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## Amplified HumPRO<sup>™</sup> Series 900MHz Transceiver Module Data Guide

Wireless made simple<sup>®</sup>

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All RF products are susceptible to RF interference that can prevent <u>communication</u>. RF products without frequency agility or hopping implemented are more subject to interference. This module does have a frequency hopping protocol built in, but the developer should still be aware of the risk of interference.

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## **Table of Contents**

- 1 Description
- 1 Features
- 2 Ordering Information
- 2 Absolute Maximum Ratings
- **3 Electrical Specifications**
- 5 Typical Performance Graphs
- 10 Pin Assignments
- 10 Pin Descriptions
- 12 Module Pin Assignments
- 13 Module Dimensions
- 14 Theory of Operation
- 15 Module Description
- 16 Overview
- 18 Addressing Modes
- 20 Automatic Addressing
- 20 Address Register Use
- 21 Acknowledgements and Assured Delivery
- 22 Frequency Hopping Spread Spectrum
- 23 Compatibility with the 250 Series
- 23 Networking
- 24 Transmitting Packets
- 25 Receiving Packets
- 29 Using the Buffer Empty (BE) Line
- 30 Exception Engine
- 32 Carrier Sense Multiple Access (CSMA)
- 33 Using the Command Response (CRESP) Line
- 34 Using the CMD Line
- 35 AES Encryption
- 38 Using the MODE\_IND Line
- 39 Using the PB Line

- 40 Restore Factory Defaults
- 40 Using the Low Power Features
- 41 Baud Rate and Transmitter Output Power
- 42 The Command Data Interface
- 43 Reading from Registers
- 44 Writing to Registers
- 45 Command Length Optimization
- 46 Example Code for Encoding Read/Write Commands
- 48 The Command Data Interface Command Set
- 95 Typical Applications
- 96 Usage Guidelines for FCC Compliance
- 96 Additional Testing Requirements
- 97 Information to the user
- 98 Product Labeling
- 98 FCC RF Exposure Statement
- 98 Antenna Selection
- 100 Power Supply Requirements
- 100 Antenna Considerations
- 101 Interference Considerations
- 102 Pad Layout
- 102 Castellation Version Reference Design
- 103 Microstrip Details
- 104 Board Layout Guidelines
- 105 Helpful Application Notes from Linx
- 106 Production Guidelines
- 106 Hand Assembly
- 106 Automated Assembly
- 108 General Antenna Rules
- 110 Common Antenna Styles
- 112 Regulatory Considerations
- 114 Notes

### Amplified HumPRO<sup>™</sup> Series 900MHz RF Transceiver Module

## Data Guide



The Amplified HumPRO<sup>™</sup> Series transceiver module is the most cost effective and easiest to implement solution for a long range wireless connection. It is a frequency hopping spread spectrum (FHSS) transceiver designed for the reliable transfer of digital data. It has a fast lock time so it can quickly wake up, send data and go back to sleep. A high-power 25dBm amplifier gives the module exceptional range.



Figure 1: Package Dimensions

The module has several features that increase the data transfer reliability. It ensures that no other modules are transmitting before it begins transmitting data. Automatic acknowledgements ensure that the remote side received valid data. Multiple hopping patterns enable several systems to operate in proximity without interference. A standard UART interface is used for module configuration and data transfer. The module's code is pre-compiled, so a few serial commands are all that are needed for configuration. No compiler or special tools are required.

All modules have a unique 32-bit serial number that can be used as an address. Source and destination addressing support point-to-point, broadcast and star links. Address masking by the receiving module allows for creating subnets. Other network topologies can also be implemented.

Housed in a tiny compact reflow-compatible SMD package, the transceiver requires no external RF components except an antenna, which greatly simplifies integration and lowers assembly costs. The module has obtained FCC and Industry Canada modular certifications.

#### Features

- Long Range (up to 8 miles)
- Simple UART interface
- Pre-compiled code
- Mixed-mode systems

- FCC and IC Pre-certified
- Secure and encrypted
- Multiple addressing modes
- Tiny extended PLCC-44 footprint
- 1 -
- Revised 6/19/2017

#### **Ordering Information**

Ordering Information	
Part Number	Description
HUM-A-900-PRO-CAS	Amplified HumPRO <sup>™</sup> Series High Power Data Transceiver with Castellation Connection
HUM-A-900-PRO-UFL	Amplified HumPRO <sup>™</sup> Series High Power Data Transceiver with U.FL Connector
EVM-A-900-PRO-CAS	Amplified HumPRO <sup>™</sup> Series Carrier Board, Castellation Connection with an edge-mount RP-SMA connector
EVM-A-900-PRO-UFL	Amplified HumPRO <sup>™</sup> Series Carrier Board, U.FL Connector
MDEV-A-900-PRO	Amplified HumPRO <sup>™</sup> Series Master Development System

Figure 2: Ordering Information

#### Absolute Maximum Ratings

Absolute Maximum Ratings				
Supply Voltage V $_{\rm cc}$	-0.3	to	+3.9	VDC
Any Input or Output Pin	-0.3	to	V <sub>cc</sub> + 0.3	VDC
RF Input		+5		dBm
Operating Temperature	-40	to	+85	°C
Storage Temperature	-40	to	+85	°C

Exceeding any of the limits of this section may lead to permanent damage to the device. Furthermore, extended operation at these maximum ratings may reduce the life of this device.

Figure 3: Absolute Maximum Ratings

Warning: This product incorporates numerous static-sensitive components. Always wear an ESD wrist strap and observe proper ESD handling procedures when working with this device. Failure to observe this precaution may result in module damage or failure.

#### **Electrical Specifications**

Amplified HumPRO <sup>™</sup> Serie	es Transce	eiver Spec	ifications			
Parameter	Symbol	Min.	Тур.	Max.	Units	Notes
Power Supply						
Operating Voltage	V <sub>cc</sub>	2.7	3.3	3.6	VDC	
TX Supply Current	I <sub>CCTX</sub>					
@ +25dBm			380	*	mA	1,2
@ +22dBm			260	*	mA	1,2
RX Supply Current	I <sub>CCRX</sub>		39		mA	1,2,3
Power-Down Current	I <sub>PDN</sub>		<1		μA	1,2
RF Section						
Operating Frequency Band	F <sub>c</sub>				MHz	
HUM-900-PRO-vvv		902		928	MHz	
Number of hop channels						
@ 19.2kbps RF Rate			50			
@ 153.6kbps RF Rate			26			
Channel spacing						
@ 19.2kbps RF Rate			375.9		kHz	
@ 153.6kbps RF Rate			751.81		kHz	
20 dB OBW						
@ 19.2kbps RF Rate			98		kHz	
@ 153.6kbps RF Rate			319		kHz	
Receiver BW						
@ 19.2kbps RF Rate			102		kHz	
@ 153.6kbps RF Rate			232		kHz	
FSK deviation						
@ 19.2kbps RF Rate			± 19.2		kHz	
@ 153.6kbps RF Rate			± 51		kHz	
Scan time / channel (avg)						
@ 19.2kbps RF Rate			1.2		ms	
@ 153.6kbps RF Rate			0.335		ms	
FHSS Lock time						
@ 19.2kbps RF Rate			63		ms	
@ 153.6kbps RF Rate			26		ms	
Modulation			2FSK			
Data Encoding			6/7 RLL			
Number of Hop Sequences				6		

