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### High voltage high/low-side driver

Datasheet - production data



#### **Features**

- High voltage rail up to 600 V
- dV/dt immunity ± 50 V/nsec in full temperature range
- Driver current capability: 290 mA source, 430 mA sink
- Switching times 75/35 nsec rise/fall with 1 nF load
- 3.3 V, 5 V TTL/CMOS inputs with hysteresis
- Integrated bootstrap diode
- Operational amplifier for advanced current sensing
- · Comparator for fast fault protection
- Smart shutdown function
- Adjustable deadtime
- · Interlocking function
- · Compact and simplified layout
- · Bill of material reduction

### **Applications**

- Home appliances
- Motor drivers
  - DC, AC, PMDC and PMAC motors
  - FOC and sensorless BEMF detection systems
- · Industrial applications and drives
- Induction heating
- HVAC
- Factory automation
- · Power supply systems

#### **Description**

The L6390 is a full featured high voltage device manufactured with the BCD ™ "offline" technology. It is a single-chip half-bridge gate driver for N-channel power MOSFETs or IGBTs. The high-side (floating) section is able to work with voltage rail up to 600 V.

Both device outputs can sink and source 430 mA and 290 mA respectively. Prevention from cross conduction is ensured by interlocking and programmable deadtime functions.

The device has dedicated input pins for each output and a shutdown pin. The logic inputs are CMOS/TTL compatible down to 3.3 V for easy interfacing with control devices. Matched delays between low-side and high-side sections guarantee no cycle distortion and allow high frequency operation.

The L6390 embeds an operational amplifier suitable for advanced current sensing in applications such as field oriented motor control or for sensorless BEMF detection. A comparator featuring advanced smartSD function is also integrated in the device, ensuring fast and effective protection against fault events like overcurrent, overtemperature, etc.

The L6390 device features also UVLO protection on both the lower and upper driving sections, preventing the power switches from operating in low efficiency or dangerous conditions.

The integrated bootstrap diode as well as all of the integrated features of this IC make the application PCB design easier, more compact and simple thus reducing the overall bill of material.

The device is available in an SO-16 tube and tape and reel packaging options.

Contents L6390

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L6390 **Block diagram** 

#### **Block diagram** 1

BOOTSTRAP DRIVER FLOATING STRUCTURE BOOT vcc ¢ --- from LVG UV DETECTION UV DETECTION HVG I DRIVER 15 LEVEL SHIFTER HVG HIN LOGIC SHOOT THROUGH PREVENTION out 🖒 LIN C V<sub>C</sub>C LVG DRIVER LVG SD/OD SD LATCH 5V SMART SD COMPARATOR GND 0 8 10 CP+ DEAD VCC TIME OPAMP OP+  $OPOUT \phi^{\frac{7}{2}}$ 

Figure 1. Block diagram

Pin connection L6390

### 2 Pin connection

Figure 2. Pin connection (top view)

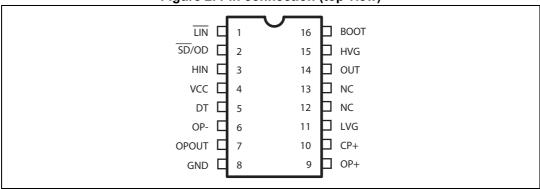


Table 1. Pin description

Pin no.	Pin name	Туре	Function
1	LIN	I	Low-side driver logic input (active low)
2	SD/OD (1)	I/O	Shutdown logic input (active low)/open drain (comparator output)
3	HIN	I	High-side driver logic input (active high)
4	VCC	Р	Lower section supply voltage
5	DT	I	Deadtime setting
6	OP-	I	Op amp inverting input
7	OPOUT	0	Op amp output
8	GND	Р	Ground
9	OP+	I	Op amp non-inverting input
10	CP+	I	Comparator input
11	LVG <sup>(1)</sup>	0	Low-side driver output
12, 13	NC		Not connected
14	OUT	Р	High-side (floating) common voltage
15	HVG <sup>(1)</sup>	0	High-side driver output
16	BOOT	Р	Bootstrap supply voltage

The circuit provides less than 1 V on the LVG and HVG pins (at I<sub>sink</sub> = 10 mA), with V<sub>CC</sub> > 3 V. This allows
the omission of the "bleeder" resistor connected between the gate and the source of the external MOSFET
normally used to hold the pin low; the gate driver assures low impedance also in SD condition.



