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FEATURES

- Filterless digital input, mono Class-D amplifier**
- Operates from a single 4.5 V to 17 V supply**
- 31.3 W output power, 17 V supply, and 4 Ω load at 1% THD + N**
- 107 dB A-weighted signal-to-noise ratio**
- 93.3% efficiency into 8 Ω load at 12 V**
- I²C control with up to 4 pin selectable slots/addresses**
- Supports multiple serial data formats up to TDM16**
- Digital interface supports sample rates from 8 kHz to 192 kHz**
- Flexible digital and analog gain adjustment**
- Flexible supply monitoring AGC function**
- 6.55 mA quiescent current with single 17 V PVDD supply**
- Short-circuit and thermal protection, thermal warning**
- 20-ball, 1.8 mm × 2.2 mm, 0.4 mm pitch WLCSP**
- Pop and click suppression**
- User selectable ultralow EMI emissions mode**
- Power-on reset**

APPLICATIONS

- Notebooks**
- Portable electronics**
- Home audio**

GENERAL DESCRIPTION

The **SSM3515** is a fully integrated, high efficiency, mono Class-D audio amplifier with digital inputs. The application circuit requires a minimum of external components and can operate from a single 4.5 V to 17 V supply. It can deliver 8.4 W of output power into an 8 Ω load or 15.8 W into a 4 Ω load from a 12 V power supply, or 31.3 W into a 4 Ω load from a 17 V power supply, all with 1% THD + N.

The **SSM3515** features a high efficiency, low noise modulation scheme that requires no external LC output filters. This scheme provides high efficiency even at low output power. It operates with 92% efficiency at 7 W into an 8 Ω load or 88% efficiency at 15 W into 4 Ω from a 12 V supply.

Spread spectrum pulse density modulation provides lower EMI radiated emissions compared with other Class-D architectures, particularly above 100 MHz.

The digital input eliminates the need for an external digital-to-analog converter (DAC). The **SSM3515** has a micropower shutdown mode with a typical shutdown current of 39 nA at the 12 V PVDD supply. The device also includes pop and click suppression circuitry that minimizes voltage glitches at the output during turn on and turn off.

The **SSM3515** operates with or without an I²C control interface. The **SSM3515** is specified over the commercial temperature range (−40°C to +85°C). It has built in thermal shutdown and output short-circuit protection. It is available in a halide-free, 20-ball, 1.8 mm × 2.2 mm wafer-level chip scale package (WLCSP).

FUNCTIONAL BLOCK DIAGRAM

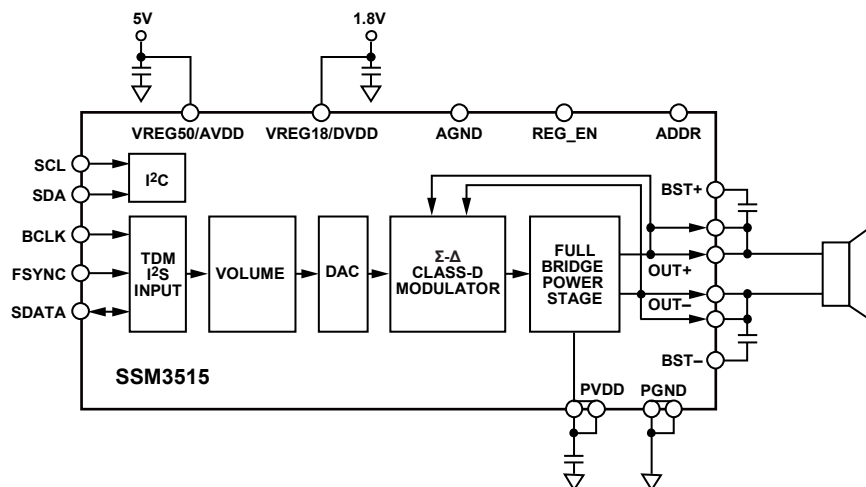


Figure 1.

Rev. A

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SSM3515* PRODUCT PAGE QUICK LINKS

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COMPARABLE PARTS

View a parametric search of comparable parts.

EVALUATION KITS

- SSM3515 Evaluation Board

DOCUMENTATION

Data Sheet

- SSM3515: 31 W, Filterless, Class-D Digital Input Audio Amplifier Data Sheet

TOOLS AND SIMULATIONS

- SSM3515 IBIS Model

DESIGN RESOURCES

- SSM3515 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

View all SSM3515 EngineerZone Discussions.

SAMPLE AND BUY

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TECHNICAL SUPPORT

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REVISION HISTORY

1/2017—Rev. 0 to Rev. A

Changes to Figure 2 and Table 5..... 6

6/2015—Revision 0: Initial Version

SPECIFICATIONS

$PV_{DD} = 12\text{ V}$, $VREG50/AVDD = 5\text{ V}$ (internal), $VREG18/DVDD = 1.8\text{ V}$ (external), $R_L = 8\ \Omega + 33\ \mu\text{H}$, $BCLK = 3.072\text{ MHz}$ and $FSYNC = 48\text{ kHz}$, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$, unless otherwise noted. The measurements are with a 20 kHz AES17 low-pass filter. The other load impedances used are $4\ \Omega + 15\ \mu\text{H}$ and $3\ \Omega + 10\ \mu\text{H}$. Measurements are with a 20 kHz AES17 low-pass filter, unless otherwise noted.

The sine wave output powers above 20 W in 4 Ω cannot be continuous and may invoke the thermal limit indicator based on the power dissipation capability of the board.

Table 1.

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit		
DEVICE CHARACTERISTICS								
Output Power/Channel $R_L = 8\ \Omega$	P_{OUT}	$f = 1\text{ kHz}$						
		THD + N = 1%, $PV_{DD} = 17\text{ V}$		16		W		
		THD + N = 1%, $PV_{DD} = 12\text{ V}$		8.4		W		
		THD + N = 1%, $PV_{DD} = 7\text{ V}$		2.8		W		
		THD + N = 1%, $PV_{DD} = 5\text{ V}$		1.4		W		
		THD + N = 10%, $PV_{DD} = 17\text{ V}$		19.7		W		
		THD + N = 10%, $PV_{DD} = 12\text{ V}$		10.5		W		
		THD + N = 10%, $PV_{DD} = 7\text{ V}$		3.5		W		
		THD + N = 10%, $PV_{DD} = 5\text{ V}$		1.8		W		
		$R_L = 4\ \Omega$	THD + N = 1%, $PV_{DD} = 17\text{ V}$		31.3		W	
			THD + N = 1%, $PV_{DD} = 12\text{ V}$		15.8		W	
			THD + N = 1%, $PV_{DD} = 7\text{ V}$		5.4		W	
			THD + N = 1%, $PV_{DD} = 5\text{ V}$		2.8		W	
			THD + N = 10%, $PV_{DD} = 17\text{ V}$		39.3		W	
			THD + N = 10%, $PV_{DD} = 12\text{ V}$		19.7		W	
		Efficiency	η	THD + N = 10%, $PV_{DD} = 7\text{ V}$		6.7		W
				THD + N = 10%, $PV_{DD} = 5\text{ V}$		3.4		W
				$P_{OUT} = 9\text{ W}$, $R_L = 8\ \Omega$, $PV_{DD} = 12\text{ V}$		93.3		%
Total Harmonic Distortion + Noise	THD + N	$P_{OUT} = 9\text{ W}$, $R_L = 8\ \Omega$, $PV_{DD} = 12\text{ V}$ (low EMI mode)		93.2		%		
		$P_{OUT} = 30\text{ W}$, $R_L = 4\ \Omega$, $PV_{DD} = 17\text{ V}$		88		%		
		$P_{OUT} = 30\text{ W}$, $R_L = 4\ \Omega$, $PV_{DD} = 17\text{ V}$ (low EMI mode)		87.8		%		
Load Resistance		$P_{OUT} = 5\text{ W}$ into $R_L = 8\ \Omega$, $f = 1\text{ kHz}$, $PV_{DD} = 16\text{ V}$		0.004		%		
			3		Ω			
Load Inductance			5	10		μH		
Output FET On Resistance	R_{ON}			110		m Ω		
Overcurrent Protection Trip Point	I_{OC}		5.8			A peak		
Average Switching Frequency	f_{SW}			300		kHz		
Differential Output DC Offset Voltage	V_{OOS}	Gain = 12.6 V		± 1	± 5.0	mV		
POWER SUPPLIES								
Supply Voltage Range	PV_{DD}	Guaranteed from PSRR test	4.5		17	V		
	VREG50/AVDD	Internal	4.5	5.0	5.5	V		
	VREG18/DVDD	Internal or external	1.62	1.80	1.98	V		
AC Power Supply Rejection Ratio	$PSRR_{AC}$	$V_{RIPPLE} = 1\text{ V rms}$ at 1 kHz		87	73	dB		
GAIN CONTROL								
Output Voltage Peak		Measured with 0 dBFS input at 1 kHz						
		Analog gain setting = 8.4 V/V with $PV_{DD} = 17\text{ V}$		8.4		V peak		
		Analog gain setting = 12.6 V/V with $PV_{DD} = 17\text{ V}$		12.6		V peak		
		Analog gain setting = 14.0 V/V with $PV_{DD} = 17\text{ V}$		14		V peak		
		Analog gain setting = 15.0 V/V with $PV_{DD} = 17\text{ V}$		15		V peak		

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
SHUTDOWN CONTROL¹						
Turn On Time, Volume Ramp Disabled	t_{WU}	Time from SPWDN = 0 to output switching, DAC_HV = 1 or DAC_MUTE = 1, t_{WU} = 4 FSYNC cycles to 7 FSYNC cycles + 7.68 ms				
f_S = 12 kHz			8.01		8.27	ms
f_S = 24 kHz			7.84		7.98	ms
f_S = 48 kHz			7.76		7.83	ms
f_S = 96 kHz			7.72		7.76	ms
f_S = 192 kHz			7.70		7.72	ms
Turn On Time, Volume Ramp Enabled	t_{WUR}	Time from SPWDN = 0 to full volume output switching, DAC_HV = 0 and DAC_MUTE = 0, VOL = 0x40				
f_S = 12 kHz		$t_{WUR} = t_{WU} + 15.83$ ms	23.84		24.10	ms
f_S = 24 kHz		$t_{WUR} = t_{WU} + 15.83$ ms	23.67		23.81	ms
f_S = 48 kHz		$t_{WUR} = t_{WU} + 15.83$ ms	23.59		23.66	ms
f_S = 96 kHz		$t_{WUR} = t_{WU} + 7.92$ ms	15.64		15.68	ms
f_S = 192 kHz		$t_{WUR} = t_{WU} + 0.99$ ms	8.69		8.71	ms
Turn Off Time, Volume Ramp Disabled	t_{SD}	Time from SPWDN = 1 to full power-down, DAC_HV = 1 or DAC_MUTE = 1		100		μ s
Turn Off Time, Volume Ramp Enabled	t_{SDR}	Time from SPWDN = 1 to full power-down, DAC_HV = 0 and DAC_MUTE = 0, VOL = 0x40				
f_S = 12 kHz		$t_{SDR} = t_{SD} + 15.83$ ms		15.932		ms
f_S = 24 kHz		$t_{SDR} = t_{SD} + 15.83$ ms		15.932		ms
f_S = 48 kHz		$t_{SDR} = t_{SD} + 15.83$ ms		15.932		ms
f_S = 96 kHz		$t_{SDR} = t_{SD} + 7.92$ ms		8.016		ms
f_S = 192 kHz		$t_{SDR} = t_{SD} + 0.99$ ms		1.09		ms
Output Impedance	Z_{OUT}		100			k Ω
NOISE PERFORMANCE²						
Output Voltage Noise	e_n	f = 20 Hz to 20 kHz, A-weighted, $PV_{DD} = 12$ V		37.5		μ V rms
		f = 20 Hz to 20 kHz, A-weighted, $PV_{DD} = 17$ V		48		μ V rms
Signal-to-Noise Ratio	SNR	$P_{OUT} = 8.2$ W, $R_L = 8$ Ω , A-weighted, $PV_{DD} = 12$ V		107		dB
		$P_{OUT} = 31$ W, $R_L = 4$ Ω , A-weighted, $PV_{DD} = 17$ V		107		dB
PVDD ADC PERFORMANCE						
PVDD Sense Full-Scale Range		PVDD with full-scale ADC out	3.8		16.2	V
PVDD Sense Absolute Accuracy		$PV_{DD} = 15$ V	-8		+8	LSB
		$PV_{DD} = 5$ V	-6		+6	LSB
Resolution		Unsigned 8-bit output with 3.8 V offset		8		Bits
DIE TEMPERATURE						
Overtemperature Warning				117		$^{\circ}$ C
Overtemperature Protection				145		$^{\circ}$ C

¹ Guaranteed by design.² Noise performance is based on the bench data for $T_A = -40^{\circ}$ C to $+85^{\circ}$ C.

