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## Triple 4:1 Single Supply Video Multiplexing Amplifier

The ISL59452 is a 4-input, single-supply, triple video multiplexer suited for component video applications. The device features single +5 V supply operation, high bandwidth and TTL/CMOS logic compatible gain select (AV2) of $x 1$ or x2. When HIZ is pulled high, the outputs are put into highimpedance states and the video inputs are disconnected putting the device in a low power state. This is an essential feature for power sensitive applications. The ISL59452 also features fast channel switching at pixel rates to allow for video overlays.

The ISL59452 will drive $150 \Omega$ loads making it suitable for $75 \Omega$ cable driving applications. The ISL59452 is ideal for RGB, YPbPr, as well as S-Video and composite applications.

The ISL59452 comes in a 32 Ld QFN package and is specified for operation over $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range.

## Ordering Information

| PART NUMBER <br> (Note) | PART <br> MARKING | PACKAGE <br> (Pb-Free) | PKG. <br> DWG. \# |
| :--- | :--- | :---: | :---: |
| ISL59452IRZ | ISL594 52IRZ | 32 Ld 5x5 QFN | L32.5×5 |
| ISL59452IRZ-T7* | ISL594 52IRZ | 32 Ld 5x5 QFN | L32.5 55 |

*Please refer to TB347 for details on reel specifications.
NOTE: These Intersil Pb-free plastic packaged products employ special Pb-free material sets; molding compounds/die attach materials and $100 \%$ matte tin plate PLUS ANNEAL - e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb -free soldering operations. Intersil Pb -free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

## Features

- 250MHz Small Signal Bandwidth (GAIN 1)
- Capable of Pixel Rate Channel Switching
- +5V Single Supply Operation
- TTL/CMOS Compatible Gain Select of x 1 or x 2
- High Impedance Output Setting
- Ideal for RGB/YPbPr/S-Video/Composite Video Signals
- $150 \Omega$ Output Load Capability for Video Cable Driving
- $0.0013 \%$ Differential Gain and $0.035^{\circ}$ Differential Phase Accuracy
- Pb-Free (RoHS Compliant)


## Applications

- SDTVs and HDTVs
- Set-Top Boxes
- Video Overlay
- Security Video
- Broadcast Video Equipment


## Pinout



EXPOSED THERMAL PAD MUST BE CONNECTED TO GND.

| Absolute Maximum Ratings ( $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ ) |  |
| :---: | :---: |
| Supply Voltage (V+ to GND) | 5.5 V |
| Input Voltage to GND. | GND - 0.5V to $\mathrm{V}++0.5 \mathrm{~V}$ |
| Voltage between HIZ, AV2 and GND | GND -0.5; $\mathrm{V}++0.5 \mathrm{~V}$ |
| Supply Turn-on Slew Rate | 1V/us |
| Digital and Analog Input Current (Note 1) | 50mA |
| Output Current (Continuous) | 50 mA |
| ESD Rating |  |
| Human Body Model (Per MIL-STD-883 | ethod 3015.7). . . .2500V |
| Machine Model | . 300 V |

## Thermal Information

Storage Temperature Range . . . . . . . . . . . . . . . . . . $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Ambient Operating Temperature . . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
Operating Junction Temperature . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$
Power Dissipation . . . . . . . . . . . . . . . . . . . . . . . . . . . . . See Curves
Pb-free reflow profile . . . . . . . . . . . . . . . . . . . . . . . . . see link below http://www.intersil.com/pbfree/Pb-FreeReflow.asp

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTE:

1. If an input signal is applied before the supplies are powered up, the input current must be limited to these maximum values.
2. Parts are $100 \%$ tested at $+25^{\circ} \mathrm{C}$. Over temperature limits established by characterization and are not production tested.

