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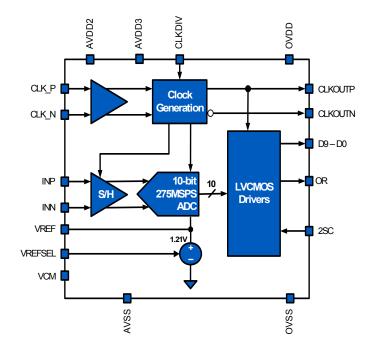


# KAD2710C

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### 10-Bit, 275/210/170/105MSPS A/D Converter

The KAD2710C is the industry's lowest power, 10-bit, 275MSPS, high performance Analog-to-Digital converter. It is designed with Intersil's proprietary FemtoCharge<sup>™</sup> technology on a standard CMOS process. The KAD2710C offers high dynamic performance (55.6dBFS SNR @  $f_{IN} = 138MHz$ ) while consuming less than 265mW. Features include an over-range indicator and a selectable divide-by-2 input clock divider. The KAD2710C is one member of a pin-compatible family offering 8 and 10-bit ADCs with sample rates from 105 to 350MSPS and LVDS-compatible or LVCMOS outputs (Table 1). This family of products is available in 68-pin RoHS-compliant QFN packages with exposed paddle. Performance is specified over the full industrial temperature range (-40°C to +85°C).



### Features

- On-Chip Reference
- · Internal Sample and Hold
- 1.5V<sub>P-P</sub> Differential Input Voltage
- 600MHz Analog Input Bandwidth
- Two's Complement or Binary Output
- Over-Range Indicator
- Selectable ÷2 Clock Input
- LVCMOS Outputs
- Pb-Free (RoHS Compliant)

### **Applications**

- High-Performance Data Acquisition
- Portable Oscilloscope
- Medical Imaging
- Cable Head Ends
- Power-Amplifier Linearization
- · Radar and Satellite Antenna Array Processing
- Broadband Communications
- · Point-to-Point Microwave Systems
- · Communications Test Equipment

## Key Specs

- SNR = 55.6dBFS at f<sub>S</sub> = 275MSPS, f<sub>IN</sub> = 138MHz
- SFDR = 68.5dBc at f<sub>S</sub> = 275MSPS, f<sub>IN</sub> = 138MHz
- Power consumption <265mW at f<sub>S</sub> = 275MSPS

## Pin-Compatible Family

#### TABLE 1. PIN-COMPATIBLE PRODUCTS

RESOLUTION, SPEED	LVDS OUTPUTS	LVCMOS OUTPUTS
8 Bits 350MSPS	KAD2708L-35	
8 Bits 275MSPS	KAD2708L-27	KAD2708C-27
8 Bits 210MSPS	KAD2708L-21	KAD2708C-21
8 Bits 170MSPS	KAD2708L-17	KAD2708C-17
8 Bits 105MSPS	KAD2708L-10	KAD2708C-10
10 Bits 275MSPS	KAD2710L-27	KAD2710C-27
10 Bits 210MSPS	KAD2710L-21	KAD2710C-21
10 Bits 170MSPS	KAD2710L-17	KAD2710C-17
10 Bits 105MSPS	KAD2710L-10	KAD2710C-10

FN6814.0

## **Ordering Information**

PART NUMBER (Note)	SPEED (MSPS)	TEMP. RANGE (°C)	PACKAGE (Pb-Free)	PKG. DWG. #
KAD2710C-27Q68	275	-40 to +85	68 Ld QFN	L68.10x10B
KAD2710C-21Q68	210	-40 to +85	68 Ld QFN	L68.10x10B
KAD2710C-17Q68	170	-40 to +85	68 Ld QFN	L68.10x10B
KAD2710C-10Q68	105	-40 to +85	68 Ld QFN	L68.10x10B

NOTE: These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and 100% matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

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### Absolute Maximum Ratings

### **Thermal Information**

Operating Temperature	40°C to +85°C
Storage Temperature	65°C to +150°C
Junction Temperature	+150°C

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

**Electrical Specifications** All specifications apply under the following conditions unless otherwise noted: AVDD2 = 1.8V, AVDD3 = 3.3V, OVDD = 1.8V, T<sub>A</sub> = -40°C to +85°C (typical specifications at +25°C), f<sub>SAMPLE</sub> = 350MSPS, 270MSPS, 210MSPS, 170MSPS and 105MSPS, f<sub>IN</sub> = Nyquist at -0.5dBFS.

