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Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China











SHARP

FEATURES

• Trigger point set at factory to 80°

· Digital output

• Range: 20 to 150 cm

Typical response time: 39 msTypical start up delay: 47 ms

· Average current consumption: 33 mA

DESCRIPTION

The GP2Y0D02YK is a distance measuring sensor with integrated signal processing and digital output.

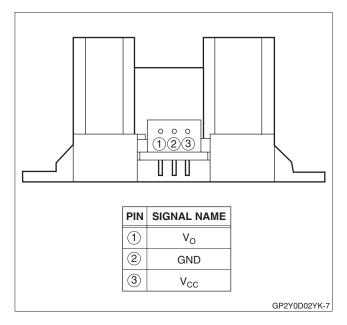


Figure 1. Pinout

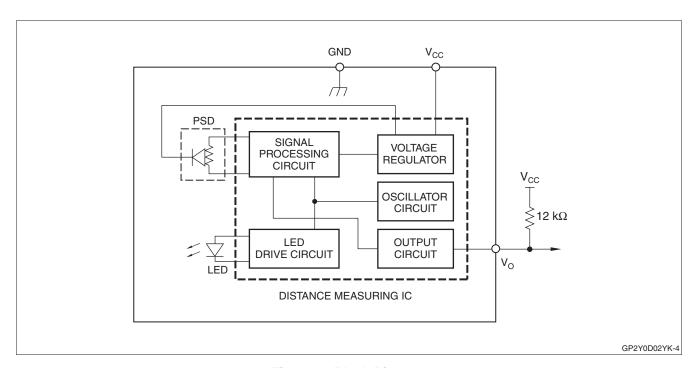


Figure 2. Block Diagram

ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

 $Ta = 25^{\circ}C$, $V_{CC} = 5 VDC$

PARAMETER	SYMBOL	RATING	UNIT	REMARKS
Supply Voltage	V _{CC}	-0.3 to +7.0	V	
Output Terminal Voltage	V _O	-0.3 to (V _{CC} + 0.3)	V	Open collector output
Output Distance Characteristics	Topr	-10 to +60	°C	
Storage Temperature	Tstg	-40 to +70	°C	

Operating Supply Voltages

PARAMETER	SYMBOL	RATING	UNIT	
Operating Supply Voltage	V _{CC}	4.5 to 5.5	V	

Electro-optical Characteristics

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT	NOTES
Measuring Distance Range	ΔL		200	-	1500	mm	1, 3
Output Terminal Voltage	V _{OH}	Output voltage at HIGH level	V _{CC} -0.3	-	-	V	1
	V _{OL}	Output voltage at LOW level	-	-	0.6	V	1
Output Distance Characteristics	V _O		700	800	900	mm	1, 2, 4
Average Supply Current	I _{CC}		-	33	50	mA	

NOTES:

- $1. \ \ Measurements\ made\ with\ Kodak\ R-27\ Gray\ Card,\ using\ the\ white\ side,\ (90\%\ reflectivity).$
- 2. Set at factory for guaranteed measurement at L = 24 cm ± 3 cm.
- 3. Measurement adjustment range.
- 4. Output switching has hysteresis. The distance specified by V_O is for switching from LOW to HIGH.
- 5. * L = Distance to reflective object.

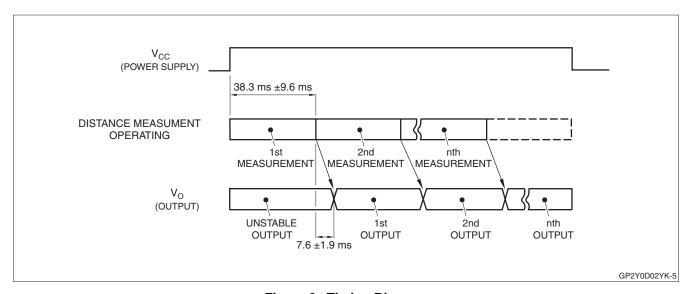


Figure 3. Timing Diagram

REALIABILITY

The reliability requirements of this device are listed in Table 1.

