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# HI-4853, 4854, 4855

High-Speed 3.0V to 5.5V, Slew-Rate Controlled RS-485/422  
Transceivers with Extended Common-Mode Range

## GENERAL DESCRIPTION

The HI-485x devices are high-speed slew-rated controlled TIA-485/TIA-422-B and ISO 8482:1993 compliant transceivers with extended receiver common-mode range for avionic and industrial control applications. The devices can operate over an extended supply (3.0V to 5.5V) and temperature (-55°C to 125°C) range. The receiver input common-mode range of [-15, 20]V and ±24V for the half and full duplex configurations respectively, is valid over the full supply and temperature specification. The HI-4853 has a half-duplex configuration, and the HI-4854 and HI-4855 are full-duplex. Slew rates are optimized for data rates below 25Mbps. The drivers slew-rate control and pre-emphasis reduces high-frequency components in the output signal transitions and also compensates for impedance mismatch. These features provide optimum EMI and jitter performance, essential in EMI sensitive environments and high-integrity data link applications such as in aerospace and industrial controls.

The devices deliver at least ± 1.50V (VDD=3.0V), and ± 2.45V (VDD= 4.5V) output levels at an extended temperature range of -55°C to +125°C into a differential load of 54Ω and 50pF.

The receiver offers true Fail-Safe operation, providing a guaranteed logic high on RO when the bus is open-circuit, short-circuit, or idle (terminated but not driven). The receiver's worst case minimum input resistance is at least 90KΩ, supporting up to 224 nodes.

## APPLICATIONS

- Extended Temperature Range RS-485/422 Networks
- Process Control and Factory Automation
- EMI Emission Sensitive Avionics
- Industrial Field Bus Networks
- Networks requiring extended common-mode range
- Miniature Munitions Stores Interface (MMSI / EBR-1553)

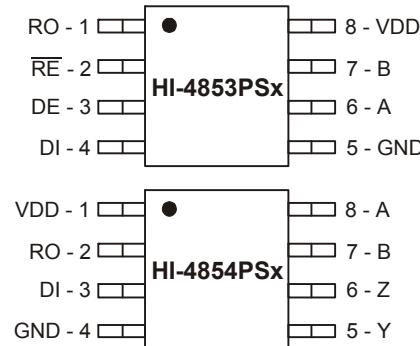
Device Selection Table			
Part Number	Half/Full Duplex	Data Rate (Mbps)*	Package
HI-4853	Half	≤ 20.0	8-pin SOIC
HI-4854	Full	≤ 20.0	8-pin SOIC
HI-4855	Full	≤ 20.0	14-pin SOIC 16-pin QFN

\* For RS-485 Transceivers optimized for data rates up to 5Mbps please refer to the HI-4850 data sheet.

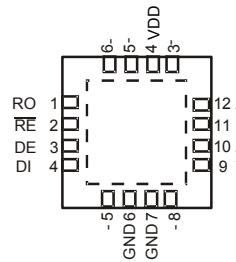
## FEATURES

- Slew Rate Control and Pre-Emphasis for superior EMI
- Extended Power Supply Operating Range 3.0V to 5.5V
- Extended Receiver Common-Mode Range:
  - **-15.0V to 20.0V Half-Duplex**
  - **±24V Full-Duplex**
- ESD Protection
  - ±16KV HBM (Bus Pins)
  - ±8KV HBM (Logic Pins)
- 20 Mbps Data Rate up to 100 ft. CAT-5 UTP
- 12 Mbps Data Rate up to 1000 ft. CAT-5 UTP
- Current Limiting Protection
- Extended Temperature Range -55°C to 125°C
- Industry Standard 75176 Pin-out

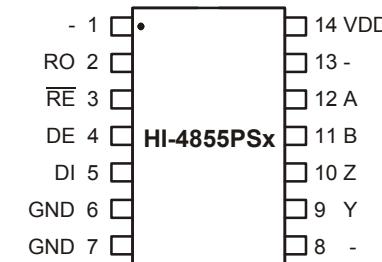
## PIN CONFIGURATIONS (Top Views)



8-Pin Plastic SOIC package (Narrow Body)



HI-4855PCx  
16- pin 4mm x 4mm Chip-scale package



14-Pin Plastic SOIC package (Narrow Body)

**PIN DESCRIPTIONS**

SIGNAL	FUNCTION	DESCRIPTION
RO	OUTPUT	Receiver Output. If $V_{ID} \geq -50mV$ , then RO is high. If $V_{ID} < -150mV$ then RO is low. If the bus is shorted, open or terminated but not driven by another terminal, RO will be high.
$\overline{RE}$	INPUT	Receiver Enable. $\overline{RE}$ = Low enables the receiver. $\overline{RE}$ High forces the receiver output (RO) into a high impedance state. Internal 450KΩ pull-down resistor
DE	INPUT	Driver Enable. DE = high enables the driver. DE = low will force the driver output into a high impedance state and the device will function as a line receiver if $\overline{RE}$ is also low. Internal 450KΩ pull-up resistor
DI	INPUT	Driver Input. Forces the logic state of the Driver's output, if Driver is enabled. Internal 450KΩ pull-up resistor
GND	POWER	Chip ground, 0V Supply
A, Y	ANALOG I/O	Non-inverting Receiver Input / Driver Output.
B, Z	ANALOG I/O	Inverting Receiver Input / Driver Output.
VDD	POWER	Positive Supply: $3.0V \leq VDD \leq 5.5V$

**TX FUNCTION TABLE**

TRANSMITTING				
INPUTS		LINE CONDITION	OUTPUTS	
$\overline{RE}$	DE	DI	B	A
X	1	1	Transmit logic high	0 1
X	1	0	Transmit logic low	1 0
0	0	X	Disable	Hi-Z Hi-Z
1	0	X	Shutdown	Hi-Z Hi-Z

**RX FUNCTION TABLE**

RECEIVING				
INPUTS		BUS PINS $V_{ID} = V_A - V_B$	OUTPUT RO	OPERATION
$\overline{RE}$	DE			
0	0	$-150mV < V_{ID} < -50mV$	X	Undefined Input
0	X	$-50mV \leq V_{ID}$	1	Receiver logic high
0	X	$V_{ID} \leq -150mV$	0	Receiver logic low
0	0	Open or Shorted	1	Default
0	0	Idle and terminated	1	Default
1	1	X	Hi-Z	Disabled
1	0	X	Hi-Z	Shutdown

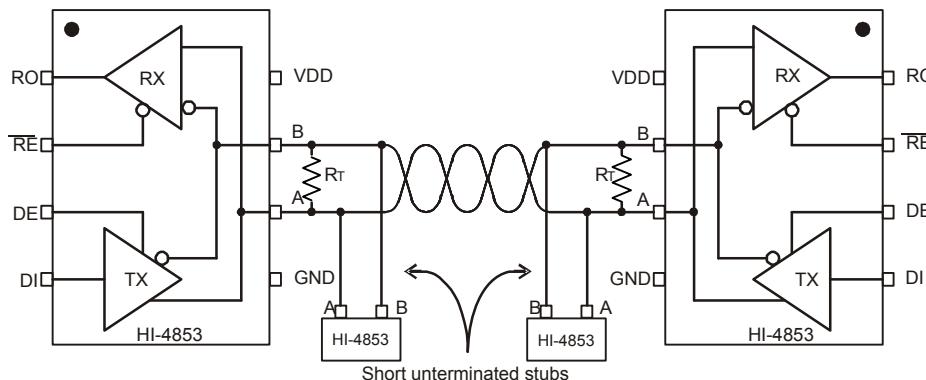
**Typical Operating Circuit**

Figure 1 - Typical half-duplex configuration

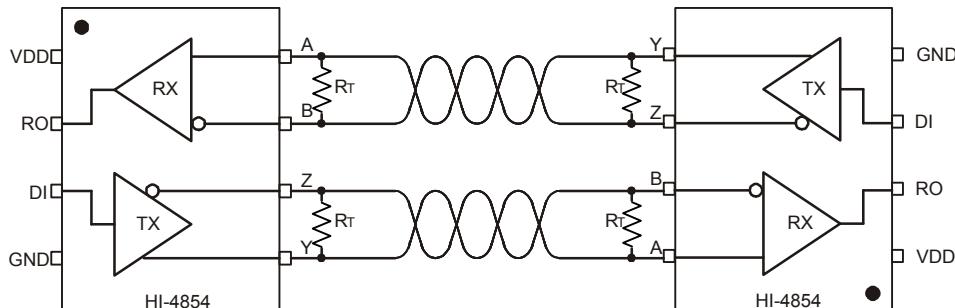


Figure 2 - Typical full-duplex 8-pin configuration

**ABSOLUTE MAXIMUM RATINGS**

(Voltages referenced to GND = 0V)

