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Tel: +86-755-8981 8866 Fax: +86-755-8427 6832 Email & Skype: info@chipsmall.com Web: www.chipsmall.com Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



Static Drive, 1/2-Duty Drive General-Purpose LCD Driver

Overview

The LC75832E and 75832W are static drive or 1/2-duty drive, microcontroller-controlled general-purpose LCD drivers that can be used in applications such as frequency display in products with electronic tuning. In addition to being capable to drive up to 108 segments directly, they can control up to 4 general-purpose output ports. Since the LC75832E and LC75832W use separate power supply systems for the LCD drive block and the logic block, the LCD driver block power-supply voltage can be set to any voltage in the range 2.7 to 6.0 volts, regardless of the logic block power-supply voltage.

Features

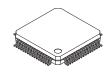
- Serial data control of switching between static drive mode and 1/2 duty drive mode.
- Up to 54 segments can be displayed in static drive (1/1 duty) mode and up to 108 segments can be displayed in 1/2 duty drive mode.
- Serial data input supports CCB* format communication with the system controller.
- Serial data control of the power-saving mode based backup function and the all segments forced off function.
- Serial data control of switching between the segment output port and general-purpose output port functions (up to 4 general-purpose output ports).
- Serial data control of the frame frequency of the common and segment output waveforms.
- Either RC oscillator operating or external clock operating mode can be selected with the serial control data.
- High generality, since display data is displayed directly without the intervention of a decoder circuit.
- Independent V_{LCD} for the LCD driver block (V_{LCD} can be set to any voltage in the range of 2.7 to 6.0 volts.) regardless of the logic block supply-voltage.
- The $\overline{\text{INH}}$ pin allows the display to be forced to the off state.
- Allows compatible operation with the LC75822 (822 mode transfer function).



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PQFP64 14x14 / QIP64E [LC75832E]



SPQFP64 10x10 / SQFP64 [LC75832W]

* Computer Control Bus (CCB) is an ON Semiconductor's original bus format and the bus addresses are controlled by ON Semiconductor.

ORDERING INFORMATION

See detailed ordering and shipping information on page 24 of this data sheet.

Specifications Absolute Maximum Ratings at Ta = 25° C, V_{SS} = 0 V

Parameter	Symbol	Conditions	Ratings	Unit	
Maximum supply voltage	V _{DD} max	V _{DD}	-0.3 to +7.0		
	V _{LCD} max	V _{LCD}	-0.3 to +7.0	V	
Input voltage	V _{IN} 1	CE, CL, DI, INH	-0.3 to +7.0		
	V _{IN} 2	OSC	–0.3 to V _{DD} +0.3	V	
Output voltage	VOUT1	OSC	–0.3 to V _{DD} +0.3	V	
	V _{OUT} 2	S1 to S54, COM1, COM2, P1 to P4	-0.3 to V _{LCD} +0.3	V	
Output current	IOUT1	S1 to S54	300	μA	
	IOUT2	COM1, COM2	3		
	I _{OUT} 3	P1 to P4	5	mA	
Allowable power dissipation	Pd max	Ta = 105°C	100	mW	
Operating temperature	Topr		-40 to +105	°C	
Storage temperature	Tstg		-55 to +125	°C	

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Allowable Operating Ranges at Ta = –40 to +105°C, V_{SS} = 0 V

Parameter	Symphol	Conditions			Ratings		unit
Parameter	Symbol			min	typ	max	unit
Supply voltage	V _{DD}	V _{DD}		2.7		6.0	V
	V _{LCD}	V _{LCD}		2.7		6.0	v
Input high-level voltage	V _{IH} 1	CE, CL, DI, IN	IH	0.8V _{DD}		6.0	V
	V _{IH} 2	OSC external	clock operating mode	0.7V _{DD}		V _{DD}	V
Input low-level voltage	V _{IL} 1	CE, CL, DI, IN	IH	0		0.2V _{DD}	V
	V _{IL} 2	OSC external	clock operating mode	0		0.3V _{DD}	V
Recommended external resistor for RC oscillation	Rosc	OSC RC oscil	lator operating mode		39		kΩ
Recommended external capacitor for RC oscillation	Cosc	OSC RC oscil	lator operating mode		1000		pF
Guaranteed range of RC oscillation	fosc	OSC RC oscillator operating mode		19	38	76	kHz
External clock operating frequency	fCK	OSC external clock operating mode [Figure 3]		19	38	76	kHz
External clock duty cycle	РСК	OSC external clock operating mode [Figure 3]		30	50	70	%
Data setup time	tds	CL, DI	[Figure 1] [Figure 2]	160			ns
Data hold time	tdh	CL, DI	[Figure 1] [Figure 2]	160			ns
CE wait time	tcp	CE, CL	[Figure 1] [Figure 2]	160			ns
CE setup time	tcs	CE, CL	[Figure 1] [Figure 2]	160			ns
CE hold time	tch	CE, CL	[Figure 1] [Figure 2]	160			ns
High-level clock pulse width	tφH	CL	[Figure 1] [Figure 2]	160			ns
Low-level clock pulse width	tφL	CL	[Figure 1] [Figure 2]	160			ns
Rise time	tr	CE, CL, DI	[Figure 1] [Figure 2]		160		ns
Fall time	tf	CE, CL, DI	[Figure 1] [Figure 2]		160		ns
INH switching time	tc	INH, CE	[Figure 4] to [Figure 7]	10			μS

