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Team Nexperia

# HEF4541B-Q100

# **Programmable timer**

Rev. 2 — 31 December 2013

**Product data sheet** 

### 1. General description

The HEF4541B-Q100 is a programmable timer. It consists of a 16-stage binary counter, an integrated oscillator to be used with external timing components, an automatic power-on reset and output control logic. The external components  $R_{TC}$  and  $C_{TC}$  determines the frequency of the oscillator within the frequency range 1 Hz to 100 kHz. An external clock signal at input RS can replace the oscillator. The timer advances on the positive-going transition of RS. A LOW on the auto reset input (AR) and a LOW on the master reset input (MR) enables the internal power-on reset. A HIGH level at input MR resets the counter independent on all other inputs. Resetting, disables the oscillator to provide no active power dissipation.

A HIGH at input AR turns off the power-on reset to provide a low quiescent power dissipation of the timer. The 16-stage counter divides the oscillator frequency by  $2^8$ ,  $2^{10}$ ,  $2^{13}$  or  $2^{16}$  depending on the state of the address inputs (A0, A1). The divided oscillator frequency is available at output O. The phase input (PH) features a complementary output signal. When the mode select input (MODE) is LOW the timer is a single transition timer and when HIGH the timer is a  $2^n$  frequency divider.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

### 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
  - ◆ Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - MIL-STD-883, method 3015 exceeds 2000 V
  - ◆ HBM JESD22-A114F exceeds 2000 V
  - ♦ MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Complies with JEDEC standard JESD 13-B



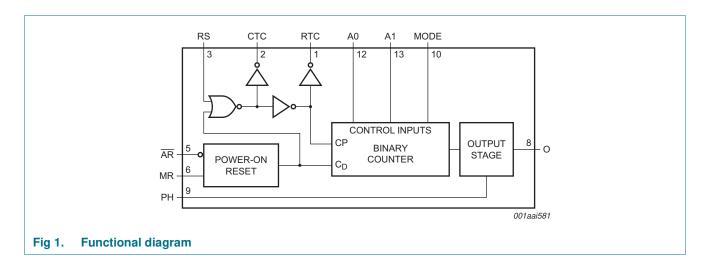
# 3. Ordering information

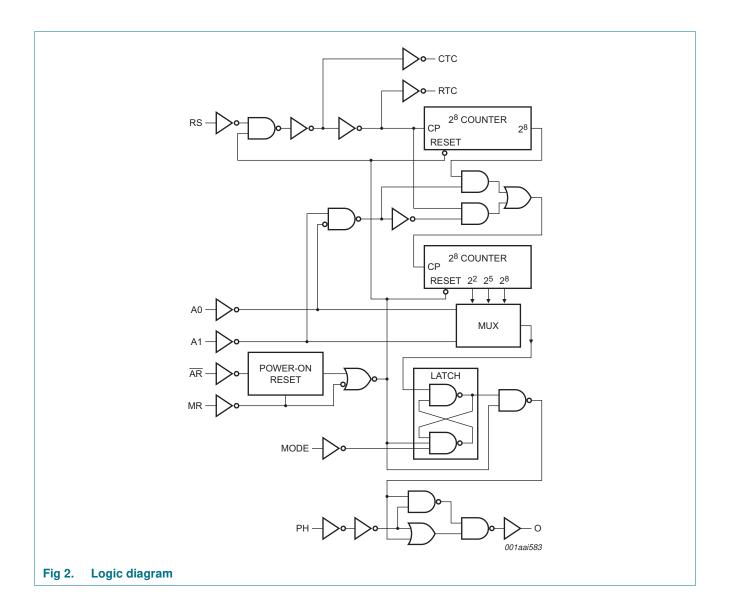
### Table 1. Ordering information

All types operate from −40 °C to +125 °C.

Type number	Package	Package						
	Name	Description	Version					
HEF4541BT-Q100	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1					

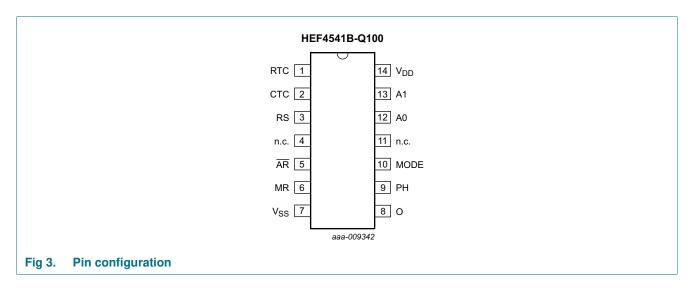
# 4. Functional diagram





# 5. Pinning information

### 5.1 Pinning



## 5.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
RTC	1	external resistor connection
CTC	2	external capacitor connection
RS	3	external resistor connection (RS) or external clock input
nc	4, 11	not connected
ĀR	5	auto reset input (active low)
MR	6	master reset input
$V_{SS}$	7	ground (0 V)
0	8	timer output
PH	9	phase input
MODE	10	mode select input
A0, A1	12, 13	address inputs
$V_{DD}$	14	supply voltage