			KA	D2710	C-27	KA	D2710	C-21	KAD2710C-17			KAD2710C-10			
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
DC SPECIFICATIONS	I.			1	1		1	1		1	1		1	1	1
Analog Input															
Full-Scale Analog Input Range	V <sub>FS</sub>		1.4	1.5	1.6	1.4	1.5	1.6	1.4	1.5	1.6	1.4	1.5	1.6	V <sub>P-P</sub>
Full Scale Range Temp. Drift	Avtc	Full Temp		230			210			198			178		ppm/°C
Common-Mode Output Voltage	V <sub>CM</sub>			860			860			860			860		mV
Power Requirements															
1.8V Analog Supply Voltage	AVDD2		1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	V
3.3V Analog Supply Voltage	AVDD3		3.15	3.3	3.45	3.15	3.3	3.45	3.15	3.3	3.45	3.15	3.3	3.45	V
1.8V Digital Supply Voltage	OVDD		1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	1.7	1.8	1.9	V
1.8V Analog Supply Current	I <sub>AVDD2</sub>			44	51		38	42		35	39		29	33	mA
3.3V Analog Supply Current	I <sub>AVDD3</sub>			41	45		33	37		28	32		21	24	mA
1.8V Digital Supply Current	IOVDD			26	30		25	28		24	27		23	26	mA
Power Dissipation	PD			261	294		222	248		199	224		163	185	mW
AC SPECIFICATIONS															
Maximum Conversion Rate	f <sub>S</sub> MAX		275			210			170			105			MSPS
Minimum Conversion Rate	f <sub>S</sub> MIN				50			50			50			50	MSPS
Differential Nonlinearity	DNL		-1.0	±0.8	1.5	-1.0	±0.8	1.5	-1.0	±0.8	1.5	-1.0	±0.8	1.5	LSB
Integral Nonlinearity	INL		-2.5	±1.0	2.0	-2.5	±1.0	1.5	-2.5	±1.0	1.5	-2.5	±1.0	1.5	LSB
Signal-to-Noise Ratio	SNR	f <sub>IN</sub> = 10MHz		55.7			56.4			56.6			56.6		dBFS
		f <sub>IN</sub> = Nyquist	53.5	55.6		53.5	56.2		53.5	56.5		53.5	56.5		dBFS
		f <sub>IN</sub> = 430MHz		55.2			54.8			54.6			54.5		dBFS
Signal-to-Noise and	SINAD	f <sub>IN</sub> = 10MHz		55.3			56.1			56.3			56.3		dBFS
Distortion		f <sub>IN</sub> = Nyquist	52.5	55.2		52.5	56.0		52.5	56.2		52.5	56.2		dBFS
		f <sub>IN</sub> = 430MHz		54.4			53.7			53.4			53.2		dBFS

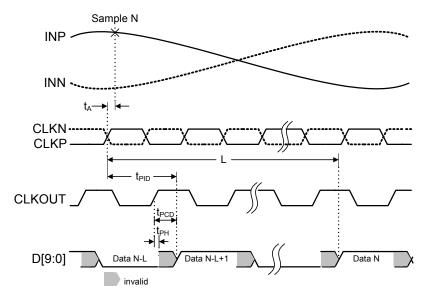
# **Electrical Specifications** All specifications apply under the following conditions unless otherwise noted: AVDD2 = 1.8V, AVDD3 = 3.3V, OVDD = 1.8V, T<sub>A</sub> = -40°C to +85°C (typical specifications at +25°C), f<sub>SAMPLE</sub> = 350MSPS, 270MSPS, 210MSPS, 170MSPS and 105MSPS, f<sub>IN</sub> = Nyquist at -0.5dBFS. **(Continued)**