L6390 Electrical data

## 3 Electrical data

### 3.1 Absolute maximum ratings

Table 2. Absolute maximum ratings

Cumbal	Dovometor	Va	Value			
Symbol	Parameter	Min.	Max.	Unit		
V <sub>CC</sub>	Supply voltage	- 0.3	21	V		
V <sub>OUT</sub>	Output voltage	V <sub>BOOT</sub> - 21	V <sub>BOOT</sub> + 0.3	V		
V <sub>BOOT</sub>	Bootstrap voltage	- 0.3	620	V		
V <sub>hvg</sub>	High-side gate output voltage	V <sub>OUT</sub> - 0.3	V <sub>BOOT</sub> + 0.3	V		
V <sub>Ivg</sub>	Low-side gate output voltage	- 0.3	V <sub>CC</sub> + 0.3	V		
V <sub>OP+</sub>	Op amp non-inverting input	- 0.3	V <sub>CC</sub> + 0.3	V		
V <sub>OP-</sub>	Op amp inverting input	- 0.3	V <sub>CC</sub> + 0.3	V		
V <sub>CP+</sub>	Comparator input voltage	- 0.3	V <sub>CC</sub> + 0.3	V		
Vi	Logic input voltage	- 0.3	15	V		
V <sub>od</sub>	Open drain voltage	- 0.3	15	V		
dV <sub>out</sub> /dt	Allowed output slew rate	-	50	V/ns		
P <sub>tot</sub>	Total power dissipation (T <sub>A</sub> = 25 °C)	-	800	mW		
T <sub>J</sub>	Junction temperature	-	150	°C		
T <sub>stg</sub>	Storage temperature	-50	150	°C		
ESD	Human body model		2	kV		

### 3.2 Thermal data

Table 3. Thermal data

Symbol	Symbol Parameter		Unit
R <sub>th(JA)</sub>	Thermal resistance junction to ambient	120	°C/W

Electrical data L6390

## 3.3 Recommended operating conditions

Table 4. Recommended operating conditions

Symbol	Pin	Parameter	Test condition	Min.	Max.	Unit
V <sub>CC</sub>	4	Supply voltage	-	12.5	20	V
V <sub>BO</sub> <sup>(1)</sup>	16 - 14	Floating supply voltage	-	12.4	20	V
V <sub>OUT</sub>	14	DC output voltage	-	- 9 <sup>(2)</sup>	580	V
f <sub>sw</sub>	-	Switching frequency	HVG, LVG load C <sub>L</sub> = 1 nF	-	800	kHz
T <sub>J</sub>	-	Junction temperature	-	-40	125	°C

<sup>1.</sup>  $V_{BO} = V_{BOOT} - V_{OUT}$ 

<sup>2.</sup> LVG off.  $V_{CC}$  = 12.5 V. Logic is operational if  $V_{BOOT}$  > 5 V. Refer to the AN2738 for more details.

## 4 Electrical characteristics

## 4.1 AC operation

Table 5. AC operation electrical characteristics (V<sub>CC</sub> = 15 V; T<sub>J</sub> = +25 °C)

Symbol	Pin	Parameter	Test condition	Min.	Тур.	Max.	Unit
t <sub>on</sub>	1 vs. 11	High/low-side driver turn-on propagation delay	V <sub>OUT</sub> = 0 V	50	125	200	ns
t <sub>off</sub>	3 vs. 15	High/low-side driver turn-off propagation delay	$V_{BOOT} = V_{CC}$ $C_L = 1 \text{ nF}$ $V_i = 0 \text{ to } 3.3 \text{ V}$	50	125	200	ns
t <sub>sd</sub>	2 vs. 11, 15	Shutdown to high/low-side driver propagation delay	See Figure 4 on page 12	50	125	200	ns
t <sub>isd</sub>	-	Comparator triggering to high/low-side driver turn-off propagation delay	Measured applying a voltage step from 0 V to 3.3 V to pin CP+.	50	200	250	ns
MT	-	Delay matching, HS and LS turn-on/off	-	-	-	30	ns
			R <sub>DT</sub> = 0	0.1	0.18	0.25	μS
		5 Deadtime setting range <sup>(1)</sup>	$R_{DT}$ = 37 k $\Omega$ , $C_L$ = 1 nF, $C_{DT}$ = 100 nF	0.48	0.6	0.72	μS
DT	5		$R_{DT}$ = 136 k $\Omega$ , $C_L$ = 1 nF, $C_{DT}$ = 100 nF	1.35	1.6	1.85	μS
			$R_{DT}$ = 260 k $\Omega$ , $C_L$ = 1 nF, $C_{DT}$ = 100 nF	2.6	3.0	3.4	μS
			R <sub>DT</sub> = 0	-	-	80	ns
			$R_{DT}$ = 37 k $\Omega$ , $C_L$ = 1 nF, $C_{DT}$ = 100 nF	-	-	120	ns
MDT	-	- Matching deadtime <sup>(2)</sup>	$R_{DT}$ = 136 k $\Omega$ , $C_L$ = 1 nF, $C_{DT}$ = 100 nF	-	-	250	ns
			$R_{DT}$ = 260 k $\Omega$ , $C_{L}$ = 1 nF, $C_{DT}$ = 100 nF	ı	-	400	ns
t <sub>r</sub>	11, 15	Rise time	C <sub>L</sub> = 1 nF	-	75	120	ns
t <sub>f</sub>	11, 13	Fall time	C <sub>L</sub> = 1 nF	-	35	70	ns

<sup>1.</sup> See Figure 3.

