHSS bit is located in the RTC Control register at address 0212h. It is important that the user sets the EHSS bit accordingly while setting the Sample Rate register. **Writing a sample rate of 0000h results in a sample rate = 0001h, causing the DS1923 to log the temperature either every minute or every second depending upon the state of the EHSS bit**.

RTC Registers Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0200h	0	10 Seconds			Single Seconds			
0201h	0	10 Minutes			Single Minutes			
0202h	0	12/24	20 Hour AM/PM	10 Hour	Single Hours			
0203h	0	0	10 Date		Single Date			
0204h	CENT	0	0	10 Months	Single Months			
0205h	10 Years				Single Years			

Note: *During a mission, there is only read access to these registers. Bit cells marked "0" always read 0 and cannot be written to 1.*

Sample Rate Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0206h	Sample Rate Low							
0207h	0	0	Sample Rate High					

Note: *During a mission, there is only read access to these registers. Bit cells marked "0" always read 0 and cannot be written to 1.*

Temperature Conversion

The DS1923's temperature range begins at -20°C and ends at +85°C. Temperature values are represented as an 8-bit or 16-bit unsigned binary number with a resolution of 0.5°C in 8-bit mode and 0.0625°C in 16-bit mode.

The higher temperature byte TRH is always valid. In 16-bit mode, only the three highest bits of the lower byte TRL are valid. The five lower bits all read 0. TRL is undefined if the device is in 8-bit temperature mode. An out-of-range temperature reading is indicated as 00h or 0000h when too cold and FFh or FFE0h when too hot.

With TRH and TRL representing the decimal equivalent of a temperature reading, the temperature value is calculated as:

$$\vartheta(°C) = TRH/2 - 41 + TRL/512 \text{ (16-bit mode, TLFS = 1, see address 0213h)}$$

$$\vartheta(°C) = TRH/2 - 41 \text{ (8-bit mode, TLFS = 0, see address 0213h)}$$

This equation is valid for converting temperature readings stored in the data-log memory as well as for data read from the Latest Temperature Conversion Result register.

To specify the temperature alarm thresholds, the previous equations are resolved to:

$$TALM = 2 \times \vartheta(°C) + 82$$

Because the temperature alarm threshold is only one byte, the resolution or temperature increment is limited to 0.5°C. The TALM value must be converted into hexadecimal format before it can be written to one of the Temperature Alarm Threshold registers (Low Alarm address 0208h; High Alarm address 0209h). Independent of the conversion mode (8-bit or 16-bit), only the most significant byte of a temperature conversion is used to determine whether an alarm is generated.

Humidity Conversion

In addition to temperature, the DS1923 can log humidity data in an 8-bit or 16-bit format. Humidity values are represented as 8-bit or 16-bit unsigned binary numbers with a resolution of 0.64%RH in the 8-bit mode and 0.04%RH in the 16-bit mode.

The DS1923 reads data from its humidity sensor whenever a Forced Conversion command is executed (see the *Memory and Control Function Commands* section) or during a mission if the device is set up to log humidity data. Regardless of its setup, the DS1923 always reads 16 bits from the humidity sensor. The result of the latest humidity reading is found at address 020Eh (low byte) and 020Fh (high byte). The most significant bit read from the humidity sensor can always be found as H11 at address 020Fh. Due to the 12-bit digital output of the humidity sensor, the lower 4 bits in 16-bit format are undefined.

Latest Temperature Conversion Result Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	BYTE
020Ch	T2	T1	T0	0	0	0	0	0	TRL
020Dh	T10	T9	T8	T7	T6	T5	T4	T3	TRH

Table 1. Temperature Conversion Examples

MODE	TRH		TRL		ϑ(°C)
	HEX	DECIMAL	HEX	DECIMAL	
8-Bit	54h	84	—	—	1.0
8-Bit	17h	23	—	—	-29.5
16-Bit	54h	84	00h	0	1.000
16-Bit	17h	23	60h	96	-29.3125

Table 2. Temperature Alarm Threshold Examples

ϑ(°C)	TALM	
	HEX	DECIMAL
25.5	85h	133
-10.0	3Eh	62

Latest Humidity Conversion Result Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	BYTE
020Eh	H3	H2	H1	H0	X	X	X	X	**HRL**
020Fh	H11	H10	H9	H8	H7	H6	H5	H4	**HRH**

During a mission, if humidity logging is enabled, the HRH byte (H11 to H4) is always recorded. The HRL byte is only recorded if the DS1923 is set up for 16-bit humidity logging. The logging mode (8-bit or 16-bit) is selected through the HLFS bit at the Mission Control register, address 0213h.