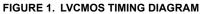
		KA	D2710	C-27	KA	D2710	C-21	KA	D2710	C-17	KA	D2710	C-10	
SYMBOL	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
ENOB	f <sub>IN</sub> = 10MHz		8.9			9.0			9.1			9.1		Bits
	f <sub>IN</sub> = Nyquist	8.4	8.9		8.4	9.0		8.4	9.0		8.4	9.0		Bits
	f <sub>IN</sub> = 430MHz		8.7			8.6			8.6			8.5		Bits
SFDR	f <sub>IN</sub> = 10MHz		68.5			70			71			71		dBc
	f <sub>IN</sub> = Nyquist	62	68.5		62	71.1		62	71		62	72		dBc
	f <sub>IN</sub> = 430MHz		63.8			62.6			60.1			60.9		dBc
2TSFDR	f <sub>IN</sub> = 133MHz, 135MHz		68			70			70			71		dBc
WER			10 <sup>-12</sup>			10 <sup>-12</sup>			10 <sup>-12</sup>			10 <sup>-12</sup>		
FPBW			600			600			600			600		MHz
	ENOB SFDR 2TSFDR WER	$\frac{\text{ENOB}}{\text{ENOB}}  \begin{array}{c} f_{\text{IN}} = 10\text{MHz} \\ \hline f_{\text{IN}} = \text{Nyquist} \\ \hline f_{\text{IN}} = 430\text{MHz} \\ \end{array}$ $\frac{\text{SFDR}}{\text{F_{IN}}}  \begin{array}{c} f_{\text{IN}} = 10\text{MHz} \\ \hline f_{\text{IN}} = 10\text{MHz} \\ \hline f_{\text{IN}} = \text{Nyquist} \\ \hline f_{\text{IN}} = 430\text{MHz} \\ \end{array}$ $2\text{TSFDR}  \begin{array}{c} f_{\text{IN}} = 133\text{MHz}, 135\text{MHz} \\ \end{array}$ $\text{WER} \qquad \begin{array}{c} \end{array}$	$\begin{tabular}{ c c c c } \hline SYMBOL & CONDITIONS & MIN \\ \hline SFOR & f_{IN} = 10MHz & & & \\ \hline f_{IN} = Nyquist & 8.4 & & \\ \hline f_{IN} = 430MHz & & & \\ \hline SFDR & f_{IN} = 10MHz & & & \\ \hline f_{IN} = Nyquist & 62 & & \\ \hline f_{IN} = 430MHz & & & \\ \hline 2TSFDR & f_{IN} = 133MHz, 135MHz & & \\ \hline WER & & & & \\ \hline \end{array}$	$\begin{tabular}{ c c c c c } \hline SYMBOL & CONDITIONS & MIN & TYP \\ \hline SPOND & f_{IN} = 10MHz & 8.9 \\ \hline f_{IN} = Nyquist & 8.4 & 8.9 \\ \hline f_{IN} = 430MHz & 8.7 \\ \hline SFDR & f_{IN} = 10MHz & 68.5 \\ \hline f_{IN} = Nyquist & 62 & 68.5 \\ \hline f_{IN} = 430MHz & 63.8 \\ \hline 2TSFDR & f_{IN} = 133MHz, 135MHz & 68 \\ \hline WER & 10^{-12} \\ \hline \end{tabular}$	$\frac{\text{ENOB}}{\text{FIN}} = 10 \text{MHz} \qquad \begin{array}{c} \text{B.9} \\ \hline \text{FIN} = 10 \text{MHz} \\ \hline \text{FIN} = 10 \text{MHz} \\ \hline \text{FIN} = 430 \text{MHz} \\ \end{array} \qquad \begin{array}{c} \text{B.4} \\ \text{B.9} \\ \hline \text{FIN} = 430 \text{MHz} \\ \hline \text{FIN} = 10 \text{MHz} \\ \hline \text{FIN} = 10$	$\begin{tabular}{ c c c c c } \hline SYMBOL & CONDITIONS & MIN & TYP & MAX & MIN \\ \hline SFOR & f_{IN} = 10MHz & 8.4 & 8.9 & 8.4 \\ \hline f_{IN} = Nyquist & 8.4 & 8.9 & 8.4 \\ \hline f_{IN} = 430MHz & 8.7 & - & - \\ \hline SFDR & f_{IN} = 10MHz & 68.5 & - & - \\ \hline f_{IN} = Nyquist & 62 & 68.5 & 62 \\ \hline f_{IN} = 430MHz & 63.8 & - & - \\ \hline f_{IN} = 430MHz & 68.8 & - & - \\ \hline SFDR & f_{IN} = 133MHz, 135MHz & 68 & - & - \\ \hline WER & - & - & - & - & - \\ \hline \end{array}$	$\begin{tabular}{ c c c c c c } \hline SYMBOL & CONDITIONS & MIN & TYP & MAX & MIN & TYP \\ \hline SYMBOL & f_{IN} = 10MHz & 8.9 & 9.0 \\ \hline f_{IN} = Nyquist & 8.4 & 8.9 & 8.4 & 9.0 \\ \hline f_{IN} = 430MHz & 8.7 & 8.6 \\ \hline SFDR & f_{IN} = 10MHz & 68.5 & 70 \\ \hline f_{IN} = 10MHz & 62 & 68.5 & 62 & 71.1 \\ \hline f_{IN} = 430MHz & 63.8 & 62.6 \\ \hline 2TSFDR & f_{IN} = 133MHz, 135MHz & 68 & 70 \\ \hline WER & 10^{-12} & 10^{-12} \\ \hline \end{array}$	$\begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c c c } \hline \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	$\begin{tabular}{ c c c c c c c c } \hline NIR & VI & $	$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	SYMBOL         CONDITIONS         MIN         TYP         MAX         MIN         TYP           ENOB $f_{IN}$ = 100HHz         8.4         8.9         8.6         70         71         71         71         71         71         62         72         72         71         61.9         72         72         71         62.9         72         71	SYMBOL         CONDITIONS         MIN         TYP         MAX         MIN

### **Digital Specifications**

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
INPUTS						
Input Voltage High (VREFSEL)	VIH		0.8*AVDD3			V
Input Voltage Low (VREFSEL)	VIL				0.2*AVDD3	V
Input Current High (VREFSEL)	Ι <sub>ΙΗ</sub>	V <sub>IN</sub> = AVDD3		0	10	μA
Input Current Low (VREFSEL)	IIL	V <sub>IN</sub> = AVSS	-90	-65	-30	μA
Input Voltage High (CLKDIV)	V <sub>IH</sub>		0.8*AVDD3			V
Input Voltage Low (CLKDIV)	VIL				0.2*AVDD3	V
Input Current High (CLKDIV)	IIH	V <sub>IN</sub> = AVDD3	100	65	10	μA
Input Current Low (CLKDIV)	۱ <sub>IL</sub>	V <sub>IN</sub> = AVSS		0	-10	μA
Input Voltage High (RST,2SC)	V <sub>IH</sub>		0.8*OVDD2			V
Input Voltage Low (RST,2SC)	VIL				0.2*OVDD2	V
Input Current High (RST,2SC)	lιΗ	VIN = OVDD		0	10	μA
Input Current Low (RST,2SC)	IIL	VIN = OVSS	-50	-30	-5	μA
Input Capacitance	C <sub>DI</sub>			3		pF
CLKP, CLKN P-P Differential Input Voltage	V <sub>CDI</sub>		0.5		3.6	V <sub>P-P</sub>
CLKP, CLKN Differential Input Resistance	R <sub>CDI</sub>			10		MΩ
CLKP, CLKN Common-Mode Input Voltage	V <sub>CCI</sub>			0.9		V
LVCMOS OUTPUTS		I	1 1			
Output Voltage High	V <sub>OH</sub>			1.8		V
Output Voltage Low	V <sub>OL</sub>			0		V
Output Rise Time	t <sub>R</sub>			1.8		ns
Output Fall Time	t <sub>F</sub>			1.4		ns