# 6. Functional description

Table 3. Function table[1]

Input			MODE	
AR	MR	PH	MODE	
Н	L	X	X	auto reset disabled
L	L	Χ	Χ	auto reset enabled[2]
Χ	Н	Χ	X	master reset active
Χ	L	X	Н	normal operation selected division to output
Χ	L	X	L	single-cycle mode[3]
Χ	L	L	X	output initially LOW after reset
Χ	L	Н	Χ	output initially HIGH, after reset

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = don't care.

Table 4. Frequency selection table

A0	A1	Number of counter stages n	$\frac{f_{OSC}}{f_O} = 2^n$
L	L	13	8192
L	Н	10	1024
Н	L	8	256
Н	Н	16	65536

# 7. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_I < -0.5 \text{ V or } V_I > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	$V_{DD} + 0.5$	V
l <sub>ok</sub>	output clamping current	$V_O < -0.5 \text{ V or } V_O > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I <sub>I/O</sub>	input/output current	O output	-	±10	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	[1] -	500	mW
Р	power dissipation		-	100	mW

<sup>[1]</sup> For SO14 package:  $P_{tot}$  derates linearly with 8 mW/K above 70 °C.

<sup>[2]</sup> For correct power-on reset, the supply voltage should be above 8.5 V. For  $V_{DD}$  < 8.5 V, disable the auto reset and connect  $\overline{AR}$  to  $V_{DD}$ .

<sup>[3]</sup> The timer is initialized on a reset pulse and the output changes state after 2<sup>n-1</sup> counts and remains in that state (latched). A master reset or a LOW to HIGH transition on the MODE input, resets this latch.

# 8. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		3	15	V
VI	input voltage		0	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{DD} = 5 V$	-	3.75	μs/V
		$V_{DD} = 10 \text{ V}$	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	0.08	μs/V

# 9. Static characteristics

Table 7. Static characteristics

 $V_{SS} = 0 \ V$ ;  $V_{I} = V_{SS} \ or \ V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	–40 °C	T <sub>amb</sub> =	25 °C	T <sub>amb</sub> =	85 °C	T <sub>amb</sub> =	125 °C	Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level	$ I_O  < 1 \mu A$	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	٧
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level	$ I_O  < 1 \mu A$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
$V_{OH}$	HIGH-level	$ I_O  < 1 \mu A$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
$V_{OL}$	LOW-level	$ I_O  < 1 \mu A$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level	CTC, RTC;										
	output current	$V_{O} = 2.5 \text{ V}$	5 V	-	-1.4	-	-1.2	-	-0.95	-	-0.95	mΑ
		$V_{O} = 4.6 \text{ V}$	5 V	-	-0.5	-	-0.4	-	-0.3	-	-0.3	mΑ
		$V_{O} = 9.5 \text{ V}$	10 V	-	-1.4	-	-1.2	-	-0.95	-	-0.95	mΑ
		V <sub>O</sub> = 13.5 V	15 V	-	-4.8	-	-4.0	-	-3.2	-	-3.2	mΑ
		O;										
		$V_{O} = 2.5 \text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mΑ
		$V_{O} = 4.6 \text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mΑ
		$V_{O} = 9.5 \text{ V}$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mΑ
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mΑ

 Table 7.
 Static characteristics ...continued

 $V_{SS} = 0 \ V$ ;  $V_{I} = V_{SS} \ or \ V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	–40 °C	T <sub>amb</sub> =	25 °C	T <sub>amb</sub> = 85 °C		T <sub>amb</sub> = 125 °C		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$I_{OL}$	LOW-level	CTC, RTC;	•		,							
	output current	$V_{O} = 0.4 \ V$	5 V	0.33	-	0.27	-	0.20	-	0.20	-	mΑ
		$V_{O} = 0.5 \ V$	10 V	1.0	-	0.85	-	0.68	-	0.68	-	mΑ
		$V_{O} = 1.5 \text{ V}$	15 V	3.2	-	2.7	-	2.3	-	2.3	-	mΑ
		О;										
		$V_{O} = 0.4 \ V$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mΑ
		$V_{O} = 0.5 \ V$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mΑ
		$V_{O} = 1.5 \text{ V}$	15 V	4.2	-	3.2	-	2.4	-	2.4	-	mΑ
I <sub>I</sub>	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μΑ
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	5	-	5	-	150	-	150	μА
			10 V	-	10	-	10	-	300	-	300	μА
			15 V	-	20	-	20	-	600	-	600	μА
C <sub>I</sub>	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

#### Table 8. Reset characteristics

 $V_{SS} = 0 \ V$ ;  $V_{I} = V_{SS}$  or  $V_{DD}$ ; see Table 12 for test conditions; unless otherwise specified.

