imall

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from, Europe, America and south Asia, supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts, Customers Priority, Honest Operation, and Considerate Service", our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip, ALPS, ROHM, Xilinx, Pulse, ON, Everlight and Freescale. Main products comprise IC, Modules, Potentiometer, IC Socket, Relay, Connector. Our parts cover such applications as commercial, industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





February 2018

6×8 DOTS MATRIX LED DRIVER WITH INDIVIDUAL AUTO BREATH FUNCTION

GENERAL DESCRIPTION

The IS31FL3738 is a general purpose 6×8 LEDs matrix driver with 1/12 cycle rate. The device can be programmed via an I2C compatible interface. Each LED can be dimmed individually with 8-bit × 4 PWM data which allowing 512 steps of linear dimming.

IS31FL3738 features 3 Auto Breathing Modes which are noted as ABM-1, ABM-2 and ABM-3. For each Auto Breathing Mode, there are 4 timing characters which include current rising / holding / falling / off time and 3 loop characters which include Loop-Beginning / Loop-Ending / Loop-Times. Every LED can be configured to be any Auto Breathing Mode or No-Breathing Mode individually.

Additionally each LED open and short state can be detected, IS31FL3738 store the open or short information in Open-Short Registers. The Open-Short Registers allowing MCU to read out via I2C compatible interface. Inform MCU whether there are LEDs open or short and the locations of open or short LEDs.

The IS31FL3738 operates from 2.7V to 5.5V and features a very low shutdown and operational current.

IS31FL3738 is available in QFN-28 (5mm×5mm) and eTSSOP-28 packages. It operates from 2.7V to 5.5V over the temperature range of -40°C to +125°C.

FEATURES

- Supply voltage range: 2.7V to 5.5V
- 8 current source outputs for row control
- 6 switch current inputs for column scan control
- Up to 48 LEDs (6×8) in dot matrix
- Programmable 6×8 (16 RGBs) matrix size with deghost function
- 1MHz I2C-compatible interface
- Selectable 3 Auto Breath Modes for each dot
- Auto Breath Loop Features interrupt pin inform MCU Auto Breath Loop completed
- Auto Breath offers 128 steps gamma current, interrupt and state look up registers
- 256 steps global current setting
- Individual on/off control
- Individual 512 PWM control steps
- Individual Auto Breath Mode select
- Individual open and short error detect function
- Cascade for synchronization of chips
- QFN-28 (5mm×5mm) and eTSSOP-28 packages

APPLICATIONS

- Mobile phones and other hand-held devices for LED display
- Gaming device (keyboard, mouse etc.)
- LED in white goods application

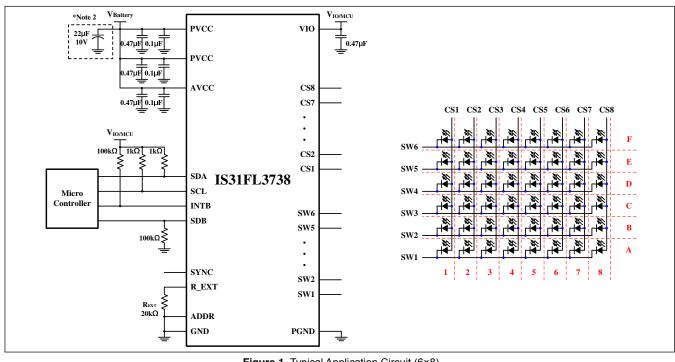


Figure 1 Typical Application Circuit (6×8)

TYPICAL APPLICATION CIRCUIT



TYPICAL APPLICATION CIRCUIT (CONTINUED)

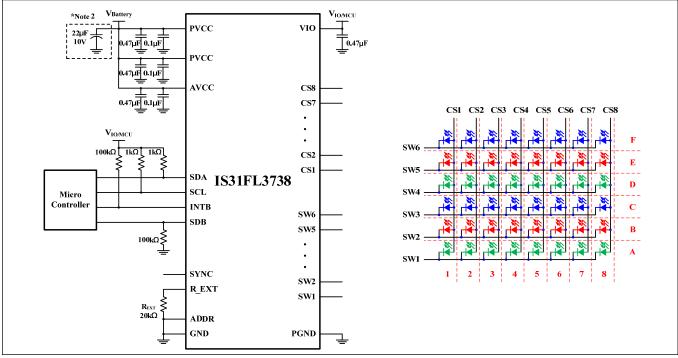


Figure 2 Typical Application Circuit (RGB)

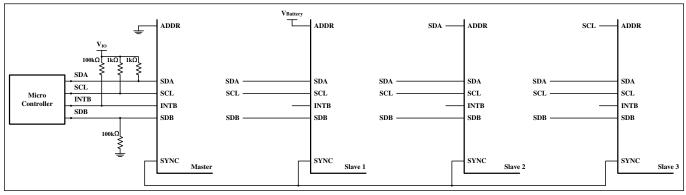


Figure 3 Typical Application Circuit (Four Parts Synchronization-Work)

Note 1: For the mobile applications the IC should be placed far away from the mobile antenna in order to prevent the EMI.

Note 2: Electrolytic/Tantalum Capacitor may considerable for high current application to avoid audible noise interference.

Note 3: One part is configured as master mode, all the other 3 parts configured as slave mode. Work as master mode or slave mode specified by Configuration Register (Function Register, address 00h). Master part output master clock, and all the other parts which work as slave input this master clock.

Note 4: The VIO should be $1.8V \le V_{IO} \le V_{CC}$. And it is recommended to be equal to V_{OH} of the micro controller. For example, if V_{OH} =1.8V, set V_{IO} =1.8V is recommended.



PIN CONFIGURATION

PIN CONFIGUE Package	Pin Configuration (Top View)
QFN-28	GND SW1 SW2 SW2 SW2 SW4 SW4 SW5 T T T SW2 SW4 SW5 T T SW2 SW4 SW5 T T SW2 SW4 SW5 SW5 T T SW2 SW4 SW5 T T SW2 SW4 SW5 SW5 SW5 SW5 SW5 SW5 SW5 SW5
eTSSOP-28	CS8 1 28 CS7 R_EXT 2 27 PVCC AVCC 3 26 CS6 VIO 4 25 CS5 SYNC 5 24 CS4 SDA 6 23 CS3 SCL 7 22 PVCC ADDR 8 21 CS2 INTB 9 20 CS1 SDB 10 19 SW6 GND 11 18 PGND SW1 12 17 SW5 SW2 13 16 SW4 PGND 14 15