# **Timing Diagram**





## **Timing Specifications**

PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS
Aperture Delay	t <sub>A</sub>		1.7		ns
RMS Aperture Jitter	j <sub>A</sub>		200		fs
Input Clock to Data Propagation Delay	t <sub>PID</sub>	3.5	5.0	6.5	ns
Data Hold Time	t <sub>PH</sub>	-300			ps
Output Clock to Data Propagation Delay	t <sub>PCD</sub>		2.8	3.7	ns
Latency (Pipeline Delay)	L		28		cycles
Overvoltage Recovery	tovr		1		cycle

### **Thermal Impedance**

PARAMETER	SYMBOL	TYP	UNIT
Junction to Paddle (Note 1)	$\theta_{JP}$	30	°C/W

NOTE:

1. Paddle soldered to ground plane.



Electrostatic charge accumulates on humans, tools and equipment and may discharge through any metallic package contacts (pins, balls, exposed paddle, etc.) of an integrated circuit. Industry-standard protection techniques have been utilized in the design of this product. However, reasonable care must be taken in the storage and handling of ESD sensitive products. Contact Intersil for the specific ESD sensitivity rating of this product.

# **Pin Descriptions**

PIN NUMBER	NAME	FUNCTION
1, 14, 18, 20	AVDD2	1.8V Analog Supply
2, 7, 10, 19, 21, 24	AVSS	Analog Supply Return
3	VREF	Reference Voltage Out/In
4	VREFSEL	Reference Voltage Select (0:Int 1:Ext)
5	VCM	Common-Mode Voltage Output
6, 15, 16, 25	AVDD3	3.3V Analog Supply
8, 9	INP, INN	Analog Input Positive, Negative
11-13, 29-33, 35, 37, 39, 42, 46, 48, 50, 52, 54, 56, 58, 62, 63, 67	DNC	Do Not Connect
17	CLKDIV	Clock Divide by Two (Active Low)
22, 23	CLKN, CLKP	Clock Input Complement, True
26, 45, 61	OVSS	Output Supply Return
27, 41, 44, 60	OVDD2	1.8V LVCMOS Supply
28	RST	Power On Reset (Active Low)
34	D0	LVCMOS Bit 0 (LSB) Output
36	D1	LVCMOS Bit 1 Output
38	D2	LVCMOS Bit 2 Output
40	D3	LVCMOS Bit 3 Output
43	CLKOUT	LVCMOS Clock Output
47	D4	LVCMOS Bit 4 Output
49	D5	LVCMOS Bit 5 Output
51	D6	LVCMOS Bit 6 Output
53	D7	LVCMOS Bit 7 Output
55	D8	LVCMOS Bit 8 Output
57	D9	LVCMOS Bit 9 (MSB) Output
59	OR	Over-Range
64-66		Connect to OVDD2
68	2SC	Two's Complement Select (Active Low)
Exposed Paddle	AVSS	Analog Supply Return