With HRH and HRL representing the decimal equivalent of a humidity reading, the actual humidity is calculated according to the algorithms shown in the table below.

16-BIT MODE, HLFS = 1	8-BIT MODE, HLFS = 0
IVAL = (HRH x 256 + HRL)/16 Round IVAL **down** to the nearest integer; this eliminates the undefined 4 bits of HRL.	(N/A)
ADVAL = IVAL x 5.02/4096	ADVAL = HRH x 5.02/256
HUMIDITY(%RH) = (ADVAL - 0.958)/0.0307	

The result is a raw humidity reading that needs to be corrected to achieve the specified accuracy. See the *Software Correction Algorithm for Humidity* section for further details.

To specify the humidity alarm thresholds, the equation needs to be resolved to:

ADVAL = HUMIDITY(%RH) x 0.0307 + 0.958

HALM = ADVAL x 256/5.02

Round HALM to the nearest integer.

The HALM value needs to be converted into hexadecimal before it can be written to one of the Humidity Alarm Threshold registers (Low Alarm address 020Ah; High Alarm address 020Bh). Independent of the conversion mode (8-bit or 16-bit), only the most significant byte of a humidity conversion is used to determine whether an alarm is generated. The alarm thresholds are applied to the raw humidity readings. Therefore, if software correction is used, the effect of the software correction is to be reversed before calculating a humidity alarm threshold. For example, let the desired alarm threshold be 60%RH. The 60% threshold may correspond to a raw reading of 65%RH (i.e., before correction). To set a 60%RH (after correction) threshold, the HALM value then needs to be calculated for 65%RH.

These examples do not include the effects of software correction.

Table 3. Humidity Conversion Examples

MODE	HRH		HRL		HUMIDITY (%RH)
	HEX	DECIMAL	HEX	DECIMAL	
8-bit	B5h	**181**	—	—	84.41
8-bit	67h	**103**	—	—	34.59
16-bit	B5h	**181**	C0h	**192**	84.89
16-bit	67h	**103**	30h	**48**	34.70

Table 4. Humidity Alarm Threshold Examples

HUMIDITY (%RH)	HALM	
	HEX	DECIMAL
65	**97h**	151
25	**58h**	88

Temperature Sensor Control Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0210h	0	0	0	0	0	0	ETHA	ETLA

Note: *During a mission, there is only read access to this register. Bits 2 to 7 have no function. They always read 0 and cannot be written to 1.*

Humidity Sensor Control Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0211h	1	1	1	1	1	1	EHHA	EHLA

Note: *During a mission, there is only read access to this register. Bits 2 to 7 have no function. They always read 1 and cannot be written to 0.*

RTC Control Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0212h	0	0	0	0	0	0	EHSS	EOSC

Note: *During a mission, there is only read access to this register. Bits 2 to 7 have no function. They always read 0 and cannot be written to 1.*

Temperature Sensor Alarm

The DS1923 has two Temperature Alarm Threshold registers (address 0208h, 0209h) to store values that determine whether a critical temperature has been reached. A temperature alarm is generated if the device measures an alarming temperature and the alarm signaling is enabled. The bits ETLA and ETHA that enable the temperature alarm are located in the Temperature Sensor Control register. The temperature alarm flags TLF and THF are found in the Alarm Status register at address 0214h.

Bit 1: Enable Temperature High Alarm (ETHA). This bit controls whether, during a mission, the temperature high alarm flag (THF) can be set, if a temperature conversion results in a value equal to or higher than the value in the Temperature High Alarm Threshold register. If ETHA is 1, temperature high alarms are enabled. If ETHA is 0, temperature high alarms are not generated.