PIN DESCRIPTION

No.				
QFN	eTSSOP	Pin	Description	
1	11	GND	Ground	
2,3	12,13	SW1, SW2	Switch pin for LED matrix scanning.	
4,8	14,18	PGND	Power GND, connect to GND.	
5~7	15~17	SW3~ SW5	Switch pin for LED matrix scanning.	
9	19	SW6	Switch pin for LED matrix scanning.	
10,11	20,21	CS1, CS2	Current source.	
12,17	22,27	PVCC	Power for current source.	
13~16	23~26	CS3~ CS6	Current source.	
18, 19	28,1	CS7, CS8	Current source.	
20	2	R_EXT	Input terminal used to connect an external resistor. This regulates current source DC current value.	
21	3	AVCC	Power for analog circuits.	
22	4	VIO	Input logic reference voltage.	
23	5	SYNC	Synchronize pin. It is used for more than one part work synchronize. If it is not used please float this pin.	
24	6	SDA	I2C compatible serial data.	
25	7	SCL	I2C compatible serial clock.	
26	8	ADDR	I2C address setting.	
27	9	INTB	Interrupt output pin. Register F0h sets the function of the INTB pin and active low when the interrupt event happens. Can be NC (float) if interrupt function no used.	
28	10	SDB	Shutdown the chip when pull to low.	
		Thermal Pad	Need to connect to GND pins.	



ORDERING INFORMATION Industrial Range: -40°C to +125°C

Order Part No.	Package	QTY/Reel
IS31FL3738-QFLS4-TR IS31FL3738-ZLS4-TR	QFN-28, Lead-free eTSSOP-28, Lead-free	2500

Copyright © 2018 Integrated Silicon Solution, Inc. All rights reserved. ISSI reserves the right to make changes to this specification and its products at any time without notice. ISSI assumes no liability arising out of the application or use of any information, products or services described herein. Customers are advised to obtain the latest version of this device specification before relying on any published information and before placing orders for products. Integrated Silicon Solution, Inc. does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless Integrated Silicon Solution, Inc. receives written assurance to its satisfaction, that: a.) the risk of injury or damage has been minimized;

b.) the user assume all such risks; and

c.) potential liability of Integrated Silicon Solution, Inc is adequately protected under the circumstances



ABSOLUTE MAXIMUM RATINGS

Supply voltage, V _{CC}	-0.3V ~ +6.0V
Voltage at any input pin	$-0.3V \sim V_{CC} + 0.3V$
Maximum junction temperature, T _{JMAX}	+150°C
Storage temperature range, T _{STG}	-65°C ~ +150°C
Operating temperature range, $T_A=T_J$	-40°C ~ +125°C
Package thermal resistance, junction to ambient (4 layer standard	41.5°C/W (QFN)
test PCB based on JEDEC standard), θ_{JA}	30.08°C/W (eTSSOP)
ESD (HBM)	±2kV
ESD (CDM)	±750V

Note:

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other condition beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

The following specifications apply for V_{CC} = 3.6V, T_A = 25°C, unless otherwise noted.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _{cc}	Supply voltage		2.7		5.5	V
V _{IO}	Input logic reference voltage		1.8		V _{CC}	V
I _{cc}	Quiescent power supply current	$V_{SDB} = V_{CC}$, all LEDs off		2.17		mA
		V _{SDB} = 0V		3		
I _{SD}	Shutdown current	V _{SDB} = V _{CC} , Configuration Register written "0000 0000		3		μA
I _{OUT}	Maximum constant current of CS1~CS8	R _{EXT} =20kΩ		84		mA
I _{LED}	Average current on each LED I _{LED} = (I _{OUT} /2/12.75)×4	R _{EXT} = 20kΩ, GCC= 255, PWM= 255		13.2		mA
M	Current sink headroom voltage SW1~SW6	I _{SINK} = 672mA (Note 1, 2)		350		m)/
V _{HR}	Current source headroom voltage CS1~CS8	I _{SOURCE} = 84mA (Note 1)		350		mV
t _{SCAN}	Period of scanning			128		μs
t _{NOL}	Non-overlap blanking time during scan, the SWy and CSx are all off during this time			8		μs
Logic El	ectrical Characteristics (SDA, SC	L, ADDR, SYNC, SDB)				
VIL	Logic "0" input voltage	V _{IO} =3.6V	GND		$0.2V_{IO}$	V
V _{IH}	Logic "1" input voltage	V _{IO} =3.6V	0.75V _{IO}		V _{IO}	V
V _{HYS}	Input schmitt trigger hysteresis	V _{IO} =3.6V		0.2		V
V _{OL}	Logic "0" output voltage for SYNC	I _{OL} = 8mA			0.4	V
V _{OH}	Logic "1" output voltage for SYNC	I _{OH} = 8mA	0.75V _{IO}		1	V
IIL	Logic "0" input current	V _{INPUT} = 0V (Note 3)		5		nA
I _{IH}	Logic "1" input current	V _{INPUT} = V _{IO} (Note 3)		5		nA



DIGITAL INPUT SWITCHING CHARACTERISTICS (NOTE 3)

Querrahaal	Parameter		Fast Mode			Fast Mode Plus		
Symbol			Тур.	Max.	Min.	Тур.	Max.	Units
f _{SCL}	Serial-clock frequency	-		400	-		1000	kHz
t _{BUF}	Bus free time between a STOP and a START condition	1.3		-	0.5		-	μs
t _{HD, STA}	Hold time (repeated) START condition	0.6		-	0.26		-	μs
$t_{\text{SU, STA}}$	Repeated START condition setup time	0.6		-	0.26		-	μs
t _{SU, STO}	STOP condition setup time	0.6		-	0.26		-	μs
t _{HD, DAT}	Data hold time	-		-	-		-	μs
$t_{\text{SU, DAT}}$	Data setup time	100		-	50		-	ns
t _{LOW}	SCL clock low period	1.3		-	0.5		-	μs
t _{HIGH}	SCL clock high period	0.7		-	0.26		-	μs
t _R	Rise time of both SDA and SCL signals, receiving	-		300	-		120	ns
t _F	Fall time of both SDA and SCL signals, receiving	-		300	-		120	ns

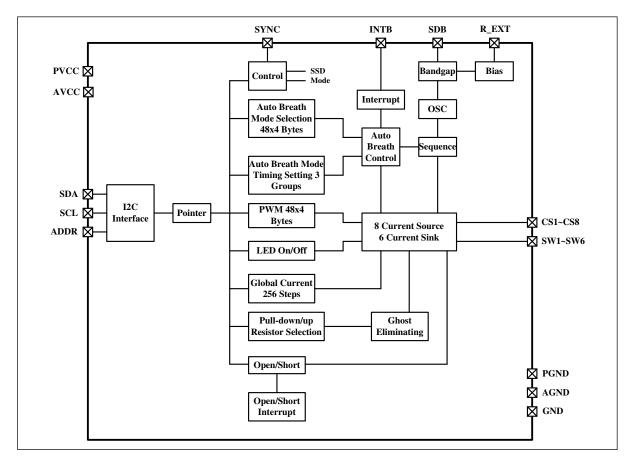
Note 1: In case of $R_{EXT} = 20k\Omega$, Global Current Control Register (PG3, 01h) written "1111 1111", GCC = "1111 1111".