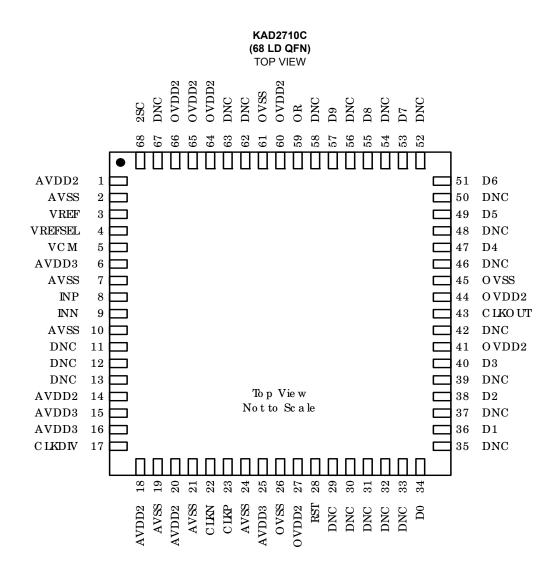
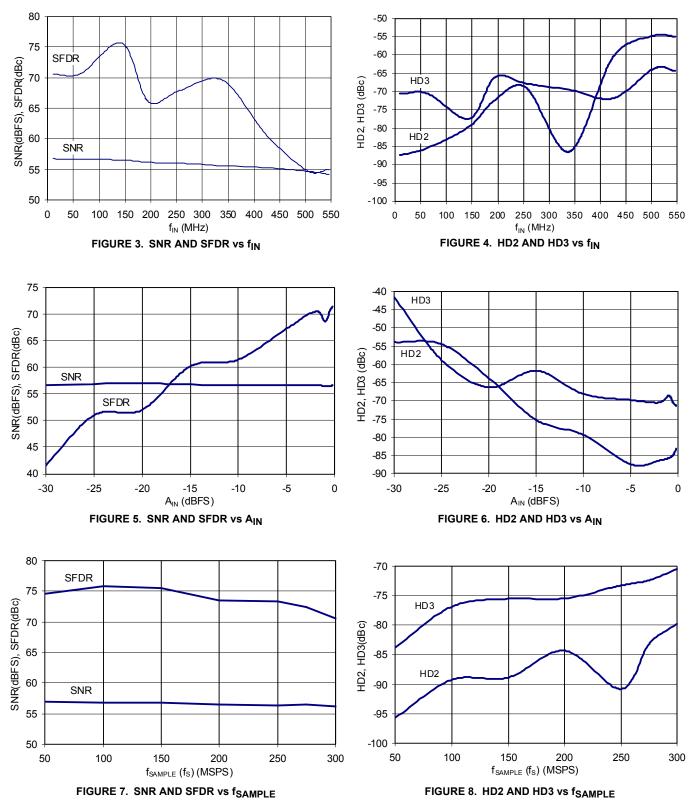
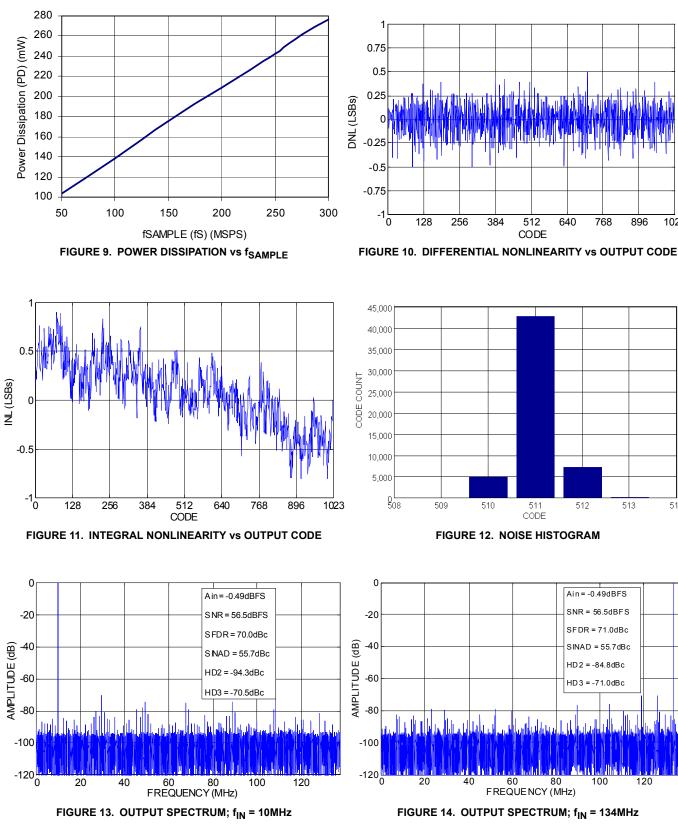
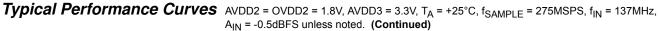


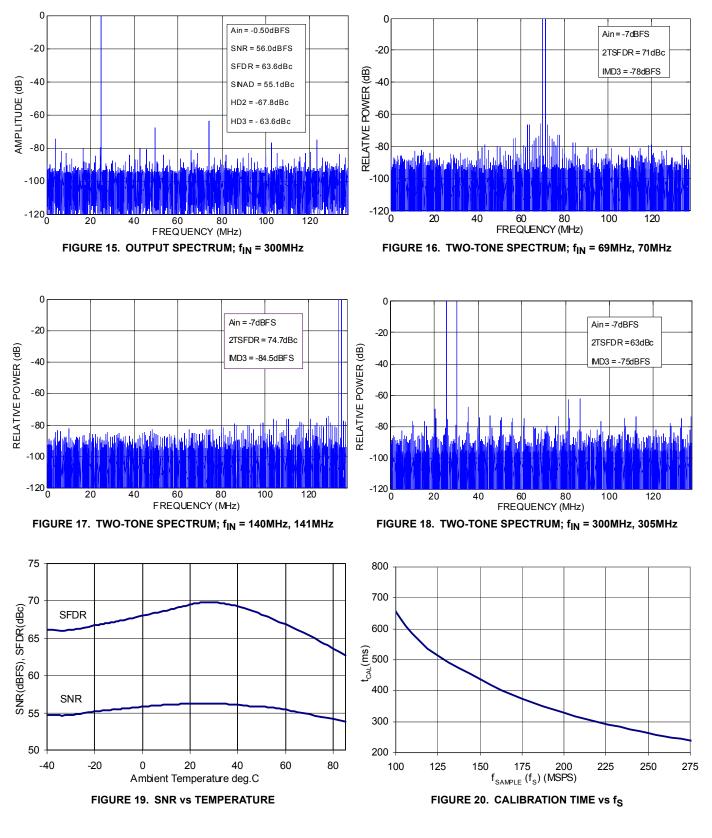
FIGURE 2. PIN CONFIGURATION

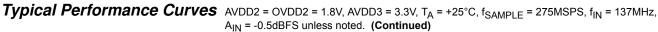


# **Typical Performance Curves** AVDD2 = OVDD2 = 1.8V, AVDD3 = 3.3V, $T_A$ = +25°C, $f_{SAMPLE}$ = 275MSPS, $f_{IN}$ = 137MHz, $A_{IN}$ = -0.5dBFS unless noted.