<sup>2.</sup> MDT =  $|DT_{LH} - DT_{HL}|$  see Figure 6 on page 13.

Electrical characteristics L6390

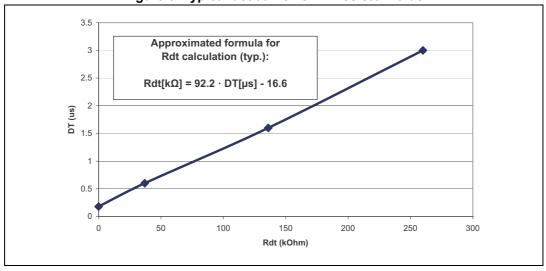


Figure 3. Typical deadtime vs. DT resistor value

## 4.2 DC operation

Table 6. DC operation electrical characteristics ( $V_{CC}$  = 15 V;  $T_J$  = + 25 °C)

Symbol	Pin	Parameter	Test condition	Min.	Тур.	Max.	Unit		
Low supply voltage section									
V <sub>CC_hys</sub>		V <sub>CC</sub> UV hysteresis	-	1200	1500	1800	mV		
V <sub>CC_thON</sub>		V <sub>CC</sub> UV turn-ON threshold	-	11.5	12	12.5	V		
V <sub>CC_thOFF</sub>		V <sub>CC</sub> UV turn-OFF threshold	-	10	10.5	11	V		
I <sub>QCCU</sub>	4	Undervoltage quiescent supply current	$\begin{aligned} & \frac{V_{CC}}{SD} = 10 \text{ V} \\ & \overline{SD} = 5 \text{ V}; \overline{\text{LIN}} = 5 \text{ V}; \\ & \text{HIN = GND;} \\ & R_{DT} = 0  \Omega; \\ & \text{CP+ = OP+ = GND;} \\ & \text{OP- = 5 V} \end{aligned}$	90	120	150	μА		
I <sub>QCC</sub>		Quiescent current	$\begin{aligned} & \underbrace{V_{CC}} = 15 \text{ V} \\ & \widehat{SD} = 5 \text{ V}; \widehat{LIN} = 5 \text{ V}; \\ & \text{HIN} = \text{GND}; \\ & R_{DT} = 0  \Omega; \\ & \text{CP+} = \text{OP+} = \text{GND}; \\ & \text{OP-} = 5 \text{ V} \end{aligned}$	300	720	1000	μΑ		
V <sub>ref</sub>	-	Internal reference voltage	-	500	540	580	mV		
Bootstrapp	ed supply	voltage section <sup>(1)</sup>							
V <sub>BO_hys</sub>		V <sub>BO</sub> UV hysteresis	-	1200	1500	1800	mV		
V <sub>BO_thON</sub>		V <sub>BO</sub> UV turn-ON threshold	-	11.1	11.5	12.1	V		
V <sub>BO_thOFF</sub>		V <sub>BO</sub> UV turn-OFF threshold	-	9.8	10	10.6	V		
I <sub>QBOU</sub>	16	Undervoltage V <sub>BO</sub> quiescent current	$\begin{aligned} & \underbrace{V_{BO}} = 9 \text{ V} \\ & \underline{SD} = 5 \text{ V}; \overline{\text{LIN}} \text{ and} \\ & \text{HIN} = 5 \text{ V}; \\ & R_{DT} = 0  \Omega; \\ & \text{CP+} = \text{OP+} = \text{GND}; \\ & \text{OP-} = 5 \text{ V} \end{aligned}$	30	70	110	μΑ		
I <sub>QBO</sub>		V <sub>BO</sub> quiescent current	$V_{BO}$ = 15 V $\overline{SD}$ = 5 V; $\overline{LIN}$ and HIN = 5 V; $R_{DT}$ = 0 $\Omega$ ; CP+ = $OP+$ = $GND$ ; OP- = 5 V	30	150	240	μА		
I <sub>LK</sub>	-	High voltage leakage current	V <sub>hvg</sub> = V <sub>OUT</sub> = V <sub>BOOT</sub> = 600 V	-	-	10	μА		
R <sub>DS(on)</sub>	-	Bootstrap driver on- resistance <sup>(2)</sup>	LVG ON	-	120	-	Ω		