Note 2: All LEDs are on and PWM = "1111 1111", GCC = "1111 1111".

Note 3: Guaranteed by design.



FUNCTIONAL BLOCK DIAGRAM





DETAILED DESCRIPTION

I2C INTERFACE

The IS31FL3738 uses a serial bus, which conforms to the I2C protocol, to control the chip's functions with two wires: SCL and SDA. The IS31FL3738 has a 7-bit slave address (A7:A1), followed by the R/W bit, A0. Set A0 to "0" for a write command and set A0 to "1" for a read command. The value of bits A4:A1 are decided by the connection of the ADDR pin. The complete slave address is:

Table 1 Slave Address:

ADDR2	ADDR1	A7:A5	A4:A1	A0
GND	GND		0000	
SCL	SCL	101	0101	0/1
SDA	SDA	101	1010	0/1
VCC	VCC		1111	

ADDR connected to GND, (A4:A1)=0000; ADDR connected to VCC, (A4:A1)=1111; ADDR connected to SCL, (A4:A1)=0101; ADDR connected to SDA, (A4:A1)=1010;

The SCL line is uni-directional. The SDA line is bidirectional (open-collector) with a pull-up resistor (typically $1k\Omega$). The maximum clock frequency specified by the I2C standard is 1MHz. In this discussion, the master is the microcontroller and the slave is the IS31FL3738.

The timing diagram for the I2C is shown in Figure 4. The SDA is latched in on the stable high level of the SCL. When there is no interface activity, the SDA line should be held high.

The "START" signal is generated by lowering the SDA signal while the SCL signal is high. The start signal will alert all devices attached to the I2C bus to check the incoming address against their own chip address.

The 8-bit chip address is sent next, most significant bit first. Each address bit must be stable while the SCL level is high.

After the last bit of the chip address is sent, the master checks for the IS31FL3738's acknowledge. The master releases the SDA line high (through a pull-up resistor). Then the master sends an SCL pulse. If the IS31FL3738 has received the address correctly, then it

holds the SDA line low during the SCL pulse. If the SDA line is not low, then the master should send a "STOP" signal (discussed later) and abort the transfer.

Following acknowledge of IS31FL3738, the register address byte is sent, most significant bit first. IS31FL3738 must generate another acknowledge indicating that the register address has been received.

Then 8-bit of data byte are sent next, most significant bit first. Each data bit should be valid while the SCL level is stable high. After the data byte is sent, the IS31FL3738 must generate another acknowledge to indicate that the data was received.

The "STOP" signal ends the transfer. To signal "STOP", the SDA signal goes high while the SCL signal is high.

ADDRESS AUTO INCREMENT

To write multiple bytes of data into IS31FL3738, load the address of the data register that the first data byte is intended for. During the IS31FL3738 acknowledge of receiving the data byte, the internal address pointer will increment by one. The next data byte sent to IS31FL3738 will be placed in the new address, and so on. The auto increment of the address will continue as long as data continues to be written to IS31FL3738 (Figure 7).

READING OPERATION

Register FEh, F1h and 18h~2Dh, 30h~45h of Page 0, 11h of Page 3 can be read.

To read the FEh and F1h, after I2C start condition, the bus master must send the IS31FL3738 device

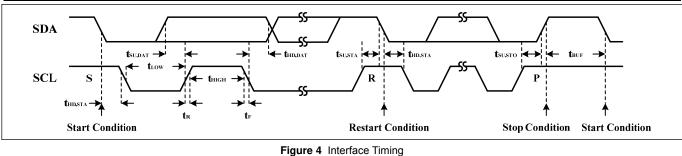
address with the R/\overline{W} bit set to "0", followed by the register address (FEh or F1h) which determines which register is accessed. Then restart I2C, the bus master should send the IS31FL3738 device address with the

R/W bit set to "1". Data from the register defined by the command byte is then sent from the CHROMA-96 to the master (Figure 8).

To read the 18h~2Dh, 30h~45h of Page 0, 11h of Page 3, the FDh should write with 00h before follow the Figure 8 sequence to read the data, that means, when you want to read 18h~2Dh, 30h~45h of Page 0, 11h of Page 3, the FDh should point to Page 0 or Page 3 first and you can read the Page 0 and Page 3 data.







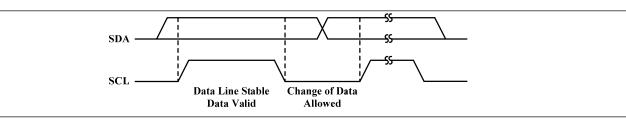


Figure 5 Bit Transfer

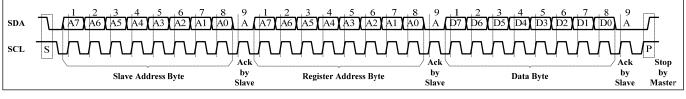
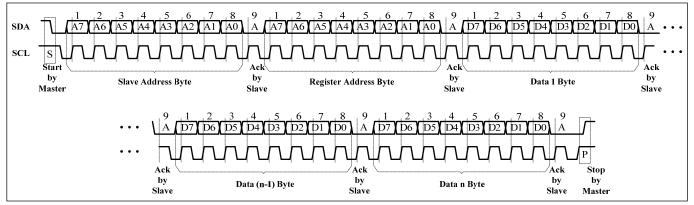
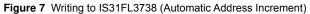


Figure 6 Writing to IS31FL3738 (Typical)





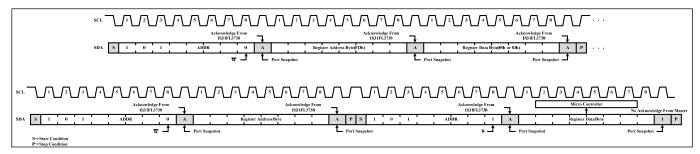


Figure 8 Reading from IS31FL3738



REGISTER DEFINITION-1

Address	Name	Function		R/W	Default
FDh	Command Register	Available Page 0 to Page 3 Registers	2	W	XXXX XXXX
FEh	Command Register Write Lock	To lock/unlock Command Register	3	R/W	
F0h	Interrupt Mask Register	Configure the interrupt function	4	W	0000 0000
F1h	Interrupt Status Register	Show the interrupt status	5	R	

