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GP1A70R/GP1A71R

OPIC Photointerrupter with Encoder Functions

■ Features

1. 2-phase (A, B) digital output

2. Sensing accuracy

(**GP1A70R** Disk slit pitch: 1.14mm) (**GP1A71R** Disk slit pitch: 0.7mm)

3. PWB mounting type (Lead bending type)

4. TTL compatible output

5. Compact, lightweight

■ Applications

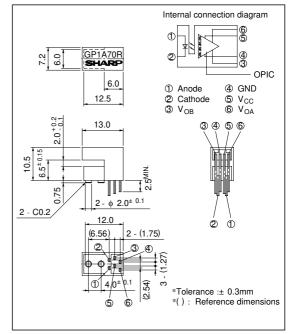
1. Printers

2. Copiers

3. Numerical control machines

■ Outline Dimensions

(Unit: mm)



^{*&}quot;OPIC" (Optical IC) is a trademark of the SHARP Corporation. An OPIC consists of a light-detecting element and signalprocessing circuit integrated onto a single chip.

■ Absolute Maximum Ratings

 $(Ta = 25^{\circ}C)$

		`	/	
	Parameter	Symbol	Rating	Unit
I	Forward current	I_F	50	mA
	*1Peak forward current	I_{FM}	1	A
Input	Reverse voltage	V _R	6	V
	Power dissipation	P	75	mW
	Supply voltage	V _{CC}	7	V
Output	Low level output current	I_{OL}	20	mA
	Power dissipation	Po	250	mW
Operating temperature		Topr	0 to + 70	°C
Storage temperature		T_{stg}	- 40 to + 80	°C
*2 Soldering temperature		T_{sol}	260	°C

^{*1} Pulse width<=100 \mu s, Duty ratio 0.01

^{*2} For 5 seconds

■ Electro-optical Characteristics

 $(Ta = 25^{\circ}C \text{ unless otherwise specified})$

Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit	
Input	Forward voltage		VF	$I_F = 20\text{mA}, \text{Ta}= 25^{\circ}\text{C}$	-	1.2	1.4	V
	Reverse current		I_R	V _R = 3V, Ta= 25°C	-	-	10	μΑ
Output	Operating supply voltage		Vcc		4.5	5.0	5.5	V
	High level output voltage		VoH	*3V _{CC} = 5V, I _F = 20mA	2.4	4.9	-	V
	Low level output voltage		Vol	*3I _{OL} = 8mA, V _{CC} = 5V, I _F = 20mA	-	0.1	0.4	V
	Supply current		Icc	*4V _{CC} = 5V, I _F = 20mA	-	5	20	mA
Transfer characteristics	Duty ratio	GP1A70R	⊢*5D₄ D ₽	*3V _{CC} = 5V, I _F = 20mA, f = 2.5kHz	25	50	75	%
		GP1A71R			25	50	75	%
	Response frequency		f MAX.	*3V _{CC} = 5V, I _F = 20mA	-	-	10	kHz

^{*3} Measured under the condition shown in Measurement Conditions.

■ Output Waveforms

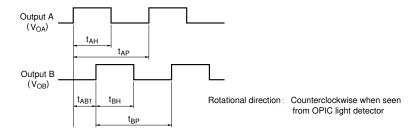


Fig. 1 Forward Current vs. Ambient Temperature

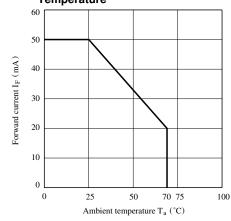
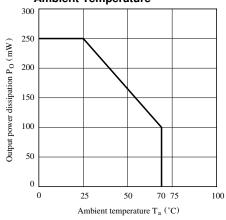


Fig. 2 Output Power Dissipation vs.
Ambient Temperature



^{*4} In the condition that output A and B are low level.

^{*5} D $_{A^{1}}$ $\,\frac{t_{AH}}{t_{AP}}\,$ x 100, D $_{B}$: $\,\frac{t_{BH}}{t_{BP}}\,$ x 100, Duty ratio : Average disk rotation time per turn

Fig. 3-a Duty Ratio vs. Frequency (GP1A70R)

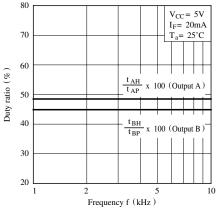


Fig. 4-a Phase Difference vs. Frequency (GP1A70R)

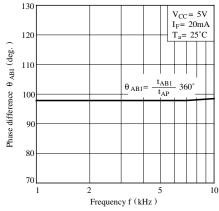


Fig. 5-a Duty Ratio vs.
Ambient Temperature
(GP1A70R)

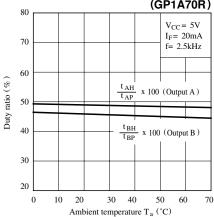


Fig. 3-b Duty Ratio vs. Frequency (GP1A71R)

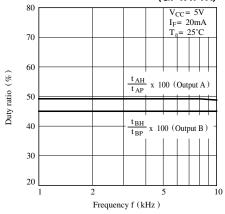


Fig. 4-b Phase Difference vs. Freauency (GP1A71R)

