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January 2013

# **FAN302HLMY\_F117 PWM Controller for Low Standby Power Battery-Charger Applications — mWSaver™ Technology**

## **Features**

- mWSaver™ Technology Provides Industry's Best-in-Class Standby Power
	- Ultra Low Power Consumption at No Load (<10 mW at 230  $V_{AC}$ )
	- Proprietary 500V High-Voltage JFET Startup Reduces Startup Resistor Loss
	- Low Operation Current in Burst Mode: 350 µA Maximum
- Constant-Current (CC) Control without Secondary-Feedback Circuitry
- Fixed PWM Frequency at 85kHz with Frequency Hopping to Reduce EMI
- High-Voltage Startup
- Low Operating Current: 3.5 mA
- Peak-Current-Mode Control with Slope Compensation
- Cycle-by-Cycle Current Limiting
- V<sub>DD</sub> Over-Voltage Protection (Auto-Restart)
- V<sub>S</sub> Over-Voltage Protection (Latch Mode)
- V<sub>DD</sub> Under-Voltage Lockout (UVLO)
- Gate Output Maximum Voltage Clamped at 15 V
- Fixed Over-Temperature Protection (Latch Mode)
- Available in an 8-Lead SOIC Package

# **Applications**

- Battery Chargers for Cellular Phones, Cordless Phones, PDAs, Digital Cameras, and Power Tools
- Replaces Linear Regulators and RCC SMPS

# **Description**

The FAN302HLMY\_F117 advanced PWM controller significantly simplifies isolated power supply design that requires CC regulation of the output. The output current is precisely estimated with information in the primary side of the transformer and controlled with an internal compensation circuit. This removes the output current sensing loss and eliminates all external Control Circuitry (CC). The Green-Mode function, with an extremely low operating current (200 µA) in Burst Mode, maximizes the light-load efficiency, enabling conformance to worldwide Standby Mode efficiency guidelines.

Integrated protections include two-level pulse-by-pulse current limit, Over-Voltage Protection (OVP), brownout protection, and Over-Temperature Protection (OTP).

Compared with a conventional approach using an external control circuit in the secondary side for CC regulation, the FAN302HLMY\_F117 can reduce total cost, component count, size, and weight; while simultaneously increasing efficiency, productivity, and system reliability.



**Figure 1. Typical Output V-I Characteristic** 

# **Ordering Information**





**FAN302HLMY\_F117— mWSaver™ PWM Controller for Low Standby Power Battery-Charger Applications** 

FAN302HLMY\_F117-- mWSaver<sup>TM</sup> PWM Controller for Low Standby Power Battery-Charger Applications



# **Pin Definitions**



# **Absolute Maximum Ratings**

Stresses exceeding the Absolute Maximum Ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.



#### **Notes:**

1. All voltage values, except differential voltages, are given with respect to GND pin.<br>2. Stresses beyond those listed under Absolute Maximum Ratings may cause perma

2. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device.<br>3. ESD ratings including the HV pin: HBM=400 V, CDM=750 V.

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# **Electrical Characteristics**

 $V_{DD}$ =15 V and  $T_A$ =25°C unless noted.



*Continued on the following page…* 

# **Electrical Characteristics (Continued)**

 $V_{DD}$ =15 V and T<sub>A</sub>=25°C unless noted.



#### **Notes:**

4.  $f_{\text{OSC-CM-MIN}}$  occurs when the power unit enters CCM operation.<br>5. A<sub>V</sub> is a scale-down ratio of the internal voltage divider of the F

5. A<sub>V</sub> is a scale-down ratio of the internal voltage divider of the FB pin. 6. Guaranteed by design; not production tested.

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FAN302HLMY\_F117-- mWSaver™ PWM Controller for Low Standby Power Battery-Charger Applications **FAN302HLMY\_F117— mWSaver™ PWM Controller for Low Standby Power Battery-Charger Applications** 





## **Operational Description**

#### **Basic Control Principle**

Figure 24 shows the internal PWM control circuit. The constant voltage (CV) regulation is implemented in the same way as the conventional isolated power supply, where the output voltage is sensed using a voltage divider and compared with the internal 2.5 V reference of a shunt regulator (KA431) to generate a compensation signal. The compensation signal is transferred to the primary side using an opto-coupler and scaled down through attenuator Av, generating the  $V_{EAY}$  signal. Then the error signal  $V_{EAY}$  is applied to the PWM comparator (PWM.V) to determine the duty cycle.