Electrical characteristics L6390

Table 6. DC operation electrical characteristics ( $V_{CC}$  = 15 V;  $T_J$  = + 25 °C) (continued)

Symbol	Pin	Parameter	Test condition	Min.	Тур.	Max.	Unit				
Driving buf	Driving buffers section										
I <sub>so</sub>	- 11, 15	High/low-side source short- circuit current	$V_{IN} = V_{ih} (t_p < 10 \ \mu s)$	200	290	-	mA				
I <sub>si</sub>	11, 13	High/low-side sink short- circuit current	$V_{IN} = V_{il} (t_p < 10 \ \mu s)$	250	430	-	mA				
Logic input	ts										
V <sub>il</sub>	1, 2, 3	Low level logic threshold voltage	-	0.8	-	1.1	V				
$V_{ih}$	1, 2, 3	High level logic threshold voltage	-	1.9	-	2.25	V				
V <sub>il_S</sub>	1, 3	Single input voltage	LIN and HIN connected together and floating	-	-	0.8	V				
I <sub>HINh</sub>	3	HIN logic "1" input bias current	HIN = 15 V	110	175	260	μА				
I <sub>HINI</sub>		HIN logic "0" input bias current	HIN = 0 V	-	-	1	μА				
I <sub>LINI</sub>	1	LIN logic "0" input bias current	LIN = 0 V	3	6	20	μА				
I <sub>LINh</sub>		LIN logic "1" input bias current	LIN = 15 V	-	-	1	μА				
I <sub>SDh</sub>		SD logic "1" input bias current	<del>SD</del> = 15 V	10	40	100	μА				
I <sub>SDI</sub>	2	SD logic "0" input bias current	SD = 0 V	-	-	1	μА				
R <sub>PD_SD</sub>	2	SD input pull-down resistor	SD = 15 V	150	375	1500	kΩ				

<sup>1.</sup>  $V_{BO} = V_{BOOT} - V_{OUT}$ 

<sup>2.</sup>  $R_{DSON}$  is tested in the following way:  $R_{DSON}$  = [( $V_{CC}$  -  $V_{BOOT1}$ ) - ( $V_{CC}$  -  $V_{BOOT2}$ )] / [ $I_1(V_{CC}, V_{BOOT1})$  -  $I_2(V_{CC}, V_{BOOT2})$ ] where  $I_1$  is the pin 16 current when  $V_{BOOT}$  =  $V_{BOOT1}$ ,  $I_2$  when  $V_{BOOT}$  =  $V_{BOOT2}$ .

Table 7. Op amp characteristics<sup>(1)</sup> ( $V_{CC}$  = 15 V,  $T_{J}$  = +25 °C)

Symbol	Pin	Parameter	Test condition	Min.	Тур.	Max.	Unit
V <sub>io</sub>		Input offset voltage	$V_{ic} = 0 \text{ V}, V_{o} = 7.5 \text{ V}$	-	-	6	mV
I <sub>io</sub>		Input offset current	$V_{ic} = 0 \text{ V}, V_{o} = 7.5 \text{ V}$	-	4	40	nA
I <sub>ib</sub>	6, 9	Input bias current <sup>(2)</sup>	v <sub>ic</sub> - 0 v, v <sub>o</sub> - 7.5 v	-	100	200	nA
V <sub>icm</sub>		Input common mode voltage range	-	0	-	V <sub>CC</sub> -4	V
V <sub>OPOUT</sub>		Output voltage swing	OPOUT = OP-; no load	0.07	-	V <sub>CC</sub> -4	V
	7	Output short-circuit current	Source, $V_{id} = +1$ ; $V_o = 0 \text{ V}$	16	30	-	mA
I <sub>o</sub>		Output short-circuit current	Sink, $V_{id} = -1$ ; $V_o = V_{CC}$	50	80	-	mA
SR	-	Slew rate	$V_i = 1 \div 4 \text{ V; } C_L = 100 \text{ pF;}$ unity gain	2.5	3.8	-	V/μs
GBWP	-	Gain bandwidth product	V <sub>o</sub> = 7.5 V	8	12	-	MHz
A <sub>vd</sub>	-	Large signal voltage gain	$R_L = 2 k\Omega$	70	85	-	dB
SVR	-	Supply voltage rejection ratio	vs. V <sub>CC</sub>	60	75	-	dB
CMRR	ı	Common mode rejection ratio	-	55	70	-	dB

<sup>1.</sup> The operational amplifier is disabled when  $V_{\mbox{\footnotesize CC}}$  is in UVLO condition.

