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LC88F52H0A

CMOS IC
FROM 512K byte, RAM 24K byte on-chip
16-bit 1-chip Microcontroller

ON Semiconductor®
http://onsemi.com

Overview

The LC88F52H0A is a 16-bit microcomputer that, centered around an Xstromy16 CPU, integrates on a single chip a number of hardware features such as 512K-byte flash ROM (onboard programmable), 24K-byte RAM, eight 16-bit timers, a base timer serving as a time-of-day clock,, a real time clock, two synchronous SIO interfaces with automatic transmission capability, two single master I^2C/synchronous SIO interface, a slave I^2C/synchronous SIO interface, four asynchronous SIO (UART) interfaces, a 16-channel 12-bit resolution AD converter, 8bit resolution DA converter, four multifrequency 12-bit PWM modules, a watchdog timer, a system clock frequency divider, a 59-source (32 modules) 14-vector interrupt feature, and on-chip debugger feature.

Features

■Xstromy16 CPU
- 4G-byte address space
- General-purpose registers: 16 bits × 16registers

■Flash ROM
- Capable of onboard programming with a wide range of voltage levels (3.0 to 5.5V).
- Block-erasable in 512 or 1K byte units.
- Data written in 2-byte units.
- 524288 × 8 bits

■RAM
- 24576 × 8 bits

* This product is licensed from Silicon Storage Technology, Inc. (USA).

■Minimum instruction cycle time (tCYC)
- 83.3 ns (12MHz) V_{DD} = 4.5 to 5.5V
- 107 ns (9.3MHz) V_{DD} = 3.0 to 5.5V
- 500 ns (2MHz) V_{DD} = 2.5 to 5.5V

■Ports
- Normal withstand voltage I/O ports
  Ports whose I/O direction can be designated in 1 bit units : 86 (P0n P1n, P2n, P3n, P4n, P5n, P6n, P7n, PAn PB0 to PB6, PC2, PD0 to PD5)
- Oscillation/normal withstand voltage I/O ports : 4 (PC0, PC1, PC3, PC4)
- Reset pins : 1 (RESB)
- TEST pins : 1 (TEST)
- Power pins : 8 (V_{SS}1 to 4, V_{DD}1 to 4)

■Timers
- Timer 0: 16-bit timer that supports PWM/toggle outputs
  1) 5-bit prescaler
  2) 8-bit PWM × 2, 8-bit timer + 8-bit PWM mode selectable
  3) Clock source selectable from system clock, OSC0, OSC1, and internal RC oscillator
- Timer 1: 16-bit timer with capture registers
  1) 5-bit prescaler
  2) May be divided into 2 channels of 8-bit timer
  3) Clock source selectable from system clock, OSC0, OSC1, and internal RC oscillator
- Timer 2: 16-bit timer with capture registers
  1) 4-bit prescaler
  2) May be divided into 2 channels of 8-bit timer
  3) Clock source selectable from system clock, OSC0, OSC1, and external events
- Timer 3: 16-bit timer that supports PWM/toggle outputs
  1) 8-bit prescaler
  2) 8-bit timer × 2ch or 8-bit timer + 8-bit PWM mode selectable
  3) Clock source selectable from system clock, OSC0, OSC1, and external events
- Timer 4: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 0
- Timer 5: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 0
- Timer 6: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 1
- Timer 7: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 1
  * Prescaler 0 and 1 are consisted of 4 bits and can choose their clock source from OSC0 or OSC1.
- Base timer
  1) Clock may be selected from OSC0 (32.768kHz crystal oscillator) and frequency-divided output of system clock.
  2) Interrupts can be generated in 7 timing schemes.

■Real time clock
1) Calender with Jan. 1, 2000 to Dec.31, 2799 including automatic leap year calculation function.
2) Consisted of Independent second- minute-hour-day-month-year-century counters.
3) Programmable count-clock calibration function.

■Serial interfaces

- SIO0: 8-bit synchronous SIO
  1) LSB first/MSB first mode selectable
  2) Supports data communication with a data length of 8 bits or less (1 to 8 bits specifiable)
  3) Built-in 8-bit baudrate generator (4 tCYC to 512 tCYC transfer clocks)
  4) Continuous/automatic data transmission (9- to 32768-bit units specifiable)
  5) Interval function (intervals specifiable in 0 to 64 tSCK units)
  6) Wakeup function
- SIO1: 8-bit synchronous SIO
  1) LSB first/MSB first mode selectable
  2) Supports data communication with a data length of 8 bits or less (1 to 8 bits specifiable)
  3) Built-in 8-bit baudrate generator (4 tCYC to 512 tCYC transfer clocks)
  4) Continuous/automatic data transmission (9- to 32768-bit units specifiable)
  5) Interval function (intervals specifiable in 0 to 64 tSCK units)
  6) Wakeup function
- SMIIC0: Single master I^2C/8-bit synchronous SIO
  Mode 0: Single-master mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
- SMIIC1: Single master I^2C/8-bit synchronous SIO
  Mode 0: Single-master mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
- SLIIC0: Slave I^2C/8-bit synchronous SIO
  Mode 0: I^2C slave mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
  Note: usable only with the external clock source
- UART0
  1) Data length : 8 bits (LSB first)
  2) Start bits : 1 bit
  3) Stop bits : 1 bit
  4) Parity bits : None/even parity/odd parity
  5) Transfer rate : 4/8 cycle
  6) Baudrate source clock: P07 input signal used as a 1 cycle signal (T0PWMH can be used as a clock source) or Timer 4 cycle.
  7) Full duplex communication
  Note: The “cycle” refers to one period of the baudrate clock source.
- UART2
  1) Data length : 8 bits (LSB first)
  2) Start bits : 1 bit
  3) Stop bits : 1/2 bit
  4) Parity bits : None/even parity/odd parity
  5) Transfer rate : 8 to 4096 cycle
  6) Baudrate source clock : System clock/OSC0/OSC1/P26 input signal
  7) Wakeup function
  8) Full duplex communication
  Note: The “cycle” refers to one period of the baudrate clock source.
- UART3
  1) Data length : 8 bits (LSB first)
  2) Start bits : 1 bit
  3) Stop bits : 1/2 bit
  4) Parity bits : None/even parity/odd parity
  5) Transfer rate : 8 to 4096 cycle
  6) Baudrate source clock: System clock/OSC0/OSC1/P36 input signal
  7) Wakeup function
  8) Full duplex communication
  Note: The “cycle” refers to one period of the baudrate clock source.

• UART4
1) Data length : 8 bits (LSB first)
2) Start bits : 1 bit
3) Stop bits : 1/2 bit
4) Parity bits : None/even parity/odd parity
5) Transfer rate : 8 to 4096 cycle
6) Baudrate source clock: System clock/OSC0/OSC1/P37 input signal
7) Wakeup function
8) Full duplex communication
Note: The "cycle" refers to one period of the baudrate clock source.