Software master power-down indicates that the clocks are turned off. Auto power-down indicates that there is no dither or zero input signal with clocks on; the device enters soft power-down after 2048 cycles of zero input values. Quiescent indicates triangular dither with zero input signal. All specifications are typical, with a 48 kHz sample rate, unless otherwise noted.

Table 2. Power Supply Current Consumption¹

Edge Rate Control Mode	REG_EN Pin	Test Conditions	No Load				4 Ω + 15 μH				8 Ω + 33 μH				Unit
			I _{PVDD}			I _{REG18}	I _{PVDD}			I _{REG18}	I _{PVDD}			I _{REG18}	
			5 V	12 V	17 V	1.8 V	5 V	12 V	17 V	1.8 V	5 V	12 V	17 V	1.8 V	
Normal	Low	Software master power-down	0.01	0.03	0.03	7	0.01	0.03	0.03	7	0.01	0.03	0.03	7	μA
		Auto power-down	0.01	0.03	0.03	54	0.01	0.03	0.03	54	0.01	0.03	0.03	54	μA
		Quiescent	4.10	5.00	5.60	0.48	4.10	5.12	5.90	0.48	4.10	5.10	5.80	0.48	mA
	PVDD	Software master power-down	0.01	0.03	0.03	N/A	0.01	0.03	0.03	N/A	0.01	0.03	0.03	N/A	μA
		Auto power-down	310	310	316	N/A	310	310	316	N/A	310	310	316	N/A	μA
		Quiescent	4.64	5.60	6.26	N/A	4.74	5.85	6.55	N/A	4.74	5.85	6.55	N/A	mA
Low EMI	Low	Software master power-down	0.01	0.03	0.03	7	0.01	0.03	0.03	7	0.01	0.03	0.03	7	μA
		Auto power-down	0.01	0.03	0.03	54	0.01	0.03	0.03	54	0.01	0.03	0.03	54	μA
		Quiescent	4.00	4.95	5.54	0.48	4.70	3.99	5.59	0.48	4.02	4.98	5.63	0.48	mA
	PVDD	Software master power-down	0.01	0.03	0.03	N/A	0.01	0.03	0.03	N/A	0.01	0.03	0.03	N/A	μA
		Auto power-down	310	310	316	N/A	310	310	316	N/A	310	310	316	N/A	μA
		Quiescent	4.60	5.60	6.17	N/A	4.60	5.65	6.35	N/A	4.60	5.60	6.40	N/A	mA

¹ N/A means not applicable.

Table 3. Power-Down Current

Parameter	Symbol	Test Conditions/Comments	Min	Typ	Max	Unit
POWER-DOWN CURRENT	I _{PVDD}	VREG18/DVDD = 1.8 V external, software master power-down, no BCLK/FSYNC				
		PV _{DD} = 5 V	27	38	95	nA
		PV _{DD} = 12 V	30	39	100	nA
	PV _{DD} = 17 V	30	39	152	nA	
	I _{DVDD}	VREG18/DVDD = 1.8 V external		7	27	μA

Table 4. Digital Input/Output

Parameter	Min	Typ	Max	Unit	Test Comments/Comments
INPUT VOLTAGE ¹					
High (V _{IH})					
BCLK, FSYNC, SCL, SDA	1.13		5.5	V	
SDATA, ADDR	0.7 × VREG18/DVDD		1.98	V	
Low (V _{IL})					
BCLK, FSYNC, SDA, SCL, SDA	-0.3		+0.54	V	
ADDR	-0.3		+1.98	V	
INPUT LEAKAGE					
High (I _{IH})			1	μA	
Low (I _{IL})			1	μA	
INPUT CAPACITANCE			5	pF	
OUTPUT VOLTAGE (SDATA)					
High (V _{OH})	1.17			V	
Low (V _{OL})			0.45	V	
OUTPUT DRIVE STRENGTH ¹					
SDA	3		5	mA	
SDATA	2		24	mA	
BCLK Frequency (BCLK)	2.048		24.576	MHz	
Sample Rate (FSYNC)	8		192	kHz	

¹ The pull-up resistor for SCL and SDA must be scaled according to the external pull-up voltage in the system. The typical value for a pull-up resistor for 1.8 V is 2.2 kΩ.

DIGITAL TIMING CHARACTERISTICS

All timing specifications are given for the default setting (I²S mode) of the serial input port.

Table 5. I²C Port Timing

Parameter	Limit		Unit	Description
	Min	Max		
I ² C PORT				
f _{SCL}		400	kHz	SCL frequency
t _{SCLH}	0.6		μs	SCL high
t _{SCLL}	1.3		μs	SCL low
t _{SCS}	0.6		μs	Setup time; relevant for repeated start condition
t _{SCH}	0.6		μs	Hold time; after this period, the first clock is generated
t _{DS}	100		ns	Data setup time
t _{SCR}		300	ns	SCL rise time
t _{SCF}		300	ns	SCL fall time
t _R		300	ns	SDA rise time, not shown in Figure 2
t _F		300	ns	SDA fall time, not shown in Figure 2
t _{BFT}	0.6		μs	Bus-free time (time between stop and start)
t _{HOLD}		140	ns	SCL falling to SDA rising
	0		ns	SCL falling to SDA falling

Table 6. Digital Input Timing

Parameter	Limit		Unit	Description
	T _{MIN}	T _{MAX}		
SERIAL PORT				
t _{BIL}	15		ns	BCLK low pulse width
t _{BIH}	15		ns	BCLK high pulse width
t _{SIS}	6		ns	SDATA setup, time to BCLK rising
t _{SIH}	6		ns	SDATA hold, time from BCLK rising
t _{LIS}	10		ns	FSYNC setup time to BCLK rising
t _{LIH}	5		ns	FSYNC hold time to BCLK rising
t _{BP}	40		ns	Minimum BCLK period

Digital Timing Diagrams

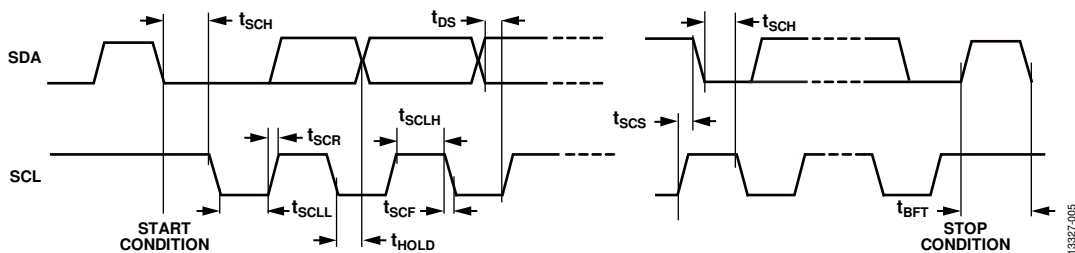


Figure 2. I²C Port Timing

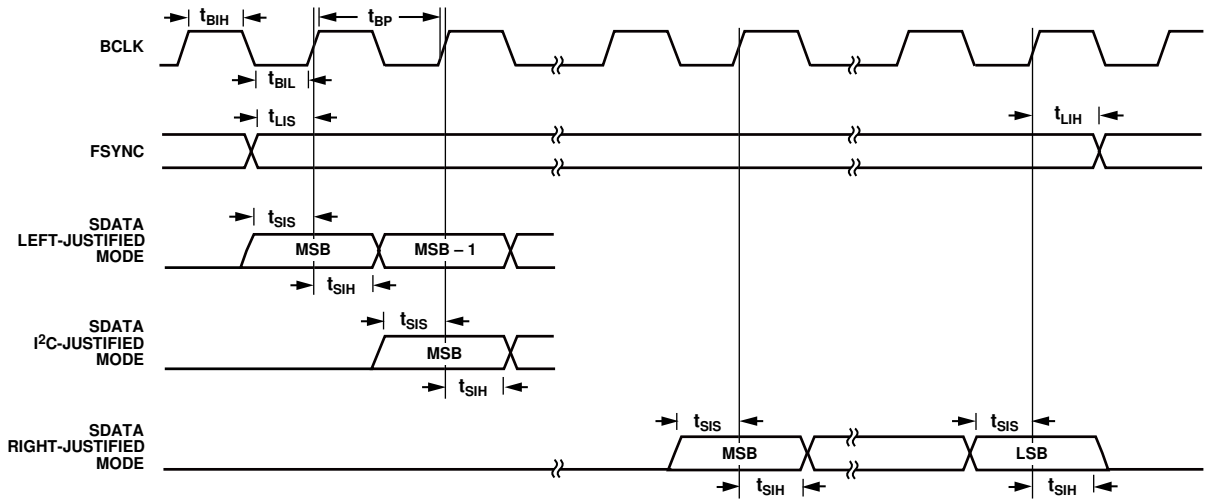


Figure 3. Serial Input Port Timing

13327-002

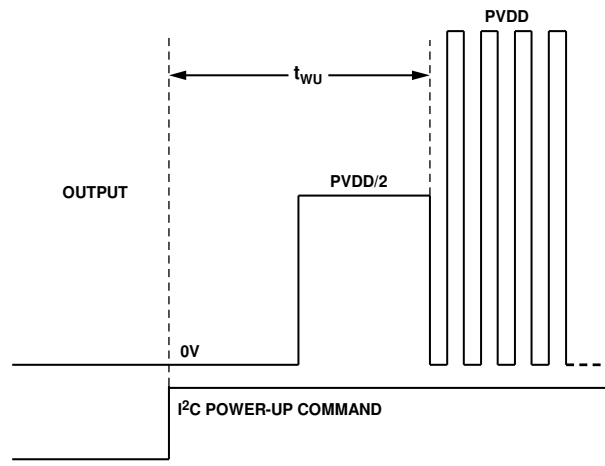


Figure 4. Turn On Hard Volume

13327-161

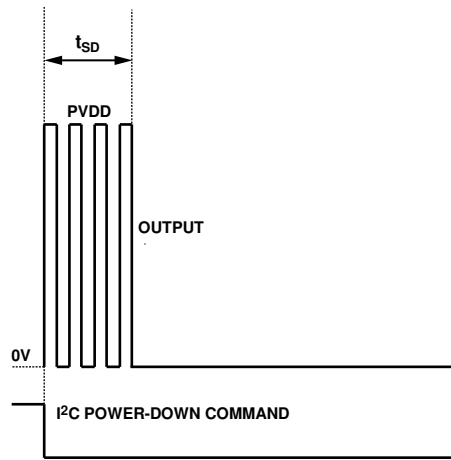


Figure 5. Turn Off Hard Volume

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ABSOLUTE MAXIMUM RATINGS

Absolute maximum ratings apply at $T_A = 25^\circ\text{C}$, unless otherwise noted.

Table 7.

Parameter	Rating
PVDD Supply Voltage	-0.3 V to +18 V
VREG18/DVDD Supply Voltage	-0.3 V to +1.98 V
VREG50/AVDD Supply Voltage	-0.3 V to +5.5 V
PGND and AGND Differential	± 0.3 V
ADDR, SDATA Input Voltage	-0.3 V to +1.98 V
SCL, SDA, BCLK, FSYNC Input Voltage	-0.3 V to +5.5 V
REG_EN Input Voltage	-0.3 V to +18 V
Storage Temperature Range	-65°C to $+150^\circ\text{C}$
Operating Temperature Range	-40°C to $+85^\circ\text{C}$
Junction Temperature Range	-65°C to $+165^\circ\text{C}$
Lead Temperature Range (Soldering, 60 sec)	300°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL RESISTANCE

θ_{JA} (junction to air) is specified for worst case conditions, that is, a device soldered in a circuit board for surface-mount packages. θ_{JA} and θ_{JB} are determined according to JESD51-9 on a 4-layer printed circuit board (PCB) with natural convection cooling.