Bit 0: Enable Temperature Low Alarm (ETLA). This bit controls whether, during a mission, the temperature low alarm flag (TLF) can be set, if a temperature conversion results in a value equal to or lower than the value in the Temperature Low Alarm Threshold register. If ETLA is 1, temperature low alarms are enabled. If ETLA is 0, temperature low alarms are not generated.

Humidity Alarm

The DS1923 has two Humidity Alarm Threshold registers (address 020Ah, 020Bh) to store values that determine whether humidity readings can generate an alarm. Such an alarm is generated if the humidity data read from the sensor qualifies for an alarm and the alarm signaling is enabled. The bits EHLA and EHHA that enable the humidity alarm are located in the Humidity Sensor Control register. The corresponding alarm flags HLF and HHF are found in the Alarm Status register at address 0214h.

Bit 1: Enable Humidity High Alarm (EHHA). This bit controls whether, during a mission, the humidity high alarm flag (HHF) can be set, if a value from the humidity sensor is equal to or higher than the value in the Humidity High Alarm Threshold register. If EHHA is 1, humidity high alarms are enabled. If EHHA is 0, humidity high alarms are not generated.

Bit 0: Enable Humidity Low Alarm (EHLA). This bit controls whether, during a mission, the humidity low alarm flag (HLF) can be set, if a value from the humidity sensor is equal to or lower than the value in the Humidity Low Alarm Threshold register. If EHLA is 1, humidity low alarms are enabled. If EHLA is 0, humidity low alarms are not generated.

RTC Control

To minimize the power consumption of a DS1923, the RTC oscillator should be turned off when the device is not in use. The oscillator on/off bit is located in the RTC Control register. This register also includes the EHSS bit, which determines whether the sample rate is specified in seconds or minutes.

Bit 1: Enable High-Speed Sample (EHSS). This bit controls the speed of the sample rate counter. When set to logic 0, the sample rate is specified in minutes. When set to logic 1, the sample rate is specified in seconds.

Bit 0: Enable Oscillator (EOSC). This bit controls the crystal oscillator of the RTC. When set to logic 1, the oscillator starts. When written to logic 0, the oscillator stops and the device is in a low-power data-retention mode. This bit must be 1 for normal operation. A Forced Conversion or Start Mission command automatically starts the RTC by changing the EOSC bit to logic 1.

Mission Control

The DS1923 is set up for its operation by writing appropriate data to its special function registers, which are located in the two register pages. The settings in the Mission Control register determine whether temperature and/or humidity is logged, which format (8 or 16 bits) applies, and whether old data can be overwritten by new data once the data-log memory is full. An additional control bit can be set to tell the DS1923 to wait with logging data until a temperature alarm is encountered.

Bit 5: Start Mission Upon Temperature Alarm (SUTA). This bit specifies whether a mission begins immediately (includes delayed start) or if a temperature alarm is required to start the mission. If this bit is 1, the device performs an 8-bit temperature conversion at the selected sample rate and begins with data logging only if an alarming temperature (high alarm or low alarm) was found. The first logged temperature is when the alarm occurred. However, the Mission Samples Counter does not increment. The start upon temperature alarm function is only available if temperature logging is enabled (ETL = 1).

Bit 4: Rollover Control (RO). This bit controls whether, during a mission, the data-log memory is overwritten with new data or whether data logging is stopped once the data-log memory is full. Setting this bit to 1 enables the rollover and data logging continues at the beginning, overwriting previously collected data. If this bit is 0, the logging and conversions stop once the data-log memory is full. However, the RTC continues to run and the MIP bit remains set until the Stop Mission command is performed.

Bit 3: Humidity Logging Format Selection (HLFS). This bit specifies the format used to store humidity readings in the data-log memory. If this bit is 0, the data is stored in 8-bit format. If this bit is 1, the 16-bit format is used (higher resolution). With 16-bit format, the most significant byte is stored at the lower address.