■AD converter
1) 12/8 bits resolution selectable
2) Analog input: 16 channels
3) Comparator mode
4) Automatic reference voltage generation

■DA converter
1) 8 bits resolution
2) 2 converters built-in
3) Able to choose output pins

■PWM
• PWM0: Multifrequency 12-bit PWM × 2 channels (PWM00 and PWM01)
1) 2-channel pairs controlled independently of one another
2) Clock source selectable from system clock or OSC1
3) 8-bit prescaler: TPWMR0=(prescaler value + 1) × clock period
4) 8-bit fundamental wave PWM generator circuit + 4-bit additional pulse generator circuit
5) Fundamental wave PWM mode
Fundamental wave period: 16 TPWMR0 to 256 TPWMR0
High pulse width : 0 to (Fundamental wave period - TPWMR0)
6) Fundamental wave + additional pulse mode
Fundamental wave period: 16 TPWMR0 to 256 TPWMR0
Overall period : Fundamental wave period × 16
High pulse width : 0 to (Fundamental wave period - TPWMR0)
• PWM1: Multifrequency 12-bit PWM × 2 channels (PWM10 and PWM11)
1) 2-channel pairs controlled independently of one another
2) Clock source selectable from system clock or OSC1
3) 8-bit prescaler: TPWMR1=(prescaler value + 1) × clock period
4) 8-bit fundamental wave PWM generator circuit + 4-bit additional pulse generator circuit
5) Fundamental wave PWM mode
Fundamental wave period: 16 TPWMR1 to 256 TPWMR1
High pulse width : 0 to (Fundamental wave period - TPWMR1)
6) Fundamental wave + additional pulse mode
Fundamental wave period: 16 TPWMR1 to 256 TPWMR1
Overall period : Fundamental wave period × 16
High pulse width : 0 to(Fundamental wave period - TPWMR1)

■Watchdog timer
1) Driven by the base timer + internal watchdog timer dedicated counter
2) Interrupt or reset mode selectable

■Interrupts (peripheral function)

- 59 sources (32 modules), 14 vector addresses

1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.

2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Interrupt Source
1	08000H	Watchdog timer (1)
2	08004H	Base timer (2)
3	08008H	Timer 0 (2)
4	0800CH	INT0 (1)
5	08014H	INT1 (1)
6	08018H	INT2 (1)/timer 1 (2)/UART2 (4)
7	0801CH	INT3 (1)/timer 2 (4)/SMIIC0 (1)/SLIIC1 (1)
8	08020H	INT4 (1)/timer 3 (2)
9	08024H	INT5 (1)/timer 4 (1)/SIO1 (2)
10	0802CH	PWM0 (1)/SMIIC1(1)
11	08030H	ADC (1)/timer 5 (1)
12	08034H	INT6 (1)/timer 6 (1)/UART 3 (4)
13	08038H	INT7 (1)/SIO0 (2)/SIO0(2)/USRT4 (4)
14	0803CH	Port 0 (3)/Port 5 (8)/RTC (1)

- 3 priority levels selectable.
- Of interrupts of the same level, the one with the smallest vector address takes precedence.
- A number enclosed in parentheses denotes the number of sources.

■Subroutine Stack: 24K-byte RAM area

- Subroutine calls that automatically save PSW, interrupt vector calls: 6 bytes
- Subroutine calls that do not automatically save PSW: 4 bytes

■Multiplication/division instructions

- 16 bits × 16 bits (18 tCYC execution time)
- 16 bits ÷ 16 bits (18 to 19 tCYC execution time)
- 32 bits ÷ 16 bits (18 to 19 tCYC execution time)

■Oscillator circuits

- RC oscillator circuit (internal): For system clock
- CF oscillator circuit (built-in Rf circuit): For system clock (OSC1)
- VCO oscillator circuit: For system clock (OSC1)
- Crystal oscillator circuit (built-in Rf circuit): For low-speed system clock (OSC0)
- SLRC oscillator circuit (internal): For system clock (In the case of exception processing)

■System clock divider function

- Can run on low current.
- 1/1 to 1/128 of the system clock frequency can be set.

■Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
  1) Oscillation is not halted automatically.
  2) Released by a system reset or occurrence of an interrupt.
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
  1) OSC1, RC and OSC0 oscillators automatically stop.
  2) There are the six ways of releasing the HOLD mode.
    (1) Setting the reset pin to the low level
    (2) Setting at least one of the INT0, INT1, INT2, INT4, INT5, INT6, and INT7 pins to the specified level
    (3) Having an interrupt source established at port 0
    (4) Having an interrupt source established at port 5
    (5) Having an interrupt established at SIO0 or SIO1
    (6) Having an interrupt established at UART2, UART3 or UART4
- HOLDX mode: Suspends instruction execution and the operation of the peripheral circuits except those which run on OSC0.
  1) OSC1 and RC oscillations automatically stop.
  2) OSC0 maintains the state that is established when the HOLDX mode is entered.
  3) There are seven ways of releasing the HOLDX mode.
    (1) Setting the reset pin to the low level
    (2) Setting at least one of the INT0, INT1, INT2, INT4, INT5, INT6, and INT7 pins to the specified level
    (3) Having an interrupt source established at port 0
    (4) Having an interrupt source established at port 5
    (5) Having an interrupt source established at the base timer circuit
    (6) Having an interrupt established at SIO0 or SIO1
    (7) Having an interrupt established at UART2, UART3 or UATR4
    .

■On-chip debugger function

- Supports software debugging with the IC mounted on the target board.
- Supports source line debugging and tracing functions, and breakpoint setting and real time display.
- Single-wire communication