Electrical Specifications $\quad \mathrm{V}+=+5 \mathrm{~V}, \mathrm{GND}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{AV} 2=\mathrm{HIZ}=0.8 \mathrm{~V}$, unless otherwise specified.

| PARAMETER | DESCRIPTION | MIN <br> (Note 2) | CONDITIONS | MAX <br> (Note 2) | UNIT |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |


| OUTPUT AMPLIFIERS |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OUT }+}$ | Output High Swing | $\mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{~V}_{\text {IN }}=4 \mathrm{~V}, \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{GAIN}=2$ | 3.5 |  |  | V |
| Vout- | Output Low Swing | $\mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{~V}_{\text {IN }}=0 \mathrm{~V}, \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{GAIN}=2$ |  |  | 30 | mV |
| ISC | Short Circuit Current | Sourcing, $\mathrm{V}_{\mathrm{IN}}=3 \mathrm{~V}, \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=10 \Omega$ to GND, GAIN = 2 |  | 125 |  | mA |
|  |  | Sinking, $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=10 \Omega$ to +3 V |  | 57 |  | mA |

## LOGIC (AV2, HIZ, S1, S0)

| $\mathrm{V}_{\mathrm{IH}}$ | Input High Voltage (HIGH) |  | 2 |  |  | V |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IL }}$ | Input Low Voltage (LOW) |  |  |  | 0.8 | V |
| $\mathrm{IIH}^{\text {I }}$ | Input High Current (Logic Inputs) | S1 = S0 = 5V (no pull-up or pull-down) | -2 | 0 | 2 | $\mu \mathrm{A}$ |
|  |  | AV2 $=\mathrm{HIZ}=5 \mathrm{~V}$ ( $300 \mathrm{k} \Omega$ internal pull-downs) | 8 | 17 | 34 | $\mu \mathrm{A}$ |
| IIL | Input Low Current (Logic Inputs) | S1 = S0 = OV (no pull-up or pull-down) | -2 | 0 | 2 | $\mu \mathrm{A}$ |
|  |  | AV2 $=$ HIZ $=5 \mathrm{~V}$ (300k internal pull-downs) | -2 | 0 | 2 | $\mu \mathrm{A}$ |
| AC GENERAL |  |  |  |  |  |  |
| PSRR | Power Supply Rejection Ratio | $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V}, \mathrm{f}=10 \mathrm{kHz} \text { to } 10 \mathrm{MHz}, \mathrm{~V}+=5 \mathrm{~V}_{\mathrm{DC}}$ $+100 \mathrm{mV} \mathrm{~V}_{\text {P-P }} \text { sine wave }$ |  | 55 |  | dB |
| $\mathrm{X}_{\text {TALK }}$ | Channel to Channel Crosstalk (ROUT/BOUT to Green Input) | $f=10 \mathrm{MHz}, \mathrm{V}_{\text {IN }}=0.7 \mathrm{~V}_{\text {P-P }} ;(\mathrm{GAIN}=1)$ |  | 75 |  | dB |
|  |  | $f=10 \mathrm{MHz}, \mathrm{V}_{\mathrm{IN}}=0.7 \mathrm{~V}_{\text {P-P }} ;(\mathrm{GAIN}=2)$ |  | 70 |  | dB |

Electrical Specifications
$\mathrm{V}+=+5 \mathrm{~V}, \mathrm{GND}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{AV} 2=\mathrm{HIZ}=0.8 \mathrm{~V}$,
unless otherwise specified. (Continued)