Amplified HumPRO <sup>™</sup> Serie	es Transce	eiver Spec	ifications			
Parameter	Symbol	Min.	Тур.	Max.	Units	Notes
Receiver Section						
Saturation (max input level)						
@ 19.2kbps RF rate			-21		dBm	
@ 153.6kbps RF rate			-23		dBm	
IF Frequency			304.7		kHz	
Receiver Sensitivity						5
@ 19.2kbps RF rate			-108		dBm	5
@ 153.6kbps RF rate			-101		dBm	5
RSSI Dynamic Range						
@ 19.2kbps RF rate			85		dB	
@ 153.6kbps RF rate			80		dB	
Transmitter Section						
Max Output Power						
@ 19.2kbps RF rate	Po		+25		dBm	6
@ 153.6kbps RF rate	Po		+22		dBm	6
Minimum Output Power	Po		-9		dBm	6
2nd Harmonic Emissions	P <sub>H</sub>			-20	dBc	6
3rd Harmonic Emissions	P <sub>H</sub>			-54	dBuV/m	6,15
Antenna Port						
RF Impedance	R <sub>IN</sub>		50		Ω	4
Environmental						
Operating Temp. Range		-40		+85	°C	4
Timing						
Module Turn-On Time						
Via V <sub>cc</sub>		87		138	ms	4
Via POWER_DOWN			6		ms	4
Via Standby			6		ms	4
Serial Command Response						
Volatile R/W			0.4	5	ms	8
NV Update			2.4	31.5	ms	8
Factory Reset		204		329	ms	14
Channel Dwell Time				400	ms	
CMD low to trigger TX with option TXnCMD	t <sub>TXnCMD</sub>	2			ms	13

Parameter	Symbol	Min.	Тур.	Max.	Units	Notes
Interface Section						
UART Data rate		9,600		115,200	bps	
Input						
Logic Low	V			0.3*V <sub>cc</sub>	VDC	
Logic High	V <sub>IH</sub>	0.7*V <sub>cc</sub>			VDC	
Output						
Logic Low, MODE_IND, BE	V <sub>OLM</sub>			0.3*V <sub>cc</sub>	VDC	1,9
Logic High, MODE_IND, BE	V <sub>OHM</sub>	0.7*V <sub>cc</sub>			VDC	1,9
Logic Low	V <sub>OL</sub>			0.3*V <sub>cc</sub>		1,10
Logic High	V <sub>OH</sub>	0.7*V <sub>cc</sub>				1,10
CRESP Hold Time		10			Bits	11
Flash (Non-Volatile) Memory	Specificatic	ns				
Flash Write Cycles				16,000	cycles	12
<ul> <li>Measured at 3.3V V<sub>cc</sub></li> <li>Measured at 25°C</li> <li>Input power &lt; -60dBm</li> <li>Characterized but not tes</li> <li>PER = 1%</li> <li>Into a 50-ohm load</li> <li>No RF interference</li> <li>From end of command to</li> </ul>	sted o start of	10. 11. 12. 13. 14. 15.	6mA source End of CMI change in 0 Number of With CSMA Start of fac of last ACK Radiated fie	e/sink D_DATA_O CRESP register wri A disabled tory reset c response eld strength	UT stop ite opera commanc n @3m w	bit to tions I to end /

Figure 4: Electrical Specifications

#### **Typical Performance Graphs**



Figure 5: Amplified HumPRO<sup>™</sup> Series Transceiver Max Output Power vs. Supply Voltage



Figure 6: Amplified HumPRO<sup>™</sup> Series Transceiver Average Current vs. Transmitter Output Power at 2.7V



Figure 9: Amplified HumPRO<sup>™</sup> Series Transceiver Average TX Current vs. Transmitter Output Power at 3.3V



Figure 8: Amplified HumPRO<sup>™</sup> Series Transceiver TX Current vs. Supply Voltage at Max Power



Figure 7: Amplified HumPRO<sup>™</sup> Series Transceiver TX Current vs. Supply Voltage at 24dBm

- 7 -







Figure 12: Amplified HumPRO<sup>™</sup> Series Transceiver Standby Current Consumption vs. Supply Voltage



Figure 11: Amplified HumPRO™ Series Transceiver RX Scan Current vs. Supply Voltage, 115.2kbps

Current consumption while the module is scanning for a transmission. The current is approximately 0.3mA higher when receiving data at 115.2kbps.



Figure 13: Amplified HumPRO<sup>™</sup> Series Transceiver RSSI Reading vs. Input Power at 25°C

#### **Pin Assignments**



Figure 14: Amplified HumPRO<sup>™</sup> Series Transceiver Pin Assignments (Top View)

#### **Pin Descriptions**

Pin Descriptions								
Pin Number	Name	I/O	Description					
1, 2, 3, 5, 6, 7, 8, 10, 11, 17-21, 37, 38, 39, 41, 42, 44	NC	_	No Electrical Connection. Do not connect any traces to these lines.					
4	BE	0	Buffer Empty. This line is high when the UART input buffer is empty, indicating that all data has been transmitted. If acknowledgment is active, it also indicates that the receiving module has acknowledged the data or a retry exception has occurred.					
9, 32	GND	_	Ground					
12	EX	0	Exception Output. A mask can be set to take this line high when an exception occurs. The line is lowered when the exception register is read (EXCEPT).					

Pin Number	Name	I/O	Description
13	CRESP	0	Command Response. This line is low when the data on the CMD_DATA_OUT line is a response to a command and not data received over the air.
14	PB	I	Push Button input. This line can be connected to Vcc through a normally open push button. Button sequences can reset configurations to default and join modules into a network. <b>Pull low when not in use;</b> <b>do not leave floating.</b>
15	CMD_DATA_OUT	0	Command Data Out. Output line for data and serial commands
16	CMD_DATA_IN	I	Command Data In. Input line for data ( $\overline{\text{CMD}}$ is high) and serial commands ( $\overline{\text{CMD}}$ is low).
22	VCC	-	Supply Voltage
33	ANTENNA	_	50-ohm RF Antenna Port
34	CTS	0	UART Clear To Send, active low. This line indicates to the host microcontroller when the module is ready to accept data. When CTS is high, the module is busy. When CTS is low, the module is ready for data.
35	CMD	I	Command Input. When this line is low, incoming bytes are command data. When high, incoming bytes are data to be transmitted.
36	MODE_IND	0	Mode Indicator. This line indicates module activity. It can source enough current to drive a small LED, causing it to flash. The duration of the flashes indicates the module's current state.
40	RESET	I	This line resets the module when pulled low. It should be high for normal operation. This line has an internal 10k resistor to supply, so leave it unconnected if not used.
43	POWER_DOWN	I	Power Down. Pulling this line low places the module into a low-power state. The module is not functional in this state. Pull high for normal operation. Do not leave floating.

Figure 15: Amplified HumPRO<sup>™</sup> Series Transceiver Pin Descriptions

#### Module Pin Assignments

The module has two versions that differ in the antenna connection. The antenna connection is routed to either a castellation (-CAS) or a u.FL connector (-UFL), depending on the part number ordered.



Figure 16: Amplified HumPRO<sup>™</sup> Series Transceiver Pre-certified Version Pin Assignments - Castellation Connection (Top View)



Figure 17: Amplified HumPRO<sup>™</sup> Series Transceiver Pre-certified Version Pin Assignments - UFL Connection (Top View)



Figure 18: Amplified HumPRO<sup>™</sup> Series Transceiver Pre-certified Version Dimensions

#### **Theory of Operation**

The Amplified HumPRO<sup>™</sup> Series transceiver is a low-cost, high-performance synthesized FSK transceiver. Figure 19 shows the module's block diagram.



Figure 19: Amplified HumPRO<sup>™</sup> Series Transceiver RF Section Block Diagram

The Amplified HumPRO<sup>™</sup> Series transceiver operates in the 902 to 928MHz frequency band. The transmitter output power is programmable. The range varies depending on the antenna implementation and the local RF environment.

The RF carrier is generated directly by a frequency synthesizer that includes an on-chip VCO. An additional front-end power amplifier boosts the transmitter power for maximum range. The received RF signal is amplified by an initial low noise amplifier (LNA) then fed into the main receiver. It is further amplified and down-converted to I/Q quadrature signals. The I/Q signals are digitized by ADCs.

A low-power onboard communications processor performs the radio control and management functions including Automatic Gain Control (AGC), filtering, demodulation and packet synchronization. A control processor performs the higher level functions and controls the serial and hardware interfaces.