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Deremeter	Sumbol	Pin	Conditions	Ratings				
Parameter	Symbol	Pin	Conditions	min	typ	max	unit	
Hysteresis	VH	CE, CL, DI, INH			0.1V _{DD}		V	
Input high-level	I _{IH} 1	CE, CL, DI, INH	V _I = 6.0 V			5.0		
current	I _{IH} 2	OSC	V _I = V _{DD} external clock operating mode			5.0	μA	
Input low-level	IIL1	CE, CL, DI, INH	V _I = 0 V	-5.0				
current	IIL2	OSC	V _I = 0 V external clock operating mode	-5.0			μA	
Output high- level voltage	V _{OH} 1	S1 to S54	I _O = -20 μA	V _{LCD} -0.9				
	V _{OH} 2	COM1, COM2	I _O = -100 μA	V _{LCD} _0.9			V	
	V _{OH} 3	P1 to P4	I _O = -1 mA	V _{LCD} _0.9				
Output low-level	V _{OL} 1	S1 to S54	I _O = 20 μA			0.9		
voltage	V _{OL} 2	COM1, COM2	I _O = 100 μA			0.9	V	
	V _{OL} 3	P1 to P4	I _O = 1 mA			0.9		
Output middle-level voltage	VMID	COM1, COM2	1/2 bias I _O = ±100 μA	1/2V _{LCD} _0.9		1/2V _{LCD} +0.9	v	
Oscillator frequency	fosc	OSC	RC oscillator operating mode Rosc = $39k\Omega$, Cosc = 1000 pF	30.4	38	45.6	kHz	
Current drain	I _{DD} 1	V _{DD}	Power-saving mode			10		
	I _{DD} 2	V _{DD}	V _{DD} = 6.0 V output open fosc = 38 kHz		250	500		
	ILCD1	V _{LCD}	Power-saving mode			15		
	ILCD ²	VLCD	V _{LCD} = 6.0 V output open Static fosc = 38 kHz		100	200	μA	
	ILCD3	VLCD	V _{LCD} = 6.0 V output open 1/2 duty fosc = 38 kHz		1300	2600		

$\label{eq:constraint} \textbf{Electrical Characteristics} \text{ for the Allowable Operating Ranges}$

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

1. When CL is stopped at the low level

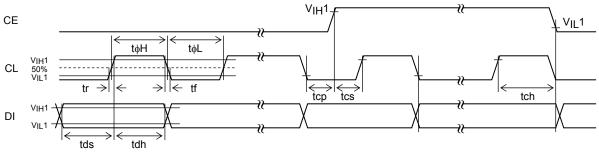
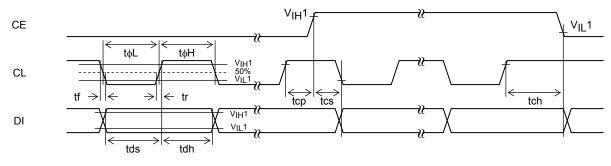


Figure 1

2. When CL is stopped at the high level





3. OSC pin clock timing in external clock operating mode

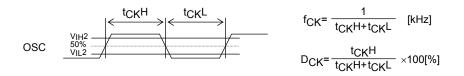


Figure 3

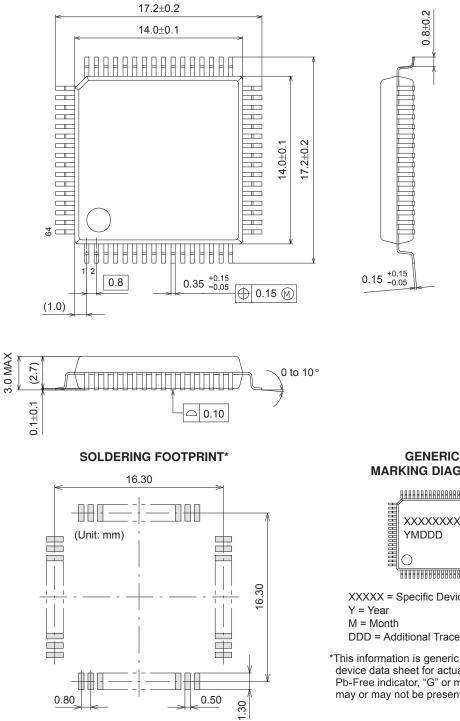
Package Dimensions

unit : mm

[LC75832E]

PQFP64 14x14 / QIP64E CASE 122BP

ISSUE A



NOTE: The measurements are not to guarantee but for reference only.