Table 8. Thermal Resistance

Package Type	θ_{JA}	Unit
20-Ball, 1.8 mm \times 2.2 mm WLCSP	55.5	$^\circ\text{C}/\text{W}$

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

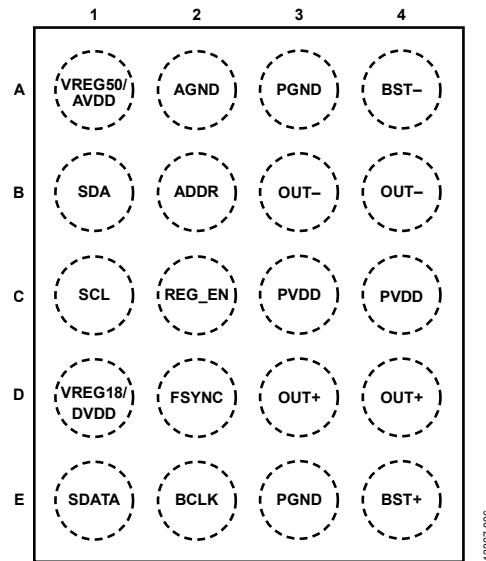


Figure 6. Pin Configuration (Top Side View)

Table 9. Pin Function Descriptions

Pin No.	Mnemonic	Type ¹	Description
A1	VREG50/AVDD	AOUT	5 V Regulator Output.
A2	AGND	PWR	Analog Ground. It is recommended to connect the AGND pin to a single ground plane on the board.
A3	PGND	PWR	Power Stage Ground. The PGND pin is shorted internally. It is recommended to connect PGND to a single ground plane on the board.
A4	BST-	AIN	Bootstrap Capacitor for OUT-.
B1	SDA	DIO	I ² C Serial Data.
B2	ADDR	DIN	I ² C Address Selection.
B3	OUT-	AOUT	Power Stage Inverting Output.
B4	OUT-	AOUT	Power Stage Inverting Output.
C1	SCL	DIN	I ² C Clock.
C2	REG_EN	AIN	Regulator Enable Tie to PVDD to Enable Regulators.
C3	PVDD	PWR	Power Stage Supply.
C4	PVDD	PWR	Power Stage Supply.
D1	VREG18/DVDD	PWR	1.8 V Regulator Output/DVDD Input.
D2	FSYNC	DIN	TDM Frame Sync Input.
D3	OUT+	AOUT	Power Stage Noninverting Output.
D4	OUT+	AOUT	Power Stage Noninverting Output.
E1	SDATA	DIO	Serial Data Input to DAC.
E2	BCLK	DIN	TDM Bit Clock Input.
E3	PGND	PWR	Power Stage Ground. The PGND pin is shorted internally. It is recommended to connect PGND to a single ground plane on the board.
E4	BST+	AIN	Bootstrap Capacitor for OUT+.

¹ AOUT is analog output; PWR is power supply or ground pin; AIN is analog input; DIO is digital input/output; DIN is digital input.

TYPICAL PERFORMANCE CHARACTERISTICS

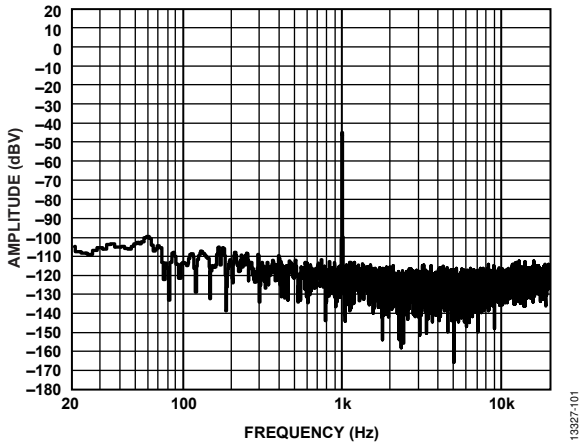


Figure 7. Fast Fourier Transform (FFT), 60 dBFS Input, Analog Gain = 8.4, $R_L = 4 \Omega$