■Package Form

- TQFP100(14×14): Lead-free and halogen-free type

■Development Tools

- On-chip debugger: EOCUIF1 + LC88F52H0A

■Programming board

Package	Programming Board
TQFP100 (14 × 14)	W88F52TQ

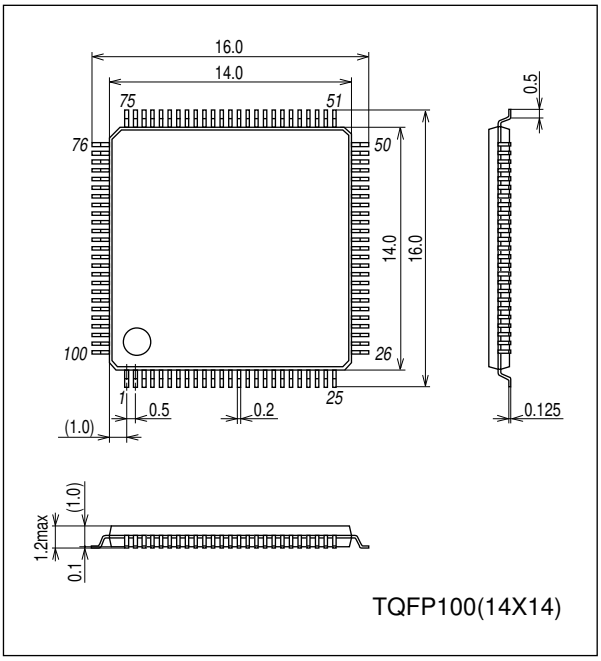
■Flash Programming

Manufacturer	Model Name	Supported Version	Device
Flash Support Group (single)	AF9708/09/09B/09C	Revision: After Rev.03.32D	88F512SN
Flash Support Group (Gang)	AF9723/23B		
	AF9833		
Our company	SKK/SKK Type-B	Application Version After 1.06 Chip Data Version After 2.22	LC88F52H0A

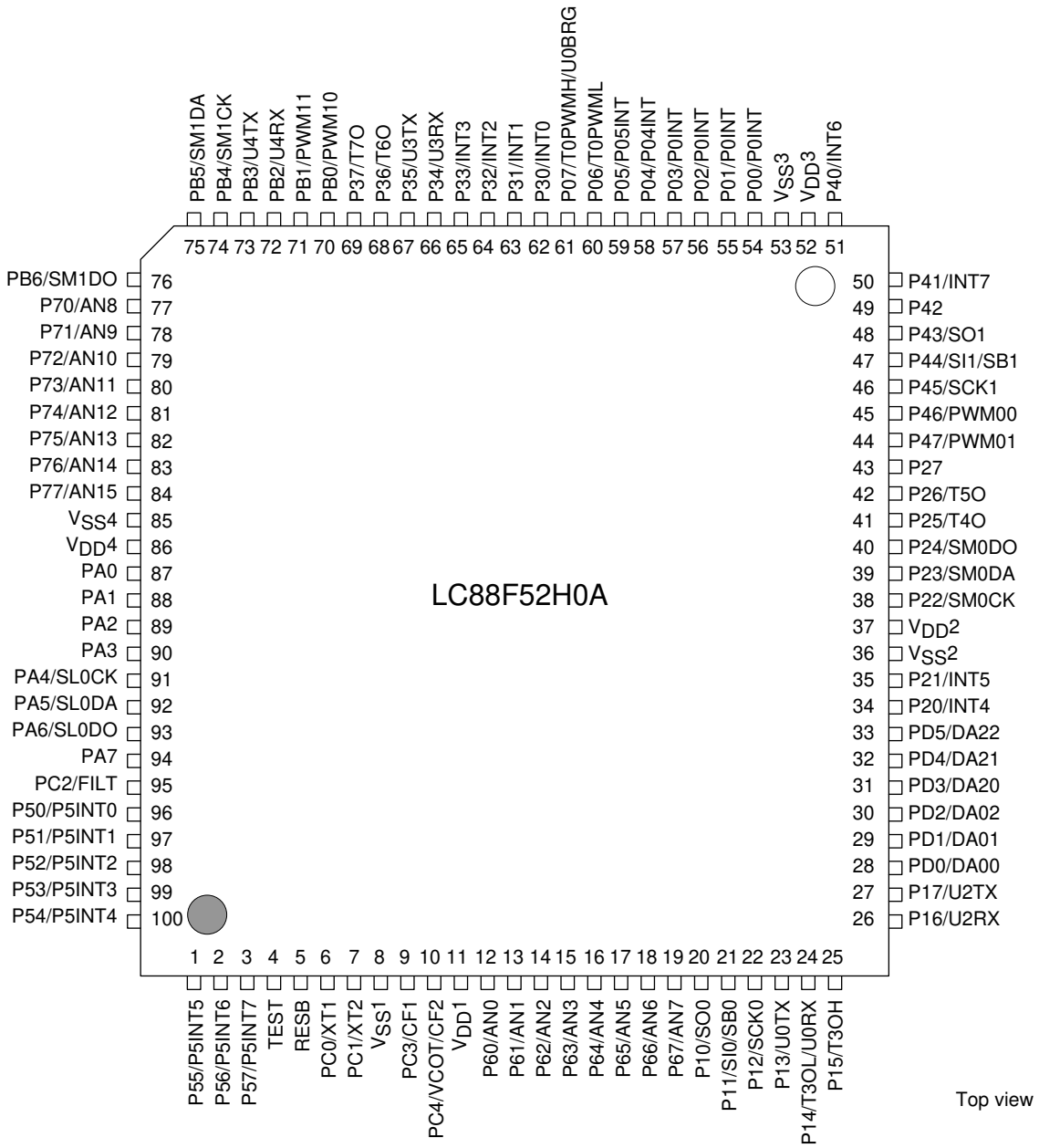
Package Dimensions

unit : mm (typ)