| PARAMETER | DESCRIPTION | CONDITIONS | $\begin{gathered} \text { MIN } \\ \text { (Note 2) } \end{gathered}$ | TYP | $\begin{array}{\|c} \text { MAX } \\ \text { (Note 2) } \end{array}$ | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Off - ISO | Off-State Isolation (any de-selected output to driven input) | $\mathrm{f}=10 \mathrm{MHz}$, Ch-Ch Off Isolation $\mathrm{V}_{\mathrm{IN}}=0.7 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ;(\mathrm{GAIN}=1)$ |  | 90 |  | dB |
|  |  | $\mathrm{f}=10 \mathrm{MHz}$, Ch-Ch Off Isolation $\mathrm{V}_{\mathrm{IN}}=0.7 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ;(\mathrm{GAIN}=2)$ |  | 90 |  | dB |
| dG | Differential Gain Error | $\mathrm{R}_{\mathrm{L}}=150$ |  | 0.0013 |  | \% |
| dP | Differential Phase Error | $\mathrm{R}_{\mathrm{L}}=150$ |  | 0.035 |  | - |
| BW | Small Signal -3dB Bandwidth | $\begin{aligned} & \mathrm{V}_{\mathrm{OUT}}=0.1 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=1) \end{aligned}$ |  | 250 |  | MHz |
|  |  | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=0.2 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=2) \end{aligned}$ |  | 210 |  | MHz |
|  | Large Signal -3dB Bandwidth | $\begin{aligned} & \mathrm{V}_{\mathrm{OUT}}=0.7 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=1) \end{aligned}$ |  | 240 |  | MHz |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{OUT}}=1.4 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=2) \end{aligned}$ |  | 200 |  | MHz |
| BW_0.1 | 0.1dB Bandwidth | $\begin{aligned} & \mathrm{V}_{\mathrm{OUT}}=1.4 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=1) \end{aligned}$ |  | 40 |  | MHz |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{OUT}}=1.4 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF} \\ & (\mathrm{GAIN}=2) \end{aligned}$ |  | 33 |  | MHz |
| SR+ | Positive Slew Rate | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=0.5 \mathrm{~V} \text { to } 2.5 \mathrm{~V}, \text { time }=20 \% \text { to } 80 \%, \\ & \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{AV} 2=0.8 \mathrm{~V}, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{GAIN}=1 \end{aligned}$ |  | 480 |  | V/us |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=0.5 \mathrm{~V} \text { to } 1.5 \mathrm{~V}, \text { time }=20 \% \text { to } 80 \%, \\ & \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{GAIN}=2 \end{aligned}$ |  | 980 |  | V/us |
| SR- | Negative Slew Rate | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=2.5 \mathrm{~V} \text { to } 0.5 \mathrm{~V}, \text { time }=80 \% \text { to } 20 \%, \\ & \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{AV} 2=0.8 \mathrm{~V}, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{GAIN}=1 \end{aligned}$ |  | 300 |  | V/us |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=1.5 \mathrm{~V} \text { to } 0.5 \mathrm{~V}, \text { time }=80 \% \text { to } 20 \%, \\ & \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{GAIN}=2 \end{aligned}$ |  | 568 |  | V/us |

## TRANSIENT RESPONSE

| $\mathrm{t}_{\mathrm{R}}$ | Rise Time $10 \%$ to $90 \%$ | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=1 \mathrm{~V}_{\text {P-P }} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \text { AV2 }=0.8 \mathrm{~V}, \mathrm{GAIN}=1 \end{aligned}$ | 1.72 | ns |
| :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=1 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \text { AV2 }=2.0 \mathrm{~V}, \mathrm{GAIN}=2 \end{aligned}$ | 1 | ns |
|  |  | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=2 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{GAIN}=2 \end{aligned}$ | 1.88 | ns |
| ${ }^{\text {t }}$ | Fall Time $90 \%$ to $10 \%$ | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=1 \mathrm{~V}_{\text {P-P }} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \text { AV2 }=0.8 \mathrm{~V}, \mathrm{GAIN}=1 \end{aligned}$ | 2.7 | ns |
|  |  | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=1 \mathrm{~V}_{\mathrm{P}-\mathrm{P}} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \text { AV2 }=2.0 \mathrm{~V}, \mathrm{GAIN}=2 \end{aligned}$ | 2.2 |  |
|  |  | $\begin{aligned} & \mathrm{V}_{\text {OUT }}=2 \mathrm{~V}_{\mathrm{P}-\mathrm{P} ;} \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \\ & \mathrm{AV} 2=2.0 \mathrm{~V}, \mathrm{GAIN}=2 \end{aligned}$ | 2.7 | ns |
| ts 1\% | Settling Time to $1 \%$ | $V_{O U T}=1 V_{P-P} ; R_{L}=150 \Omega, C_{L}=2.1 \mathrm{pF}$, GAIN $=1$, time from $90 \%$ crossing to $1 \%$ of final value | 3 | ns |
|  |  | $\mathrm{V}_{\text {OUT }}=1 \mathrm{~V}_{\text {P-P }} ; \mathrm{R}_{\mathrm{L}}=150 \Omega, \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}$, GAIN $=2$, time from $90 \%$ crossing to $1 \%$ of final value | 5 | ns |
| SWITCHING CHARACTERISTICS |  |  |  |  |
| $\mathrm{V}_{\text {GLITCH }}$ | HIZ High to Low Switching Glitch | $\mathrm{V}_{\mathrm{IN}}=1 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega ; \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{AV} 2=0.8 \mathrm{~V}$ | 400 | $m V_{P-P}$ |
|  |  | $\mathrm{V}_{\mathrm{IN}}=1 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega ; \mathrm{C}_{\mathrm{L}}=2.1 \mathrm{pF}, \mathrm{AV} 2=2.0 \mathrm{~V}$ | 300 | $m V_{P-P}$ |

