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Integrated Power Hybrid IC for
Appliance Motor Drive Applications

IRAMS12UP60A

*i*MOTION™ Series

12A, 600V

with Open Emitter Pins

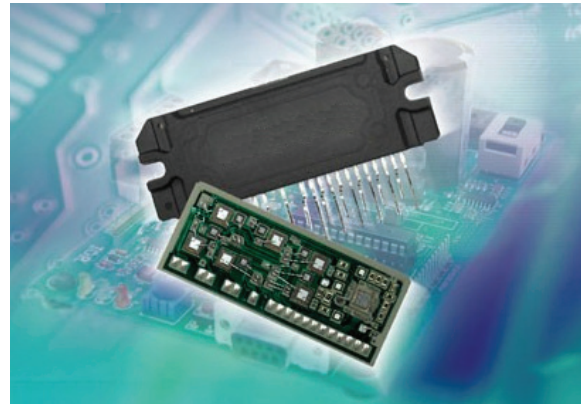
Description

International Rectifier's IRAMS12UP60A is a 12A, 600V Integrated Power Hybrid IC with Open Emitter pins for advanced Appliance Motor Drives applications such as energy efficient Washing Machine and Refrigerator Compressor Drivers. IR's technology offers an extremely compact, high performance AC motor-driver in a single isolated package to simplify design.

This advanced HIC is a combination of IR's low $V_{CE(on)}$ Trench IGBT technology and the industry benchmark 3 phase high voltage, high speed driver in a fully isolated thermally enhanced package. A built-in high precision temperature monitor and over-current protection feature, along with the short-circuit rated IGBTs and integrated under-voltage lockout function, deliver high level of protection and fail-safe operation. Using a Single in line package with full transfer mold structure and $CTI > 600$ minimizes PCB space and resolves isolation problems to heatsink.

Features

- Integrated gate drivers and bootstrap diodes
- Temperature monitor
- Protection shutdown pin
- Low $V_{CE(on)}$ Trench IGBT technology
- Undervoltage lockout for all channels
- Matched propagation delay for all channels
- Schmitt-triggered input logic
- Cross-conduction prevention logic
- Lower di/dt gate driver for better noise immunity
- Motor Power range 0.3~0.9kW / 85~253 Vac
- Isolation 2000V_{RMS} min and $CTI > 600$



Absolute Maximum Ratings

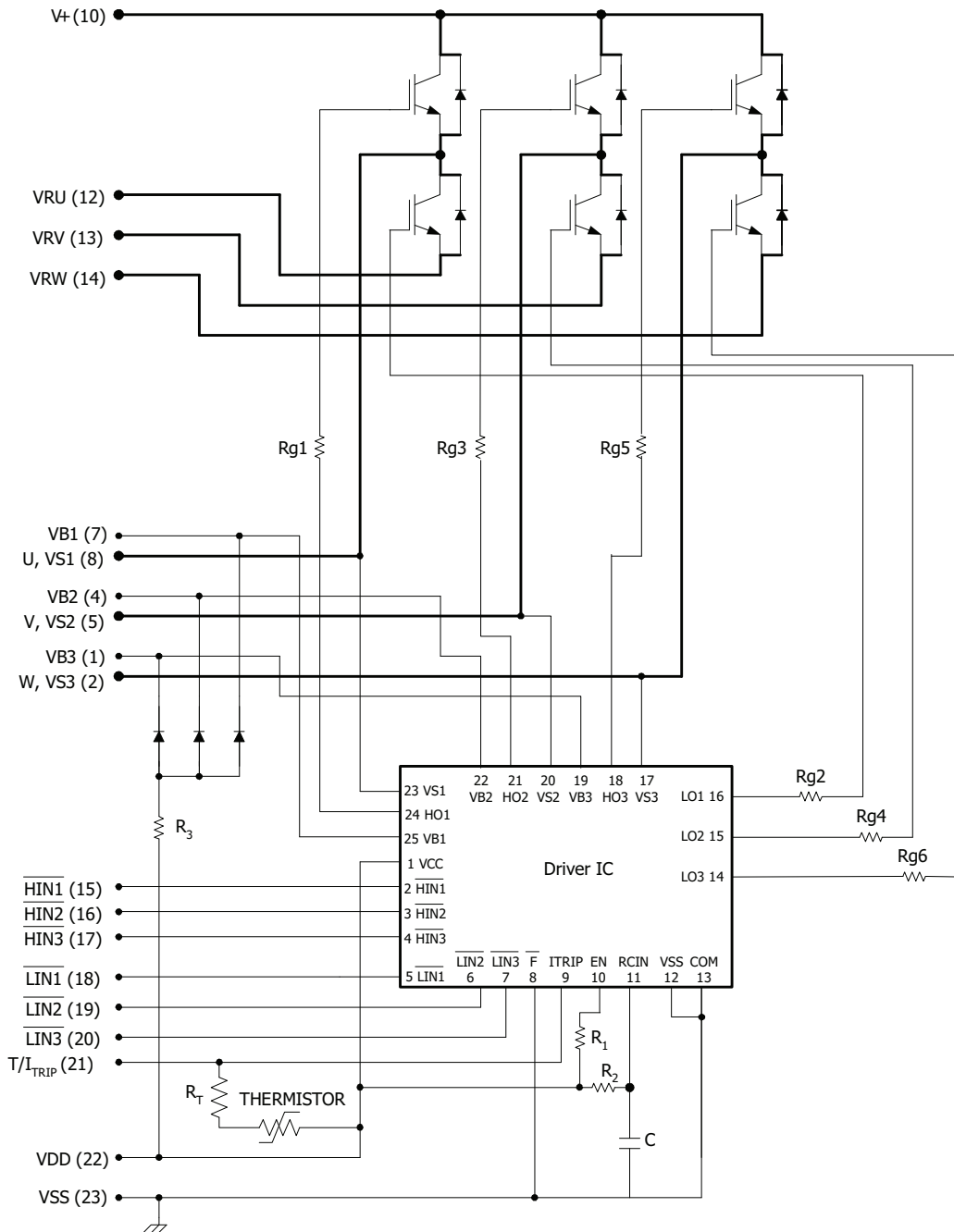
| | | | |
|-------------------------------|---|-------------|-----------|
| V_{CES} / V_{RRM} | IGBT/ FW Diode Blocking Voltage | 600 | V |
| V^+ | Positive Bus Input Voltage | 450 | |
| $I_o @ T_C=25^\circ\text{C}$ | RMS Phase Current at $F_{PWM}=16\text{kHz}$ (Note 1) | 12 | A |
| $I_o @ T_C=100^\circ\text{C}$ | RMS Phase Current at $F_{PWM}=16\text{kHz}$ (Note 1) | 6 | |
| I_{pk} | Maximum Peak Phase Current (Note 2) | 18 | |
| F_p | Maximum PWM Carrier Frequency | 20 | kHz |
| P_d | Maximum Power dissipation per IGBT @ $T_C = 25^\circ\text{C}$ | 26 | W |
| V_{ISO} | Isolation Voltage (1min) | 2000 | V_{RMS} |
| T_J (IGBT & Diode & IC) | Maximum Operating Junction Temperature | +150 | °C |
| T_C | Operating Case Temperature Range | -20 to +100 | |
| T_{STG} | Storage Temperature Range | -40 to +125 | |
| T | Mounting torque Range (M3 screw) | 0.8 to 1.0 | Nm |

