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EVAL-M3-CM615PN User Manual

iMOTION™ Modular Application Design Kit

About this document

Scope and purpose

This user manual provides an overview of the evaluation board Eval-M3-CM615PN including its main features, key data, pin assignments and mechanical dimensions.

Eval-M3-CM615PN is an evaluation board as part of the iMOTION™ Modular Application Design Kit. This power board includes a PFC integrated 3-phase CIPOS™ Mini Intelligent Power Module (IPM) for motor drive application. In combination with the control board equipped with the M3 30pin interface connector such as EVAL-M3-102T, it features and demonstrates Infineon's CIPOS™ Mini IPM technology and Advanced Motion Control Engine (MCE 2.0) technology for permanent magnet motors drive over the full speed range.

The inverter section has 600V of voltage and 15A of current rating, and the PFC section has 650V of voltage and 30A of current rating. It is optimized to major home appliances like air conditioners and low power motor dirve application with high frequency switching operation of power factor correction.

This evaluation board Eval-M3-CM615PN was developed to support customers during their first steps designing applications with CIPOS™ Mini PFC integrated IPM IFCM15P60GD and running any permanent magnet motor via sensorless sinusoidal control.

Intended audience

This user manual is intended for all technical specialists who know motor control and high power electronics converter and this board is intended to be used under laboratory conditions.

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1 Safety precautions

In addition to the precautions listed throughout this manual, please read and understand the following statements regarding hazards associated with development systems.

Table 1   Precautions

⚠	*Attention: The ground potential of the EVAL-M3-CM615PN system is biased to a negative DC bus voltage potential. When measuring voltage waveform by oscilloscope, the scope's ground needs to be isolated. Failure to do so may result in personal injury or death and equipment damage.*
⚠	*Attention: Only personnel familiar with the drive and associated machinery should plan or implement the installation, start-up and subsequent maintenance of the system. Failure to comply may result in personal injury and/or equipment damage.*
⚠	*Attention: The surfaces of the drive may become hot, which may cause injury.*
⚠	*Attention: EVAL-M3-CM615PN system contains parts and assemblies sensitive to Electrostatic Discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing this assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to applicable ESD protection handbooks and guidelines.*
⚠	*Attention: A drive, incorrectly applied or installed, can result in component damage or reduction in product lifetime. Wiring or application errors such as under sizing the motor, supplying an incorrect or inadequate DC supply or excessive ambient temperatures may result in system malfunction.*
⚠	*Attention: Remove or connect the control board from or to the power drive. Wait three minutes after removing power from the power drive to discharge the bus capacitors. Do not attempt to service the drive until the bus capacitors have discharged to zero. Failure to do so may result in personal injury or death.*
⚠	*Attention: EVAL-M3-CM615PN system is shipped with packing materials that need to be removed prior to installation. Failure to remove all packing materials which are unnecessary for system installation may result in overheating or abnormal operating condition.*

2   Introduction

The Eval-M3-CM615PN evaluation power board is a part of the iMOTION™ Modular Application Design Kit for motor drives (iMOTION™ MADK). In order to run a motor, the matching control board is required to interface this power board.

The MADK platform is intended to use various power stages with different control boards. These boards can easily be interfaced through the 30-pin iMOTION™ MADK M3 such as Eval-M3-102T, or the 20-pin iMOTION™ MADK M1 interface connector to control board. This board is equipped with 30-pin M3 connector and is intended for single motor control only.

This evaluation board is designed to give Easy-to-use power stage based on the Infineon's CIPOS™ Mini Inteligent Power Module (IPM). The board is equipped with all assembly groups for sensorless field oriented control (FOC). It provides a single-phase AC-connector, rectifier, a PFC inductor connector, Boost PFC and 3-phase output for connecting the motor. The power stage also contains emitter shunts for current sensing and a voltage divider for DC-link voltage measurement.

The Eval-M3-CM615PN evaluation board is available through regular Infineon distribution partners as well as on Infineon's website. The features of this board are described in the main features chapter of this document, whereas the remaining paragraphs provide information to enable the customers to copy, modify and qualify the design for production according to their own specific requirements.

Environmental conditions were considered in the design of the Eval-M3-CM615PN, but it is not qualified regarding safety requirements or manufacturing and operation over the whole operating temperature range or lifetime. The boards provided by Infineon are subject to functional testing only.

The block diagram of the Eval-M3-CM615PN is depicted in Figure 1. This evaluation board includes an EMI filter and soft power up circuit, 30 pins iMOTION™ MADK-M3 interface connector, auxiliary power supply to provide 15V and 3.3V, PFC gate dirve circuit and the CIPOS™ Mini IPM IFCM15P60GD.
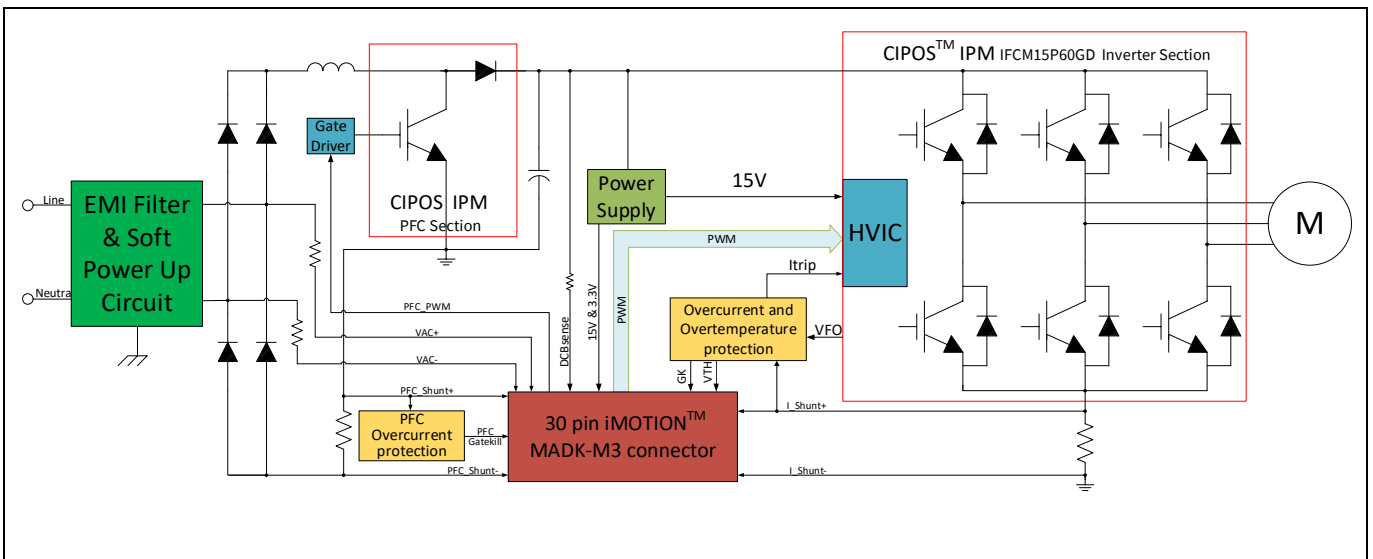
Figure 1   The Block Diagram of the Eval-M3-CM615PN

The hardware circuit regarding overtemperature and overcurrent protection is also included in this power board. The sense connection to common emitter shunt resistor is connected to the 30 pins iMOTION™ MADK-M3 interface connector. This power board is compatible with PFC integrated CIPOS™ Mini IPMs that feature 3 phase common emitter and built-in NTC considering motor power rating and IPM's current rating.

Evaluation boards are not subject to the same procedures as regular products regarding Returned Material Analysis (RMA), Process Change Notification (PCN) and Product Discontinuation (PD). Evaluation boards are intended to be used under laboratory conditions by technical specialists only.

3 EVAL-M3-CM615PN main features

Eval-M3-CM615PN is an evaluation board for motor drive applications with single phase PFC integrated 3 phase IPM. Combined in a kit with one of the available MADK control board options, it demonstrates Infineon's motion control IC and IPM technology for motor drives with single phase PFC.

Main features of CIPOS™ Mini IPM IFCM15P60GD are:

- 3 half bridges with TRENCHSTOP™ IGBT3 15A/600V and antiparallel diodes for inverter section
- 30A/650V TRENCHSTOP™ 5 IGBT and rapid switching emitter controlled diode for PFC section
- Lead-free terminal plating; RoHS compliant
- Very low thermal resistance due to DCB
- Rugged SOI gate driver technology with stability against transient and negative voltage
- Negative potential allowed up to VS =-11V for single transmission at VBS=15V
- Integrated bootstrap functionality
- Overcurrent shutdown
- Temperature monitor
- Undervoltage lockout at all channels
- Low side common emitter
- Cross conduction prevention
- All six switches turn off during protection

The evaluation board characteristics are:

- Input voltage 160~265VAC
- Maximum 650W motor power output
- Power Factor Correction
- On board EMI filter
- Current sensing with single shunt
- Auxiliary power supply with 15V, 3.3V
- Overcurrent protection
- Overtemperature hardware protection
- Sensing of DC-link voltage
- Thermistor output
- Fault diagnostic output
- Measurement test-points compatible to standard oscilloscope probes
- PCB is 120 mm × 120 mm and has two layers with 35μm copper each
- RoHS complaint

3.1 EVAL-M3- CM615PN board specifications

Table 2 depicts the important specifications of the evaluation board Eval-M3-CM615PN.

Table 2   Eval-M3-CM615PN board specifications

Parameters	Values	Conditions / comments
Input		
Voltage	165 - 265 V_{rms}	lower AC input, less motor power output
Input current	3.15 A_{rms}	input 220 V_{AC}, T_a=25°C, IFCM15P60GD
Output		
Power (3phases)	650 W	input 220V_{AC}, f_{PWM}=6 kHz, T_a=25°C, T_h=80°C
Current per leg	2.32 A_{rms}	input 220V_{AC}, f_{PWM}=6 kHz, T_a=25°C, T_h=80°C
DC Bus Voltage		
Maximum DC bus voltage	420 V	
Minimum DC bus voltage	120 V	
Switching Frequency		
PFC switching frequency f_{PFC}	60 kHz (max)	Limited by controller board (maximum 50 kHz for Eval-M3-102T)
Inverter switching frequency f_{PWM}	20 kHz (max)	
Current feedback		
PFC current sensing resistor R1	30 mΩ	
Inverter current sensing resistor RS2	30 mΩ	R2 is the IPM inverter section's common emitter current sensing resistor.
Protections		
PFC Gatekill protection level	15.5 A_{peak}	Configured by either PFC current sensing resistor RS1, or adapting comparator threshold divider resistor R17.
Output current trip level	[1]15.7 A_{peak}	Configured by changing shunt resistor RS2. ITRIP positive going threshold is about 470mV.
Temperature trip level	100 °C	For controller board Eval-M3-188
On board power supply		
15 V	15 V ± 5 %, max. 50 mA	Used for CIPOS™ IPM gate driver and LDO
3.3 V	3.3 V ± 2 %, max. 20 mA	Supplying the 3.3V to the controller board and protection circuits
PCB characteristics		
Material	FR4, 1.6mm thickness, 2 layers. 35 μm copper thickness	
Dimension	120 mm x 120 mm	
System environment		
Ambient temperature	From 0 to 50°C	Non-condensing, maximum RH of 95 %

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[1]   For iMOTION™ IC IMC1xx, there are three types of Gatekill Input Source (Refer to section 5.2.3 or control board user manual for detail). Please note that, if select comparator for Gatekill Input Source, the external Gatekill signal will be not used. And the signal I_Shunt will be compared by the internal comparator with the "Gatekill Comparator Reference" value set in MCEWizard only.