Symbol	Parameter	Conditions	Conditions	Conditions	Conditions	Conditions	Conditions	$V_{DD}$	T <sub>amb</sub> =	–40 °C	Tami	<sub>b</sub> = +2	25 °C	T <sub>amb</sub> =	+85 °C	T <sub>amb</sub> = +	⊦125 °C	Unit
				Min	Max	Min	Тур	Max	Min	Max	Min	Max						
$I_{DD}$	supply current	,	5 V	-	80	-	20	80	-	230	-	230	μΑ					
		for power-on	10 V	-	750	-	250	600	-	700	-	700	μΑ					
		reset enable;  AR = MR = 0 V;  Other inputs at  0 V or V <sub>DD</sub>	15 V	-	1.6	-	0.5	1.3	-	1.5	-	1.5	mA					
$V_{DD}$	supply voltage	supply voltage for automatic reset initialization; $\overline{AR} = MR = 0 V$ ; Other inputs at $0 V$ or $V_{DD}$	-	-	-	8.5	5	-	-	-	-	-	V					

# 10. Dynamic characteristics

Table 9. Dynamic characteristics

 $V_{SS} = 0 \text{ V}$ ;  $T_{amb} = 25 \, ^{\circ}\text{C}$  unless otherwise specified. For test circuit, see <u>Figure 5</u>.

Symbol	Parameter	Conditions	$V_{DD}$		Extrapolation formula	Min	Typ[1]	Max	Unit
t <sub>pd</sub>	propagation delay	RS to O;	5 V	[2]	$348 \text{ ns} + (0.55 \text{ ns/pF})C_L$	-	375	750	ns
		28 selected; see Figure 4	10 V		139 ns + (0.23 ns/pF)C <sub>L</sub>	-	150	300	ns
		see <u>rigure 4</u>	15 V		102 ns + (0.16 ns/pF)C <sub>L</sub>	-	110	220	ns
		RS to O; 2 <sup>10</sup> selected; see Figure 4	5 V		$398 \text{ ns} + (0.55 \text{ ns/pF})C_L$	-	425	850	ns
			10 V		154 ns + (0.23 ns/pF)C <sub>L</sub>	-	165	330	ns
		300 riguro +	15 V		112 ns + (0.16 ns/pF)C <sub>L</sub>	-	120	240	ns
		RS to O;	5 V		483 ns + $(0.55 \text{ ns/pF})C_L$	-	510	1020	ns
	2 <sup>13</sup> selected; see Figure 4	10 V		179 ns + $(0.23 \text{ ns/pF})C_L$	-	190	380	ns	
		300 <u>riguro +</u>	15 V		127 ns + $(0.16 \text{ ns/pF})C_L$	-	135	270	ns
		RS to O;	5 V		548 ns + (0.55 ns/pF)C <sub>L</sub>	-	575	1150	ns
		2 <sup>16</sup> selected; see <u>Figure 4</u>	10 V		199 ns + (0.23 ns/pF)C <sub>L</sub>	-	210	420	ns
			15 V		$142 \text{ ns} + (0.16 \text{ ns/pF})C_L$	-	150	300	ns
$t_W$	pulse width	RS LOW;	5 V	[3]		60	30	-	ns
		MR HIGH; see <u>Figure 4</u>	10 V			30	15	-	ns
		<u> </u>	15 V			24	12	-	ns
$f_{clk(max)}$	maximum clock	RS; see Figure 4	5 V			8	16	-	MHz
	frequency		10 V			15	30	-	MHz
			15 V			18	36	-	MHz
$f_{osc}$	oscillator frequency	$R_t = 5 k\Omega;$	5 V			-	90	-	kHz
		$C_t = 1 \text{ nF};$ $R_S = 10 \text{ k}\Omega;$	10 V			-	90	-	kHz
		see Figure 6	15 V			-	90	-	kHz
		$R_t = 56 \text{ k}\Omega;$	5 V			-	8	-	kHz
		$C_t = 1 \text{ nF};$ $R_S = 120 \text{ k}\Omega;$	10 V			-	8	-	kHz
		see <u>Figure 6</u>	15 V			-	8	-	kHz

<sup>[1]</sup> The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

<sup>[2]</sup>  $t_{pd}$  is the same as  $t_{PHL}$  and  $t_{PLH}$ .