3274

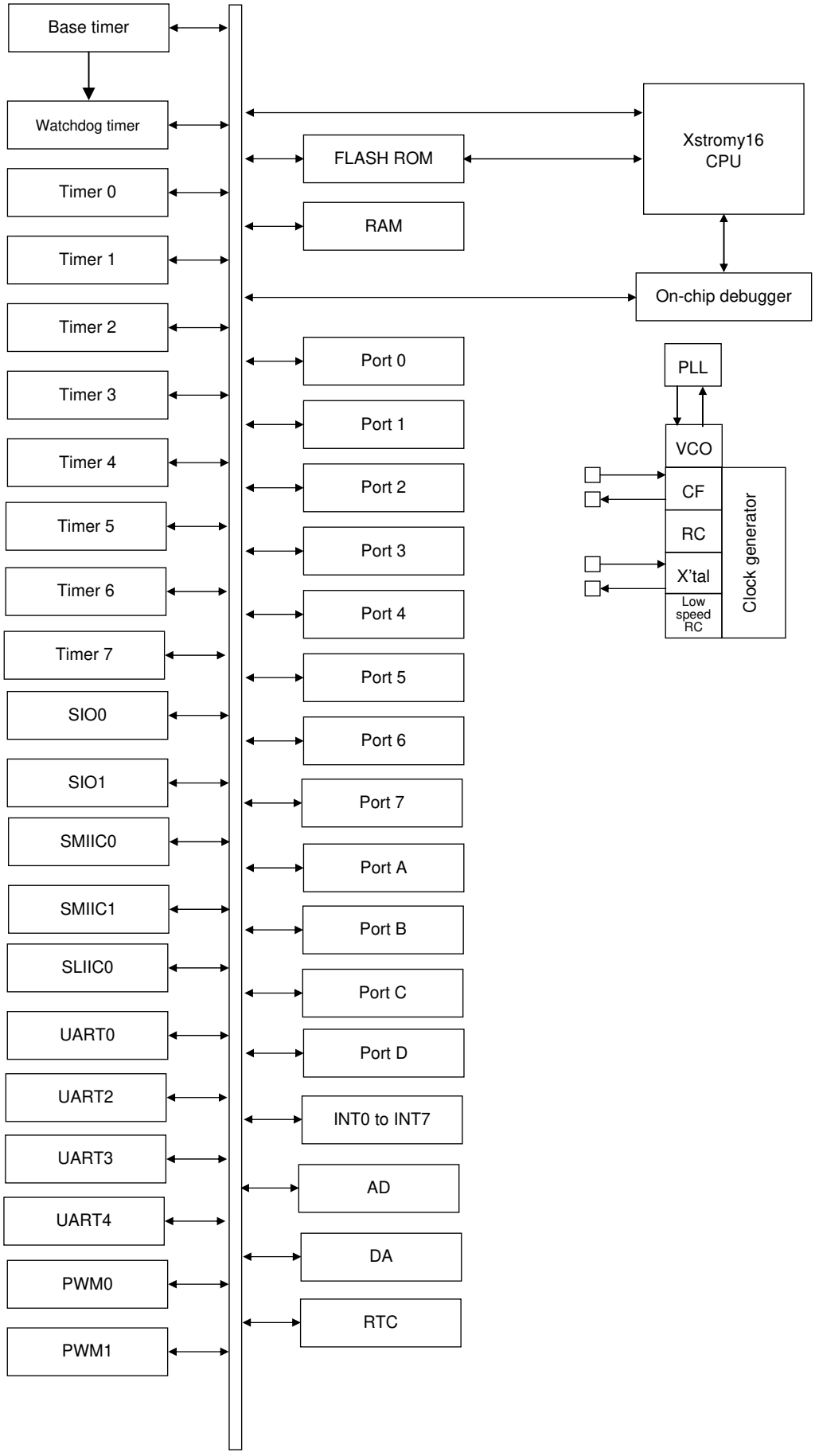


Pin Assignment



TQFP100 (14×14) (Lead-free and halogen-free type)

System Block Diagram



Pin Description

Pin Name	I/O	Description
$V_{SS}1$, $V_{SS}2$, $V_{SS}3$, $V_{SS}4$	-	- Power sources
$V_{DD}1$, $V_{DD}2$, $V_{DD}3$, $V_{DD}4$	-	+ Power sources
Port 0 P00 to P07	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • HOLD release input (P00 to P03, P04, P05) • Port 0 interrupt input (P00 to P03, P04, P05) • Pin functions P06: Timer 0L output P07: Timer 0L output/UART0 clock input
Port 1 P10 to P17	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions P10: SIO0 data output P11: SIO0 data input/pulse input/output P12: SIO0 clock input/output P13: UART0 transmit P14: Timer 3L output/UART0 receive P15: Timer 3H output P16: UART2 receive P17: UART2 transmit
Port 2 P20 to P27	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions P20: INT4 input/HOLD release input/timer 3 event input/timer 2L capture input/timer 2H capture input P21: INT5 input/HOLD release input/timer 3 event input/timer 2L capture input/timer 2H capture input P22: SMIIC0 clock input/output P23: SMIIC0 bus input/output/data input P24: SMIIC0 data output (used in 3-wire SIO mode) P25: Timer 4 output P26: Timer 5 output Interrupt acknowledge type INT4, INT5: H level, L level, H edge, L edge, both edges
Port 3 P30 to P37	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions P30: INT0 input/HOLD release/timer 2L capture input P31: INT1 input/HOLD release/timer 2H capture input P32: INT2 input/HOLD release/timer 2 event input/timer 2L capture input P33: INT3 input/HOLD release/timer 2 event input/timer 2H capture input P34: UART3 receive P35: UART3 transmit P36: Timer 6 output P37: Timer 7 output Interrupt acknowledge type INT0 to INT3: H level, L level, H edge, L edge, both edges

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Pin Name	I/O	Description
Port 4 P40 to P47	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions P40: INT6 input/HOLD release input P41: INT7 input/HOLD release input P43: SIO1 data output P44: SIO1 data input/bus input/output P45: SIO1 clock input/output P46: PWM00 output P47: PWM01 output Interrupt acknowledge type INT6, INT7: H level, L level, H edge, L edge, both edges
Port 6 P60 to P67	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions AN0 (P60) to AN7 (P67): AD converter input port
Port 7 P70 to P77	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions AN8 (P70) to AN15 (P77): AD converter input port
Port A PA0 to PA7	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Multiplexed pin functions PA4: SLIIC0 clock input PA5: SLIIC0 bus input/output/data input PA6: SLIIC0 data output (used in 3-wire SIO mode)
Port B PB0 to PB6	I/O	• 7-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Multiplexed pin functions PB0: PWM10 output PB1: PWM11 output PB2: UART4 receive PB3: UART4 transmit PB4: SMIIC1 clock input/output PB5: SMIIC1 bus input/output/data input PB6: SMIIC1 data output (used in 3-wire SIO mode)
Port C PC0 to PC4	I/O	• 5-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units (PC2) • Pin functions PC0: 32.768 kHz crystal oscillator input PC1: 32.768 kHz crystal oscillator output PC2: FILT PC3: Ceramic oscillator input PC4: Ceramic oscillator output/VCO output
Port D PD0 to PD5	I/O	• 6-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Multiplexed pin functions PD0: DA00 output PD1: DA01 output PD2: DA02 output PD3: DA10 output PD4: DA11 output PD5: DA12 output
TEST	I/O	• TEST pin • Used to communicate with on-chip debugger. • Connects an external 100kΩ pull-down resistor.
RESB	I	Reset pin

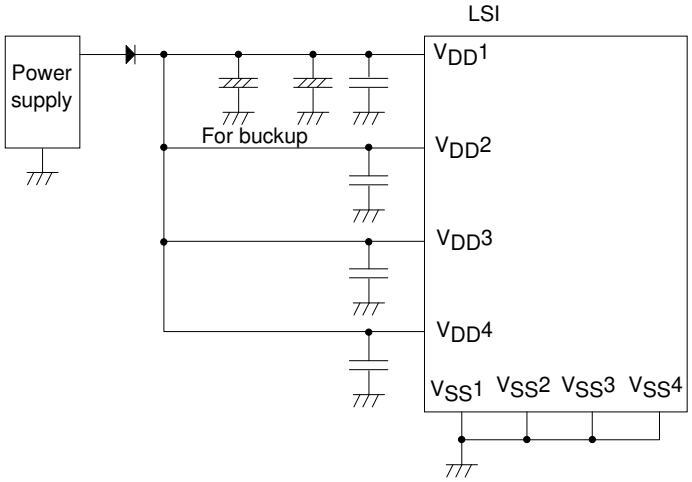
Port Output Types

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.
Data can be read into any input port even if it is in the output mode.