REGISTER CONTROL

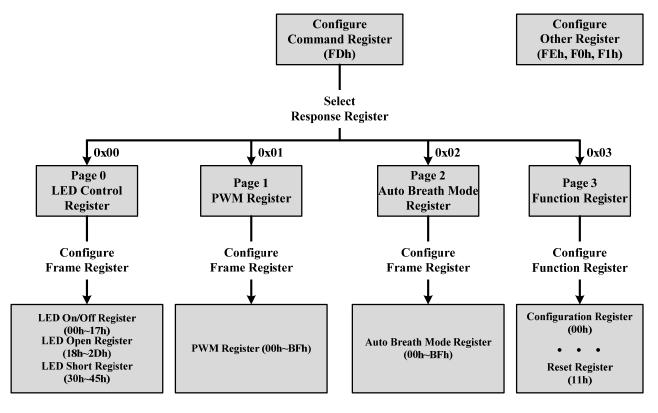


Table 2 FDh Command Register (Write Only)

Data	Function
0000 0000	Point to Page 0 (PG0, LED Control Register is available)
0000 0001	Point to Page 1 (PG1, PWM Register is available)
0000 0010	Point to Page 2 (PG2, Auto Breath Mode Register is available)
0000 0011	Point to Page 3 (PG3, Function Register is available)
Others	Reserved

Note: FDh is locked when power up, need to unlock this register before write command to it. See Table 3 for detail.

The Command Register should be configured first after writing in the slave address to choose the available register. Then write data in the choosing register. Power up default state is "0000 0000".

For example, when write "0000 0001" in the Command Register (FDh), the data which writing after will be stored in the Auto breath mode Register. Write new data can configure other registers.



Table 3 FEh Command Register Write Lock (Read/Write)

Bit	D7:D0
Name	CRWL
Default	0000 0000 (FDh write disable)

To select the PG0~PG3, need to unlock this register first, with the purpose to avoid misoperation of this register. When FEh is written with 0xC5, FDh is allowed to modify once, after the FDh is modified the FEh will reset to be 0x00 at once.

CRWL Command Register Write Lock

0x00 FDh write disable

0xC5 FDh write enable once

Table 4 F0h Interrupt Mask Register

Bit	D7:D4	D3	D2	D1	D0
Name	-	IAC	IAB	IS	IO
Default	0000	0	0	0	0

Configure the interrupt function for IC.

IAC Auto Clear Interrupt Bit

0 Interrupt could not auto clear

1 Interrupt auto clear when INTB stay low exceeds 8ms

- IAB Auto Breath Interrupt Bit
- 0 Disable auto breath loop finish interrupt
- 1 Enable auto breath loop finish interrupt
- IS Dot Short Interrupt Bit
- 0 Disable dot short interrupt
- 1 Enable dot short interrupt
- IO Dot Open Interrupt Bit
- 0 Disable dot open interrupt
- 1 Enable dot open interrupt

Table 5 F1h Interrupt Status Register

Bit	D7:D5	D4	D3	D2	D1	D0
Name	-	ABM3	ABM2	ABM1	SB	OB
Default	000	0	0	0	0	0

Show the interrupt status for IC.

ABM3 Auto Breath Mode 3 Finish Bit

- 0 ABM3 not finish
- 1 ABM3 finish

ABM2 Auto Breath Mode 2 Finish Bit

- 0 ABM2 not finish
- 1 ABM2 finish
- ABM1 Auto Breath Mode 1 Finish Bit
- 0 ABM1 not finish
- 1 ABM1 finish
- SB Short Bit
- 0 No short
- 1 Short happens

OB Open Bit

- 0 No open
- 1 Open happens



REGISTER DEFINITION-2

Address	Name	Function	Table	R/W	Default	
PG0 (0x00)	: LED Control Register		<u>.</u>			
00h ~ 17h	LED On/Off Register	Set on or off state for each LED	7	W		
18h ~ 2Dh	LED Open Register	Store open state for each LED	8	R	0000 0000	
30h ~ 45h	LED Short Register	Store short state for each LED	9	R		
PG1 (0x01)	: PWM Register					
00h~BFh	PWM Register	Set PWM duty for LED	10	W	0000 0000	
PG2 (0x02)	: Auto Breath Mode Regist	er				
00h~BFh	Auto Breath Mode Register	Set operating mode of each dot	11	W	0000 0000	
PG3 (0x03)	: Function Register					
00h	Configuration Register	Configure the operation mode	13	W		
01h	Global Current Control Register	Set the global current	14	W		
02h	Auto Breath Control Register 1 of ABM-1	Set fade in and hold time for breath function of ABM-1	15	W		
03h	Auto Breath Control Register 2 of ABM-1	Set the fade out and off time for breath function of ABM-1	16	W		
04h	Auto Breath Control Register 3 of ABM-1	Set loop characters of ABM-1	17	W	_	
05h	Auto Breath Control Register 4 of ABM-1	Set loop characters of ABM-1	18	18 W		
06h	Auto Breath Control Register 1 of ABM-2	Set fade in and hold time for breath function of ABM-2	15	W		
07h	Auto Breath Control Register 2 of ABM-2	Set the fade out and off time for breath function of ABM-2	16	W		
08h	Auto Breath Control Register 3 of ABM-2	Set loop characters of ABM-2	17	W	0000 0000	
09h	Auto Breath Control Register 4 of ABM-2	Set loop characters of ABM-2	18	W		
0Ah	Auto Breath Control Register 1 of ABM-3	Set fade in and hold time for breath function of ABM-3	15	W		
0Bh	Auto Breath Control Register 2 of ABM-3	Set the fade out and off time for breath function of ABM-3	16	W		
0Ch	Auto Breath Control Register 3 of ABM-3	Set loop characters of ABM-3	17	W		
0Dh	Auto Breath Control Register 4 of ABM-3	Set loop characters of ABM-3	18	W	W	
0Eh	Time Update Register	Update the setting of 02h ~ 0Dh registers	-	W		
0Fh	SWy Pull-Up Resistor Selection Register	Set the pull-up resistor for SWy	19	W		
10h	CSx Pull-Down Resistor Selection Register	Set the pull-down resistor for CSx	20	W		
11h	Reset Register	Reset all register to POR state	-	R		