# Functional Description

The KAD2710 is a ten bit, 275MSPS A/D converter in a pipelined architecture. The input voltage is captured by a sample and hold circuit and converted to a unit of charge. Proprietary charge-domain techniques are used to compare the input to a series of reference charges. These comparisons determine the digital code for each input value. The converter pipeline requires 24 sample clocks to produce a result. Digital error correction is also applied, resulting in a total latency of 28 clock cycles. This is evident to the user as a latency between the start of a conversion and the data being available on the digital outputs.

At power-up, a self-calibration is performed to minimize gain and offset errors. The reset pin (RST) is held low internally at power-up and will remain in that state until the calibration is complete. The clock frequency should remain fixed during this time.

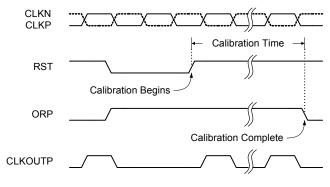
Calibration accuracy is maintained for the sample rate at which it is performed, and therefore should be repeated if the clock frequency is changed by more than 10%. Recalibration can be initiated via the RST pin, or power cycling, at any time.

### Reset

Recalibration of the ADC can be initiated at any time by driving the RST pin low for a minimum of one clock cycle. An open-drain driver is recommended.

The calibration sequence is initiated on the rising edge of RST, as shown in Figure 21. The over-range output (OR) is set high once RST is pulled low, and remains in that state until calibration is complete. The OR output returns to normal operation at that time, so it is important that the analog input be within the converter's full-scale range in order to observe the transition. If the input is in an over-range state the OR pin will stay high and it will not be possible to detect the end of the calibration cycle.

While RST is low, the output clock (CLKOUT) stops toggling and is set low. Normal operation of the output clock resumes at the next input clock edge (CLKP/CLKN) after RST is deasserted. At 275MSPS the nominal calibration time is ~240ms.





### Voltage Reference

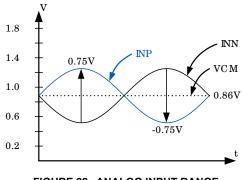
The VREF pin is the reference voltage which sets the fullscale input voltage for the chip. This pin requires a bypass capacitor of 0.1uF at a minimum. The internally generated bandgap reference voltage is provided by an on-chip voltage buffer.buffer can sink or source up to  $50\mu$ A externally.

An external voltage may be applied to this pin to provide a more accurate reference than the internally generated bandgap voltage, or to match the full-scale reference for multiple KAD2710C chips.One option in the latter configuration is to use one KAD2710C's internally generated reference as the external reference voltage for the other chips in the system. Additionally, an externally provided reference can be changed from the nominal value to adjust the full-scale input voltage within a limited range.

To select whether the full-scale reference is internally generated or externally provided, the digital input VREFSEL is set low for internal, or high for external. This pin has internal pull-up.use the internally generated reference VREFSEL can be tied directly to AVSS, and to use an external reference VREFSEL can be left unconnected.

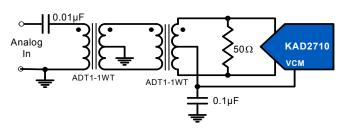
### Analog Input

The ADC core contains a fully differential input (INP/INN) to the sample and hold circuit. The ideal full-scale input voltage is 1.50V, centered at the VCM voltage of 0.86V as shown in Figure 22.





Best performance is obtained when the analog inputs are driven differentially. The common-mode output voltage, VCM, should be used to properly bias the inputs as shown in Figures 23 and 24. An RF transformer will give the best noise and distortion performance for wideband and/or high intermediate frequency (IF) inputs. Two different transformer input schemes are shown in Figures 23 and 24.





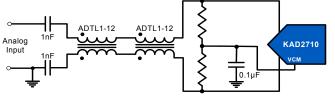


FIGURE 24. TRANSMISSION-LINE TRANSFORMER INPUT FOR HIGH IF APPLICATIONS

A back-to-back transformer scheme is used to improve common-mode rejection, which keeps the common-mode level of the input matched to  $V_{CM}$ . The value of the shunt resistor should be determined based on the desired load impedance.

The sample and hold circuit design uses a switched capacitor input stage, which creates current spikes when the sampling capacitance is reconnected to the input voltage. This creates a disturbance at the input which must settle before the next sampling point. Lower source impedance will result in faster settling and improved performance. Therefore a 1:1 transformer and low shunt resistance are recommended for optimal performance.