Bit 2: Temperature Logging Format Selection (TLFS). This bit specifies the format used to store temperature readings in the data-log memory. If this bit is 0, the data is stored in 8-bit format. If this bit is 1, the 16-bit format is used (higher resolution). With 16-bit format, the most significant byte is stored at the lower address.

Bit 1: Enable Humidity Logging (EHL). To set up the DS1923 for a humidity-logging mission, this bit must be set to logic 1. If temperature and humidity logging are enabled, the recorded humidity values begin at address 2000h (TLFS = HLFS) or 1A00h (TLFS = 0; HLFS = 1) or 2400h (TLFS = 1; HLFS = 0). If only humidity logging is enabled, the recorded values are stored starting at address 1000h. Since humidity data has little scientific value without knowing the temperature, typically both humidity and temperature logging are enabled (i.e., ETL and EHL are set to 1).

Bit 0: Enable Temperature Logging (ETL). To set up the device for a temperature-logging mission, this bit must be set to logic 1. To successfully start a mission, ETL or EHL must be 1. If temperature logging is enabled, the recorded temperature values are always stored starting at address 1000h.

Mission Control Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0213h	1	1	SUTA	RO	HLFS	TLFS	EHL	ETL

***Note:** During a mission, there is only read access to this register. Bits 6 and 7 have no function. They always read 1 and cannot be written to 0.*

Alarm Status Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0214h	BOR	1	1	1	HHF	HLF	THF	TLF

Note: *There is only read access to this register. Bits 4 to 6 have no function. They always read 1. All five alarm status bits are cleared simultaneously when the Clear Memory command is invoked. See the* Memory and Control Function Commands *section for details.*

General Status Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0215h	1	1	0	WFTA	MEMCLR	0	MIP	0

Note: *There is only read access to this register. Bits 0, 2, 5, 6, and 7 have no function.*

Alarm Status

The fastest way to determine whether a programmed temperature or humidity threshold was exceeded during a mission is through reading the Alarm Status register. In a networked environment that contains multiple DS1923 devices, the devices that encountered an alarm can quickly be identified by means of the Conditional Search ROM command (see the *1-Wire ROM Function Commands* section). The humidity and temperature alarm only occurs if enabled (see the *Temperature Sensor Alarm* and *Humidity Alarm* sections). The BOR alarm is always enabled.

Bit 7: Battery-On Reset Alarm (BOR). If this bit reads 1, the device has performed a power-on reset. This indicates that the device has experienced a shock big enough to interrupt the internal battery power supply. The device can still appear functional, but it has lost its factory calibration. Any data found in the data-log memory should be disregarded.

Bit 3: Humidity High Alarm Flag (HHF). If this bit reads 1, there was at least one humidity reading during a mission revealing a value equal to or higher than the value in the Humidity High Alarm register. A forced conversion can affect the HHF bit.

Bit 2: Humidity Low Alarm Flag (HLF). If this bit reads 1, there was at least one humidity reading during a mission revealing a value equal to or lower than the value in the Humidity Low Alarm register. A forced conversion can affect the HLF bit.

Bit 1: Temperature High Alarm Flag (THF). If this bit reads 1, there was at least one temperature conversion during a mission revealing a temperature equal to or higher than the value in the Temperature High Alarm register. A forced conversion can affect the THF bit. This bit can also be set with the initial alarm in the SUTA = 1 mode.

Bit 0: Temperature Low Alarm Flag (TLF). If this bit reads 1, there was at least one temperature conversion during a mission revealing a temperature equal to or lower than the value in the Temperature Low Alarm register. A forced conversion can affect the TLF bit. This bit can also be set with the initial alarm in the SUTA = 1 mode.

General Status

The information in the General Status register tells the host computer whether a mission-related command was executed successfully. Individual status bits indicate whether the DS1923 is performing a mission, waiting for a temperature alarm to trigger the logging of data or whether the data from the latest mission has been cleared.