Table 1. Reliability

TEST ITEMS	TEST CONDITIONS	FAILURE JUDGEMENT CRITERIA	SAMPLES (n), DEFECTIVE (C)
Temperature Cycling	One cycle -40°C (30 min.) to +70°C in 30 minutes, repeated 25 times		n = 11, C = 0
High Temperature and High Humidity Storage	+40°C, 90% RH, 500h		n = 11, C = 0
High Temperature Storage	emperature Storage +70°C, 500h n =		n = 11, C = 0
Low Temperature Storage	40° C, 500h Initial × 0.8 > V_{O}		n = 11, C = 0
Operation Life (High Temperature)	$+60^{\circ}$ C, $V_{CC} = 5$ V, 500h $V_{O} > Initial \times 1.2$		n = 11, C = 0
Mechanical Shock	nock		n = 6, C = 0
Variable Frequency Vibration	10-to-55-to-10 Hz in 1 minute Amplitude: 1.5 mm 2h in each X, Y, Z direction		n = 6, C = 0

NOTES:

- 1. Test conditions are according to Electro-optical Characteristics, shown on page 2.
- 2. At completion of the test, allow device to remain at nominal room temperature and humidity (non-condensing) for two hours.
- 3. Confidence level: 90%, Lot Tolerance Percent Defect (LTPD): 20%/40%.

MANUFACTURER'S INSPECTION

Inspection Lot

Inspection shall be carried out per each delivery lot.

Inspection Method

A single sampling plan, normal inspection level II based on ISO 2859 shall be adopted.

Table 2. Quality Level

DEFECT	INSPECTION ITEM/TEST METHOD	AQL (%)
Major Defect	Electro-optical characteristics defect	0.4
Minor Defect	Defect on appearance and dimension (crack, split, chip, scratch, stain)*	1.0

NOTE: *Any one of these that affects the Electro-optical Characteristics shall be considered a defect.

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Data Sheet

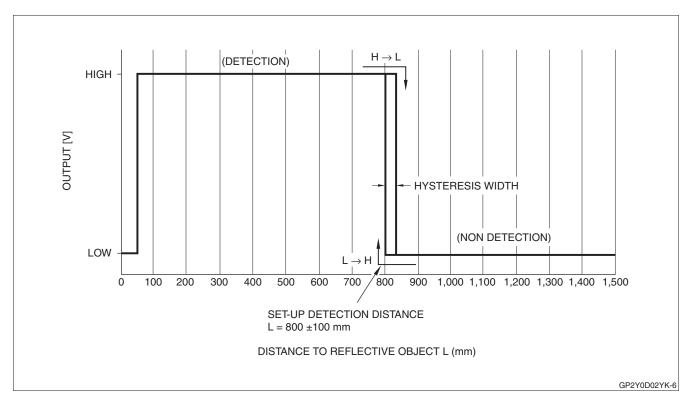
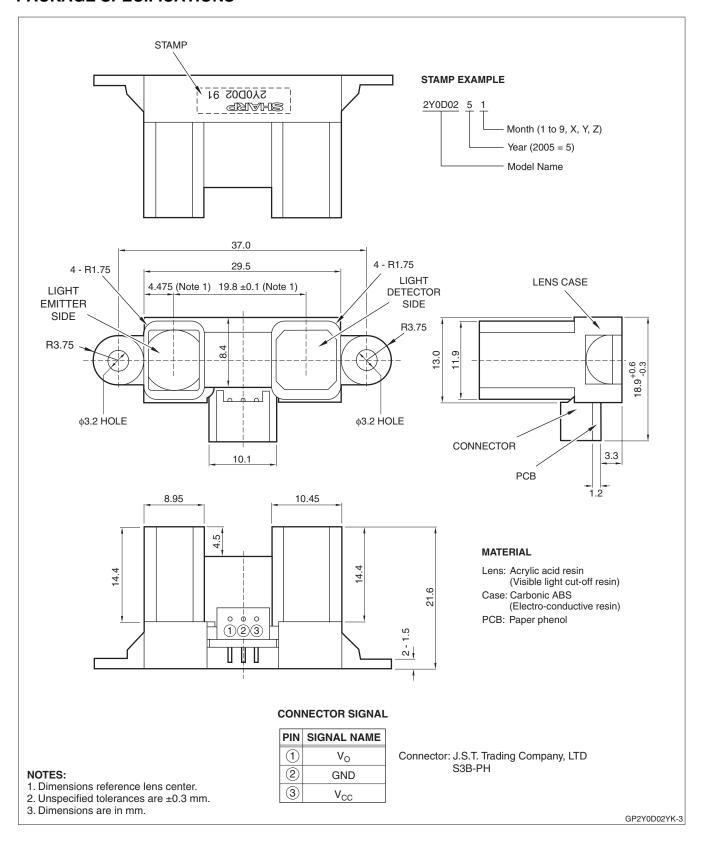


