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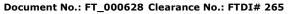
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Future Technology Devices International Ltd. FT200XD (USB I2C SLAVE IC)



The FT200XD is a USB to I²C interface • with the following advanced features:

- Single chip USB to I²C interface.
- Up to 3.4MHz, high speed mode, I²C supported
- Entire USB protocol handled on the chip. No USB specific firmware programming required.
- Fully integrated 2048 byte multi-timeprogrammable (MTP) memory storing device descriptors and CBUS I/O configuration.
- Fully integrated clock generation with no external crystal required plus optional clock output selection enabling a glue-less interface to external MCU or FPGA.
- 512 byte receive buffer and 512 byte transmit buffer utilising buffer smoothing technology to allow for high data throughput.
- FTDI's royalty-free Virtual Com Port (VCP) and Direct (D2XX) drivers eliminate the requirement for USB driver development in most cases.
- Unique USB FTDIChip-ID™ feature.
- Configurable CBUS I/O pin.
- Transmit and receive LED drive signals.
- USB Battery Charger Detection. Allows for USB peripheral devices to detect the presence of a higher power source to enable improved charging.
- Device supplied pre-programmed with unique USB serial number.

- USB Power Configurations; supports buspowered, self-powered and bus-powered with power switching.
- Integrated +3.3V level converter for USB I/O.
- True 3.3VCMOS drive output and TTL input;
 Operates down to 1V8 with external pull-ups.
 Tolerant of 5V input.
- Configurable I/O pin output drive strength; 4 mA(min) and 16 mA(max).
- Integrated power-on-reset circuit.
- Fully integrated AVCC supply filtering no external filtering required.
- + 5V Single Supply Operation.
- Internal 3V3/1V8 LDO regulators
- Low operating and USB suspend current; 8mA (active-typ) and 125uA (suspend-typ).
- UHCI/OHCI/EHCI host controller compatible.
- USB 2.0 Full Speed compatible.
- Extended operating temperature range; -40°C to +85°C.
- Available in compact Pb-free 10 Pin DFN package (3mmx3mm) (RoHS compliant).

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1 Typical Applications

- Upgrading Legacy Peripherals to USB
- Utilising USB to add system modularity
- Incorporate USB interface to enable PC transfers for development system communication
- Motherboard and system monitoring through USB
- USB dongle implementations for Software/ Hardware Encryption and Wireless Modules
- Interfacing MCU/PLD/FPGA based designs to add USB connectivity
- USB Instrumentation
- USB Industrial Control
- USB Digital Camera Interface
- Capable of detecting dedicated USB charger ports for charging batteries with high current

1.1 Driver Support

Royalty free VIRTUAL COM PORT (VCP) DRIVERS for...

- Windows 8 32-,64-bit
- Windows 7 32-,64-bit
- Windows Vista and Vista 64-bit
- Windows XP and XP 64-bit
- Windows Embedded Operating Systems
- Server 2003, XP and Server 2008
- Windows CE 4.2, 5.0 and 6.0
- Mac OS-X
- Linux 3.2 and greater
- Android OS

Royalty free D2XX *Direct* Drivers (USB Drivers + DLL S/W Interface)

- Windows 8 32-,64-bit
- Windows 7 32-,64-bit
- Windows Vista and Vista 64-bit
- Windows XP and XP 64-bit
- Windows Embedded Operating Systems
- Server 2003, XP and Server 2008
- Windows CE 4.2, 5.0 and 6.0
- Mac OS-X
- Linux 2.6 and greater
- Android OS

The drivers listed above are all available to download for free from FTDI website (www.ftdichip.com). Various 3rd party drivers are also available for other operating systems - see FTDI website(www.ftdichip.com) for details.

For driver installation, please refer to http://www.ftdichip.com/Documents/InstallGuides.htm

1.2 Part Numbers

Part Number	Package		
FT200XD-x	10 Pin DFN		

Table 1.1 Ordering part numbers

Note: Packing codes for -x is:

- R: Taped and Reel, 5,000pcs per reel

- T: Tray packing, 490pcs per tray

For example: FT200XD-R is 5,000pcs taped and reel packing



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1.3 USB Compliant

The FT200XD is fully compliant with the USB 2.0 specification and has been given the USB-IF Test-ID (TID) 40001459 (Rev D).



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2 FT200XD Block Diagram

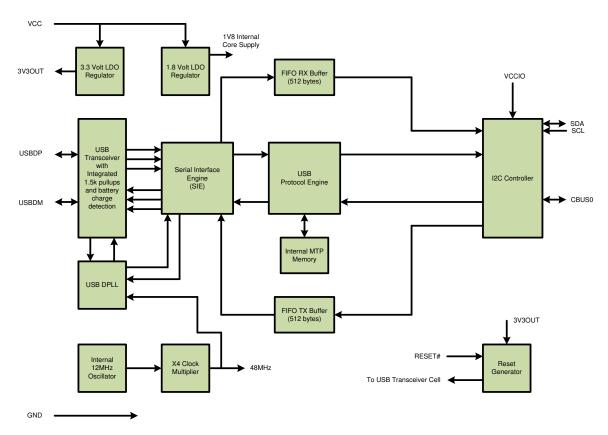


Figure 2.1FT200XD Block Diagram

For a description of each function please refer to Section 4.