Note 1: Sinusoidal Modulation at $V^+=320\text{V}$, $V_{CC}=15\text{V}$, $T_J=150^\circ\text{C}$, $MI=0.8$, $PF=0.6$, See Figure 3.

Note 2: $t_p < 100\text{ms}$, $V_{CC}=15\text{V}$, $T_C=25^\circ\text{C}$, $F_{PWM}=16\text{kHz}$.

IRAMS12UP60A

Internal Electrical Schematic – IRAMS12UP60A



Absolute Maximum Ratings (Continued)

| Symbol | Parameter | Min | Max | Units | Conditions |
|----------------|--|-------------------|--|-------|---|
| I_{BDF} | Bootstrap Diode Peak Forward Current | --- | 1.0 | A | $t_p=10ms$, $T_j=150^\circ C$, $T_c=100^\circ C$ |
| $P_{BR\ Peak}$ | Bootstrap Resistor Peak Power (Single Pulse) | --- | 15.0 | W | $t_p=100\mu s$, $T_c=100^\circ C$ ESR series |
| $V_{S1,2,3}$ | High side floating supply offset voltage | $V_{B1,2,3} - 20$ | $V_{B1,2,3} + 0.3$ | V | |
| $V_{B1,2,3}$ | High side floating supply voltage | -0.3 | 600 | V | |
| V_{CC} | Low Side and logic fixed supply voltage | -0.3 | 20 | V | |
| V_{IN} | Input voltage LIN, HIN, T/Ittrip | -0.3 | Lower of ($V_{SS}+15V$) or $V_{CC}+0.3V$ | V | |

Inverter Section Electrical Characteristics

V_{BIAS} (V_{CC} , $V_{BS1,2,3}$)=15V, $T_j=25^\circ C$, unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|---------------------------------|---|-----|------|---------|---------------|--|
| $V_{(BR)CES}$ | Collector-to-Emitter Breakdown Voltage | 600 | --- | --- | V | $V_{IN}=5V$, $I_C=250\mu A$ |
| $\Delta V_{(BR)CES} / \Delta T$ | Temperature Coeff. Of Breakdown Voltage | --- | 0.47 | --- | V/ $^\circ C$ | $V_{IN}=5V$, $I_C=500\mu A$ ($25^\circ C - 150^\circ C$) |
| $V_{CE(ON)}$ | Collector-to-Emitter Saturation Voltage | --- | 1.5 | 1.8 | V | $I_C=6A$, $T_j=25^\circ C$ |
| | | --- | 1.7 | --- | | $I_C=6A$, $T_j=150^\circ C$ |
| I_{CES} | Zero Gate Voltage Collector Current | --- | 6 | 80 | μA | $V_{IN}=5V$, $V^+=600V$ |
| | | --- | 30 | --- | | $V_{IN}=5V$, $V^+=600V$, $T_j=150^\circ C$ |
| V_{FM} | Diode Forward Voltage Drop | -- | 1.85 | 2.45 | V | $I_F=6A$ |
| | | --- | 1.5 | --- | | $I_F=6A$, $T_j=150^\circ C$ |
| V_{BDFM} | Bootstrap Diode Forward Voltage Drop | --- | --- | 1.25 | V | $I_F=1A$ |
| | | --- | --- | 1.10 | | $I_F=1A$, $T_j=125^\circ C$ |
| R_{BR} | Bootstrap Resistor Value | --- | 2 | --- | Ω | $T_j=25^\circ C$ |
| $\Delta R_{BR}/R_{BR}$ | Bootstrap Resistor Tolerance | --- | --- | ± 5 | % | $T_j=25^\circ C$ |

IRAMS12UP60A

Inverter Section Switching Characteristics

$V_{BIAS} (V_{CC}, V_{BS1,2,3})=15V, T_J=25^{\circ}C$, unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|-----------|-----------------------------------|-------------|-----|-----|---------|--|
| E_{ON} | Turn-On Switching Loss | --- | 270 | 400 | μJ | $I_C=6A, V^+=400V$ $V_{CC}=15V, L=1.2mH$ Energy losses include "tail" and diode reverse recovery |
| E_{OFF} | Turn-Off Switching Loss | --- | 55 | 85 | | |
| E_{TOT} | Total Switching Loss | --- | 325 | 485 | | |
| E_{REC} | Diode Reverse Recovery energy | --- | 10 | 20 | | |
| t_{RR} | Diode Reverse Recovery time | --- | 100 | --- | ns | See CT1 |
| E_{ON} | Turn-on Switching Loss | --- | 390 | --- | μJ | $I_C=6A, V^+=400V$ $V_{CC}=15V, L=1.2mH, T_J=150^{\circ}C$ Energy losses include "tail" and diode reverse recovery |
| E_{OFF} | Turn-off Switching Loss | --- | 110 | --- | | |
| E_{TOT} | Total Switching Loss | --- | 500 | --- | | |
| E_{REC} | Diode Reverse Recovery energy | --- | 35 | --- | | |
| t_{RR} | Diode Reverse Recovery time | --- | 140 | --- | ns | See CT1 |
| Q_G | Turn-On IGBT Gate Charge | --- | 19 | 29 | nC | $I_C=8A, V^+=400V, V_{GE}=15V$ |
| RBSOA | Reverse Bias Safe Operating Area | FULL SQUARE | | | | $T_J=150^{\circ}C, I_C=6A, V_P=600V$ $V^+=450V,$ $V_{CC}=+15V$ to 0V See CT3 |
| SCSOA | Short Circuit Safe Operating Area | 5 | --- | --- | μs | $T_J=25^{\circ}C, V^+=400V,$ $V_{GE}=+15V$ to 0V |

