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## GP1A35RV

## Features

1. 2-phase (A, B) digital output
2. High sensing accuracy
(Disk slit pitch: 0.22 mm , Moire stripe application )
3. TTL compatible output
4. Compact and light

## Applications

1. Copiers
2. Electronic typewriters, printers
3. Numerical control machines

High Sensing Accuracy OPIC Photointerrupter with Encoder Functions

■ Outline Dimensions
(Unit: mm )

*" OPIC" (Optical IC) is a trademark of the SHARP Corporation. An OPIC consists of a light-detecting element and signalprocessing circuit integrated onto a single chip.

■ Absolute Maximum Ratings
$\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

|  | Parameter | Symbol | Rating | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Input | Forward current | $\mathrm{I}_{\mathrm{F}}$ | 65 | mA |
|  | ${ }^{*}$ Peak forward current | $\mathrm{I}_{\mathrm{FM}}$ | 1 | A |
|  | Reverse voltage | $\mathrm{V}_{\mathrm{R}}$ | 6 | V |
|  | Power dissipation | P | 100 | mW |
| Output | Supply voltage | $\mathrm{V}_{\text {cC }}$ | 7 | V |
|  | Low level output current | Iol | 20 | mA |
|  | Power dissipation | $\mathrm{P}_{0}$ | 250 | mW |
| Operating temperature |  | $\mathrm{T}_{\text {opr }}$ | 0 to +70 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature |  | $\mathrm{T}_{\text {stg }}$ | -40 to +80 | ${ }^{\circ} \mathrm{C}$ |
| ${ }^{* 2}$ Soldering temperature |  | $\mathrm{T}_{\text {sol }}$ | 260 | ${ }^{\circ} \mathrm{C}$ |

*1 Pulse width $<=100 \mu \mathrm{~s}$, Duty ratio $=0.01$
*2 For 5 seconds

Electro-optical Characteristics
$\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| Parameter |  |  |  | Symbol | Conditions | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input | Forward voltage |  |  | $V_{\text {F }}$ | $\mathrm{IF}_{\mathrm{F}}=30 \mathrm{~mA}$ | - | 1.2 | 1.5 | V |
|  | Reverse current |  |  | $\mathrm{I}_{\mathrm{R}}$ | $\mathrm{V}_{\mathrm{R}}=3 \mathrm{~V}$ | - | - | 10 | $\mu \mathrm{A}$ |
| Output | Output voltage | Phase A | High level | $\mathrm{V}_{\text {AH }}$ | $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{F}}=30 \mathrm{~mA}$ | 2.4 | 4.9 | - | V |
|  |  |  | Low level | $\mathrm{V}_{\text {AL }}$ | $\mathrm{IoL}=8 \mathrm{~mA}, \mathrm{IF}=30 \mathrm{~mA}, \mathrm{~V}_{\mathrm{cc}}=5 \mathrm{~V}$ | - | 0.1 | 0.4 |  |
|  |  | Phase B | High level | $\mathrm{V}_{\text {BH }}$ | $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}, \mathrm{I} \mathrm{F}=30 \mathrm{~mA}$ | 2.4 | 4.9 | - |  |
|  |  |  | Low level | $\mathrm{V}_{\text {вL }}$ | $\mathrm{IoL}=8 \mathrm{~mA}, \mathrm{I} \mathrm{F}=30 \mathrm{~mA}, \mathrm{~V}$ cc $=5 \mathrm{~V}$ | - | 0.1 | 0.4 |  |
|  | Dissipation current |  |  | ICC | ${ }^{*}{ }^{3} \mathrm{~V}$ CC $=5 \mathrm{~V}, \mathrm{I}_{\mathrm{F}}=30 \mathrm{~mA}$ | - | 5 | 20 | mA |
| Transfer characteristics | Duty ratio |  |  | ${ }^{* 4} \Delta_{\text {A }}$ | $\begin{gathered} \mathrm{I}_{\mathrm{F}}=30 \mathrm{~mA} \\ { }^{*} \mathrm{f} \mathrm{f}=12 \mathrm{kHz} \\ \mathrm{~V}_{\mathrm{CC}}=5 \mathrm{~V} \\ \hline \end{gathered}$ | 30 | 50 | 70 | \% |
|  |  |  |  | ${ }^{*} \Delta^{4} \mathrm{~B}_{\mathrm{B}}$ |  |  |  |  |  |
|  | Phase difference |  |  | ${ }^{* 5} \theta_{\text {AB1 }}$ |  | 50 | 90 | 130 | deg. |
|  | Response speed |  |  | $\mathrm{t}_{\mathrm{r}}$ | $\begin{aligned} \mathrm{I}_{\mathrm{F}} & =30 \mathrm{~mA}, \mathrm{~V}_{\mathrm{CC}}=5 \mathrm{~V} \\ { }^{6} \mathrm{f} & =12 \mathrm{kHz} \end{aligned}$ | - | 1.0 | 2.0 | $\mu \mathrm{s}$ |
|  |  |  |  | $\mathrm{tf}_{\mathrm{f}}$ |  | - | 1.0 | 2.0 |  |

*3 In the condition that output A and B are low level.
$* 5 \theta_{\mathrm{AB} 1}=\frac{\mathrm{t}_{\mathrm{AB} 1}}{\mathrm{t}_{\mathrm{AP}}} \times 360^{\circ}$
$* 4 \Delta_{\mathrm{A}}=\frac{\mathrm{t}_{\mathrm{AH}}}{\mathrm{t}_{\mathrm{AP}}} \times 100, \Delta_{\mathrm{B}}=\frac{\mathrm{t}_{\mathrm{BH}}}{\mathrm{t}_{\mathrm{BP}}} \times 100$
*6 Measured under the condition shown in Measurement Conditions.

## Output Waveforms



Fig. 1 Forward Current vs. Ambient Temperature


Fig. 2 Output Power Dissipation vs. Ambient Temperature


Fig. 3 Duty Ratio vs. Frequency


Fig. 5 Duty Ratio vs. Ambient Temperature


Fig. 7 Duty Ratio vs. Distance (Xdirection)


Fig. 4 Phase Difference vs. Frequency


Fig. 6 Phase Difference vs. Ambient Temperature


Fig. 8 Phase Difference vs.


Distance X ( mm ) (Shifting encoder)

Fig. 9 Duty Ratio vs. Distance (Ydirection)


Fig. 11 Duty Ratio vs. Distance (Zdirection)


Fig. 10 Phase Difference vs. Distance (Ydirection)


Fig. 12 Phase Difference vs. Distance (Zdirection)


## Measurement Conditions



Note 1) Distance between disk surface and case surface in the detector side is 0.3 mm .
2) Encoder positioning pin is positioned on $X-X^{\prime}$ axis.

Distance between center of disk and portion A of positioning pin is 12.86 mm .
3) Center of disk slit is R14.0.

## - Precautions for Use

(1) This module is designed to be operated at $I_{F}=30 \mathrm{~mA}$ TYP.
(2) Fixing torque : MAX. $0.6 \mathrm{~N} \cdot \mathrm{~m}$
(3) In order to stabilize power supply line, connect a by-pass capacitor of more than $0.01 \mu \mathrm{~F}$ between Vcc and GND near the device.
(4) As for other general cautions, refer to the chapter "Precautions for Use".

Application Circuit (Detection of Rotational Direction)


When gate delay causes pulse noise in Q4 output, apply the CR filter to remove pulse noise.

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