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

MARKING DIAGRAM*



XXXXX = Specific Device Code DDD = Additional Traceability Data

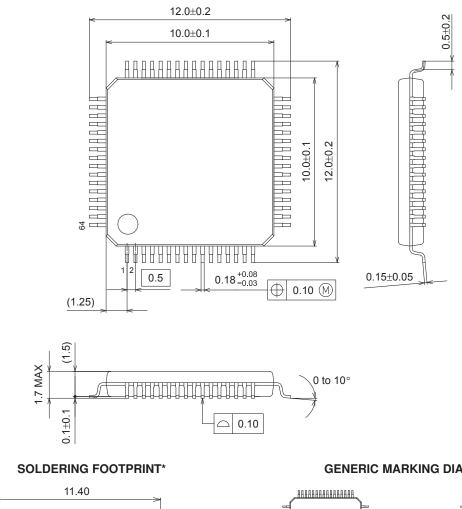
*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "■", may or may not be present.

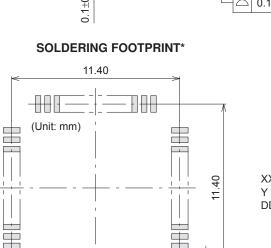
Package Dimensions

unit : mm

[LC75832W]

SPQFP64 10x10 / SQFP64 CASE 131AK **ISSUE A**

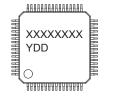




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8.

GENERIC MARKING DIAGRAM*





XXXXX = Specific Device Code Y = Year DD = Additional Traceability Data XXXXX = Specific Device Code Y = Year M = Month DDD = Additional Traceability Data

*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot ".", may or may not be present.

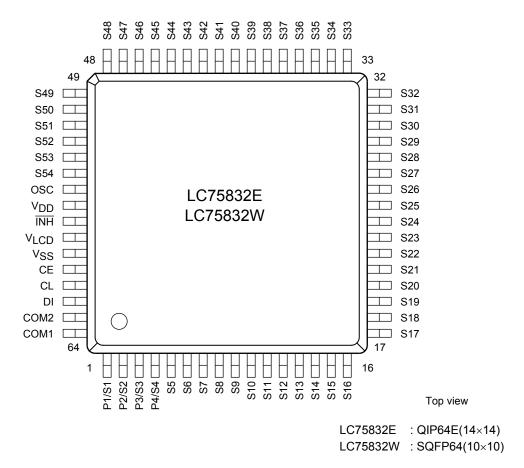
NOTE: The measurements are not to guarantee but for reference only.

H

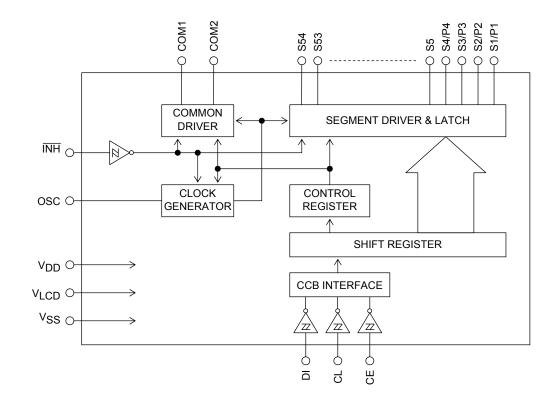
0.50

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

Pin Assignment



Block Diagram



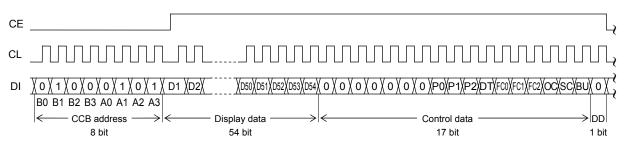
Pin Functions

					Handling
Symbol	Pin No.	Function	Active	I/O	when unused
S1/P1 to	1 to 4	Segment outputs for displaying the display data transferred by serial data input.	-	0	OPEN
S4/P4		The S1/P1 to S4/P4 pins can be used as general-purpose output ports when so set			
S5 to S54	5 to 54	up by the control data.			
COM1	64	Common driver outputs. The frame frequency is fo [Hz].	-	0	OPEN
COM2	63				
OSC	55	Oscillator connection. An oscillator circuit is formed by connecting an external	-	I/O	V _{DD}
		resistor and capacitor to this pin. This pin can be used as the external clock input			
		pin if external clock operating mode is selected with the control data.			
CE	60	Serial data transfer inputs. Must be connected to the controller.	н	I.	GND
CL	61	CE: Chip enable		Т	
DI	62	CL: Synchronization clock		I	
		DI: Transfer data			
INH	57	Display off control input	L	I	GND
		• INH = low (V _{SS})Display forced off			
		S1/P1 to S4/P4 = low (V _{SS})			
		(These pins are forcibly set to the segment output port function			
		and held at the V _{SS} level.)			
		S5 to S54 = low (V _{SS})			
		COM1, COM2 = low (V_{SS})			
		OSC = Z (high impedance)			
		RC oscillation stopped			
		Inhibits external clock input.			
		• INH = high (V _{DD})Display on			
		RC oscillation enabled (RC oscillator operating mode)			
		Enables external clock input (external clock operating mode).			
		However, serial data transfer is possible when the display is forced off.			
V _{DD}	56	Logic block power supply. Provide a voltage in the range 2.7 to 6.0 V.	-	-	-
V _{LCD}	58	LCD driver block power supply. Provide a voltage in the range 2.7 to 6.0 V.	-	-	-
VSS	59	Ground pin. Must be connected to ground.	-	-	-