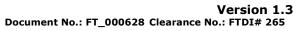




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3 Device Pin Out and Signal Description

3.1 10-LD DFN Package

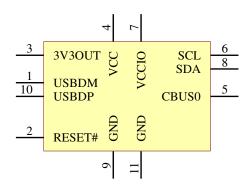


Figure 3.1 DFN Schematic Symbol

3.1.1 DFN Package Pin Out Description

Note: # denotes an active low signal.

Pin No.	Name	Туре	Description				
4	** VCC	POWER Input	5 V (or 3V3) supply to IC				
7	VCCIO	POWER Input	1V8 - 3V3 supply for the IO cells				
3	** 3V3OUT	POWER Output	3V3 output at 50mA. May be used to power VCCIO. When VCC is 3V3; pin 3 is an input pin and should be connected to pin 4.				
9	GND	POWER Input	0V Ground input.				

Table 3.1 Power and Ground

^{**} If VCC is 3V3 then 3V3OUT must also be driven with 3V3 input

Pin No.	Name	Туре	Description			
1	USBDM	INPUT	USB Data Signal Minus.			
10	USBDP	INPUT	USB Data Signal Plus.			
2	RESET#	INPUT	Reset input (active low).			

Table 3.2 Common Function pins

^{*}Pin 11 is the centre pad on the chip package base. This should be connected to GND



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Pin No.	Name	Туре	Description			
8	SDA	I/O	I ² C bi-directional data line. The signal is open drain.			
6	SCL	Input	I ² C clock input			
5	CBUS0	I/O	Configurable CBUS I/O Pin. Function of this pin is configured in the device MTP memory. See CBUS Signal Options, Table 3.4.			

Table 3.3 I²C Interface and CBUS Group (see note 1)

Note:

- 1. When used in Input Mode, the input pins are pulled to VCCIO via internal $75k\Omega$ (approx) resistors. These pins can be programmed to gently pull low during USB suspend (PWREN# = "1") by setting an option in the MTP memory.
- 2. Clock stretching is not supported

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3.2 CBUS Signal Options

The following options can be configured on the CBUS I/O pins. These options can be configured in the internal MTP memory using the software utility FT_PROG, which can be downloaded from the FTDI Utilities (www.ftdichip.com). The default configuration is noted below and described in Section 10.

CBUS Signal Option	Available On CBUS Pin	Description
TRI-STATE	CBUS0	IO Pad is tri-stated
DRIVE 1	CBUS0	Output a constant 1
DRIVE 0	CBUS0	Output a constant 0
PWREN#	CBUS0	Output is low after the device has been configured by USB, then high during USB suspend mode. This output can be used to control power to external logic P-Channel logic level MOSFET switch. Enable the interface pull-down option when using the PWREN# in this way.
SLEEP#	CBUS0	Goes low during USB suspend mode. Typically used to power down an external logic to reduce power consumption.
CLK24MHz	CBUS0	24 MHz Clock output.*
CLK12MHz	CBUS0	12 MHz Clock output.*
CLK6MHz	CBUS0	6 MHz Clock output.*
GPIO	CBUS0	CBUS bit bang mode option A separate application note, AN232R-01, available from FTDI website(www.ftdichip.com) describes in more detail how to use CBUS bit bang mode.
BCD Charger	CBUS0	Battery Charge Detect, indicates when the device is connected to a dedicated battery charger host. Active high output.
BCD Charger#	CBUS0	Inverse of BCD Charger (open drain)
BitBang_WR#	CBUS0	Synchronous and asynchronous bit bang mode WR# strobe output.
BitBang_RD#	CBUS0	Synchronous and asynchronous bit bang mode RD# strobe output.
I2C_TXE#	CBUS0	Transmit buffer empty, used to indicate to $\text{\rm I}^2\text{\rm C}$ master device status of the FT200XDtransmit buffer
I2C_RXF#	CBUS0	Receive buffer full, used to indicate to $\ensuremath{\mathrm{I}}^2\ensuremath{\mathrm{C}}$ master device status of FT200XD receive buffer
VBUS Sense	CBUS0	Input to detect when VBUS is present.
Time Stamp	CBUS0	Toggle signal which changes state each time a USB SOF is received
Keep_Awake#	CBUS0	Prevents the device from entering suspend state when unplugged. May be used if programming the MTP memory over ${\rm I}^2{\rm C}$

Table 3.4 CBUS Configuration Control

 $^{{}^{*}\}mbox{When in USB}$ suspend mode the outputs clocks are also suspended.



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4 Function Description

The FT200XD is a package and pin optimised USB to I^2C interface device which simplifies USB to I^2C designs and reduces external component count by fully integrating an external EEPROM and a clock circuit which requires no external crystal in a small form factor $3x3mm\ 10$ pin package. It has been designed to operate efficiently with a USB host controller by using as little of the total USB bandwidth available as possible.

4.1 Key Features

Functional Integration. Fully integrated MTP memory, clock generation, AVCC filtering, Power-On Reset (POR) and LDO regulators.

Configurable CBUS I/O Pin Options. The fully integrated MTP memory allows configuration of the Control Bus (CBUS) functionality and drive strength selection. There is 1 configurable CBUS I/O pin. These configurable options are defined in section 3.2.

The device is supplied with the most commonly used pin definitions pre-programmed - see Section 10 for details.