<sup>[3]</sup>  $t_W$  is the same as  $t_{WL(min)}$  and  $t_{WH(min)}$ .

Table 10. Dynamic power dissipation

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0$  V;  $t_r = t_f \le 20$  ns;  $T_{amb} = 25$  °C.

Symbol	Parameter	$V_{DD}$	Typical formula
P <sub>D</sub> dynamic power dissipation		Per pa	ckage
		5 V	$P_D = 1300 \times f_i + (f_o \times C_L \times V_{DD}^2) \mu W$
		10 V	$P_D = 5300 \times f_i + (f_o \times C_L \times V_{DD}^2) \mu W$
		15 V	$P_D = 12000 \times f_i + (f_0 \times C_L \times V_{DD}^2) \mu W$
		Total, ι	using the on-chip oscillator
		5 V	$P_D = 1300 \times f_{osc} + f_o C_L V_{DD}^2 + 2C_{TC} V_{DD}^2 f_{osc} + 10 V_{DD} \mu W$
		10 V	$P_{D} = 5300 \times f_{osc} + f_{o}C_{L}V_{DD}^{2} + 2C_{TC}V_{DD}^{2} f_{osc} + 100V_{DD} \mu W$
		15 V	$P_D = 12000 \times f_{osc} + f_o C_L V_{DD}^2 + 2C_{TC} V_{DD}^2 f_{osc} + 400 V_{DD} \mu W$

<sup>[1]</sup>  $f_i$  = input frequency in MHz;  $f_o$  = output frequency in MHz;  $C_L$  = output load capacitance in pF;  $V_{DD}$  = supply voltage in V;  $f_{osc}$  = oscillator frequency in MHz;  $C_{TC}$  = timing capacitance in pF.

### 11. Waveforms

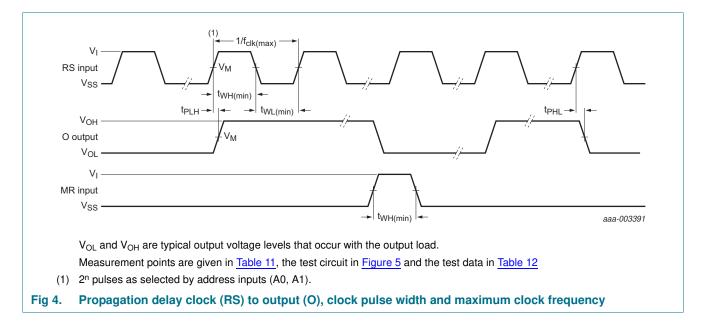
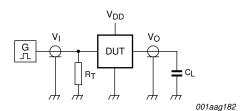


Table 11. Measurement points

Supply voltage	Input	Output
$V_{DD}$	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



Test data is given in Table 12.

Definitions for test circuit:

DUT - Device Under Test.

 $R_L$  = Load resistance.

 $C_L$  = load capacitance.

 $R_T$  = Termination resistance should be equal to output impedance of  $Z_0$  of the pulse generator.

Fig 5. Test circuit for measuring switching times

#### Table 12. Test data

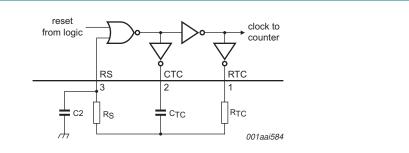
Supply	Input		Load
$V_{DD}$	V <sub>I</sub>	t <sub>r</sub> , t <sub>f</sub>	C <sub>L</sub>
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

# 12. Application information

#### RC oscillator timing component limitations

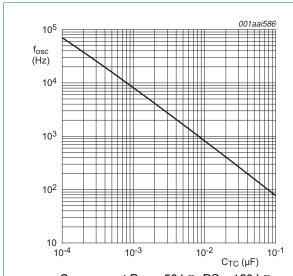
 $R_{TC}C_{TC}$  determines the oscillator frequency, provided  $R_{TC} << R_S$  and  $R_SC_2 << R_{TC}C_{TC}$ . The function of  $R_S$  is to minimize the influence of the forward voltage across the input protection diodes on the frequency. The stray capacitance  $C_2$  should be kept as small as possible. In consideration of accuracy,  $C_{TC}$  must be larger than the inherent stray capacitance.  $R_{TC}$  must be larger than the LOCMOS 'ON' resistance in series with it, which typically is 500  $\Omega$  at  $V_{DD} = 5$  V, 300  $\Omega$  at  $V_{DD} = 10$  V and 200  $\Omega$  at  $V_{DD} = 15$  V.