A crystal oscillator generates the reference frequency for the synthesizer and clocks for the ADCs and the processor.

#### Module Description

The Amplified HumPRO<sup>™</sup> Series module is a completely integrated RF transceiver and processor designed to transmit digital data across a wireless link. It employs a fast-locking FHSS system for noise immunity and amplified transmitter and receiver for best-in-class range.

When the module does not have data to send it scans all of the channels for incoming data. If it finds a valid preamble, it pauses and looks for the start of a packet. When it receives a valid packet with a matching destination address the module outputs the data through the UART.

The transmitting module accepts data bytes through its UART until a configurable number of bytes is reached or a configurable timeout expires between bytes on the UART. At this point the module transmits the packet.

When the module has data to send it goes to the next channel in its hopping pattern. It measures the RSSI on that channel to ensure that the channel is clear. If the RSSI check passes, then it transmits the packets. If the RSSI fails, then it implements a random wait time and tries again. When the channel is clear, the module transmits the data.

The module can stay on one channel for up to 400ms. If the module is ready to start transmitting near the end of the channel time, it transmits the number of bytes that it can in the remaining time. It then hops to the next channel in its hopping pattern to transmit the remaining data.

The module supports automatic acknowledgements for assured delivery. When enabled, the receiving module responds to a valid transmission with an acknowledgement to let the transmitting module know that it received the data. If an acknowledgement is not received then the transmitting module repeats the transmission for a configurable number of retries. If the retry limit is exceeded without an acknowledgement then the transmitting module issues an exception error to let the host micro know of the communication problem.

A standard UART interface is used to configure the module for operation and for the data input and output. This is suitable for direct connection to UARTs on many microcontrollers, USB converters and RS-232 converters. A simple command set is used for configuration and control.

Modules can be pre-configured for fixed point-to-point or broadcast topologies allowing streaming data (no commands) during operation.

#### **Overview**

The Amplified HumPRO<sup>™</sup> Series RF transceiver module offers a number of features that make it suitable for many data transfer applications. This section provides a basic overview of the features while following sections dive into them in more detail.

#### Addressing

The modules have a very powerful addressing method. Each module is given a unique 16 or 32 bit address. The receiving modules use an address mask that determines how it responds to a received transmission.

The addressing and masking allow for the creation of point-to-point, many-to-one and one-to-many wireless links. This allows the creation of many network topologies, such as star, tree and mesh. The routing for the network topology is managed outside the module.

The addressing is the primary configuration when getting started with the modules. RG-00105, the HumPRO<sup>™</sup> Addressing Mode Reference Guide has details about configuring the addressing.

#### Acknowledgements and Assured Delivery

The modules support assured delivery in the form of acknowledgements and retries. When the acknowledgements are enabled, the receiving device sends an acknowledge message to let the sender know that the transmission was received. If the sender does not get an acknowledgement it resends the message up to a configurable number of retries. If there is still no acknowledgement, the module triggers an exception to let the host processor know of the error.

### Command Mode and Data Mode

The module has two main interface modes controlled by the state of the CMD line. Command mode routes the data coming in on the CMD\_DATA\_IN line to the processor for configuring the module. Data mode routes the data to the transmitter for transmission over-the-air. The CMD line is normally controlled by an external microcontroller.

#### Encryption

The module supports AES-128 encryption to provide a secure wireless link. All of the modules must have encryption enabled and be using the same key in order for communication to be successful. There are two ways of entering an encryption key: directly by writing the key to registers through the Command Data Interface or through a JOIN process.

#### Streaming Data and Explicit Packets

The module's default configuration is for streaming data. At some UART rates the module sends the data at a higher rate over-the-air than it is input on the UART. This hides the time required for the protocol transactions and the frequency hopping. The result is that the data appears to stream through the module with no breaks in the data apparent to the host processor.

Alternatively, the module can be configured for explicit packet transmission. This allows the host processor to control when packets are sent and what data is in each packet

#### **Exceptions and Host Processor Interface**

The module has several indicator lines that provide feedback to the host processor on the module's operation and current status. This includes an exception line (EX) that informs the processor when errors occur so that it can take steps to manage the issue gracefully. The state of the status lines can also be read through the module's Command Data Interface to reduce the number of hardware connections that are required.

#### Command Data Interface

The module has a Command Data Interface that consists of a set of serial commands entered through a UART. These are shorter and simpler than AT commands that are popular with many modules. These commands control the configuration of the module as well as allow feedback on the operation and status of the module.

### Carrier Sense Multiple Access (CSMA)

The module implements a Carrier Sense Multiple Access method. It listens to the channel and makes sure that it is clear before it transmits. If the channel is in use, the module either waits for it to clear or hops to the next channel depending on its current state. This reduces the overall potential for interference and improves the robustness of the link.

#### High Power Front End Amplifiers

The HumPRO-A adds a high-power 25dBm power amplifier and an additional low noise amplifier to greatly increase the module's link budget. With +25dBm transmit power and -108dBm sensitivity, the resulting link budget of 133dBm gives the module a line-of-sight range of over 6 miles with good antennas and a good operational environment.

#### **Addressing Modes**

The module has very flexible addressing methods selected with the ADDMODE register. It can be changed during operation. The transmitting module addresses packets according to the addressing mode configuration. The receiving module processes all addressing types regardless of the ADDMODE configuration. If the received message matches the addressing criteria, it is output on the UART. Otherwise it is discarded. The ADDMODE configuration also enables assured delivery.

There are three addressing modes: DSN, User and Extended User. Each mode offers different communications methods, but all use source and destination addressing. The source address is for the transmitting unit, the destination address is the intended receiver. Each mode uses different registers for the source and destination addresses.

All three addressing modes can be configured to be compatible with the older 250 Series modules. The default operation has an additional level of masking on the receiving module that helps prevent interference from adjacent networks.

The following sections give brief descriptions of the three modes, but a detailed explanation and examples are given in RG-00105, the HumPRO<sup>™</sup> Addressing Mode Reference Guide.

.....

#### **DSN Addressing Mode**

Device Serial Number Addressing mode is the simplest mode and supports point-to-point communications. Each module is programmed at the factory with a unique 4-byte serial number that cannot be changed. These bytes are found in the non-volatile read-only MYDSN registers (MYDSN[3-0]). DSN Addressing mode uses this serial number as an address. The transmitting unit's DSN is used as the source address and the intended receiver's DSN is written into the destination address registers (DESTDSN[3-0]). All modules within range hear the transmission, but only the module with the serial number that matches the destination address outputs the data on its UART. All others ignore the transmission.

#### User Addressing Mode

User Addressing Mode is a more flexible method than DSN Addressing Mode. It uses the customer ID bytes (CUSTID[1-0]) for unencrypted messages and two of the user destination bytes (UDESTID[1-0]) as a destination address. The customer ID bytes are programmed at the factory and cannot be changed. These are determined by the factory for specific customers to prevent their systems from operating with any other systems. Contact Linx for more details.

The module's local address is contained in two of the user source ID registers (USRCID[1-0]). In this mode, USRCID [1-0] contain the node address and USRCID [3-2] must be 0 in the receiver.

In normal operation each module has a user ID mask (UMASK[3-0]) that splits the 32 address bits into up to three fields to provide a network address and address fields for sub-networks, supporting both individual addressing and broadcast addressing within the user's network. A detailed explanation and examples are given in Reference Guide RG-00105. The 16 bits in the UDESTID[1-0] registers are transmitted. The upper 16 bits of USRCID[3-2] in the receiver must be 0.

If acknowledgements are enabled, only the module with a user source ID that exactly matches the transmitted user destination ID responds. The mask is not used for this determination.

#### Extended User Addressing Mode

Extended User Addressing mode is the same as User Addressing mode but uses 32-bit addresses. The two customer ID bytes are still used (CUSTID[1-0]) for unencrypted messages but four bytes are used for the user destination address (UDESTID[3-0]), user source ID (USRCID[3-0]) and user ID mask (UMASK[3-0]). This provides more addressing capabilities at the expense of more overhead in the packet.