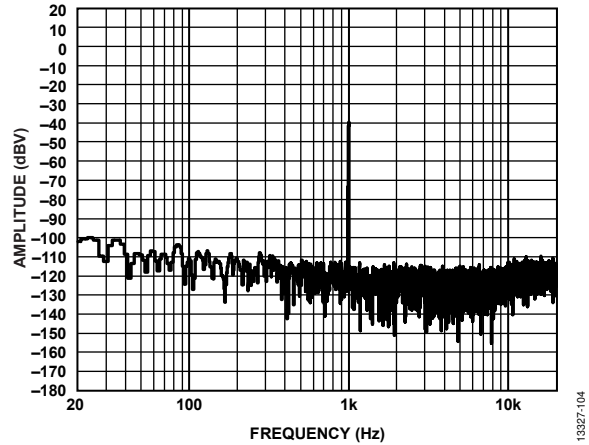


Figure 10. FFT, 60 dBFS Input, Analog Gain = 15, $R_L = 4 \Omega$

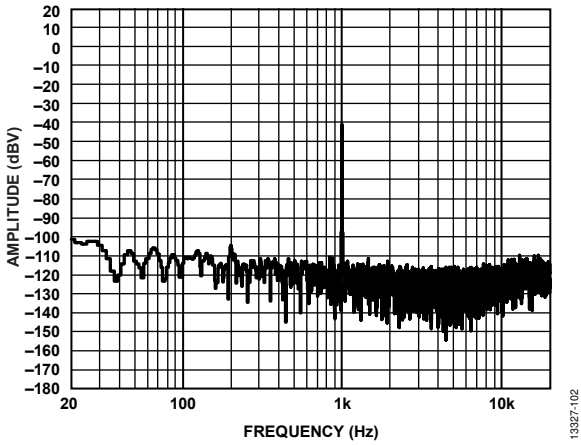


Figure 8. FFT, 60 dBFS Input, Analog Gain = 12.6, $R_L = 4 \Omega$

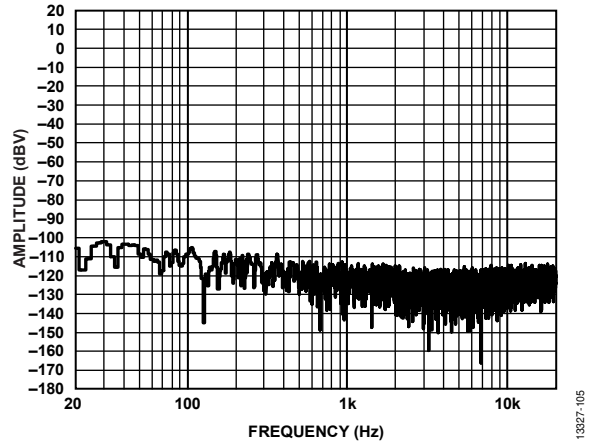


Figure 11. FFT, No Signal, Analog Gain = 8.4, $R_L = 4 \Omega$

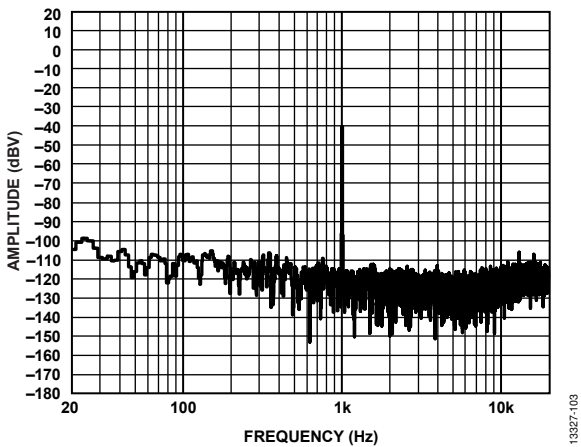


Figure 9. FFT, 60 dBFS Analog Gain = 14, $R_L = 4 \Omega$

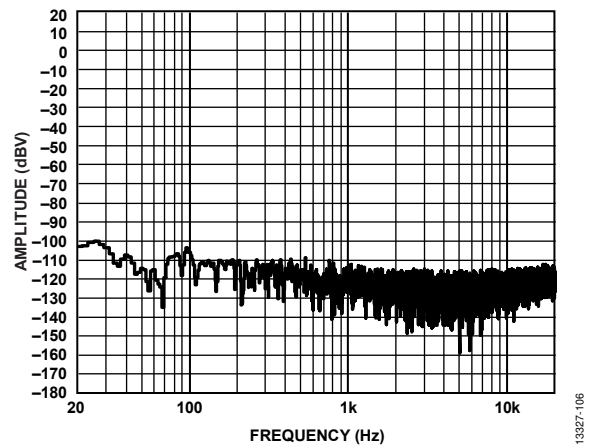


Figure 12. FFT, No Signal, Analog Gain = 12.6, $R_L = 4 \Omega$

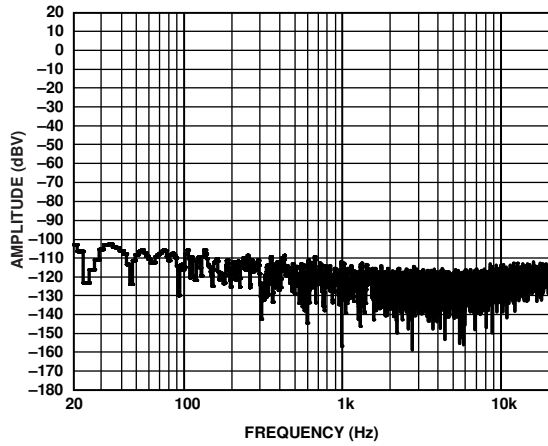


Figure 13. FFT, No Signal, Analog Gain = 14, $R_L = 4 \Omega$

13327-107

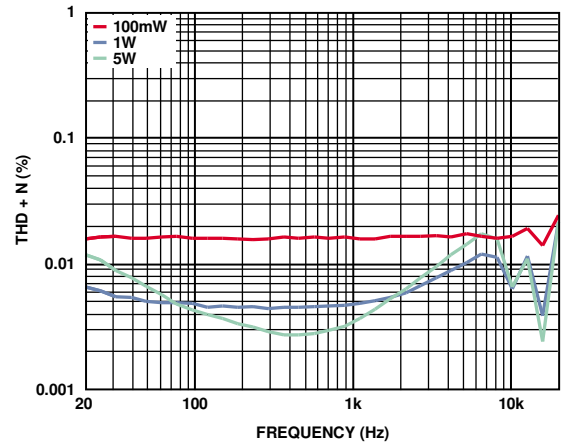


Figure 16. THD + N vs. Frequency, $R_L = 4 \Omega$, $PV_{DD} = 12 V$

13327-008

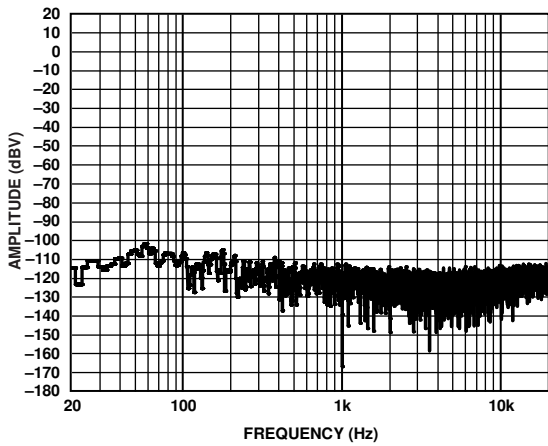


Figure 14. FFT, No Signal, Analog Gain = 15, $R_L = 4 \Omega$

13327-108

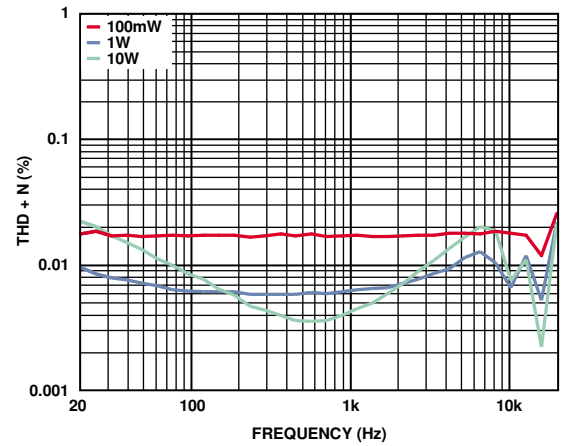


Figure 17. THD + N vs. Frequency, $R_L = 4 \Omega$, $PV_{DD} = 17 V$

13327-009

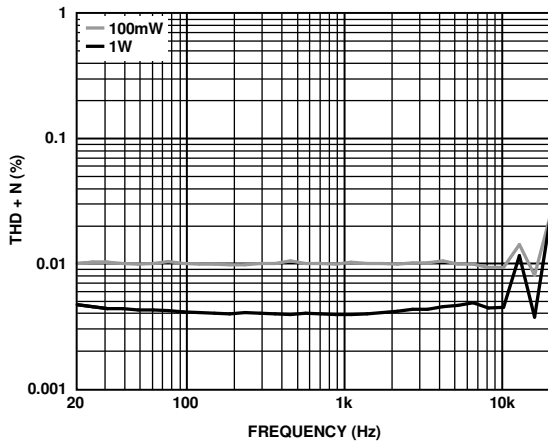


Figure 15. THD + N vs. Frequency into $R_L = 4 \Omega$, $PV_{DD} = 4.5 V$

13327-007

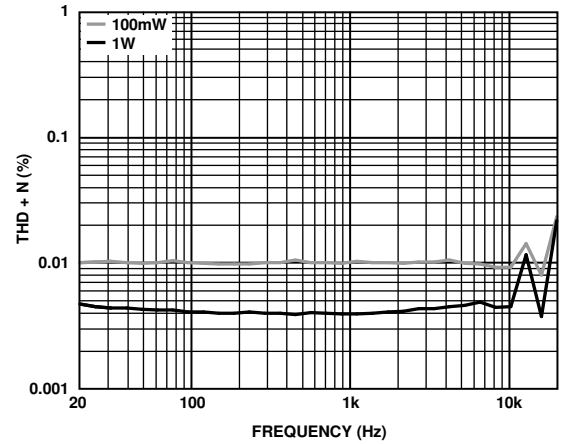


Figure 18. THD + N vs. Frequency, $R_L = 8 \Omega$, $PV_{DD} = 4.5 V$

13327-010

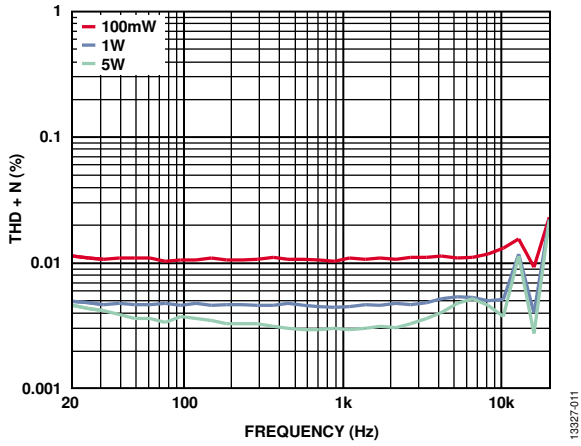


Figure 19. THD + N vs. Frequency, $R_L = 8 \Omega$, $PV_{DD} = 12 V$

13327-011

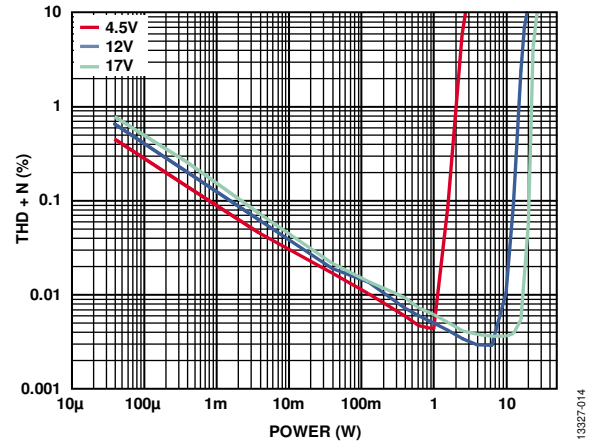


Figure 22. THD + N vs. Output Power, $R_L = 4 \Omega$, Analog Gain = 12.6

13327-014

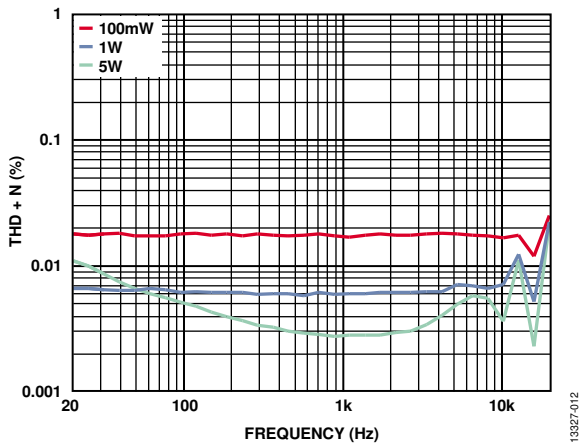


Figure 20. THD + N vs. Frequency, $R_L = 8 \Omega$, $PV_{DD} = 17 V$

13327-012

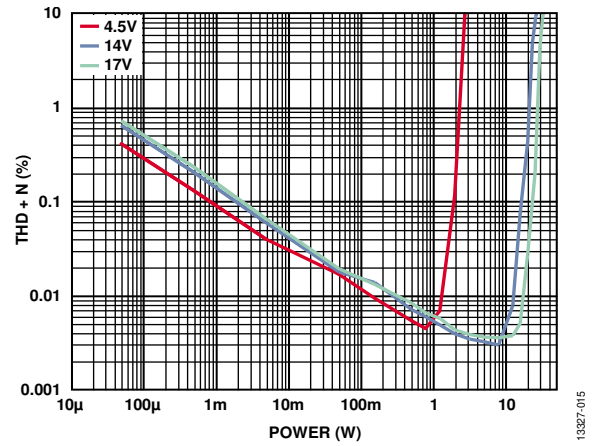


Figure 23. THD + N vs. Output Power, $R_L = 4 \Omega$, Analog Gain = 14

13327-015

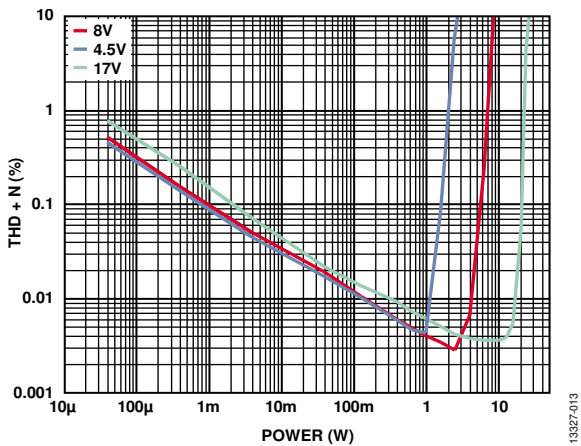


Figure 21. THD + N vs. Output Power, $R_L = 4 \Omega$, Analog Gain = 8.4

13327-013

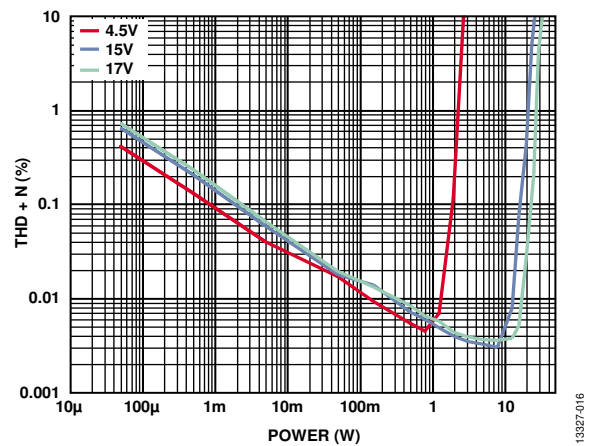


Figure 24. THD + N vs. Output Power, $R_L = 4 \Omega$, Analog Gain = 15

13327-016

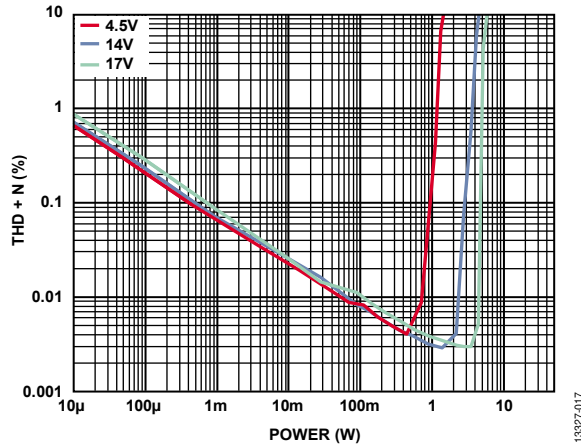


Figure 25. THD + N vs. Output Power, $R_L = 8 \Omega$, Analog Gain = 8.4

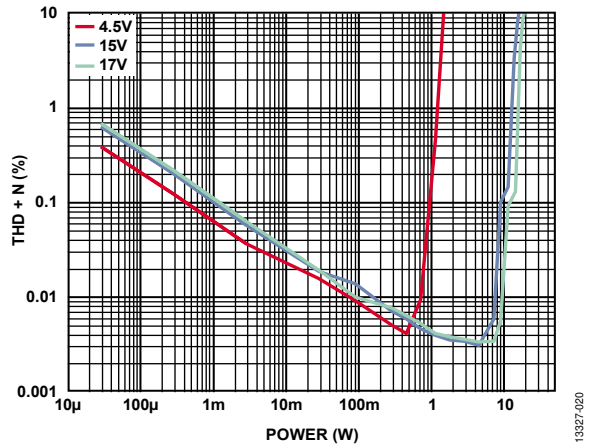


Figure 28. THD + N vs. Output Power, $R_L = 8 \Omega$, Analog Gain = 15

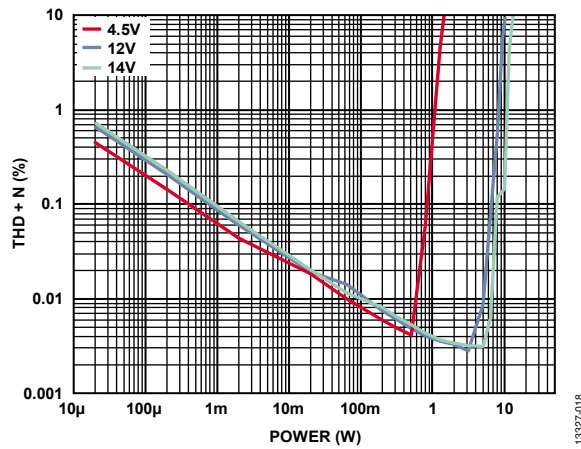


Figure 26. THD + N vs. Output Power, $R_L = 8 \Omega$, Analog Gain = 12.6

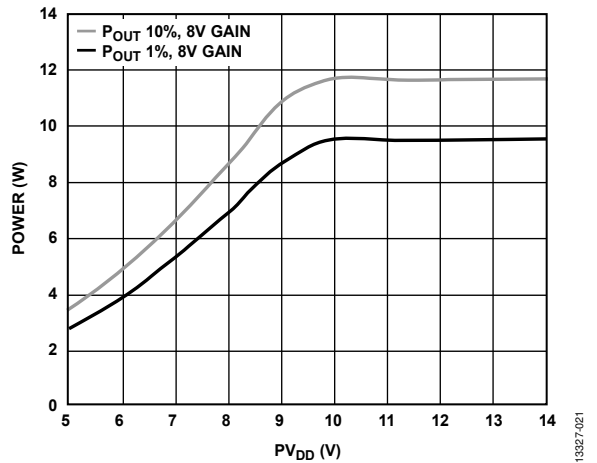


Figure 29. Output Power vs. PV_{DD} Supply Voltage (PV_{DD}), $R_L = 4 \Omega$, Analog Gain = 8.4