Asynchronous Bit Bang Mode with RD# and WR# Strobes. The FT200XD supports FTDI's previous chip generation bit-bang mode. In bit-bang mode, the 2 I²C lines can be switched from the regular interface mode to a 2-bit general purpose I/O port. Data packets can be sent to the device and they will be sequentially sent to the interface at a rate controlled by an internal timer (equivalent to the baud rate pre-scalar). In the FT200XD device this mode has been enhanced by outputting the internal RD# and WR# strobes signals which can be used to allow external logic to be clocked by accesses to the bit-bang I/O bus. This option will be described more fully in a separate application note available from FTDI website (www.ftdichip.com).

Synchronous Bit Bang Mode. The FT200XD supports synchronous bit bang mode. This mode differs from asynchronous bit bang mode in that the interface pins are only read when the device is written to. This makes it easier for the controlling program to measure the response to an output stimulus as the data returned is synchronous to the output data. An application note, AN232R-01, available from FTDI website(www.ftdichip.com) describes this feature.

Low Power Consumption, The FT200XD is capable of operating at a voltage supply between +3.3V and +5V with a nominal operational mode current of 8mA and a nominal USB suspend mode current of 125μ A. This allows greater margin for peripheral designs to meet the USB suspend mode current limit of 2.5mA. An integrated level converter within the I^2 C interface allows the FT200XD to interface to I^2 C logic running at +1.8V to +3.3V (5V tolerant).

4.2 Functional Block Descriptions

The following paragraphs detail each function within the FT200XD. Please refer to the block diagram shown in Figure 2.1.

Internal MTP Memory. The internal MTP memory in the FT200XD is used to store USB Vendor ID (VID), Product ID (PID), device serial number, product description string and various other USB configuration descriptors. The internal MTP memory is also used to configure the CBUS pin functions. The FT200XD is supplied with the internal MTP memory pre-programmed as described in Section10. A user area of the internal MTP memory is available to system designers to allow storing of additional data from the user application over USB. The internal MTP memory descriptors can be programmed in circuit, over USB without any additional programming voltage requirements. The descriptors can be programmed using the FTDI utility software called FT_PROG, which can be downloaded from FTDI Utilitieson the FTDI website (www.ftdichip.com). Additionally the MTP memory can be configured over the $\rm I^2C$ interface.

- **+1.8V LDO Regulator.** The +1.8V LDO regulator generates the +1.8V reference voltage for driving the internal core of the IC.
- **+3.3V LDO Regulator.** The +3.3V LDO regulator generates the +3.3V reference voltage for driving the USB transceiver cell output buffers. It requires an external decoupling capacitor to be connected to the 3V3OUT regulator output pin. It also provides +3.3V power to the $1.5k\Omega$ internal pull up resistor on USBDP. The main function of the LDO is to power the USB Transceiver and the Reset Generator Cells rather than to power external logic. However, it can be used to supply external circuitry requiring a +3.3V nominal supply with a maximum current of 50mA.

USB Transceiver. The USB Transceiver Cell provides the USB 1.1 / USB 2.0 full-speed physical interface to the USB cable. The output drivers provide +3.3V level slew rate control signalling, whilst a differential



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input receiver and two single ended input receivers provide USB data in, Single-Ended-0 (SE0) and USB reset detection conditions respectfully. This function also incorporates a $1.5 \mathrm{k}\Omega$ pull up resistor on USBDP. The block also detects when connected to a USB power supply which will not enumerate the device but still supply power and may be used for battery charging.

USB DPLL. The USB DPLL cell locks on to the incoming NRZI USB data and generates recovered clock and data signals for the Serial Interface Engine (SIE) block.

Internal 12MHz Oscillator - The Internal 12MHz Oscillator cell generates a 12MHz reference clock. This provides an input to the x4 Clock Multiplier function. The 12MHz Oscillator is also used as the reference clock for the SIE, USB Protocol Engine and UART FIFO controller blocks.

Clock Multiplier / Divider. The Clock Multiplier / Divider takes the 12MHz input from the Internal Oscillator function and generates the 48MHz, 24MHz, 12MHz and 6MHz reference clock signals. The 48MHz clock reference is used by the USB DPLL and the Baud Rate Generator blocks.

Serial Interface Engine (SIE). The Serial Interface Engine (SIE) block performs the parallel to serial and serial to parallel conversion of the USB data. In accordance with the USB 2.0 specification, it performs bit stuffing/un-stuffing and CRC5/CRC16 generation. It also checks the CRC on the USB data stream.

USB Protocol Engine. The USB Protocol Engine manages the data stream from the device USB control endpoint. It handles the low level USB protocol requests generated by the USB host controller and the commands for controlling the functional parameters of the I^2C in accordance with the USB 2.0 specification chapter 9.

FIFO RX Buffer (512 bytes). Data sent from the USB host controller to the I2C interface via the USB data OUT endpoint is stored in the FIFO RX (receive) buffer. Data is removed from the buffer to the I2C transmit register under control of the I2C Controller.(RX is relative to the USB interface).

FIFO TX Buffer (512 bytes). Data from the I²C receive register is stored in the TX buffer. The USB host controller removes data from the FIFO TX Buffer by sending a USB request for data from the device data IN endpoint.(TX is relative to the USB interface).

 I^2C Controller. Module to handle the latching in and out of serial data on the I^2C interface. Supports up to 3.4MHz, High Speed Serial Mode.