#### **Network Addressing**

Network Addressing is selected by setting COMPAT to 0x03. It allows the receiver to receive all messages sent in User Address or Extended User Address mode with a destination address matching the USRCID group 1 bits (continuous high-order zero bits in UMASK). For example, with USRCID = 0x12345678 and UMASK = 0x000FFFFF, messages with destination address 0x123zzzz, where z is any value, is received.

#### Automatic Addressing

The module supports an automatic addressing mode that reads the Source Address from a valid received packet and uses it to fill the Destination Address register. This makes sure that a response is sent to the device that transmitted the original message. This also allows the host microcontroller to read out the address of the sending unit. The automatic addressing is enabled for the different addressing modes with register AUTOADDR.

#### Address Register Use

Figure 20 shows the address registers that are used with each addressing mode.

Amplified HumPRO <sup>™</sup> Series Transceiver Address Registers								
COMPAT	0x00 (Rela	xed Addres	ssing)	0x02 (Norr	nal Address	sing)		
	0x04 (DSN)	0x06 (User)	0x07 (Ex User)	0x04 (DSN)	0x06 (User)	0x07 (Ex User)		
ADDMODE	0x14 (DSN +ACK)	0x16 (User +ACK)	0x17 (ExUser +ACK)	0x14 (DSN +ACK)	0x16 (User +ACK)	0x17 (ExUser +ACK)		
UDESTID[3-0]			Х			Х		
UDESTID[1-0]		Х			Х			
USRC[3-0]			Х		Х	Х		
USRC[1-0]		Х						
UMASK[3-0]			Х		Х	Х		
UMASK[1-0]		Х						
DESTDSN[3-0]	Х			Х				

Figure 20: Amplified HumPRO<sup>™</sup> Series Transceiver Address Register Use

#### Acknowledgements and Assured Delivery

When a module transmits with assured delivery enabled, the receiving module returns an acknowledgement packet. The transmitting module waits for this acknowledgement for a preset amount of time based on the data rate. If an acknowledgement is not received, it retransmits the packet. If the receiver receives more than one of the same packet, it discards the duplicate packet contents but sends an acknowledgment. This way, duplicate data is not output by the module.

If the received destination address matches the local address, the receiving module immediately sends an acknowledgement. This packet lets the sending module know that the message has been received. An acknowledgement packet is sent immediately following reception; CSMA delay is not applied to these packets since permission belongs to the interacting modules. When the sending module receives the acknowledgement packet, it marks the current block of data as completed. If this is the last message in the queue, the sending module takes the BE line high to indicate that all outgoing data has been sent.

Assured delivery should only be used when addressing a specific module in a point-to-point link. It should not be used when multiple receivers are enabled. When address masking is used, only the receiver with an exact match to the address in the transmitted packet responds. If none of the enabled receivers has an exact match, then there is no response and the transmitting module continues to re-transmit the data until the max number of retries is attempted. This causes the transmitting module to appear slow or unresponsive. It also impedes valid communications.

#### **Frequency Hopping Spread Spectrum**

The module uses Frequency Hopping Spread Spectrum to allow operation at higher power levels per regulations and to reduce interference with other transmitters. The module is configured for operation in one of 6 different hopping sequences. Each sequence uses 26 channels for the high RF data rate or 50 channels for the low RF data rate. Modules must use the same hopping sequence to communicate. Assigning different hopping sequences to multiple networks in the same area minimizes the interference.

When the module is awake and not transmitting, it rapidly scans all channels for a packet preamble. When a module starts transmitting at the beginning of a new channel, it transmits a packet with a long preamble of alternating 0 and 1 bits. This long preamble is sufficient to allow receiving modules to scan through all of the channels in the hopping sequence and find it. Modules that are scanning detect the preamble and pause on that channel, waiting for a valid packet.

If a packet is received with a valid CRC (unencrypted) or authentication (encrypted), the header is examined to determine whether the module should synchronize to the transmitter. Synchronization requires that the hop sequence matches and that the message is addressed to the receiver.

When synchronized, the receiver stays on the current channel to either transmit a packet or to receive an additional packet. Additional packets transmitted on the same channel within the time slot use short preambles since the receivers are already listening to the current channel.

At the end of the time slot for the current channel, all modules which locked to the original transmission switch to the next channel in the hop sequence. The first transmission on each new channel has a long preamble.

A receiver that has synchronized to a transmitter continues to stay in synchronism by staying on the received channel until the expiration of the time slot, then waiting on the next hop channel for the duration of the time slot. If no further packets are received, the receiver loses lock and reverts to scanning. This allows the receiver to stay synchronized for a short while if a packet is not received correctly.

The module supports the option to send the long preamble with every packet rather than just the first packet on each channel. This can be beneficial for systems that have modules asleep most of the time. It gives modules that just woke up the chance to synchronize to any transmitted packet instead of having to wait for the transmitter to complete its time slot and jump to the next channel. This can reduce the synchronization time and power consumption of the sleeping nodes.

#### Compatibility with the 250 Series

When DSN mode is used with a specific address, the module can communicate with 250 Series modules at UART data rates of 38,400 to 115,200 bps, non-encrypted. For other addressing modes, the Amplified HumPRO<sup>™</sup> Series modules can be configured to operate with them. Setting the COMPAT register to 0x00 enables the compatible operation. This allows mixed-mode systems and upgrades of legacy products that still maintain backwards compatibility. Only the higher baud rates are compatible.

The main feature of compatibility operation is that it configures the same addressing methods used by the 250 Series. These methods are more susceptible to interference from adjacent networks of 250 Series modules which use DSN (GUI) broadcast messages. Please see Reference Guide RG-00105 for more details.

#### Networking

The Amplified HumPRO<sup>™</sup> Series modules can be used to create many types of wireless networks. The modules do not provide network routing since the internal memory size of the module would limit the overall network size. The Amplified HumPRO<sup>™</sup> can work as the MAC/PHY layers of a network stack and the memory and processing speed of the external microcontroller can be sized according to the size of the network that is needed for the application.

This requires more software development, but avoids the cost of adding extra memory on the module for applications that don't need it. Linx can assist with network frameworks and concepts and can create custom designs on a contract basis. Contact Linx for more details.

#### **Transmitting Packets**

In default operation when transmitting, the host microcontroller writes bytes to the CMD\_DATA\_IN line while the  $\overline{CMD}$  line is held high at the baud rate selected by the UARTBAUD register. The incoming bytes are buffered until one of the following conditions triggers the packet to be transmitted:

- 1. The number of bytes in the buffer exceeds the value in the Byte Count Trigger (BCTRIG) register.
- 2. The time since the last received byte exceeds the value in the Data Timeout (DATATO) register.
- 3. A SENDP command is written to the CMD register.
- 4. The  $\overline{\text{CMD}}$  line is taken low with option PKOPT: TXnCMD = 1.
- 5. The number of buffered bytes exceeds what can be sent before the radio must hop channels.

The first four conditions can be controlled by the host microcontroller. In the last case, the module transmits what it can in the remaining time then sends the rest on the next channel. This can cause the data to be divided up into multiple packets and is not within the control of the host micro.

In cases where all data needs to be sent in the same packet or where the microcontroller needs greater control over the radio, the Amplified HumPRO<sup>™</sup> Series offers explicit control of packet transmission with options in the PKTOPT register.

When the TXPKT option is enabled (PKTOPT register, bit 0 = 1), the data is held until a SENDP command is written to the CMD register. Alternatively, if option TXnCMD is enabled (PKTOPT register, bit 1 = 1), then lowering the CMD line triggers the packet transmission, reducing the number of UART transactions that are required. The BCTRIG, DATATO and hop-timing conditions are ignored when the TXPKT option is enabled.

Once triggered, the transmitted packet contains the bytes in the buffer as of the trigger event, even if more data bytes are received before the packet can be sent. Multiple outgoing packets can be buffered in this way.