Recommended Operating Conditions Driver Function

The Input/Output logic timing diagram is shown in Figure 1. For proper operation the device should be used within the recommended conditions. All voltages are absolute referenced to COM. The V_s offset is tested with all supplies biased at 15V differential (Note 3)

| Symbol | Definition | Min | Typ | Max | Units |
|--------------|--|------------|----------|------------|---------|
| $V_{B1,2,3}$ | High side floating supply voltage | $V_S+12.5$ | V_S+15 | $V_S+17.5$ | V |
| $V_{S1,2,3}$ | High side floating supply offset voltage | Note 4 | --- | 450 | V |
| V_{CC} | Low side and logic fixed supply voltage | 13.5 | 15 | 16.5 | V |
| $V_{T/TRIP}$ | T/I_{TRIP} input voltage | V_{SS} | --- | $V_{SS}+5$ | V |
| V_{IN} | Logic input voltage LIN, HIN | V_{SS} | --- | $V_{SS}+5$ | V |
| HIN | High side PWM pulse width | 1 | --- | --- | μs |
| Deadtime | External dead time between HIN and LIN | 1 | --- | --- | μs |

Note 3: For more details, see IR21365 data sheet

Note 4: Logic operational for V_s from COM-5V to COM+600V. Logic state held for V_s from COM-5V to COM- V_{BS} . (please refer to DT97-3 for more details)

Static Electrical Characteristics Driver Function

V_{BIAS} (V_{CC} , $V_{BS1,2,3}$)=15V, T_J =25°C, unless otherwise specified. The V_{IN} and I_{IN} parameters are referenced to COM and are applicable to all six channels. (Note 3)

| Symbol | Definition | Min | Typ | Max | Units |
|---------------------------|---|------|------|------|-------|
| $V_{IN,th+}$ | Positive going input threshold for LIN, HIN | 3.0 | --- | --- | V |
| $V_{IN,th-}$ | Negative going input threshold for LIN, HIN | --- | --- | 0.8 | V |
| V_{CCUV+} , V_{BSUV+} | V_{CC}/V_{BS} supply undervoltage, Positive going threshold | 10.6 | 11.1 | 11.6 | V |
| V_{CCUV-} , V_{BSUV-} | V_{CC}/V_{BS} supply undervoltage, Negative going threshold | 10.4 | 10.9 | 11.4 | V |
| V_{CCUVH} , V_{BSUVH} | V_{CC} and V_{BS} supply undervoltage lock-out hysteresis | --- | 0.2 | --- | V |
| I_{QBS} | Quiescent V_{BS} supply current | --- | --- | 120 | μA |
| I_{QCC} | Quiescent V_{CC} supply current | --- | --- | 2.3 | mA |
| I_{LK} | Offset Supply Leakage Current | --- | --- | 50 | μA |
| I_{IN+} | Input bias current (OUT=LO) | --- | 100 | 220 | μA |
| I_{IN-} | Input bias current (OUT=HI) | -1 | 200 | 300 | μA |
| $V(T/I_{TRIP})$ | I_{TRIP} threshold Voltage | 3.85 | 4.3 | 4.75 | V |
| $V(T/I_{TRIP}, HYS)$ | I_{TRIP} Input Hysteresis | --- | 0.15 | --- | V |

Dynamic Electrical Characteristics

V_{BIAS} (V_{CC} , $V_{BS1,2,3}$)=15V, T_J =25°C, unless otherwise specified. Driver only timing unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|-----------------|--|-----|-----|------|-------|--|
| T_{ON} | Input to Output propagation turn-on delay time (see fig.11) | --- | 600 | --- | ns | $I_C=6A$, $V^+=300V$ |
| T_{OFF} | Input to Output propagation turn-off delay time (see fig. 11) | --- | 600 | --- | ns | |
| T_{FILIN} | Input filter time (HIN,LIN) | --- | 200 | --- | μs | $V_{IN}=0$ or $V_{IN}=5V$ |
| $T_{BLT-ITRIP}$ | I_{TRIP} Blanking Time | --- | 150 | --- | ns | $V_{IN}=0$ or $V_{IN}=5V$, $V_{ITRIP}=5V$ |
| T_{ITRIP} | I_{TRIP} to six switch turn-off propagation delay (see fig. 2) | --- | --- | 1.75 | μs | $I_C=6A$, $V^+=300V$ |
| D_T | Internal Dead Time injected by driver | 220 | 290 | 360 | ns | $V_{IN}=0$ or $V_{IN}=5V$ |
| M_T | Matching Propagation Delay Time (On & Off) all channels | --- | 40 | 75 | ns | External dead time > 400ns |
| $T_{FLT-CLR}$ | Post I_{TRIP} to six switch turn-off clear time (see fig. 2) | --- | 7.7 | --- | ms | $T_C = 25^\circ C$ |
| | | --- | 6.7 | --- | | $T_C = 100^\circ C$ |

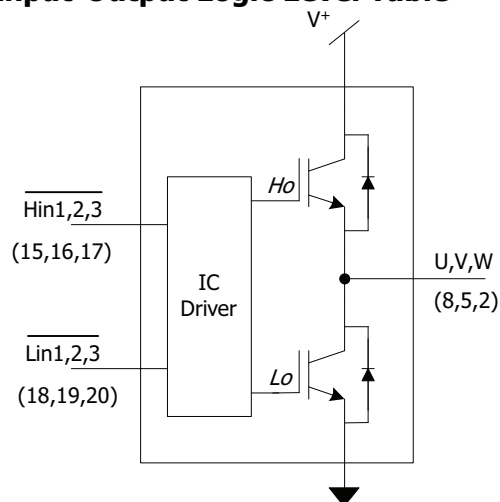
Thermal and Mechanical Characteristics

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|---------------|-------------------------------|-----|-----|-----|-------|---|
| $R_{th(J-C)}$ | Thermal resistance, per IGBT | --- | 4.7 | 5.2 | °C/W | Inverter Operating Condition Flat, greased surface. Heatsink compound thermal conductivity 1W/mK |
| $R_{th(J-C)}$ | Thermal resistance, per Diode | --- | 5.8 | 6.9 | | |
| $R_{th(C-S)}$ | Thermal resistance, C-S | --- | 0.1 | --- | | |
| CTI | Comparative Tracking Index | 600 | --- | --- | V | |
| BKCurve | Curvature of module backside | 0 | --- | --- | μm | Convex only |