Supply Voltage, VDD:.....	7 V	Operating Temperature Range:(Industrial).....	-40°C to +85°C
Control Input Currents: .....	-100mA to 100mA	(Hi-Temp).....	-55°C to +125°C
Control Input Voltages:.....	-0.5V to VDD + 0.5V		
Digital Input Voltages (DI, DE, RE):.....	-0.5V to VDD + 0.5V		
Bus Voltage (AY, BZ):.....	+25V	Internal Power Dissipation:.....	900mW
Digital Output Voltage (RO):.....	-0.5V to V + 0.5V	Storage Temperature Range: .....	-65°C to +150°C
Short-Circuit Duration, Driver (V: ±15V).....	∞		
ESD (Human Body Model):			
AY, BZ, VDD, GND pins:.....	±16KV	Solder Temperature: (Reflow).....	260°C
DI, DE, RE, RO pins:.....	±8KV		

**NOTE:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**SPECIFIED OPERATING CONDITIONS**

PARAMETERS	SYMBOL	CONDITIONS	LIMITS			UNIT
			MIN	TYP	MAX	
Supply Voltage	V <sub>DD</sub>		3.0	3.3 / 5.0	5.5	V
Temperature	T		-55		125	°C
TX Common-Mode Bus Loading	V <sub>OCM</sub>	See Figure 4	-7		12	V
RX Input Common-Mode Voltage	V <sub>ICM</sub>	Half-Duplex	-16		20	V
Differential Load Resistance	R <sub>L</sub>		54	60	∞	Ω
Differential Load Capacitance	C <sub>L</sub>			100		pF
Digital Input High Voltage	V <sub>IH</sub>	DE, DI, RE	70			%V <sub>DD</sub>
Digital Input Low Voltage	V <sub>IL</sub>	DE, DI, RE			30	%V <sub>DD</sub>
Digital Input Current high	I <sub>IH</sub>	DE, DI, V <sub>IH</sub> = V <sub>DD</sub>			1	μA
Digital Input Pull-Down Current	I <sub>PD</sub>	RE, V <sub>IH</sub> = V <sub>DD</sub>	6		18	μA
Digital Input Current low	I <sub>IL</sub>	RE, V <sub>IH</sub> = 0	-1			μA
Digital Input Pull-Up Current	I <sub>PU</sub>	DE, DI, V <sub>IH</sub> = 0V	-18		-6	μA

**DRIVER DC ELECTRICAL CHARACTERISTICS**

VDD = 3.0V to 3.6V or 4.5V to 5.5V; T = -55°C to 125°C; MIN and MAX values are at range boundaries

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Differential Output Voltage with no load	V <sub>OD1</sub>	R <sub>L</sub> = ∞	3	V <sub>DD</sub> -0.1		V <sub>DD</sub>	V <sub>DD</sub> -0.1		V <sub>DD</sub>	V
Differential Output Voltage into load with no common-mode voltage	V <sub>OD2</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF	3	1.5		3.0	2.45		4.0	V
Differential Output Voltage into load with applied common-mode voltage	V <sub>OD3</sub>	-7V ≤ V <sub>OCM</sub> ≤ 12V T <sub>A</sub> = 25°C	4	1.5		3.0	2.45		4.0	V
Differential Output Over/Under Shoot						5.5			3.2	%V <sub>OD</sub>
Change in Differential Output Voltage between logic states	ΔV <sub>OD</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF	3	-125		125	-125		125	mV
Output Common-Mode Voltage	V <sub>OCM</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF	4	1.40	1.60	2.0	2.15	2.45	3.0	V
Change in output Common-Mode Voltage between logic states	ΔV <sub>OCM</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF	4	-125		125	-150		150	mV
Bus Pin Leakage Current (High-Z Power On)	I <sub>OHZ1</sub>	DE=0, -15V ≤ V <sub>OCM</sub> ≤ 15V DE=0, -12V ≤ V <sub>OCM</sub> ≤ 15V		-200		200	-200		200	μA
Bus Pin Leakage Current (Power Off)	I <sub>OHZ2</sub>	V <sub>OCM</sub> = ±15V		-200		200	-200		200	μA
Peak Short Circuit Current	I <sub>SCPK</sub>	DE = V <sub>DD</sub> , Bus Pin = ±15		-230		230	-250		250	mA
Steady State Short Circuit Current	I <sub>SC</sub>	DE = V <sub>DD</sub> , Bus Pin = ±15		0		50	0		50	μA
Differential Output Capacitance	C <sub>OD</sub>	DE = 0				16			16	pF
Static Supply Current	I <sub>DD</sub>	DE=V <sub>DD</sub> , RE=0, R <sub>L</sub> =∞			8	10		10	12	mA
Supply Current (Shutdown)	I <sub>DDQ</sub>	DE=0, RE=V <sub>DD</sub> , R <sub>L</sub> =∞			90	110		125	400	μA

## DRIVER SWITCHING CHARACTERISTICS

VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Propagation Delay Low - to - High	t <sub>PDR</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> =50pF	5 & 6	17	26	33	16	24	30	ns
Propagation Delay High - to - Low	t <sub>PDF</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> =50pF	5 & 6	17	26	33	16	24	30	ns
Differential Rise Time	t <sub>r</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> =50pF	5 & 6	9	12	15	8	11	16	ns
Differential Fall Time	t <sub>f</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> =50pF	5 & 6	9	12	15	8	11	16	ns
Output Pulse Skew	t <sub>MSK</sub>	R <sub>L</sub> = 54Ω, C <sub>L</sub> =50pF	5 & 6		2	8		2	8	ns
Driver Enable to Output High	t <sub>ZH</sub>	R <sub>L</sub> = 500Ω, C <sub>L</sub> =50pF	7		95	120		90	117	ns
Driver Enable to output Low	t <sub>ZL</sub>	R <sub>L</sub> = 500Ω, C <sub>L</sub> =50pF	7		95	120		90	117	ns
Driver Disable from Output High	t <sub>HZ</sub>	R <sub>L</sub> = 500Ω, C <sub>L</sub> =50pF	7		20	33		18	30	ns
Driver Disable from Output Low	t <sub>LZ</sub>	R <sub>L</sub> = 500Ω, C <sub>L</sub> =50pF	7		20	33		18	30	ns
Shutdown to Active Output Delay	t <sub>ON</sub>	R <sub>L</sub> = 500Ω, C <sub>L</sub> =50pF	7			10			10	μs
Shutdown Delay	t <sub>OFF</sub>					10			10	μs

## RECEIVER DC ELECTRICAL CHARACTERISTICS

VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Differential Input Threshold Voltage	V <sub>TH</sub>	-15 ≤ V <sub>ICM</sub> ≤ +20		-200	-100	-50	-200	-100	-50	mV
Input Hysteresis	V <sub>HYS</sub>	V <sub>ICM</sub> = 0V		17	28	33	17	28	33	mV
Input Resistance	R <sub>IN</sub>	-15 ≤ V <sub>ICM</sub> ≤ +20		80	92		80	92		KΩ
RO Output High Level	V <sub>OH</sub>	V <sub>ICM</sub> = +200mV I <sub>OUT</sub> = -3.0mA		90%			90%			V <sub>DD</sub>
RO Output Low Level	V <sub>OL</sub>	V <sub>ICM</sub> = -200mV I <sub>OUT</sub> = +3.0mA				10%			10%	V <sub>DD</sub>
RO Output Hi-Z Leakage Current	I <sub>OZH</sub>	0V ≤ V <sub>RO</sub> ≤ V <sub>DD</sub> :		-1		1	-1		1	μA