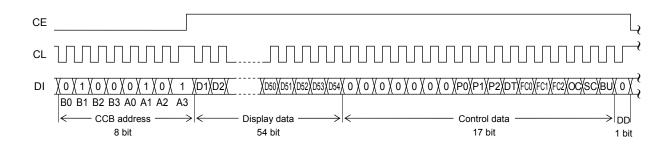
Serial Data Transfer Formats

(1) Static drive mode

1. When CL is stopped at the low level



2. When CL is stopped at the high level

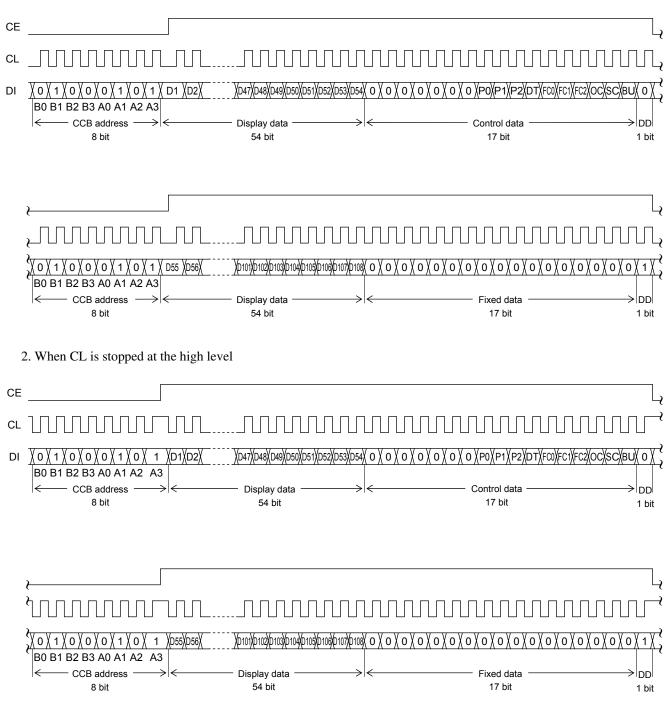


Note: DD is the direction data.

- CCB address "A2H"
- D1 to D54 Display data
- P0 to P2 Segment output port/general-purpose output port switching control data
- DT Static drive or 1/2 duty drive switching control data
- FC0 to FC2 Common/segment output waveform frame frequency control data
- OC RC oscillator operating mode/external clock operating mode switching control data
- SC Segments on/off control data
- BU Normal mode/power-saving mode control data

(2) 1/2 duty drive mode

1. When CL is stopped at the low level

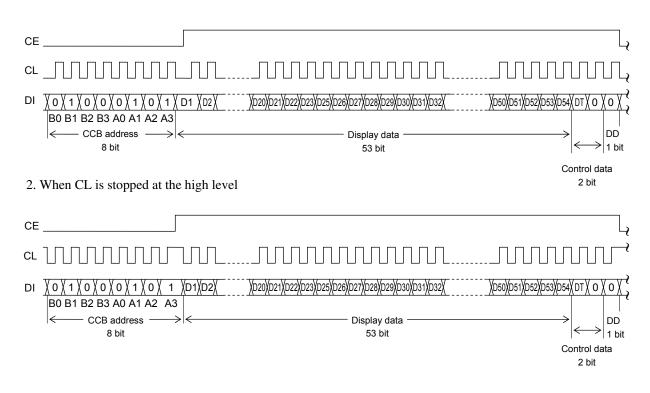


Note: DD is the direction data.

- CCB address "A2H"
- D1 to D108 Display data
- P0 to P2 Segment output port/general-purpose output port switching control data
- DT Static drive or 1/2 duty drive switching control data
- FC0 to FC2 Common/segment output waveform frame frequency control data
- OC RC oscillator operating mode/external clock operating mode switching control data
- SC Segments on/off control data
- BU Normal mode/power-saving mode control data

Serial Data Transfer Formats (When in 822 mode data transfer)

- (1) Static drive mode (When in 822 mode data transfer)
- 1. When CL is stopped at the low level



Note: DD is the direction data.

- CCB address "A2H"
- D1 to D23, D25 to D54 Display data
- DT Static drive or 1/2 duty drive switching control data

(2) 1/2 duty drive mode (When in 822 mode data transfer)

1. When CL is stopped at the low level

CE			
CL			Γ.
DI		D1 XD2X XD31XD32XD33XD34XD35XD36XD37XD38XD39XD40XD41XD42XD43XD44XD45XD46XD49XD50XD51XD52XD53XD54X O XDTX	οχοχζ
	B0 B1 B2 B3 A0 A1 A2 A3	Control c	
	<u>،</u> مالىلىلىكى كەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئەربىلىكە ئ	 	ب ب 117,
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	2. When CL is stopped at	the high level	
CE			
CL			
DI	$\begin{array}{c c} & & & \\ & & &$	XD1 XD2 X XD31 XD32 XD33 XD34 XD35 XD36 XD37 XD38 XD39 XD40 XD41 XD42 XD43 XD44 XD45 XD46 XD49 XD50 XD51 XD52 XD53 XD54 (O X DT X	$\rightarrow DD$ 1 bit
	<pre> }</pre>		
	ote: DD is the direction da	ta.	