Internal NTC - Thermistor Characteristics

| Parameter | Definition | Min | Typ | Max | Units | Conditions |
|---------------------------|----------------------|------|------|------|-------|------------------------------------|
| R_{25} | Resistance | 97 | 100 | 103 | kΩ | $T_C = 25^\circ\text{C}$ |
| R_{125} | Resistance | 2.25 | 2.52 | 2.80 | kΩ | $T_C = 125^\circ\text{C}$ |
| B | B-constant (25-50°C) | 4165 | 4250 | 4335 | k | $R_2 = R_1 e^{[B(1/T_2 - 1/T_1)]}$ |
| Temperature Range | | -40 | --- | 125 | °C | |
| Typ. Dissipation constant | | --- | 1 | --- | mW/°C | $T_C = 25^\circ\text{C}$ |
| R_T | Resistance | --- | 12 | --- | kΩ | $T_C = 25^\circ\text{C}$ |
| $\Delta R_T/R_T$ | Resistor Tolerance | --- | --- | ±1 | % | $T_C = 25^\circ\text{C}$ |

Input-Output Logic Level Table



| I_{TRIP} | $\overline{HIN1,2,3}$ | $\overline{LIN1,2,3}$ | U,V,W |
|------------|-----------------------|-----------------------|-------|
| 0 | 0 | 1 | V+ |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | Off |
| 0 | 0 | 0 | Off |
| 1 | X | X | Off |

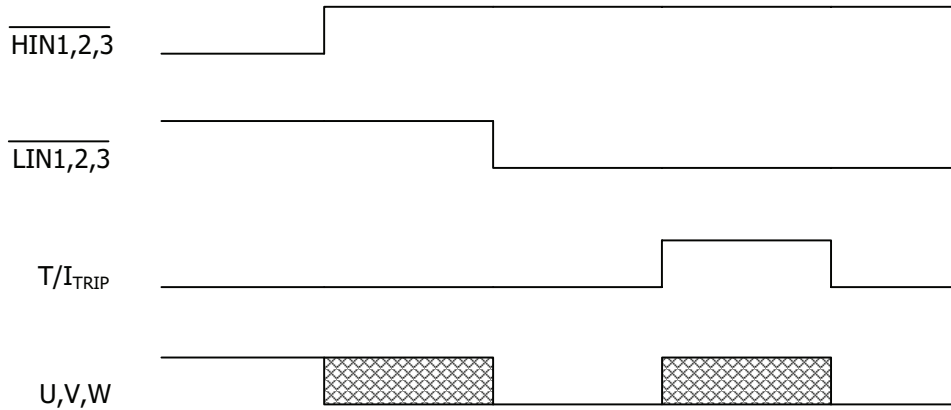


Figure1. Input/Output Timing Diagram

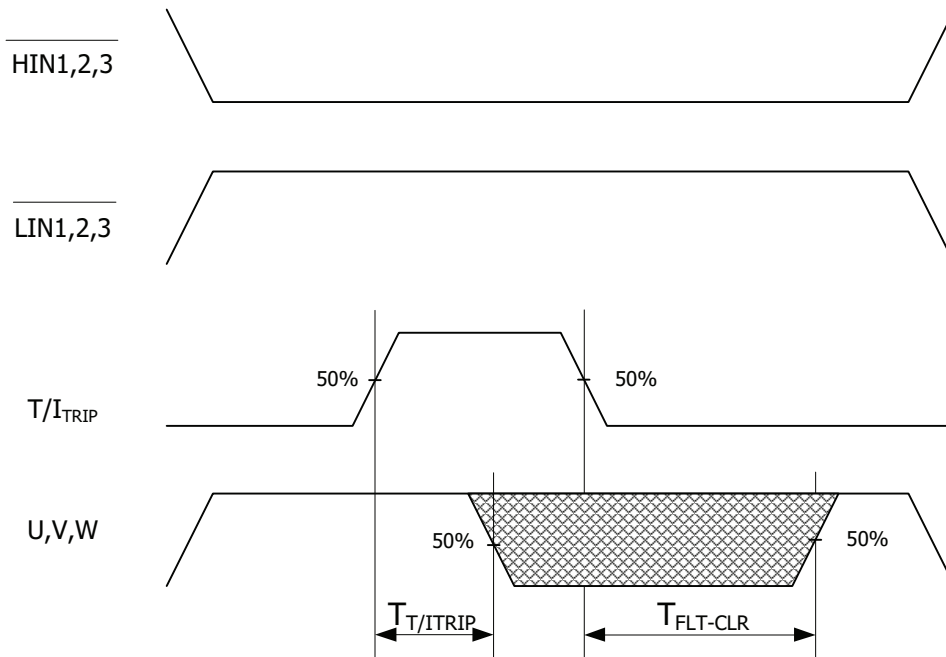


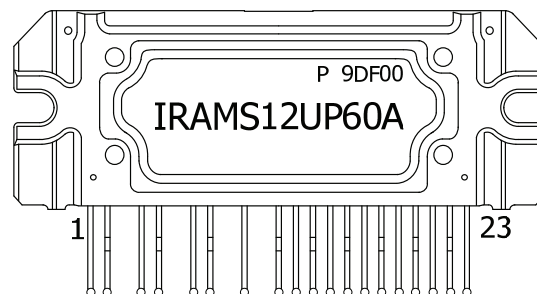
Figure 2. T/I_{TRIP} Timing Waveform

Note 5: The shaded area indicates that both high-side and low-side switches are off and therefore the half-bridge output voltage would be determined by the direction of current flow in the load.

