imall

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GP1A35RV

Features

- 1. 2-phase (A, B) digital output
- 2. High sensing accuracy
- (Disk slit pitch: 0.22mm, Moire stripe application)
- 3. TTL compatible output
- 4. Compact and light

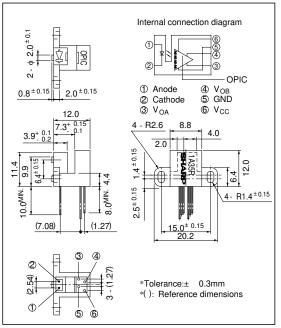
Applications

- 1. Copiers
- 2. Electronic typewriters, printers
- 3. Numerical control machines

High Sensing Accuracy OPIC Photointerrupter with Encoder Functions

Outline Dimensions

(Unit: mm)



*" OPIC" (Optical IC) is a trademark of the SHARP Corporation. An OPIC consists of a light-detecting element and signalprocessing circuit integrated onto a single chip.

■ Absolute Maximum Ratings

(Ta= 25°C)

			((14-25-6)		
	Parameter	Symbol	Rating	Unit		
	Forward current	I_F	65	mA		
T (*1Peak forward current	I _{FM}	1	A		
Input	Reverse voltage	VR	6	V		
	Power dissipation	Р	100	mW		
	Supply voltage	Vcc	7	V		
Output	Low level output current	I _{OL}	20	mA		
Γ	Power dissipation	Po	250	mW		
Operating temperature		Topr	0 to + 70	°C		
Storage tem	perature	Tstg	- 40 to + 80	°C		
*2 Soldering temperature		T _{sol}	260	°C		

*1 Pulse width<=100 μ s, Duty ratio= 0.01

*2 For 5 seconds

" In the absence of confirmation by device specification sheets, SHARP takes no responsibility for any defects that occur in equipment using any of SHARP's devices, shown in catalogs, data books, etc. Contact SHARP in order to obtain the latest version of the device specification sheets before using any SHARP's device."

■ Electro-optical Characteristics (Ta= 25°C								
Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit		
Forward voltage	VE	$I_{\rm F}=30\rm{mA}$	-	1.2	1.5	V		

T drameter		bymoor	Conditions	ivin (.	111.	101/121.	Unit		
Input	Forward voltage		VF	I _F = 30mA	-	1.2	1.5	V	
	Reverse current		IR	V _R = 3V	-	-	10	μΑ	
Output	Output voltage	Phase A	High level	V AH	V _{CC} = 5V, I _F = 30mA	2.4	4.9	-	v
			Low level	V AL	$I_{OL} = 8mA, I_F = 30mA, V_{CC} = 5V$	-	0.1	0.4	
		Phase B	High level	V BH	$V_{CC}=5V, I_{F}=30mA$	2.4	4.9	-	
			Low level	V BL	I_{OL} = 8mA, I F= 30mA, V _{CC} = 5V	-	0.1	0.4	
	Dissipation current			Icc	$^{*3}V_{CC} = 5V, I_F = 30mA$	-	5	20	mA
Transfer charac- teristics	Duty ratio		$^{*4}\Delta_A$	$I_F = 30 \text{mA}$	30	50	70	%	
			$^{*4}\Delta_{\rm B}$	*6 f= 12kHz					
	Phase difference			$^{*5} \theta_{AB1}$	$V_{CC}=5V$	50	90	130	deg.
	Response speed		tr	$I_{F}= 30 \text{mA}, V_{CC}= 5 \text{V}$	-	1.0	2.0		
			tf	*6 f= 12kHz	-	1.0	2.0	μs	

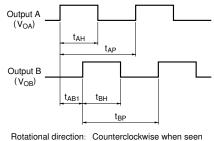
*3 In the condition that output A and B are low level.

*4 $\Delta_{A} = \frac{t_{AH}}{t_{AP}} \times 100$, $\Delta_{B} = \frac{t_{BH}}{t_{BP}} \times 100$

*5 $\theta_{AB1} = \frac{t_{AB1}}{t_{AP}} \times 360^{\circ}$

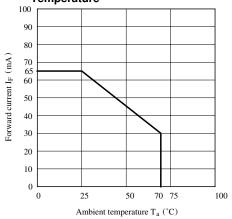
*6 Measured under the condition shown in Measurement Conditions.