## RECEIVER SWITCHING CHARACTERISTICS

VDD = 3.0V - 3.6V or 4.5V - 5.5V as noted , Operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	FIGURE	VDD = 3.3V ± 10%			VDD = 5.0V ± 10%			UNIT
				MIN	TYP	MAX	MIN	TYP	MAX	
Propagation Delay Low - to - High	t <sub>RPDR</sub>	V <sub>ID</sub> = +1.5V, C <sub>L</sub> =15pF	8	20	26	32	20	26	32	ns
Propagation Delay High - to - Low	t <sub>RPDF</sub>	V <sub>ID</sub> = -1.5V, C <sub>L</sub> =15pF	8	20	26	32	20	26	32	ns
RO Output Rise Time	t <sub>Rr</sub>	V <sub>ID</sub> = +1.5V, C <sub>L</sub> =15pF	8	1.1	1.9	3.3	1.1	1.9	3.3	ns
RO Output Fall Time	t <sub>Rf</sub>	V <sub>ID</sub> = -1.5V, C <sub>L</sub> =15pF	8	1.1	1.9	3.3	1.1	1.9	3.3	ns
Output Pulse Skew	t <sub>RMSK</sub>	V <sub>ID</sub> = +1.5V, C <sub>L</sub> =15pF	8		0.8	1.6		0.8	1.6	ns
Receiver Enable to RO Output High	t <sub>RZH</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9		12	16		12	16	ns
Receiver Enable to output Low	t <sub>RZL</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9		12	16		12	16	ns
Receiver Disable from Output High	t <sub>RHZ</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9		6	10		6	10	ns
Receiver Disable from Output Low	t <sub>RLZ</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9		6	10		6	10	ns
Shutdown to RO Active Output Delay	t <sub>RON</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9			5			5	μs
Shutdown Delay to RO HiZ	t <sub>ROFF</sub>	R <sub>L</sub> = 1KΩ, C <sub>L</sub> =15pF	9		60	100		60	100	ns

## TEST CIRCUITS

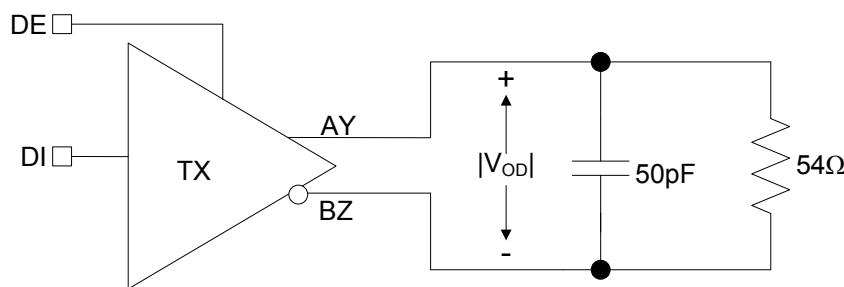


Figure 3 - Driver DC Characteristics ( $V_{OD}$ ,  $V_{OD2}$ , and  $\Delta V_{OD}$ )

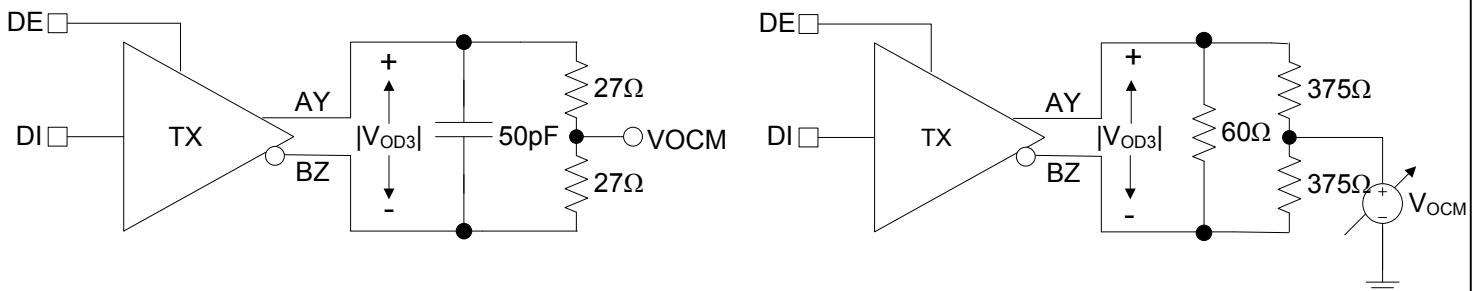


Figure 4 - Driver DC Characteristics with and without Common-Mode Loading ( $V_{OCM}$ ,  $V_{OD3}$ , and  $\Delta V_{OD}$ )

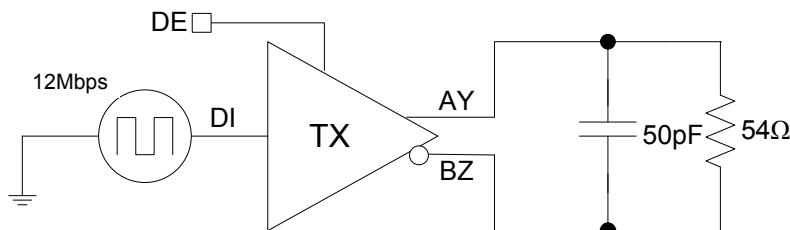


Figure 5 - Driver Switching Characteristics ( $t_{PDR}$ ,  $t_{PDF}$ ,  $t_r$  and  $t_f$ )