Table 6-1 Page 0 (PG0, 0x00): LED Control Register - On Off Register

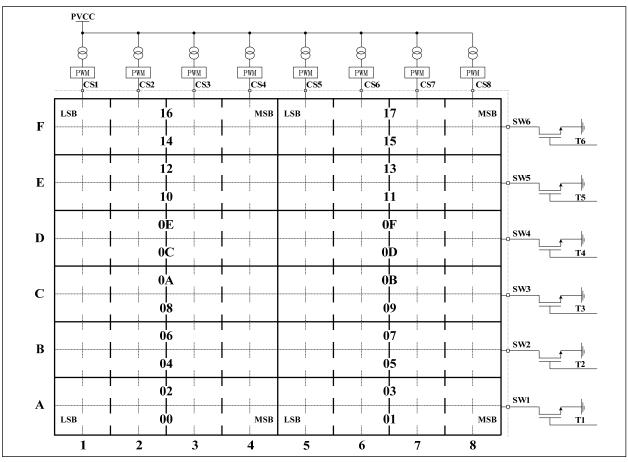


Figure 9 On off Register

Table 7 00h ~ 17h LED On/Off Register

Bit	D7:D0
Name	C_{CS8} : C_{CS1} or C_{CS16} : C_{CS9}
Default	0000 0000

The LED On/Off Registers store the on or off state of each LED in the Matrix.

Each LED has 4 bits on and off state, need to turn on/off them when turn on/off the LED.

For example:

When turn on LED 1-A, need to turn on D1:D0 of 00h, and D1:D0 of 02h

C_{X-Y} LED State Bit

- 0 LED off
- 1 LED on



Table 6-2 Page 0 (PG0, 0x00): LED Control Register – Open Detect Register

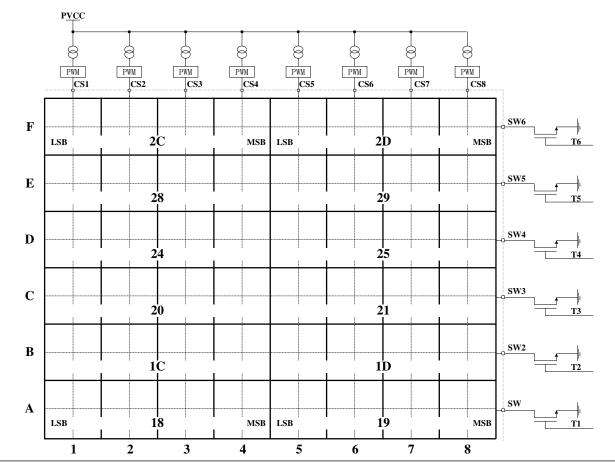


Figure 10 On off Register

Table 8 18h ~ 2Dh LED Open Register

Bit	D7	D6	D5	D4	D3	D2	D1	D0
Name	OP ₈	-	OP_6	-	OP ₄	-	OP_2	-
Default	0	-	0	-	0	-	0	-

The LED Open Registers store the open or normal state of each LED in the Matrix.

- OPx LED Open Bit
- 0 LED normal
- 1 LED open



Table 6-3 Page 0 (PG0, 0x00): LED Control Register – Short Detect Register

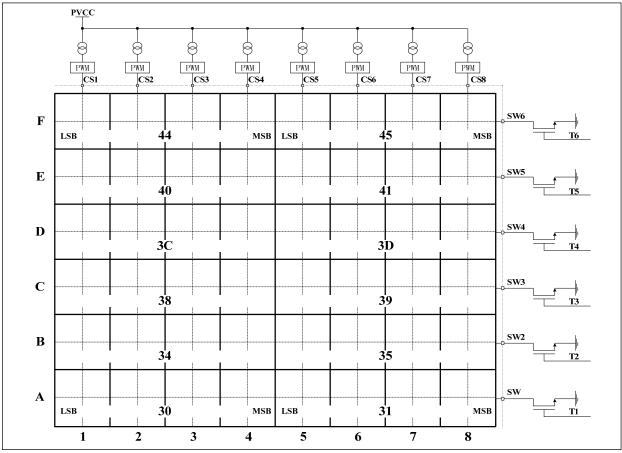


Figure 10 On off Register

Table 9 30h ~ 45h LED Short Register

Bit	D7	D6	D5	D4	D3	D2	D1	D0
Name	ST ₈	-	ST_6	-	ST_4	-	ST_2	-
Default	0	-	0	-	0	-	0	-

The LED Short Registers store the short or normal state of each LED in the Matrix.

OPx LED Short Bit

0 LED normal

1 LED short



Table 6-4 Page 1 (PG1, 0x01): PWM Register

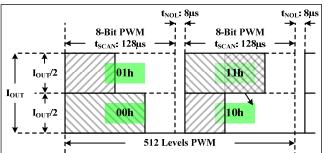
	PV	cc															
	P	M CS1	P	M CS2	_	MM CS3		M CS4	P	→ → CS5	_) M CS6		M CS7	_		
F	B0	B1	B2	B3	B4	B5	B6	B7	B8	B9	BA	BB	BC	BD	BE	BF	SW6
Г	A0	A1	A2	A3	A4	A5	A6	A7	A8	A9	AA	AB	AC	AD	AE	AF	
Е	90	91	92	93	94	95	96	97	98	99	9A	9B	9C	9D	9E	9F	SW5
L	80	81	82	83	84	85	86	87	88	89	8A	8B	8C	8D	8 E	8 F	
D	70	71	72	73	74	75	76	77	78	79	7A	7B	7C	7D	7E	7 F	SW4
D	60	61	62	63	64	65	66	67	68	69	6A	6B	6C	6D	6E	6 F	
С	50	51	52	53	54	55	56	57	58	59	5A	5B	5C	5D	5E	5F	
C	40	41	42	43	44	45	46	47	48	49	4 A	4B	4C	4D	4E	4F	
В	30	31	32	33	34	35	36	37	38	39	3A	3B	3C	3D	3E	3F	SW2
D	20	21	22	23	24	25	26	27	28	29	2A	2B	2C	2D	2E	2F	
А	10	Λ^{11}	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	SW1
28	00	A 01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F	
		1		2		3	4	4	:	5		5	,	7		8	

Figure 11 PWM Register

Table 10 00h ~ BFh PWM Register

Bit	D7:D0
Name	PWM
Default	0000 0000

Each dot has 4 bytes to modulate the PWM duty in 512 steps. Each byte controls half of the I_{OUT} and half of the duty, like LED 1A (Figure 11), the current will be as shown below:



The value of the PWM Registers decides the average current of each LED noted I_{LED} . I_{LED} computed by Formula (1):

$$I_{LED} = \frac{\sum PWM}{512} \times I_{OUT} \times Duty \qquad (1)$$
$$PWM = \sum_{n=0}^{7} D[n] \cdot 2^{n}$$

Where Duty is the duty cycle of SWy/2,

$$Duty = \frac{128\mu s}{(128\mu s + 8\mu s)} \times \frac{1}{6} \times \frac{1}{2} = \frac{1}{12.75}$$
 (2)

 I_{OUT} is the output current of CSx (x=1~8),

$$I_{OUT} = \frac{840}{R_{FXT}} \times \frac{GCC}{256} \times 2 \tag{3}$$

GCC is the Global Current Control register (PG3, 01h) value and R_{EXT} is the external resistor of R_EXT pin. D[n] stands for the individual bit value, 1 or 0, in location n.