RESET Generator - The integrated Reset Generator Cell provides a reliable power-on reset to the device internal circuitry at power up. The RESET# input pin allows an external device to reset the FT200XD.

RESET# can be tied to 3V3OUT.



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5 I²C Interface Description

 I^2C (Inter Integrated Circuit) is a multi-master serial bus invented by Philips. I^2C uses two bi-directional open-drain wires called serial data (SDA) and serial clock (SCL). Common I^2C bus speeds are the 100 kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS)

An I²C bus node can operate either as a master or a slave:

- Master node issues the clock and addresses slaves
- Slave node receives the clock line and address.

The FT200XD device only operates as a slave, and is capable of speeds up to 3.4MBit/s. There are four potential modes of operation for a given bus device, although most devices only use a single role (Master or Slave) and its two modes (Transmit and Receive):

- Master transmit sending data to a slave
- Master receive receiving data from a slave
- Slave transmit sending data to a master
- Slave receive receiving data from the master

The master is initially in master transmit mode by sending a start bit followed by the 7-bit address of the slave it wishes to communicate with, which is finally followed by a single bit representing whether it wishes to write(0) to or read(1) from the slave.

If the slave exists on the bus then it will respond with an ACK bit (active low for acknowledged) for that address. The master then continues in either transmit or receive mode (according to the read/write bit it sent), and the slave continues in its complementary mode (receive or transmit, respectively).

The address and the data bytes are sent most significant bit first. The start bit is indicated by a high-to-low transition of SDA with SCL high; the stop bit is indicated by a low-to-high transition of SDA with SCL high.

If the master wishes to write to the slave then it repeatedly sends a byte with the slave sending an ACK bit. (In this situation, the master is in master transmit mode and the slave is in slave receive mode.)

If the master wishes to read from the slave then it repeatedly receives a byte from the slave, the master sends an ACK bit after every byte but the last one. (In this situation, the master is in master receive mode and the slave is in slave transmit mode.)

The master then ends transmission with a stop bit, or it may send another START bit if it wishes to retain control of the bus for another transfer (a "combined message").

I²C defines three basic types of message, each of which begins with a START and ends with a STOP:

- Single message where a master writes data to a slave;
- Single message where a master reads data from a slave;
- Combined messages, where a master issues at least two reads and/or writes to one or more slaves

In a combined message, each read or write begins with a START and the slave address. After the first START, these are also called repeated START bits; repeated START bits are not preceded by STOP bits, which is how slaves know the next transfer is part of the same message.

Please refer to the I²C specification for more information on the protocol.

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6 Devices Characteristics and Ratings

6.1 Absolute Maximum Ratings

The absolute maximum ratings for the FT200XD devices are as follows. These are in accordance with the Absolute Maximum Rating System (IEC 60134). Exceeding these may cause permanent damage to the device.

Parameter	Value	Unit	Conditions
Storage Temperature	-65°C to 150°C	Degrees C	
Floor Life (Out of Bag) At Factory Ambient (30°C / 60% Relative Humidity)	168 Hours (IPC/JEDEC J- STD-033A MSL Level 3 Compliant)*	Hours	
Ambient Operating Temperature (Power Applied)	-40°C to 85°C	Degrees C	
MTTF FT200XD	TBD	Hours	
MTTF FT200XD	TBD	Hours	
VCC Supply Voltage	-0.3 to +5.5	V	
VCCIO IO Voltage	-0.3 to +4.0	V	
DC Input Voltage – USBDP and USBDM	-0.5 to +3.63	V	
DC Input Voltage – High Impedance Bi-directionals (powered from VCCIO)	-0.3 to +5.8	V	
DC Output Current – Outputs	22	mA	

Table 6.1 Absolute Maximum Ratings

6.2 ESD and Latch-up Specifications

Description	Specification
Human Body Mode (HBM)	> ± 2kV
Machine mode (MM)	> ± 200V
Charged Device Mode (CDM)	> ± 500V
Latch-up	> ± 200mA

Table 6.2 ESD and Latch-Up Specifications

^{*} If devices are stored out of the packaging beyond this time limit the devices should be baked before use. The devices should be ramped up to a temperature of +125°C and baked for up to 17 hours.

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6.3 DC Characteristics

DC Characteristics (Ambient Temperature = -40°C to +85°C)

Parameter	Description	Minimum	Typical	Maximum	Units	Conditions
VCC	VCC Operating Supply Voltage	2.97	5	5.5	٧	Normal Operation
VCC2	VCCIO Operating Supply Voltage	1.62		3.63	٧	
Icc1	Operating Supply Current	6.8	8	9.1	mA	Normal Operation
Icc2	Operating Supply Current		125		μA	USB Suspend
3V3	3.3v regulator output	2.97	3.3	3.63	V	VCC must be greater than 3V3 otherwise 3V3OUT is an input which must be driven with 3.3V in this instance pins 3 and 4 of the package should be shorted together.