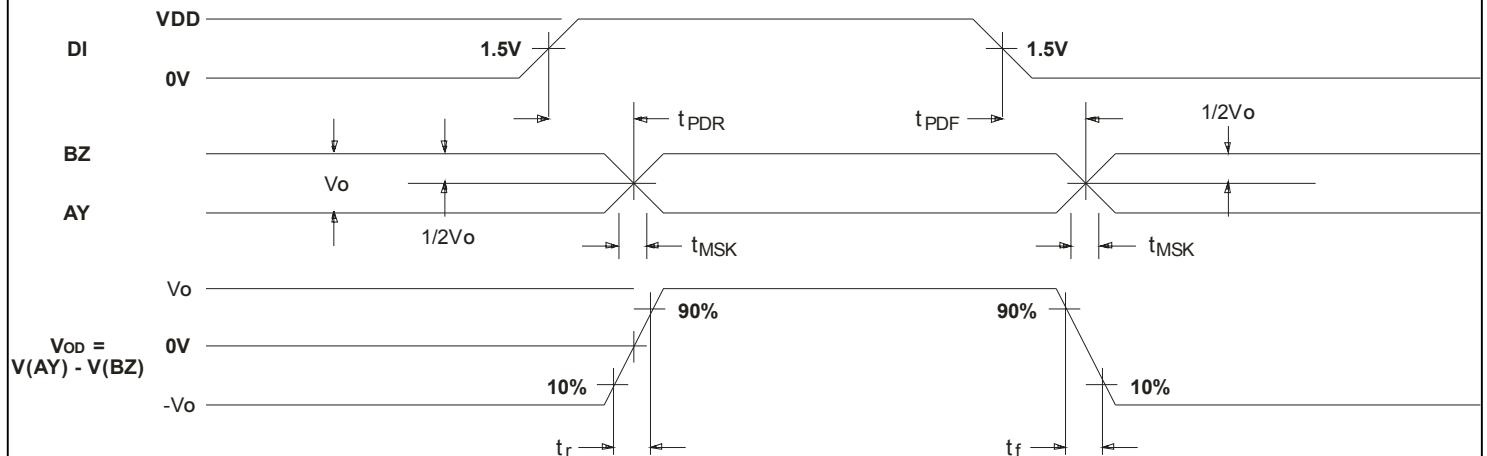
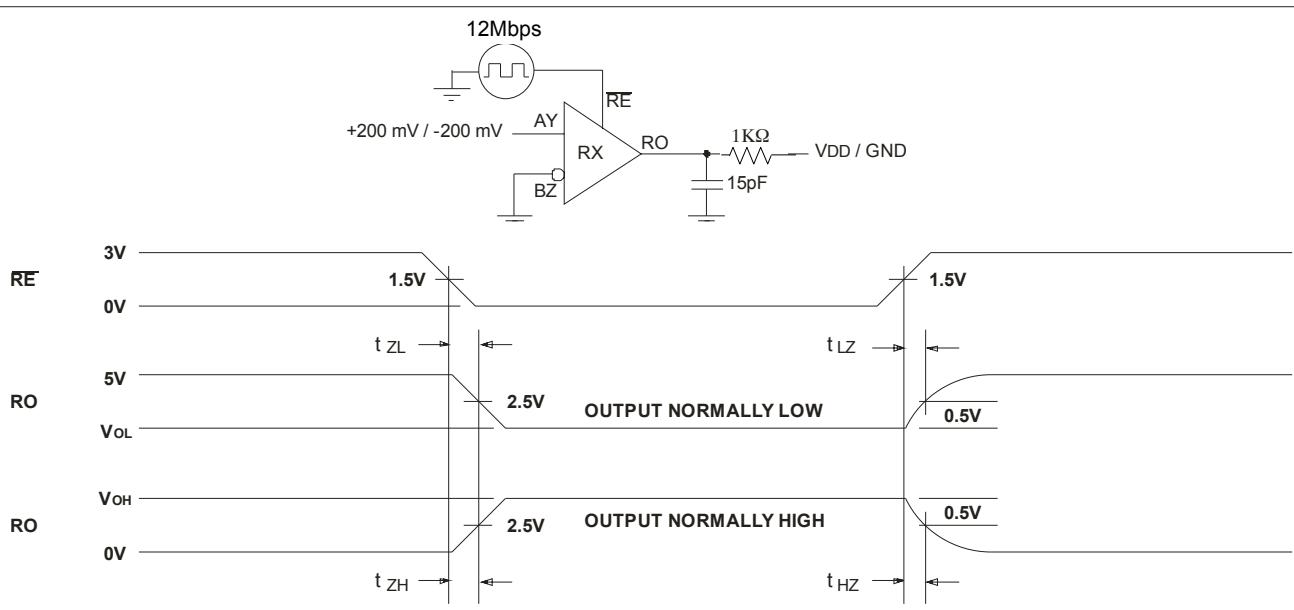
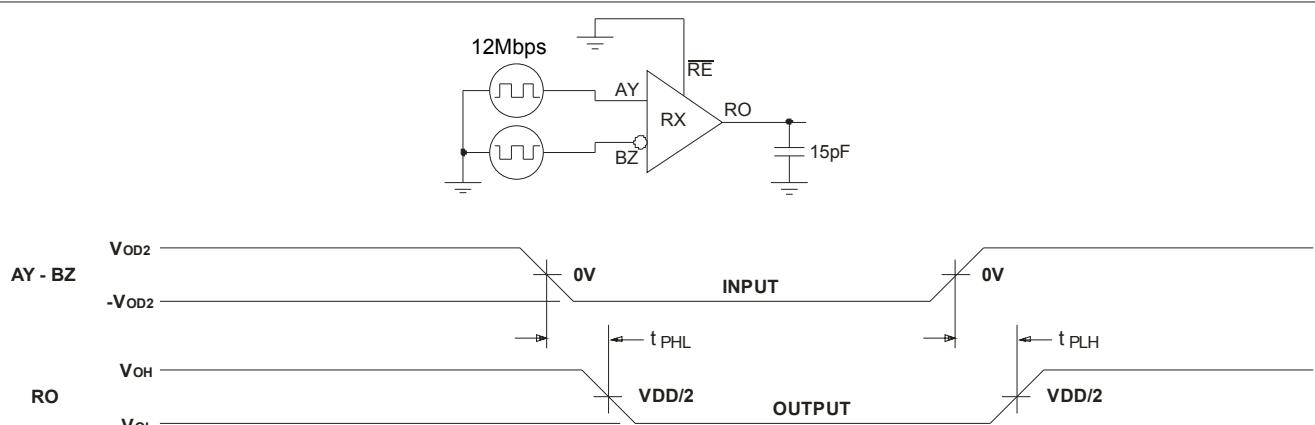
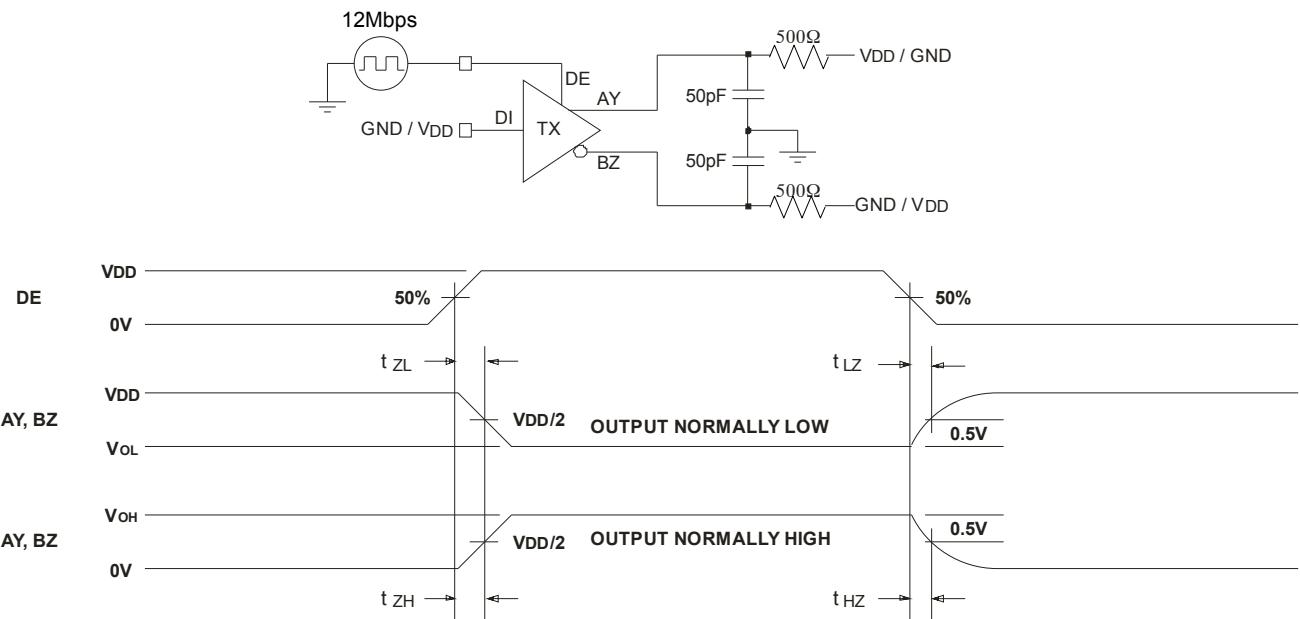
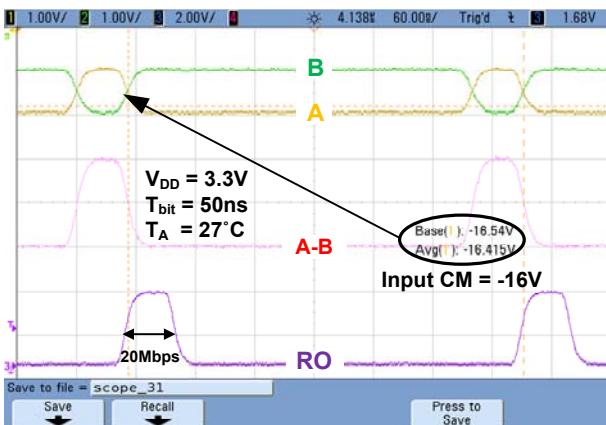