For example 1:

If 00h=0xff, 01h=0xff, 10h=0xff, 11h=0xff, GCC=255. R_{EXT} =20k Ω (I_{OUT}=84mA),



$$\begin{split} I_{LED-1A} &= \frac{0 x f f + 0 x f f + 0 x f f + 0 x f f + 0 x f f}{512} \times I_{OUT} \times \frac{1}{12.75} \\ &= 13.13 m A \\ \text{For example 2:} \\ \text{If 00h=0x80, 01h=0x80, 10h=0x80, 11h=0x00,} \\ \text{GCC=255. R_{EXT}=20 k\Omega (I_{OUT}=84 \text{mA}),} \\ I_{LED-1A} &= \frac{0 x 80 + 0 x 80 + 0 x 80 + 0 x 00}{512} \times I_{OUT} \times \frac{1}{12.75} \\ &= 4.94 m A \end{split}$$



Table 6-4 Page 2 (PG2, 0x02): Auto Breath Mode Register

	PV	<u>c</u> c															
	_	3	6	3	_	3	6	3	6	3				3			
		CS1	PI	CS2		M CS3		VM CS4		M CS5		MM CS6	<u>P</u>	M CS7	<u>P</u>	VM CS8	
F	BO	B1	B2	B3	B4	B5	B6	B7	B8	B9	BA	BB	BC	BD	BE	BF	SW6
ſ	A0	A1	A2	A3	A4	A5	A6	A7	A8	A9	AA	AB	AC	AD	AE	AF	
E	90	91	92	93	94	95	96	97	98	99	9A	9B	9C	9D	9E	9F	SW5
	80	81	82	83	84	85	86	87	88	89	8A	8B	8C	8D	8 E	8 F	
D	70	71	72	73	74	75	76	77	78	79	7A	7B	7C	7D	7 E	7 F	SW4
	60	61	62	63	64	65	66	67	68	69	6A	6B	6C	6D	6E	6F	
C	50	51	52	53	54	55	56	57	58	59	5A	5B	5C	5D	5E	5F	SW3
	40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4 E	4F	
В	30	31	32	33	34	35	36	37	38	39	3A	3B	3C	3D	3 E	3F	SW2
	20	21	22	23	24	25	26	27	28	29	2A	2B	2C	2D	2E	2F	
A	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	SW
	00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F	
		1	,	2		3	4	4		5		6		7	8	8	•

Figure 12 Auto Breath Mode Selection Register

Table 11 00h ~ BFh Auto Breath Mode Register

Bit	D7:D2	D1:D0		
Name	-	ABMS		
Default	000000	00		

The Auto Breath Mode Register sets operating mode of each dot, notice four registers should be the same value when you selecting the mode.

For example, if 00h=0x01, 01h=0x01, 10h=0x01, 11h=0x01, then LED 1A works as ABM-1 mode.

ABMS Auto Breath Mode Selection Bit

00 PWM control mode

- 01 Select Auto Breath Mode 1 (ABM-1)
- 10 Select Auto Breath Mode 2 (ABM-2)
- 11 Select Auto Breath Mode 3 (ABM-3)



Table 12 Page 3 (PG3, 0x03): Function Register

Register	Name	Function	R/W	Default
00h	Configuration Register	Configure the operation mode	W	
01h	Global Current Control Register	Set the global current	W	
02h	Auto Breath Control Register 1 of ABM-1	Set fade in and hold time for breath function of ABM-1	W	
03h	Auto Breath Control Register 2 of ABM-1	Set the fade out and off time for breath function of ABM-1	W	
04h	Auto Breath Control Register 3 of ABM-1	Set loop characters of ABM-1	W	
05h	Auto Breath Control Register 4 of ABM-1	Set loop characters of ABM-1	W	
06h	Auto Breath Control Register 1 of ABM-2	Set fade in and hold time for breath function of ABM-2	W	
07h	Auto Breath Control Register 2 of ABM-2	Set the fade out and off time for breath function of ABM-2	W	
08h	Auto Breath Control Register 3 of ABM-2	Set loop characters of ABM-2	W	0000
09h	Auto Breath Control Register 4 of ABM-2	Set loop characters of ABM-2	W	0000
0Ah	Auto Breath Control Register 1 of ABM-3	Set fade in and hold time for breath function of ABM-3	W	
0Bh	Auto Breath Control Register 2 of ABM-3	Set the fade out and off time for breath function of ABM-3	W	
0Ch	Auto Breath Control Register 3 of ABM-3	Set loop characters of ABM-3	W	
0Dh	Auto Breath Control Register 4 of ABM-3	Set loop characters of ABM-3	W	
0Eh	Time Update Register	Update the setting of 02h ~ 0Dh registers	W	
0Fh	SWy Pull-Up Resistor Selection Register	Set the pull-up resistor for SWy	W	
10h	CSx Pull-Down Resistor Selection Register	Set the pull-down resistor for CSx	W	
11h	Reset Register	Reset all register to POR state	R	

Table 13 00h Configuration Register

Bit	D7:D6	D5:D3	D2	D1	D0
Name	SYNC	-	OSD	B_EN	SSD
Default	00	000	0	0	0

The Configuration Register sets operating mode of IS31FL3738.

When SYNC bits are set to "01", the IS31FL3738 is configured as the master clock source and the SYNC pin will generate a clock signal distributed to the clock slave devices. To be configured as a clock slave device and accept an external clock input the slave device's SYNC bits must be set to "10". When OSD set high, open/short detection will be trigger once, the user could trigger OS detection again by set OSD from 0 to 1.

When B_EN enable, those dots select working in ABM-x mode will start to run the pre-established timing. If it is disabled, all dots work in PWM mode. Following Figure 16 to enable the Auto Breath mode When SSD is "0", IS31FL3738 works in software shutdown mode and to normal operate the SSD bit should set to "1".