Figure 2 points out the functional groups on the top side of the Eval-M3-CM615PN evaluation board.
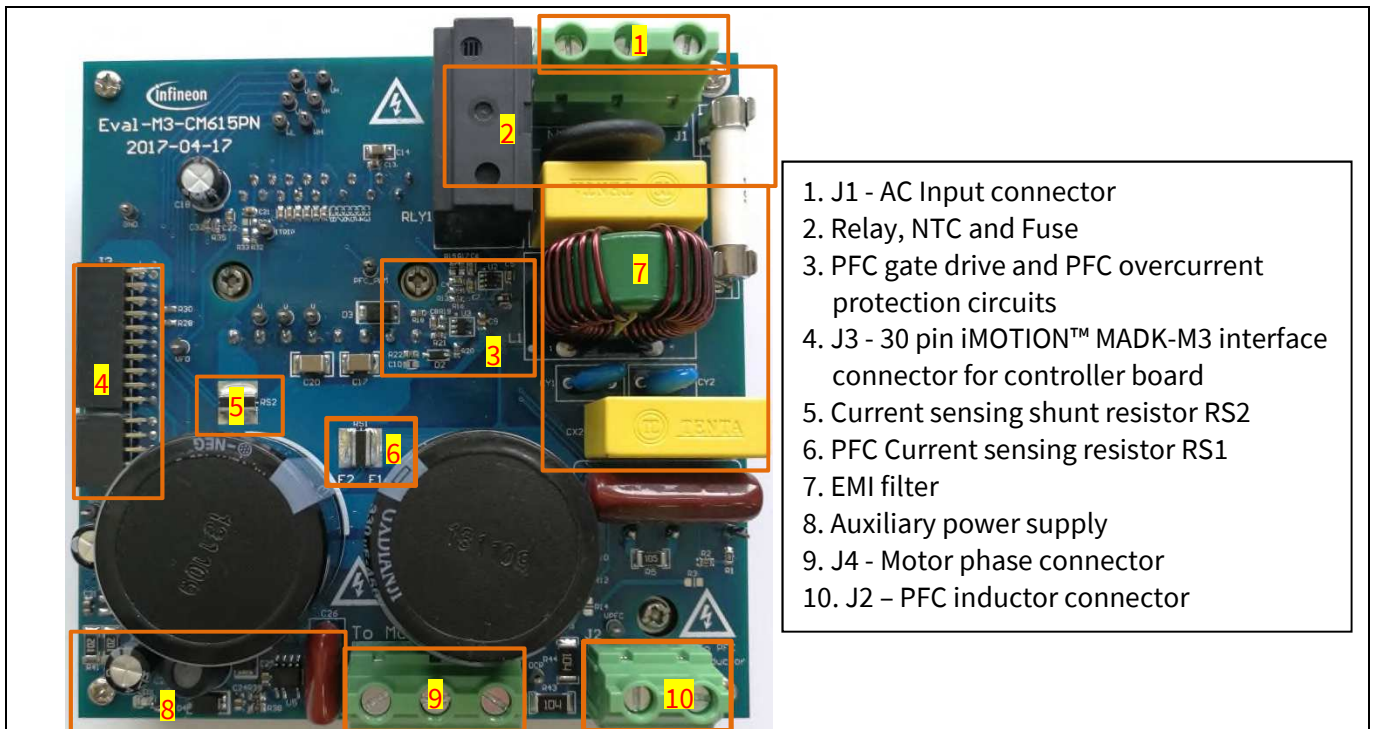
1. J1 - AC Input connector
2. Relay, NTC and Fuse
3. PFC gate drive and PFC overcurrent protection circuits
4. J3 - 30 pin iMOTION™ MADK-M3 interface connector for controller board
5. Current sensing shunt resistor RS2
6. PFC Current sensing resistor RS1
7. EMI filter
8. Auxiliary power supply
9. J4 - Motor phase connector
10. J2 – PFC inductor connector

Figure 2   Functional groups of the Eval-M3-CM615PN evaluation board's top side

Figure 3 points out the functional groups on the bottom side of the Eval-M3-CM615PN evaluation board.
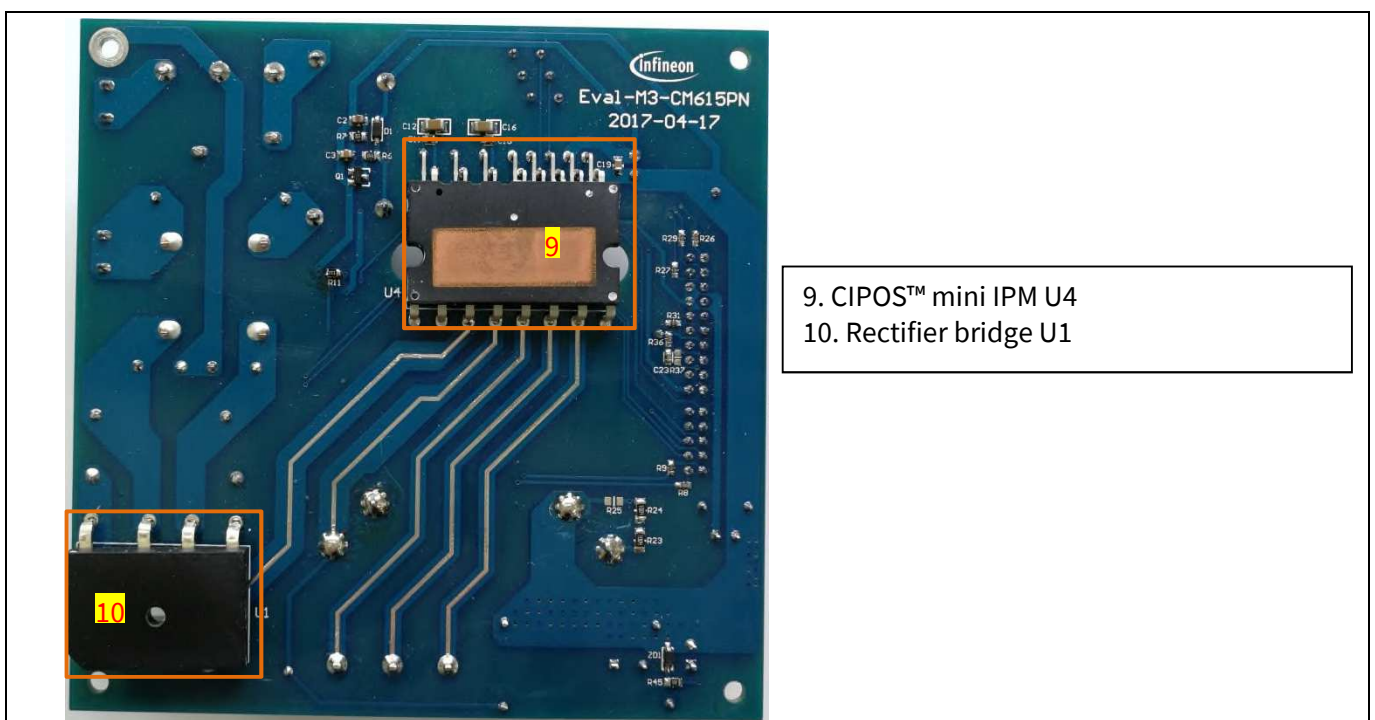
9. CIPOS™ mini IPM U4
10. Rectifier bridge U1

Figure 3   Functional groups of the Eval-M3-CM615PN evaluation board's bottom side

3.2 Pin assignment

General information about the connectors of the Eval-M3-CM615PN evaluation board is reported. Table 3 includes the details of the AC input connector J1.

Table 3   J1- AC Line connector

S. No.	Pin	Details
1	**N**eutral	AC neutral input
2	**E**arth	Earth ground
3	**L**ine	AC line input

Table 4 denotes the details of the PFC inductor connector J2.

Table 4   J2- DC link connector

S. No.	Pin	Details
1	L+	Connected to one side of PFC inductor
2	L-	Connected to the other side of PFC inductor

Table 5 provides the details of the motor side connector J4.

Table 5   J4- Motor side connector

S. No.	Pin	Details
1	U	Connected to motor phase U
2	V	Connected to motor phase V
3	W	Connected to motor phase W

Table 6 provides the pin assignments of the 30 pins iMOTION™ MADK-M3 interface connector J3. This connector is the interface to the controller board.

Table 6   J3 - iMOTION™ MADK-M3 30 pin interface connector for controller board

Pin	Name	Pin Name Connectors
1	PWMUH	3.3 V compatible logic input for high side gate driver-Phase U
2	GND	Ground
3	PWMUL	3.3 V compatible logic input for low side gate driver-Phase U
4	GND	4 GND Ground
5	PWMVH	3.3 V compatible logic input for high side gate driver-Phase V
6	+3.3V	On board 3.3 V supply
7	PWMVL	3.3 V compatible logic input for low side gate driver-Phase V
8	+3.3V	On board 3.3 V supply
9	PWMWH	3.3 V compatible logic input for high side gate driver-Phase W
10	I_U	Positive Current sense output

Pin	Name	Pin Name Connectors
11	PWMWL	3.3 V compatible logic input for low side gate driver-Phase W
12	I_U-	Negative current sense output or Ground
13	GK	Gate kill signal – active low when overcurrent is detected
14	DCBSense	DC bus positive voltage, scaled in 0-3.3 V range by a voltage divider
15	VTH	Thermistor Output
16	I_V	Not used
17	I_V-	Not used
18	I_W	Not used
19	I_W-	Not used
20	VCC	15 V Power Supply
21	PFCG0	3.3 V compatible logic input for PFC gate driver IC
22	GND	Ground
23	PFCG1	Not used
24	+3.3V	On board 3.3 V supply
25	PFCGK	PFC Gate kill signal – active low when PFC overcurrent is detected
26	DCBSense	DC bus positive voltage, scaled in 0-3.3 V range by a voltage divider
27	VAC+	AC voltage sensing positive cycle
28	VAC-	AC voltage sensing negative cycle
29	IPFC+	PFC current sensing positive
30	IPFC-	PFC current sensing negative

4 Getting Started with EVAL-M3-CM615PN

In order to run the motor system, a combination of the iMOTION™ MADK power board (EVAL-M3-CM615PN) and the matching MADK control board is required. The iMOTION™ Software Tools MCEDesigner and MCEWizard are also required in order to initialy setup the system, as well as to control and fine-tune the system performance to match users exact needs. This chapter provides more details on setting up the system and getting started with iMOTION™ MADK development platform.

4.1 Setting up the system

After downloading and installing the iMOTION™ PC Tools (MCEWizard and MCEDesigner), following steps needs to be executed in order to run the motor. Refer to user manul for iMOTION™ MADK control board such as (EVAL-M3-102T), MCEWizard and MCEDesigner documentation for more information.

Figure 4 shows the system connection using EVAL-M3-CM615PN and control board (used control board EVAL-M3-102T for example).
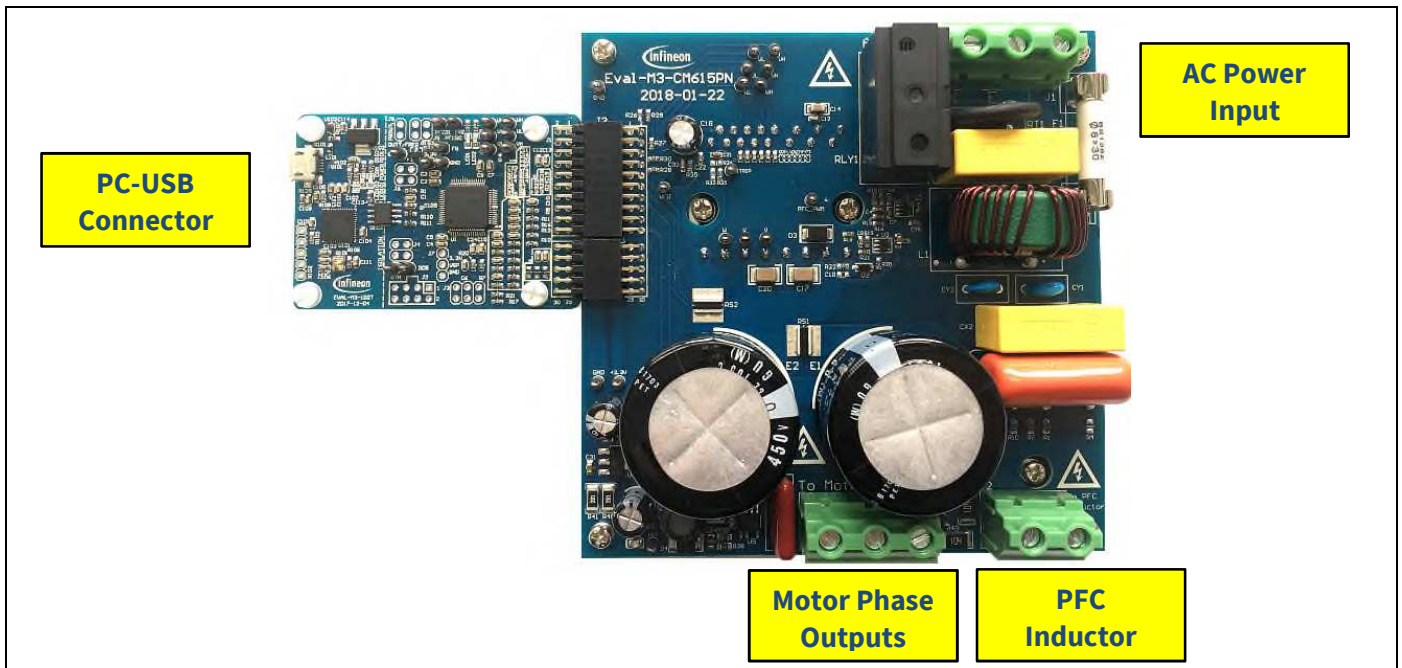