Meanwhile, the CC regulation is implemented internally without directly sensing the output current. The output current estimator reconstructs output current information  $(V_{CCR})$  using the transformer primary-side current and diode current discharge time. Then  $V_{CCR}$  is compared with a reference voltage (2.5 V) by an internal error amplifier, generating the  $V_{EA,I}$  signal to determine the duty cycle.

The two error signals,  $V_{EA, I}$  and  $V_{EA, V}$ , are compared with an internal sawtooth waveform  $(V<sub>SAW</sub>)$  by PWM comparators PWM.I and PWM.V to determine the duty cycle. As shown in Figure 25, the outputs of two comparators (PWM.I and PWM.V) are combined with an OR gate and used as a reset signal of flip-flop to determine the MOSFET turn-off instant. The lower signal,  $V_{EA,V}$  or  $V_{EA,I}$ , determines the duty cycle, as shown in Figure 25. During CV regulation,  $V_{EA,V}$ determines the duty cycle while  $V_{EA,I}$  is saturated to HIGH. During CC regulation, V<sub>EA.I</sub> determines the duty cycle while  $V_{EA,V}$  is saturated to HIGH.







**Figure 25. PWM Operation for CC and CV** 

#### **Output Current Estimation**

Figure 26 shows the key waveform of a flyback converter operating in Discontinuous Conduction Mode (DCM), where the secondary-side diode current reaches zero before the next switching cycle begins. Since the output current estimator is designed for DCM operation, the power stage should be designed such that DCM is guaranteed for the entire operating range. The output current is obtained by averaging the triangular output diode current area over a switching cycle:

$$
I_{O} = _{AVG} = I_{PK} \frac{N_{P}}{N_{S}} \bullet \frac{t_{DIS}}{2t_{S}}
$$
(1)

where  $I_{PK}$  is the peak value of the primary-side current;  $N_P$  and  $N_S$  are the number of turns of transformer primary-side and secondary-side, respectively;  $t_{DIS}$  is the diode current discharge time; and  $t<sub>S</sub>$  is the switching period.

With a given current sensing resistor, the output current can be programmed as:

$$
l_o = \frac{1.25}{K \bullet R_{\text{SENSE}}} \frac{N_p}{N_S} \tag{2}
$$

where K is the design parameter of IC, which is 10.5.

The peak value of primary-side current is obtained by an internal peak detection circuit, while diode current discharge time is obtained by detecting the diode current zero-crossing instant. Since the diode current cannot be sensed directly with primary-side control, Zero Crossing Detection (ZCD) is accomplished indirectly by monitoring the auxiliary winding voltage. When the diode current reaches zero, the transformer winding voltage begins to drop by the resonance between the MOSFET output capacitance and the transformer magnetizing inductance. To detect the starting instant of the resonance, the  $V<sub>S</sub>$  is sampled at 85% of diode current discharge time of the previous switching cycle, then compared with the instantaneous  $V_S$  voltage. When instantaneous  $V_S$  drops below the sampled voltage by more than 200 mV, ZCD of diode current is obtained, as shown in Figure 27.



## **Frequency Reduction in CC Mode**

An important design consideration is that the transformer guarantee DCM operation across the whole range since the output current is properly estimated only in DCM operation. As can be seen in Figure 28, the discharge time  $(t_{DIS})$  of the diode current increases as the output voltage decreases in CC Mode. The converter tends to go into CCM as output voltage drops in CC Mode when operating at the fixed switching frequency. To prevent this CCM operation while maintaining good output current estimation in DCM, FAN302HLMY\_F117 decreases switching frequency as output voltage drops, as shown in Figure 28 and Figure 29. FAN302HLMY\_F117 indirectly monitors the output voltage by the sample-and-hold voltage  $(V_{SH})$  of  $V_S$ , which is taken at 85% of diode current discharge time of the previous switching cycle, as shown in Figure 27. Figure 30 shows how the frequency reduces as the sample-and-hold voltage of VS decreases.