Electrical Specifications $\quad \mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{GND}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{AV} 2=\mathrm{HIZ}=0.8 \mathrm{~V}$, unless otherwise specified. (Continued)

| PARAMETER | DESCRIPTION | CONDITIONS | $\begin{gathered} \text { MIN } \\ \text { (Note 2) } \end{gathered}$ | TYP | $\begin{gathered} \text { MAX } \\ \text { (Note 2) } \end{gathered}$ | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tsw-L-H | Channel Switching Delay Time Low to High | 1.2 V logic threshold to $10 \%$ movement of analog output |  | 3 |  | ns |
| tsw-H-L | Channel Switching Delay Time High to Low | 1.2 V logic threshold to $10 \%$ movement of analog output |  | 5 |  | ns |
| $t_{\text {thIZ-L-H }}$ | HIZ Switching Delay Time Low to High | 1.2 V logic threshold to $10 \%$ movement of analog output |  | 30 |  | ns |
| thiz-H-L | HIZ Switching Delay Time High to Low | 1.2 V logic threshold to $10 \%$ movement of analog output |  | 220 |  | ns |
| tpd | Propagation Delay | $10 \%$ input to $10 \%$ output, $\mathrm{V}_{\text {IN }}=100 \mathrm{mV} \mathrm{V}_{\text {P-P }}$ |  | 5 |  | ns |
|  |  | $10 \%$ input to $10 \%$ output, $\mathrm{V}_{\text {IN }}=700 \mathrm{mV} \mathrm{V}_{\text {P-P }}$ |  | 2 |  | ns |

## Settling Time Diagram



## Typical Application Diagram



Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified.


FIGURE 1. SMALL SIGNAL GAIN vs FREQUENCY vs $C_{L}$ INTO $150 \Omega$ LOAD, GAIN = 1


FIGURE 3. SMALL SIGNAL GAIN vs FREQUENCY vs $C_{L}$ INTO $150 \Omega$ LOAD, GAIN = 2


FIGURE 5. SMALL SIGNAL GAIN FLATNESS, GAIN = 1


FIGURE 2. LARGE SIGNAL GAIN vs FREQUENCY vs $C_{L}$ INTO $150 \Omega$ LOAD, GAIN = 1


FIGURE 4. LARGE SIGNAL GAIN vs FREQUENCY vs $C_{L}$ INTO $150 \Omega$ LOAD, GAIN = 2


FIGURE 6. LARGE SIGNAL GAIN FLATNESS, GAIN = 1

Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified. (Continued)


FIGURE 7. SMALL SIGNAL GAIN FLATNESS, GAIN = 2


FIGURE 9. SUPPLY CURRENT vs SUPPLY VOLTAGE


FIGURE 11. ZOUT vs FREQUENCY - ENABLED


FIGURE 8. LARGE SIGNAL GAIN FLATNESS, GAIN = 2


FIGURE 10. DISABLED SUPPLY CURRENT vs SUPPLY VOLTAGE


FIGURE 12. ZOUT vs FREQUENCY - DISABLED

Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified. (Continued)


FIGURE 13. $Z_{\text {IN }}$ vs FREQUENCY


FIGURE 15. CROSSTALK


FIGURE 17. DISABLED ISOLATION


FIGURE 14. PSRR vs FREQUENCY


FIGURE 16. OFF ISOLATION


FIGURE 18. OUTPUT REFERRED NOISE vs FREQUENCY

Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified. (Continued)


FIGURE 19. DIFFERENTIAL GAIN; $f_{0}=3.58 \mathrm{MHz}, R_{L}=150 \Omega$


FIGURE 21. SMALL SIGNAL TRANSIENT RESPONSE; GAIN =1


FIGURE 23. LARGE SIGNAL TRANSIENT RESPONSE; GAIN = 1


FIGURE 20. DIFFERENTIAL PHASE; $\mathrm{fo}=3.58 \mathrm{MHz}, \mathrm{R}_{\mathrm{L}}=150 \Omega$


FIGURE 22. SMALL SIGNAL TRANSIENT RESPONSE; GAIN $=2$


FIGURE 24. LARGE SIGNAL TRANSIENT RESPONSE;
GAIN = 2

Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified. (Continued)