Figure 4   **System connection example using EVAL-M3-CM615PN and EVAL-M3-102T**

1. Connect PC-USB connector on the on-board-debugger to the PC via USB cable.
2. Connect EVAL-M3-CM615PN's MADK M3 30-pin interface connector (J3) to control board (see Figure 4).
3. Get the latest "IMC102T-F064 MCE Software Package" available on www.infineon.com/imotion-software web page. (Infineon iMOTION™ control IC IMC102T-F064 is used for control board EVAL-M3-102T).
4. Connect motor phase outputs to the motor.
5. Use MCEWizard to enter the motor and evaluation board hardware parameters and click button "Export to Designer file (.txt)" to system drive parameters file which will be used by MCEDesigner.
6. Connect AC power to power input connector and power on system.
7. Open MCEDesigner and open MCEDesigner default configuration file (.irc) for IMC102T devices (IMC102T_xx.irc) by clicking "File" menu and select "Open" in the pull down list.
8. Import system drive parameters file (generated in step 5) into MCEDesigner by clicking "File" > "Import Drive Parameters". Select "Update All" radio button.

9. Program the MCE Firmware and system parameters into the internal Flash memory of iMOTION™ IC by clicking "Tools > Programmer "in the pull down menu, and then clicking on the "Program Firmware and Parameter" radio button. See chapter MCEDesigner setup overview setion 4.2.2 for more details. If the latest version of MCE firmware is already programmed into the IMC102T-F064 IC, then programming firmware can be skipped by selecting "Program Parameters" radio button option. Finally click "Start" button to program firware and parameter (or parameters only when programming firmware was skipped).

10. Start the motor by clicking the green traffic light button in the control bar.

4.2 iMOTION™ development tools and software

The iMOTION™Development Tool installers for MCEDesigner and MCEWizard are available for download via Infineon iMOTION™website (http://www.infineon.com/imotion-software). All the available tools and software variants are listed there.

On-board debugger uses the SEGGER J-Link's driver for UART communication with IMC102T-F064. J-Link driver will be installed during the MCEDesigner installation. In case the driver is not installed properly, please go to SEGGER J-Link website to download and install the latest J-Link "Software and Documentation pack for Windows".

4.2.1 MCEWizard setup overview

After installing the MCEWizard, the shortcut for MCEWizard appears on the Windows desktop. Double click the shortcut to open the MCEWizard and configure the parameters for evaluation boards or motor. Figure 6 shows the "Welcome Page" for MCEWizard, where the MADK control board or power board can be selected through the pull-down list. Infineon keeps releasing new MADK controller and power boards. Therefore, it could happen that some of the newest power boards are not pre-configured in the MCEWizard tool and cannot be selected through the pull-down menu. In that case, the user should select any other power board (as similar as possible) and follow the MCEWizard setup steps by entering the parameter values which are specific to the chosen board. Make sure both "I have modified the circuit board" and "Enable advanced question" checkmarks are selected. Please refer to the User Manual of the corresponding power board for additional information.

After selecting the MADK control and the power board, start the MCEWizard system setup procedure by clicking the "Next" button in the right bottom corner as shown in Figure 6.
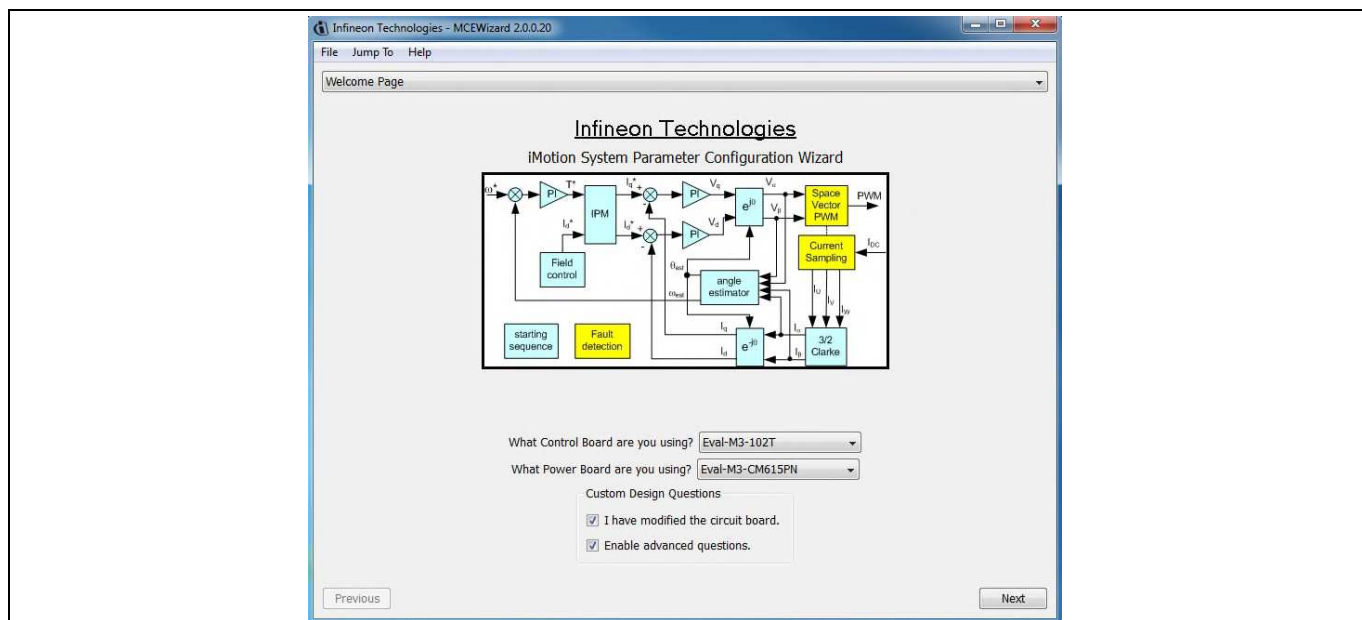

Figure 5   Welcome Page of MCEWizard

iMOTION™ MADK system enables users to easily test different combination of control and power board with their motors. User should be familiar with the system level parameters which are related to the motor used. There are very limited numbers of parameters which are specific to the control board or power board hardware. Table 7 provides the MCEWizard setup overview for hardware related parameters. Similar tables will be available in each power board's User Manual. Combination of this table and the corresponding table of the power board provides enough information to setup the MADK-based motor drive system in shortest time.

Table 7   MCEWizard setup overview table

Page	Parameter	Value	Comment
Welcome Page	Power Board selecting	MADK power board name	If no, select similar power board to modify
Options Page	Motor 1 Shunt Configuration	30mΩ	
Question 3	Controller Supply Voltage	Refer to control board user manual	
Question 19	Max DC Bus Voltage	420V	
Question 23	DC Bus Sensing High Resistor	2MΩ	
Question 24	DC Bus Sensing Low Resistor	Refer to control board user manual	13.3kΩ by default
Question 54	NTC Temperature Shutdown value	Calculated as the Section 5.3.3	Refer to the control board user manual
Question 63	GateSense Low-Side Devices	High is true	
Question 64	GateSense High-Side Devices	High is true	
Question 69	Motor 1 Current Input	Calculated as the Section 5.2.2	
Question 83	PFC Topology	Boost PFC	
Question 85	PFC Current Input	Calculated as the Section 5.1.2	
Question 90	AC Voltage Sensing High Resistor	2000kΩ	
Question 91	AC Voltage Sensing low Resistor	Refer to control board user manual	15kΩ by default for EVAL-M3-102T
Question 92	PFC Gate Driver Polarity High Side	High is active	no high side, just compatibility
Question 93	PFC Gate Driver Polarity Low Side	High is active	

After all the MCEWizard questions are answered, the "Verify & Save Page" will be shown as in Figure 6
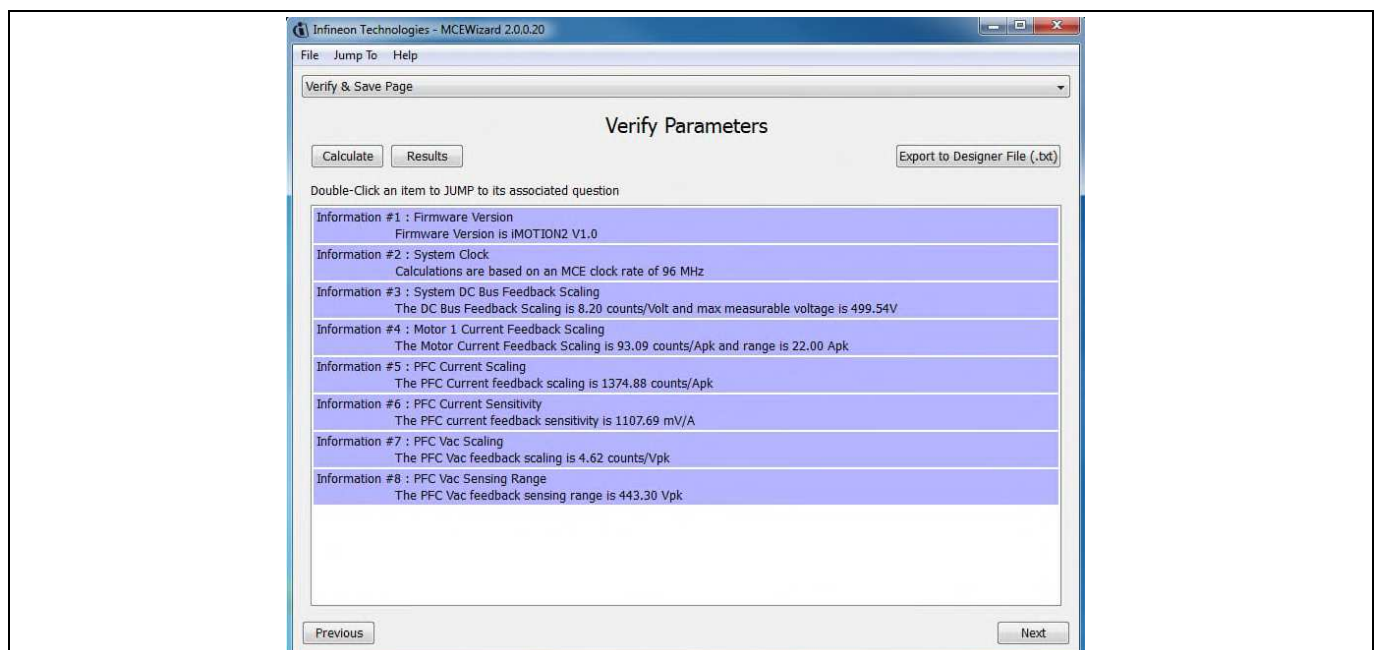

Figure 6   Verify and Save page for MCEWizard

Click "Calculate" button and "Export to Designer File (.txt)" button to save the parameter file which will be used by the MCEDesigner in the next steps.