### **CCM Prevention Function**

Even if the power supply is designed to operate in DCM, it can go into CCM when there is not enough design margin to cover all the circuit parameter variations and operating conditions. FAN302HLMY\_F117 has a CCMprevention function that delays the next cycle turn-on of MOSFET until ZCD on the VS pin is obtained, as shown in Figure 31. To guarantee stable DCM operation, FAN302HLMY\_F117 prohibits the turn-on of the next switching cycle for 10% of its switching period after ZCD is obtained. In Figure 31, the first switching cycle has ZCD before 90% of its original switching period and, therefore, the turn-on instant of the next cycle is determined without being affected by the ZCD instant. The second switching cycle does not have ZCD by the end of the original switching period; thus, the turn-on of the third switching cycle occurs after ZCD is obtained, with a delay of 10% of its original switching period. The minimum switching frequency that CCM prevention function allows is 18 kHz ( $f_{\text{OSC-CM-MIN}}$ ). If the ZCD is not given until the end of maximum switching period of 55.6 µs (1/18 kHz), the converter can go into CCM operation, losing output regulation.



**Figure 31. CCM Prevention Function** 

## **Power Limit Mode**

When the sampled voltage of VS ( $V_{\text{SH}}$ ) drops below  $V_{\text{S}}$ - $CM-MIN$  (0.55 V), FAN302HLMY F117 enters constant Power Limit Mode, where the primary-side current-limit voltage (V<sub>CS</sub>) changes from  $V_{STH}$  (0.8 V) to  $V_{STH-VA}$  $(0.3 V)$  to avoid  $V<sub>S</sub>$  sampling and ZCD, as shown in Figure 32. Once  $V_S$  sampling voltage is higher than  $V_{S}$ - $CM-MAX$  (0.75 V), the V<sub>CS</sub> returns to V<sub>STH</sub>. This mode prevents the power supply from going into CCM and losing output regulation when the output voltage is too low. This effectively protects the power supply when there is a fault condition in the load, such as output short or overload. This mode also implements soft-start by limiting the transformer current until  $V_s$  sampling voltage reaches  $V_{S\text{-}CM\text{-}MAX}$  (0.75 V).

![](_page_13_Figure_7.jpeg)

**Figure 32. Power Limit Mode Operation** 

## **High-Voltage Startup**

Figure 33 shows the high-voltage (HV) startup circuit. Internally, JFET is used to implement the high-voltage current source, whose characteristics are shown in Figure 34. Technically, the HV pin can be directly connected to the DC link  $(V_{DL})$ . To improve reliability and surge immunity; it is typical to use about a 100 k $\Omega$ resistor between the HV pin and the DC link. The actual HV current with given DC link voltage and startup resistor is determined by the intersection of V-I characteristics line and load line, as shown in Figure 34.

During startup, the internal startup circuit is enabled and the DC link supplies the current,  $I_{HV}$ , to charge the holdup capacitor,  $C_{VDD}$ , through  $R_{STAT}$ . When the  $V_{DD}$ voltage reaches  $V_{DD-ON}$ , the internal HV startup circuit is disabled and the IC starts PWM switching. Once the HV startup circuit is disabled, the energy stored in  $C_{VDD}$ should supply the IC operating current until the transformer auxiliary winding voltage reaches the nominal value. Therefore, C<sub>VDD</sub> should be designed to prevent  $V_{DD}$  from dropping to  $V_{DD-OFF}$  before the auxiliary winding builds up enough voltage to supply  $V_{DD}$ . Capacitance tolerance is an important factor to consider for  $C_{DD}$  selection. Connecting a 22  $\mu$ F capacitor between the  $V_{DD}$  and GND pins is recommended to ensure system stability across the wide operation temperature range.

![](_page_13_Figure_12.jpeg)

![](_page_14_Figure_1.jpeg)

## **Frequency Hopping**

EMI reduction is accomplished by frequency hopping, which spreads the energy over a wider frequency range than the bandwidth of the EMI test equipment. The frequency-hopping circuit changes the switching frequency progressively between 82 kHz and 88 kHz with a period of  $t<sub>o</sub>$ , as shown in Figure 35.

![](_page_14_Figure_4.jpeg)

**Figure 35. Frequency Hopping** 

### **Burst-Mode Operation**

The power supply enters Burst Mode at no-load or extremely light-load conditions. As shown in Figure 36, when  $V_{FB}$  drops below  $V_{FBL}$ ; the PWM output shuts off and the output voltage drops at a rate dependent on load current. This causes the feedback voltage to rise. Once  $V_{FB}$  exceeds  $V_{FBH}$ , the internal circuit starts to provide switching pulse. The feedback voltage then falls and the process repeats. Burst Mode operation alternately enables and disables switching of the MOSFET, reducing the switching losses in Standby Mode. Once FAN302HLMY\_F117 enters Burst Mode, the operating current is reduced from 3.5 mA to 200 μA to minimize power consumption.