IRAMS12UP60A

Module Pin-Out Description

| Pin | Name | Description |
|-----|--------------|---|
| 1 | V_{B3} | High Side Floating Supply Voltage 3 |
| 2 | U, V_{S3} | Output 3 - High Side Floating Supply Offset Voltage |
| 3 | NA | none |
| 4 | V_{B2} | High Side Floating Supply voltage 2 |
| 5 | V, V_{S2} | Output 2 - High Side Floating Supply Offset Voltage |
| 6 | NA | none |
| 7 | V_{B1} | High Side Floating Supply voltage 1 |
| 8 | W, V_{S1} | Output 1 - High Side Floating Supply Offset Voltage |
| 9 | NA | none |
| 10 | V^+ | Positive Bus Input Voltage |
| 11 | NA | none |
| 12 | L_{E1} | Low Side Emitter Connection - Phase 1 |
| 13 | L_{E2} | Low Side Emitter Connection - Phase 2 |
| 14 | L_{E3} | Low Side Emitter Connection - Phase 3 |
| 15 | H_{IN1} | Logic Input High Side Gate Driver - Phase 1 |
| 16 | H_{IN2} | Logic Input High Side Gate Driver - Phase 2 |
| 17 | H_{IN3} | Logic Input High Side Gate Driver - Phase 3 |
| 18 | L_{IN1} | Logic Input Low Side Gate Driver - Phase 1 |
| 19 | L_{IN2} | Logic Input Low Side Gate Driver - Phase 2 |
| 20 | L_{IN3} | Logic Input Low Side Gate Driver - Phase 3 |
| 21 | T/I_{TRIP} | Temperature Monitor and Shut-down Pin |
| 22 | V_{CC} | +15V Main Supply |
| 23 | V_{SS} | Negative Main Supply |



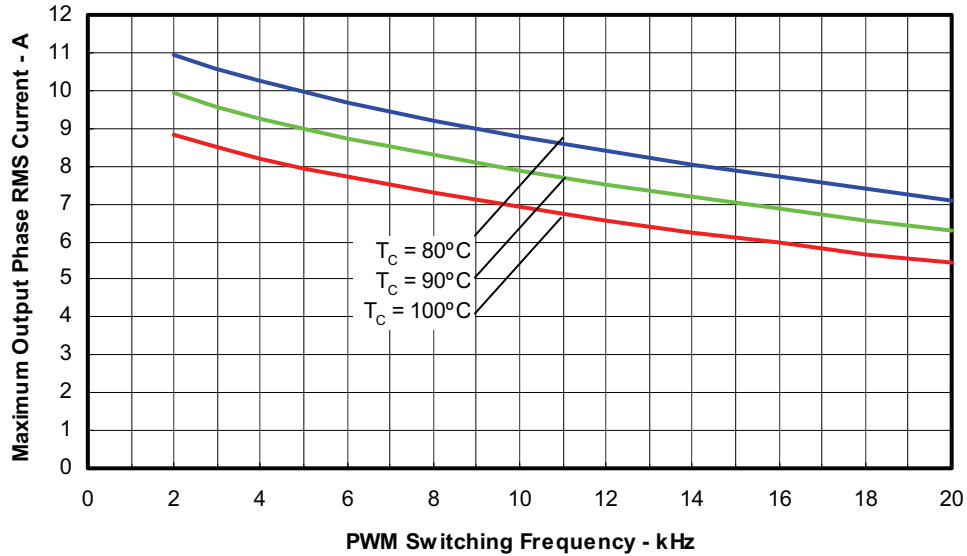


Figure 3. Maximum Sinusoidal Phase Current vs. PWM Switching Frequency
Sinusoidal Modulation, $V^+ = 400\text{V}$, $T_J = 150^\circ\text{C}$, $MI = 0.8$, $PF = 0.6$, $f_{\text{mod}} = 50\text{Hz}$

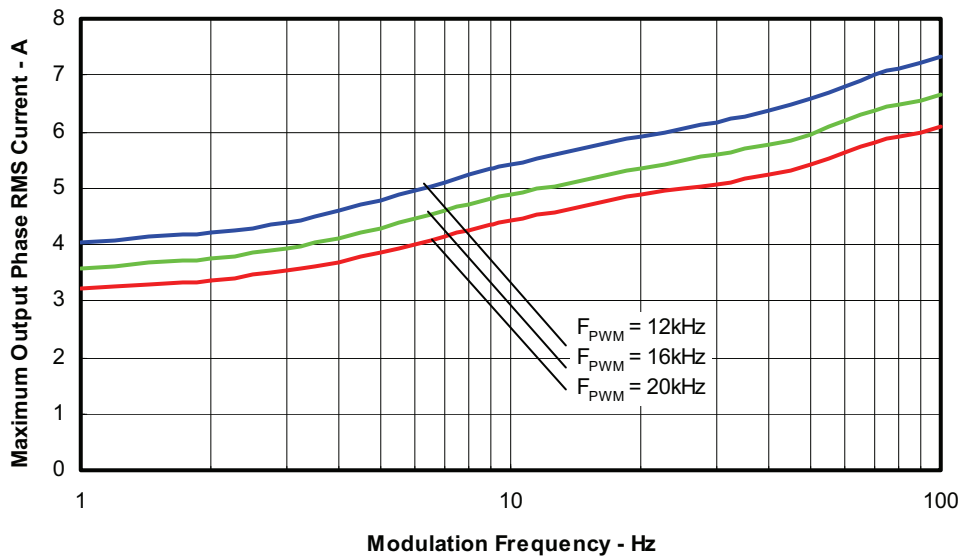


Figure 4. Maximum Sinusoidal Phase Current vs. Modulation Frequency
Sinusoidal Modulation, $V^+ = 400\text{V}$, $T_J = 150^\circ\text{C}$, $T_C = 100^\circ\text{C}$, $MI = 0.8$, $PF = 0.6$