A differential amplifier can be used in applications that require dc coupling. In this configuration the amplifier will typically determine the achievable SNR and distortion. A typical differential amplifier circuit is shown in Figure 25.

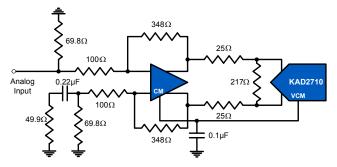


FIGURE 25. DIFFERENTIAL AMPLIFIER INPUT

### **Clock Input**

The sample clock input circuit is a differential pair (see Figure 29). Driving these inputs with a high level (up to  $1.8V_{P-P}$  on each input) sine or square wave will provide the lowest jitter performance.

The recommended drive circuit is shown in Figure 26. The clock can be driven single-ended, but this will reduce the edge rate and may impact SNR performance.

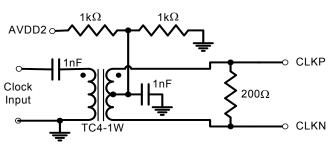


FIGURE 26. RECOMMENDED CLOCK DRIVE

Use of the clock divider is optional. The KAD2710C's ADC requires a clock with 50% duty cycle for optimum performance. If such a clock is not available, one option is to generate twice the desired sampling rate and use the KAD2710C's divide-by-2 setting. This frequency divider uses the rising edge of the clock, so 50% clock duty cycle is assured. Table 2 describes the CLKDIV connection.

TABLE 2. CLKDIV PIN SETTINGS

CLKDIV PIN	DIVIDE RATIO
AVSS	2
AVDD	1

CLKDIV is internally pulled low, so a pull-up resistor or logic driver must be connected for undivided clock.

#### Jitter

In a sampled data system, clock jitter directly impacts the achievable SNR performance. The theoretical relationship between clock jitter ( $t_J$ ) and SNR is shown in Equation 1 and is illustrated in Figure 27.

$$SNR = 20 \log_{10} \left( \frac{1}{2\pi f_{IN} t_J} \right)$$
(EQ. 1)

Where  $t_J$  is the RMS uncertainty in the sampling instant.

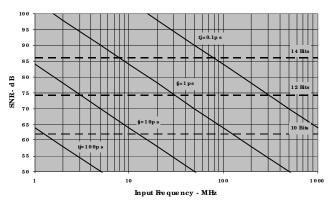
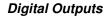


FIGURE 27. SNR vs CLOCK JITTER

This relationship shows the SNR that would be achieved if clock jitter were the only non-ideal factor. In reality, achievable SNR is limited by internal factors such as linearity, aperture jitter and thermal noise. Internal aperture jitter is the uncertainty in the sampling instant shown in Figure 1. The internal aperture jitter combines with the input clock jitter in a root-sum-square fashion, since they are not statistically correlated, and this determines the total jitter in the system. The total jitter, combined with other noise sources, then determines the achievable SNR.

# **Equivalent Circuits**



Data is output on a parallel bus with LVCMOS drivers.

The output format (Binary or Two's Complement) is selected via the 2SC pin as shown in Table 3.

TABLE 3.	2SC PIN	SETTINGS

2SC PIN	MODE
AVSS	Two's Complement
AVDD (or unconnected)	Binary

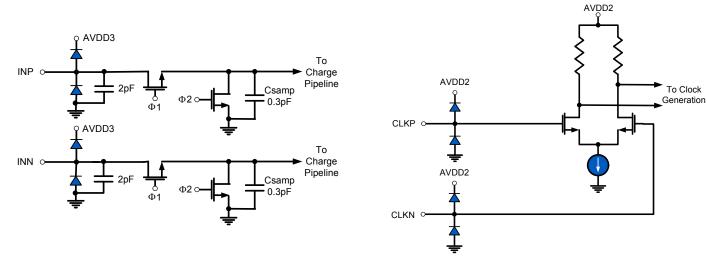


FIGURE 28. ANALOG INPUTS

**FIGURE 29. CLOCK INPUTS** 

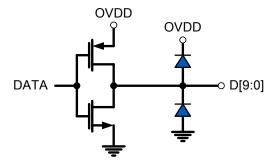


FIGURE 30. LVCMOS OUTPUTS

For additional products, see www.intersil.com/en/products.html

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# Layout Considerations

### Split Ground and Power Planes

Data converters operating at high sampling frequencies require extra care in PC board layout. If analog and digital ground planes are separate, analog supply and ground planes should be laid out under signal and clock inputs and digital planes under outputs and logic pins. Grounds should be joined under the chip.

### **Clock Input Considerations**

Use matched transmission lines to the inputs for the analog input and clock signals. Locate transformers, drivers and terminations as close to the chip as possible.

### Bypass and Filtering

Bulk capacitors should have low equivalent series resistance. Tantalum is recommended. Keep ceramic bypass capacitors very close to device pins. Longer traces will increase inductance, resulting in diminished dynamic performance and accuracy. Make sure that connections to ground are direct, and low impedance.

### LVCMOS Outputs

Output traces and connections must be designed for  $50\Omega$  characteristic impedance. Keep trace lengths equal, and minimize bends where possible. Avoid crossing ground and power-plane breaks with signal traces.