SYNC	Synchronize Configuration
00/11	High impedance
01	Master
10	Slave
OSD	Open/Short Detection Enable Bit
0	Disable open/short detection
1	Enable open/short detection
B_EN	Auto Breath Enable
0	PWM Mode enable
1	Auto Breath Mode enable
SSD	Software Shutdown Control
0	Software shutdown
1	Normal operation

Table 14 01h Global Current Control Register

Bit	D7:D0
Name	GCCx
Default	0000 0000

The Global Current Control Register modulates all CSx (x=1~8) DC current which is noted as I_{OUT} in 256 steps.

I_{OUT} is computed by the Formula (3):

$$I_{OUT} = \frac{840}{R_{EXT}} \times \frac{GCC}{256}$$
(3)
$$GCC = \sum_{n=0}^{7} D[n] \cdot 2^{n}$$

Where D[n] stands for the individual bit value, 1 or 0, in location n, R_{EXT} is the external resistor of REXT pin.

For example: if D7:D0 = 1011 0101,

$$I_{OUT} = \frac{2^0 + 2^2 + 2^4 + 2^5 + 2^7}{256} \times \frac{840}{R_{EXT}}$$

Table 15 02h, 06h, 0Ah Auto Breath Control Register 1 of ABM-x

Bit	D7:D5	D4:D1	D0
Name	T1	T2	-
Default	000	0000	0

Auto Breath Control Register 1 set the T1&T2 time in Auto Breath Mode.

T1 000 001 010 011 100 101	T1 Setting 0.21s 0.42s 0.84s 1.68s 3.36s 6.72s
110	13.44s
111	26.88s
T2	T2 Setting
0000	0s
0001	0.21s
0010	0.42s
0011	0.84s
0100	1.68s
0101	3.36s
0110	6.72s
0111	13.44s
1000	26.88s
Others	Unavailable

Table 16 03h, 07h, 0Bh Auto Breath Control Register 2 of ABM-x

Bit	D7:D5	D4:D1	D0
Name	Т3	T4	-
Default	000	0000	0

Auto Breath Control Register 2 set the T3&T4 time in Auto Breath Mode.

Т3	T3 Setting	
000	0.21s	
001	0.42s	
010	0.84s	
011	1.68s	
100	3.36s	
101	6.72s	
110	13.44s	
111	26.88s	
T4	T4 Setting	
0000	0s	
0001	0.21s	
0010	0.42s	
0011	0.84s	
0100	1.68s	
0101	3.36s	
0110	6.72s	
0111	13.44s	
1000	26.88s	
1001	53.76s	
1010	107.52s	
Others	Unavailable	





Table 17 04h, 08h, 0Ch Auto Breath Control Register 3 of ABM-x

Bit	D7:D6	D5:D4	D3:D0
Name	LE	LB	LTA
Default	00	00	0000

Total loop times= LTA ×256 + LTB.

For example, if LTA=2, LTB=100, the total loop times is 256×2+100= 612 times.

For the counting of breathing times, do follow Figure 16 to enable the Auto Breath Mode.

If the loop start from T4,

T4->T1->T2->T3(1)->T4->T1->T2->T3(2)->T4->T1->... and so on.

If the loop not start from T4,

Tx->T3(1) ->T4->T1->T2->T3(2)->T4-> T1->... and so on.

If the loop ends at off state (End of T3), the LED will be off state at last. If the loop ends at on state (End of T1), the LED will run an extra T4&T1, which are not included in loop.

00	Loop end at off state	(End of T3)
----	-----------------------	-------------

- 01 Loop end at on state (End of T1)
- Others Unavailable

LB	Loop Beginning	Time
----	----------------	------

- 00 Loop begin from T1
- 01 Loop begin from T2
- 10 Loop begin from T3
- 11 Loop begin from T4

LTA	8-11 Bits Of Loop Times
0000	Endless loop

- 0000 Endle: 0001 1
- 0010 2
-

1111 15

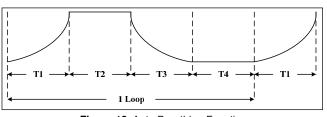




Table 18 05h, 09h, 0DhAuto Breath ControlRegister 4 of ABM-x

Bit	D7:D0
Name	LTB
Default	0000 0000

Total loop times= LTA ×256 + LTB.

For example, if LTA=2, LTB=100, the total loop times is $256 \times 2+100 = 612$ times.

0-7 Bits Of Loop Times
Endless loop
1
2
255

0Eh Time Update Register (02h~0Dh)

The data sent to the time registers (02h~0Dh) will be stored in temporary registers. A write operation of "0000 0000" data to the Time Update Register is required to update the registers (02h~0Dh). Please follow Figure 16 to enable the Auto Breath mode and update the time parameters.

Table 19 0Fh SWy Pull-Up Resistor SelectionRegister

Bit	D7:D3	D2:D0
Name	-	PUR
Default	00000	000

Set pull-up resistor for SWy.

PUR SWy Pull-up Resistor Selection Bit	PUR	SWy Pull-up	Resistor	Selection	Bit
---	-----	-------------	----------	-----------	-----

000	No pull-up resiste	or

001	0.5kΩ	
010	1.0kΩ	

011 2.0kΩ

100 4.0kΩ

101 8.0kΩ
110 16kΩ

111 32kΩ



Table 20 10h CSx Pull-Down Resistor Selection Register

Bit	D7:D3	D2:D0
Name	-	PDR
Default	00000	000

Set the pull-down resistor for CSx.

PDR CSx Pull-down Resistor Selection Bit

000	No pull-down resistor	
-----	-----------------------	--

001	0.5kΩ
010	1.0kΩ
011	2.0kΩ
100	4.0kΩ

101 8.0kΩ

110 16kΩ

111 32kΩ

11h Reset Register

Once user read the Reset Register, IS31FL3738 will reset all the IS31FL3738 registers to their default value. On initial power-up, the IS31FL3738 registers are reset to their default values for a blank display.



APPLICATION INFORMATION

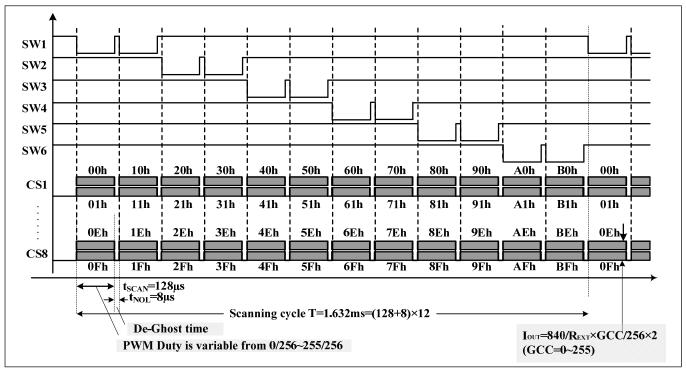


Figure 14 Scanning Timing

SCANING TIMING

As shown in Figure 12, the SW1~SW6 is turned on by serial, LED is driven 8 by 8 within the SWy (x=1~6) on time (SWy, y=1~6) is sink and pull low when LED on), including the non-overlap blanking time during scan, the duty cycle of SWy (active low, y=1~6) is:

$$Duty = \frac{128\mu s}{(128\mu s + 8\mu s)} \times \frac{1}{6} \times \frac{1}{2} = \frac{1}{12.75} \quad (2)$$

Where 128 μs is $t_{SCAN},$ the period of scanning and 8 μs is $t_{NOL},$ the non-overlap time.