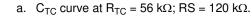
The recommended values for these components to maintain agreement with the typical oscillation formula are:  $C_{TC} \ge 100$  pF, up to any typical value,  $10 \text{ k}\Omega \le R_{TC} \le 1 \text{ M}\Omega$ .

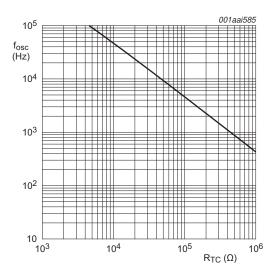


Typical formula for oscillator frequency:  $f_{\rm osc} = \frac{I}{2.3 \times R_{TC} \times C_{TC}}$ 

Fig 6. External component connection for RC oscillator;  $R_S \approx R_{TC}$ 

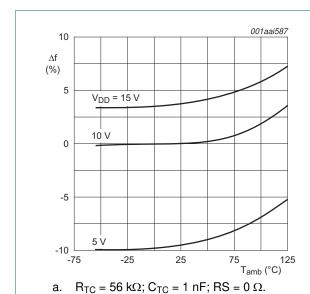


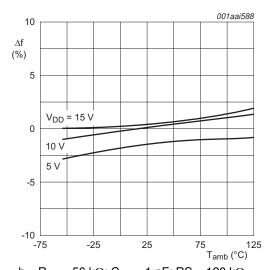




b.  $R_{TC}$  curve at  $C_{TC} = 1$  nF; RS = 2  $R_{TC}$ .

Fig 7. RC oscillator frequency as a function of  $R_{TC}$  and  $C_{TC}$  at  $V_{DD}$  = 5 V to 15 V;  $T_{amb}$  = 25 °C





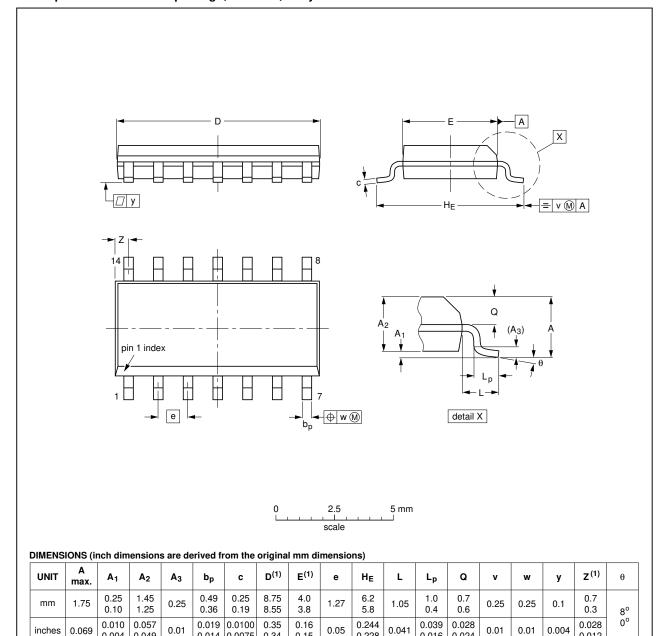
b.  $R_{TC}$  = 56  $k\Omega$ ;  $C_{TC}$  = 1 nF; RS = 120  $k\Omega$ .

Fig 8. Frequency deviation ( $\Delta f$ ) as a function of ambient temperature

# 13. Package outline

### SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1



## inches

0.069

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

0.014

0.0075

0.34

0.15

OUTLINE		REFERENCES			EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEDEC JEITA		PROJECTION	ISSUE DATE
SOT108-1	076E06	MS-012				<del>99-12-27</del> 03-02-19

0.05

0.228

0.016

0.024

Package outline SOT108-1 (SO14)

0.049

0.004

HEF4541B\_Q100

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0.012

# 14. Abbreviations

### Table 13. Abbreviations

Acronym	Description	
CMOS	Complementary Metal Oxide Semiconductor	
DUT	Device Under Test	
ESD	ElectroStatic Discharge	
HBM	Human Body Model	
MIL	Military	
MM	Machine Model	
TTL	Transistor-Transistor Logic	

# 15. Revision history

### Table 14. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4541B_Q100 v.2	20131231	Product data sheet	-	HEF4541B_Q100 v.1
Modifications:	<ul> <li>Maximum temperature changed to 125 °C throughout.</li> </ul>			
HEF4541B_Q100 v.1	20131021	Product data sheet	-	-

### 16. Legal information

#### 16.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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