Table 8. Sense comparator characteristics<sup>(1)</sup> ( $V_{CC}$  = 15 V,  $T_{J}$  = +25 °C)

Symbol	Pin	Parameter	Test condition	Min.	Тур.	Max.	Unit
l <sub>ib</sub>	10	Input bias current	V <sub>CP+</sub> = 1 V	-	-	1	μΑ
V <sub>OL</sub>	2	Open drain low level output voltage	I <sub>OD</sub> = - 3 mA	-	-	0.5	V
R <sub>ON_OD</sub>	2	Open drain ON resistor	-	-	125	167	kΩ
t <sub>d_comp</sub>	-	Comparator delay	SD/OD pulled to 5 V through 100 kΩ resistor	-	90	130	ns
SR	2	Slew rate	$C_L = 180 \text{ pF}; R_{pu} = 5 \text{ k}\Omega$	-	60	-	V/μs

<sup>1.</sup> The comparator is disabled when  $\rm V_{\rm CC}$  is in UVLO condition.

<sup>2.</sup> The direction of the input current is out of the IC.

## 5 Timing and waveforms definitions

Figure 4. Propagation delay timing definition

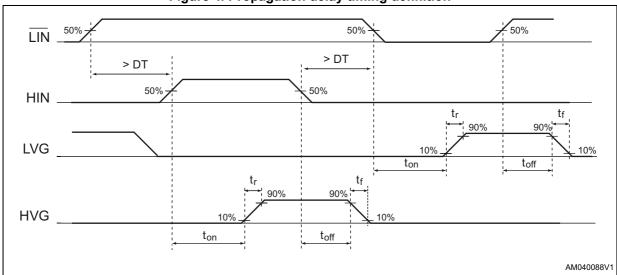
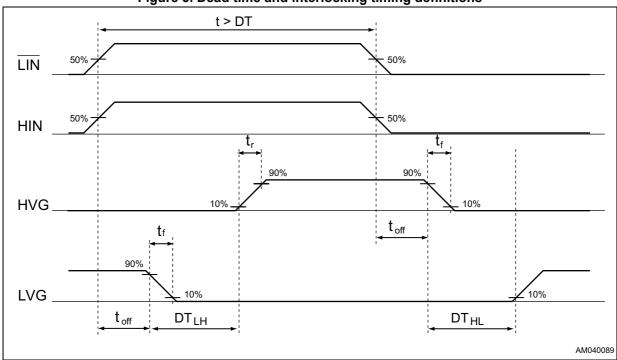


Figure 5. Dead time and interlocking timing definitions



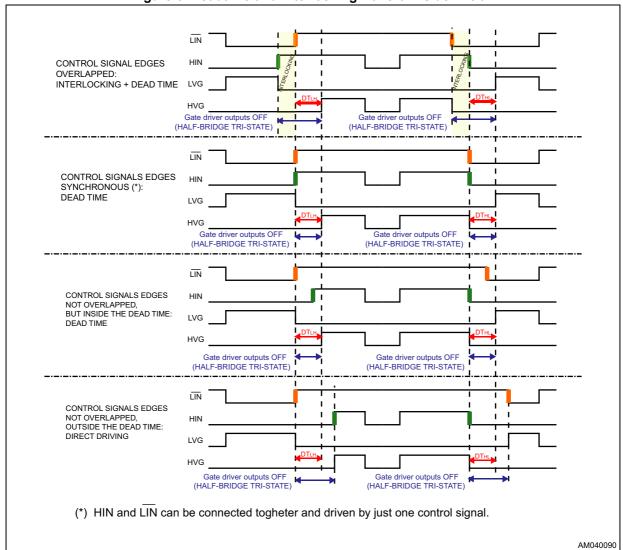


Figure 6. Deadtime and interlocking waveforms definition



Input logic L6390

## 6 Input logic

Input logic is provided with an interlocking circuitry which avoids the two outputs (LVG, HVG) being active at the same time when both the logic input pins (LIN, HIN) are at a high logic level. In addition, to prevent cross conduction of the external MOSFETs, after each output is turned off, the other output cannot be turned on before a certain amount of time (DT) (see Figure 5: Dead time and interlocking timing definitions).

Table 9. Truth table

	Input	Output		
SD	LIN	HIN	LVG	HVG
L	X <sup>(1)</sup>	X <sup>(1)</sup>	L	L
Н	Н	L	L	L
Н	L	Н	L	L
Н	L	L	Н	L
Н	Н	Н	L	Н

<sup>1.</sup> X: don't care.