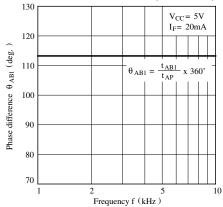


Fig. 5-b Duty Ratio vs.
Ambient Temperature

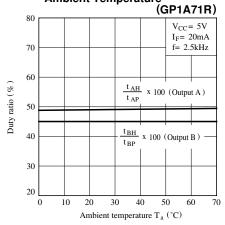


Fig. 6-a Phase Difference vs. Ambient Temperature

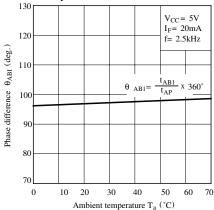
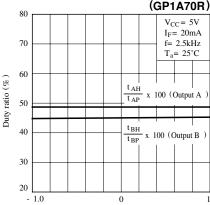
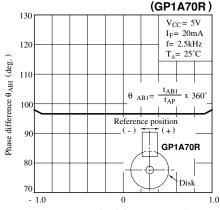


Fig. 7-a Duty Ratio vs.
Distance (Xdirection)



Distance X (mm) (Shifting encoder)

Fig. 8-a Phase Difference vs. Distance (X direction)



Distance X (mm) (Shifting encoder)

Fig. 6-b Phase Difference vs. Ambient Temperature

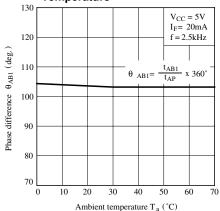
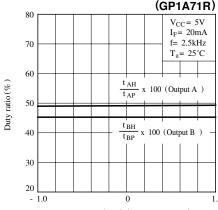
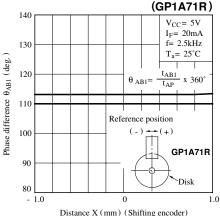


Fig. 7-b Duty Ratio vs.
Distance (X direction)

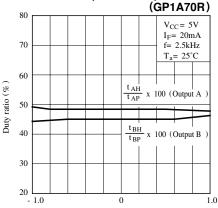


Distance X (mm) (Shifting encoder)

Fig. 8-b Phase Difference vs. Distance (X direction)

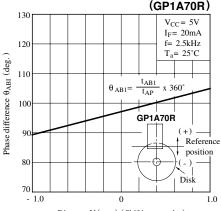






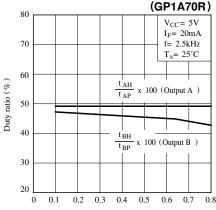
Distance Y (mm) (Shifting encoder)

Fig.10-a Phase Difference vs. Distance (Y direction)



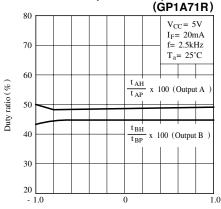
Distance Y (mm) (Shifting encoder)

Fig.11-a Duty Ratio vs.
Distance (Z direction)
(GP1A70F



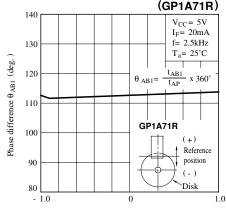
Distance Z (mm) (Shifting encoder)

Fig. 9-b Duty Ratio vs.
Distance (Y direction)



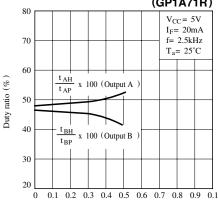
Distance Y (mm) (Shifting encoder)

Fig.10-b Phase Difference vs. Distance (Y direction)



Distance Y (mm) (Shifting encoder)

Fig.11-b Duty Ratio vs.
Distance (Z direction)
(GP1A71R)



Distance Z (mm) (Shifting encoder)

Fig.12-a Phase Difference vs. Distance (Z direction)

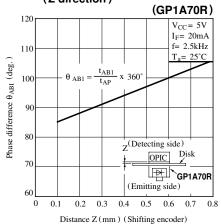
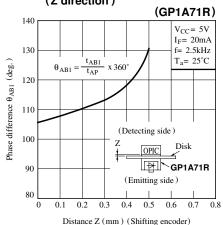
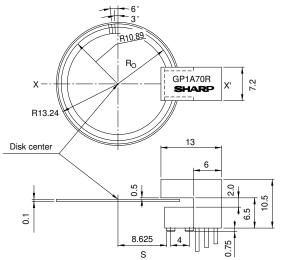
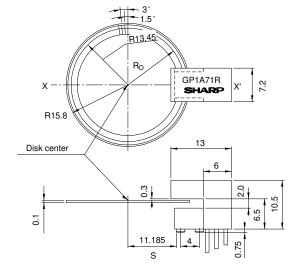


Fig.12-b Phase Difference vs. Distance (Z direction)



<Measurement Conditions> (Unit : mm)





< GP1A70R Basic Design>

 R_O (distance between the disk center and half point of a slit) and S (installing position of $\mbox{\bf GP1A70R})$ will be provided by the following equations.

 $R_O \!\!=\!\! N/60~x~10.89~(mm)~N$: number of slits $S \!\!=\! R_{O^-}~2.265~(mm)$

< GP1A71R Basic Design>

 R_O (distance between the disk center and half point of a slit) and S (installing position of GP1A71R) will be provided by the following equations.

 $R_{O}{=}$ N/120 x 13.45 (mm) N: number of slits $S{=}$ $R_{O}{^-}$ 2.265(mm)

■ Precautions for Use

- (1) This device is designed to be used under the condition of $I_F = 20 \text{mA}$
- (2) It is recommended that a by-pass capacitor of more than $0.01\mu F$ be added between $V_{\rm CC}$ and GND near the device in order to stabilize power supply line.
- (3) As for other general cautions, refer to the chapter "Precautions for Use".

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- Consumer electronics
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- Traffic signals
- Gas leakage sensor breakers
- Alarm equipment
- Various safety devices, etc.
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