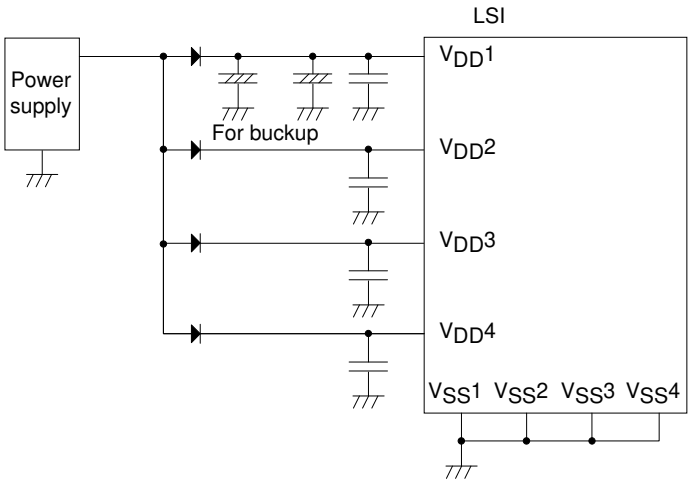
Port Name	Option Selected in Units of	Output Type	Pull-up Resistor
P00 to P07	1 bit	CMOS	Programmable
P10 to P17 P20 to P27 P30 to P37 P40 to P47 P50 to P57 P60 to P67 P70 to P77 PA0 to PA7 PB0 to PB6		Able to program special functions' output type from CMOS output or N-channel open drain	
P60 to P67 P70 to p77 PD0 to PD5 PC2		CMOS	
PC0	-	N-channel open drain (32.768kHz crystal oscillator input)	None
PC1	-	N-channel open drain (32.768kHz crystal oscillator output)	None
PC3	-	CMOS (ceramic oscillator input)	None
PC4	-	CMOS (ceramic oscillator output)	None

* Make the following connection to minimize the noise input to the $V_{DD}1$ pin and prolong the backup time.
  Be sure to electrically short the $V_{SS}1$, $V_{SS}2$, $V_{SS}3$ and VSS4 pins.

Example 1: When data is being backed up in the HOLD mode, the H level signals to the output ports are fed by the backup capacitors.



Example 2: When data is being backed up in the HOLD mode, the H level output at any ports is not sustained and is unpredictable.



Absolute Maximum Ratings at Ta = 25°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter		Symbol	Applicable Pin /Remarks	Conditions		Specification			
					V_{DD}[V]	min	typ	max	unit
Maximum supply voltage		V_{DD} max	$V_{DD}1$, $V_{DD}2$, $V_{DD}3$, $V_{DD}4$	$V_{DD}1=V_{DD}2=V_{DD}3=V_{DD}4$		-0.3		+6.5	V
Input voltage		V_I(1)	RESB			-0.3		V_{DD} +0.3	
Input/output voltage		V_{IO}(1)	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D			-0.3		V_{DD} +0.3	
High level output current	Peak output current	IOPH(1)	Ports 0, 1, 2, 3 P40 to P45 Ports 7, A, D PB2 to PB6	CMOS output selected Per applicable pin		-10			mA
		IOPH(2)	P46, P47 PB0, PB1	Per applicable pin		-20			
		IOPH(3)	Port 5, 6 PC0 to PC4	Per applicable pin		-5			
	Average output current (Note 1-1)	IOMH(1)	Ports 0, 1, 2, 3 P40 to P45 Ports 5, 6, 7, A PB2 to PB6 Ports D	CMOS output selected Per applicable pin		-7.5			
		IOMH(2)	P46, P47 PB0, PB1	Per applicable pin		-10			
		IOMH(3)	Port 5, 6 PC0 to PC4	Per applicable pin		-3			
	Total output current	ΣIOAH(1)	Pprts 5 PC0 to PC4	Total of currents at applicable pins		-15			
		ΣIOAH(2)	Port 6	Total of currents at applicable pins		-15			
		ΣIOAH(3)	Port 5, 6 PC0 to PC4	Total of currents at applicable pins		-20			
		ΣIOAH(4)	Ports 1,D1 P20 to P21	Total of currents at applicable pins		-25			
		ΣIOAH(5)	P22 to P27	Total of currents at applicable pins		-25			
		ΣIOAH(6)	Ports 1, 2, D	Total of currents at applicable pins		-45			
		ΣIOAH(7)	Ports 4	Total of currents at applicable pins		-25			
		ΣIOAH(8)	Ports 0, 3	Total of currents at applicable pins		-25			
		ΣIOAH(9)	Ports 0, 3, 4	Total of currents at applicable pins		-45			
		ΣIOAH(10)	Ports B, 7	Total of currents at applicable pins		-25			
		ΣIOAH(11)	Ports A	Total of currents at applicable pins		-25			
		ΣIOAH(12)	Ports 7, A, B	Total of currents at applicable pins		-45			

Note 1-1: Average output current refers to the average of output currents measured for a period of 100ms.

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Parameter		Symbol	Applicable Pin /Remarks	Conditions	Specification				
					V_{DD}[V]	min	typ	max	unit
Low level output current	Peak output current	IOPL(1)	Ports 0, 1, 3, 4 Ports 7, A, B P20, P21, P24 to P27 PA0 to PA4, PA6, PA7 PB0 to PB4, PB6, PB7	Per applicable pin				20	mA
		IOPL(2)	P22, P23 PA4, PA5 PB4, PB5	Per applicable pin				25	
		IOPL(3)	Ports 5, 6 PC0 to PC4	Per applicable pin				10	
	Average output current (Note 1-1)	IOML(1)	Ports 0, 1, 3, 4 Ports 7, A, B P20, P21, P24 to P27 PA0 to PA4, PA6, PA7 PB0 to PB4, PB6, PB7	Per applicable pin				15	
		IOML(2)	P22, P23 PA4, PA5 PB4, PB5	Per applicable pin				20	
		IOML(3)	Ports 5, 6 PC0 to PC4	Per applicable pin				7.5	
	Total output current	ΣIOAL(1)	Ports 5 PC0 to PC2	Total of currents at applicable pins				15	
		ΣIOAL(2)	Port 6 PC3 to PC4	Total of currents at applicable pins				15	
		ΣIOAL(3)	Port 5, 6 PC0 to PC4	Total of currents at applicable pins				20	
		ΣIOAL(4)	Ports 1, D P20, P21	Total of currents at applicable pins				45	
		ΣIOAL(5)	P22 to P27	Total of currents at applicable pins				45	
		ΣIOAL(6)	Ports 1, 2, D	Total of currents at applicable pins				80	
		ΣIOAL(7)	Port 4	Total of currents at applicable pins				45	
		ΣIOAL(8)	Port 0, 3	Total of currents at applicable pins				45	
		ΣIOAL(9)	Port 0, 3, 4	Total of currents at applicable pins				80	
		ΣIOAL(10)	Port 7, B	Total of currents at applicable pins				45	
		ΣIOAL(11)	Port A	Total of currents at applicable pins				45	
		ΣIOAL(12)	Port 7, A, B	Total of currents at applicable pins				80	
Allowable power dissipation		Pd max	TQFP100(14×14)	Ta=-40 to +85°C				250	mW
Operating ambient temperature		Topr				-40		+85	°C
Storage ambient temperature		Tstg				-55		+125	