#### 7 Smart shutdown function

The L6390 device integrates a comparator committed to the fault sensing function. The comparator has an internal voltage reference  $V_{ref}$  connected to the inverting input, while the non-inverting input is available on the pin 10. The comparator input can be connected to an external shunt resistor in order to implement a simple overcurrent detection function. The output signal of the comparator is fed to an integrated MOSFET with the open drain output available on the pin 2, shared with the  $\overline{SD}$  input. When the comparator triggers, the device is set in shutdown state and both its outputs are set to low level leaving the half-bridge in tristate.

Figure 7. Smart shutdown timing waveforms CP+ HIN/LIN **PROTECTION** HVG/LVG SD/OD  $au_2$ Open drain gate (internal)  $t_2$ Disable time Fast shut down: The driver outputs are set in SD state immediately after the comparator triggering even if the SD signal has not yet reach the lower input threshold. An approximation of the disable time is given by:  $t_1 \cong \tau_1 \cdot ln \left( \frac{V_{off} - V_{on}}{V_{il} - V_{on}} \right)$ SHUT-DOWN CIRCUIT  $t_2 \cong \tau_2 \cdot ln \left( \frac{V_{il} - V_{off}}{V_{ih} - V_{off}} \right)$  $R_{SD}$ where:  $\tau_1 = \left(R_{ON\_OD}//R_{SD}\right) \cdot C_{SD}$ SD/OD  $\tau_2 = \left(R_{PD\_SD}//R_{SD}\right) \cdot C_{SD}$ FROM/TO SMART 
$$\begin{split} V_{on} &= \frac{R_{ON\_OD}}{R_{ON\_OD} + R_{SD}} \cdot V_{BIAS} \\ V_{off} &= \frac{R_{PD\_SD}}{R_{PD\_SD} + R_{SD}} \cdot V_{BIAS} \end{split}$$
 $C_{\text{SD}}$ AM12947v2

In common overcurrent protection architectures the comparator output is usually connected to the SD input and an RC network is connected to this SD/OD line in order to provide a monostable circuit, which implements a protection time that follows the fault condition. Differently from the common fault detection systems, the L6390 smart shutdown architecture allows immediate turn-off of the outputs of the gate driver in the case of fault, by minimizing the propagation delay between the fault detection event and the actual output switch-off. In fact, the time delay between the fault detection and the output turn-off is no longer dependent on the value of the external RC network connected to the SD/OD pin. In the smart shutdown circuitry the fault signal has a preferential path which directly switches off the outputs after the comparator triggering. At the same time the internal logic turns on the open drain output and holds it on until the SD voltage goes below the SD logic input lower threshold. When such threshold is reached, the open drain output is turned off, allowing the external pull-up to recharge the capacitor. The driver outputs restart following the input pins as soon as the voltage at the SD/OD pin reaches the higher threshold of the SD logic input. The smart shutdown system provides the possibility to increase the time constant of the external RC network (that determines the disable time after the fault event) up to very large values without increasing the delay time of the protection.

Any external signal provided to the  $\overline{SD}$  pin is not latched and can be used as control signal in order to perform, for instance, PWM chopping through this pin. In fact when a PWM signal is applied to the  $\overline{SD}$  input and the logic inputs of the gate driver are stable, the outputs switch from the low level to the state defined by the logic inputs and vice versa.

In some applications it may be useful to latch the driver in the shutdown condition for an arbitrary time, until the controller decides to reset it to normal operation. This may, for example, be achieved with a circuit similar to the one shown in *Figure 8*. When the open drain starts pulling down the  $\overline{SD}/OD$  pin, the external latch turns on and keeps the pin to GND, preventing it from being pulled up again once the  $\overline{SD}$  logic input lower threshold is reached and the internal open drain turns off. One pin of the controller is used to release the external latch, and one to externally force a shutdown condition and also to read the status of the  $\overline{SD}/OD$  pin.

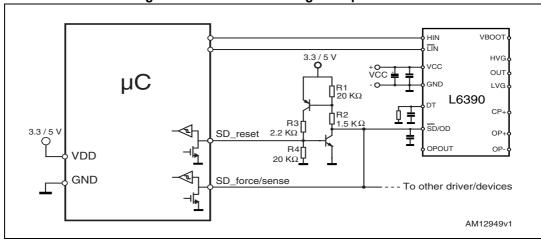


Figure 8. Protection latching example circuit

In applications using only one L6390 for the protection of several different legs (such as a single-shunt inverter, for example) it may be useful to implement the resistor divider shown in *Figure 9*. This simple network allows the pushing of the  $\overline{\text{SD}}$  pins of the other devices to a voltage lower than L6390  $V_{il}$ , so that each device can reach its low logic level regardless of part-to-part variations of the thresholds.