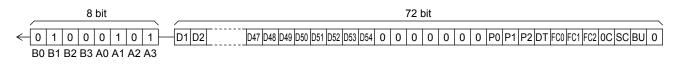
• D1 to D46, D49 to D106 Display data

• DT Static drive or 1/2 duty drive switching control data

Serial Data Transfer Examples

(1) Static drive mode

The serial data shown in the figure below must be sent.



(2) 1/2 duty drive mode

• When 55 or more segments are used

160 bits of serial data (including CCB address bits) must be sent.

8 bit	72 bit			
← 0 1 0 0 0 1 0 1 D1 D2				
B0 B1 B2 B3 A0 A1 A2 A3				
0 1 0 0 1 0 1 0 1 D55 D56	p101 p102 p103 p104 p105 p106 p107 p108 o o o o o o o o o o o o o o o o o o o			

B0 B1 B2 B3 A0 A1 A2 A3

• When fewer than 55 segments are used The serial data shown below (the D1 to D54 display data and the control data) must always be sent.

8 bit	72 bit			
← 0 1 0 0 0 1 0 1 B0 B1 B2 B3 A0 A1 A2 A3				

Serial Data Transfer Example (When in 822 mode data transfer)

(1) Static drive mode

The serial data shown in the figure below must be sent.

8 bit	56 bit
← 0 1 0 0 0 1 0 1 B0 B1 B2 B3 A0 A1 A2 A3	D1 D2 D17 D18 D19 D20 D21 D22 D23 D25 D26 D27 D28 D29 D30 D31 D32 D50 D51 D52 D53 D54 DT 0 0
(2) 1/2 duty drive modeWhen 53 or more segmentation	
128 bits of serial data (1	ncluding CCB address bits) must be sent.
8 bit	56 bit
← 0 1 0 0 0 1 0 1 B0 B1 B2 B3 A0 A1 A2 A3	
0 1 0 0 0 1 0 1 B0 B1 B2 B3 A0 A1 A2 A3	
• When fewer than 53 seg The serial data shown in be sent.	gments are used n the figure below (the D1 to D46 and D49 to D54 display data, and the control data) must
8 bit	56 bit

8 DIt	56 bit
$\leftarrow 0 1 0 0 1 0 1 0 1$	D31 D32 D33 D34 D35 D36 D37 D38 D39 D40 D41 D42 D43 D44 D45 D46 D49 D50 D51 D52 D53 D54 O DT O O
B0 B1 B2 B3 A0 A1 A2 A3	

Control Data Functions

1. P0 to P2: Segment output port/general-purpose output port switching control data

These control data bits switch the segment output port/general-purpose output port functions of the S1/P1 to S4/P4 output pins.

However, segment output port is forcibly selected when in 822 mode data transfer.

Control data			Output pin state			
P0	P1	P2	S1/P1	S2/P2	S3/P3	S4/P4
0	0	0	S1	S2	S3	S4
0	0	1	P1	S2	S3	S4
0	1	0	P1	P2	S3	S4
0	1	1	P1	P2	P3	S4
1	0	0	P1	P2	P3	P4

Note: Sn (n = 1 to 4): Segment output ports

Pn (n = 1 to 4): General-purpose output ports

Note that when the general-purpose output port function is selected, the correspondence between the output pins and the display data will be that shown in the table.

Output size	Corresponding display data			
Output pin	Static drive mode	1/2 duty drive mode		
S1/P1	D1	D1		
S2/P2	D2	D3		
S3/P3	D3	D5		
S4/P4	D4	D7		

For example, if the general-purpose output port function is selected for the S4/P4 output pin in 1/2 duty drive mode, it will output a high level (V_{LCD}) when display data D7 is 1, and a low level (V_{SS}) when D7 is 0.

2. DT: Static drive mode/1/2 duty drive mode switching control data

This control data bit selects either static drive mode or 1/2 duty drive mode.

DT	Duty drive mode	Output pin state (COM2)	
0	Static drive mode	V _{SS} level	
1	1/2 duty drive mode	COM2	

3. FC0 to FC2: Common/segment output waveform frame frequency control data These control data bits set the frame frequency of the common and segment output waveforms. However, fo=fosc/384 is forcibly selected when in 822 mode data transfer.

	Control data		
FC0	FC1	FC2	Frame frequency fo [Hz]
1	1	0	fosc/768, f _{CK} /768
1	1	1	fosc/576, f _{CK} /576
0	0	0	fosc/384, f _{CK} /384
0	0	1	fosc/288, f _{CK} /288
0	1	0	fosc/192, f _{CK} /192

4. OC: RC oscillator operating mode/external clock operating mode switching control data. This control data bit switches the OSC pin function

(either RC oscillator operating mode or external clock operating mode).

However RC oscillator operating mode is forcibly selected when in 822 mode data transfer.

OC	OSC pin function	
0	RC oscillator operating mode	
1	External clock operating mode	

Note: An external resistor, Rosc, and an external capacitor, Cosc, must be connected to the OSC pin if RC oscillator operating mode is selected.

5. SC: Segment on/off control data

This control data bit controls the on/off state of the segments.

However, the segment on state is forcibly selected when in 822 mode data transfer.