If the full packet cannot be sent in the time remaining on the current channel, then it is held until the module hops to the next channel.

This option gives the host microcontroller very fine control over when packets are transmitted and what they contain.

#### **Receiving Packets**

In default operation when receiving valid packets, the module outputs all received bytes as soon as the packet is validated (CRC checks pass if unencrypted or key-based verification if encrypted) and if the addressing permits it at the baud rate selected by the UARTBAUD register. No command or control bytes are output and no action is required of an external microcontroller. The first byte from a packet directly follows the last byte of the previously received packet.

In cases where the host microcontroller needs more control over the data or where dynamic configuration changes could set up race conditions between incoming data and outgoing commands, the module offers explicit control over received packets.

When the RXPKT option is enabled (PKTOPT register, bit 2 = 1), received data is output on the CMD\_DATA\_OUT line one packet at a time after a GETPH, GETPD, or GETPHD command is written to the CMD register. Writing one of these commands begins the received packet transfer cycle.

Two lines are used as flow control and indicators during the transfer cycle. The CMD line is controlled by the host microcontroller. The module uses either the CTS line or the CRESP line as a status line, depending on the state of the RXP\_CTS option in the PKOPT register.

When a valid packet is received, the EX\_RXWAIT exception flag is set in the EEXFLAG1 register. If the corresponding bit in the EEXMASK1 register is set, then the EX line goes high. The host microcontroller can monitor the EX line or periodically check the EEXFLAG or LSTATUS registers to determine if data is ready to be read.

The transfer cycle is begun by writing a Get Packet Header (GETPH), Get Packet Data (GETPD), or Get Packet Header and Data (GETPHD) command to the CMD register. The module sends the command ACK byte and sets the selected status line high. Once the status line goes high, the host microcontroller sets the CMD line high and the module outputs the received data. The command sent determines whether the bytes sent are the header, data, or header followed by data.

When all packet bytes have been sent the control line goes low. When the host microcontroller detects that the line is low, it sets  $\overline{CMD}$  low, completing the transfer cycle. The cycle is shown in Figure 21.



Figure 21: HumPRO-A<sup>™</sup> Series Transceiver Received Packet Transfer Cycle

If a GETPH was sent and header data received, the following data can then be read by repeating the cycle with the GETPD command. If the next GETPx command is a GETPH or GETPHD, the data associated with the header read by GETPH is discarded and the header or header plus data of the following packet is returned.

If there is RF-received data waiting to be sent to the UART and the mask for EX\_RXWAIT is set in the EEXMASK register, EX is raised if it is low.

If there is no packet waiting when a GETPx command is sent, the control line is still taken high and not reset until after  $\overline{CMD}$  goes high, thereby performing a zero-byte transfer cycle.

The header and payload structures differ between encrypted packets and unencrypted packets. The header and data structures for explicit unencrypted packets are shown in Figure 22.

The Tag field identifies the start of the block and if it is the header information (0x01) or the packet data (0x02).

The Header Length field identifies the number of header bytes that follow.

The Frame Type field identifies what kind of packet was received. The values are shown in Figure 23.

The Hop ID field is the hop sequence number, 0 - 5.

The Sequence byte is incremented for each new packet, modulo 255. A received packet is discarded if the sequence byte matches the previously received packet to prevent delivering duplicate copies of an automatically retransmitted packet.

DSN Address Packet Header

Tag	Header	Frame	Hop ID	Sequence	Dest DSN	Source	Data
-	Length	Туре		-		DSN	Length
0x01	1	1	1	1	4	4	1

User Address Packet Header

ſ	Tag	Header	Frame	Hop ID	Sequence	Cust ID	Dest Addr	Source	Source	Data
I		Length	Туре					Addr	DSN	Length
I	0x01	1	1	1	1	2	2 or 4	2 or 4	4	1

Packet Data

Tag	Data	Data
	Length	
0x02	1	Data Length Bytes

Figure 22: HumPRO-A<sup>™</sup> Series Transceiver Unencrypted Packet Header and Data Structure

Amplified HumPRO <sup>™</sup> Series Transceiver Frame Types					
Frame Type	Packet Type				
0x04	DSN Addressing Mode				
0x06	User Addressing Mode				
0x07	Extended User Addressing Mode				
+0x10	Acknowledgements Enabled				
+0x20	Encrypted Packet				
+0x40	Long Preamble Packet				

Figure 23: Amplified HumPRO<sup>™</sup> Series Transceiver Frame Types

The Cust ID field is a number that can be assigned to a specific customer. Only modules with the same customer ID respond to unencrypted transmissions. By default, Cust ID is 0x7FFF for packets transmitted with COMPAT = 2 or 0xFFFF for packets transmitted with COMPAT = 0. This field is not used in DSN mode.

The Dest Addr field has the received destination address. This is 2 bytes long with User Addressing Mode and 4 bytes with DSN and Extended User Addressing Modes.

The Source Addr Field is the address of the transmitting module. This is 2 bytes long with User Addressing Mode and 4 bytes with DSN and Extended User Addressing Modes.

The Data Length byte indicates how many bytes of data are in the packet. This value is the same in the packet header and the associated data block. The header and data structures for explicit encrypted packets are shown in Figure 24. The header and data blocks returned by the module are the decrypted message contents.

#### Encrypted DSN Address Packet Header

Tag	Header	Frame	Hop Key	Sequence	Dest DSN	Source	EBlock	Payload
_	Length	Туре				DSN	Length	Туре
0x11	1	1	1	6	4	4	1	1

Encrypted User Address Packet Header

Tag	Header	Frame	Hop Key	Sequence	Dest Addr	Source	Source	EBlock	Payload
-	Length	Type		-		Addr	DSN	Length	Туре
0x11	1	1	1	6	2 or 4	2 or 4	4	1	1

Encrypted Packet Data

Tag	Data Length	Data
0x12	1	Data Length Bytes

Figure 24: HumPRO-A<sup>™</sup> Series Transceiver Encrypted Packet Header and Data Structure

The Tag, Header Length and Frame Type fields are the same as for unencrypted packets.

The Hop Key field uses the first three low-order bits to indicate the Hop Sequence number, which is the same as unencrypted packets. The upper two bits indicate which key is being used. Either the factory-set key that is used to securely transfer the network key or a network key that has been written or created by the JOIN process. This is shown in Figure 25.

Amplified Hum	PRO™ Series HopKey Byte Values
HopKey Bit	Value
0 - 3	Hop Sequence Number, 1 to 5
4 - 5	= 0
6 - 7	Encryption key 0 = factory 1 = user network

Figure 25: Amplified HumPRO<sup>™</sup> Series HopKey Byte Values

The Sequence bytes contain a counter that is incremented for each new transmitted message. The initial value is randomized when the module is reset. The extended sequence becomes part of an initialization vector which is used to vary the encrypted contents of identical packets. A received packet is discarded if the sequence byte matches the previously received packet to prevent delivering duplicate copies of an automatically retransmitted packet.

The Dest DSN, Source DSN, Dest Addr and Source Addr fields are the source and destination addresses, the same as in unencrypted packets.

The EBlock length field is the total number of bytes of data in the encrypted payload block. This length includes the Payload Type byte.

The Payload Type byte indicates what data is contained in the payload. 0x00 indicates that the payload is user data. 0x01 indicates that the payload is the 16-byte AES key followed by any user data. This is used for transferring the network encryption key during the JOIN process.

For the Encrypted Packet Data packet, the Data Length byte indicates the number of bytes of data payload that follow. This value is one less than the EBlock length in the header. The reason for this is that the Payload Type byte is included in the encrypted block, but is reported with the header since it is not user data.