### **Unused Inputs**

The RST and 2SC inputs are internally pulled up, and can be left open-circuit if not used.

CLKDIV is internally pulled low, which divides the input clock by two.

VREFSEL must be held low for internal reference, but can be left open for external reference.

# Definitions

**Analog Input Bandwidth** is the analog input frequency at which the spectral output power at the fundamental frequency (as determined by FFT analysis) is reduced by 3dB from its full-scale low-frequency value. This is also referred to as Full Power Bandwidth.

**Aperture Delay or Sampling Delay** is the time required after the rise of the clock input for the sampling switch to open, at which time the signal is held for conversion.

**Aperture Jitter** is the RMS variation in aperture delay for a set of samples.

**Clock Duty Cycle** is the ratio of the time the clock wave is at logic high to the total time of one clock period.

**Differential Non-Linearity (DNL)** is the deviation of any code width from an ideal 1 LSB step.

**Effective Number of Bits (ENOB)** is an alternate method of specifying Signal to Noise-and-Distortion Ratio (SINAD). In dB, it is calculated as: ENOB = (SINAD - 1.76)/6.02

**Gain Error** is the ratio of the difference between the voltages that cause the lowest and highest code transitions to the full-scale voltage (less 2 LSB). It is typically expressed in percent.

**Integral Non-Linearity (INL)** is the deviation of each individual code from a line drawn from negative full-scale (1/2 LSB below the first code transition) through positive full-scale (1/2 LSB above the last code transition). The deviation of any given code from this line is measured from the center of that code.

**Least Significant Bit (LSB)** is the bit that has the smallest value or weight in a digital word. Its value in terms of input voltage is  $V_{FS}/(2^N - 1)$  where N is the resolution in bits.

**Missing Codes** are output codes that are skipped and will never appear at the ADC output. These codes cannot be reached with any input value.

**Most Significant Bit (MSB)** is the bit that has the largest value or weight.

**Pipeline Delay** is the number of clock cycles between the initiation of a conversion and the appearance at the output pins of the data.

**Power Supply Rejection Ratio (PSRR)** is the ratio of a change in input voltage necessary to correct a change in output code that results from a change in power supply voltage.

**Signal to Noise-and-Distortion (SINAD)** is the ratio of the RMS signal amplitude to the RMS sum of all other spectral components below one half the clock frequency, including harmonics but excluding DC.

**Signal-to-Noise Ratio (SNR)** (without Harmonics) is the ratio of the RMS signal amplitude to the RMS sum of all other spectral components below one-half the sampling frequency, excluding harmonics and DC.

SNR and SINAD are either given in units of dBc (dB to carrier) when the power level of the fundamental is used as the reference, or dBFS (dB to full scale) when the converter's full-scale input power is used as the reference.

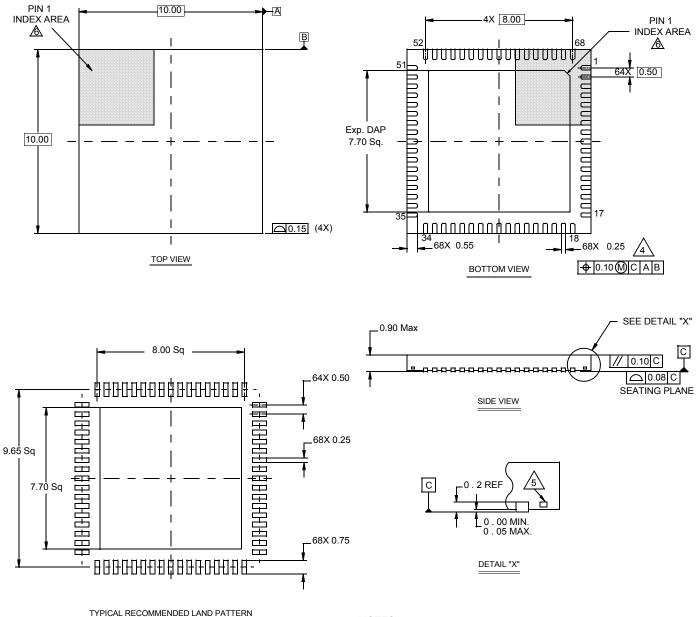
**Spurious-Free-Dynamic Range (SFDR)** is the ratio of the RMS signal amplitude to the RMS value of the peak spurious spectral component. The peak spurious spectral component may or may not be a harmonic.

**Two-Tone SFDR** is the ratio of the RMS value of the lowest power input tone to the RMS value of the peak spurious component, which may or may not be an IMD product.

# Package Outline Drawing

### L68.10x10B

68 LEAD QUAD FLAT NO-LEAD PLASTIC PACKAGE Rev 0, 11/08



NOTES:

- Dimensions are in millimeters. Dimensions in ( ) for Reference Only.
- 2. Dimensioning and tolerancing conform to AMSEY14.5m-1994.
- 3. Unless otherwise specified, tolerance : Decimal  $\pm 0.05$
- 4. Dimension b applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip.
- 5. Tiebar shown (if present) is a non-functional feature.
- 6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.