SC	Display state
0	On
1	Off

Note that when the segments are turned off by setting SC to 1, the segments are turned off by outputting segment off waveforms from the segment output pins.

6. BU: Normal mode/power-saving mode control data

This control data bit selects either normal mode or power-saving mode.

However, the normal mode is forcibly selected when in 822 mode data transfer.

BU	Mode			
0	Normal mode			
1	Power-saving mode. $\left(\begin{array}{c} In \ RC \ oscillator \ operating \ mode \ (OC = 0), \ the \ OSC \ pin \ oscillator \ is \ stopped, \ and \ in \ external \ clock \ operating \ mode \ (OC = 1), \ acceptance \ of \ the \ external \ clock \ is \ stopped. \ In \ this \ mode \ the \ common \ and \ segment \ output \ pins \ go \ to \ the \ V_{SS} \ levels. \ However, \ S1/P1 \ to \ S4/P4 \ output \ pins \ that \ are \ set \ to \ be \ general-purpose \ output \ ports \ by \ the \ control \ data \ P0 \ to \ P2 \ can \ be \ used \ as \ general-purpose \ output \ ports. \ $			

Display Data and Output Pin Correspondence

Output pin	COM1	Output pin	COM1
S1/P1	D1	S21	D21
S2/P2	D2	S22	D22
S3/P3	D3	S23	D23
S4/P4	D4	S24	D24
S5	D5	S25	D25
S6	D6	S26	D26
S7	D7	S27	D27
S8	D8	S28	D28
S9	D9	S29	D29
S10	D10	S30	D30
S11	D11	S31	D31
S12	D12	S32	D32
S13	D13	S33	D33
S14	D14	S34	D34
S15	D15	S35	D35
S16	D16	S36	D36
S17	D17	S37	D37
S18	D18	S38	D38
S19	D19	S39	D39
S20	D20	S40	D40

Output pin	COM1
S41	D41
S42	D42
S43	D43
S44	D44
S45	D45
S46	D46
S47	D47
S48	D48
S49	D49
S50	D50
S51	D51
S52	D52
S53	D53
S54	D54

Note 1: This applies to the case where the S1/P1 to S4/P4 output pins are set to be segment output ports. Note 2: The S24 output pin outputs a low level (VSS level) when in 822 mode data transfer.

For example, the table below lists the output states for the S21 output pin.

Display data		
D21	Output pin (S21) state	
0	The LCD segment corresponding to COM1 is off	
1	The LCD segment corresponding to COM1 is on	

(2)1/2 duty drive mode

Output pin	COM1	COM2	Output pin	COM1	COM2
S1/P1	D1	D2	S21	D41	D42
S2/P2	D3	D4	S22	D43	D44
S3/P3	D5	D6	S23	D45	D46
S4/P4	D7	D8	S24	D47	D48
S5	D9	D10	S25	D49	D50
S6	D11	D12	S26	D51	D52
S7	D13	D14	S27	D53	D54
S8	D15	D16	S28	D55	D56
S9	D17	D18	S29	D57	D58
S10	D19	D20	S30	D59	D60
S11	D21	D22	S31	D61	D62
S12	D23	D24	S32	D63	D64
S13	D25	D26	S33	D65	D66
S14	D27	D28	S34	D67	D68
S15	D29	D30	S35	D69	D70
S16	D31	D32	S36	D71	D72
S17	D33	D34	S37	D73	D74
S18	D35	D36	S38	D75	D76
S19	D37	D38	S39	D77	D78
S20	D39	D40	S40	D79	D80

Output pin	COM1	COM2
S41	D81	D82
S42	D83	D84
S43	D85	D86
S44	D87	D88
S45	D89	D90
S46	D91	D92
S47	D93	D94
S48	D95	D96
S49	D97	D98
S50	D99	D100
S51	D101	D102
S52	D103	D104
S53	D105	D106
S54	D107	D108

Note 1: Applies when the S1/P1 to S4/P4 output pins are to their segment output function.

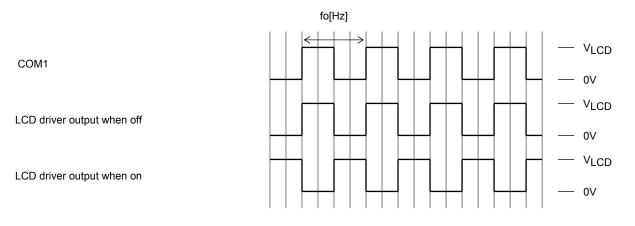
Note 2: The S24 output pin outputs a low level (VSS level) when in 822 mode data transfer.

Note 3: The S54 output pin outputs an all-segment-on waveform when in 822 mode data transfer.

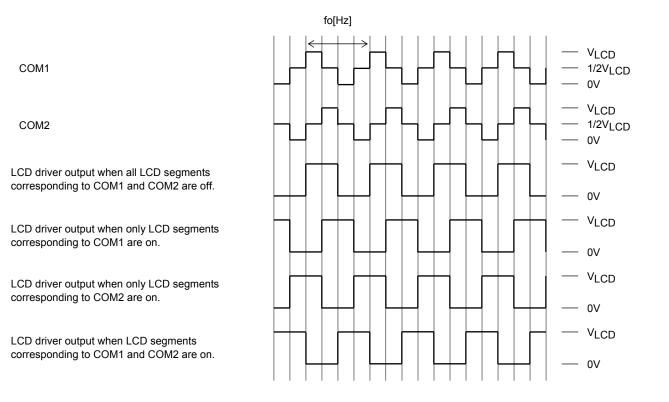
For example, the table below lists the output states for the S21 output pin.