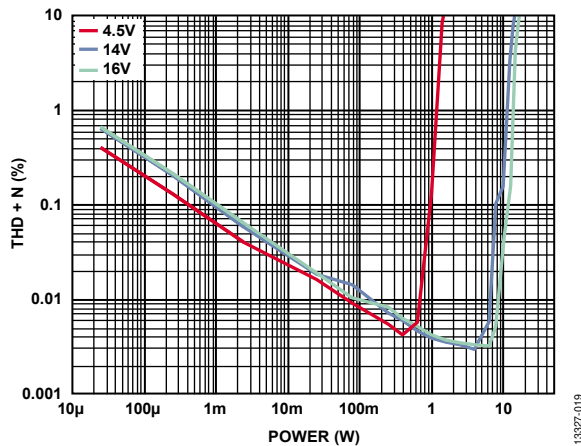


Figure 27. THD + N vs. Output Power, $R_L = 8 \Omega$, Analog Gain = 14

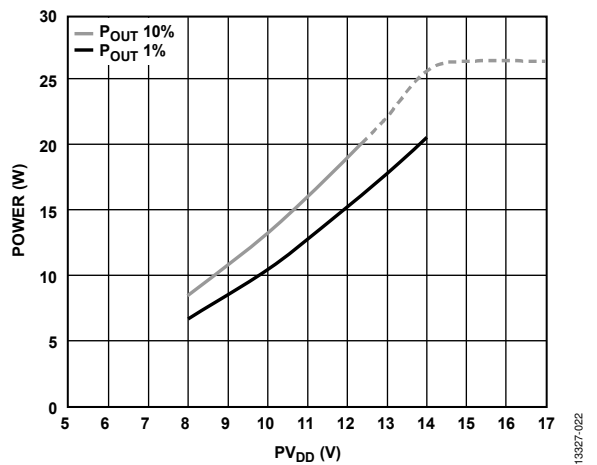


Figure 30. Output Power vs. PV_{DD} , $R_L = 4 \Omega$, Analog Gain = 12.6

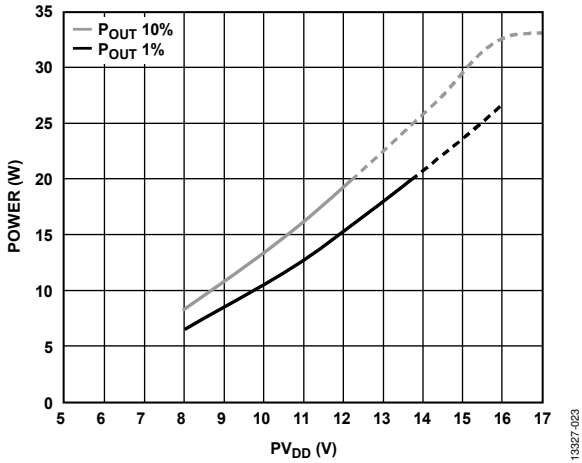


Figure 31. Output Power vs. P_{VDD} , $R_L = 4 \Omega$, Analog Gain = 14

13327-023

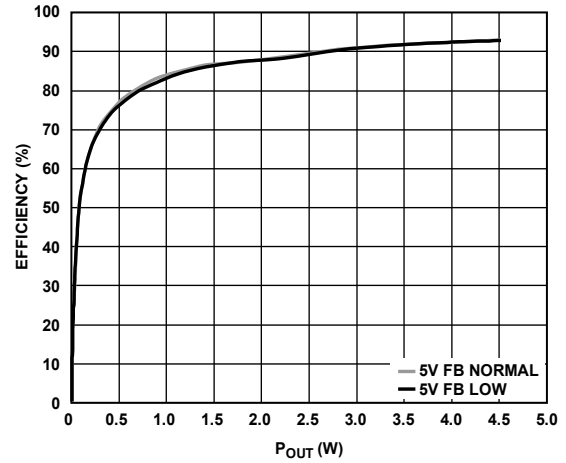


Figure 34. Efficiency vs. P_{OUT} , $R_L = 4 \Omega$, FB and 220 pF Capacitor, $P_{VDD} = 5 V$, Analog Gain = 8.4

13327-026

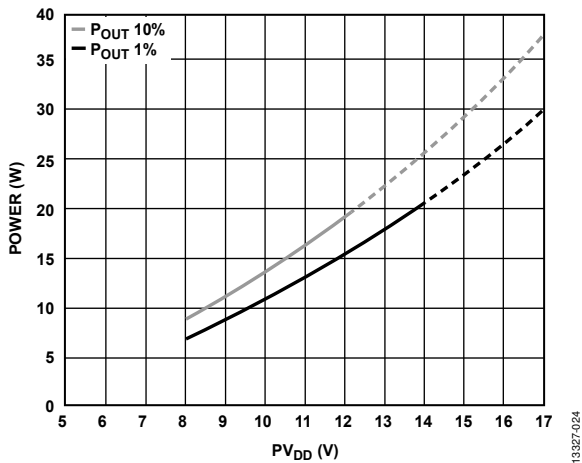


Figure 32. Output Power vs. P_{VDD} , $R_L = 4 \Omega$, Analog Gain = 15

13327-024

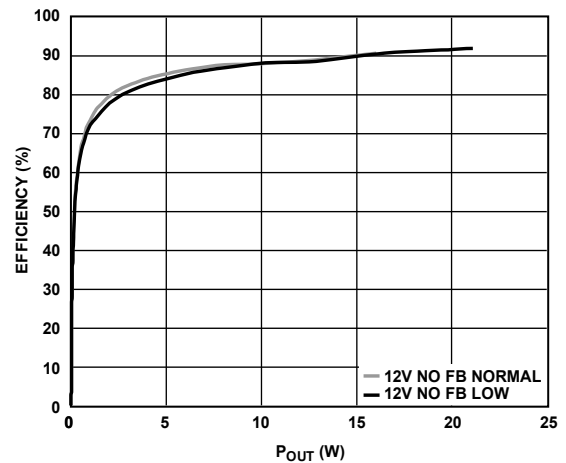


Figure 35. Efficiency vs. P_{OUT} , $R_L = 4 \Omega$, No FB and 220 pF, $P_{VDD} = 12 V$, Analog Gain = 12.6

13327-027

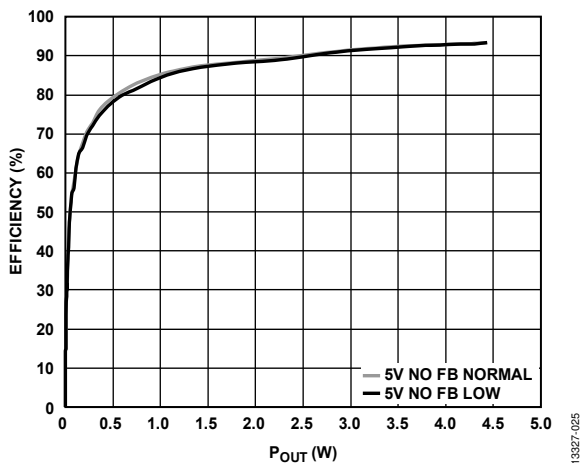


Figure 33. Efficiency vs. Output Power (P_{OUT}), $R_L = 4 \Omega$, No Ferrite Bead (FB) and 220 pF Capacitor, $P_{VDD} = 5 V$, Analog Gain = 8.4

13327-025

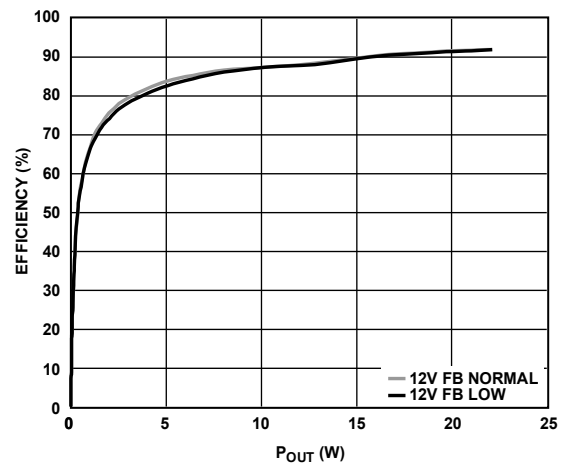


Figure 36. Efficiency vs. P_{OUT} , $R_L = 4 \Omega$, FB and 220 pF Capacitor, $P_{VDD} = 12 V$, Analog Gain = 12.6

13327-028

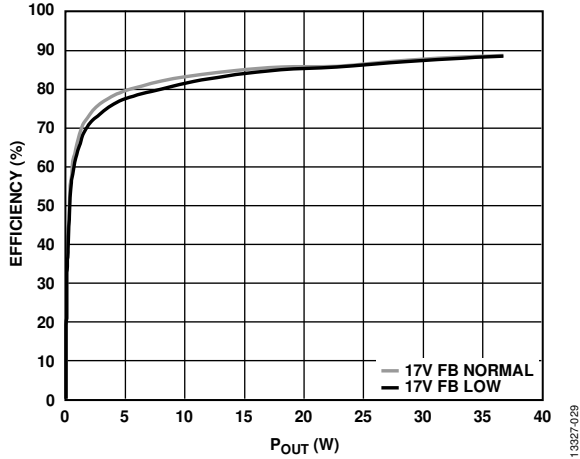


Figure 37. Efficiency vs. P_{OUT} , $R_L = 4 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 17 V$, Analog Gain = 14

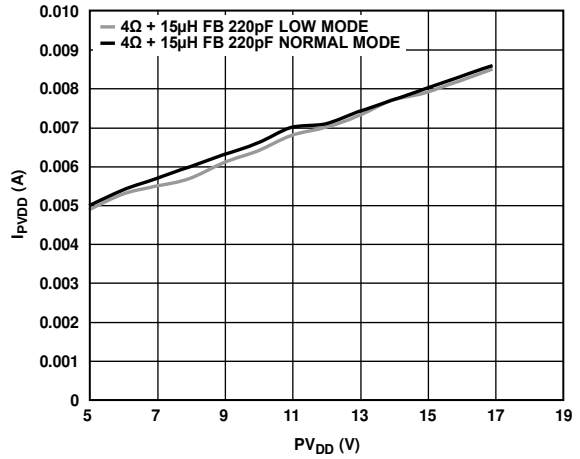


Figure 40. Quiescent Current, $R_L = 4 \Omega$, FB and 220 pF Capacitor, Analog Gain = 12

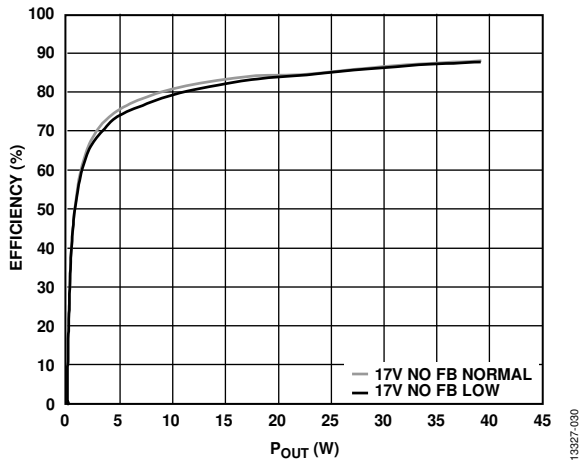


Figure 38. Efficiency vs. P_{OUT} , $R_L = 4 \Omega$, No FB and 220 pF Capacitor, $PV_{DD} = 17 V$, Analog Gain = 14

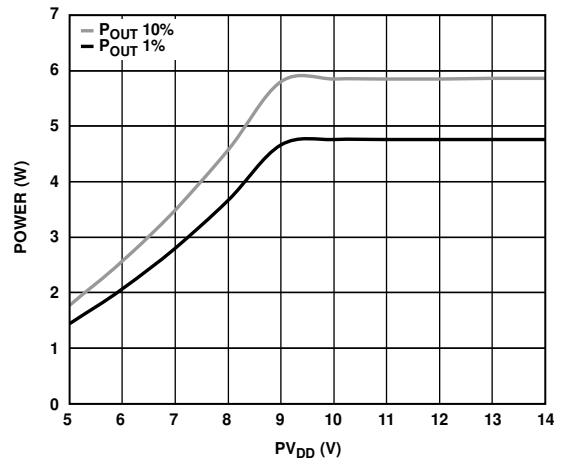


Figure 41. Output Power vs. PV_{DD} , $R_L = 8 \Omega$, Analog Gain = 8

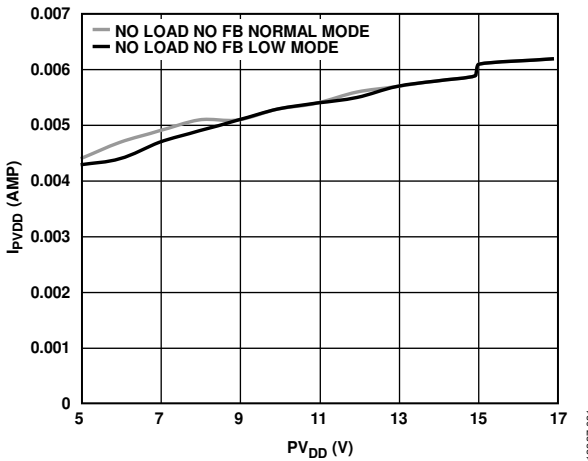


Figure 39. Quiescent Current, $R_L = 4 \Omega$, No FB and 220 pF Capacitor, Analog Gain = 12