Figure 6. Driver Switching Waveforms

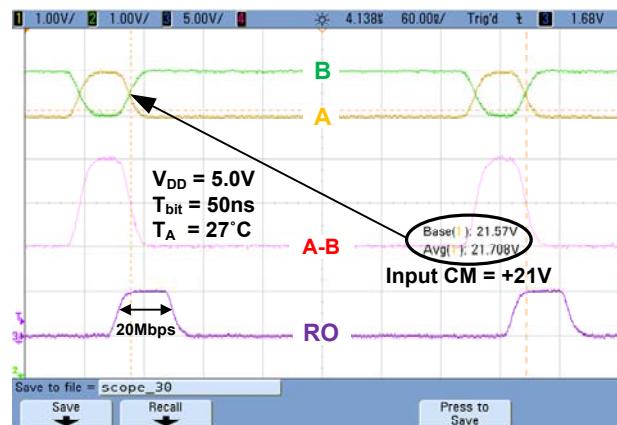


## EXTENDED COMMON-MODE PERFORMANCE CHARACTERISTICS

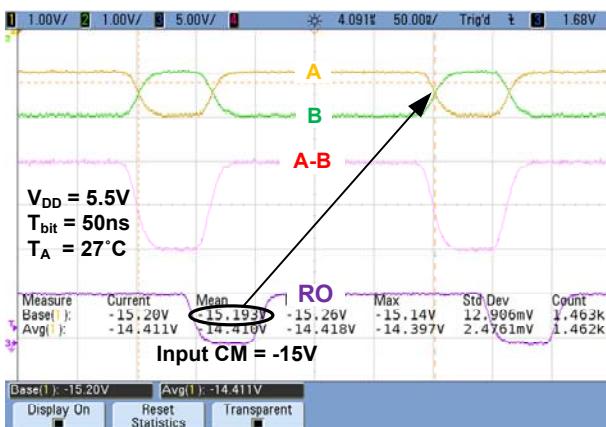
**RX Extended Common-Mode Range:  
Typical Supply, Maximum (-) Common-Mode**



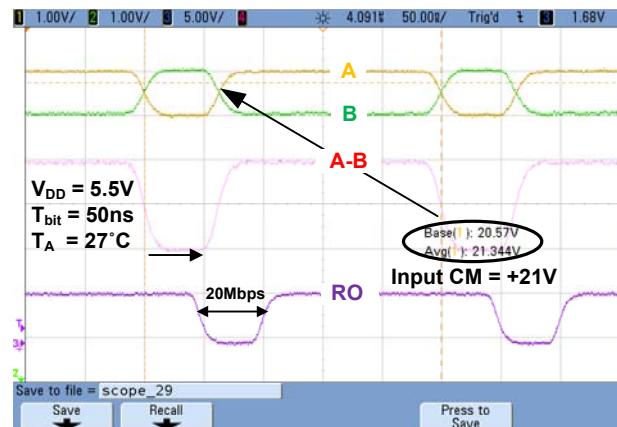
**RX Extended Common-Mode Range:  
Typical Supply, Maximum (+) Common-Mode**



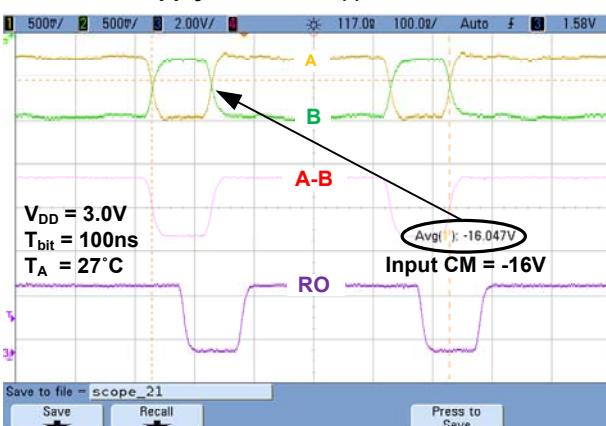
**RX Extended Common-Mode Range:  
Maximum Supply, Maximum (-) Common-Mode**



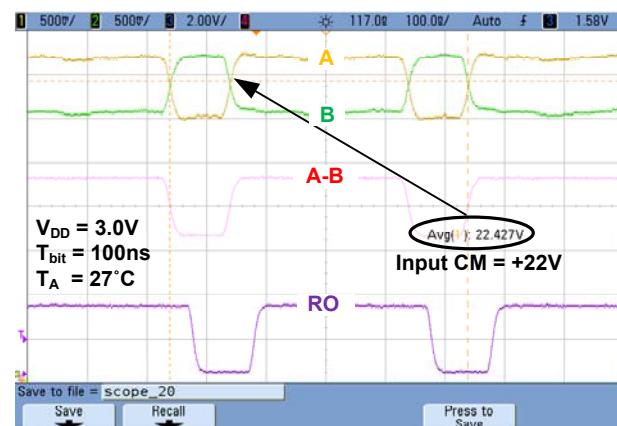
**RX Extended Common-Mode Range:  
Maximum Supply, Maximum (+) Common-Mode**



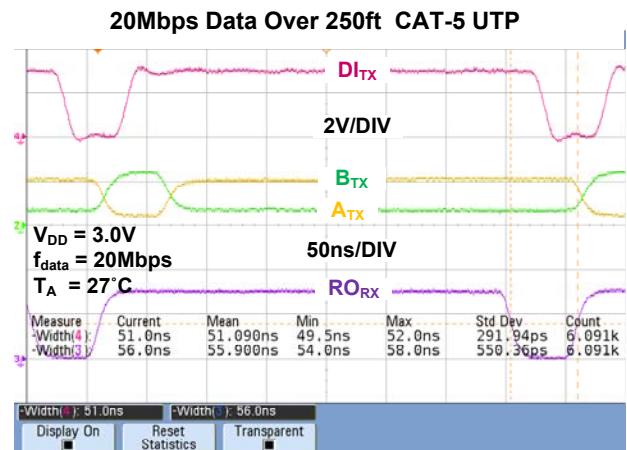
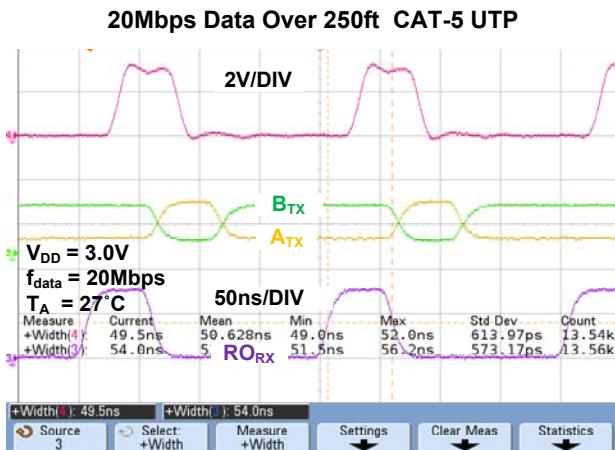
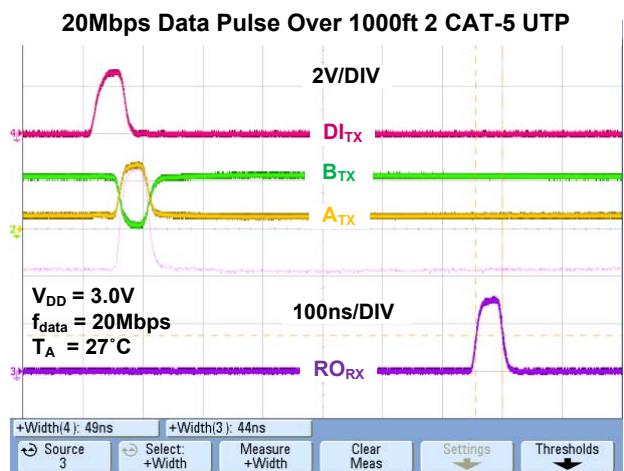
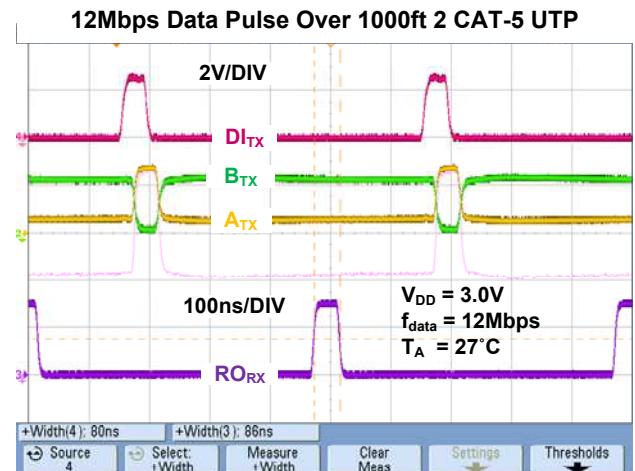
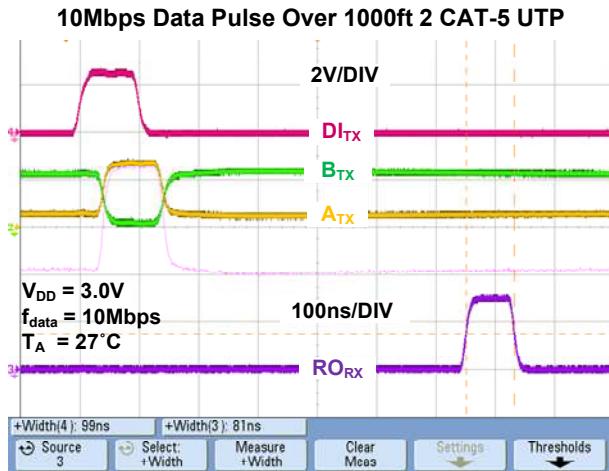
**RX Extended Common-Mode Range:  
Minimum Supply, Maximum (-) Common-Mode**