Table 6.3 Operating Voltage and Current

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Parameter	Description	Minimum	Typical	Maximum	Units	Conditions
		2.97	VCCIO	VCCIO	V	Ioh =-2mA I/O Drive strength* = 4mA
Voh	Output Voltage High	2.97	VCCIO	VCCIO	V	I/O Drive strength* = 8mA
		2.97	VCCIO	VCCIO	V	I/O Drive strength* = 12mA
		2.97	VCCIO	VCCIO	V	I/O Drive strength* = 16mA
			0	0.4	V	Iol = +2mA I/O Drive strength* = 4mA
Vol	Output Voltage Low		0	0.4	V	I/O Drive strength* = 8mA
			0	0.4	V	I/O Drive strength* = 12mA
			0	0.4	V	I/O Drive strength* = 16mA
Vil	Input low Switching Threshold			0.8	V	LVTTL
Vih	Input High Switching Threshold	2.0			V	LVTTL
Vt	Switching Threshold		1.49		V	LVTTL
Vt-	Schmitt trigger negative going threshold voltage		1.15		V	
Vt+	Schmitt trigger positive going threshold voltage		1.64		V	
Rpu	Input pull-up resistance	40	75	190	ΚΩ	Vin = 0
Rpd	Input pull-down resistance	40	75	190	ΚΩ	Vin =VCCIO
Iin	Input Leakage Current	-10	+/-1	10	μА	Vin = 0
Ioz	Tri-state output leakage current	-10	+/-1	10	μА	Vin = 5.5V or 0

Table 6.4 I/O Pin Characteristics VCCIO = +3.3V (except USB PHY pins)

* The I/O drive strength and slow slew-rate are configurable in the MTP memory.



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Parameter	Description	Minimum	Typical	Maximum	Units	Conditions
		2.25	VCCIO	VCCIO	V	Ioh = +/-2mA I/O Drive strength* = 4mA
Voh	Output Voltage High	2.25	VCCIO	VCCIO	V	I/O Drive strength* = 8mA
		2.25	VCCIO	VCCIO	V	I/O Drive strength* = 12mA
		2.25	VCCIO	VCCIO	V	I/O Drive strength* = 16mA
			0	0.4	V	Iol = +/-2mA I/O Drive strength* = 4mA
Vol	Output Voltage Low		0	0.4	V	I/O Drive strength* = 8mA
			0	0.4	V	I/O Drive strength* = 12mA
			0	0.4	V	I/O Drive strength* = 16mA
Vil	Input low Switching Threshold			0.8	V	LVTTL
Vih	Input High Switching Threshold	0.8			V	LVTTL
Vt	Switching Threshold		1.1		V	LVTTL
Vt-	Schmitt trigger negative going threshold voltage		0.8		V	
Vt+	Schmitt trigger positive going threshold voltage		1.2		V	
Rpu	Input pull-up resistance	40	75	190	ΚΩ	Vin = 0
Rpd	Input pull-down resistance	40	75	190	ΚΩ	Vin =VCCIO
Iin	Input Leakage Current	-10	+/-1	10	μА	Vin = 0
Ioz	Tri-state output leakage current	-10	+/-1	10	μА	Vin = 5.5V or 0

Table 6.5 I/O Pin Characteristics VCCIO = +2.5V (except USB PHY pins)

* The I/O drive strength and slow slew-rate are configurable in the MTP memory.

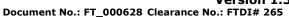


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Parameter	Description	Minimum	Typical	Maximum	Units	Conditions
Voh	Output Voltage High	1.62	VCCIO	VCCIO	V	Ioh = +/-2mA I/O Drive strength* = 4mA
		1.62	VCCIO	VCCIO	V	I/O Drive strength* = 8mA
		1.62	VCCIO	VCCIO	V	I/O Drive strength* = 12mA
		1.62	VCCIO	VCCIO	V	I/O Drive strength* = 16mA
Vol	Output Voltage Low		0	0.4	V	Iol = +/-2mA I/O Drive strength* = 4mA
			0	0.4	V	I/O Drive strength* = 8mA
			0	0.4	V	I/O Drive strength* = 12mA
			0	0.4	V	I/O Drive strength* = 16mA
Vil	Input low Switching Threshold			0.77	V	LVTTL
Vih	Input High Switching Threshold	1.6			V	LVTTL
Vt	Switching Threshold		0.77		V	LVTTL
Vt-	Schmitt trigger negative going threshold voltage		0.557		V	
Vt+	Schmitt trigger positive going threshold voltage		0.893		V	
Rpu	Input pull-up resistance	40	75	190	ΚΩ	Vin = 0
Rpd	Input pull-down resistance	40	75	190	ΚΩ	Vin =VCCIO
Iin	Input Leakage Current	-10	+/-1	10	μΑ	Vin = 0
Ioz	Tri-state output leakage current	-10	+/-1	10	μА	Vin = 5.5V or 0

Table 6.6 I/O Pin Characteristics VCCIO = +1.8V (except USB PHY pins)

* The I/O drive strength and slow slew-rate are configurable in the MTP memory.





Parameter	Description	Minimum	Typical	Maximum	Units	Conditions
Voh	Output Voltage High	VCC-0.2			V	
Vol	Output Voltage Low			0.2	V	
Vil	Input low Switching Threshold		-	0.8	V	
Vih	Input High Switching Threshold	2.0	-		V	

Table 6.7 USB I/O Pin (USBDP, USBDM) Characteristics

6.4 MTP Memory Reliability Characteristics

The internal 2048 Byte MTP Memory has the following reliability characteristics:

Parameter	Value	Unit
Data Retention	10	Years
Write Cycle	2,000 minimum	Cycles
Read Cycle	Unlimited	Cycles

Table 6.8 MTP Memory Characteristics

6.5 Internal Clock Characteristics

The internal Clock Oscillator has the following characteristics:

Parameter		Unit			
r urumeter	Minimum	Typical	Maximum	S.III.C	
Frequency of Operation (see Note 1)	11.98	12.00	12.02	MHz	
Clock Period	83.19	83.33	83.47	ns	
Duty Cycle	45	50	55	%	

Table 6.9 Internal Clock Characteristics

Note 1: Equivalent to +/-1667ppm

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7 USB Power Configurations

The following sections illustrate possible USB power configurations for the FT200XD.