![](_page_14_Figure_8.jpeg)

**Figure 36. Burst-Mode Operation** 

## **Slope Compensation**

The sensed voltage across the current-sense resistor is used for Current-Mode control and pulse-by-pulse current limiting. A synchronized ramp signal with positive slope is added to the current sense information at each switching cycle, improving noise immunity of Current-Mode control.

## **Protections**

The self-protection functions include  $V_{DD}$  Over-Voltage Protection (OVP), internal Over-Temperature Protection (OTP), V<sub>S</sub> Over-Voltage Protection (OVP), and brownout protection.  $V_{DD}$  OVP and brownout protection are implemented as Auto-Restart Mode, while the  $V<sub>S</sub>$ OVP and internal OTP are implemented as Latch Mode.

When an Auto-Restart Mode protection is triggered, switching is terminated and the MOSFET remains off, causing  $V_{DD}$  to drop. When  $V_{DD}$  drops to the  $V_{DD}$  turnoff voltage of 5 V; the protection is reset, the internal startup circuit is enabled, and the supply current drawn from the HV pin charges the hold-up capacitor. When  $V_{DD}$  reaches the turn-on voltage of 16 V, normal operation resumes. In this manner, auto-restart alternately enables and disables MOSFET switching until the abnormal condition is eliminated, as shown in Figure 37.

When a Latch Mode protection is triggered, PWM switching is terminated and the MOSFET remains off, causing  $V_{DD}$  to drop. When  $V_{DD}$  drops to the  $V_{DD}$  turn-off voltage of 5 V, the internal startup circuit is enabled without resetting the protection and the supply current drawn from HV pin charges the hold-up capacitor. Since the protection is not reset, the IC does not resume PWM switching even when  $V_{DD}$  reaches the turn-on voltage of 16 V, disabling HV startup circuit. Then  $V_{DD}$  drops down to 5 V. In this manner, the Latch Mode protection alternately charges and discharges  $V_{DD}$  until there is no more energy in the DC link capacitor. The protection is reset when  $V_{DD}$  drops to 2.5 V, which is allowed only after the power supply is unplugged from the AC line, as shown in Figure 38.

![](_page_15_Figure_0.jpeg)

![](_page_15_Figure_1.jpeg)

#### **Over-Temperature Protection (OTP)**

The temperature-sensing circuit shuts down PWM output if the junction temperature exceeds  $140^{\circ}$ C (t<sub>OTP</sub>).

#### **V<sub>DD</sub>** Over-Voltage Protection

V<sub>DD</sub> over-voltage protection prevents IC damage from over-voltage exceeding the IC voltage rating. When the  $V_{DD}$  voltage exceeds 26.5 V due to an abnormal condition, the protection is triggered. This protection is typically caused by open circuit in the secondary-side feedback network.

#### **Input Voltage Sensing**

The FAN302HL indirectly senses input voltage using the VS pin current while the MOSFET is turned on. Since the VS pin voltage is clamped at 0.7 V when the MOSFET is turned on, the current flowing out of the VS pin is approximately proportional to the input voltage as:

$$
I_{VS,ON} = \frac{(\frac{N_A}{N_P}V_{DL} + 0.7)}{R_{VS1}} + \frac{0.7}{R_{VS2}} \approx \frac{N_A}{N_P} \frac{V_{DL}}{R_{VS1}}
$$
(3)

![](_page_15_Figure_9.jpeg)

**Figure 39. Vs Pin Current Sensing** 

FAN302HL modulates the minimum on time of the MOSFET such that it reduces as input voltage increases, as shown Figure 40. This allows smaller minimum on time for high line condition, ensuring Burst Mode operation occurs at almost same power level regardless of line voltage variation. The minimum on time is related to the bundle frequency of Burst Mode.

When selecting  $R_{VS1}$  and  $R_{VS2}$ , 150  $\mu$ A is the VS current level to consider seriously. If the VS current is lower than 150  $\mu$ A, t<sub>on min</sub> won't be larger.

![](_page_15_Figure_13.jpeg)

**Figure 40. Minimum On Time vs. VS Pin Current** 

#### **VS Over-Voltage Protection (OVP)**

V<sub>S</sub> over-voltage protection prevents damage due to output over-voltage conditions. Figure 41 shows the VS OVP protection method. The OVP is triggered when the  $V_S$  sampling voltage is above 2.8 V ( $V_{VS}$   $_{OVP}$ ) for longer than eight switching cycles. Then PWM pulses are disabled and FAN302HL enters Latch Mode. The protection is reset and normal operation resumes when  $V_{DD}$  drops below  $V_{DD-LH}$ . Vs overvoltage conditions are usually caused by an open circuit in the secondary-side feedback network or abnormal behavior by the VS pin divider resistor.