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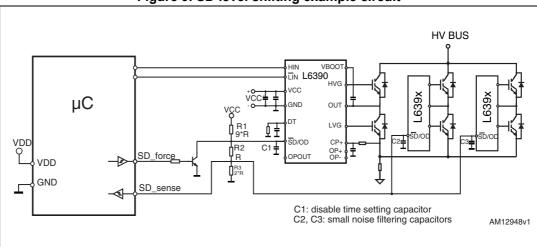


Figure 9. SD level shifting example circuit

# 8 Typical application diagram

PROM CONTROLLER IN 3

FROM CONTROLLER IN 3

FROM CONTROLLER IN 4

OPAMP

TO ADC

ROW COMPARATOR

FROM CONTROLLER IN 5

OPAMP

TO ADC

FROM CONTROLLER IN 5

OPAMP

Figure 10. Application diagram



L6390 Bootstrap driver

### 9 Bootstrap driver

A bootstrap circuitry is needed to supply the high voltage section. This function is normally accomplished by a high voltage fast recovery diode (*Figure 11.a*). In the L6390 device a patented integrated structure replaces the external diode. It is realized by a high voltage DMOS, driven synchronously with the low-side driver (LVG), with a diode in series, as shown in *Figure 11.b*. An internal charge pump (*Figure 11.b*) provides the DMOS driving voltage.

### **C**BOOT selection and charging

To choose the proper  $C_{BOOT}$  value the external MOS can be seen as an equivalent capacitor. This capacitor  $C_{EXT}$  is related to the MOS total gate charge:

#### **Equation 1**

$$C_{EXT} = \frac{Q_{gate}}{V_{gate}}$$

The ratio between the capacitors  $C_{\text{EXT}}$  and  $C_{\text{BOOT}}$  is proportional to the cyclical voltage loss. It must be:

#### **Equation 2**

E.g.: if  $Q_{gate}$  is 30 nC and  $V_{gate}$  is 10 V,  $C_{EXT}$  is 3 nF. With  $C_{BOOT}$  = 100 nF the drop would be 300 mV.

If HVG must be supplied for a long time, the  $C_{BOOT}$  selection must also take the leakage and quiescent losses into account.

E.g.: HVG steady-state consumption is lower than 240  $\mu$ A, so if HVG  $T_{ON}$  is 5 ms,  $C_{BOOT}$  must supply 1.2  $\mu$ C to  $C_{EXT}$ . This charge on a 1  $\mu$ F capacitor means a voltage drop of 1.2 V.

The internal bootstrap driver offers important advantages: the external fast recovery diode can be avoided (it usually has a high leakage current).

This structure can work only if  $V_{OUT}$  is close to GND (or lower) and, at the same time, the LVG is on. The charging time ( $T_{charge}$ ) of the  $C_{BOOT}$  is the time in which both conditions are fulfilled and it must be long enough to charge the capacitor.

The bootstrap driver introduces a voltage drop due to the DMOS  $R_{DSon}$  (typical value: 120  $\Omega$ ). This drop can be neglected at low switching frequency, but it should be taken into account when operating at high switching frequency.

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The following equation is useful to compute the drop on the bootstrap DMOS:

#### **Equation 3**

$$V_{drop} = I_{charge}R_{dson} \rightarrow V_{drop} = \frac{Q_{gate}}{T_{charge}}R_{dson}$$

where  $Q_{gate}$  is the gate charge of the external power MOSFET,  $R_{dson}$  is the on-resistance of the bootstrap DMOS and  $T_{charge}$  is the charging time of the bootstrap capacitor.

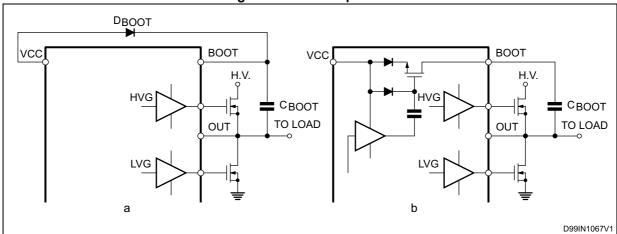
For example: using a power MOSFET with a total gate charge of 30 nC, the drop on the bootstrap DMOS is about 1 V, if the  $T_{charge}$  is 5  $\mu s$ . In fact:

#### **Equation 4**

$$V_{drop} \, = \, \frac{30nC}{5\mu s} \cdot 120\Omega \sim 0.7 V$$

 $V_{drop}$  should be taken into account when the voltage drop on  $C_{BOOT}$  is calculated: if this drop is too high, or the circuit topology doesn't allow a sufficient charging time, an external diode can be used.