7.1 USB Bus Powered Configuration

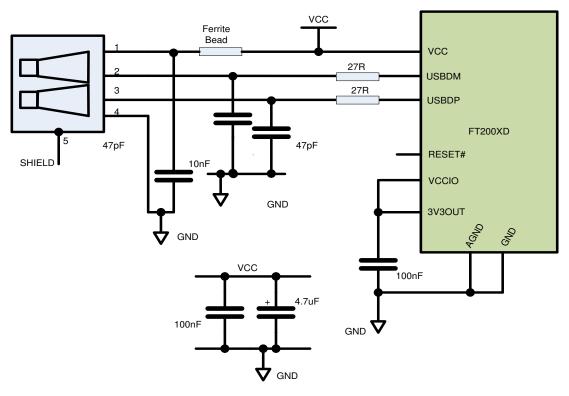


Figure 7.1 Bus Powered Configuration

Figure 7.1Illustrates the FT200XD in a typical USB bus powered design configuration. A USB bus powered device gets its power from the USB bus. Basic rules for USB bus power devices are as follows –

- i) On plug-in to USB, the device must draw no more current than 100mA.
- ii) In USB Suspend mode the device must draw no more than 2.5mA.
- A bus powered high power USB device (one that draws more than 100mA) should use the CBUS pins configured as PWREN# and use it to keep the current below 100mA on plug-in and 2.5mA on USB suspend. Using the CBUS pin for PWREN# prevents the FT200XD from indicating a USB Battery Charger is connected.
- iv) A device that consumes more than 100mA cannot be plugged into a USB bus powered hub.
- v) No device can draw more than 500mA from the USB bus.

The power descriptors in the internal MTP Memory of the FT200XDmustbe programmed to match the current drawn by the device.

A ferrite bead is connected in series with the USB power supply to reduce EMI noise from the FT200XD and associated circuitry being radiated down the USB cable to the USB host. The value of the Ferrite Bead depends on the total current drawn by the application. A suitable range of Ferrite Beads is available from Laird Technologies (http://www.lairdtech.com), for example Laird Technologies Part # MI0805K601R-10.

Note: If using PWREN# (available using the CBUS) the pin must be pulled to VCCIO using a $10k\Omega$ resistor.

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7.2 Self Powered Configuration

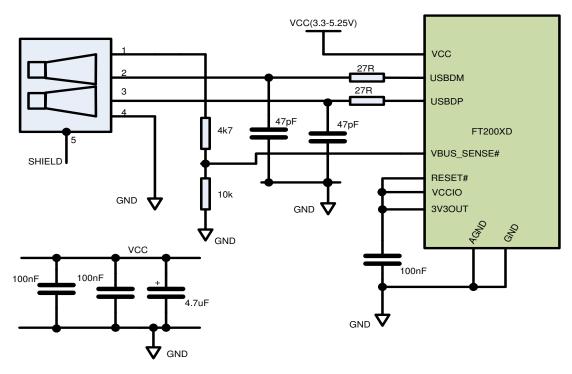


Figure 7.2 Self Powered Configuration

Figure 7.2 illustrates the FT200XD in a typical USB self powered configuration. A USB self powered device gets its power from its own power supply, VCC, and does not draw current from the USB bus. The basic rules for USB self powered devices are as follows –

- i) A self powered device must not force current down the USB bus when the USB host or hub controller is powered down.
- ii) A self powered device can use as much current as it needs during normal operation and USB suspend as it has its own power supply.
- iii) A self powered device can be used with any USB host, a bus powered USB hub or a self powered USB hub.

The power descriptor in the internal MTP memory of the FT200XD should be programmed to a value of zero (self powered).

In order to comply with the first requirement above, the USB bus power (pin 1) is used to control the VBUS_Sense pin of the FT200XD device. When the USB host or hub is powered up an internal $1.5k\Omega$ resistor on USBDP is pulled up to +3.3V, thus identifying the device as a full speed device to the USB host or hub. When the USB host or hub is powered off, VBUS_Sense pin will be low and the FT200XDis held in a suspend state. In this state the internal $1.5k\Omega$ resistor is not pulled up to any power supply (hub or host is powered down), so no current flows down USBDP via the $1.5k\Omega$ pull-up resistor. Failure to do this may cause some USB host or hub controllers to power up erratically.

Figure 7.2 illustrates a self powered design which has a +3.3V to +5.25V supply.

Note:

1. When the FT200XD is in reset, the interface I/O pins are tri-stated. Input pins have internal $200k\Omega$ pull-up resistors to VCCIO, so they will gently pull high unless driven by some external logic.