**RX Extended Common-Mode Range:  
Minimum Supply, Maximum (+) Common-Mode**

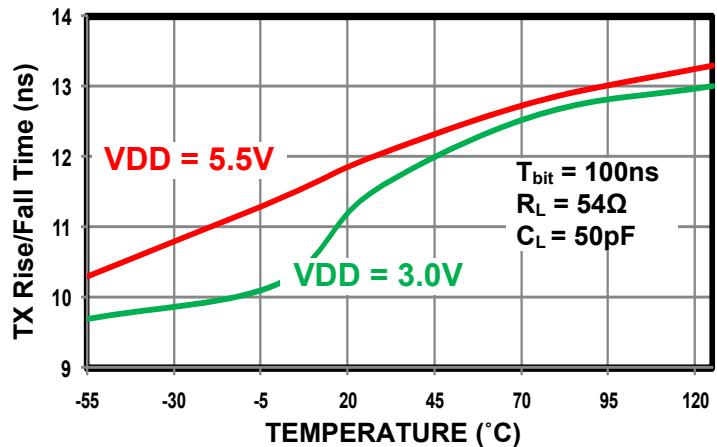


## High-Speed Performance Characteristics Over Distance

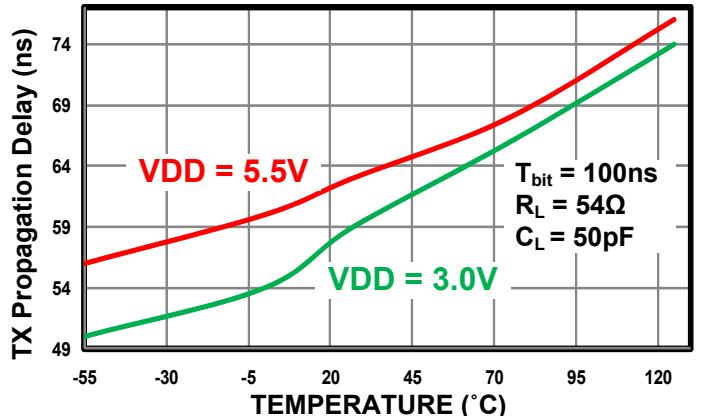


## PERFORMANCE CHARACTERISTICS OVER SUPPLY AND TEMPERATURE

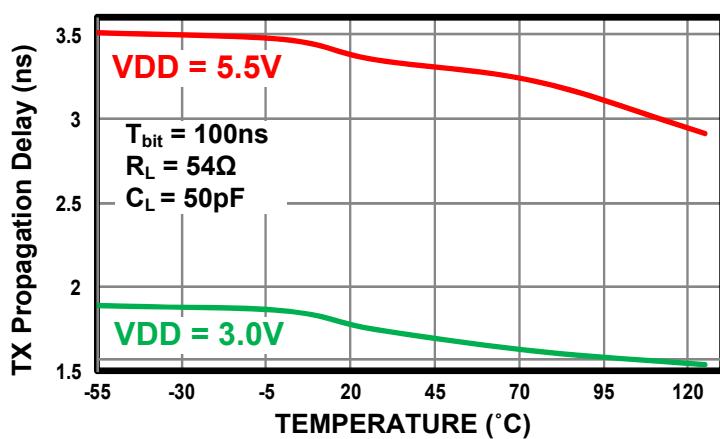
TX Differential Rise/Fall Time vs. Temperature



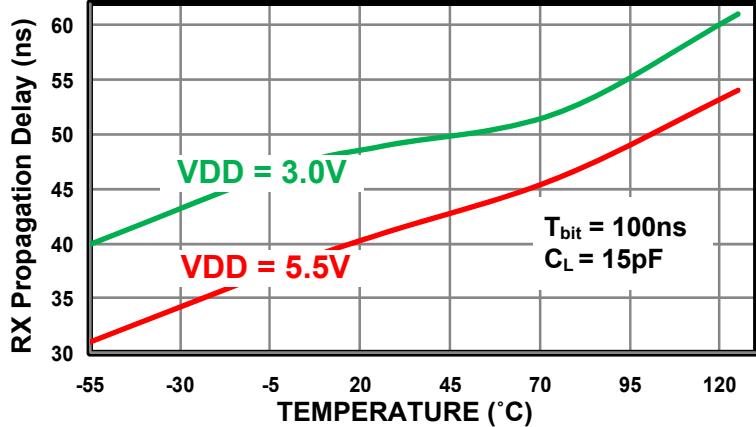
TX Differential Rise/Fall Time vs. Temperature