Note 1-1: Average output current refers to the average of output currents measured for a period of 100ms.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Allowable Operating Conditions at Ta = -40°C to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Operating supply voltage (Note 2-1)	$V_{DD}(1)$	$V_{DD}1=V_{DD}2=V_{DD}3$	0.081µs≤tCYC≤66µs		4.0		5.5	V
			0.103µs≤tCYC≤66µs		3.0		5.5	
			0.490µs≤tCYC≤66µs		2.5		5.5	
Memory sustaining supply voltage	VHD	$V_{DD}1=V_{DD}2=V_{DD}3$	RAM and register contents sustained in HOLD mode		2.0		5.5	
High level input voltage	$V_{IH}(1)$	Ports 0, 1, 2, 3, 4 Port 5, A, B		2.5 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	
	$V_{IH}(2)$	Ports 6, 7, PC2		2.5 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	
	$V_{IH}(3)$	RESB PC0, PC1, PC3, PC4		2.5 to 5.5	$0.75V_{DD}$		V_{DD}	
	$V_{IH}(4)$	P22, P23, PA4, PA5, PB4, PB5 I^2C side		2.5 to 5.5	$0.7V_{DD}$		V_{DD}	
Low level input voltage	$V_{IL}(1)$	When ports 1, 2, 3, 4, 5, A and port B, PnFSAn=0 Ports 0, 6, 7, PC2		4.0 to 5.5	V_{SS}		$0.1V_{DD}$ +0.4	
	$V_{IL}(2)$			2.5 to 4.0	V_{SS}		$0.2V_{DD}$	
	$V_{IL}(3)$	When ports 1, 2, 3, 4, 5, A and port B, PnFSAn=1		4.0 to 5.5	V_{SS}		$0.15V_{DD}$ +0.4	
	$V_{IL}(4)$			2.5 to 4.0	V_{SS}		$0.2V_{DD}$	
	$V_{IL}(5)$	CF1, RESB PC0, PC1, PC3, PC4		2.5 to 5.5	V_{SS}		$0.25V_{DD}$	
	$V_{IL}(6)$	P22, P23, PA4, PA5, PB4, PB5 I^2C side		2.5 to 5.5	V_{SS}		$0.3V_{DD}$	
Instruction cycle time (Note 2-2)	tCYC			4.5 to 5.5	0.081		66	µs
				2.8 to 5.5	0.122		66	
				2.5 to 5.5	0.490		66	
External system clock frequency	FEXCF(1)	CF1	• CF2 pin open • System clock frequency division ratio=1/1 • External system clock DUTY50±5%	4.5 to 5.5	0.1		12	MHz
				3.0 to 5.5	0.1		8.3	
				2.5 to 5.5	0.1		2	
			• CF2 pin open • System clock frequency division ratio=1/2	4.5 to 5.5	0.2		24	
				3.0 to 5.5	0.2		18.6	
				2.5 to 5.5	0.2		4	

Note 2-1: V_{DD}≥3.0V must be maintained when making onboard programming into flash ROM.

Note 2-2: Relationship between tCYC and oscillation frequency is 1/FmCF when frequency division ratio is 1/1 and 2/FmCF when the ratio is 1/2.

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Parameter	Symbol	Applicable Pin /Remarks	Conditions		Specification			
				V_{DD}[V]	min	typ	max	unit
Oscillation frequency range (Note 2-3)	FmCF(1)	PC3 (CF1), PC4 (CF2)	12MHz ceramic oscillator mode See Fig. 1.	4.5 to 5.5		12		MHz
	FmCF(2)	PC3(CF1), PC4(CF2)	8MHz ceramic oscillator mode See Fig. 1.	3.0 to 5.5		8		
	FmCF(3)	PC3(CF1), PC4(CF2)	4MHz ceramic oscillator mode See Fig. 1.	2.5 to 5.5		4		
	FmRC		Internal RC oscillation	2.5 to 5.5	0.5	1.0	2.0	
	FmSLRC		Internal low-speed RC oscillation	2.5 to 5.5	18	30	45	kHz
	FsX'tal	XT1, XT2	32.768kHz crystal oscillator mode See Fig. 2.	2.5 to 5.5		32.768		
	FmVCO(1)		VCO oscillator When setting VC3=1 When SELDIV=0 or 1 See Fig. 9.	2.5 to 3.8	5.0		9.0	MHz
	FmVCO(2)		VCO oscillator When setting VC3=0 When SELDIV=2 or 3 See Fig. 9.	2.5 to 3.8	5.0		12	
	FmVCO(3)		VCO oscillator When setting VC3=1 When SELDIV=0 or 1 See Fig. 9.	3.6 to 5.5	5.0		9.0	
	FmVCO(4)		VCO oscillator When setting VC3=0 When SELDIV=2 or 3 See Fig. 9.	3.6 to 5.5	9.0		12	
	FmVCO(5)		VCO oscillator When OSC0=32.768KHz SELDIV setting range=0 to 3 SELDLY setting range=0 to 3	2.5 to 5.5		Note 2-4		

Note 2-3: See Tables 1 and 2 for oscillator constant values.