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7.3 USB Bus Powered with Power Switching Configuration

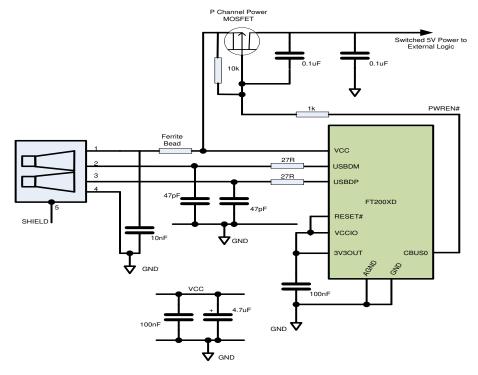


Figure 7.3 Bus Powered with Power Switching Configuration

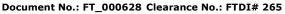
A requirement of USB bus powered applications, is when in USB suspend mode, the application draws a total current of less than 2.5mA. This requirement includes external logic. Some external logic has the ability to power itself down into a low current state by monitoring the PWREN# signal. For external logic that cannot power itself down in this way, the FT200XD provides a simple but effective method of turning off power during the USB suspend mode.

Figure 7.3 shows an example of using a discrete P-Channel MOSFET to control the power to external logic. A suitable device to do this is an International Rectifier (www.irf.com) IRLML6402, or equivalent. It is recommended that a "soft start" circuit consisting of a $1k\Omega$ series resistor and a $0.1\mu\text{F}$ capacitor is used to limit the current surge when the MOSFET turns on. Without the soft start circuit it is possible that the transient power surge, caused when the MOSFET switches on, will reset the FT200XD or the USB host/hub controller. The soft start circuit example shown in Figure 7.3 powers up with a slew rate of approximaely12.5V/ms. Thus supply voltage to external logic transitions from GND to +5V in approximately 400 microseconds.

As an alternative to the MOSFET, a dedicated power switch IC with inbuilt "soft-start" can be used. A suitable power switch IC for such an application is the Micrel (www.micrel.com) MIC2025-2BM or equivalent.

With power switching controlled designs the following should be noted:

- i) The external logic to which the power is being switched should have its own reset circuitry to automatically reset the logic when power is re-applied when moving out of suspend mode.
- ii) Set the Pull-down on Suspend option in the internal FT200XD MTP memory.
- iii) The CBUS Pin should be configured as PWREN# in the internal FT200XD MTP memory, and used to switch the power supply to the external circuitry. Detection of a USB battery charger port is not possible.
- iv) For USB high-power bus powered applications (one that consumes greater than 100mA, and up to 500mA of current from the USB bus), the power consumption of the application must be set in the Max Power field in the internal FT200XD MTP memory. A high-power bus powered application uses the descriptor in the internal FT200XD MTP memory to inform the system of its power requirements.
- v) PWREN# gets its VCC from VCCIO. For designs using 3V3 logic, ensure VCCIO is not powered down using the external logic. In this case use the +3V3OUT.





8 Application Examples

The following sections illustrate possible applications of the FT200XD.

8.1 USB to I²C Converter

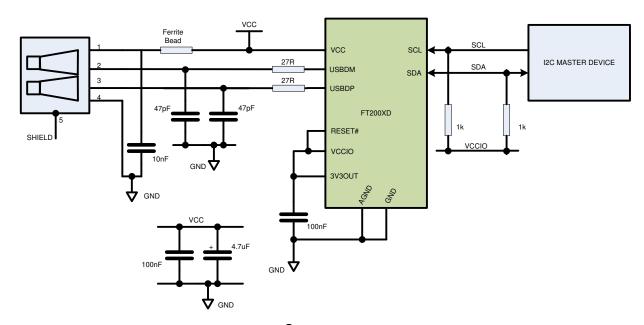


Figure 8.1 Application Example showing USB to I²C Converter

An example of using the FT200XD as an I^2 C peripheral is shown in Figure 8.1. The FT200XD is the slave on the I^2 C bus.

Therefore the clock supplied to the SCL pin must come from the I^2C Master. The device will support standard I^2C data rates such as 100 kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS).

The data line SDA is bi-directional.

The master is initially in master transmit mode by sending a start bit followed by the 7-bit address of the slave it wishes to communicate with, which is finally followed by a single bit representing whether it wishes to write(0) to or read(1) from the slave.

If the slave (FT200XD) exists on the bus then it will respond with an ACK bit (active low for acknowledged) for that address. The master then continues in either transmit or receive mode (according to the read/write bit it sent), and the slave continues in its complementary mode (receive or transmit, respectively).

The address and the data bytes are sent most significant bit first. The start bit is indicated by a high-to-low transition of SDA with SCL high; the stop bit is indicated by a low-to-high transition of SDA with SCL high.

If the master wishes to write to the slave then it repeatedly sends a byte with the slave sending an ACK bit. (In this situation, the master is in master transmit mode and the slave is in slave receive mode.)

If the master wishes to read from the slave then it repeatedly receives a byte from the slave, the master sending an ACK bit after every byte but the last one. (In this situation, the master is in master receive mode and the slave is in slave transmit mode.)

The master then ends transmission with a stop bit, or it may send another START bit if it wishes to retain control of the bus for another transfer (a "combined message").

I²C defines three basic types of message, each of which begins with a START and ends with a STOP:

- Single message where a master writes data to a slave;
- Single message where a master reads data from a slave;

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 Combined messages, where a master issues at least two reads and/or writes to one or more slaves

In a combined message, each read or write begins with a START and the slave address. After the first START, these are also called repeated START bits; repeated START bits are not preceded by STOP bits, which is how slaves know the next transfer is part of the same message.