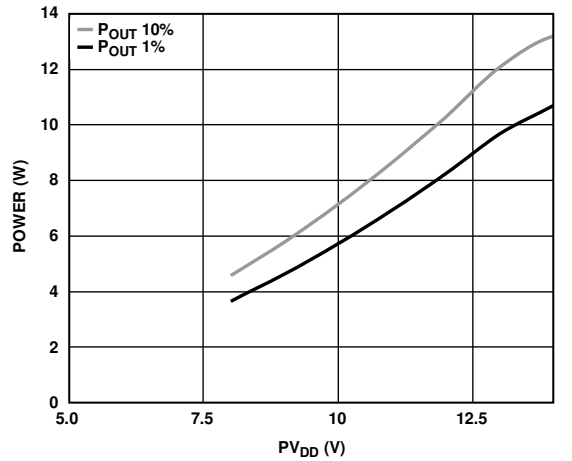


Figure 42. Output Power vs. PV_{DD} , $R_L = 8 \Omega$, Analog Gain = 12

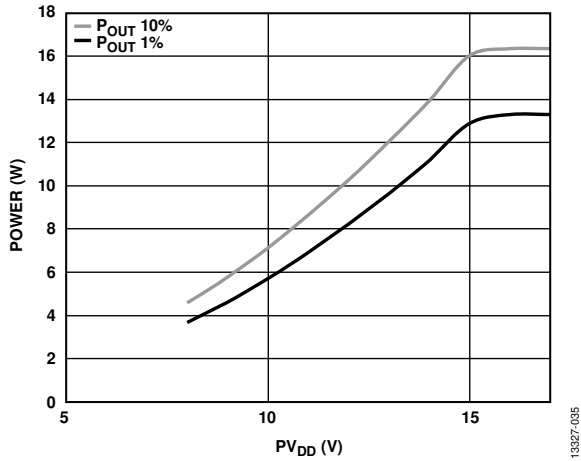


Figure 43. Output Power vs. P_{VDD} , $R_L = 8 \Omega$, Analog Gain = 14

13327-035

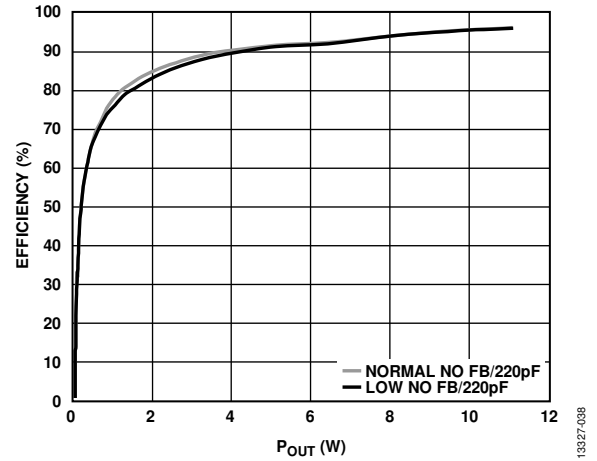


Figure 46. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, No FB and 220 pF Capacitor, $P_{VDD} = 12 V$, Analog Gain = 12.6

13327-038

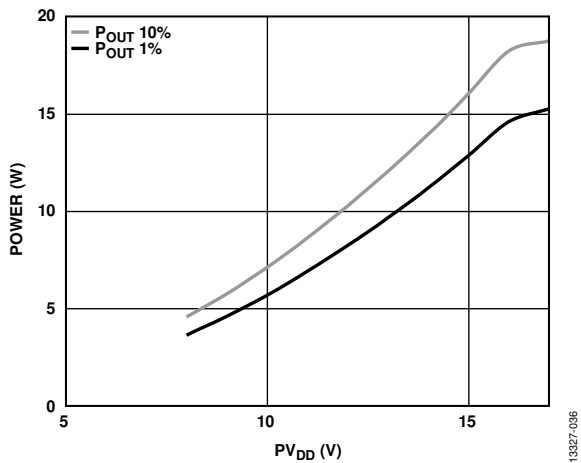


Figure 44. Output Power vs. P_{VDD} , $R_L = 8 \Omega$, Analog Gain = 15

13327-036

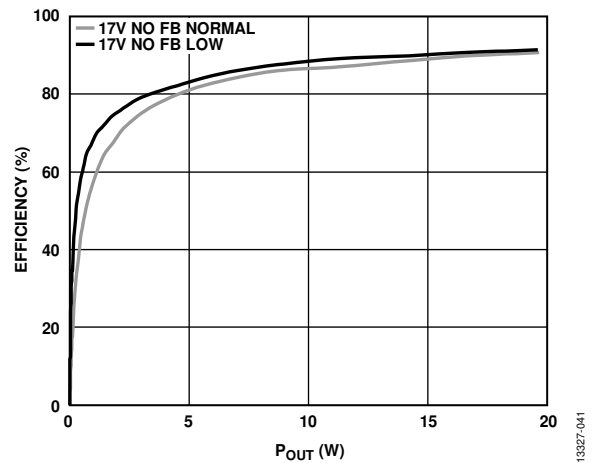


Figure 47. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, No FB and 220 pF Capacitor, $P_{VDD} = 17 V$, Analog Gain = 14

13327-041

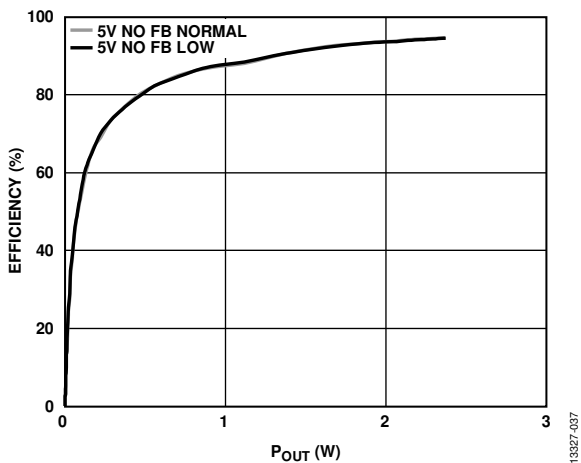


Figure 45. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, No FB and 220 pF Capacitor, $P_{VDD} = 5 V$, Analog Gain = 8.4

13327-037

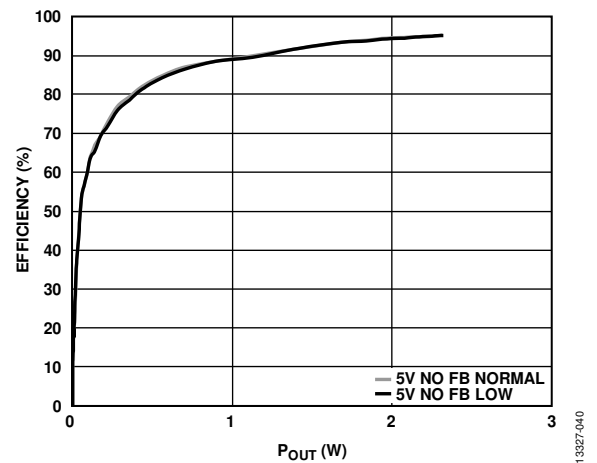


Figure 48. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, FB and 220 pF Capacitor, $P_{VDD} = 5 V$, Analog Gain = 8.4

13327-040

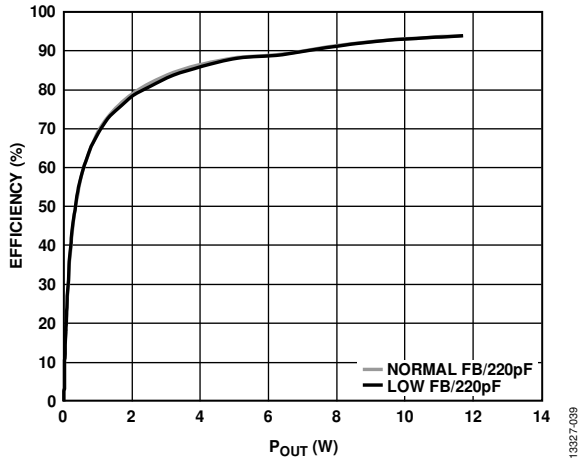


Figure 49. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 12 V$, Analog Gain = 12.6

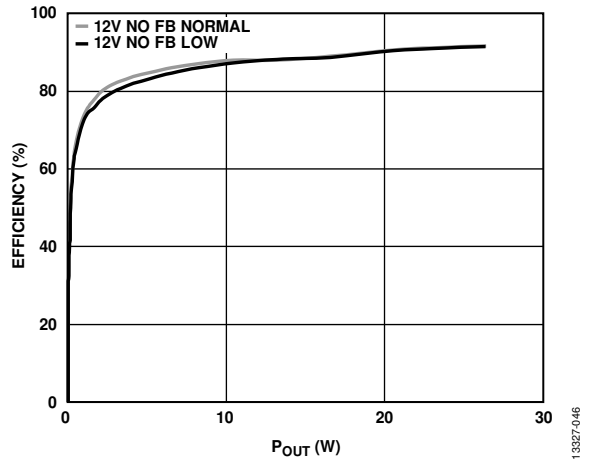


Figure 52. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, No FB and 220 pF Capacitor, $PV_{DD} = 12 V$, Analog Gain = 12.6

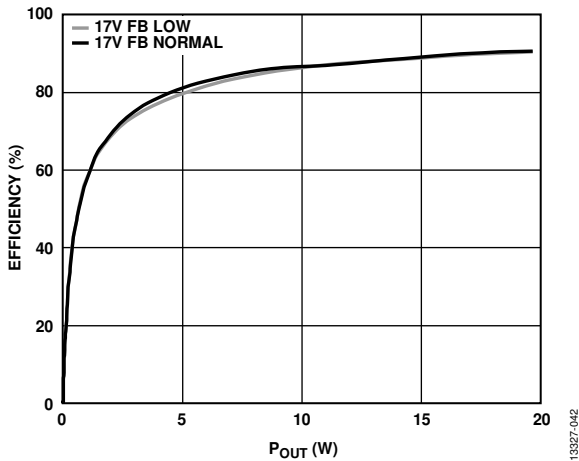


Figure 50. Efficiency vs. P_{OUT} , $R_L = 8 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 17 V$, Analog Gain = 14

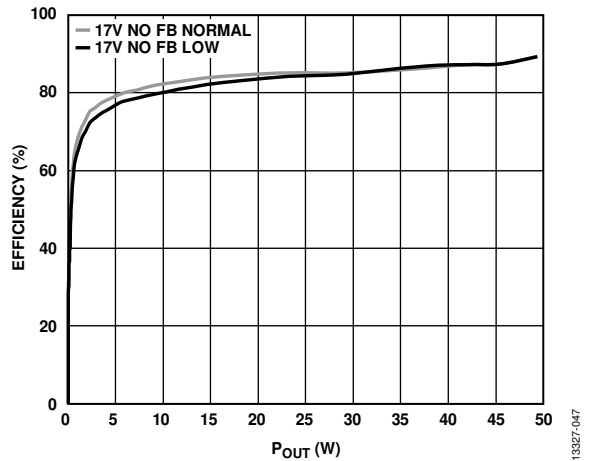


Figure 53. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, No FB and 220 pF Capacitor, $PV_{DD} = 17 V$, Analog Gain = 14

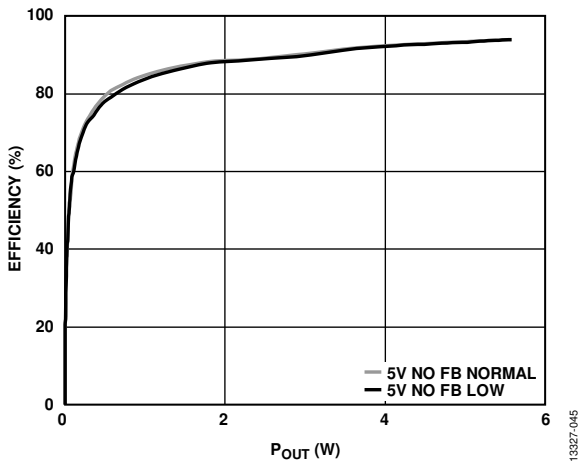


Figure 51. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, No FB and 220 pF Capacitor, $PV_{DD} = 5 V$, Analog Gain = 8.4

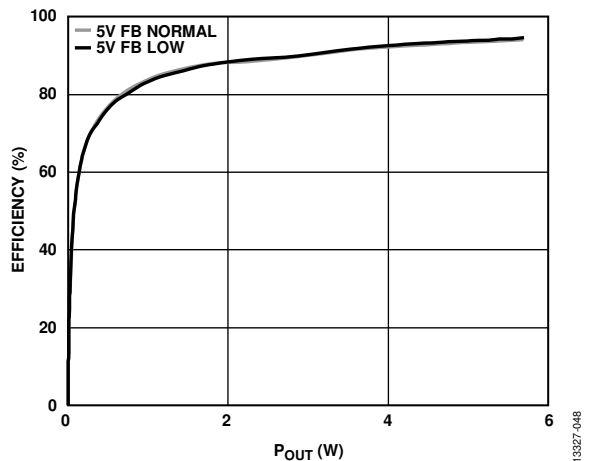


Figure 54. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 5 V$, Analog Gain = 8.4