FIGURE 25. HIZ SWITCHING GLITCH, $\mathrm{V}_{\mathrm{IN}}=0, G A I N=1$


FIGURE 27. HIZ TIMING, GAIN = 1


FIGURE 26. HIZ SWITCHING GLITCH, $\mathrm{V}_{\text {IN }}=0$, GAIN $=2$


FIGURE 28. HIZ TIMING, GAIN = 2


FIGURE 29. CHANNEL TO CHANNEL SWITCHING TIME

Typical Performance Curves $\mathrm{V}_{+}=+5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=150 \Omega$ to $\mathrm{GND}, \mathrm{C}_{\mathrm{L}}=0.6 \mathrm{pF}, \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise specified. (Continued)


FIGURE 30. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

Functional Block Diagram (Each Output Channel)



FIGURE 31. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

TABLE 1. CHANNEL SELECT LOGIC TABLE

| S1 | S0 | HIZ | OUTPUT |
| :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | R0, G0, B0 |
| 0 | 1 | 0 | R1, G1, B1 |
| 1 | 0 | 0 | R2, G2, B2 |
| 1 | 1 | 0 | R3, G3, B3 |
| X | X | 1 | High Impedance, <br> Inputs Disconnected |

ISL59452

## Pin Descriptions

| $\begin{aligned} & \text { ISL59452 } \\ & \text { (32 LD QFN) } \end{aligned}$ | PIN NAME | EQUIVALENT CIRCUIT | DESCRIPTION |
| :---: | :---: | :---: | :---: |
| 1 | R1 | Circuit 1 | Channel 1 Red/Pr/Chroma Input |
| 2 | B1 | Circuit 1 | Channel 1 Blue/Pb/Chroma Input |
| 3 | G1 | Circuit 1 | Channel 1 Green/Luma Input |
| $\begin{gathered} 4,6,10,16,17,22 \\ 23,27,32 \end{gathered}$ | GND | Circuit 4 | Ground |
| 5, 19, 20, 28 | V+ | Circuit 4 | Positive Supply. Bypass to GND with $0.01 \mu \mathrm{~F}$ and 1 nF capacitors. |
| 7 | R2 | Circuit 1 | Channel 2 Red/Pr/Chroma Input |
| 8 | B2 | Circuit 1 | Channel 2 Blue/Pb/Chroma Input |
| 9 | G2 | Circuit 1 | Channel 2 Green/Luma Input |
| 11 | R3 | Circuit 1 | Channel 3 Red/Pr/Chroma Input |
| 12 | B3 | Circuit 1 | Channel 3 Blue/Pb/Chroma Input |
| 13 | G3 | Circuit 1 | Channel 3 Green/Luma Input |
| 14 | S1 | Circuit 2 | Channel selection pin MSB (binary logic code). This pin does not have internal pull-up or pull-down resistors |
| 15 | S0 | Circuit 2 | Channel selection pin LSB (binary logic code). This pin does not have internal pull-up or pull-down resistors |
| 18 | GOUT | Circuit 3 | Green/Luma Output |
| 21 | BOUT | Circuit 3 | Blue/Pb/Chroma Output |
| 24 | ROUT | Circuit 3 | Red/Pr/Chroma Output |
| 25 | AV2 | Circuit 2 | Gain Set. Set to logic high for gain of $\mathrm{x} 2(+6 \mathrm{~dB})$, or set to logic low for a gain of $\mathrm{x} 1(0 \mathrm{~dB})$. If left floating, an internal pull-down resitor pulls this pin low ( 300 k pull-down). |
| 26 | HIZ | Circuit 2 | Output disable (active high). Internal pull-down resistor ensures the device will be active with no connection to this pin. A logic high, puts the outputs in a high impedance state. Use this state to control logic when more than one MUX-amp share the same video output line. During high impedance state, there is a $2 \mathrm{k} \Omega$ pull-down present at each output. If left floating, an internal pull-down resistor pulls this pin low (300k pull-down). |
| 29 | R0 | Circuit 1 | Channel 0 Red/Pr/Chroma Input |
| 30 | B0 | Circuit 1 | Channel 0 Blue/Pb/Chroma Input |
| 31 | G0 | Circuit 1 | Channel 0 Green/Luma Input |
| PAD | EP |  | Exposed Pad. Connect to GND |
|  <br> V+ <br> GND |  <br> CIRCUIT 1 | $-V_{+}$ <br> GND <br> ACITIVELY | *NOT ALWAYS PRESENT. REFER TO PIN DESCRIPTION <br> CIRCUIT 3 <br> THERMAL HEAT SINK PAD <br> GND |



