imall

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TDFN



SO8

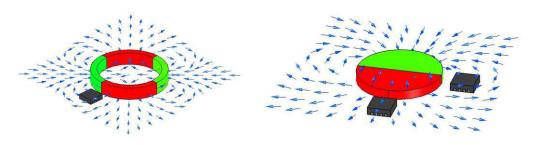
KMT32B

Magnetic Angle Sensor

SPECIFICATIONS

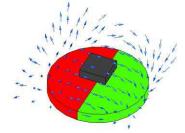
- AMR Sensor with 180° period
- high accuracy
- high resolution
- for the use at moderate field strengths
- tiny TDFN package
- ROHS & REACH compliant

The KMT32B is a magnetic field sensor based on the anisotropic magneto resistance effect, i.e. it is sensing the **magnetic field direction** independently on the magnetic field strength for applied field strengths H>25 kA/m. The sensor contains two parallel supplied Wheatstone bridges, which enclose a sensitive angle of 45 degrees.



A rotating magnetic field in the surface parallel to the chip (x-y plane) will therefore deliver two independent sinusoidal output signals, one following a $\cos(2\alpha)$ and the second following a $\sin(2\alpha)$ function, α being the angle between sensor and field direction (see Figure 2).

The KMT32B magnetic field sensor is suited for high precision angle measurement applications at a regular field strength of H₀ \ge 25 kA/m (generated for example with magnet 67.044 from Magnetfabrik Bonn at a distance of 5.2 mm at room temperature). With reduced accuracy, the sensor KMT32B may be used with a field strength of H₀ \ge 14 kA/m (at room temperature; be aware of the influence of the earth magnetic field!). Most magnets show a decreasing field strength with temperature while the magnetic field direction is unchanged.



FEATURES

- Contactless angular position, ideal for harsh environments
- Design optimized for linearity
- High accuracy
- Low cost, low power
- Self diagnosis feature
- Attractive SMD packages
- User has complete control over signal evaluation
- Extended operating temperature range (-40 °C to +150 °C, +160°C on request)
- REACH & RoHS compliant (lead free)

APPLICATIONS

- Absolute and incremental angle measurement
- Automotive (steering angle, torque)
- Robotics
- Camera positioning
- Potentiometer replacement
- Position measurement in medical applications
- Motor motion control

CHARACTERISTIC VALUES

Parameter	Symbol	Condition	Min	Тур	Мах	Unit
A. Operating Limits						
Max. supply voltage	Vcc,max				10	V
Max. current (single bridge)	Icc,max				4	mA
Operating temperature	T _{op}		-40		+150	°C
Storage temperature	T _{st}		-40		+150	°C
B. Sensor Specifications (T=	25 °C)					
Supply voltage	Vcc			5		V
Resistance (single bridge)	Rb		2400	3000	3600	Ω
Output signal amplitude	VPEAK	Condition A, B	9	11	13	mV/V
Offset voltage	Voff	Condition A, B	-1	0	+1	mV/V
Angular inaccuracy	Δα	Condition A, B		0.05	0.2	deg
Angular hysteresis	ΔαΗ	Condition A, B			0.1	deg
C. Sensor Specifications						
TC of amplitude	TCSV	Condition A, C		-0.35		%/K
TC of resistance	TCBR	Condition A, C		+0.35		%/K
TC of offset	TCVoff	Condition A, C	-4	0	+4	μV/V/K

Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

MEASUREMENT CONDITIONS

Parameter	Symbol	Unit	Condition	
Condition A: Set Up Conditions				
Ambient temperature	Т	°C	T = 25 °C (unless otherwise noted)	
Supply voltage	Vcc	V	Vcc = 5 V	
Applied magnetic field	Н	kA/m	H = 25 kA/m	

Condition B: Sensor Specifications (360° turn , Vo _{max} >0, Vo _{min} <0)				
Output signal amplitude	VPEAK	mV/V	V _{PEAK} = (Vo _{max} - Vo _{min})/2/Vcc	
Offset voltage	V _{OFF}	mV/V	V _{OFF} = (V _{Omax} + V _{Omin})/2/Vcc	
Angular inaccuracy	Δα	deg	$\Delta \alpha = MAX \alpha_0 - \alpha $; max. angular difference between actual field angle α_0 and measured angle α due to deviations from ideal sinusoidal characteristics, calculated from the third and fifth harmonics of the Fourier spectrum; offset voltage error contributions not included	
Angular hysteresis	ΔαΗ	deg	$\Delta \alpha H = \alpha_{left turn} - \alpha_{right turn} $ angular difference between left and right turn	