Figure 4. GP2Y0D02YK Example of Output Distance Characteristics

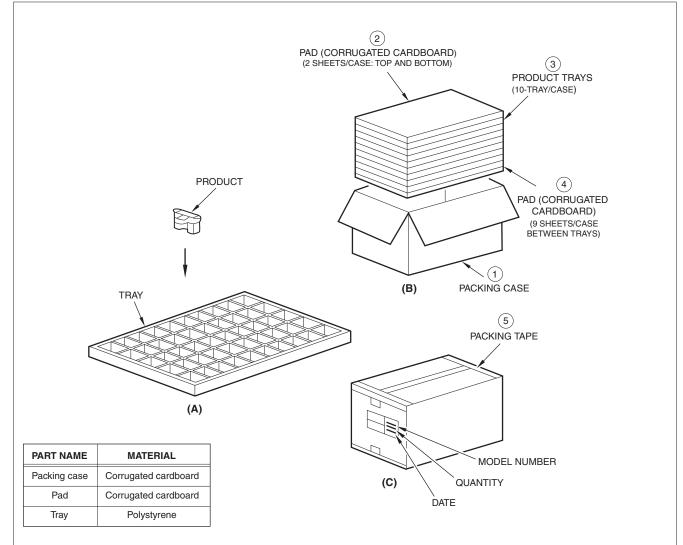
4

PACKAGE SPECIFICATIONS



5

PACKING SPECIFICATION



6

PACKING METHOD

- 1. Each tray holds 50 pieces. Packing methods are shown in (A).
- 2. Each box holds 10 trays. Pads are added to top and bottom, and between layers, as in (B). top and bottom. Put pads between each tray (9 pads total) see above drawing (B).
- 3. The box is sealed with craft tape. (C) shows the location of the Model number, Quantity, and Inspection date.
- 4. Package weight: Approximately 4 kg.

GP2Y0D02YK-9

Data Sheet

NOTES

- Keep the sensor lens clean. Dust, water, oil, and other contaminants can deteriorate the characteristics of this device. Applications should be designed to eliminate sources of lens contamination.
- When using a protective cover over the emitter and detector, ensure the cover efficiently transmits light throughout the wavelength range of the LED (λ = 850 nm ± 70 nm). Both sides of the protective cover should be highly polished. Use of a protective cover may decrease the effective distance over which the sensor operates. Ensure that any cover does not negatively affect the operation over the intended application range.
- Objects in proximity to the sensor may cause reflections that can affect the operation of the sensor.
- Sources of high ambient light (the sun or strong artificial light) may affect measurement. For best results, the application should be designed to prevent interference from direct sunlight or artificial light.

- Using the sensor with a mirror can induce measurement errors. Often, changing the incident angle on the mirror can correct this problem.
- If a prominent boundary line exists in the surface being measured, it should be aligned vertically to avoid measurement error. See Figure 5 for further details.
- When measuring the distance to objects in motion, align the sensor so that the motion is in the horizontal direction instead of vertical. Figure 6 illustrates the preferred alignment.
- A 10 μF (or larger) bypass capacitor between V_{CC} and GND near the sensor is recommended.
- To clean the sensor, use a dry cloth. Use of any liquid to clean the device may result in decreased sensitivity or complete failure.
- Excessive mechanical stress can damage the internal sensor or lens.