Note 2-4: VCO oscillation frequency = 0.032768×(56×(SELDIV+3)+SELDLY)

Electrical Characteristics at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable/ Remarks	Conditions		Specification			
				V_{DD}[V]	min	typ	max	unit
High level input current	I_{IH}(1)	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D RESB	Output disabled Pull-up resistor off $V_{IN}=V_{DD}$ (Including output Tr. off leakage current)	2.5 to 5.5			1	μA
Low level input current	I_{IL}(1)	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D RESB	Output disabled Pull-up resistor off $V_{IN}=V_{SS}$ (Including output Tr. off leakage current)	2.5 to 5.5	-1			
High level output voltage	V_{OH}(1)	Ports 0, 1, 2, 3 Ports 4, A, D P40 to P45 PB2 to PB6	I_{OH}=-1.0mA	4.5 to 5.5	V_{DD}-1			V
	V_{OH}(2)		I_{OH}=-0.4mA	3.0 to 5.5	V_{DD}-0.4			
	V_{OH}(3)		I_{OH}=-0.2mA	2.5 to 5.5	V_{DD}-0.4			
	V_{OH}(4)	Port 5, 6 PC2	I_{OH}=-0.4mA	3.0 to 5.5	V_{DD}-0.4			
	V_{OH}(5)		I_{OH}=-0.2mA	2.5 to 5.5	V_{DD}-0.4			
	V_{OH}(6)	P46, P47 PB0, PB1	I_{OH}=-10mA	4.5 to 5.5	V_{DD}-1.5			
	V_{OH}(7)		I_{OH}=-1.6mA	3.0 to 5.5	V_{DD}-0.4			
	V_{OH}(8)		I_{OH}=-1.0mA	2.5 to 5.5	V_{DD}-0.4			
	V_{OH}(9)	PC0, PC1, PC3, PC4,	I_{OH}=-1.0mA	3.0 to 5.5	V_{DD}-0.4			
	V_{OH}(10)		I_{OH}=-0.4mA	2.5 to 5.5	V_{DD}-0.4			
Low level output voltage	V_{OL}(1)	Ports 0, 1, 3, 4 Ports 7, D P20 to P21, P24 to P27 PA0 to PA3 PA6 to PA7 PB0 to PB3, PB6	I_{OL}=10mA	4.5 to 5.5			1.5	
	V_{OL}(2)		I_{OL}=1.6mA	3.0 to 5.5			0.4	
	V_{OL}(3)		I_{OL}=1.0mA	2.5 to 5.5			0.4	
	V_{OL}(4)	P22, P23, PA4, PA5, PB4, PB5	I_{OL}=11mA	4.5 to 5.5			1.5	
	V_{OL}(5)		I_{OL}=3.0mA	3.0 to 5.5			0.4	
	V_{OL}(6)		I_{OL}=1.3mA	2.5 to 5.5			0.4	
	V_{OL}(7)	Ports 5, 6 PC2	I_{OL}=1.6mA	3.0 to 5.5			0.4	
	V_{OL}(8)		I_{OL}=1.0mA	2.5 to 5.5			0.4	
	V_{OL}(9)	PC0, PC1, PC3, PC4	I_{OL}=1.0mA	3.0 to 5.5			0.4	
	V_{OL}(10)		I_{OL}=0.4mA	2.5 to 5.5			0.4	
Pull-up resistor	Rpu(1)	Ports 0, 1, 2, 3 Ports 4, 5, 6, 7 Ports A, B, D, PC2	V_{OH}=0.9V_{DD}	4.5 to 5.5	15	35	80	kΩ
	Rpu(2)			2.5 to 4.5	18	55	150	
Hysteresis voltage	VHYS	RESB When ports 1, 2, 3, 4, A PnFSAn=1		2.5 to 5.5		0.1V_{DD}		V
Pin capacitance	CP	All pins	Pins other than that under test $V_{IN}=V_{SS}$ f=1MHz Ta=25°C	2.5 to 5.5		10		pF

Serial I/O Characteristics at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Serial I/O Characteristics (Wakeup Function Disabled) (Note 4-1-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Serial clock	Input clock	Period	tSCK(1)	SCK0(P12)	• See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(1)				2			
		High level pulse width	tSCKH(1)				2			
			tSCKHA(1)		• Automatic communication mode • See Fig. 6.		6			
			tSCKHBSY(1a)		• Automatic communication mode • See Fig. 6.		23			
			tSCKHBSY(1b)		• Mode other than automatic communication mode • See Fig. 6.		4			
	Output clock	Period	tSCK(2)	SCK0(P12)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(2)				1/2			tSCK
		High level pulse width	tSCKH(2)				1/2			
			tSCKHA(2)		• Automatic communication mode • CMOS output selected • See Fig. 6.		6			tCYC
			tSCKHBSY(2a)		• Automatic communication mode • CMOS output selected • See Fig. 6.		4		23	
			tSCKHBSY(2b)		• Mode other than automatic communication mode • See Fig. 6.		4			
Serial input	Data setup time		tsDI(1)	SI0(P11), SB0(P11)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(1)				0.03			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	• (Note 4-1-2)	2.5 to 5.5			1tCYC +0.05	
	Output clock		tdDO(2)		• (Note 4-1-2)				1tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

SIO0 Serial Input/Output Characteristics (Wakeup Function Enabled) (Note 4-2-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	Specification				
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(3)	SCK0 (P12)	• See Fig. 6.	2.5 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
			tSCKHBSY(3)				2			
Serial input	Data setup time		tsDI(2)	SI0 (P11), SB0 (P11)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(2)				0.03			
Serial output	Input clock	Output delay time	tdD0(3)	SO0 (P10), SB0 (P11)	• (Note 4-2-2)	2.5 to 5.5			1tCYC +0.05	

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-2-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig.6.

SIO1 Serial Input/Output Characteristics (Wakeup Function Disabled) (Note 4-3-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Serial clock	Input clock	Period	tSCK(4)	SCK1(P45)	• See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(4)				2			
		High level pulse width	tSCKH(4)				2			
			tSCKHA(4)		• Automatic communication mode • See Fig. 6.		6			
			tSCKHBSY(4a)		• Automatic communication mode • See Fig. 6.		23			
			tSCKHBSY(4b)		• Mode other than automatic communication mode • See Fig. 6.		4			
	Output clock	Period	tSCK(5)	SCK1(P45)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			tSCK
		Low level pulse width	tSCKL(5)				1/2			
		High level pulse width	tSCKH(5)				1/2			
			tSCKHA(5)		• Automatic communication mode • CMOS output selected • See Fig. 6.		6			tCYC
			tSCKHBSY(5a)		• Automatic communication mode • CMOS output selected • See Fig. 6.		4		23	
			tSCKHBSY(5b)		• Mode other than automatic communication mode • See Fig. 6.		4			
Serial input	Data setup time		tsDI(3)	SI1(P44), SB1(P44)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(3)				0.03			
Serial output	Input clock	Output delay time	tdD0(4)	SO1(P43), SB1(P44)	• (Note 4-3-2)	2.5 to 5.5			1tCYC +0.05	µs
	Output clock		tdDO(5)		• (Note 4-3-2)				1tCYC +0.05	

Note 4-3-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-3-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