EXTERNAL RESISTOR (R_{EXT})

The output current for each CSx can be can be set by a single external resistor, $R_{\text{EXT}},$ as described in Formula (3).

$$I_{OUT} = \frac{840}{R_{FXT}} \times \frac{GCC}{256} \times 2 \tag{3}$$

GCC is Global Current Control Register (PG3, 01h) data showing in Table 14.

PWM CONTROL

After setting the I_{OUT} and GCC, the brightness of each LEDs (LED average current (I_{LED})) can be modulated with 512 steps by PWM Register, as described in Formula (1).

$$I_{LED} = \frac{\sum PWM}{256} \times (I_{OUT} / 2) \times Duty$$
(1)

Where PWM is PWM Registers (PG1, 00h~BFh) data showing in Table 10.

For example, in Figure 1, 00h=0xff, 01h=0xff, 10h=0xff, 11h=0xff, GCC=255. R_{EXT}=20k Ω (I_{OUT}=84mA),

$$I_{LED-1A} = \frac{0xff + 0xff + 0xff + 0xff + 0xff}{256} \times (I_{OUT} / 2) \times \frac{1}{12.75}$$

= 13.13mA

For example 2:

In Figure 1, 00h=0x80, 01h=0x80, 10h=0x80, 11h=0x00, GCC=255. REXT=20kΩ (IOUT=84mA),

$$I_{LED-1A} = \frac{0x80 + 0x80 + 0x80 + 0x00}{256} \times (I_{OUT} / 2) \times \frac{1}{12.75}$$

= 4.94 mA

Writing new data continuously to the registers can modulate the brightness of the LEDs to achieve a breathing effect.



LED AVERAGE CURRENT (ILED)

As described in Formula (1), the LED average current (I_{LED}) is effected by 3 factors:

1. R_{EXT} , resistor which is connected R_EXT pin and GND. R_{EXT} sets the current of all CSx (x=1~8) based on Formula (3).

2. Global Current Control Register (PG3, 01h). This register adjusts all CSx (x=1~8) output currents by 256 steps as shown in Formula (3).

3. PWM Registers (PG1, 00h~BFh), every LED has an own PWM register. PWM Registers adjust individual LED average current by 512 steps as shown in Formula (1).

GAMMA CORRECTION

In order to perform a better visual LED breathing effect we recommend using a gamma corrected PWM value to set the LED intensity. This results in a reduced number of steps for the LED intensity setting, but causes the change in intensity to appear more linear to the human eye.

Gamma correction, also known as gamma compression or encoding, is used to encode linear luminance to match the non-linear characteristics of display. Since the IS31FL3738 can modulate the brightness of the LEDs with 512 steps, a gamma correction function can be applied when computing each subsequent LED intensity setting such that the changes in brightness matches the human eye's brightness curve.

Table 21 32 Gamma Steps with 256 PWM Steps

C(0)	C(1)	C(2)	C(3)	C(4)	C(5)	C(6)	C(7)
0	1	2	4	6	10	13	18
C(8)	C(9)	C(10)	C(11)	C(12)	C(13)	C(14)	C(15)
22	28	33	39	46	53	61	69
C(16)	C(17)	C(18)	C(19)	C(20)	C(21)	C(22)	C(23)
78	86	96	106	116	126	138	149
C(24)	C(25)	C(26)	C(27)	C(28)	C(29)	C(30)	C(31)
161	173	186	199	212	226	240	255

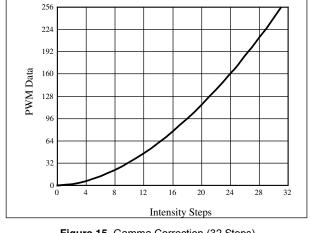


Figure 15 Gamma Correction (32 Steps)

Choosing more gamma steps provides for a more continuous looking breathing effect. This is useful for very long breathing cycles. The recommended configuration is defined by the breath cycle T. When T=1s, choose 32 gamma steps, when T=2s, choose 64 gamma steps. The user must decide the final number of gamma steps not only by the LED itself, but also based on the visual performance of the finished product.

Table 22 64 Gamma Steps with 256 PWM Steps

C(0)	C(1)	C(2)	C(3)	C(4)	C(5)	C(6)	C(7)
0	1	2	3	4	5	6	7
C(8)	C(9)	C(10)	C(11)	C(12)	C(13)	C(14)	C(15)
8	10	12	14	16	18	20	22
C(16)	C(17)	C(18)	C(19)	C(20)	C(21)	C(22)	C(23)
24	26	29	32	35	38	41	44
C(24)	C(25)	C(26)	C(27)	C(28)	C(29)	C(30)	C(31)
47	50	53	57	61	65	69	73
C(32)	C(33)	C(34)	C(35)	C(36)	C(37)	C(38)	C(39)
77	81	85	89	94	99	104	109
C(40)	C(41)	C(42)	C(43)	C(44)	C(45)	C(46)	C(47)
114	119	124	129	134	140	146	152
C(48)	C(49)	C(50)	C(51)	C(52)	C(53)	C(54)	C(55)
158	164	170	176	182	188	195	202
C(56)	C(57)	C(58)	C(59)	C(60)	C(61)	C(62)	C(63)
209	216	223	230	237	244	251	255

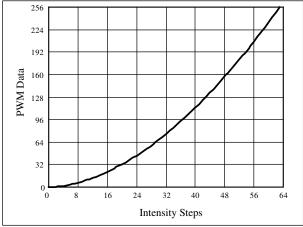


Figure 16 Gamma Correction (64 Steps)

Note: The data of 32 gamma steps is the standard value and the data of 64 gamma steps is the recommended value.

OPERATING MODE

Each dot of IS31FL3738 has two selectable operating modes, PWM Mode and Auto Breath Mode.

PWM Mode

By setting the Auto Breath Mode Register bits of the Page 2 (PG2, 00h~BFh) to "00", or disable the B_EN bit of Configure Register (PG3, 00h), the IS31FL3738 operates in PWM Mode. The brightness of each LED can be modulated with 512 steps by PWM registers.