#### Using the Buffer Empty (BE) Line

The BE line indicates the state of the module's UART buffer. It is high to indicate that the UART input buffer is empty, indicating that all data has been transmitted. When the module receives data on the CMD\_DATA\_IN line and the CMD line is high, the BE line is lowered until all data in the buffer has been processed by the protocol engine. If acknowledgement is not enabled, the BE line is raised as soon as the module transmits the outgoing packets. If acknowledgement is enabled, the buffer is not updated until either the data transmissions are acknowledged by the remote end or delivery fails after the maximum number of retries. When the BE line returns high, the EX line may be sampled, or the EXCEPT or EEXFLAG register polled to determine if an error occurred during transmission.

The state of the BE line can be read in the LSTATUS register, reducing the number of hardware connections that are needed.

#### **Exception Engine**

The Amplified HumPRO<sup>™</sup> Series is equipped with an internal exception engine to notify the host microcontroller of an unexpected event. If errors occur during module operation, an exception is raised. There are two methods of driving the EX pin when an exception condition exists:

- 1. From the EXMASK and EXCEPT registers (legacy operation)
- 2. From the EEXMASKx and EEXFLAGx registers (standard operation)

If EXMASK is non-zero, the first method is used, otherwise the second method is used.

For legacy operation with the 250 and 25 Series, the EX line is set and reset by the Exception (EXCEPT) register processing. It is set when an exception occurs and the exception code ANDed with the current Exception Mask (EXMASK) register is non-zero. It is reset when the EXCEPT register is read through a command. No other operations affect the state of EX. Setting EXMASK non-zero does not change the state of EX.

If an exception code is already present in the register when an error occurs, the new exception code overwrites the old value. Exception codes are organized by type for ease of masking. Figure 26 lists the exception codes and their meanings.

Amplified HumPF	Amplified HumPRO <sup>™</sup> Series Transceiver Exception Codes						
Exception Code	Exception Name	Description					
0x08	EX_BUFOVFL	Incoming UART buffer overflowed.					
0x09	EX_RFOVFL	Outgoing UART buffer overflowed.					
0x13	EX_WRITEREGFAILED	Attempted write to register failed.					
0x20	EX_NORFACK	Acknowledgement packet not received after maximum number of retries.					
0x40	EX_BADCRC	Bad CRC detected on incoming packet.					
0x42	EX_BADHEADER	Bad CRC detected in packet header.					
0x43	EX_BADSEQID	Sequence ID was incorrect in ACK packet.					
0x44	EX_BADFRAMETYPE	Attempted transmit with Invalid setting in reg:NETMODE or invalid packet type in received packet header					

Figure 26: Amplified HumPRO<sup>™</sup> Series Transceiver Exception Codes

The EX line can be asserted to indicate to the host that an error has occurred. The EXCEPT register must be read to reset the line. Figure 27 lists some example exception masks.

Amplified HumPF	Amplified HumPRO <sup>™</sup> Series Transceiver Example Exception Masks						
Exception Mask	Exception Name						
0x08	Allows only EX_BUFOVFL and EX_RFOVFL to trigger the EX line						
0x10	Allows only EX_WRITEREGFAILED to trigger the EX line						
0x20	Allows only EX_NORFACK to trigger the EX line						
0x40	Allows only EX_BADCRC, EX_BADHEADER, EX_BADSEQID and EX_BADFRAMETYPE exceptions to trigger the EX line						
0x60	Allows EX_BADCRC, EX_BADHEADER, EX_BADSEQID, EX_ BADFRAMETYPE and EX_NORFACK exceptions to trigger the EX line						
0xFF	Allows all exceptions to trigger the EX line						

Figure 27: Amplified HumPRO<sup>™</sup> Series Transceiver Example Exception Masks

The exception mask has no effect on the exceptions stored in the exception register. It only controls which exceptions affect the EX line.

The extended exception registers offer more functionality with more exceptions and a separate bit for each exception. These registers are the default and should be used with new applications. When an exception sets an exception code in the EXCEPT register, the corresponding flag in the EEXFLAG register is also set.

The EX line is set and reset by the Extended Exception Flags (EEXFLAG) and Extended Exception Mask (EEXMASK) register processing. It is set whenever the EEXFLAG value ANDed with the EEXMASK value is non-zero. EX can change on any write to either of these registers that affects the result of ANDing the registers. Clearing an EEXFLAG register bit or value can leave EX set if there is another masked condition bit set.

The state of the EX line can also be read in the LSTATUS register, reducing the number of hardware lines that are required.

#### Carrier Sense Multiple Access (CSMA)

CSMA is an optional feature. It is a best-effort delivery system that listens to the channel before transmitting a message. If CSMA is enabled and the module detects another transmitter on the same channel, it waits until the active transmitter finishes before sending its payload. This helps to eliminate RF message corruption and make channel use more efficient.

When a module has data ready to transmit and CSMA is enabled, it listens on the intended transmit channel for activity. If no signal is detected, transmission is started.

If a carrier is detected with an RSSI above the CSMA threshold in the CRSSI register, transmission is inhibited. If a signal below the threshold is detected that has a compatible preamble or packet structure, transmission is also inhibited.

If the module is synchronized from a recent packet transfer, it waits for a random interval, then checks again for activity. If the detected carrier lasts longer than the time allowed for the current channel, the module hops to the next channel in the hop sequence and again waits for a clear channel before transmitting.

If the module is not synchronized, it hops to the next channel and again checks for interference. When no activity is detected it starts transmitting.

#### Using the Command Response (CRESP) Line

The CRESP line is high when sending data bytes and low when sending command response bytes. This indicates to an external host microcontroller that the data on the CMD\_DATA\_OUT line is a response to a command and not data received over-the-air. CRESP is held in the correct state at least one byte time after the last byte for the indicated source (command response or data, although it normally stays in the same state until a change is required).

If a data packet is received when the module is processing a command, it sends the command response, raises  $\overline{\text{CRESP}}$ , and then sends the received data bytes.

When reading or writing the module's register settings, it is possible for incoming RF data to intermix with the module's response to a configuration command. This can make it difficult to determine if commands were successfully processed as well as to capture the received RF data. Setting the CMDHOLD register to 0x01 causes the module to store incoming RF traffic (up to the RF buffer capacity) while the CMD line is low. When the CMD line is returned high, the module outputs the buffered data on the UART. This allows the external host microcontroller to have separate configuration times and data times instead of potentially having to handle both at once.

The CRESP line stays low for at least ten bit times after the stop bit of the last command response. Figure 28 shows the timing.



Figure 28: Amplified HumPRO<sup>™</sup> Series Transceiver CRESP Line Timing

#### Using the CMD Line

The CMD line informs the module where incoming UART data should be routed. When the line is high, all incoming UART data is treated as payload data and is routed to the transmitter to be sent over the air. If the CMD line is low, the incoming UART data is treated as command bytes and is routed to the controller for processing.

Since the module's controller looks at UART data one byte at a time, the <u>CMD</u> line must be held low for the entire duration of the command plus time for ten bits as margin for processing. Leaving the line low for additional time (for example, until the ACK byte is received by the application) does not adversely affect the module. If RF packets are received while the <u>CMD</u> line is active, they are still processed and output on the module's UART (assuming CMDHOLD=0 and PKOPT:RXPKT=0). Figure 29 shows this timing.

CMD_DATA_IN Start D0	<u>XD6</u> <u>XD7</u> <u>Stop</u> <u>≥10 bit</u>
	times

Figure 29: Amplified HumPRO<sup>™</sup> Series Transceiver CMD Line Timing

Commands can be entered sequentially without having to raise the  $\overline{CMD}$  line after each one. The  $\overline{CMD}$  line just needs to be raised to be able to enter data for transmission.

If the CMDHOLD register is 0x01 then any received data is held until the  $\overline{\text{CMD}}$  line is raised. This prevents received data from being intermingled with command responses.

#### **AES Encryption**

The Amplified HumPRO<sup>™</sup> Series modules offer AES encryption. Encryption algorithms are complex mathematical calculations that use a large number called a key to scramble data before transmission. This is done so that unauthorized persons who may intercept the signal cannot access the data. To decrypt the data, the receiver must use the same key that was used to encrypt it. It performs the same calculations as the transmitter and if the key is the same, the data is recovered.