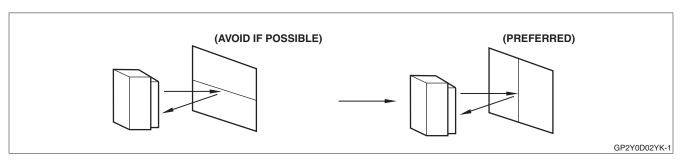


Figure 5. Proper Alignment to Surface Being Measured

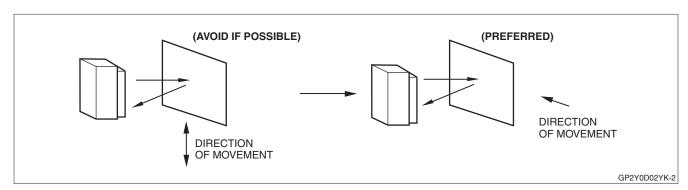


Figure 6. Proper Alignment to Moving Surfaces

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Data Sheet

SHARP GP2Y0D02YK

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SHARP CORPORATION

SALES & MARKETING GROUP

ELECTRONIC COMPONENTS & DEVICES

22-22 NAGAIKE-CHO, ABENO-KU, OSAKA 545-8522, JAPAN

PHONE: (81) 6-6621-1221

FAX: (81) 6117-725300, 6117-725301, 6117-725302

http://sharp-world.com/products/device

Specifications are subject to change without notice.

Countries and Areas

U.S.A.

SHARP MICROELECTRONICS OF THE AMERICAS

North American Head Office

5700 North West Pacific Rim Boulevard Camas, Washington 98607 USA PHONE: (1)360-834-2500 FAX: (1)360-834-8903 http://www.sharpsma.com

Western Area

1980 Zanker Road, San Jose, CA 95112 PHONE: (1)408-436-4900 FAX: (1)408-436-0924

5901 Bolsa Ave

Huntington Beach, CA 92647-2053 PHONE: (1)714-903-4600 FAX: (1)714-903-0295

6390 Greenwich Drive, S uite 175 San Diego, CA 92122 PHONE: (1)858-597-0982 FAX: (1)858-597-8701

Central Area

85 W. Algonquin Road, Suite 280 Arlington Heights, IL 60005 PHONE: (1)847-258-2750 FAX: (1)847-439-2479

6303 Commerce Drive, Suite 175 Irving, TX 75063

PHONE: (1)972-582-1710 FAX: (1)972-580-7537

8911 Capitol of Texas Hwv. Suite 3130

Austin, TX 78759 PHONE: (1)512-349-7262 FAX: (1)512-349-7002

20333 State Hwy. 249, Suite 200 Houston, TX 77070 PHONE: (1)281-378-1520

PHONE: (1)281-378-1520 FAX: (1)281-378-1521

W129 S 9647 Tony Lema Lane Muskego, WI 53150

PHONE: (1)414-529-9568 FAX: (1)414-529-9569

3001 West Big Beaver Road, Suite 722

Troy, ML 48084 PHONE: (1)248-458-1527 FAX: (1)248-458-6255

Eastern Area

1070 N. Kimbles Road, Yardley, PA 19067

PHONE: (1)215-321-5530 FAX: (1)215-321-5534

200 Wheeler Rd., Burlington, MA 01803 PHONE: (1)781-270-7979; (1)781-229-5100

FAX: (1)781-229-9117

8000 Regency Parkway, Suite 280 Cary, NC 27511

PHONE: (1)919-460-0695 FAX: (1)919-460-0795

2321 Sidney St. Pittsburgh, PA 15203

PHONE: (1)412-381-1191 FAX: (1)412-381-1192

4875 North Federal Highway, Third Floor

Ft. Lauderlade, FL 33318 PHONE: (1)954-267-8883 FAX: (1)954-267-0254

EUROPE

SHARP MICROELECTRONICS EUROPE A division of Sharp Electronics (Europe) GmbH

Head Office

Sonninstrasse 3, 20097, Hamburg, Germany

PHONE: (49)180-5073507 FAX: (49)40-2376-2232 http://www.sharpsme.com/

Germany

SME München Office Fuerstenriederstrasse 5, 80687 München, Germany PHONE: (49)89-5468420