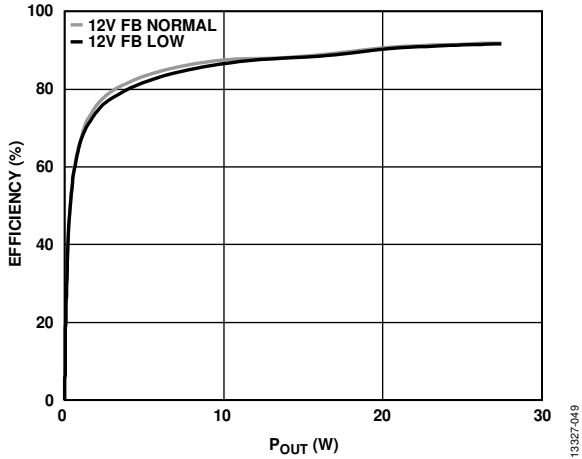


Figure 55. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 12 V$, Analog Gain = 12.6

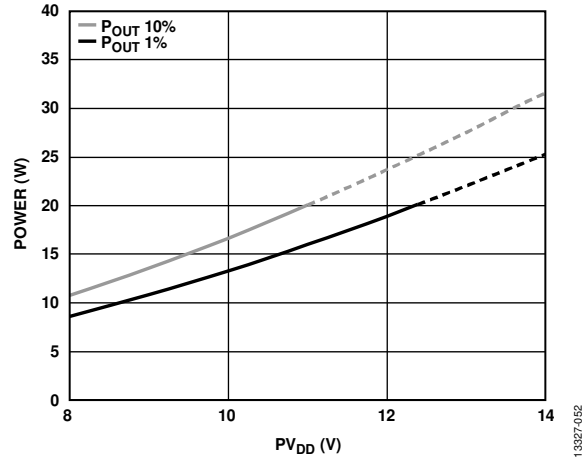


Figure 58. Output Power vs. PV_{DD} , $R_L = 3 \Omega$, Analog Gain = 12.6

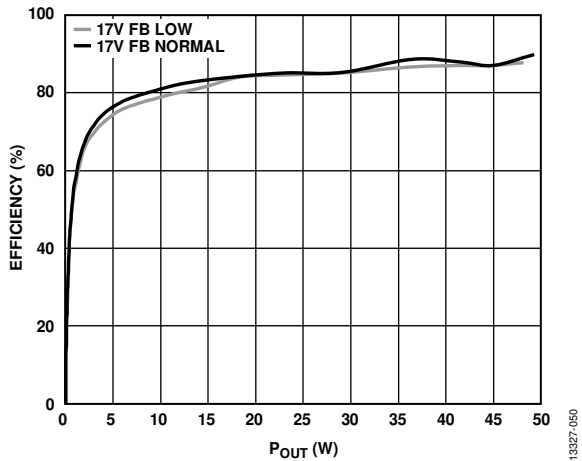


Figure 56. Efficiency vs. P_{OUT} , $R_L = 3 \Omega$, FB and 220 pF Capacitor, $PV_{DD} = 17 V$, Analog Gain = 14

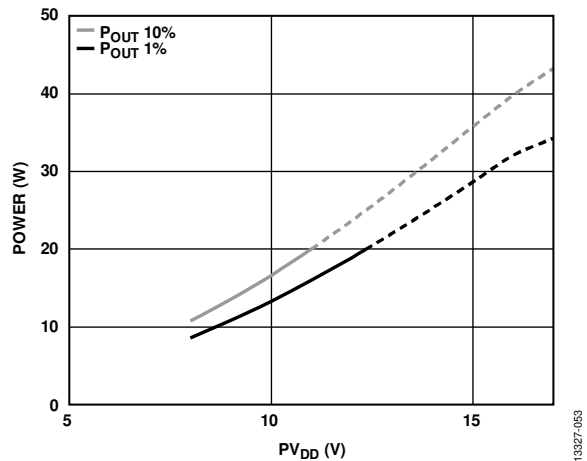


Figure 59. Output Power vs. PV_{DD} , $R_L = 3 \Omega$, Analog Gain = 14

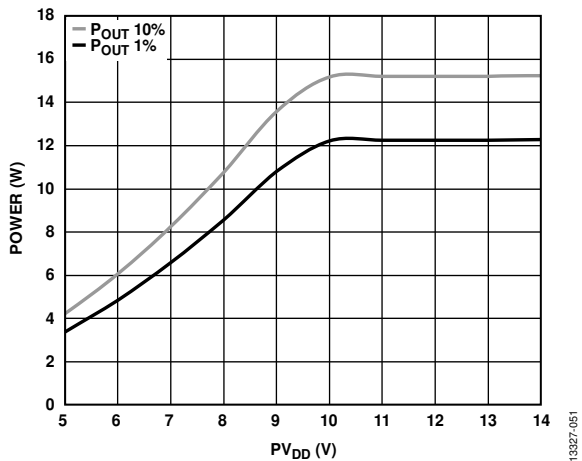


Figure 57. Output Power vs. PV_{DD} , $R_L = 3 \Omega$, Analog Gain = 8.4

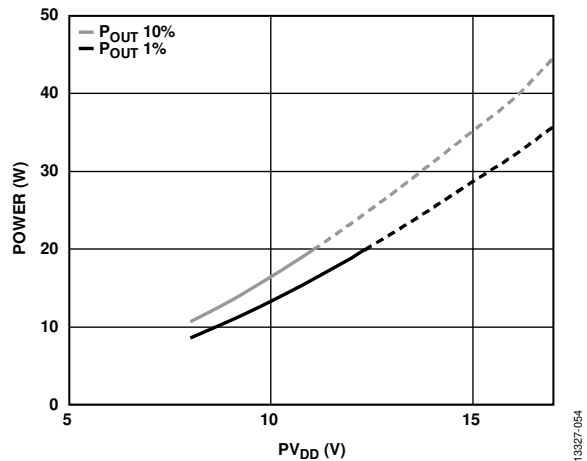


Figure 60. Output Power vs. PV_{DD} , $R_L = 3 \Omega$, Analog Gain = 15

THEORY OF OPERATION

OVERVIEW

The [SSM3515](#) Class-D audio amplifier features a filterless modulation scheme that greatly reduces the external component count, conserving board space and reducing system cost. The [SSM3515](#) does not require an output filter; it relies on the inherent inductance of the speaker coil and the natural filtering of the speaker and human ear to recover the audio component of the square wave output.

Most Class-D amplifiers use some variation of pulse-width modulation (PWM), but the [SSM3515](#) uses Σ - Δ modulation to determine the switching pattern of the output devices, resulting in a number of important benefits. Σ - Δ modulators do not produce a sharp peak with many harmonics in the AM broadcast band, as pulse-width modulators often do. Σ - Δ modulation reduces the amplitude of spectral components at high frequencies, reducing EMI emission that may otherwise be radiated by speakers and long cable traces. Due to the inherent spread spectrum nature of Σ - Δ modulation, the need for oscillator synchronization is eliminated for designs incorporating multiple [SSM3515](#) amplifiers.

The [SSM3515](#) also integrates overcurrent and temperature protection and a thermal warning with optional programmable gain reduction.

POWER SUPPLIES

The power supply pins on the [SSM3515](#) are PVDD, VREG50/AVDD, and VREG18/DVDD.

PVDD, the battery supply, is used for the output stage and also supplies power to the 5 V regulator. In addition, it can be used to supply power to the 1.8 V regulator. This pin must be decoupled to ground using a 100 nF capacitor in parallel with a 1 μ F MLCC capacitor to ground as close as possible to the respective pins. In addition, a bulk electrolytic capacitor may be required depending on the output power to supply the current at low frequency output. Typically, 220 μ F and 25 V is recommended. This must be sized according to the power supply regulation in the system.

VREG50/AVDD (5 V) is the analog supply used for the input stage, modulator, power stage driver, and other blocks. It uses the VREG50/AVDD pin. It is generated internally by the integrated 5 V linear regulator. This pin must be decoupled to ground using the 100 nF and 10 μ F capacitor.

VREG18/DVDD (1.8 V) is the supply for the digital circuitry. It uses the VREG18/DVDD pin. It can be generated internally using an integrated 1.8 V linear regulator. Alternatively, an external 1.8 V supply can be used to save the power dissipation. The VREG18/DVDD pin must be decoupled to ground using 100 nF and 10 μ F MLCC capacitors close to the pin.

POWER-UP SEQUENCE

If the REG_EN pin is tied to PVDD, the power-up sequence is performed internally. As the PVDD voltage ramps up, the VREG18/DVDD voltage (generated internally) also ramps up. The typical wait time before the I²C commands can be sent to the device depends on the PVDD supply ramp-up time.

If the REG_EN pin is tied low, ensure that 1.8 V is supplied externally and that PV_{DD} is greater than 4.5 V before sending I²C commands to enable the device.

POWER-DOWN OPERATION

The [SSM3515](#) offers several power down options via I²C. Register 0x00 provides multiple options for setting the various power-down modes.

Set the SPWDN bit to 1 to fully power down the device. Only the I²C, 1.8 V regulator is kept alive.

The [SSM3515](#) monitors both the BCLK and FSYNC pins for clock presence when in 2-wire mode. When no BCLK or FSYNC signals are present, the device automatically powers down all internal circuitry to its lowest power state. When a BCLK or FSYNC signal returns, the device automatically powers up following its usual power up sequence.

When enabled, the APWDN_EN bit (auto power down), activates a low power state as soon as 2048 consecutive zero input samples are received. Only the I²C and digital audio input blocks are kept active.

REG_EN PIN SETUP AND CONTROL

The REG_EN (regulator enable) pin enables or disables the internal 1.8 V regulator.

Table 10. Regulator Enable Pin Function

REG_EN	1.8 V Regulator	Comment
Ground	Disabled	External 1.8 V
PVDD	Enabled	Internal 1.8 V

The status of the REG_EN pin determines if the 1.8 V supply is generated internally or if it must be provided externally. If the REG_EN pin is tied to PVDD, the internal 1.8 V regulator is enabled. If the REG_EN pin is tied to ground, a 1.8 V supply must be supplied externally to the VREG18/DVDD pin for the device to operate. For the device to respond to I²C commands, the 1.8 V supply must be stable.

ADDR PIN SETUP AND CONTROL

The ADDR pin sets the device I²C address. See Table 11 for details.

CLOCKING

In 3-wire mode (BCLK, FSYNC, SDATA), a BCLK signal must be provided to the [SSM3515](#) for correct operation. The BCLK

signal must have a minimum frequency of 2.048 MHz. The BCLK signal is used for internal clocking of the device. The BCLK rate is detected automatically, but the sampling frequency must be known to the device. The supported BCLK rates at 32 kHz to 48 kHz are 50, 64, 100, 128, 192, 200, 256, 384, 400, and 512 times the sample rate.

Table 11. Pin Setup List

ADDR Pin	SCL Pin	SDA Pin	Control Mode	7-Bit I ² C Address	TDM Slot
Connected to Ground Using a 47 k Ω Resistor	SCL	SDA	I ² C	0x14	1
Open (No Connection)	SCL	SDA	I ² C	0x15	2
Connected to 1.8 V Using a 47 k Ω Resistor	SCL	SDA	I ² C	0x16	3
Connected to 1.8 V	SCL	SDA	I ² C	0x17	4

DIGITAL AUDIO SERIAL INTERFACE

The **SSM3515** includes a standard serial audio interface that is slave only. The interface is capable of receiving I²S, left justified, PCM, or TDM formatted data.

The serial interface has three main operating modes, listed in Table 12.

Table 12. Operating Modes

Mode	Format	Comments
2-Channel (Stereo)	I ² S/left justified	Register control using I ² C port
Multichannel TDM	I ² S/left justified	Register control using I ² C port

Stereo modes, typically I²S or left justified, are used when there is one or two devices on the interface bus. Standard multichannel TDM modes are more flexible and offer the ability to have multiple devices on the bus. In both of these cases, the register control uses an I²C port.

STEREO (I²S/LEFT JUSTIFIED) OPERATING MODE

Stereo modes use both edges of FSYNC to determine placement of data. Stereo mode is enabled when SAI_MODE = 0 and the data format is determined by the SDATA_FMT register setting.

The I²S or left justified interface formats accept any number of BCLK cycles per FSYNC cycle. Sample rates from 8 kHz to 192 kHz are accepted. The maximum BCLK rate is 24.576 MHz.