The amplified HumPRO<sup>™</sup> Series module has the option for AES encryption, arguably the most common encryption algorithm on the market. This is implemented in a secure mode of operation to ensure the secrecy of the transmitted data. It uses a 128-bit key to encrypt the transmitted data. The source and destination addresses are sent in the clear.

Encryption is disabled by default. There are two ways to enable encryption and set the key: sending serial commands and using the JOIN process.

#### Writing an encryption key to the module with the CDI

The module has no network key when shipped from the factory. An encryption key can be written to the module using the CDI. The CMD register is used to write or clear a key. The key cannot be read.

The same key must be written to all modules that are to be used together. If they do not have the same key then they will not communicate in encrypted mode.

#### The JOIN Process

The JOIN process is a method of generating an encryption key and distributing the key and addresses to associated modules through a series of button presses. This makes it very simple to establish an encrypted network in the field or add new nodes to an existing network without any additional equipment. It is also possible to trigger the JOIN process through commands on the Command Data Interface.

The JOIN process configures a star network with the central unit as system administrator. Other units are added to the network one at a time.

The hardware required is a pushbutton that is connected to the PB line. This takes the line to VCC when it is pressed and ground when it is released. An LED connected to the MODE\_IND line provides visual indication of the module's state.

A module is set as an administrator by pressing and holding the button for 30 seconds to start the Generate Key function. While the button is held, the MODE\_IND line is on. After 30s, the MODE\_IND line repeats a double blink, indicating that the function has begun. When the button is released the key and address generation are complete and the module is an administrator.

When Generate Key is performed, the unit is set as the network administrator. It generates a random 128-bit AES encryption key based on ambient RF noise and scrambled by an encryption operation. If UMASK is the default value (0xFFFFFFF), it is set to 0x000000FF, supporting up to 255 nodes, and ADDMODE is set to Extended User Address with encryption (0x27) (or without encryption (0x07) if flag PGKEY in the SECOPT register is 0). UMASK and ADDMODE are not changed if UMASK is not 0xFFFFFFFF. A random 32-bit address is generated. By default, the lower 8 bits are 0, forming the network base address. Other nodes are assigned sequential addresses, starting with network base address +1. UDESTID is set to the bitwise OR of USRCID and UMASK, which is the network broadcast address.

A module becomes a node by joining with an administrator. This is done by pressing and releasing the PB button on both units. The modules automatically search for each other using a special protocol. When they find each other, the administrator sends the node the encryption key, UMASK and its network address. The UDESTID is set to the address of the administrator. The values are encrypted using a special factory-defined key. Once the JOIN process is complete, the MODE\_IND blinks on both units and they now operate together. This is shown in Figure 30 A.

If UMASK is pre-set when Generate Key is initiated, then the JOIN process uses that mask and sets the address accordingly. This can allow more nodes in the network. This is shown in Figure 30 B. Likewise, the network key can be written to the module with the CDI interface and the JOIN process used to create an address and associate new modules. Or the administrator can be completely configured through the CDI and the JOIN process used to associate nodes in the field. This gives the system designer many options for configuration.

The SECOPT register is used to configure options related to the JOIN process. This allows the OEM to set desired values at the factory and allow final network configuration in the field. This includes disabling the ability to change the address, change the key and share the key. The built-in security prohibits changing a node to an administrator without changing the key.



Figure 30: Amplified HumPRO<sup>™</sup> Series JOIN Process

#### Using the MODE\_IND Line

The MODE\_IND line is designed to be connected to an LED to provide visual indication of the module's status and current actions. The pattern of blinks indicates the particular feedback from the module. Figure 31 shows the different blink patterns and their meanings.

Amplified HumPRO™ Series MODE_IND Line Timing						
Display [on/off time in seconds]	Module Status					
Join Operation						
Two quick blinks	Administrator Join. The administrator is looking for a node to join with.					
One quick blink	Node Join. The node is looking for an administrator to join with.					
Quick blink	Key Transfer Active. Key transfer is taking place (administrator and node).					
Slow Blink	Key Transfer Complete. The module has completed a key transfer (administrator and node).					
Temporary On	On when the PB line is high					
Two quick blinks, one time	Join Canceled.					
Slow blink, repeat 3 times	Failure. For Share Key or Get Key, there are multiple units attempting to pair, protocol error, or timeout without response					
Slow blink and two quick blinks	Long Hold Acknowledgement. The long hold period for Generate Key or Reset Sequence was recognized (PB is asserted)					
Key Test Results						
One quick blink Three times	No Key. There is no network key or network address.					
Two quick blinks Three times	Key Set, node. The network key and network address are set on a node.					
Three quick blinks Three times	Key Set, administrator. The network key and network address are set on an administrator.					
Normal operation						
Off	No activity					
Temporarily on	Transmitting or receiving packet					

Figure 31: Amplified HumPRO<sup>™</sup> Series MODE\_IND Line Timing

Figure 33 shows the MODE\_IND displays in a graphical format.

Operation	MODE_IND Display	Comments
Administrator Join		Repeats for 30 seconds or until JOIN is complete
Node Join		Repeats for 30 seconds or until JOIN is complete
Key Transfer Active		Repeats for the duration of the transfer
Key Transfer Complete		Six blinks total
JOIN Cancelled		
Long Hold		Repeats for as long as the PB line is asserted after the long hold period has been recognized
Failure		
No Key Set		Repeats, three times total
Key Set, Node		Repeats, three times total
Key Set, Administrator		Repeats, three times total
Time (seconds)	0 0.5 1 1.5 2 2.5	5

Figure 33: Amplified HumPRO<sup>™</sup> Series MODE\_IND Displays

#### Using the PB Line

The PB Line is used to trigger functions associated with the JOIN process. This line should be connected to a momentary pushbutton that pulls the line to VCC when it is pressed and opens the circuit when it is released. There is no internal pull-down, so a resistor to ground should be used to pull the line down when the button is not pressed. A value of  $10k\Omega$  to  $100k\Omega$  works well.

The sequence of presses determines which function is triggered. Figure 32 shows the sequences.

Amplified HumPRO <sup>™</sup> Series PB Line Operation						
Function	Sequence					
Join a network	1 short pulse					
Cancel a Join Process that is in progress	1 short pulse					
Generate a network key and address	Hold PB high for 30 seconds					
Reset to factory defaults	4 short pulses and hold high for 3 seconds					
Test key and address	3 short pulses					
A short pulse is a logic high that is betwee	n 100 and 2 000ms in duration					

Figure 32: Amplified HumPRO<sup>™</sup> Series PB Line Operation

#### **Restore Factory Defaults**

The transceiver is reset to factory default by taking the PB line high briefly 4 times, then holding PB high for more than 3 seconds. Each brief interval must be high 0.1 to 2 seconds and low 0.1 to 2 seconds. (1 second nominal high / low cycle). The sequence helps prevent accidental resets. Once the sequence is recognized, the MODE\_IND line blinks in groups of three until the PB line goes low. After PB goes low, the non-volatile configurations are set to the factory default values and the module is restarted. The default UART data rate is 9,600bps.

If the timing on PB does not match the specified limits, the sequence is ignored. Another attempt can be made after lowering PB for at least 3 seconds.

#### Using the Low Power Features

The module supports several low-power features to save current in battery-powered applications. This allows the module to be asleep most of the time, but be able to quickly wake up, send data and go back to sleep.

Taking the Power Down ( $\overrightarrow{POWER}$ \_DOWN) line low places the module into the lowest power state. In this mode, the internal voltage regulator and all oscillators are turned off. All circuits powered from the voltage regulator are also off. The module is not functional while in this mode and current consumption drops to below 1µA. Taking the line high wakes the module.

When the POWER\_DOWN line is high, the IDLE register determines sleep operation.