4.2.2 MCEDesigner setup overview

After installing MCEDesigner installer, there is a shortcut for MCEDesigner on Windows desktop. Double click the shortcut to open MCEDesigner and then open "IMC102T_xx.irc" file as shown in Table 7.
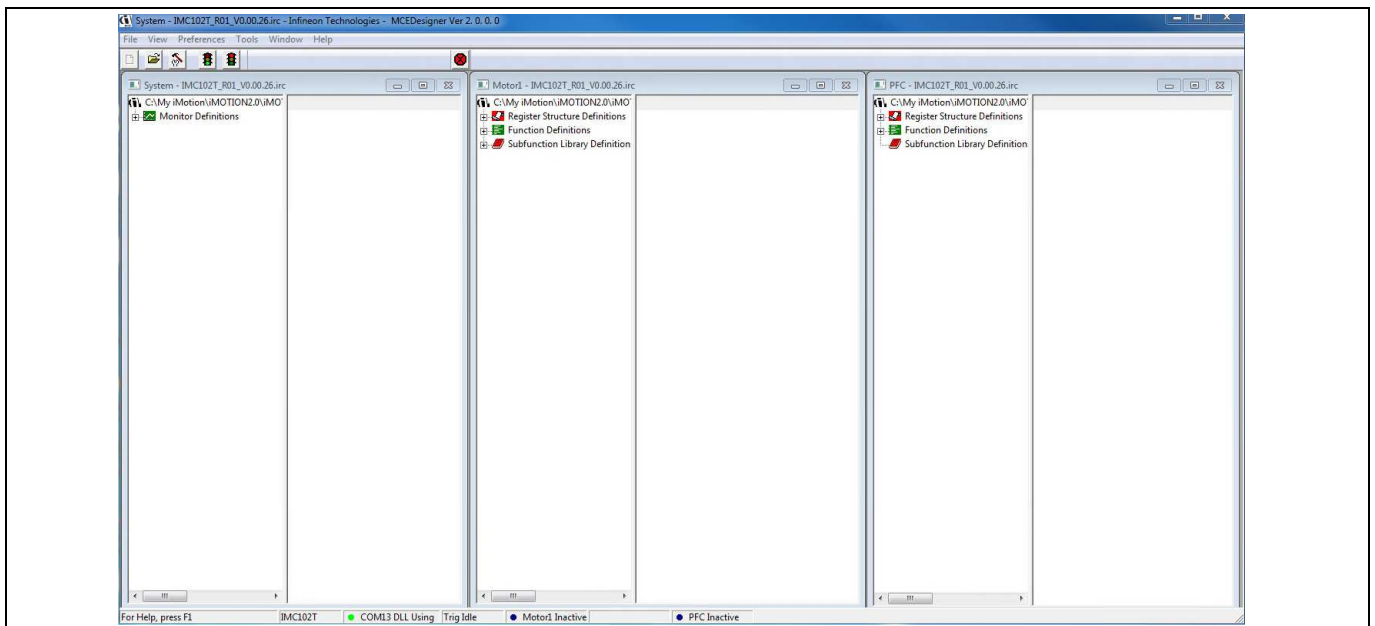

Figure 7   MCEDesigner's Main Display for EVAL-M3-102T

To program system drive parameters into IMC102T-F064, please click "Tools" menu and select "Programmer" in the pull down list. The pop-up window "Program IMC controller" will show up as in Figure 8. Click on the "Program Parameters" radio button (this is the default option), and then select the Drive System Parameter file created using MCEWizard by clicking on "Browse". Finally, click on the "Start" button to program the parameter file into the IMC102T-F064 IC.
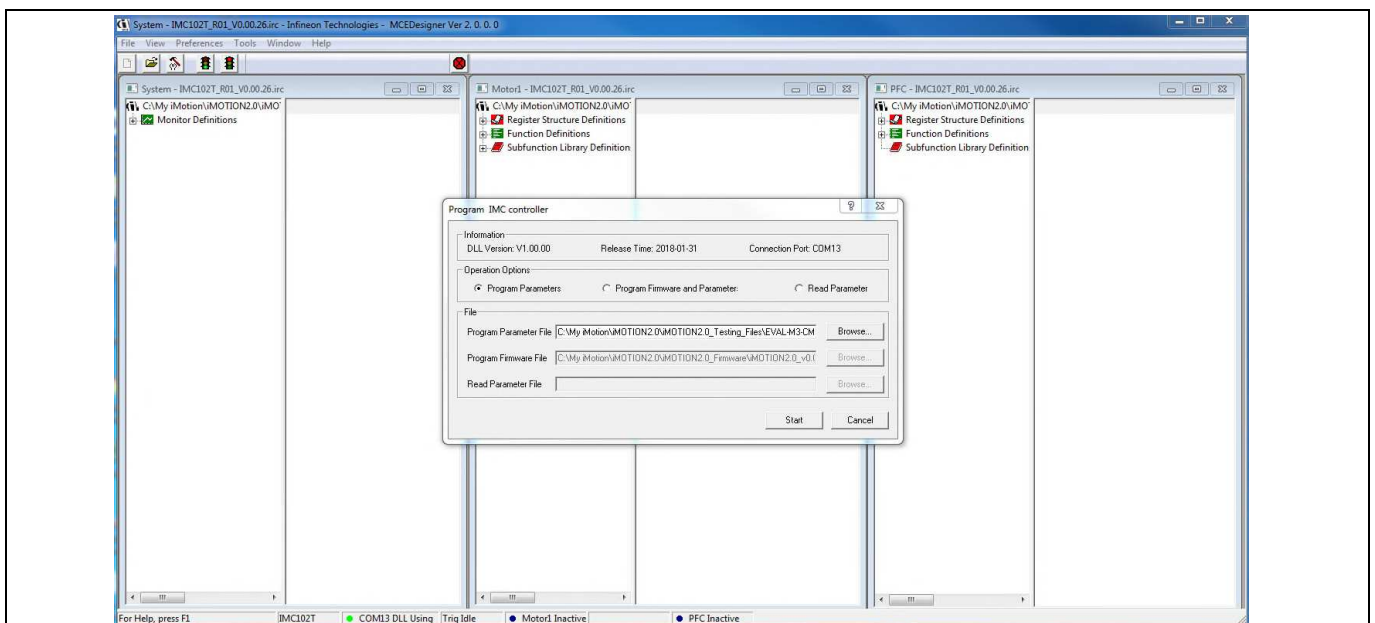

Figure 8   "Program IMC Controller" pop-up window

After Drive System Parameter file has been programmed into IMC102 controller, and the motor drive system is powered, the MCEDesigner can be used to start/stop the motor, display motor current traces, change the motor speeds, modify drive parameters and many other functions. Please refer to the MCEDesigner documentation for more details.

Note: *On-board Debugger portion of EVAL-M3-102T is galvanically isolated from the controller portion and the attached power board. In order to program the parameters or firmware to the IMC102T-F064 controller, the 3.3V DC voltage needs to be supplied to the controller portion of the EVAL-M3-102T. This voltage can either be supplied by the power board (MADK power boards are designed to supply the 3.3V to the control board through M3 connector) or by feeding the 3.3V DC voltage to the control board through some of the available 3.3V access/test points if the power board is not attached to the EVAL-M3-102T control board.*

To program new firmware and Drive System Parameter into IMC102T-F064, please click "Tools" menu and select "Programmer" in the pull down list. The pop-up window "Program IMC controller" will show up as in Figure 9. Click on the "Program Firmware and Parameter" radio button, and select the Drive System Parameter file created using MCEWizard by clicking on the "Browse" button on the row of "Program Parameter File", and then select the firmware file by clicking on the "Browse" button on the row of "Program Firmware File". Finally, click on the "Start" button to program the parameter file into the IMC102T-F064 IC.
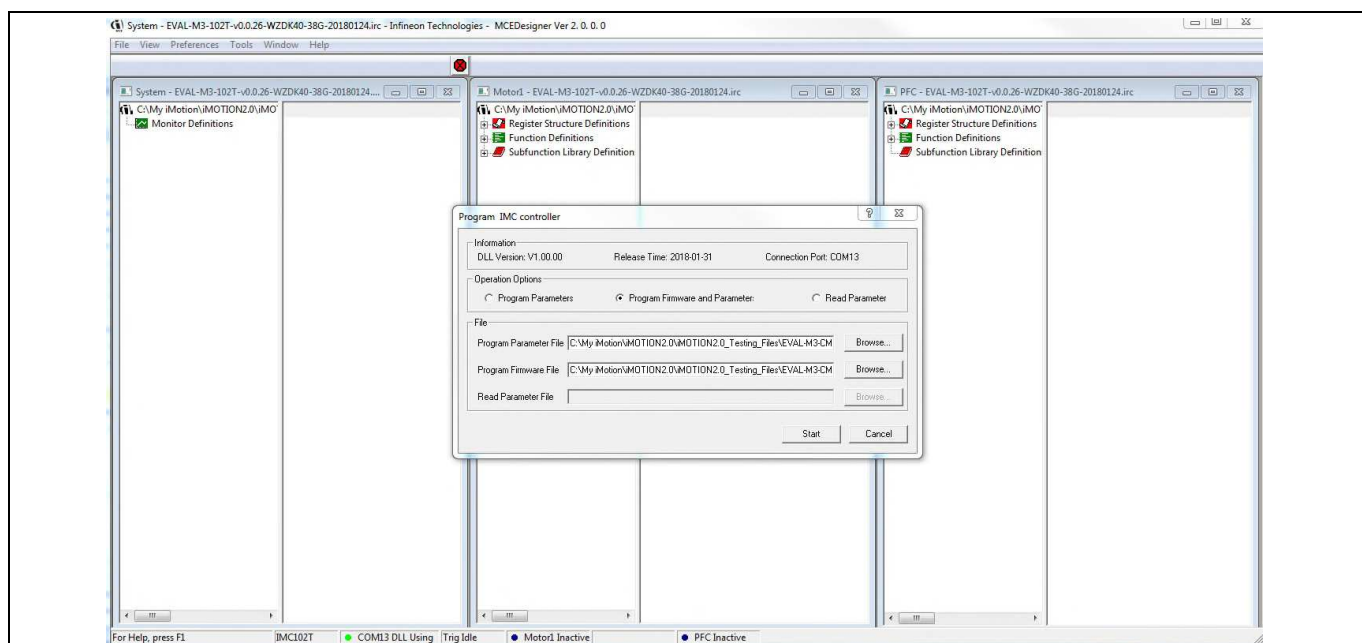

Figure 9   Program Firmware and Parameter in "Program IMC Controller" pop-up window

All latest firmware file for different type of iMOTION™ control ICs are available for download via Infineon iMOTION™ website (http://www.infineon.com/imotion-software).

5 Hardware description of EVAL-M3-CM615PN

To meet individual customer requirements and make the Eval-M3-CM615PN evaluation board a basis for development or modification, all necessary technical data like schematics, layout and components are included in this chapter.