SIO1 Serial Input/Output Characteristics (Wakeup Function Enabled) (Note 4-4-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	Specification				
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(6)	SCK1(P45)	• See Fig. 6.	2.5 to 5.5	2			tCYC
		Low level pulse width	tSCKL(6)				1			
		High level pulse width	tSCKH(6)				1			
			tSCKHBSY(6)				2			
Serial input	Data setup time		tsDI(4)	SI1(P44), SB1(P44)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(4)				0.03			
Serial output	Input clock	Output delay time	tdD0(6)	SO1(P43), SB1(P44)	• (Note 4-4-2)	2.5 to 5.5			1tCYC +0.05	

Note 4-4-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-4-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

SMIIC0 Simple SIO Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	Specification				
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(7)	SM0CK(P22)	See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(7)				2			
		High level pulse width	tSCKH(7)				2			
	Output clock	Period	tSCK(8)	SM0CK(P22)	• CMOS output selected • See Fig. 6.		4			
		Low level pulse width	tSCKL(8)			2.5 to 5.5	1/2			tSCK
		High level pulse width	tSCKH(8)				1/2			
Serial input	Data setup time		tsDI(5)	SM0DA(P23)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(5)				0.03			
Serial output	Output delay time		tdD0(7)	SM0DO(P24), SM0DA(P23)	• Specified with respect to falling edge of SIOCLK • Specified as interval up to time when output state starts changing. • See Fig. 6.	2.5 to 5.5			1tCYC +0.05	

Note 4-5-1: These specifications are theoretical values. Add margin depending on its use.

SMIIC0 I²C Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Clock	Input clock	Period	tSCL	SM0CK(P22)	• See Fig. 8.	2.5 to 5.5	5			Tfilt
		Low level pulse width	tSCLL				2.5			
		High level pulse width	tSCLH				2			
	Output clock	Period	tSCLx	SM0CK(P22)	• Specified as interval up to time when output state starts changing.	2.5 to 5.5	10			
		Low level pulse width	tSCLLx				1/2			tSCL
		High level pulse width	tSCLHx				1/2			
SM0CK and SM0DA pins input spike suppression time			tsp	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5			1	Tfilt
Bus release time between start and stop	Input		tBUF	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	2.5			Tfilt
	Output		tBUFx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			
Start/restart condition hold time	Input		tHD;STA	SM0CK(P22) SM0DA(P23)	• When SMIIC register control bit, I²CSHDS=0 • See Fig. 8.	2.5 to 5.5	2.0			Tfilt
					• When SMIIC register control bit, I²CSHDS=1 • See Fig. 8.		2.5			
	Output		tHD;STAx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.1			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.0			
Restart condition setup time	Input		tSU;STA	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output		tSU;STAx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			

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Parameter		Symbol	Applicable Pin/Remarks	Conditions	Specification				
					V_{DD}[V]	min	typ	max	unit
Stop condition setup time	Input	tSU;STO	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output	tSU;STOx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.9			µs
				• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.1			
Data hold time	Input	tHD;DAT	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	0			Tfilt
	Output	tHD;DATx	SM0CK(P22) SM0DA(P23)	• Specified as interval up to time when output state starts changing.		1		1.5	
Data setup time	Input	tSU;DAT	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1			Tfilt
	Output	tSU;DATx	SM0CK(P22) SM0DA(P23)	• Specified as interval up to time when output state starts changing.		1tSCL -1.5Tfilt			
SM0CK and SM0DA pins fall time	Input	tF	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5			300	ns
	Output	tF	SM0CK (P22) SM0DA (P23)	• When SMIIC register control bits, PSLW=1, P5V=1	5	20 +0.1Cb		250	
				• When SMIIC register control bits, PSLW=1, P5V=0	3	20 +0.1Cb		250	
				• SM0CK, SM0DA port output FAST mode • Cb≤400pF	3 to 5.5			100	

Note 4-6-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-6-2: The value of Tfilt is determined by the values of the register SMIC0BRG, bits 7 and 6 (BRP1, BRP0) and the system clock frequency.

BRP1	BRP0	Tfilt
0	0	tCYC×1
0	1	tCYC×2
1	0	tCYC×3
1	1	tCYC×4

Set bits (BPR1, BPR0) so that the value of Tfilt falls between the following range:

250ns ≥ Tfilt >140ns

Note 4-6-3: Cb represents the total loads (in pF) connected to the bus pins. Cb ≤ 400pF

Note 4-6-4: The standard clock mode refers to a mode that is entered by configuring SMIC0BRG as follows:

250ns ≥ Tfilt >140ns

BRDQ (bit5) = 1

SCL frequency setting ≤ 100kHz

The high-speed clock mode refers to a mode that is entered by configuring SMIC0BRG as follows:

250ns ≥ Tfilt >140ns

BRDQ (bit5) = 0

SCL frequency setting ≤ 400kHz

SMIIC1 Simple SIO Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions		Specification			
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(7)	SM1CK(PB4)	See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(7)				2			
		High level pulse width	tSCKH(7)				2			
	Output clock	Period	tSCK(8)	SM1CK(PB4)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			
		Low level pulse width	tSCKL(8)				1/2			tSCK
		High level pulse width	tSCKH(8)				1/2			
Serial input	Data setup time		tsDI(5)	SM1DA(PB5)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
	Data hold time		thDI(5)				0.03			
Serial output	Output delay time		tdD0(7)	SM1DO(PB6), SM1DA(PB5)	• Specified with respect to falling edge of SIOCLK • Specified as interval up to time when output state starts changing. • See Fig. 6.	2.5 to 5.5			1tCYC +0.05	

Note 4-7-1: These specifications are theoretical values. Add margin depending on its use.

SMIIC1 I²C Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Clock	Input clock	Period	tSCL	SM1CK(PB4)	• See Fig. 8.	2.5 to 5.5	5			Tfilt
		Low level pulse width	tSCLL				2.5			
		High level pulse width	tSCLH				2			
	Output clock	Period	tSCLx	SM1CK(PB4)	• Specified as interval up to time when output state starts changing.	2.5 to 5.5	10			
		Low level pulse width	tSCLLx				1/2			tSCL
		High level pulse width	tSCLHx				1/2			
SM0CK and SM0DA pins input spike suppression time			tsp	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5			1	Tfilt
Bus release time between start and stop	Input		tBUF	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	2.5			Tfilt
	Output		tBUFx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			
Start/restart condition hold time	Input		tHD;STA	SM1CK(PB4) SM1DA(PB5)	• When SMIIC register control bit, I^2CSHDS=0 • See Fig. 8.	2.5 to 5.5	2.0			Tfilt
					• When SMIIC register control bit, I^2CSHDS=1 • See Fig. 8.		2.5			
	Output		tHD;STAx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.1			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.0			
Restart condition setup time	Input		tSU;STA	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output		tSU;STAx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			

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