If IDLE is set to 1 during normal operation, the module sends an ACK byte, waits for completion of an active transmission, then goes into sleep mode. Unsent data in the incoming UART data buffer does not inhibit sleep. During sleep mode, the output lines are in the states in Figure 34.

A rising transition on the PB, POWER\_DOWN or CMD\_DATA\_IN lines wakes the module. If a negative-going pulse is needed to generate a rising edge, the pulse width should be greater than 1µs.

Other lines also wake the module but it immediately goes back to sleep. Floating inputs should be avoided since they may cause unintended transitions and cause the module to draw additional current.

Amplified HumPRO <sup>™</sup> Series Output Line Sleep States						
Output Line	Sleep State					
EX	Unchanged					
CRESP	Low					
LNA_EN	Low					
PA_EN	Low					
TXD	High					
CTS	High					
MODE_IND	Low					
BE	Unchanged					

Figure 34: Amplified HumPRO<sup>™</sup> Series Output Line Sleep States

If the volatile registers have been corrupted during sleep, a software reset is performed. This restarts the module as if power were cycled. This can be caused by power surges or brownout among other things.

After the module wakes up, it sets the IDLE register to 0 (active). If the WAKEACK register is set to 1, then the module outputs the 0x06 byte on the CMD\_DATA\_OUT line. The CRESP line is taken high and the module then begins normal operation.

Pulsing RESET low causes the module to restart rather than continue from sleep.

#### **Baud Rate and Transmitter Output Power**

The FCC and Industry Canada regulations link the maximum transmitter output power and the number of hopping channels in a frequency hopping system. A transmitter with 50 or more hopping channels is allowed up to 1W of output power. A transmitter with at least 25 channels is allowed up to 0.25W of output power.

The Amplified HumPRO<sup>™</sup> Series uses a different number of hopping channels based on the value of the UARTBAUD register. Rates of 9,600bps (0x01) and 19,200bps (0x02) use 50 channels. The rest of the rates use 26 channels. This means that UARTBAUD values of 0x01 or 0x02 are allowed the full range of TXPWR register values. **All other UARTBAUD values are limited to 24dBm, or a TXPWR register value of 0x07 or less.** 

The module automatically links these values, so the output power is limited appropriately.

#### The Command Data Interface

The Amplified HumPRO<sup>™</sup> Series transceiver has a serial Command Data Interface (CDI) that is used to configure and control the transceiver through software commands. This interface consists of a standard UART with a serial command set. The CMD\_DATA\_IN and CMD\_DATA\_OUT lines are the interface to the module's UART. The UART is configured for 1 start bit, 1 stop bit, 8 data bits, no parity and a serial data rate set by register UARTBAUD (default 9,600bps). The CMD line tells the module if the data on the UART is for configuration commands (low) or data transmission (high).

The module has a 256 byte buffer for incoming data. The module starts transmitting when the buffer reaches a specified limit or when the time since the last received byte on the UART reaches a specified value. This allows the designer to optimize the module for fixed length and variable length data.

If the buffer gets nearly full (about 224 bytes), the module pulls the CTS line high, indicating that the host should not send any more data. Data sent by the host while the buffer is full is lost, so the CTS line provides a warning and should be monitored. When there is outgoing data waiting to be transmitted or acknowledged the BE line is low, otherwise BE is high.

Configuration settings are stored in two types of memory inside the module. Volatile memory is quick to access, but it is lost when power is removed from the module. Non-volatile memory has a limited number of write cycles, but is retained when power is removed. When a configuration parameter has both a non-volatile and volatile register, the volatile register controls the operation unless otherwise stated. The non-volatile register holds the default value that is loaded into the volatile register on power-up.

Configuration settings are read from non-volatile memory on power up and saved in volatile memory. The volatile and non-volatile registers have different address locations, but the same read and write commands. The two locations can be changed independently.

The general serial command format for the module is:

[FF] [Length] [Command]

The Length byte is the number of bytes in the Command field. The

Command field contains the register address that is to be accessed and, in the case of a write command, the value to be written. Neither Length nor Command can contain a 0xFF byte.

Byte values of 128 (0x80) or greater can be sent as a two-byte escape sequence of the format:

0xFE, [value - 0x80]

For example, the value 0x83 becomes 0xFE, 0x03. The Length count includes the added escape bytes.

A response is returned for all valid commands. The first response byte is CMD\_ACK (0x06) or CMD\_NACK (0x15). Additional bytes may follow, as determined by the specific command.

#### **Reading from Registers**

A register read command is constructed by placing an escape character (0xFE) before the register number. The module responds by sending an ACK (0x06) followed by the register number and register value. The register value is sent unmodified, so if the register value is 0x83, 0x83 is returned. If the register number is invalid, the module responds with a NACK (0x15). The command and response are shown in Figure 35.

Amplifie	d HumPR	O™ Serie	s Read Fre	om Config	uration	Register	
Commar	nd						
Header	Size	Escape	Address				
0xFF	0x02	0xFE	REG				
Respons	se						
ACK	Address	Value					
0x06	REG	V					
Commar	nd for an A	ddress g	reater than	128 (0x80	))		
Header	Size	Escape	Addr1	Addr2			
0xFF	0x03	0xFE	0xFE	REG-80			
Respons	se						
ACK	Address	Value					
0x06	REG	V					

Figure 35: Amplified HumPRO<sup>™</sup> Series Read from Configuration Register Command and Response

#### Writing to Registers

To allow any byte value to be written, values of 128 (0x80) or greater can be encoded into a two-byte escape sequence of the format 0xFE, [value - 0x80]. This includes register addresses as well as values to be written to the registers. The result is that there are four possible packet structures because of the possible escape sequences. These are shown in Figure 36.

Amplifie	d Hum	PRO™ Se	ries Write to	Configu	ration Re	egist
Register and Value less than 128 (0x80)						
Header	Size	Address	Value			
0xFF	0x02	REG	V			
Register less than 128 (0x80) and a Value greater than or eq						
Header	Size	Address	Escape	Value		
0xFF	0x03	REG	0xFE	V-0x80		
Register greater than or equal to 128 (0x80) and a Value less						
Header	Size	Escape	Address	Value		
0xFF	0x03	0xFE	REG-0x80	V		
Register and Value greater than or equal to 128 (0x80)						
Header	Size	Escape	Address	Escape	Value	
0xFF	0x04	0xFE	REG-0x80	0xFE	V-0x80	

Figure 36: Amplified HumPRO<sup>™</sup> Series Write to Configuration Register Command

Generally, there are three steps to creating the command.

- 1. Determine the register address and the value to be written.
- 2. Encode the address and value as either the number (N) or the encoded number (0xFE, N-0x80) as appropriate.
- 3. Add the header (0xFF) and the size.

The module responds with an ACK (0x06). If the ACK is not received, the command should be resent. The module responds with a NACK (0x15) if a write is attempted to a read-only or invalid register.

As an example, to write 01 to register 0x83, send

#### FF 03 FE 03 01

Note: The non-volatile memory has a life expectancy of 16,000 write operations.

#### **Command Length Optimization**

Some commands may be shortened by applying the following rules:

- Escape sequences are not required for byte values 0x00 to 0xEF (besides 0xFE and 0xFF, bytes 0xF0 – 0xFD are reserved for future use).
- 2. An escape byte inverts bit 7 of the following data byte.
- 3. The 0xFE as the first byte of the Read Register Command field is an escape byte.
- 4. Two consecutive escape bytes cancel unless the following data byte is 0xf0-0xff.

#### Examples:

- FF 02 FE 02 (read nv:TXPWR) is equivalent to FF 01 82.
- FF 03 FE FE 53 (read v:PKOPT) is equivalent to FF 01 53.
- FF 03 1A FE 7F (write FF to nv:UMASK0) cannot be shortened.
- FF 03 1A FE 40 (write C0 to nv:UMASK0) is equivalent to FF 02 1A C0.

These rules are implemented in the sample code file EncodeProCmd.c, which can be downloaded from the Linx website.