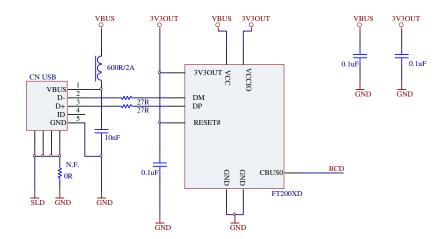
The I²C address of the FT200XD is stored in the device internal MTP memory.

Please refer to the 1²C specification for more information on the protocol.

8.2 USB Battery Charging Detection

A recent addition to the USB specification

(http://www.usb.org/developers/devclass docs/BCv1.2 011912.zip) is to allow for additional charging profiles to be used for charging batteries in portable devices. These charging profiles do not enumerate the USB port of the peripheral. The FT200XD device will detect that a USB compliant dedicated charging port (DCP) is connected. Once detected while in suspend mode a battery charge detection signal is provided to allow external logic to switch to charging mode as opposed to operation mode.



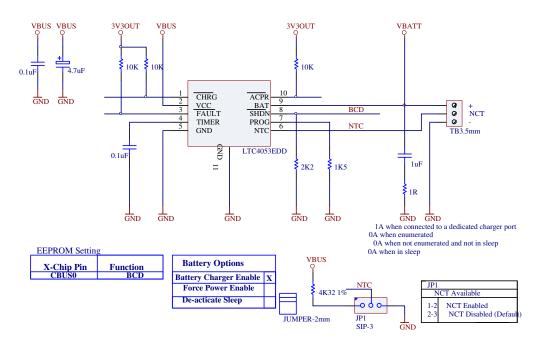


Figure 8.2 USB Battery Charging Detection

To use the FT200XD with battery charging detection the CBUS pins must be reprogrammed to allow for the BCD Charger output to switch the external charger circuitry on. The CBUS pins are configured in the



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internal MTP memory with the free utility FTPROG. If the charging circuitry requires an active low signal to enable it, the CBUS pin can be programmed to BCD Charger# as an alternative.

When connected to a USB compliant dedicated charging port (DCP, as opposed to a standard USB host) the device USB signals will be shorted together and the device suspended. The BCD charger signal will bring the LTC4053 out of suspend and allow battery charging to start. The charge current in the example above is 1A as defined by the resistance on the PROG pin.

To calculate the equivalent resistance on the PROG pin select a charge current, then Res = $1500V/I_{chg}$ For more configuration options of the LTC4053 refer to:

AN_175_Battery Charging Over USB

Note: If the FT200XD is connected to a standard host port such that the device is enumerated the battery charge detection signal is inactive as the device will not be in suspend.



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9 USB and I²C Interfacing

This section covers the transfer of data from USB to I²C and vice versa.

Please note that the FT200XD and FT201X are I^2C slave devices only and should be interfaced to an I^2C host (often in a microcontroller or FPGA). If an I^2C master is required, please see the FT232H, FT2232H, FT4232H and FT2232D devices.

This section covers transfer of data only. The USB and I^2C interfaces on the FT200XD and FT201X can also be used for programming of the MTP memory, which is covered in a separate section.

Throughout this section, the reference FT-X applies to the FT200XD and FT201X devices, as the other members of the FT-X family do not have I^2C interfaces.

9.1 Host Interface (USB)

From the host computer's point of view, the I^2C data can be sent and received in the same way as when interfacing to one of the standard UART devices such as the FT232R. The FT-X handles the entire I^2C protocol inside the chip and so reading and writing data does not require any special programming from the PC side. It can be treated as a simple data bridge.

9.1.1 VCP and D2xx Interfaces

Like the other FTDI devices, the host can use D2xx commands or can use a Virtual COM Port (VCP) to communicate with the device.

D2xx Interface

The D2xx method allows the application software to use the functions in the FTDI D2xx library to communicate directly with the device. This is a library provided free-of-charge by FTDI and is available within the driver download files at the link below.

http://www.ftdichip.com/Drivers/D2XX.htm

It includes functions to find the FTDI devices on the system, open a particular device, send data to the device and read data from the device. Any data written using FT_Write, for example, will be sent to the FT-X chip and will be available for the external I^2C Master to read. As mentioned above, only the data itself needs to be sent as the FT-X handles all of the I^2C specific protocol.

There are many other functions available, and full details can be found in the D2xx Programmers Guide.

http://www.ftdichip.com/Support/Documents/ProgramGuides/D2XX_Programmer's_Guide(FT_000071).pd f

Virtual COM Port Interface

If using the Virtual Com Port (VCP), the device will appear as if it were a real COM port on the computer. This is useful where an application has already been written to use an RS232 port on the computer as it allows that application to treat the FT-X as if it were a real COM port. This port can be opened in a terminal program or a custom application in the same way as a serial port would be opened. Data can then be sent or received using standard serial / COM port functions.

No I^2C decoding is required as the chip itself handles the I^2C protocol. Because of this, even I^2C versions of the FT-X family can be used with the VCP interface. Any data which the host PC sends to the Virtual COM Port (for example, typed into the terminal window in HyperTerminal) will be sent over USB to the FT-X and can then be read by the external I^2C Master. Likewise, any data written to the FT-X over I^2C will be sent to the PC where the terminal program will display it.

Since the FT-X is the I^2C slave and does not generate a clock signal, the settings such as baud rate and handshaking do not have any effect.