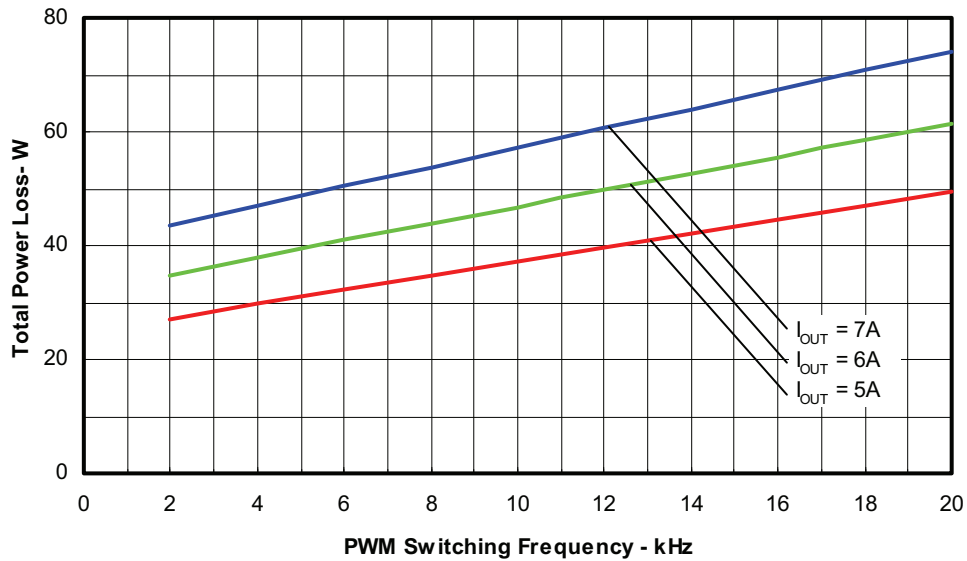


Figure 5. Total Power Losses vs. PWM Switching Frequency
Sinusoidal Modulation, $V^+ = 400V$, $T_J = 150^\circ C$, $MI = 0.8$, $PF = 0.6$, $f_{mod} = 50Hz$

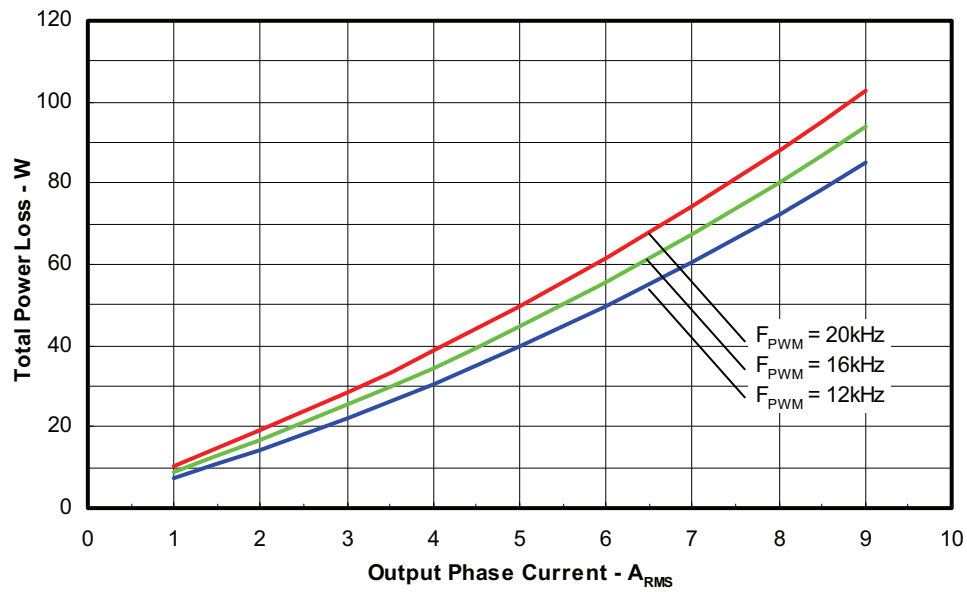


Figure 6. Total Power Losses vs. Output Phase Current
Sinusoidal Modulation, $V^+ = 400V$, $T_J = 150^\circ C$, $MI = 0.8$, $PF = 0.6$, $f_{mod} = 50Hz$

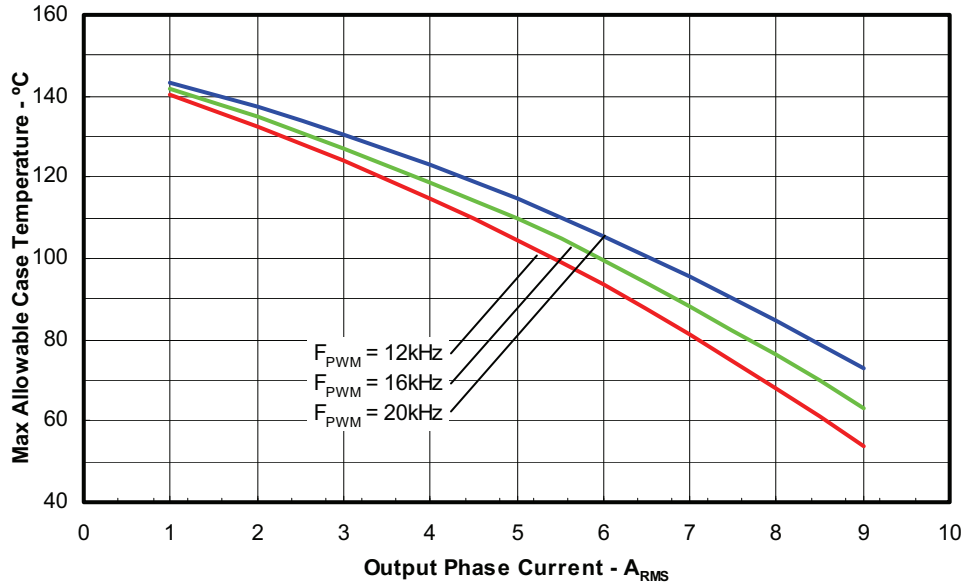


Figure 7. Maximum Allowable Case Temperature vs. Output RMS Current per Phase
Sinusoidal Modulation, $V^+=400V$, $T_J=150^\circ C$, $MI=0.8$, $PF=0.6$, $f_{mod}=50Hz$