Display data		Output nin (201) state	
D41	D42	Output pin (S21) state	
0	0	The LCD segments corresponding to COM1 and COM2 are off	
0	1	The LCD segment corresponding to COM2 is on	
1	0	The LCD segment corresponding to COM1 is on	
1	1	The LCD segments corresponding to COM1 and COM2 are on	

Output Waveforms (Static drive mode)



Output Waveforms (1/2 duty, 1/2 bias drive mode)



Control data			
FC0	FC1	FC2	Frame frequency fo [Hz]
1	1	0	fosc/768, f _{CK} /768
1	1	1	fosc/576, f _{CK} /576
0	0	0	fosc/384, f _{CK} /384
0	0	1	fosc/288, f _{CK} /288
0	1	0	fosc/192, f _{CK} /192

Display Control and the INH Pin

Since the IC's internal data (the display data D1 to D54 and the control data when in static drive mode, and the display data D1 to D108 and the control data when in 1/2 duty drive mode) is undefined when power is first applied, applications should set the \overline{INH} pin low at the same time as power is applied to turn off the display (setting S1/P1 to S4/P4 and S5 to S54, COM1, and COM2 to the VSS level) and during this period send serial data from the controller. The controller should then set the \overline{INH} pin high after the data transfer has completed. This procedure prevents unnecessary display at power on (See Figures 4 to 7).

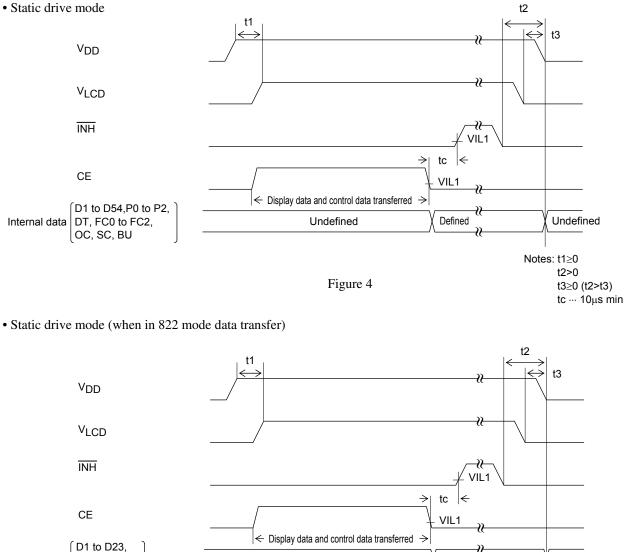
Notes on the Power On/Off Sequences

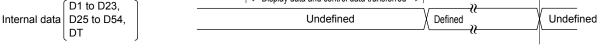
Applications should observe the following sequence when turning the LC75832E and LC75832W power on and off. (See Figures 4 to 7):

• At power on: Logic block power supply (V_{DD}) on \rightarrow LCD driver block power supply (V_{LCD}) on

• At power off: LCD driver block power supply (V_{LCD}) off \rightarrow Logic block power supply (V_{DD}) off

However, if the logic and LCD driver block use a shared power supply, then power supplies can be turned on and off at the same time.

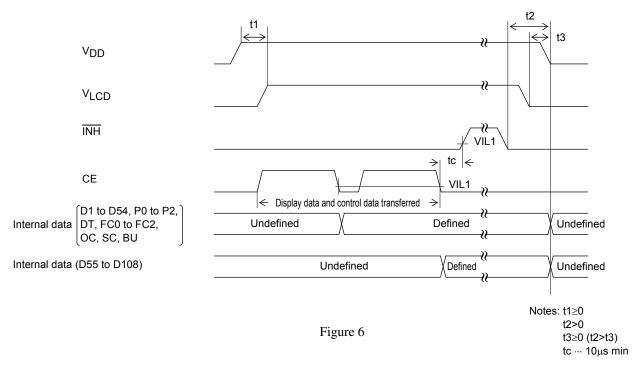




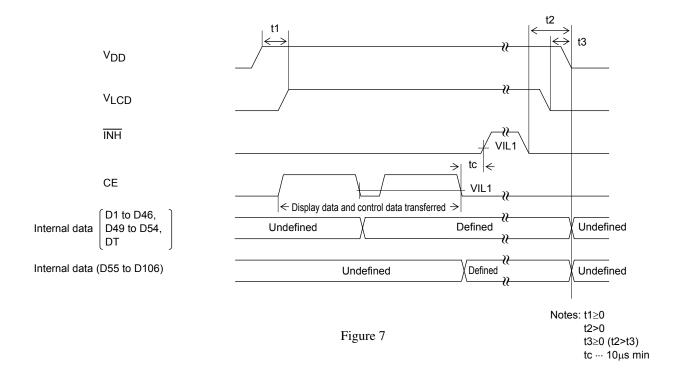
Notes: t1≥0 t2>0 t3≥0 (t2>t3) tc ··· 10µs min

Figure 5

• 1/2 duty drive mode



1/2 duty drive mode (when in 822 mode data transfer)

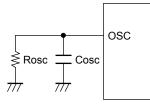


Notes on Controller Transfer of Display Data

Since the LC75832E/W transfer the display data (D1 to D108) in two separate transfer operations in 1/2 duty drive mode, we recommend that applications make a point of completing all of the display data transfer within a period of less than 30 ms to prevent observable degradation of display quality.