5.1 Boost PFC section using CIPOS™ mini IPM

Figure 10 depicts the schematic from the AC input connector J1 to the rectified DC bus voltage DCP. This circuitry includes a passive EMI filter consisting of elements CX1, CX2, L1, CY1 and CY2, a 25 A/600 V rectifier bridge U1, a fuse F1 for inrush current protection, a NTC resistor RT1 and a relay RLY1 for soft powering up and reducing conduction losses in steady state. The PFC section is implemented using the CIPOS™ mini IPM as sketched in Figure 10. The IRS44273L is used to drive IGBT for PFC section. A PFC inductor should be connected to J2. PFC inductor is included in this evaluation kit.
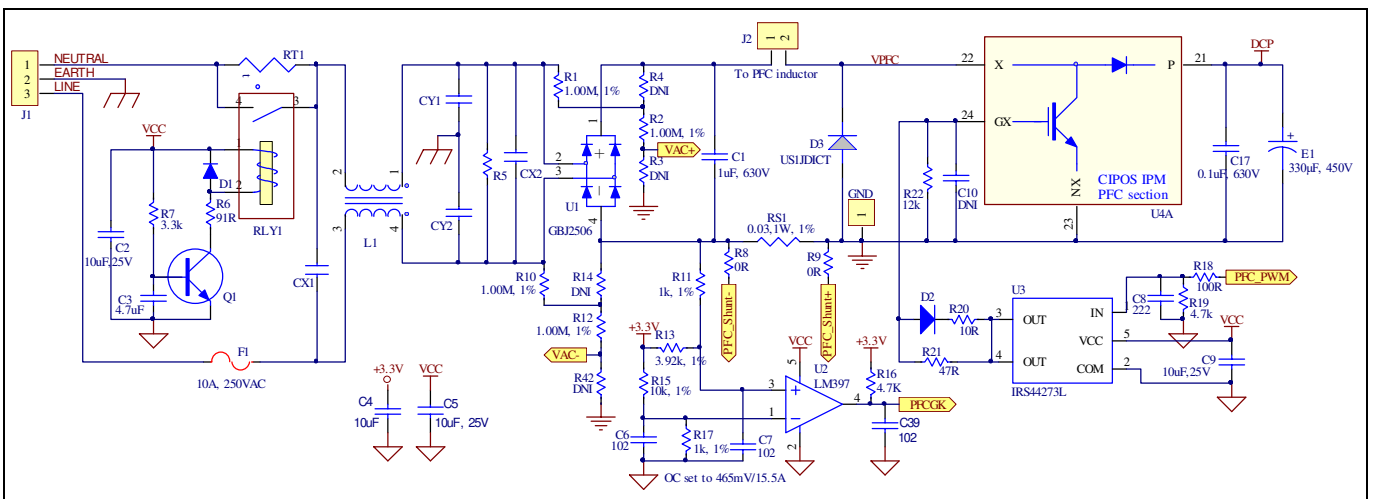

Figure 10   Schematic for EMI filter and PFC section of the Eval-M3-CM615PN evaluation board

The PFC section of CIPOS™ IPM IFCM15P60GD contains a TRENCHSTOP™ 5 IGBT and a rapid switching emitter controlled diode. The PFC IGBT's anti-parallel diode D3 is mandatory. For 650W power output, the inductance of PFC inductor should be larger than 3mH. Two electrolytic capacitors E1 and E2 are used for buffering the rectified DC bus voltage DCP.

5.1.1 AC Voltage sensing and MCEWizard configuration

AC voltage sensing is in the front of rectifier bridge U1 by default as shown in Figure 10. To dive the boost PFC circuitry for EVAL-M3-CM615PN, the default matching MADK control board is EVAL-M3-102T. Figure 11 shows the VAC sensing schematic of EVAL-M3-102T evaluation board.
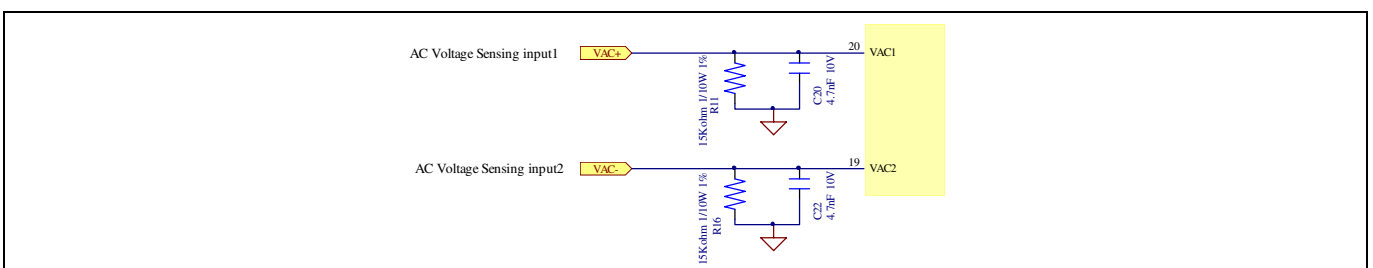

Figure 11   The AC Voltage sensing schematic of EVAL-M3-102T

There are two AC voltage sensing modes in MCEWizard, differential mode and single-ended as shown in Figure 12. Please select differential mode for the combination between EVAL-M3-CM615PN and EVAL-M3-102T.
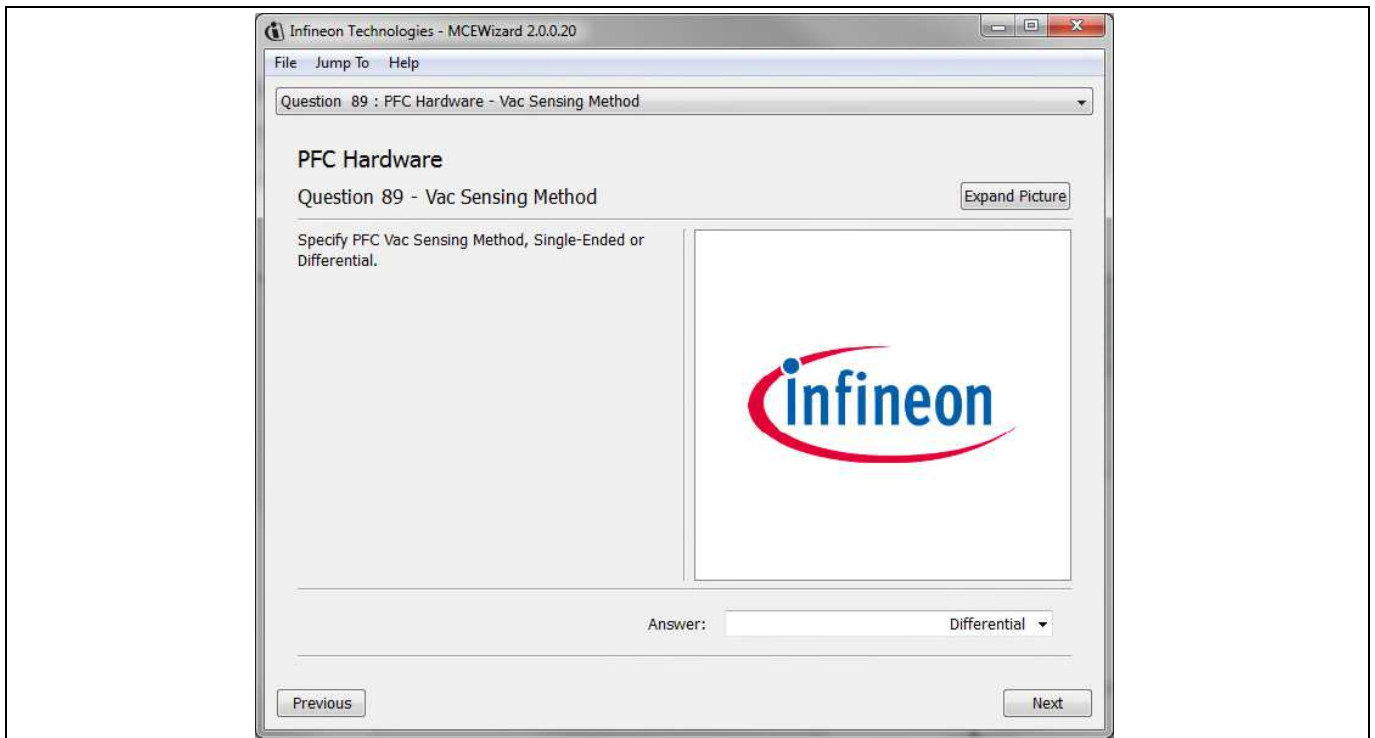

Figure 12   Vac Sensing Method configuration for EVAL-M3-102T and EVAL-M3-CM615PN

The high side resistors R1 and R2 or R12 and R14 for the AC voltage sensing resistor divider on the power board EVAL-M3-CM615PN is 2000kΩ, and should be configured in MCEWizard as shown in Figure 13. For the low side resistor value, please refer to the User Manual of the corresponding control board.
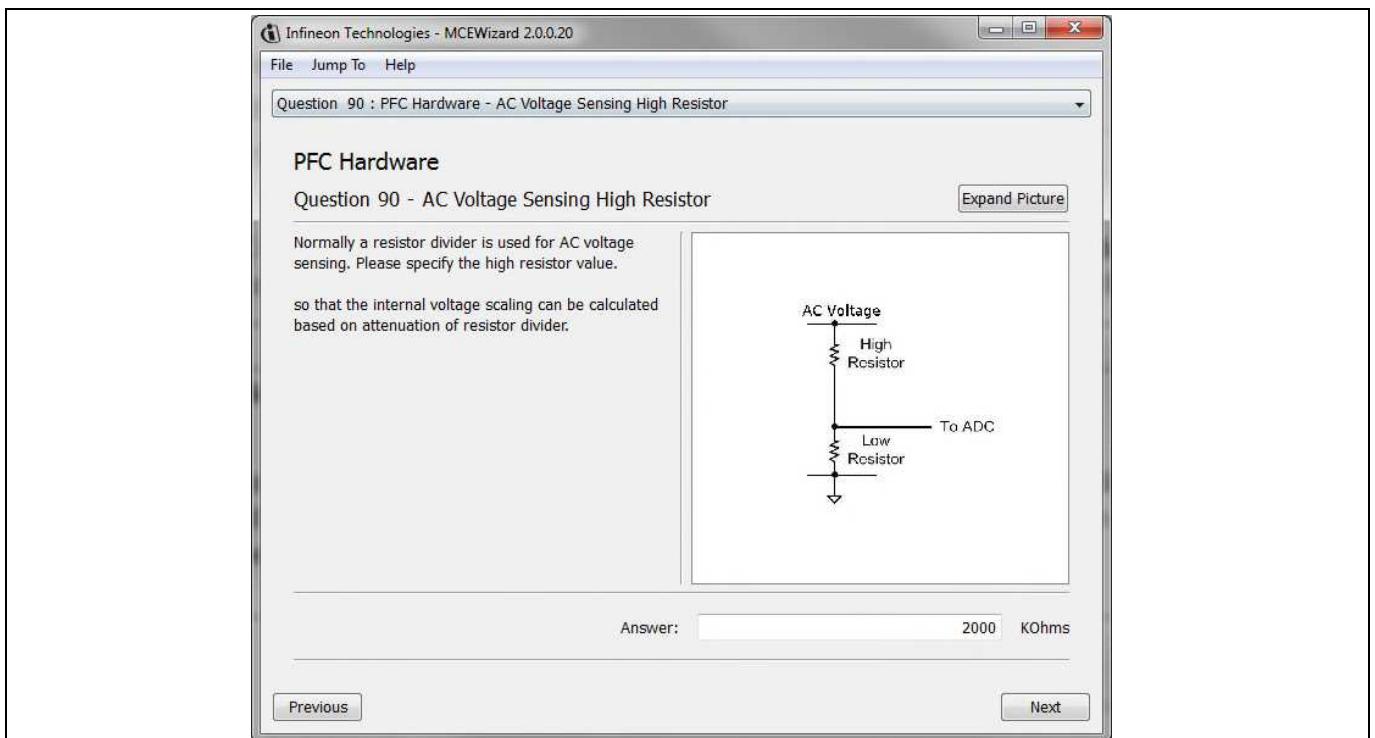

Figure 13   AC Voltage sensing configuration in MCEWizard

5.1.2   PFC External Current feedback configuration and calculation

The PFC shunt resistor RS1 is 30mΩ for EVAL-M3-CM615PN. But for control board EVAL-M3-102T, the current input value is product of the shunt resistance in milliohms and gain of External current sense amplifier as shown in Figure 14.
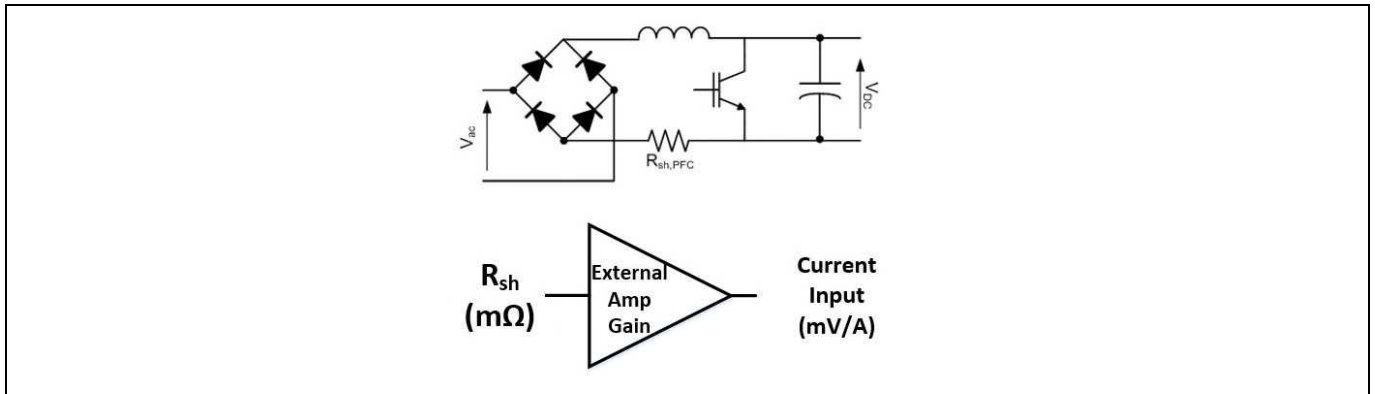