TDM OPERATING MODE

The TDM operating mode allows multiple chips to use a single serial interface bus for audio data.

The FSYNC signal operates at the desired sample rate. A rising edge of the FSYNC signal indicates the start of a new frame. For proper operation, this signal must be one BCLK cycle wide, transitioning on a falling BCLK edge. The MSB of data must be present on the SDATA one BCLK cycle later. The SDATA signal latches on the rising edge of BCLK.

Each chip on the TDM bus can occupy 16, 24, 32, 48, or 64 BCLK cycles. This is set with the TDM_BCLKS bits and all devices on the bus must have the same setting. Up to 16 **SSM3515** devices can be used on a single TDM bus, but only 4 unique I²C device addresses are available. The **SSM3515** automatically determines how many possible devices can be placed on the bus from the BCLK rate. There is no limit to the total number of BCLK cycles per FSYNC pulse.

Which chip slot each **SSM3515** uses is determined by the ADDR pin settings (see Table 11 for details), or by the TDM_SLOT bits in Register 0x05.

The input data width to the DAC can be either 16-bit or 24-bit.

I²C CONTROL

The **SSM3515** supports a 2-wire serial (I²C-compatible) microprocessor bus driving multiple peripherals. Two pins, serial data (SDA) and serial clock (SCL), carry information between the **SSM3515** and the system I²C master controller. The **SSM3515** is always a slave on the bus, meaning it cannot initiate a data transfer. Each slave device is recognized by a unique address. Using the ADDR pin provides the four device addresses, which are listed in Table 11. The address byte format is shown in Table 13. The address resides in the first seven bits of the I²C write. The LSB of this byte sets either a read or write operation. Logic Level 1 corresponds to a read operation, and Logic Level 0 corresponds to a write operation.

Connect 2.2 k Ω pull-up resistors on the lines connected to the SDA and SCL pins. The voltage on these signal lines must not be more than 5 V.

Addressing

Initially, each device on the I²C bus is in an idle state, monitoring the SDA and SCL lines for a start condition and the proper address. The I²C master initiates a data transfer by establishing a start condition, defined by a high to low transition on SDA while SCL remains high. This indicates that an address or data stream follows. All devices on the bus respond to the start condition and shift the next eight bits (the 7-bit address plus the R/W bit) MSB first. The device that recognizes the transmitted address responds by pulling the data line low during the ninth clock pulse. This ninth bit is an acknowledge bit. All other devices withdraw from the bus at this point and return to the idle condition. The device address for the **SSM3515** is determined by the state of the ADDR pin. See Table 11 for four available addresses.

The R/W bit determines the direction of the data. A Logic 0 on the LSB of the first byte means the master writes information to the peripheral, whereas a Logic 1 means the master reads information from the peripheral after writing the subaddress and repeating the start address. A data transfer occurs until a stop condition is encountered. A stop condition occurs when SDA transitions from low to high while SCL is held high. The timing for the I²C port is shown in Figure 61.

Stop and start conditions can be detected at any stage during the data transfer. If these conditions are asserted out of sequence with normal read and write operations, the **SSM3515** immediately jumps to the idle condition. During a given SCL high period, the user must issue only one start condition, one stop condition, or a single stop condition followed by a single start condition. If the user issues an invalid subaddress, the **SSM3515** does not issue an acknowledge and returns to the idle condition. If the user exceeds the highest subaddress while in auto-increment mode, one of two actions is taken.

In read mode, the SSM3515 outputs the highest subaddress register contents until the master device issues a no acknowledge, indicating the end of a read. A no acknowledge condition is when the SDA line is not pulled low on the ninth clock pulse on SCL. If the highest subaddress location is reached while in write mode, the data for the invalid byte is not loaded into any subaddress register, a no acknowledge is issued by the SSM3515, and the device returns to the idle condition.

I²C Read and Write Operations

Figure 62 shows the timing of a single-word write operation. Every ninth clock, the SSM3515 issues an acknowledge (ACK) by pulling SDA low.

Figure 63 shows the timing of a burst mode write sequence. This figure shows an example in which the target destination registers are two bytes. The SSM3515 increments its subaddress register

every byte because the requested subaddress corresponds to a register or memory area with a byte word length.

The timing of a single word read operation is shown in Figure 64. Note that the first R/W bit is 0, indicating a write operation.

This is because the subaddress still must be written to set up the internal address. After the SSM3515 acknowledges the receipt of the subaddress, the master must issue a repeated start command followed by the chip address byte with the R/W set to 1 (read). This causes the SSM3515 SDA to reverse and begin driving data back to the master. The master then responds every ninth pulse with an acknowledge pulse to the SSM3515. See Table 15 for a list of abbreviations in Figure 62 through Figure 65.

Table 13. I²C Device Address Byte Format Using the ADDR Pin¹

Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
0	0	1	0	1	X	X	R/W

¹ X means don't care.

Table 14. ADDR Pin to I²C Device Address Mapping

ADDR Pin	ADDR Voltage	I ² C Address Bit 5	I ² C Address Bit 6
GND	GND	Not applicable	Not applicable
Pull-Down 47 kΩ Resistor	$0.25 \times V_{REG18}/DVDD$	0	0
Open	$0.5 \times V_{REG18}/DVDD$	0	1
Pull-Up 47 kΩ Resistor	$0.75 \times V_{REG18}/DVDD$	1	0
DVDD	DVDD	1	1

Table 15. Abbreviations for Figure 62 Through Figure 65

Symbol	Meaning
S	Start bit
P	Stop bit
A _M	Acknowledge by master
A _S	Acknowledge by slave

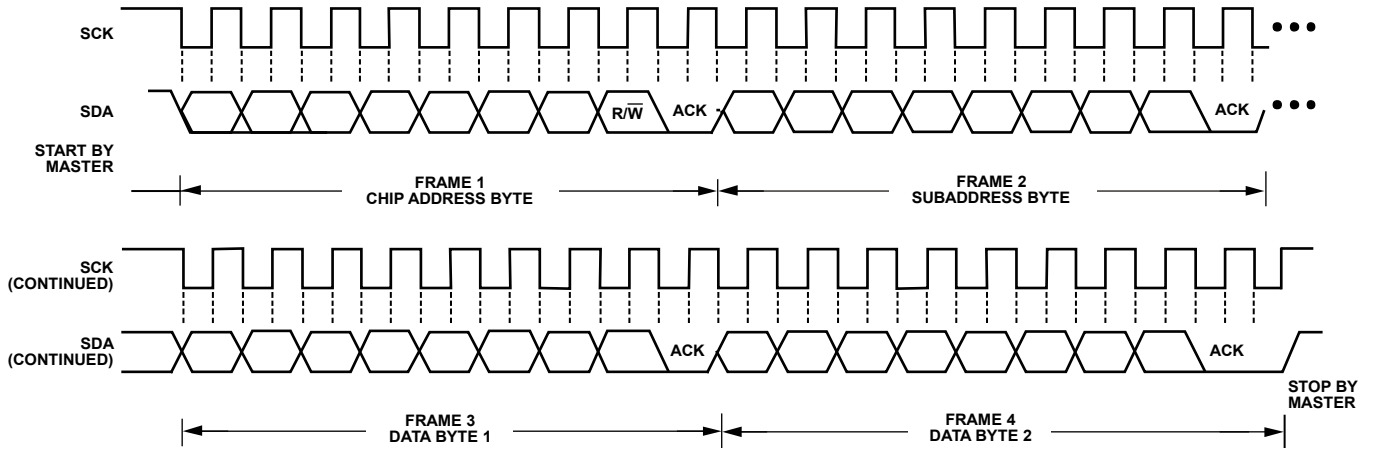


Figure 61. I²C Read/Write Timing

13327-066

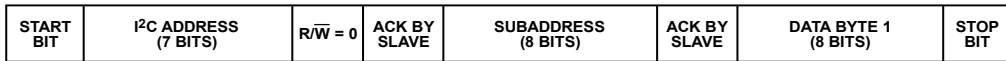


Figure 62. Single Word I²C Write Format

13327-067

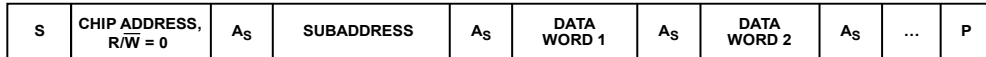


Figure 63. Burst Mode I²C Write Format

13327-068



Figure 64. Single Word I²C Read Format

13327-069

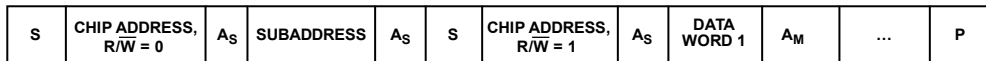


Figure 65. Burst Mode I²C Read Format

13327-070

ANALOG AND DIGITAL GAIN

Several selectable settings are available for the analog gain of the system. These provide optimal gain settings at various PVDD supply voltages. The ANA_GAIN bits are available in Register 0x01, Bits[1:0].

The available options are as shown in Table 16.

Table 16. Analog Gain Options

PV _{DD}	ANA_GAIN	Amplifier Analog Gain Selection
5 V to 9 V	00	8.4 V full-scale gain mapping
9 V to 13 V	01	12.6 V full-scale gain mapping
13 V to 14 V	10	14 V full-scale gain mapping
14 V to 16 V	11	15 V full-scale gain mapping

There is also a digital gain or volume control that provides fine control in 0.375 dB steps from -70 dB to +24 dB.

POP AND CLICK SUPPRESSION

Voltage transients at the output of audio amplifiers may occur when shutdown is activated or deactivated. Voltage transients as small as 10 mV can be heard as an audible pop in the speaker. Clicks and pops are defined as undesirable audible transients generated by the amplifier system that do not come from the system input signal.

Such transients may be generated when the amplifier system changes its operating mode. For example, system power-up and power-down can be sources of audible transients.

The SSM3515 has a pop and click suppression architecture that reduces these output transients, resulting in noiseless activation and deactivation.

Either mute or power-down must be set before the BCLK is removed to ensure a pop free power-down.

EMI NOISE

The SSM3515 uses a proprietary modulation and spread spectrum technology to minimize EMI emissions from the device. The SSM3515 can pass FCC Class B emissions testing with an unshielded 20-inch cable using ferrite bead-based filtering. For applications that have difficulty passing FCC Class B emission tests, the SSM3515 includes a modulation select pin (ultralow EMI emission mode) that significantly reduces the radiated emissions at the Class-D outputs, particularly above 100 MHz. Note that reducing the supply voltage greatly reduces radiated emissions.

OUTPUT MODULATION DESCRIPTION

The SSM3515 uses three-level, Σ - Δ output modulation. Each output can swing from GND to PV_{DD} and vice versa. Ideally, when no input signal is present, the output differential voltage is 0 V because there is no need to generate a pulse. In a real-world situation, there are always noise sources present.

Due to this constant presence of noise, a differential pulse is occasionally generated in response to this stimulus. A small amount of current flows into the inductive load when the differential pulse is generated. However, most of the time, the output differential voltage is 0 V. This feature ensures that the current flowing through the inductive load is small.

When the user sends an input signal, an output pulse is generated to follow the input voltage. The differential pulse density is increased by raising the input signal level. Figure 66 depicts three-level, Σ - Δ output modulation with and without input stimulus.

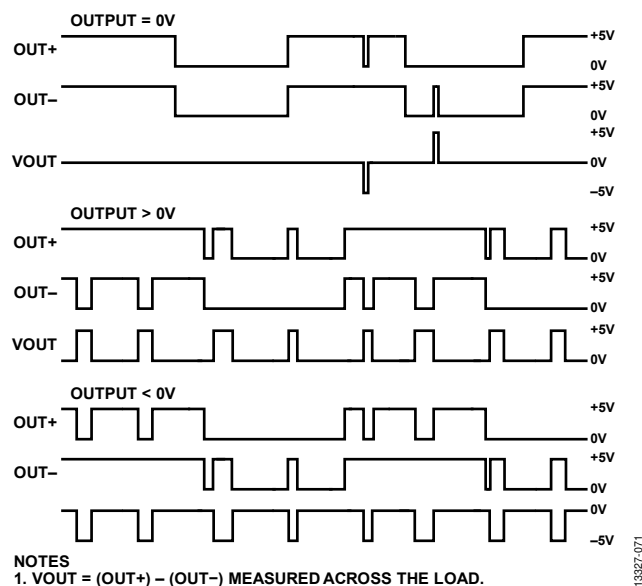


Figure 66. Three-Level, Σ - Δ Output Modulation With and Without Input Stimulus