FIGURE 32A. TEST CIRCUIT WITH OPTIMAL OUTPUT LOAD


FIGURE 32B. INTER-STAGE APPLICATION CIRCUIT

${ }^{*} \mathrm{C}_{\mathrm{L}}$ Includes PCB trace capacitance
FIGURE 32C. $150 \Omega$ TEST CIRCUIT WITH $50 \Omega$ LOAD

${ }^{*} \mathrm{C}_{\mathrm{L}}$ Includes PCB trace capacitance
FIGURE 32D. BACKLOADED TEST CIRCUIT FOR $150 \Omega$ VIDEO CABLE APPLICATION
FIGURE 32. AC TEST CIRCUITS

## AC Test Circuits

Figure 32A and 32B illustrate the optimum output load for testing AC performance at $150 \Omega$ loads. Figure 32C illustrates how to use the optimal $150 \Omega$ load for a $50 \Omega$ cable. Figure 32D illustrates the optimum output load for $50 \Omega$ and $75 \Omega$ cable-driving.

## Application Information

## General

The ISL59452 triple 4:1 video MUX features +5 V single-supply operation, high bandwidth and TTL/CMOS logic compatible gain select (AV2) of $x 1$ ( 0 dB ) or $\mathrm{x} 2(+6 \mathrm{~dB})$. The ISL59452 also features buffered high impedance analog inputs and excellent AC performance at output loads down to $150 \Omega$ for video cabledriving. The current feedback output amplifiers are stable operating into capacitive loads.

## AC Design Considerations

High speed current-feed amplifiers are sensitive to capacitance at the inverting input and output terminals. Capacitance at the output terminal increases gain peaking and overshoot. The AC response of the ISL59452 is optimized for a total output capacitance of 2.1 pF with a load of $150 \Omega$ (Figure 32A). When PCB trace capacitance and component capacitance exceed $2 p F$, overshoot becomes strongly dependent on the input pulse amplitude and slew rate. Increasing levels of output capacitance reduce stability, resulting in increased overshoot and settling time.

PC board trace length ( $\mathrm{L}_{\mathrm{CRIT}}$ ) should be kept to a minimum in order to minimize output capacitance. At 500 MHz , trace lengths approaching 1 " begin exhibiting transmission line behavior and may cause excessive ringing if controlled impedance traces are not used. Figure 32B shows the optimum inter-stage circuit when the total output trace length is less than the critical length of the highest signal frequency.

As a general rule of thumb the trace lengths should be less than one-tenth of the wavelength of the highest frequency component in the signal. Equation 1 shows an approximate way to calculate $\mathrm{L}_{\text {CRIT }}$ in meters.
$\mathrm{L}_{\text {CRIT }} \leq \frac{\mathrm{C}}{10 \times \mathrm{f}_{\mathrm{MAX}} \times \sqrt{\varepsilon_{\mathrm{R}}}}$
$\mathrm{c}=$ speed of light $\left(3 \times 10^{\wedge} 8 \mathrm{~m} / \mathrm{s}\right)$
$f_{M A X}=$ maximum frequency component
$\varepsilon_{R}=$ relative dielectric of board material (e.g. FR4 $=4.2$ )
For applications where inter-stage distances are long but pulse response is not critical, capacitor $\mathrm{C}_{S}$ can be added to low values of $R_{S}$ to form a low-pass filter to dampen pulse overshoot. This approach avoids the need for the large gain correction required by the -6 dB attenuation of the back-loaded controlled impedance interconnect. Load resistor $R_{L}$ is still required but can be $500 \Omega$ or greater, resulting in a much smaller attenuation factor.

For applications where pulse response is critical and where inter-stage distances exceed LCRIT, the circuit shown in $^{\text {n }}$ Figure 32C is recommended. Resistor RS constrains the capacitance seen by the amplifier output to the trace capacitance betweeen the output pin and the resistor. Therefore, $R_{S}$ should be placed as close to the ISL59452 output pin as possible. For inter-stage distances much greater than $L_{\text {CRIT, }}$ the back-loaded circuit shown in Figure 32D should be used with controlled impedance PCB lines, with $R_{S}$ and $R_{L}$ equal to the controlled impedance.