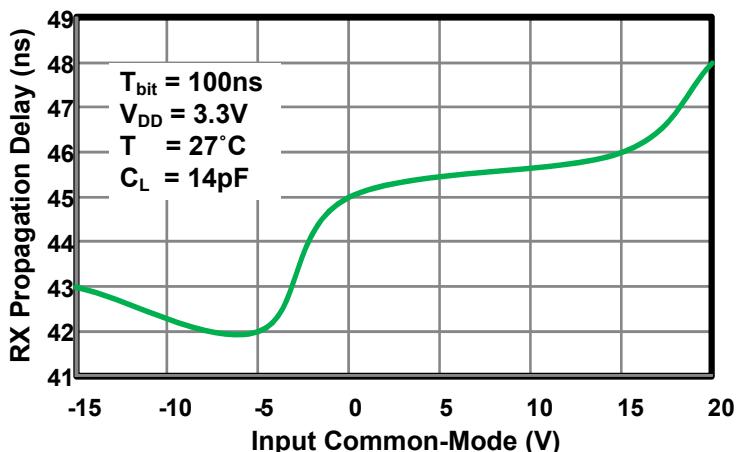
TX Differential Zero To Peak Amplitude



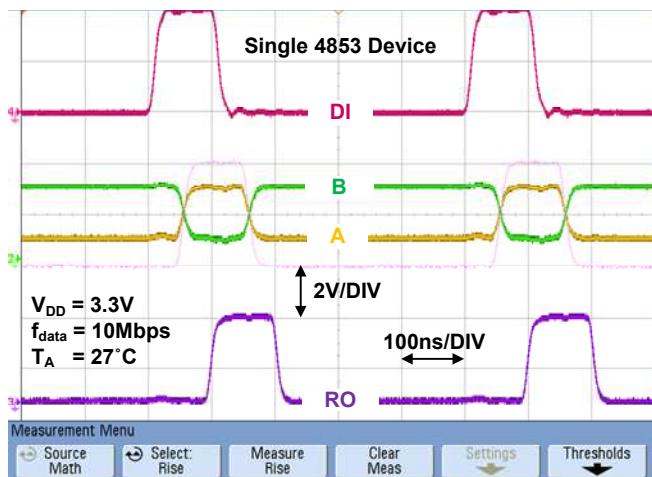
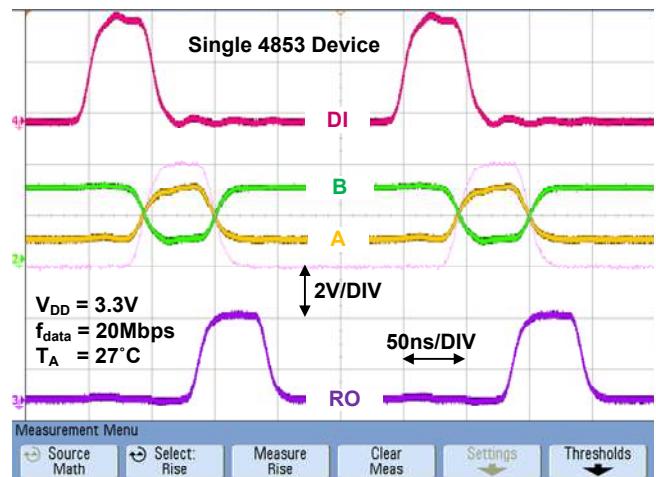
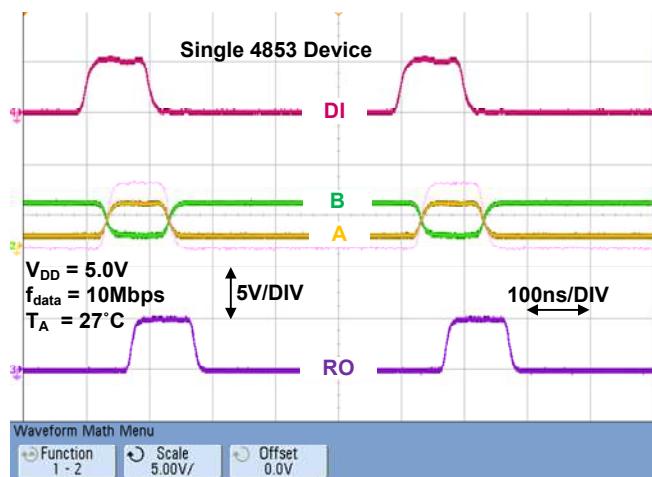
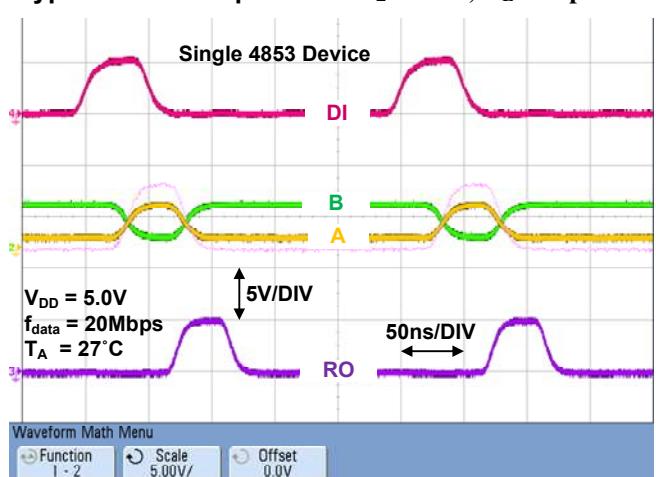
RX Propagation Delay vs. Temperature



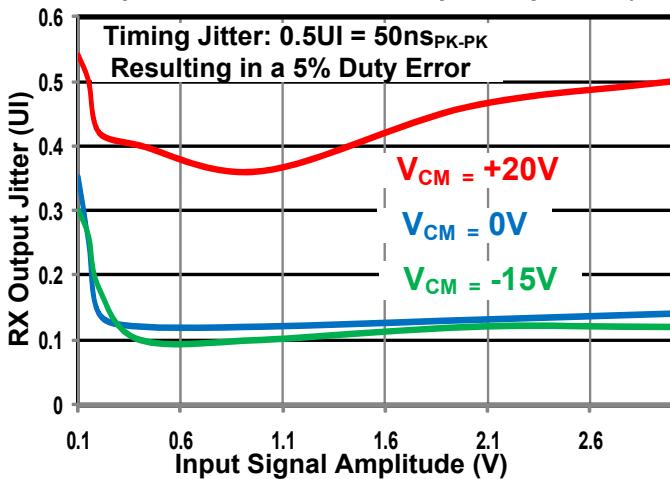
RX Propagation Delay vs. Common-Mode



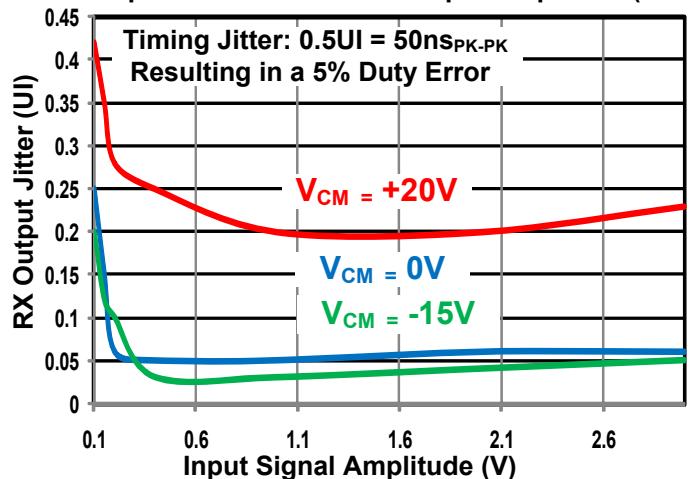
## TYPICAL TRANSCEIVER PERFORMANCE CHARACTERISTICS

Typical 10Mb/s Operation:  $R_L = 54\Omega$ ;  $C_L = 50\text{pF}$ Typical 20Mb/s Operation:  $R_L = 54\Omega$ ;  $C_L = 50\text{pF}$ Typical 10Mb/s Operation:  $R_L = 54\Omega$ ;  $C_L = 50\text{pF}$ Typical 20Mb/s Operation:  $R_L = 54\Omega$ ;  $C_L = 50\text{pF}$ 

RX Output Jitter Over CM and Input Amplitude (5.5V)



RX Output Jitter Over CM and Input Amplitude (3.0V)



## ORDERING INFORMATION

**HI-485x XX X X**

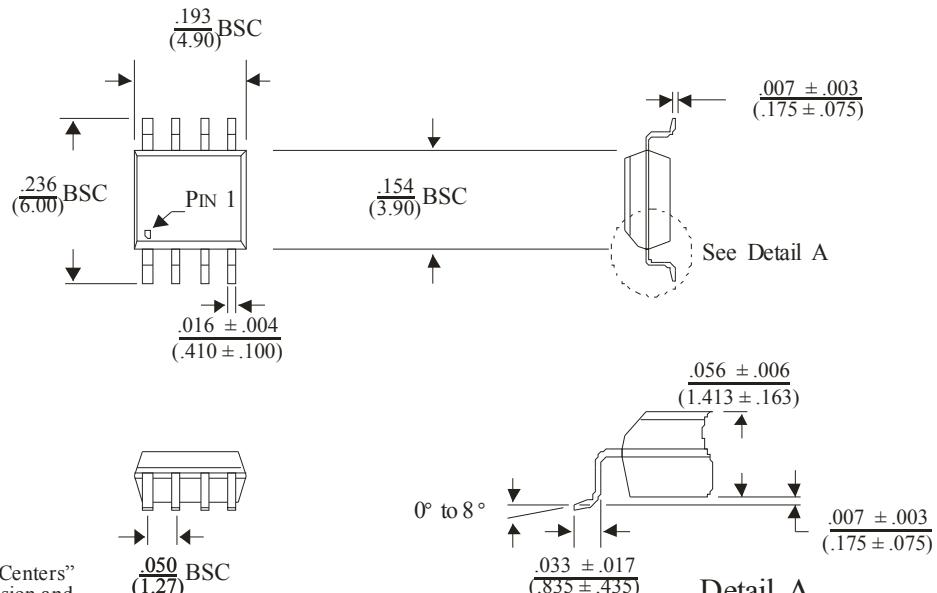
PART NUMBER	LEAD FINISH		
Blank	Tin / Lead (Sn / Pb) Solder		
F	100% Matte Tin (Pb-free, RoHS compliant)		
PART NUMBER	TEMPERATURE RANGE	FLOW	BURN IN
I	-40°C TO +85°C	I	NO
T	-55°C TO +125°C	T	NO
M	-55°C TO +125°C	M	YES
PART NUMBER	PACKAGE DESCRIPTION		
PC	16 PIN PLASTIC 4 x 4 mm CHIP SCALE (16PCS) (HI-4855 only. No M-flow)		
PS	8 PIN PLASTIC NARROW BODY SOIC (8HN) (HI-4853, HI-4854)		
PS	14 PIN PLASTIC NARROW BODY SOIC (14HN) (HI-4855 only)		
CR	8 PIN CERDIP (8D) not available Pb-free (HI-4853, HI-4854)		
PART NUMBER	FUNCTION		
4853	HALF DUPLEX TRANSCEIVER		
4854	FULL DUPLEX TRANSCIEVER ALWAYS ENABLED		
4855	FULL DUPLEX TRANSCEIVER WITH ENABLE PINS		