Figure 14   PFC Current shunt feedback and sample timing

Figure 15 depicts IPFC- current feedback sensing circuity on EVAL-M3-102T evaluation board. Please note that the default external amplification gain is less than 1 for current sense in this evaluation board.
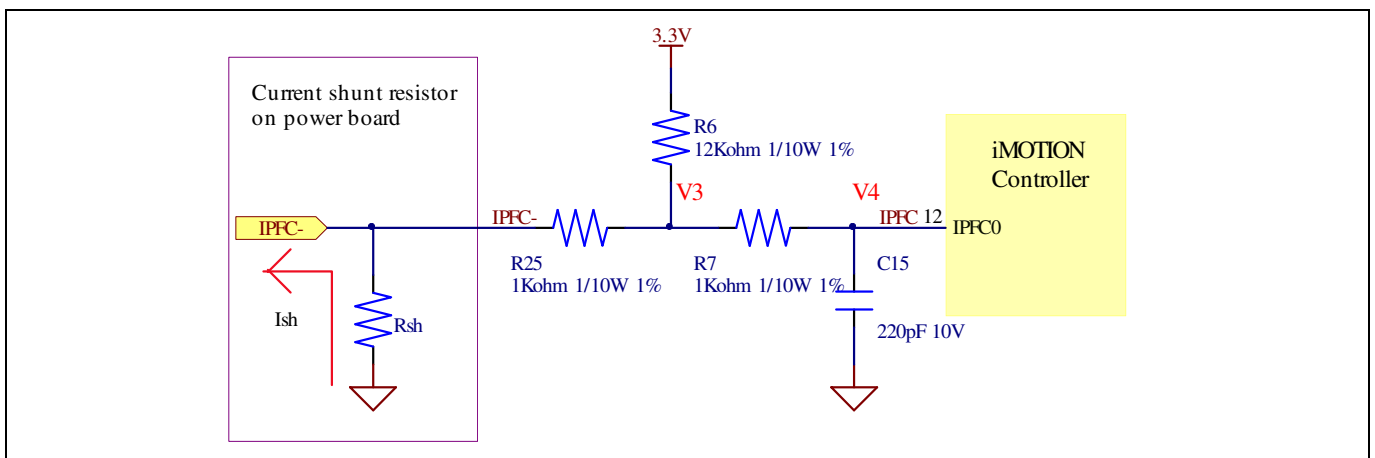

Figure 15   The PFC Current feedback circuit for EVAL-M3-102T evaluation board

Based on the principle of Kirchhoff's voltage law,

$$V_4 \approx V_3 \approx (V_{DD} + I_{sh} * R_{sh}) * \frac{R_{25}}{R_6 + R_{25}} - I_{sh} * R_{sh} = \frac{R_{25}}{R_6 + R_{25}} V_{DD} - \frac{R_6}{R_6 + R_{25}} R_{sh} * I_{sh}$$

$$Current\ input = \frac{R_6}{R_6 + R_{25}} R_{sh} = \frac{12}{13} R_{sh}$$

Based on this calculation, the current input for the MADK combination of EVAL-M3-102T and EVAL-M3-CM615PN is 27.69 mV/A. Please use same procedure to calculate the current input for other combinations of MADK boards and enter it into MCEWizard.

5.1.3   PFC Overcurrent protection circuit and PFC Gatekill configuration

PFC protection circuit for EVAL-M3-CM615PN as shown in Figure 16, but the left side of RS1 is negative. If the bus current Ibus is larger than the setting value, the output PFCGK of U2 will be trigger low and be active.
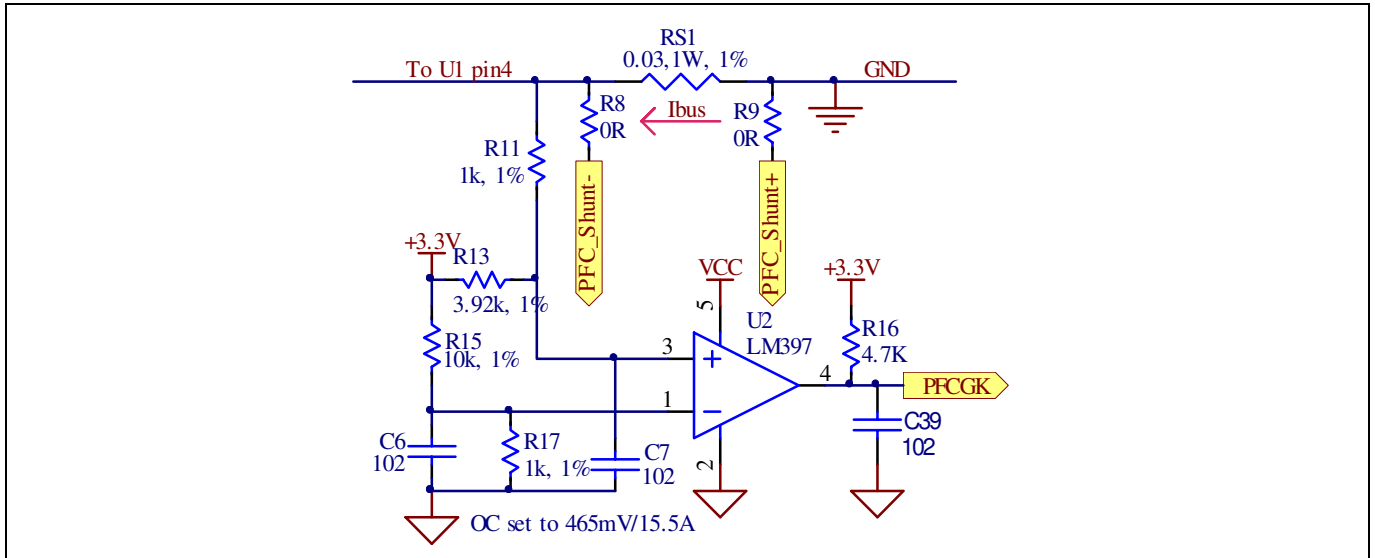

Figure 16   PFC protection Circuit on the EVAL-M3-CM615PN evaluation board

The PFCGK active setting current is 15.5A for EVAL-M3-CM615PN evaluation board. And the calculation formula is as follows,

$$I_{PFCGK} = \frac{\left(\dfrac{R_{11}}{R_{11} + R_{13}} - \dfrac{R_{17}}{R_{17} + R_{15}}\right) * V_{DD}}{\dfrac{R_{11}}{R_{11} + R_{13}} R_{S1}} = \frac{\left(\dfrac{R_{11}}{R_{13}} - \dfrac{(R_{11} + R_{13}) * R_{17}}{(R_{17} + R_{15}) * R_{13}}\right) * V_{DD}}{R_{S1}}$$

Please attention that for control board EVAL-M3-102T, it doesn't use the external PFC gatekill signal PFCGK.

Note: PFC Overcurrent protection circuit just generates the signal of PFCGK, and there is no more action for EVAL-M3-CM615PN. The power board will not turn off the PFC gate driver IC if the control board doesn't do anything when PFCGK is active.
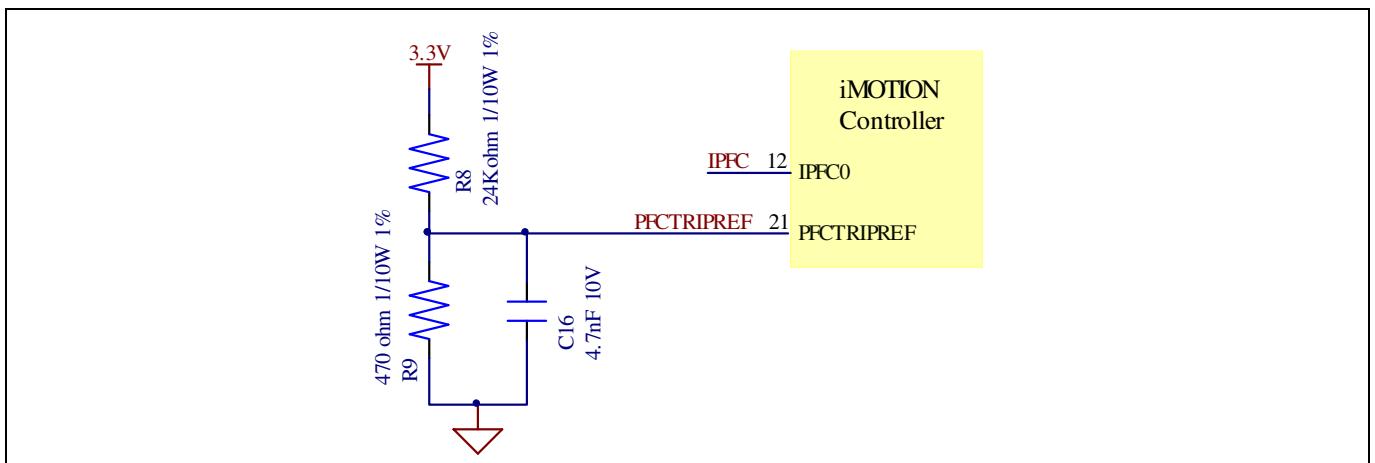

Figure 17   The PFCTRIPREF Circuit on the EVAL-M3-102T evaluation board

The PFC's overcurrent protection circuit on the control board EVAL-M3-102T is shown in Figure 15 and Figure 17. The $I_{PFCTRIP\_Peak}$ equal to 6.347A for the combination between EVAL-M3-102T and EVAL-M3-CM615PN only.

The calculation formula is as follows,

$$I_{PFCTRIP_{Peak}} = \frac{\left(\frac{R_9}{R_8 + R_9} - \frac{R_6}{R_6 + R_{25}}\right) * V_{DD}}{R_{S1}}$$

If larger PFC current protection setting value needed, please use smaller resistance of PFC shunt resistor RS1, or modify the control board EVAL-M3-102T following the previous formula. Please refer to the control board's user manual for more details.

5.2 Inverter section using CIPOS™ mini IPM

The inverter section is also implemented using the CIPOS™ mini IPM as sketched in Figure 18. The inverter section of IPM module includes an optimized SOI gate driver and a three-phase inverter consisting of TRENCHSTOP™ IGBTs and anti parallel diodes.