Bit 4: Waiting for Temperature Alarm (WFTA). If this bit reads 1, the mission start upon temperature alarm was selected and the Start Mission command was successfully executed, but the device has not yet experienced the temperature alarm. This bit is cleared after a temperature alarm event, but is not affected by the Clear Memory command. Once set, WFTA remains set if a mission is stopped before a temperature alarm occurs. To clear WFTA manually before starting a new mission, set the high temperature alarm (address 0209h) to -40°C and perform a forced conversion.

Bit 3: Memory Cleared (MEMCLR). If this bit reads 1, the Mission Timestamp, Mission Samples Counter, and all the alarm flags of the Alarm Status register have been cleared in preparation of a new mission. Executing the Clear Memory command clears these memory sections. The MEMCLR bit returns to 0 as soon as a new mission is started by using the Start Mission command. The memory must be cleared for a mission to start.

Bit 1: Mission in Progress (MIP). If this bit reads 1, the device has been set up for a mission and this mission is still in progress. The MIP bit returns from logic 1 to logic 0 when a mission is ended. See the *Start Mission [with Password] [CCh]* and *Stop Mission [with Password] [33h]* sections.

Mission Start Delay Counter Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0216h	Delay Low Byte							
0217h	Delay Center Byte							
0218h	Delay High Byte							

Note: *During a mission, there is only read access to this register.*

Mission Timestamp Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0219h	0	10 Seconds			Single Seconds			
021Ah	0	10 Minutes			Single Minutes			
021Bh	0	12/24	20 Hours AM/PM	10 Hours	Single Hours			
021Ch	0	0	10 Date		Single Date			
021Dh	CENT	0	0	10 Months	Single Months			
021Eh	10 Years				Single Years			

Note: *There is only read access to this register.*

Mission Samples Counter Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0220h	Low Byte							
0221h	Center Byte							
0222h	High Byte							

Note: *There is only read access to this register. Note that when both the internal temperature and humidity logging are enabled, the two log readings are counted as one event in the Mission Samples Counter and Device Samples Counter.*

Mission Start Delay

The content of the Mission Start Delay Counter register tells how many minutes must expire from the time a mission was started until the first measurement of the mission takes place (SUTA = 0) or until the device starts testing the temperature for a temperature alarm (SUTA = 1). The Mission Start Delay register is stored as an unsigned 24-bit integer number. The maximum delay is 16,777,215min, equivalent to 11,650 days or roughly 31yr. If the start delay is nonzero and the SUTA bit is set to 1, first the delay must expire before the device starts testing for temperature alarms to begin logging data.

For a typical mission, the Mission Start Delay is 0. If a mission is too long for a single DS1923 to store all readings at the selected sample rate, one can use several devices and set the Mission Start Delay for the second device to start recording as soon as the memory of the first device is full, and so on. The RO bit in the Mission Control register (address 0213h) must be set to 0 to prevent overwriting of collected data once the data-log memory is full.

Mission Timestamp

The Mission Timestamp register indicates the date and time of the first temperature and humidity sample of the mission. There is only read access to the Mission Timestamp register.

Mission Progress Indicator

Depending on settings in the Mission Control register (address 0213h), the DS1923 logs temperature and/or humidity in 8-bit or 16-bit format. The description of the ETL and EHL bit explains where the device stores data in its data-log memory. The Mission Samples Counter register together with the starting address and the logging format (8 or 16 bits) provide the information to identify valid blocks of data that have been gathered during the current (MIP = 1) or latest mission (MIP = 0). See the *Data-Log Memory Usage* section for an illustration. Note that when SUTA = 1, the Mission Samples Counter does not increment when the first sample is logged.

The number read from the Mission Samples Counter indicates how often the DS1923 woke up during a mission to measure temperature and/or humidity. The number format is 24-bit unsigned integer. The Mission Samples Counter is reset through the Clear Memory command.