## Control Signals

S0, S1, AV2, and HIZ are binary coded, TTL/CMOS compatible control inputs. The S0, S1 pins select the inputs. All three output amplifiers are switched simultaneously from their respective inputs. When HIZ is pulled high, it puts the outputs in a high-impedance state. For control signal rise and
fall times less than 10 ns , the use of termination resistors on the control lines close to the part may be necessary to prevent reflections and to minimize transients coupled to the output. See Table 1 for the S1, S0 selection states.

## HIZ State

An internal pull-down resistor ensures the device will be active with no connection to the HIZ pin. The HIZ state is established within approximately 30ns (Figure 26) by placing a logic high ( $>2 \mathrm{~V}$ ) on the HIZ pin. If the HIZ state is selected, the output impedance is $\sim 2000 \Omega$ (Figure 12). The supply current during this state is reduced to $\sim 3 \mathrm{~mA}$.

## Limiting the Output Current

No output short circuit current limit exists on these parts. All applications need to limit the output current to less than 50 mA . Adequate thermal heat sinking of the parts is also required.

## PC Board Layout

The AC performance of this circuit depends greatly on the care taken in designing the PC board. The following are recommendations to achieve optimum high frequency performance from your PC board.

- Use low inductance components, such as chip resistors and chip capacitors whenever possible.
- Minimize signal trace lengths. Trace inductance and capacitance can easily limit circuit performance. Avoid sharp corners; use rounded corners when possible. Vias in the signal lines add inductance at high frequency and should be avoided. PCB traces longer than 1" begin to exhibit transmission line characteristics with signal rise/fall times of 1 ns or less. To maintain frequency performance with longer traces, use striplines.
- Match channel-to-channel analog I/O trace lengths and layout symmetry. This will minimize propagation delay mismatches.
- All signal I/O lines should be routed over continuous ground planes (i.e. no split planes or PCB gaps under these lines).
- Put the proper termination resistors in their optimum location as close to the device as possible.
- When testing, use good quality connectors and cables, matching cable types and keeping cable lengths to a minimum.
- Decouple well, using aminimum of 2 power supply decoupling capacitors ( $1000 \mathrm{pF}, 0.01 \mu \mathrm{~F}$ ), placed as close to the devices as possible. Avoid vias between the
capacitor and the device because vias adds unwanted inductance. Larger caps can be farther away. When vias are required in a layout, they should be routed as far away from the device as possible.


## The QFN Package Requires Additional PCB Layout Rules for the Thermal Pad

The thermal pad is electrically connected to GND through the high resistance IC substrate. Its primary function is to provide heat sinking for the IC.

Maximum AC performance is achieved if the thermal pad is attached to a dedicated decoupled layer in a multi-layered PC board. In cases where a dedicated layer is not possible, AC performance may be reduced at upper frequencies.

- The thermal pad requirements are proportional to power dissipation and ambient temperature. A dedicated layer (oftern the ground plane) eliminates the need for individual thermal pad area. When a dedicated layer is not possible, a 1 " $x 1$ " pad area is sufficient for an ISL59452 dissipating 0.5 W at $+50^{\circ} \mathrm{C}$ ambient. Pad area requirements should be evaluated according to the maximum ambient temperature, the maximum supply current (including worst case signals + loads), and the thermal characteristic of the PCB.

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## Package Outline Drawing

## L32.5x5

32 LEAD QUAD FLAT NO-LEAD PLASTIC PACKAGE Rev 2, 02/07


TOP VIEW


TYPICAL RECOMMENDED LAND PATTERN


BOTTOM VIEW


NOTES:

1. Dimensions are in millimeters.

Dimensions in ( ) for Reference Only.
2. Dimensioning and tolerancing conform to AMSE Y14.5m-1994.
3. Unless otherwise specified, tolerance : Decimal $\pm 0.05$
4. Dimension $b$ applies to the metallized terminal and is measured between 0.15 mm and 0.30 mm from the terminal tip.
5. Tiebar shown (if present) is a non-functional feature.
6. The configuration of the pin \#1 identifier is optional, but must be located within the zone indicated. The pin \#1 indentifier may be either a mold or mark feature.


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