Output Waveforms



from OPIC light detector







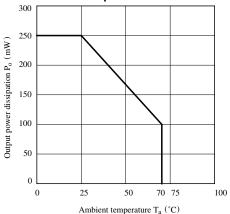


Fig. 3 Duty Ratio vs. Frequency

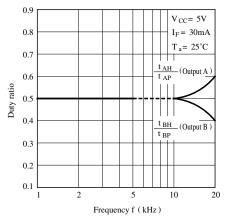


Fig. 5 Duty Ratio vs. Ambient Temperature

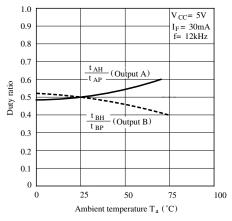


Fig. 7 Duty Ratio vs. Distance (Xdirection)

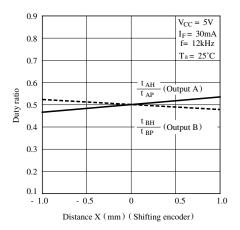


Fig. 4 Phase Difference vs. Frequency

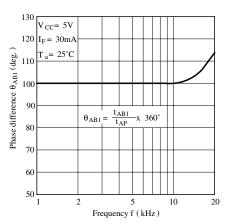


Fig. 6 Phase Difference vs. Ambient Temperature

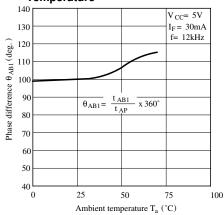


Fig. 8 Phase Difference vs. Distance (Xdirection)

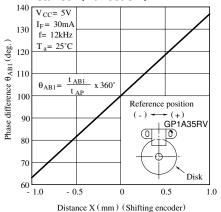


Fig. 9 Duty Ratio vs. Distance (Ydirection)

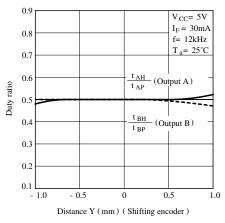


Fig.11 Duty Ratio vs. Distance (Zdirection)

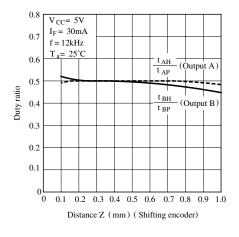


Fig.10 Phase Difference vs. Distance (Ydirection)

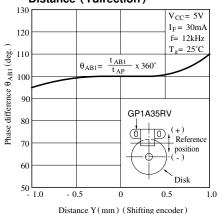
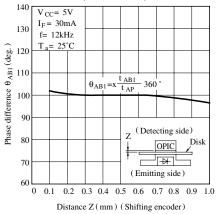
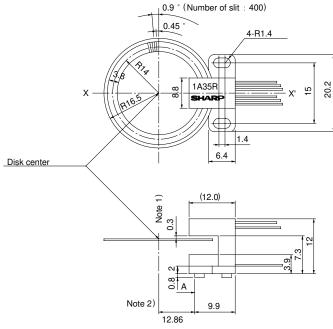


Fig.12 Phase Difference vs. Distance (Zdirection)



Measurement Conditions



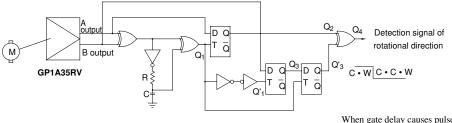
Note 1) Distance between disk surface and case surface in the detector side is 0.3mm.

- 2) Encoder positioning pin is positioned on X-X' axis.
 - Distance between center of disk and portion A of positioning pin is 12.86mm.
- 3) Center of disk slit is R14.0.

Precautions for Use

- (1) This module is designed to be operated at I $_{F}$ = 30mA TYP.
- (2) Fixing torque: MAX. 0.6N m
- (3) In order to stabilize power supply line, connect a by-pass capacitor of more than $0.01 \mu F$ between Vcc and GND near the device.
- (4) As for other general cautions, refer to the chapter "Precautions for Use".

■ Application Circuit (Detection of Rotational Direction)



When gate delay causes pulse noise in Q4 output, apply the CR filter to remove pulse noise.

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 - Office automation equipment
 - Telecommunication equipment [terminal]
 - Test and measurement equipment
 - Industrial control
 - Audio visual equipment
 - Consumer electronics

(ii)Measures such as fail-safe function and redundant design should be taken to ensure reliability and safety when SHARP devices are used for or in connection with equipment that requires higher reliability such as:

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- Traffic signals
- Gas leakage sensor breakers
- Alarm equipment
- Various safety devices, etc.

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