Device Samples Counter Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0223h	Low Byte							
0224h	Center Byte							
0225h	High Byte							

Note: *There is only read access to this register.*

Device Configuration Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	PART
0226h	0	0	0	0	0	0	0	0	DS2422
	0	0	1	0	0	0	0	0	DS1923
	0	1	0	0	0	0	0	0	DS1922L
	0	1	1	0	0	0	0	0	DS1922T
	1	0	0	0	0	0	0	0	DS1922E

Note: *There is only read access to this register.*

Password Control Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0227h	EPW							

Note: *During a mission, there is only read access to this register.*

Other Indicators

The Device Samples Counter register is similar to the Mission Samples Counter register. During a mission this counter increments whenever the DS1923 wakes up to measure and log data and when the device is testing for a temperature alarm in Start Mission Upon Temperature Alarm mode. Between missions, the counter increments whenever the Forced Conversion command is executed. This way the Device Samples Counter register functions like a gas gauge for the battery that powers the iButton device.

The Device Samples Counter register is reset to zero when the iButton device is assembled. The number format is 24-bit unsigned integer. The maximum number that can be represented in this format is 16,777,215. Due to the calibration and tests at the factory, new devices can have a count value of up to 35,000. The typical value is well below 10,000.

The code in the Device Configuration register allows the master to distinguish between the DS2422 chip and different versions of the DS1922 devices. The *Device Configuration Register Bitmap* table shows the codes assigned to the various devices.

Security by Password

The DS1923 is designed to use two passwords that control read access and full access. Reading from or writing to the scratchpad as well as the Forced Conversion command does not require a password. The password must be transmitted immediately after the command code of the memory or control function. If password checking is enabled, the password transmitted is compared to the passwords stored in the device. The data pattern stored in the Password Control register determines whether password checking is enabled.

To enable password checking, the EPW bits need to form a binary pattern of 10101010 (AAh). The default pattern of EPW is different from AAh. If the EPW pattern is different from AAh, any pattern is accepted as long as it has a length of exactly 64 bits. Once enabled, changing the passwords and disabling password checking requires the knowledge of the current full-access password.

Read-Access Password Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0228h	RP7	RP6	RP5	RP4	RP3	RP2	RP1	RP0
0229h	RP15	RP14	RP13	RP12	RP11	RP10	RP9	RP8
…	…							
022Eh	RP55	RP54	RP53	RP52	RP51	RP50	RP49	RP48
022Fh	RP63	RP62	RP61	RP60	RP59	RP58	RP57	RP56

Note: *There is only write access to this register. Attempting to read the password reports all zeros. The password cannot be changed while a mission is in progress.*

Full-Access Password Register Bitmap

ADDRESS	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
0230h	FP7	FP6	FP5	FP4	FP3	FP2	FP1	FP0
0231h	FP15	FP14	FP13	FP12	FP11	FP10	FP9	FP8
…	…							
0236h	FP55	FP54	FP53	FP52	FP51	FP50	FP49	FP48
0237h	FP63	FP62	FP61	FP60	FP59	FP58	FP57	FP56

Note: *There is only write access to this register. Attempting to read the password reports all zeros. The password cannot be changed while a mission is in progress.*

Before enabling password checking, passwords for read-only access as well as for full access (read/write/control) must be written to the password registers. Setting up a password or enabling/disabling the password checking is done in the same way as writing data to a memory location; only the address is different. Since they are located in the same memory page, both passwords can be redefined at the same time.

The Read Access Password must be transmitted exactly in the sequence RP0, RP1…RP62, RP63. This password only applies to the Read Memory with CRC command. The DS1923 delivers the requested data only if the password transmitted by the master was correct or if password checking is not enabled.

The Full Access Password must be transmitted exactly in the sequence FP0, FP1…FP62, FP63. It affects the commands Read Memory with CRC, Copy Scratchpad, Clear Memory, Start Mission, and Stop Mission. The DS1923 executes the command only if the password transmitted by the master was correct or if password checking is not enabled.

Due to the special behavior of the write-access logic, the Password Control register and both passwords must be written at the same time. When setting up new passwords, always verify (read back) the scratchpad before sending the Copy Scratchpad command. After a new password is successfully copied from the scratchpad to its memory location, erase the scratchpad by filling it with new data (Write Scratchpad command). Otherwise, a copy of the passwords remains in the scratchpad for public read access.