The three pairs of capacitors C11 and C12, C13 and C14, C15 and C16 are used as bootstrap capacitors to provide the necessary floating supply voltages V_{BS1}, V_{BS2} and V_{BS3} respectively.
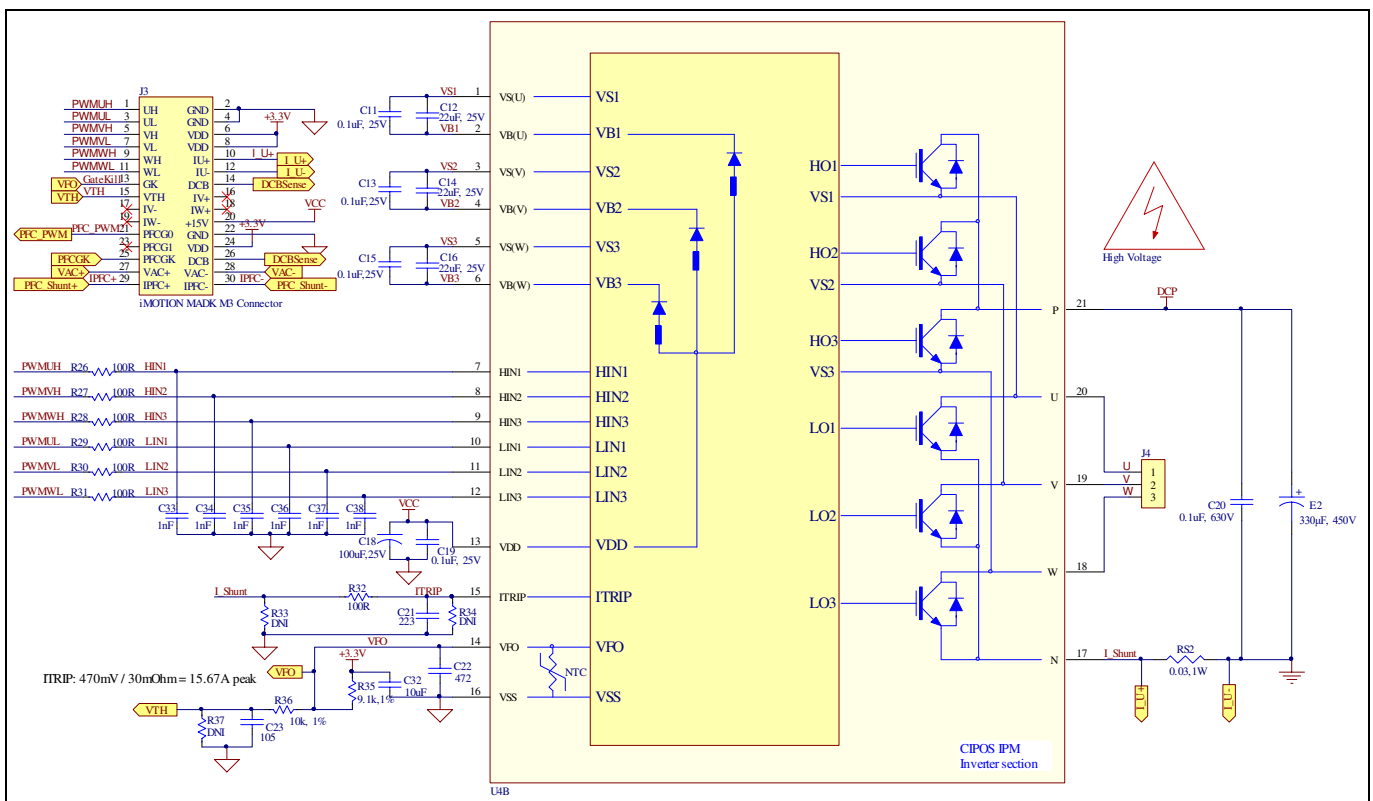

Figure 18   Schematic of the 3-phase inverter section using CIPOS™ mini IPM on Eval-M3-CM615PN

5.2.1   DC bus sensing and MCEWizard configuration

Pin 14 and pin 26 of connector J3 provide access to the DC-link voltage DCBsense. Three possible feedback cases are associated with these pins. Figure 19 provides the DC bus sense resistor details. By default, the resistor R25 is not mounted on Eval-M3-CM615PN. There must be a pull-down resistor mounted on the corresponding controller board.
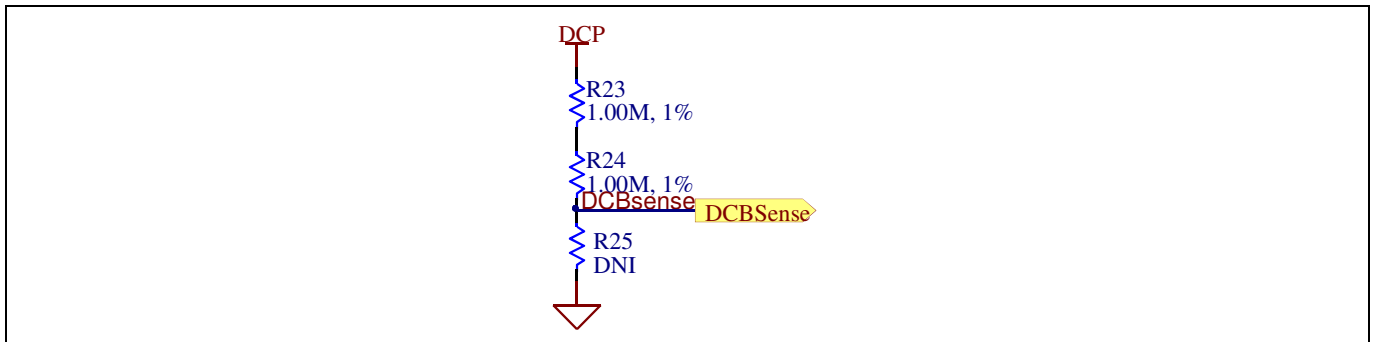

Figure 19   DC bus sense resistor on Eval-M3-CM615PN evaluation board

If a pull down resistor of 13.3 kΩ referred to ground is inserted either on the Eval-M3-CM615PN evaluation board or on the control board, the DCBSense voltage results in the range of 0 to 3.3 V on the pin reflecting a DC bus voltage range of 0 to 420 V.If a pull down resistor of 13.3 kΩ is inserted on both, Eval-M3-CM615PN evaluation board and on the control card, the DCBSense results scale to 0-1.65 V. No safety issue occurs. If no feedback is desired on the DCBSense pin, R23 or R24 should be removed to avoid high voltage on the connector.

The high side resistors R23 and R24 for the DC bus sensing resistor divider on the controller board EVAL-M3-CM615PN are 2000kΩ, and should be configured in MCEWizard as shown in Figure 20. For the low side resistor value, please refer to the User Manual of the corresponding control board.
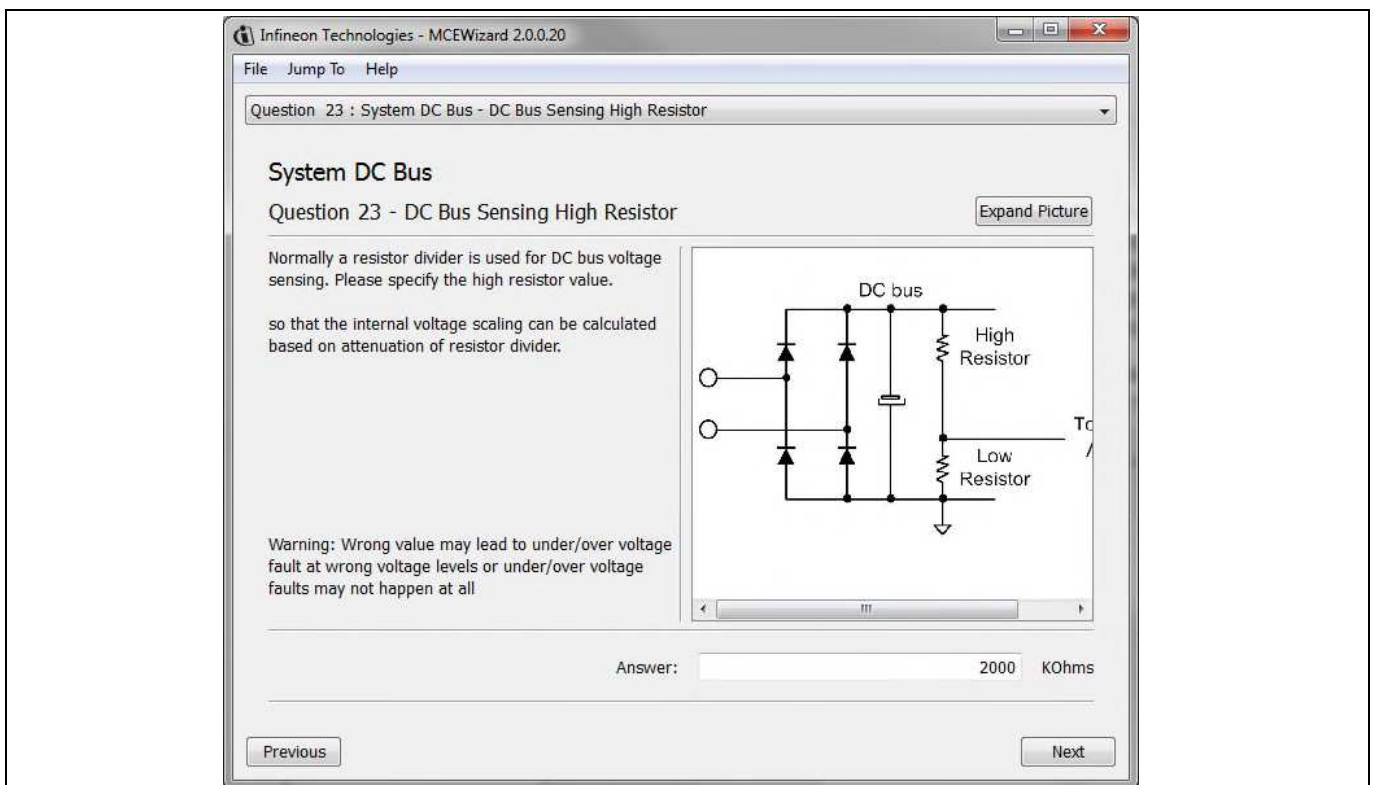

Figure 20   DC bus sensing configuration in MCEWizard

5.2.2 Motor External Current feedback configuration and calculation

The current input value is product of the shunt resistance in milliohms and gain of External current sense amplifier for EVAL-M3-102T as shown in Figure 21.
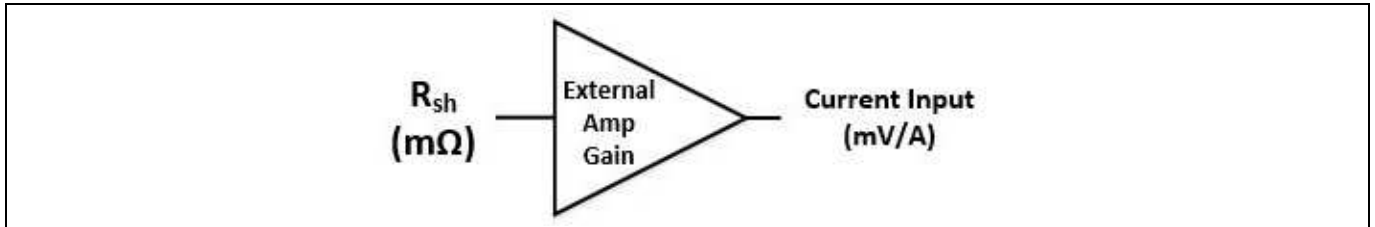

Figure 21   Current shunt feedback and sample timing for EVAL-M3-102T

The External Amplifier Gain circuit can be found in the schematics or User Manual for the control board (For example, EVAL-M3-102T see Figure 22).

Figure 22 depicts IU+ current feedback sensing circuity on EVAL-M3-102T evaluation board. Please note that the default external amplification gain is less than 1 for current sense in this evaluation board.
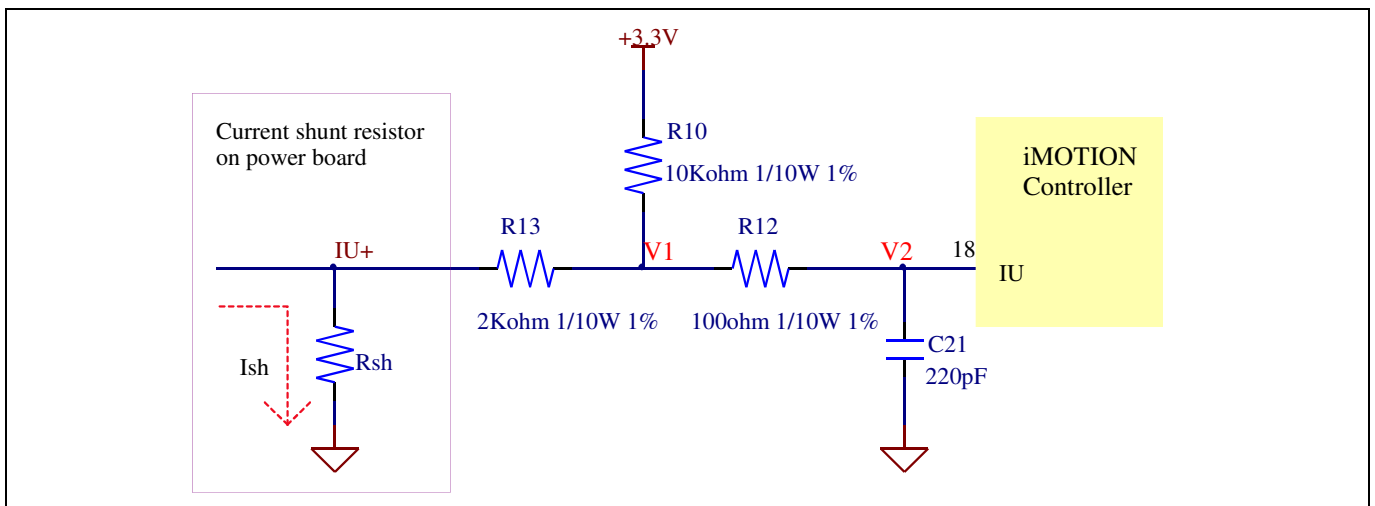

Figure 22   The part of Current feedback on the EVAL-M3-102T evaluation board

Based on the principle of Kirchhoff's voltage law,

$$V_2 \approx V_1 \approx (V_{DD} - I_{sh} * R_{sh}) * \frac{R_{13}}{R_{10} + R_{13}} + I_{sh} * R_{sh} = \frac{R_{13}}{R_{10} + R_{13}} V_{DD} + \frac{R_{10}}{R_{10} + R_{13}} R_{sh} * I_{sh}$$

$$Current\ input = \frac{R_{10}}{R_{10} + R_{13}} R_{sh} = \frac{5}{6} R_{sh}$$

Based on this calculation, the current input for the MADK combination of EVAL-M3-102T and EVAL-M3-CM615PN is 25 mV/A.