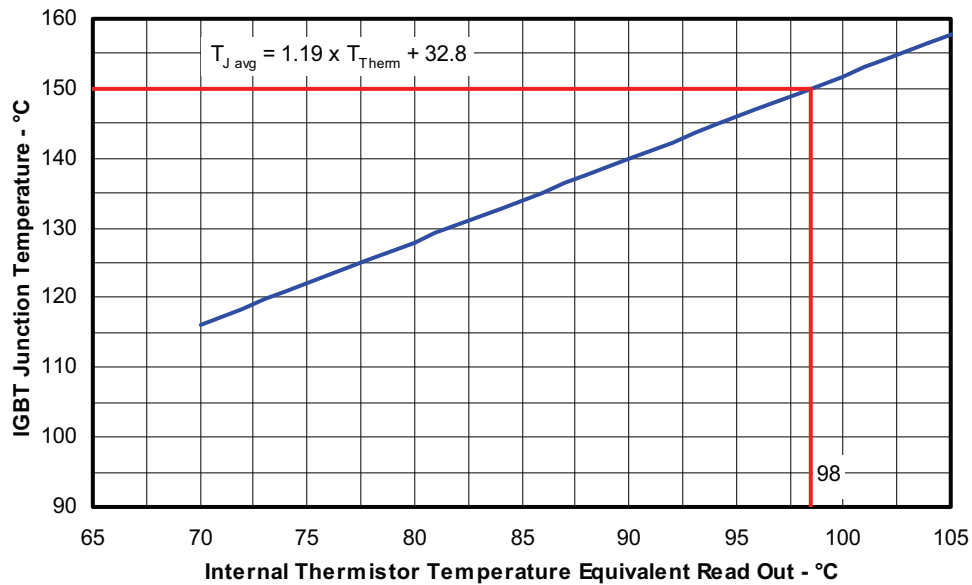


Figure 8. Estimated Maximum IGBT Junction Temperature vs. Thermistor Temperature
Sinusoidal Modulation, $V^+=400V$, $I_{phase}=6A_{rms}$, $f_{sw}=16kHz$, $f_{mod}=50Hz$, $MI=0.8$, $PF=0.6$

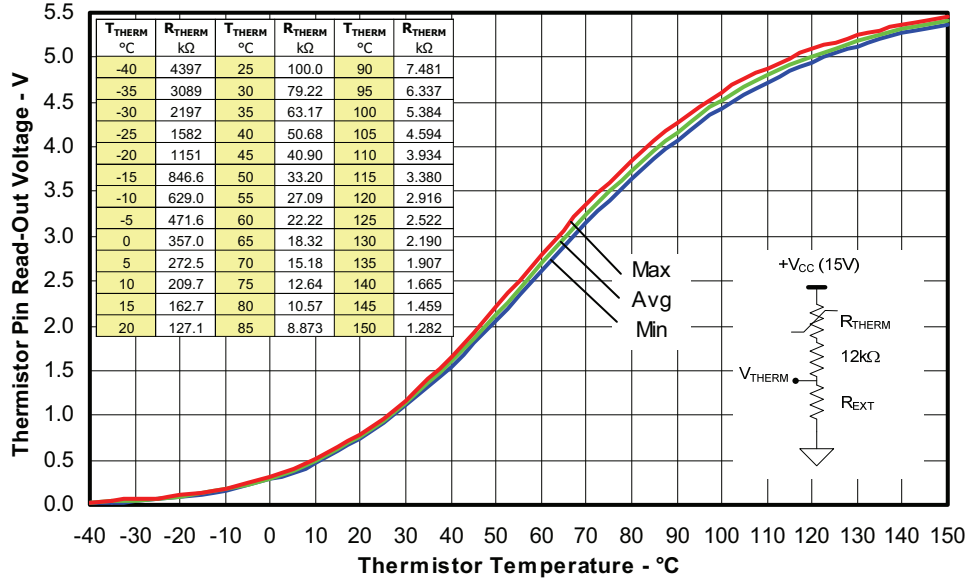


Figure 9. Thermistor Readout vs. Temperature (7.5kohm R_{EXT} pull-down resistor) and Normal Thermistor Resistance values vs. Temperature Table.

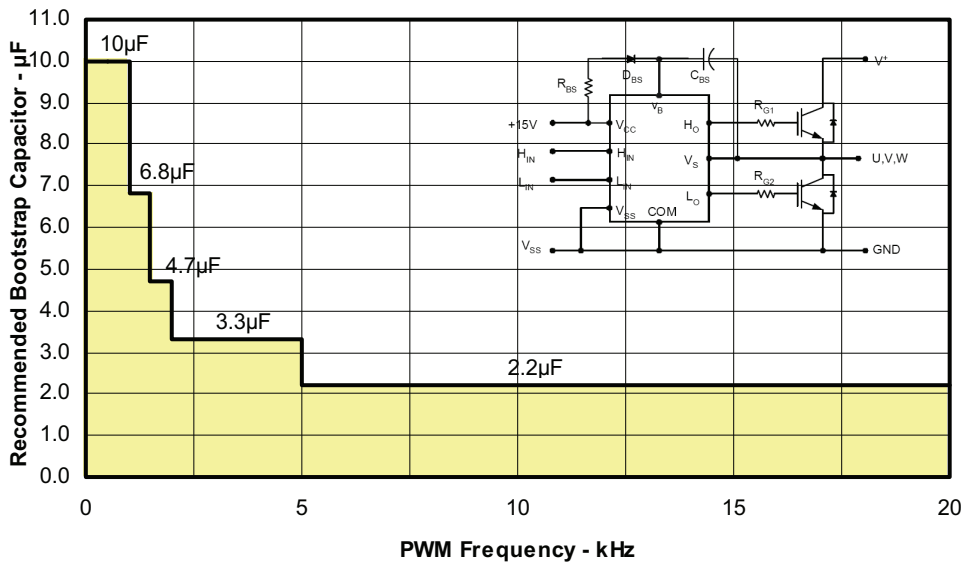


Figure 10. Recommended Bootstrap Capacitor Value vs. Switching Frequency

Figure 11. Switching Parameter Definitions

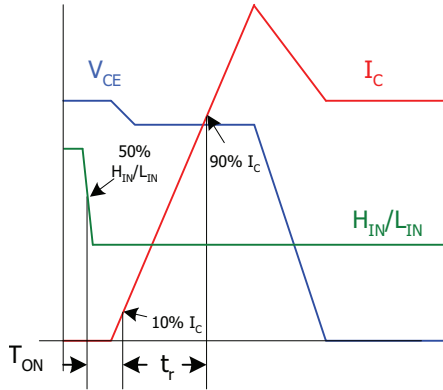


Figure 11a. Input to Output propagation turn-on delay time.