Figure 11. Bootstrap driver



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L6390 **Package information** 

#### 10 **Package information**

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

#### SO-16 package information 10.1

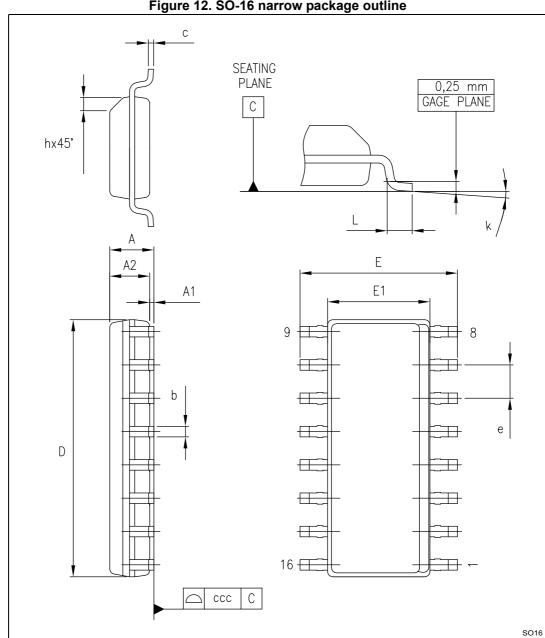


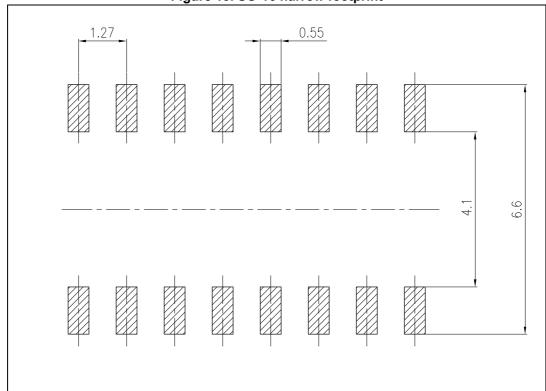
Figure 12. SO-16 narrow package outline

Package information L6390

Table 10. SO-16 narrow package mechanical data

Cumb al		Dimensions (mm)	
Symbol	Min.	Тур.	Max.
Α	-	-	1.75
A1	0.10	-	0.25
A2	1.25	-	-
b	0.31	-	0.51
С	0.17	-	0.25
D	9.80	9.90	10.00
E	5.80	6.00	6.20
E1	3.80	3.90	4.00
е	-	1.27	-
h	0.25	-	0.50
L	0.40	-	1.27
k	0	-	8°
ccc	-	-	0.10

Figure 13. SO-16 narrow footprint



L6390 Order codes

## 11 Order codes

Table 11. Order codes

Order code	Package	Packaging
L6390D	SO-16	Tube
L6390DTR	SO-16	Tape and reel

Revision history L6390

# 12 Revision history

Table 12. Document revision history

Date	Revision	Changes	
20-Jun-2014	8	Updated Section: Applications on page 1 (replaced by new applications).  Updated Section: Description on page 1 (replaced by new description).  Updated Table 1: Device summary (moved from page 1 to page 24, updated title to Table 11: Order codes).  Updated Section 4.1: Absolute maximum ratings on page 6 (removed note below Table 3: Absolute maximum ratings).  Updated Table 7 on page 10 (updated I <sub>QBO</sub> max. value).  Updated Section: C <sub>BOOT</sub> selection and charging on page 18 (updated values of "E.g.: HVG").  Updated Section 10: Package information on page 20 (updated titles, reversed order of Figure 11 and Table 10, Figure 11 and Table 10, updated headers of Table 10 and Table 10).  Minor modifications throughout document.	
11-Sep-2015	9	Removed DIP-16 package from the whole document.  Updated <i>Table 3 on page 6</i> (added ESD parameter and value).  Updated <i>Table 4 on page 6</i> (updated R <sub>th(JA)</sub> value).  Updated note 1.and 2. below <i>Table 7 on page 10</i> (minor modifications, replaced V <sub>CBOOTx</sub> by V <sub>BOOTx</sub> ).  Minor modifications throughout document.	
07-Apr-2017	10	Updated <i>Table 5 on page 7</i> (updated cross reference to <i>Figure 4 on page 12</i> instead of removed <i>Figure 3. Timing</i> ).  Updated <i>Table 6 on page 9</i> (added R <sub>PD_SD</sub> ) and <i>Table 8 on page 11</i> (added R <sub>ON_OD</sub> ).  Updated <i>Section 5 on page 12</i> (updated title, added <i>Figure 4</i> and <i>Figure 5</i> ).  Added <i>Section 6 on page 14</i> (and moved <i>Table 9: Truth table</i> to this section).  Updated <i>Figure 11 on page 20</i> and <i>Figure 12 on page 21</i> (replaced by new figure).  Minor modifications throughout document.	

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