Please use same procedure to calculate the current input for other combinations of MADK boards and enter it into MCEWizard as shown in Figure 23.
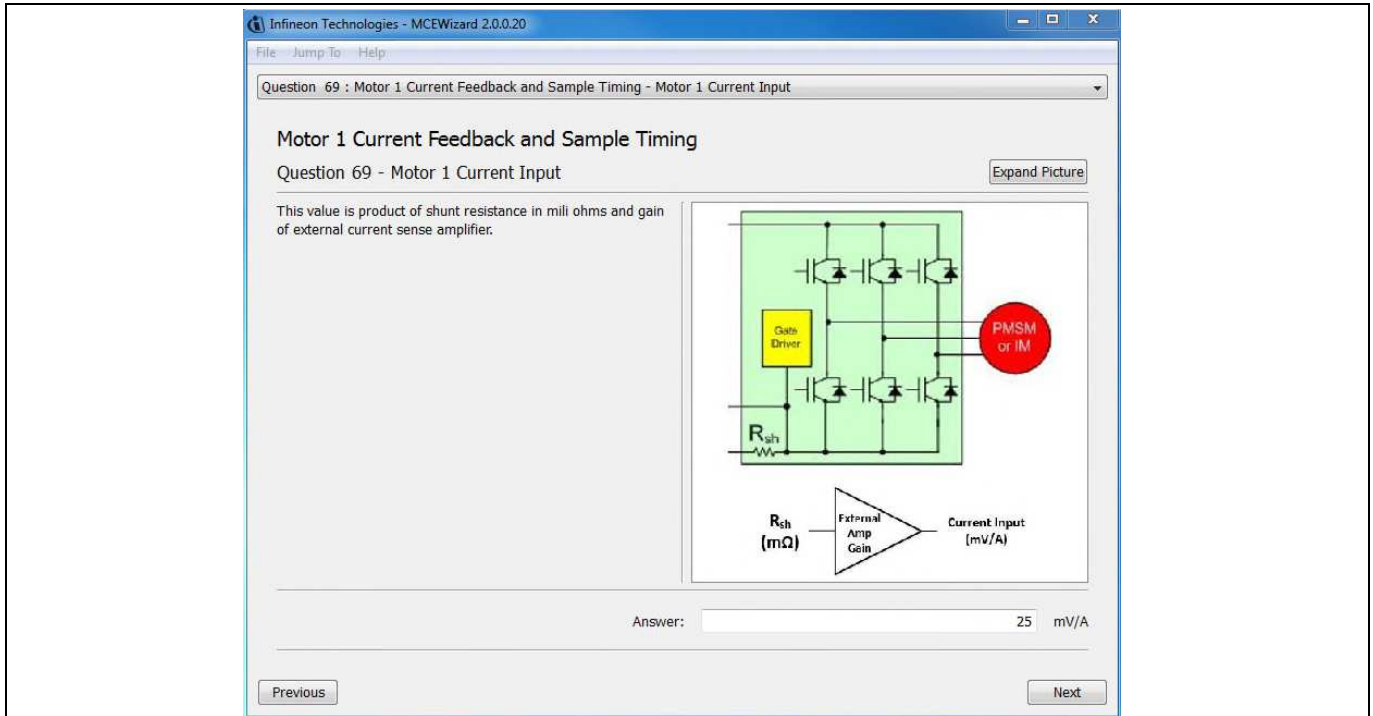

Figure 23   Current feedback configuration in MCEWizard for EVAL-M3-102T and EVAL-M3-CM615PN

5.2.3   Inverter Overcurrent protection and Motor Gatekill configuration

Figure 24 displays the overcurrent protection circuitry. The current sensing signal I_Shunt is connected to ITRIP via the resistor R32, and ITRIP is filtered through capacitor C21.
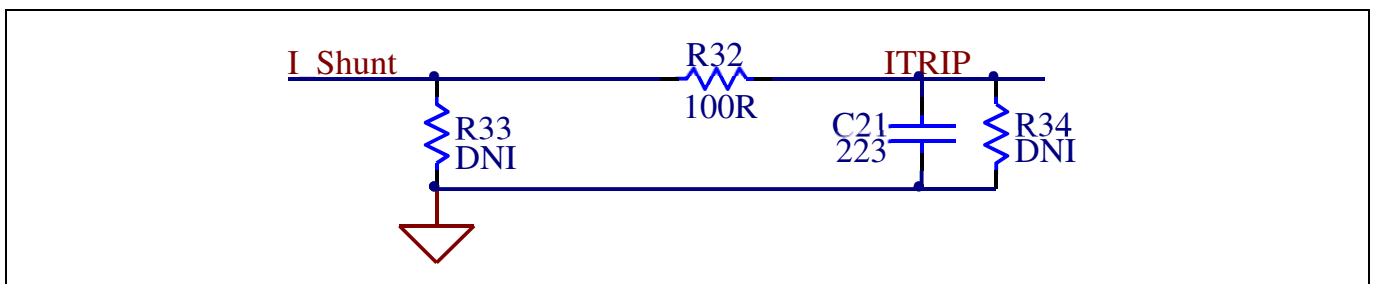

Figure 24   Overcurrent protection circuit on the Eval-M3-CM615PN evaluation board

The typical value of ITRIP positive going threshold $V_{IT, TH+}$ is 470mV. So the inverter output peak current is about 15.67A.

$$I_{trip} = \frac{V_{IT,TH+}}{R_{shunt}} = \frac{470mV}{30m\Omega} = 15.67A$$

If the motor peak current larger than the setting value I_{trip} for more than ITRIP Input filter time, VFO will be trigger low which is mean that the signal Gatekill is active. For iMOTION™ IMC1xx control IC, there are three types of Gatekill Input Source (as shown in Figure 25). For Gatekill Input Source configured Gatekill-Pin or Both, iMOTION™ control IC will stop the Motor when the signal GateKill is active.

But please note that, if select comparator for Gatekill Input Source, the external Gatekill signal will be not used. And the current sensing signal I_Shunt will be compared by the internal comparator with the "Gatekill Comparator Reference" value set in MCEWizard only.
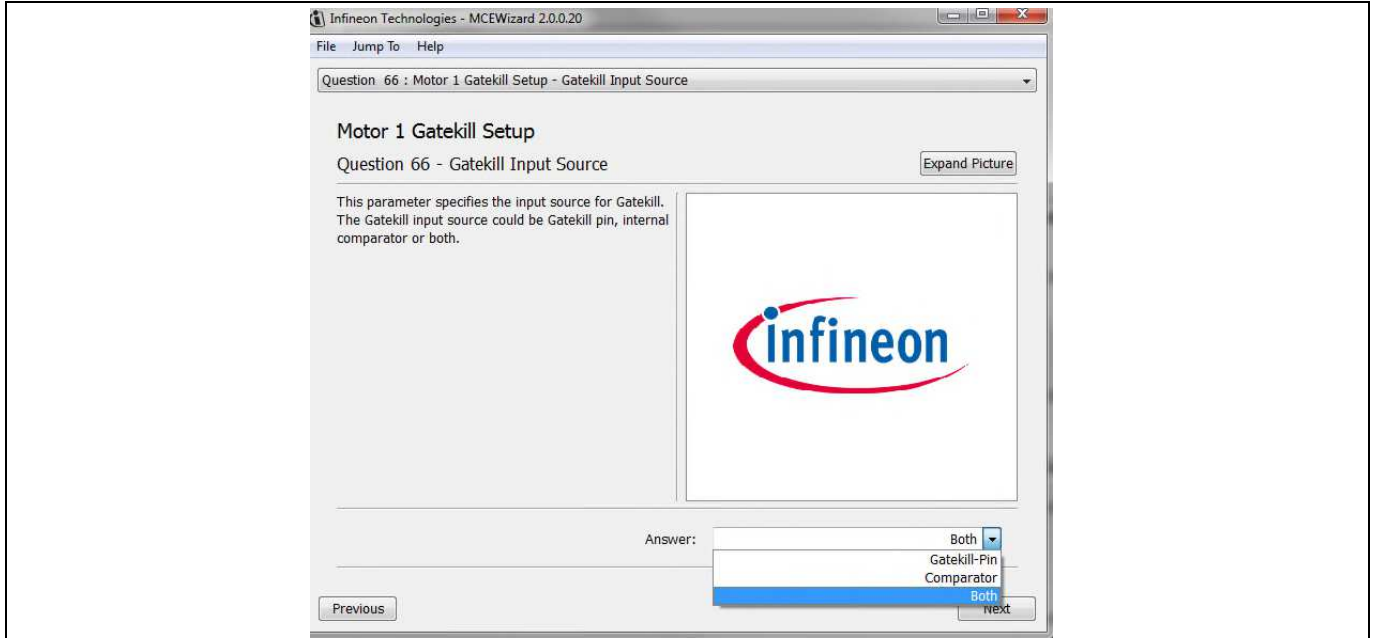

Figure 25   Gatekill configuration in MCEWizard for EVAL-M3-102T

5.3   Thermistor/NTC Characteristics and protection calculation

This board provides Thermistor/NTC output on pin 15 of the 30 pins connector J3. Temperatures can be calculated by resistor measurement.

5.3.1   CIPOS™ Internal NTC – Thermistor Characteristics

The thermistor characteristics for CIPOS™ mini IPM with build in NTC are listed as summarized in Table 8.

Table 8   CIPOS™ Internal NTC – Thermistor Characteristics

Description	Condition	Symbol	Value			Unit
			min	typ	max	
Resistor	$T_{NTC} = 25°C$	R_{NTC}	79.638	85.000	90.362	kΩ
Resistor	$T_{NTC} = 50°C$	R_{NTC}	28.400	29.972	31.545	kΩ
Resistor	$T_{NTC} = 60°C$	R_{NTC}	19.517	20.515	21.514	kΩ
Resistor	$T_{NTC} = 70°C$	R_{NTC}	13.670	14.315	14.960	kΩ
Resistor	$T_{NTC} = 80°C$	R_{NTC}	9.745	10.169	10.593	kΩ
Resistor	$T_{NTC} = 90°C$	R_{NTC}	7.062	7.345	7.628	kΩ
Resistor	$T_{NTC} = 100°C$	R_{NTC}	5.199	5.388	5.576	kΩ
Resistor	$T_{NTC} = 110°C$	R_{NTC}	3.856	4.009	4.163	kΩ
Resistor	$T_{NTC} = 120°C$	R_{NTC}	2.900	3.024	3.149	kΩ
Resistor	$T_{NTC} = 125°C$	R_{NTC}	2.527	2.639	2.751	kΩ
B-constant of NTC		B(25/100)		4092		K