MEASUREMENT CONDITIONS

Parameter	Symbol	Unit	Condition				
Condition C: Sensor Specif	Condition C: Sensor Specifications (-25°C, +125°C)						
Ambient temperatures	Т	°C	$T_1 = -25 \ ^{\circ}C, T_0 = +25 \ ^{\circ}C, T_2 = +125 \ ^{\circ}C$				
TC of amplitude	TCSV	%/K	$TCV = \frac{1}{(T_2 - T_1)} \cdot \frac{\frac{\Delta Vn}{Vcc}(T_2) - \frac{\Delta Vn}{Vcc}(T_1)}{\frac{\Delta Vn}{Vcc}(T_1)} \cdot 100\%$				
TC of resistance	TCBR	%/K	$TCR = \frac{1}{(T_2 - T_1)} \cdot \frac{R(T_2) - R(T_1)}{R(T_1)} \cdot 100\%$				
TC of offset	TCVoff	(μV/V)/ Κ	$TCVoff = \frac{Voff(T_2) - Voff(T_1)}{(T_2 - T_1)}$				

BLOCK DIAGRAM

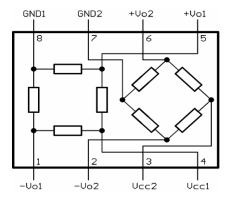


Figure 1: Circuit Diagram

TYPICAL PERFORMANCE CURVES

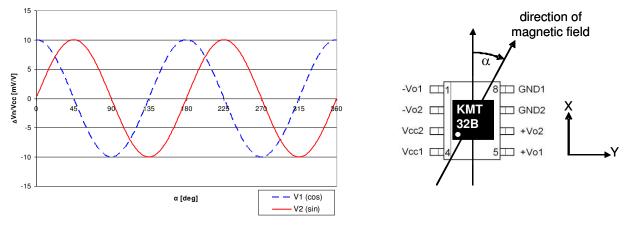
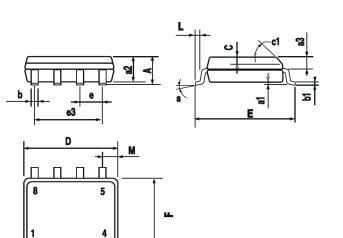


Figure 2: Characteristic curves for KMT32B (SO8, TDFN)

PACKAGES

SO8

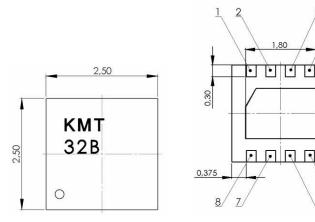


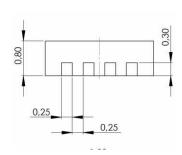
DIM.		mm		inch			
Dina.	MIN. TYP.		MAX.	MIN.	TYP.	MAX.	
А			1.75			0.069	
a1	0.1		0.25	0.004		0.010	
a2			1.65			0.065	
a3	0.65		0.85	0.026		0.033	
b	0.35		0.48	0.014		0.019	
b1	0.19		0.25	0.007		0.010	
С	0.25		0.5	0.010		0.020	
c1	45° (typ.)						
D (1)	4.8		5.0	0.189		0.197	
Е	5.8		6.2	0.228		0.244	
е		1.27			0.050		
e3		3.81			0.150		
F (1)	3.8		4.0	0.15		0.157	
L	0.4		1.27	0.016		0.050	
М			0.6			0.024	
s	8° (max.)						

Π

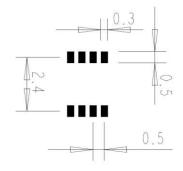
TDFN 2.5*2.5

unit: mm





RECOMMENDED SOLDER PAD LAYOUT FOR TDFN



PIN ASSIGNMENT (SO8, TDFN)

Pin (SO8)	Pin (TDFN)	Symbol	Function	
1	7	-V ₀₁	negative output bridge 1	
2	8	-V ₀₂	negative output bridge 2	
3	1	V _{cc2}	positive supply voltage bridge 2	
4	2	V _{cc1}	positive supply voltage bridge 1	
5	3	+V ₀₁	+V _{o1} positive output bridge 1	
6	4	+V ₀₂	positive output bridge 2	
7	5	GND ₂	negative supply voltage bridge 2	
8	6	GND ₁	negative supply voltage bridge 1	

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0.60

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SOLDER PROFILE

Recommended solder reflow process according to IPC/JEDEC J-STD-020D (Pb-Free Process)

TAPE AND REEL PACKAGING INFORMATION

Description	Reel size	Units/reel	Pin 1 orientation	Note
KMT32B/TD	7"	3,000	Top-right of sprocket hole side	
KMT32B/SO	13"	2,500	Top-left of sprocket hole side	

ORDERING CODE

Device	Package	MOQ	Part Number
KMT 32B/SO	SO-8	1 reel	G-MRCO-015
KMT 32B/TD	TDFN 2.5 x 2.5	1 reel	G-MRCO-016

ORDERING INFORMATION

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