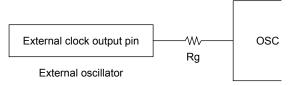
OSC Pin Peripheral Circuit

RC oscillator operating mode (control data OC = 0)
 An external resistor, Rosc, and an external capacitor, Cosc, must be connected between the OSC pin and GND if RC oscillator operating mode is selected.



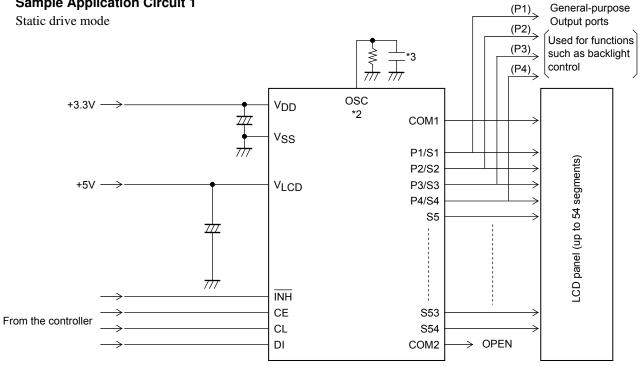
(2) External clock operating mode (control data OC = 1)

When the external clock operating mode is selected, insert a current protection resistor Rg (4.7 to 47 k Ω) between the OSC pin and external clock output pin (external oscillator). Determine the value of the resistance according to the allowable current value at the external clock output pin. Also make sure that the waveform of the external clock is not heavily distorted.

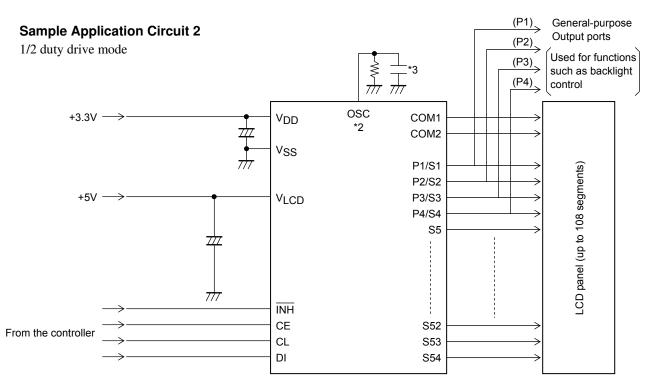


Note: Allowable current value at external clock output pin > $\frac{V_{DD}}{Rg}$

Sample Application Circuit 1



- *2: In RC oscillator operating mode, an external resistor, Rosc, and an external capacitor, Cosc, must be connected between the OSC pin and ground. If external clock operating mode is selected, a current protection resistor, Rg (4.7 to 47 k Ω), must be inserted between the external clock output pin (on the external oscillator) and the OSC pin. (See the "OSC Pin Peripheral Circuit" section.)
- *3: When a capacitor except the recommended external capacitance (Cosc = 1000 pF) is connected to the OSC pin, it should be in the range 220 to 2200 pF.



- *2: In RC oscillator operating mode, an external resistor, Rosc, and an external capacitor, Cosc, must be connected between the OSC pin and ground. If external clock operating mode is selected, a current protection resistor, Rg (4.7 to 47 k Ω), must be inserted between the external clock output pin (on the external oscillator) and the OSC pin. (See the "OSC Pin Peripheral Circuit" section.)
- *3: When a capacitor except the recommended external capacitance (Cosc = 1000 pF) is connected to the OSC pin, it should be in the range 220 to 2200 pF.

ORDERING INFORMATION

Device	Package	Shipping (Qty / Packing)
LC75832E-E	PQFP64 14x14 / QIP64E (Pb-Free)	300 / Tray Foam
LC75832EH-E	PQFP64 14x14 / QIP64E (Pb-Free)	300 / Tray Foam
LC75832ES-E	PQFP64 14x14 / QIP64E (Pb-Free)	300 / Tray Foam
LC75832W-E	SPQFP64 10x10 / SQFP64 (Pb-Free)	800 / Tray JEDEC
LC75832W-TBM-E	SPQFP64 10x10 / SQFP64 (Pb-Free)	1000 / Tape & Reel
LC75832WH-E	SPQFP64 10x10 / SQFP64 (Pb-Free)	800 / Tray JEDEC
LC75832WS-E	SPQFP64 10x10 / SQFP64 (Pb-Free)	800 / Tray JEDEC
LC75832WS-TBM-E	SPQFP64 10x10 / SQFP64 (Pb-Free)	1000 / Tape & Reel

† For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D. http://www.onsemi.com/pub_link/Collateral/BRD8011-D.PDF

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