## REVISION HISTORY

<b>Revision</b>	<b>Date</b>	<b>Description of Change</b>
DS4853, Rev New	03/30/2012	Initial Release
Rev. A	05/21/2012	Fix typos on package ordering information
Rev. B	08/2/2012	Updated Rx Function Table rows 2 and 3 on p. 2 for DE = X. Updated package drawings for SOIC-8 (8HN), QFN-16 (16PCS) and SOIC-14 (14HN) packages.
Rev. C	02/25/2013	Correct typo on nRE pull-up resistor (should be pull-down). Update Digital Input pull-up/pull-down current. Update typo in Figure 4 resistors. Update solder temperature (reflow) in Max. Ratings

**8-PIN PLASTIC SMALL OUTLINE (SOIC) - NB**  
(Narrow Body)

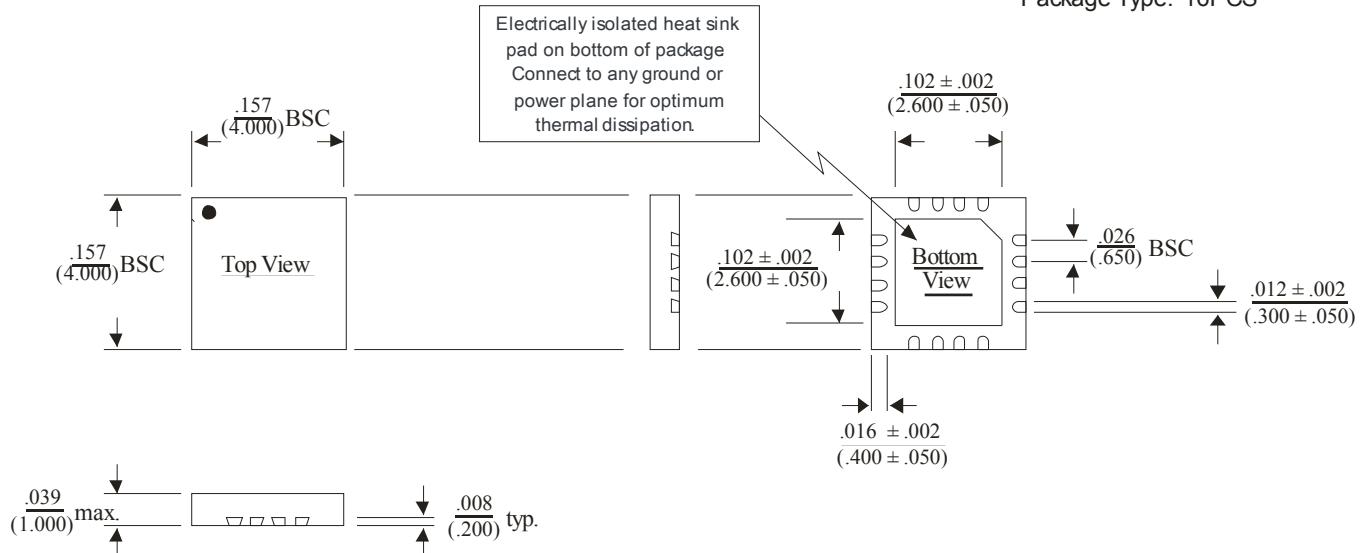
*inches (millimeters)*  
Package Type: 8HN



BSC = "Basic Spacing between Centers" is the theoretical true position dimension and has no tolerance. (EDEC Standard 95)

**16-PIN PLASTIC CHIP-SCALE PACKAGE**

*inches (millimeters)*  
Package Type: 16PCS

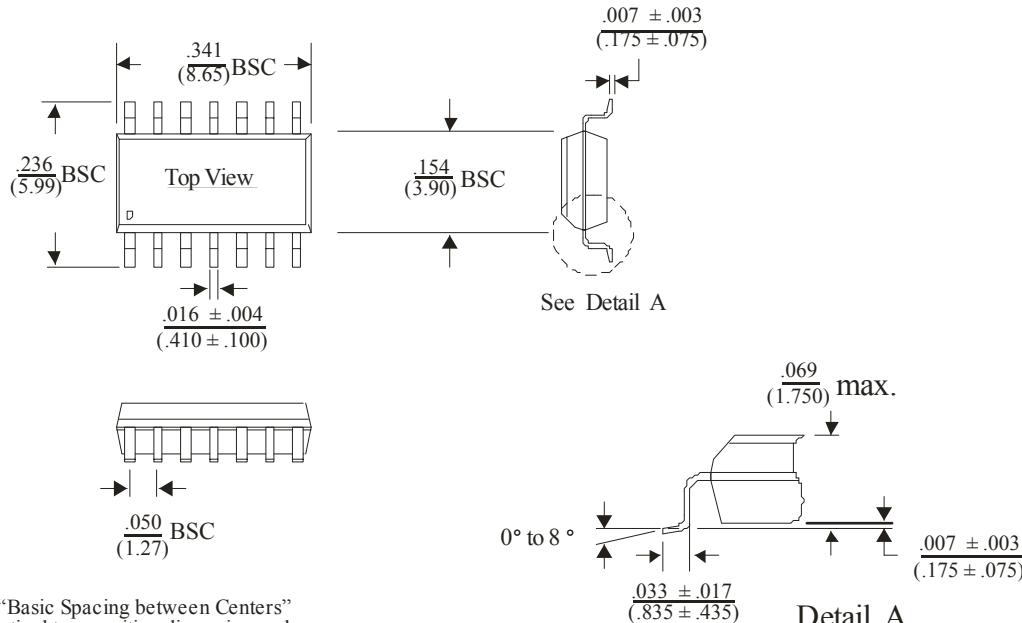


BSC = "Basic Spacing between Centers" is the theoretical true position dimension and has no tolerance. (EDEC Standard 95)

### 14-PIN PLASTIC SMALL OUTLINE (SOIC) - NB (Narrow Body)

*inches (millimeters)*

Package Type: 14HN

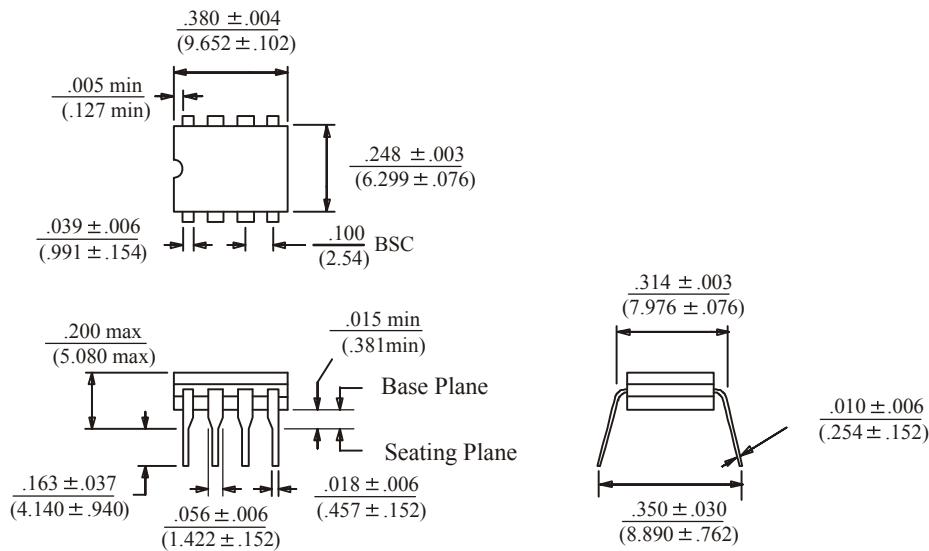


BSC = "Basic Spacing between Centers" is theoretical true position dimension and has no tolerance. ( JEDEC Standard 95)

### 8-PIN CERDIP

*inches (millimeters)*

Package Type: 8D



BSC = "Basic Spacing between Centers" is theoretical true position dimension and has no tolerance. ( JEDEC Standard 95)