FAX: (49)89-54 684250

France

SME Paris Office 1 Rue Raoul Follereau Bussy Saint Georges 77608 Marne la Vallee Cedex 3

PHONE: (33)1 6476 22 22 FAX: (33)1 6476 22 23

Italy

SME Milano Office Centro Direzionale Colleoni Palazzo Taurus Ingresso 2 20041 Agrate Brianza, Milano, Italy PHONE: (390)39-68 99 946 FAX: (390)39-68 99 948

U.K.

SME London Office Centennial Court, Easthampstead Road, Bracknell, Berkshire R G12 1YQ, United Kingdom PHONE: (44)1344-86 99 22

FAX: (44)1344-36 09 03

Ireland

SME Dublin Office First Floor, Block 1, St. Johns Court, Santry,

Dublin 9, Ireland

PHONE: (353)1-842 87 05 FAX: (353)1-842 84 55

ASIA

SHARP ELECTRONICS (SHANGHAI) CO., LTD. Microelectronics Sales & Marketing Division 16F, King Tower, 28 Xin Jin Qiao Road, Pudong DIST, Shanghai 201206 P.R. China PHONE: (86)21-5854-7710/21-5834-6056 FAX: (86)21-5854-4340/21-5834-6057

Registered Address

No. 11, De Bao Road, Xin Development BLDG 46 Wai Gao Qiao Free Trade Zone, Shanghai 200131, P.R. China

Beijing Office

Room 1062, Beijing Jing An Center No. 8 East Bei San Huan Road, Chao Yang DIST, Beijing 100028 P.R. China

PHONE: (86) 10-6466-7543/10-6466-6561

FAX: (86) 10-6468-8920

http://sharp-world.com/products/devicechina/

index.html

SHARP-ROXY (HONG KONG) LTD. Device Sales Division, 17/F, Admiralty Centre, Tower 1, 18 Harcourt Road, Hong Kong

PHONE: (852)28229311 FAX: (852)28660779 http://www.sharp.com.hk

Shenzhen Representative Office

Room 13B1, Tower C, Electronics Science & Technology Building, Shen Nan Zhong Road, Shenzhen, P.R. China

PHONE: (86)755-83273731 FAX: (86)755-83273735

SHARP ELECTRONIC COMPONENTS (TAIWAN) CORPORATION

8F-A, No. 16, Sec. 4, Nanking E. R d., Taipei, Taiwan PHONE: (886)2-2577-7341 FAX: (886)2-2577-7326/2-2577-7328

CHARD ELECTRONICS (CINCARORE) DE

SHARP ELECTRONICS (SINGAPORE) PTE ., LTD. 396 Alexandra Road #07-00 BP Tower Singapore 119954 PHONE: (65) 62713866 FAX: (65) 62713855 http://www.sesl-sharp.com

SHARP MICROELECTRONICS TECHNOLOGY (M) SDN BHD. Suite E 408, 4th Floor, East Tower, Wisma Consplant 1, No. 2 J In. SS 16/4,

Subng Jaya, 47500, Selangor Darul Ehsan, Malaysia

PHONE: (60) 3-5637-8964 FAX: (60) 3-5638-4029

SHARP ELECTRONIC COMPONENTS (KOREA) CORPORATION RM 501 iLsin B/D. 541, Dohwa-dong, Mapo-ku, Seoul, Korea, 121-701 PHONE: (82)2-711-5813 ~ 8 FAX: (82)2-711-5819

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