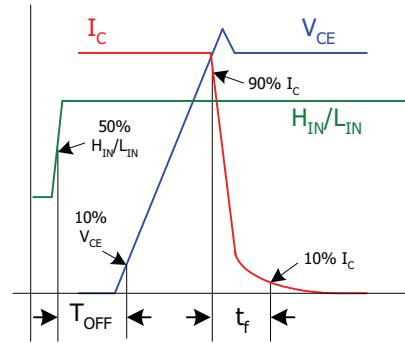


Figure 11b. Input to Output propagation turn-off delay time.

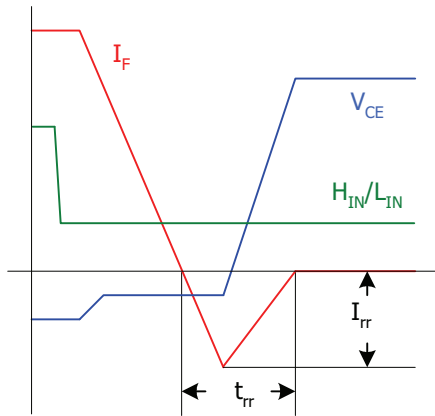


Figure 11c. Diode Reverse Recovery.

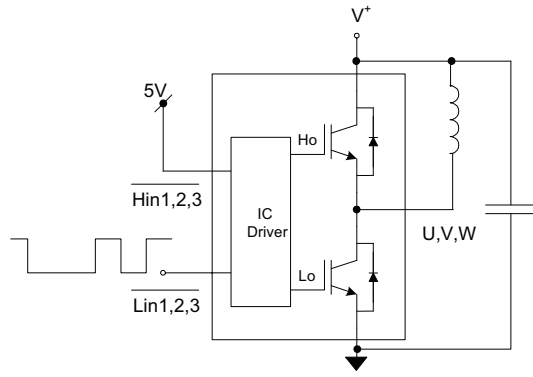


Figure CT1. Switching Loss Circuit

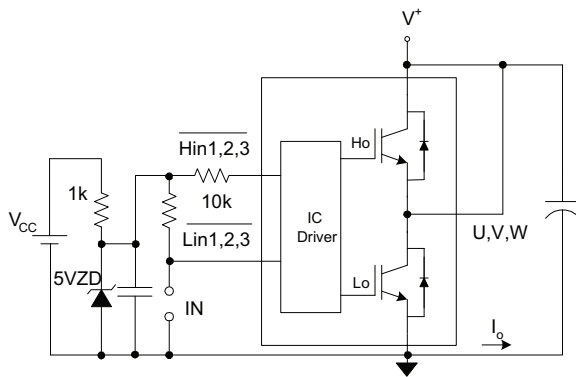
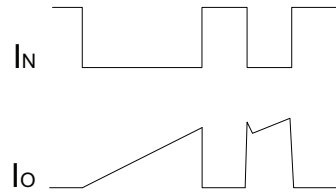


Figure CT2. S.C.SOA Circuit

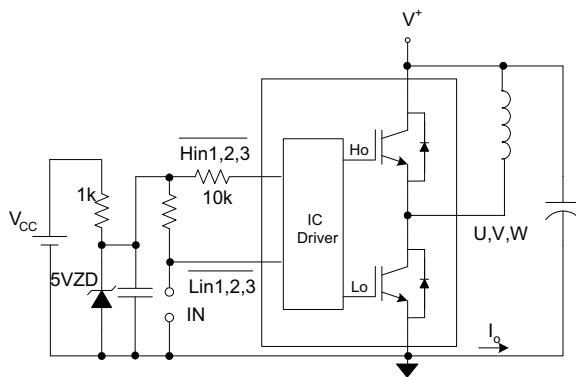
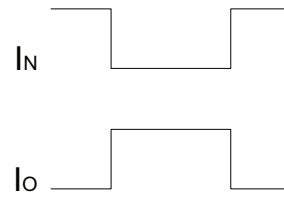
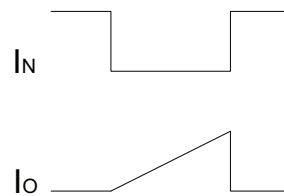
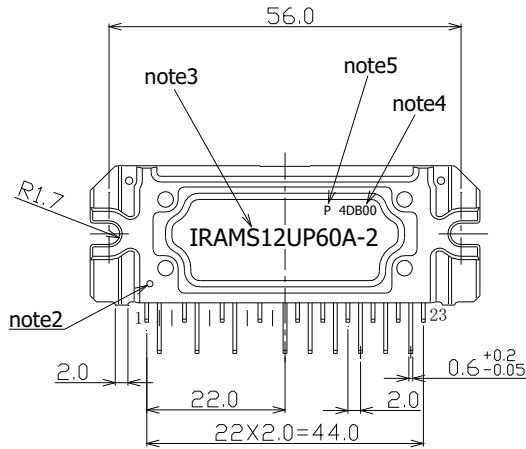


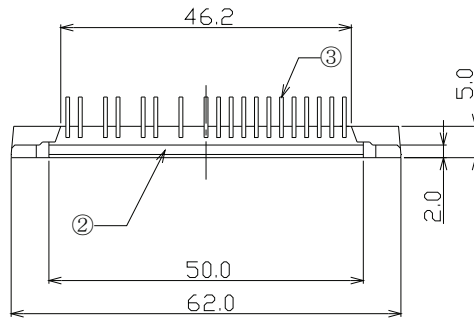
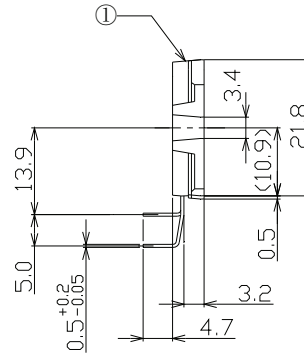
Figure CT3. R.B.SOA Circuit



Package Outline IRAMS12UP60A-2



missing pin : 3,6,9,11



- note1: Unit Tolerance is ± 0.5 mm, Unless Otherwise Specified.
- note2: Mirror Surface Mark indicates Pin1 Identification.
- note3: Part Number Marking. Characters Font in this drawing differs from Font shown on Module.
- note4: Lot Code Marking. Characters Font in this drawing differs from Font shown on Module.
- note5: "P" Character denotes Lead Free. Characters Font in this drawing differs from Font shown on Module.

Dimensions in mm
 For mounting instruction see AN-1049