When the secondary-side feedback circuit is opened, no current flows through the opto-coupler diode, which pulls up the feedback voltage, commanding maximum power be delivered to the load. Since more power than the load demand is delivered, the output voltage rises until the OVP is triggered.

The worst-case OVP trip point at no load is calculated as:

$$
V_o^{OVP} = \sqrt{\left[V_{VS\_OVP} \frac{N_S}{N_A} \frac{R_{VS1} + R_{VS2}}{R_{VS2}}\right]^2 + \frac{2E_{SLRPLUS}}{C_O}} \tag{4}
$$

where E<sub>SURPLUS</sub> is the surplus energy delivered to the load during the debounce time.

The E<sub>SURPLUS</sub> can be defined as:

$$
E_{\text{SURPLUS}} = \frac{L_m}{2} \left( \frac{V_{\text{STH}}}{R_{\text{CS}}} + \frac{V_{\text{DL}}}{L_m} (t_{\text{DLY.OFF}}) \right)^2 \times 8 \tag{5}
$$

![](_page_16_Figure_9.jpeg)

#### **Leading-Edge Blanking (LEB)**

Each time the power MOSFET is switched on, a turn-on spike occurs at the sense resistor. To avoid premature termination of the switching pulse, a 150 ns leadingedge blanking time is built in. Conventional RC filtering can therefore be omitted. During this blanking period, the current-limit comparator is disabled and it cannot switch off the gate driver.

#### **Noise Immunity**

Noise from the current sense or the control signal can cause significant pulse-width jitter. While slope compensation helps alleviate these problems, further precautions should still be taken. Good placement and layout practices should be followed. Avoid long PCB traces and component leads. Locate bypass filter components near the PWM IC.

FAN302HLMY\_F117 -- mWSaver<sup>TM</sup> PWM Controller for Low Standby Power Battery-Charger Applications **FAN302HLMY\_F117 — mWSaver™ PWM Controller for Low Standby Power Battery-Charger Applications** 

# **Typical Application Circuit (Flyback Charger)**

![](_page_17_Picture_463.jpeg)

# **Features**

- High Efficiency (>71% Avg.), Meets Energy Star V2.0 Standard (Avg. 68.17%)
- Ultra-Low Standby Power Consumption, <10 mW at 230 V<sub>AC</sub> (Pin=6.3 mW for 115 V<sub>AC</sub> and Pin=7.3 mW for 230  $V_{AC}$ )
- Output Regulation:  $CV= ±5\%$ ,  $CC= ±15\%$

![](_page_17_Figure_7.jpeg)

**C3**

**C5 20pF**

**33µF**

**D5**

**IN4935**

**N<sup>A</sup>**

٢. ξ

**R7**

**91K**Ω

**R8**

**CS 1**

**HV**

**FB**

**6**

**C10**

**1nF**

**8 NC 7**

**VDD VS**

**3**

**10**Ω

**GND 4 5**

**U1**

**FAN302HLMY\_F117**

**1N4148**

**GATE 2**

**40.2K**Ω

**Figure 43.Schematic of Typical Application Circuit** 

**R9**

**1.3**Ω

**R4**

**Q1 4A/650V**

**100**Ω

**TL431**

₹

**FOD817S**

**C11 470pF**

┥┠

**C7**

**10nF R6 0**Ω

**R18**

**64.9K**Ω

**R17**

**63.4K**Ω

# **Typical Application Circuit (Continued)**

# **Transformer Specification**

- Core: EI12.5
- Bobbin: EI12.5

![](_page_18_Figure_4.jpeg)

**Figure 44.Transformer** 

**Notes:** 

- 7. W1 consists of four layers with different number of turns. The number of turns of each layer is specified in Table 1. Add one insulation tape between the second and third layers.
- 8. W2 consists of two layers with triple-insulated wire. The leads of positive and negative fly lines are 3.5 cm and 2.5 cm, respectively.
- 9. W3 is space winding in one layer.

### **Table 1. Transformer Winding Specifications**

![](_page_18_Picture_152.jpeg)

**Note:** 

10. W4 is the outermost and space winding.

![](_page_18_Picture_153.jpeg)

![](_page_19_Figure_0.jpeg)

![](_page_20_Picture_0.jpeg)

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![](_page_20_Picture_255.jpeg)

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